The Eval Monad and Strategies

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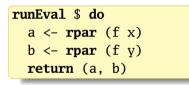


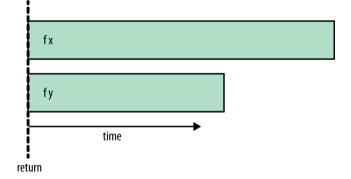
The Eval Monad: An Alternative to seq and par

```
When in doubt, create a Monad
```

```
module Control.Parallel.Strategies where
data Eval a = \dots
instance Monad Eval where ....
runEval :: Eval a -> a -- Get the result
rpar :: a -> Eval a -- Spark evaluation
rseq :: a -> Eval a -- Wait for evaluation to WHNF
```

rpar/rpar

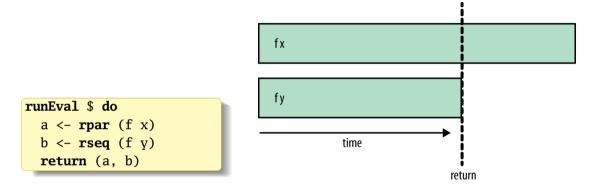




Start parallel evaluation of f x and f y

Return immediately

rpar/rseq



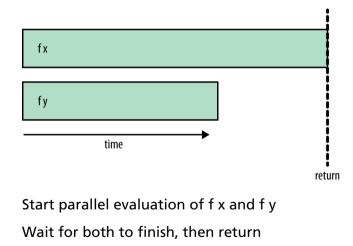
Start parallel evaluation of f x and f y Wait for f y to finish, then return Do we really know f y is faster?

rpar/rpar/rseq/rseq

```
runEval $ do
    a <- rpar (f x)
    b <- rseq (f y)
    rseq a
    return (a, b)</pre>
```

Equivalent and symmetrical:

```
runEval $ do
    a <- rpar (f x)
    b <- rpar (f y)
    rseq a
    rseq b
    return (a, b)</pre>
```



Marlow's Sudoku Solver Example (single-threaded)

\$ wget https://github.com/simonmar/parconc-examples/archive/master.tar.gz

```
$ tar --strip-components=1 -zxf master.tar.gz \
    parconc-examples-master/{Sudoku.hs,sudoku17.1000.txt}
```

```
import Sudoku ; import Control.Exception
import System.Environment ; import Data.Maybe
main :: IO ()
main = do [f] <- getArgs
    file <- readFile f
    let puzzles = lines file
        solutions = map solve puzzles
    print (length (filter isJust solutions))</pre>
```

\$ stack ghc -- -02 sudoku1.hs -rtsopts

\$./sudoku1 sudoku17.1000.txt +RTS -s

Static Partitioning

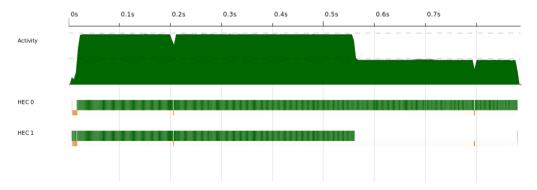
```
import Sudoku
import Data.Maybe ; import System.Environment
import Control.Parallel.Strategies ; import Control.DeepSeq
main :: IO ()
main = do puzzles <- getArgs >>= \[f] -> lines <$> readFile f
          let (as.bs) = splitAt (length puzzles `div` 2) puzzles
              solutions = runEval $ do
                as' <- rpar (force (map solve as)) -- To normal
                bs' <- rpar (force (map solve bs)) -- form
                _ <- rseq as'</pre>
                _ <- rseq bs'</pre>
                return (as' ++ bs')
```

print (length (filter isJust solutions))

The Problem with Static Partitioning

- \$ stack install parallel
- \$ stack ghc -- -02 -Wall sudoku2.hs -threaded -rtsopts -eventlog
- \$./sudoku2 sudoku17.1000.txt +RTS -N2 -s -ls
- \$ threadscope sudoku2.eventlog

