

Computer Graphics - Week 3



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Questions about Last Week ?



Overview of Week 3

- ▶ Viewing transformations
- ▶ Projections
- ▶ Camera models

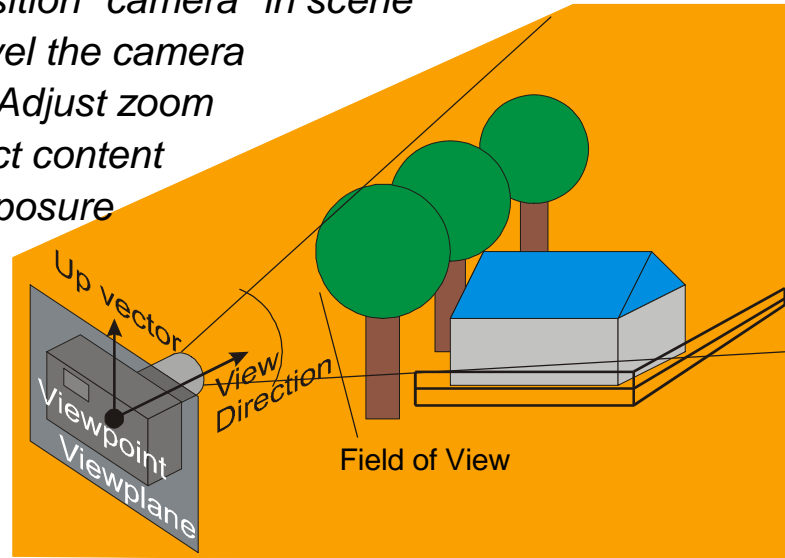


Viewing Transformation



Viewing Compared to Taking Pictures

- ▶ **View Vector & Viewplane:** *Direct camera towards subject*
- ▶ **Viewpoint:** *Position "camera" in scene*
- ▶ **Up Vector:** *Level the camera*
- ▶ **Field of View:** *Adjust zoom*
- ▶ **Clipping:** *Select content*
- ▶ **Projection:** *Exposure*



Viewing Transformation

- ▶ **Position and orient camera**
 - Set viewpoint, viewing direction and upvector
- ▶ **Use geometric transformation to position**
 - camera with respect to the scene or ...
 - scene with respect to the camera.
 - Both approaches are mathematically equivalent.



Viewing Pipeline and Coordinate Systems

► Modeling Transformation

- Position objects in world coordinates

► Viewing Transformation

- Position objects in eye/camera coordinates
 - EC a.k.a. View Reference Coordinates

► Perspective Transformation

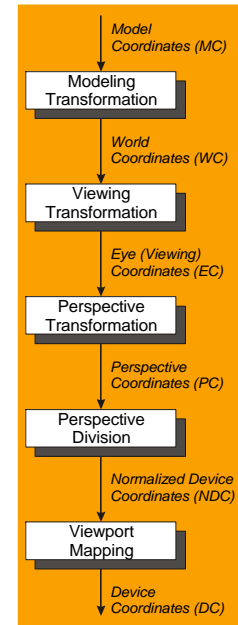
- Convert view volume to a canonical view volume
- Also used for clipping
 - PC a.k.a. clip coordinates

► Perspective Division

- Perform mapping from 3D to 2D

► Viewport Mapping

- Map normalized device coordinates into window/screen coordinates



Why a special eye coordinate system ?

- In principal it is possible to directly project on an arbitray viewplane. However, this is computationally very involved.

- Instead, the scene is transformed into special coordinate system, that makes projection easy.

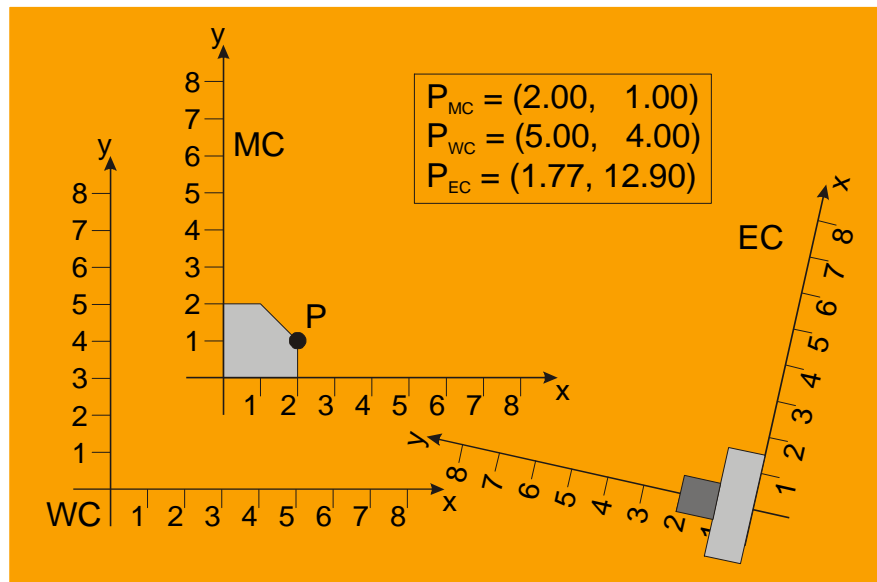
- View down the negative z-axis
- Projection plane parallel to $z=0$

- This "extra" transformation is free !

- It can be combined with the modeling transformation
- Therefore, every point must be transformed only once.
- This transformation is known in OpenGL as the Model-View Matrix.



Model, World and Eye Coordinates



Computing the Viewing Transformation

- ▶ Changing from WC to EC is simple change of coordinate systems which can be expressed using a 4x4 matrix:

$$P_{EC} = M_{WE} \cdot P_{WC}$$

$$M_{WE} = (Wx_{EC} \quad Wy_{EC} \quad Wz_{EC} \quad Wo_{EC})$$

- Wi_{EC} is unit vector on the WC i -axis expressed in EC
- Wo_{EC} is the WC origin expressed in EC
- M_{ME} is the Model-View Matrix.

- ▶ Same approach for changing from MC to WC



Computing the Viewing Transformation: Example

$$(1 \ 0)_{WC}^T = (0.21 \ -0.98)_{EC}^T$$

$$(0 \ 1)_{WC}^T = (0.98 \ 0.21)_{EC}^T$$

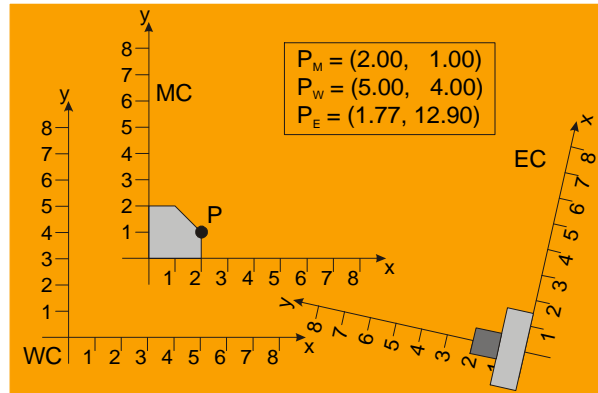
$$(0 \ 0)_{WC}^T = (-3.25 \ 17.00)_{EC}^T$$

$$\mathbf{M}_{WE} = \begin{pmatrix} 0.21 & 0.98 & -3.25 \\ -0.98 & 0.21 & 17.00 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\mathbf{M}_{MW} = \begin{pmatrix} 1 & 0 & 3 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\mathbf{M}_{ME} = \mathbf{M}_{WE} \cdot \mathbf{M}_{MW} = \begin{pmatrix} 0.21 & 0.98 & 0.32 \\ -0.98 & 0.21 & 14.69 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\mathbf{P}_E = \mathbf{M}_{ME} \cdot \mathbf{P}_M = \begin{pmatrix} 0.21 & 0.98 & 0.32 \\ -0.98 & 0.21 & 14.69 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 2.0 \\ 1.0 \\ 1.0 \end{pmatrix} = \begin{pmatrix} 1.72 \\ 12.94 \\ 1 \end{pmatrix}$$



Projection



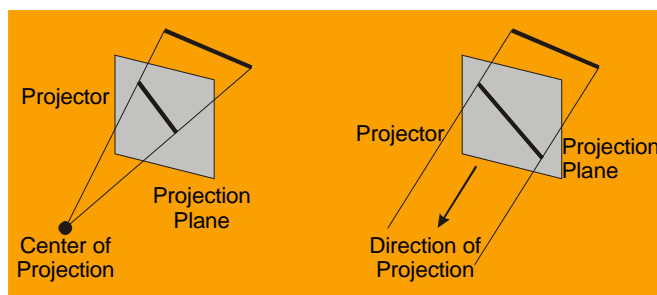
Projection: Overview

- ▶ Now, the scene is transformed to the EC system
- ▶ Next, the scene must be projected onto the view plane
- ▶ This is done in several steps
 - Selecting the projection type
 - Selecting center/direction of projection
 - Computing the view volume
 - Transforming the view volume into a *canonical* representation
 - Projection onto the viewplane



