# COMS 3261 Fall 2023 Review Handout: Turing Machines 

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## 1 Definition

A Turing Machine is a 7 -tuple, $\left(Q, \Sigma, \Gamma, \delta, q_{0}, q_{\text {accept }}, q_{\text {reject }}\right)$ :

1. $Q$ is a finite set of states.
2. $\Sigma$ is the (finite) input alphabet not containing the blank symbol.
3. $\Gamma$ is the (finite) tape alphabet, where $\sqcup \in \Gamma$ and $\Sigma \subset \Gamma$.
4. $\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times\{L, R\}$ is the transition function.
5. $q_{0} \in Q$ is the start state.
6. $q_{\text {accept }} \in Q$ is the accept state.
7. $q_{\text {reject }} \in Q$ is the reject state, where $q_{\text {reject }} \neq q_{\text {accept }}$.

For a Turing Machine $M$ :

- $M$ receives its input $w=w_{1} w_{2} \ldots w_{n} \in \Sigma^{*}$ on the left-most $n$ squares of the tape, leaving the rest of the tape blank. The start configuration on input $w$ is $q_{0}$, where the reading head is pointing to the first (leftmost) square of the tape, and the state is $q_{0}$. Then at each step, the transition $\delta$ is applied.
- First blank symbol marks the end of input (initially, afterwards $M$ could write blank symbols anywhere).
- If $M$ ever tries to move its head to the left of the leftmost square of the tape, it stays in place.
- It may sometimes be helpful to have an indicator symbol like $\#$, to indicate the leftmost position of the tape, but this is not automatically there (so if this is not defined as a requirement for a valid input, the TM could be designed to start by inserting it).
- If at any point $\delta$ takes $M$ to $q_{\text {accept }}$ or $q_{\text {reject }}$, then $M$ halts, and we say it accepted/rejected the string. Otherwise, if $\delta$ keeps being applied (algorithm keeps running) without ever accepting or rejecting, then we say this machine runs forever (or is in an infinite loop). A TM that always halts on every input is called a decider.
- On any input, there are three possible behaviors of a TM $M: M$ will accept, reject, or run forever on this input. The language recognized by a Turing Machine $M$ is the set of strings that $M$ accepts.


## 2 Implementation-Level Example: Using Turing Machine to Compute Functions

## Example 1

Let $\Sigma=\{\#, a, b, c\}$. We aim to provide an implementation level description of an input-output Turing Machine (TM) that computes the following function:

$$
f(x)=\# x
$$

## Solution 1

Idea: Essentially, we need to insert a \# key in the beginning and move every character in x one position to the right on the tape. Therefore, we can use the states of the Turing Machine to remember which symbol we need to add to move.

## Implementation:

## States:

- $q_{\text {start }}$ : The start state.
- $q_{\mathrm{a}}$ : State for remembering to add symbol "a" next
- $q_{\mathrm{b}}$ : State for remembering to add symbol "b" next
- $q_{c}$ : State for remembering to add symbol " $b$ " next
- $q_{\text {halt }}:$ Halting(accepting) state


## Transition Function ( $\delta$ ):

1. From $q_{\text {start }}$, look at the first symbol in the input string, transition to the next state representing that symbol, write a \# on the tape, and move right.
2. In $q_{\mathrm{a}}$, remember the symbol that the head is currently pointing to, transition to that corresponding state, and write a symbol "a", and move the head to the right. Same thing for $q_{\mathrm{b}}, q_{\mathrm{c}}$
3. In any state, if current symbol encountered is blank, it means that we've reached the end of the string, then write the symbol corresponding to current state, and finish by transitioning to the halting state.

## Diagram



## Example 2

Let $\Sigma=\{\#, 0,1\}$. We aim to provide an implementation level description of an input-output Turing Machine (TM) that computes the following function:

$$
f(\#\langle a\rangle \#\langle b\rangle)=f(\#\langle a+b\rangle)
$$

where $\langle\mathrm{x}\rangle$ stands for the binary representation of the number x .

## Solution 2

Idea We have two ways of achieving this: we can either use a (or b ) as a counter and decrement it by 1 every time while increasing b (or a) by 1. Alternatively, we can also implement a full-adding Turing machine, which would perform addition as we normally would on paper. The description given here uses the first approach. Please observe that we still need to deal with the case of using extra
tape cells.

## Implementation

## States:

- $q_{\text {start }}$ : The start state.
- $q_{\text {a_scan }}$ : State for scanning right on string a to find the end of the first number.
- $q_{\text {a_subtraction }}$ : State for performing the subtraction on a.
- $q_{\text {a_move right }}$ : State for moving the head after the subtraction on a.
- $q_{\mathrm{b} \text { _scan }}$ : State for scanning right on string b to find the end of the second number
- $q_{\mathrm{b} \text { _addition }}$ : State for performing the addition on string b
- $q_{\mathrm{b} \_m o v e ~ l e f t ~}$ : State for moving the head after the addition on b .
- $q_{\text {cleanup }}$ : State for cleaning up the tape and preparing the output.
- $q_{\text {accept }}:$ Accept state.


