

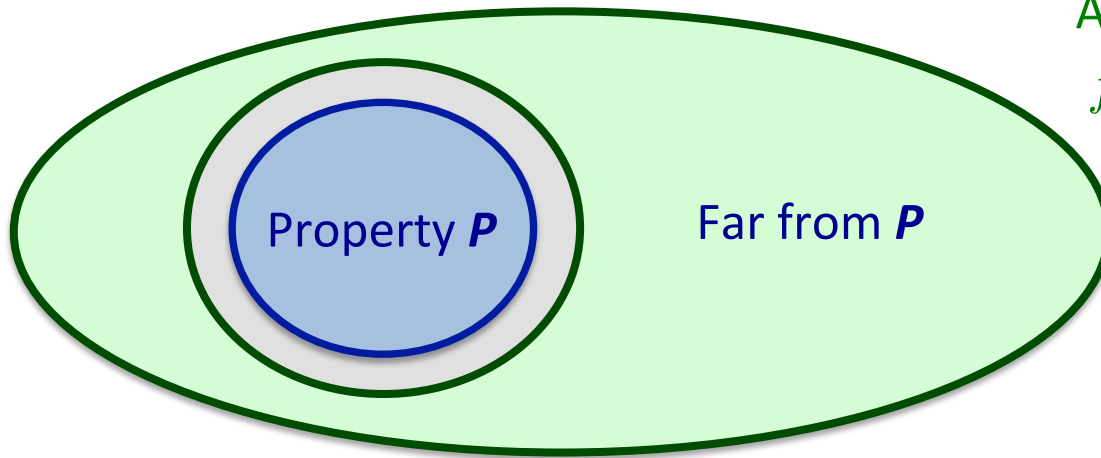
# A Polynomial Lower Bound for Monotonicity Testing of Boolean Functions

Joint work with Xi Chen and Rocco Servedio



# Property Testing

Simplest question about a Boolean function: Does it have some property  $P$ ?



All Boolean functions  
 $f : \{0, 1\}^n \rightarrow \{0, 1\}$

- Query access to unknown  $f$  on any input  $x$
- With as few queries as possible, decide if

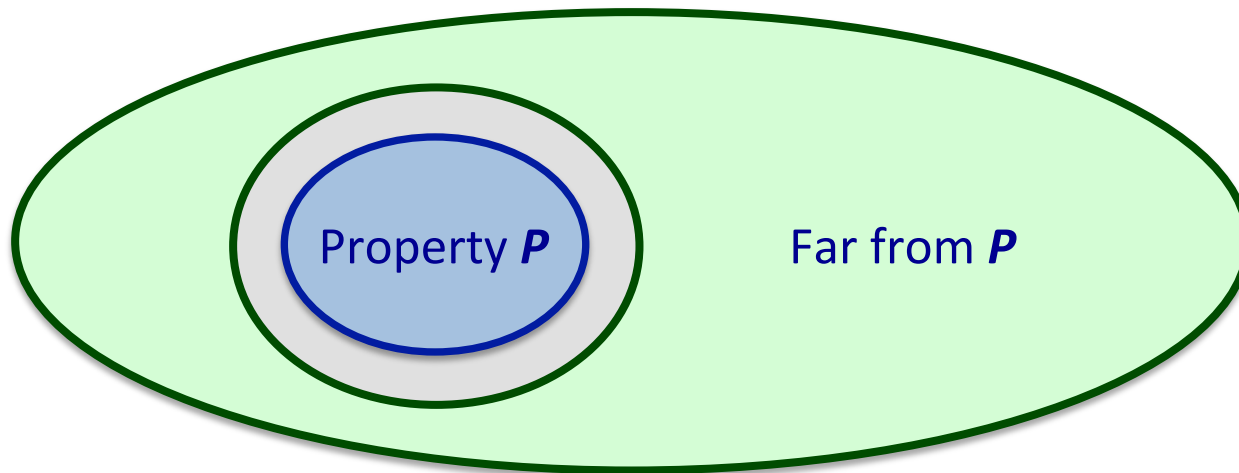
Unreasonable:  
Easy lower bound of  $\Omega(2^n)$

$f$  has Property  $P$  vs.  ~~$f$  does not have Property  $P$~~

$f$  is far from having Property  $P$

# Rules of the game

All Boolean functions



Query access to unknown  $f$  on any input  $x$

1. If  $f$  has Property  $P$ , accept w.p.  $> 2/3$ .
2. If  $f$  is  $\epsilon$ -far from having Property  $P$ , reject w.p.  $> 2/3$ .
3. Otherwise: doesn't matter what we do.

# Super-efficient algorithms

Sublinear Space

Streaming,  
Sketching

Sublinear Time

Property Testing

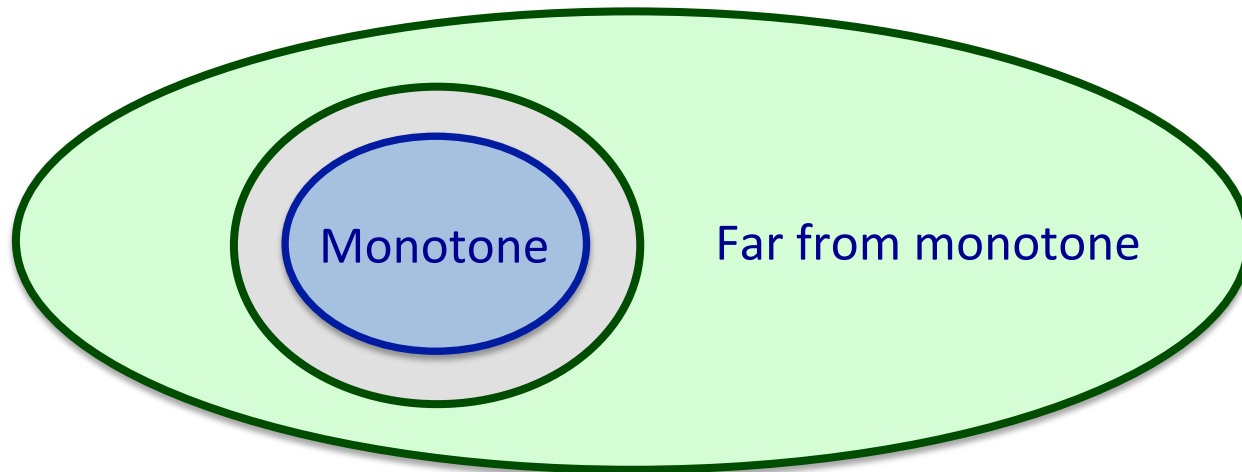
Sublinear Measurement

Sparse Recovery,  
Compressed Sensing

Two recurring messages:

1. Many properties  $P$  testable with surprisingly few queries.
2. Rich connections with many other areas:
  - Learning theory
  - Hardness of approximation
  - Communication complexity
  - ...

This work:  $P = \text{monotonicity}$



Well-studied problem:

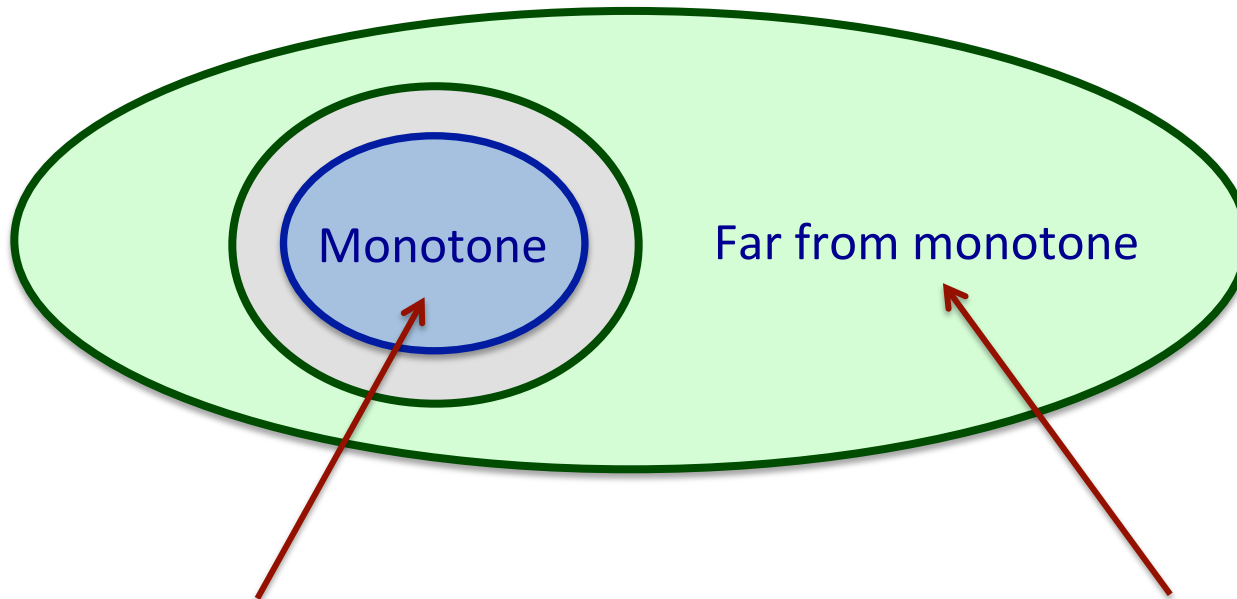
[GGR98, GGL+98, DGL+99, FLN+02, HK08, BCGM12, RRS+12, BBM12, BRY13, CS13, ...]

but still significant gaps in our understanding.

