

# Handout 11B: Complexity review - Solutions

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## Exercise 1 (True False).

1. All of  $n * \log(n)$ ,  $n^{100} + 3n^2$ ,  $n^{0.001n}$ ,  $2^{\sqrt{n}}$  are polynomial.

Answer :  $n * \log(n)$ ,  $n^{100} + 3n^2$  are polynomial,  $n^{0.001n}$ ,  $2^{\sqrt{n}}$  aren't.

2. If you show a verifier  $V(x, c)$  for a language  $L$ , where  $V$  runs in time polynomial in  $|x| + |c|$ , then  $L$  must be in NP.

Answer : False, for  $L$  to be in NP you need a verifier with runtime polynomial in  $|x|$ .<sup>1</sup> If you allow  $c$  to be of length exponential in  $|x|$ , and you allow  $V$  to run in time polynomial in  $|x| + |c|$ , then you have effectively allowed  $V$  to run in time exponential in  $|x|$ .

3. All NP Complete problems are polytime reducible to each other.

Answer : True. Here's a proof.

Let  $A, B$  be NP-Complete, we want to show  $A \leq_P B$ .

We know  $B$  is NP complete, and thus it's NP hard. So for any  $L \in \text{NP}$ , we have  $L \leq_P B$ .

Since  $A$  is NP complete, it means  $A \in \text{NP}$ .

Combining the two (taking the language  $L = A$ ), we have  $A \leq_P B$ .

4. Say the input of a TM is an integer  $N$  given in binary, and  $M$  runs in time  $O(N^2)$ , then  $M$  runs in polynomial time.

Answer : False.  $N$  is given as input in binary, so the input size is  $O(\log_2(N))$ . But  $N^2 = 2^{2 \log_2(N)}$ , using  $N = 2^{\log_2(N)}$ . So the runtime is exponential in the input length.

## Exercise 2. Show that NP is closed under union. That is if $L_1, L_2 \in \text{NP}$ then $L_1 \cup L_2 \in \text{NP}$ .

Let  $L_1, L_2 \in \text{NP}$ . Then by definition, there exists a polynomial time verifier  $V_1$ , such that :

$$x \in L_1 \Leftrightarrow \exists c_1 \text{ such that } V_1(x, c_1) \text{ accepts.}$$

Similarly, we have a polynomial time verifier  $V_2$  for  $L_2$  such that :

$$x \in L_2 \Leftrightarrow \exists c_2 \text{ such that } V_2(x, c_2) \text{ accepts.}$$

We now want to build a polynomial time verifier  $V$  for  $L_1 \cup L_2$ . The idea is that given  $c$ , we first run  $V_1$  to check if it accepts, and then we run  $V_2$ . We accept if either accepts, and reject if they both reject.

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<sup>1</sup>But this means that if  $x \in L$  there is a  $c$  of length polynomial in  $|x|$  such that  $V(x, c)$  accepts. Otherwise,  $V$  wouldn't have the time to read  $c$  in polynomial time.

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**Algorithm 1** A verifier for  $L_1 \cup L_2$ 

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**Input:**  $x, c$ 

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Run  $V_1$  on  $x, c$   $\triangleright V_1$  runs in polynomial time in  $|x|$ 
if  $V_1$  accepts then
    Accept  $x$ 
end if

Run  $V_2$  on  $x, c$   $\triangleright V_2$  runs in polynomial time in  $|x|$ 
if  $V_2$  accepts then
    Accept  $x$ 
end if
Reject.
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First, it's clear that  $V$  runs in polynomial time in  $|x|$ , as all it does is run  $V_1, V_2$  on  $x, c$ .<sup>2</sup>

So it remains to show

$$x \in L_1 \cup L_2 \iff \exists c \text{ such that } V(x, c) \text{ accepts.}$$

Assume  $x \in L_1 \cup L_2$ , we want to show there exists a  $c$  such that  $V(x, c)$  accepts. If  $x \in L_1$ , we know there exists a  $c_1$  such that  $V_1(x, c_1)$  accepts. So taking  $c = c_1$  leads to  $V$  accepting. Else if  $x \in L_2$ , we know there exists a  $c_2$  such that  $V_2(x, c_2)$  accepts. So taking  $c = c_2$  leads to  $V$  accepting.

