## Distributed Systems [Fall 2013]

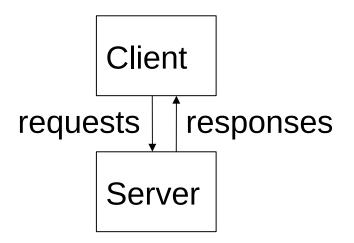
Lec 3: Example use cases (continued) Cloud computing

#### **Example Use Cases**

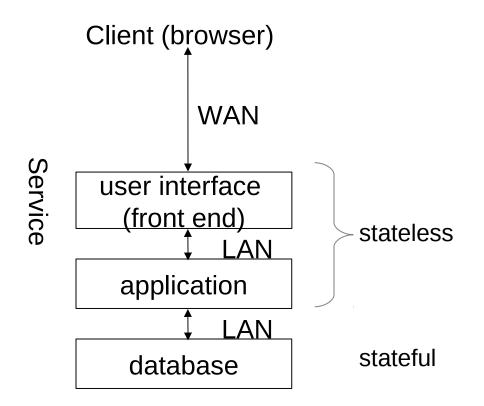
- Web architectures (last time)
  - Simple architectures and real-world architectures
- Cloud computing (today)
  - What it means and how it began

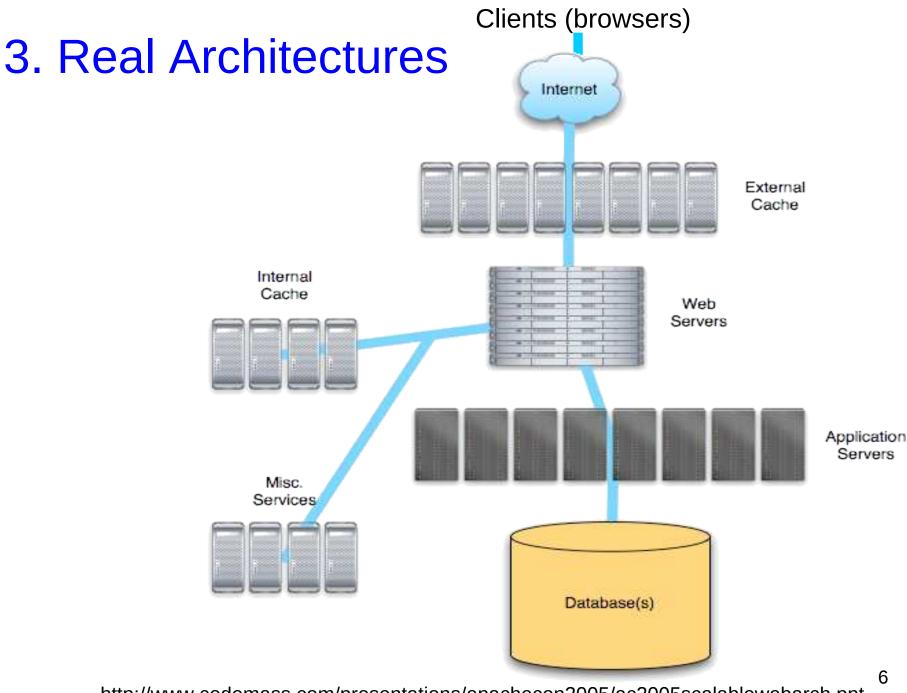
#### What Are Some Web Architectures?

#### 1. The Client-Server Model



#### 2. The Three-Tiered Architecture





http://www.codemass.com/presentations/apachecon2005/ac2005scalablewebarch.ppt

## So, What Did We Learn?

- Web architectures are complex
- But there are well-known solutions
- There are lots of tradeoffs and understanding workload is key in choosing the right solution at each layer
- Each layer has distinct hardware requirements and likely distinct bottlenecks
- What does the last observation tell us?

#### **Example Use Cases**

- Web architectures (last time)
  - Simple architectures and real-world architectures
- Cloud computing (today)
  - What it means and how it began

# What is cloud computing?

- Computing technology in which data and/or computation are outsourced to a massive-scale, multi-user infrastructure that is managed by a third-party.
- Appeared gradually due to two important challenges facing the Web:
  - Scaling
  - Management
- I'll tell you the story of <u>how it appeared</u>, so as to help you understand <u>what it is</u>

# Around 1995: The Scaling Challenge

• The Web and e-commerce were gaining traction



- Their challenge: how to scale?
  - 1996 to 1997: eBay grew from 41,000 to 341,000 users!