Projection: Introduction

- ▶ Projections map points from n dimensions to m dimensions, with $m < n$.
 - Here: from 3D to 2D
- ▶ Points are projected along straight lines, called **projectors**, onto the **projection plane**
 - Perspective projection: projectors go through a single point
 - Parallel projection: projectors are parallel



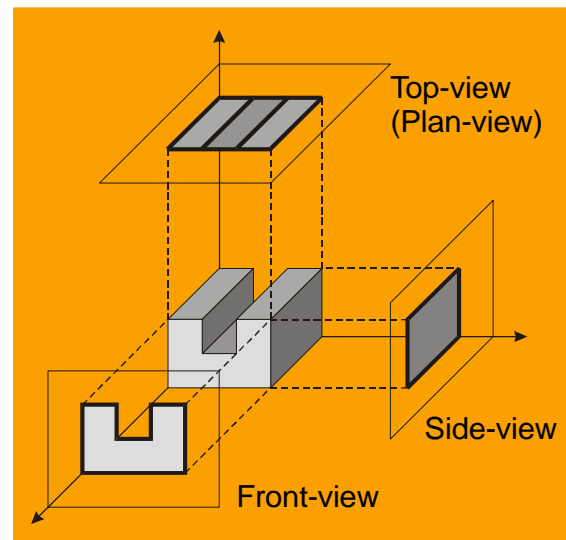
Parallel Projection: Properties

- ▶ **Objects appear at the same size irrespective of distance**
- ▶ **Lines map into lines**
- ▶ **Maintains distances but not angles**
 - Angles only maintained for lines parallel to the viewplane
 - However, parallel lines remain parallel



Parallel Projection: Orthographic

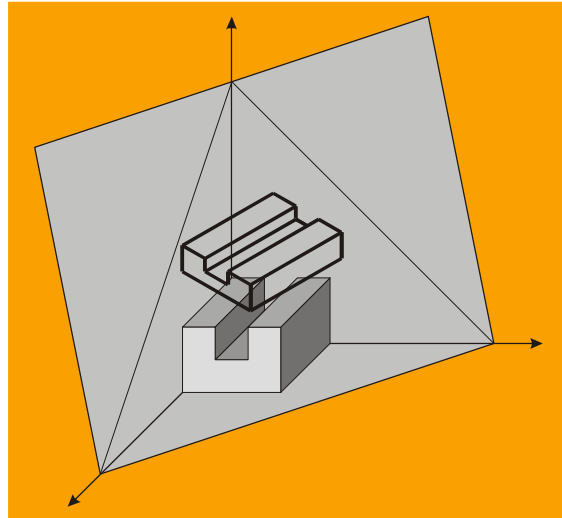
- ▶ **Projectors are perpendicular to the viewplane**
- ▶ **Frequently used orthographic projections have a viewplane perpendicular to a principal axis**
 - front elevation
 - top elevation (plan view)
 - side elevation



Parallel Projection: Orthographic

► **Axonometric orthographic projections have a viewplane that is not perpendicular to a principal axis**

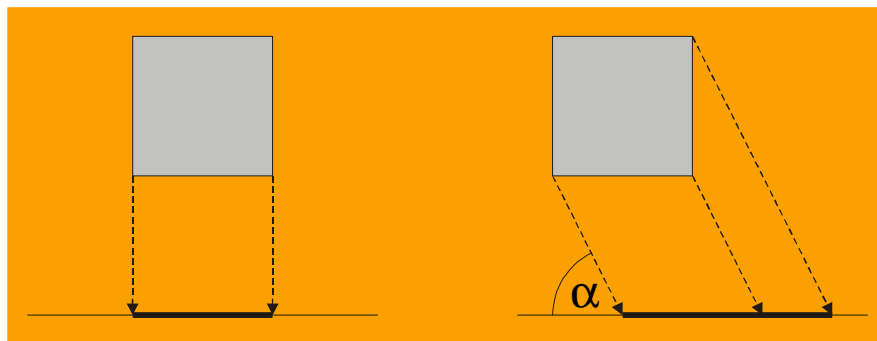
- Show more than one side
- Uniform foreshortening, i.e. unlike perspective projection does not depend on depth of a point
- Isometric projection is an axonometric projection where viewplane has same angle with all axes



Parallel Projection: Oblique

► **Projectors are not perpendicular to the viewplane**

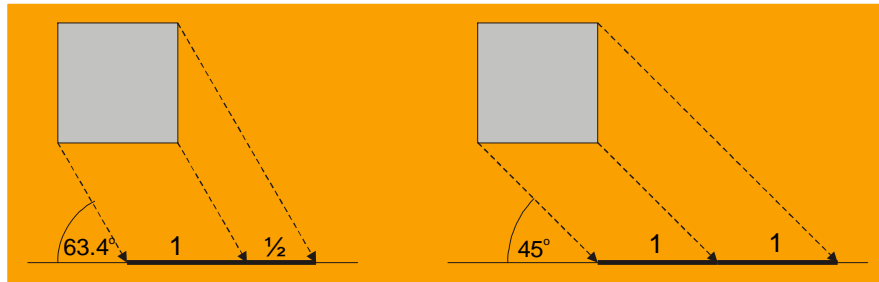
- For viewplane perpendicular to an axis
- Combination of plan-view projection and axonometric projection
- Shows faces parallel to viewplane with proper length and angles
- Uniform foreshortening of faces non-parallel to viewplane



Parallel Projection: Oblique

► Angle between viewplane and projectors determines foreshortening

- 45 degrees: Cavalier projection
 - All axis appear at true length
 - Easy to measure lengths, but looks unrealistic
- 63.4 degrees: Cabinet projection
 - Lines perpendicular to the viewplane are shortened to half length
 - Closer to perspective display



Perspective Projection: Properties

► Distant objects appear smaller than close ones

- Perspective foreshortening

► Lines map into lines

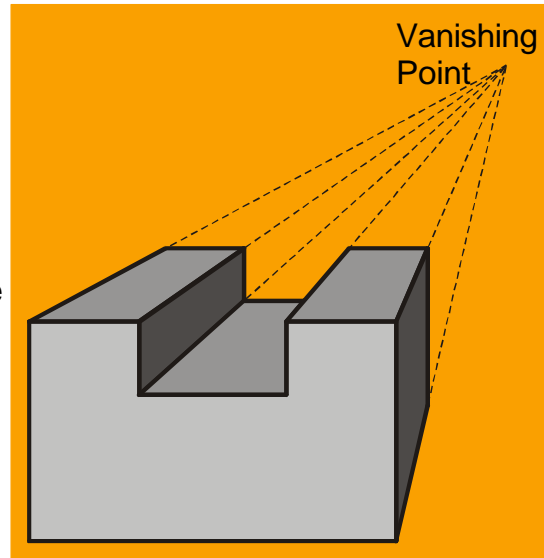
► Distances and angles are not maintained

- In particular parallel lines do not remain parallel
- Angles are maintained only for lines parallel to the view plane



Perspective Projections: Vanishing Points

- ▶ **Parallel lines not parallel to the view plane intersect in a single point: the *vanishing point* for those lines**
 - Vanishing points can be used to construct perspective drawings

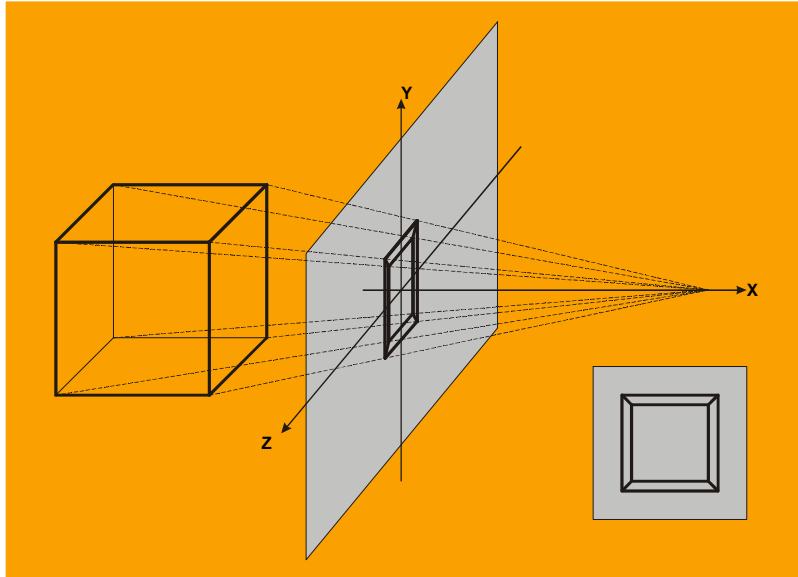


Perspective Projection: Vanishing Points

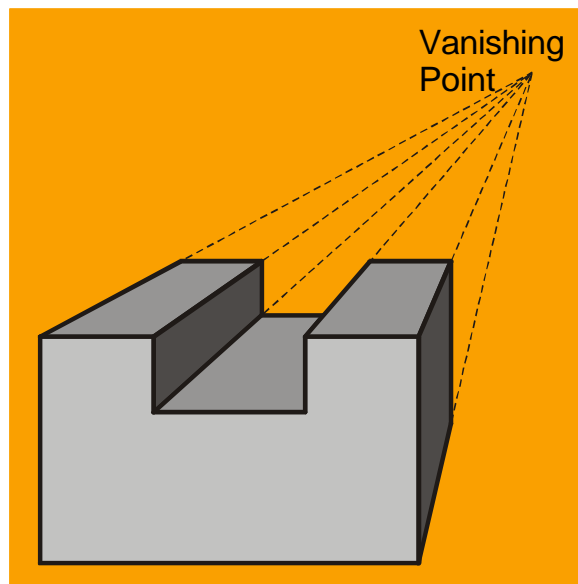
- ▶ **Lines parallel to one of the axes converge in a *principal vanishing point***
- ▶ **Number of principal vanishing points equals the number of axes intersected by the view plane.**
 - In 3D there are up to 3 principal vanishing points.
 - Most frequently used are 1 and 2 vanishing points
 - Three vanishing points add little realism over two vanishing points



