

**Digital Picture Frame
Final Report**

**Embedded Systems
Spring 2005
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Introduction:

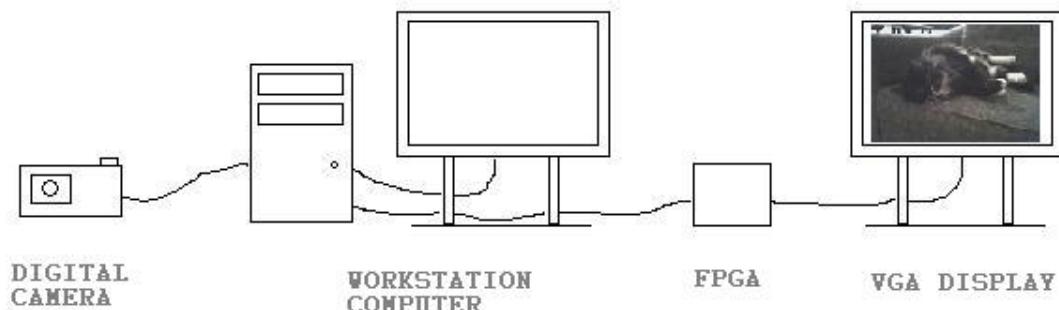
Digital images have replaced film in the common household, and for good reason. Film is expensive, must be bought, must be inserted into the camera, taken out, and developed. Film is expensive, and the development process is time consuming. ‘Hard’ pictures degrade over time, cannot be manipulated, are costly, take up physical space (photo albums), and can be sent only as fast as the mail can go.

Digital images and cameras have vastly improved upon the old process of image capture/management. For a relatively low cost, a digital camera can be bought with a memory stick, and then all the user has to do is point and click. The user will empty the images onto a computer when he/she feels like; then have an empty memory card ready to go. The images can be archived on disk, sent around the world instantly and can be manipulated using any one of the many programs for graphics.

To get digital pictures in a frame, the user will most likely print them out; then manually insert them into the frame. We are suggesting a digital picture frame that allows the user to download the picture onto the picture frame module; then have the module display the picture onto a VGA display.

Hardware:

- 1) Personal computer that is capable of manipulating JPEGS, and equipped with a serial port.
- 2) XESS XSB-300E SPARTAN 2E FPGA. This is a FPGA which is sold by XESS. More information can be found [here](#).
- 3) VGA monitor.
- 4) All necessary cables/connectors that are needed to put the pieces of hardware together. We assume that the end user has already used a proprietary digital camera to place the images onto the computer.



The Flow of the project:

The original idea was to implement a jpeg decoder purely in hardware. Since it was a proud work of a couple of doctorate students, we decided to move on software.

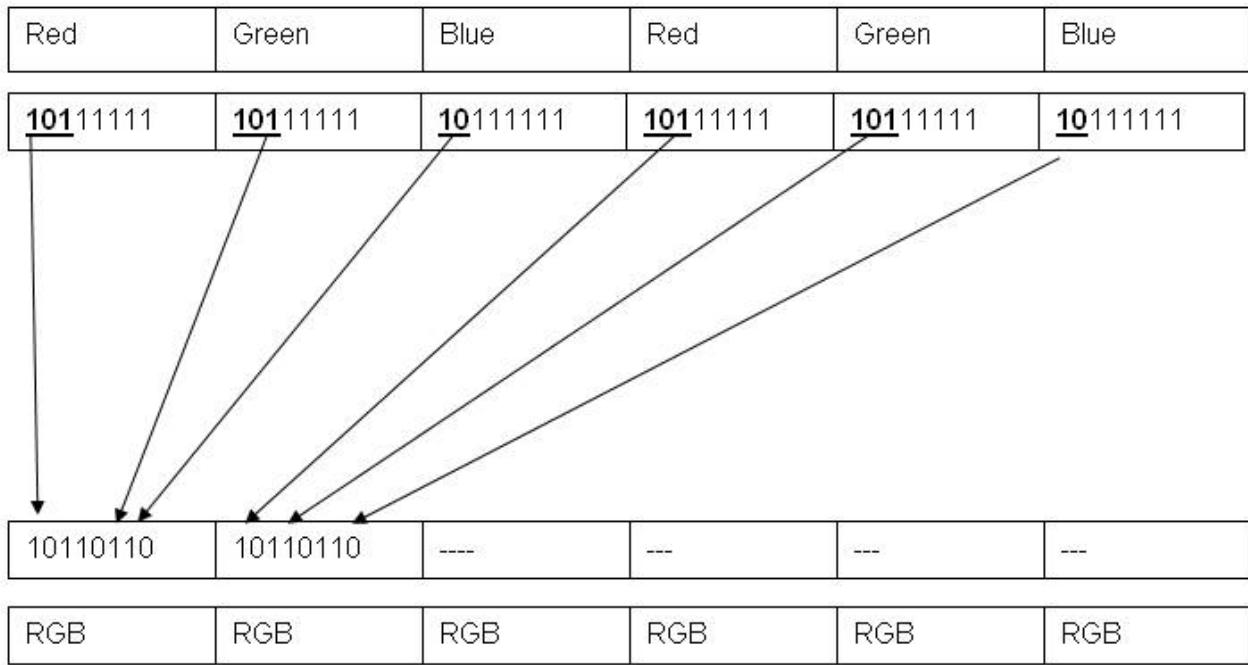
After a month of trying to simplify the robust code of Independent JPEG group and run their library on the board itself, we got a permission of Prof. Edwards to use the DJPEG software and continue

Software:

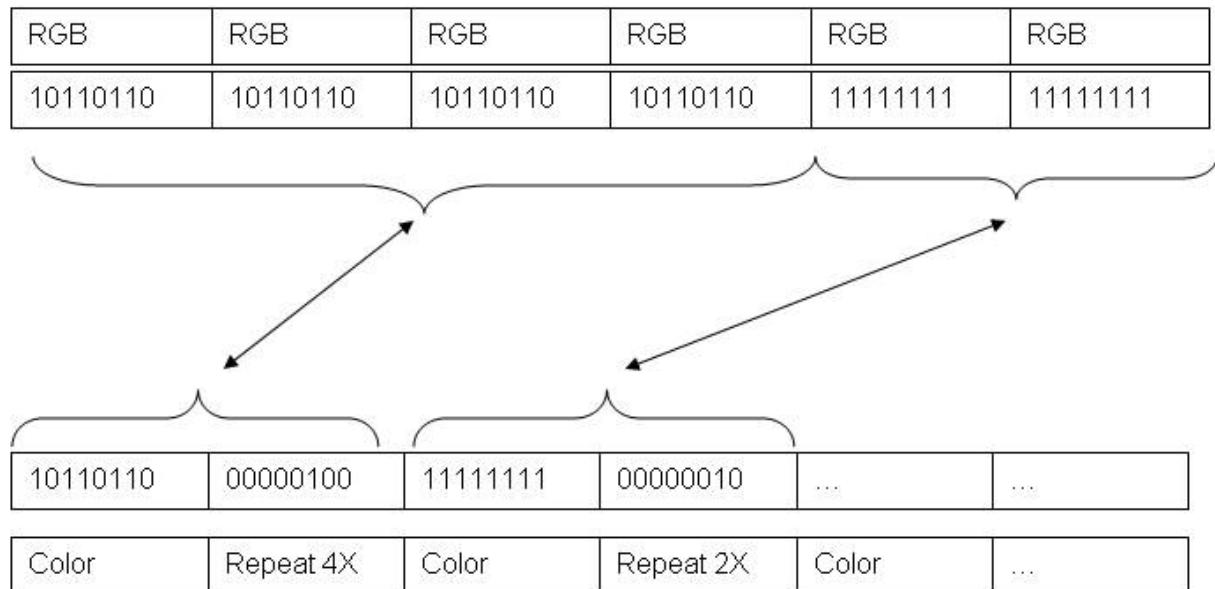
We are using several pieces of software to get the image to its final destination on the monitor. Our test picture is a picture of Olympus, Sam's cat.

- 1) DJPEG: We are using a class library called djpeg that is distributed by the Independent JPEG group. Information about them, and code, and be found [here](#). The program takes as input a JPEG, we are using an image that is 640X480, and outputs the image in a PPM format. A PPM is a ‘portable pixel map’, and has information stored in red/green/blue values, more information [here](#).
- 2) PPM2BIN: We then take the PPM file, strip the padding, and process each pixel. There are 3 bytes of color information, one byte a piece for red/green/blue. We take the first three bits of red, first three bits of green and first two bits of blue, and put them into a new color. This color will now be representative of the pixel.
- 3) TEST232: A program that Marcio Buss showed us how to use. It simply opens up the serial port and sends a file across the port byte by byte.
- 4) COMPRESS: It was taking a long time to draw the picture as we were sending a byte for each pixel across the serial cable. 307200 bytes were being sent across at 9600 baud. We decided to use a compression technique that is based on run length encoding. Since many of the adjacent pixels in a JPEG are of the same color, we decided we could create a compression program that would look ahead, and see how many pixels there are in a line that are of the same color. We will then send two bytes, the first byte with the color and the second byte with the number of pixels that are of that color. This look ahead only works for up to 256 pixels, as that is all the information that can be held in eight bits. But that is plenty anyway because (excluding test pictures with only a couple of colors) on the average repetition of the pixels with same color is less than 50.
- 5) MAIN.C/ISR.C: On the receiving end. These programs are set up to grab each byte as they come across the serial port. The programs take the first byte, set the color, take the second byte, and loop the number of pixels of that color. This makes picture display much faster. The technique used here is a large FIFO buffer with two pointers chasing each other. First one is the pointer to the fresh data and the second one is the pointer to the data that is being read and processed on the screen. The size of the buffer determines the flexibility of the process, increases the speed and minimizes the probability of error
- 6) HARDWARE SIMULATION: memoryctrl.vhd, opb_xsb200.vhd, pad_io.vhd, vga_timing.vhd, vga.vhd. These files are taken from last year’s Lab 5 and are used to control the video display.