# Pre-1995 Answer: Big, Expensive Computers

- Example: eBay used Sun E-10000 "supermini"
  - 64 processors @250MHz, 64GB RAM, 20TB disk, ~\$1M
- The good:
  - Easy to manage
  - Easy to program
  - Simple failure mode
- The bad:
  - Q: Any ideas?



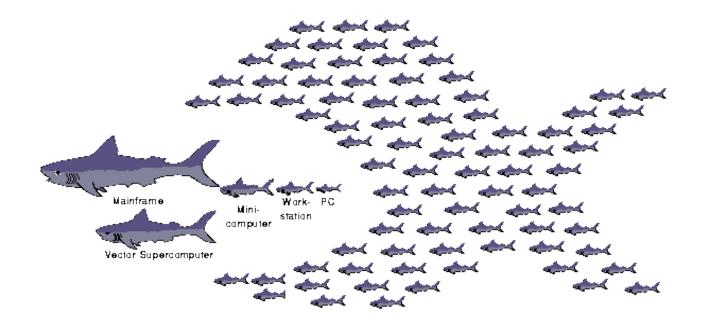
# Pre-1995 Answer: Big, Expensive Computers

- Example: eBay used Sun E-10000 "supermini"
  - 64 processors @250MHz, 64GB RAM, 20TB disk, ~\$1M
- The good:
  - Easy to manage
  - Easy to program
  - Simple failure mode
- The bad:
  - Expensive
  - Single point of failure
  - No incremental scalability



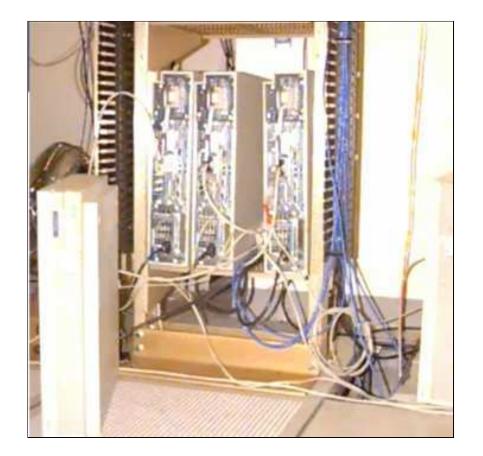
# 1995: Berkeley Network of Workstations (NOW)

- Idea: Leverage many interconnected small, cheap, general-purpose machines for incremental scalability and reliability
  - Typical PC: 200 MHz CPU, 32MB RAM, 4GB disk



#### NOW-0

• 1994: NOW had 4 HP-735's



#### NOW-1

• 1995: NOW had 32 Sun SPARC stations



#### NOW-2

- 1997: 60 Sun SPARC-2's
- Build Inktomi app



# **Companies Adopt NOW**

- Everybody builds their own clusters and grows them to handle more and more load
  - Examples: eBay, Amazon, Google, all .com bubble companies
- Similar to early days of electricity when everyone built their own generator

Q: What do you think happened next?

# Late 1990s: The Manageability Challenge

- Hard to manage and program large clusters
  - How to write scalable distributed programs?
  - How to debug large-scale programs?
  - How to make services reliable?
  - How to architect the network infrastructure?
  - How to provision a cluster to handle peak load?
  - How to administer a huge number of computers?

- Each company had to build own complex software
  - Like each of us building an OS from scratch!

# Early 2000s: Scalable Cluster Primitives

- Very few technically strong companies create powerful scalable and reliable primitives for cluster management and programming
- Examples:
  - Google's Map/Reduce
  - The Google File System (GFS)
  - Google's Bigtable
  - Amazon's Dynamo
  - Distributed debugging and tracing tools
  - Datacenter temperature regulators
  - Scalable distributed communication mechanisms

# Mid 2000s: Three Valuable Commodities

- Giant-scale clusters with enormous excess capacity
  - Everybody provisioned for peak

Q: How big was a typical Google datacenter around 2005? a. 1,000 machines b. 5,000 machines c. 10,000 machines d. 50,000 machines e. 100,000 machines

# Mid 2000s: Three Valuable Commodities

- Giant-scale clusters with enormous excess capacity
  - Everybody provisioned for peak
- Expertise for managing and operating clusters at low cost
  - "Economies of scale"
- Complex software to help program/manage clusters
  - Even full applications (e.g., Gmail, Google Calendar, etc.)

