Machine learning lecture slides

COMS 4771 Fall 2020

Regression I: Linear regression

Outline

- Statistical model for regression
- College GPA example
- Ordinary least squares for linear regression
- The expected mean squared error
- Different views of ordinary least squares
- Features and linearity
- Over-fitting
- Beyond empirical risk minimization

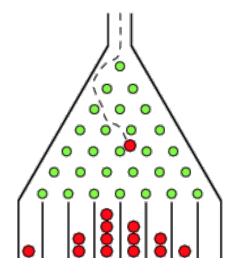


Figure 1: Galton board

Real-valued predictions

- Example: Galton board
- Physical model: hard
- Statistical model: final position of ball is random
 - Normal (Gaussian) distribution with mean μ and variance σ^2
 - Written $N(\mu, \sigma^2)$

Probability density function is

$$p_{\mu,\sigma^2}(y) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y-\mu)^2}{2\sigma^2}}, \quad y \in \mathbb{R}.$$

 Goal: predict final position accurately, measure <u>squared loss</u> (also called <u>squared error</u>)

$$({\sf prediction}-{\sf outcome})^2$$

Outcome is random, so look at <u>expected squared loss</u> (also called mean squared error)

Optimal prediction for mean squared error

- Predict ŷ ∈ ℝ; true final position is Y (random variable) with <u>mean</u> 𝔼(Y) = μ and <u>variance</u> var(Y) = 𝔼[(Y − 𝔼(Y))²] = σ².
 Squared error is (ŷ − Y)².
- Bias-variance decomposition:

$$\mathbb{E}[(\hat{y} - Y)^2] = \mathbb{E}[(\hat{y} - \mu + \mu - Y)^2]$$

= $(\hat{y} - \mu)^2 + 2(\hat{y} - \mu)\mathbb{E}[(\mu - Y)] + \mathbb{E}[(\mu - Y)^2]$
= $(\hat{y} - \mu)^2 + \sigma^2$.

- This is true for any random variable Y; don't need normality assumption.
- So optimal prediction is $\hat{y} = \mu$.

. . .

When parameters are unknown, can estimate from related data,

Can also do an analysis of a plug-in prediction

Statistical model for regression

- Setting is same as for classification except:
 - Label is real number, rather than $\{0,1\}$ or $\{1,2,\ldots,K\}$
 - Care about squared loss, rather than whether prediction is correct
 - ► Mean squared error of f:

$$\operatorname{mse}(f) := \mathbb{E}[(f(X) - Y)^2],$$

the expected squared loss of f on random example

Optimal prediction function for regression

► If (*X*, *Y*) is random test example, then *optimal prediction function* is

 $f^{\star}(x) = \mathbb{E}[Y \mid X = x]$

- ► Also called the *regression function* or <u>conditional mean function</u>
- Prediction function with smallest MSE
- Depends on conditional distribution of Y given X

Test MSE (1)

- ▶ Just like in classification, we can use test data to estimate $mse(\hat{f})$ for a function \hat{f} that depends only on training data.
- ► IID model:
 - $(X_1,Y_1),\ldots,(X_n,Y_n),(X_1',Y_1'),\ldots,(X_m',Y_m'),(X,Y)$ are iid
 - Training examples (that you have): $S := ((X_1, Y_1), \dots, (X_n, Y_n))$
 - Test examples (that you have): $T := ((X'_1, Y'_1), \dots, (X'_m, Y'_m))$
 - Test example (that you don't have) used to define MSE: (X, Y)
- Predictor \hat{f} is based only on training examples
- Hence, test examples are independent of f̂ (very important!)
- We would like to estimate $mse(\hat{f})$

Test MSE (2)

• Test MSE $\operatorname{mse}(\hat{f},T) = \frac{1}{m} \sum_{i=1}^{m} (\hat{f}(X'_i) \neq Y'_i)^2$

▶ By law of large numbers, $mse(\hat{f}, T) \to mse(\hat{f})$ as $m \to \infty$

Example: College GPA

- Data from 750 Dartmouth students' College GPA
 - Mean: 2.46
 - Standard deviation: 0.746
- Assume this data is iid sample from the population of Dartmouth students (false)
- Absent any other features, best constant prediction of a uniformly random Dartmouth student's College GPA is ŷ := 2.46.