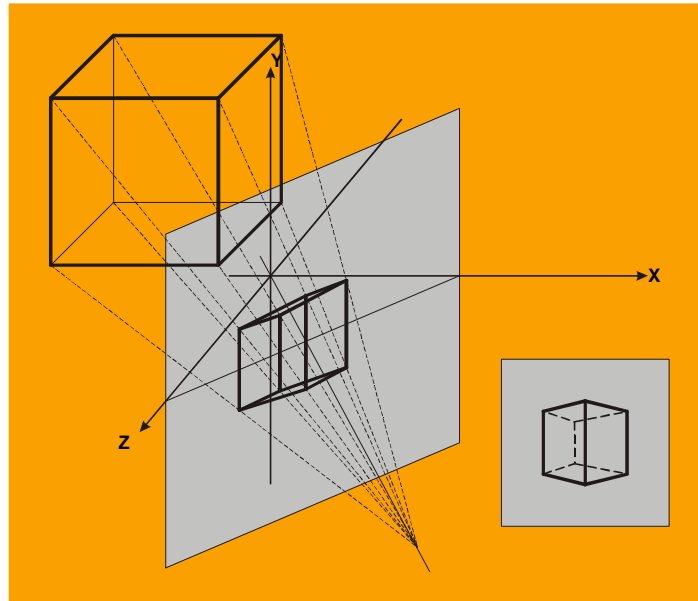
Perspective Projection: One-point Perspective



Perspective Projection: 1 Vanishing Point



Perspective Projection: Two-Point Perspective

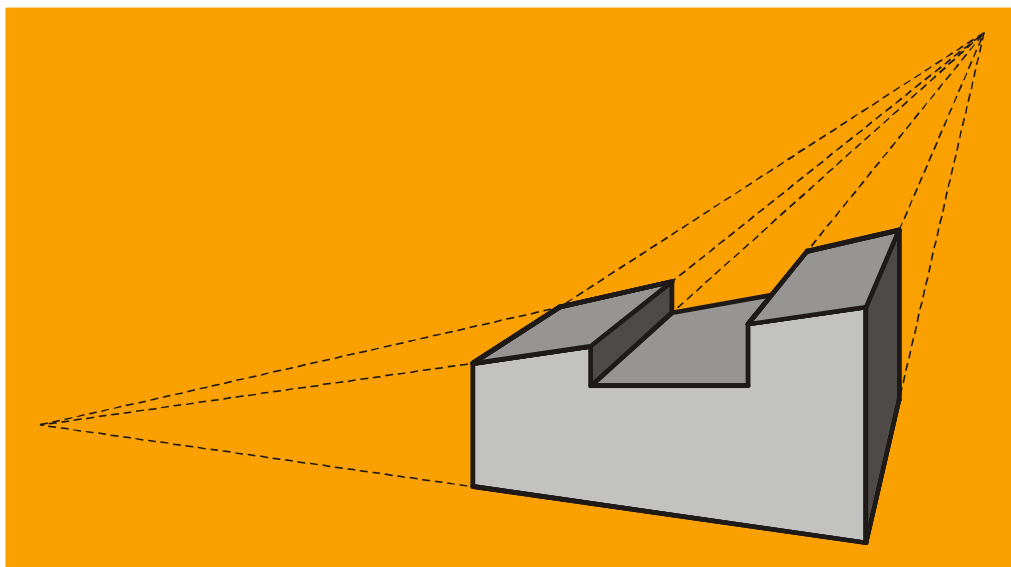


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Perspective Projection: 2 Vanishing Points

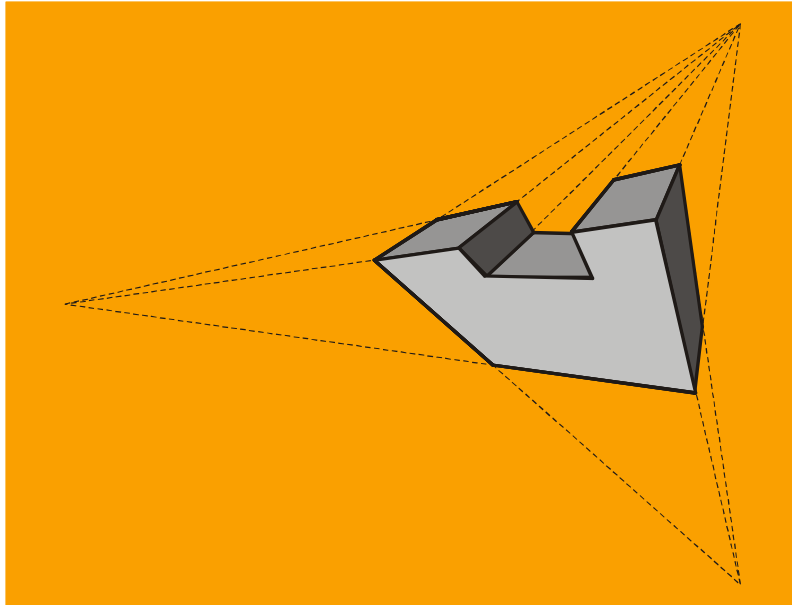


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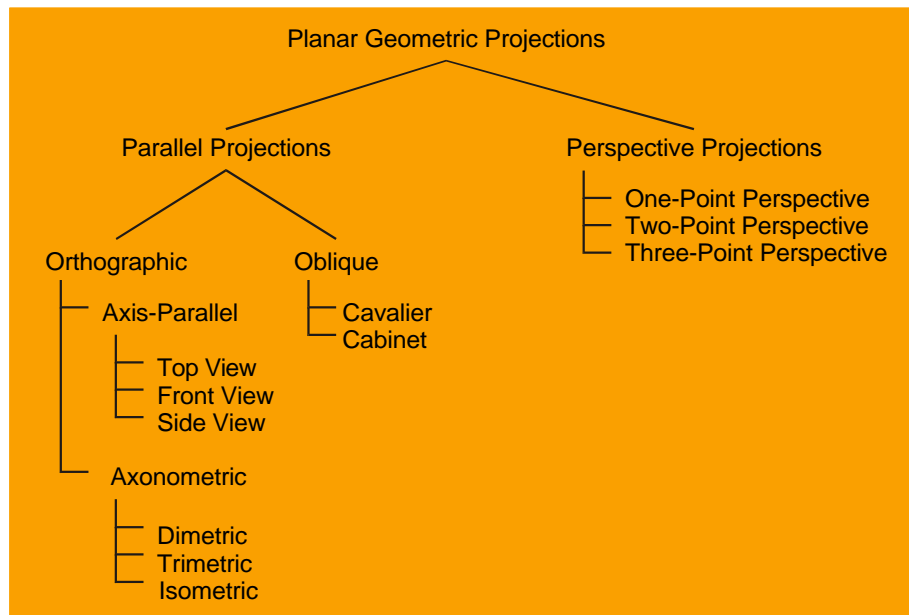


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Perspective Projection: 3 Vanishing Points



Projection Types: Summary



Projections: Mathematical Treatment

► How can we describe all these types of projections ?

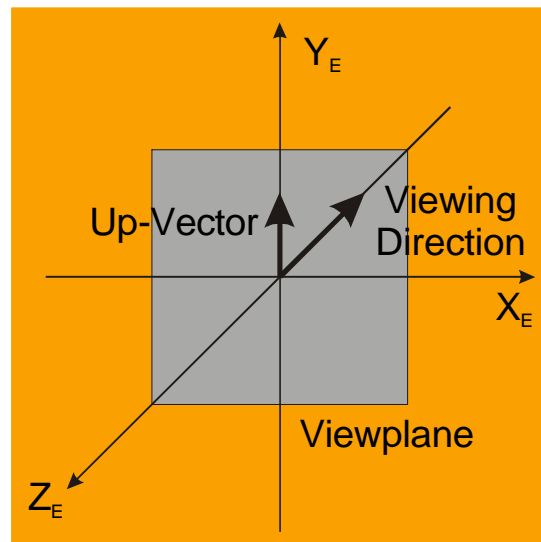
► **Overview:**

- Define a suitable coordinate system
- Compute the mapping of points from 3-space on the viewplane
- Determine matrix form



Projection: Eye Coordinate System

- **Viewplane: $z=0$**
 - Viewing direction down negative z-axis
- **Up vector: y-axis**
- **Project onto $z=0$ plane**



Orthographic Projection

► Projection by "dropping" z-coordinate

$$\mathbf{P}_S = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \cdot \mathbf{P}_E$$
$$\mathbf{P}_S = \mathbf{M}_{OZ} \cdot \mathbf{P}_E$$

► Projection along other axes can be achieved similarly.

