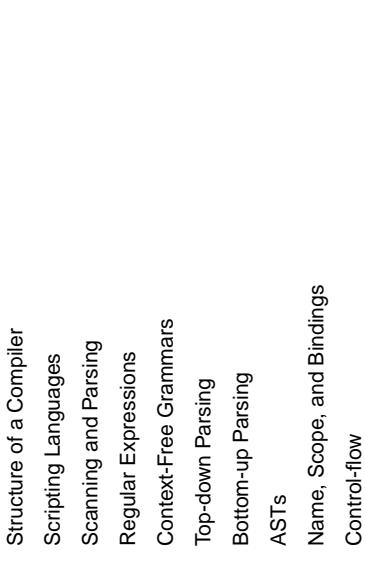


The Midterm

Topics



Review for the Midterm

COMS W4115

Prof. Stephen A. Edwards
Spring 2007
Columbia University
Department of Computer Science

- One sheet of notes of your own devising
- Comprehensive: Anything discussed in class is fair game
- Little, if any, programming.
- Details of ANTLR/C/Java/Prolog/ML syntax not required
- Broad knowledge of languages discussed

Compiling a Simple Program

```
int gcd(int a, int b)
{
    while (a != b) {
        if (a > b) a -= b;
        else b -= a;
    }
}
```

```
int gcd(int a, int b)
{
    while (a != b) {
        if (a > b) a -= b;
        else b -= a;
    }
}
```

Text file is a sequence of characters

What the Compiler Sees

```
int gcd(int a, int b)
{
    while (a != b) {
        if (a > b) a -= b;
        else b -= a;
    }
}
```

Lexical Analysis Gives Tokens

```
int gcd(int a, int b)
{
    while (a != b) {
        if (a > b) a -= b;
        else b -= a;
    }
}
```

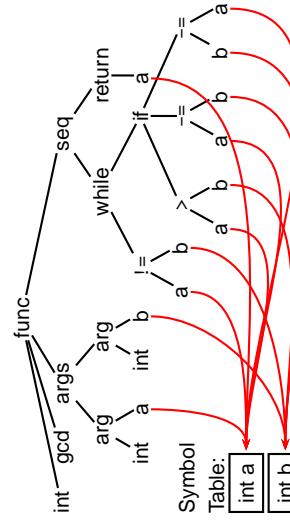
A stream of tokens. Whitespace, comments removed.

Parsing Gives an AST

```
int gcd(int a, int b)
{
    while (a != b) {
        if (a > b) a -= b;
        else b -= a;
    }
}
```

Abstract syntax tree built from parsing rules.

Semantic Analysis Resolves Symbols



Types checked; references to symbols resolved.

Translation into 3-Address Code

```
L0: sm $1, a, b
seq $0, $1, 0
btrue $0, L1 % while (a != b)
$1 $3, b, a
seq $2, $3, 0
btrue $2, L4 % if (a < b)
sub a, a, b % a -= b
jmp L5
L4: sub b, b, a % b -= a
L5: jmp L0
L1: ret a
```

```
int gcd(int a, int b)
{
    while (a != b) {
        if (a > b) a -= b;
        else b -= a;
    }
}
```

Idealized assembly language w/ infinite registers

Generation of 80386 Assembly

Describing Tokens

```

gcd:    pushl %ebp          % Save frame pointer
        movl %esp,%ebp
        movl 8(%ebp),%eax  % Load a from stack
        movl 12(%ebp),%edx  % Load b from stack
.I8:   cmpl %edx,%eax
        je .L3             % while (a != b)
        jle .L5             % if (a < b)
        subl %edx,%eax
        jmp .L8             % a -= b
.L5:   subl %eax,%edx
        jmp .L8             % b -= a
.L3:   leave              % Restore SP, BP
        ret

```

Scanning and Automata

Alphabet: A finite set of symbols
Examples: { 0, 1 }, { A, B, C, ..., Z }, ASCII, Unicode

String: A finite sequence of symbols from an alphabet
Examples: ϵ (the empty string), Stephen, $\alpha\beta\gamma$

Language: A set of strings over an alphabet
Examples: \emptyset (the empty language), { 1, 11, 111, 1111 }, all English words, strings that start with a letter followed by any sequence of letters and digits