#### Q: What do you think happened next?

# 2006: Cloud computing

- AWS sells resources, expertise, and access to cloud primitives in a pay-for-what-you-use model
  - Resources: CPU, network bandwidth, persistent storage
  - Cloud primitives: Amazon S3, EC2, SQS, Map/Reduce, ...
- Google launches Google Apps for Your Domain
  - Customizable Gmail, Google Docs, Google Calendar under a custom domain (e.g., gmail.cs.columbia.edu)
- Google then launches the App Engine
  - Web hosting infrastructure (such infrastructures existed before, but didn't come with many primitives)
- Microsoft launches Azure in 2009

# Advantages of cloud computing

- Low barrier of market entry for startups
- Cheaper, low-management email, calendars, CRM solutions
- New mobile applications
- Faster batch processing via parallelization across many machines

# What do Clouds have to do w/ distributed systems?

- Clouds are powered by (and sell) distributed, scalable systems, which can be used as building blocks for easy bootstrap of new applications and services
  - Often times, you hear about clouds as being great because you don't have to purchase machines upfront
  - I think their major advantage lies in fact in the scalable services they provide
- This is unlike prior Web hosting infrastructures that predated "clouds" by many years
  - Those offered (and some still do) bare-metal and no add-on value-added services

## Next time

- Communication: remote procedure calls
- Homework 1 is due tomorrow
- Homework 2 will be out on Thursday
  - Start with the writing piece and then do the coding
  - It's long, so start coding soon
  - Next time TA will go over the YFS series

Distributed Systems [Fall 2012]

Lec 3 (Part 2): OS Background Processes, Threads, and Local Coordination

# **OS Background**

- Topics:
  - Processes
  - Threads
  - Local coordination
    - Inter-process communication (or how processes coordinate)
    - Thread synchronization (or how threads coordinate)
- Is this an OS course?!
  - No, but concepts are essential for distributed systems
  - They often have 1:1 relationships with distributed coordination concepts

# Outline

- Processes
- Inter-process communication (IPC)
- Threads
- Thread synchronization

- Slide acknowledgements:
  - Junfeng Yang (www.cs.columbia.edu/~junfeng/12sp-w4118/lectures/I04-proc.pdf)
  - Dave Andersen (www.cs.cmu.edu/~dga/15-440/F10/lectures/04-work.pdf)
  - Jinyang Li (www.news.cs.nyu.edu/~jinyang/fa09/notes/ds-lec2.pdf)

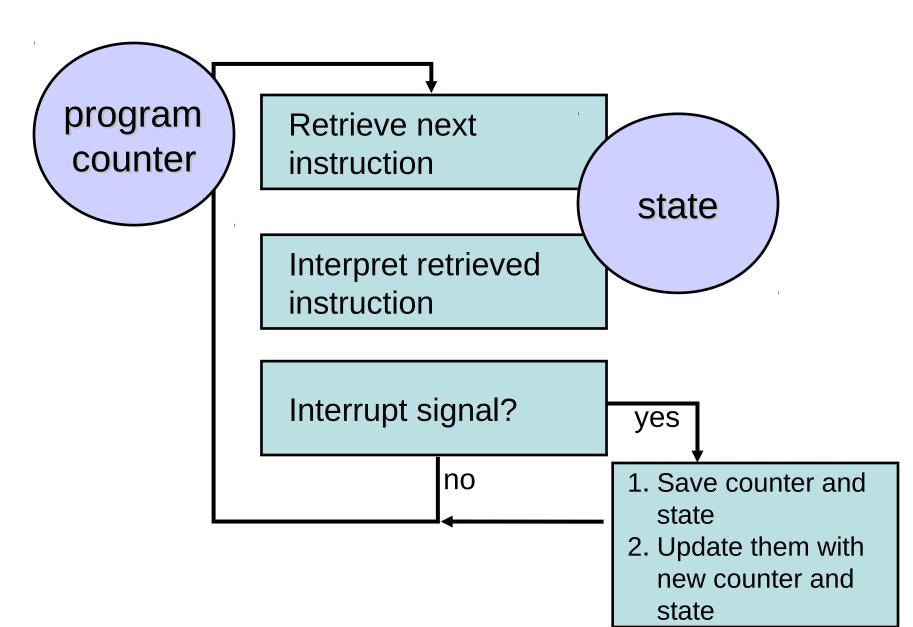
#### What Is a Process?

