

neural networks for natural language processing (nn4nlp)

Chris Kedzie
kedzie@cs.columbia.edu

October 31, 2017

who am i?

Chris Kedzie

kedzie@cs.columbia.edu

Ph.D. Candidate

(Advisor: Kathy McKeown)

Interested in text summarization, compression, and generation.

Lesson Plan

linear models

multi-layer perceptron

optimization

feed-forward language model

Lesson Plan

linear models

multi-layer perceptron

optimization

feed-forward language model

Linear Models

Whenever we want to classify a document, a tweet, etc., we typically train a discriminative model $p(Y|X; W)$.

Predictive models usually built around a linear decision function:

$$\sum_{i=1}^d W_{y,i} \cdot \phi_i(x, y) > \sum_{i=1}^d W_{y',i} \cdot \phi_i(x, y') \quad \forall y' \neq y$$

Linear Models

Whenever we want to classify a document, a tweet, etc., we typically train a discriminative model $p(Y|X; W)$.

Predictive models usually built around a linear decision function:

$$\sum_{i=1}^d W_{y,i} \cdot \phi_i(x, y) > \sum_{i=1}^d W_{y',i} \cdot \phi_i(x, y') \quad \forall y' \neq y$$

- ▶ $W \in \mathbb{R}^{|\mathcal{Y}| \times d} \triangleq$ a matrix of weights for each feature function and class label $y \in \mathcal{Y}$

Linear Models

Whenever we want to classify a document, a tweet, etc., we typically train a discriminative model $p(Y|X; W)$.

Predictive models usually built around a linear decision function:

$$\sum_{i=1}^d W_{y,i} \cdot \phi_i(x, y) > \sum_{i=1}^d W_{y',i} \cdot \phi_i(x, y') \quad \forall y' \neq y$$

- ▶ $W \in \mathbb{R}^{|\mathcal{Y}| \times d} \triangleq$ a matrix of weights for each feature function and class label $y \in \mathcal{Y}$
- ▶ Feature templates of the form $\phi_i : \mathcal{X} \times \mathcal{Y} \rightarrow \mathbb{R}$

Example: Classifying Political Tweets w/ Logistic Regression

Example: Classifying Political Tweets w/ Logistic Regression

$$\phi(x, y) = \mathbb{1} \{ \text{ngram}(\textit{affordable, care, act}) \in x \wedge y = \textit{democrat} \}$$

Example: Classifying Political Tweets w/ Logistic Regression

$$\phi(x, y) = \mathbb{1} \{ \text{ngram}(\textit{affordable, care, act}) \in x \wedge y = \textit{democrat} \}$$

$$\phi(x, y) = \mathbb{1} \{ \text{ngram}(\textit{obamacare}) \in x \wedge y = \textit{republican} \}$$

Example: Classifying Political Tweets w/ Logistic Regression

$$\phi(x, y) = \mathbb{1} \{ \text{ngram}(\textit{affordable, care, act}) \in x \wedge y = \textit{democrat} \}$$

$$\phi(x, y) = \mathbb{1} \{ \text{ngram}(\textit{obamacare}) \in x \wedge y = \textit{republican} \}$$

$$\phi(x, y) = \mathbb{1} \{ \text{ngram}(\textit{ACA}) \in x \wedge y = \textit{democrat} \}$$

⋮

Example: Classifying Political Tweets w/ Logistic Regression

$$\phi(x, y) = \mathbb{1} \{ \text{ngram}(\textit{affordable, care, act}) \in x \wedge y = \textit{democrat} \}$$

$$\phi(x, y) = \mathbb{1} \{ \text{ngram}(\textit{obamacare}) \in x \wedge y = \textit{republican} \}$$

$$\phi(x, y) = \mathbb{1} \{ \text{ngram}(\textit{ACA}) \in x \wedge y = \textit{democrat} \}$$

⋮

$$p(Y = \textit{democrat} | X = x) = \frac{\exp(\sum_i W_{\textit{dem}, i} \cdot \phi_i(x, \textit{dem}))}{\sum_{y \in \{\textit{dem}, \textit{rep}\}} \exp(\sum_i W_{y, i} \cdot \phi_i(x, y))}$$

Example: Classifying Political Tweets w/ Logistic Regression

- ▶ Designing features can be challenging in certain domains. E.g. speech recognition or image classification.

Example: Classifying Political Tweets w/ Logistic Regression

- ▶ Designing features can be challenging in certain domains. E.g. speech recognition or image classification.
- ▶ **Inefficient parameter sharing!**

Learning about

$$\phi(x, y) = \mathbb{1} \{ \text{ngram}(\textit{affordable}, \textit{care}, \textit{act}) \in x \wedge y = \textit{democrat} \}$$

doesn't tell us anything about

$$\phi(x, y) = \mathbb{1} \{ \text{ngram}(\textit{ACA}) \in x \wedge y = \textit{democrat} \}$$

even though they may occur in similar contexts.

By comparison, neural network models will allow us to efficiently **share parameters** and **learn useful representations**.

They also have their own particular shortcomings as well!

Lesson Plan

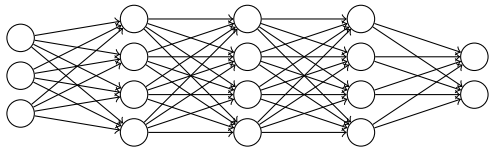
linear models

multi-layer perceptron

optimization

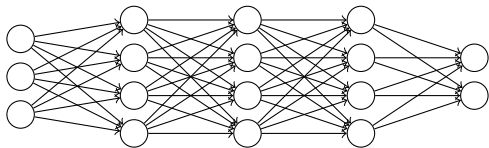
feed-forward language model

Feed-forward Neural Network



Feed-forward Neural Network

- ▶ Input is introduced to the first layer neurons.