Operations on Languages

Let $L = \{ \epsilon, \text{wo} \}$, $M = \{ \text{man}, \text{men} \}$

Concatenation: Strings from one followed by the other

$L.M = \{ \text{man, men, woman, women} \}$

Union: All strings from each language

$L \cup M = \{ \epsilon, \text{wo, man, men} \}$

Kleene Closure: Zero or more concatenations

$M^* = \{ \epsilon, M, MM, MMM, \dots \} =$

$\{ \epsilon, \text{man, men, manman, menmen, menmen, manmanman, manmanmen, manmenmen, \dots } \}$

Regular Expressions over an Alphabet Σ

A standard way to express languages for tokens.

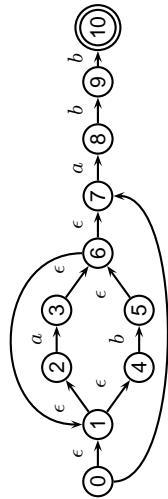
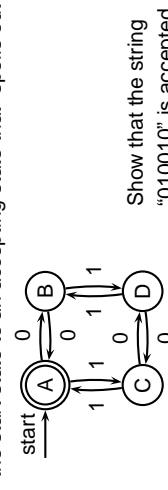
1. ϵ is a regular expression that denotes $\{ \epsilon \}$
2. If $a \in \Sigma$, a is an RE that denotes $\{ a \}$
3. If r and s denote languages $L(r)$ and $L(s)$,
 - $(r)s$ denotes $L(r) \cup L(s)$
 - $(r)^*$ denotes $\{ tu : t \in L(r), u \in L(s) \}$
 - $(r)^*$ denotes $\cup_{i=0}^{\infty} L^i$ ($L^0 = \emptyset$ and $L^i = LL^{i-1}$)

Nondeterministic Finite Automata

"All strings containing an even number of 0's and 1's"	1. Set of states $S: \{ \textcircled{A}, \textcircled{B}, \textcircled{C}, \textcircled{D} \}$
	2. Set of input symbols $\Sigma: \{ 0, 1 \}$
	3. Transition function $\sigma: S \times \Sigma_e \rightarrow \{ 0, 1 \}$
	state ϵ 0 1
start	\textcircled{A} \textcircled{B} \textcircled{C} \textcircled{D}
	0 \textcircled{B} \textcircled{A} \textcircled{D} \textcircled{C}
	1 \textcircled{C} \textcircled{D} \textcircled{A} \textcircled{B}
	0 \textcircled{D} \textcircled{C} \textcircled{B} \textcircled{A}
	1 \textcircled{A} \textcircled{B} \textcircled{D} \textcircled{C}
	4. Start state $s_0: \textcircled{A}$
	5. Set of accepting states $F: \{ \textcircled{A} \}$

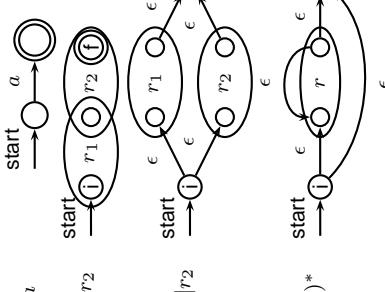
The Language induced by an NFA

An NFA accepts an input string x iff there is a path from the start state to an accepting state that "spells out" x .



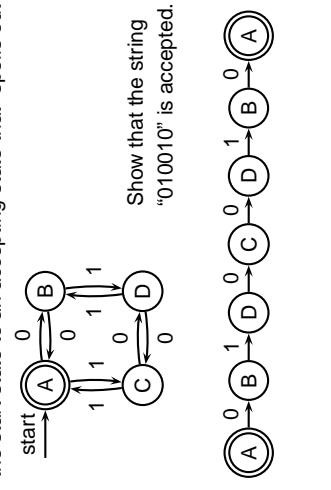
Translating REs into NFAs

Example: translate $(a|b)^*abb$ into an NFA



Translating REs into NFAs

Show that the string "aaabb" is accepted.



