

# Embedded System Design

## Project Report

### Internet Radio

Yingjian Gu    yg2154@columbia.edu  
Qiutao Yu     qy2104@columbia.edu  
Chun-Chuen Li   cl2222@columbia.edu  
Imran Quyyum   iq2101@columbia.edu

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# 1. Project Overview

We have implemented an internet radio server using the XESS XSB-300E board. In this project we have been able to access as much as possible peripherals on the FPGA board, and learned more from the embedded system design course. We do not focus on a real functional complex internet server software in this project.

We implemented the live broadcast radio with configurable advertisement insertion. We captured the audio through the audio codec chip, and playback the broadcast content for monitoring through the codec chip and speaker. We used the UDP protocol to streaming out the audio through the ethernet controller. We could insert advertisement to the broadcast under user control.. In order to implement the configurable features, we used the VGA with menu display, and user input control from UART channel, so that the user input can be used to change the mode. We provided the SRAM, and Flash memory interface for the data storage. The SRAM is used to save the codec serial data during the capturing, also it is used as the software code running. The Flash is used to save the advertisement sound data. The SDRAM was developed, but we could not make it work with intensive audio data access.

The following is the system diagram,

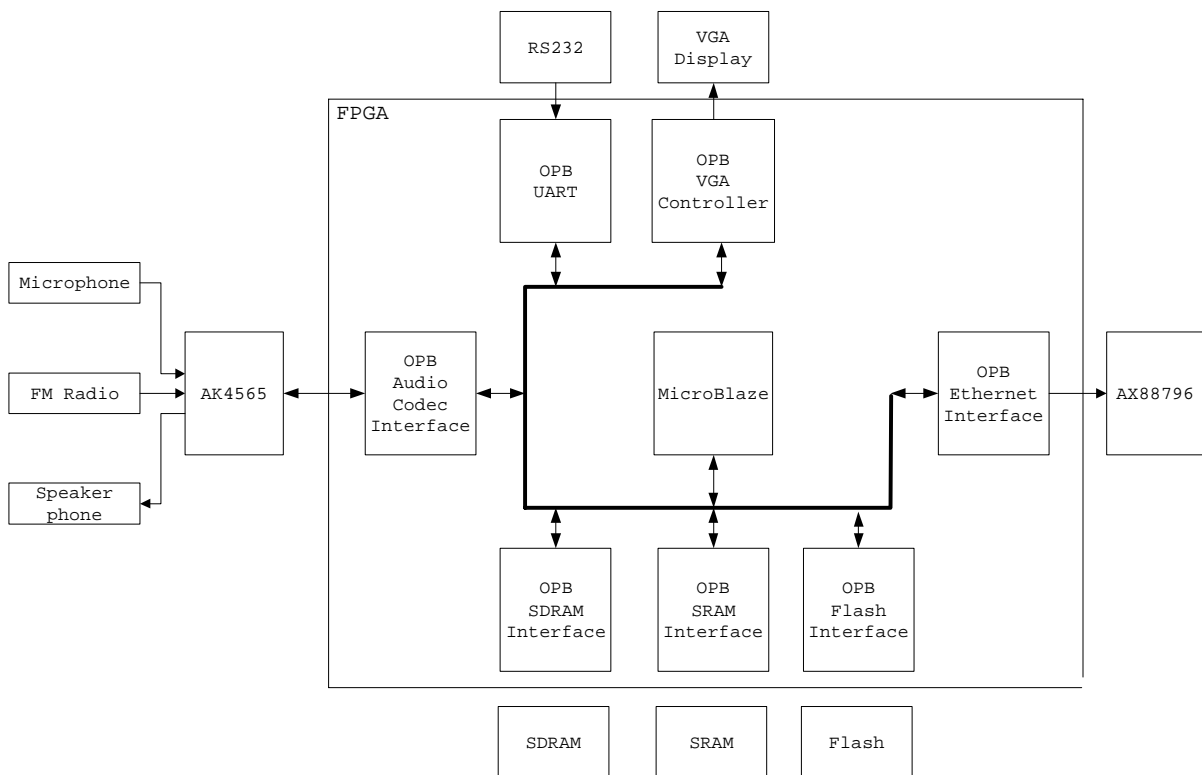


Figure 1 System Diagram

## 2. Project Design

### 2.1 System Memory Map

There are multiple peripherals, such as the BRAM, SRAM, Flash, SDRAM, VGA, Ethernet, Audio Sampler, Audio Controller, UART, Interrupt controller and MUX, being used in the project design. The memory address map is defined in the mhs file. The following memory map is created in the OPB memory space,

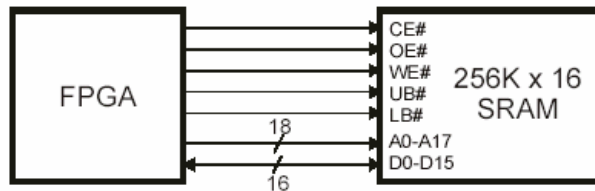
0x00000000 0x00000FFF	BRAM
0x00800000 0x00FFFFFF	Ethernet
0x20000000 0x2FFFFFFF	SRAM
0x30000000 0x3FFFFFFF	Flash
0x40000000 0x4FFFFFFF	SDRAM
0xFEFF0100 0xFEFF01FF	UART
0xFEFF0300 0xFEFF03FF	Audio Sampler
0xFEFF0400 0xFEFF04FF	Audio Controller
0xFEFF1000 0xFEFF1FFF	VGA
0xFFEF0500 0xFFEF05FF	MUX

System Memory Mapping

## 2.2 SRAM Controller Design

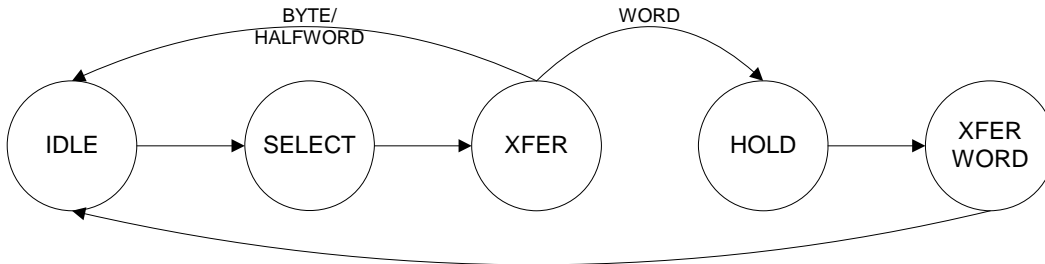
The SRAM memory is used to run the application code by the processor. It is also used as the audio data buffer. The BRAM size is very limited in terms of the program code size, and we were not able to fit the application to the BRAM. So the SRAM interface is required to run application.

The SRAM interface will handle the transfer from 32 bit OPB data bus to 16 bit SRAM data bus. All the processor access modes are supported, such as the byte mode, halfword mode and word mode. All the 512KB memory space will be accessible from the processor.

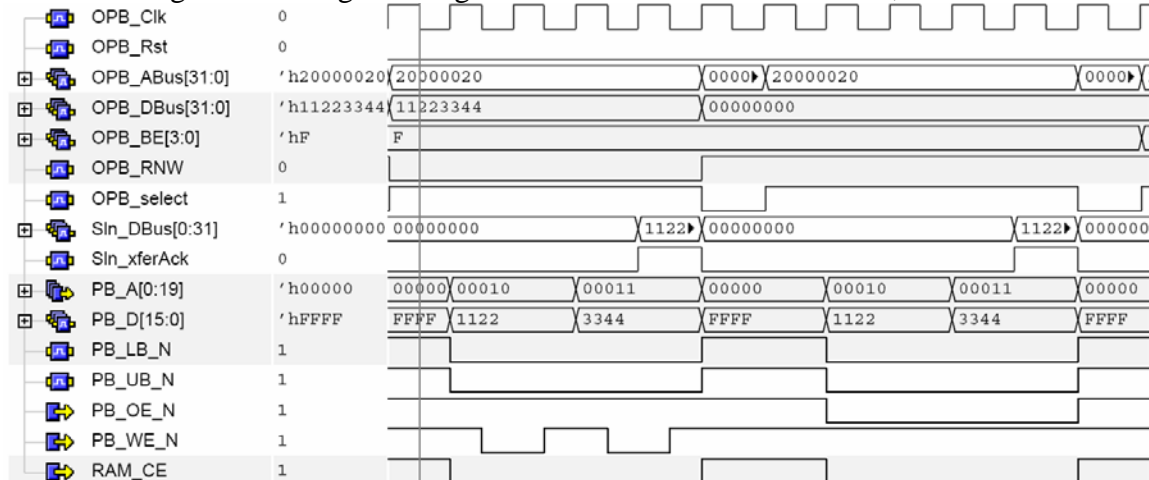


SRAM/FPGA connection

The SRAM controller will do byte mode and halfword mode in one SRAM access cycle, and word access in two SRAM access cycle. The following is the state machine of the SRAM controller,



The following is the timing showing the SRAM access in word mode,

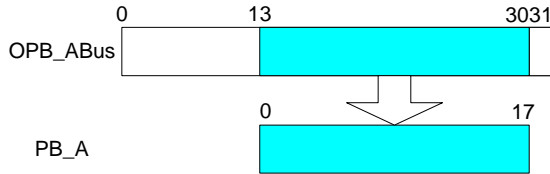


We are using big Endian notation, which has the following format:

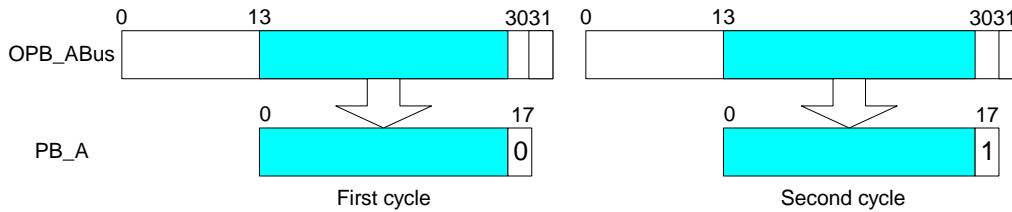


For example, the address bit 0 will be the highest bit A17 on the SRAM chip.

The OPB bus has 32-bit address bus, while the SRAM has 18-bit address bus. The following shows the mapping between the OPB and SRAM in byte and halfword mode,



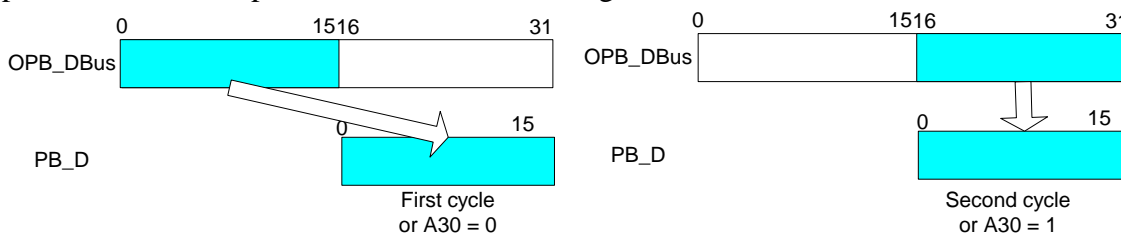
In the word mode, we will drive the lowest bit address of the SRAM as 0 in the first cycle, and drive it as 1 in the second cycle.



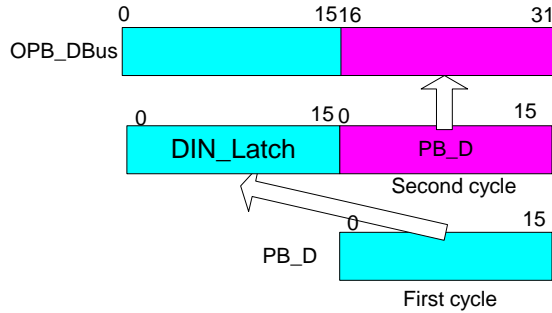
The OPB bus has 32-bit data bus, while the SRAM has 16-bit data bus. The data bus mappings are different depending on the access modes.

In the write mode, we have similar mapping for word, halfword and byte access. In the word mode, we select the OPB\_DBus higher 16 bit(0 to 15) to the SRAM data bus in the first cycle. Then we select the OPB\_DBus lower 16 bit(16 to 31) to the SRAM data bus in the second cycle.

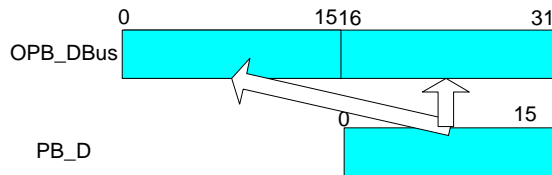
In the halfword or byte mode, we select the OPB\_DBus higher 16 bit(0 to 15) to the SRAM data bus when the A30 is 0. We select the OPB\_DBus lower 16 bit(16 to 31) to the SRAM data bus when the A30 is 1. This is not really necessary, since the MicroBlaze processor seems to provide write data mirroring.



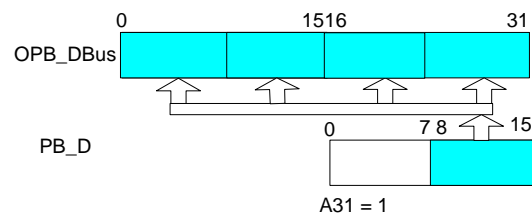
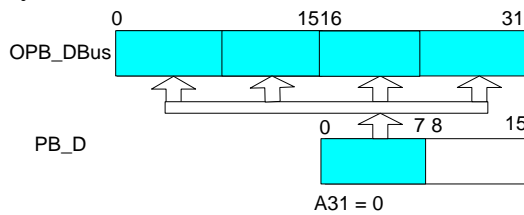
In the word mode read, we need to latch and save the first 16-bit read back data in a buffer DIN\_LATCH. Then we drive this data together with the second 16-bit read back data to the OPB\_DBus.



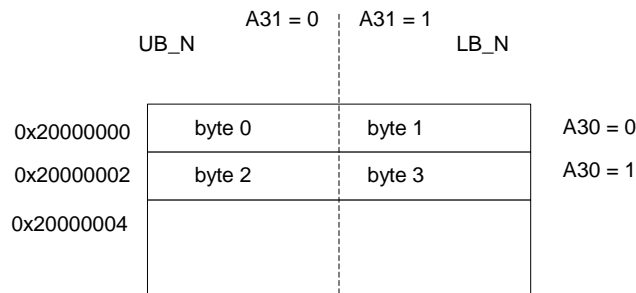
In the halfword mode read, we always drive the SRAM data output to both of the OPB\_DBus higher 16 bit and lower 16 bit.



In the byte mode read, when the A31 is 0, we drive the OPB\_DBus with SRAM higher byte (PB\_D bit 0 to 7). When the A31 is 1, we drive the OPB\_DBus with SRAM lower byte (PB\_D bit 8 to 15).



The following is the diagram shows the SRAM data and address in different access mode(byte, halfword and word),



The LB\_N and UB\_N signal is generated in the following way,

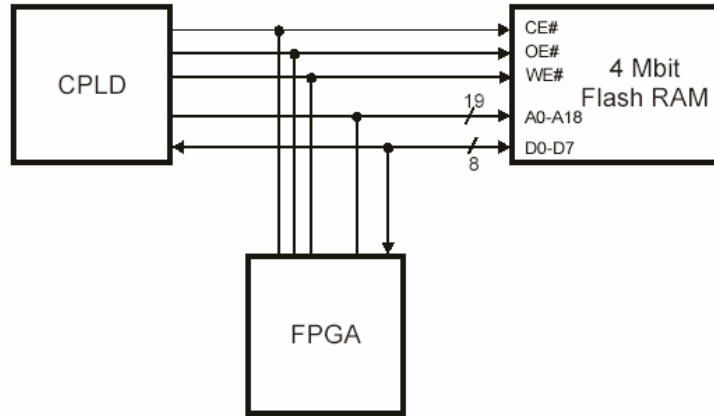
In the read operation, we drive them as active low for all the cases, since read will not destroy data any way.

In the word or halfword mode write, we drive them as active low, since both byte lane will be written.

In the byte mode, we drive them according to A31 address bit. When A31 is 1, we drive LB\_N active low. When A31 is 0, we drive UB\_N active low.

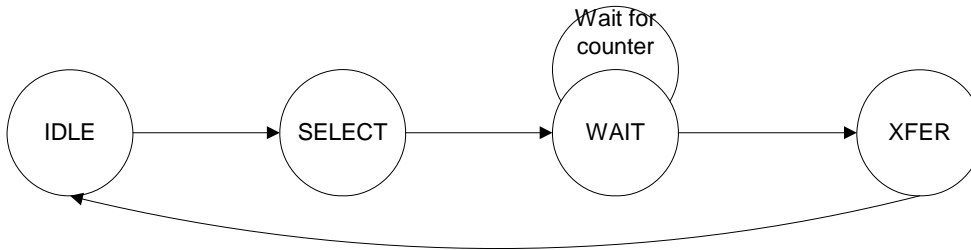
### 2.3 Flash Controller

The Flash memory is used to store the audio data. The Flash controller will provide byte mode access to the processor. All the 512KB memory space will be accessible from the processor.



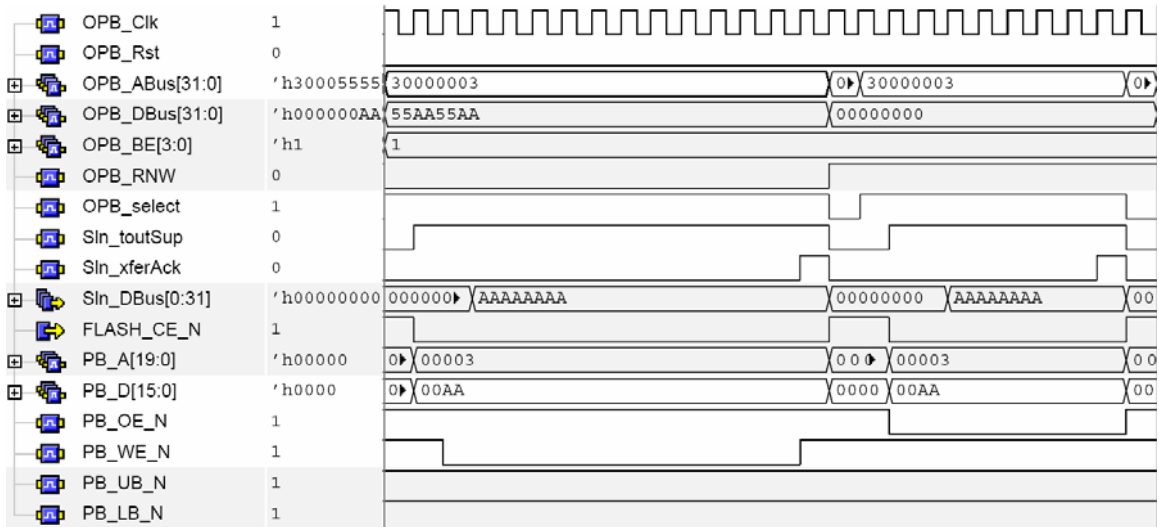
Flash/FPGA Connection

The Flash controller generates read and write timing to the Flash memory. The Flash access time is much slower than the SRAM. We had used a counter to measure the wait time during the Flash access. The following is the Flash access state machine,

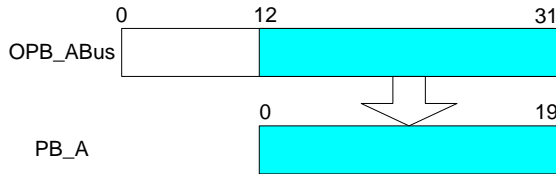


The following is the timing diagram showing the Flash access,

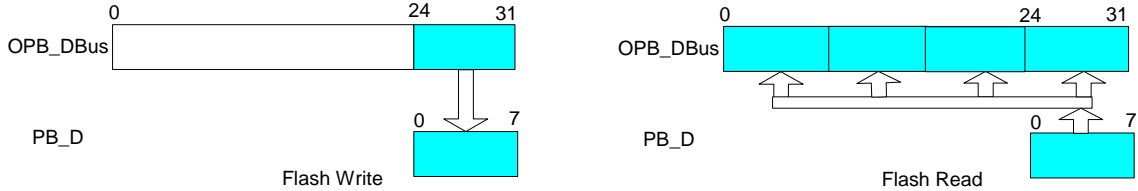




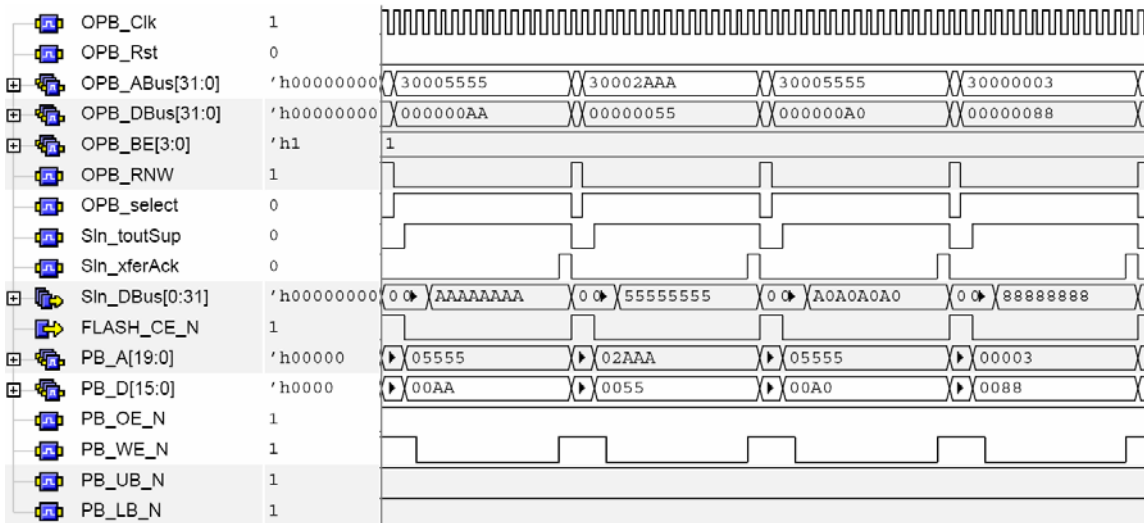
The Flash Address is mapped into byte address, and the following is the mapping:



The Flash data access is always in byte mode, and the following is the data mapping:



The Flash requires a special writing sequence for the erase and program operation. We had developed subroutine to support these operations. The following diagram shows the Flash programming cycles:



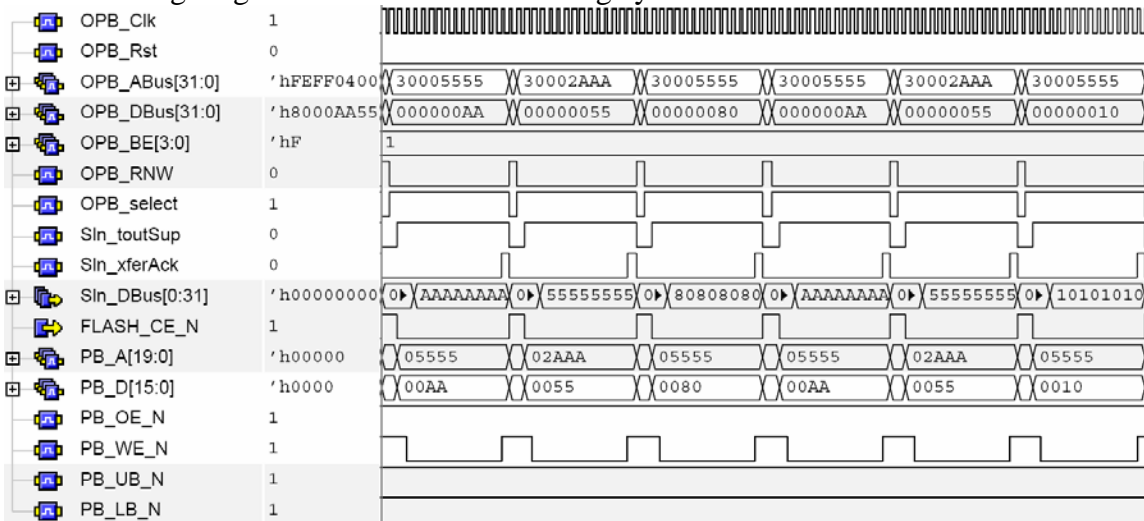
Flash Programming Timing

The Flash program subroutine takes the address and data as inputs, and then it does the following writing sequence,

```
FlashWrite(0x30005555, 0xAA);
FlashWrite(0x30002AAA, 0x55);
FlashWrite(0x30005555, 0xA0);
FlashWrite(address, data);
```

Then it will do the polling of the Flash status by calling the FlashPolling subroutine.

The following diagram shows the Flash erasing cycles:



Flash Erasing Timing

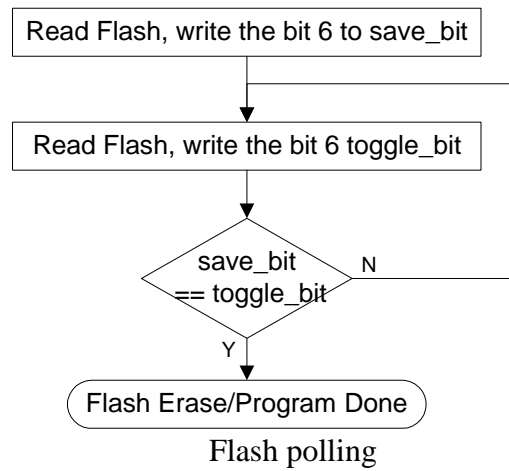
The Flash chip erase subroutine does the following writing sequence,

```
FlashWrite(0x30005555, 0xAA);
FlashWrite(0x30002AAA, 0x55);
FlashWrite(0x30005555, 0x80);
FlashWrite(0x30005555, 0xAA);
```

```
FlashWrite(0x30002AAA, 0x55);  
FlashWrite(0x30005555, 0x10);
```

Then it will do the polling of the Flash status by calling the FlashPolling subroutine.

The Flash erase and program operation takes long time to finish. During the Flash internal non volatile operation, there are toggling provided on the Flash data bus. We developed polling routine, and check the Flash status. The following shows the polling routine:



## 2.4 SDRAM Controller

The on board SDRAM provides larger memory space. We had developed SDRAM controller to provide the software SDRAM access.

The SDRAM controller works fine in memory test routine, however it fails in the extensive audio data application.

The SDRAM interface will be designed such that the SDRAM is accessed in a similar way as the SRAM. The refresh operation of the SDRAM will be done by the SDRAM controller itself. The SDRAM controller provides simple read and write operation to the OPB bus.

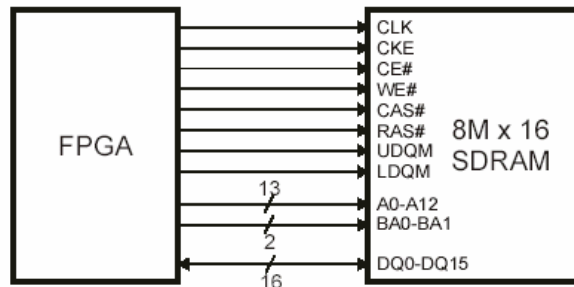
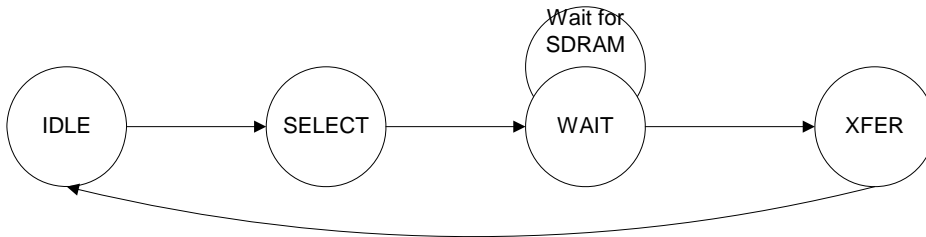


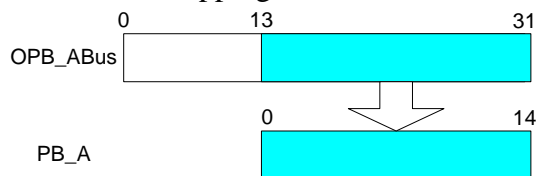
Figure 7 SDRAM/FPGA connection

We had used the XESS SDRAM controller reference design, and the details are in the an-071205-xsbsdramctl.pdf. We wrapped up the XESS SDRAM IP core, and implemented the OPB interface with our own logic.

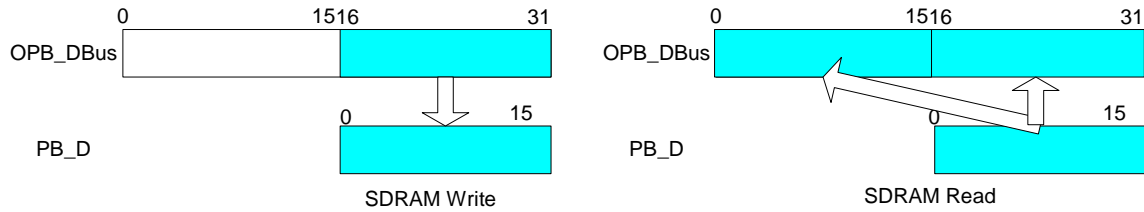
The following is the OPB state machine of the SDRAM controller,



The SDRAM interface provides 16-bit mode access to the processor. The following is the address bus mapping:



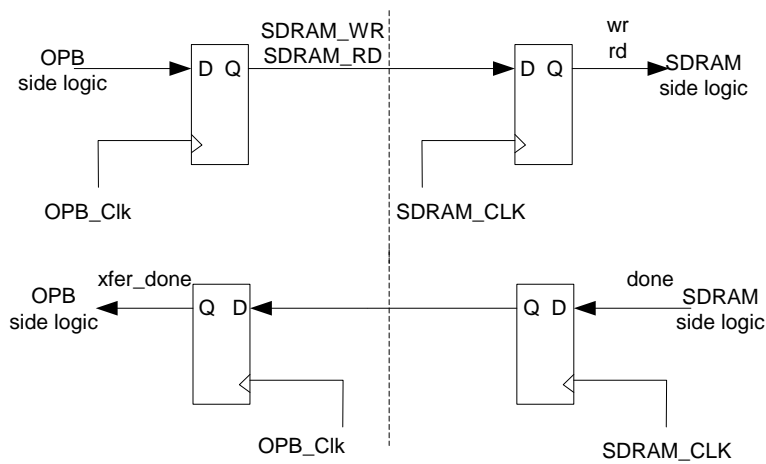
The following is the data bus mapping,



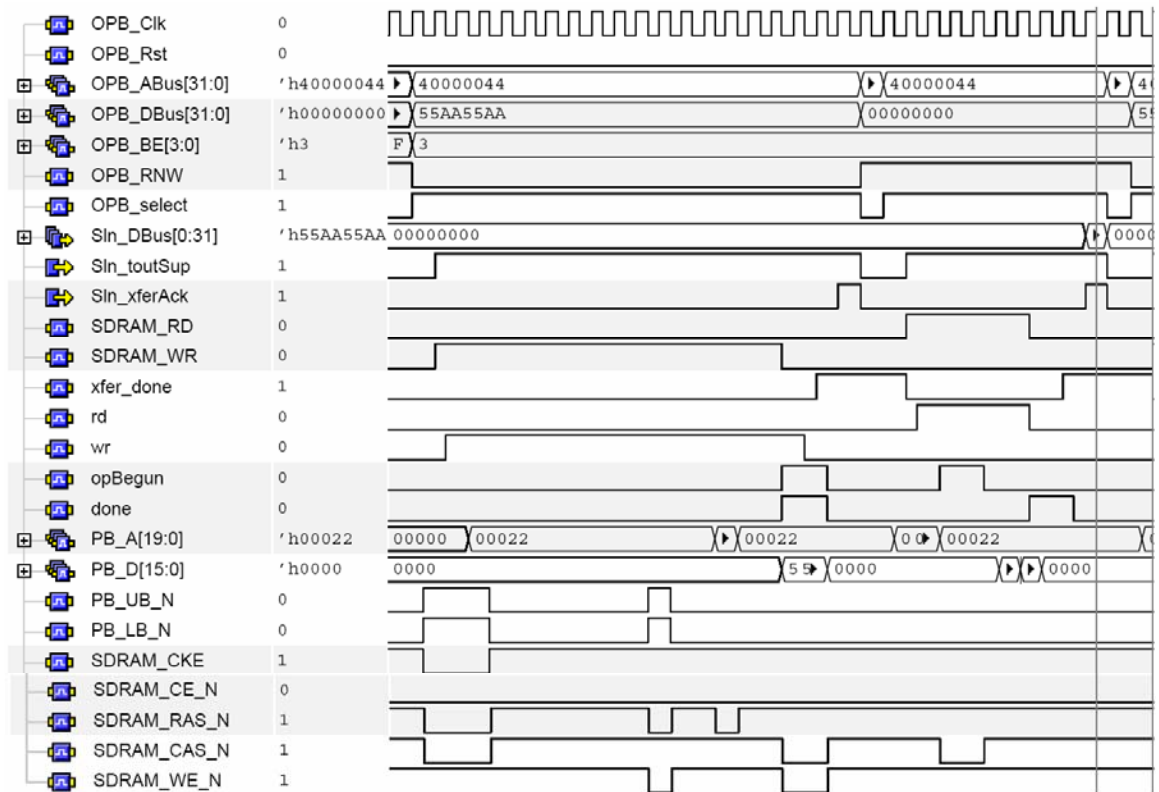
We provides halfword access for the SDRAM interface, so the C code will be looking like:

```
Unsigned short * SDRAM_BUFFER;
SDRAM_BUFFER[address] = value;
```

In the SDRAM controller, there are two global clock, OPB\_Clk (50MHz) and SDRAM clock(66MHz). The SDRAM controller works across clock domain, and we have to provide synchronization between them. The OPB\_Clk generated signal (OPB\_Clk domain) will be latched by the SDRAM clock first, then it is used to drive the SDRAM IP(SDRAM clock domain). The SDRAM IP generated signal (SDRAM clock domain) will be latched by the OPB\_Clk, then it is used to drive the OPB state machine.