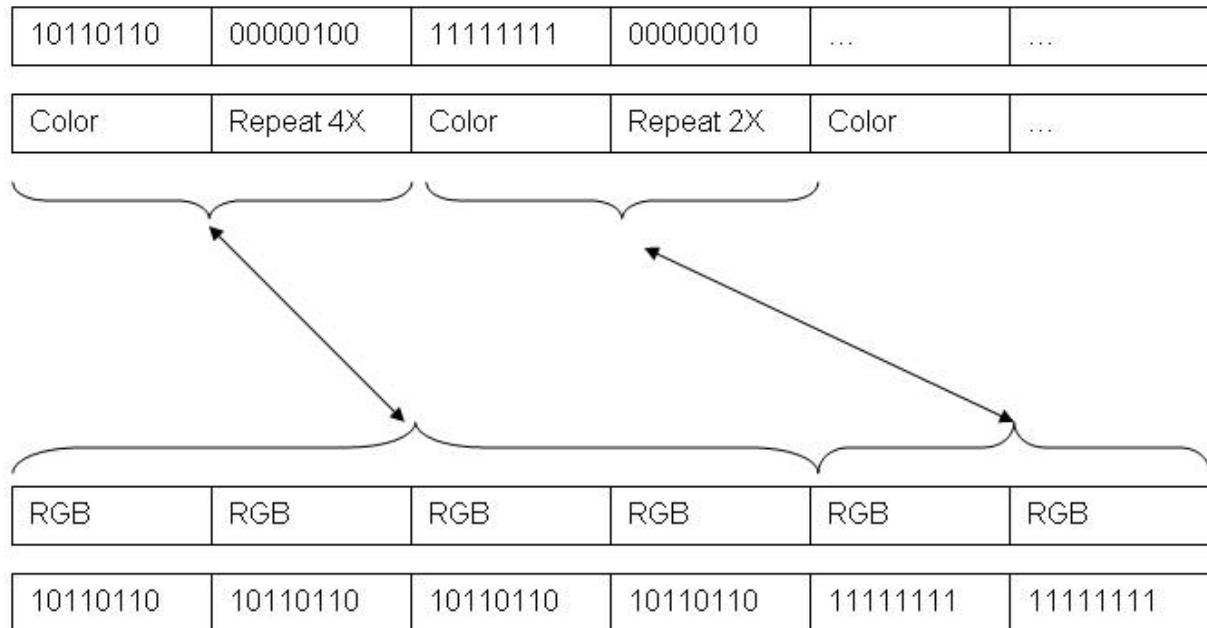
ppm2bin



Compress



Decompress



Command Log:

```
#make download  
#djpeg < olympus.jpg > olympus.ppm  
#./ppm2bin olympus.pnm olympus.bin  
#./compress olympus.bin olympus.nas  
#./test232 < olympus.nas
```

A user can also browse to the c_source_files and use the command:

```
#sh ./LoadPicture.sh
```

to run a shell script that will automatically put everything on the board and take care of all the picture manipulation. All the user has to do is rename the image ‘picturetoload.jpg’ and place it in the jpg folder.

The above commands will put an image onto the VGA monitor.

Continuing Implementation:

Quality: The picture is noticeably fuzzy and blocky. This is because of the sampling that is being done in ppm2bin. There are ways to smooth the picture out, namely using a dithering algorithm. Dithering uses the concept of blurring, or juxtaposing, adjacent pixels to make it appear as though there is a third color.

The benefits of dithering can be seen in these two pictures:



The dithering algorithm can be implemented in code, but for our purposes, and under our time constraints, we decided to focus more on the speed of getting the image across. With the speed in place, it will be easier for someone to work on the quality of the picture.

Conclusions:

Who did what:

Nenad and Sam worked on all parts of the implementation together. Each of us pushed ahead with all testing, development and troubleshooting.

Lessons learned:

- The FPGA has limited memory resources. We spent much time trying to strip down the DJPEG code to no functioning avail.
- The serial port is terribly slow; we even kicked around transferring through USB or parallel, but did not have the time to begin thinking of any of those implementations.
- I personally dislike the lab when it is busy, the best times to work are during the week from ~7 to ~10.

Advice on future projects:

- Of course start early.
- Ask questions, Professor Edwards and the T.A. (s) are there to help, and are more than willing to do so.
- Do not be disheartened with the complexity and apparent difficulty of the work. At the beginning of this project we had no idea how we were going to actually implement anything. But after much time in the lab, and asking questions, we slowly pushed our way forward towards completion.

Code:

Code Listing:

ppm2bin.c
compress.c
test232.c
isr.c
main.c
system.mhs
Makefile
PictureLoad.sh
memoryctyl.vhd
opb_xsb300.vhd
pad_io.vhd
vga.vhd
vga_timing.vhd

ppm2bin.c:

```
#include <stdio.h>

FILE *ip, *op;
int red, green, blue, color, redl, greenl, bluel;

void fskip(FILE *ip, int num_bytes)
{
    int i;
```

```

    for (i=0; i<num_bytes; i++)
        fgetc(ip);
}

int main (int argc, char *argv[])
{
    if ((ip = fopen (argv[1], "rb")) == NULL)
    {
        printf("Cannot open input \n", argv[1]);
        return(1);
    }
    if ((op = fopen(argv[2], "wb")) == NULL)
    {
        printf("Cannont open output \n", argv[2]);
        return(2);
    }

    fskip(ip, 15);

    do
    {
        red1 = fgetc(ip);
        green1 = fgetc(ip);
        blue1 = fgetc(ip);

        red = red1 & 0xE0;
        green = green1 & 0xE0;
        green = green >> 3;
        blue = blue1 & 0xC0;
        blue = blue >> 6;

        color = red | green | blue;
        fputc(color, op);

    }while ((red1!=EOF) | (green1!=EOF) | (blue1!=EOF));
    printf("DONE \n");
    fclose(ip);
    fclose(op);
    return(0);
}

```

compress.c:

```

#include <stdio.h>

FILE *ip, *op;

int color, another;
int counter;

int main (int argc, char *argv[])
{
    if ((ip = fopen (argv[1], "rb")) == NULL)
    {
        printf("Cannot open input \n", argv[1]);
        return(1);
    }

```

```

        }
if ((op = fopen(argv[2], "wb")) == NULL)
{
    printf("Cannont open output \n", argv[2]);
    return(2);
}

color = fgetc(ip);
another = fgetc(ip);
counter = 1;

do
{
    if (color == another)
    {
        counter++;

        if (counter == 120)
        {
            fputc(color, op);
            //printf("color %d    ",color);
            fputc(counter, op);
            //printf("counter %d \n", counter);
            color = another;
            another = fgetc(ip);
            counter = 1;
        }
        another = fgetc(ip);

    } else
    {
        fputc(color, op);
        //printf("color %d    ",color);
        fputc(counter, op);
        //printf("counter %d \n", counter);
        color = another;
        another = fgetc(ip);
        counter = 1;
    }
} while ((color!=EOF) | (another!=EOF));

printf("DONE \n");
fclose(ip);
fclose(op);
return(0);
}

```

test232.c:

```

#include <stdio.h>
#include <unistd.h>
#include <sys/types.h>
#include <sys/stat.h>
#include <sys/select.h>
#include <fcntl.h>
#include <termios.h>
#include <string.h>
#include <errno.h>

```

```

#define DEBUG 0

int main()
{
    char rdbuf[1024], tdbuf[1024];

    int fd, nbrx, nbtw, ptx, prx, nb;
    fd_set rfdsin, rfdsout;

    struct termios my_termios;

    fd = open( "/dev/ttyS0", O_RDWR | O_NOCTTY | O_NDELAY);

    // configure the serial port
    tcgetattr(fd, &my_termios);
    tcflush(fd, TCIFLUSH);
    my_termios.c_cflag = B9600 | CS8 |CREAD | CLOCAL | HUPCL;
    cfmakeraw(&my_termios);
    cfsetospeed(&my_termios, B9600);
    tcsetattr(fd, TCSANOW, &my_termios);

    nbtw=nbrx=0; ptx=prx=0;

    // the following code tries to be as "nice" as possible

    FD_SET(0, &rfdsin); // stdin
    FD_SET(fd, &rfdsin); // rs232 rx

    while(1){

        FD_ZERO(&rfdsin);
        FD_ZERO(&rfdsout);

        if(nbtw==0) FD_SET(0, &rfdsin); else FD_SET(fd, &rfdsout);
        if(nbrx==0) FD_SET(fd, &rfdsin); else FD_SET(1, &rfdsout);

        select(5, &rfdsin, &rfdsout, NULL, NULL);

        if(nbtw == 0 && FD_ISSET(0, &rfdsin)){ // tx buf empty and data on stdin
            ptx=0;
            nbtw=read(0,tdbuf,1024);
            DEBUG && fprintf(stderr,"stdin: read %d\n",nbtw);
        }

        if(nbtw > 0 && FD_ISSET(fd, &rfdsout)){ // have tx data and rs232 free
            nb= write(fd,tdbuf+ptx, nbtw);
            DEBUG && fprintf(stderr,"rs232: wrote %d\n",nb);
            ptx += nb;
            nbtw -= nb;
        }

        if(nbrx == 0 && FD_ISSET(fd, &rfdsin)){ // rx buf empty and data on rs232
            prx=0;
            nbrx=read(fd,rdbuf,1024);
            DEBUG && fprintf(stderr,"rs232: read %d\n",nbrx);
        }
    }
}