Simulating NFAs

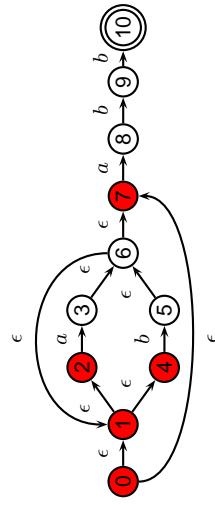
Problem: you must follow the “right” arcs to show that a string is accepted. How do you know which arc is right?

Solution: follow them all and sort it out later.

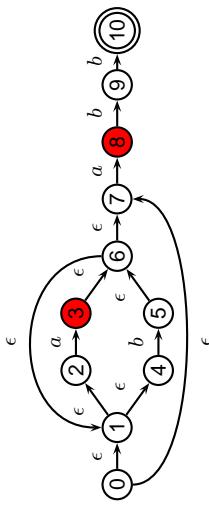
1. Initial states: the ϵ -closure of the start state
 2. For each character c_i
 - New states: follow all transitions labeled c_i
 - Form the ϵ -closure of the current states
 3. Accept if any final state is accepting

Simulating an NFA: $aabb$, Start

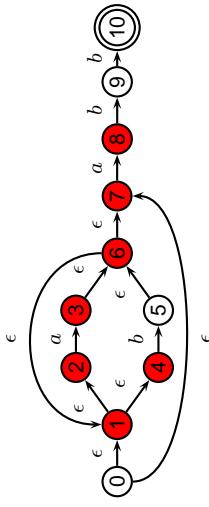
Simulating an NFA: $aabb, \epsilon$ -closure



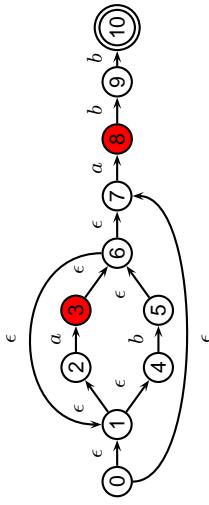
Simulating an NFA: $a \cdot abb$



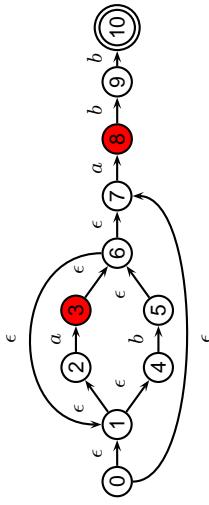
Simulating an NFA: $a \cdot abb, \epsilon$ -closure



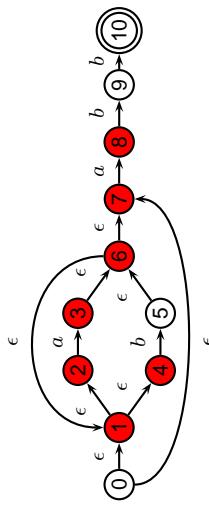
Simulating an NFA: $a \cdot abb, \epsilon$ -closure



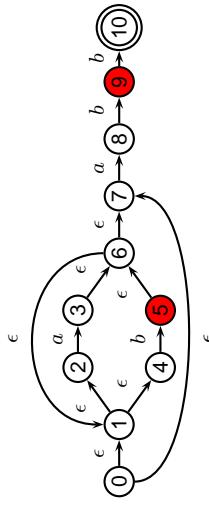
Simulating an NFA: $aa \cdot bb$



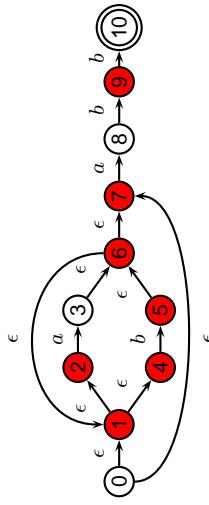
Simulating an NFA: $aa.bb, \epsilon$ -closure



Simulating an NFA: $aab.b$

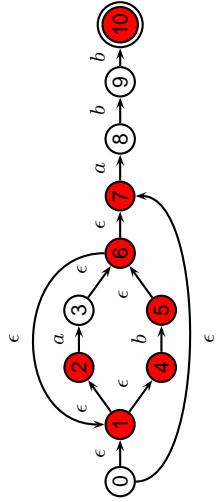
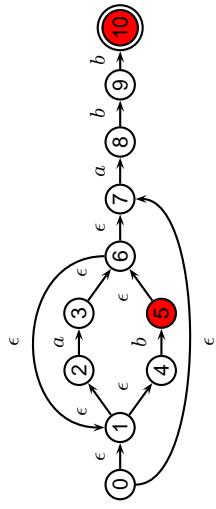