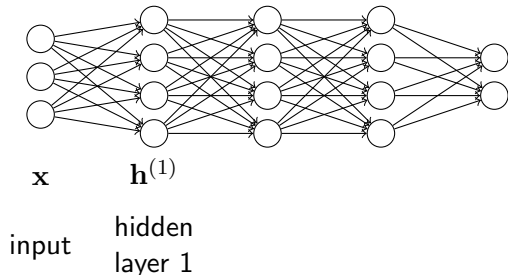


x

input

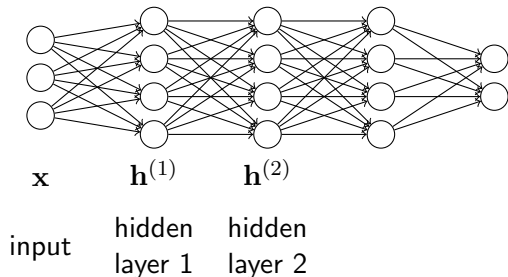
Feed-forward Neural Network

- ▶ Input is introduced to the first layer neurons.
- ▶ Each successive layer activates the next layer,



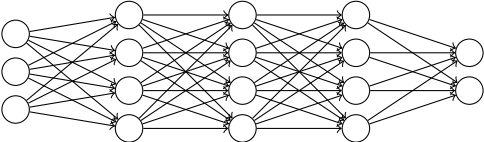
Feed-forward Neural Network

- ▶ Input is introduced to the first layer neurons.
- ▶ Each successive layer activates the next layer,



Feed-forward Neural Network

- ▶ Input is introduced to the first layer neurons.
- ▶ Each successive layer activates the next layer,



x

h⁽¹⁾

h⁽²⁾

h⁽³⁾

input

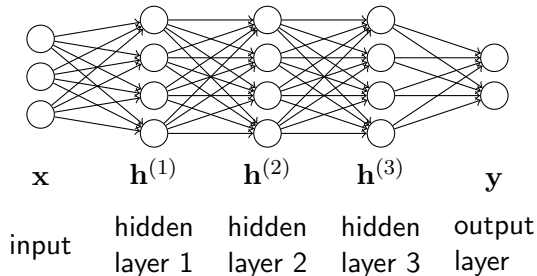
hidden
layer 1

hidden
layer 2

hidden
layer 3

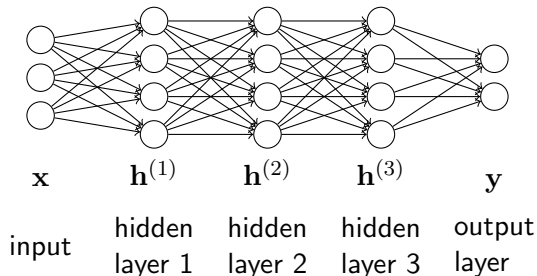
Feed-forward Neural Network

- ▶ Input is introduced to the first layer neurons.
- ▶ Each successive layer activates the next layer,
- ▶ finally, producing activations at the output neurons.



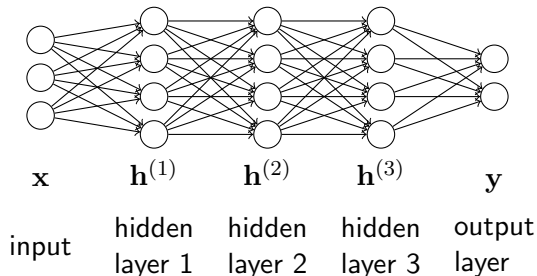
Feed-forward Neural Network

- ▶ Input is introduced to the first layer neurons.
- ▶ Each successive layer activates the next layer,
- ▶ finally, producing activations at the output neurons.
- ▶ Fully connected: each neuron in layer i connects to every neuron in layer $i + 1$.



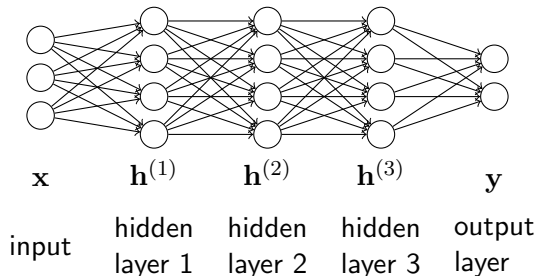
Feed-forward Neural Network

- ▶ Input is introduced to the first layer neurons.
- ▶ Each successive layer activates the next layer,
- ▶ finally, producing activations at the output neurons.
- ▶ Fully connected: each neuron in layer i connects to every neuron in layer $i + 1$.
- ▶ No feedback/cycles (network is a directed acyclic graph).



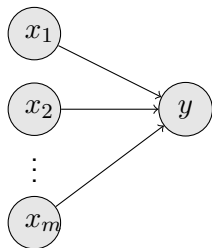
Feed-forward Neural Network

- ▶ Input is introduced to the first layer neurons.
- ▶ Each successive layer activates the next layer,
- ▶ finally, producing activations at the output neurons.
- ▶ Fully connected: each neuron in layer i connects to every neuron in layer $i + 1$.
- ▶ No feedback/cycles (network is a directed acyclic graph).
- ▶ Not a generative model of the input (discriminative).



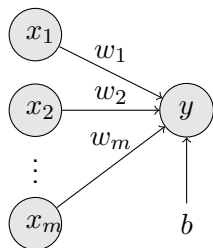
Single Layer Perceptron

(m input neurons, 1 output neuron)



Single Layer Perceptron

(m input neurons, 1 output neuron)

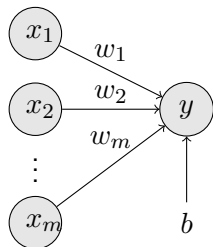


$$\text{activation } y = f \left(\underbrace{\sum_{i=1}^m w_i \cdot x_i + b}_{\text{preactivation}} \right)$$

- ▶ w_i indicates the strength of the connection between the input activation x_i and the output activation y .

Single Layer Perceptron

(m input neurons, 1 output neuron)

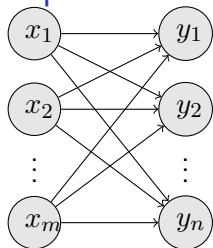


$$\text{activation } y = f \left(\underbrace{\sum_{i=1}^m w_i \cdot x_i + b}_{\text{preactivation}} \right)$$

- ▶ w_i indicates the strength of the connection between the input activation x_i and the output activation y .
- ▶ $f : \mathbb{R} \rightarrow \mathbb{R}$ is a nonlinear function.
Typically, tanh, relu, sigmoid, or softmax.