```

```

    }

    if(nbrx > 0 && FD_ISSET(1, &rfdsout)){ // have rx data and stdout free
        nb=write(1, rdbuf+prx, nbrx);
        DEBUG && fprintf(stderr,"stdout: wrote %d\n",nb);
        prx+= nb;
        nbrx -= nb;
    }
}

close(fd);
}

```

isr.c:

```

#include "xbasic_types.h"
#include "xio.h"
#include "xparameters.h"
#include "xuartlite_1.h"

#define BUFFSIZE 15000

int uart_interrupt_count = 0;
char uart_character;
char buffer[BUFFSIZE];
char *last_in = buffer;
char *last_out = buffer;
int last_in_loop_count = 0;

/*
 * Interrupt service routine for the UART
 */
void uart_handler(void *callback)
{
    Xuint32 IsrStatus;

    Xuint8 incoming_character;

    /* Check the ISR status register so we can identify the interrupt source */
    IsrStatus = XIo_In32(XPAR_MYUART_BASEADDR + XUL_STATUS_REG_OFFSET);

    if (((IsrStatus & (XUL_SR_RX_FIFO_FULL | XUL_SR_RX_FIFO_VALID_DATA)) != 0) {
        /* The input FIFO contains data: read it */
        incoming_character =
            (Xuint8) XIo_In32( XPAR_MYUART_BASEADDR + XUL_RX_FIFO_OFFSET );

        uart_character = incoming_character;
        ++uart_interrupt_count;
    }

    if (((IsrStatus & XUL_SR_TX_FIFO_EMPTY) != 0) {
        /* The output FIFO is empty: we can send another character */
    }

    /*
     * putting data into buffer
     * will read it in main.c
     */
}

if (last_in == buffer + BUFFSIZE) // loop around

```

```

    {
        last_in = buffer;
        last_in_loop_count++;
    }

    *last_in = uart_character; //input a new character
    last_in++; //pointer
}

main.c:
#include "xbasic_types.h"
#include "xio.h"

#include "xintc_l.h"
#include "xuartlite_l.h"

#define W 640
#define H 480
#define VGA_START 0x00800000
#define RED 0xE0
#define GREEN 0x1C
#define BLUE 0x03

#define BUFFSIZE 15000

// defined in isr.c

extern void uart_handler(void *callback);
extern volatile int uart_interrupt_count;
extern volatile char uart_character;
extern volatile char buffer[BUFFSIZE];
extern volatile char *last_in;
extern volatile char *last_out;
extern volatile int last_in_loop_count;

int z=0;
int init_count;
char color;
char counter;
int last_out_loop_count = 0;

/*
 * setup_interrupts: Initialize the interrupt sources and handlers
 *
 * Should be called once when the system starts
 *
 * The main _interrupt_handler() function from Xilinx
 *
 * Saves and restores CPU context, etc.
 *
 * Sees which interrupts are pending, and for each it
 *      acknowledges the interrupt and
 *      calls a user-defined interrupt handler in Xintc_InterruptVectorTable
 *
 * Place interrupt service routines in isr.c to ensure they are placed in
 * the proper memory segment.
 */

```

```

void setup_interrupts()
{
    /*
     * Reset the interrupt controller peripheral
     */

    /* Disable the interrupt signal */
    XIIntc_mMasterDisable(XPAR_INTC_SINGLE_BASEADDR);

    /* Disable all interrupt sources */
    XIIntc_mEnableIntr(XPAR_INTC_SINGLE_BASEADDR, 0);

    /* Acknowledge all possible interrupt sources
       to make sure none are pending */
    XIIntc_mAckIntr(XPAR_INTC_SINGLE_BASEADDR, 0xffffffff);

    /*
     * Install the UART interrupt handler
     */

    XIIntc_InterruptVectorTable[XPAR_INTC_MYUART_INTERRUPT_INTR].Handler =
        uart_handler;

    /*
     * Enable interrupt sources
     */

    /* Enable CPU interrupts */
    microblaze_enable_interrupts();

    /* Enable interrupts from the interrupt controller */
    XIIntc_mMasterEnable(XPAR_INTC_SINGLE_BASEADDR);

    /* Tell the interrupt controller to accept interrupts from the UART */
    XIIntc_mEnableIntr(XPAR_INTC_SINGLE_BASEADDR, XPAR_MYUART_INTERRUPT_MASK);

    /* Enable UART interrupt generation */
    XUartLite_mEnableIntr(XPAR_MYUART_BASEADDR);
}

void clear_screen()
{
    int q;
    for (q=0; q<H*W; q++)
    {
        XIo_Out8(VGA_START + q, 0);
    }
}

void write_pixel()
{
    char j;

    color = *last_out; // take color byte

    last_out++; // increment pointer value

    counter = *last_out; // take a byte that says
                        // how many times to repeat the color byte
}

```

```

if (last_out == buffer + BUFFSIZE) // loop around
{
    last_out = buffer;
    last_out_loop_count++;
}
else
    last_out++;

for (j=0; j<counter; j++) // display color byte counter times
{
    XIo_Out8(VGA_START + z, color);
    z++;
}
}

int main()
{
    microblaze_enable_icache();

    setup_interrupts();

    clear_screen();

    /* in the next few lines
     * skipping first two bytes
     * initializing stuff (can solve it with header, minor thing)*/
    init_count = uart_interrupt_count;
    while (init_count == uart_interrupt_count){}

    color = uart_character;

    init_count = uart_interrupt_count;
    while (init_count == uart_interrupt_count){}

    counter = uart_character;

    for (;;)
    {
        if (last_out == buffer + BUFFSIZE) // loop around
        {
            last_out = buffer;
            last_out_loop_count++;
        }

        if (last_in_loop_count > last_out_loop_count)
        {
            if (last_in < last_out)
            {
                write_pixel();
            }
        }

        if (last_out_loop_count == last_in_loop_count)

```

```

    {
        if (last_in > last_out + 1)          // write as long as we have fresh data
            write_pixel();
    }
    else {}

}

return 0;
}

```

system.mhs:

Parameters

PARAMETER VERSION = 2.0.0

Global Ports

```

PORT PB_A = PB_A, DIR = OUT, VEC = [19:0]
PORT PB_D = PB_D, DIR = INOUT, VEC = [15:0]
PORT PB_LB_N = PB_LB_N, DIR = OUT
PORT PB_UB_N = PB_UB_N, DIR = OUT
PORT PB_WE_N = PB_WE_N, DIR = OUT
PORT PB_OE_N = PB_OE_N, DIR = OUT
PORT RAM_CE_N = RAM_CE_N, DIR = OUT
PORT VIDOUT_CLK = VIDOUT_CLK, DIR = OUT
PORT VIDOUT_HSYNC_N = VIDOUT_HSYNC_N, DIR = OUT
PORT VIDOUT_VSYNC_N = VIDOUT_VSYNC_N, DIR = OUT
PORT VIDOUT_BLANK_N = VIDOUT_BLANK_N, DIR = OUT
PORT VIDOUT_RCR = VIDOUT_RCR, DIR = OUT, VEC = [9:0]
PORT VIDOUT_GY = VIDOUT_GY, DIR = OUT, VEC = [9:0]
PORT VIDOUT_BCB = VIDOUT_BCB, DIR = OUT, VEC = [9:0]
PORT FPGA_CLK1 = FPGA_CLK1, DIR = IN
PORT RS232_TD = RS232_TD, DIR=OUT
PORT RS232_RD = RS232_RD, DIR=IN
PORT AU_CSN_N = AU_CSN_N, DIR=OUT
PORT AU_BCLK = AU_BCLK, DIR=OUT
PORT AU_MCLK = AU_MCLK, DIR=OUT
PORT AU_LRCK = AU_LRCK, DIR=OUT
PORT AU_SDTI = AU_SDTI, DIR=OUT
PORT AU_SDTO0 = AU_SDTO0, DIR=IN