Simulating an NFA: $aab.b, \epsilon$ -closure



Simulating an NFA: $aabb$, Done

Simulating an NFA: $aabb$, Done



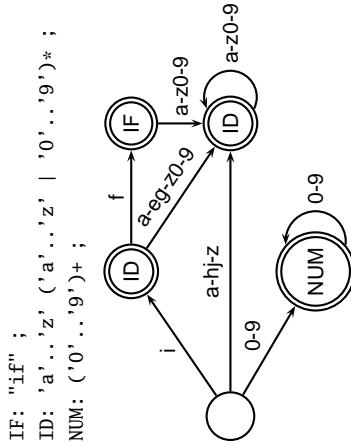
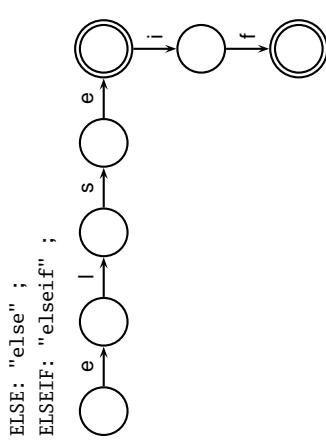
Simulating an NFA: $aabb$, Done

Deterministic Finite Automata

- Restricted form of NFAs:
 - No state has a transition on ϵ .
 - For each state s and symbol a , there is at most one edge labeled a leaving s .
- Differs subtly from the definition used in COMS W3261 (Sipser, *Introduction to the Theory of Computation*)
- Very easy to check acceptance: simulate by maintaining current state. Accept if you end up on an accepting state. Reject if you end on a non-accepting state or if there is no transition from the current state for the next symbol.