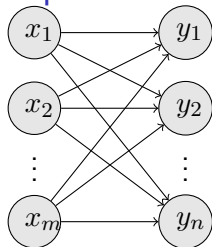
Single Layer Perceptron

(m input neurons, n output neuron)



Single Layer Perceptron

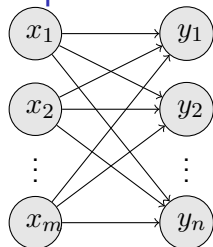
(m input neurons, n output neuron)



►
$$y_i = f \left(\sum_{j=1}^m w_{i,j} \cdot x_j + b_i \right)$$

Single Layer Perceptron

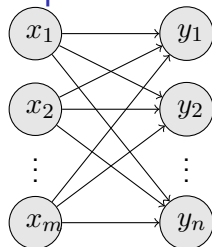
(m input neurons, n output neuron)



- ▶ $y_i = f \left(\sum_{j=1}^m w_{i,j} \cdot x_j + b_i \right)$
- ▶ Equivalently, $y = f(W^\top x + b)$
where $W \in \mathbb{R}^{m \times n}$, $x \in \mathbb{R}^m$, and $b \in \mathbb{R}^n$

Single Layer Perceptron

(m input neurons, n output neuron)



- ▶ $y_i = f \left(\sum_{j=1}^m w_{i,j} \cdot x_j + b_i \right)$
- ▶ Equivalently, $y = f(W^\top x + b)$
where $W \in \mathbb{R}^{m \times n}$, $x \in \mathbb{R}^m$, and $b \in \mathbb{R}^n$
- ▶ f is applied elementwise to a vector $v \in \mathbb{R}^n$:

$$f(v) = [f(v_1) \quad f(v_2) \quad \dots \quad f(v_n)]$$

$$f(v)_i = f(v_i)$$

Limitations of a single layer perceptron

- ▶ Can only learn functions where input is linearly separable.

Limitations of a single layer perceptron

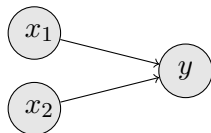
- ▶ Can only learn functions where input is linearly separable.
- ▶ E.g. Can't learn xor function.

Limitations of a single layer perceptron

- ▶ Can only learn functions where input is linearly separable.
- ▶ E.g. Can't learn xor function.
- ▶ We could design a different kernel/feature representation.

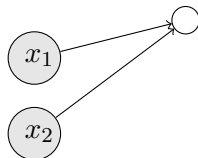
Limitations of a single layer perceptron

- ▶ Can only learn functions where input is linearly separable.
- ▶ E.g. Can't learn xor function.
- ▶ We could design a different kernel/feature representation.
- ▶ Or simply add more layers...



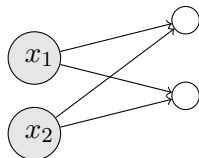
Limitations of a single layer perceptron

- ▶ Can only learn functions where input is linearly separable.
- ▶ E.g. Can't learn xor function.
- ▶ We could design a different kernel/feature representation.
- ▶ Or simply add more layers...



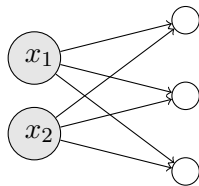
Limitations of a single layer perceptron

- ▶ Can only learn functions where input is linearly separable.
- ▶ E.g. Can't learn xor function.
- ▶ We could design a different kernel/feature representation.
- ▶ Or simply add more layers...



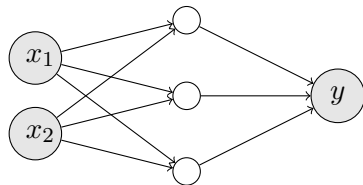
Limitations of a single layer perceptron

- ▶ Can only learn functions where input is linearly separable.
- ▶ E.g. Can't learn xor function.
- ▶ We could design a different kernel/feature representation.
- ▶ Or simply add more layers...

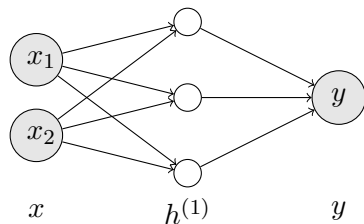


Limitations of a single layer perceptron

- ▶ Can only learn functions where input is linearly separable.
- ▶ E.g. Can't learn xor function.
- ▶ We could design a different kernel/feature representation.
- ▶ Or simply add more layers...

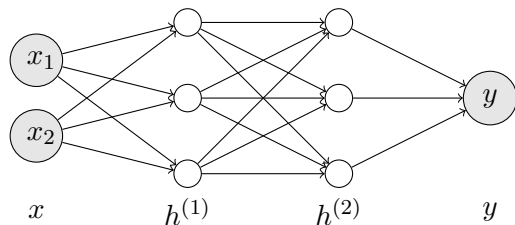


Multi-Layer Perceptron



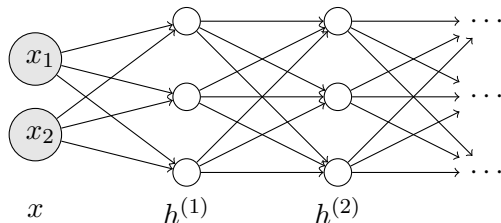
$$h^{(1)} = f(W^{(1)} \cdot x + b^{(1)})$$
$$y = f(W^{(2)} \cdot h^{(1)} + b^{(2)})$$