The following is the SDRAM timing diagram from the XESS application note,



SDRAM Read/Write Timing

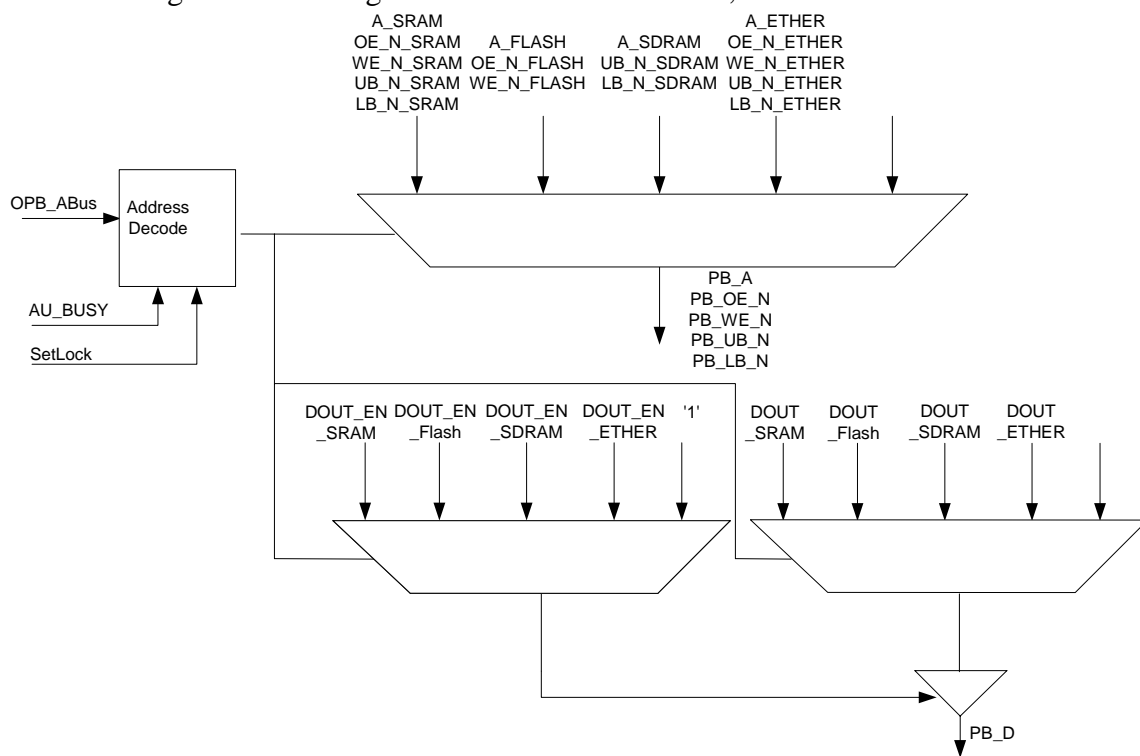
## 2.5 Peripheral Bus MUX

The FPGA board provides peripherals, such as the SRAM, Flash, SDRAM, Ethernet, and Audio, but all these peripherals share the same PB\_A, PB\_D, PB\_LB\_N, PB\_UB\_N, PB\_OE\_N, PB\_WE\_N bus signals, which are driven by the same sets of FPGA pins.

In order to access all these peripherals at the same time, we have developed peripheral bus MUX.

The MUX will consider the OPB bus address, and pick up the correct peripheral, then multiplex the address, data, and control signals to the FPGA pins.

The following shows the diagram of the MUX controller,



There are two special things in the MUX design, which is the SDRAM initialization and Audio Controller interface.

The SDRAM initialization needs dedicated PB\_A bus access, so that the SDRAM refresh, precharge, and load mode register can be done. This process takes hundreds of micro second (us). We have to lock the PB bus to the SDRAM controller during this time. This locking is done by the hardware and software cooperation. The hardware provides a SDRAM control register inside the MUX module. The following is the bit map of this register at address 0xFFEF0500,

### SDRAM CONTROL REGISTER

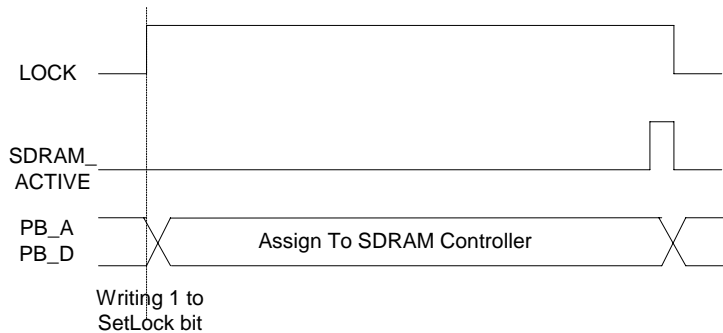
BIT 23	BIT 24	BIT 26	BIT 27	BIT 28	BIT 29	BIT 30	BIT 31
						SDRAM BUSY	SET LOCK

The InitializeSDRAM routine has been developed for this purpose. This routine will first set the LOCK as high,

```
preg = (volatile unsigned long *)SDRAM_CTL_REG_ADDR;
*preg = 1;
```

Then the MUX controller will assign the PB\_A bus to the SDRAM controller, and the BUSY bit will be driven high. When the SDRAM initialization is done, the BUSY bit will be cleared. So the code checks for the BUSY bit for the status information,

```
while (status != 0)
{
    status = *preg;
}
```



The Audio controller also requires dedicated access during the serial download. The AUDIO\_BUSY signal is created for this purpose. When the Audio controller is downloading, the MUX will lock the PB\_B bus to the Audio controller.



## 2.6 OPB TimeOut

The OPB operation defines 16 clock cycle as the time out limit. Any operation that exceeds 16 clock cycles will get time out error.

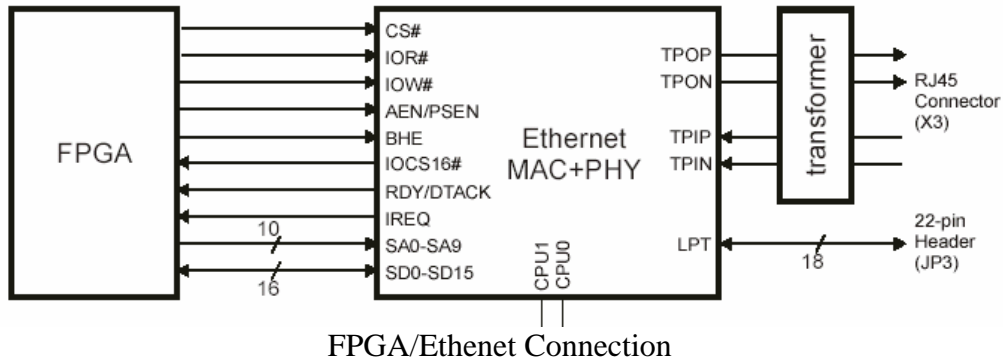
In our application, the Flash requires long writing time, but it is still within 16 clock cycles.

However, there is no guarantee that the SDRAM read or write can be done within 16 clocks. Since the SDRAM might be in the refresh mode or precharge mode when it is accessed, then it takes longer time to finish the access.

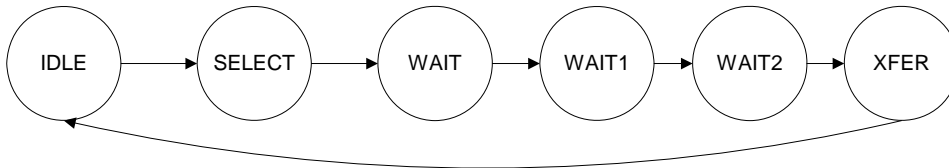
We used the Sln\_toutSup signal to suppress the time out condition on the OPB, so that we never get time out. We drive the Sln\_toutSup signal high during the access, and drive it low when the access is done.

## 2.7 Ethernet Controller

The RTP protocol will be used for the audio streaming to the internet. The processor will take the payload data from the buffer, and construct the IP/UDP/RTP packet. The Ethernet Controller ASIX AX88796L will be initialized and used to transmit the audio data to the internet.

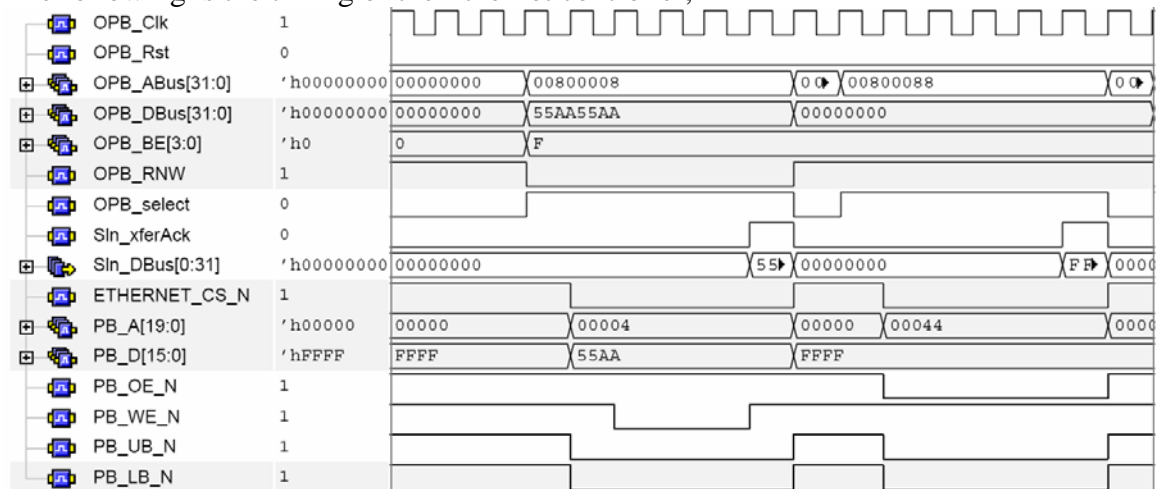


The Ethernet controller provides 16 bit interface to the processor. The following is the state machine of the Ethernet OPB interface,



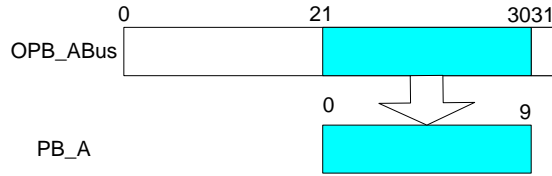
The Ethernet access provides longer wait time by additional WAIT states.

The following is the timing of the Ethernet controller,

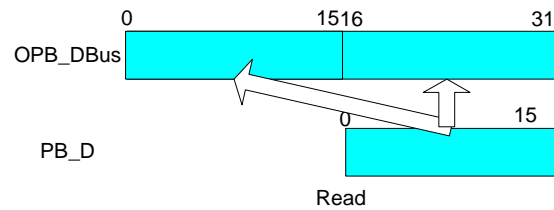
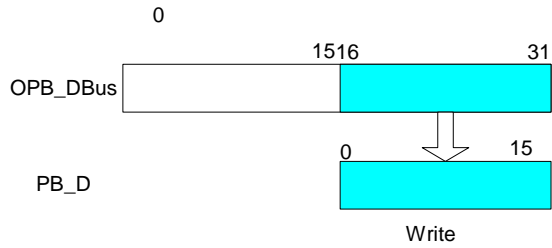


Ethernet Timing

The following is the address mapping between the OPB and PB bus,



The following is the data bus mapping,



The Ethernet controller has similar timing as the SRAM. The IO registers are mapped to halfword address in the OPB address space. So all the C accessible register address equals Ethernet chip defined address times two. The data bus width is fixed to be 16-bit, so that the access to the Ethernet is always halfword mode.

## 2.8 User Interface

The VGA display and UART is used to implement user interface. The operation of the server is controlled by the menu displayed on the VGA. The user select the menu command from the UART channel. Based on the user inputs, the operation of the server can be changed, such as switch between live broadcast and advertisement, record advertisement to Flash, etc.

The following is the menu configuration:

```
Live broadcast  ----- Enable live broadcast
                |
                |----- Disable live broadcast
                |
                |----- Return

Advertisement Insertion ----- Start Ad insertion
                |
                |----- Return

Utility         ----- Erase Flash buffer
                |
                |----- Record Ad to Flash
                |
                |----- Return
```

We use fixed address in the Flash to save the advertisement and back ground music. The size of the data is also fixed.

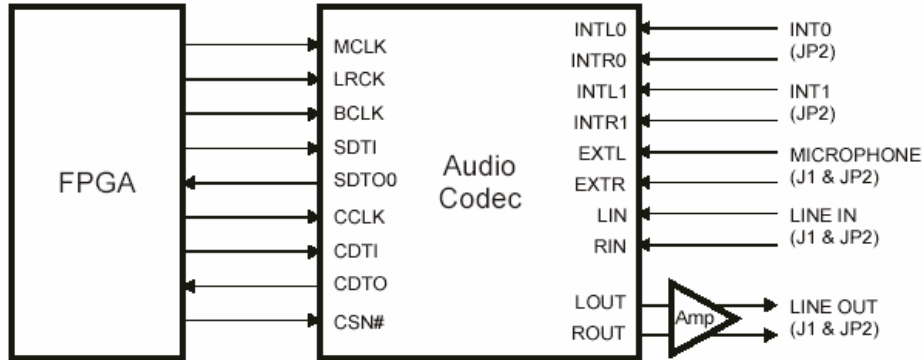
We use the text mode VGA. Because of time limit we didn't implement the graphics mode VGA for better visual effects.

The menu selection is controlled from the UART channel, and there are double right arrows pointing to the menu item which the user has chosen using up-down arrow key. The corresponding operation will be implemented after the user press enter.

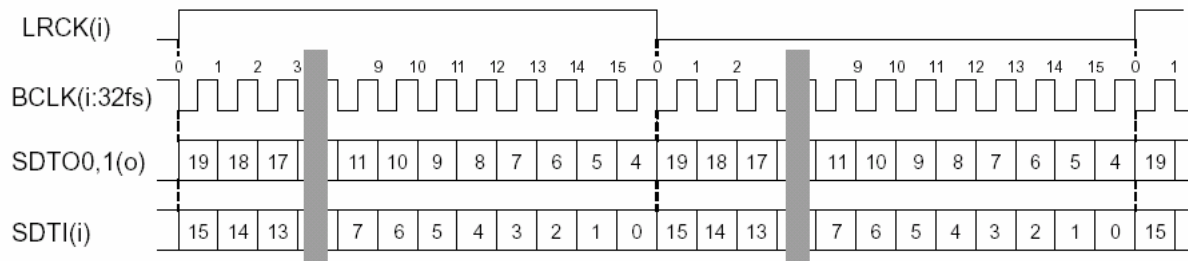
## 2.9 Live Broadcast

The audio input is taken from the AK4565 Audio Codec. The Line In is used to input sound for the broadcast. The audio codec interface is built in the FPGA, and serialized bit

stream is sent out to Ethernet controller onboard RAM. The header of packets is fixed. We send 32-bit sampler data to Ethernet as soon as one sampler interrupt occurs. Once the payload for one packet is filled. The Ethernet will transmit the constructed packet to Internet.



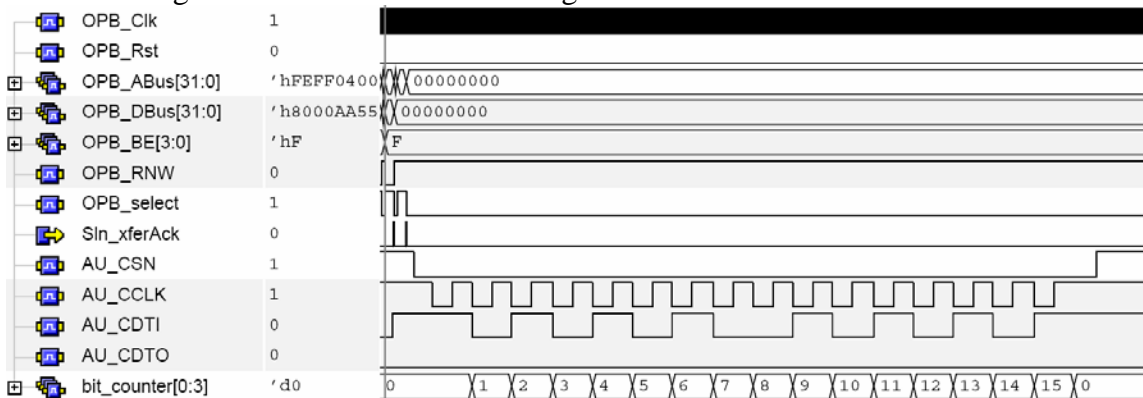
FPGA/Audio Codec Connection



Codec Timing Diagram

In order to configure the Audio Codec, we developed the Audio controller. It will handle the serial protocol between the FPGA and Codec. The FPGA starts the controller by writing to the Audio Control Register, then the OPB bus is switched to the Audio by the AU\_BUSY signal to the MUX, and the serial data is downloaded to the Audio.

The following is the Audio controller timing:



## 2.10 Advertisement Insertion

The advertisement clip would be inserted to the broadcast. The source data for the advertisement is saved in the Flash memory in advance, and sent to the ethernet controller when the advertisement mode is enabled.

The Flash OPB interface need to be designed in the FPGA. The 8-bit Flash data bus to 32 bit processor data bus conversion will be done automatically. The Flash programming and erasing command will be started by the software, as well as the polling of the status.

## 2.11 Ad/Background Sound Recording

In order to facilitate the advertisement and background music feature, the line in will be sampled in the same way as the broadcasting, and the serialized codec data will be saved in the SRAM memory temporarily.

The size of the captured data will be in fixed length to simplify the design. The SRAM buffer is then programmed to the Flash memory, so that the contents are not lost after power down.

## 2.12 Packet Receiving Debug Tools

We use several tools to test our audio packet sent out via Ethernet can be properly received.

Ethereal: sniffing packets on the network.

Rtpdump: `rtpdump -F payload -t 0.5 -o test.pcm /3042`

Dump packets from port 3042 to file test.pcm for 0.5 minutes

Cool Edit: play PCM audio file dumped by rtp tools

Mplayer: playing client

`mplayer -demuxer rawaudio -rawaudio channels=2:rate=11800`

`rtp://128.59.144.169:3042`

## **3. Conclusion**

### **3.1 Who Did What And Lessons Learned**

#### **Yingjian Gu**

I did the SRAM controller, Flash controller, MUX and SDRAM controller hardware design. I also did the Flash driver software, including the programming, erasing and polling routine. I did the SDRAM initialization software routine as well, and the memory access test code. The SRAM controller is verified by processor code running. The Flash controller is verified in the Audio application. The MUX is the key to implement and access all the peripherals in the same design. The SDRAM controller design works in test code, but fails in extensive data application as the Audio recording. I did not realize that the SDRAM controller had multiple clock domain issue, and had no synchronization logic between clock domains at the beginning. This caused the SDRAM controller did not work stable, and system hang up some time.

#### **Qiutao Yu**

I love embedded system design! I am really fascinated by the small XESS XSB-300E FPGA board. I am so glad that I took this course. Most of the system software design is done by me. First I spend countless hours trying to figure out the system principle of this project from last year's successfully implemented internet radio project. As I read their project report I realize this is really not an easy job. The guys of last year did very well. After I analyzed their C codes and well written report things become more and more clear. Basically our project should have improvement over last year so we add more function to the internet radio server built on the FPGA board.

Originally we plan to add background music to our live broadcast, create our own client software and use graphic VGA to display the user interface for better visual effects. We do not incorporate these to our final project because of time constraints. The BRAM is really too small for our project. When I design the menu interface to be displayed on VGA something really weird happens. There are just random characters on the VGA which is not expected and the program does not respond to any input from the uart. At first I do not realize this is because the length of the codes is out of the BRAM space. It is really painful when you debug your code and find even the sequence of two similar statements can have different consequence. I should have found out the reason much earlier. After I realized it is the problem of the BRAM limit I have to move most of our codes to SRAM which will lower down our program running speed such that we have to lower down the sampling frequency of the audio codes in order to the frequency of interrupt handling. We use the audio chip Line In as audio input and create our own audio controller but it does not work properly so I found a tool from XSTOOL provided by XESS to configure the audio chip with specified sampling frequency and input method first before the bit stream is downloaded to FPGA. I find a lot of fun when I successfully make my own program work after days of debugging.

### **Chun-Chuen Li**

Teamwork is really, really important! There are times we missed meeting each other, and got a bit lazy. However, it was great we came back with new ideas toward the project. I learned to criticize my teammate's work and provided suggestion to have the C code run more efficient. Working in team also helps alleviate anxiety built from trying to understand things on our own, as reading specifications and think "worldly" in this real world like project environment. I was trying to figure out how to vary the rate of the audio output by changing the MPlayer. Out of the blue, I found out an answer to it. The real world is vast, yet there is somewhere we can fetch for the facts. This is what I learned from this team project.

### **Imran Quyyum**

I help with team to create the audio sampler OPB peripheral to sample the audio data in. The distinction between computer programming and computer engineering is hard to grasp until this course is taken. The programming style that the Intro. to Computer Science taught becomes less relevant and FSM diagrams and debugging soon top the list of things that makes you question sometimes whether engineering is really for you or not. But when the project actually works, it's an overwhelming feeling of joy and you will be glad that you took the challenge.

## **3.2 Future Work**

There can be a lot of things to do for future enhancement of our project. It would be fine to create the client on our own not just the Mplayer we use. For this project we only broadcast out the rtp packets to a computer with destination IP and MAC address specified in the header of the packets. That the audio packets can be received anywhere with connection to Internet would be great. Also more function such as mixing the live broadcast with background music can be added. If the audio sampling frequency can be increased without affecting the execution of the main program the sound quality would be much improved.



## 4. Code Listings

### 4.1 Configuration Files

#### 4.1.1 system.mhs

```
#-----#
# CSEE 4840 Embedded System Design #
# #
# Internet Radio #
# #
# Team Members: Qiutao Yu #
# Yingjian Gu #
# Chun-Chuen Li #
# Imran Quyyum #
#-----#

# Parameters
PARAMETER VERSION = 2.1.0

# Global Ports
PORT FPGA_CLK1 = FPGA_CLK1, DIR = IN
PORT RS232_TD = RS232_TD, DIR = OUT
PORT RS232_RD = RS232_RD, DIR = IN
#PORT RIGHT_LED = RIGHT_LED, DIR = OUT, VEC = [7:0]
#PORT LEFT_LED = LEFT_LED, DIR = OUT, VEC = [7:0]
#PORT BAR_LED = BAR_LED, DIR = OUT, VEC = [9:0]
PORT VIDOUT_CLK = VIDOUT_CLK, DIR = OUT
PORT VIDOUT_HSYNC_N = VIDOUT_HSYNC_N, DIR = OUT
PORT VIDOUT_VSYNC_N = VIDOUT_VSYNC_N, DIR = OUT
PORT VIDOUT_BLANK_N = VIDOUT_BLANK_N, DIR = OUT
PORT VIDOUT_RED = VIDOUT_RED, DIR = OUT, VEC = [9:0]
PORT VIDOUT_GREEN = VIDOUT_GREEN, DIR = OUT, VEC = [9:0]
PORT VIDOUT_BLUE = VIDOUT_BLUE, DIR = OUT, VEC = [9:0]

# PH bus ports
PORT PB_D = PB_D, DIR = INOUT, VEC=[15:0]
PORT PB_A = PB_A, DIR = OUT, VEC=[19:0]
PORT PB_OE_N = PB_OE_N, DIR = OUT
PORT PB_WE_N = PB_WE_N, DIR = OUT
PORT PB_UB_N = PB_UB_N, DIR = OUT
PORT PB_LB_N = PB_LB_N, DIR = OUT
PORT RAM_CE_N = RAM_CE_N, DIR = OUT

# Ethernet Ports
```

```
PORT ETHERNET_CS_N = ETHERNET_CS_N, DIR = OUT
PORT ETHERNET_IOCS16_N = ETHERNET_IOCS16_N, DIR = IN
PORT ETHERNET_RDY = ETHERNET_RDY, DIR = IN
PORT ETHERNET_IREQ = ETHERNET_IREQ, DIR = IN
```

```
# Audio Codec Ports
```

```
PORT AU_CSN = AU_CSN, DIR=OUT
PORT AU_MCLK = AU_MCLK, DIR=OUT
PORT AU_LRCK = AU_LRCK, DIR=OUT
PORT AU_BCLK = AU_BCLK, DIR=OUT
PORT AU_SDTI = AU_SDTI, DIR=OUT
PORT AU_SDT00 = AU_SDT00, DIR=IN
```

```
#SDRAM Ports
```

```
PORT SDRAM_CKE = SDRAM_CKE , DIR = OUT
PORT SDRAM_CAS_N = SDRAM_CAS_N , DIR = OUT
PORT SDRAM_RAS_N = SDRAM_RAS_N , DIR = OUT
PORT SDRAM_CE_N = SDRAM_CE_N , DIR = OUT
PORT SDRAM_WE_N = SDRAM_WE_N , DIR = OUT
PORT SDRAM_CLK = SDRAM_CLK, DIR = IN
```

```
#Flash Ports
```

```
PORT FLASH_CE_N = FLASH_CE_N, DIR = OUT
```

```
# Hint: Put your peripheral first in this file so it will be analyzed
# first and will generate errors faster.
# BRAM example peripheral
```

```
BEGIN opb_pb_mux
PARAMETER INSTANCE = pb_mux
PARAMETER HW_VER = 1.00.a
PARAMETER C_BASEADDR = 0xFFEF0500
PARAMETER C_HIGHADDR = 0xFFEF05FF
BUS_INTERFACE SOPB = myopb_bus
PORT OPB_Clk = sys_clk
PORT PB_D = PB_D
PORT PB_A = PB_A
PORT PB_OE_N = PB_OE_N
PORT PB_WE_N = PB_WE_N
PORT PB_UB_N = PB_UB_N
PORT PB_LB_N = PB_LB_N

PORT PB_DIN = PB_DIN
PORT PB_DOUT_SRAM = PB_DOUT_SRAM
PORT PB_DOUT_EN_SRAM = PB_DOUT_EN_SRAM
```

```

PORT PB_A_SRAM = PB_A_SRAM
PORT PB_OE_N_SRAM = PB_OE_N_SRAM
PORT PB_WE_N_SRAM = PB_WE_N_SRAM
PORT PB_UB_N_SRAM = PB_UB_N_SRAM
PORT PB_LB_N_SRAM = PB_LB_N_SRAM

PORT PB_DOUT_FLASH = PB_DOUT_FLASH
PORT PB_DOUT_EN_FLASH = PB_DOUT_EN_FLASH
PORT PB_A_FLASH = PB_A_FLASH
PORT PB_OE_N_FLASH = PB_OE_N_FLASH
PORT PB_WE_N_FLASH = PB_WE_N_FLASH

PORT PB_DOUT_SDRAM = PB_DOUT_SDRAM
PORT PB_DOUT_EN_SDRAM = PB_DOUT_EN_SDRAM
PORT PB_A_SDRAM = PB_A_SDRAM
PORT PB_UB_N_SDRAM = PB_UB_N_SDRAM
PORT PB_LB_N_SDRAM = PB_LB_N_SDRAM

PORT PB_DOUT_ETHER = PB_DOUT_ETHER
PORT PB_DOUT_EN_ETHER = PB_DOUT_EN_ETHER
PORT PB_A_ETHER = PB_A_ETHER
PORT PB_OE_N_ETHER = PB_OE_N_ETHER
PORT PB_WE_N_ETHER = PB_WE_N_ETHER
PORT PB_UB_N_ETHER = PB_UB_N_ETHER
PORT PB_LB_N_ETHER = PB_LB_N_ETHER

PORT AU_BUSY = AU_BUSY
PORT AU_CCLK = AU_CCLK
PORT AU_CDTI = AU_CDTI

PORT SDRAM_LOCK = SDRAM_LOCK
PORT SDRAM_ACTIVE = SDRAM_ACTIVE

END

BEGIN opb_sram
PARAMETER INSTANCE = sram
PARAMETER HW_VER = 1.00.a
PARAMETER C_BASEADDR = 0x20000000
PARAMETER C_HIGHADDR = 0x2FFFFFFF
BUS_INTERFACE SOPB = myopb_bus
PORT OPB_Clk = sys_clk
PORT PB_DIN = PB_DIN
PORT PB_DOUT = PB_DOUT_SRAM
PORT PB_DOUT_EN = PB_DOUT_EN_SRAM
PORT PB_A = PB_A_SRAM