Deterministic Finite Automata

Deterministic Finite Automata

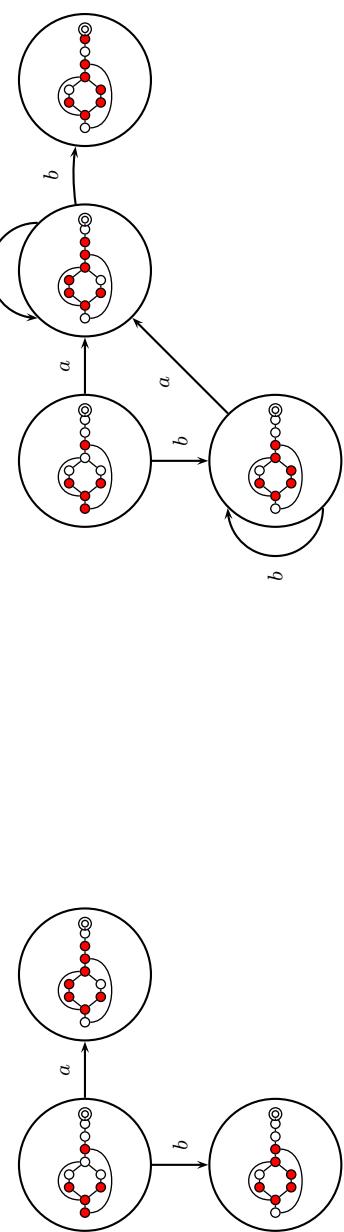


Deterministic Finite Automata

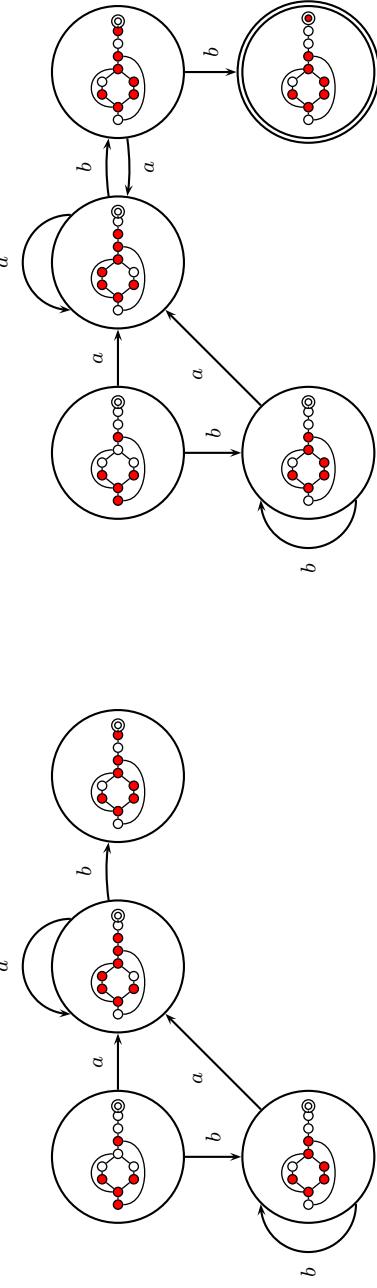
- Subset construction algorithm
- Simulate the NFA for all possible inputs and track the states that appear.
- Each unique state during simulation becomes a state in the DFA.

Building a DFA from an NFA

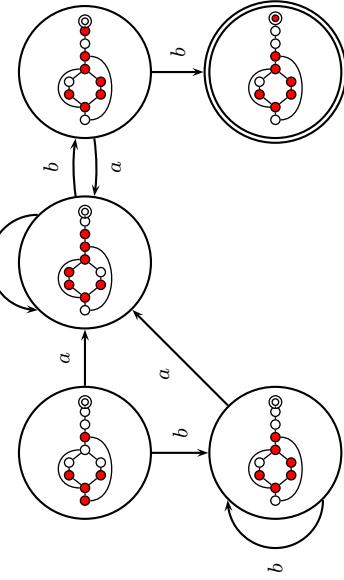
Subset construction for $(a|b)^*abb$ (1)



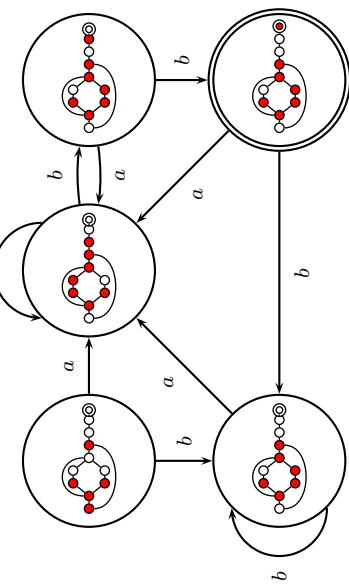
Subset construction for $(a|b)^*abb$ (2)



Subset construction for $(a|b)^*abb$ (3)



Subset construction for $(a|b)^*abb$ (4)

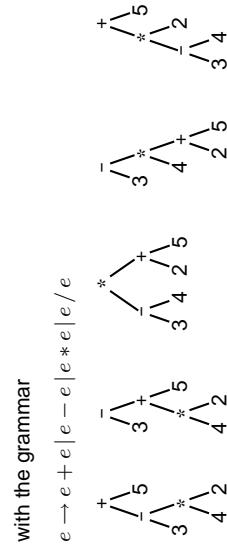


Ambiguous Grammars

A grammar can easily be ambiguous. Consider parsing

$3 - 4 * 2 + 5$

Grammars and Parsing



Fixing Ambiguous Grammars

Original ANTLR grammar specification

```
expr : expr '+' expr
      | expr '-' expr
      | expr '*' expr
      | expr '/' expr
      | NUMBER
      ;
```

Ambiguous: no precedence or associativity.