- Process: an execution stream (or program) in the context of a particular process state
  - "Program in execution," "virtual CPU"
- Execution stream: a stream of instructions
- Process state: determines effect of running code
  - Registers: general purpose, instruction pointer (program counter), floating point, …
  - Memory: everything a process can address, code, data, stack, heap, ...
  - I/O status: file descriptor table, ...

#### Program vs. Process

- Program != process
  - Program: static code + static data
  - Process: dynamic instantiation of code + data + more
- Program ⇔ process: no 1:1 mapping
  - Process > program: more than code and data
  - Program > process: one program runs many processes
  - Process > program: many processes of same program

#### The CPU



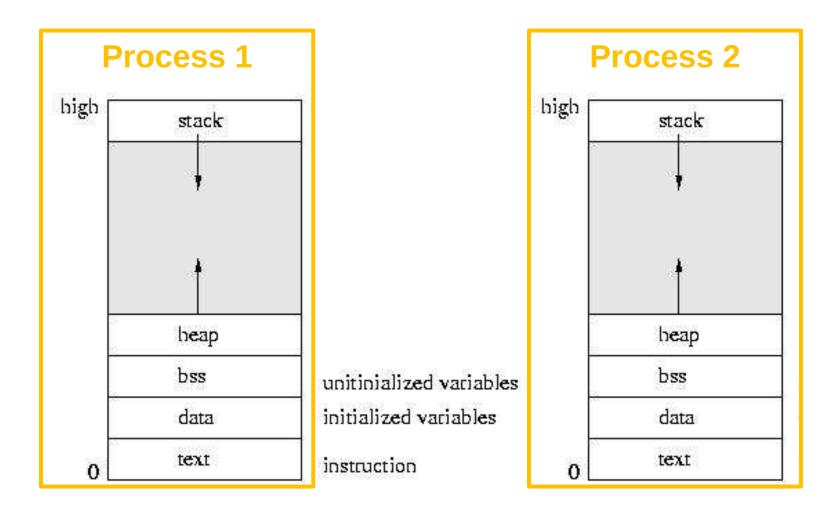
# Why Use Processes?

- Express concurrency
  - Systems have many concurrent jobs going on
  - E.g. Apache can spawn multiple processes to process requests in parallel on multiple CPUs and parallelize I/O...
  - OS manages concurrency
- General principle of divide and conquer
  - Decompose a large problem into smaller ones easier to think of well contained smaller problems
- Processes are isolated from each other
  - Sequential with well defined interactions

#### **Address Spaces**

- Address Space (AS): all memory a process can address
  - Really large memory to use
  - Linear array of bytes: [0, N), N roughly 2<sup>32</sup> / 2<sup>64</sup>
- Process \Leftharpoint address space: 1:1 mapping
   Address space = protection domain
- OS isolates address spaces
  - One process can't access another's address space
  - Same pointer address in different processes point to different memory

#### **Address Space Illustration**



#### **Practical Stuff: Using Processes**

- Creating a new process: fork()
  - Makes an almost exact copy of calling process (PID changes, etc.)
  - New process has its own memory (although some of it is shared – copy-on-write)
  - How to tell difference between the two processes?
     Return value is 0 in child, child PID in parent.
- Executing a different *program*: exec()
  - Replaces the process' image with a new one running the new program

#### Example: Fork/Exec

```
#include <iostream>
#include <sys/wait.h>
#include <unistd.h>
using namespace std;
int main() {
 pid_t pid;
 int status, died;
 switch (pid = fork()) {
  case -1: cout << "can't fork\n";
            exit(-1);
  case 0 : execl("/usr/bin/date","date",0); // this is the code the child runs
  default: died= wait(&status); // this is the code the parent runs
```

#### Outline

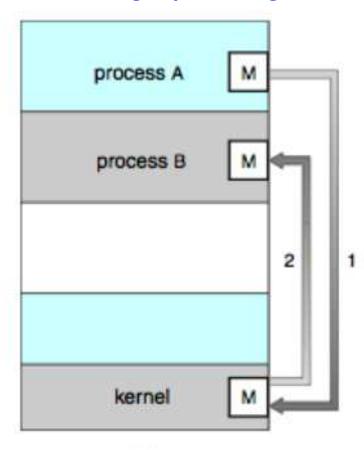
- Processes
- Inter-process communication (IPC)
- Threads
- Thread synchronization