```

Sub Components

BEGIN microblaze

PARAMETER INSTANCE = mymicroblaze

PARAMETER HW_VER = 2.00.a

PARAMETER C_USE_BARREL = 1

PARAMETER C_USE_ICACHE = 1

PARAMETER C_ADDR_TAG_BITS = 6

PARAMETER C_CACHE_BYTE_SIZE = 2048

```
PARAMETER C_ICACHE_BASEADDR = 0x00860000
PARAMETER C_ICACHE_HIGHADDR = 0x0087FFFF
PORT Clk = sys_clk
PORT Reset = fpga_reset
PORT Interrupt = intr
BUS_INTERFACE DLMB = d_lmb
BUS_INTERFACE ILMB = i_lmb
BUS_INTERFACE DOPB = myopb_bus
BUS_INTERFACE IOPB = myopb_bus
END
```

```
BEGIN opb_intc
PARAMETER INSTANCE = intc
PARAMETER HW_VER = 1.00.c
PARAMETER C_BASEADDR = 0xFFFF0000
PARAMETER C_HIGHADDR = 0xFFFF00FF
PORT OPB_Clk = sys_clk
PORT Intr = uart_intr
PORT Irq = intr
BUS_INTERFACE SOPB = myopb_bus
END
```

```
BEGIN bram_block
PARAMETER INSTANCE = bram
PARAMETER HW_VER = 1.00.a
BUS_INTERFACE PORTA = conn_0
BUS_INTERFACE PORTB = conn_1
END
```

```
BEGIN opb_xsb300
PARAMETER INSTANCE = xsb300
PARAMETER HW_VER = 1.00.a
PARAMETER C_BASEADDR = 0x00800000
PARAMETER C_HIGHADDR = 0x00FFFFFF
PORT PB_A = PB_A
PORT PB_D = PB_D
PORT PB_LB_N = PB_LB_N
PORT PB_UB_N = PB_UB_N
PORT PB_WE_N = PB_WE_N
PORT PB_OE_N = PB_OE_N
PORT RAM_CE_N = RAM_CE_N
PORT OPB_Clk = sys_clk
PORT pixel_clock = pixel_clock
PORT VIDOUT_CLK = VIDOUT_CLK
PORT VIDOUT_HSYNC_N = VIDOUT_HSYNC_N
PORT VIDOUT_VSYNC_N = VIDOUT_VSYNC_N
PORT VIDOUT_BLANK_N = VIDOUT_BLANK_N
PORT VIDOUT_RCR = VIDOUT_RCR
PORT VIDOUT_GY = VIDOUT_GY
```

```
PORt VIDOUT_BCB = VIDOUT_BCB  
BUS_INTERFACE SOPB = myopb_bus  
END
```

```
BEGIN clkgen  
PARAMETER INSTANCE = clkgen_0  
PARAMETER HW_VER = 1.00.a  
PORT FPGA_CLK1 = FPGA_CLK1  
PORT sys_clk = sys_clk  
PORT pixel_clock = pixel_clock  
PORT fpga_reset = fpga_reset  
END
```

```
BEGIN lmb_lmb_bram_if_cntlr  
PARAMETER INSTANCE = lmb_lmb_bram_if_cntlr_0  
PARAMETER HW_VER = 1.00.a  
PARAMETER C_BASEADDR = 0x00000000  
PARAMETER C_HIGHADDR = 0x00000FFF  
BUS_INTERFACE DLMB = d_lmb  
BUS_INTERFACE ILMB = i_lmb  
BUS_INTERFACE PORTA = conn_0  
BUS_INTERFACE PORTB = conn_1  
END
```

```
BEGIN opb_uartlite  
PARAMETER INSTANCE = myuart  
PARAMETER HW_VER = 1.00.b  
PARAMETER C_CLK_FREQ = 50_000_000  
PARAMETER C_USE_PARITY = 0  
PARAMETER C_BASEADDR = 0xFEFF0100  
PARAMETER C_HIGHADDR = 0xFEFF01FF  
PORT OPB_Clk = sys_clk  
PORT Interrupt = uart_intr  
BUS_INTERFACE SOPB = myopb_bus  
PORT RX=RS232_RD  
PORT TX=RS232_TD  
END
```

```
BEGIN opb_v20  
PARAMETER INSTANCE = myopb_bus  
PARAMETER HW_VER = 1.10.a  
PARAMETER C_DYNAM_PRIORITY = 0  
PARAMETER C_REG_GRANTS = 0  
PARAMETER C_PARK = 0  
PARAMETER C_PROC_INTRFCE = 0  
PARAMETER C_DEV_BLK_ID = 0  
PARAMETER C_DEV_MIR_ENABLE = 0  
PARAMETER C_BASEADDR = 0xffff1000  
PARAMETER C_HIGHADDR = 0xffff10ff
```

```

PORT SYS_Rst = fpga_reset
PORT OPB_Clk = sys_clk
END

BEGIN lmb_v10
PARAMETER INSTANCE = d_lmb
PARAMETER HW_VER = 1.00.a
PORT LMB_Clk = sys_clk
PORT SYS_Rst = fpga_reset
END

```

```

BEGIN lmb_v10
PARAMETER INSTANCE = i_lmb
PARAMETER HW_VER = 1.00.a
PORT LMB_Clk = sys_clk
PORT SYS_Rst = fpga_reset
END

```

Makefile:

```

# Makefile for CSEE 4840, Lab 3

SYSTEM = system

MICROBLAZE_OBJS = \
    c_source_files/main.o \
    c_source_files/isr.o

LIBRARIES = mymicroblaze/lib/libxil.a

ELF_FILE = $(SYSTEM).elf

NETLIST = implementation/$(SYSTEM).ngc

# Bitstreams for the FPGA

FPGA_BITFILE = implementation/$(SYSTEM).bit
MERGED_BITFILE = implementation/download.bit

# Files to be downloaded to the SRAM

SRAM_BINFILE = implementation/sram.bin
SRAM_HEXFILE = implementation/sram.hex

MHSFILE = $(SYSTEM).mhs
MSSFILE = $(SYSTEM).mss

FPGA_ARCH = spartan2e
DEVICE = xc2s300epq208-6

LANGUAGE = vhdl
PLATGEN_OPTIONS = -p $(FPGA_ARCH) -lang $(LANGUAGE)
LIBGEN_OPTIONS = -p $(FPGA_ARCH) $(MICROBLAZE_LIBG_OPT)

# Paths for programs

```

```

XILINX = /usr/cad/xilinx/ise6.1i
ISEBINDIR = $(XILINX)/bin/lin
ISEENVCMDS = LD_LIBRARY_PATH=$(ISEBINDIR) XILINX=$(XILINX) PATH=$(ISEBINDIR)

XILINX_EDK = /usr/cad/xilinx/edk3.2

MICROBLAZE = /usr/cad/xilinx/gnu
MBBINDIR = $(MICROBLAZE)/bin
XESSBINDIR = /usr/cad/xess/bin

# Executables

XST = $(ISEENVCMDS) $(ISEBINDIR)/xst
XFLOW = $(ISEENVCMDS) $(ISEBINDIR)/xflow
BITGEN = $(ISEENVCMDS) $(ISEBINDIR)/bitgen
DATA2MEM = $(ISEENVCMDS) $(ISEBINDIR)/data2mem
XSLOAD = $(XESSBINDIR)/xsload
XESS_BOARD = XSB-300E

MICROBLAZE_CC = $(MBBINDIR)/microblaze-gcc
MICROBLAZE_CC_SIZE = $(MBBINDIR)/microblaze-size
MICROBLAZE_OBJCOPY = $(MBBINDIR)/microblaze-objcopy

# External Targets

all :
    @echo "Makefile to build a Microprocessor system :"
    @echo "Run make with any of the following targets"
    @echo "  make libs      : Configures the sw libraries for this system"
    @echo "  make program   : Compiles the program sources for all the processor
instances"
    @echo "  make netlist    : Generates the netlist for this system ($(SYSTEM)) "
    @echo "  make bits       : Runs Implementation tools to generate the
bitstream"
    @echo "  make init_bram: Initializes bitstream with BRAM data"
    @echo "  make download   : Downloads the bitstream onto the board"
    @echo "  make netlistclean: Deletes netlist"
    @echo "  make hwclean    : Deletes implementation dir"
    @echo "  make libsclean: Deletes sw libraries"
    @echo "  make programclean: Deletes compiled ELF files"
    @echo "  make clean      : Deletes all generated files/directories"
    @echo "  "
    @echo "  make <target> : (Default)"
    @echo "          Creates a Microprocessor system using default initializations"
    @echo "          specified for each processor in MSS file"

bits : $(FPGA_BITFILE)

netlist : $(NETLIST)

libs : $(LIBRARIES)

program : $(ELF_FILE)

init_bram : $(MERGED_BITFILE)

clean : hwclean libsclean programclean
        rm -f bram_init.sh

```

```

rm -f _impact.cmd

hwclean : netlistclean
    rm -rf implementation synthesis xst hdl
    rm -rf xst.srp $(SYSTEM).srp

netlistclean :
    rm -f $(FPGA_BITFILE) $(MERGED_BITFILE) \
        $(NETLIST) implementation/$(SYSTEM)_bd.bmm

libsclean :
    rm -rf mymicroblaze/lib

programclean :
    rm -f $(ELF_FILE) $(SRAM_BITFILE) $(SRAM_HEXFILE)

#
# Software rules
#
MICROBLAZE_MODE = executable

# Assemble software libraries from the .mss and .mhs files

$(LIBRARIES) : $(MHSFILE) $(MSSFILE)
    PATH=$$PATH:$(MBBINDIR) XILINX=$(XILINX) XILINX_EDK=$(XILINX_EDK) \
        perl -I $(XILINX_EDK)/bin/nt/perl5lib $(XILINX_EDK)/bin/nt/libgen.pl \
            $(LIBGEN_OPTIONS) $(MSSFILE)

# Compilation

MICROBLAZE_CC_CFLAGS =
MICROBLAZE_CC_OPT = -O3 #-mxl-gp-opt
MICROBLAZE_CC_DEBUG_FLAG =# -gstabs
MICROBLAZE_INCLUDES = -I./mymicroblaze/include/ # -I
MICROBLAZE_CFLAGS = \
    $(MICROBLAZE_CC_CFLAGS) \
    -mxl-barrel-shift \
    $(MICROBLAZE_CC_OPT) \
    $(MICROBLAZE_CC_DEBUG_FLAG) \
    $(MICROBLAZE_INCLUDES)

$(MICROBLAZE_OBJS) : %.o : %.c
    PATH=$(MBBINDIR) $(MICROBLAZE_CC) $(MICROBLAZE_CFLAGS) -c $< -o $@

# Linking

# Uncomment the following to make linker print locations for everything
# MICROBLAZE_LD_FLAGS = -Wl,-M
MICROBLAZE_LINKER_SCRIPT = -Wl,-T -Wl,mylinkscript
MICROBLAZE_LIBPATH = -L./mymicroblaze/lib/
MICROBLAZE_CC_START_ADDR_FLAG= -Wl,-defsym -Wl,_TEXT_START_ADDR=0x00000000
MICROBLAZE_CC_STACK_SIZE_FLAG= -Wl,-defsym -Wl,_STACK_SIZE=0x200
MICROBLAZE_LFLAGS = \
    -xl-mode-$(MICROBLAZE_MODE) \
    $(MICROBLAZE_LD_FLAGS) \
    $(MICROBLAZE_LINKER_SCRIPT) \
    $(MICROBLAZE_LIBPATH) \
    $(MICROBLAZE_CC_START_ADDR_FLAG) \