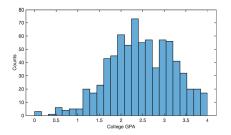
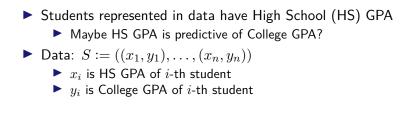


Figure 2: Histogram of College GPA

Predicting College GPA from HS GPA (1)



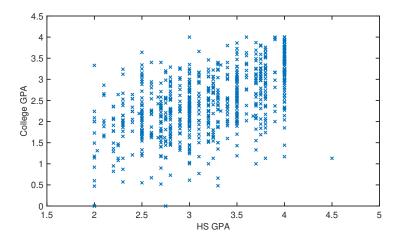


Figure 3: Plot of College GPA vs HS GPA

Predicting College GPA from HS GPA (2)

First attempt:

Define intervals of possible HS GPAs:

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(0.00, 0.25], (0.25, 0.50], (0.50, 0.75], \cdots
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For each such interval I, record the mean $\hat{\mu}_I$ of the College GPAs of students whose HS GPA falls in I.

$$\hat{f}(x) := \begin{cases} \hat{\mu}_{(0.00, 0.25]} & \text{if } x \in (0.00, 0.25] \\ \hat{\mu}_{(0.25, 0.50]} & \text{if } x \in (0.25, 0.50] \\ \hat{\mu}_{(0.50, 0.75]} & \text{if } x \in (0.50, 0.75] \\ & \vdots \end{cases}$$

 (What to do about an interval I that contains no student's HS GPA?)

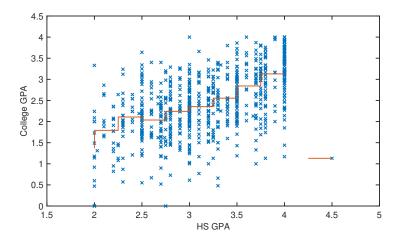


Figure 4: Plot of mean College GPA vs binned HS GPA

Predicting College GPA from HS GPA (3)

Define

$$\operatorname{mse}(f, S) := \frac{1}{|S|} \sum_{(x,y) \in S} (f(x) - y)^2,$$

the mean squared error of predictions made by f on examples in $\boldsymbol{S}.$

"mean" is with respect to the uniform distribution on examples in S.

$$\begin{split} & \mathrm{mse}(\hat{f},S) = 0.376 \\ & \sqrt{\mathrm{mse}(\hat{f},S)} = 0.613 < 0.746 \text{ (the standard deviation of the } y_i\text{'s)} \end{split}$$

Piece-wise constant function î is an improvement over the constant function (i.e., just predicting the mean 2.46 for all x)!

Predicting College GPA from HS GPA (4)

- But \hat{f} has some quirks.
- E.g., those with HS GPA between 2.50 and 2.75 are predicted to have a lower College GPA than those with HS GPA between 2.25 and 2.50.
- E.g., something unusual with the student who has HS GPA of 4.5

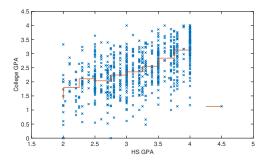


Figure 5: Plot of mean College GPA vs binned HS GPA

Least squares linear regression (1)

Suppose we'd like to only consider functions with a specific functional form, e.g., a linear function:

$$f(x) = mx + \theta$$

for $m, \theta \in \mathbb{R}$.

- Technically, $x \mapsto mx + \theta$ is linear iff $\theta = 0$. If $\theta \neq 0$, the function is not linear but <u>affine</u>.
- Semantics: Positive *m* means higher HS GPA gets a higher prediction of College GPA.

Least squares linear regression (2)

What is the linear function with smallest MSE on (x₁, y₁),..., (x_n, y_n) ∈ ℝ × ℝ? This is the problem of *least squares linear regression*.

