

Last time:

- Randomized Weighted Majority alg (RWM)
- Start next unit:

Probably Approximately Correct (PAC)
Learning Model

- motivation
- basic definition
- learning $\mathcal{C}$ = intervals over $X = \mathbb{R}$
(start)

Today:

- Finish PAC learning $\mathcal{C}$ = intervals over $X = \mathbb{R}$
- OLCMB $\Rightarrow$ PAC conversion: get all our OLCMB results in PAC model "

- Revisit PAC learning definition:

- "size" of concepts
- efficiency of evaluating hyp. h

- "Chernoff bounds" (tail bounds on sums of indep. random variables) + applic. to hypothesis testing

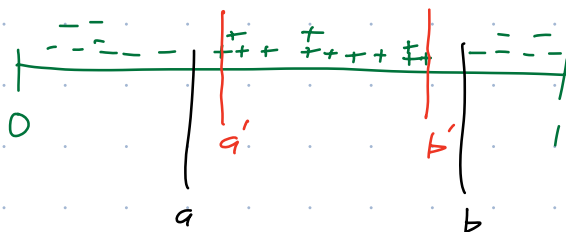
Admin:

- ps1 sol. out tonight
- graded ps1 back soon

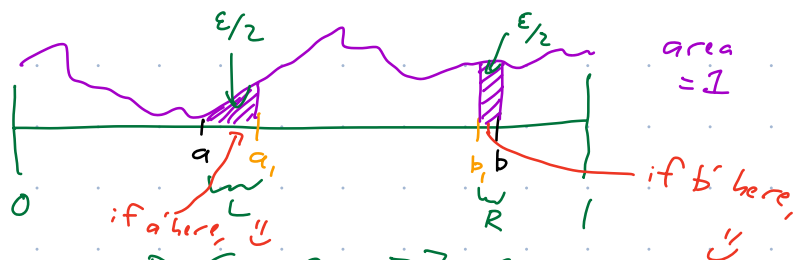
Questions?

Recall our int. learning problem:

Data POV:



"Analysis POV":



Define $a_1 =$ value s.t. $\Pr_{x \sim \mathcal{D}}[x \in [a, a_1]] = \epsilon/2$

$b_1 =$ value s.t. $\Pr_{x \sim \mathcal{D}}[x \in [b_1, b]] = \epsilon/2$.

Obs: if got
 • an ex. in $[a, a_1]$, +
 • an ex. in $[b_1, b]$,
 then error of our hyp. is $\leq \epsilon/2 + \epsilon/2 = \epsilon$ ✓.

$$\Pr_{x \sim \mathcal{D}}[x \text{ misses } L] = 1 - \epsilon/2$$

$$\text{So } \Pr[m \text{ indep. ex. all miss } L] = (1 - \epsilon/2)^m$$

$$\text{Like wise } R = (1 - \epsilon/2)^m.$$

$$\text{So as long as } \left(1 - \frac{\epsilon}{2}\right)^m \leq \frac{\delta}{2},$$

$$\text{have } \Pr[\text{some ex. hit } L, \text{ and } \text{some ex. hit } R] \geq 1 - 2 \cdot \frac{\delta}{2} = 1 - \delta.$$

→ Recall $1 - x \leq e^{-x}$, so

$$\left(1 - \frac{\epsilon}{2}\right)^m \leq e^{-\frac{\epsilon}{2} \cdot m}; \text{ to have this } \leq \frac{\delta}{2},$$

take $m = \frac{2}{\epsilon} \cdot \ln\left(\frac{2}{\delta}\right)$.

For indep. events A, B ,

$$\Pr[A \wedge B] = \Pr[A] \cdot \Pr[B].$$

For any events A, B ,

$$\Pr[A \text{ or } B] \leq \Pr[A] + \Pr[B].$$

Note: δ controls prob. that sample is "bad"/atypical;

ϵ controls (inevitable) small error.