## This talk

- The natural tester and its analysis [Goldreich *et al.* 1998]
- **Our main result:**
  - A **polynomial lower bound** on query complexity
- **Our main technical ingredient:**
  - Multidimensional Central Limit Theorems**
- Generalizing our main result: **Testing monotonicity on *hypergrids***

## A quick reminder



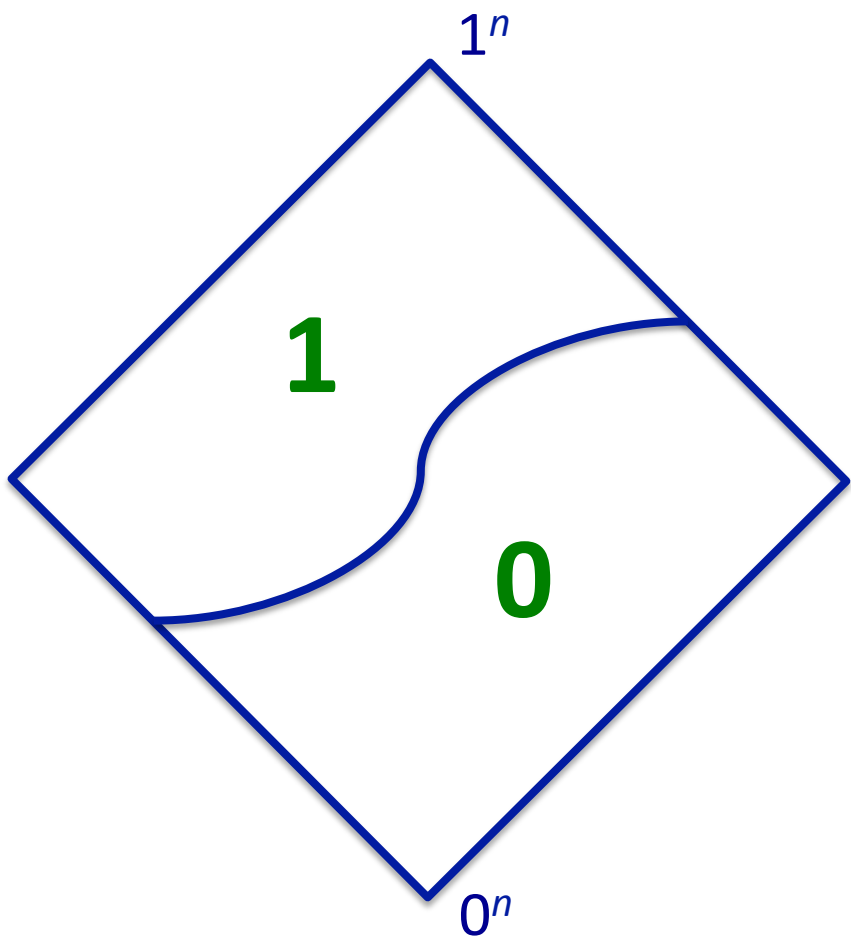
A monotone function is one that satisfies:

$$\underbrace{\forall x \preceq y, f(x) \leq f(y)}_{x_i \leq y_i \forall i \in [n]}$$

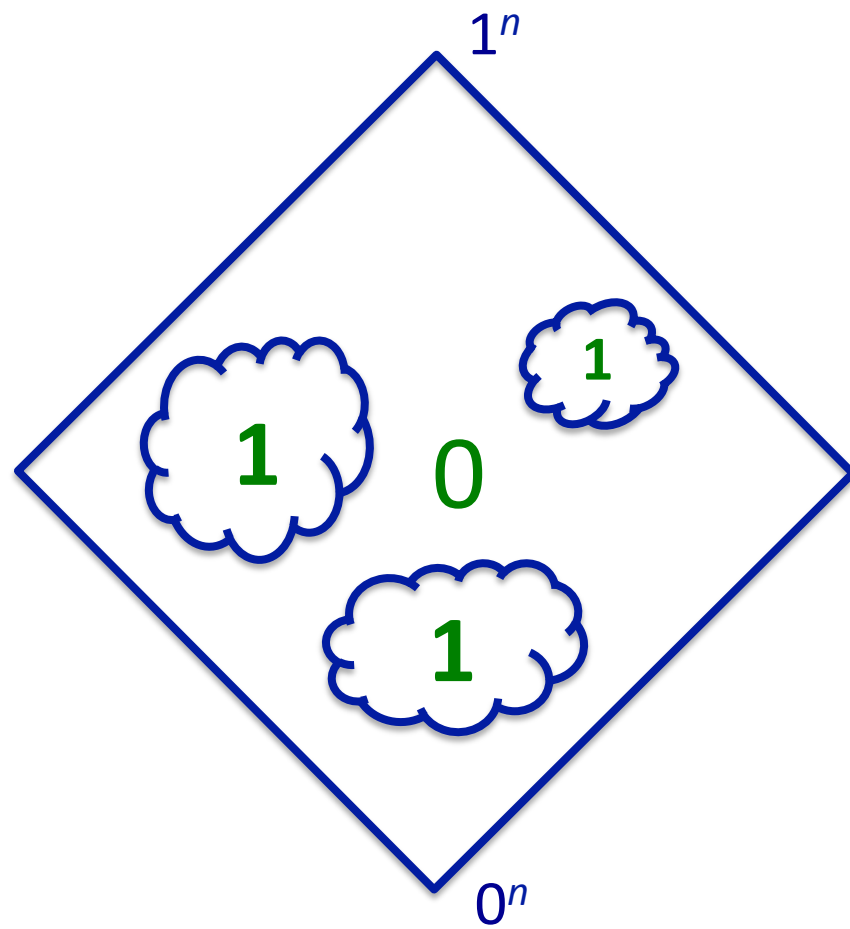
For all monotone functions  $g$ :

$$\Pr_{\mathbf{x} \in \{0,1\}^n} [f(\mathbf{x}) \neq g(\mathbf{x})] \geq \varepsilon$$

“Flipping an input bit from **0** to **1** cannot make  $f$  go from **1** to **0**”