 $\blacktriangleright \ \ \mbox{Find} \ (m,\theta) \in \mathbb{R}^2$ to minimize

$$\frac{1}{n}\sum_{i=1}^{n}(mx_i+\theta-y_i)^2.$$

Also called <u>ordinary least squares</u> (<u>OLS</u>)

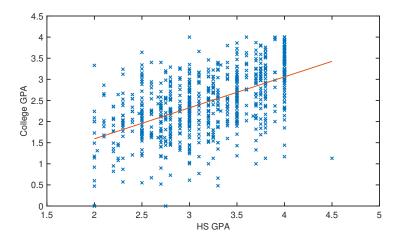


Figure 6: Plot of least squares linear regression line

Computing OLS (1)

Derivatives equal zero conditions (*normal equations*):

$$\frac{\partial}{\partial \theta} \left\{ \frac{1}{n} \sum_{i=1}^{n} (mx_i + \theta - y_i)^2 \right\} = \frac{2}{n} \sum_{i=1}^{n} (mx_i + \theta - y_i) = 0$$
$$\frac{\partial}{\partial m} \left\{ \frac{1}{n} \sum_{i=1}^{n} (mx_i + \theta - y_i)^2 \right\} = \frac{2}{n} \sum_{i=1}^{n} (mx_i + \theta - y_i) x_i = 0.$$

System of two linear equations with two unknowns (m, θ).
 Define

$$\overline{x} := \frac{1}{n} \sum_{i=1}^{n} x_i, \qquad \overline{x^2} := \frac{1}{n} \sum_{i=1}^{n} x_i^2;$$
$$\overline{xy} := \frac{1}{n} \sum_{i=1}^{n} x_i y_i, \qquad \overline{y} := \frac{1}{n} \sum_{i=1}^{n} y_i,$$

so system can be re-written as

$$\overline{x}m + \theta = \overline{y}$$
$$\overline{x^2}m + \overline{x}\theta = \overline{x}\overline{y}.$$
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Computing OLS (2)

Write in matrix notation:

$$\begin{bmatrix} \overline{x} & 1 \\ \overline{x^2} & \overline{x} \end{bmatrix} \begin{bmatrix} m \\ \theta \end{bmatrix} = \begin{bmatrix} \overline{y} \\ \overline{xy} \end{bmatrix}.$$

▶ Solution:
$$(\hat{m}, \hat{\theta}) \in \mathbb{R}^2$$
 given by

$$\hat{m} := \frac{\overline{xy} - \overline{x} \cdot \overline{y}}{\overline{x^2} - \overline{x}^2}, \quad \hat{\theta} := \overline{y} - \frac{\overline{xy} - \overline{x} \cdot \overline{y}}{\overline{x^2} - \overline{x}^2} \cdot \overline{x}.$$

Computing OLS (3)

► Catch: The above solution only makes sense if $\overline{x^2} - \overline{x}^2 \neq 0$, i.e., the variance of the x_i 's is non-zero.

• If $\overline{x^2} - \overline{x}^2 = 0$, then the matrix defining the LHS of system of equations is singular.

Computing OLS (4)

In general, "derivative equals zero" is only a necessary condition for a solution to be optimal; not necessarily a sufficient condition!

Theorem: Every solution to the normal equations is an optimal solution to the least squares linear regression problem.

Decomposition of expected MSE (1)

- ► Two different functions of HS GPA for predicting College GPA.
 - What makes them different?
 - We care about prediction of College GPA for student we haven't seen before based on their HS GPA.
- ▶ IID model: $(X_1, Y_1), \ldots, (X_n, Y_n), (X, Y)$ are iid
- Say training examples (X₁, Y₁), ..., (X_n, Y_n) are used to determine f̂.
- What is $\mathbb{E}[\operatorname{mse}(\hat{f})]$?

