

# CU RACING

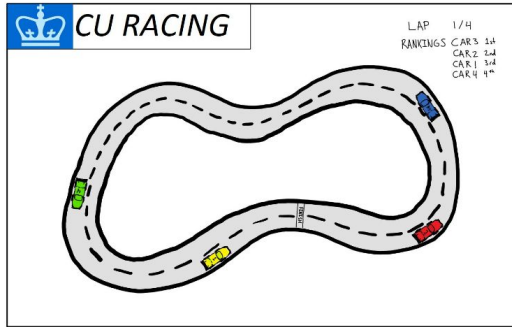
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Raghavendra Sirigeri  
Shikhar Kwatra  
Chandan Kanungo

 NEW GAME  
SCORES  
QUIT



# Project Concept Evolution

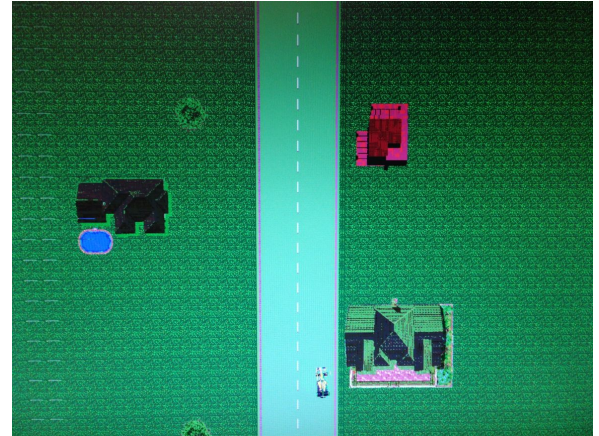
Early Concept



Precedent Ideas



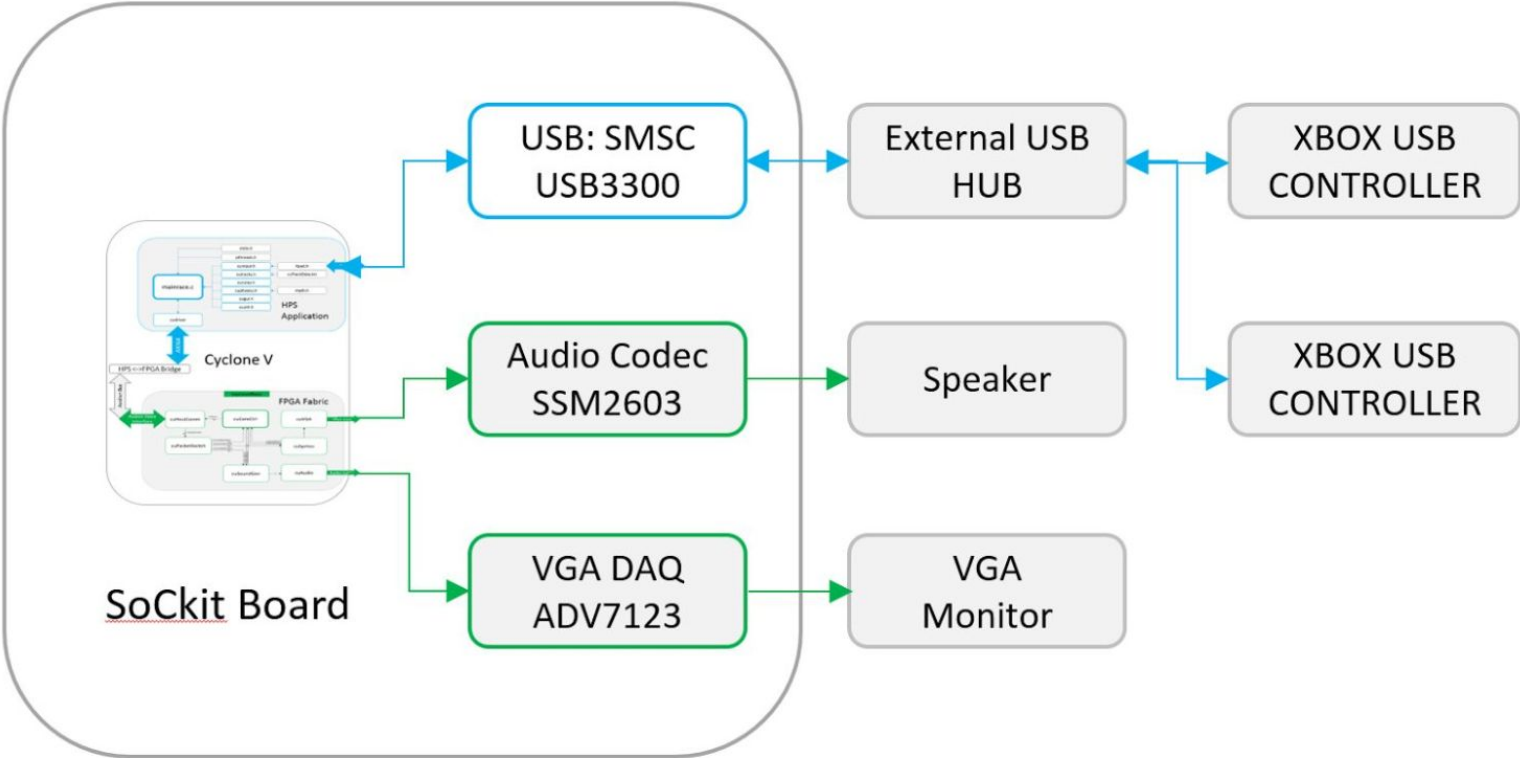
Final Gameplay



# Project Goals

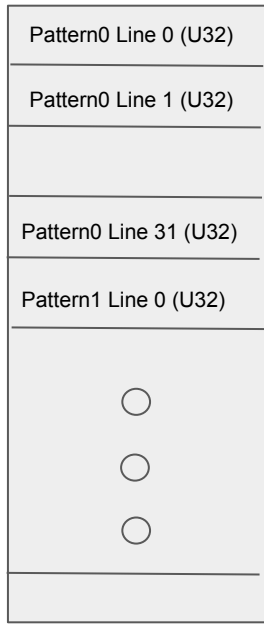
- Design a Sprites Graphics engine inspired from the TI TMS9918
  - Extend texture resolution from 8 pixels to **32 pixels, sprite resolution  $\geq$  64 pixels**
  - Update colors from Light/Dark pixels to **9 bit colorspace** (512 color alternatives/pixel)
- Enable screen scrolling in all directions
- Runtime image programming interface for background patterns
  - No Graphics MIFs!
  - Allows for simplified creation of new game tracks and menus
  - Mitigates limited RAM space on the Cyclone V
- Update VGA resolution to XGA (1024 x 768 60 Hz)
- Implement real-time computation of sprite rotation
- Enable game sounds
- Model car physics and have realistic race dynamics

# CU Racing HW Interface Diagram



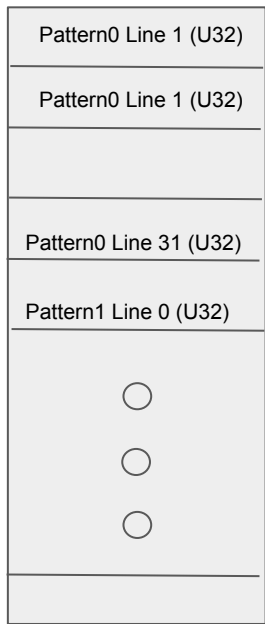
# Sprite Graphics Implementation - Pattern Tables