Assigning Precedence Levels

Split into multiple rules, one per level

```
expr : expr '+' term
      | expr '-' term
      | term ;
term : term '*' atom
      | term '/' atom
      | atom ;
```

atom : NUMBER ;

Still ambiguous: associativity not defined

Assigning Associativity

Make one side or the other the next level of precedence

```
expr : expr '+' term
      | expr '-' term
      | term ;
term : term '*' atom
      | term '/' atom
      | atom ;
```

atom : NUMBER ;

Writing LL(k) Grammars

Cannot have left-recursion

```
expr : expr '+' term | term ;
becomes
```

```
AST expr() {
    switch (next-token) {
        case NUMBER : expr(); /* Infinite Recursion */
        case "while" : match("while"); expr(); match("then"); expr();
        case ":" : match(":");
        case ";" : match(";");
        case "=" : match("=");
    }
}
```

Writing LL(1) Grammars

Cannot have common prefixes

```
expr : ID '(' expr ')',
      | ID '=' expr
becomes
```

```
AST expr() {
    switch (next-token) {
        case ID : match(ID); match('('); expr(); match(')');
        case ID : match(ID); match('='); expr();
    }
}
```

A Top-Down Parser

```
stmt : 'if' expr 'then' expr
      | 'while' expr 'do' expr
      | expr ':=' expr ;
expr : NUMBER | '(' expr ')' ;
AST stmt() {
    switch (next-token) {
        case NUMBER : expr(); /* Infinite Recursion */
        case "if" : match("if"); expr(); match("then"); expr();
        case "while" : match("while"); expr(); match("do"); expr();
        case ":" : match(":");
        case ";" : match(";");
        case "=" : match("=");
    }
}
```

Eliminating Common Prefixes

Eliminating Left Recursion

Consolidate common prefixes:

```
expr
: expr '+' term
| expr '-' term
| term
;
```

becomes

```
expr : term exprt ;
exprt : '+' term exprt
| '-' term exprt
| /* nothing */
;
```

Understand the recursion and add tail rules

```
expr
: expr ('+' term | '-' term )
| term
;

becomes
```

```
expr : term exprt ;
exprt : '+' term exprt
| '-' term exprt
| /* nothing */
;
```

Rightmost Derivation

```
1: e → t + e
2: e → t
3: t → id * t
4: t → id
```

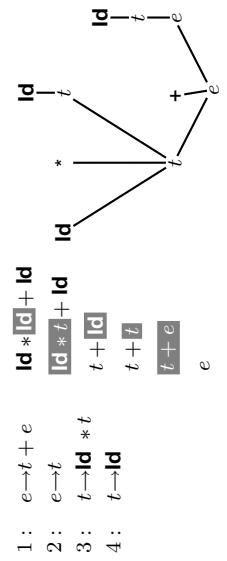
A rightmost derivation for **id * id + id**:

$$\boxed{e} \rightarrow \boxed{t + \boxed{e}} \rightarrow \boxed{t + \boxed{id}} \rightarrow \boxed{id * \boxed{id}}$$

Basic idea of bottom-up parsing:
construct this rightmost derivation
backward.

Here, I've drawn a box around
each symbol to expand.
id * id + id

Handles



This is a reverse rightmost derivation for **id * id + id**.

Each highlighted section is a **handle**.

Taken in order, the handles build the tree from the leaves to the root.

Shift-reduce Parsing

	input	action
1:	e → t + e	stack
2:	e → t	shift
3:	t → id * t	reduce (3)
4:	t → id	shift

Scan input left-to-right, looking for handles.
An oracle tells what to do

LR Parsing

	input	stack	input	action
1:	e → t + e	0	id * id + id \$	shift, goto 1
2:	e → t	0	* id + id \$	shift, goto 3
3:	t → id * t	0	id + id \$	shift, goto 1
4:	t → id	0	+ id \$	reduce w/ 4

	input	stack	input	action
1:	e → t + e	0	id * id + id \$	shift, goto 1
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	input	stack	input	action
1:	e → t + e	0	id * id + id \$	shift, goto 1
2:				

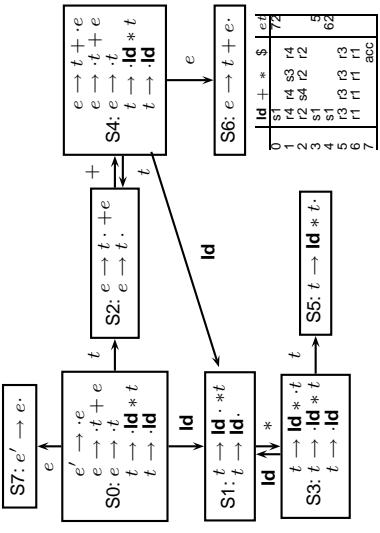
Constructing the SLR Parse Table

Constructing the SLR Parsing Table

The states are places we could be in a reverse-rightmost derivation. Let's represent such a place with a dot.