Decomposition of expected MSE (2)

$$\begin{split} \mathbb{E}[\operatorname{mse}(\hat{f})] \\ &= \mathbb{E}\left[\mathbb{E}[(\hat{f}(X) - Y)^2 \mid \hat{f}]\right] \\ &= \mathbb{E}\left[\mathbb{E}[(\hat{f}(X) - Y)^2 \mid \hat{f}, X]\right] \\ &= \mathbb{E}\left[\operatorname{var}(Y \mid X) + (\hat{f}(X) - \mathbb{E}[Y \mid X])^2\right] \\ &= \mathbb{E}\left[\operatorname{var}(Y \mid X) + \mathbb{E}[(\hat{f}(X) - \mathbb{E}[Y \mid X])^2 \mid X]\right] \\ &= \mathbb{E}\left[\operatorname{var}(Y \mid X) + \operatorname{var}(\hat{f}(X) \mid X) + (\mathbb{E}[\hat{f}(X) \mid X] - \mathbb{E}[Y \mid X])^2\right] \\ &= \underbrace{\mathbb{E}\left[\operatorname{var}(Y \mid X)\right]}_{\text{unavoidable error}} + \underbrace{\mathbb{E}\left[\operatorname{var}(\hat{f}(X) \mid X)\right]}_{\text{variability of } \hat{f}} + \underbrace{\mathbb{E}\left[(\mathbb{E}[\hat{f}(X) \mid X] - \mathbb{E}[Y \mid X])^2\right]}_{\text{approximation error of } \hat{f}} \end{split}$$

Decomposition of expected MSE (3)

- First term is quantifies inherent unpredictability of Y (even after seeing X)
- Second term measures the "variability" of \hat{f} due to the random nature of training data. Depends on:
 - probability distribution of training data,
 - type of function being fit (e.g., piecewise constant, linear),
 - method of fitting (e.g., OLS),
 - etc.
- Third term quantifies how well a function produced by the fitting procedure can approximate the regression function, even after removing the "variability" of f.

Multivariate linear regression (1)

- ▶ For Dartmouth data, also have SAT Score for all students.
 - Can we use both <u>predictor variables</u> (HS GPA and SAT Score) to get an even better prediction of College GPA?
 - Binning approach: instead of a 1-D grid (intervals), consider a 2-D grid (squares).
 - Linear regression: a function $f : \mathbb{R}^2 \to \mathbb{R}$ of the form

$$f(x) = m_1 x_1 + m_2 x_2 + \theta$$

for some $(m_1, m_2) \in \mathbb{R}^2$ and $\theta \in \mathbb{R}$.

Multivariate linear regression (2)

▶ The general case: a (homogeneous) linear function $f : \mathbb{R}^d \to \mathbb{R}$ of the form

$$f(x) = x^{\mathsf{T}} w$$

for some $w \in \mathbb{R}^d$.

- ▶ w is called the *weight vector* or <u>coefficient vector</u>.
- What about inhomogeneous linear functions?
 - Just always include a "feature" that always has value 1. Then the corresponding weight acts like θ from before.

Multivariate ordinary least squares (1)

What is the linear function with smallest MSE on (x1, y1),..., (xn, yn) ∈ ℝ^d × ℝ?
 Find w ∈ ℝ^d to minimize

$$\widehat{\mathcal{R}}(w) := \frac{1}{n} \sum_{i=1}^{n} (x_i^{\mathsf{T}} w - y_i)^2.$$



Multivariate ordinary least squares (2)

In matrix notation:

$$\widehat{\mathcal{R}}(w) := \|Aw - b\|_2^2$$

where

$$A := \frac{1}{\sqrt{n}} \begin{bmatrix} \longleftarrow & x_1^{\mathsf{T}} & \longrightarrow \\ & \vdots & \\ \leftarrow & x_n^{\mathsf{T}} & \longrightarrow \end{bmatrix} \in \mathbb{R}^{n \times d}, \quad b := \frac{1}{\sqrt{n}} \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} \in \mathbb{R}^n.$$

• If we put vector $v \in \mathbb{R}^d$ in the context of matrix multiplication, it is treated as a column vector by default!

• If we want a row vector, we write v^{T} .