Speedup on two cores: $1.37/0.891 = 1.53 \times$



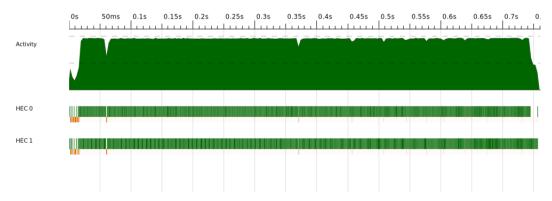
Better Balancing using parMap

```
import Sudoku
import System.Environment : import Data.Maybe
import Control.Parallel.Strategies hiding (parMap)
parMap :: (a \rightarrow b) \rightarrow [a] \rightarrow Eval [b]
parMap _ [] = return []
parMap f (a:as) = do b <- rpar (f a) -- Spark evaluation of f a
                      bs <- parMap f as -- Recurse
                      return (b:bs)
main :: IO ()
main = do puzzles <- getArgs >>= \[f] -> lines <$> readFile f
          let solutions = runEval (parMap solve puzzles)
          print (length (filter isJust solutions))
```

The Advantage of Dynamic Partitioning

- \$ stack ghc -- -02 -Wall sudoku3.hs -threaded -rtsopts -eventlog
- \$./sudoku3 sudoku17.1000.txt +RTS -N2 -s -ls
- \$ threadscope sudoku3.eventlog

Speedup on two cores: $1.37/0.751 = 1.82 \times$ versus $1.53 \times$ with static partitioning



Amdahl's Law: Why Parallelism is Difficult

Validity of the single processor approach to achieving large scale computing capabilities

by DR. GENE M. AMDAHL International Business Machines Corporation Sunnyvale, California

AFIPS Joint Computer Conference, 1967

P is the parallel fraction of the task*N* is the degree of parallelism*S* is the speedup

$$S = \frac{1}{(1-P) + P/N}$$

 $\lim_{N\to\infty} S \text{ is the depressing part:}$

If
$$P = 0.5$$
, $S \rightarrow 2$ as $N \rightarrow \infty$

If
$$P = 0.95$$
, $S \rightarrow 20$ as $N \rightarrow \infty$

DeepSeq and Normal Form

Weak Head Normal Form = Top is data constructor or lambda, not application

Normal Form = Data constructors or lambdas all the way down

In Control.Deepseq,

```
class NFData a where
 rnf :: a -> () -- "Reduce to Normal Form"
 rnf a = a `seq` () -- Default, e.g., for numbers
deepseq :: NFData a => a -> b -> b
deepseq a b = rnf a `seq` b -- Evaluate a to NF; return b
force :: NFData a => a -> a
force a = a `deepseg` a ___ Evaluate a to NF; return it
($!!) :: NFData a => (a -> b) -> a -> b
f !! x = x deepseq f x -- evaluate x then f x
```

Normal Form vs. Weak Head Normal Form

```
Prelude> import Control.DeepSeq
Prelude Control.DeepSeq> let x = [1..10] :: [Int]
Prelude Control.DeepSeg> :sprint x
x =
Prelude Control.DeepSeq> :sprint x
x =
Prelude Control.DeepSeq> x  seq ()
()
Prelude Control.DeepSeq> :sprint x
x = 1:
Prelude Control.DeepSeq> (last $ take 3 x) `seq` ()
()
Prelude Control.DeepSeq> :sprint x
x = 1 : 2 : 3 :
Prelude Control.DeepSea> x  deepsea ()
()
Prelude Control.DeepSeg> :sprint x
x = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10]
```