```

```
PORT RAM_CE = RAM_CE_N
PORT PB_OE_N = PB_OE_N_SRAM
PORT PB_WE_N = PB_WE_N_SRAM
PORT PB_UB_N = PB_UB_N_SRAM
PORT PB_LB_N = PB_LB_N_SRAM
END
```

```
BEGIN opb_flash
PARAMETER INSTANCE = flash
PARAMETER HW_VER = 1.00.a
PARAMETER C_BASEADDR = 0x30000000
PARAMETER C_HIGHADDR = 0x3FFFFFFF
BUS_INTERFACE SOPB = myopb_bus
PORT OPB_Clk = sys_clk
PORT PB_DIN = PB_DIN
PORT PB_DOUT = PB_DOUT_FLASH
PORT PB_DOUT_EN = PB_DOUT_EN_FLASH
PORT PB_A = PB_A_FLASH
PORT PB_OE_N = PB_OE_N_FLASH
PORT PB_WE_N = PB_WE_N_FLASH
PORT FLASH_CE_N = FLASH_CE_N
END
```

```
BEGIN opb_sdram
PARAMETER INSTANCE = sdram
PARAMETER HW_VER = 1.00.a
PARAMETER C_BASEADDR = 0x40000000
PARAMETER C_HIGHADDR = 0x4FFFFFFF
BUS_INTERFACE SOPB = myopb_bus
PORT OPB_Clk = sys_clk
PORT PB_DIN = PB_DIN
PORT PB_DOUT = PB_DOUT_SDRAM
PORT PB_DOUT_EN = PB_DOUT_EN_SDRAM
PORT PB_A = PB_A_SDRAM
PORT SDRAM_CKE = SDRAM_CKE
PORT SDRAM_CAS_N = SDRAM_CAS_N
PORT SDRAM_RAS_N = SDRAM_RAS_N
PORT SDRAM_CE_N = SDRAM_CE_N
PORT SDRAM_WE_N = SDRAM_WE_N
PORT PB_UB_N = PB_UB_N_SDRAM
PORT PB_LB_N = PB_LB_N_SDRAM
PORT SDRAM_LOCK = SDRAM_LOCK
PORT SDRAM_ACTIVE = SDRAM_ACTIVE
PORT SDRAM_CLK = SDRAM_CLK
END
```

```

# Useful trick: put the IP you are developing first in this list
# so that it is compiled (and therefore may fail) before anything else
# Video Controller
BEGIN opb_xsb300e_vga
PARAMETER INSTANCE = vga
PARAMETER HW_VER = 1.00.a
PARAMETER C_BASEADDR = 0xFEFF1000
PARAMETER C_HIGHADDR = 0xFEFF1fff
BUS_INTERFACE SOPB = myopb_bus
PORT OPB_Clk = sys_clk
PORT pixel_clock = pixel_clock
PORT VIDOUT_CLK = VIDOUT_CLK
PORT VIDOUT_RED = VIDOUT_RED
PORT VIDOUT_GREEN = VIDOUT_GREEN
PORT VIDOUT_BLUE = VIDOUT_BLUE
PORT VIDOUT_BLANK_N = VIDOUT_BLANK_N
PORT VIDOUT_HSYNC_N = VIDOUT_HSYNC_N
PORT VIDOUT_VSYNC_N = VIDOUT_VSYNC_N
END

```

```

# Ethernet peripheral

```

```

BEGIN opb_ethernet
PARAMETER INSTANCE = ethernet_peripheral
PARAMETER HW_VER = 1.00.a
PARAMETER C_BASEADDR = 0x00800000
PARAMETER C_HIGHADDR = 0x00FFFFFF
PORT OPB_CLK = sys_clk
BUS_INTERFACE SOPB = myopb_bus

PORT ETHERNET_CS_N = ETHERNET_CS_N
PORT ETHERNET_RDY = ETHERNET_RDY
PORT ETHERNET_IREQ = ETHERNET_IREQ
PORT ETHERNET_IOCS16_N = ETHERNET_IOCS16_N

PORT PB_DIN = PB_DIN
PORT PB_DOUT = PB_DOUT_ETHER
PORT PB_DOUT_EN = PB_DOUT_EN_ETHER
PORT PB_A = PB_A_ETHER
PORT IORD_N = PB_OE_N_ETHER
PORT IOWR_N = PB_WE_N_ETHER
PORT BHE_N = PB_UB_N_ETHER
PORT AEN = PB_LB_N_ETHER

END

```

```

# Audio Sampler Peripheral
BEGIN opb_audio_sampler
  PARAMETER INSTANCE = audio_sampler
  PARAMETER HW_VER = 1.00.a
  PARAMETER C_BASEADDR = 0xFEFF0300
  PARAMETER C_HIGHADDR = 0xFEFF03FF
  BUS_INTERFACE SOPB = myopb_bus
  PORT OPB_Clk = sys_clk
  PORT AU_MCLK = AU_MCLK
  PORT AU_LRCK = AU_LRCK
  PORT AU_BCLK = AU_BCLK
  PORT AU_SDTI = AU_SDTI
  PORT AU_SDTO0 = AU_SDTO0
  PORT INTERRUPT = sampler_intr
END

```

```

# Audio Controller Peripheral
BEGIN opb_audio_controller
  PARAMETER INSTANCE = audio_controller
  PARAMETER HW_VER = 1.00.a
  PARAMETER C_BASEADDR = 0xFEFF0400
  PARAMETER C_HIGHADDR = 0xFEFF04FF
  BUS_INTERFACE SOPB = myopb_bus
  PORT OPB_Clk = sys_clk
  PORT AU_BUSY = AU_BUSY
  PORT AU_CSN = AU_CSN
  PORT AU_CCLK = AU_CCLK
  PORT AU_CDTI = AU_CDTI
  PORT PB_DIN = PB_DIN
END

```

```

# Interrupt controller for dealing with interrupts from the UART
BEGIN opb_intc
  PARAMETER INSTANCE = intc
  PARAMETER HW_VER = 1.00.c
  PARAMETER C_BASEADDR = 0xFFFF0000
  PARAMETER C_HIGHADDR = 0xFFFF00FF
  BUS_INTERFACE SOPB = myopb_bus
  PORT OPB_Clk = sys_clk
  PORT Intr = uart_intr & sampler_intr
  PORT Irq = intr
END

```

```

# Block RAM for code and data is connected through two LMB busses
# to the Microblaze, which has two ports on it for just this reason.

```

```

# Data LMB bus
BEGIN lmb_v10
  PARAMETER INSTANCE = d_lmb
  PARAMETER HW_VER = 1.00.a
  PORT LMB_Clk = sys_clk
  PORT SYS_Rst = fpga_reset
END

BEGIN lmb_bram_if_cntlr
  PARAMETER INSTANCE = lmb_data_controller
  PARAMETER HW_VER = 1.00.b
  PARAMETER C_BASEADDR = 0x00000000
  PARAMETER C_HIGHADDR = 0x00000FFF
  BUS_INTERFACE SLMB = d_lmb
  BUS_INTERFACE BRAM_PORT = conn_0
END

# Instruction LMB bus
BEGIN lmb_v10
  PARAMETER INSTANCE = i_lmb
  PARAMETER HW_VER = 1.00.a
  PORT LMB_Clk = sys_clk
  PORT SYS_Rst = fpga_reset
END

BEGIN lmb_bram_if_cntlr
  PARAMETER INSTANCE = lmb_instruction_controller
  PARAMETER HW_VER = 1.00.b
  PARAMETER C_BASEADDR = 0x00000000
  PARAMETER C_HIGHADDR = 0x00000FFF
  BUS_INTERFACE SLMB = i_lmb
  BUS_INTERFACE BRAM_PORT = conn_1
END

# The actual block memory
BEGIN bram_block
  PARAMETER INSTANCE = bram
  PARAMETER HW_VER = 1.00.a
  BUS_INTERFACE PORTA = conn_0
  BUS_INTERFACE PORTB = conn_1
END

# Clock divider to make the whole thing run
BEGIN clkgen
  PARAMETER INSTANCE = clkgen_0
  PARAMETER HW_VER = 1.00.a

```

```

PORT FPGA_CLK1 = FPGA_CLK1
PORT sys_clk = sys_clk
PORT pixel_clock = pixel_clock
PORT fpga_reset = fpga_reset
END

# The OPB bus controller connected to the Microblaze
# All peripherals are connected to this
BEGIN opb_v20
PARAMETER INSTANCE = myopb_bus
PARAMETER HW_VER = 1.10.a
PARAMETER C_DYNAM_PRIORITY = 0
PARAMETER C_REG_GRANTS = 0
PARAMETER C_PARK = 0
PARAMETER C_PROC_INTRFCE = 0
PARAMETER C_DEV_BLK_ID = 0
PARAMETER C_DEV_MIR_ENABLE = 0
PARAMETER C_BASEADDR = 0x0fff1000
PARAMETER C_HIGHADDR = 0x0fff10ff
PORT SYS_Rst = fpga_reset
PORT OPB_Clk = sys_clk
END

# UART: Serial port hardware
BEGIN opb_uartlite
PARAMETER INSTANCE = myuart
PARAMETER HW_VER = 1.00.b
PARAMETER C_CLK_FREQ = 50_000_000
PARAMETER C_USE_PARITY = 0
PARAMETER C_BASEADDR = 0xFEFF0100
PARAMETER C_HIGHADDR = 0xFEFF01FF
BUS_INTERFACE SOPB = myopb_bus
PORT OPB_Clk = sys_clk
PORT Interrupt = uart_intr
PORT RX = RS232_RD
PORT TX = RS232_TD
END

# Very simple LED controller for the XESS XSB-300E board
#BEGIN opb_xsbleds
# PARAMETER INSTANCE = leds
# PARAMETER HW_VER = 1.00.a
# PARAMETER C_BASEADDR = 0xFEFF0200
# PARAMETER C_HIGHADDR = 0xFEFF02ff
# BUS_INTERFACE SOPB = myopb_bus
# PORT OPB_Clk = sys_clk

```



```

# PORT RIGHT_LED = RIGHT_LED
# PORT LEFT_LED = LEFT_LED
# PORT BAR_LED = BAR_LED
#END

# The main processor core
BEGIN microblaze
PARAMETER INSTANCE = mymicroblaze
PARAMETER HW_VER = 3.00.a
PARAMETER C_USE_BARREL = 1
PARAMETER C_USE_ICACHE = 0
BUS_INTERFACE DLMB = d_lmb
BUS_INTERFACE ILMB = i_lmb
BUS_INTERFACE DOPB = myopb_bus
BUS_INTERFACE IOPB = myopb_bus
PORT Clk = sys_clk
PORT Reset = fpga_reset
PORT Interrupt = intr
END

```

#### 4.1.2 system.mss

```

#-----#
# CSEE 4840 Embedded System Design #
# #
# Internet Radio #
# #
# Team Members: Qiutao Yu #
# Yingjian Gu #
# Chun-Chuen Li #
# Imran Quyyum #
#-----#

PARAMETER VERSION = 2.2.0
PARAMETER HW_SPEC_FILE = system.mhs

```

```

BEGIN OS
PARAMETER PROC_INSTANCE = mymicroblaze
PARAMETER OS_NAME = standalone
PARAMETER OS_VER = 1.00.a
PARAMETER STDIN = myuart
PARAMETER STDOUT = myuart
END

```

```
BEGIN PROCESSOR
PARAMETER HW_INSTANCE = mymicroblaze
PARAMETER DRIVER_NAME = cpu
PARAMETER DRIVER_VER = 1.00.a
END
```

```
BEGIN DRIVER
PARAMETER HW_INSTANCE = myuart
PARAMETER DRIVER_NAME = uartlite
PARAMETER DRIVER_VER = 1.00.b
END
```

```
BEGIN DRIVER
PARAMETER HW_INSTANCE = intc
PARAMETER DRIVER_NAME = intc
PARAMETER DRIVER_VER = 1.00.c
END
```

```
# Assign a null driver for hardware that doesn't need one,
# mostly to disable warnings
```

```
BEGIN DRIVER
PARAMETER HW_INSTANCE = vga
PARAMETER DRIVER_NAME = generic
PARAMETER DRIVER_VER = 1.00.a
END
```

```
BEGIN DRIVER
PARAMETER HW_INSTANCE = lmb_data_controller
PARAMETER DRIVER_NAME = generic
PARAMETER DRIVER_VER = 1.00.a
END
```

```
BEGIN DRIVER
PARAMETER HW_INSTANCE = lmb_instruction_controller
PARAMETER DRIVER_NAME = generic
PARAMETER DRIVER_VER = 1.00.a
END
```

### **4.1.3 system.ucf**

```
net FPGA_CLK1 loc="p77";
```

```
net RS232_TD loc="p71";
```

```
net RS232_RD loc="p73";
```

```
net VIDOUT_CLK loc="p23";
net VIDOUT_BLANK_N loc="p24";
net VIDOUT_HSYNC_N loc="p8";
net VIDOUT_VSYNC_N loc="p7";
```

```
net VIDOUT_RED<0> loc="p41";
net VIDOUT_RED<1> loc="p40";
net VIDOUT_RED<2> loc="p36";
net VIDOUT_RED<3> loc="p35";
net VIDOUT_RED<4> loc="p34";
net VIDOUT_RED<5> loc="p33";
net VIDOUT_RED<6> loc="p31";
net VIDOUT_RED<7> loc="p30";
net VIDOUT_RED<8> loc="p29";
net VIDOUT_RED<9> loc="p27";
```

```
net VIDOUT_GREEN<0> loc="p9" ;
net VIDOUT_GREEN<1> loc="p10";
net VIDOUT_GREEN<2> loc="p11";
net VIDOUT_GREEN<3> loc="p15";
net VIDOUT_GREEN<4> loc="p16";
net VIDOUT_GREEN<5> loc="p17";
net VIDOUT_GREEN<6> loc="p18";
net VIDOUT_GREEN<7> loc="p20";
net VIDOUT_GREEN<8> loc="p21";
net VIDOUT_GREEN<9> loc="p22";
```

```
net VIDOUT_BLUE<0> loc="p42";
net VIDOUT_BLUE<1> loc="p43";
net VIDOUT_BLUE<2> loc="p44";
net VIDOUT_BLUE<3> loc="p45";
net VIDOUT_BLUE<4> loc="p46";
net VIDOUT_BLUE<5> loc="p47";
net VIDOUT_BLUE<6> loc="p48";
net VIDOUT_BLUE<7> loc="p49";
net VIDOUT_BLUE<8> loc="p55";
net VIDOUT_BLUE<9> loc="p56";
```

# Ethernet

```
net ETHERNET_CS_N loc="p82";
net ETHERNET_RDY loc="p81";
net ETHERNET_IREQ loc="p75";
net ETHERNET_IOCS16_N loc="p74";
```

```
# OPB_ETHERNET
net PB_OE_N loc="p125";
net PB_WE_N loc="p123";
net PB_UB_N loc="p146";
net PB_LB_N loc="p140";

net RAM_CE_N loc="p147";
```

```
# OPB_Data
net PB_D<0> loc="p153";
net PB_D<1> loc="p145";
net PB_D<2> loc="p141";
net PB_D<3> loc="p135";
net PB_D<4> loc="p126";
net PB_D<5> loc="p120";
net PB_D<6> loc="p116";
net PB_D<7> loc="p108";
net PB_D<8> loc="p127";
net PB_D<9> loc="p129";
net PB_D<10> loc="p132";
net PB_D<11> loc="p133";
net PB_D<12> loc="p134";
net PB_D<13> loc="p136";
net PB_D<14> loc="p138";
net PB_D<15> loc="p139";
```

```
#OPB_Address
net PB_A<0> loc="p83";
net PB_A<1> loc="p84";
net PB_A<2> loc="p86";
net PB_A<3> loc="p87";
net PB_A<4> loc="p88";
net PB_A<5> loc="p89";
net PB_A<6> loc="p93";
net PB_A<7> loc="p94";
net PB_A<8> loc="p100";
net PB_A<9> loc="p101";
net PB_A<10> loc="p102";
net PB_A<11> loc="p109";
net PB_A<12> loc="p110";
net PB_A<13> loc="p111";
net PB_A<14> loc="p112";
net PB_A<15> loc="p113";
net PB_A<16> loc="p114";
net PB_A<17> loc="p115";
net PB_A<17> loc="p115";
```

```
net PB_A<18> loc="p121";
net PB_A<19> loc="p122";
```

#### # Audio Codec

```
net AU_CSN loc="p165";
net AU_MCLK loc="p167";
net AU_LRCK loc="p168";
net AU_BCLK loc="p166";
net AU_SDTI loc="p169";
net AU_SDTO0 loc="p173";
```

#### #SDRAM

```
net SDRAM_CKE loc = "p99";
net SDRAM_CAS_N loc = "p96";
net SDRAM_RAS_N loc = "p97";
net SDRAM_CE_N loc = "p98";
net SDRAM_WE_N loc = "p95";
net SDRAM_CLK loc = "p80";
```

#### #Flash

```
net FLASH_CE_N loc = "p57";
```

```
NET "SDRAM_CLK" TNM_NET = "SDRAM_CLK";
TIMESPEC "TS_SDRAM_CLK" = PERIOD "SDRAM_CLK" 10 ns HIGH 50 %;
```

```
NET "PB_A<10>" DRIVE = 24;
NET "PB_A<0>" DRIVE = 24;
NET "PB_A<1>" DRIVE = 24;
NET "PB_A<2>" DRIVE = 24;
NET "PB_A<3>" DRIVE = 24;
NET "PB_A<4>" DRIVE = 24;
NET "PB_A<5>" DRIVE = 24;
NET "PB_A<6>" DRIVE = 24;
NET "PB_A<7>" DRIVE = 24;
NET "PB_A<8>" DRIVE = 24;
NET "PB_A<9>" DRIVE = 24;
NET "PB_A<11>" DRIVE = 24;
NET "PB_A<12>" DRIVE = 24;
NET "PB_A<13>" DRIVE = 24;
NET "PB_A<14>" DRIVE = 24;
NET "PB_D<0>" DRIVE = 24;
NET "PB_D<1>" DRIVE = 24;
NET "PB_D<2>" DRIVE = 24;
NET "PB_D<3>" DRIVE = 24;
NET "PB_D<4>" DRIVE = 24;
NET "PB_D<5>" DRIVE = 24;
```

```
NET "PB_D<6>" DRIVE = 24;
NET "PB_D<7>" DRIVE = 24;
NET "PB_D<8>" DRIVE = 24;
NET "PB_D<9>" DRIVE = 24;
NET "PB_D<10>" DRIVE = 24;
NET "PB_D<11>" DRIVE = 24;
NET "PB_D<12>" DRIVE = 24;
NET "PB_D<13>" DRIVE = 24;
NET "PB_D<14>" DRIVE = 24;
NET "PB_D<15>" DRIVE = 24;
NET "PB_UB_N" DRIVE = 24;
NET "PB_LB_N" DRIVE = 24;
NET "SDRAM_CAS_N" DRIVE = 24;
NET "SDRAM_CE_N" DRIVE = 24;
NET "SDRAM_CKE" DRIVE = 24;
NET "SDRAM_RAS_N" DRIVE = 24;
NET "SDRAM_WE_N" DRIVE = 24;
NET "PB_A<0>" FAST;
NET "PB_A<1>" FAST;
NET "PB_A<2>" FAST;
NET "PB_A<3>" FAST;
NET "PB_A<4>" FAST;
NET "PB_A<5>" FAST;
NET "PB_A<6>" FAST;
NET "PB_A<7>" FAST;
NET "PB_A<8>" FAST;
NET "PB_A<9>" FAST;
NET "PB_A<10>" FAST;
NET "PB_A<11>" FAST;
NET "PB_A<12>" FAST;
NET "PB_A<13>" FAST;
NET "PB_A<14>" FAST;
NET "PB_D<0>" FAST;
NET "PB_D<1>" FAST;
NET "PB_D<2>" FAST;
NET "PB_D<3>" FAST;
NET "PB_D<4>" FAST;
NET "PB_D<5>" FAST;
NET "PB_D<6>" FAST;
NET "PB_D<7>" FAST;
NET "PB_D<8>" FAST;
NET "PB_D<9>" FAST;
NET "PB_D<10>" FAST;
NET "PB_D<11>" FAST;
NET "PB_D<12>" FAST;
NET "PB_D<13>" FAST;
```

```
NET "PB_D<14>" FAST;
NET "PB_D<15>" FAST;
NET "PB_UB_N" FAST;
NET "PB_LB_N" FAST;
NET "SDRAM_CAS_N" FAST;
NET "SDRAM_CE_N" FAST;
NET "SDRAM_CKE" FAST;
NET "SDRAM_RAS_N" FAST;
NET "SDRAM_WE_N" FAST;
```

#### 4.1.4 Makefile

```
#-----#
# CSEE 4840 Embedded System Design #
# #
# Internet Radio #
# #
# Team Members: Qiutao Yu #
# Yingjian Gu #
# Chun-Chuen Li #
# Imran Quyyum #
#-----#
```

```
SYSTEM = system
```

```
MICROBLAZE_OBJS = \
    c_source_files/audio.o \
    c_source_files/flash.o \
    c_source_files/main.o \
    c_source_files/menu.o \
    c_source_files/initialization.o \
    c_source_files/int.o \
    c_source_files/ether.o
```

```
LIBRARIES = mymicroblaze/lib/libxil.a
```

```
ELF_FILE = $(SYSTEM).elf
```

```
NETLIST = implementation/$(SYSTEM).ngc
```

```
# Bitstreams for the FPGA
```

```
FPGA_BITFILE = implementation/$(SYSTEM).bit
MERGED_BITFILE = implementation/download.bit
```

```

# Files to be downloaded to the SRAM

SRAM_BINFILE = implementation/sram.bin
SRAM_HEXFILE = implementation/sram.hex

MHSFILE = $(SYSTEM).mhs
MSSFILE = $(SYSTEM).mss

FPGA_ARCH = spartan2e
DEVICE = xc2s300epq208-6

LANGUAGE = vhdl
PLATGEN_OPTIONS = -p $(FPGA_ARCH) -lang $(LANGUAGE)
LIBGEN_OPTIONS = -p $(FPGA_ARCH) $(MICROBLAZE_LIBG_OPT)

# Paths for programs

XILINX = /usr/cad/xilinx/ise7.1i
ISEBINDIR = $(XILINX)/bin/lin
ISEENVCMDSDIR = LD_LIBRARY_PATH=$(ISEBINDIR) XILINX=$(XILINX)
PATH=$(ISEBINDIR)

XILINX_EDK = /usr/cad/xilinx/edk7.1i

MICROBLAZE = /usr/cad/xilinx/edk7.1i/gnu/microblaze/lin
MBBINDIR = $(MICROBLAZE)/bin
XESSBINDIR = /usr/cad/xess/bin

# Executables

XST = $(ISEENVCMDSDIR) $(ISEBINDIR)/xst
XFLOW = $(ISEENVCMDSDIR) $(ISEBINDIR)/xflow
BITGEN = $(ISEENVCMDSDIR) $(ISEBINDIR)/bitgen
DATA2MEM = $(ISEENVCMDSDIR) $(ISEBINDIR)/data2mem
XSLOAD = $(XESSBINDIR)/xsload
XESS_BOARD = XSB-300E

MICROBLAZE_CC = $(MBBINDIR)/mb-gcc
MICROBLAZE_LD = $(MBBINDIR)/mb-ld
MICROBLAZE_CC_SIZE = $(MBBINDIR)/mb-size
MICROBLAZE_OBJCOPY = $(MBBINDIR)/mb-objcopy

# External Targets

all :
    @echo "Makefile to build a Microprocessor system :"

```



```

    @echo "Run make with any of the following targets"
    @echo " make libs   : Configures the sw libraries for this system"
    @echo " make program : Compiles the program sources for all the processor
instances"
    @echo " make netlist : Generates the netlist for this system ($(SYSTEM))"
    @echo " make bits   : Runs Implementation tools to generate the bitstream"
    @echo " make init_bram: Initializes bitstream with BRAM data"
    @echo " make download : Downloads the bitstream onto the board"
    @echo " make netlistclean: Deletes netlist"
    @echo " make hwclean  : Deletes implementation dir"
    @echo " make libsclean: Deletes sw libraries"
    @echo " make programclean: Deletes compiled ELF files"
    @echo " make clean   : Deletes all generated files/directories"
    @echo " "
    @echo " make <target> : (Default)"
    @echo "      Creates a Microprocessor system using default initializations"
    @echo "      specified for each processor in MSS file"

```

```
#bits : $(FPGA_BITFILE)
```

```
netlist : $(NETLIST)
```

```
libs : $(LIBRARIES)
```

```
program : $(ELF_FILE)
```

```
init_bram : $(MERGED_BITFILE)
```

```
clean : hwclean libsclean programclean
        rm -f bram_init.sh
        rm -f _impact.cmd
```

```
hwclean : netlistclean
        rm -rf implementation synthesis xst hdl
        rm -rf xst.srp $(SYSTEM).srp
```

```
netlistclean :
        rm -f $(FPGA_BITFILE) $(MERGED_BITFILE) \
            $(NETLIST) implementation/$(SYSTEM)_bd.bmm
```

```
libsclean :
        rm -rf mymicroblaze/lib
```

```
programclean :
        rm -f $(ELF_FILE) $(SRAM_BITFILE) $(SRAM_HEXFILE)
```

```

#
# Software rules
#

MICROBLAZE_MODE = executable

# Assemble software libraries from the .mss and .mhs files

$(LIBRARIES) : $(MHSFILE) $(MSSFILE)
#   PATH=$$PATH:$(MGBINDIR) XILINX=$(XILINX)
XILINX_EDK=$(XILINX_EDK) \
#   perl -I $(XILINX_EDK)/bin/nt/perl5lib $(XILINX_EDK)/bin/nt/libgen.pl \
#   $(LIBGEN_OPTIONS) $(MSSFILE)
    @echo "Fetal ERROR! Library should be generated by the XPS GUI."

# Compilation

MICROBLAZE_CC_CFLAGS =
MICROBLAZE_CC_OPT = -O3 #-mxl-gp-opt
MICROBLAZE_CC_DEBUG_FLAG =# -gstabs
MICROBLAZE_INCLUDES = -I./mymicroblaze/include/ # -I
MICROBLAZE_CFLAGS = \
    $(MICROBLAZE_CC_CFLAGS)\
    -mxl-barrel-shift \
    $(MICROBLAZE_CC_OPT) \
    $(MICROBLAZE_CC_DEBUG_FLAG) \
    $(MICROBLAZE_INCLUDES)

$(MICROBLAZE_OBJS) : %.o : %.c
    PATH=$(MGBINDIR) $(MICROBLAZE_CC) $(MICROBLAZE_CFLAGS) -c
$< -o $@

# Linking

# Uncomment the following to make linker print locations for everything
# MICROBLAZE_LD_FLAGS = -Wl,-M
MICROBLAZE_LINKER_SCRIPT = -Wl,-T -Wl,linkscript
MICROBLAZE_LIBPATH = -L./mymicroblaze/lib/
MICROBLAZE_CC_START_ADDR_FLAG= -Wl,-defsym -
Wl,_TEXT_START_ADDR=0x00000000
MICROBLAZE_CC_STACK_SIZE_FLAG= -Wl,-defsym -Wl,_STACK_SIZE=0x200
MICROBLAZE_LFLAGS = \
    -xl-mode-$(MICROBLAZE_MODE) \
    $(MICROBLAZE_LD_FLAGS) \
    $(MICROBLAZE_LINKER_SCRIPT) \

```

```

$(MICROBLAZE_LIBPATH) \
$(MICROBLAZE_CC_START_ADDR_FLAG) \
$(MICROBLAZE_CC_STACK_SIZE_FLAG)
#MICROBLAZE_LDFLAGS = -T linker -lc -lm -L./mymicroblaze/lib/ -lxil -defsym
_TEXT_START_ADDR=0x00000000 -defsym _STACK_SIZE=0x200
MICROBLAZE_LDFLAGS1 = -T linker -lc -lm
MICROBLAZE_LDFLAGS2 = -L./mymicroblaze/lib/ -lxil -defsym
_TEXT_START_ADDR=0x00000000 -defsym _STACK_SIZE=0x200

#$(ELF_FILE) : $(LIBRARIES) $(MICROBLAZE_OBJS)
$(ELF_FILE) : $(MICROBLAZE_OBJS)
    PATH=$(MGBINDIR) $(MICROBLAZE_LD) $(MICROBLAZE_LDFLAGS1)
$(MICROBLAZE_OBJS) -o $(ELF_FILE) $(MICROBLAZE_LDFLAGS2)
    $(MICROBLAZE_CC_SIZE) $(ELF_FILE)
    rm -f c_source_files/*.o

#
# Hardware rules
#

# Hardware compilation : optimize the netlist, place and route

#$(FPGA_BITFILE) : $(NETLIST) \
#     etc/fast_runtime.opt etc/bitgen.ut data/$(SYSTEM).ucf
#     cp -f etc/bitgen.ut implementation/
#     cp -f etc/fast_runtime.opt implementation/
#     cp -f data/$(SYSTEM).ucf implementation/$(SYSTEM).ucf
#     $(XFLOW) -wd implementation -p $(DEVICE) -implement fast_runtime.opt \
#     $(SYSTEM).ngc
#     cd implementation; $(BITGEN) -f bitgen.ut $(SYSTEM)

# Hardware assembly: Create the netlist from the .mhs file

#$(NETLIST) : $(MHSFILE)
#     XILINX=$(XILINX) XILINX_EDK=$(XILINX_EDK) \
#     perl -I $(XILINX_EDK)/bin/nt/perl5lib $(XILINX_EDK)/bin/nt/platgen.pl \
#     $(PLATGEN_OPTIONS) -st xst $(MHSFILE)
#     perl synth_modules.pl < synthesis/xst.scr > xst.scr
#     $(XST) -ifn xst.scr
#     rm -r xst xst.scr
#     $(XST) -ifn synthesis/$(SYSTEM).scr

#
# Downloading
#

# Add software code to the FPGA bitfile

```

```

#$(MERGED_BITFILE) : $(FPGA_BITFILE) $(ELF_FILE)
$(MERGED_BITFILE) : $(ELF_FILE)
    bitinit system.mhs -pe mymicroblaze system.elf \
    -bt implementation/system.bit -o implementation/download.bit

# Create a .hex file with data for the SRAM

$(SRAM_HEXFILE) : $(ELF_FILE)
    $(MICROBLAZE_OBJCOPY) \
        -j .sram_text -j .sdata2 -j .sdata -j .rodata -j .data \
        -O binary $(ELF_FILE) $(SRAM_BINFILE)
    ./bin2hex -a 20000000 < $(SRAM_BINFILE) > $(SRAM_HEXFILE)

# Download the files to the target board

download : $(MERGED_BITFILE) $(SRAM_HEXFILE)
    $(XSLOAD) -ram -b $(XESS_BOARD) $(SRAM_HEXFILE)
    $(XSLOAD) -fpga -b $(XESS_BOARD) $(MERGED_BITFILE)

```

## 4.2 C Code

### 4.2.1 audio.h

```

#define XPAR_AUDIO_CONTROLLER_BASEADDR 0xFEFF0400
#define XPAR_AUDIO_SAMPLER_BASEADDR 0xFEFF0300
// The subroutine to enable the Audio
unsigned long InitializeAudio (unsigned long command );

```

### 4.2.2 ether.h

```

#include "xio.h"
#include "xbasic_types.h"

#define dprint print

#ifndef BYTE
#define BYTE unsigned char
#endif
#ifndef WORD
#define WORD unsigned short
#endif

// define the size of a packet

#define MAC_HEADER_SIZE 14
#define IP_HEADER_SIZE 20

