

AdaBoost

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The algorithm

The input training data is $\{(x_i, y_i)\}_{i=1}^n$ from $\mathcal{X} \times \{-1, +1\}$.

- Initialize $D_1(i) := 1/n$ for each $i = 1, \dots, n$.
- For $t = 1, \dots, T$, do:
 - Give D_t -weighted examples to Weak Learner; get back $h_t: \mathcal{X} \rightarrow \{-1, +1\}$.
 - Compute weight on h_t and update weights on examples:

$$s_t := \sum_{i=1}^n D_t(i) \cdot y_i h_t(x_i)$$
$$\alpha_t := \frac{1}{2} \ln \frac{1 + s_t}{1 - s_t}$$
$$D_{t+1}(i) := \frac{D_t(i) \cdot \exp(-\alpha_t \cdot y_i h_t(x_i))}{Z_t} \quad \text{for each } i = 1, \dots, n$$

where

$$Z_t := \sum_{i=1}^n D_t(i) \cdot \exp(-\alpha_t \cdot y_i h_t(x_i))$$

is the normalizer that makes D_{t+1} a probability distribution.

- Final hypothesis is \hat{h} defined by $\hat{h}(x) := \text{sign}\left(\sum_{t=1}^T \alpha_t \cdot h_t(x)\right)$ for $x \in \mathcal{X}$.

Training error rate bound

Let $\hat{\ell}$ be the function defined by

$$\hat{\ell}(x) := \sum_{t=1}^T \alpha_t \cdot h_t(x) \quad \text{for } x \in \mathcal{X}$$

so $\hat{h}(x) = \text{sign}(\hat{\ell}(x))$. The training error rate of \hat{h} can be bounded above by the average exponential loss of $\hat{\ell}$:

$$\frac{1}{n} \sum_{i=1}^n \mathbf{1}\{\hat{h}(x_i) \neq y_i\} \leq \frac{1}{n} \sum_{i=1}^n \exp(-y_i \hat{\ell}(x_i)).$$

This holds because

$$\hat{h}(x_i) \neq y_i \Leftrightarrow -y_i \hat{\ell}(x_i) \geq 0 \Leftrightarrow \exp(-y_i \hat{\ell}(x_i)) \geq 1.$$

Furthermore, the average exponential loss of $\hat{\ell}$ equals the product of the normalizers from all rounds:

$$\begin{aligned}
\frac{1}{n} \sum_{i=1}^n \exp(-y_i \hat{\ell}(x_i)) &= \sum_{i=1}^n D_1(i) \cdot \exp\left(-\sum_{t=1}^T \alpha_t \cdot y_i h_t(x_i)\right) \\
&= Z_1 \sum_{i=1}^n \frac{D_1(i) \cdot \exp(-\alpha_1 \cdot y_i h_1(x_i))}{Z_1} \cdot \exp\left(-\sum_{t=2}^T \alpha_t \cdot y_i h_t(x_i)\right) \\
&= Z_1 \sum_{i=1}^n D_2(i) \cdot \exp\left(-\sum_{t=2}^T \alpha_t \cdot y_i h_t(x_i)\right) \\
&= Z_1 Z_2 \sum_{i=1}^n \frac{D_2(i) \cdot \exp(-\alpha_2 \cdot y_i h_2(x_i))}{Z_2} \cdot \exp\left(-\sum_{t=3}^T \alpha_t \cdot y_i h_t(x_i)\right) \\
&= Z_1 Z_2 Z_3 \sum_{i=1}^n D_3(i) \cdot \exp\left(-\sum_{t=3}^T \alpha_t \cdot y_i h_t(x_i)\right) \\
&= \dots \\
&= \prod_{t=1}^T Z_t.
\end{aligned}$$

Since each $y_i h_t(x_i) \in \{-1, +1\}$, the normalizer Z_t can be written as

$$\begin{aligned}
Z_t &= \sum_{i=1}^n D_t(i) \cdot \exp(-\alpha_t \cdot y_i h_t(x_i)) \\
&= \sum_{i=1}^n D_t(i) \cdot \left(\frac{1 + y_i h_t(x_i)}{2} \exp(-\alpha_t) + \frac{1 - y_i h_t(x_i)}{2} \exp(\alpha_t) \right) \\
&= \sum_{i=1}^n D_t(i) \cdot \left(\frac{1 + y_i h_t(x_i)}{2} \sqrt{\frac{1 - s_t}{1 + s_t}} + \frac{1 - y_i h_t(x_i)}{2} \sqrt{\frac{1 + s_t}{1 - s_t}} \right) \\
&= \sqrt{(1 + s_t)(1 - s_t)} \\
&= \sqrt{1 - s_t^2}.
\end{aligned}$$

So, we conclude the following bound on the training error rate of \hat{h} :

$$\frac{1}{n} \sum_{i=1}^n \mathbf{1}\{\hat{h}(x_i) \neq y_i\} \leq \frac{1}{n} \sum_{i=1}^n \exp(-y_i \hat{\ell}(x_i)) = \prod_{t=1}^T Z_t = \prod_{t=1}^T \sqrt{1 - s_t^2} \leq \exp\left(-\frac{1}{2} \sum_{t=1}^T s_t^2\right)$$

where the last step uses the fact that $1 + x \leq e^x$ for any real number x .

(The bound is usually written in terms of $\gamma_t := s_t/2$, i.e., as $\exp(-2 \sum_{t=1}^T \gamma_t^2)$.)

Margins on training examples

Let \hat{g} be the function defined by

$$\hat{g}(x) := \frac{\sum_{t=1}^T \alpha_t \cdot h_t(x)}{\sum_{t=1}^T |\alpha_t|} \quad \text{for } x \in \mathcal{X}$$

so $y_i \hat{g}(x_i)$ is the margin achieved on example (x_i, y_i) . We may assume without loss of generality that $\alpha_t \geq 0$ for each $t = 1, \dots, T$ (by replacing h_t with $-h_t$ as needed.) Fix a value $\theta \in (0, 1)$, and consider the fraction

of training examples on which \hat{g} achieves a margin at most θ :

$$\frac{1}{n} \sum_{i=1}^n \mathbf{1}\{y_i \hat{g}(x_i) \leq \theta\}.$$

This quantity can be bounded above using the arguments from before:

$$\begin{aligned} \frac{1}{n} \sum_{i=1}^n \mathbf{1}\{y_i \hat{g}(x_i) \leq \theta\} &= \frac{1}{n} \sum_{i=1}^n \mathbf{1}\left\{y_i \hat{\ell}(x_i) \leq \theta \sum_{t=1}^T \alpha_t\right\} \\ &\leq \exp\left(\theta \sum_{t=1}^T \alpha_t\right) \cdot \frac{1}{n} \sum_{i=1}^n \exp(-y_i \hat{\ell}(x_i)) \\ &= \exp\left(\theta \sum_{t=1}^T \alpha_t\right) \cdot \prod_{t=1}^T \sqrt{1 - s_t^2} \\ &= \prod_{t=1}^T \sqrt{(1 + s_t)^{1+\theta} (1 - s_t)^{1-\theta}}. \end{aligned}$$

Suppose that for some $\gamma > 0$, $s_t \geq 2\gamma$ for all $t = 1, \dots, T$. If $\theta < \gamma$, then using calculus, it can be shown that each term in the product is less than 1:

$$\sqrt{(1 + s_t)^{1+\theta} (1 - s_t)^{1-\theta}} < 1.$$

Hence, the bound decreases to zero exponentially fast with T .