Roll-your-own NFData

```
import Control.DeepSeq
data Tree a = Empty | Branch (Tree a) a (Tree a)
instance NFData a => NFData (Tree a) where
rnf Empty = ()
rnf (Branch l a r) = rnf l `seq` rnf a `seq` rnf r
```

```
*Main> let singleton x = Branch Empty x Empty
*Main> let x = Branch (singleton 'a') 'b' (singleton 'c')
*Main> :sprint x
x = Branch 'b'
*Main> x  seq ()
()
*Main> :sprint x
x = Branch _ 'b'
*Main> rnf x
()
*Main> :sprint x
x = Branch (Branch Empty 'a' Empty) 'b' (Branch Empty 'c' Empty)
```

Evaluation Strategies

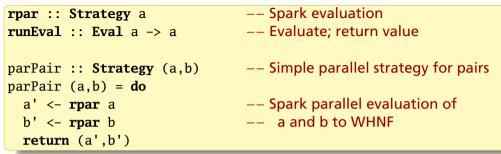
"Strategies are a means for modularizing parallel code by separating the algorithm from the parallelism. Sometimes they require you to rewrite your algorithm, but once you do so, you will be able to parallelize it in different ways just by substituting a new Strategy." —Simon Marlow

- 1. Build a lazy data structure representing the computation
- 2. Apply a Strategy that traverses the computation applying *rpar* and *rseq*

A Strategy: an identity function in the Eval monad (Control.Parallel.Strategies)

type Strategy = a -> Eval a

An Example: A Parallel Strategy for Pairs



runEval (parPair (fib 35, fib 36))

More elegantly,

using :: a -> Strategy a -> a -- In Control.Parallel.Strategies x `using` s = runEval (s x) -- Apply s, return x

(fib 35, fib 36) `using` parPair

Basic Strategies

In Control.Parallel.Strategies:

```
r0 :: Strategy a
r0 x = return x -- Do not evaluate x
rseq :: Strategy a -- Evaluate to WHNF; wait for completion
rdeepseg :: NFData a => Strategy a -- Fully evaluate then proceed
rdeepseq x = rseq (rnf x) >> return x
rpar :: Strategy a -- Spark evaluation (in parallel) to WHNF
rparWith :: Strategy a -> Strategy a
rparWith s x -- Spark evaluation of x 'using' s
```

Building Strategies from Strategies

A skeleton for expressing stategies for evaluating tuples:

parPair :: Strategy (a, b)
parPair = evalTuple2 rpar rpar -- Spark elements' evaluation to WHNF

What if we wanted to fully evaluate the two elements in parallel?

```
parPair :: Strategy a -> Strategy b -> Strategy (a, b)
parPair sa sb = evalTuple2 (rparWith sa) (rparWith sb)
```

parPair rdeepseq rdeepseq (fib 25, fib 26)

parPair rdeepseq rdeepseq (a, b)

"Spark two parallel threads that fully evaluate a and b to normal form"

A cartoon of how this works:

```
parPair rdeepseq rdeepseq (a, b)
  = evalTuple2 (rparWith rdeepseq) (rparWith rdeepseq) (a, b)
  = do a' <- (rparWith rdeepseq) a
       b' <- (rparWith rdeepseq) b
       return (a', b')
  = do a' <- rpar (a `using` x \rightarrow rseg (rnf x) >> return x)
       b' <- rpar (b`using` x \rightarrow rseq (rnf x) >> return x)
       return (a', b')
```

Evaluating a List in Parallel

In Control.Parallel.Strategies,

Combining these to evaluate all list elements to WHNF in parallel:

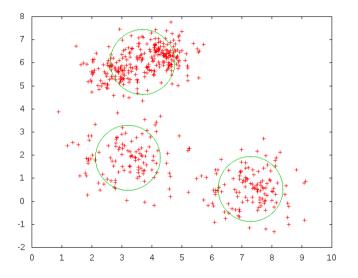
parMap :: (a -> b) -> [a] -> [b]
parMap f xs = map f xs `using` parList rseq