#### **Interprocess Communication**

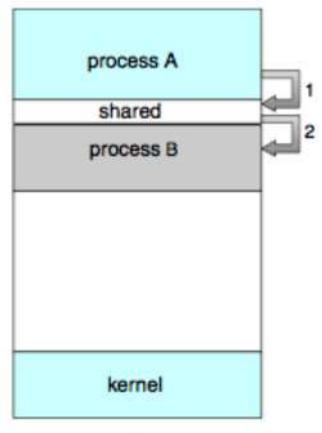
- Often, multiple processes are part of the same "program"
- Hence, they need to coordinate
- Example: Apache and its worker processes, each serving a request
  - Apache must send requests to each worker
- This is very similar to how processes (or tasks) in distributed systems must coordinate

#### **IPC Models**

#### Message passing



#### Shared memory



#### Message Passing vs. Shared Memory

- Message passing
  - Why good? All sharing is explicit less chance for error
  - Why bad? Overhead
    - Data copying, across protection domains (context switches)
- Shared memory
  - Why good? Performance
    - Set up shared memory once, then access w/o crossing protection domains
  - Why bad? Things change behind your back error prone

#### **IPC Example: UNIX Signals**

- Signals
  - A very short message: just a small integer
  - A fixed set of available signals. Examples:
    - 9: kill
    - 11: segmentation fault
- Installing a handler for a signal: signal()

   sighandler\_t signal(int signum, sighandler\_t handler);
- Send a signal to a process: kill()
   kill(pid\_t pid, int signum)

#### **IPC Example: UNIX Pipe**

- int pipe(int fds[2])
  - Creates a one way communication channel
  - fds[2] holds the returned two file descriptors
  - Bytes written to fds[1] will be read from fds[0]

```
int pipefd[2];
pipe(pipefd); // error handling ignored
switch(pid = fork()) {
 case -1: perror("fork"); exit(1);
 case 0: close(pipefd[0]);
          // write to fd 1
           break;
 default: close(pipefd[1]);
          // read from fd 0
  break;
```

#### IPC Example: UNIX Shared Memory

- int shmget(key\_t key, size\_t size, int shmflg)
  - Create a shared memory segment; returns ID of segment
  - key: unique key of a shared memory segment, or IPC\_PRIVATE
- int shmat(int shmid, const void \*addr, int flg)
  - Attach shared memory segment to address space of calling process
  - shmid: id returned by shmget()
- int shmdt(const void \*shmaddr);
  - Detach from shared memory
- Problem: synchronization! (similar concept as in threads)

### Today

- Processes
- Inter-process communication (IPC)
- Threads
- Thread synchronization

#### Threads

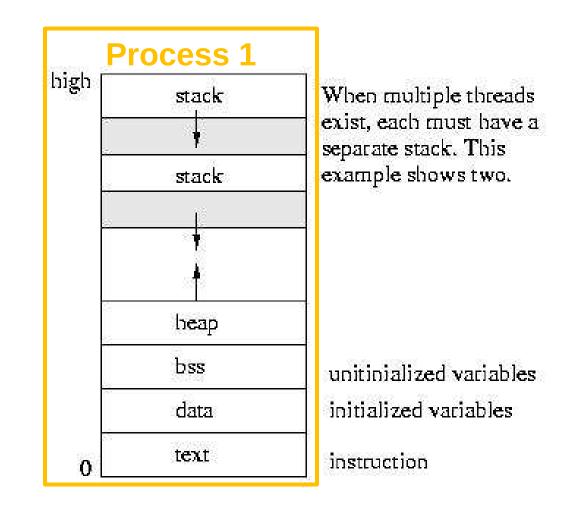
- Threads: separate streams of executions that share an address space
  - Allow one process to have multiple points of execution, can use multiple CPUs
- Per-thread state (not shared across threads)
  - Program counter (EIP on x86)
  - Other registers
  - Stack
- Conceptually similar to processes, but different
  - Often called "lightweight processes"