Multi-Layer Perceptron



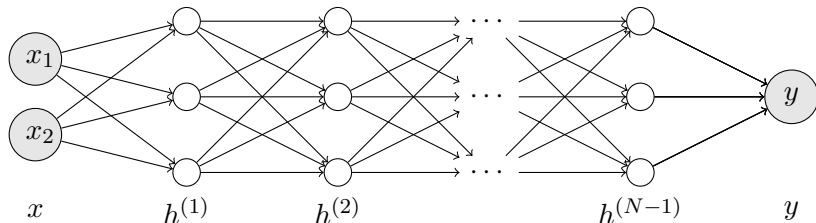
$$\begin{aligned}h^{(1)} &= f(W^{(1)} \cdot x + b^{(1)}) \\h^{(2)} &= f(W^{(2)} \cdot h^{(1)} + b^{(2)}) \\y &= f(W^{(3)} \cdot h^{(2)} + b^{(3)})\end{aligned}$$

Multi-Layer Perceptron



$$\begin{aligned}h^{(1)} &= f(W^{(1)} \cdot x + b^{(1)}) \\h^{(2)} &= f(W^{(2)} \cdot h^{(1)} + b^{(2)}) \\ \vdots & \quad \vdots \quad \vdots\end{aligned}$$

Multi-Layer Perceptron



$$\begin{aligned}h^{(1)} &= f(W^{(1)} \cdot x + b^{(1)}) \\h^{(2)} &= f(W^{(2)} \cdot h^{(1)} + b^{(2)}) \\&\vdots \\y &= f(W^{(N)} \cdot h^{(N-1)} + b^{(N)})\end{aligned}$$

Activation Functions

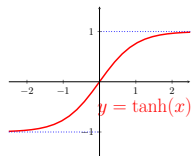
- ▶ tanh
- ▶ ReLU
- ▶ sigmoid
- ▶ softmax

There are many variants/alternative functions with different properties.

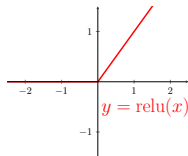
Must be continuous and differentiable (almost everywhere)

Activation Functions (hidden layers)

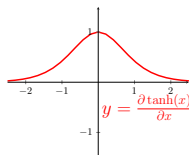
$$\tanh(x) = \frac{1 - \exp(-2x)}{1 + \exp(-2x)}$$



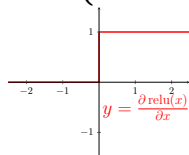
$$\text{relu}(x) = \max(0, x)$$



$$\frac{\partial \tanh(x)}{\partial x} = 1 - \tanh^2(x)$$



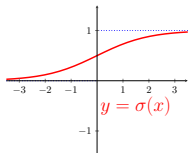
$$\frac{\partial \text{relu}(x)}{\partial x} = \begin{cases} 1 & \text{if } x > 0 \\ 0 & \text{otherwise} \end{cases}$$



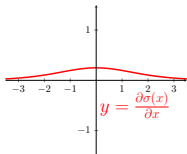
Activation Functions (hidden layers/output layers)

Logistic Sigmoid

$$\sigma(x) = \frac{1}{1 + \exp(-x)}$$



$$\frac{\partial \sigma(x)}{\partial x} = \sigma(x) \cdot (1 - \sigma(x))$$



Softmax

$$\sigma(x)_i = \frac{\exp(x_i)}{\sum_{i'=1}^d \exp(x_{i'})} \text{ where } x \in \mathbb{R}^d$$

$$\frac{\partial \sigma(x)_i}{\partial x_j} = \begin{cases} \sigma(x)_i \cdot (1 - \sigma(x)_i) & \text{if } i = j \\ -\sigma(x)_i \cdot \sigma(x)_j & \text{if } i \neq j \end{cases}$$

Activation Functions (output layers)

- ▶ Output layer typically a sigmoid or softmax
- ▶ $a = W^{(N)} \cdot h^{(N-1)} + b^{(N)}$
- ▶ sigmoid:

$$p(Y = 1|X = x; \theta) = \sigma(a) = \frac{1}{1 + \exp(-a)}$$

$$p(Y = 0|X = x; \theta) = 1 - p(Y = 1|X = x; \theta)$$

- ▶ softmax:

$$p(Y = i|X = x; \theta) = \sigma(a)_i = \frac{\exp(a_i)}{\sum_{i'} \exp(a_{i'})}$$

Lesson Plan

linear models

multi-layer perceptron

optimization

feed-forward language model

Loss Functions/Objective Functions

Cross Entropy

- ▶ Given a training dataset $\mathcal{D} = (x^{(i)}, y^{(i)})|_{i=1}^N$
- ▶ Multi-Class Cross Entropy loss:

$$\mathcal{L}(\theta) = -\frac{1}{N} \sum_i \ln p(y^{(i)} | x^{(i)}; \theta)$$

- ▶ Also referred to as the negative log likelihood.

Optimization

Learning of the network parameters θ is done by minimizing the loss function with respect to θ .

$$\min_{\theta} \mathcal{L}(\theta)$$

Typically, this is done by performing some variant of **stochastic gradient descent** (SGD).

Algorithm 1 Stochastic Gradient Descent

- 1: Randomly initialize θ .
 - 2: **for** EPOCH = 1 to MAXEPOCHS **do**
 - 3: Shuffle dataset $\mathcal{D} = (x^{(i)}, y^{(i)})|_{i=1}^N$
 - 4: **for** $i = 1$ to N **do**
 - 5: $\theta \leftarrow \theta - \eta \frac{\partial \mathcal{L}_i(\theta)}{\partial \theta}$
 - 6: **end for**
 - 7: **end for**
-

Optimization

Learning of the network parameters θ is done by minimizing the loss function with respect to θ .

$$\min_{\theta} \mathcal{L}(\theta)$$

Typically, this is done by performing some variant of **stochastic gradient descent** (SGD).

Algorithm 2 Stochastic Gradient Descent

- 1: Randomly initialize θ .
 - 2: **for** EPOCH = 1 to MAXEPOCHS **do**
 - 3: Shuffle dataset $\mathcal{D} = (x^{(i)}, y^{(i)})|_{i=1}^N$
 - 4: **for** $i = 1$ to N **do**
 - 5: $\theta \leftarrow \theta - \eta \frac{\partial \mathcal{L}_i(\theta)}{\partial \theta}$
 - 6: **end for**
 - 7: **end for**
-

η is the learning rate, typically a small value e.g. 10^{-3}

Backpropagation

To perform SGD, we need to efficiently compute $\frac{\partial \mathcal{L}_i(\theta)}{\partial \theta}$.