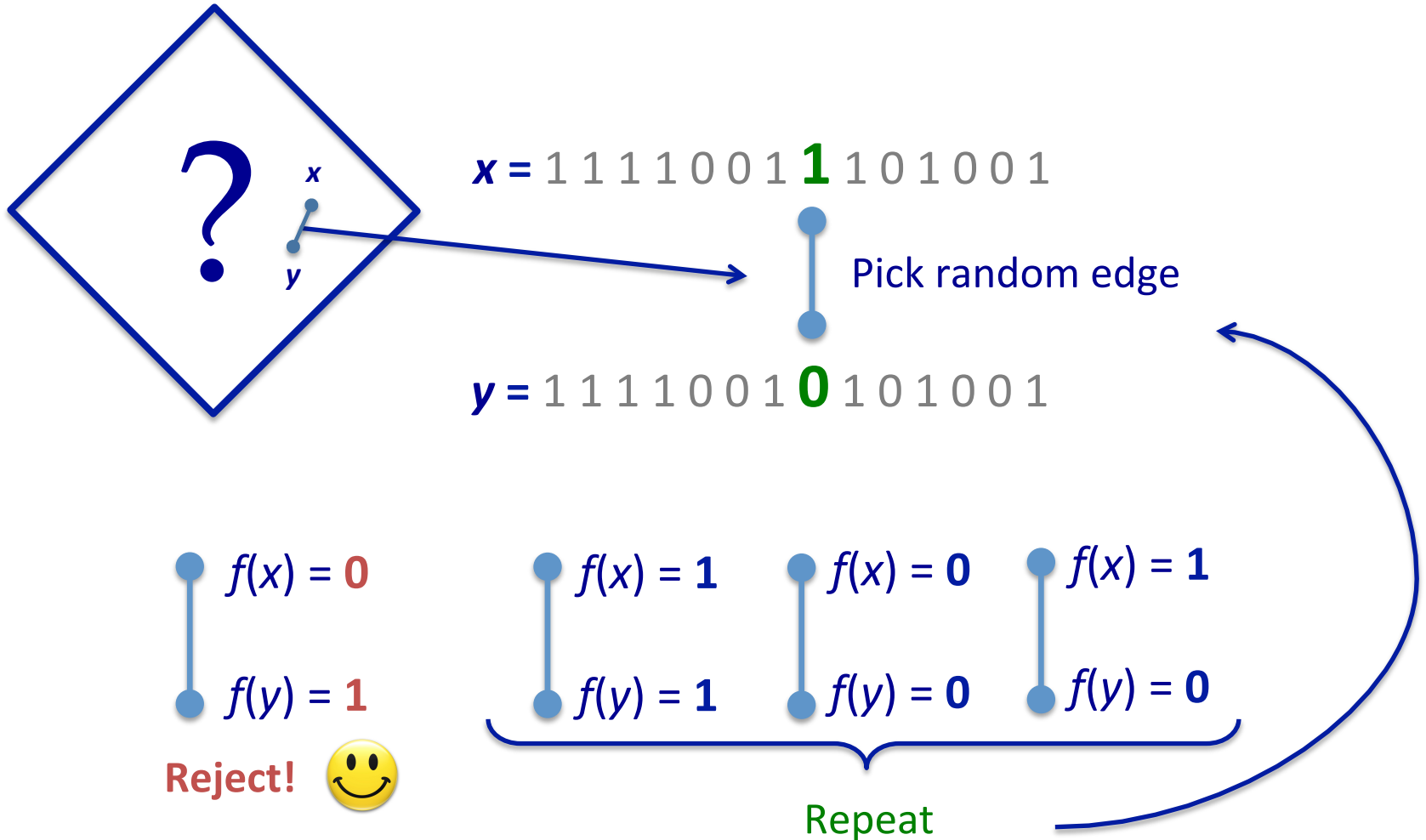
Monotone



Far from monotone

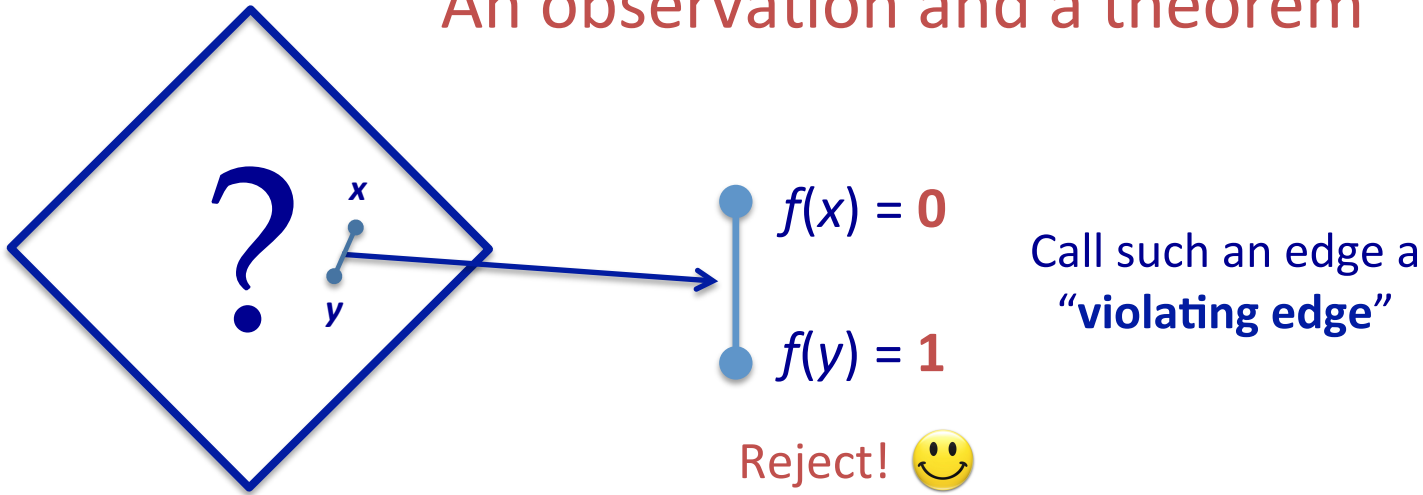


# First test that comes to mind



Call such an edge a  
"violating edge"

## An observation and a theorem



Tester = Sample random edges, check for violations.

**Simple observation:** If  $f$  is monotone, tester never rejects.

**Question:** If  $f$  is  $\varepsilon$ -far from monotone, how likely to catch violating edge?

**Theorem** [Goldreich *et al.* 1998, 2000]

If  $f$  is  $\varepsilon$ -far from monotone,  $\Omega(\varepsilon/n)$  fraction of edges are violations.  
Therefore tester will reject within  $O(n/\varepsilon)$  queries.

# An exponential gap

- **Goldreich *et al.*** [FOCS 1998, SICOMP 2000]
  - Introduced problem, gave tester with  $O(n)$  query complexity.
- **Fischer *et al.*** [STOC 2002]
  - Any non-adaptive tester must make  $\Omega(\log n)$  queries.
  - Therefore, any adaptive tester must make  $\Omega(\log \log n)$  queries.

[GGR98, DGL+99, HK08, BCGM12, RRS+12, BRY13, CS13, ...]

- **Chakrabarty-Seshadhri** [STOC 2013]
  - $O(n^{7/8})$ -query non-adaptive tester!



**Theorem [Chen-Servedio-T 2014]**

Any non-adaptive tester must make  $\tilde{\Omega}(n^{1/5})$  queries.  
Therefore, any adaptive tester must make  $\Omega(\log n)$  queries.

Exponential improvements over  $\Omega(\log n)$  and  $\Omega(\log \log n)$   
lower bounds of Fischer *et al.* (2002)

**Theorem [Chen-Servedio-T 2014]**

There is a non-adaptive tester that makes  $\tilde{O}(n^{5/6})$  queries.

Polynomial improvement over  $O(n^{7/8})$  upper bound of  
Chakrabarty and Sheshadhri (2013)

# Yao's minimax principle

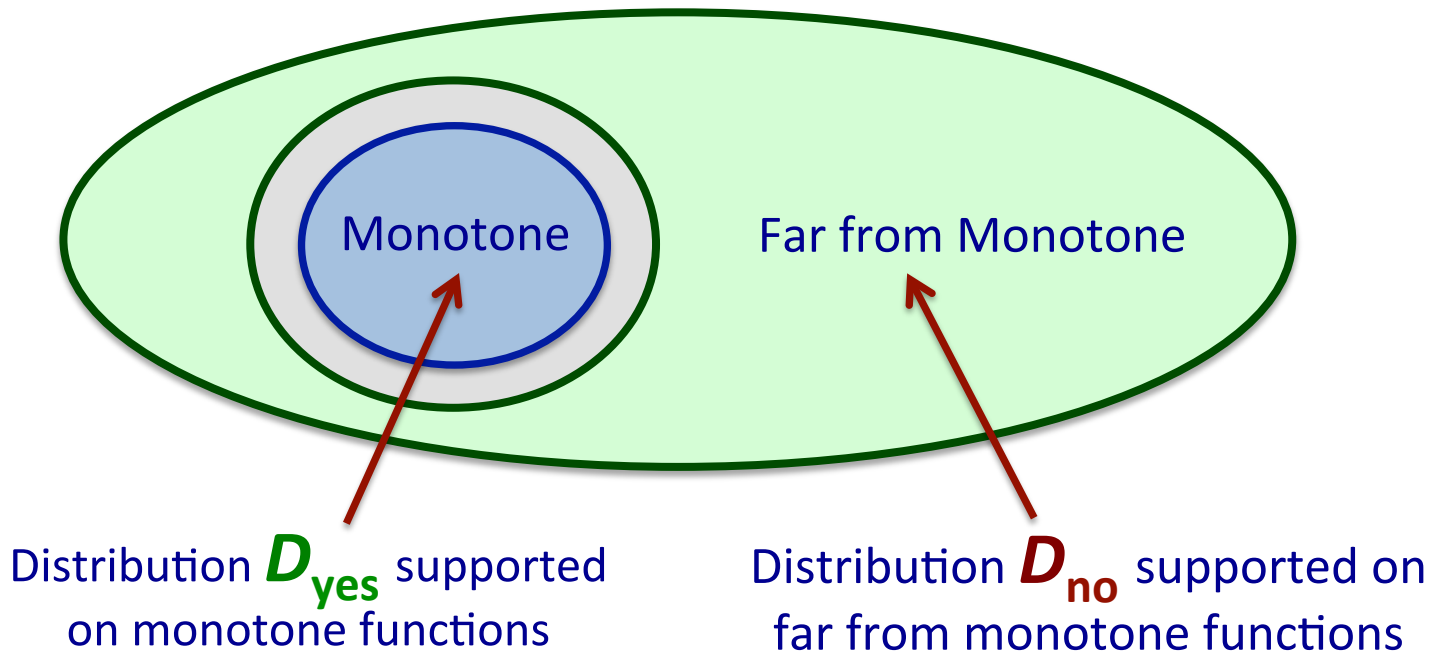
Lower bound against  
**randomized** algorithms

implies

Tricky distribution over inputs  
to **deterministic** algorithms



## Yao's principle in our setting



**Indistinguishability.** For all  $T =$  deterministic tester that makes  $o(n^{1/5})$  queries,

$$\left| \Pr_{f_{\text{yes}} \sim D_{\text{yes}}} [\mathcal{T} \text{ accepts } f_{\text{yes}}] - \Pr_{f_{\text{no}} \sim D_{\text{no}}} [\mathcal{T} \text{ accepts } f_{\text{no}}] \right| = o_n(1)$$

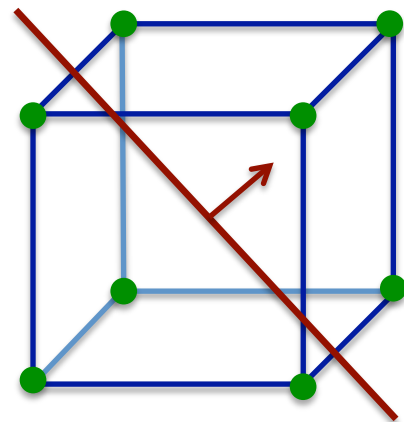
## Our $D_{\text{yes}}$ and $D_{\text{no}}$ distributions

Both supported on *Linear Threshold Functions* (LTFs) over  $\{-1,1\}^n$ :

$$f(x) = \text{sign}(w_1x_1 + \dots + w_nx_n) \quad \vec{w} \in \mathbb{R}^n$$

$D_{\text{yes}}$ :  $\sigma_i =$  uniform from  $\{1,3\}$

$D_{\text{no}}$ :  $\nu_i = -1$  with prob 0.1,  $7/3$  with prob 0.9



**Verify:**  $D_{\text{yes}}$  LTFs are monotone,  $D_{\text{no}}$  LTFs far from monotone w.h.p.

### Main Structural Result: **Indistinguishability**

Any deterministic tester that makes few queries cannot tell  $D_{\text{yes}}$  from  $D_{\text{no}}$

**Key property:**  $\mathbb{E}[\sigma_i] = \mathbb{E}[\nu_i]$ ,  $\text{Var}[\sigma_i] = \text{Var}[\nu_i]$ .

# Indistinguishability

$q = 1$  query

**Claim.** For all  $T =$  deterministic tester that makes  ~~$q = o(n^{1/5})$  queries,~~

$$\left| \Pr_{\mathbf{f}_{yes} \sim \mathcal{D}_{yes}} [\mathcal{T} \text{ accepts } \mathbf{f}_{yes}] - \Pr_{\mathbf{f}_{no} \sim \mathcal{D}_{no}} [\mathcal{T} \text{ accepts } \mathbf{f}_{no}] \right| = o_n(1)$$