Thread #1

Thread #2

Time

#### **Threads in Memory**



#### Thread vs. Process

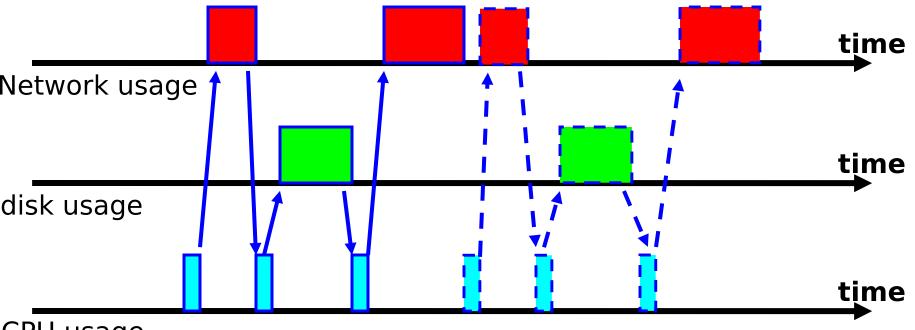
- Why threads?
  - Thread allows running code concurrently within a single process
  - Switching among threads is lightweight
  - Sharing data among threads requires no IPC
- Why processes?

- Fault isolation: One buggy process cannot crash others

### Why Multi-threaded Programming?

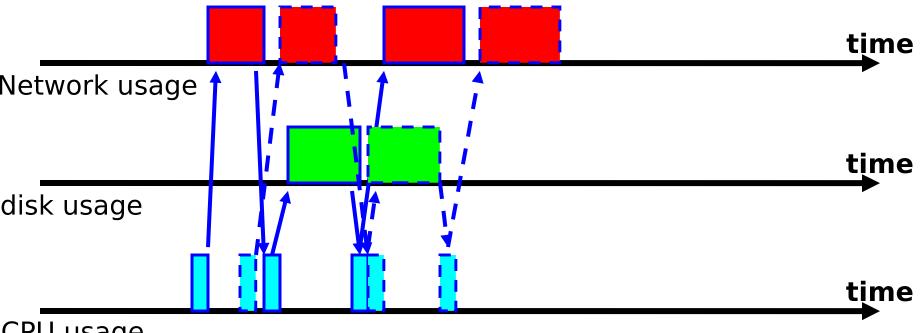
- Exploit multiple CPUs (multi-core) with little overhead
- Exploit I/O concurrency
  - Do some processing while waiting for disk, network, user
- Reduce latency of networked services
  - Servers serve multiple requests in parallel
  - Clients issue multiple requests in parallel
- Example:
  - In addition to multi-process support, Apache has multi-thread support, which is much more common.

# Single-threaded servers do not fully utilize I/O and CPU



CPU usage

### Multi-threaded servers achieve I/O concurrency



### Practical Stuff: The pthread Library

- int pthread\_create(pthread\_t \*thread, const pthread\_attr\_t \*attr, void \*(\*start\_routine)(void\*), void \*arg);
  - Create a new thread to run **start\_routine** on **arg**
  - thread holds the new thread's id
  - Can be customized via attr
- int pthread\_join(pthread\_t thread, void \*\*value\_ptr);
  - Wait for thread termination, and retrieve return value in **value\_ptr**
- void pthread\_exit(void \*value\_ptr);
  - Terminates the calling thread, and returns value\_ptr to threads waiting in pthread\_join

#### **Pthread Creation Example**

```
void* thread_fn(void *arg) {
 int id = (int)arg;
 printf("thread %d runs\n", id);
 return NULL;
}
int main() {
 pthread_t t1, t2;
 pthread_create(&t1, NULL, thread_fn, (void*)1);
 pthread_create(&t2, NULL, thread_fn, (void*)2);
 pthread_join(t1, NULL);
 pthread_join(t2, NULL);
                                  $ gcc –o threads threads.c –Wall –lpthread
 return 0;
                                  $./threads
```

\$ yee –0 threads threads.c –wall –ipthread \$ ./threads thread 1 runs thread 2 runs 27

#### **Thread Pools**

- Problem:
  - Creating a thread for each request: costly
    - And, the created thread exits after serving a request
  - More user requests  $\rightarrow$  more threads, server overload
- Solution: thread pool
  - Pre-create a number of threads waiting for work
  - Wake up thread to serve user request faster than thread creation
  - When request done, don't exit go back to pool and wait
  - Limits the max number of threads
- Your YFS server will have thread pools
- Apache supports thread (and process) pools

### Today

- Processes
- Inter-process communication (IPC)
- Threads
- Thread synchronization