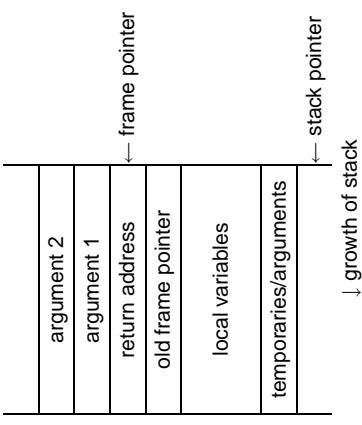
- 1 : $e \rightarrow t + e$
- 2 : $e \rightarrow t$
- 3 : $t \rightarrow \text{id} * t$
- 4 : $t \rightarrow \text{id}$

Say we were at the beginning ($\cdot e$). This corresponds to
 $e' \rightarrow \cdot e$
 $e \rightarrow \cdot t$
 $e \rightarrow \cdot t + e$
 $t \rightarrow \cdot \text{id} * t$
 $t \rightarrow \cdot \text{id}$



Names, Objects, and Bindings

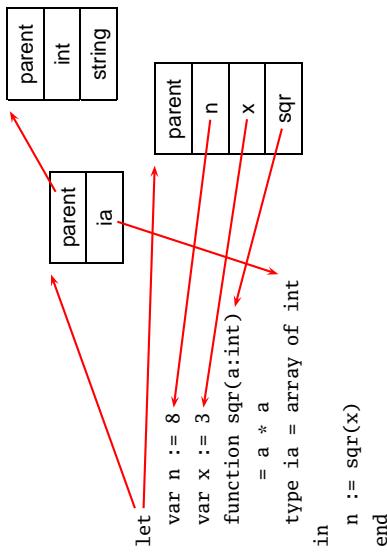
Activation Records



Activation Records



Control-Flow



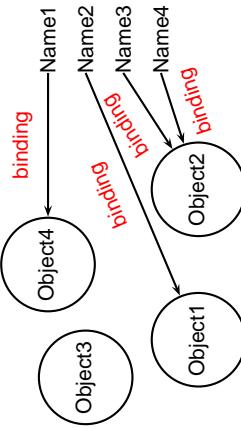
Nested Subroutines in Pascal

```

procedure A;
var a : integer;
procedure B;
var b : integer;
procedure C;
var c : integer;
begin
begin .. end
procedure D;
var d : integer;
begin
begin { Body of B }
C;
end;
begin;
procedure E;
var e : integer;
begin
B;
end;
begin { Body of A }
E;
end;

```

Symbol Tables in a Functional Lang.



Side-effects

Misbehaving Floating-Point Numbers

```
int x = 0;
int foo() { x += 5; return x; }

int a = foo() + x + foo();
GCC sets a=25.
```

Sun's C compiler gave a=20.

C says expression evaluation order is implementation-dependent.

$(1 + 9e-7) + 9e-7 \neq 1 + (9e-7 + 9e-7)$
 $9e-7 \ll 1$, so it is discarded, however, $1.8e-6$ is large enough
 $1.00001(1.000001 - 1) \neq 1.000001 \cdot 1.000001 - 1.000001 \cdot 1$
 $1.00001 \cdot 1.000001 = 1.000011\textbf{00001}$ requires too much intermediate precision.

Gotos vs. Structured Programming

Break and continue leave loops prematurely:

```
for ( i = 0 ; i < 10 ; i++ ) {
    if ( i == 5 ) continue;
    if ( i == 8 ) break;
    printf("%d\n", i);
}

Again: if (!(i < 10)) goto Break;
if ( i == 5 ) goto Continue;
if ( i == 8 ) goto Break;
printf("%d\n", i);
Continue: i++; goto Again;
Break:
```

Implementing multi-way branches

If the cases are *dense*, a branch table is more efficient:

```
switch (s) {
    case 1: one(); break;
    case 2: two(); break;
    case 3: three(); break;
    case 4: four(); break;
}

labels[1] = { L1, L2, L3, L4 }; /* Array of labels */

if (s>1 && s<=4) goto l[s-1]; /* not legal C */
L1: one(); goto Break;
L2: two(); goto Break;
L3: three(); goto Break;
L4: four(); goto Break;
Break:
```