Thus

$$x \in L_1 \cup L_2 \Rightarrow \exists c \text{ such that } V(x, c) \text{ accepts}$$

We now show the other direction. Assume there exists a  $c$  such that  $V(x, c)$  accepts. Then in the pseudocode either  $V_1(x, c)$  or  $V_2(x, c)$  must have accepted. If  $V_1$  accepted, then by definition

$$V_1(x, c) \text{ accepts} \Rightarrow x \in L_1$$

Else if  $V_2$  accepted then by definition

$$V_2(x, c) \text{ accepts} \Rightarrow x \in L_2$$

Anyway, it must be that  $x \in L_1 \cup L_2$ . So  $V(x, c) \text{ accepts} \Rightarrow x \in L_1 \cup L_2$ .

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<sup>2</sup>Here's a technical point you can ignore. We should first check that  $c$  isn't too large. By that, I mean  $|c| = O(n^k)$  where we have  $V_1, V_2$  both run in time  $O(n^k)$ . I.e, if  $c$  is bigger than the runtime of  $V_1$  and  $V_2$ , we should reject. This to avoid the case where  $c$  is so large that giving it as input to  $V_1$  would take too long. And if  $c$  is bigger than the runtime of  $V_1, V_2$  we know they would never accept  $(x, c)$ .

### Exercise 3.

- Fix some constant  $k$ . The problem  $k$ -Clique is defined as follow : You are given as input a graph  $G$ ,  $G$  is a graph on  $n$  nodes. You can think of  $G$  as being described by a  $n \times n$  binary matrix  $A$  where  $A_{i,j} = 1$  iff there's an edge  $(i,j)$  in  $G$  (so the input size is  $n^2$  ). You must accept  $G$  if and only there is a subset of  $k$  vertices  $V^*$  of  $G$ , such that these vertices form a complete graph (any two nodes have an edge between them). Why is this problem in P ?

We can give a polynomial time algorithm for the problem as follow :

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**Algorithm 2** An algorithm for  $k$ -Clique

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**Input:**  $\langle G \rangle$  where  $G$  is a graph

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for all subset  $S$  of  $k$  vertices from  $G$  do
    Check that for each pairs  $(u, v)$ , with  $u, v \in S$  we have that  $(u, v)$  is an edge in  $G$ .
    ▷ This means the vertices in  $S$  form a complete graph.
    If for all pairs, the edge  $(u, v)$  is in  $G$ , accept.
end for
Reject.
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This algorithm basically looks at all the subsets of  $k$  vertices in  $G$  and checks they form a complete graph. Clearly if  $\langle G \rangle \in k$ -Clique, then we will accept, and otherwise we will reject.

In the algorithm, we look at all the  $\binom{n}{k}$  subsets of  $k$  vertices of  $G$ . For each subset, we need to check  $O(k^2)$  edges are present, one for all pair. Since  $k$  is a constant, we can assume this takes constant time. So the runtime of the algorithm is  $O(n^k)$ . Since  $k$  is a constant, this is polynomial time.

- The NP complete problem Clique is defined as follow : You are given as input a graph  $G$ ,  $G$  is a graph on  $n$  nodes. **But now  $k$  is given to you as input in decimal.** (So the input size is roughly  $(n^2 + \log_{10}(k))$  ). Again, You must accept  $G$  if and only there is a subset of  $k$  vertices  $V^*$  of  $G$ , such that these vertices form a complete graph. Why doesn't the previous proof work to show this problem is in P ?