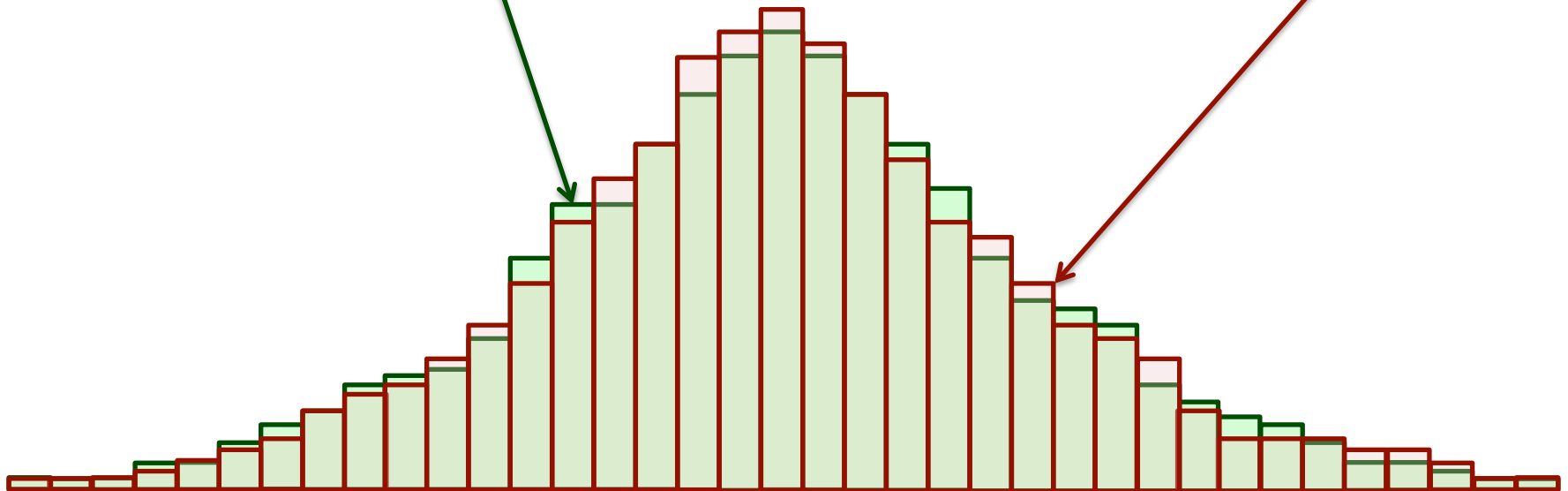
# Non-trivial proof of a triviality

**Claim.** Let  $T$  = deterministic tester that makes 1 query  $\mathbf{z}$ . Then:

$$\underbrace{\left| \Pr_{\mathbf{f}_{yes} \sim \mathcal{D}_{yes}} [\mathcal{T} \text{ accepts } \mathbf{f}_{yes}] - \Pr_{\mathbf{f}_{no} \sim \mathcal{D}_{no}} [\mathcal{T} \text{ accepts } \mathbf{f}_{no}] \right|}_{(*)} = o_n(1)$$
$$(*) \leq d_{TV}(\mathbf{R}_{yes}, \mathbf{R}_{no})$$

Tester sees:

$$\mathbf{R}_{yes} = \text{sign}(\underbrace{\sigma_1 z_1 + \dots + \sigma_n z_n}_{\text{green}}) \text{ vs. } \mathbf{R}_{no} = \text{sign}(\underbrace{\nu_1 z_1 + \dots + \nu_n z_n}_{\text{red}})$$

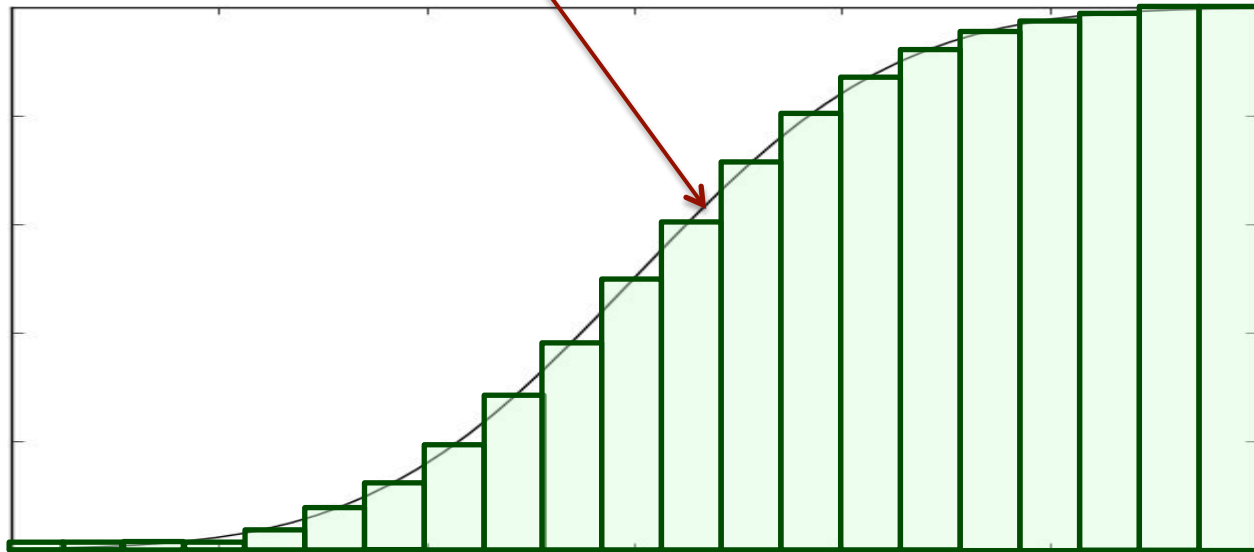


**Central Limit Theorems.** Sum of many independent “reasonable” random variables converges to Gaussian of same mean and variance.

Main analytic tool (Baby version):

**Berry–Esséen CLT.** Let  $\mathbf{S} = \mathbf{X}_1 + \cdots + \mathbf{X}_n$  where  $\mathbf{X}_1, \dots, \mathbf{X}_n$  are independent real-valued random variables satisfying  $|\mathbf{X}_j - \mathbf{E}[\mathbf{X}_j]| \leq \tau$  with probability 1 for all  $j \in [n]$ . Let  $\mathcal{G}$  be a Gaussian with mean  $\mathbf{E}[\mathbf{S}]$  and variance  $\mathbf{Var}[\mathbf{S}]$ . Then for all  $\theta \in \mathbb{R}$ ,

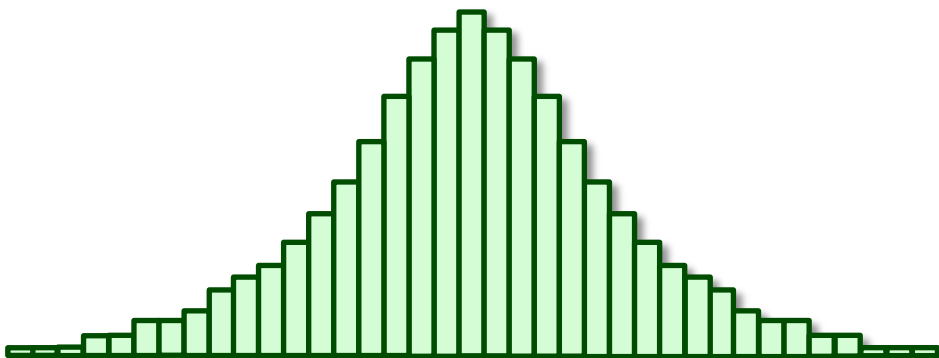
$$|\Pr[\mathbf{S} \leq \theta] - \Pr[\mathcal{G} \leq \theta]| \leq \frac{O(\tau)}{\mathbf{Var}[\mathbf{S}]^{1/2}}.$$



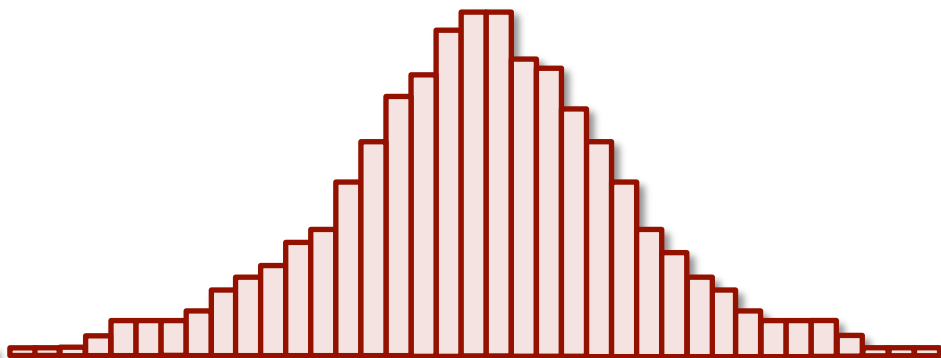
**Goal:** Upper bound  $d_{\text{TV}}(\text{sign}(\mathbf{S}_{\text{yes}}), \text{sign}(\mathbf{S}_{\text{no}}))$

$$\mathbf{S}_{\text{yes}} = \boldsymbol{\sigma}_1 z_1 + \cdots + \boldsymbol{\sigma}_n z_n$$

$$\mathbf{S}_{\text{no}} = \boldsymbol{\nu}_1 z_1 + \cdots + \boldsymbol{\nu}_n z_n$$



$$\mathbf{S}_{\text{yes}} \rightarrow \mathcal{G}_1$$



$$\mathbf{S}_{\text{no}} \rightarrow \mathcal{G}_2$$

Recall key property:

$$\left. \begin{array}{l} \mathbb{E}[\boldsymbol{\sigma}_i] = \mathbb{E}[\boldsymbol{\nu}_i] \\ \text{Var}[\boldsymbol{\sigma}_i] = \text{Var}[\boldsymbol{\nu}_i] \end{array} \right\} \longrightarrow \begin{array}{l} \mathbb{E}[\mathbf{S}_{\text{yes}}] = \mathbb{E}[\mathbf{S}_{\text{no}}] \\ \text{Var}[\mathbf{S}_{\text{yes}}] = \text{Var}[\mathbf{S}_{\text{no}}] \\ \mathcal{G}_1 = \mathcal{G}_2 \end{array}$$

We just proved:

**Claim.** Let  $T$  = deterministic tester that makes **1 query**. Then:

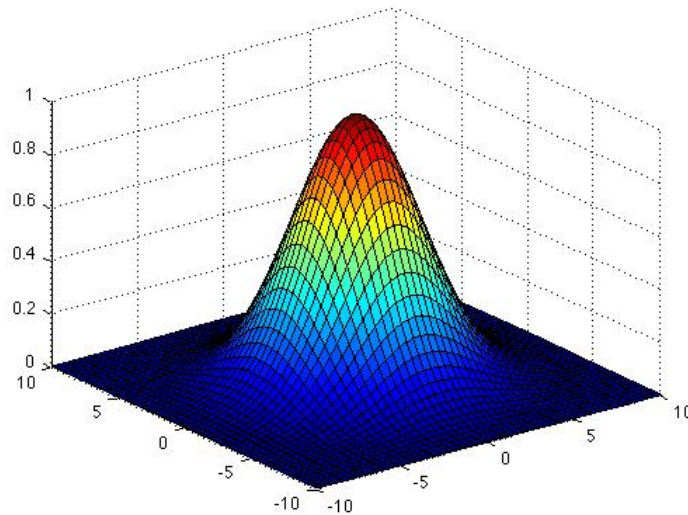
$$\left| \Pr_{\mathbf{f}_{yes} \sim \mathcal{D}_{yes}} [\mathcal{T} \text{ accepts } \mathbf{f}_{yes}] - \Pr_{\mathbf{f}_{no} \sim \mathcal{D}_{no}} [\mathcal{T} \text{ accepts } \mathbf{f}_{no}] \right| = O(n^{-1/2})$$

Plenty of room to spare!  
Would be happy with  $< 0.1$

$q$  queries instead of 1

Main analytic tool (Grown-up version):

**Multidimensional CLTs.** Sum of many independent “reasonable”  $q$ -dimensional random variables converge to  $q$ -dimensional Gaussian of same mean and variance.



# Multidimensional CLTs



→  $\Omega(n^{1/12})$   
Lower bound

[Mossel 08, Gopalan-O'Donnell-Wu-Zuckerman 10]



[Valiant-Valiant 11]

Main technical work:  
Adapting multidimensional CLT  
for Earth Mover Distance to get

$$\tilde{\Omega}(n^{1/5})$$

Let's prove the real thing:

**Claim.** For all  $T =$  deterministic tester that makes  $q = o(n^{1/5})$  queries,

$$\left| \Pr_{\mathbf{f}_{yes} \sim \mathcal{D}_{yes}} [\mathcal{T} \text{ accepts } \mathbf{f}_{yes}] - \Pr_{\mathbf{f}_{no} \sim \mathcal{D}_{no}} [\mathcal{T} \text{ accepts } \mathbf{f}_{no}] \right| = o_n(1)$$

## Setting things up

Arrange the  $q$  queries of tester  $T$  in a  $q \times n$  matrix  $\mathbf{Q} \in \{-1, 1\}^{q \times n}$

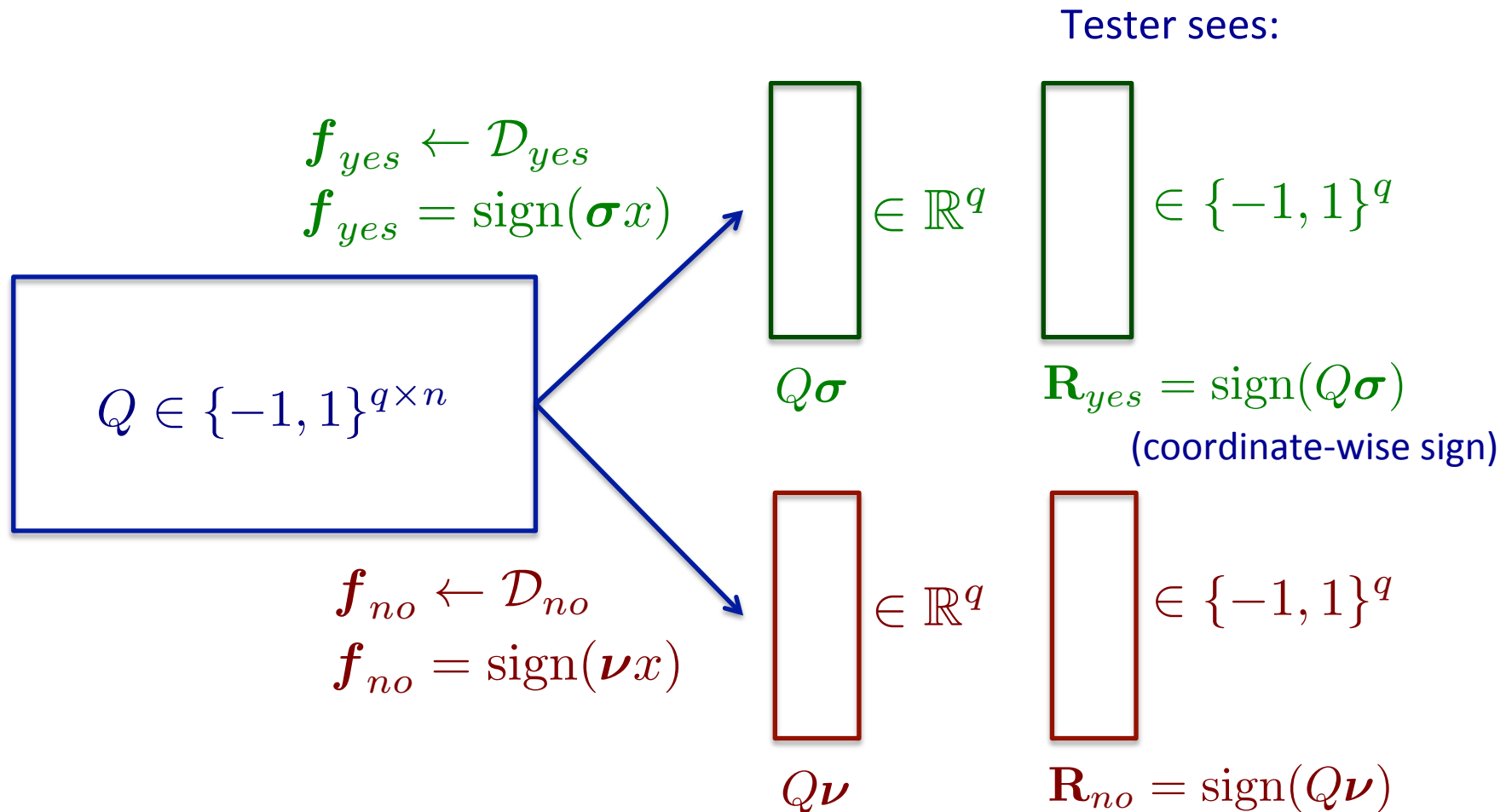
$$\begin{array}{l} Q_1 \\ Q_2 \\ Q_3 \\ \vdots \\ Q_q \end{array} \left[ \begin{array}{c} \\ \\ \\ \\ \\ \\ \end{array} \right. \begin{array}{c} \\ \\ Q \in \{-1, 1\}^{q \times n} \\ \\ Q_i = i\text{-th query string} \\ \\ \end{array} \end{array}$$

Recall: Tester's goal is to distinguish

$$f_{yes} = \text{sign}(\sigma x) \text{ versus } f_{no} = \text{sign}(\nu x)$$

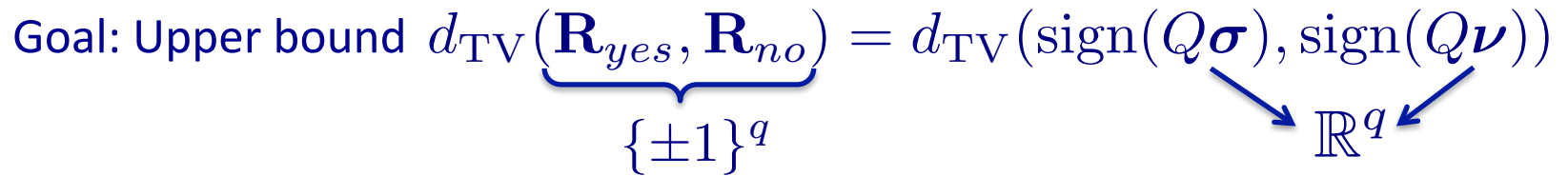


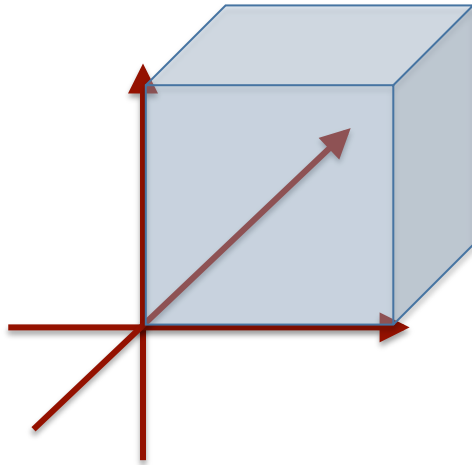
# What does the tester see?