Red Color  
Pattern Table "Bit 2"  
0x0000



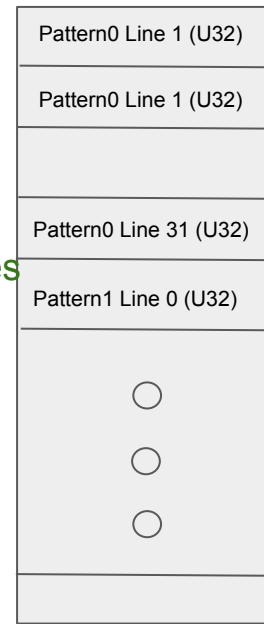
0x1FFF

Red Color  
Pattern Table "Bit 1"  
0x0000



0x1FFF

Blue Color  
Pattern Table "Bit 0"  
0x0000

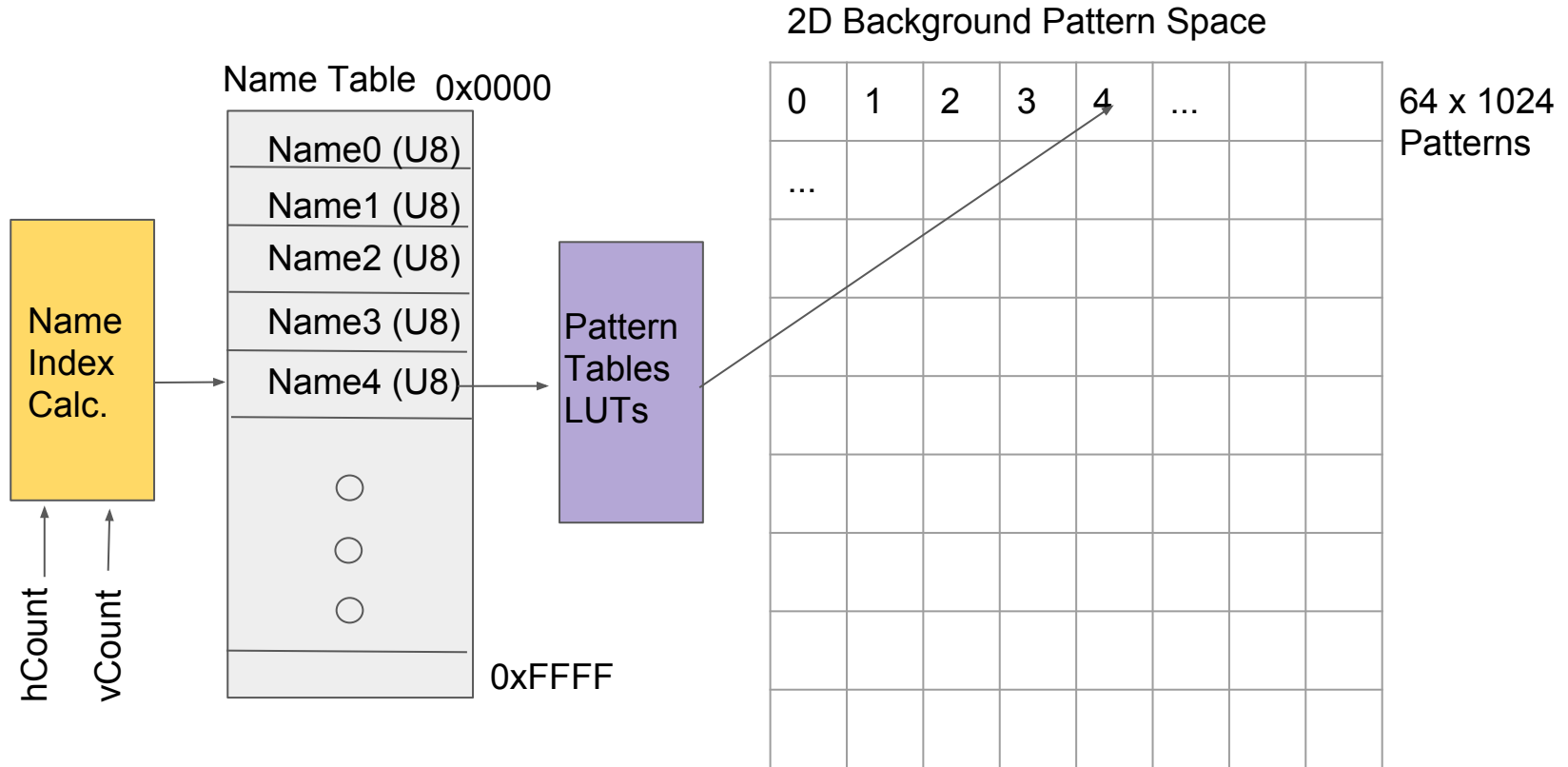


0x1FFF

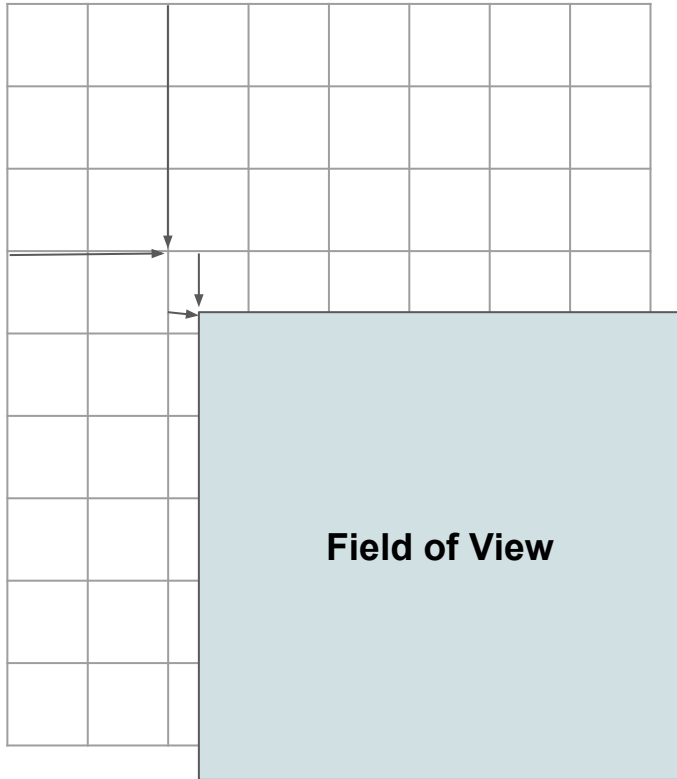
Green Color  
Pattern Tables  
○ ○ ○

- 9 Independent Dual Port RAMs to represent 512 colors/pixel
- Large "register address space"
- 8192 32 bit words / (32 bits/ pattern)
  - 256 patterns

# Sprite Graphics Implementation - Pattern Lookup



# Sprite Graphics Implementation - Movement



- Coarse and fine grain movement
  - 32 pixels "nameOffsetX/Y"
  - 1 pixel "pixelOffsetX/Y"
- Updated synced to VSYNC of VGA
- Unsigned offsets were a non-ideal design choice
  - Made movement more complicated than necessary
- Reasonably smooth movement, still isolating a few bugs

# Programmatic Map Generation

```
treeRowsTop = range(0,1024, 16)
treeRowsBottom = range(1,1025, 16)

houseRowsZero = range(0,1024, 24)
houseRowsOne = range(1,1025, 24)
houseRowsTwo = range(2,1026, 24)
houseRowsThree = range(3,1027, 24)

for row in range(0,1024):
    for col in range(0,64):
        if col == 29:
            print 1
        elif col == 30 or col == 32:
            print 2
        elif col == 31:
            print 3
        elif col == 33:
            print 4
        # Trees
        elif col == 26 and row in treeRowsBottom:
            print 6
        elif col == 27 and row in treeRowsBottom:
            print 8
        elif col == 26 and row in treeRowsTop:
            print 5
        elif col == 27 and row in treeRowsTop:
            print 7
        # House 0
        elif col == 35 and row in houseRowsZero:
            print 9
        elif col == 36 and row in houseRowsZero:
            print 10
        elif col == 37 and row in houseRowsZero:
            print 11
        elif col == 38 and row in houseRowsZero:
            print 12
        # House 1
        elif col == 35 and row in houseRowsOne:
            print 13
        elif col == 36 and row in houseRowsOne:
            print 14
        elif col == 37 and row in houseRowsOne:
            print 15
        elif col == 38 and row in houseRowsOne:
            print 16
```