Simpler Parallel Sudoku

```
import Sudoku(solve)
import System.Environment(getArgs)
import Data.Maybe(isJust)
import Control.Parallel.Strategies(using, parList, rseq)
main :: IO ()
main = do [fname] <- getArgs</pre>
          puzzles <- lines <$> readFile fname
          let solutions = map solve puzzles `using` parList rseq
          print $ length $ filter isJust solutions
```

Note that *rseq* only evaluates to WHNF, but that suffices for Sudoku About the same performance as the "parMap" version presented earlier

Example: The K-Means Problem



Lloyd's (approximation) algorithm

Give a number of clusters k,

- 1. Guess a center for each cluster
- 2. Group points by closest centerpoint
- 3. Calculate the centroid (average) of each group
- Repeat steps 3–4 until satisfied

Example: The K-Means Problem

- \$ wget https://github.com/simonmar/parconc-examples/archive/master.tar.gz
- $tar --strip-components=1 -zxf master.tar.gz \$

parconc-examples-master/kmeans

2D points (to simplify visualization) and clusters, in KMeansCore.hs,

```
data Point = Point !Double !Double -- ! disables laziness
```

```
zeroPoint :: Point
zeroPoint = Point 0 0
```

sqDistance :: Point -> Point -> Double -- Distance squared for speed
sqDistance (Point x1 y1) (Point x2 y2) = ((x1-x2)^2) + ((y1-y2)^2)

data Cluster = Cluster { clId :: Int -- number of this cluster
 , clCent :: Point -- centroid of this cluster
 }

Example: The K-Means Problem

For computing the centroids (average of all points in a cluster), in kmeans.hs,

```
data PointSum = PointSum !Int !Double !Double
```

```
addToPointSum :: PointSum -> Point -> PointSum
addToPointSum (PointSum count xs ys) (Point x y)
= PointSum (count+1) (xs + x) (vs + y)
```

1. Accumulate Points in PointSums for Nearest Centroid

assign :: Int -> [Cluster] -> [Point] -> Vector PointSum assign nclusters clusters points = Vector.create \$ do vec <- MVector.replicate nclusters (PointSum 0 0 0)</pre>

```
let addpoint p = do
         let c = nearest p ; cid = clId c
         ps <- MVector.read vec cid
         MVector.write vec cid $! addToPointSum ps p
   mapM addpoint points
   return vec
where
nearest p = fst $ minimumBy (compare `on` snd)
              [ (c, sqDistance (clCent c) p) | c <- clusters ]</pre>
```

Vectors are Haskell's fixed-length, random-access arrays that are "mutable" in the right monad. See Data.Vector and Data.Vector.Mutable

2. Create New Clusters from PointSums

```
makeNewClusters :: Vector PointSum -> [Cluster]
makeNewClusters vec =
  [ pointSumToCluster i ps
  | (i,ps@(PointSum count _ _)) <- zip [0..] (Vector.toList vec)
  , count > 0
  ]
```

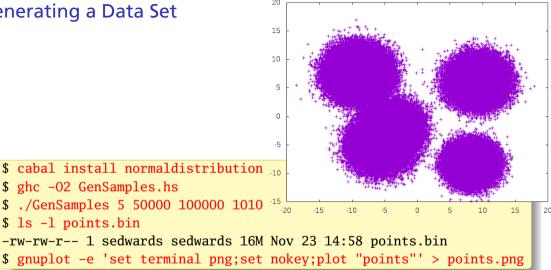
One step of the algorithm: group by nearest centroid; calculate new centroids

