DuckFeed

An Embedded Take on The Classic Video Game "Duck Hunt"

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Intro Slide - Kevin



Zapper Schematic

- Open Collector Outputs
 - \circ Easy to pull up to 3.3V (board voltage)
- Band pass filter
 - Place 390k resistor in parallel with existing one



Hardware Interfacing



Timing (screen blanking) Slide

State	Task	Time
1	Wait for trigger pull	Indefinite
2	Wait for trigger release	Indefinite
3	Set timer to debounce trigger release	200,000 cycles
4	Wait for raster scan to reach end of field	< 416,000 cycles
5	Turn screen black for one frame. Ensure there is no light signal from the gun.	332,500 cycles
6	Keep screen black but place white targets in the place of ducks in binary search pattern. Look for light signals.	450,000 cycles
7	Return screen to background and flying ducks	After 5 flashes

Background Encoding Saves Memory!

Background is 640 x 480 pixels, each pixel is 24 bits (rgb)

 Almost 1MB! Definitely won't fit on chip

 Solution: Run Length Encoding with 16 Colors

 Multiplex colors into 4 bits, length encoded in 8 bits
 Fits in less than 10% of the memory
 Pain to implement



Sprites



Sprites are made out of pixel arrays stored in a rom

 ducks need 5 colors:

type duck_type is array (0 to 1599) of unsigned(3 downto 0);

score numbers and duck food need only 1 color:
 type score_type is array (0 to 1599) of std_logic;
 type fish_type is array (0 to 399) of std_logic;

- each sprite can be read simultaneously up to 2 timesneed multiple constants
- Pixels are read from the rom and colors are decoded in processes in the VGA raster- 1 transparent color
- Then RGB pixel values are called in the VideoOut method which draws the sprites

Sprites

Array Indexing:



- Use horizontal and vertical counters from the raster and duck position from software to calculate the index in the sprite arrays
- Ducks display differently depending on how the sprites are indexed, for example right and left facing ducks.

Flapping: alternate between up-winged duck image and downwinged duck image at every duck flap.



Software

The cerebral cortex of the operation

Defines level variables (number of ducks, speed, time limit, etcetera)

Consistently loops and:

Controls duck position, duck visibility, etc.
Keeps track of time and shots remaining
Decides when a level has been won or lost

Finding the Right Duck - Scott

2.

3.

4.

5.

Actually using Data Structures knowledge! Implemented a binary search algorithm which will determine which duck was hit, checking for cheaters, in five cycles.

Lessons Learned

The best advice we got this semester:
Fix the small problems before tackling the big problems!
Fixing a bug in the VGA raster helped us get the background working
Understand the hardware

• Dual-Ported ROMs made our life easier

Questions?