The Forward-Backward Algorithm

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1 Introduction

This note describes the *forward-backward algorithm*. The forward-backward algorithm has very important applications to both hidden Markov models (HMMs) and conditional random fields (CRFs). It is a dynamic programming algorithm, and is closely related to the Viterbi algorithm for decoding with HMMs or CRFs.

This note describes the algorithm at a level of abstraction that applies to both HMMs and CRFs. We will also describe its specific application to these cases.

2 The Forward-Backward Algorithm

The problem set-up is as follows. Assume that we have some sequence length m, and some set of possible states S. For any state sequence $s_1 \dots s_m$ where each $s_i \in S$, we define the *potential* for the sequence as

$$\psi(s_1 \dots s_m) = \prod_{j=1}^m \psi(s_{j-1}, s_j, j)$$

Here we define s_0 to be *, where * is a special start symbol in the model. Here $\psi(s, s', j) \ge 0$ for $s, s' \in S$, $j \in \{1 \dots m\}$ is a potential function, which returns a value for the state transition s to s' at position j in the sequence.

The potential functions $\psi(s_{j-1}, s_j, j)$ might be defined in various ways. As one example, consider an HMM applied to an input sentence $x_1 \dots x_m$. If we define

$$\psi(s', s, j) = t(s|s')e(x_j|s)$$

then

$$\psi(s_1 \dots s_m) = \prod_{j=1}^m \psi(s_{j-1}, s_j, j)$$
$$= \prod_{j=1}^m t(s_j | s_{j-1}) e(x_j | s_j)$$

$$= p(x_1 \dots x_m, s_1 \dots s_m)$$

where $p(x_1 \dots x_m, s_1 \dots s_m)$ is the probability mass function under the HMM.

As another example, consider a CRF where we have a feature-vector definition $\underline{\phi}(x_1 \dots x_m, s', s, j) \in \mathbb{R}^d$, and a parameter vector $\underline{w} \in \mathbb{R}^d$. Assume again that we have an input sentence $x_1 \dots x_m$. If we define

$$\psi(s',s,j) = \exp\left(\underline{w} \cdot \underline{\phi}(x_1 \dots x_m, s', s, j)\right)$$

then

$$\psi(s_1 \dots s_m) = \prod_{j=1}^m \psi(s_{j-1}, s_j, j)$$
$$= \prod_{j=1}^m \exp\left(\underline{w} \cdot \underline{\phi}(x_1 \dots x_m, s_{j-1}, s_j, j)\right)$$
$$= \exp\left(\sum_{j=1}^m \underline{w} \cdot \underline{\phi}(x_1 \dots x_m, s_{j-1}, s_j, j)\right)$$

Note in particular, by the model form for CRFs, it follows that

$$p(s_1 \dots s_m | x_1 \dots x_m) = \frac{\psi(s_1 \dots s_m)}{\sum_{s_1 \dots s_m} \psi(s_1 \dots s_m)}$$

The forward-backward algorithm is shown in figure 1. Given inputs consisting of a sequence length m, a set of possible states S, and potential functions $\psi(s', s, j)$ for $s, s' \in S$, and $j \in \{1 \dots m\}$, it computes the following quantities:

- 1. $Z = \sum_{s_1...s_m} \psi(s_1...s_m).$
- 2. For all $j \in \{1 \dots m\}, a \in \mathcal{S}$,

$$\mu(j,a) = \sum_{s_1\dots s_m: s_j = a} \psi(s_1\dots s_m)$$

3. For all $j \in \{1 \dots (m-1)\}, a, b \in S$,

$$\mu(j,a,b) = \sum_{s_1\dots s_m: s_j=a, s_{j+1}=b} \psi(s_1\dots s_m)$$

Inputs: Length m, set of possible states S, function $\psi(s, s', j)$. Define * to be a special initial state.

Initialization (forward terms): For all $s \in S$,

$$\alpha(1,s) = \psi(*,s,1)$$

Recursion (forward terms): For all $j \in \{2...m\}, s \in S$,

$$\alpha(j,s) = \sum_{s' \in \mathcal{S}} \alpha(j-1,s') \times \psi(s',s,j)$$

Initialization (backward terms): For all $s \in S$,

 $\beta(m,s) = 1$

Recursion (backward terms): For all $j \in \{1 \dots (m-1)\}, s \in S$,

$$\beta(j,s) = \sum_{s' \in \mathcal{S}} \beta(j+1,s') \times \psi(s,s',j+1)$$

Calculations:

$$Z = \sum_{s \in \mathcal{S}} \alpha(m,s)$$

For all $j \in \{1 \dots m\}, a \in \mathcal{S}$,

$$\mu(j,a) = \alpha(j,a) \times \beta(j,a)$$

For all $j \in \{1 \dots (m-1)\}, a, b \in \mathcal{S}$,

$$\mu(j, a, b) = \alpha(j, a) \times \psi(a, b, j+1) \times \beta(j+1, b)$$

Figure 1: The forward-backward algorithm.

3 Application to CRFs

The quantities computed by the forward-backward algorithm play a central role in CRFs. First, consider the problem of calculating the conditional probability

$$p(s_1 \dots s_m | x_1 \dots x_m) = \frac{\exp\left(\sum_{j=1}^m \underline{w} \cdot \underline{\phi}(x_1 \dots x_m, s_{j-1}, s_j, j)\right)}{\sum_{s_1 \dots s_m} \exp\left\{\left(\sum_{j=1}^m \underline{w} \cdot \underline{\phi}(x_1 \dots x_m, s_{j-1}, s_j, j)\right)\right\}}$$

The numerator in the above expression is easy to compute; the denominator is more challenging, because it requires a sum over an exponential number of state sequences. However, if we define

$$\psi(s',s,j) = \exp\left(\underline{w} \cdot \underline{\phi}(x_1 \dots x_m, s', s, j)\right)$$

in the algorithm in figure 1, then as we argued before we have

$$\psi(s_1 \dots s_m) = \exp\left(\sum_{j=1}^m \underline{w} \cdot \underline{\phi}(x_1 \dots x_m, s_{j-1}, s_j, j)\right)$$

It follows that the quantity Z calculated by the algorithm is equal to the denominator in the above expression; that is,

$$Z = \sum_{s_1...s_m} \exp\left(\sum_{j=1}^m \underline{w} \cdot \underline{\phi}(x_1...x_m, s_{j-1}, s_j, j)\right)$$

Next, recall that the key difficulty in the calculation of the gradient of the loglikelihood function in CRFs was to calculate the terms

$$q_j^i(a,b) = \sum_{\underline{s}: s_{j-1} = a, s_j = b} p(\underline{s} | \underline{x}^i; \underline{w})$$

for a given input sequence $\underline{x}^i = x_1^i \dots x_m^i$, for each $j \in \{2 \dots m\}$, for each $a, b \in S$ (see the note on log-linear models). Again, if we define

$$\psi(s',s,j) = \exp\left(\underline{w} \cdot \underline{\phi}(x_1^i \dots x_m^i, s', s, j)\right)$$

then it can be verified that

$$q^i_j(a,b) = \frac{\mu(j,a,b)}{Z}$$

where $\mu(j, a, b)$ and Z are the terms computed by the algorithm in figure 1.