```

```

$(MICROBLAZE_CC_STACK_SIZE_FLAG)

$(ELF_FILE) : $(LIBRARIES) $(MICROBLAZE_OBJS)
    PATH=$(MBBINDIR) $(MICROBLAZE_CC) $(MICROBLAZE_LFLAGS) \
        $(MICROBLAZE_OBJS) -o $(ELF_FILE)
    $(MICROBLAZE_CC_SIZE) $(ELF_FILE)

#
# Hardware rules
#

# Hardware compilation : optimize the netlist, place and route

$(FPGA_BITFILE) : $(NETLIST) \
    etc/fast_runtime.opt etc/bitgen.ut data/$(SYSTEM).ucf
    cp -f etc/bitgen.ut implementation/
    cp -f etc/fast_runtime.opt implementation/
    cp -f data/$(SYSTEM).ucf implementation/$(SYSTEM).ucf
    $(XFLOW) -wd implementation -p $(DEVICE) -implement fast_runtime.opt \
        $(SYSTEM).ngc
    cd implementation; $(BITGEN) -f bitgen.ut $(SYSTEM)

# Hardware assembly: Create the netlist from the .mhs file

$(NETLIST) : $(MHSFILE)
    XILINX=$(XILINX) XILINX_EDK=$(XILINX_EDK) \
    perl -I $(XILINX_EDK)/bin/nt/perl5lib $(XILINX_EDK)/bin/nt/platgen.pl \
        $(PLATGEN_OPTIONS) -st xst $(MHSFILE)
    perl synth_modules.pl < synthesis/xst.scr > xst.scr
    $(XST) -ifn xst.scr
    rm -r xst xst.scr
    $(XST) -ifn synthesis/$(SYSTEM).scr

#
# Downloading
#

# Add software code to the FPGA bitfile

$(MERGED_BITFILE) : $(FPGA_BITFILE) $(ELF_FILE)
    $(DATA2MEM) -bm implementation/$(SYSTEM)_bd \
        -bt implementation/$(SYSTEM) \
        -bd $(ELF_FILE) tag bram -o b $(MERGED_BITFILE)

# Create a .hex file with data for the SRAM

$(SRAM_HEXFILE) : $(ELF_FILE)
    $(MICROBLAZE_OBJCOPY) \
        -j .sram_text -j .sdata2 -j .sdata -j .rodata -j .data \
        -O binary $(ELF_FILE) $(SRAM_BINFILE)
    ./bin2hex -a 60000 < $(SRAM_BINFILE) > $(SRAM_HEXFILE)

# Download the files to the target board

download : $(MERGED_BITFILE) $(SRAM_HEXFILE)
    $(XSLOAD) -ram -b $(XESS_BOARD) $(SRAM_HEXFILE)
    $(XSLOAD) -fpga -b $(XESS_BOARD) $(MERGED_BITFILE)

```

PictureLoad.sh:

```

#!/bin/sh

cd ..
make download
cd jpg/
djpeg <picturetoload.jpg>picturetoload.ppm
./ppm2bin picturetoload.ppm picturetoload.bin
./compress picturetoload.bin picturetoload.nas
./test232 < picturetoload.nas

```

memoryctrl.vhd:

```

-----
-- Memory controller state machine
--
-- Arbitrates between requests from the processor and video system
-- The video system gets priority
-- Also handles 32- to 16-bit datapath width conversion (sequencing)
--
-- Cristian Soviani, Dennis Lim, and Stephen A. Edwards
--

library IEEE;
use IEEE.STD_LOGIC_1164.ALL;

entity memoryctrl is
  port (
    rst : in std_logic;
    clk : in std_logic;
    cs : in std_logic;                                -- chip select (address valid)
    select0 : in std_logic;                           -- select (true through whole cycle)
    rnw : in std_logic;                             -- read/write'
    vreq : in std_logic;                            -- video request
    onecycle : in std_logic;                        -- one- or two-byte access (not four)

    videocycle : out std_logic;                      -- acknowledges vreq
    hihalf : out std_logic;                         -- doing bytes 2,3 of 32-bit access
    pb_wr : out std_logic;                          -- Write request to off-chip memory
    pb_rd : out std_logic;                          -- Read request to off-chip memory
    xfer : out std_logic;                           -- Transfer acknowledge for OPB

    ce0 : out std_logic;                            -- lower 16 bit OPB data latch enable
    cel : out std_logic;                            -- upper 16 bit OPB data latch enable
    rres : out std_logic;                           -- clear OPB data output latches

    video_ce : out std_logic);                     -- video buffer latch enable
  end memoryctrl;

architecture Behavioral of memoryctrl is
  -- State machine bits
  -- largely one-hot, but one ra and one rb bit can be true simultaneously
  signal r_idle : std_logic;
  signal r_common : std_logic;
  signal r_ral : std_logic;
  signal r_ra2 : std_logic;
  signal r_rbl : std_logic;

```

```

signal r_rb2 : std_logic;
signal r_rb3 : std_logic;
signal r_w : std_logic;
signal r_xfer : std_logic;

signal vcycle_1 : std_logic;
signal vcycle_2 : std_logic;

signal r_idle_next_state : std_logic;
signal r_common_next_state : std_logic;
signal r_ra1_next_state : std_logic;
signal r_ra2_next_state : std_logic;
signal r_rb1_next_state : std_logic;
signal r_rb2_next_state : std_logic;
signal r_rb3_next_state : std_logic;
signal r_w_next_state : std_logic;
signal r_xfer_next_state : std_logic;

begin

-- Sequential process for the state machine

process (clk, rst)
begin
  if rst = '1' then
    r_idle <= '1';
    r_common <= '0';
    r_ra1 <= '0';
    r_ra2 <= '0';
    r_rb1 <= '0';
    r_rb2 <= '0';
    r_rb3 <= '0';
    r_w <= '0';
    r_xfer <= '0';
  elsif clk'event and clk='1' then
    r_idle <= r_idle_next_state;
    r_common <= r_common_next_state;
    r_ra1 <= r_ra1_next_state;
    r_ra2 <= r_ra2_next_state;
    r_rb1 <= r_rb1_next_state;
    r_rb2 <= r_rb2_next_state;
    r_rb3 <= r_rb3_next_state;
    r_w <= r_w_next_state;
    r_xfer <= r_xfer_next_state;
  end if;
end process;

-- Combinational next-state logic

r_idle_next_state <= (r_idle and (not cs)) or r_xfer or (not select0);
r_common_next_state <= select0 and
                      ((r_idle and cs) or (r_common and vreq));
r_ra1_next_state <= select0 and
                     r_common and (not vreq) and rnw;
r_ra2_next_state <= select0 and
                     r_ra1;
r_rb1_next_state <= select0 and
                     ((r_common and not onecycle and not vreq and rnw) or
                      (r_rb1 and vreq));

```

```

r_rb2_next_state <= select0 and
                  (r_rb1 and (not vreq));
r_rb3_next_state <= select0 and
                  r_rb2;
r_w_next_state <= select0 and
                  ((r_common and (not rnw) and (not vreq) and
                    (not onecycle)) or
                   (r_w and vreq));
r_xfer_next_state <= select0 and
                  ((r_common and onecycle and
                    (not rnw) and (not vreq)) or
                   (r_w and (not vreq)) or (r_ra2 and onecycle) or r_rb3);

-- Combinational output logic

pb_wr <= (r_common and (not rnw) and (not vreq)) or (r_w and (not vreq));
pb_rd <= vreq or (r_common and (not vreq) and rnw) or (r_rb1 and (not vreq));

hihalf <= (r_w and (not vreq)) or (r_rb1 and (not vreq));

ce0 <= r_ra2;
cel <= r_rb3;
rres <= r_xfer;
xfer <= r_xfer;

-- Two-cycle delay of video request
-- (implicitly assumes video cycles always succeed)
process (clk, rst)
begin
  if(rst = '1') then
    vcycle_1 <= '0';
    vcycle_2 <= '0';
  elsif clk'event and clk='1' then
    vcycle_1 <= vreq;
    vcycle_2 <= vcycle_1;
  end if;
end process;

videocycle <= vreq;
video_ce <= vcycle_2;

end Behavioral;

```

opb_xsb300.vhd:

```

-- 
-- OPB bus bridge for the XESS XSB-300E board
-- 
-- Includes a memory controller, a VGA framebuffer, and glue for the SRAM
-- 
-- 
-- Cristian Soviani, Dennis Lim, and Stephen A. Edwards
-- 
-- 