- ▶ Forward pass — compute the $\mathcal{L}_i(\theta)$ (e.g. the probability of y_i) given input x_i with the current θ .
(Store intermediate outputs for backward pass)
- ▶ Backward pass — propagate the gradient of the loss backwards through the network, collecting the parameter gradients $\nabla \theta$

Chain Rule of Calculus

We want to compute the derivative of nested function $f(g(x))$ with respect to x .

By the chain rule:

$$\frac{df(g(x))}{dx} = \frac{df(g(x))}{dg(x)} \cdot \frac{dg(x)}{dx}$$

Chain Rule of Calculus

We want to compute the derivative of nested function $f(g(x))$ with respect to x .

By the chain rule:

$$\frac{df(g(x))}{dx} = \frac{df(g(x))}{dg(x)} \cdot \frac{dg(x)}{dx}$$

A concrete example:

$$\begin{aligned} f(z) &= \ln z & \frac{df(z)}{dz} &= \frac{1}{z} \\ g(x) &= 2x & \frac{dg(x)}{dx} &= 2 \end{aligned}$$

Chain Rule of Calculus

We want to compute the derivative of nested function $f(g(x))$ with respect to x .

By the chain rule:

$$\frac{df(g(x))}{dx} = \frac{df(g(x))}{dg(x)} \cdot \frac{dg(x)}{dx}$$

A concrete example:

$$\begin{aligned} f(z) &= \ln z & \frac{df(z)}{dz} &= \frac{1}{z} \\ g(x) &= 2x & \frac{dg(x)}{dx} &= 2 \end{aligned}$$

$$\frac{df(g(x))}{dx} = \frac{df(g(x))}{dg(x)} \cdot \frac{dg(x)}{dx}$$

Chain Rule of Calculus

We want to compute the derivative of nested function $f(g(x))$ with respect to x .

By the chain rule:

$$\frac{df(g(x))}{dx} = \frac{df(g(x))}{dg(x)} \cdot \frac{dg(x)}{dx}$$

A concrete example:

$$\begin{aligned} f(z) &= \ln z & \frac{df(z)}{dz} &= \frac{1}{z} \\ g(x) &= 2x & \frac{dg(x)}{dx} &= 2 \end{aligned}$$

$$\begin{aligned} \frac{df(g(x))}{dx} &= \frac{df(g(x))}{dg(x)} \cdot \frac{dg(x)}{dx} \\ &= \frac{1}{2x} \cdot 2 \end{aligned}$$

Chain Rule of Calculus

We want to compute the derivative of nested function $f(g(x))$ with respect to x .

By the chain rule:

$$\frac{df(g(x))}{dx} = \frac{df(g(x))}{dg(x)} \cdot \frac{dg(x)}{dx}$$

A concrete example:

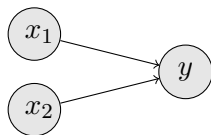
$$\begin{aligned} f(z) &= \ln z & \frac{df(z)}{dz} &= \frac{1}{z} \\ g(x) &= 2x & \frac{dg(x)}{dx} &= 2 \end{aligned}$$

$$\begin{aligned} \frac{df(g(x))}{dx} &= \frac{df(g(x))}{dg(x)} \cdot \frac{dg(x)}{dx} \\ &= \frac{1}{2x} \cdot 2 = \frac{1}{x} \end{aligned}$$

Backpropagation (Forward Pass)

Simple, 1-layer sigmoid network

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$
- ▶ $\mathcal{D} = \{(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)})\}$
where $x^{(1)}, x^{(2)} \in \mathbb{R}^2$ and $y^{(1)}, y^{(2)} \in \{0, 1\}$
- ▶ $y^{(1)} = 1, y^{(2)} = 0$



Backpropagation (Forward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$
- ▶ $\mathcal{D} = \{(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)})\}$
where $x^{(1)}, x^{(2)} \in \mathbb{R}^2$ and $y^{(1)}, y^{(2)} \in \{0, 1\}$
- ▶ $y^{(1)} = 1, y^{(2)} = 0$

Forward Pass

Backpropagation (Forward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$
- ▶ $\mathcal{D} = \{(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)})\}$
where $x^{(1)}, x^{(2)} \in \mathbb{R}^2$ and $y^{(1)}, y^{(2)} \in \{0, 1\}$
- ▶ $y^{(1)} = 1, y^{(2)} = 0$

Forward Pass

1. $a^{(1)} = w_1 \cdot x_1^{(1)} + w_2 \cdot x_2^{(1)} + b$

Backpropagation (Forward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$
- ▶ $\mathcal{D} = \{(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)})\}$
where $x^{(1)}, x^{(2)} \in \mathbb{R}^2$ and $y^{(1)}, y^{(2)} \in \{0, 1\}$
- ▶ $y^{(1)} = 1, y^{(2)} = 0$

Forward Pass

1. $a^{(1)} = w_1 \cdot x_1^{(1)} + w_2 \cdot x_2^{(1)} + b$
2. $p(Y = 1|x^{(1)}) = \sigma(a^{(1)})$

Backpropagation (Forward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$
- ▶ $\mathcal{D} = \{(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)})\}$
where $x^{(1)}, x^{(2)} \in \mathbb{R}^2$ and $y^{(1)}, y^{(2)} \in \{0, 1\}$
- ▶ $y^{(1)} = 1, y^{(2)} = 0$

Forward Pass

1. $a^{(1)} = w_1 \cdot x_1^{(1)} + w_2 \cdot x_2^{(1)} + b$
2. $p(Y = 1|x^{(1)}) = \sigma(a^{(1)})$
3. $p(y^{(1)}|x^{(1)}) = p(Y = 1|x^{(1)})$