```

```

#define UDP_HEADER_SIZE 8
#define RTP_HEADER_SIZE 12

#define HEADER_SIZE
(MAC_HEADER_SIZE+IP_HEADER_SIZE+UDP_HEADER_SIZE+RTP_HEADER_
SIZE)

#define IP_LENGTH (PACKET_SIZE-MAC_HEADER_SIZE)
#define UDP_LENGTH (IP_LENGTH-IP_HEADER_SIZE)

#define IP_CHECKSUM_OFFSET 24
#define UDP_CHECKSUM_OFFSET 40
#define RTP_SEQNUM_OFFSET 44
#define RTP_TIMESTAMP_OFFSET 46

#define DATA_CHUNK_SIZE 16
#define DATA_CHUNKS_IN_PACKET 90

#define PAYLOAD_SIZE (DATA_CHUNKS_IN_PACKET*DATA_CHUNK_SIZE)
#define PACKET_SIZE (PAYLOAD_SIZE+HEADER_SIZE)

#define PACKET_BUFFERS 1

// NE2000 definitions
#define NIC_BASE (0x00800400) // Base I/O address of the NIC card
#define DATAPORT (0x10*2)
#define NE_RESET (0x1f*2)

// NIC page0 register offsets
#define CMDR (0x00*2) // command register for read & write
#define PSTART (0x01*2) // page start register for write
#define PSTOP (0x02*2) // page stop register for write
#define BNR (0x03*2) // boundary reg for rd and wr
#define TPSR (0x04*2) // tx start page start reg for wr
#define TBCR0 (0x05*2) // tx byte count 0 reg for wr
#define TBCR1 (0x06*2) // tx byte count 1 reg for wr
#define ISR (0x07*2) // interrupt status reg for rd and wr
#define RSAR0 (0x08*2) // low byte of remote start addr
#define RSAR1 (0x09*2) // hi byte of remote start addr
#define RBCR0 (0x0A*2) // remote byte count reg 0 for wr
#define RBCR1 (0x0B*2) // remote byte count reg 1 for wr
#define RCR (0x0C*2) // rx configuration reg for wr
#define TCR (0x0D*2) // tx configuration reg for wr
#define DCR (0x0E*2) // data configuration reg for wr
#define IMR (0x0F*2) // interrupt mask reg for wr

```

```

// NIC page 1 register offsets
#define PAR0 (0x01*2) // physical addr reg 0 for rd and wr
#define CURR (0x07*2) // current page reg for rd and wr
#define MAR0 (0x08*2) // multicast addr reg 0 for rd and WR

// Buffer Length and Field Definition Info
#define TXSTART 0x41 // Tx buffer start page
#define TXPAGES 8 // Pages for Tx buffer
#define RXSTART (TXSTART+TXPAGES) // Rx buffer start page
#define RXSTOP 0x7e // Rx buffer end page for word mode

#define BASE_ADDR (XPAR_ETHERNET_PERIPHERAL_BASEADDR+0x400)
// macros for reading and writing registers
#define outnic(addr, data) XIo_Out16(NIC_BASE+addr, data)
#define innic(addr) (XIo_In16(NIC_BASE+addr))

#define PACKET_END_ADDRESS PACKET_START_ADDRESS+PACKET_SIZE
#define PACKET_START_ADDRESS (TXSTART << 8)

#define PAYLOAD_START_ADDRESS
PACKET_START_ADDRESS+HEADER_SIZE;
#define UDP_CHECKSUM_ADDRESS
PACKET_START_ADDRESS+UDP_CHECKSUM_OFFSET
#define RTP_SEQNUM_ADDRESS
PACKET_START_ADDRESS+RTP_SEQNUM_OFFSET

/* function prototypes, external interface. */
BYTE init();
BYTE output_sample(WORD *sample);
int diagnostics();
void wait(int mult);

/* symbolic names for various register bits */

#define ISR_PTX 0x02 // packet transmitted with no error
#define ISR_RXE 0x04 // receive error
#define ISR_RDC 0x40 // Remote DMA Successful

#define CR_STOP 0x01
#define CR_START 0x02
#define CR_TXP 0x04
#define CR_READ 0x08

```

```
#define CR_WRITE 0x10
#define CR_ABORT 0x20
#define CR_COMPLETE 0x20
#define CR_PAGE0 0x00
#define CR_PAGE1 0x40
```

### 4.2.3 flash.h

```
#define FLASH_BASE_ADDR 0x30000000
```

```
// Flash program subroutine
void FlashProgram (unsigned long address, unsigned char data);
```

```
// Chip Erase subroutine
void FlashErase (void);
```

### 4.2.4 menu.h

```
#define FLASH_BASE_ADDR 0x30000000
```

```
// Flash program subroutine
void FlashProgram (unsigned long address, unsigned char data);
```

```
// Chip Erase subroutine
void FlashErase (void);
```

### 4.2.5 flash.c

```
#include "xsbmemory.h"
```

```
// The Flash polling routine checks the Flash response
// Returns when the program or erase operation is complete
int FlashPolling(void)
```

```
{
    volatile unsigned char * p;
    volatile unsigned char toggle_bit, save_bit;
    unsigned char data;
    int i;
    int loop, null;

    p = (volatile unsigned char * ) 0x30000000;

    save_bit = *p;
    save_bit = save_bit & 0x40;
    //putnum (save_bit);
```

```

for (;;)
{
    toggle_bit = *p;
    //putnum (toggle_bit);

    toggle_bit = toggle_bit & 0x40;
    //putnum (toggle_bit);
    //print ("\r\n");

    if (save_bit == toggle_bit)
        return ;
    save_bit = toggle_bit;
}

return null;

}

// The Flash write routine generate the writing timing to the Flash
int FlashWrite(unsigned long address, unsigned char data)
{
    volatile unsigned char * p;
    int i;
    int loop, null;

    p = (volatile unsigned char * ) address;
    * p = data;

    null = 0;
    // Delay for some time before the next write
    for ( loop = 1; loop < 5; loop ++)
    {
        null = null + data;
    }

    return null;
}

// The Program routine program 1 byte to the specified address
void FlashProgram (unsigned long address, unsigned char data)
{
    FlashWrite(0x30005555, 0xAA);
    FlashWrite(0x30002AAA, 0x55);
    FlashWrite(0x30005555, 0xA0);
}

```



```

FlashWrite(address, data);

FlashPolling();
}

// Chip Erase 6 cycles
// 5555 AA 2AAA 55 5555 80 5555 AA 2AAA 55 5555 10

void FlashErase (void)
{
FlashWrite(0x30005555, 0xAA);
FlashWrite(0x30002AAA, 0x55);
FlashWrite(0x30005555, 0x80);
FlashWrite(0x30005555, 0xAA);
FlashWrite(0x30002AAA, 0x55);
FlashWrite(0x30005555, 0x10);

FlashPolling();
}

```

#### **4.2.6 audio.c**

```

#include "xbasic_types.h"
#include "xio.h"

#include "xintc_1.h"
#include "xuartlite_1.h"
#include "xparameters.h"

#include "audio.h"

unsigned long InitializeAudio (unsigned long command )
{
unsigned short * p;

volatile unsigned long * preg;
unsigned long status;

preg = (volatile unsigned long * )XPAR_AUDIO_CONTROLLER_BASEADDR;
* preg = command | 0x80000000;

status = 0x80000000;

while (status != 0)
{

```

```

    status = (* preg) & 0x80000000;
}

status = *preg;

return status;
}

```

#### 4.2.7 ether.c

```

/*-----
# CSEE 4840 Embedded System Design
#
# Most of the codes are taken from Internet Radio 2005
#
-----*/

#include "ether.h"

#include "xparameters.h"
#include "xbasic_types.h"
#include "xio.h"
#include "xintc_1.h"

/* function prototypes, internal helpers */
static BYTE send(WORD *data, WORD addr, WORD dmalen);
static BYTE transmit(WORD sendlen);

/* note that at one point we had lots more functions. the code
   indicates where they were. Many of them were flattened for code
   space reasons (the compiler had some inlining issues, possibly due
   to out smashing the stack). */

/* static data */

/* stored without the one's complement */
/* note: ip checksum can actually be constant!! */
/* all the pseudo headers and most of the headers on the udp_checksum
   can be calculated in advance. we just need to ask ethereal what it
   should be :). since time_stamp and sequence number are increments,
   we can just add (with carries) these increments to the new initial
   values each new packet. so all we need is the update stuff in append. */
/* static unsigned long udp_checksum; */

/* the real note: udp checksum can actually be (and now is) 0. This
   means that it is ignored. We originally wrote code to calculate a

```

proper udp checksum (it is still in the code, just commented out).  
we later commented it out and decided to use 0 due to code space  
limitations. (this also allowed us to put back in diagnostics).

note to future people: smashing your stack is a bad idea.

```
*/
static WORD cur_payload_addr;

struct {
    WORD padding;
    WORD sequence_number;
    unsigned long time_stamp;
} dynamic_data;

/* #define UDP_INIT_CHECKSUM (~((WORD)(0xaa78))); */
/* #define UDP_INIT_CHECKSUM (~((WORD)(0xb15d))); */

static BYTE header[HEADER_SIZE] = {
    /* create the static portion of the packets */
    /* MAC header (14 bytes) */
    /* Destination MAC address (6 bytes): fixed */
    /* 0-5 * 0x00,0x0C, 0xF1, 0x73, 0x4C, 0x9C,
    */
    /* Laptop MAC */
    0x00,0x01,0x6C,0xC9,0xD7,0x2B,
    /* Source MAC address (6 bytes): fixed */
    /* 6 */ 0x00,
    /* 7 */ 0x0D,
    /* 8 */ 0x60,
    /* 9 */ 0x7F,
    /* 10 */ 0xF9,
    /* 11 */ 0xAF,
    /* Length (2 bytes): fixed */
    /* used as a type */
    /* 12 */ 0x08,
    /* 13 */ 0x00,
    /* IP header (20 bytes) */
    /* Version (4 bits): fixed */
    /* IHL (4 bits): fixed */
    /* 14 */ 0x45,
    /* TOS (1 byte): fixed */
    /* 15 */ 0x00,
    /* Total Length (2 bytes): fixed */
    /* 16 */ IP_LENGTH >> 8,
    /* 17 */ IP_LENGTH & (0xff),
    /* Identification (2 bytes): fixed */
```

```

/* 18 */ 0x00,
/* 19 */ 0x00,
/*  Flags (3 bits): fixed */
/*  Fragment Offset (13 bits): fixed */
/* 20 */ 0x00,
/* 21 */ 0x00,
/*  TTL (1 byte): fixed */
/* for now, this should die on contact*/
/* 22 */ 0x04,
/*  Protocol (1 byte): fixed */
/*  UDP=17 */
/* 23 */ 0x11,
/*  Header Checksum (2 bytes): updated. see update_ip_checksum */
// Micro4
    0x8A,0x63,
/*  Source IP (4 bytes): fixed */
/* 26 */ 0x80,
/* 27 */ 0x3B,
/* 28 */ 0x95,
/* 29 */ 0xA2,
/*  Destination IP (4 bytes): fixed */
// Micro4
    128,59,144,169,
///* 30 */ 128,
///* 31 */ 59,
///* 32 */ 144,
///* 33 */ 168,
/*  UDP header (6 Bytes) */
/*  Source Port (2 bytes): fixed */
/* 34 */ 0x0B,
/* 35 */ 0xE2,
/*  Destination Port (2 bytes): fixed */
/*  in decimal: 3042 */
/* 36 */ 0x0B,
/* 37 */ 0xE2,
/*  Length (2 bytes): fixed */
/* 38 */ UDP_LENGTH>>8,
/* 39 */ UDP_LENGTH & 0xff,
/*  Checksum (2 bytes): updated */
/* 40 */ 0,
/* 41 */ 0,
/*  RTP header (12 bytes) */
/*  Version (2 bits): fixed */
/* 10 */
/*  Padding (1 bit): fixed */
/* 0 */

```

```

/* Extension (1 bit): fixed */
/* 0 */
/* CSRC count (4 bits): fixed */
/* 0 */
/* 42 */ 0x80,
/* Marker bit (1 bit): fixed */
/* 0 */
/* Payload type (7 bits): fixed */
/* L16=10 (2 channel( (see
   http://www.networksorcery.com/enp/protocol/rtp.htm) */
/* 43 */ 0x0a,
/* Sequence number (16 bits): updated */
/* 44 */ 0x00,
/* 45 */ 0x00,
/* Time stamp (32 bits): updated */
/* 46 */ 0x00,
/* 47 */ 0x00,
/* 48 */ 0x00,
/* 49 */ 0x00,
/* SSRC (32 bits): fixed */
/* should be a random value: I don't think this is what is meant :)
   -- since we don't change our source transport address and don't
   handle multiple synchronization source within the same RTP
   channel, this should not be a problem. */
/* 50 */ 0x42,
/* 51 */ 0x42,
/* 52 */ 0x42,
/* 53 */ 0x42
/* CSRC list (0 bits): fixed */
/* we are evil and don't give proper attribution to sources. */
};

```

```

/* a simple wait function that burns clock cycles. */
void wait(int mult){
    volatile int j=0, i=1000000;
    for(; i > 0; --i) {
        for(; mult > 0; --mult) {
            // a smart compiler with aggresive inliner should unroll this
            ++j;
        }
    }
}

```

```

/*
INITIALIZATION

```

```

*/

/* Diagnostics based on page 31 of the Ethernet Controller manual
   Write on two pages first and then read to avoid being fooled by
   data latched in both write and read.
*/

int diagnostics() {
    // outnic(CMDR, 0x21);          // stop AX88796
    wait(10);

    outnic(CMDR,0x61);
    outnic(PSTART, 0x4E);

    outnic(CMDR,0x21);
    outnic(PSTOP, 0x3E);

    outnic(CMDR,0x61);
    if(innic(PSTART) != 0x4e)
        return 1;

    outnic(CMDR,0x21);          // switch to page 0
    if(innic(PSTOP) != 0x3e)
        return 2;

    if(innic(0x16*2) != 0x15)
        return 3;

    if(innic(0x12*2) != 0x0c)
        return 4;

    if(innic(0x13*2) != 0x12)
        return 5;

    return 0;
}

/* initializes the ethernet card and our data structures. sets up the
   static part of the packet header in memory. */
BYTE init() {
    int ret;

    outnic(NE_RESET, innic(NE_RESET)); // trigger a reset
    wait(2);
    if ((innic(ISR) & 0x80) == 0)    // Report if failed
        {

```

```

//print(" Ethernet card failed to reset!\r\n");
//print("Ethernet NIC not present or not initializing correctly\r\n");
return 1;
}
else
{
//dprint("Ethernet card reset successful!\r\n");
/* ether_reset(); */ /* Reset Ethernet card, */

/* Write 21h to Command Register to abort current DMA operations. */
outnic(CMDR, 0x21);
/* Wait 2 milliseconds (timeout for inter-frame gap timer) */
wait(10);
/* Write 01h to Data Control Register to enable 16-bit word transfers. */
outnic(DCR, 0x01);
/* Write 00h to both Remote Byte Count Registers to zero out DMA counter. */
outnic(RBCR0, 0x00);
outnic(RBCR1, 0x00);
/* Write 00h to Interrupt Mask Register to mask interrupts. */
outnic(IMR, 0x00);
/* Write ffh to Interrupt Status Register to clear interrupt flags */
outnic(ISR, 0xff);
/* Write 20h to Receive Configuration Register to put NIC in monitor mode */
outnic(RCR, 0x20);
/* Write 02h to Transmit Configuration Register to put NIC in loop-back mode */
outnic(TCR, 0x02);
/* Set RX Start and Stop, Boundary, and TX start page. */
outnic(PSTART, RXSTART);
outnic(PSTOP, RXSTOP);
outnic(BNRY, (BYTE)(RXSTOP-1));
outnic(TPSR, TXSTART);
/* Reset interrupt mask and flags. */
outnic(ISR, 0xFF); // clear interrupt status register
outnic(IMR, 0x00); // Mask completion irq
/* Write 22h to Command Register to start NIC */
outnic(CMDR, 0x22);
/* Write 00h to Transmit Configuration Register to set normal transmit operation */
outnic(TCR, 0x00);

//dprint("Ethernet card intialization complete!\r\n");
}

/* init_packet_setup(); */
dynamic_data.sequence_number = 0;
dynamic_data.time_stamp = 0;

```

```

/* udp_checksum = UDP_INIT_CHECKSUM; */
cur_payload_addr = PAYLOAD_START_ADDRESS;

/* now lets initialize the buffers. */
return send((WORD *)header, PACKET_START_ADDRESS, 54);//HEADER_SIZE);
}

/* actually transmits a (filled in) packet. */
static BYTE transmit(WORD sendlen)
{
    int j;
    outnic(TPSR, TXSTART); // set Transmit Page Start Register
    outnic(TBCR0, (sendlen&0xff)); // set Transmit Byte Count
    outnic(TBCR1, (sendlen>>8));

    outnic(CMDR, CR_COMPLETE|CR_TXP); // start transmission
    j=1000;
    while(j-->0 && !(innic(ISR) & ISR_PTX));
    if(!j){
        return 1;
    }

    outnic(ISR,0xFF);
    return 0;
}

/* low level function that does dma to send data to card. */
/* based on code from Josh's group. */
static BYTE send(WORD *data, WORD addr, WORD dmalen){
    int i, j, h;
    WORD counter;
    WORD word;

    counter = dmalen>>1;

    outnic(RSAR0, (addr&0xff)); // set DMA starting address
    outnic(RSAR1, (addr>>8));

    outnic(ISR, 0xFF); // clear ISR

    outnic(RBCR0, (dmalen&0xff)); // set Remote DMA Byte Count
    outnic(RBCR1, (dmalen>>8));
}

```



```

outnic(CMDR, CR_WRITE|CR_START); // start the DMA write - 0x12

// change order of MS/LS since DMA
// writes LS byte in 15-8, and MS byte in 7-0
for(i=0; i<counter; i++){
    word = (data[i]<<8)|(data[i]>>8);
    outnic(DATAPORT, word);
}

if(!(innic(ISR) & ISR_RDC)){
    // print("Data - DMA did not finish\r\n");
    return 1;
}

outnic(CMDR,CR_COMPLETE);

return 0;
}

/* external interface */
/* takes a 2 word sample, and sends it out. sends packet if needed */
/* 0 return is success */
BYTE output_sample(WORD *sample) {
    BYTE ret = 0;
    /* WORD check; */

    /* ret = append(sample); */
    ret = send(sample, cur_payload_addr, 4);

    /* if(ret)
        return ret; */
    cur_payload_addr+=4;
    /* update checksums */

    /* udp_checksum += *(sample+1); */
    /* udp_checksum += *(sample); */
    /* while (udp_checksum>>16) */
    /* udp_checksum = (udp_checksum & 0xffff) + (udp_checksum >> 16); */

    if(cur_payload_addr >= PACKET_END_ADDRESS) {
        /* finalize_packet() */
        /* take the ones complement, as well as shoving it into a word */
        /* while (udp_checksum>>16) */
        /* udp_checksum = (udp_checksum & 0xffff) + (udp_checksum >> 16); */

        /* check = ~((WORD)(udp_checksum&0xffff)); */

```

```

/*  check = 0; */
/*  ret = send(&check, UDP_CHECKSUM_ADDRESS, 2); */
/*  if(ret) { */
/*      print("Error writing udp checksum\r\n"); */
/*      return ret; */
/*  } */
ret = send(((WORD *)&dynamic_data)+1, RTP_SEQNUM_ADDRESS, 6);

if(ret) {
    //print("Error writing rtp header data\r\n");
}

if(ret) {
    //print("Error finalizing packet. dropping.\r\n");
} else {
    ret = transmit(PACKET_SIZE);
    // print("probable success transmitting packet. happy! happy!\r\n");
}

/*  next_packet_setup(); */
++dynamic_data.sequence_number;
dynamic_data.time_stamp += 20;

/*  udp_checksum = dynamic_data.sequence_number + (unsigned
short)((dynamic_data.time_stamp) >> 16) + (unsigned
short)((dynamic_data.time_stamp)&0xffff); */
/*  udp_checksum += UDP_INIT_CHECKSUM; */
/*  while (udp_checksum>>16) */
/*  udp_checksum = (udp_checksum & 0xffff) + (udp_checksum >> 16); */
cur_payload_addr=PAYLOAD_START_ADDRESS;
}

return ret;
}

```

#### 4.2.8 initialization.c

```

#include "xbasic_types.h"
#include "xio.h"

#include "xintc_1.h"
#include "xuartlite_1.h"
#include "xparameters.h"

#include "flash.h"
#include "sdram.h"
#include "audio.h"

```

```

#include "menu.h"

void main_init()
{
    int ret;
    ////////////////////////////////////////////////////////////////////
    // The Initialization and Self test
    ////////////////////////////////////////////////////////////////////

    //print("\r\n");
    //print(" Running Ethernet diagnostics\r\n");

    if (ret=diagnostics()) {
        //print(" Diagnostics failed. internal error number ");

        //print("\r\n");

    } else {
        //print(" Diagnostics successful.\r\n");
    }

    if(init()) {
        //print(" Ethernet NIC not present or not initializing correctly\r\n");
        //return 1;
    }

    //print(" Ethernet initialization done!\r\n");

    //print ( " Initialize Audio now.....\r\n");
    //print ( " Attention: Audio initialization NOT done yet.\r\n");

    //print ( "\r\n");

    ////////////////////////////////////////////////////////////////////
    // To be done
    // Example of Audio initialize subroutine calling
    //InitializeAudio(0x8000E008); // Select LineIN
    ////////////////////////////////////////////////////////////////////

    //print ( "\r\n");
    //print("Reading audio register 0");
    //print ( "\r\n");
    //print("The data is: ");
    //putnum(InitializeAudio(0x8000C000));

```

```

//print ( "\r\n");

//print("\r\n\r\n Entering main loop now...\r\n");
}

```

#### 4.2.9 int.c

```

#include "xparameters.h"
#include "xbasic_types.h"
#include "xio.h"
#include "xintc_1.h"
#include "xuartlite_1.h"

extern volatile short uart_interrupt_count;
extern char uart_character;
extern volatile unsigned short new_data;

void audio_sampler_handler(void *callback)
{
    // microblaze_disable_interrupts();
    new_data=1;
    //microblaze_enable_interrupts();
}

/*
 * Interrupt service routine for the UART
 */
void uart_handler(void *callback)
{
    Xuint32 IsrStatus;

    Xuint8 incoming_character;

    /* Check the ISR status register so we can identify the interrupt source */
    IsrStatus = XIo_In32(XPAR_MYUART_BASEADDR +
XUL_STATUS_REG_OFFSET);

    if ((IsrStatus & (XUL_SR_RX_FIFO_FULL |
XUL_SR_RX_FIFO_VALID_DATA)) != 0) {
        /* The input FIFO contains data: read it */
        incoming_character =
            (Xuint8) XIo_In32( XPAR_MYUART_BASEADDR + XUL_RX_FIFO_OFFSET );

        uart_character = incoming_character;
        uart_interrupt_count=1;
    }
}

```

```

if ((IsrStatus & XUL_SR_TX_FIFO_EMPTY) != 0) {
    /* The output FIFO is empty: we can send another character */
}
}

```

#### 4.2.10 menu.c

```

#include "xbasic_types.h"
#include "xio.h"
#include "xintc_1.h"
#include "xuartlite_1.h"
#include "xparameters.h"
#include "flash.h"
#include "menu.h"

void FlashOut();
void FlashRecord();
volatile int j=1;
volatile int k=5;
volatile int flag=0;
extern volatile int out_enable;

// Write a text string on the display
void put_string(char *string, int row, int column)
{
    char *p = &(CHAR(row, column));
    while (*p++ = *string++)
        ;
}

void putMenu()
{
    char space_array[26]="          ";
    volatile unsigned char *p;
    for ( p = &(CHAR(0,0)) ; p < &(CHAR(29,80)) ; ++p)           //clear VGA screen
        *p = ' ';
    put_string("INTERNET RADIO", 3, 30);                          //display menu items
    put_string("1. Live Broadcast          ", 5, 27);
    put_string("2. Advertisement Insertion  ", 7,27 );
    put_string("3. Utility                  ", 9, 27);
    put_string(space_array, 11, 27);
    put_string(space_array, 13, 27);
    put_string(space_array, 15, 27);
    put_string(" ", k, 24);
    put_string(">>>", 5, 24);
    j=1; //j save the menu item number
}

```

```

    k=5; //k save the row position for ">>"
}

void vga_menu(char buf)
{

    char space_array[26]="          ";
    volatile unsigned char *p;

    if (buf==0xd) //Enter key
    {

        switch (j)
        {
        case 1:
            put_string("Enable live broadcast  ", 5, 27);
            put_string("Disable live broadcast  ", 7, 27);
            put_string("Return          ", 9, 27);
            put_string(" ", k, 24);
            k=5;
            put_string(">>", 5, 24);
            j=4;
            break;

        case 2:
            put_string("Start Ad insertion  ", 5, 27);
            put_string("Return          ", 7, 27);
            put_string(space_array, 9, 27);
            put_string(" ", k, 24);
            k=5;
            put_string(">>", 5, 24);
            j=7;
            break;

        case 3:
            put_string("Erase Flash buffer  ", 5, 27);
            put_string("Record Ad to Flash  ", 7, 27);
            put_string("Return          ", 9, 27);
            put_string(" ", k, 24);
            put_string(">>", 5, 24);
            k=5;
            j=9;
            break;

        case 4:
            out_enable=1;

```

```

        break;

    case 5:
        out_enable=0;
        break;

    case 6:
        putMenu();
        break;

    case 7:
        for ( p = &(CHAR(25,20)) ; p < &(CHAR(29,80)) ; ++p) *p = ' ';
        put_string("Playing advertisement now.....", 25, 25);
        FlashOut();
        put_string("Ad insertion completed", 27, 25);
        break;

    case 8:
        putMenu();
        break;

    case 9:
        for ( p = &(CHAR(25,20)) ; p < &(CHAR(29,80)) ; ++p) *p = ' ';
        put_string("Start erasing flash.....", 25, 25);
        FlashErase();
        put_string("Flash is empty now", 27, 25);
        break;

    case 10:
        //record sound
    to flash

        for ( p = &(CHAR(25,20)) ; p < &(CHAR(29,80)) ; ++p) *p = ' ';
        put_string("Erase the entire Flash chip now.....", 25, 20);
        FlashErase();
        put_string("Record now.....", 26, 20);
        FlashRecord();
        put_string("Record to Flash successfully", 27, 20);
        break;

    case 11:
        putMenu();
        break;
    }

}

else if (buf==0x1b || flag==1) //Up or Down arrow key

```

```

    {
        flag=1;
        if(buf==0x41)
            {
                if(j!=1 && j!=4 && j!=7 && j!=9) { j--; put_string(" ", k,
24); k=k-2; put_string(">>", k, 24);}
                flag=0;
            }
        if(buf==0x42)
            {
                if(j!=3 && j!=6 && j!=8 && j!=11) { j++; put_string(" ",
k, 24); k=k+2; put_string(">>", k, 24);}
                flag=0;
            }
    }
}

```

#### 4.2.11 main.c

```

#include "xbasic_types.h"
#include "xio.h"

```

```

#include "xintc_1.h"
#include "xuartlite_1.h"
#include "xparameters.h"

```

```

#include "ether.h"
#include "flash.h"
#include "audio.h"
#include "menu.h"

```

```

void main_init(); //function declaration
void audio_sampler_handler(void *callback);
void uart_handler(void *callback);

```

```

volatile short uart_interrupt_count=0;
char uart_character;
unsigned long uart_out;
volatile unsigned short new_data;
volatile int out_enable=0;

```

```

void FlashRecord() //record audio to flash
{
    int i = 0;
    unsigned long sample_count = 0;

```



```

unsigned long max_count = 128000;
unsigned char byte;

while (sample_count < max_count)
{
    /* new_data is set in the interrupt handler when new data is ready. */
    if(new_data == 1) {

        new_data = 0;

        /* grab the data from the audio controller*/
        uart_out = XIo_In32(XPAR_AUDIO_SAMPLER_BASEADDR);
        /* the standard audio format is little endian, so we swap the bytes:
        we have 4 bytes, they get reordered from 1234 to 2143. */
        uart_out = ((uart_out >> 24 & 0xff) << 16) |
        ((uart_out >> 16 & 0xff) << 24) |
        (uart_out >> 8 & 0xff) |
        ((uart_out & 0xff) << 8);

        sample_count++;
        // Take 10 sample data from Audio, and save in SRAM
        // Save lower 16 bit
        //sram_buffer[2*sample_count] = sampler_out;
        // Save upper 16 bit
        //sram_buffer[2*sample_count+1] = sampler_out>>16;

        // write the 0th 8 bit
        //byte = flash_buffer[i*4+1];
        //word = word << 8 | byte;
        byte = uart_out & 0xff;
        FlashProgram(FLASH_BASE_ADDR+(sample_count<<2)+1, byte);

        // write the 1th 8 bit
        //byte = flash_buffer[i*4];
        //word = word << 8 | byte;
        byte = uart_out>>8;
        FlashProgram(FLASH_BASE_ADDR+(sample_count<<2), byte);

        // write the 2th 8 bit
        //byte = flash_buffer[i*4+3];
        //word = word << 8 | byte;
        byte = uart_out>>16;
        FlashProgram(FLASH_BASE_ADDR+(sample_count<<2)+3, byte);
    }
}

```

```

        // write the 3th 8 bit
        //byte = flash_buffer[i*4+2];
        //word = byte;
        byte = uart_out>>24;
        FlashProgram(FLASH_BASE_ADDR+(sample_count<<2)+2, byte);
    }
}
}

void FlashOut() //playing audio saved in flash before
{
    int i;
    unsigned long max_count = 128000;
    volatile unsigned char *flash_buffer;
    unsigned char byte;
    unsigned long word;

    flash_buffer = (volatile unsigned char *) FLASH_BASE_ADDR;

    for (i = 0; i < max_count ; )
    {
        ///////////////////////////////////////////////////////////////////
        // 32bit: 3/2/1/0
        ///////////////////////////////////////////////////////////////////
        // read the 3th(highest) 8 bit

        if(new_data == 1) {
            i ++;
            new_data = 0;
            byte = flash_buffer[(i<<2)+2];
            word = byte;

            // read the 2th 8 bit
            byte = flash_buffer[(i<<2)+3];
            word = word << 8 | byte;

            // read the 1th 8 bit
            byte = flash_buffer[i<<2];
            word = word << 8 | byte;

            // read the 0th 8 bit
            byte = flash_buffer[(i<<2)+1];
            word = word << 8 | byte;
            output_sample((WORD *)(&word));
        }
    }
}