“trackXNames.txt”

0  
0  
0  
0  
0  
0  
0  
0  
0  
0  
0  
0  
7  
0  
8  
0  
0  
1  
2  
3  
2  
4  
0  
0  
0  
0  
0  
0  
0  
0  
0  
0  
0  
0  
0  
0  
0

```
for i in range(0, 256):
    if i == 1:
        print "straightGrassLeft.png"
    elif i == 2:
        print "roadTileWithoutLine.png"
    elif i == 3:
        print "roadTileWithLine.png"
    elif i == 4:
        print "straightGrassRight.png"

    elif i == 5:
        print "tree-0-0.png"
    elif i == 6:
        print "tree-0-1.png"
    elif i == 7:
        print "tree-1-0.png"
    elif i == 8:
        print "tree-1-1.png"

    elif i == 9:
        print "TopRedHouse-0-0.png"
    elif i == 10:
        print "TopRedHouse-1-0.png"
    elif i == 11:
        print "TopRedHouse-2-0.png"
    elif i == 12:
        print "TopRedHouse-3-0.png"

    elif i == 13:
        print "TopRedHouse-0-1.png"
    elif i == 14:
        print "TopRedHouse-1-1.png"
    elif i == 15:
        print "TopRedHouse-2-1.png"
    elif i == 16:
        print "TopRedHouse-3-1.png"
```

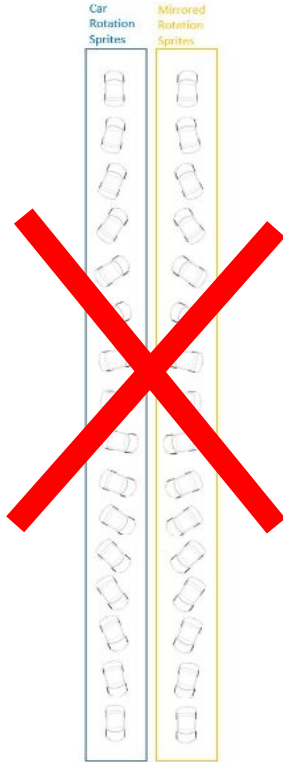


grassYellow.png  
straightGrassLeft.png  
roadTileWithoutLine.png  
roadTileWithLine.png  
straightGrassRight.png  
tree-0-0.png  
tree-0-1.png  
tree-1-0.png  
tree-1-1.png  
grassYellow.png  
grassYellow.png  
grassYellow.png  
grassYellow.png  
grassYellow.png  
grassYellow.png  
grassYellow.png  
grassYellow.png  
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grassYellow.png  
grassYellow.png