OLMB to PAC Conversion

Say A is an OLMB alg. w/ mist. bd. M
 $\Rightarrow$ for ϵ .

Can automatically get PAC alg for $\mathcal{C}$:

Thm: If $\quad$, then there's a PAC learner for $\mathcal{C}$
with sample complexity

$$m \leq M + \frac{M+1}{\epsilon} \cdot \ln\left(\frac{M+1}{\delta}\right).$$

(Comput. efficiency also preserved.)

Pf: Say OLCMB alg A is conservative
if it only updates its h when makes mistake.

Claim: If $\exists A$, then $\exists$ conservative.

Justif.: The conserv. version, A' , simply ignores ex. (doesn't update h) on which no mistake.

This can't make $M+1$ mist. on any seq., or else A would too. $\times$.

So, we can assume A is conservative.

A natural PAC alg:

Run A on seq. of indep. ex. from $EX(c, \mathcal{P})$.
Keep track, for each hyp. h that is current hyp,
of # examples in a row it got right.

If h gets $\frac{1}{\epsilon} \cdot \ln\left(\frac{M+1}{\delta}\right)$ ex. right in a row,
stop & output that h .

Note: this alg. uses $\leq M + \frac{M+1}{\epsilon} \cdot \ln\left(\frac{M+1}{\delta}\right)$ ex:

$\leq \frac{1}{\epsilon} \cdot \ln\left(\frac{M+1}{\delta}\right)$ $M+1$ mistakes

$\begin{array}{ccccccc} \checkmark & \checkmark & \checkmark & \dots & \checkmark & \times & \checkmark & \dots & \checkmark & \times & \checkmark & \dots & \checkmark & \times & \dots & \times & \checkmark & \dots & \checkmark \\ \uparrow & \uparrow & & & \uparrow & \uparrow & \uparrow & & \uparrow & \uparrow & \uparrow & & \uparrow & \uparrow & & \uparrow & \uparrow & & \uparrow \\ h \text{ right} & & & & h \text{ wrong,} & & & & & & & & & & & & & & \end{array}$

$\leq M$ $\times$'s (mistakes)

$\leq M+1$ many "runs"

of $\leq \frac{1}{\epsilon} \cdot \ln\left(\frac{M+1}{\delta}\right)$

$\checkmark$'s

Remains to show: $\Pr\{\text{output } (1-\epsilon) \text{ acc. hyp}\} \geq 1-\delta.$

Say a hyp. h is bad if $\text{err}_D(h, c) > \epsilon.$

We'll argue: $\Pr\{\text{our alg. outputs a bad } h\} \leq \delta;$
then done.

Fix any bad $h.$

$$\Pr_{x \sim D}[h(x) \neq c(x)] > \epsilon, \text{ i.e. } \Pr_{x \sim D}[h(x) = c(x)] < 1-\epsilon.$$

So $\Pr[h \text{ gets } k \text{ ex. right in a row}] < (1-\epsilon)^k.$

For $k = \frac{1}{\epsilon} \cdot \ln\left(\frac{M+1}{\delta}\right),$
 $(1-x \leq e^{-x})$

$\searrow < \frac{\delta}{M+1}$

Since $\leq M+1$ distinct h 's ever generated by the alg A (conservative!),

by UB over all bad hyp's A generates ($\leq M+1$ many),

$$\Pr[\text{any bad } h \text{ is output}] \leq (M+1) \cdot \frac{\delta}{M+1} = \delta. \blacksquare$$

So we have PAC alg's for all our specific $\mathcal{C}$'s from OCMB unit.

Ex: can PAC learn conj. over $\{0,1\}^n$ with

$$m \leq n + \frac{n+1}{\epsilon} \cdot \ln\left(\frac{n+1}{\epsilon}\right) = O\left(\frac{n}{\epsilon} \cdot \ln\left(\frac{1}{\epsilon}\right)\right)$$

examples.