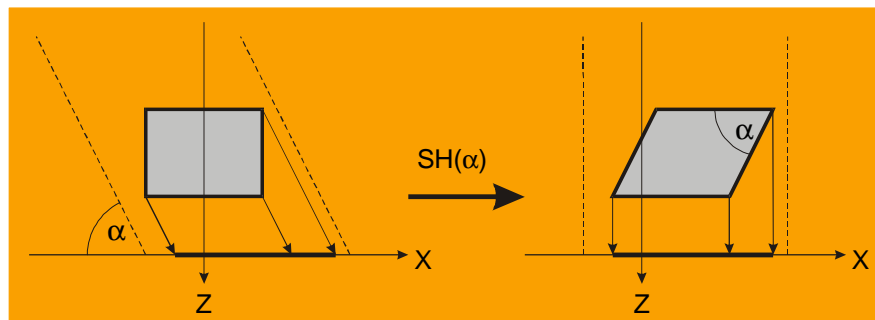
► This matrix will be the final part of all other projections.



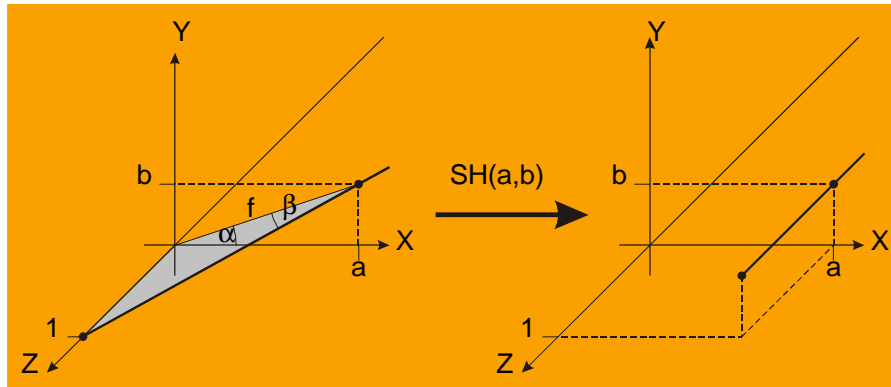
Oblique Projections: 2D Explanation

► Two-step process

- Oblique transformation
- Shear along the x-axis
- Orthographic projection along the z-axis



Oblique Projection: 3D Analysis

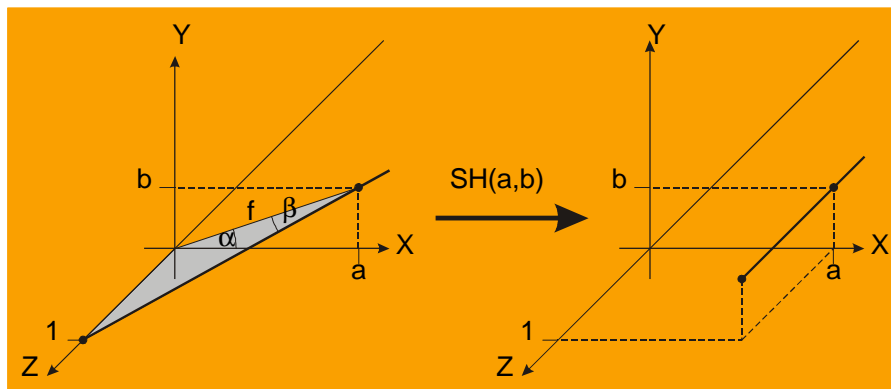


$$\mathbf{P}_s = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & a & 0 \\ 0 & 1 & b & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \cdot \mathbf{P}_E = \begin{pmatrix} 1 & 0 & a & 0 \\ 0 & 1 & b & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \cdot \mathbf{P}_E$$

$$\mathbf{P}_s = \mathbf{SH}(a,b) \cdot \mathbf{M}_{OZ} \cdot \mathbf{P}_E = \mathbf{M}_{ObZ} \cdot \mathbf{P}_E$$



Oblique Projection: 3D Analysis (cont'd)



$f = \cot b$ (Foreshortening factor)

$$\mathbf{M}_{ObZ} = \begin{pmatrix} 1 & 0 & -a & 0 \\ 0 & 1 & -b & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & f \cos a & 0 \\ 0 & 1 & f \sin a & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$



Two-Step Process

- ▶ **The two-step process is also used with other projections, in particular with perspective projection.**
 - First projection *transformation*, i.e. distortion of objects
 - Then, orthographic *projection*
- ▶ **This a typical divide-and-conquer approach**
 - Partition problem into simpler subproblems



Perspective Projection

- ▶ **We will look at a simple and common case**
 - Viewplane at $z = 0$
 - Center of projection at $z = d$
 - This can always be ensured with the appropriate combination of viewing and projection transformations !
- ▶ **Analysis of a general projection**
 - Center of projection off the z-axis
 - Line through center of projection and center of window not perpendicular to viewplane
 - Parallel and perspective projections
 - See Foley et al. or backup charts at the end of this chart set.



Perspective Transformation

$$\frac{x'}{x} = \frac{d}{d-z} ; \frac{y'}{y} = \frac{d}{d-z}$$

⇔

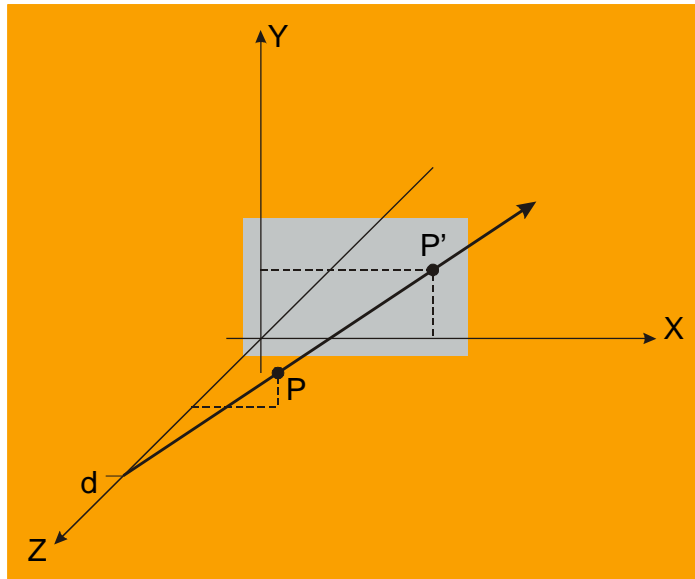
$$x' = \frac{x}{1-z/d} ; y' = \frac{y}{1-z/d}$$

By analogy we define

$$z' = \frac{z}{1-z/d}$$

$$\mathbf{P}' = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1/d & 1 \end{pmatrix} \cdot \mathbf{P}$$

$$\mathbf{P}' = \mathbf{M}_{\text{PER}} \cdot \mathbf{P}$$



Perspective Projection

- Perform orthographic projection after perspective transformation

$$\mathbf{P}' = \mathbf{M}_{\text{Oz}} \cdot \mathbf{M}_{\text{PER}} \cdot \mathbf{P} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1/d & 1 \end{pmatrix} \cdot \mathbf{P} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & -1/d & 1 \end{pmatrix} \cdot \mathbf{P}$$



Perspective Projection: Vanishing Points

► Mapping of points at infinity

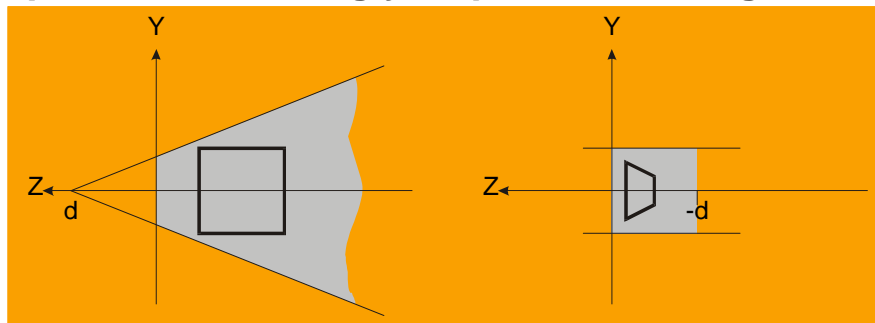
$$\mathbf{VP} = \mathbf{M}_{\text{PER}} \cdot \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1/d & 1 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \\ -1/d \end{pmatrix} \Rightarrow \mathbf{vp} = \begin{pmatrix} 0 \\ 0 \\ -d \end{pmatrix}$$

- Note that the vanishing point for lines parallel to the direction of projection (z-axis) is reflection of the center of projection at the view plane.