Goal: Upper bound  $d_{\text{TV}}(\mathbf{R}_{yes}, \mathbf{R}_{no}) = d_{\text{TV}}(\text{sign}(Q\sigma), \text{sign}(Q\nu))$

Goal: Upper bound  $d_{\text{TV}}(\underbrace{\mathbf{R}_{yes}, \mathbf{R}_{no}}_{\{\pm 1\}^q}) = d_{\text{TV}}(\text{sign}(Q\boldsymbol{\sigma}), \text{sign}(Q\boldsymbol{\nu}))$





$\mathbf{R}_{yes} \equiv$  orthant of  $\mathbb{R}^q$  that  $Q\boldsymbol{\sigma}$  falls in  
 $\mathbf{R}_{no} \equiv$  orthant of  $\mathbb{R}^q$  that  $Q\boldsymbol{\nu}$  falls in

Random variables supported on  $2^q$  orthants of  $\mathbb{R}^q$

$$d_{\text{TV}}(\mathbf{R}_{yes}, \mathbf{R}_{no}) = \sum_{\substack{2^q \text{ orthants} \\ O_i \text{ of } \mathbb{R}^q}} |\Pr[Q\boldsymbol{\sigma} \in O_i] - \Pr[Q\boldsymbol{\nu} \in O_i]|$$

union of orthants  $\longrightarrow = \max_{O \subseteq \mathbb{R}^q} |\Pr[Q\boldsymbol{\sigma} \in O] - \Pr[Q\boldsymbol{\nu} \in O]|$

“roughly equal weight on any union of orthants”

$$d_{\text{TV}}(\mathbf{R}_{\text{yes}}, \mathbf{R}_{\text{no}}) = \max_{\mathcal{O} \subseteq \mathbb{R}^q} |\Pr[Q\boldsymbol{\sigma} \in \mathcal{O}] - \Pr[Q\boldsymbol{\nu} \in \mathcal{O}]|$$

$$\begin{array}{ccccccc}
 & Q_{*1} & Q_{*2} & & \dots & & Q_{*n} \\
 Q_1 & \begin{array}{|c} \hline \\ \hline \end{array} & & & & & \\
 Q_2 & & & & & & \\
 \vdots & & & & & & \\
 Q_q & & & & & & 
 \end{array}$$

$Q \in \{-1, 1\}^{q \times n}$

Fixed  $\rightarrow$

$$Q\boldsymbol{\sigma} = \sum_{i=1}^n Q_{*i} \boldsymbol{\sigma}_i \quad \text{Ditto: } Q\boldsymbol{\nu} = \sum_{i=1}^n Q_{*i} \boldsymbol{\nu}_i$$

from product distribution over  $\mathbb{R}^n$

sum of  $n$  independent vectors in  $\mathbb{R}^q$

$$\left. \begin{array}{l} \mathbb{E}[\boldsymbol{\sigma}_i] = \mathbb{E}[\boldsymbol{\nu}_i] \\ \text{Var}[\boldsymbol{\sigma}_i] = \text{Var}[\boldsymbol{\nu}_i] \end{array} \right\} \rightarrow \begin{array}{l} \mathbb{E}[Q\boldsymbol{\sigma}] = \mathbb{E}[Q\boldsymbol{\nu}] \\ \text{Cov}[Q\boldsymbol{\sigma}] = \text{Cov}[Q\boldsymbol{\nu}] \end{array}$$

## The final setup

**Goal:** Two sums of  $n$  independent vectors in  $\mathbb{R}^q$  are “close”

$$Q\sigma = \sum_{i=1}^n Q_{\star i} \sigma_i \quad Q\nu = \sum_{i=1}^n Q_{\star i} \nu_i$$

where closeness = roughly equal weight on any union of orthants.

Furthermore, since

$$\begin{aligned} \mathbb{E}[Q\sigma] &= \mathbb{E}[Q\nu] \\ \mathbf{Cov}[Q\sigma] &= \mathbf{Cov}[Q\nu] \end{aligned}$$

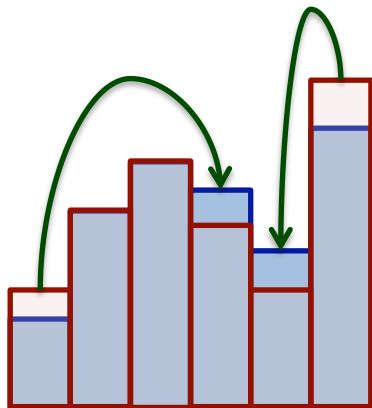
suffices to show each are close to  $q$ -dimensional Gaussian with matching mean and covariance matrix.

# Valiant-Valiant Multidimensional CLT

Sum of many independent “reasonable”  **$q$ -dimensional** random variables is close to  **$q$ -dimensional** Gaussian of same mean and variance.

with respect to **Earth Mover Distance**:

Minimum amount of work necessary to “get one PDF to look like the other”, where **work** := mass x distance



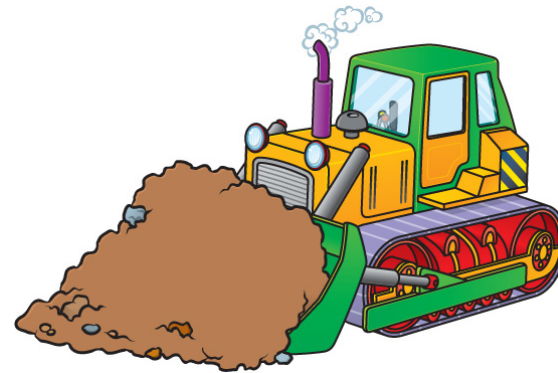
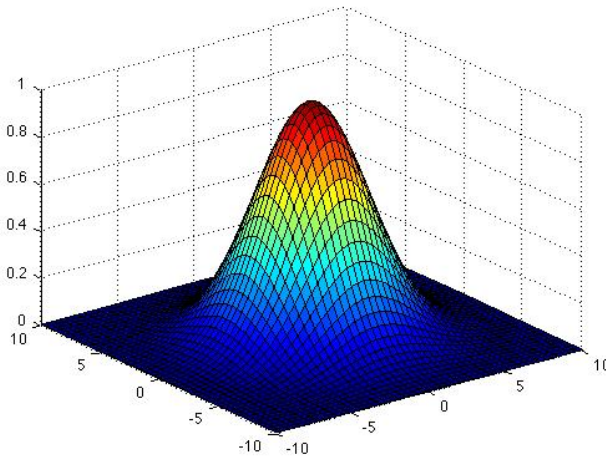
**Key technical lemma:**

Closeness in EMD  $\longrightarrow$  roughly equal weight on any union of orthants

# Valiant-Valiant Multidimensional CLT

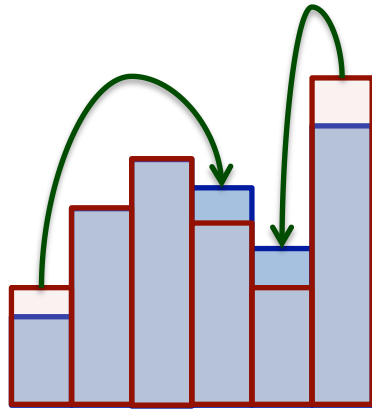
Let  $\mathbf{S} = \mathbf{X}_1 + \cdots + \mathbf{X}_n$ , where the  $\mathbf{X}_j$ 's are independent  $\mathbb{R}^q$ -valued random variables satisfying  $\|\mathbf{X}_j - \mathbf{E}[\mathbf{X}_j]\|_2 \leq \tau$  with probability 1 for all  $j \in [n]$ . Let  $\mathcal{G}$  be the  $q$ -dimensional Gaussian with the same mean and covariance matrix as  $\mathbf{S}$ . Then

$$d_{\text{EMD}}(\mathbf{S}, \mathcal{G}) \leq O(\tau q \log n).$$

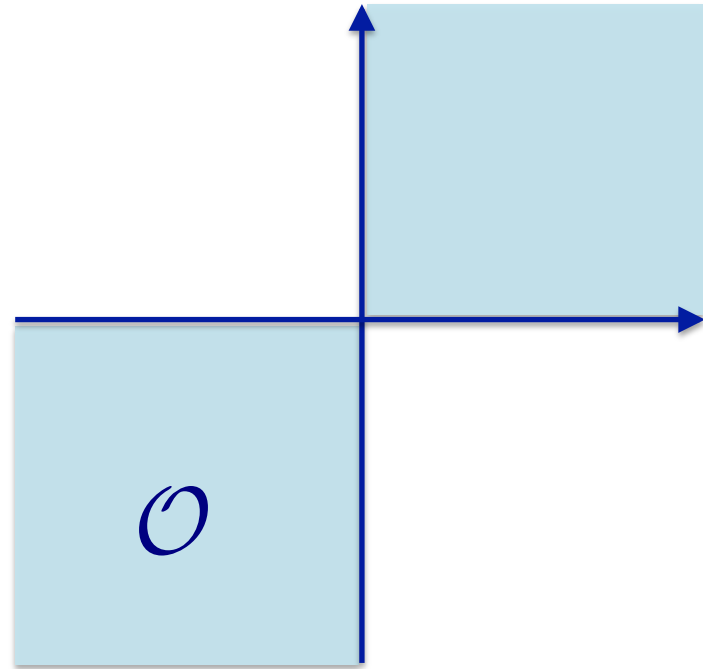


## Key technical lemma

Closeness in EMD



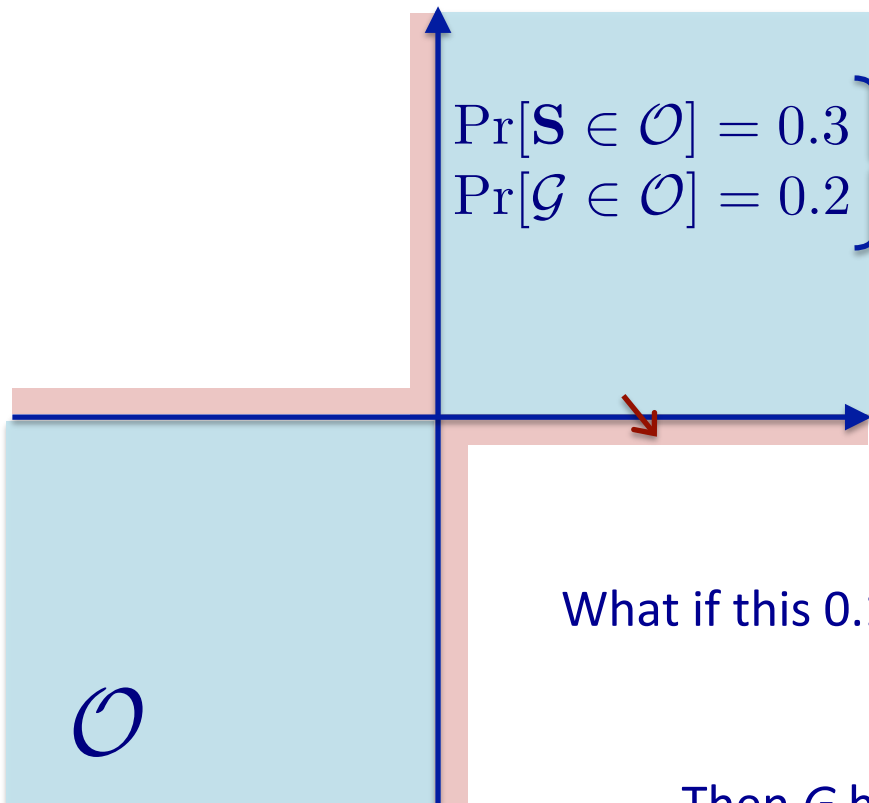
Roughly equal weight on any union of orthants



$$d_{\text{EMD}}(\mathbf{S}, \mathcal{G}) \text{ small} \implies |\Pr[\mathbf{S} \in \mathcal{O}] - \Pr[\mathcal{G} \in \mathcal{O}]| \text{ small}$$

