LAME (Linear Algebra Made Easy)

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MOTIVATION

Performing calculations and operations by hand is tedious, time consuming and error prone.

a)
$$2x-y+z=3$$

b) $x+y=-1$
c) $3x-y-zz=7$
d) $a+b$ $3x+z=2$
e) $b+c$ $4x-2z=6$
2d $6x+zz=4$
e $4x-zz=6$
 $10x=10$
 $x=1$ $y=-2$ $z=-1$

However, computers **IOVE** this stuff!

Why LAME isn't (lame)

- LAME allows for basic control flow operations (if, while)
- Performs matrix/vector operations (resizing, transpose, multiplication, exponentiation) so you don't have to
- Imperative language with C and MATLAB like syntax



The Basics

Basic Types

- Boolean
- String
- Scalar
 - 64 bit signed double precision float
- Matrix
 - Dynamically sized2-D array
 - Elements can be scalars or other matrices

Basic Operations

- Addition
- Negation
- Multiplication
 - Division
- Exponentiation

Basic Operators

- print
- if
- while
- dim
- Relational Operators
- Logical Operators
- Transpose

Example time!

Let us implement an algorithm using LAME to solve a system of simultaneous linear equations. The equations are:

$$3x_1 + x_2 = 3$$

$$9x_1 + 4x_2 = 6$$

We use the following algorithm to solve this problem.

$$A = \left[\begin{array}{cc} 3 & 1 \\ 9 & 4 \end{array} \right]$$

$$B = \left[\begin{array}{c} 3 \\ 6 \end{array} \right]$$

$$X = \left[\begin{array}{c} x_1 \\ x_2 \end{array} \right] = A^{-1}B$$

$$A^{-1} = \frac{1}{|A|} \mathrm{Adj}(A) = \frac{1}{A_{0,0} A_{1,1} - A_{0,1} A_{1,0}} \left[\begin{array}{cc} A_{1,1} & -A_{0,1} \\ -A_{1,0} & A_{0,0} \end{array} \right]$$

Doing This (fingers crossed)

```
matrix A = \{ 3, 1; 9, 4 \};
matrix B = \{ 3; 6 \};
matrix X;
print "\nSolving system of simultaneous linear
equations:\n";
print A[0,0] + "x1 + " + A[0,1] + "x2 = " + B[0] +
"\n";
print A[1,0] + "x1 + " + A[1,1] + "x2 = " + B[1] +
"\n";
print "\nA = \n" + A + "\n";
print "\nB = \n" + B + "\n";
scalar det_of_A = A[0,0]*A[1,1] - A[0,1]*A[1,0];
print "\nDeterminant(A) = " + det of A + "\n";
```

Outputs This

Solving system of simultaneous linear equations:

$$3 \times 1 + 1 \times 2 = 3$$

$$9 x1 + 4 x2 = 6$$

A =

3 1

94

B =

3

6

Determinant(A) = 3

Doing This

```
if(det_of_A != 0) {
... //see next slide
} else {
print "A is singular and its inverse doesn't
exist.\n";
```

Doing This (continued)

```
matrix inv_of_A;
inv_of_A [0,0] = A[1,1];
inv_of_A [0,1] = -1*A[0,1];
inv_of_A [1,0] = -1*A[1,0];
inv_of_A [1,1] = A[0,0];
inv_of_A = inv_of_A / det_of_A;
X = inv of A * B;
print "\nInverse(A) = \n" + inv_of_A + "\n";
print "X = Inverse(A) * B = \n" + X + \n";
print "Solution:\n";
print "x1 = " + X[0] + "\n";
print "x2 = " + X[1] + "\n";
```

Outputs This (Yay!)

```
Inverse(A) =
1.33333 -0.333333
-3 1
X = Inverse(A) * B =
Solution:
x1 = 2
x2 = -3
```

The Whole Shebang

```
matrix A = \{ 3, 1; 9, 4 \};
                                                   inv of A[0,1] = -1*A[0,1];
                                                   inv of A [1,0] = -1*A[1,0];
matrix B = \{ 3; 6 \};
                                                   inv of A[1,1] = A[0,0];
matrix X;
print "\nSolving system of simultaneous linear inv of A = inv of A / det of A;
equations:\n";
                                                   X = inv of A * B;
print A[0,0] + "x1 + " + A[0,1] + "x2 = " + B[0] +
                                                   print "\nInverse(A) = \n'' + inv of A + "\n'';
"\n":
                                                   print "X = Inverse(A) * B = \n'' + X + \n'';
print A[1,0] + "x1 + " + A[1,1] + "x2 = " + B[1] +
                                                    print "Solution:\n";
"\n":
                                                   print "x1 = " + X[0] + "\n";
print "\nA = \n" + A + "\n";
                                                   print "x2 = " + X[1] + "\n";
print "nB = n" + B + "n";
                                                   } else {
scalar det of A = A[0,0]*A[1,1] - A[0,1]*A[1,0];
                                                   print "A is singular and its inverse doesn't
print "\nDeterminant(A) = " + det_of_A + "\n";
                                                   exist.\n";
if(det of A = 0) {
matrix inv of A;
inv_of_A [0,0] = A[1,1];
```

All Together Now

Solving system of simultaneous linear equations:

$$3 x1 + 1 x2 = 3$$

$$9 x1 + 4 x2 = 6$$

$$A =$$

3 1

94

B =

3

6

Determinant(A) = 3

Inverse(A) =

1.33333 -0.333333

-3 1

X = Inverse(A) * B =

2

-3

Solution:

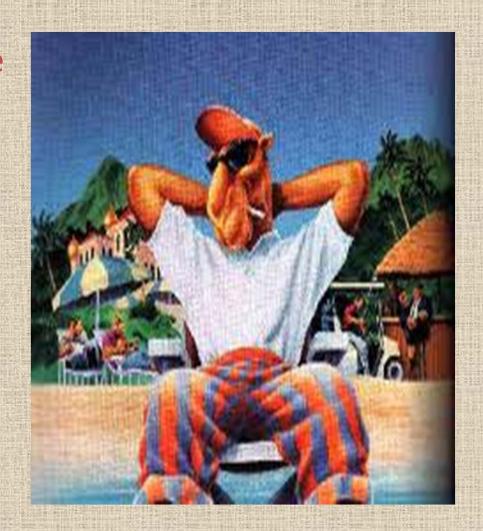
$$x1 = 2$$

$$x2 = -3$$

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Implementation

- O'Caml takes care of the hard work
- iLAME 3-op code is converted into C ++
- C++ is then used to perform matrix operations and output the result



Lessons Learned

- Get started early!
- Make sure the problem is well defined math really is your friend
- Set and keep to deadlines
- Be open to revision
- Formal interfaces document/code style, module interaction
- AWK is better than O'Caml (kidding)

Questions?