Perspective Transformation: Space Distortion

- Remember: Perspective projection is a combination of perspective transformation and orthographic projection
- Distant objects appear smaller
 - Lines along the viewing direction map into parallels to the z-axis.
 - View frustum is transformed into a box
- Space is increasingly "squashed" as z grows.



Perspective Transformation: Coordinate Mapping (1)

► The perspective transformation remaps z !

$$\mathbf{P}' = \mathbf{M}_{\text{PER}} \cdot \mathbf{P} \Leftrightarrow \begin{pmatrix} X' \\ Y' \\ Z' \\ W' \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1/d & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} \Rightarrow \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} X'/W' \\ Y'/W' \\ Z'/W' \end{pmatrix}$$

$$Z' = z, \quad W' = 1 - z/d, \quad z' = \frac{z}{1 - z/d} = \frac{1}{1/z - 1/d}$$

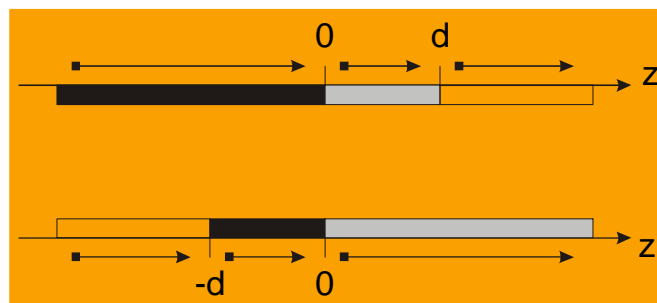
$$z: [-\infty, 0] \rightarrow z': [-d, 0] \quad z: [0, d] \rightarrow z': [0, +\infty] \quad z: [d, +\infty] \rightarrow z': [+ \infty, -d]$$



Perspective Transformation: Coordinate Mapping (2)

► The perspective transformation remaps z !

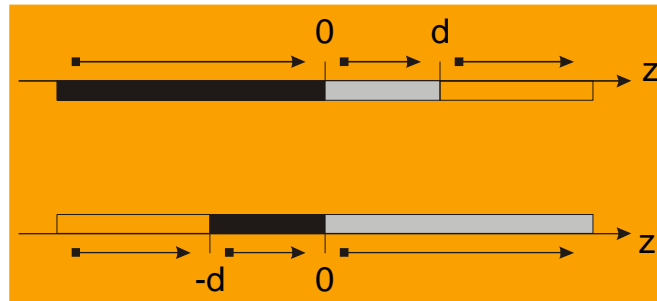
- Points between eye and projection plane ($0 < z < d$) map to behind the eye ($z' > 0$).
- Points beyond the projection plane ($z < 0$) map to $-d < z' < 0$.
- Points behind the eye ($z > d$) map to $z' < -d$.
- Points behind the eye wrap to in front of the eye !!



Perspective Transformation: Coordinate Mapping (3)

► The perspective transformation remaps z !

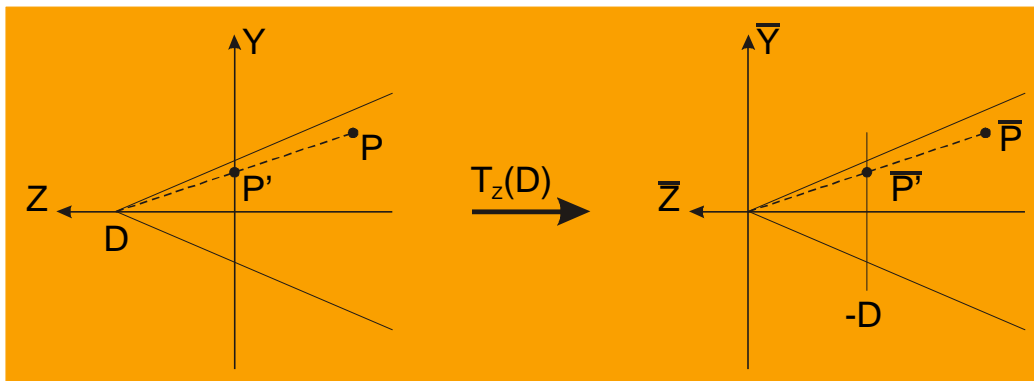
- Objects extending from behind the eye to in front of the eye
- This requires special attention unless any objects (or parts of objects) behind the eye are eliminated, i.e. clipped.
- Therefore, we introduce clip planes to reject points behind the eye.



Perspective Transformation: Viewpoint at the Origin (1)

► Transform coordinate system such, that $z = d$ maps to $z = 0$.

- Translate coordinate system by $+d$ along the z -axis.



Perspective Transformation: Viewpoint at the Origin (2)

- ▶ Transform coordinate system such, that $z = d$ maps to $z = 0$.
 - Translate coordinate system by $+d$ along the z-axis.

$$\tilde{\mathbf{P}}' = \tilde{\mathbf{M}}_{\text{PER}} \cdot \tilde{\mathbf{P}} = \mathbf{M}_{\text{PER}} \cdot \mathbf{T}_z(d) \cdot \mathbf{P}$$
$$\tilde{\mathbf{M}}_{\text{PER}} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1/d & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & d \\ 0 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & d \\ 0 & 0 & -1/d & 0 \end{pmatrix}$$



Clipping

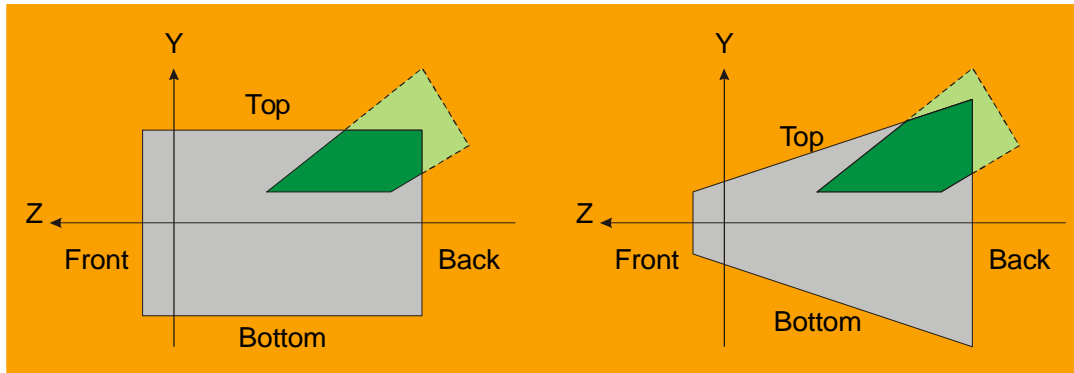
- ▶ Clipping is the process of eliminating parts of the scene outside the view volume.
- ▶ Clipping serves multiple purposes
 - Elimination of "fake" objects, that are wrapped in front of the eye by the perspective transformation.
 - Reduction of geometry that is processed during rasterization.
 - Prevention of numerical problems for objects outside the view volume.
 - Decrease of visual clutter by removal of close and distant objects.
- ▶ The view volume is delimited by clipping planes.
 - Reasonable approximation to human view volume, that is described by overlapping view cones.
 - Matches the view volume of a photographic camera.



Clipping: View Volume

► **Clipping planes define the extent of the view volume.**

- Perspective view volume a.k.a. view frustum
- Front and back clipping planes a.k.a. hither and yon.
- Front and back clipping planes are optional.



Clipping Algorithm

- **Each object must be intersected with each clip plane.**
- **Many objects are delimited by edges or polygons.**

► **Edge-plane intersection:**

- Straight-forward process
- However, intersection of lines with arbitrary planes is compute-intensive.