► Therefore

$$Aw - b = \frac{1}{\sqrt{n}} \begin{bmatrix} x_1^{\mathsf{T}}w - y_1 \\ \vdots \\ x_n^{\mathsf{T}}w - y_n \end{bmatrix}$$

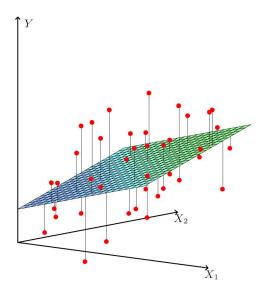


Figure 7: Geometric picture of least squares linear regression

Multivariate normal equations (1)

Like the one-dimensional case, optimal solutions are characterized by a system of linear equations (the "derivatives equal zero" conditions) called the *normal equations*:

$$\nabla_{w} \,\widehat{\mathcal{R}}(w) = \begin{bmatrix} \frac{\partial \,\widehat{\mathcal{R}}(w)}{\partial w_{1}} \\ \vdots \\ \frac{\partial \,\widehat{\mathcal{R}}(w)}{\partial w_{d}} \end{bmatrix} = 2A^{\mathsf{T}}(Aw - b) = 0,$$

which is equivalent to

$$A^{\mathsf{T}}Aw = A^{\mathsf{T}}b.$$

Multivariate normal equations (2)

If A^TA is non-singular (i.e., invertible), then there is a unique solution given by

$$\hat{w} := (A^{\mathsf{T}}A)^{-1}A^{\mathsf{T}}b.$$

• If $A^{\mathsf{T}}A$ is singular, then there are infinitely many solutions!

Theorem: Every solution to the normal equations is an optimal solution to the least squares linear regression problem.

Algorithm for least squares linear regression

- ▶ How to solve least squares linear regression problem?
 - Just solve the normal equations, a system of d linear equations in d unknowns.
 - Time complexity (naïve) of Gaussian elimination algorithm: O(d³).
 - Actually, also need to count time to form the system of equations, which is O(nd²).

Classical statistics view of OLS (1)

- Normal linear regression model
- ▶ Model training examples $(X_1, Y_1), \ldots, (X_n, Y_n)$ as iid random variables taking values in $\mathbb{R}^d \times \mathbb{R}$, where

$$Y_i \mid X_i = x_i \sim \mathcal{N}(x_i^{\mathsf{T}} w, \sigma^2)$$

 $\blacktriangleright \ w \in \mathbb{R}^d \text{ and } \sigma^2 > 0 \text{ are the parameters of the model}.$

▶ The least squares linear regression problem is the same as the problem of finding the maximum likelihood value for *w*.

Classical statistics view of OLS (2)

- Suppose your data really does come from a distribution in this statistical model, say, with parameters w and σ².
 - Then the function with smallest MSE is the linear function f^{*}(x) = x^Tw, and its MSE is mse(f^{*}) = σ².
 - ► So estimating *w* is a sensible idea! (Plug-in principle...)

Statistical learning view of OLS (1)

▶ IID model: $(X_1, Y_1), \ldots, (X_n, Y_n), (X, Y) \sim_{iid} P$ are iid random variables taking values in $\mathbb{R}^d \times \mathbb{R}$

• (X, Y) is the (unseen) "test" example

• Goal: find a (linear) function $w \in \mathbb{R}^d$ with small MSE

$$\operatorname{mse}(w) = \mathbb{E}[(X^{\mathsf{T}}w - Y)^2].$$

We cannot directly minimize mse(w) as a function of w ∈ ℝ^d, since it is an expectation (e.g., integral) with respect to the unknown distribution P

Statistical learning view of OLS (2)

- However, we have an iid sample $S := ((X_1, Y_1), \dots, (X_n, Y_n)).$
- ► We swap out P in the definition of mse(f), and replace it with the *empirical distribution* on S:

$$P_n(x,y) := \frac{1}{n} \sum_{i=1}^n \mathbf{1}_{\{(x,y)=(x_i,y_i)\}}.$$

- This is the distribution that puts probability mass 1/n on the *i*-th training example.
- Resulting objective function is

$$\mathbb{E}[(\tilde{X}^{\mathsf{T}}w - \tilde{Y})^{2}] = \frac{1}{n} \sum_{i=1}^{n} (X_{i}^{\mathsf{T}}w - Y_{i})^{2}$$

where $(\tilde{X}, \tilde{Y}) \sim P_n$.