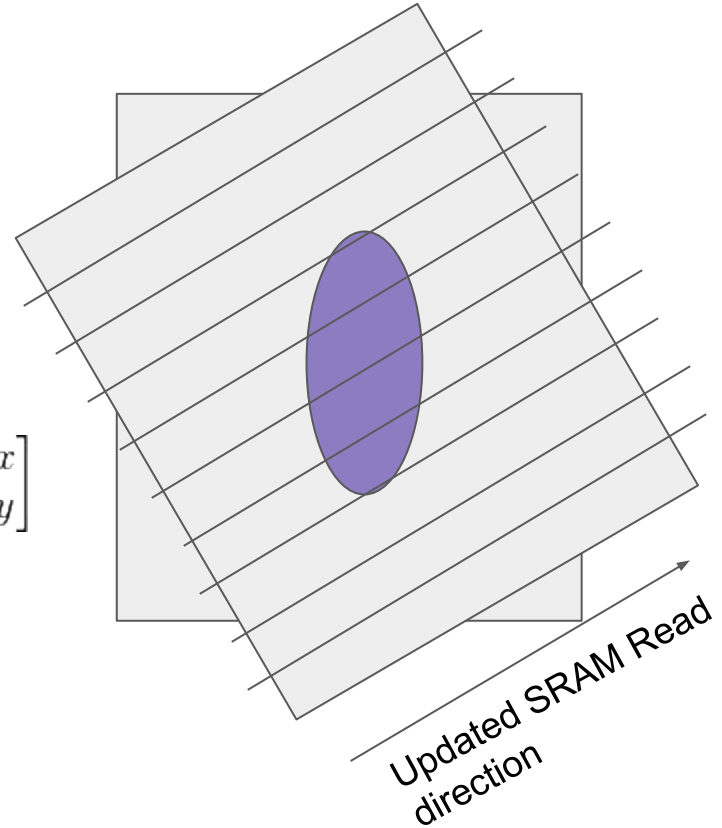
“trackXPatterns.txt”



# Sprite Rotation - Rotation Matrix Approach



$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$



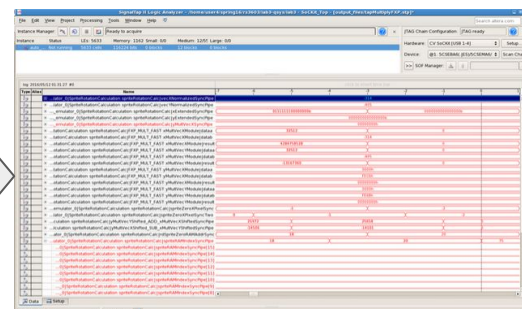
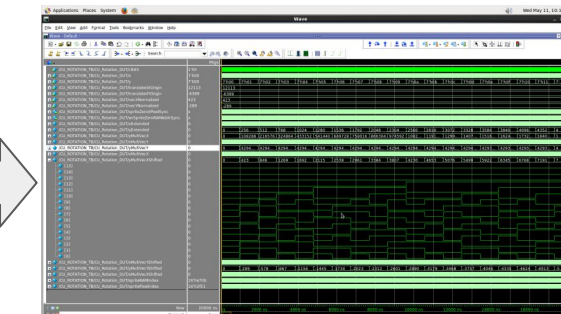
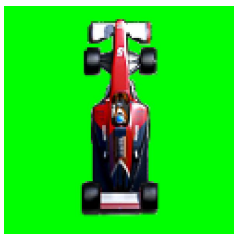
# Sprite Rotation - Development Approach

## 1) High Level Software Algorithm POC

```
val theta = -.6  
val rotationOriginX = -64 * math.cos(theta) - 64 * math.sin(theta)  
val rotationOriginY = -64 * math.sin(theta) + 64 * math.cos(theta)  
val translatedXOrigin = rotationOriginX + 64  
val translatedYOrigin = -(rotationOriginY - 64)
```

```
println("TRANSLATED ORIGIN Y" ++ translatedYOrigin.toString)  
println("TRANSLATED ORIGIN X" ++ translatedXOrigin.toString)
```

```
val vecXNormalized = 2 * math.cos(theta)  
val vecYNormalized = 2 * math.sin(theta)
```



# Lessons Learned

- Teamwork in an academic setting is difficult
  - Different experience levels, time commitments, interest etc. etc.
- Quartus II software has many quirks
  - $X \leq Y$  can yield unexpected results, sometimes it's better to manually index the bits you care about
  - Parameter constants can be different in the RTL viewer from what you would expect based on your System Verilog code
  - Warnings are almost too forgiving, some may be better to fail the compilation (net inference)
- Module based encapsulation is critical to help debug RTL code and allow for reasonable viewing of the system interconnections
- Signal Tap II is a crucial debugging tool, without it our project would have missed several desired deliverables.
- Open source drivers can be unpredictable to work with and be non-trivial to build for an embedded target