► **Therefore, we define a *canonical view volume*.**

- Intersection calculations are simplified
- Transformation to the canonical view volume is "free". It can be combined with the viewing transformation



Computing a Canonical View Volume

- ▶ Definition of canonical view volume
- ▶ Transformation of the view volume after viewing transformation into the canonical view volume
- ▶ Process is known as *normalizing* the view volume
 - Coordinates are called Normalized Device Coordinates (NDC)
- ▶ Similar procedure for parallel and perspective projection
 - We will treat them separately



Normalization: Parallel Projection

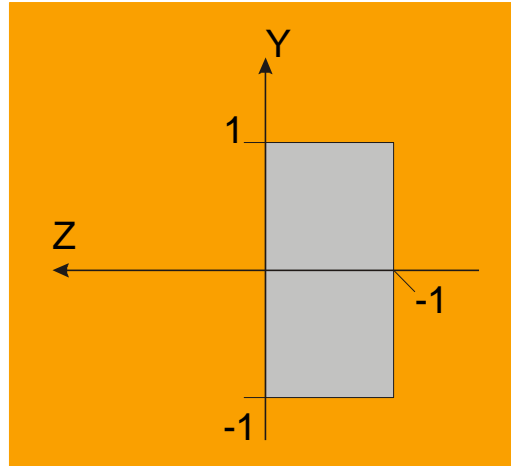


Normalization: Parallel Projection (1)

► Axis-aligned box

- Right, Left $x = +/-1$
- Top, Bottom $y = +/-1$
- Front, Back $z = 0, -1$

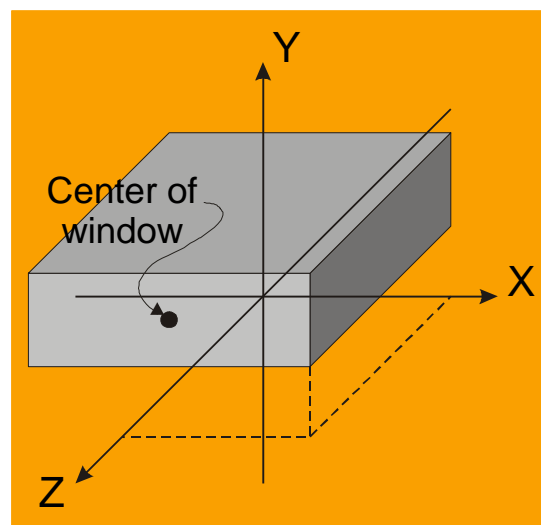
- Much simpler intersection calculations.
- Cost of computing canonical view volume is amortized over many objects.



Normalization: Parallel Projection (2)

► View volume after viewing transformation:

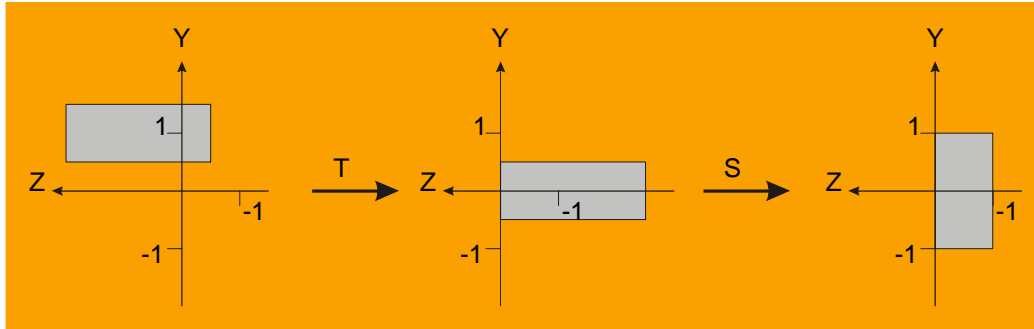
- Viewing direction along negative z-axis
 - Clip planes asymmetric around z-axis and not aligned with $z = 0$.
- ### ► X and Y clipping planes define a *window*.
- Center of the window may be displaced from the origin.
 - Width and height determine the window aspect ratio.
 - The window will eventually get mapped to the viewport.



Normalization: Parallel Projection (3)

► Steps to create the canonical view volume from the view volume after the viewing transformation:

- Translate the view volume such that the front clipping plane lies in the plane $z = 0$.
- Translate and scale such that the other clip planes become the canonical clip planes.



Normalization: Parallel Projection (4)

- Center of window is at $C = (C_x, C_y, C_z)^T$
- Window has the dimensions $W \times H \times D$
- Then we get for the normalization transformation:

$$N_{\text{PAR}} = S \cdot T = \begin{pmatrix} 2/W & 0 & 0 & 0 \\ 0 & 2/H & 0 & 0 \\ 0 & 0 & 1/D & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 0 & -C_x \\ 0 & 1 & 0 & -C_y \\ 0 & 0 & 1 & -C_z \\ 0 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 2/W & 0 & 0 & -2C_x/W \\ 0 & 2/H & 0 & -2C_y/H \\ 0 & 0 & 1/D & -C_z/D \\ 0 & 0 & 0 & 1 \end{pmatrix}$$



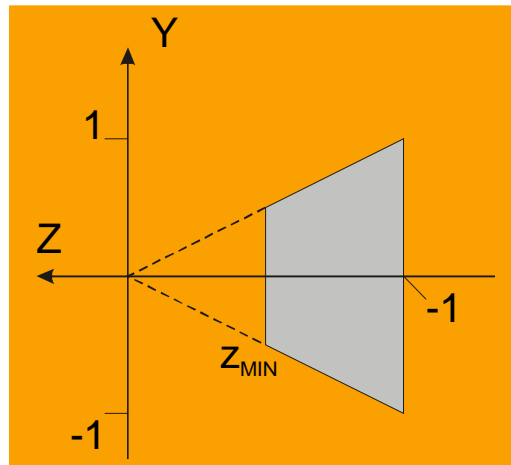
Normalization: Perspective Projection



Normalization: Perspective Projection (1)

► Truncated pyramid with tip at the origin

- Right, Left $x = +/-z$
- Top, Bottom $y = +/-z$
- Front, Back $z = z_{MIN}, -1$



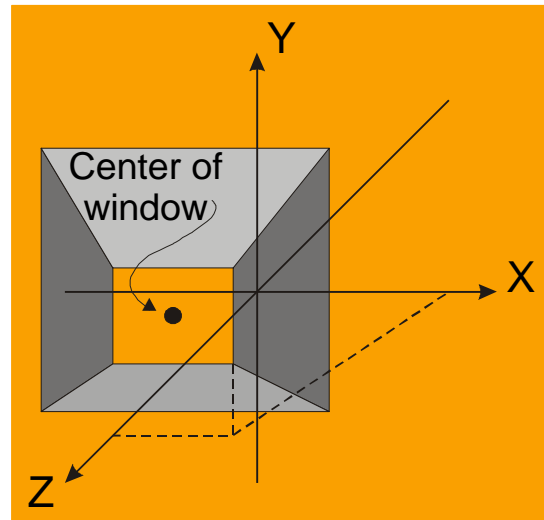
Normalization: Perspective Projection (2)

► View volume after viewing transformation:

- Viewing direction along negative z-axis
- Clip planes asymmetric around z-axis and not aligned with $z = 0$.

► X and Y clipping planes define a *window*.

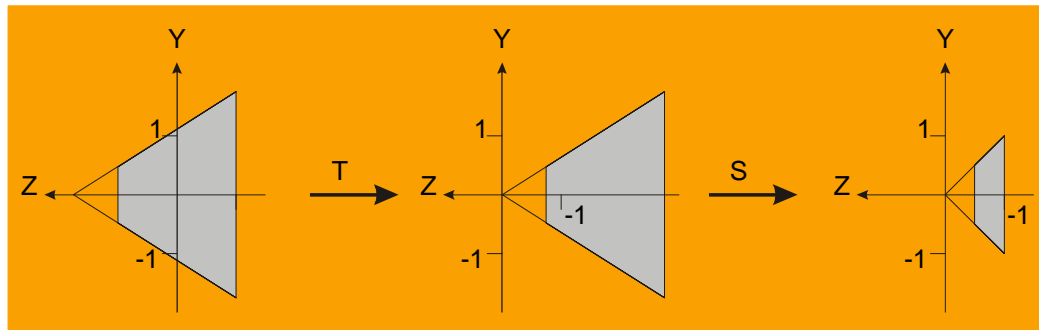
- Center of the window may be displaced from the origin.
- Width and height determine the window aspect ratio.
- The window will eventually get mapped to the viewport.



Normalization: Perspective Projection (3)

► Steps to create the canonical view volume from the view volume after the viewing transformation:

- Translate the view volume such that the center of projection lies at the origin
- Translate and scale such that the other clip planes become the canonical clip planes.



Normalization: Perspective Projection (4)

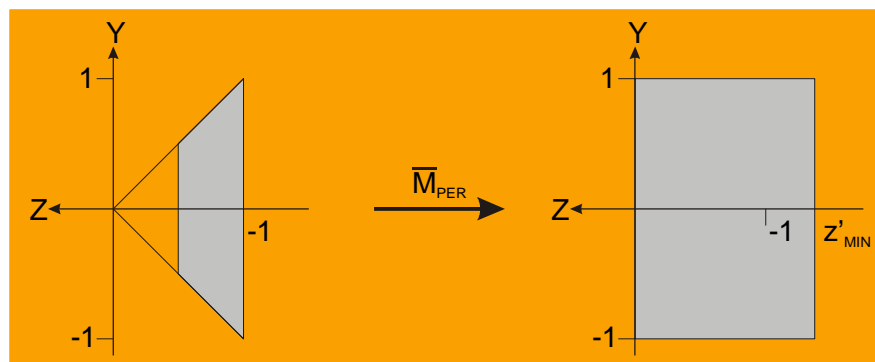
- ▶ Center of projection is at origin
- ▶ Window has the dimensions $W \times H \times D$
- ▶ Then we get for the normalization transformation:

$$N_{\text{PER}} = S \cdot T = \begin{pmatrix} 2/W & 0 & 0 & 0 \\ 0 & 2/H & 0 & 0 \\ 0 & 0 & 1/D & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -d \\ 0 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 2/W & 0 & 0 & 0 \\ 0 & 2/H & 0 & 0 \\ 0 & 0 & 1/D & -d/D \\ 0 & 0 & 0 & 1 \end{pmatrix}$$



Perspective Division (1)

- ▶ After normalization, perspective transformation turns the canonical viewing frustum into a axis-aligned box.
- ▶ We would like to convert that box into the canonical view volume for the parallel projection.
- ▶ First: Compute z'_{MIN} ...