$OLMB \Rightarrow PAC.$

$PAC \xRightarrow{\text{does not}} OLMB:$

- $\mathcal{C} = \text{intervals}$
- is PAC learnable
 - is not OLMB learnable w/ finite mistake bd.

Refine our notion of PAC learning, by considering

- (1) "size" / "complexity" of target c ;
- (2) efficient evaluability of hyp. h .

①: Often natural to have a notion of "size" or "cxity" of concepts $c \in \mathcal{C}$.

Ex: size k of a disj. over $\{0,1\}^n$

Ex: $\mathcal{C} = \{\text{all DNF formulas over } \{0,1\}^n\}.$

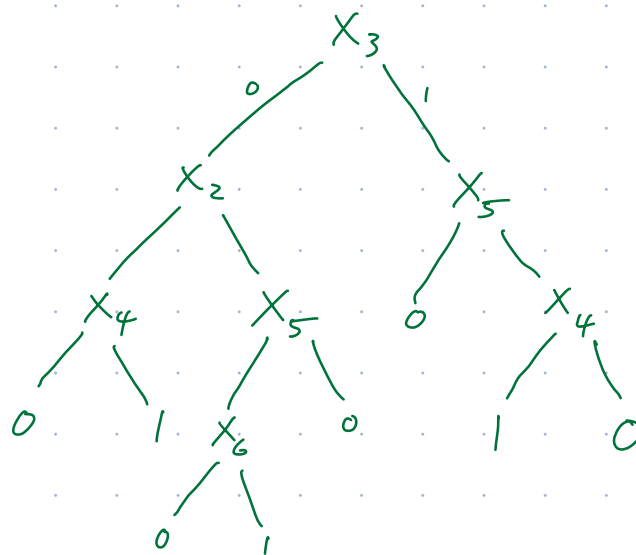
Can define $DNFSIZE(f)$, for any $f: \{0,1\}^n \rightarrow \{0,1\}$, as min # terms in any DNF computing f .

$\rightarrow$ (dream)

A' ONF learning alg would be allowed to run in time $\text{poly}(n, \underline{\text{DNFSIZE}(c)}, \frac{1}{\epsilon}, \frac{1}{\delta})$.

Other classes also have size param's as well: ^{associated}

Ex: a Boolean decision tree is a fn $f: \{0,1\}^n \rightarrow \{0,1\}$ like



size = #leaves
depth = depth

②: What hyp. classes $\mathcal{H}$ are reasonable?

$\mathcal{C}$ = class of functions

$\mathcal{H}$ = class of representations of functions
(i.e. of programs)

$h = x_3 \vee x_4 \vee x_7$

If a learning alg outputs a hyp. h that takes very long to run, not useful...

We say a hyp. class $\mathcal{H}$ over $\{0,1\}^n$ or $\mathbb{R}^n$ is polynomially evaluable if every $h \in \mathcal{H}$ can be evaluated, on every x , in $\text{poly}(n)$ time.

An efficient PAC learner must use a .

Or: view runtime of PAC learner as

- time to construct h , +
 - time to evaluate h .
-

Tail bounds on sums of indep. RV's, & "hypothesis testing".

PAC scenario: have a hyp. h ,
have $EX(c, \mathcal{D})$.

Natural q: how good is h ? what is $er_{\mathcal{D}}(h, c)$?

Natural answer:

- draw m ex from $EX(c, \mathcal{D})$
compute $h(x)$ on each.

guess for
is $\frac{(\# \text{ ex. of the } m \text{ that } h \text{ got } \overset{\text{wrong}}{\text{wrong}})}{m}$

How good is this
estimate of ?

$\equiv$ to:

Have $(\$)$ coin w $\Pr[\text{Heads}] = p$ ^{unknown} $\downarrow$

To estimate p : toss coin m times,
output $\frac{(\#H \text{ you got})}{m}$.

How good is this estimate?

Next time: tools for this.