```

```

library IEEE;
use IEEE.STD_LOGIC_1164.ALL;

entity opb_xsb300 is

```

```

generic (
    C_OPB_AWIDTH      : integer := 32;
    C_OPB_DWIDTH      : integer := 32;
    C_BASEADDR        : std_logic_vector := X"2000_0000";
    C_HIGHADDR        : std_logic_vector := X"2000_00FF");

port (
    OPB_Clk : in std_logic;
    OPB_Rst : in std_logic;
    OPB_ABus : in std_logic_vector (31 downto 0);
    OPB_BE : in std_logic_vector (3 downto 0);
    OPB_DBus : in std_logic_vector (31 downto 0);
    OPB_RNW : in std_logic;
    OPB_select : in std_logic;
    OPB_seqAddr : in std_logic;
    pixel_clock : in std_logic;
    UIO_DBus : out std_logic_vector (31 downto 0);
    UIO_errAck : out std_logic;
    UIO_retry : out std_logic;
    UIO_toutSup : out std_logic;
    UIO_xferAck : out std_logic;
    PB_A : out std_logic_vector (19 downto 0);
    PB_UB_N : out std_logic;
    PB_LB_N : out std_logic;
    PB_WE_N : out std_logic;
    PB_OE_N : out std_logic;
    RAM_CE_N : out std_logic;
    VIDOUT_CLK : out std_logic;
    VIDOUT_RCR : out std_logic_vector (9 downto 0);
    VIDOUT_GY : out std_logic_vector (9 downto 0);
    VIDOUT_BCB : out std_logic_vector (9 downto 0);
    VIDOUT_BLANK_N : out std_logic;
    VIDOUT_HSYNC_N : out std_logic;
    VIDOUT_VSYNC_N : out std_logic;
    PB_D : inout std_logic_vector (15 downto 0));
end opb_xsb300;

```

```

architecture Behavioral of opb_xsb300 is

    constant C_MASK : integer := 0; -- huge address window as we are a bridge

    signal addr_mux : std_logic_vector(19 downto 0);
    signal video_addr : std_logic_vector (19 downto 0);
    signal video_data : std_logic_vector (15 downto 0);
    signal video_req : std_logic;
    signal video_ce : std_logic;
    signal i : integer;
    signal cs : std_logic;

    signal onecycle : std_logic ;
    signal videocycle, amuxsel, hihalf : std_logic;
    signal rce0, rcel, rreset : std_logic;
    signal xfer : std_logic;
    signal pb_wr, pb_rd : std_logic;

    signal sram_ce : std_logic;

    signal rnw : std_logic;

```

```

signal addr : std_logic_vector (23 downto 0);

signal be : std_logic_vector (3 downto 0);
signal pb_bytesel : std_logic_vector (1 downto 0);

signal wdata : std_logic_vector (31 downto 0);
signal wdata_mux : std_logic_vector (15 downto 0);

signal rdata : std_logic_vector (15 downto 0); -- register data read - FDRE

component vga
port (
    clk : in std_logic;
    pix_clk : in std_logic;
    rst : in std_logic;
    video_data : in std_logic_vector(15 downto 0);
    video_addr : out std_logic_vector(19 downto 0);
    video_req : out std_logic;
    vidout_clk : out std_logic;
    vidout_RCR : out std_logic_vector(9 downto 0);
    vidout_GY : out std_logic_vector(9 downto 0);
    vidout_BCB : out std_logic_vector(9 downto 0);
    vidout_BLANK_N : out std_logic;
    vidout_HSYNC_N : out std_logic;
    vidout_VSYNC_N : out std_logic);
end component;

component memoryctrl
port (
    rst : in std_logic;
    clk : in std_logic;
    cs : in std_logic;
    select0 : in std_logic;
    rnw : in std_logic;
    vreq : in std_logic;
    onecycle : in std_logic;
    videocycle : out std_logic;
    hihalf : out std_logic;
    pb_wr : out std_logic;
    pb_rd : out std_logic;
    xfer : out std_logic;
    ce0 : out std_logic;
    cel : out std_logic;
    rres : out std_logic;
    video_ce : out std_logic);
end component;

component pad_io
port (
    clk : in std_logic;
    rst : in std_logic;
    PB_A : out std_logic_vector(19 downto 0);
    PB_UB_N : out std_logic;
    PB_LB_N : out std_logic;
    PB_WE_N : out std_logic;
    PB_OE_N : out std_logic;
    RAM_CE_N : out std_logic;
    PB_D : inout std_logic_vector(15 downto 0);
    pb_addr : in std_logic_vector(19 downto 0));

```

```

pb_ub : in std_logic;
pb_lb : in std_logic;
pb_wr : in std_logic;
pb_rd : in std_logic;
ram_ce : in std_logic;
pb_dread : out std_logic_vector(15 downto 0);
pb_dwrite : in std_logic_vector(15 downto 0));
end component;

begin

-- Framebuffer

vgal : vga
port map (
    clk => OPB_Clk,
    pix_clk => pixel_clock,
    rst => OPB_Rst,
    video_addr => video_addr,
    video_data => video_data,
    video_req => video_req,
    VIDOUT_CLK => VIDOUT_CLK,
    VIDOUT_RCR => VIDOUT_RCR,
    VIDOUT_GY => VIDOUT_GY,
    VIDOUT_BCB => VIDOUT_BCB,
    VIDOUT_BLANK_N => VIDOUT_BLANK_N,
    VIDOUT_HSYNC_N => VIDOUT_HSYNC_N,
    VIDOUT_VSYNC_N => VIDOUT_VSYNC_N);

-- Memory control/arbitration state machine

memoryctrl1 : memoryctrl port map (
    rst => OPB_Rst,
    clk => OPB_Clk,
    cs => cs,
    select0 => OPB_select,
    rnw => rnw,
    vreq => video_req,
    onecycle => onecycle,
    videocycle => videocycle,
    hihalf => hihalf,
    pb_wr => pb_wr,
    pb_rd => pb_rd,
    xfer => xfer,
    ce0 => rce0,
    cel => rcel,
    rres => rreset,
    video_ce => video_ce);

-- I/O pads

pad_iol : pad_io port map (
    clk => OPB_Clk,
    rst => OPB_Rst,
    PB_A => PB_A,
    PB_UB_N => PB_UB_N,
    PB_LB_N => PB_LB_N,
    PB_WE_N => PB_WE_N,
    PB_OE_N => PB_OE_N,

```

```

RAM_CE_N => RAM_CE_N,
PB_D => PB_D,
pb_addr => addr_mux,
pb_rd => pb_rd,
pb_wr => pb_wr,
pb_ub => pb_byteselect(1),
pb_lb => pb_byteselect(0),
ram_ce => sram_ce,
pb_dread => rdata,
pb_dwrite => wdata_mux);

sram_ce <= pb_rd or pb_wr;

amuxsel <= videocycle;

addr_mux <= video_addr when (amuxsel = '1')
else (addr(20 downto 2) & (addr(1) or hihalf));

onecycle <= (not be(3)) or (not be(2)) or (not be(1)) or (not be(0));

wdata_mux <= wdata(15 downto 0) when ((addr(1) or hihalf) = '1')
else wdata(31 downto 16);

process(videocycle, be, addr(1), hihalf, pb_rd, pb_wr)
begin
  if videotime = '1' then
    pb_byteselect <= "11";
  elsif pb_rd='1' or pb_wr='1' then
    if addr(1)='1' or hihalf='1' then
      pb_byteselect <= be(1 downto 0);
    else
      pb_byteselect <= be(3 downto 2);
    end if;
  else
    pb_byteselect <= "00";
  end if;
end process;

cs <= OPB_Select when OPB_ABus(31 downto 20) = X"008" else '0';

process (OPB_Clk)
begin
  if OPB_Clk'event and OPB_Clk = '1' then
    if OPB_Rst = '1' then
      rnw <= '0';
    else
      rnw <= OPB_RNW;
    end if;
  end if;
end process;

process (OPB_Clk)
begin
  if OPB_Clk'event and OPB_Clk = '1' then
    if OPB_RST = '1' then
      addr <= X"000000";
    else
      addr <= OPB_ABus(23 downto 0);
    end if;
  end if;

```

```

    end if;
end process;

process (OPB_Clk)
begin
    if OPB_Clk'event and OPB_Clk = '1' then
        if OPB_Rst = '1' then
            be <= "0000";
        else
            be <= OPB_BE;
        end if;
    end if;
end process;

process (OPB_Clk)
begin
    if OPB_Clk'event and OPB_Clk = '1' then
        if OPB_Rst = '1' then
            wdata <= X"00000000";
        else
            wdata <= OPB_DBus;
        end if;
    end if;
end process;

process (OPB_Clk)
begin
    if OPB_Clk'event and OPB_Clk = '1' then
        if video_ce = '1' then
            video_data <= rdata;
        end if;
    end if;
end process;

-- Write the low two bytes if rce0 or rcel is enabled

process (OPB_Clk, OPB_Rst)
begin
    if OPB_Rst = '1' then
        UIO_DBus(15 downto 0) <= X"0000";
    elsif OPB_Clk'event and OPB_Clk = '1' then
        if rreset = '1' then
            UIO_DBus(15 downto 0) <= X"0000";
        elsif (rcel or rce0) = '1' then
            UIO_DBus(15 downto 0) <= rdata(15 downto 0);
        end if;
    end if;
end process;

-- Write the high two bytes if rce0 is enabled

process (OPB_Clk, OPB_Rst)
begin
    if OPB_Rst = '1' then
        UIO_DBus(31 downto 16) <= X"0000";
    elsif OPB_Clk'event and OPB_Clk = '1' then
        if rreset = '1' then
            UIO_DBus(31 downto 16) <= X"0000";
        elsif rce0 = '1' then