If we had to adapt the above algorithm for this proof it would look like that :

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**Algorithm 3** An algorithm for Clique

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**Input:**  $\langle G, k \rangle$  ▷  $k$  is now part of the input

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for all subset  $S$  of  $k$  vertices from  $G$  do
    Check that for each pairs  $(u, v) \in S$   $(u, v)$  is an edge in  $G$ .
    if for all pairs, the edge  $(u, v)$  is in  $G$  then
        Accept.
    end if
end for
Reject.
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Imagine the input is  $(G, k = \frac{n}{2})$ . Then, the algorithm will have to look at  $\binom{n}{\frac{n}{2}}$  subsets, but that

is roughly  $2^n$  many subsets. However, the input size is only  $n^2 + \log_{10}(n)$ , so the runtime of the algorithm is exponential.<sup>3</sup>

**Exercise 4.** Problem 7.18 in the book. Show that if  $P = NP$ , then every language  $A \in P$ , except  $A = \emptyset$  and  $A = \Sigma^*$ , is NP-Complete. ( Hint : think about the definition of  $L \leq_P A$ , knowing that  $L \in NP$  implies  $L \in P$ . )

This exercise is great to test how comfortable you feel with the definition of NP completeness.

Assume  $P = NP$  and let  $A \in P$ , be any language except  $\emptyset$  or  $\Sigma^*$ . That means there exists two strings  $y, z$  such that  $y \in A$  and  $z \notin A$ .

Now consider the NP complete problem 3-SAT, since  $P = NP$  by assumption, we have  $3\text{-SAT} \in P$ . So there exists a polynomial time decider  $M$  for 3-SAT.

We want to show  $A$  is NP-hard. We will show  $3\text{-SAT} \leq_P A$ . So, we claim the following is a mapping reduction from 3-SAT to  $A$ .

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**Algorithm 4** A mapping reduction  $f$  from 3-SAT to  $A$

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**Input:**  $\langle \phi \rangle$  ▷  $\phi$  is a CNF

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Run  $M$  on  $\langle \phi \rangle$            ▷ This takes polynomial time           ▷ This tells us if  $\langle \phi \rangle \in 3\text{-SAT}$  or not
if  $M$  accepts then
    Return  $y$                 ▷  $\langle \phi \rangle \in 3\text{-SAT}$ , so we return  $y \in A$ 
else
    Return  $z$                 ▷  $\langle \phi \rangle \notin 3\text{-SAT}$ , so we return  $z \notin A$ 
end if

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It's clear the above mapping  $f$  is computed in polynomial time. Besides it's also clear that if  $\langle \phi \rangle \in 3\text{-SAT}$ , we have  $f(\langle \phi \rangle) = y \in A$ . And if  $\langle \phi \rangle \notin 3\text{-SAT}$ , then  $f(\langle \phi \rangle) = z \notin A$ . So  $f(\langle \phi \rangle) \in A \iff \langle \phi \rangle \in 3\text{-SAT}$ .

So this is a valid polynomial time mapping reduction from 3-SAT to  $A$ .

So  $A$  is NP-hard, and since  $A \in P$ ,  $A \in NP$  and thus by definition  $A$  is NP complete.

You might wonder why we need that  $A$  isn't  $\emptyset$  or  $\Sigma^*$ . In a mapping reduction from a language  $L$  to  $A$ , we need  $x \in L \iff f(x) \in A$ .

But if we let  $A = \emptyset$ , then there's no strings in  $A$ ! So if  $x \in L$ , we can never have  $f(x) \in A$ . So there can't be a mapping reduction from  $L$  to  $A$  if  $L \neq \emptyset$ .

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<sup>3</sup>.It's important to realize we look at the running time in the WORST CASE input. And here, the algorithm is very slow whenever you give  $k = n/2$  (or any large enough function of  $n$ ).

Similarly, if  $A = \Sigma^*$ , then all strings are in  $A$ . So if  $x \notin L$ , we can never have  $f(x) \notin A$ . So there can't be a mapping reduction from  $L$  to  $A$  if  $L \neq \Sigma^*$ .