Implementing multi-way branches

Multi-way Branching



```
switch (s) {
    case 1: one(); break;
    case 2: two(); break;
    case 3: three(); break;
    case 4: four(); break;
}

Switch sends control to one of the case labels. Break terminates the statement.
```

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L2: two(); goto Break;
L3: three(); goto Break;
L4: four(); goto Break;
Break:
```

Obvious way:

```
if (s == 1) { one(); }
else if (s == 2) { two(); }
else if (s == 3) { three(); }
else if (s == 4) { four(); }
```

Reasonable, but we can sometimes do better.

Applicative- and Normal-Order Evaluation

```
int p(int i) { printf("%d ", i); return i; }
void q(int a, int b, int c)
{
    int total = a;
    printf("%d ", b);
    total += c;
}
q( p(1), 2, p(3) );
```

Applicative: arguments evaluated before function is called.
Result: 1 3 2

Normal: arguments evaluated when used.
Result: 1 2 3

Nondeterminism

Nondeterminism is not the same as random:

Compiler usually chooses an order when generating code.
Optimization, exact expressions, or run-time values may affect behavior.

Bottom line: don't know what code will do, but often know set of possibilities.

```
int p(int i) { printf("%d ", i); return i; }
int q(int a, int b, int c)
{
    q( p(1), p(2), p(3) );
}
Will not print 5 6 7. It will print one of
1 2 3, 1 3 2, 2 1 3, 2 3 1, 3 1 2, 3 2 1
```

Implementing Inheritance

Simple: Add new fields to end of the object
Fields in base class always at same offset in derived class
Consequence: Derived classes can never remove fields

C++

```
class Shape {
    double x, y;
};

class Box : Shape {
    double h, w;
};

struct Shape {
    double x, y;
};

struct Box {
    double x, y;
};
```

Virtual Functions

Virtual Functions

Virtual Functions

```
class Shape {
    virtual void draw(); // Invoked by object's class
};

class Line : public Shape {
    void draw();
};

class Arc : public Shape {
    void draw();
};

Shape *s[10];
s[0] = new Line;
s[1] = new Arc;
s[0]->draw(); // Invoke Line::draw()
s[1]->draw(); // Invoke Arc::draw()
```

The Trick: Add a "virtual table" pointer to each object.

```
struct A {
    int x;
    virtual void Foo();
    virtual void Bar();
    { do_something(); }
};

struct B : A {
    int y;
    virtual void Foo();
    virtual void Baz();
};

A a1, a2;
B b1;
```

```
struct A {
    int x;
    virtual void Foo();
    virtual void Bar();
    { do_something(); }
};

struct B : A {
    int y;
    virtual void Foo();
    virtual void Baz();
};

A *a = new B;
a->Bar();
```

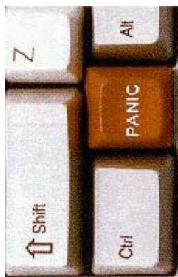
Exceptions

A high-level replacement for C's setjmp/longjmp.

```
struct Except {
};

void baz() { throw Except(); }
void bar() { baz(); }

void foo() {
    try {
        bar();
    } catch (Except e) {
        printf("oops");
    }
}
```



One Way to Implement Exceptions

```
try {
    push(Ex, Handler);
    throw Ex;
    pop();
    goto Exit;
}
catch (Ex e) {
    Handler:
    foo();
    Exit:
}

push() adds a handler to a stack
pop() removes a handler
throw() finds first matching handler
```

Problem: imposes overhead even with no exceptions

Implementing Exceptions Cleverly

Real question is the nearest handler for a given PC.

Lines	Action
1–2	Reraise
3	look in table
4	try { bar(); }
5	catch (Ex1 e) { H1: a(); }
6	6–9 Reraise
7	2. H2 doesn't handle Ex1, reraise
8	void bar() {
9	1. look in table
10	try { throw Ex1(); }
11	11 } catch (Ex2 e) { H2: b(); }
12	12 } reraise
13	13 }
14	14 }