## Transition Function ( $\delta$ ):

1. From $q_{\text {start }}$, expect the $\#$ symbol and transition to $q_{\text {a_scan }}$, move to right position
2. In $q_{\text {a_scan }}$, move right until you encounter a $\#$ symbol (representing the end of the first number). Transition to $q_{\text {a_subtraction }}$ and move left.
3. In $q_{\text {a_subtraction }}$, perform the subtraction by the following. If the next digit is 0 , change it to 1 and continue moving left. If it's 1 change it to 0 and stop carrying. Transition to $q_{\text {a_move right }}$ and move right
4. In $q_{\text {a_move right }}$, move right until you see a $\#$ symbol, indicating that we've reached the end of a . Then, transition to $q_{\mathrm{b} \text { _scan }}$ and move right.
5. In $q_{\mathrm{b} \text { _scan }}$, similar to that of a, move right until you see a blank symbol, indicating that we've reached the end of $b$, at which point it moves left and transitions to $q_{\mathrm{b} \_ \text {_addition }}$
6. The logic in $q_{\mathrm{b} \text { _addition }}$ is similar to that of a, except that it's reversed. It continues moving left and carrying over as long as it sees consecutive 1s. On the first 0 , it changes 0 to 1 and transitions to $q_{\text {b_move left }}$.
7. In $q_{\mathrm{b} \_m o v e ~ l e f t ~}$, it moves left with all symbols until seeing a $\#$, which indicates that it has reached the end of number a. At that point, it repeats by transitioning to $q_{\text {a_subtraction }}$ and moves left.
8. We need the Turing Machine to finish the computation when the first number has become 0 . Therefore, when we are in state $q_{\text {a_subtraction }}$, if we've reached the \# symbol without seeing any 1 s , we can transition to $q_{\text {cleanup }}$.
9. In $q_{\text {cleanup }}$, we keep removing 1 s to blanks until we reach $\#$, at which point we erase it and move to $q_{\text {accept }}$

## Diagram



## 3 High-Level Example

First, recall from the definitions that:
A language is Turing-recognizable $\Leftrightarrow$ there exists a TM that accepts strings in that language and doesn't accept strings that aren't in that language.

- $w \in L \Rightarrow M$ accepts $w$
- $w \notin L \Rightarrow M$ rejects or runs forever on $w$

A language is Turing-decidable $\Leftrightarrow$ there exists a TM that accepts strings in that language and rejects strings that aren't in that language. A decider halts on every input.

- $w \in L \Rightarrow M$ accepts $w$
- $w \notin L \Rightarrow M$ rejects $w$

Remark. If $M$ is a decider it will always halt, but if $M$ is a recognizer it may not halt.

### 3.1 Examples of Turing Decideable Languages

- ADFA $=\{\langle D, w\rangle \mid D$ is a DFA and $D$ accepts $w\}$
- ANFA $=\{\langle N, w\rangle \mid N$ is an NFA and $N$ accepts $w\}$
- EDFA $=\{\langle D\rangle \mid D$ is a DFA and $L(D)=\emptyset\}$
- EQDFA $=\{\langle D 1, D 2\rangle \mid D 1$ and $D 2$ are DFAs and $L(D 1)=L(D 2)\}$


## 4 Closure Properties of Turing Recognizeable and Decidable Languages

Theorem 1 (Closure Properties of Decidable Languages). Decidable languages are closed under the following:

- union
- intersection
- concatenation
- complement
- Kleene star

Proof. For union: Suppose $M_{1}$ and $M_{2}$ are deciders. We will create $M$ to decide their union as follows:
$M$ on input $x$ :

1. Run $M_{1}$ on $x$. If $M_{1}$ accepts, accept.
2. Run $M_{2}$ on $x$. If $M_{2}$ accepts, accept.
3. Reject.

Observe that $M$ will always halt (either reach an accept state or reject state, not run forever). This is because step 1 will always halt (since $M_{1}$ is a decider) and step 2 will always halt (since $M_{2}$ is a decider). Hence, $M$ is also a decider. Moreover, $M$ accepts $x \Leftrightarrow M_{1}$ accepts $x$ or $M_{2}$ accepts $x \Leftrightarrow x \in L_{1} \cup L_{2}$ (since $M_{1}$ is a decider for $L_{1}$ and $M_{2}$ is a decider for $L_{2}$ ).