```

```

        UIO_DBus(31 downto 16) <= rdata(15 downto 0);
    end if;
end if;
end process;

-- unused outputs

UIO_errAck <= '0';
UIO_retry <= '0';
UIO_toutSup <= '0';

UIO_xferAck <= xfer;

end Behavioral;

```

pad_io.vhd:

```

-- I/O Pads and associated circuitry for the XSB-300E board
-- Cristian Soviani, Dennis Lim, and Stephen A. Edwards
-- Pad drivers, a little glue logic, and flip-flops for most bus signals
-- All signals, both control and the data and address busses, are registered.
-- FDC and FDP flip-flops are forced into the pads to do this.
-- Only the data bus is mildly complex: it latches data in both directions
-- as well as delaying the tristate control signals a cycle.
-- 
```

```

library IEEE;
use IEEE.STD_LOGIC_1164.ALL;

entity pad_io is
  port (
    clk : in std_logic;
    rst : in std_logic;
    PB_A : out std_logic_vector(19 downto 0);
    PB_UB_N : out std_logic;
    PB_LB_N : out std_logic;
    PB_WE_N : out std_logic;
    PB_OE_N : out std_logic;
    RAM_CE_N : out std_logic;
    PB_D : inout std_logic_vector(15 downto 0);
    pb_addr : in std_logic_vector(19 downto 0);
    pb_ub : in std_logic;
    pb_lb : in std_logic;
    pb_wr : in std_logic;
    pb_rd : in std_logic;
    ram_ce : in std_logic;
    pb_dread : out std_logic_vector(15 downto 0);
    pb_dwrite : in std_logic_vector(15 downto 0));
end pad_io;

```

```

architecture Behavioral of pad_io is

```

```

  -- Flip-flop with asynchronous clear

```

```

component FDC
  port (
    C : in std_logic;
    CLR : in std_logic;
    D : in std_logic;
    Q : out std_logic);
end component;

-- Flip-flop with asynchronous preset

component FDP
  port (
    C : in std_logic;
    PRE : in std_logic;
    D : in std_logic;
    Q : out std_logic);
end component;

-- Setting the iob attribute to "true" ensures that instances of these
-- components are placed inside the I/O pads and are therefore very fast

attribute iob : string;
attribute iob of FDC : component is "true";
attribute iob of FDP : component is "true";

-- Fast off-chip output buffer, low-voltage TTL levels, 24 mA drive
-- I is the on-chip signal, O is the pad

component OBUF_F_24
  port (
    O : out STD_ULOGIC;
    I : in STD_ULOGIC);
end component;

-- Fast off-chip input/output buffer, low-voltage TTL levels, 24 mA drive
-- T is the tristate control input, IO is the pad,

component IOBUF_F_24
  port (
    O : out STD_ULOGIC;
    IO : inout STD_ULOGIC;
    I : in STD_ULOGIC;
    T : in STD_ULOGIC);
end component;

signal pb_addr_1: std_logic_vector(19 downto 0);
signal pb_dwrite_1: std_logic_vector(15 downto 0);
signal pb_tristate: std_logic_vector(15 downto 0);
signal pb_dread_a: std_logic_vector(15 downto 0);
signal we_n, pb_we_n1: std_logic;
signal oe_n, pb_oe_n1: std_logic;
signal lb_n, pb_lb_n1: std_logic;
signal ub_n, pb_ub_n1: std_logic;
signal ramce_n, ram_ce_n1: std_logic;
signal dataz : std_logic;

begin

```

```

-- Write enable

we_n <= not pb_wr;

we_ff : FDP port map (
  C => clk, PRE => rst,
  D => we_n,
  Q => pb_we_n1);

we_pad : OBUF_F_24 port map (
  O => PB_WE_N,
  I => pb_we_n1);

-- Output Enable

oe_n <= not pb_rd;

oe_ff : FDP port map (
  C => clk,
  PRE => rst,
  D => oe_n,
  Q => pb_oe_n1);

oe_pad : OBUF_F_24 port map (
  O => PB_OE_N,
  I => pb_oe_n1);

-- RAM Chip Enable

ramce_n <= not ram_ce;

ramce_ff : FDP port map (
  C => clk, PRE => rst,
  D => ramce_n,
  Q => ram_ce_n1);

ramce_pad : OBUF_F_24 port map (
  O => RAM_CE_N,
  I => ram_ce_n1);

-- Upper byte enable

ub_n <= not pb_ub;

ub_ff : FDP port map (
  C => clk, PRE => rst,
  D => ub_n,
  Q => pb_ub_n1);

ub_pad : OBUF_F_24 port map (
  O => PB_UB_N,
  I => pb_ub_n1);

-- Lower byte enable

lb_n <= not pb_lb;

lb_ff : FDP port map (
  C => clk,

```

```

PRE => rst,
D => lb_n,
Q => pb_lb_n1);

lb_pad : OBUF_F_24 port map (
    O => PB_LB_N,
    I => pb_lb_n1);

-- 20-bit address bus

addressbus : for i in 0 to 19 generate
    address_ff : FDC port map (
        C => clk, CLR => rst,
        D => pb_addr(i),
        Q => pb_addr_1(i));

    address_pad : OBUF_F_24 port map (
        O => PB_A(i),
        I => pb_addr_1(i));
end generate;

-- 16-bit data bus

dataz <= (not pb_wr) or pb_rd;

databus : for i in 0 to 15 generate
    dtff : FDP port map (                                -- Trisate enable
        C => clk,
        PRE => rst,
        D => dataz,
        Q => pb_tristate(i));

    drff : FDP port map (
        C => clk,
        PRE => rst,
        D => pb_dread_a(i),
        Q => pb_dread(i));

    dwff : FDP port map (
        C => clk,
        PRE => rst,
        D => pb_dwrite(i),
        Q => pb_dwrite_1(i));

    data_pad : IOBUF_F_24 port map (
        O => pb_dread_a(i),
        IO => PB_D(i),
        I => pb_dwrite_1(i),
        T => pb_tristate(i));
end generate;

```

end Behavioral;

vga.vhd:

```

-----
-- 
-- VGA video generator
-- 
-- Uses the vga_timing module to generate hsync etc.

```

```
-- Massages the RAM address and requests cycles from the memory controller
-- to generate video using one byte per pixel
--
-- Cristian Soviani, Dennis Lim, and Stephen A. Edwards
--
```

```
library IEEE;
use IEEE.STD_LOGIC_1164.ALL;

entity vga is
  port (
    clk          : in std_logic;
    pix_clk      : in std_logic;
    rst          : in std_logic;
    video_data   : in std_logic_vector(15 downto 0);
    video_addr   : out std_logic_vector(19 downto 0);
    video_req    : out std_logic;
    VIDOUT_CLK   : out std_logic;
    VIDOUT_RCR   : out std_logic_vector(9 downto 0);
    VIDOUT_GY    : out std_logic_vector(9 downto 0);
    VIDOUT_BCB   : out std_logic_vector(9 downto 0);
    VIDOUT_BLANK_N : out std_logic;
    VIDOUT_HSYNC_N : out std_logic;
    VIDOUT_VSYNC_N : out std_logic);
end vga;
```

```
architecture Behavioral of vga is
```

```
-- Fast low-voltage TTL-level I/O pad with 12 mA drive
```

```
component OBUF_F_12
  port (
    O : out STD_ULOGIC;
    I : in STD_ULOGIC);
end component;
```

```
-- Basic edge-sensitive flip-flop
```

```
component FD
  port (
    C : in std_logic;
    D : in std_logic;
    Q : out std_logic);
end component;
```

```
-- Force instances of FD into pads for speed
```

```
attribute iob : string;
attribute iob of FD : component is "true";
```

```
component vga_timing
  port (
    h_sync_delay      : out std_logic;
    v_sync_delay      : out std_logic;
    blank             : out std_logic;
    vga_ram_read_address : out std_logic_vector (19 downto 0);
    pixel_clock       : in std_logic;
    reset              : in std_logic);
```

```

end component;

signal r          : std_logic_vector (9 downto 0);
signal g          : std_logic_vector (9 downto 0);
signal b          : std_logic_vector (9 downto 0);
signal blank      : std_logic;
signal hsync      : std_logic;
signal vsync      : std_logic;
signal vga_ram_read_address : std_logic_vector(19 downto 0);
signal vreq       : std_logic;
signal vreq_1     : std_logic;
signal load_video_word : std_logic;
signal vga_shreg  : std_logic_vector(15 downto 0);

begin

st : vga_timing port map (
  pixel_clock => pix_clk,
  reset => rst,
  h_sync_delay => hsync,
  v_sync_delay => vsync,
  blank => blank,
  vga_ram_read_address => vga_ram_read_address);

-- Video request is true when the RAM address is even

-- FIXME: This should be disabled during blanking to reduce memory traffic

vreq <= not vga_ram_read_address(0);

-- Generate load_video_word by delaying vreq two cycles

process (pix_clk)
begin
  if pix_clk'event and pix_clk='1' then
    vreq_1 <= vreq;
    load_video_word <= vreq_1;
  end if;
end process;

-- Generate video_req (to the RAM controller) by delaying vreq by
-- a cycle synchronized with the pixel clock

process (clk)
begin
  if clk'event and clk='1' then
    video_req <= pix_clk and vreq;
  end if;
end process;

-- The video address is the upper 19 bits from the VGA timing generator
-- because we are using two pixels per word and the RAM address counts words

video_addr <= '0' & vga_ram_read_address(19 downto 1);

-- The video shift register: either load it from RAM or shift it up a byte

process (pix_clk)
begin

