Representational strengths and limitations of transformers

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Motivation

Transformer [Vaswani et al, 2017]: self-attention nets used in large language models

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 - convolutional neural networks (CNNs)
 - recurrent neural networks (RNNs)

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Transformer [Vaswani et al, 2017]: self-attention nets used in large language models

- Alternative to "classical" neural network architectures, e.g.,
 - fully-connected neural networks (FNNs)
 - convolutional neural networks (CNNs)
 - recurrent neural networks (RNNs)
- Amazing theoretical capabilities

. . .

- Turing-completeness [Pérez, Barceló, Marinkovic, 2021; Wei, Chen, Ma, 2021; ...]
- Recognize formal languages [Bhattamishra, Ahuja, Goyal, 2020; Hahn, 2020; Yao, Peng, Papadimitriou,

Narasimhan, 2021; Hao, Angluin, Frank, 2022; Liu, Ash, Goel, Krishnamurthy, Zhang, 2022; Angluin, Chiang, Yang, 2023; ...]

Solve inference/learning problems ("in-context learning") [Garg, Tsipras, Liang, Valiant, 2022; Akyürek, Schuurmans, Andreas, Ma, Zhou, 2022; Zhang, Frei, Bartlett, 2023; Abernethy, Agarwal, Marinov, Warmuth, 2023; Bai, Chen, Wang, Xiong, Mei, 2023; ...]

What is special about transformers?

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- Succinct parameterization of sequence-to-sequence functions (?)
- ► Ability to capture "long-range interactions" (?)

"What does BERT look at?"

[Clark, Khandelwal, Levy, Manning, 2019]

Attends to next token



Attends to periods



"What does BERT look at?"

- **Noun modifiers** (e.g., determiners) attend to their noun
- 94.3% accuracy at the det relation



[SEP]

[SEP]

- Coreferent mentions attend to their antecedents

[Clark, Khandelwal, Levy, Manning, 2019]

- 65.1% accuracy at linking the head of a coreferent mention to the head of an antecedent



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What we do: Formalize advantages of transformers over classical architectures (as well as limitations of transformers) in terms of "communication" bottlenecks

Results are only about **representational** strengths/limitations of transformers (No direct analysis of learning/generalization)

1. Transformers 101 + our results

2. Sparse Averaging

3. Element matching problems

1. Transformers 101 + our results



Self-attention unit: mapping of N-tuples from $\mathcal{X} = \mathbb{R}^{d_{\text{in}}}$ to N-tuples from $\mathcal{Y} = \mathbb{R}^{d_{\text{out}}}$ of a particular parametric form



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 $\operatorname{att}(X) = \operatorname{softmax}((XW_Q)(XW_K)^{\mathsf{T}}) XW_V$

- ▶ Parameters: W_Q, W_K ∈ ℝ^{d_{in}×m}, W_V ∈ ℝ<sup>d_{in}×d_{out} (query, key, & value params.)
 ▶ m = (internal) embedding dimension
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- ► softmax is applied row-wise:

softmax
$$(M)_{i,j} = \frac{\exp(M_{i,j})}{\sum_{k=1}^{N} \exp(M_{i,k})}$$

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Mapping is permutation-equivariant

• Each row of $\operatorname{att}(X)$ is in convex hull of {rows of XW_V }

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- Each self-attention unit is also allowed to process each element of input tuple using a feedforward neural network

$$\phi \colon \mathbb{R}^{d_{\mathrm{in}}} \to \mathbb{R}^{d'_{\mathrm{in}}}$$

(same ϕ is applied to each element of input tuple) with $d'_{in} = O(m)$

• Can also process output tuple with some $\phi \colon \mathbb{R}^{d'_{\text{out}}} \to \mathbb{R}^{d_{\text{out}}}$, $d'_{\text{out}} = O(m)$

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- \blacktriangleright ϕ 's are akin to "activation functions" in classical architectures

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- Allow element-wise maps ϕ to be arbitrary functions
- How must "size" parameters L, H, m grow with N?

► On a sparse decoding problem: "Sparse Averaging"

On element matching problems: "Pair/Triple Matching"

On a sparse decoding problem: "Sparse Averaging"

- ▶ Self-att. unit with $m = O(d_{in} + q \log N)$ suffices for sparsity level q^1
- Every FNN requires width $\Omega(N)$ even if q = 1, $d_{in} = \tilde{O}(1)$
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2. Sparse Averaging

q-Sparse Averaging (qSA)

Input:
$$(x_1, x_2, \dots, x_N)$$
 where
 $x_i = (\operatorname{enc}(i), \operatorname{enc}(S_i), v_i) \in \mathbb{R}^{d_{\operatorname{in}}}, \quad d_{\operatorname{in}} = O(d + (q+1)\log N),$
and

$$\begin{array}{ll} 1, 2, \dots, N & \text{ are the "keys"} \\ S_1, S_2, \dots, S_N \in \binom{[N]}{q} & \text{ are the "queries"} \\ v_1, v_2, \dots, v_N \in \mathbb{R}^d & \text{ are the "values" (with } \|v_i\| \leq 1) \end{array}$$