The Sequential Loop: step until converged or give up

```
kmeans_seq :: Int -> [Point] -> [Cluster] -> IO [Cluster]
kmeans_seg nclusters points clusters =
 let loop :: Int -> [Cluster] -> IO [Cluster]
     loop n clusters | n > tooMany = do
       putStrLn "giving up."
       return clusters
     loop n clusters = do
        printf "iteration %d\n" n
        putStr (unlines (map show clusters))
        let clusters' = step nclusters clusters points
        if clusters' == clusters
           then return clusters
           else loop (n+1) clusters'
 in loop 0 clusters
```

tooMany = 80

Generating a Data Set

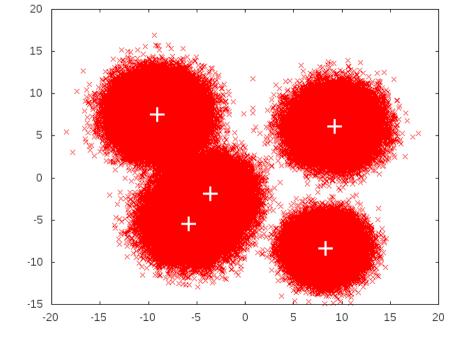


Compiling and Running K-Means

- \$ stack install monad-par
- \$ cd kmeans
- \$ stack ghc -- -02 -threaded -rtsopts -eventlog kmeans.hs

Run it in sequential mode:

```
$ ./kmeans seq
...
iteration 20
Cluster {clId = 0, clCent = Point -5.84359465 -5.46502314}
Cluster {clId = 1, clCent = Point 8.316354592 -8.33043084}
Cluster {clId = 2, clCent = Point -9.06455081 7.561852464}
Cluster {clId = 3, clCent = Point 9.243597731 6.138576051}
Cluster {clId = 4, clCent = Point -3.62170911 -1.82458124}
Total time: 0.73
```



Parallelizing K-Means

Computing nearest center for each point is the main operation to parallelize. This is a fold with an associative accumulation function *addToPointSum*.

Too many points and not enough work per point for per-point parallelism; overhead would dominate. Better to split work into coarser chunks.

```
split :: Int -> [a] -> [[a]] -- Divide into numChunks chunks
split numChunks xs = chunk (length xs `quot` numChunks) xs
```

```
chunk :: Int -> [a] -> [[a]] -- Split into n-point chunks
chunk _ [] = []
chunk n xs = let (as,bs) = splitAt n xs in as : chunk n bs
```

```
addPointSums :: PointSum -> PointSum -> PointSum -- Accumulate PointSums
addPointSums (PointSum c1 x1 y1) (PointSum c2 x2 y2)
= PointSum (c1+c2) (x1+x2) (y1+y2)
```

combine :: Vector PointSum -> Vector PointSum -> Vector PointSum
combine = Vector.zipWith addPointSums -- Accumulate vectors

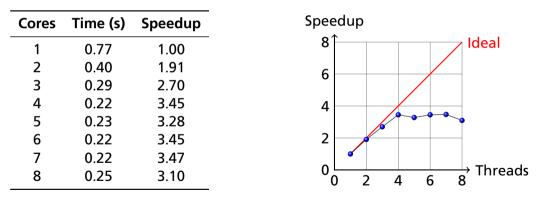
Analyze the chunks in parallel; merge; and make new clusters:

```
parSteps_strat :: Int -> [Cluster] -> [[Point]] -> [Cluster]
parSteps_strat nclusters clusters pointss
= makeNewClusters $
    foldr1 combine $ -- Merge the results from each chunk
    (map (assign nclusters clusters) pointss -- Analyze chunks
    `using` parList rseq) -- in parallel
```

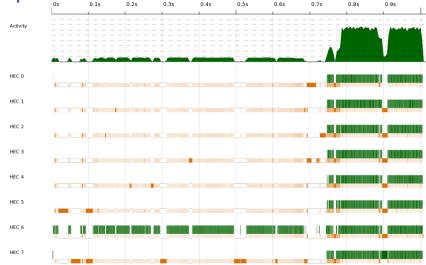
```
The Parallel Loop: Divide into chunks; apply parSteps_strat
    kmeans_strat :: Int -> Int -> [Point] -> [Cluster] -> IO [Cluster]
    kmeans_strat numChunks nclusters points clusters =
     let chunks = split numChunks points -- One big change
         loop :: Int -> [Cluster] -> IO [Cluster]
         loop n clusters | n > tooMany = do
            printf "giving up."
           return clusters
          loop n clusters = do
            printf "iteration %d\n" n
            putStr (unlines (map show clusters))
            let clusters' = parSteps_strat nclusters clusters chunks
            if clusters' == clusters
              then return clusters
              else loop (n+1) clusters'
      in loop 0 clusters
```