Backpropagation (Forward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$
- ▶ $\mathcal{D} = \{(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)})\}$
where $x^{(1)}, x^{(2)} \in \mathbb{R}^2$ and $y^{(1)}, y^{(2)} \in \{0, 1\}$
- ▶ $y^{(1)} = 1, y^{(2)} = 0$

Forward Pass

1. $a^{(1)} = w_1 \cdot x_1^{(1)} + w_2 \cdot x_2^{(1)} + b$
2. $p(Y = 1|x^{(1)}) = \sigma(a^{(1)})$
3. $p(y^{(1)}|x^{(1)}) = p(Y = 1|x^{(1)})$
4. $a^{(2)} = w_1 \cdot x_1^{(2)} + w_2 \cdot x_2^{(2)} + b$

Backpropagation (Forward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$
- ▶ $\mathcal{D} = \{(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)})\}$
where $x^{(1)}, x^{(2)} \in \mathbb{R}^2$ and $y^{(1)}, y^{(2)} \in \{0, 1\}$
- ▶ $y^{(1)} = 1, y^{(2)} = 0$

Forward Pass

1. $a^{(1)} = w_1 \cdot x_1^{(1)} + w_2 \cdot x_2^{(1)} + b$
2. $p(Y = 1|x^{(1)}) = \sigma(a^{(1)})$
3. $p(y^{(1)}|x^{(1)}) = p(Y = 1|x^{(1)})$
4. $a^{(2)} = w_1 \cdot x_1^{(2)} + w_2 \cdot x_2^{(2)} + b$
5. $p(Y = 1|x^{(2)}) = \sigma(a^{(2)})$

Backpropagation (Forward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$
- ▶ $\mathcal{D} = \{(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)})\}$
where $x^{(1)}, x^{(2)} \in \mathbb{R}^2$ and $y^{(1)}, y^{(2)} \in \{0, 1\}$
- ▶ $y^{(1)} = 1, y^{(2)} = 0$

Forward Pass

1. $a^{(1)} = w_1 \cdot x_1^{(1)} + w_2 \cdot x_2^{(1)} + b$
2. $p(Y = 1|x^{(1)}) = \sigma(a^{(1)})$
3. $p(y^{(1)}|x^{(1)}) = p(Y = 1|x^{(1)})$
4. $a^{(2)} = w_1 \cdot x_1^{(2)} + w_2 \cdot x_2^{(2)} + b$
5. $p(Y = 1|x^{(2)}) = \sigma(a^{(2)})$
6. $p(y^{(2)}|x^{(2)}) = 1 - p(Y = 1|x^{(2)})$

Backpropagation (Forward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$
- ▶ $\mathcal{D} = \{(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)})\}$
where $x^{(1)}, x^{(2)} \in \mathbb{R}^2$ and $y^{(1)}, y^{(2)} \in \{0, 1\}$
- ▶ $y^{(1)} = 1, y^{(2)} = 0$

Forward Pass

1. $a^{(1)} = w_1 \cdot x_1^{(1)} + w_2 \cdot x_2^{(1)} + b$
2. $p(Y = 1|x^{(1)}) = \sigma(a^{(1)})$
3. $p(y^{(1)}|x^{(1)}) = p(Y = 1|x^{(1)})$
4. $a^{(2)} = w_1 \cdot x_1^{(2)} + w_2 \cdot x_2^{(2)} + b$
5. $p(Y = 1|x^{(2)}) = \sigma(a^{(2)})$
6. $p(y^{(2)}|x^{(2)}) = 1 - p(Y = 1|x^{(2)})$
7. $\mathcal{L} = -\frac{1}{2} [\ln p(y^{(1)}|x^{(1)}) + \ln p(y^{(2)}|x^{(2)})]$

Backpropagation (Backward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$

$$\frac{\partial \mathcal{L}}{\partial w_1} = -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial w_1} \right]$$

Backpropagation (Backward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$

$$\begin{aligned}\frac{\partial \mathcal{L}}{\partial w_1} &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial w_1} \right] \\ &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial p(y^{(1)}|x^{(1)})} \cdot \frac{\partial p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial p(y^{(2)}|x^{(2)})} \cdot \frac{\partial p(y^{(2)}|x^{(2)})}{\partial w_1} \right]\end{aligned}$$

Backpropagation (Backward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$

$$\begin{aligned}\frac{\partial \mathcal{L}}{\partial w_1} &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial w_1} \right] \\ &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial p(y^{(1)}|x^{(1)})} \cdot \frac{\partial p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial p(y^{(2)}|x^{(2)})} \cdot \frac{\partial p(y^{(2)}|x^{(2)})}{\partial w_1} \right] \\ &= -\frac{1}{2} \left[\begin{array}{l} \frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial p(y^{(1)}|x^{(1)})} \cdot \frac{\partial p(y^{(1)}|x^{(1)})}{\partial a^{(1)}} \cdot \frac{\partial a^{(1)}}{\partial w_1} \\ + \\ \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial p(y^{(2)}|x^{(2)})} \cdot \frac{\partial p(y^{(2)}|x^{(2)})}{\partial a^{(2)}} \cdot \frac{\partial a^{(2)}}{\partial w_1} \end{array} \right]\end{aligned}$$

Backpropagation (Backward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$

$$\begin{aligned}\frac{\partial \mathcal{L}}{\partial w_1} &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial w_1} \right] \\ &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial p(y^{(1)}|x^{(1)})} \cdot \frac{\partial p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial p(y^{(2)}|x^{(2)})} \cdot \frac{\partial p(y^{(2)}|x^{(2)})}{\partial w_1} \right] \\ &= -\frac{1}{2} \left[\begin{array}{l} \frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial p(y^{(1)}|x^{(1)})} \cdot \frac{\partial p(y^{(1)}|x^{(1)})}{\partial a^{(1)}} \cdot \frac{\partial a^{(1)}}{\partial w_1} \\ + \\ \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial p(y^{(2)}|x^{(2)})} \cdot \frac{\partial p(y^{(2)}|x^{(2)})}{\partial a^{(2)}} \cdot \frac{\partial a^{(2)}}{\partial w_1} \end{array} \right]\end{aligned}$$