```

```

if pix_clk'event and pix_clk='1' then
  if load_video_word = '1' then
    vga_shreg <= video_data;
  else
    -- Shift the low byte of read video data into the high byte
    vga_shreg <= vga_shreg(7 downto 0) & "00000000";
  end if;
end if;
end process;

-- Copy the upper byte of the video word to the color signals
-- Note that we use three bits for red and green and two for blue.

r(9 downto 7) <= vga_shreg (15 downto 13);
r(6 downto 0) <= "0000000";
g(9 downto 7) <= vga_shreg (12 downto 10);
g(6 downto 0) <= "0000000";
b(9 downto 8) <= vga_shreg (9 downto 8);
b(7 downto 0) <= "00000000";

-- Video clock I/O pad to the DAC

vidclk : OBUF_F_12 port map (
  O => VIDOUT_clk,
  I => pix_clk);

-- Control signals: hsync, vsync, and blank

hsync_ff : FD port map (
  C => pix_clk,
  D => not hsync,
  Q => VIDOUT_HSYNC_N );

vsync_ff : FD port map (
  C => pix_clk,
  D => not vsync,
  Q => VIDOUT_VSYNC_N );

blank_ff : FD port map (
  C => pix_clk,
  D => not blank,
  Q => VIDOUT_BLANK_N );

-- Three digital color signals

rgb_ff : for i in 0 to 9 generate

  r_ff : FD port map (
    C => pix_clk,
    D => r(i),
    Q => VIDOUT_RCR(i) );

  g_ff : FD port map (
    C => pix_clk,
    D => g(i),
    Q => VIDOUT_GY(i) );

  b_ff : FD port map (
    C => pix_clk,

```

```

    D => b(i),
    Q => VIDOUT_BCB(i) );

end generate;

end Behavioral;

```

vga_timing.vhd

```

-- VGA timing and address generator
-- Fixed-resolution address generator. Generates h-sync, v-sync, and blanking
-- signals along with a 20-bit RAM address. H-sync and v-sync signals are
-- delayed two cycles to compensate for the DAC pipeline.
-- Cristian Soviani, Dennis Lim, and Stephen A. Edwards
-- 
```

```

library IEEE;
use IEEE.STD_LOGIC_1164.ALL;
use IEEE.STD_LOGIC_ARITH.ALL;
use IEEE.STD_LOGIC_UNSIGNED.ALL;

entity vga_timing is
  port (
    pixel_clock : in std_logic;
    reset       : in std_logic;
    h_sync_delay : out std_logic;
    v_sync_delay : out std_logic;
    blank       : out std_logic;
    vga_ram_read_address : out std_logic_vector(19 downto 0));
end vga_timing;

```

```
architecture Behavioral of vga_timing is
```

```

  constant SRAM_DELAY : integer := 3;

-- 640 X 480 @ 60Hz with a 25.175 MHz pixel clock
  constant H_ACTIVE      : integer := 640;
  constant H_FRONT_PORCH : integer := 16;
  constant H_BACK_PORCH  : integer := 48;
  constant H_TOTAL        : integer := 800;

  constant V_ACTIVE      : integer := 480;
  constant V_FRONT_PORCH : integer := 11;
  constant V_BACK_PORCH  : integer := 31;
  constant V_TOTAL        : integer := 524;

  signal line_count : std_logic_vector (9 downto 0); -- Y coordinate
  signal pixel_count : std_logic_vector (10 downto 0); -- X coordinate

  signal h_sync : std_logic; -- horizontal sync
  signal v_sync : std_logic; -- vertical sync

  signal h_sync_delay0 : std_logic; -- h_sync delayed 1 clock
  signal v_sync_delay0 : std_logic; -- v_sync delayed 1 clock

```

```

signal h_blank : std_logic;           -- horizontal blanking
signal v_blank : std_logic;           -- vertical blanking

-- flag to reset the ram address during vertical blanking
signal reset_vga_ram_read_address : std_logic;

-- flag to hold the address during horizontal blanking
signal hold_vga_ram_read_address : std_logic;

signal ram_address_counter : std_logic_vector (19 downto 0);

begin

    -- Pixel counter

    process ( pixel_clock, reset )
    begin
        if reset = '1' then
            pixel_count <= "000000000000";
        elsif pixel_clock'event and pixel_clock = '1' then
            if pixel_count = (H_TOTAL - 1) then
                pixel_count <= "000000000000";
            else
                pixel_count <= pixel_count + 1;
            end if;
        end if;
    end process;

    -- Horizontal sync

    process ( pixel_clock, reset )
    begin
        if reset = '1' then
            h_sync <= '0';
        elsif pixel_clock'event and pixel_clock = '1' then
            if pixel_count = (H_ACTIVE + H_FRONT_PORCH - 1) then
                h_sync <= '1';
            elsif pixel_count = (H_TOTAL - H_BACK_PORCH - 1) then
                h_sync <= '0';
            end if;
        end if;
    end process;

    -- Line counter

    process ( pixel_clock, reset )
    begin
        if reset = '1' then
            line_count <= "0000000000";
        elsif pixel_clock'event and pixel_clock = '1' then
            if ((line_count = V_TOTAL - 1) and (pixel_count = H_TOTAL - 1)) then
                line_count <= "0000000000";
            elsif pixel_count = (H_TOTAL - 1) then
                line_count <= line_count + 1;
            end if;
        end if;
    end process;

    -- Vertical sync

```

```

process ( pixel_clock, reset )
begin
    if reset = '1' then
        v_sync <= '0';
    elsif pixel_clock'event and pixel_clock = '1' then
        if line_count = (V_ACTIVE + V_FRONT_PORCH -1) and
            pixel_count = (H_TOTAL - 1) then
            v_sync <= '1';
        elsif line_count = (V_TOTAL - V_BACK_PORCH - 1) and
            pixel_count = (H_TOTAL - 1) then
            v_sync <= '0';
        end if;
    end if;
end process;

-- Add two-cycle delays to h/v_sync to compensate for the DAC pipeline

process ( pixel_clock, reset )
begin
    if reset = '1' then
        h_sync_delay0 <= '0';
        v_sync_delay0 <= '0';
        h_sync_delay <= '0';
        v_sync_delay <= '0';
    elsif pixel_clock'event and pixel_clock = '1' then
        h_sync_delay0 <= h_sync;
        v_sync_delay0 <= v_sync;
        h_sync_delay <= h_sync_delay0;
        v_sync_delay <= v_sync_delay0;
    end if;
end process;

-- Horizontal blanking

-- The constants are offset by two to compensate for the delay
-- in the composite blanking signal

process ( pixel_clock, reset )
begin
    if reset = '1' then
        h_blank <= '0';
    elsif pixel_clock'event and pixel_clock = '1' then
        if pixel_count = (H_ACTIVE - 2) then
            h_blank <= '1';
        elsif pixel_count = (H_TOTAL - 2) then
            h_blank <= '0';
        end if;
    end if;
end process;

-- Vertical Blanking

-- The constants are offset by two to compensate for the delay
-- in the composite blanking signal

process ( pixel_clock, reset )
begin
    if reset = '1' then

```

```

    v_blank <= '0';
elsif pixel_clock'event and pixel_clock = '1' then
    if line_count = (V_ACTIVE - 1) and pixel_count = (H_TOTAL - 2) then
        v_blank <= '1';
    elsif line_count = (V_TOTAL - 1) and pixel_count = (H_TOTAL - 2) then
        v_blank <= '0';
    end if;
end if;
end process;

-- Composite blanking

process ( pixel_clock, reset )
begin
    if reset = '1' then
        blank <= '0';
    elsif pixel_clock'event and pixel_clock = '1' then
        if (h_blank or v_blank) = '1' then
            blank <= '1';
        else
            blank <= '0';
        end if;
    end if;
end process;

-- RAM address counter

-- Two control signals:

-- reset_ram_read_address is active from the end of each field until the
-- beginning of the next

-- hold_vga_ram_read_address is active from the end of each line to the
-- start of the next

process ( pixel_clock, reset )
begin
    if reset = '1' then
        reset_vga_ram_read_address <= '0';
    elsif pixel_clock'event and pixel_clock = '1' then
        if line_count = V_ACTIVE - 1 and
            pixel_count = ( (H_TOTAL - 1 ) - SRAM_DELAY ) then
            -- reset the address counter at the end of active video
            reset_vga_ram_read_address <= '1';
        elsif line_count = V_TOTAL - 1 and
            pixel_count =((H_TOTAL -1) - SRAM_DELAY) then
            -- re-enable the address counter at the start of active video
            reset_vga_ram_read_address <= '0';
        end if;
    end if;
end process;

process ( pixel_clock, reset )
begin
    if reset = '1' then
        hold_vga_ram_read_address <= '0';
    elsif pixel_clock'event and pixel_clock = '1' then
        if pixel_count = ((H_ACTIVE - 1) - SRAM_DELAY) then
            -- hold the address counter at the end of active video

```

```

    hold_vga_ram_read_address <= '1';
  elsif pixel_count = ((H_TOTAL - 1) - SRAM_DELAY) then
    -- re-enable the address counter at the start of active video
    hold_vga_ram_read_address <= '0';
  end if;
end if;
end process;

process ( pixel_clock, reset )
begin
  if reset = '1' then
    ram_address_counter <= "000000000000000000000000";
  elsif pixel_clock'event and pixel_clock = '1' then
    if reset_vga_ram_read_address = '1' then
      ram_address_counter <= "000000000000000000000000";
    elsif hold_vga_ram_read_address = '0' then
      ram_address_counter <= ram_address_counter + 1;
    end if;
  end if;
end process;

vga_ram_read_address <= ram_address_counter;

end Behavioral;

```