Statistical learning view of OLS (3)

In some circles:

- (*True/population*) risk of w: $\mathcal{R}(w) := \mathbb{E}[(X^{\mathsf{T}}w Y)^2]$
- <u>Empirical risk</u> of w: $\widehat{\mathcal{R}}(w) := \frac{1}{n} \sum_{i=1}^{n} (X_i^{\mathsf{T}} w Y_i)^2$
- This is another instance of the plug-in principle!
 - ▶ We want to minimize mse(w) but we don't know P, so we replace it with our estimate P_n.

Statistical learning view of OLS (4)

- This is not specific to linear regression; also works for other types of functions, and also other types of prediction problems, including classification.
- For classification:
 - (*True/population*) risk of $f: \mathcal{R}(f) := \mathbb{E}[\mathbf{1}_{\{f(X) \neq Y\}}]$
 - Empirical risk of $f: \widehat{\mathcal{R}}(f) := \frac{1}{n} \sum_{i=1}^{n} \mathbf{1}_{\{f(X_i) \neq Y_i\}}$

All that changed is the <u>loss function</u> (squared loss versus <u>zero/one loss</u>)

 Procedure that minimizes empirical risk: *Empirical risk minimization* (<u>ERM</u>)

Upgrading linear regression (1)

- Make linear regression more powerful by being creative about features
 - We are forced to do this if x is not already provided as a vector of numbers
- lnstead of using x directly, use $\varphi(x)$ for some transformation φ (possibly vector-valued)

Upgrading linear regression (2)

Examples:

- ▶ Affine feature expansion, e.g., $\varphi(x) = (1, x)$, to accommodate intercept
- Standardization, e.g., $\varphi(x) = (x \mu)/\sigma$ where (μ, σ^2) are (estimates of) the mean and variance of the feature value
- \blacktriangleright Non-linear scalar transformations, e.g., $\varphi(x) = \ln(1+x)$
- ► Logical formula, e.g., $\varphi(x) = (x_1 \land x_5 \land \neg x_{10}) \lor (\neg x_2 \land x_7)$
- Trigonometric expansion, e.g., $\varphi(x) = (1, \sin(x), \cos(x), \sin(2x), \cos(2x), \dots)$
- Polynomial expansion, e.g., $\varphi(x) = (1, x_1, \dots, x_d, x_1^2, \dots, x_d^2, x_1x_2, \dots, x_{d-1}x_d)$
- <u>Headless neural network</u> $\varphi(x) = N(x) \in \mathbb{R}^k$, where $N \colon \mathbb{R}^d \to \mathbb{R}^k$ is a map computed by a intermediate layer of a neural network

► (Later, we'll talk about how to "learn" N.)

Example: Taking advantage of linearity

- Example: y is health outcome, x is body temperature
 - ▶ Physician suggests relevant feature is (square) deviation from normal body temperature $(x 98.6)^2$
 - What if you didn't know the magic constant 98.6? (Apparently it is wrong in the US anyway)
 - Use $\varphi(x) = (1, x, x^2)$
 - ► Can learn coefficients $w \in \mathbb{R}^3$ such that $\varphi(x)^{\mathsf{T}}w = (x 98.6)^2$, or any other quadratic polynomial in x (which could be better!)

Example: Binning features

Dartmouth data example, where we considered intervals for the HS GPA variable:

 $(0.00, 0.25], (0.25, 0.50], (0.50, 0.75], \cdots$

▶ Use $\varphi(x) = (\mathbf{1}_{\{x \in (0.00, 0.25]\}}, \mathbf{1}_{\{x \in (0.25, 0.50]\}}, \dots)$ with a linear function

• What is
$$\varphi(x)^{\mathsf{T}}w$$
?

• $\varphi(x)^{\mathsf{T}}w = w_j$ if x is in the *j*-th interval.