```

```

}

int main()
{
    uart_interrupt_count = 0;
    new_data = 0;

    ////////////////////////////////////////////////////////////////////
    // Setup Interrupt
    ////////////////////////////////////////////////////////////////////
    /* Enable UART and Audio interrupts and register the ISR */
    XIntc_RegisterHandler( XPAR_INTC_BASEADDR,
    XPAR_INTC_MYUART_INTERRUPT_INTR,
                        (XInterruptHandler)uart_handler, (void *)0);
    XIntc_RegisterHandler(XPAR_INTC_SINGLE_BASEADDR,
    XPAR_INTC_AUDIO_SAMPLER_INTERRUPT_INTR,
                        audio_sampler_handler, (void*)0);

    XIntc_mEnableIntr( XPAR_INTC_BASEADDR,
    XPAR_MYUART_INTERRUPT_MASK |
    XPAR_AUDIO_SAMPLER_INTERRUPT_MASK);
    //XIntc_mEnableIntr(XPAR_INTC_SINGLE_BASEADDR,
    XPAR_AUDIO_SAMPLER_INTERRUPT_MASK);

    XIntc_mMasterEnable( XPAR_INTC_BASEADDR );
    XIntc_Out32(XPAR_INTC_BASEADDR + XIN_MER_OFFSET,
    XIN_INT_MASTER_ENABLE_MASK);
    microblaze_enable_interrupts();
    XUartLite_mEnableIntr(XPAR_MYUART_BASEADDR);

    main_init(); //initialization
    putMenu(); //display menu on VGA

    while (1)
    {
        if ( uart_interrupt_count != 0) {

            vga_menu(uart_character); //call the vga_menu if there is input from
uart
            uart_interrupt_count = 0;

        }

        /* new_data is set in the interrupt handler when new data is ready. */

```

```

if(new_data == 1) {

    new_data = 0;

    /* grab the data from the audio controller*/
    uart_out = XIo_In32(XPAR_AUDIO_SAMPLER_BASEADDR);
    /* the standard audio format is little endian, so we swap the bytes:
    we have 4 bytes, they get reordered from 1234 to 2143. */
    uart_out = ((uart_out >> 24 & 0xff) << 16) |
    ((uart_out >> 16 & 0xff) << 24) |
    (uart_out >> 8 & 0xff) |
    ((uart_out & 0xff) << 8);
    if(out_enable==0) uart_out=0x00000000;
    /* output the new sample to the ethernet card */
    output_sample((WORD *)&uart_out);
}
}

return 0;
}

```

## 4.3 VHDL Code

### 4.3.1 opb\_sram.vhd

```

-----
--
-- OPB SRAM controller
--
-----

library ieee;
use ieee.std_logic_1164.all;

entity opb_sram is

    generic (
        C_OPB_AWIDTH : integer           := 32;
        C_OPB_DWIDTH  : integer           := 32;
        C_BASEADDR    : std_logic_vector(0 to 31) := X"20000000";
        C_HIGHADDR    : std_logic_vector(0 to 31) := X"2FFFFFFF");

    port (
        OPB_Clk   : in std_logic;
        OPB_Rst   : in std_logic;
        OPB_ABus  : in std_logic_vector(0 to C_OPB_AWIDTH-1);
        OPB_BE    : in std_logic_vector(0 to C_OPB_DWIDTH/8-1);
        OPB_DBus  : in std_logic_vector(0 to C_OPB_DWIDTH-1);

```

```

OPB_RNW   : in std_logic;
OPB_select : in std_logic;
OPB_seqAddr : in std_logic;    -- Sequential Address
Sln_DBus   : out std_logic_vector(0 to C_OPB_DWIDTH-1);
Sln_errAck : out std_logic;    -- (unused)
Sln_retry  : out std_logic;    -- (unused)
Sln_toutSup : out std_logic;   -- Timeout suppress
Sln_xferAck : out std_logic;   -- Transfer acknowledge

PB_DIN   : in std_logic_vector(0 to 15);   -- SRAM data bus
PB_DOUT  : out std_logic_vector(0 to 15);  -- SRAM data bus output
PB_DOUT_EN : out std_logic;               -- SRAM data bus output enable
PB_A     : out std_logic_vector (0 to 19); -- SRAM address bus
RAM_CE   : out std_logic;                 -- SRAM chip select
PB_OE_N  : out std_logic;                 -- SRAM output enable
PB_WE_N  : out std_logic;                 -- SRAM write enable
PB_UB_N  : out std_logic;                 -- SRAM byte enable
PB_LB_N  : out std_logic;                 -- SRAM byte enable
);

```

end opb\_sram;

architecture Behavioral of opb\_sram is

```

constant RAM_AWIDTH : integer := 18; -- Number of address lines on the RAM
constant RAM_DWIDTH : integer := 16; -- Number of data lines on the RAM

```

```

signal RNW : std_logic;
signal RAM_DI: std_logic_vector(0 to 31);
signal ABus : std_logic_vector(0 to RAM_AWIDTH-1);
signal chip_select : std_logic;
signal output_enable : std_logic;
signal WE : std_logic;
signal BE : std_logic_vector(0 to 3);
signal A31: std_logic;
signal A30R: std_logic;
signal RAM_RD_DATA : std_logic_vector (0 to 31);
signal RAM_RD_DATA_MUX : std_logic_vector (0 to 31);
signal RAM_WR_DATA : std_logic_vector (0 to 31);

```

```

signal CE : std_logic;    -- SRAM chip enable
signal OE : std_logic;    -- SRAM output enable
signal xfer_start: std_logic; -- Transfer start
signal xfer_end: std_logic;  -- Transfer end
signal xfer_idle: std_logic; -- No transfer pending
signal obuf_oe: std_logic;  -- Data output buffer enable

```

```

signal xfer_done: std_logic;    -- Transfer has been done
signal byte_start: std_logic;
signal word_address: std_logic;
signal byte_mode: std_logic;
signal halfword_mode: std_logic;
signal word_mode: std_logic;
signal A30 : std_logic;
signal word_access: std_logic;
signal word_latch: std_logic;
signal set_a30: std_logic;
signal DIN_Latch: std_logic_vector(0 to 15);

-- Critical: Sln_xferAck is generated directly from state bit 0!
constant STATE_BITS : integer := 3;
constant ST_IDLE    : std_logic_vector(0 to STATE_BITS-1) := "000";
constant ST_SELECTED : std_logic_vector(0 to STATE_BITS-1) := "001";
constant ST_WAIT    : std_logic_vector(0 to STATE_BITS-1) := "011";
constant ST_XFER    : std_logic_vector(0 to STATE_BITS-1) := "111";
constant ST_WORDINIT : std_logic_vector(0 to STATE_BITS-1) := "010";
constant ST_HOLD    : std_logic_vector(0 to STATE_BITS-1) := "100";
constant ST_WAITWORD : std_logic_vector(0 to STATE_BITS-1) := "101";
constant ST_XFERWORD : std_logic_vector(0 to STATE_BITS-1) := "110";

signal present_state, next_state : std_logic_vector(0 to STATE_BITS-1);

begin

register_opb_inputs: process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    RAM_DI <= (others => '0');
    ABus <= (others => '0');
    RNW <= '0';
    A31 <= '0';
    A30R <= '0';
    BE <= (others => '0');
  elsif OPB_Clk'event and OPB_Clk = '1' then
    RAM_DI <= OPB_DBus(0 to C_OPB_DWIDTH-1);
    if ( word_address = '1') then
      ABus <= OPB_ABus(C_OPB_AWIDTH-2-(RAM_AWIDTH-1) to
C_OPB_AWIDTH-3) & '1';
    else
      ABus <= OPB_ABus(C_OPB_AWIDTH-2-(RAM_AWIDTH-1) to
C_OPB_AWIDTH-2);
    end if ;
    A31 <= OPB_ABus(31);
  end if ;
end process ;

```

```

A30R <= OPB_ABus(30);
if (xfer_idle = '1') then
  BE <= OPB_BE(0 to 3);
  RNW <= OPB_RNW;
end if;
end if;
end process register_opb_inputs;

-- register_opb_outputs: process (OPB_Clk, OPB_Rst)
-- begin
--   if OPB_Rst = '1' then
--     Sln_DBus <= (others => '0');
--   elsif OPB_Clk'event and OPB_Clk = '1' then
--     if (output_enable = '1' and RNW = '1') then
--       if (output_enable = '1') then
--         Sln_DBus <= RAM_RD_DATA_MUX;
--       else
--         Sln_DBus <= (others => '0');
--       end if;
--     end if;
--   end process register_opb_outputs;

process (RAM_RD_DATA_MUX, output_enable)
begin
  if (output_enable = '1') then
    Sln_DBus <= RAM_RD_DATA_MUX;
  else
    Sln_DBus <= (others => '0');
  end if;
end process;

-- Unused outputs
Sln_errAck <= '0';
Sln_retry <= '0';
Sln_toutSup <= '0';
--Sln_DBus(RAM_DWIDTH to C_OPB_DWIDTH-1) <= (others => '0');

chip_select <=
'1' when OPB_select = '1' and
  OPB_ABus(0 to C_OPB_AWIDTH-2-RAM_AWIDTH) =
  C_BASEADDR(0 to C_OPB_AWIDTH-2-RAM_AWIDTH) else
'0';

Sln_xferAck <= xfer_done;

-- Sequential part of the FSM

```

```

fsm_seq : process(OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    present_state <= ST_IDLE;
  elsif OPB_Clk'event and OPB_Clk = '1' then
    present_state <= next_state;
  end if;
end process fsm_seq;

-- Combinational part of the FSM
fsm_comb : process(present_state, chip_select, OPB_Select, word_mode)
begin
  case present_state is
    when ST_IDLE =>
      if chip_select = '1' then
        next_state <= ST_SELECTED;
      else
        next_state <= ST_IDLE;
      end if;

    when ST_SELECTED =>
      if OPB_Select = '1' then
        next_state <= ST_XFER;
      else
        next_state <= ST_IDLE;
      end if;

    -- State encoding is critical here: xfer must only be true here
    when ST_XFER =>
      if word_mode = '1' then
        next_state <= ST_HOLD;
      else
        next_state <= ST_IDLE;
      end if;

    when ST_HOLD =>
      if OPB_Select = '1' then
        next_state <= ST_XFERWORD;
      else
        next_state <= ST_IDLE;
      end if;

    when ST_XFERWORD =>
      next_state <= ST_IDLE;
    when others =>
      next_state <= ST_IDLE;
  end case;
end process fsm_comb;

```



```

        end case;

end process fsm_comb;

fsm_output: process (present_state, word_mode)
begin
    output_enable <= '0';
    xfer_start <= '0';
    byte_start <= '0';
    xfer_end <= '0';
    xfer_idle <= '0';
    xfer_done <= '0';
    word_latch <= '0';
    word_address <= '0';
    set_a30 <= '0';
    case present_state is
        when ST_IDLE =>
            xfer_idle <= '1';
            byte_start <= '1';
        when ST_SELECTED =>
            xfer_start <= '1';
        when ST_XFER =>
            output_enable <= not word_mode;
            word_latch <= '1';
            xfer_end <= not word_mode;
            xfer_done <= not word_mode;
            set_a30 <= word_mode;
            word_address <= word_mode;
        when ST_HOLD =>
            xfer_start <= '1';
            word_address <= '1';
        when ST_XFERWORD =>
            output_enable <= '1';
            xfer_end <= '1';
            xfer_done <= '1';

        when others =>
            output_enable <= '0';
            byte_start <= '0';
            xfer_start <= '0';
            xfer_end <= '0';
            xfer_idle <= '0';
            set_a30 <= '0';
            word_latch <= '0';
            word_address <= '0';
    end case;
end process;

```

```

end process fsm_output;

-- The following process generates the SRAM OE output signal
sram_oe_reg: process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    OE <= '1';
  elsif OPB_Clk 'event and OPB_Clk = '1' then
    if ( next_state = ST_SELECTED) then
      OE <= not OPB_RNW;
    elsif ( next_state = ST_IDLE) then
      OE <= '1';
    end if;
  end if;
end process sram_oe_reg;

-- The following process generates the SRAM chip enable output signal
sram_ce_reg: process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    CE <= '1';
  elsif OPB_Clk 'event and OPB_Clk = '1' then
    if ( next_state = ST_SELECTED) then
      CE <= '0';
    elsif ( next_state = ST_IDLE) then
      CE <= '1';
    end if;
  end if;
end process sram_ce_reg;

-- The following process generates the SRAM WE output signal
sram_we_reg: process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    WE <= '1';
  elsif OPB_Clk 'event and OPB_Clk = '0' then
    if ( xfer_start = '1' and chip_select = '1' ) then
      WE <= RNW;
    else
      WE <= '1';
    end if;
  end if;
end process sram_we_reg;

-- Detect the current access mode
process (BE)

```

```

begin
  byte_mode <= '0';
  halfword_mode <= '1';
  word_mode <= '0';
  case BE is
    when "0001" =>
      byte_mode <= '1';
      halfword_mode <= '0';
      word_mode <= '0';
    when "0010" =>
      byte_mode <= '1';
      halfword_mode <= '0';
      word_mode <= '0';
    when "0100" =>
      byte_mode <= '1';
      halfword_mode <= '0';
      word_mode <= '0';
    when "1000" =>
      byte_mode <= '1';
      halfword_mode <= '0';
      word_mode <= '0';
    when "0011" =>
      byte_mode <= '0';
      halfword_mode <= '1';
      word_mode <= '0';
    when "1100" =>
      byte_mode <= '0';
      halfword_mode <= '1';
      word_mode <= '0';
    when "1111" =>
      byte_mode <= '0';
      halfword_mode <= '0';
      word_mode <= '1';
    when others =>
      byte_mode <= '0';
      halfword_mode <= '1';
      word_mode <= '0';
  end case;
end process;

process ( OPB_Clk, OPB_Rst)
begin
  if (OPB_Rst = '1') then
    DIN_Latch <= (others => '0');
  elsif ( OPB_Clk 'event and OPB_Clk = '1') then
    if ( word_latch = '1') then

```

```

        DIN_Latch <= PB_DIN;
    end if;
end if;
end process;

process (OPB_Clk, OPB_Rst)
begin
    if (OPB_Rst = '1') then
        word_access <= '0';
    elsif (OPB_Clk 'event and OPB_Clk = '1') then
        if (byte_start = '1' or xfer_idle = '1' or xfer_end = '1' ) then
            word_access <= '0';
        elsif ( set_a30 = '1' and word_mode = '1') then
            word_access <= '1';
        end if;
    end if;
end process;

--

--RAM_WR_DATA <= RAM_DI;
process ( RAM_DI, word_access, word_mode, A30R)
begin
    if ( word_mode = '0') then
        if ( A30R = '1') then
            RAM_WR_DATA(16 to 31) <= RAM_DI(16 to 31);
        else
            RAM_WR_DATA(16 to 31) <= RAM_DI(0 to 15);
        end if;
    else
        if (word_access = '1') then
            RAM_WR_DATA(16 to 31) <= RAM_DI(16 to 31);
        else
            RAM_WR_DATA(16 to 31) <= RAM_DI(0 to 15);
        end if;
    end if;
end process;

--RAM_RD_DATA <= DIN_Latch & PB_DIN;

process ( PB_DIN, DIN_Latch, A31, byte_mode)
begin
    if ( A31 = '0' and byte_mode = '1') then
        RAM_RD_DATA(24 to 31) <= PB_DIN(0 to 7);
    else
        RAM_RD_DATA(24 to 31) <= PB_DIN(8 to 15);
    end if;
end process;

```

```

end if;

RAM_RD_DATA(16 to 23) <= PB_DIN(0 to 7) ;
RAM_RD_DATA(0 to 15) <= DIN_Latch ;
end process;

process ( RAM_RD_DATA, byte_mode, halfword_mode)
begin
  if ( byte_mode = '1') then
    RAM_RD_DATA_MUX <= RAM_RD_DATA(24 to 31) & RAM_RD_DATA(24
to 31) & RAM_RD_DATA(24 to 31) & RAM_RD_DATA(24 to 31);
  elsif (halfword_mode = '1' ) then
    RAM_RD_DATA_MUX <= RAM_RD_DATA(16 to 31) & RAM_RD_DATA(16
to 31);
  else
    RAM_RD_DATA_MUX <= RAM_RD_DATA;
  end if;
end process;

```

----

```
A30 <= ABus(RAM_AWIDTH-1) or word_access;
```

```

process (A31, CE, byte_mode, RNW)
begin
  if ( RNW = '0') then
    if ( byte_mode = '1') then
      if ( A31 = '1') then
        PB_UB_N <= '1';
        PB_LB_N <= CE;
      else
        PB_UB_N <= CE;
        PB_LB_N <= '1';
      end if;
    else
      PB_UB_N <= CE;
      PB_LB_N <= CE;
    end if;
  else
    PB_UB_N <= CE;
    PB_LB_N <= CE;
  end if;
end process;

```

-- The following assign the SRAM output signals

```

PB_OE_N <= OE;
PB_WE_N <= WE;
RAM_CE <= CE;
--PB_UB_N <= CE;
--PB_LB_N <= CE;
PB_A <= "00" & ABus(0 to RAM_AWIDTH-1); -- & A30;
PB_DOUT <= RAM_WR_DATA(16 to 31);
PB_DOUT_EN <= (not CE) and OE;

```

end Behavioral;

### 4.3.2 opb\_flash.vhd

```

-----
--
-- OPB Flash controller
--
--
-----
library ieee;
use ieee.std_logic_1164.all;
use ieee.std_logic_arith.all;
use ieee.std_logic_unsigned.all;

entity opb_flash is

    generic (
        C_OPB_AWIDTH : integer           := 32;
        C_OPB_DWIDTH : integer           := 32;
        C_BASEADDR   : std_logic_vector(0 to 31) := X"30000000";
        C_HIGHADDR   : std_logic_vector(0 to 31) := X"3FFFFFFF");

    port (
        OPB_Clk   : in  std_logic;
        OPB_Rst   : in  std_logic;
        OPB_ABus  : in  std_logic_vector(0 to C_OPB_AWIDTH-1);
        OPB_BE    : in  std_logic_vector(0 to C_OPB_DWIDTH/8-1);
        OPB_DBus  : in  std_logic_vector(0 to C_OPB_DWIDTH-1);
        OPB_RNW   : in  std_logic;
        OPB_select : in  std_logic;
        OPB_seqAddr : in  std_logic;    -- Sequential Address
        Sln_DBus  : out std_logic_vector(0 to C_OPB_DWIDTH-1);
        Sln_errAck : out std_logic;    -- (unused)
        Sln_retry  : out std_logic;    -- (unused)
        Sln_toutSup : out std_logic;    -- Timeout suppress

```

```

Sln_xferAck : out std_logic;    -- Transfer acknowledge

PB_DIN  : in std_logic_vector(0 to 15);    -- FLASH data bus
PB_DOUT : out std_logic_vector(0 to 15);    -- FLASH data bus output
PB_DOUT_EN : out std_logic;                -- FLASH data bus output enable
PB_A    : out std_logic_vector (0 to 19);    -- FLASH address bus
PB_OE_N : out std_logic;                    -- FLASH output enable
PB_WE_N : out std_logic;                    -- FLASH write enable
FLASH_CE_N : out std_logic                 -- FLASH byte enable
);

```

```
end opb_flash;
```

architecture Behavioral of opb\_flash is

```

constant FLASH_AWIDTH : integer := 19; -- Number of address lines on the FLASH
constant FLASH_DWIDTH : integer := 8;  -- Number of data lines on the FLASH

```

```

signal RNW : std_logic;
signal FLASH_DI: std_logic_vector(0 to 31);
signal ABus : std_logic_vector(0 to FLASH_AWIDTH-1);
signal chip_select : std_logic;
signal output_enable : std_logic;
signal WE : std_logic;
signal BE : std_logic_vector(0 to 3);
signal A30A31: std_logic_vector (0 to 1);
signal FLASH_RD_DATA : std_logic_vector (0 to 31);
signal FLASH_WR_DATA : std_logic_vector (0 to 31);
signal TOSUP : std_logic;

```

```

signal CE : std_logic;    -- FLASH chip enable
signal OE : std_logic;    -- FLASH output enable
signal xfer_start: std_logic; -- Transfer start
signal xfer_end: std_logic;  -- Transfer end
signal xfer_idle: std_logic; -- No transfer pending
signal obuf_oe: std_logic;  -- Data output buffer enable
signal xfer_done: std_logic; -- Transfer has been done
signal wait_expire: std_logic;
signal wait_counter: std_logic_vector ( 0 to 3 );

```

```
-- Critical: Sln_xferAck is generated directly from state bit 0!
```

```

constant STATE_BITS : integer := 3;
constant ST_IDLE     : std_logic_vector(0 to STATE_BITS-1) := "000";
constant ST_SELECTED : std_logic_vector(0 to STATE_BITS-1) := "001";
constant ST_WAIT     : std_logic_vector(0 to STATE_BITS-1) := "011";
constant ST_XFER     : std_logic_vector(0 to STATE_BITS-1) := "111";

```

```

constant ST_HOLD    : std_logic_vector(0 to STATE_BITS-1) := "100";
constant ST_WAITWORD : std_logic_vector(0 to STATE_BITS-1) := "101";
constant ST_XFERWORD : std_logic_vector(0 to STATE_BITS-1) := "110";

signal present_state, next_state : std_logic_vector(0 to STATE_BITS-1);

begin

register_opb_inputs: process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    FLASH_DI <= (others => '0');
    ABus <= (others => '0');
    RNW <= '0';
    A30A31 <= (others => '0');
    BE <= (others => '0');
  elsif OPB_Clk'event and OPB_Clk = '1' then
    FLASH_DI <= OPB_DBus(0 to C_OPB_DWIDTH-1);
    ABus <= OPB_ABus(C_OPB_AWIDTH-1-(FLASH_AWIDTH-1) to
C_OPB_AWIDTH-1);
    RNW <= OPB_RNW;
    A30A31 <= OPB_ABus(30 to 31);
    BE <= OPB_BE(0 to 3);
  end if;
end process register_opb_inputs;

register_opb_outputs: process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    Sln_DBus <= (others => '0');
  elsif OPB_Clk'event and OPB_Clk = '1' then
--   if (output_enable = '1' and RNW = '1') then
    if (output_enable = '1') then
      Sln_DBus <= FLASH_RD_DATA;
    else
      Sln_DBus <= (others => '0');
    end if;
  end if;
end process register_opb_outputs;

-- Unused outputs
Sln_errAck <= '0';
Sln_retry  <= '0';
Sln_toutSup <= TOSUP;
--Sln_DBus(FLASH_DWIDTH to C_OPB_DWIDTH-1) <= (others => '0');

```



```

chip_select <=
  '1' when OPB_select = '1' and
    OPB_ABUS(0 to C_OPB_AWIDTH-2-FLASH_AWIDTH) =
      C_BASEADDR(0 to C_OPB_AWIDTH-2-FLASH_AWIDTH) else
  '0';

Sln_xferAck <= xfer_end;

-- Sequential part of the FSM
fsm_seq : process(OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    present_state <= ST_IDLE;
  elsif OPB_Clk'event and OPB_Clk = '1' then
    present_state <= next_state;
  end if;
end process fsm_seq;

-- Combinational part of the FSM
fsm_comb : process(present_state, chip_select, OPB_Select , wait_expire)
begin
  case present_state is
    when ST_IDLE =>
      if chip_select = '1' then
        next_state <= ST_SELECTED;
      else
        next_state <= ST_IDLE;
      end if;

    when ST_SELECTED =>
      if OPB_Select = '1' then
        next_state <= ST_WAIT;
      else
        next_state <= ST_IDLE;
      end if;

    when ST_WAIT =>
      if OPB_Select = '1' then
        if ( wait_expire = '1' ) then
          next_state <= ST_XFER;
        else
          next_state <= ST_WAIT;
        end if;
      else
        next_state <= ST_IDLE;
      end if;
  end case;
end process fsm_comb;

```

```

-- State encoding is critical here: xfer must only be true here
when ST_XFER =>
    next_state <= ST_IDLE;

when others =>
    next_state <= ST_IDLE;
end case;

end process fsm_comb;

fsm_output: process (present_state)
begin
    output_enable <= '0';
    xfer_start <= '0';
    xfer_end <= '0';
    xfer_idle <= '0';
    case present_state is
        when ST_IDLE =>
            xfer_idle <= '1';
        when ST_SELECTED =>
            xfer_start <= '1';
        when ST_WAIT =>
            output_enable <= '1';
        when ST_XFER =>
            xfer_end <= '1';
        when others =>
            output_enable <= '0';
            xfer_start <= '0';
            xfer_end <= '0';
            xfer_idle <= '0';
    end case;
end process fsm_output;

-- The following process generates the SFLASH OE output signal
flash_oe_reg: process (OPB_Clk, OPB_Rst)
begin
    if OPB_Rst = '1' then
        OE <= '1';
    elsif OPB_Clk 'event and OPB_Clk = '1' then
        if ( chip_select = '1' and xfer_idle = '1') then
            OE <= not OPB_RNW;
        elsif ( xfer_end = '1') then
            OE <= '1';
        end if;
    end if;
end if;

```

```

end process flash_oe_reg;

-- The following process generates the flash chip enable output signal
flash_ce_reg: process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    CE <= '1';
  elsif OPB_Clk 'event and OPB_Clk = '1' then
    if ( chip_select = '1' and xfer_idle = '1') then
      CE <= '0';
    elsif ( xfer_end = '1') then
      CE <= '1';
    end if;
  end if;
end process flash_ce_reg;

process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    TOSUP <= '0';
  elsif OPB_Clk 'event and OPB_Clk = '1' then
    if ( chip_select = '1' and xfer_idle = '1') then
      TOSUP <= '1';
    elsif ( xfer_end = '1') then
      TOSUP <= '0';
    end if;
  end if;
end process;

-- The following process generates the flash WE output signal
flash_we_reg: process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    WE <= '1';
  elsif OPB_Clk 'event and OPB_Clk = '1' then
    if ( xfer_start = '1') then
      WE <= RNW;
    elsif (wait_expire = '1') then
      WE <= '1';
    end if;
  end if;
end process flash_we_reg;

-- Wait counter
process (OPB_Clk, OPB_Rst)

```

```

begin
  if ( OPB_Rst = '1') then
    wait_counter <= (others => '0');
  elsif OPB_Clk 'event and OPB_Clk = '1' then
    if ( xfer_start = '1' or xfer_idle = '1' ) then
      wait_counter <= "0000";
    else
      wait_counter <= wait_counter + '1';
    end if;
  end if;
end process;

process ( wait_counter, RNW)
begin
  if (RNW = '1') then
    if ( wait_counter = "0101" ) then
      wait_expire <= '1';
    else
      wait_expire <= '0';
    end if;
  else
    if ( wait_counter = "1011" ) then
      wait_expire <= '1';
    else
      wait_expire <= '0';
    end if;
  end if;
end process;

--
FLASH_WR_DATA <= FLASH_DI ;
FLASH_RD_DATA <= PB_DIN(8 to 15) & PB_DIN(8 to 15) & PB_DIN(8 to 15) &
PB_DIN(8 to 15);

-- The following assign the flash output signals
PB_OE_N <= OE;
PB_WE_N <= WE;
FLASH_CE_N <= CE;
PB_A <= '0' & ABus;
PB_DOUT <= "00000000" & FLASH_WR_DATA(24 to 31);
--FLASH_DO <= FLASH_RD_DATA;
PB_DOUT_EN <= not CE and OE;

end Behavioral;

```

### 4.3.3 opb\_mux.vhd

```
-----  
--  
-- OPB Bus Multiplexer  
--  
-----  
library ieee;  
use ieee.std_logic_1164.all;  
  
entity opb_pb_mux is  
  
    generic (  
        C_OPB_AWIDTH : integer          := 32;  
        C_OPB_DWIDTH : integer          := 32;  
        C_BASEADDR   : std_logic_vector(0 to 31) := X"FFEF0500";  
        C_HIGHADDR   : std_logic_vector(0 to 31) := X"FFFF05FF");  
  
    port (  
        OPB_Clk   : in std_logic;  
        OPB_Rst   : in std_logic;  
        OPB_ABus  : in std_logic_vector(0 to C_OPB_AWIDTH-1);  
        OPB_BE    : in std_logic_vector(0 to C_OPB_DWIDTH/8-1);  
        OPB_DBus  : in std_logic_vector(0 to C_OPB_DWIDTH-1);  
        OPB_RNW   : in std_logic;  
        OPB_select : in std_logic;  
        OPB_seqAddr : in std_logic;    -- Sequential Address  
        Sln_DBus   : out std_logic_vector(0 to C_OPB_DWIDTH-1);  
        Sln_errAck : out std_logic;    -- (unused)  
        Sln_retry  : out std_logic;    -- (unused)  
        Sln_toutSup : out std_logic;    -- Timeout suppress  
        Sln_xferAck : out std_logic;    -- Transfer acknowledge  
  
        PB_D : inout std_logic_vector(0 to 15);    -- SRAM data bus  
        PB_A : out std_logic_vector (0 to 19);    -- SRAM address bus  
        PB_OE_N : out std_logic;                -- SRAM output enable  
        PB_WE_N : out std_logic;                -- SRAM write enable  
        PB_UB_N : out std_logic;                -- SRAM byte enable  
        PB_LB_N : out std_logic;                -- SRAM byte enable  
        PB_DIN : out std_logic_vector (0 to 15); -- SRAM data bus  
  
        PB_DOUT_SRAM : in std_logic_vector(0 to 15);  
        PB_DOUT_EN_SRAM : in std_logic;
```

```

PB_A_SRAM : in std_logic_vector(0 to 19);
PB_OE_N_SRAM : in std_logic;
PB_WE_N_SRAM : in std_logic;
PB_UB_N_SRAM : in std_logic;
PB_LB_N_SRAM : in std_logic;

PB_DOUT_FLASH : in std_logic_vector(0 to 15);
PB_DOUT_EN_FLASH : in std_logic;
PB_A_FLASH : in std_logic_vector(0 to 19);
PB_OE_N_FLASH : in std_logic;
PB_WE_N_FLASH : in std_logic;

PB_DOUT_SDRAM : in std_logic_vector(0 to 15);
PB_DOUT_EN_SDRAM : in std_logic;
PB_A_SDRAM : in std_logic_vector(0 to 19);
PB_UB_N_SDRAM : in std_logic;
PB_LB_N_SDRAM : in std_logic;

PB_DOUT_ETHER : in std_logic_vector(0 to 15);
PB_DOUT_EN_ETHER : in std_logic;
PB_A_ETHER : in std_logic_vector(0 to 19);
PB_OE_N_ETHER : in std_logic;
PB_WE_N_ETHER : in std_logic;
PB_UB_N_ETHER : in std_logic;
PB_LB_N_ETHER : in std_logic;

AU_BUSY : in std_logic;
AU_CCLK : in std_logic;
AU_CDTI : in std_logic;
--AU_CDTO : out std_logic;

SDRAM_LOCK : out std_logic;
SDRAM_ACTIVE : in std_logic
);

```

end opb\_pb\_mux;

architecture Behavioral of opb\_pb\_mux is

```

component IOBUF_F_24
port(
O : out std_ulogic;
IO : inout std_ulogic;
I : in std_ulogic;
T : in std_ulogic
);

```

```

end component;

----- component OBUF_F_24          -----
component OBUF_F_24
  port(
    O : out std_ulogic;
    I : in  std_ulogic
  );
end component;

signal current_slave : std_logic_vector (0 to 2) ;
signal Abus : std_logic_vector (0 to 8);
signal PB_DOUT : std_logic_vector(0 to 15);
signal PB_DOUT_EN : std_logic;

signal SetLock : std_logic;
signal Lock : std_logic;
signal RNW : std_logic;
signal chip_select : std_logic;
signal output_enable : std_logic;

signal xfer_start: std_logic;  -- Transfer start
signal xfer_end: std_logic;    -- Transfer end
signal xfer_idle: std_logic;   -- No transfer pending
signal obuf_oe: std_logic;     -- Data output buffer enable
signal xfer_done: std_logic;   -- Transfer has been done
signal oe_audio: std_logic;

-- Critical: Sln_xferAck is generated directly from state bit 0!
constant STATE_BITS : integer := 3;
constant ST_IDLE    : std_logic_vector(0 to STATE_BITS-1) := "000";
constant ST_SELECTED : std_logic_vector(0 to STATE_BITS-1) := "001";
constant ST_WAIT    : std_logic_vector(0 to STATE_BITS-1) := "011";
constant ST_XFER    : std_logic_vector(0 to STATE_BITS-1) := "111";

signal present_state, next_state : std_logic_vector(0 to STATE_BITS-1);

begin

register_opb_inputs: process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    SetLock <= '0';
    RNW <= '0';
  elsif OPB_Clk'event and OPB_Clk = '1' then