#### **The Problem**

- Memory is shared across all threads
- Hence threads must coordinate so as to update shared memory correctly

### Banking Example

```
int balance = 1000;
int main() {
  pthread_t t1, t2;
  pthread_create(&t1, NULL, withdraw, (void*)800);
  pthread create(&t2, NULL, withdraw, (void*)800);
  pthread_join(t1, NULL);
  pthread_join(t2, NULL);
  printf("All done: balance is $%d\n", balance);
  return 0;
}
void* withdraw(void *arg) {
  int amount = (int)arg;
  if (balance >= amount) {
     balance -= amount;
     printf("ATM gives user $%d\n", amount);
  }
```

Imagine that these threads are created in response to requests from ATM machines

What are possible results?

#### **Results of Banking Example**

Result 2

\$ gcc –Wall –Ipthread –o bank bank.c

#### \$ ./bank

ATM gives user \$800 Result 1 All done: balance is \$200

#### \$ ./bank

ATM gives user \$800 ATM gives user \$800 All done: balance is \$-600

#### \$ ./bank

ATM gives user \$800 ATM gives user \$800 All done: balance is \$200

## How are each of these achieved?

```
Schedule 1 (for Result 1)
        Thread 1
                               Thread 2
    if (balance >= amount)
register = balance - amount;
         balance = register
                           if (balance >= amount)
                          register = balance - amount;
                          balance = register
                       time
```

```
Schedule 2 (for Result 2)
        Thread 1
                               Thread 2
    if (balance >= amount)
                           if (balance >= amount)
register = balance - amount;
         balance = register
                          register = balance - amount;
                          balance = register
                       time
```

```
Schedule 3 (for Result 3)
                               Thread 2
        Thread 1
    if (balance >= amount)
                           if (balance >= amount)
register = balance - amount;
                          register = balance - amount;
         balance = register
                          balance = register
                       time
```

#### **Race Conditions**

- Definition: a timing dependent error involving shared state
- Can be very bad
  - "Non-deterministic:" don't know what the output will be, and it is likely to be different across runs
  - Hard to detect: too many possible schedules
  - Hard to debug: debugging changes timing so hides bugs ("heisenbug")

#### **Synchronization Mechanisms**

- Multiple mechanisms, each solving a different problem
  - Locks
  - Condition variables
  - Semaphores
  - Monitors
  - Barriers

We'll cover here briefly

Read in OS textbook or lectures: http://www.cs.columbia.edu/~junfeng/12spw4118/lectures/l09-lock.pdf, http://www.cs.columbia.edu/~junfeng/12spw4118/lectures/l10-semaphore-monitor.pdf)

- Synchronization both local and distributed is used pervasively in distributed systems
  - Will use synchronization mechanisms in most labs
  - Will build distributed locking for Lab 1
  - MapReduce uses barriers to synchronize threads

#### Locks

- Locks allow only one thread to pass through a "critical section" at any time
  - lock(I): acquire lock exclusively; wait if not available
  - unlock(I): release exclusive access to lock

```
pthread_mutex_t l = PTHREAD_MUTEX_INITIALIZER;
void* withdraw(void *arg) {
    int amount = (int)arg;
    pthread_mutex_lock(l);
    if (balance >= amount) {
        balance -= amount;
        printf("ATM gives user $%d\n", amount);
    }
    pthread_mutex_unlock(l);
```

What's

problem

now?

the

#### **Common Pitfalls**

- Wrong lock granularity
  - Too small granularity leads to races
  - Too large granularity leads to bad performance
- Deadlocks
  - Better bugs than race
- Starvation
- Discussion of each is subject of another course...

#### Processes, Threads, and Coordination in Distributed Systems

- All these topics are extremely relevant for distributed systems
  - Every server is multi-threaded
  - Servers need to coordinate, and they do so using similar methods as IPC, shared memory, locking, barriers, etc.
- In distributed systems, a process is often times called a "task" (unit of processing)
- A program is often times called a "job"

#### **Next Time**

- Inter-machine communication
  - Remote procedure calls
  - Semantics and complexities of RPCs

#### Appendix

### Cool Process Internals: Copy-on-Write (CoW)

- CoW is a useful, general technique that shows up all over in systems
  - Mark parents' memory read-only
  - Have child share parents memory instead of copying
  - If either one writes -- hey, it was read only! (CPU will raise an exception)
    - *Now* give the child its own copy of the page of memory someone was writing