Perspective Division (2)

$$\tilde{M}_{PER} \bullet (\text{CP - top, CP - bot, CP - front, CP - back}) \quad \text{for } d = 1$$

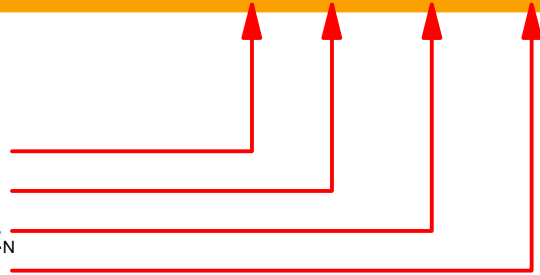
$$= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & -1 & 0 \end{pmatrix} \bullet \begin{pmatrix} x & x & x & x \\ -z & z & y & y \\ z & z & z_{MIN} & -1 \\ 1 & 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} x & x & x & x \\ -z & z & y & y \\ z+1 & z+1 & z_{MIN}+1 & 0 \\ -z & -z & -z_{MIN} & 1 \end{pmatrix}$$

Top: $y = 1$

Bottom: $y = -1$

Front: $z = -(z_N+1)/z_N$

Back: $z = 0$



Perspective Division (3)

► **No adjustment of necessary for X and Y dimensions**

► **Z dimension:**

- Near clip plane farther from viewer than far clip plan
- Z orientation reversed

● Depth range not 0 ... -1

■ $-(z_{MIN}+1)/z_{MIN} = -1 - 1/z_{MIN} < -1$ for $0 > z_{MIN} > -1$

► **Steps:**

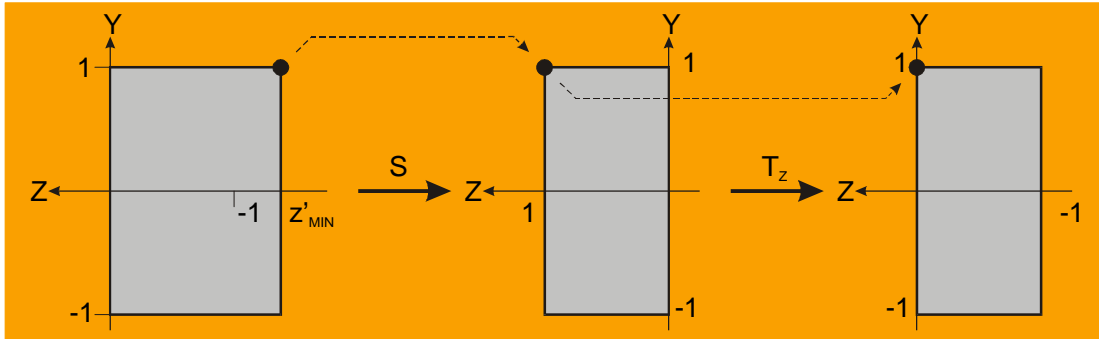
- Reverse orientation by reflection on $z=0$ and scale to depth = 1
- Transform so that near clip plane maps to $z=0$



Perspective Division (4)

$$\mathbf{M} = \mathbf{T}_Z \cdot \mathbf{S} \cdot \tilde{\mathbf{M}}_{\text{PER}}$$

$$= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{z_{\text{MIN}}}{z_{\text{MIN}} + 1} & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & -1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{1}{z_{\text{MIN}} + 1} & \frac{-z_{\text{MIN}}}{z_{\text{MIN}} + 1} \\ 0 & 0 & -1 & 0 \end{pmatrix}$$



Viewport Mapping (1)

- ▶ Now both, parallel and perspective transformation have yielded the same normalized view volume.
- ▶ Final step: Map the normalized device coordinates to screen coordinates
- ▶ **Terminology** (to be consistent with the textbook)
 - Window: Rectangle in World-coordinates describing (together with the projection) which objects are visible
 - Do not confuse with on-screen windows, managed by the window manager !!!
 - Viewport: On-screen rectangle describing where the image will appear on the screen



Viewport Mapping (2)

▶ **Window in world coordinates:**

- Width W_w and Height H_w
- Aspect ratio $A_w = W_w / H_w$

▶ **Viewport in screen coordinates:**

- Width W_v and Height H_v
- Aspect ratio $A_v = W_v / H_v$

▶ **Window aspect ratio should be maintained**

▶ **If the aspect ratios are not equal, several choices**

- Fit the window into the viewport, leaving part of the viewport empty
- Fill the the viewport, clipping off parts of the window



Viewport Mapping (3)

▶ **Transformation to the canonical view volume has destroyed the window aspect ratio (now: unit square)**

▶ **Window aspect ratio can be restored by non-uniform scaling of the unit square.**

▶ **Steps:**

- Restore window aspect ratio (normalized device coordinates)
- Compare with viewport aspect ratio
- Determine appropriate scale factor (device coordinates)
- Translate adjusted window to viewport



Viewport Mapping (4)

- ▶ Assuming that $A_w > 1$ and that $W_v/W_w < H_v/H_w$
 - Center of viewport at (v_x, v_y)

$$M_{NV} = T \cdot S_v \cdot S_N = \begin{pmatrix} 1 & 0 & v_x \\ 0 & 1 & v_y \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} W_v / W_w & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 / A_w & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} W_v / W_w & 0 & v_x \\ 0 & 1 / A_w & v_y \\ 0 & 0 & 1 \end{pmatrix}$$

- ▶ Sometimes screen coordinates are left-handed coordinate systems, e.g. origin at top-right corner and z-axis pointing out of the screen.
 - Then the y-axis must be reflected during the viewport mapping.



That's basically it !

- ▶ To summarize ...



Modeling and Viewing

► Modeling

- Transforms objects from local model coordinates to world coordinates
- Typically done with linear transformations

► Viewing

- Places and orients the camera in world coordinates
- Look down negative z-axis of EC
- Up vector along y-axis of EC



Clipping

- Clip planes define a view volume
- Clipping intersects objects with view frustum
- Clipping occurs in normalized device coordinates
- Canonical view volume is delimited by planes parallel or at 45° angle to coordinate axes
- Canonical view volume facilitates clipping



Projection and Viewport Mapping

► Perspective Transformation

- Distort objects such that view volume becomes a rectilinear box
- Remap the transformed the perspective canonical view volume into the parallel canonical view volume.

► Parallel Projection

- "Drop" the z-coordinate, i.e. project onto $z=0$.

► Viewport Mapping

- Map the projected scene from normalized device coordinates to screen coordinates
- Map the projected scene from normalized device coordinates to screen coordinates

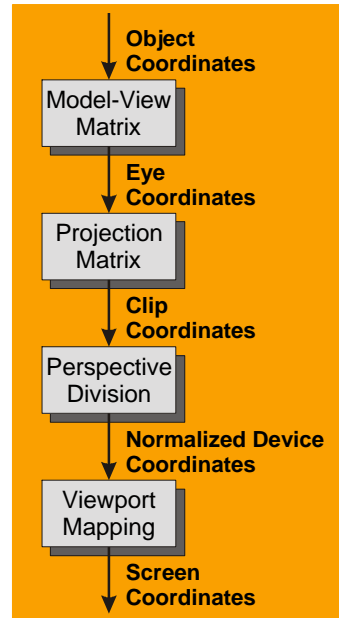


OpenGL



OpenGL: Rendering Pipeline

- ▶ Very similar to our discussion of the various transformations
- ▶ Single step for modeling + viewing transformation
 - World coordinates are not explicitly specified
- ▶ Projection Matrix creates canonical view volume



OpenGL: Viewing Transformation

- ▶ All modeling transformations
 - `glRotate()`, `glTranslate()`, `glScale()`, `glLoadMatrix()`, ...
- ▶ `gluLookAt()`
 - Specifies in current coordinate system: viewpoint, look-at point and up-vector
 - Viewpoint and Look-at point specify viewing direction
 - Can be re-implemented using standard modeling transformations



OpenGL: Projections

▶ glOrtho()

- Specifies orthographic view volume, delimited by 6 clip planes

▶ glFrustum()

- Specifies perspective view volume as the position and size of the near clip window (and implicitly the viewpoint).