Backpropagation (Backward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$

$$\begin{aligned}\frac{\partial \mathcal{L}}{\partial w_1} &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial w_1} \right] \\ &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial p(y^{(1)}|x^{(1)})} \cdot \frac{\partial p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial p(y^{(2)}|x^{(2)})} \cdot \frac{\partial p(y^{(2)}|x^{(2)})}{\partial w_1} \right] \\ &= -\frac{1}{2} \left[\begin{aligned} &\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial p(y^{(1)}|x^{(1)})} \cdot \frac{\partial p(y^{(1)}|x^{(1)})}{\partial a^{(1)}} \cdot \mathbf{x}_1 \\ &+ \\ &\frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial p(y^{(2)}|x^{(2)})} \cdot \frac{\partial p(y^{(2)}|x^{(2)})}{\partial a^{(2)}} \cdot \mathbf{x}_1 \end{aligned} \right]\end{aligned}$$

Backpropagation (Backward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$

$$\begin{aligned}\frac{\partial \mathcal{L}}{\partial w_1} &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial w_1} \right] \\ &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial p(y^{(1)}|x^{(1)})} \cdot \frac{\partial p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial p(y^{(2)}|x^{(2)})} \cdot \frac{\partial p(y^{(2)}|x^{(2)})}{\partial w_1} \right] \\ &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial p(y^{(1)}|x^{(1)})} \cdot \frac{\partial p(y^{(1)}|x^{(1)})}{\partial a^{(1)}} \cdot x_1 \right. \\ &\quad \left. + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial p(y^{(2)}|x^{(2)})} \cdot \frac{\partial p(y^{(2)}|x^{(2)})}{\partial a^{(2)}} \cdot x_1 \right]\end{aligned}$$

Backpropagation (Backward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$

$$\begin{aligned}\frac{\partial \mathcal{L}}{\partial w_1} &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial w_1} \right] \\ &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial p(y^{(1)}|x^{(1)})} \cdot \frac{\partial p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial p(y^{(2)}|x^{(2)})} \cdot \frac{\partial p(y^{(2)}|x^{(2)})}{\partial w_1} \right] \\ &= -\frac{1}{2} \left[\begin{aligned} &\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial p(y^{(1)}|x^{(1)})} \cdot \sigma(a^{(1)})(1 - \sigma(a^{(1)})) \cdot x_1 \\ &+ \\ &\frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial p(y^{(2)}|x^{(2)})} \cdot -\sigma(a^{(2)})(1 - \sigma(a^{(2)})) \cdot x_1 \end{aligned} \right]\end{aligned}$$

Backpropagation (Backward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$

$$\begin{aligned}\frac{\partial \mathcal{L}}{\partial w_1} &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial w_1} \right] \\ &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial p(y^{(1)}|x^{(1)})} \cdot \frac{\partial p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial p(y^{(2)}|x^{(2)})} \cdot \frac{\partial p(y^{(2)}|x^{(2)})}{\partial w_1} \right] \\ &= -\frac{1}{2} \left[\begin{aligned} &\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial p(y^{(1)}|x^{(1)})} \cdot \sigma(a^{(1)})(1 - \sigma(a^{(1)})) \cdot x_1 \\ &+ \\ &\frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial p(y^{(2)}|x^{(2)})} \cdot -\sigma(a^{(2)})(1 - \sigma(a^{(2)})) \cdot x_1 \end{aligned} \right]\end{aligned}$$

Backpropagation (Backward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$

$$\begin{aligned}\frac{\partial \mathcal{L}}{\partial w_1} &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial w_1} \right] \\ &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial p(y^{(1)}|x^{(1)})} \cdot \frac{\partial p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial p(y^{(2)}|x^{(2)})} \cdot \frac{\partial p(y^{(2)}|x^{(2)})}{\partial w_1} \right] \\ &= -\frac{1}{2} \left[\begin{array}{c} \frac{1}{\sigma(a^{(1)})} \cdot \sigma(a^{(1)})(1 - \sigma(a^{(1)})) \cdot x_1 \\ + \\ \frac{1}{1 - \sigma(a^{(2)})} \cdot -\sigma(a^{(2)})(1 - \sigma(a^{(2)})) \cdot x_1 \end{array} \right]\end{aligned}$$

Backpropagation (Backward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$

$$\begin{aligned}\frac{\partial \mathcal{L}}{\partial w_1} &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial w_1} \right] \\ &= -\frac{1}{2} \left[\frac{\partial \ln p(y^{(1)}|x^{(1)})}{\partial p(y^{(1)}|x^{(1)})} \cdot \frac{\partial p(y^{(1)}|x^{(1)})}{\partial w_1} + \frac{\partial \ln p(y^{(2)}|x^{(2)})}{\partial p(y^{(2)}|x^{(2)})} \cdot \frac{\partial p(y^{(2)}|x^{(2)})}{\partial w_1} \right] \\ &= -\frac{1}{2} \left[\begin{array}{c} \frac{1}{\sigma(a^{(1)})} \cdot \sigma(a^{(1)})(1 - \sigma(a^{(1)})) \cdot x_1 \\ + \\ \frac{1}{1 - \sigma(a^{(2)})} \cdot -\sigma(a^{(2)})(1 - \sigma(a^{(2)})) \cdot x_1 \end{array} \right] \\ &= -\frac{1}{2} \left[(1 - \sigma(a^{(1)})) \cdot x_1 - \sigma(a^{(2)}) \cdot x_1 \right]\end{aligned}$$

Backpropagation (Backward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$

$$\frac{\partial \mathcal{L}}{\partial w_1} = -\frac{1}{2} \left[(1 - \sigma(a^{(1)})) \cdot x_1 - \sigma(a^{(2)}) \cdot x_1 \right]$$