```

```

    SetLock <= OPB_DBus(C_OPB_DWIDTH-1);
    RNW <= OPB_RNW;
end if;
end process register_opb_inputs;

register_opb_outputs: process (OPB_Clk, OPB_Rst)
begin
    if OPB_Rst = '1' then
        Sln_DBus <= (others => '0');
    elsif OPB_Clk'event and OPB_Clk = '1' then
        if (output_enable = '1' and RNW = '1') then
            Sln_DBus <= "0000000000000000" & "00000000" & "000000" & Lock & '0';
        else
            Sln_DBus <= (others => '0');
        end if;
    end if;
end process register_opb_outputs;

-- Unused outputs
Sln_errAck <= '0';
Sln_retry <= '0';
Sln_toutSup <= '0';

chip_select <=
    '1' when OPB_select = '1' and
        OPB_ABus(0 to C_OPB_AWIDTH-1) = C_BASEADDR(0 to C_OPB_AWIDTH-1)
else
    '0';

Sln_xferAck <= present_state(0);

-- Sequential part of the FSM
fsm_seq : process(OPB_Clk, OPB_Rst)
begin
    if OPB_Rst = '1' then
        present_state <= ST_IDLE;
    elsif OPB_Clk'event and OPB_Clk = '1' then
        present_state <= next_state;
    end if;
end process fsm_seq;

-- Combinational part of the FSM
fsm_comb : process(present_state, chip_select, OPB_Select)
begin
    case present_state is
        when ST_IDLE =>

```



```

    if chip_select = '1' then
        next_state <= ST_SELECTED;
    else
        next_state <= ST_IDLE;
    end if;
when ST_SELECTED =>
    if OPB_Select = '1' then
        next_state <= ST_WAIT;
    else
        next_state <= ST_IDLE;
    end if;
when ST_WAIT =>
    if OPB_Select = '1' then
        next_state <= ST_XFER;
    else
        next_state <= ST_IDLE;
    end if;
-- State encoding is critical here: xfer must only be true here
when ST_XFER =>
    next_state <= ST_IDLE;
when others =>
    next_state <= ST_IDLE;
end case;

```

```
end process fsm_comb;
```

```

process (present_state)
begin
    if ( present_state = ST_WAIT) then
        output_enable <= '1';
    else
        output_enable <= '0';
    end if;
end process;

```

```

process (OPB_Clk, OPB_Rst)
begin
    if OPB_Rst = '1' then
        Lock <= '0';
    elsif OPB_Clk 'event and OPB_Clk = '1' then
        if ( present_state = ST_WAIT and SetLock = '1' ) then
            Lock <= '1';
        elsif (SDRAM_ACTIVE = '1') then
            Lock <= '0';
        end if;
    end if;
end process;

```

```

end process;

process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    SDRAM_LOCK <= '0';
  elsif OPB_Clk 'event and OPB_Clk = '1' then
    if ( Lock = '1' ) then
      SDRAM_LOCK <= '1';
    end if;
  end if;
end process;

-- PB_DIN <= PB_D;

-- process (PB_DOUT, PB_DOUT_EN) begin
--   if ( PB_DOUT_EN = '1' ) then
--     PB_D <= PB_DOUT;
--   else
--     PB_D <= "ZZZZZZZZZZZZZZZZZZZZ";
--   end if;
-- end process;

Abus <= OPB_ABus ( 0 to 8);

process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    current_slave <= "000";
  elsif OPB_Clk 'event and OPB_Clk = '1' then
    if ( Lock = '1' ) then
      current_slave <= "010";
    elsif ( AU_BUSY = '1' ) then
      current_slave <= "100";
    elsif ( OPB_select = '1' ) then
      case Abus is
        when "001000000" => -- 20000000
          current_slave <= "000";
        when "001100000" => -- 30000000
          current_slave <= "001";
        when "010000000" => -- 40000000
          current_slave <= "010";
        when "000000001" => -- 00800000
          current_slave <= "011";
        when "111111111" => -- FFEF0000

```

```

        current_slave <= "100";
    when others =>
        current_slave <= "010";
    end case;
end if;
end if;
end process;

--AU_CDTO <= PB_D(13);
--AU_CDTO <= '0';

process (  PB_DOUT_SRAM,
          PB_DOUT_EN_SRAM,
          PB_A_SRAM,
          PB_OE_N_SRAM,
          PB_WE_N_SRAM,
          PB_UB_N_SRAM,
          PB_LB_N_SRAM,

          PB_DOUT_FLASH,
          PB_DOUT_EN_FLASH,
          PB_A_FLASH,
          PB_OE_N_FLASH,
          PB_WE_N_FLASH,

          PB_DOUT_SDRAM,
          PB_DOUT_EN_SDRAM,
          PB_A_SDRAM,
          PB_UB_N_SDRAM,
          PB_LB_N_SDRAM,

          PB_DOUT_ETHER,
          PB_DOUT_EN_ETHER,
          PB_A_ETHER,
          PB_OE_N_ETHER,
          PB_WE_N_ETHER,
          PB_UB_N_ETHER,
          PB_LB_N_ETHER,

          AU_CCLK,
          AU_CDTI )
begin
    case current_slave is
    when "000" =>
        PB_A    <= PB_A_SRAM;
        PB_OE_N <= PB_OE_N_SRAM;

```

```

PB_WE_N  <= PB_WE_N_SRAM;
PB_UB_N  <= PB_UB_N_SRAM;
PB_LB_N  <= PB_LB_N_SRAM;
PB_DOUT  <= PB_DOUT_SRAM;
PB_DOUT_EN <= PB_DOUT_EN_SRAM;
when "001" =>
  PB_A    <= PB_A_FLASH;
  PB_OE_N <= PB_OE_N_FLASH;
  PB_WE_N <= PB_WE_N_FLASH;
  PB_UB_N <= '1';
  PB_LB_N <= '1';
  PB_DOUT <= PB_DOUT_FLASH;
  PB_DOUT_EN <= PB_DOUT_EN_FLASH;
when "010" =>
  PB_A    <= PB_A_SDRAM;
  PB_OE_N <= '1';
  PB_WE_N <= '1';
  PB_UB_N <= PB_UB_N_SDRAM;
  PB_LB_N <= PB_LB_N_SDRAM;
  PB_DOUT <= PB_DOUT_SDRAM;
  PB_DOUT_EN <= PB_DOUT_EN_SDRAM;
when "011" =>
  PB_A    <= PB_A_ETHER;
  PB_OE_N <= PB_OE_N_ETHER;
  PB_WE_N <= PB_WE_N_ETHER;
  PB_UB_N <= PB_UB_N_ETHER;
  PB_LB_N <= PB_LB_N_ETHER;
  PB_DOUT <= PB_DOUT_ETHER;
  PB_DOUT_EN <= PB_DOUT_EN_ETHER;

when "100" =>
  PB_A    <= (others => '0') ;
  PB_OE_N <= '1';
  PB_WE_N <= '1';
  PB_UB_N <= '1';
  PB_LB_N <= '1';
  PB_DOUT <= "0000000000000000" & AU_CDTI & AU_CCLK;
  PB_DOUT_EN <= '1';

when others =>
  PB_A    <= PB_A_SDRAM;
  PB_OE_N <= '1';
  PB_WE_N <= '1';
  PB_UB_N <= PB_UB_N_SDRAM;
  PB_LB_N <= PB_LB_N_SDRAM;
  PB_DOUT <= PB_DOUT_SDRAM;

```

```
        PB_DOUT_EN <= PB_DOUT_EN_SDRAM;
    end case;
end process;
```

```
obuf_oe <= not PB_DOUT_EN;
```

```
-- Audio CDTO must be input mode in case of audio controller transfer
process ( PB_DOUT_EN , AU_BUSY)
begin
    if ( AU_BUSY = '1') then
        oe_audio <= '1';
    else
        oe_audio <= not PB_DOUT_EN;
    end if;
end process;
```

```
-- The following assign the data pads
data0_pad: IOBUF_F_24 port map (
    O => PB_DIN(0),
    IO => PB_D(0),
    I => PB_DOUT(0),
    T => obuf_oe
);
```

```
data1_pad: IOBUF_F_24 port map (
    O => PB_DIN(1),
    IO => PB_D(1),
    I => PB_DOUT(1),
    T => obuf_oe
);
```

```
data2_pad: IOBUF_F_24 port map (
    O => PB_DIN(2),
    IO => PB_D(2),
    I => PB_DOUT(2),
    T => obuf_oe
);
```

```
data3_pad: IOBUF_F_24 port map (
    O => PB_DIN(3),
    IO => PB_D(3),
    I => PB_DOUT(3),
    T => obuf_oe
);
```

```
data4_pad: IOBUF_F_24 port map (  
O => PB_DIN(4),  
IO => PB_D(4),  
I => PB_DOUT(4),  
T => obuf_oe  
);
```

```
data5_pad: IOBUF_F_24 port map (  
O => PB_DIN(5),  
IO => PB_D(5),  
I => PB_DOUT(5),  
T => obuf_oe  
);
```

```
data6_pad: IOBUF_F_24 port map (  
O => PB_DIN(6),  
IO => PB_D(6),  
I => PB_DOUT(6),  
T => obuf_oe  
);
```

```
data7_pad: IOBUF_F_24 port map (  
O => PB_DIN(7),  
IO => PB_D(7),  
I => PB_DOUT(7),  
T => obuf_oe  
);
```

```
data8_pad: IOBUF_F_24 port map (  
O => PB_DIN(8),  
IO => PB_D(8),  
I => PB_DOUT(8),  
T => obuf_oe  
);
```

```
data9_pad: IOBUF_F_24 port map (  
O => PB_DIN(9),  
IO => PB_D(9),  
I => PB_DOUT(9),  
T => obuf_oe  
);
```

```
data10_pad: IOBUF_F_24 port map (  
O => PB_DIN(10),  
IO => PB_D(10),  
I => PB_DOUT(10),
```

```
T => obuf_oe
);
```

```
data11_pad: IOBUF_F_24 port map (
O => PB_DIN(11),
IO => PB_D(11),
I => PB_DOUT(11),
T => obuf_oe
);
```

```
data12_pad: IOBUF_F_24 port map (
O => PB_DIN(12),
IO => PB_D(12),
I => PB_DOUT(12),
T => obuf_oe
);
```

```
data13_pad: IOBUF_F_24 port map (
O => PB_DIN(13),
IO => PB_D(13),
I => PB_DOUT(13),
T => oe_audio
);
```

```
data14_pad: IOBUF_F_24 port map (
O => PB_DIN(14),
IO => PB_D(14),
I => PB_DOUT(14),
T => obuf_oe
);
```

```
data15_pad: IOBUF_F_24 port map (
O => PB_DIN(15),
IO => PB_D(15),
I => PB_DOUT(15),
T => obuf_oe
);
```

```
end Behavioral;
```

#### 4.3.4 opb\_sdram.vhd

```
-----
--
-- OPB SDRAM controller
--
--
```

```

-----
library ieee;
use ieee.std_logic_1164.all;
use ieee.std_logic_unsigned.all;
use ieee.std_logic_arith.all;
--library IEEE, UNISIM;
--use IEEE.std_logic_1164.all;
--use IEEE.std_logic_unsigned.all;
use IEEE.numeric_std.all;
--use WORK.common.all;

entity opb_sdram is

generic (
    C_OPB_AWIDTH : integer          := 32;
    C_OPB_DWIDTH : integer          := 32;
    C_BASEADDR   : std_logic_vector(0 to 31) := X"40000000";
    C_HIGHADDR   : std_logic_vector(0 to 31) := X"4FFFFFFF");

port (
    OPB_Clk   : in std_logic;
    OPB_Rst   : in std_logic;
    OPB_ABus  : in std_logic_vector(0 to C_OPB_AWIDTH-1);
    OPB_BE    : in std_logic_vector(0 to C_OPB_DWIDTH/8-1);
    OPB_DBus  : in std_logic_vector(0 to C_OPB_DWIDTH-1);
    OPB_RNW   : in std_logic;
    OPB_select : in std_logic;
    OPB_seqAddr : in std_logic;    -- Sequential Address
    Sln_DBus   : out std_logic_vector(0 to C_OPB_DWIDTH-1);
    Sln_errAck : out std_logic;    -- (unused)
    Sln_retry  : out std_logic;    -- (unused)
    Sln_toutSup : out std_logic;   -- Timeout suppress
    Sln_xferAck : out std_logic;   -- Transfer acknowledge

    SDRAM_CLK : in std_logic;
    SDRAM_LOCK : in std_logic;
    SDRAM_ACTIVE : out std_logic;
    PB_DIN   : in std_logic_vector(0 to 15);    -- SDRAM data bus
    PB_DOUT  : out std_logic_vector(0 to 15);   -- SDRAM data bus output
    PB_DOUT_EN : out std_logic;                -- SDRAM data bus output enable
    PB_A     : out std_logic_vector (0 to 19);  -- SDRAM address bus
    PB_UB_N  : out std_logic;                  -- SDRAM DQM
    PB_LB_N  : out std_logic;                  -- SDRAM DQM
    SDRAM_CKE : out std_logic;                -- SDRAM Clock enable
    SDRAM_CAS_N : out std_logic;              -- SDRAM CAS
    SDRAM_RAS_N : out std_logic;              -- SDRAM RAS

```



```

    SDRAM_CE_N : out std_logic;           -- SDRAM chip enable
    SDRAM_WE_N : out std_logic           -- SDRAM write enable
);

end opb_sdram;

architecture Behavioral of opb_sdram is

    component IBUFG
    port(
        O : out std_ulogic;

        I : in std_ulogic
    );
    end component;

    constant SDRAM_AWIDTH : integer := 23; -- Number of address lines on the RAM
    constant SDRAM_DWIDTH : integer := 16; -- Number of data lines on the RAM
    constant FREQ : natural := 67_000; -- operating frequency in KHz
    constant IN_PHASE : boolean := true; -- SDRAM and controller work on same or
    opposite clock edge
    constant PIPE_EN : boolean := false; -- if true, enable pipelined read operations
    constant MAX_NOP : natural := 10000; -- number of NOPs before entering self-
    refresh
    constant MULTIPLE_ACTIVE_ROWS : boolean := false; -- if true, allow an active
    row in each bank
    constant DATA_WIDTH : natural := 16; -- host & SDRAM data width
    constant NROWS : natural := 4096; -- number of rows in SDRAM array
    constant NCOLS : natural := 512; -- number of columns in SDRAM array
    constant HADDR_WIDTH : natural := 23; -- host-side address width
    constant SADDR_WIDTH : natural := 12; -- SDRAM-side address width

    signal RNW : std_logic;
    signal SDRAM_DI: std_logic_vector(0 to 31);
    signal ABus : std_logic_vector(0 to SDRAM_AWIDTH-1);
    signal chip_select : std_logic;
    signal output_enable : std_logic;
    signal WE : std_logic;
    signal BE : std_logic_vector(0 to 3);
    signal A30A31: std_logic_vector (0 to 1);
    signal SDRAM_RD_DATA : std_logic_vector (0 to 31);
    signal SDRAM_WR_DATA : std_logic_vector (0 to 31);

    signal CE : std_logic;           -- SDRAM chip enable
    signal OE : std_logic;           -- SDRAM output enable
    signal SDRAM_RD: std_logic;

```

```

signal SDRAM_WR: std_logic;
signal RD_RST: std_logic;
signal WR_RST: std_logic;
signal SDRAM_DATA_EN: std_logic;
signal done_lat: std_logic;
signal xfer_start: std_logic; -- Transfer start
signal xfer_end: std_logic; -- Transfer end
signal xfer_idle: std_logic; -- No transfer pending
signal obuf_oe: std_logic; -- Data output buffer enable
signal xfer_done: std_logic; -- Transfer has been done
signal xfer_done0: std_logic;
signal xfer_done1: std_logic;
signal TOSUP: std_logic;
signal timeout_cnt: std_logic_vector ( 0 to 5 ) ;
signal timeout : std_logic;

-- Critical: Sln_xferAck is generated directly from state bit 0!
constant STATE_BITS : integer := 3;
constant ST_IDLE : std_logic_vector(0 to STATE_BITS-1) := "000";
constant ST_SELECTED : std_logic_vector(0 to STATE_BITS-1) := "001";
constant ST_WAIT : std_logic_vector(0 to STATE_BITS-1) := "011";
constant ST_XFER : std_logic_vector(0 to STATE_BITS-1) := "111";
constant ST_HOLD : std_logic_vector(0 to STATE_BITS-1) := "100";
constant ST_WAITWORD : std_logic_vector(0 to STATE_BITS-1) := "101";
constant ST_XFERWORD : std_logic_vector(0 to STATE_BITS-1) := "110";

signal present_state, next_state : std_logic_vector(0 to STATE_BITS-1);

-- SDRAM controller signals
signal clk : std_logic; -- master clock
signal lock : std_logic; -- true if clock is stable
signal rst : std_logic; -- reset
signal rd : std_logic; -- initiate read operation
signal wr : std_logic; -- initiate write operation
signal earlyOpBegun : std_logic; -- read/write/self-refresh op has begun (async)
signal opBegun : std_logic; -- read/write/self-refresh op has begun (clocked)
signal rdPending : std_logic; -- true if read operation(s) are still in the pipeline
signal done : std_logic; -- read or write operation is done
signal rdDone : std_logic; -- read operation is done and data is available
signal hAddr : std_logic_vector(HADDR_WIDTH-1 downto 0); -- address from
host to SDRAM
signal hDIn : std_logic_vector(DATA_WIDTH-1 downto 0); -- data from host
to SDRAM
signal hDOut : std_logic_vector(DATA_WIDTH-1 downto 0); -- data from
SDRAM to host

```

```

signal status      : std_logic_vector(3 downto 0); -- diagnostic status of the FSM

-- SDRAM side
signal cke      : std_logic;      -- clock-enable to SDRAM
signal ce_n     : std_logic;      -- chip-select to SDRAM
signal ras_n    : std_logic;      -- SDRAM row address strobe
signal cas_n    : std_logic;      -- SDRAM column address strobe
signal we_n     : std_logic;      -- SDRAM write enable
signal ba       : std_logic_vector(1 downto 0); -- SDRAM bank address
signal sAddr    : std_logic_vector(SADDR_WIDTH-1 downto 0); -- SDRAM
row/column address
signal sDIn     : std_logic_vector(DATA_WIDTH-1 downto 0); -- data from SDRAM
signal sDOut    : std_logic_vector(DATA_WIDTH-1 downto 0); -- data to SDRAM
signal sDOutEn  : std_logic;      -- true if data is output to SDRAM on sDOut
signal dqmh     : std_logic;      -- enable upper-byte of SDRAM databus if true
signal dqml     : std_logic;      -- enable lower-byte of SDRAM databus if true

-----
-- The following signals are copied from the XESS design
-----

constant OUTPUT : std_logic := '1'; -- direction of dataflow w.r.t. this controller
constant INPUT  : std_logic := '0';
constant NOP    : std_logic := '0'; -- no operation
constant READ   : std_logic := '1'; -- read operation
constant WRITE  : std_logic := '1'; -- write operation

-- SDRAM timing parameters
constant Tinit : natural := 200; -- min initialization interval (us)
constant Tras  : natural := 45; -- min interval between active to precharge commands
(ns)
constant Trcd  : natural := 20; -- min interval between active and R/W commands
(ns)
constant Tref  : natural := 64_000_000; -- maximum refresh interval (ns)
constant Trfc  : natural := 66; -- duration of refresh operation (ns)
constant Trp   : natural := 20; -- min precharge command duration (ns)
constant Twr   : natural := 15; -- write recovery time (ns)
constant Txsr  : natural := 75; -- exit self-refresh time (ns)

-- SDRAM timing parameters converted into clock cycles (based on FREQ)
constant NORM   : natural := 1_000_000; -- normalize ns * KHz
constant INIT_CYCLES : natural := 1+((Tinit*FREQ)/1000); -- SDRAM power-on
initialization interval
constant RAS_CYCLES : natural := 1+((Tras*FREQ)/NORM); -- active-to-precharge
interval

```

```

    constant RCD_CYCLES : natural := 1+((Trcd*FREQ)/NORM); -- active-to-R/W
interval
    constant REF_CYCLES : natural := 1+(((Tref/NROWS)*FREQ)/NORM); -- interval
between row refreshes
    constant RFC_CYCLES : natural := 1+((Trfc*FREQ)/NORM); -- refresh operation
interval
    constant RP_CYCLES : natural := 1+((Trp*FREQ)/NORM); -- precharge operation
interval
    constant WR_CYCLES : natural := 1+((Twr*FREQ)/NORM); -- write recovery time
    constant XSR_CYCLES : natural := 1+((Txsr*FREQ)/NORM); -- exit self-refresh
time
    constant MODE_CYCLES : natural := 2; -- mode register setup time
    constant CAS_CYCLES : natural := 3; -- CAS latency
    constant RFSH_OPS : natural := 8; -- number of refresh operations needed to init
SDRAM

-- timer registers that count down times for various SDRAM operations
    signal timer_r, timer_x : natural range 0 to INIT_CYCLES; -- current SDRAM op
time
    signal rasTimer_r, rasTimer_x : natural range 0 to RAS_CYCLES; -- active-to-
precharge time
    signal wrTimer_r, wrTimer_x : natural range 0 to WR_CYCLES; -- write-to-
precharge time
    signal refTimer_r, refTimer_x : natural range 0 to REF_CYCLES; -- time between row
refreshes
    signal rfshCntr_r, rfshCntr_x : natural range 0 to NROWS; -- counts refreshes that are
neede
    signal nopCntr_r, nopCntr_x : natural range 0 to MAX_NOP; -- counts consecutive
NOP operations

    signal doSelfRfsh : std_logic; -- active when the NOP counter hits zero and self-
refresh can start

-- states of the SDRAM controller state machine
    type cntlState is (
        INITWAIT, -- initialization - waiting for power-on initialization to
complete
        INITPCHG, -- initialization - initial precharge of SDRAM banks
        INITSETMODE, -- initialization - set SDRAM mode
        INITRFSH, -- initialization - do initial refreshes
        RW, -- read/write/refresh the SDRAM
        ACTIVATE, -- open a row of the SDRAM for reading/writing
        REFRESHROW, -- refresh a row of the SDRAM
        SELFREFRESH -- keep SDRAM in self-refresh mode with CKE low
    );
    signal state_r, state_x : cntlState; -- state register and next state

```

```

-- commands that are sent to the SDRAM to make it perform certain operations
-- commands use these SDRAM input pins (ce_n,ras_n,cas_n,we_n,dqmh,dqml)
subtype sdramCmd is std_logic_vector(5 downto 0);
constant NOP_CMD   : sdramCmd := "011100";
constant ACTIVE_CMD : sdramCmd := "001100";
constant READ_CMD  : sdramCmd := "010100";
constant WRITE_CMD : sdramCmd := "010000";
constant PCHG_CMD  : sdramCmd := "001011";
constant MODE_CMD  : sdramCmd := "000011";
constant RFSH_CMD  : sdramCmd := "000111";

-- SDRAM mode register
-- the SDRAM is placed in a non-burst mode (burst length = 1) with a 3-cycle CAS
subtype sdramMode is std_logic_vector(11 downto 0);
constant MODE : sdramMode := "00" & "0" & "00" & "011" & "0" & "000";

-- the host address is decomposed into these sets of SDRAM address components
--constant ROW_LEN : natural := log2(NROWS); -- number of row address bits
--constant COL_LEN : natural := log2(NCOLS); -- number of column address bits
constant ROW_LEN : natural := 12; -- number of row address bits
constant COL_LEN : natural := 9;  -- number of column address bits

signal bank   : std_logic_vector(ba'range); -- bank address bits
signal row    : std_logic_vector(ROW_LEN - 1 downto 0); -- row address within bank
signal col    : std_logic_vector(sAddr'range); -- column address within row

-- registers that store the currently active row in each bank of the SDRAM
--constant NUM_ACTIVE_ROWS      : integer :=
int_select(MULTIPLE_ACTIVE_ROWS = false, 1, 2**ba'length);
constant NUM_ACTIVE_ROWS      : integer := 1;
type activeRowType is array(0 to NUM_ACTIVE_ROWS-1) of
std_logic_vector(row'range);
signal activeRow_r, activeRow_x : activeRowType;
signal activeFlag_r, activeFlag_x : std_logic_vector(0 to NUM_ACTIVE_ROWS-1);
-- indicates that some row in a bank is active
signal bankIndex      : natural range 0 to NUM_ACTIVE_ROWS-1; -- bank
address bits
signal activeBank_r, activeBank_x : std_logic_vector(ba'range); -- indicates the bank
with the active row
signal doActivate     : std_logic; -- indicates when a new row in a bank needs
to be activated

-- there is a command bit embedded within the SDRAM column address
constant CMDBIT_POS : natural := 10; -- position of command bit

```

```

constant AUTO_PCHG_ON : std_logic := '1'; -- CMDBIT value to auto-precharge the
bank
constant AUTO_PCHG_OFF : std_logic := '0'; -- CMDBIT value to disable auto-
precharge
constant ONE_BANK    : std_logic := '0'; -- CMDBIT value to select one bank
constant ALL_BANKS   : std_logic := '1'; -- CMDBIT value to select all banks

-- status signals that indicate when certain operations are in progress
signal wrInProgress   : std_logic; -- write operation in progress
signal rdInProgress   : std_logic; -- read operation in progress
signal activateInProgress : std_logic; -- row activation is in progress

-- these registers track the progress of read and write operations
signal rdPipeline_r, rdPipeline_x : std_logic_vector(CAS_CYCLES+1 downto 0); --
pipeline of read ops in progress
signal wrPipeline_r, wrPipeline_x : std_logic_vector(0 downto 0); -- pipeline of write
ops (only need 1 cycle)

-- registered outputs to host
signal opBegun_r, opBegun_x      : std_logic; -- true when SDRAM read or write
operation is started
signal hDOut_r, hDOut_x          : std_logic_vector(hDOut'range); -- holds data read
from SDRAM and sent to the host
signal hDOutOppPhase_r, hDOutOppPhase_x : std_logic_vector(hDOut'range); --
holds data read from SDRAM on opposite clock edge

-- registered outputs to SDRAM
signal cke_r, cke_x      : std_logic; -- clock enable
signal cmd_r, cmd_x      : sDRAMCmd; -- SDRAM command bits
signal ba_r, ba_x        : std_logic_vector(ba'range); -- SDRAM bank address bits
signal sAddr_r, sAddr_x  : std_logic_vector(sAddr'range); -- SDRAM row/column
address
signal sData_r, sData_x  : std_logic_vector(sDOut'range); -- SDRAM out databus
signal sDataDir_r, sDataDir_x : std_logic; -- SDRAM databus direction control bit

begin

register_opb_inputs: process (OPB_Clk, OPB_Rst)
begin
if OPB_Rst = '1' then
SDRAM_DI <= (others => '0');
ABus <= (others => '0');
RNW <= '0';
A30A31 <= (others => '0');
BE <= (others => '0');
elsif OPB_Clk'event and OPB_Clk = '1' then

```

```

    SDRAM_DI <= OPB_DBus(0 to C_OPB_DWIDTH-1);
    ABus <= OPB_ABus(C_OPB_AWIDTH-2-(SDRAM_AWIDTH-1) to
C_OPB_AWIDTH-2);
    RNW <= OPB_RNW;
    A30A31 <= OPB_ABus(30 to 31);
    BE <= OPB_BE(0 to 3);
end if;
end process register_opb_inputs;

process (output_enable, SDRAM_RD_DATA)
begin
    if (output_enable = '1') then
        Sln_DBus <= SDRAM_RD_DATA;
    else
        Sln_DBus <= (others => '0');
    end if;
end process;

-- Unused outputs
Sln_errAck <= '0';
Sln_retry <= '0';
Sln_toutSup <= TOSUP;
--Sln_DBus(SDRAM_DWIDTH to C_OPB_DWIDTH-1) <= (others => '0');

chip_select <=
'1' when OPB_select = '1' and
    OPB_ABus(0 to C_OPB_AWIDTH-2-SDRAM_AWIDTH) =
    C_BASEADDR(0 to C_OPB_AWIDTH-2-SDRAM_AWIDTH) else
'0';

Sln_xferAck <= xfer_end;

-- Sequential part of the FSM
fsm_seq : process(OPB_Clk, OPB_Rst)
begin
    if OPB_Rst = '1' then
        present_state <= ST_IDLE;
    elsif OPB_Clk'event and OPB_Clk = '1' then
        present_state <= next_state;
    end if;
end process fsm_seq;

-- Combinational part of the FSM
fsm_comb : process(present_state, chip_select, OPB_Select, xfer_done)
begin
    case present_state is

```

```

when ST_IDLE =>
  if chip_select = '1' then
    next_state <= ST_SELECTED;
  else
    next_state <= ST_IDLE;
  end if;

when ST_SELECTED =>
  if OPB_Select = '1' then
    next_state <= ST_WAIT;
  else
    next_state <= ST_IDLE;
  end if;

when ST_WAIT =>
  if OPB_Select = '1' then
    if ( xfer_done = '1' ) then
      next_state <= ST_XFER;
    else
      next_state <= ST_WAIT;
    end if;
  else
    next_state <= ST_IDLE;
  end if;

-- State encoding is critical here: xfer must only be true here
when ST_XFER =>
  next_state <= ST_IDLE;

when others =>
  next_state <= ST_IDLE;
end case;

end process fsm_comb;

fsm_output: process (present_state)
begin
  output_enable <= '0';
  xfer_start <= '0';
  xfer_end <= '0';
  xfer_idle <= '0';
  case present_state is
    when ST_IDLE =>
      xfer_idle <= '1';
    when ST_SELECTED =>
      xfer_start <= '1';
  end case;
end process;

```



```

when ST_WAIT =>
  --output_enable <= '1';
when ST_XFER =>
  output_enable <= '1';
  xfer_end <= '1';
when others =>
  output_enable <= '0';
  xfer_start <= '0';
  xfer_end <= '0';
  xfer_idle <= '0';
end case;
end process fsm_output;

```

```
RD_RST <= OPB_Rst or done;
```

```

process (OPB_Clk, RD_RST)
begin
  if RD_RST = '1' then
    SDRAM_RD <= '0';
  elsif OPB_Clk 'event and OPB_Clk = '1' then
    if ( chip_select = '1' and xfer_idle = '1') then
      SDRAM_RD <= OPB_RNW;
    elsif ( xfer_end = '1') then
      SDRAM_RD <= '0';
    end if;
  end if;
end process;

```

```
WR_RST <= OPB_Rst or opBegun;
```

```

process (OPB_Clk, WR_RST)
begin
  if WR_RST = '1' then
    SDRAM_WR <= '0';
  elsif OPB_Clk 'event and OPB_Clk = '1' then
    if ( chip_select = '1' and xfer_idle = '1') then
      SDRAM_WR <= not OPB_RNW;
    elsif ( xfer_end = '1') then
      SDRAM_WR <= '0';
    end if;
  end if;
end process;