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Output: N vectors in $\mathbb{R}^{d_{\text{out}}}$ with $d_{\text{out}} = d$, where *i*th output vector is

$$\approx \frac{1}{q} \sum_{j \in S_i} v_j$$
- Self-att. unit with $m = O(d_{in} + q \log N)$ suffices for sparsity level q (+ almost matching lower bound)
- Every FNN requires width $\Omega(N)$ even if q = 1, $d_{in} = \tilde{O}(1)$
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Self-attention solution (overview)

Design
$$\phi \colon \mathbb{R}^{d_{\mathrm{in}}} \to \mathbb{R}^{d'_{\mathrm{in}}}, W_Q, W_K \in \mathbb{R}^{d'_{\mathrm{in}} \times m}, W_V \in \mathbb{R}^{m \times d_{\mathrm{out}}}$$
 such that
 $\operatorname{softmax}((\phi(X)W_Q)(\phi(X)W_K)^{\mathsf{T}})_{i,j} \approx \begin{cases} 1/q & \text{if } S_i \ni j\\ 0 & \text{if } S_i \not\ni j \end{cases}$

 and

$$\phi(X)W_Q = \begin{bmatrix} \longleftarrow & w_{S_1}^{\mathsf{T}} & \longrightarrow \\ & \vdots & \\ \leftarrow & w_{S_N}^{\mathsf{T}} & \longrightarrow \end{bmatrix}, \ (\phi(X)W_K)^{\mathsf{T}} = \begin{bmatrix} \uparrow & & \uparrow \\ u_1 & \cdots & u_N \\ \downarrow & & \downarrow \end{bmatrix}, \ \phi(X)W_V = \begin{bmatrix} \longleftarrow & v_1^{\mathsf{T}} & \longrightarrow \\ & \vdots & \\ \leftarrow & v_N^{\mathsf{T}} & \longrightarrow \end{bmatrix}$$

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 ϕ will do most of the work; W_Q, W_K, W_V extract relevant parts of each $\phi(x_i)$

Empirical solution

"Attention matrices" softmax $((\phi(X)W_Q)(\phi(X)W_K)^{\intercal}) \in \mathbb{R}^{20 \times 20}$ for same fixed X, after training transformer for T epochs to solve qSA with q = 3



Construction using q-neighborly 0/1 polytopes

[Candès & Tao, 2005] There exist $u_1, u_2, \ldots, u_N \in \{\pm \frac{1}{\sqrt{k}}\}^k$ with $k = O(q \log N)$, such that, for every $S \in {[N] \choose q}$, there exists $w_S \in \mathbb{R}^k$ satisfying

$$\begin{split} \|w_S\| &\leq 2\sqrt{q} \\ \langle w_S, u_j \rangle &= 1 & \text{for all } j \in S \\ |\langle w_S, u_j \rangle| &\leq 1/2 & \text{for all } j \notin S \end{split}$$

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Our
$$\phi \colon \mathbb{R}^{d_{\text{in}}} \to \mathbb{R}^{d'_{\text{in}}}$$
 with $d'_{\text{in}} = O(d + q \log N)$ is
 $\phi(\text{enc}(i), \text{enc}(S_i), v_i) = (u_i, \alpha w_{S_i}, v_i)$
for suitably large $\alpha > 0$

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$$x_i = (\operatorname{enc}(i), \operatorname{enc}(\emptyset), \underline{a_i}) \quad \text{for all } i \in [N]$$

(Alice sends nth hidden state to Bob)

$$x_{n+1} = (\operatorname{enc}(n+1), \operatorname{enc}(\{b\}), 0)$$

3. Element matching problems

Pair and Triple Matching

Input: $(x_0, x_1, x_2, ..., x_N)$ where

dummy element: $x_0 = \text{enc}(\perp)$, (for technical reasons) for all $i \in [N]$: $x_i = \text{enc}(z_i)$, $z_i \in \{1, 2, \dots, M\}$

and $N \ll M = \operatorname{poly}(N)$

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(Triple Matching) Output: ith output is

$$1 \{ \exists j, k \in [N] \text{ s.t. } z_i + z_j + z_k = 0 \pmod{M} \}$$

What we show (element matching problems)

- (Standard) self-att. unit can solve Pair Matching with $m = O(d_{in})$
- "Third-order" self-att. unit can solve Triple Matching with $m = O(d_{in})$
- Multi-headed self-att. layer requires $Hm = \tilde{\Omega}(N)$ to solve Triple Matching (+ almost matching upper bound)

Self-attention solution (Pair Matching)

Main idea: Choose $\phi \colon \mathbb{R}^{d_{\text{in}}} \to \mathbb{R}^m$, W_Q, W_K s.t.