For concatenation: Suppose $M_{1}$ and $M_{2}$ are deciders. Let $L_{1}$ and $L_{2}$ be their respective languages. We will create $M$ to decide their concatenation as follows:
$M$ on input $x$ :

1. For every way to split $x$ into $x=y z$ :
(a) Run $M_{1}$ on input $y$.
(b) Run $M_{2}$ on input $z$.
(c) If both $M_{1}$ and $M_{2}$ accept, let $M$ accept.
2. Reject.
(Proof that this is a decider for concatenation left as an exercise).
Note: a different way to prove closure under concatenation is to construct a non-deterministic TM, which starts by non-deterministically splitting $x$ into $y$ and z. Complement was covered in class and intersection is left as an exercise for the reader.

Theorem 2 (Closure Properties of Recognizable Languages). Recognizable languages are closed under the following:

- union
- intersection
- concatenation
- Kleene star

In particular, we note that recognizable languages are NOT closed under the following:

- complement (will be shown later in the class)

Proof. For union: Suppose $M_{1}$ and $M_{2}$ are TMs, but not necessarily deciders. What happens when we attempt to repeat the proof above?
$M$ on input $x$ :

1. Run $M_{1}$ on $x$.
2. Run $M_{2}$ on $x$.
3. If either $M_{1}$ or $M_{2}$ accepts, let $M$ accept, else reject.

A problem occurs if $M_{1}$ runs forever on $x$. Then, even if $M_{2}$ accepts $x$ (and hence, $M$ should accept $x$ ), we never get to that point because we're running forever with $M_{1}$. One solution to this is using an NTM (non-deterministic Turing machine) $N$, which allows us to run both $M_{1}$ and $M_{2}$ simultaneously on two different branches.
$N$ on input $x$ :

1. Non-deterministically choose either $M_{1}$ or $M_{2}$.
2. Run the chosen TM $M_{i}$ on $x$. If it accepts, accept.

Recall that with an NTM, an input $x$ is in the language if any branch of the computation tree accepts (just like an NFA). Thus, the machine $N$ defined above will accept if and only if either $M_{1}$ or $M_{2}$ accepts, which happens if and only if $x \in L_{1}$ or $x \in L_{2}$, which is if and only if $x \in L_{1} \cup L_{2}$, as we wanted.

An alternative solution using a deterministic TM $M$ can also be designed. We can't run $M_{1}$ first then $M_{2}$ (or vice versa) because there's a chance one machine runs forever on an input $x$, which prevents us from attempting to run the other machine. However, to circumvent this, we can run the two machines in parallel using a two-tape machine (simulate $M_{1}$ using one tape, and simulate $M_{2}$ using the other tape).

## 5 More Practice Problems

### 5.1 Problem 1

Consider the input-output Turing Machine $M=\left(Q, \Sigma, \Gamma, \delta, q_{0}, q_{\text {halt }}\right)$ where $Q=$ $\left\{q_{0}, q_{1}, q_{\text {halt }}\right\}, \Sigma=\{0,1\}, \Gamma=\{0,1, \sqcup\}$, and $\delta$ is given by:

$$
\begin{aligned}
\delta\left(q_{0}, 0\right) & =\left(q_{0}, 0, R\right), \\
\delta\left(q_{0}, 1\right) & =\left(q_{0}, 1, R\right), \\
\delta\left(q_{0}, \sqcup\right) & =\left(q_{1}, \sqcup, L\right), \\
\delta\left(q_{1}, 0\right) & =\left(q_{\text {halt }}, 1, R\right), \\
\delta\left(q_{1}, 1\right) & =\left(q_{1}, 0, L\right), \\
\delta\left(q_{1}, \sqcup\right) & =\left(q_{\text {halt }}, \sqcup, L\right) .
\end{aligned}
$$

(a) Provide the complete sequence of configurations of $M$ when run on input 100. What is the output of $M$ on this input?
(b) What is the output of $M$ on 10011? On input 11?
(c) What function is computed by $M$ ?

### 5.2 Problem 2

Let $\Sigma=\{\#, a, b\}$. We aim to provide an implementation level description of an input-output Turing Machine (TM) that computes the following function:

$$
f(\#\langle x\rangle)= \begin{cases}\#\left\langle\frac{x}{2}\right\rangle & \text { if } x \text { is even } \\ \#\langle 3 x+1\rangle & \text { otherwise }\end{cases}
$$

where $\langle x\rangle$ stands for the binary representation of the number x .

### 5.3 Problem 3

Show that $\mathrm{ECFG}=\{\langle G\rangle \mid G$ is a CFG and $L(G)=\emptyset\}$ is decidable.

### 5.4 Problem 4

Let $L=\{\langle M, k\rangle \mid M$ is a TM, $k$ is a positive integer, and there exists an input to $M$ that makes $M$ run for at least $k$ steps $\}$. Prove that $L$ is decidable.