Effect of feature expansion on expected MSE

$$\mathbb{E}[\operatorname{mse}(\hat{f})] = \underbrace{\mathbb{E}\left[\operatorname{var}(Y \mid X)\right]}_{\text{unavoidable error}} + \underbrace{\mathbb{E}\left[\operatorname{var}(\hat{f}(X) \mid X)\right]}_{\text{variability of }\hat{f}} + \underbrace{\mathbb{E}\left[\left(\mathbb{E}[\hat{f}(X) \mid X] - \mathbb{E}[Y \mid X]\right)^2\right]}_{\text{approximation error of }\hat{f}}$$

- Feature expansion can help reduce the third term (approximation error)
- But maybe at the cost of increasing the second term (variability)

Performance of OLS (1)

- Study in context of IID model
- $(X_1, Y_1), \ldots, (X_n, Y_n), (X, Y)$ are iid, and assume $\mathbb{E}[XX^{\mathsf{T}}]$ is invertible (WLOG).
- Let w^* denote the minimizer of mse(w) over all $w \in \mathbb{R}^d$.
 - Inductive bias assumption: $mse(w^*)$ is small, i.e., there is a linear function with low MSE.
 - This is a fairly "weak" modeling assumption, especially compared to the normal regression model.
- How much larger is $mse(\hat{w})$ compared to $mse(w^*)$?

Performance of OLS (2)

Theorem: In the IID model, the OLS solution \hat{w} satisfies

$$n\left(\mathbb{E}[\operatorname{mse}(\hat{w})] - \operatorname{mse}(w^*)\right) \to \operatorname{tr}(\operatorname{cov}(\varepsilon W))$$

as $n \to \infty$, where $W = \mathbb{E}[XX^{\mathsf{T}}]^{-1/2}X$ and $\varepsilon = Y - X^{\mathsf{T}}w^*$.

► Corollary: If, in addition, (X, Y) follows the normal linear regression model $Y \mid X = x \sim N(x^{\mathsf{T}}w^*, \sigma^2)$, then

$$n\left(\mathbb{E}[\operatorname{mse}(\hat{w})] - \operatorname{mse}(w^*)\right) \to \sigma^2 d,$$

which is more typically written as

$$\mathbb{E}[\operatorname{mse}(\hat{w})] \to \left(1 + \frac{d}{n}\right) \operatorname{mse}(w^*).$$

Linear algebraic view of OLS (1)

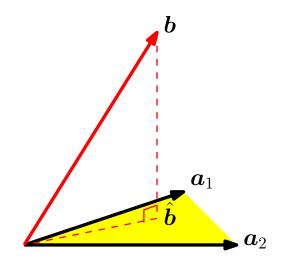


Figure 8: Orthogonal projection of b onto range(A)

Linear algebraic view of OLS (2)

- ▶ Solution \hat{b} is *orthogonal projection* of *b* onto range(*A*)
 - \hat{b} is unique
 - <u>Residual</u> $b \hat{b}$ is orthogonal to \hat{b}
 - To get w from \hat{b} , solve $Aw = \hat{b}$ for w.
 - If rank(A) < d (always the case if n < d), then infinitely-many ways to write b̂ as linear combination of a₁,..., a_d.
- ► Upshot: Uniqueness of least squares solution requires n ≥ d, and n < d guarantees non-uniqueness!</p>

Over-fitting (1)

In the IID model, <u>over-fitting</u> is the phenomenon where the true risk is much worse than the empirical risk.

Over-fitting (2)

Example:

- φ(x) = (1, x, x², ..., x^k), degree-k polynomial expansion

 Dimension is d = k + 1
- Any function of $\leq k + 1$ points can be interpolated by polynomial of degree $\leq k$
- So if n ≤ k + 1 = d, least squares solution ŵ will have zero empirical risk, regardless of its true risk (assuming no two training examples with distinct x_i's have different y_i's).

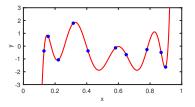


Figure 9: Polynomial interpolation

Beyond empirical risk minimization

Recall plug-in principle

- ▶ Want to minimize risk with respect to (unavailable) *P*; use *P_n* instead
- What if we can't regard data as iid from P?
 - Example: Suppose we know $P = \frac{1}{2}M + \frac{1}{2}F$ (*mixture distribution*)
 - \blacktriangleright We get size n_1 iid sample from M, and size n_2 iid sample from $F,\,n_2 \ll n_1$
 - How to implement plug-in principle?