```

```

process (OPB_Clk, OPB_Rst)
begin

```

```

if OPB_Rst = '1' then
    TOSUP <= '0';
elsif OPB_Clk 'event and OPB_Clk = '1' then
    if ( chip_select = '1' and xfer_idle = '1') then
        TOSUP <= '1';
    elsif ( xfer_end = '1') then
        TOSUP <= '0';
    end if;
end if;
end process;

```

```

process (OPB_Rst, OPB_Clk)
begin
    if ( OPB_Rst = '1') then
        xfer_done <= '0';
    elsif (OPB_Clk'event and OPB_Clk = '1') then
        if (timeout = '1') then
            xfer_done <= '1';
        elsif (xfer_start = '1') then
            xfer_done <= '0';
        else
            xfer_done <= xfer_done1;
        end if;
    end if;
end process;

```

```

process (done, OPB_Clk)
begin
    if ( done = '1') then
        xfer_done0 <= '1';
    elsif (OPB_Clk'event and OPB_Clk = '1') then
        if (xfer_start = '1' or xfer_idle = '1') then
            xfer_done0 <= '0';
        end if;
    end if;
end process;

```

```

process (OPB_Rst, OPB_Clk)
begin
    if ( OPB_Rst = '1') then
        xfer_done1 <= '0';
    elsif (OPB_Clk'event and OPB_Clk = '1') then
        if (xfer_start = '1' or xfer_idle = '1') then
            xfer_done1 <= '0';
        else
            xfer_done1 <= xfer_done0;
        end if;
    end if;
end process;

```

```

    end if;
  end if;
end process;

```

```

process (timeout_cnt)
begin
  if ( timeout_cnt = "111111") then
    timeout <= '1';
  else
    timeout <= '0';
  end if;
end process;

```

```

process (OPB_Clk, OPB_Rst)
begin
  if ( OPB_Rst = '1') then
    timeout_cnt <= "000000";
  elsif ( OPB_Clk 'event and OPB_Clk = '1') then
    if ( xfer_start = '1' or xfer_idle = '1' ) then
      timeout_cnt <= "000000";
    else
      timeout_cnt <= timeout_cnt + '1';
    end if;
  end if;
end process;

```

```

process (state_r )
begin
  if (state_r = RW ) then
    SDRAM_ACTIVE <= '1';
  else
    SDRAM_ACTIVE <= '0';
  end if;
end process;

```

```

-- The following assign the SDRAM output signals
--SDRAM_DO <= SDRAM_RD_DATA;

```

```

process( clk)
begin
  if ( clk'event and clk = '1') then
    if ( SDRAM_DATA_EN = '1') then
      SDRAM_RD_DATA <= hDOut& hDOut;
    end if;
  end if;
end process;

```

```

process( clk)
begin
  if ( clk'event and clk = '1') then
    done_lat <= done;
  end if;
end process;

SDRAM_DATA_EN <= not done_lat and done;

-- clk <= SDRAM_CLK;
clkibuf : IBUFG port map (
  I => SDRAM_CLK,
  O => clk
);

lock <= SDRAM_LOCK;

rst <= OPB_Rst;
hAddr <= ABus;
hDin <= SDRAM_DI(16 to 31);
sDin <= PB_DIN;

PB_DOUT <= sDOut;
PB_DOUT_EN <= sDOutEn;
PB_A <= "000000" & ba & sAddr;
PB_UB_N <= dqmh;
PB_LB_N <= dqml;
SDRAM_CKE <= cke;
SDRAM_CAS_N <= cas_n;
SDRAM_RAS_N <= ras_n;
SDRAM_CE_N <= ce_n;
SDRAM_WE_N <= we_n;

process(OPB_Rst, clk)
begin
  if ( OPB_Rst = '1') then
    wr <= '0';
  elsif ( clk'event and clk = '1') then
    if ( opBegun = '1') then
      wr <= '0';
    elsif ( SDRAM_WR = '1') then
      wr <= '1';
    end if;
  end if;
end process;

```

```

end process;

process(RD_RST, clk)
begin
  if ( RD_RST = '1') then
    rd <= '0';
  elsif ( clk'event and clk = '1') then
--    if ( OpBegun = '1') then
--      rd <= '0';
--    els
    if ( SDRAM_RD = '1') then
      rd <= '1';
    end if;
  end if;

end process;

--
*****
**
--
*****
**
--**          **
--** The following SDRAM controller is taken from XESS design      **
--**          **
--
*****
**
--
*****
**

-- Company : XESS Corp.
-- Engineer : Dave Vanden Bout
-- Creation Date : 05/17/2005
-- Copyright : 2005, XESS Corp
-- Tool Versions : WebPACK 6.3.03i
--
-- Description:
-- SDRAM controller
--
-- Revision:
-- 1.4.0
--
-- Additional Comments:

```

```

-- 1.4.0:
-- Added generic parameter to enable/disable independent active rows in each bank.
-- 1.3.0:
-- Modified to allow independently active rows in each bank.
-- 1.2.0:
-- Modified to allow pipelining of read/write operations.
-- 1.1.0:
-- Initial release.
--
-- License:
-- This code can be freely distributed and modified as long as
-- this header is not removed.
-----

-----
-- attach some internal signals to the I/O ports
-----

-- attach registered SDRAM control signals to SDRAM input pins
(ce_n, ras_n, cas_n, we_n, dqmh, dqml) <= cmd_r; -- SDRAM operation control bits
cke                <= cke_r; -- SDRAM clock enable
ba                 <= ba_r;  -- SDRAM bank address
sAddr              <= sAddr_r; -- SDRAM address
sDOut              <= sData_r; -- SDRAM output data bus
sDOutEn            <= '1' when sDataDir_r = OUTPUT else '0'; -- output
databus enable

-- attach some port signals
hDOut <= hDOut_r;      -- data back to host
opBegun <= opBegun_r; -- true if requested operation has begun

-----
-- compute the next state and outputs
-----

combinatorial : process(rd, wr, hAddr, hDIn, hDOut_r, sDIn, state_r, opBegun_x,
    activeFlag_r, activeRow_r, rdPipeline_r, wrPipeline_r,
    hDOutOppPhase_r, nopCntr_r, lock, rfshCntr_r, timer_r, rasTimer_r,
    wrTimer_r, refTimer_r, cmd_r, cke_r)

begin

-----
-- setup default values for signals
-----

```

```

opBegun_x  <= '0';          -- no operations have begun
earlyOpBegun <= opBegun_x;
cke_x      <= '1';          -- enable SDRAM clock
cmd_x      <= NOP_CMD;      -- set SDRAM command to no-operation
sDataDir_x <= INPUT;        -- accept data from the SDRAM
sData_x    <= hDIn(sData_x'range); -- output data from host to SDRAM
state_x    <= state_r;      -- reload these registers and flags
activeFlag_x <= activeFlag_r; --          with their existing values
activeRow_x <= activeRow_r;
activeBank_x <= activeBank_r;
rfshCntr_x <= rfshCntr_r;

-----

-- setup default value for the SDRAM address
-----

-- extract bank field from host address
ba_x      <= hAddr(ba'length + ROW_LEN + COL_LEN - 1 downto
ROW_LEN + COL_LEN);
if MULTIPLE_ACTIVE_ROWS = true then
  bank     <= (others => '0');
  bankIndex <= CONV_INTEGER(ba_x);
else
  bank     <= ba_x;
  bankIndex <= 0;
end if;
-- extract row, column fields from host address
row       <= hAddr(ROW_LEN + COL_LEN - 1 downto COL_LEN);
-- extend column (if needed) until it is as large as the (SDRAM address bus - 1)
col       <= (others => '0'); -- set it to all zeroes
col(COL_LEN-1 downto 0) <= hAddr(COL_LEN-1 downto 0);
-- by default, set SDRAM address to the column address with interspersed
-- command bit set to disable auto-precharge
sAddr_x   <= col(col'high-1 downto CMDBIT_POS) & AUTO_PCHG_OFF
& col(CMDBIT_POS-1 downto 0);

-----

-- manage the read and write operation pipelines
-----

-- determine if read operations are in progress by the presence of
-- READ flags in the read pipeline
if rdPipeline_r(rdPipeline_r'high downto 1) /= 0 then
  rdInProgress <= '1';
else

```

```

    rdInProgress <= '0';
end if;
rdPending    <= rdInProgress;    -- tell the host if read operations are in progress

-- enter NOPs into the read and write pipeline shift registers by default
rdPipeline_x <= NOP & rdPipeline_r(rdPipeline_r'high downto 1);
wrPipeline_x(0) <= NOP;

-- transfer data from SDRAM to the host data register if a read flag has exited the
pipeline
-- (the transfer occurs 1 cycle before we tell the host the read operation is done)
if rdPipeline_r(1) = READ then
    hDOutOppPhase_x <= sDIn(hDOut'range); -- gets value on the SDRAM databus on
the opposite phase
    if IN_PHASE then
        -- get the SDRAM data for the host directly from the SDRAM if the controller and
SDRAM are in-phase
        hDOut_x    <= sDIn(hDOut'range);
    else
        -- otherwise get the SDRAM data that was gathered on the previous opposite clock
edge
        hDOut_x    <= hDOutOppPhase_r(hDOut'range);
    end if;
else
    -- retain contents of host data registers if no data from the SDRAM has arrived yet
    hDOutOppPhase_x <= hDOutOppPhase_r;
    hDOut_x        <= hDOut_r;
end if;

done <= rdPipeline_r(0) or wrPipeline_r(0); -- a read or write operation is done
rdDone <= rdPipeline_r(0);    -- SDRAM data available when a READ flag exits
the pipeline

-----
-- manage row activation
-----

-- request a row activation operation if the row of the current address
-- does not match the currently active row in the bank, or if no row
-- in the bank is currently active
if (bank /= activeBank_r) or (row /= activeRow_r(bankIndex)) or
(activeFlag_r(bankIndex) = '0') then
    doActivate <= '1';
else
    doActivate <= '0';
end if;

```



```

-----
-- manage self-refresh
-----

-- enter self-refresh if neither a read or write is requested for MAX_NOP consecutive
cycles.
if (rd = '1') or (wr = '1') then
  -- any read or write resets NOP counter and exits self-refresh state
  nopCntr_x <= 0;
  doSelfRfsh <= '0';
elsif nopCntr_r /= MAX_NOP then
  -- increment NOP counter whenever there is no read or write operation
  nopCntr_x <= nopCntr_r + 1;
  doSelfRfsh <= '0';
else
  -- start self-refresh when counter hits maximum NOP count and leave counter
unchanged
  nopCntr_x <= nopCntr_r;
  doSelfRfsh <= '1';
end if;

-----

-- update the timers
-----

-- row activation timer
if rasTimer_r /= 0 then
  -- decrement a non-zero timer and set the flag
  -- to indicate the row activation is still inprogress
  rasTimer_x <= rasTimer_r - 1;
  activateInProgress <= '1';
else
  -- on timeout, keep the timer at zero and reset the flag
  -- to indicate the row activation operation is done
  rasTimer_x <= rasTimer_r;
  activateInProgress <= '0';
end if;

-- write operation timer
if wrTimer_r /= 0 then
  -- decrement a non-zero timer and set the flag
  -- to indicate the write operation is still inprogress
  wrTimer_x <= wrTimer_r - 1;
  wrInPRogress <= '1';
else

```

```

-- on timeout, keep the timer at zero and reset the flag that
-- indicates a write operation is in progress
wrTimer_x <= wrTimer_r;
wrInPRogress <= '0';
end if;

-- refresh timer
if refTimer_r /= 0 then
  refTimer_x <= refTimer_r - 1;
else
  -- on timeout, reload the timer with the interval between row refreshes
  -- and increment the counter for the number of row refreshes that are needed
  refTimer_x <= REF_CYCLES;
  rfshCntr_x <= rfshCntr_r + 1;
end if;

-- main timer for sequencing SDRAM operations
if timer_r /= 0 then
  -- decrement the timer and do nothing else since the previous operation has not
  -- completed yet.
  timer_x <= timer_r - 1;
  status <= "0000";
else
  -- the previous operation has completed once the timer hits zero
  timer_x <= timer_r;      -- by default, leave the timer at zero

-----
-- compute the next state and outputs
-----
case state_r is

-----
  -- let clock stabilize and then wait for the SDRAM to initialize
-----
  when INITWAIT =>
    if lock = '1' then
      -- wait for SDRAM power-on initialization once the clock is
stable
      timer_x <= INIT_CYCLES;  -- set timer for initialization duration
      state_x <= INITPCHG;
    else
      -- disable SDRAM clock and return to this state if the clock is
not stable

      -- this insures the clock is stable before enabling the SDRAM
      -- it also insures a clean startup if the SDRAM is currently in
self-refresh mode

```

```

    cke_x <= '0';
end if;
status <= "0001";

-----
-- precharge all SDRAM banks after power-on initialization
-----
when INITPCHG =>
    cmd_x      <= PCHG_CMD;
    sAddr_x(CMDBIT_POS) <= ALL_BANKS; -- precharge all banks
    timer_x    <= RP_CYCLES; -- set timer for precharge operation duration
    rfsnCntr_x <= RFSH_OPS; -- set counter for refresh ops needed after
precharge
    state_x    <= INITRFSH;
    status     <= "0010";

-----
-- refresh the SDRAM a number of times after initial precharge
-----
when INITRFSH =>
    cmd_x      <= RFSH_CMD;
    timer_x    <= RFC_CYCLES; -- set timer to refresh operation duration
    rfsnCntr_x <= rfsnCntr_r - 1; -- decrement refresh operation counter
    if rfsnCntr_r = 1 then
        state_x <= INITSETMODE; -- set the SDRAM mode once all refresh ops are
done
    end if;
    status     <= "0011";

-----
-- set the mode register of the SDRAM
-----
when INITSETMODE =>
    cmd_x <= MODE_CMD;
    sAddr_x <= MODE; -- output mode register bits on the SDRAM address
bits
    timer_x <= MODE_CYCLES; -- set timer for mode setting operation duration
    state_x <= RW;
    status <= "0100";

-----
-- process read/write/refresh operations after initialization is done
-----
when RW =>
-----
-- highest priority operation: row refresh

```

```

-- do a refresh operation if the refresh counter is non-zero
-----
if rfshCntr_r /= 0 then
    -- wait for any row activations, writes or reads to finish before
doing a precharge
    if (activateInProgress = '0') and (wrInProgress = '0') and (rdInProgress = '0') then
        cmd_x          <= PCHG_CMD; -- initiate precharge of the SDRAM
        sAddr_x(CMDBIT_POS) <= ALL_BANKS; -- precharge all banks
        timer_x        <= RP_CYCLES; -- set timer for this operation
        activeFlag_x   <= (others => '0'); -- all rows are inactive after a
precharge operation
        state_x        <= REFRESHROW; -- refresh the SDRAM after the
precharge
    end if;
    status             <= "0101";
    -----
    -- do a host-initiated read operation
    -----
    elsif rd = '1' then
        -- Wait one clock cycle if the bank address has just
changed and each bank has its own active row.
        -- This gives extra time for the row activation circuitry.
        if (ba_x = ba_r) or (MULTIPLE_ACTIVE_ROWS=false) then
            -- activate a new row if the current read is outside the active row
or bank
            if doActivate = '1' then
                -- activate new row only if all previous activations, writes, reads
are done
                if (activateInProgress = '0') and (wrInProgress = '0') and (rdInProgress = '0')
then
                    cmd_x          <= PCHG_CMD; -- initiate precharge of the SDRAM
                    sAddr_x(CMDBIT_POS) <= ONE_BANK; -- precharge this bank
                    timer_x        <= RP_CYCLES; -- set timer for this operation
                    activeFlag_x(bankIndex) <= '0'; -- rows in this bank are inactive after a
precharge operation
                    state_x        <= ACTIVATE; -- activate the new row after the precharge
is done
                end if;
                -- read from the currently active row if no previous read
operation
                -- is in progress or if pipeline reads are enabled
                -- we can always initiate a read even if a write is already in
progress
            elsif (rdInProgress = '0') or PIPE_EN then
                cmd_x          <= READ_CMD; -- initiate a read of the SDRAM

```

```

end                                     -- insert a flag into the pipeline shift register that will exit the
available
    rdPipeline_x           <= READ & rdPipeline_r(rdPipeline_r'high downto 1);
    opBegun_x             <= '1'; -- tell the host the requested operation has begun
    end if;
    end if;
    status                 <= "0110";
    -----
    -- do a host-initiated write operation
    -----
    elsif wr = '1' then
        -- Wait one clock cycle if the bank address has just
        changed and each bank has its own active row.
        -- This gives extra time for the row activation circuitry.
        if (ba_x = ba_r) or (MULTIPLE_ACTIVE_ROWS=false) then
            -- activate a new row if the current write is outside the active
            row or bank
            if doActivate = '1' then
                -- activate new row only if all previous activations, writes, reads
                are done
                if (activateInProgress = '0') and (wrInProgress = '0') and (rdInProgress = '0')
                then
                    cmd_x           <= PCHG_CMD; -- initiate precharge of the SDRAM
                    sAddr_x(CMDBIT_POS) <= ONE_BANK; -- precharge this bank
                    timer_x         <= RP_CYCLES; -- set timer for this operation
                    activeFlag_x(bankIndex) <= '0'; -- rows in this bank are inactive after a
                    precharge operation
                    state_x         <= ACTIVATE; -- activate the new row after the precharge
                    is done
                    end if;
                    -- write to the currently active row if no previous read operations
                    are in progress
                    elsif rdInProgress = '0' then
                        cmd_x           <= WRITE_CMD; -- initiate the write operation
                        sDataDir_x     <= OUTPUT; -- turn on drivers to send data to SDRAM
                        -- set timer so precharge doesn't occur too soon after write
                        operation
                        wrTimer_x     <= WR_CYCLES;
                        -- insert a flag into the 1-bit pipeline shift register that will exit
                        on the
                        -- next cycle. The write into SDRAM is not actually done by
                        that time, but
                        -- this doesn't matter to the host
                        wrPipeline_x(0) <= WRITE;

```

```

        opBegun_x          <= '1'; -- tell the host the requested operation has begun
    end if;
end if;
status          <= "0111";
-----
-- do a host-initiated self-refresh operation
-----
elsif doSelfRfsh = '1' then
    -- wait until all previous activations, writes, reads are done
    if (activateInProgress = '0') and (wrInProgress = '0') and (rdInProgress = '0') then
        cmd_x          <= PCHG_CMD; -- initiate precharge of the SDRAM
        sAddr_x(CMDBIT_POS) <= ALL_BANKS; -- precharge all banks
        timer_x        <= RP_CYCLES; -- set timer for this operation
        activeFlag_x   <= (others => '0'); -- all rows are inactive after a
precharge operation
        state_x        <= SELFREFRESH; -- self-refresh the SDRAM after the
precharge
    end if;
    status          <= "1000";
    -----
    -- no operation
    -----
else
    state_x          <= RW; -- continue to look for SDRAM operations to
execute
    status          <= "1001";
end if;

-----
-- activate a row of the SDRAM
-----
when ACTIVATE          =>
    cmd_x          <= ACTIVE_CMD;
    sAddr_x        <= (others => '0'); -- output the address for the row to be
activated
    sAddr_x(row'range) <= row;
    activeBank_x    <= bank;
    activeRow_x(bankIndex) <= row; -- store the new active SDRAM row address
    activeFlag_x(bankIndex) <= '1'; -- the SDRAM is now active
    rasTimer_x     <= RAS_CYCLES; -- minimum time before another
precharge can occur
    timer_x        <= RCD_CYCLES; -- minimum time before a read/write
operation can occur
    state_x        <= RW; -- return to do read/write operation that initiated this
activation
    status          <= "1010";

```

```

-----
-- refresh a row of the SDRAM
-----

when REFRESHROW =>
  cmd_x   <= RFSH_CMD;
  timer_x <= RFC_CYCLES; -- refresh operation interval
  rfshCntr_x <= rfshCntr_r - 1; -- decrement the number of needed row refreshes
  state_x  <= RW;        -- process more SDRAM operations after refresh is done
  status   <= "1011";

-----

-- place the SDRAM into self-refresh and keep it there until further notice
-----

when SELFREFRESH      =>
  if (doSelfRfsh = '1') or (lock = '0') then
    -- keep the SDRAM in self-refresh mode as long as requested
    and until there is a stable clock
      cmd_x   <= RFSH_CMD; -- output the refresh command; this is only needed
on the first clock cycle
      cke_x   <= '0';     -- disable the SDRAM clock
    else
      -- else exit self-refresh mode and start processing read and write
operations
      cke_x   <= '1';     -- restart the SDRAM clock
      rfshCntr_x <= 0;    -- no refreshes are needed immediately after leaving self-
refresh
      activeFlag_x <= (others => '0'); -- self-refresh deactivates all rows
      timer_x   <= XSR_CYCLES; -- wait this long until read and write operations
can resume
      state_x   <= RW;
    end if;
    status     <= "1100";

-----

-- unknown state
-----

when others =>
  state_x <= INITWAIT; -- reset state if in erroneous state
  status <= "1101";

end case;
end if;
end process combinatorial;

```

-----  
-- update registers on the appropriate clock edge  
-----

```
update : process(rst, clk)
begin
    if rst = '1' then
        -- asynchronous reset
        state_r    <= INITWAIT;
        activeFlag_r <= (others => '0');
        rfshCntr_r <= 0;
        timer_r    <= 0;
        refTimer_r <= REF_CYCLES;
        rasTimer_r <= 0;
        wrTimer_r  <= 0;
        nopCntr_r  <= 0;
        opBegun_r  <= '0';
        rdPipeline_r <= (others => '0');
        wrPipeline_r <= (others => '0');
        cke_r      <= '0';
        cmd_r      <= NOP_CMD;
        ba_r       <= (others => '0');
        sAddr_r    <= (others => '0');
        sData_r    <= (others => '0');
        sDataDir_r <= INPUT;
        hDOut_r    <= (others => '0');
    elsif rising_edge(clk) then
        state_r    <= state_x;
        activeBank_r <= activeBank_x;
        activeRow_r <= activeRow_x;
        activeFlag_r <= activeFlag_x;
        rfshCntr_r <= rfshCntr_x;
        timer_r    <= timer_x;
        refTimer_r <= refTimer_x;
        rasTimer_r <= rasTimer_x;
        wrTimer_r  <= wrTimer_x;
        nopCntr_r  <= nopCntr_x;
        opBegun_r  <= opBegun_x;
        rdPipeline_r <= rdPipeline_x;
        wrPipeline_r <= wrPipeline_x;
        cke_r      <= cke_x;
        cmd_r      <= cmd_x;
        ba_r       <= ba_x;
        sAddr_r    <= sAddr_x;
        sData_r    <= sData_x;
```



```

    sDataDir_r <= sDataDir_x;
    hDOut_r    <= hDOut_x;
end if;

-- the register that gets data from the SDRAM and holds it for the host
-- is clocked on the opposite edge. We don't use this register if IN_PHASE=TRUE.
if rst = '1' then
    hDOutOppPhase_r <= (others => '0');
elsif falling_edge(clk) then
    hDOutOppPhase_r <= hDOutOppPhase_x;
end if;

end process update;

end Behavioral;

```

### 4.3.5 opb\_Ethernet.vhd

```

-----
--
-----

library IEEE;
use IEEE.STD_LOGIC_1164.ALL;
use IEEE.STD_LOGIC_ARITH.ALL;
use IEEE.STD_LOGIC_UNSIGNED.ALL;

entity opb_ethernet is
    generic (
        C_OPB_AWIDTH : integer          := 32;
        C_OPB_DWIDTH : integer          := 32;
        C_BASEADDR   : std_logic_vector(0 to 31) := X"00800000";
        C_HIGHADDR   : std_logic_vector(0 to 31) := X"00FFFFFF");

    port (
        OPB_Clk   : in  std_logic;
        OPB_Rst   : in  std_logic;
        OPB_ABus  : in  std_logic_vector(0 to C_OPB_AWIDTH-1);
        OPB_BE    : in  std_logic_vector(0 to C_OPB_DWIDTH/8-1);
        OPB_DBus  : in  std_logic_vector(0 to C_OPB_DWIDTH-1);
        OPB_RNW   : in  std_logic;
        OPB_select : in  std_logic;
        OPB_seqAddr : in  std_logic;    -- Sequential Address
        Sln_DBus  : out std_logic_vector(0 to C_OPB_DWIDTH-1);
        Sln_errAck : out std_logic;    -- (unused)
        Sln_retry  : out std_logic;    -- (unused)
    );
end entity opb_ethernet;

```

```

Sln_toutSup : out std_logic;    -- Timeout suppress
Sln_xferAck : out std_logic;    -- Transfer acknowledge

PB_DIN  : in std_logic_vector(0 to 15);    -- ETHER data bus
PB_DOUT : out std_logic_vector(0 to 15);    -- ETHER data bus output
PB_DOUT_EN : out std_logic;                -- ETHER data bus output enable
PB_A : out std_logic_vector (0 to 19);
IORD_N : out std_logic;
IOWR_N : out std_logic;
AEN : out std_logic;
BHE_N : out std_logic;
ETHERNET_CS_N : out std_logic;
ETHERNET_RDY : in std_logic;
ETHERNET_IREQ : in std_logic;
ETHERNET_IOCS16_N : in std_logic
    );
end opb_ethernet;

```

architecture Behavioral of opb\_ethernet is

```

constant ETHER_AWIDTH : integer := 10; -- Number of address lines on the ETHER
constant ETHER_DWIDTH : integer := 16; -- Number of data lines on the ETHER

```

```

signal RNW : std_logic;
signal ETHER_DI: std_logic_vector(0 to 31);
signal ABus : std_logic_vector(0 to ETHER_AWIDTH-1);
signal chip_select : std_logic;
signal output_enable : std_logic;
signal TE : std_logic;
signal BE : std_logic_vector(0 to 3);
signal A30: std_logic;
signal ETHER_RD_DATA : std_logic_vector (0 to 31);
signal ETHER_WR_DATA : std_logic_vector (0 to 31);

signal CE : std_logic;    -- ETHER chip enable
signal OE : std_logic;    -- ETHER output enable
signal xfer_start: std_logic; -- Transfer start
signal xfer_end: std_logic;  -- Transfer end
signal xfer_idle: std_logic;  -- No transfer pending
signal obuf_oe: std_logic;    -- Data output buffer enable
signal xfer_done: std_logic;  -- Transfer has been done
signal data_latch: std_logic;

```

```

-- Critical: Sln_xferAck is generated directly from state bit 0!
constant STATE_BITS : integer := 3;

```

```

constant ST_IDLE    : std_logic_vector(0 to STATE_BITS-1) := "000";
constant ST_SELECTED : std_logic_vector(0 to STATE_BITS-1) := "001";
constant ST_WAIT    : std_logic_vector(0 to STATE_BITS-1) := "011";
constant ST_XFER    : std_logic_vector(0 to STATE_BITS-1) := "111";
constant ST_WAIT1   : std_logic_vector(0 to STATE_BITS-1) := "100";
constant ST_WAIT2   : std_logic_vector(0 to STATE_BITS-1) := "101";

signal present_state, next_state : std_logic_vector(0 to STATE_BITS-1);

begin

register_opb_inputs: process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    ETHER_DI <= (others => '0');
    ABus <= (others => '0');
    RNW <= '0';
    A30 <= '0';
    BE <= (others => '0');
  elsif OPB_Clk'event and OPB_Clk = '1' then
    ETHER_DI <= OPB_DBus(0 to C_OPB_DWIDTH-1);
    ABus <= OPB_ABus(C_OPB_AWIDTH-2-(ETHER_AWIDTH-1) to
C_OPB_AWIDTH-2);
    RNW <= OPB_RNW;
    A30 <= OPB_ABus(30);
    BE <= OPB_BE(0 to 3);
  end if;
end process register_opb_inputs;

register_opb_outputs: process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    SIn_DBus <= (others => '0');
  elsif OPB_Clk'event and OPB_Clk = '1' then
--   if ( output_enable = '1' and RNW = '1') then
    if ( output_enable = '1') then
      SIn_DBus <= ETHER_RD_DATA;
    else
      SIn_DBus <= (others => '0');
    end if;
  end if;
end process register_opb_outputs;

-- Unused outputs
SIn_errAck <= '0';
SIn_retry  <= '0';

```

```

Sln_toutSup <= '0';
--Sln_DBus(ETHER_DWIDTH to C_OPB_DWIDTH-1) <= (others => '0');

chip_select <=
  '1' when OPB_select = '1' and
    OPB_ABus(0 to C_OPB_AWIDTH-2-ETHER_AWIDTH) =
    C_BASEADDR(0 to C_OPB_AWIDTH-2-ETHER_AWIDTH) else
  '0';

Sln_xferAck <= xfer_done;

-- Sequential part of the FSM
fsm_seq : process(OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    present_state <= ST_IDLE;
  elsif OPB_Clk'event and OPB_Clk = '1' then
    present_state <= next_state;
  end if;
end process fsm_seq;

-- Combinational part of the FSM
fsm_comb : process(present_state, chip_select, OPB_Select)
begin
  case present_state is
    when ST_IDLE =>
      if chip_select = '1' then
        next_state <= ST_SELECTED;
      else
        next_state <= ST_IDLE;
      end if;

    when ST_SELECTED =>
      if OPB_Select = '1' then
        next_state <= ST_WAIT;
      else
        next_state <= ST_IDLE;
      end if;

    when ST_WAIT =>
      if OPB_Select = '1' then
        next_state <= ST_WAIT1;
      else
        next_state <= ST_IDLE;
      end if;
    when ST_WAIT1 =>

```

```

    if OPB_Select = '1' then
        next_state <= ST_WAIT2;
    else
        next_state <= ST_IDLE;
    end if;
when ST_WAIT2 =>
    if OPB_Select = '1' then
        next_state <= ST_XFER;
    else
        next_state <= ST_IDLE;
    end if;

-- State encoding is critical here: xfer must only be true here
when ST_XFER =>
    next_state <= ST_IDLE;

    when others =>
        next_state <= ST_IDLE;
end case;

end process fsm_comb;

fsm_output: process (present_state)
begin
    output_enable <= '0';
    xfer_start <= '0';
    xfer_end <= '0';
    xfer_idle <= '0';
    xfer_done <= '0';
    case present_state is
        when ST_IDLE =>
            xfer_idle <= '1';
        when ST_SELECTED =>
            xfer_start <= '1';
        when ST_WAIT2 =>
            output_enable <= '1';
        when ST_XFER =>
            xfer_end <= '1';
            xfer_done <= '1';
        when others =>
            output_enable <= '0';
            xfer_start <= '0';
            xfer_end <= '0';
            xfer_idle <= '0';
    end case;
end process fsm_output;

```

```

-- The following process generates the OE output signal
ether_oe_reg: process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    OE <= '1';
  elsif OPB_Clk 'event and OPB_Clk = '1' then
    if ( chip_select = '1' and xfer_idle = '1') then
      OE <= not OPB_RNW;
    elsif ( xfer_end = '1') then
      OE <= '1';
    end if;
  end if;
end process ether_oe_reg;

-- The following process generates the chip enable output signal
ether_ce_reg: process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    CE <= '1';
  elsif OPB_Clk 'event and OPB_Clk = '1' then
    if ( chip_select = '1' and xfer_idle = '1') then
      CE <= '0';
    elsif ( xfer_end = '1') then
      CE <= '1';
    end if;
  end if;
end process ether_ce_reg;

-- The following process generates the TE output signal
ether_we_reg: process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    TE <= '1';
  elsif OPB_Clk 'event and OPB_Clk = '1' then
    if ( xfer_start = '1') then
      TE <= '0';
    elsif (output_enable = '1') then
      TE <= '1';
    end if;
  end if;
end process ether_we_reg;

--

ETHER_RD_DATA <= PB_DIN & PB_DIN;