▶ gluPerspective()

- Wrapper around glFrustum() to more conveniently define a perspective view volume based on ...
- field of view and aspect ratio of the view volume
- distance of the near and far clip planes



Summary

▶ Mathematical description of

- Viewing Transformations
- Clipping Volume
- Projections (parallel and perspective)
- Viewport mapping



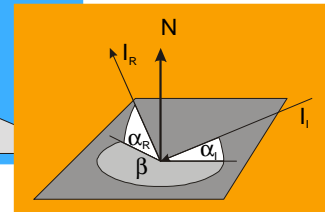
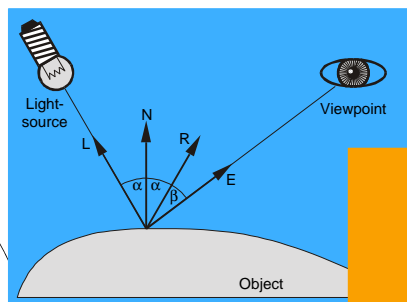
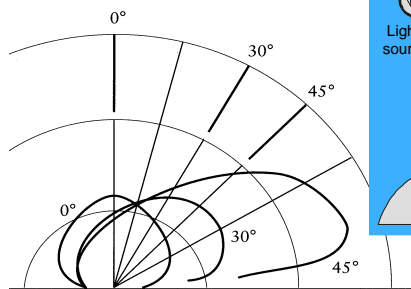
Homework

- ▶ OpenGL rendering primitives
- ▶ Foley et al. Chapter 16



Next Week ...

- ▶ Lighting Models



$$I = k_A \cdot I_A + k_D \cdot \sum_{i=0}^l I_i \cdot (\mathbf{N} \cdot \mathbf{L}_i) + k_S \cdot \sum_{i=0}^l I_i (\mathbf{R} \cdot \mathbf{E})^n$$



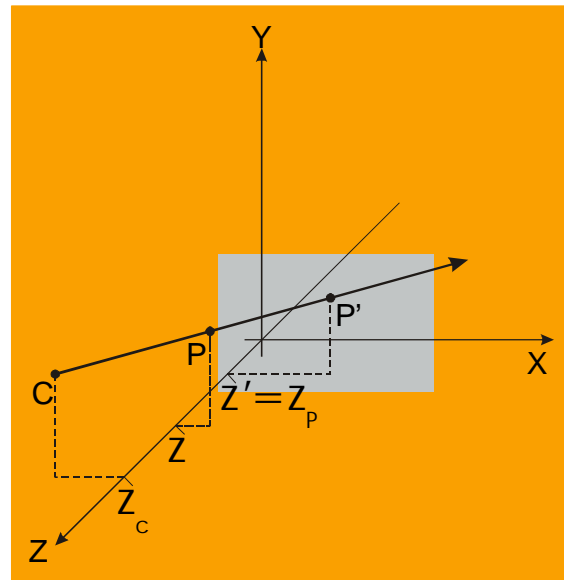
Backup Charts

► General Projection



Projection: General Case (1)

- Viewplane at $z=z_p$
- Center of projection C off the z -axis



Projection: General Case (2)

$$P' = C + I(P - C) \quad ; \quad z' = z_P$$

⇒

$$z' = z_P = z_C + I(z - z_C)$$

⇒

$$I = \frac{z_P - z_C}{z - z_C} \quad ; \quad \Lambda = 1/I = \frac{z - z_C}{z_P - z_C}$$

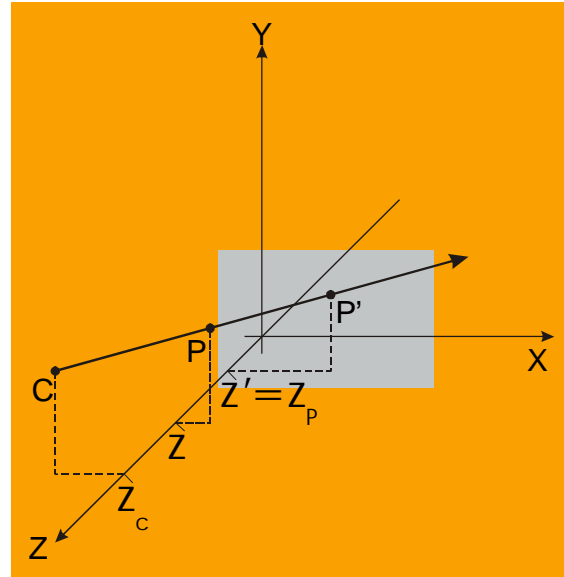
⇒

$$x' = x_C + I(x - x_C)$$

$$= x_C \frac{\Lambda}{\Lambda} + \frac{x - x_C}{\Lambda} = \frac{x + x_C(\Lambda - 1)}{\Lambda}$$

$$= \frac{x + x_C \frac{z - z_P}{z_P - z_C}}{\Lambda} = \frac{x + z \frac{x_C}{z_P - z_C} - \frac{x_C \cdot z_P}{z_P - z_C}}{\Lambda}$$

$$y' = \frac{y + z \frac{y_C}{z_P - z_C} - \frac{y_C \cdot z_P}{z_P - z_C}}{\Lambda}$$



Projection: General Case (3)

$$x' = \frac{1}{\Lambda} \cdot \left(x + z \frac{x_C}{z_P - z_C} - \frac{x_C \cdot z_P}{z_P - z_C} \right)$$

$$y' = \frac{1}{\Lambda} \cdot \left(y + z \frac{y_C}{z_P - z_C} - \frac{y_C \cdot z_P}{z_P - z_C} \right)$$

$$z' = z_P = z_P \frac{\Lambda}{\Lambda} = \frac{1}{\Lambda} \cdot z_P \frac{z - z_C}{z_P - z_C}$$

$$= \frac{1}{\Lambda} \cdot \left(z \frac{z_P}{z_P - z_C} - \frac{z_P \cdot z_C}{z_P - z_C} \right)$$

$$w' = \Lambda = \frac{z}{z_P - z_C} - \frac{z_C}{z_P - z_C}$$

$$P' = \begin{pmatrix} 1 & 0 & \frac{x_C}{z_P - z_C} & -x_C \frac{z_P}{z_P - z_C} \\ 0 & 1 & \frac{y_C}{z_P - z_C} & -y_C \frac{z_P}{z_P - z_C} \\ 0 & 0 & \frac{z_P}{z_P - z_C} & -z_C \frac{z_P}{z_P - z_C} \\ 0 & 0 & \frac{1}{z_P - z_C} & -\frac{z_C}{z_P - z_C} \end{pmatrix} \cdot P$$

$$= \begin{pmatrix} 1 & 0 & x_C / d & -x_C \cdot z_P / d \\ 0 & 1 & y_C / d & -y_C \cdot z_P / d \\ 0 & 0 & x_P / d & -z_C \cdot z_P / d \\ 0 & 0 & 1 / d & -z_C / d \end{pmatrix} \cdot P$$

$$P' = P_{\text{per}} \cdot P$$



Projection: General Case (4)

$$\mathbf{P}' = \mathbf{P}_{\text{per}} \cdot \mathbf{P} = \begin{pmatrix} 1 & 0 & x_C / d & -x_C \cdot z_P / d \\ 0 & 1 & y_C / d & -y_C \cdot z_P / d \\ 0 & 0 & x_P / d & -z_C \cdot z_P / d \\ 0 & 0 & 1 / d & -z_C / d \end{pmatrix} \cdot \mathbf{P}$$

Orthographic Projection: $z_P = 0$, $C = \lim_{z \rightarrow \infty} (0 \ 0 \ z)$

Cavalier Projection: $z_P = 0$, $C = \lim_{z \rightarrow \infty} (z \ 0 \ z)$

Perspective Projection: $z_P = 0$, $C = (0 \ 0 \ d)$



Perspective Transformation: Clip Planes

- How are the clip planes transformed by the perspective transformation ?

Back CP Front CP Bottom CP Top CP

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1/d & 1 \end{pmatrix} \cdot \begin{pmatrix} x & x & x & x \\ y & y & -a \cdot (z-d) & a \cdot (z-d) \\ z_F & z_B & z & z \\ 1 & 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} x & x & x & x \\ y & y & -a \cdot (z-d) & a \cdot (z-d) \\ z_F & z_B & z & z \\ 1 - \frac{z_F}{d} & 1 - \frac{z_B}{d} & 1 - \frac{z}{d} & 1 - \frac{z}{d} \end{pmatrix}$$



Perspective Transformation: Clip Planes

- ▶ Plane at $y = y'_B$
- ▶ Plane at $y = y'_T$
- ▶ Plane at $z = z'_B$
- ▶ Plane at $z = z'_F$

$$\begin{pmatrix} \frac{x \cdot d}{d - z_F} & \frac{x \cdot d}{d - z_B} & \frac{x \cdot d}{d - z} & \frac{x \cdot d}{d - z} \\ \frac{y \cdot d}{d - z_F} & \frac{y \cdot d}{d - z_B} & -a \cdot d \cdot (z - d) & a \cdot d \cdot (z - d) \\ \frac{z_F \cdot d}{d - z_F} & \frac{z_B \cdot d}{d - z_B} & \frac{z \cdot d}{d - z} & \frac{z \cdot d}{d - z} \end{pmatrix} = \begin{pmatrix} x' & x' & x' & x' \\ y' & y' & y'_T & y'_B \\ z'_F & z'_B & z' & z' \end{pmatrix}$$