$d_{\text{EMD}}(\mathbf{S}, \mathcal{G})$  small  $\implies |\Pr[\mathbf{S} \in \mathcal{O}] - \Pr[\mathcal{G} \in \mathcal{O}]|$  small  
for all unions of orthants  $\mathcal{O}$

Let's consider the contrapositive:



If we want to make  $\mathbf{S}$  look like  $\mathcal{G}$ ,  
 $\geq 0.1$  unit of mass must be moved  
out of  $\mathcal{O}$  😊

Recall:  
**work** = mass x distance



**Slight technical obstacle:**

What if this 0.1 unit of mass only moves a *tiny* distance?

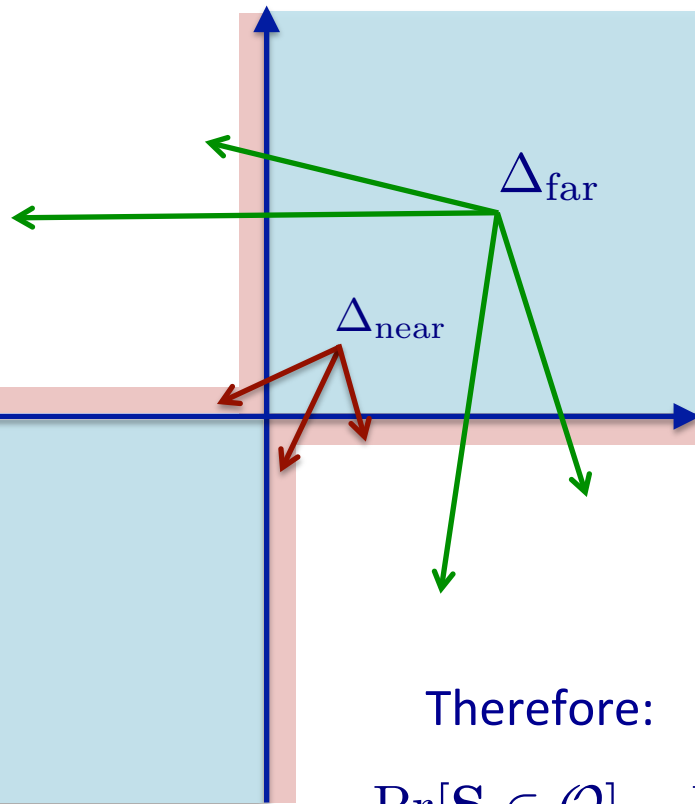
**Solution:**

Then  $\mathcal{G}$  has  $\geq 0.1$  weight on red boundary.  
Not possible thanks to anti-concentration of  $\mathcal{G}$  😊



## In slightly more detail

$\Pr[\mathbf{S} \in \mathcal{O}] - \Pr[\mathcal{G} \in \mathcal{O}] = \Delta$ , has to be moved out of  $\mathcal{O}$



For all  $r > 0$ ,  
define  $B_r :=$  radius  $r$  boundary around  $\mathcal{O}$

$$\Delta = \Delta_{\text{near}} + \Delta_{\text{far}}$$

$$\Delta_{\text{near}} \leq \Pr[\mathcal{G} \in B_r]$$

$$r \cdot \Delta_{\text{far}} \leq d_{\text{EMD}}(\mathbf{S}, \mathcal{G})$$

Therefore:

$$\Pr[\mathbf{S} \in \mathcal{O}] - \Pr[\mathcal{G} \in \mathcal{O}] \leq \frac{d_{\text{EMD}}(\mathbf{S}, \mathcal{G})}{r} + \Pr[\mathcal{G} \in B_r]$$

## We just proved

Let  $\mathbf{S} = \mathbf{X}_1 + \cdots + \mathbf{X}_n$ , where the  $\mathbf{X}_j$ 's are independent  $\mathbb{R}^q$ -valued random variables. Let  $\mathcal{G}$  be the  $q$ -dimensional Gaussian with the same mean and covariance matrix as  $\mathbf{S}$ . Then for all unions of orthants  $\mathcal{O} \subseteq \mathbb{R}^q$  and for all  $r > 0$ ,

$$\left| \Pr[\mathbf{S} \in \mathcal{O}] - \Pr[\mathcal{G} \in \mathcal{O}] \right| \leq \underbrace{\frac{d_{\text{EMD}}(\mathbf{S}, \mathcal{G})}{r}}_{\text{Valiant-Valiant CLT}} + \underbrace{\Pr[\mathcal{G} \in B_r]}_{\text{Gaussian anti-concentration}}$$

## Recap

**Indistinguishability.** For all  $T =$  deterministic tester that makes  $q = o(n^{1/5})$  queries,

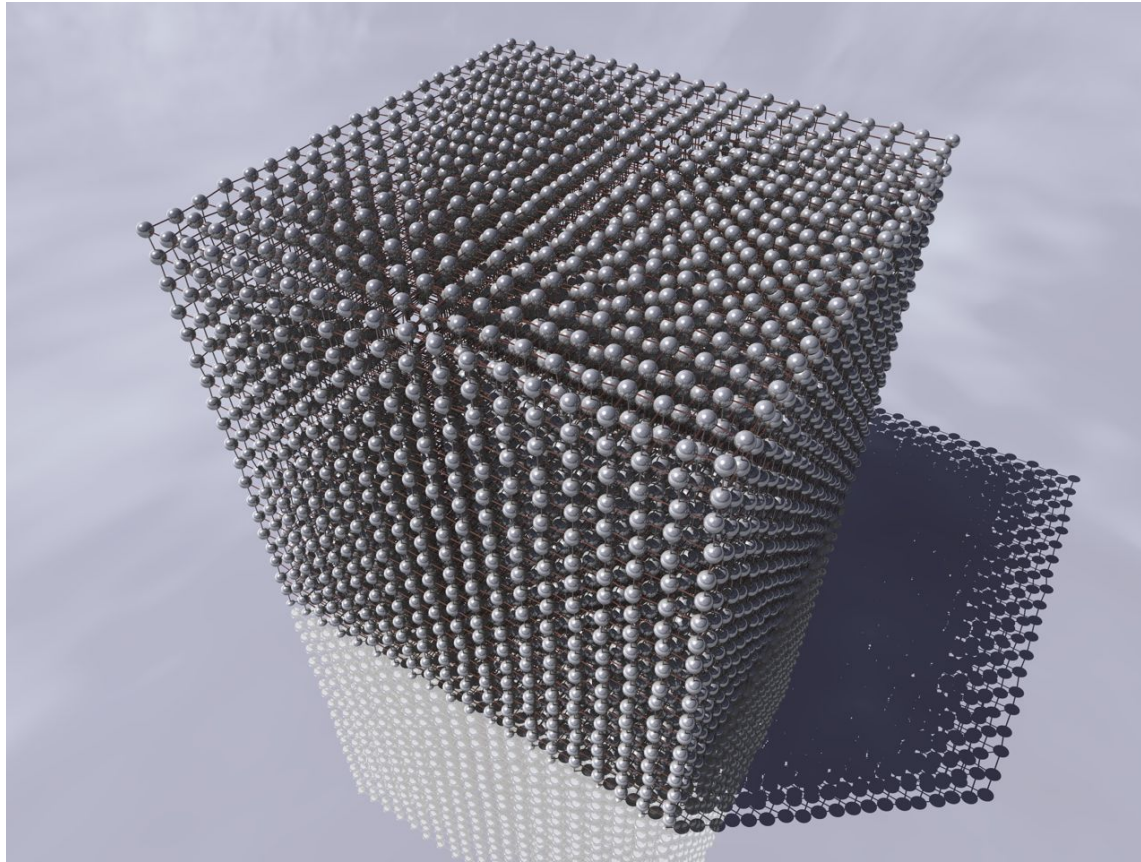
$$\left| \Pr_{\mathbf{f}_{yes} \sim \mathcal{D}_{yes}} [\mathcal{T} \text{ accepts } \mathbf{f}_{yes}] - \Pr_{\mathbf{f}_{no} \sim \mathcal{D}_{no}} [\mathcal{T} \text{ accepts } \mathbf{f}_{no}] \right| = o_n(1)$$



### Theorem

Any non-adaptive tester must make  $\tilde{\Omega}(n^{1/5})$  queries.  
Therefore, any adaptive tester must make  $\Omega(\log n)$  queries.