```

```

-- ETHER_WR_DATA <= ETHER_DI;
process ( ETHER_DI, A30)
begin
  if ( A30 = '1') then
    ETHER_WR_DATA (16 to 31) <= ETHER_DI(16 to 31);
  else
    ETHER_WR_DATA (16 to 31) <= ETHER_DI(0 to 15);
  end if;
end process;

```

```

IORD_N <= OE;

```

```

-- The following assign the output signals
process ( RNW, TE)
begin
  if ( RNW = '1') then
--    IORD_N <= TE;
    IOWR_N <= '1';
  else
--    IORD_N <= '1';
    IOWR_N <= TE;
  end if;
end process;

```

```

-- process ( BE )
-- begin
--   if ( BE = "1100" or BE = "0011" ) then
--     BHE_N <= '0';
--   else
--     BHE_N <= '1';
--   end if;
-- end process;

```

```

BHE_N <= CE;

```

```

ETHERNET_CS_N <= CE;
AEN <= CE;
PB_A <= "0000000000" & ABus;
PB_DOUT <= ETHER_WR_DATA(16 to 31);
PB_DOUT_EN <= (not CE) and OE;

```

```

end Behavioral;

```

### 4.3.6 opb\_audio\_controller.vhd

```
-----  
--  
-- Audio Controller OPB Peripheral  
--  
--  
-----  
  
library ieee;  
use ieee.std_logic_1164.all;  
use ieee.std_logic_unsigned.all;  
  
entity opb_audio_controller is  
  
    generic (  
        C_OPB_AWIDTH : integer           := 32;  
        C_OPB_DWIDTH : integer           := 32;  
        C_BASEADDR   : std_logic_vector(0 to 31) := X"FEFF0400";  
        C_HIGHADDR   : std_logic_vector(0 to 31) := X"FEFF04FF");  
  
    port (  
        -- OPB Input Signals  
        OPB_Clk   : in std_logic;  
        OPB_Rst   : in std_logic;  
        OPB_ABus  : in std_logic_vector(0 to C_OPB_AWIDTH-1);  
        OPB_BE    : in std_logic_vector(0 to C_OPB_DWIDTH/8-1);  
        OPB_DBus  : in std_logic_vector(0 to C_OPB_DWIDTH-1);  
        OPB_RNW   : in std_logic;  
        OPB_select : in std_logic;  
        OPB_seqAddr : in std_logic;    -- Sequential Address  
  
        -- OPB Output Signals  
        Sln_DBus   : out std_logic_vector(0 to C_OPB_DWIDTH-1);  
        Sln_errAck : out std_logic;    -- (unused)  
        Sln_retry  : out std_logic;    -- (unused)  
        Sln_toutSup : out std_logic;    -- Timeout suppress  
        Sln_xferAck : out std_logic;    -- Transfer acknowledge  
  
        -- Audio IO Signals  
        AU_BUSY    : out std_logic;    -- Audio interface busy  
        AU_CSN     : out std_logic;    -- Audio Chip Select  
        AU_CCLK    : out std_logic;    -- Audio Cntl Clock  
        AU_CDTI    : out std_logic;    -- Audio Cntl Data In  
        PB_DIN     : in std_logic_vector(0 to 15)  
        --AU_CDTO   : in std_logic      -- Audio Cntl Data Out
```



```
);  
end opb_audio_controller;
```

architecture behavioral of opb\_audio\_controller is

```
signal AU_CDTO: std_logic;  
signal Command : std_logic_vector(0 to 15);  
signal Status: std_logic_vector (0 to 7);  
signal Busy : std_logic;  
signal SetBusy : std_logic;  
signal RNW : std_logic;  
signal CmdLoad: std_logic;  
signal chip_select : std_logic;  
signal output_enable : std_logic;  
signal audio_done: std_logic;  
signal shift_enable: std_logic;  
signal capture_enable: std_logic;  
signal shift_mode: std_logic;  
signal rising: std_logic;  
signal falling: std_logic;  
signal clear: std_logic;  
signal cs_setup: std_logic;  
signal cs_hold: std_logic;  
signal baud_counter: std_logic_vector ( 0 to 3 );  
signal bit_counter: std_logic_vector (0 to 3);  
signal bit_counter_ov: std_logic;  
  
constant ST_AU_IDLE: std_logic_vector( 0 to 2) := "000";  
constant ST_AU_START: std_logic_vector( 0 to 2) := "001";  
constant ST_AU_SETUP: std_logic_vector( 0 to 2) := "010";  
constant ST_AU_SHIFT: std_logic_vector( 0 to 2) := "011";  
constant ST_AU_END: std_logic_vector( 0 to 2) := "100";  
constant ST_AU_HOLD: std_logic_vector( 0 to 2) := "101";  
signal au_current_state, au_next_state : std_logic_vector (0 to 2);  
  
signal xfer_start: std_logic; -- Transfer start  
signal xfer_end: std_logic; -- Transfer end  
signal xfer_idle: std_logic; -- No transfer pending  
signal obuf_oe: std_logic; -- Data output buffer enable  
signal xfer_done: std_logic; -- Transfer has been done  
  
-- Critical: SIn_xferAck is generated directly from state bit 0!  
constant STATE_BITS : integer := 3;  
constant ST_IDLE : std_logic_vector(0 to STATE_BITS-1) := "000";  
constant ST_SELECTED : std_logic_vector(0 to STATE_BITS-1) := "001";
```

```

constant ST_WAIT    : std_logic_vector(0 to STATE_BITS-1) := "011";
constant ST_XFER    : std_logic_vector(0 to STATE_BITS-1) := "111";

signal present_state, next_state : std_logic_vector(0 to STATE_BITS-1);

begin

-----
-- OPB interface
-----

register_opb_inputs: process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    SetBusy <= '0';
    RNW <= '0';
  elsif OPB_Clk'event and OPB_Clk = '1' then
    SetBusy <= OPB_DBus(0);
    RNW <= OPB_RNW;
  end if;
end process register_opb_inputs;

register_opb_outputs: process (OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    SIn_DBus <= (others => '0');
  elsif OPB_Clk'event and OPB_Clk = '1' then
    if (output_enable = '1' and RNW = '1') then
      SIn_DBus <= Busy & "0000000" & Status & "00000000000000000000";
    else
      SIn_DBus <= (others => '0');
    end if;
  end if;
end process register_opb_outputs;

-- Unused outputs
SIn_errAck <= '0';
SIn_retry  <= '0';
SIn_toutSup <= '0';

chip_select <=
  '1' when OPB_select = '1' and
    OPB_ABus(0 to C_OPB_AWIDTH-1) = C_BASEADDR(0 to C_OPB_AWIDTH-1)
else
  '0';

SIn_xferAck <= present_state(0);

```

```

-- Sequential part of the FSM
fsm_seq : process(OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    present_state <= ST_IDLE;
  elsif OPB_Clk'event and OPB_Clk = '1' then
    present_state <= next_state;
  end if;
end process fsm_seq;

-- Combinational part of the FSM
fsm_comb : process(present_state, chip_select, OPB_Select)
begin
  case present_state is
    when ST_IDLE =>
      if chip_select = '1' then
        next_state <= ST_SELECTED;
      else
        next_state <= ST_IDLE;
      end if;
    when ST_SELECTED =>
      if OPB_Select = '1' then
        next_state <= ST_WAIT;
      else
        next_state <= ST_IDLE;
      end if;
    when ST_WAIT =>
      if OPB_Select = '1' then
        next_state <= ST_XFER;
      else
        next_state <= ST_IDLE;
      end if;
    -- State encoding is critical here: xfer must only be true here
    when ST_XFER =>
      next_state <= ST_IDLE;
    when others =>
      next_state <= ST_IDLE;
  end case;

end process fsm_comb;

process (present_state)
begin
  if ( present_state = ST_WAIT) then
    output_enable <= '1';
  end if;
end process;

```

```

else
    output_enable <= '0';
end if;
end process;

-----
-- Audio interface
-----

AU_CDTO <= PB_DIN (13); -- PB_D2

process (present_state , SetBusy)
begin
    if ( present_state = ST_WAIT and SetBusy = '1' and RNW = '0' ) then
        CmdLoad <= '1';
    else
        CmdLoad <= '0';
    end if;
end process;

-- Audio controller is busy shifting out the command
-- Must be assigned the PH bus at this time
process (OPB_Clk, OPB_Rst)
begin
    if OPB_Rst = '1' then
        Busy <= '0';
    elsif OPB_Clk 'event and OPB_Clk = '1' then
        if ( CmdLoad = '1' ) then
            Busy <= '1';
        elsif (audio_done = '1') then
            Busy <= '0';
        end if;
    end if;
end process;
AU_BUSY <= Busy;

-- Audio command register
process (OPB_Clk, OPB_Rst)
begin
    if OPB_Rst = '1' then
        Command <= (others => '0');
    elsif OPB_Clk 'event and OPB_Clk = '1' then
        if ( CmdLoad = '1' ) then
            Command <= OPB_DBus(16 to 31);
        elsif (shift_enable = '1') then
            Command <= Command( 1 to 15) & '0';
        end if;
    end if;
end process;

```

```

        end if;
    end if;
end process;

-- Audio controll data output
AU_CDTI <= Command (0);

-- Audio read back data
process (OPB_Clk, OPB_Rst)
begin
    if OPB_Rst = '1' then
        Status <= (others => '0');
    elsif OPB_Clk 'event and OPB_Clk = '1' then
        if (capture_enable = '1') then
            Status <= AU_CDTO & Status( 0 to 6) ;
        end if;
    end if;
end process;

-- Counter for the CCLK divider
-- 50MHz / 16
process (OPB_Clk, OPB_Rst)
begin
    if ( OPB_Rst = '1') then
        baud_counter <= "0000";
    elsif ( OPB_Clk 'event and OPB_Clk = '1') then
        if (clear = '1') then
            baud_counter <= "0000";
        else
            baud_counter <= baud_counter + '1';
        end if;
    end if;
end process;

-- Detect the time for the CCLK rising and falling
process ( baud_counter )
begin
    if ( baud_counter = "0111" ) then
        rising <= '1';
    else
        rising <= '0';
    end if;

    if ( baud_counter = "1111" ) then
        falling <= '1';
    else

```

```

        falling <= '0';
    end if;

end process;

-- Audio controller serial shift bit counter
process ( OPB_Clk, OPB_Rst)
begin
    if (OPB_Rst = '1' ) then
        bit_counter <= "0000";
    elsif ( OPB_Clk 'event and OPB_Clk = '1') then
        if ( clear = '1' or cs_setup = '1' ) then
            bit_counter <= "0000";
        elsif (falling = '1') then
            bit_counter <= bit_counter + '1';
        end if;
    end if;
end process;

process (bit_counter )
begin
    if ( bit_counter = "1111") then
        bit_counter_ov <= '1';
    else
        bit_counter_ov <= '0';
    end if;
end process;

-- Data output shift enable
shift_enable <= shift_mode and falling;

-- Data input shift enable
capture_enable <= shift_mode and rising;

-- Audio controller state machine
process ( OPB_Clk, OPB_Rst)
begin
    if ( OPB_Rst = '1') then
        au_current_state <= ST_AU_IDLE;
    elsif (OPB_Clk 'event and OPB_Clk = '1') then
        au_current_state <= au_next_state;
    end if;
end process;

-- Audio controller next state logic
process ( au_current_state, CmdLoad, rising, bit_counter_ov)

```

```

begin
  case au_current_state is
    when ST_AU_IDLE =>
      if ( CmdLoad = '1') then
        au_next_state <= ST_AU_START;
      else
        au_next_state <= ST_AU_IDLE;
      end if;
    when ST_AU_START =>
      if ( rising = '1' ) then
        au_next_state <= ST_AU_SETUP;
      else
        au_next_state <= ST_AU_START;
      end if;
    when ST_AU_SETUP =>
      if ( rising = '1' ) then
        au_next_state <= ST_AU_SHIFT;
      else
        au_next_state <= ST_AU_SETUP;
      end if;
    when ST_AU_SHIFT =>
      if ( rising = '1' and bit_counter_ov = '1') then
        au_next_state <= ST_AU_HOLD;
      else
        au_next_state <= ST_AU_SHIFT;
      end if;
    when ST_AU_HOLD =>
      if ( rising = '1' ) then
        au_next_state <= ST_AU_END;
      else
        au_next_state <= ST_AU_HOLD;
      end if;
    when ST_AU_END =>
      au_next_state <= ST_AU_IDLE;
    when others =>
      au_next_state <= ST_AU_IDLE;
  end case;

end process;

-- Audio controller control signal decode from state machine
process ( au_current_state, rising, bit_counter_ov)
begin
  shift_mode <= '0';
  clear <= '0';
  cs_setup <= '0';

```

```

cs_hold <= '0';
audio_done <= '0';
case au_current_state is
  when ST_AU_IDLE =>
    shift_mode <= '0';
    clear <= '1';
    cs_setup <= '0';
    audio_done <= '0';
  when ST_AU_SETUP =>
    cs_setup <= '1';
  when ST_AU_SHIFT =>
    shift_mode <= '1';
  when ST_AU_HOLD =>
    cs_hold <= '1';
  when ST_AU_END =>
    audio_done <= '1';
  when others =>
    shift_mode <= '0';
    clear <= '0';
    cs_setup <= '0';
    audio_done <= '0';
    cs_hold <= '0';
end case;
end process;

process ( OPB_Clk, OPB_Rst)
begin
  if ( OPB_Rst = '1') then
    AU_CSN <= '1';
  elsif (OPB_Clk 'event and OPB_Clk = '1') then
    if ( clear = '1' or audio_done = '1') then
      AU_CSN <= '1';
    elsif ( cs_setup = '1' ) then
      AU_CSN <= '0';
    end if ;
  end if;
end process;

process ( OPB_Clk, OPB_Rst)
begin
  if ( OPB_Rst = '1') then
    AU_CCLK <= '1';
  elsif (OPB_Clk 'event and OPB_Clk = '1') then
    if ( clear = '1' or cs_hold = '1' or rising = '1') then
      AU_CCLK <= '1';
    elsif ( falling = '1' and cs_hold = '0' ) then

```



```

        AU_CCLK <= '0';
    end if ;
end if;
end process;

```

```

end behavioral;

```

### 4.3.7 opb\_audio\_sampler.vhd

```

-----
-- CSEE 4840 Embedded System Design - Audio Sampling OPB Peripheral
--
-- SOBA Server
--
-- Team Warriors: Avraham Shinnar as1619@columbia.edu
-- Benjamin Dweck bjd2102@columbia.edu
-- Oliver Irwin omi3@columbia.edu
-- Sean White sw2061@columbia.edu
--
-----

```

```

-----
-- Use clock enable instead of C to do the latch_32
-- Xilinx generates global clock buffer for the C as clock
-- Which caused abused global clock buffer over flow
-- "Number of GCLKs:          5 out of  4 125% (OVERMAPPED)"
-- 04/11/06
-----

```

```

-----
--
-- 32-bit Positive Edge Triggered Left Shift Register
-- with Serial In and Parallel Out
--
-- Used to receive samples serially from the audio codec
-----

```

```

library ieee;
use ieee.std_logic_1164.all;

```

```

entity shift_32 is
port(
    SI : in std_logic;
    CK: in std_logic;
    C  : in std_logic;
    D  : out std_logic_vector(31 downto 0)

```

```
);  
end shift_32;
```

architecture arch of shift\_32 is

```
    signal tmp : std_logic_vector(31 downto 0);  
    signal EN, C_L : std_logic;
```

```
begin  
    -- Add clock to generate a enable signal for the latch  
    process (CK)  
    begin  
        if (CK 'event and CK = '1') then  
            C_L <= C;  
        end if;  
    end process;  
    EN <= not C_L and C;
```

```
    process (CK)  
    begin  
        if CK'event and CK='1' then  
            if ( EN = '1') then  
                tmp <= tmp(30 downto 0) & SI;  
            end if;  
        end if;  
    end process;
```

```
    D <= tmp;
```

```
end arch;
```

```
-----  
--  
-- 32-bit Positive Edge Triggered Latch  
-- with Asynchronous Reset  
--  
-- Used to receive samples serially from the audio codec  
--  
-----
```

```
library ieee;  
use ieee.std_logic_1164.all;
```

```
entity latch_32 is
```

```

port(
  R : in std_logic;
  CK: in std_logic;
  C : in std_logic;
  D : in std_logic_vector(31 downto 0);
  Q : out std_logic_vector(31 downto 0)
);
end latch_32;

```

architecture arch of latch\_32 is

```

  signal tmp : std_logic_vector(31 downto 0);
  signal EN, C_L : std_logic;

```

```
begin
```

```
-- Add clock to generate a enable signal for the latch
```

```
process (CK, R)
```

```
begin
```

```
  if ( R = '1') then
```

```
    C_L <= '0';
```

```
  elsif (CK 'event and CK = '1') then
```

```
    C_L <= C;
```

```
  end if;
```

```
end process;
```

```
EN <= not C_L and C;
```

```
process (CK, R)
```

```
begin
```

```
  if R='1' then
```

```
    tmp <= X"00000000";
```

```
  elsif CK'event and CK='1' then
```

```
    if ( EN = '1' ) then
```

```
      tmp <= D;
```

```
    end if;
```

```
  end if;
```

```
end process;
```

```
Q <= tmp;
```

```
end arch;
```

```
-----
--
```

-- Audio Sampler Peripheral

--

-----  
library ieee;

use ieee.std\_logic\_1164.all;

use ieee.std\_logic\_unsigned.all;

entity opb\_audio\_sampler is

generic (

  C\_OPB\_AWIDTH : integer := 32;

  C\_OPB\_DWIDTH : integer := 32;

  C\_BASEADDR : std\_logic\_vector(0 to 31) := X"00000000";

  C\_HIGHADDR : std\_logic\_vector(0 to 31) := X"FFFFFFFF");

port (

  -- OPB Input Signals

  OPB\_Clk : in std\_logic;

  OPB\_Rst : in std\_logic;

  OPB\_ABus : in std\_logic\_vector(0 to C\_OPB\_AWIDTH-1);

  OPB\_BE : in std\_logic\_vector(0 to C\_OPB\_DWIDTH/8-1);

  OPB\_DBus : in std\_logic\_vector(0 to C\_OPB\_DWIDTH-1);

  OPB\_RNW : in std\_logic;

  OPB\_select : in std\_logic;

  OPB\_seqAddr : in std\_logic;    -- Sequential Address

  -- OPB Output Signals

  AUS\_DBus : out std\_logic\_vector(0 to C\_OPB\_DWIDTH-1);

  AUS\_errAck : out std\_logic;    -- (unused)

  AUS\_retry : out std\_logic;    -- (unused)

  AUS\_toutSup : out std\_logic;   -- Timeout suppress

  AUS\_xferAck : out std\_logic;   -- Transfer acknowledge

  -- Interrupt

  Interrupt : out std\_logic;    -- Interrupt Signal

  -- Audio IO Signals

  AU\_MCLK : out std\_logic;    -- Audio Chip Master Clock

  AU\_LRCK : out std\_logic;    -- Audio Left/Right Channel Clock

  AU\_BCLK : out std\_logic;    -- Audio Bit Clock

  AU\_SDTI : out std\_logic;    -- Audio Data In (TO Codec)

  AU\_SDTO0 : in std\_logic;    -- Audio Data Out 0 (FROM Codec)

end opb\_audio\_sampler;

architecture behavioral of opb\_audio\_sampler is

```
-- Clock counter used to generate audio transmission clocks
signal opb_clk_count : std_logic_vector(10 downto 0);

-- Internal Utility Signals
signal int_selected  : std_logic; -- Decoded chip select signal
signal int_aus_dbus_en : std_logic; -- Enables output to AUS_DBus
signal int_shift_out  : std_logic_vector(31 downto 0); -- Output of shift-in register
signal int_sample     : std_logic_vector(31 downto 0); -- Last received sample

-- Internal Buffer Signals
signal int_interrupt : std_logic;
signal int_au_mclk   : std_logic;
signal int_au_bclk   : std_logic;
signal int_au_lrck   : std_logic;
signal int_au_sdto0  : std_logic;

signal lrck_lat: std_logic;
signal lrck_rising: std_logic;
signal int_counter: std_logic_vector (0 to 2);

-- State constants
constant Idle : std_logic := '0';
constant Xfer : std_logic := '1';

signal sample_lat0 : std_logic_vector(31 downto 0);
signal sample_lat1 : std_logic_vector(31 downto 0);
signal sample_lat2 : std_logic_vector(31 downto 0);
signal sample_out   : std_logic_vector(31 downto 0);
signal sample_enable : std_logic;
signal sample_counter : std_logic_vector(1 downto 0);
signal present_state, next_state : std_logic;

-- 32-bit Shift Left Register with Serial In and Parallel Out
component shift_32 is
  port (
    SI : in std_logic;
    CK: in std_logic;
    C : in std_logic;
    D : out std_logic_vector(31 downto 0));
end component;

-- 32-bit Latch with Asynchronous Reset
component latch_32 is
  port (
```

```

    R : in std_logic;
    C : in std_logic;
    CK: in std_logic;
    D : in std_logic_vector(31 downto 0);
    Q : out std_logic_vector(31 downto 0));
end component;

-- Output buffer for FPGA outputs to audio codec
component OBUF_F_8 is
port (
    O : out std_ulogic;  -- Out to Audio codec
    I : in std_ulogic);  -- In from Audio codec
end component;

component IBUF is
port (
    I : in std_logic;
    O : out std_logic);
end component;

begin

-- Receiving Shift Register
shift_rcv : shift_32
port map (SI => int_au_sdto0,
          CK => OPB_Clk,
          C  => int_au_bclk,
          D  => int_shift_out);

-- Sample Latch
latch_sample : latch_32
port map (R => OPB_Rst,
          CK => OPB_Clk,
          C  => int_au_lreck,
          D  => int_shift_out,
          Q  => int_sample);

-- AU_MCLK Buffer
au_mclk_buff : OBUF_F_8
port map (
    O => AU_MCLK,
    I => int_au_mclk);

-- AU_BCLK Buffer
au_bclk_buff : OBUF_F_8
port map (

```

```

    O => AU_BCLK,
    I => int_au_bclk);

-- AU_LRCK Buffer
au_lrck_buff : OBUF_F_8
  port map (
    O => AU_LRCK,
    I => int_au_lrck);

-- AU_SDTI Buffer
au_sdti_buff : OBUF_F_8
  port map (
    O => AU_SDTI,
    I => int_au_sdto0);

-- AU_MCLK Buffer
au_sdto0_buff : IBUF
  port map (
    O => int_au_sdto0,
    I => AU_SDTO0);

-- Produce chip select signal by decoding OPB address and checking OPB_select
int_selected <= '1' when OPB_select = '1' and
                OPB_ABus(0 to C_OPB_AWIDTH-9) =
                C_BASEADDR(0 to C_OPB_AWIDTH-9)
                else '0';

-- Tie unused OPB slave outputs
AUS_errAck <= '0';
AUS_retry <= '0';
AUS_toutSup <= '0';

-- Tie OPB ack to output enable signal
AUS_xferAck <= int_aus_dbus_en;

-- Tie unused audio output
--AU_SDTI <= '0';

-- Tie off-FPGA signals to internal buffer signals
INTERRUPT <= int_interrupt;

--int_au_sdto0 <= AU_SDTO0;

-- Generate Audio Transmission Clocks
int_au_mclk <= opb_clk_count(1);

```

```

int_au_bclk <= opb_clk_count(4);
int_au_lrck <= NOT opb_clk_count(9);

opb_clk_count_proc : process(OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    opb_clk_count <= "00000000000";
  elsif OPB_Clk'event and OPB_Clk='1' then
    opb_clk_count <= opb_clk_count + 1;
  end if;
end process opb_clk_count_proc;

-- Gate output to AUS_DBus with int_au_dbus_en
gate_au_dbus_output : process (OPB_Rst, OPB_RNW, int_au_dbus_en)
begin
  if OPB_Rst = '1' then
    AUS_DBus(0 to C_OPB_DWIDTH-1) <= (others => '0');
  else
    if int_au_dbus_en = '1' then
      if ( OPB_ABus(29) = '1' ) then
        AUS_DBus(0 to C_OPB_DWIDTH-1) <= sample_out(23 downto 16) &
sample_out(31 downto 24) & sample_out(7 downto 0) & sample_out(15 downto 8);
      else
        AUS_DBus(0 to C_OPB_DWIDTH-1) <= sample_out(31 downto 0);
      end if;
    else
      AUS_DBus(0 to C_OPB_DWIDTH-1) <= (others => '0');
    end if;
  end if;
end process gate_au_dbus_output;

-- Send interrupt pulse upon receiving sample
-- SMALL HACK: Using int_au_mclk to reset the interrupt
-- send_interrupt : process (int_au_mclk, int_au_lrck, int_interrupt)
-- begin
--   if int_au_mclk='1' then
--     int_interrupt <= '0';
--   elsif int_au_lrck'event and int_au_lrck='1' then
--     int_interrupt <= '1';
--   end if;
-- end process send_interrupt;

process(OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then
    lrck_lat <= '0';

```



```

    elsif OPB_Clk'event and OPB_Clk = '1' then
        lrck_lat <= int_au_lrck;
    end if;
end process;

lrck_rising <= (not lrck_lat) and int_au_lrck;

process(OPB_Clk, OPB_Rst)
begin
    if OPB_Rst = '1' then
        int_interrupt <= '0';
    elsif OPB_Clk'event and OPB_Clk = '1' then
        if ( lrck_rising = '1' and sample_counter = "11" ) then
            int_interrupt <= '1';
        elsif int_counter = "111" then
            int_interrupt <= '0';
        end if;
    end if;
end process;

process(OPB_Clk, OPB_Rst)
begin
    if OPB_Rst = '1' then
        int_counter <= "000";
    elsif OPB_Clk'event and OPB_Clk = '1' then
        if lrck_rising = '1' then
            int_counter <= "000";
        else
            int_counter <= int_counter + '1';
        end if;
    end if;
end process;

process(OPB_Clk, OPB_Rst)
begin
    if OPB_Rst = '1' then
        sample_counter <= "00";
    elsif OPB_Clk'event and OPB_Clk = '1' then
        if lrck_rising = '1' then
            sample_counter <= sample_counter + '1';
        end if;
    end if;
end process;

sample_enable <= lrck_rising or int_aus_dbus_en;

```

```

sample_out <= sample_lat2;

process(OPB_Clk, OPB_Rst)
begin
  if ( OPB_Rst = '1') then
    sample_lat0 <= (others => '0');
    sample_lat1 <= (others => '0');
    sample_lat2 <= (others => '0');
  elsif (OPB_Clk 'event and OPB_Clk = '1') then
    if (sample_enable = '1') then
      sample_lat0 <= int_sample;
      sample_lat1 <= sample_lat0;
      sample_lat2 <= sample_lat1;
    end if;
  end if;
end process;

-- Sequential part of the FSM
fsm_seq : process(OPB_Clk, OPB_Rst)
begin
  if OPB_Rst = '1' then      -- Asynchronous reset to Idle state
    present_state <= Idle;
  elsif OPB_Clk'event and OPB_Clk = '1' then  -- Positive edge OPB_Clk
    present_state <= next_state;      -- advance to next state
  end if;
end process fsm_seq;

-- Combinational part of the FSM
fsm_comb : process (present_state, int_selected)
begin
  int_aus_dbus_en <= '0';

  case present_state is

    when Idle =>
      int_aus_dbus_en <= '0';
      if int_selected='1' then
        next_state <= Xfer;
      else
        next_state <= Idle;
      end if;

    when Xfer =>
      int_aus_dbus_en <= '1';
      next_state <= Idle;

```

```

        when others =>
            int_au_s_dbus_en <= '0';
            next_state <= Idle;

        end case;
    end process fsm_comb;

end behavioral;

```

### 4.3.8 opb\_xsb300e\_vga.vhd

```

-----
--
-- Text-mode VGA controller for the XESS-300E
--
-- Uses an OPB interface, e.g., for use with the Microblaze soft core
--
-- Stephen A. Edwards
-- sedwards@cs.columbia.edu
--
-----
library ieee;
use ieee.std_logic_1164.all;
use ieee.std_logic_arith.all;
use ieee.std_logic_unsigned.all;

entity opb_xsb300e_vga is

    generic (
        C_OPB_AWIDTH : integer           := 32;
        C_OPB_DWIDTH : integer           := 32;
        C_BASEADDR   : std_logic_vector(31 downto 0) := X"FEFF1000";
        C_HIGHADDR   : std_logic_vector(31 downto 0) := X"FEFF1FFF");

    port (
        OPB_Clk      : in std_logic;
        OPB_Rst      : in std_logic;

        -- OPB signals
        OPB_ABus     : in std_logic_vector (31 downto 0);
        OPB_BE       : in std_logic_vector (3 downto 0);
        OPB_DBus     : in std_logic_vector (31 downto 0);
        OPB_RNW      : in std_logic;
        OPB_select   : in std_logic;
        OPB_seqAddr  : in std_logic;

```

```

VGA_DBus    : out std_logic_vector (31 downto 0);
VGA_errAck  : out std_logic;
VGA_retry   : out std_logic;
VGA_toutSup : out std_logic;
VGA_xferAck : out std_logic;

Pixel_Clock : in std_logic;

-- Video signals
VIDOUT_CLK  : out std_logic;
VIDOUT_RED  : out std_logic_vector(9 downto 0);
VIDOUT_GREEN : out std_logic_vector(9 downto 0);
VIDOUT_BLUE  : out std_logic_vector(9 downto 0);
VIDOUT_BLANK_N : out std_logic;
VIDOUT_HSYNC_N : out std_logic;
VIDOUT_VSYNC_N : out std_logic);

end opb_xsb300e_vga;

architecture Behavioral of opb_xsb300e_vga is

    constant BASEADDR : std_logic_vector(31 downto 0) := X"FEFF1000";

    -- Video parameters

    constant HTOTAL : integer := 800;
    constant HSYNC : integer := 96;
    constant HBACK_PORCH : integer := 48;
    constant HACTIVE : integer := 640;
    constant HFRONT_PORCH : integer := 16;

    constant VTOTAL : integer := 525;
    constant VSYNC : integer := 2;
    constant VBACK_PORCH : integer := 33;
    constant VACTIVE : integer := 480;
    constant VFRONT_PORCH : integer := 10;

    -- 512 X 8 dual-ported Xilinx block RAM
    component RAMB4_S8_S8
    port (
        DOA  : out std_logic_vector (7 downto 0);
        ADDRA : in std_logic_vector (8 downto 0);
        CLKA  : in std_logic;
        DIA  : in std_logic_vector (7 downto 0);
        ENA  : in std_logic;

```

```
RSTA : in std_logic;  
WEA  : in std_logic;  
DOB  : out std_logic_vector (7 downto 0);  
ADDRB : in std_logic_vector (8 downto 0);  
CLKB : in std_logic;  
DIB  : in std_logic_vector (7 downto 0);  
ENB  : in std_logic;  
RSTB : in std_logic;  
WEB  : in std_logic);  
end component;
```