**Exercise 5.** Problem 7.21 in the book. Let  $G$  represent an undirected graph. Also let

- $\text{SPATH} = \{\langle G, a, b, k \rangle \mid G \text{ contains a simple path of length at most } k \text{ from } a \text{ to } b\}$
- $\text{LPATH} = \{\langle G, a, b, k \rangle \mid G \text{ contains a simple path of length at least } k \text{ from } a \text{ to } b\}$

Show that  $\text{SPATH} \in \text{P}$  and  $\text{LPATH}$  is NP-Complete. ( A simple path is a path that doesn't visit the same node twice. )

Recall that a simple path is a path that never visits a node twice ( i.e. the path has no cycles ).

We first show  $\text{SPATH} \in \text{P}$ . To check there is a simple path of length  $\leq k$  from  $a$  to  $b$  it suffices to do the following : Perform a Breath-First Search starting at  $a$  in  $G$ .

When we perform a Breath first search (BFS), we first see all the nodes at distance 1 from  $a$ , then we see the ones at distance 2, etc... So if we reach  $b$  before we're at distance  $k + 1$ , we accept, else we reject. Obviously doing a BFS takes times polynomial in the size of the input.

We now show  $\text{LPATH}$  is NP-Complete.

First, we show  $\text{LPATH}$  is in NP. Here's a verifier for  $\text{LPATH}$  :

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**Algorithm 5** A verifier for  $\text{LPATH}$

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**Input:**  $\langle G, a, b, k \rangle, p$   $\triangleright p$  is the extra string the verifier takes as input

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Check  $p$  is a simple path from  $a$  to  $b$  in  $G$ .  
Check that  $p$  has length at least  $k$ .

**if** Both of the above are true **then**  
    Accept.  
**else**  
    Reject.  
**end if**

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Clearly, the above runs in polynomial time. Also it's clear that if  $\langle G, a, b, k \rangle \in \text{LPATH}$ , then there must be a simple path of length  $\geq k$  between  $a$  and  $b$ . So just set  $p$  to be this path, this will lead the verifier to accept. Obviously, if no such path exists, there's no  $p$  that would lead the verifier to accept  $\langle G, a, b, k \rangle, p$ .

So it remains to show the problem is NP-hard. To do this we will reduce the NP-Complete problem  $\text{HamPath}$  to  $\text{LPATH}$ . We need to give a polynomial time mapping reduction from  $\text{HamPath}$  to  $\text{LPATH}$ .

Recall that HamPath is the following problem : Given a graph  $G$  and two nodes  $s, t$  is there an Hamiltonian path from  $s$  to  $t$  in  $G$ .

Given  $G, s, t$  as input for HamPath, our function outputs  $\langle G, a = s, b = t, k = n \rangle$ . I.e.  $f(\langle G, s, t \rangle) = \langle G, s, t, n \rangle$ .

Clearly this is computable in polynomial time. So it remains to show that  $\langle G, s, t \rangle \in \text{HamPath}$  if and only if  $\langle G, s, t, n \rangle \in \text{LPATH}$ .

This isn't hard, once we unpack the definition of Hamiltonian path. By definition there is an Hamiltonian path from  $s$  to  $t$ , if and only if, there is a simple path between  $s$  and  $t$  that visits every vertex once.

Since the path starts at  $s$ , ends at  $t$  and goes through every of the  $n$  vertices once, it means it must be of length  $n$ <sup>4</sup>.

So by definition  $G$  has an Hamiltonian path from  $s$  to  $t$  if and only if there is a simple path between  $s$  and  $t$  of length  $n$ .

Also note that simple paths can't have length more than  $n$ , else a vertex would be repeated so it wouldn't be simple.

Thus, we clearly have that there's an Hamiltonian path from  $s$  to  $t$  if and only if there is a simple path between  $s$  and  $t$  of length at least  $n$ .

So  $\langle G, s, t \rangle \in \text{HamPath}$  iff  $\langle G, s, t, n \rangle \in \text{LPATH}$ . This proves  $\text{HamPath} \leq_P \text{LPATH}$ . So LPATH is NP-hard.

Since LPATH is NP-hard and in NP, it's NP complete.

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<sup>4</sup>Here I count the length of a path as number of vertices