 $\left\langle W_Q^{\mathsf{T}}\phi(\operatorname{enc}(z)), W_K^{\mathsf{T}}\phi(\operatorname{enc}(z')) \right\rangle = \alpha \, \cos(\frac{2\pi(z+z')}{M})$



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Large enough $\alpha = O(M^2 \log N)$ ensures we can distinguish between

- \blacktriangleright z_i 's with at least one match
- \blacktriangleright z_i 's with no matches

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(Dummy element supplies $W_V^{\mathsf{T}}\phi(\operatorname{enc}(\bot)) \neq W_V^{\mathsf{T}}\phi(\operatorname{enc}(z_i))$

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Every H-headed self-attention layer with embedding dimension m that solves Triple Matching requires $H\times m=\tilde{\Omega}(N)$

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 Goal: After some communication, Bob determines if ∀i ∈ [n], a_i ∧ b_i = 0
 Lower bound (Yao, 1979): Alice and Bob must exchange at least n bits

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- Create input x for Triple Matching from a and b (with N = 2n + 1):

$$x_{i} = \begin{cases} \operatorname{enc}(1) & \text{if } a_{i} = 0\\ \operatorname{enc}(i+1) & \text{if } a_{i} = 1 \end{cases}$$

$$x_{n+i} = \begin{cases} \operatorname{enc}(1) & \text{if } b_{i} = 0\\ \operatorname{enc}(M-(i+1)) & \text{if } b_{i} = 1 \end{cases}$$

$$\operatorname{triple match with}_{N \text{th query iff}}_{N \text{th query iff}}_{DISJ(a, b) = 0}$$

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Main idea: Alice & Bob can jointly compute (2n + 1)th output



1. Alice sends parts of softmax normalization terms to Bob

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- 1. Alice sends parts of softmax normalization terms to Bob
- 2. Bob completes softmax normalization terms; sends back to Alice
- 3. Alice sends partial weighted averages of "values" to Bob

H-headed self-attention layer with embedding dimension m for Triple Matching provides a communication protocol using $H\times m\times \operatorname{poly} \log(N)$ bits



- 1. Alice sends parts of softmax normalization terms to Bob
- 2. Bob completes softmax normalization terms; sends back to Alice
- 3. Alice sends partial weighted averages of "values" to Bob
- 4. Bob completes computation of weighted averages of "values"

Lower bounds for *L*-layer transformers with L > 1

We conjecture (and wanted to prove):

Every transformer requires $L \times H \times m = N^{\Omega(1)}$ to solve Triple Matching

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 $1\!\!\!1\{\exists j,k\in [i-T,i+T] \quad \text{s.t.} \quad z_i+z_j+z_k=0 \pmod{M}\}$
Easier variants of Triple Matching

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Can reduce to qSA problem with q = O(T) and $d_{in} = \tilde{O}(T)$

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Thank you!

%llion0: FAIR's paper seems to concentrate solely on the convolutional aspect %of their model and have the attention as an after thought almost, this gives %us a good opportunity to differentiate ourselves from their paper.

```
%We are simpler in a number of ways and should have the simplicity as a big selling point:
%\begin{itemize}
%\item No convolutions
%\item No need for such careful initializations and
%normalization.
%\item Simpler non-lineararities, they use the gated linear
%units.
%\item Less layers?
%\end{itemize}
%One thing we do more is that we have self attention.
%Another selling point is the increased interpretability as
%shown with the visualizations. Which comes from the
%simplicity and use of only attentions.
```

Third-order self-attention unit:

$$f(X) = \text{softmax}\left((XW_Q) \left((XW_K^{(1)}) \star (XW_K^{(2)}) \right)^{\mathsf{T}} \right) \left((XW_V^{(1)}) \star (XW_V^{(2)}) \right)$$

where \star is column-wise Kornecker product (a.k.a. Khatri-Rao product)

- ▶ Input: $X \in \mathbb{R}^{N \times N}$, adjacency matrix of digraph $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ with $\mathcal{V} = [N]$
- Graph self-attention unit:

softmax
$$\left(\kappa\left(X, (XW_Q)(XW_K)^{\mathsf{T}}\right)\right) XW_V$$

where $\kappa\colon \mathbb{R}\to \mathbb{R}$ is an arbitrary function applied element-wise

(Directed 3-Cycle) Output: ith output is

 $\mathbbm{1}\{\exists j,k\in[N]\quad\text{s.t.}\quad(i,j),(j,k),(k,i)\in\mathcal{E}\}$

(Undirected 5-Cycle) Output: ith output is

 $\mathbb{1}\{\exists j_1, j_2, j_3, j_4 \in [N] \quad \text{s.t.} \quad \{i, j_1\}, \{j_1, j_2\}, \{j_2, j_3\}, \{j_3, j_4\}, \{j_4, i\} \in \mathcal{E}\}$

Model sizes

Model	Input size (N)	# Layers (L)	# Heads/layer (H)	Emb. dim. (<i>m</i>)	$\# \operatorname{nodes}/\phi$
BERT	512	24	16	1024	4K
GPT-2	1K	12	12	768	?
GPT-3	2K	96	96	128	12K
GPT-4	32K	120 ?	?	?	?