Performance of kmeans_strat on 1-8 Cores

- ./kmeans strat 64 +RTS -N1
- ./kmeans strat 64 +RTS -N8

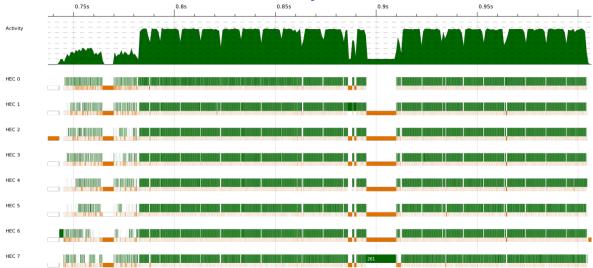


Using "Total time" reported by the program; ignores reading point data



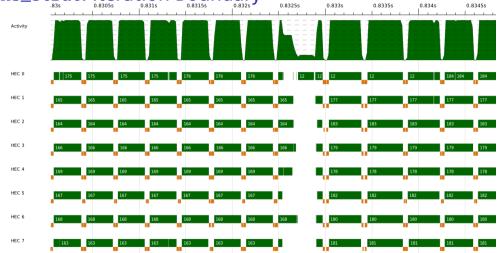
Lots of sequential file processing start: not being counted against speedup

kmeans_strat: Parallel Section Only



Off to a difficult start; iterations are periodic hiccups; big garbage collect

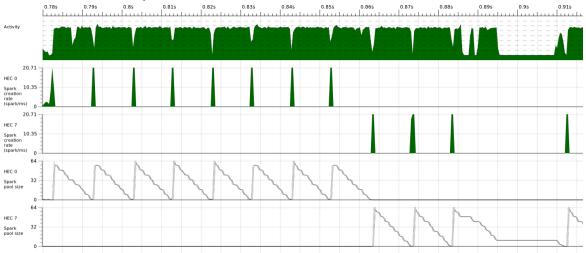
kmeans_strat: Iteration Boundary



Program suddenly turns completely sequential; darn Amdahl.

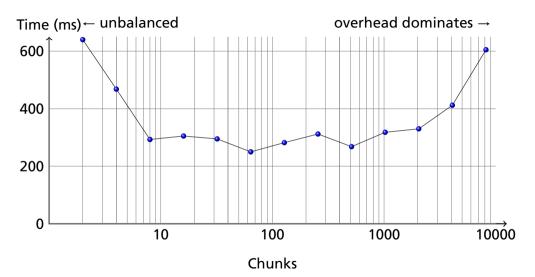
Marlow found printing was a major culprit, but removing it didn't matter on

kmeans_strat: Spark creation and conversion



Iteration: sudden spark creation activity in single HEC pool, then slow conversion. Main thread migrated after 8 iterations. (Under the "Traces" tab)

The Effects of Granularity (N=8)



GC'ed Sparks and Speculative Parallelism [Marlow p. 48]

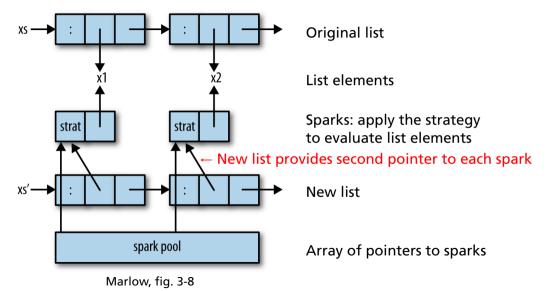
parList/evalList creates a new list, which seems wasteful

```
parList :: Strategy a
       -> Strategy [a]
parList s =
    evalList (rparWith s)
evalList :: Strategy a
         -> Strategy [a]
evalList _ [] = return []
evalList s (x:xs) =
 do x' <- s x
    xs' <- evallist s xs
    return (x':xs') -- Cons
```