# Testing monotonicity of Boolean functions over general hypergrid domains



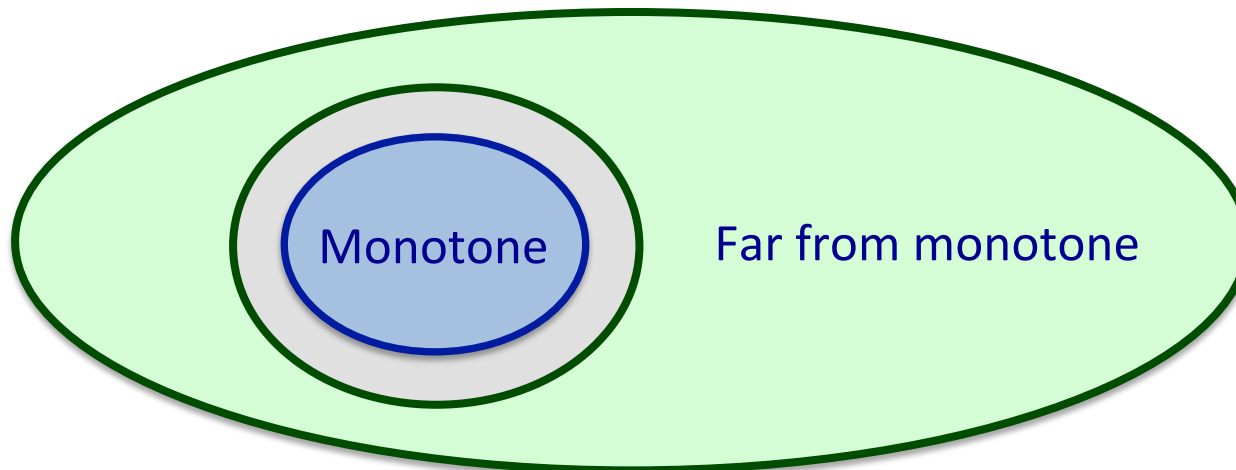
## Boolean functions over hypergrids

$$F : \{1, 2, \dots, m\}^n \rightarrow \{0, 1\}$$

Testing monotonicity of Boolean functions over hypergrids

**All hypergrid functions**

~~All Boolean functions~~



**Theorem [Chen-Servedio-T 2014]**

Any non-adaptive tester for testing monotonicity of  $f : [m]^n \rightarrow \{0, 1\}$  must make  $\tilde{\Omega}(n^{1/5})$  queries.

Proof by reduction to  $m=2$  case (Boolean hypercube)

# A useful characterization

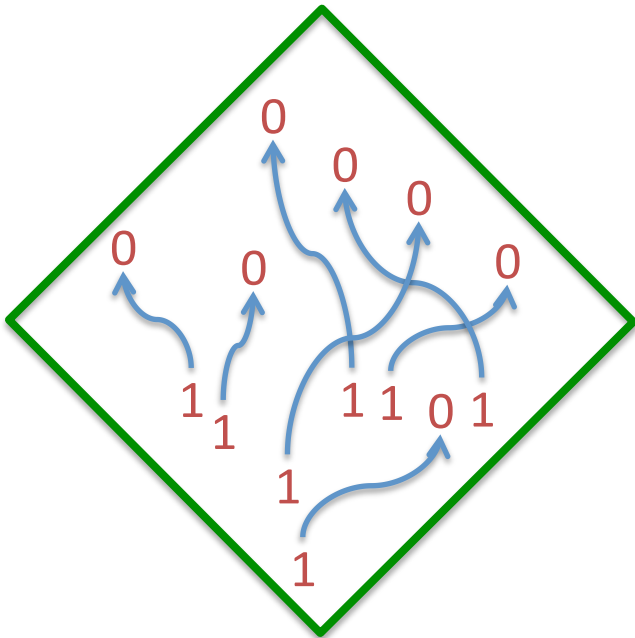
**Theorem.** [Dodis *et al.* 1999]

$F : \{1, 2, \dots, m\}^n \rightarrow \{0, 1\}$  is  $\varepsilon$ -far from monotone



There exists  $\varepsilon \cdot m^n$  vertex-disjoint pairs  $(x_i, y_i) \in [m]^n$   
such that  $x_i \preceq y_i$  and  $f(x_i) > f(y_i)$ .

“violating pair”



(Upward direction is easy)

## Reducing to $m = 2$

Given any  $f : \{0, 1\}^n \rightarrow \{0, 1\}$ , define  $F : [m]^n \rightarrow \{0, 1\}$  as follows:

$$F(\underbrace{x_1, \dots, x_n}_{\text{numbers in } [m]}) = f(\underbrace{\mathbf{1}[x_1 > \frac{m}{2}], \dots, \mathbf{1}[x_n > \frac{m}{2}]}_{\text{bits in } \{0,1\}})$$

Easy: If  $f$  is monotone then so is  $F$ .

**Remains to argue:**

If  $f$  is  $\varepsilon$ -far from monotone then so is  $F$ .

Useful  
characterization

Useful  
characterization

Exists  $\varepsilon 2^n$  vertex-disjoint pairs in  $\{0,1\}^n$  that are violations w.r.t.  $f$

suffices to show:

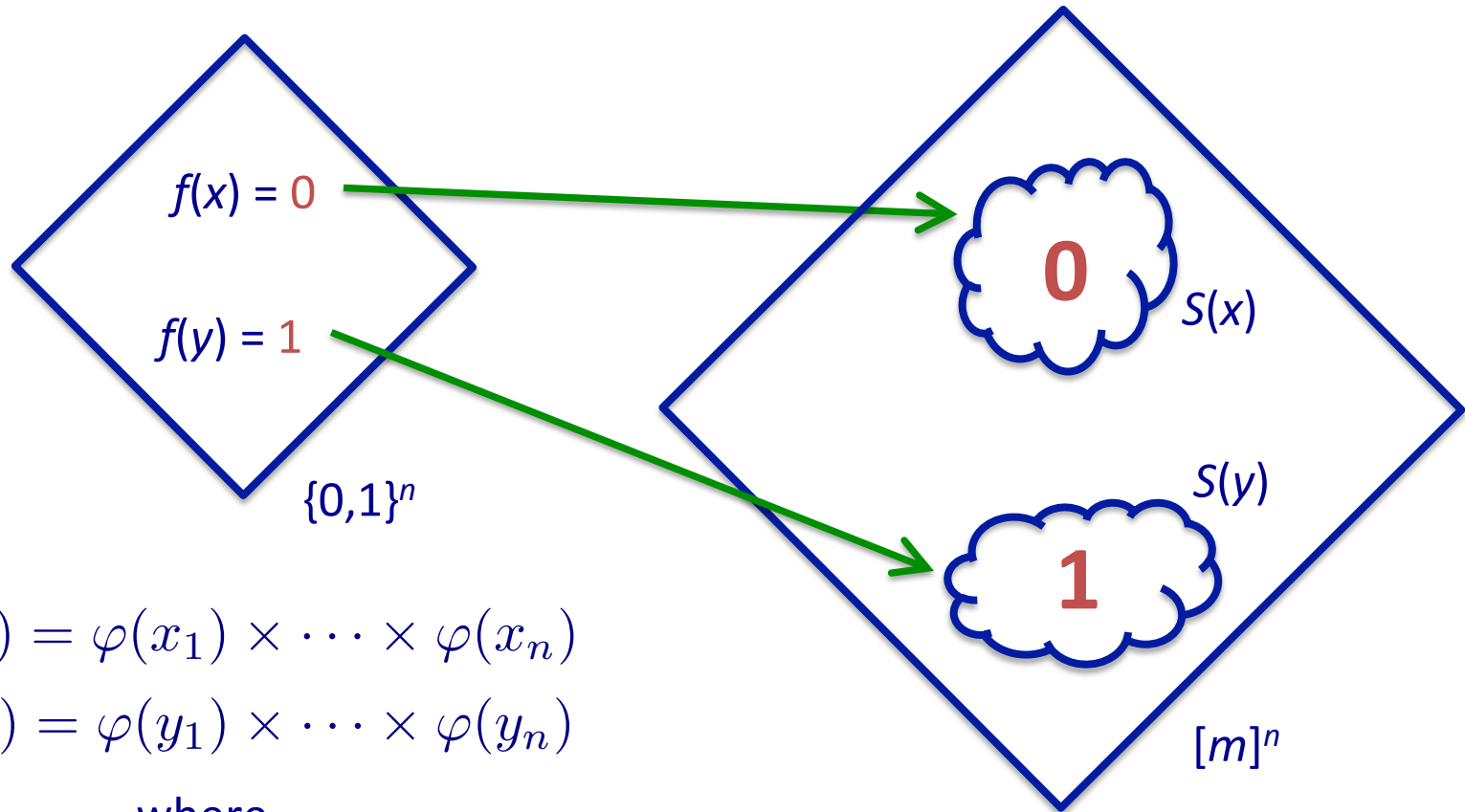
Exists  $\varepsilon \cdot m^n$  vertex-disjoint pairs in  $[m]^n$  that are violations w.r.t.  $F$

Each violating pair

$(m/2)^n$  vertex-disjoint violating pairs



Each violating pair in  $\{0, 1\}^n \implies \left(\frac{m}{2}\right)^n$  violating pairs in  $[m]^n$



$$S(x) = \varphi(x_1) \times \cdots \times \varphi(x_n)$$

$$S(y) = \varphi(y_1) \times \cdots \times \varphi(y_n)$$

where

$$\varphi(0) = \{0, 1, \dots, \frac{m}{2}\}$$

$$\varphi(1) = \{\frac{m}{2} + 1, \dots, m\}$$

$$|S(x)| = |S(y)| = (m/2)^n$$

Easy end game: exhibit order-preserving bijection between  $S(x)$  and  $S(y)$

# Conclusion

- A polynomial lower bound for testing monotonicity of Boolean functions

## Theorem

Any non-adaptive tester must make  $\tilde{\Omega}(n^{1/5})$  queries.  
Therefore, any adaptive tester must make  $\Omega(\log n)$  queries.

- Main technical ingredient: multidimensional central limit theorems
- Proof extends to testing monotonicity over general hypergrid domains

**Open Problem:** Polynomial lower bounds against *adaptive* testers?

Thank you!