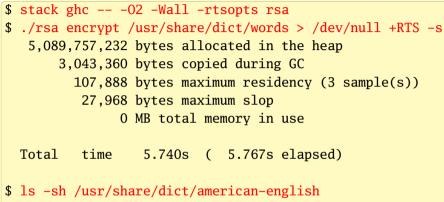
Consider this walk-the-list alternative that "touches" elements with *rparWith* parList :: Strategy a -> Strategy [a] parList strat xs = **do** go xs return xs where go [] = return ()go (x:xs) = **do rparWith** strat x go xs

Doesn't work: each spark created by *rparWith* is garbage-collected because it is never used. Critical that the result of *rpar/rparWith* be returned.

Heap Layout of Working parList: New List Inhibits Spark GC



Parallelizing Lazy Streams: RSA Encoder/Decoder from Marlow



920K /usr/share/dict/american-english

Dictionary file is about 1 MB, but runtime only uses 107,888 bytes maximum because of Data.ByteString.Lazy.Char8

Parallelizing RSA

Sequential implementation:

encrypt :: Integer -> Integer -> ByteString -> ByteString
encrypt n e = B.unlines Join results
. map (B.pack . show . power e n . code) Encrypt
. chunk (size n) Split

First try (rsa1.hs): use parList rdeepseq

```
encrypt n e = B.unlines
    withStrategy (parList rdeepseq)
    map (B.pack . show . power e n . code)
    chunk (size n)
```

withStrategy s e = e `using` s

Speedup using parList rdeepseq

```
$ stack ghc -- -02 -Wall -threaded -rtsopts rsa1
$ ./rsa1 encrypt /usr/share/dict/words > /dev/null +RTS -N8 -s
   5,319,033,432 bytes allocated in the heap
      18,619,728 bytes copied during GC
       3,029,464 bytes maximum residency (10 sample(s))
         570,920 bytes maximum slop
               2 MB total memory in use
 SPARKS: 9988
        (8254 converted, 1734 overflowed, 0 dud, 0 GC'd, 0 fizzled)
  Total
         time 14.403s ( 2.991s elapsed)
```

Speedup of 1.92 over sequential (rsa.hs) (4.8× itself)

Maximum memory use now 3 MB (cf. 107 KB): parList traverses the whole list.

Control.Parallel.Strategies.parBuffer: Regulate number of outstanding sparks

parBuffer 100 creates 100 outstanding sparks; sparks more once consumed

parBuffer :: Int -> Strategy a -> Strategy [a]

. chunk (size n)

```
$ ./rsa2 encrypt /usr/share/dict/words > /dev/null +RTS -N8 -s
506,640 bytes maximum residency (18 sample(s))
SPARKS: 9988
        (9987 converted, 0 overflowed, 0 dud, 0 GC'd, 1 fizzled)
Total time 12.160s ( 1.641s elapsed)
```

Down to 500 KB residency, 3.5× over sequential, excellent 7.4× self-speedup

Spark Creation and Pool with parBuffer



HEC5 got the spark creation process Spark pool remains around 100 Hiccups primarily garbage collection No creation or pools on other HECs Gray on graph denotes variance About 11% overhead

RSA Strategies (parList, parBuffer) Compared

Technique	Memory	Sparks					Time	Speedup
	(K)	Converted O	verflowed	Dud	GC'ed	Fizzled	(s)	
Sequential	105						5.77	1
parList	2958	8254	1734	0	0	0	2.99	1.92
parBuffer	495	9987	0	0	0	1	1.64	3.52

Both generate the same number of sparks

parList forces the entire file to be loaded (memory consumption) and generates all the sparks at the beginning (spark pool overflow).