Backpropagation (Backward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$

$$\frac{\partial \mathcal{L}}{\partial w_1} = -\frac{1}{2} \left[(1 - \sigma(a^{(1)})) \cdot x_1 - \sigma(a^{(2)}) \cdot x_1 \right]$$

$$w_1 \leftarrow w_1 - \eta \frac{\partial \mathcal{L}}{\partial w_1}$$

Backpropagation (Backward Pass)

- ▶ $a = w_1 \cdot x_1 + w_2 \cdot x_2 + b$
- ▶ $o = p(Y = 1|x; w_1, w_2, b) = \sigma(a)$

$$\frac{\partial \mathcal{L}}{\partial w_1} = -\frac{1}{2} \left[(1 - \sigma(a^{(1)})) \cdot x_1 - \sigma(a^{(2)}) \cdot x_1 \right]$$

$$w_1 \leftarrow w_1 - \eta \frac{\partial \mathcal{L}}{\partial w_1}$$

Repeat for w_2 and b

Optimization tricks

- ▶ When implementing a model, try to fit to 100% accuracy on 1 or 2 data points.
- ▶ Decrease the learning rate with each epoch, or when the loss stops decreasing on validation data.
- ▶ Find a good initial learning rate before adjusting other hyperparameters.
- ▶ Train with dropout. (Great for image classification; YMMV for NLP)
- ▶ Even better use a different optimizer:
 - ▶ SGD with momentum or Nesterov accelerated gradient
 - ▶ rmsprop
 - ▶ adagrad
 - ▶ adadelat
 - ▶ adam

All of these take the parameter gradient as input.

For a good overview of these methods, see

<http://ruder.io/optimizing-gradient-descent/>

Lesson Plan

linear models

multi-layer perceptron

optimization

feed-forward language model

Language Modeling and you

A *language model* assigns a probability to an arbitrary sequence of word tokens.

Often used in speech recognition and machine translation.

Typically, lms make a low-order Markov assumption.

$p(\textit{the}, \textit{werewolf}, \textit{howled}, \textit{at}, \textit{the}, \textit{moon}) =$

$$\begin{aligned} & p(\textit{the}|\square, \square, \square) \\ \times & p(\textit{werewolf}|\square, \square, \textit{the}) \\ \times & p(\textit{howled}|\square, \textit{the}, \textit{werewolf}) \\ \times & p(\textit{at}|\textit{the}, \textit{werewolf}, \textit{howled}) \\ \times & p(\textit{the}|\textit{werewolf}, \textit{howled}, \textit{at}) \\ \times & p(\textit{moon}|\textit{howled}, \textit{at}, \textit{the}) \end{aligned}$$

Language Modeling and you

Traditionally, the design of *ngram language models* focused on estimating terms like $p(\text{moon}|\text{howled}, \text{at}, \text{the})$ by:

- ▶ counting occurrence of ngrams
(*howled, at, the, moon*),
(*at, the, moon*),
(*the, moon*),
(*moon*)
- ▶ interpolating lower order models built on these counts

Unfortunately, these counts are sparse (especially beyond trigrams)

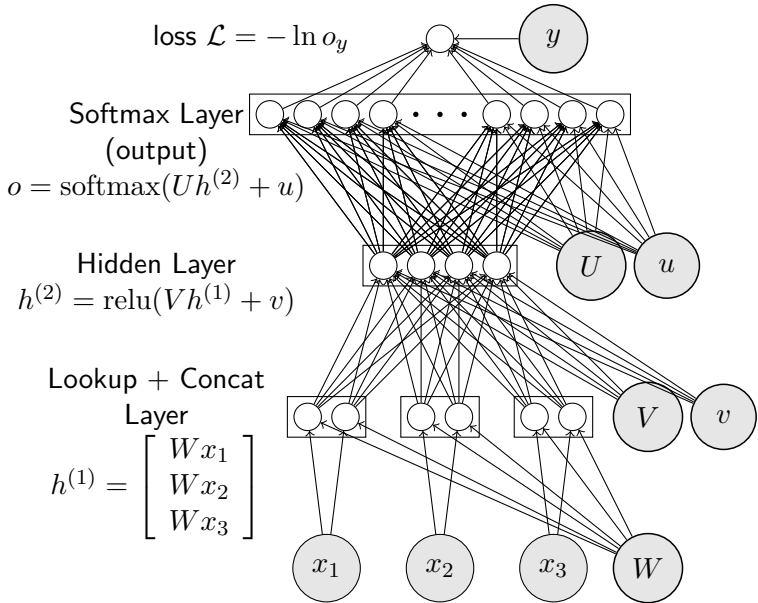
Observing (*barked, at, the, moon*) doesn't tell us much about (*howled, at, the, moon*)

A Feedforward Language Model

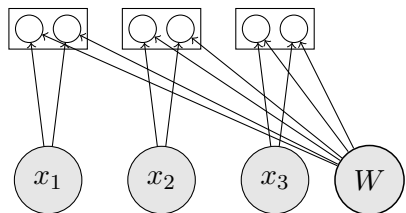
A Neural Probabilistic Language Model (Bengio et al., 2003)

The main ideas (copied verbatim from the paper):

1. associate with each word in the vocabulary a distributed *word feature vector* (a real-valued vector in \mathbb{R}^m),
2. express the joint *probability function* of word sequences in terms of the feature vectors of these words in the sequence, and
3. learn simultaneously the *word feature vectors* and the parameters of that *probability function*.



Lookup and Concat Layer (View 1)



howled

at

the

$$\begin{bmatrix} 0 \\ 1 \\ 0 \\ \vdots \end{bmatrix}$$

$$\begin{bmatrix} 0 \\ 0 \\ 1 \\ \vdots \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 0 \\ 0 \\ \vdots \end{bmatrix}$$

Each word is encoded as a one-hot vector $x_i \in \mathbb{R}^V$.

Word embeddings $W \in \mathbb{R}^{m \times V}$

Lookup and Concat Layer (View 1)

$$\begin{bmatrix} W_{1,1} & W_{1,2} & \dots & W_{1,V} \\ W_{2,1} & W_{2,2} & \dots & W_{2,V} \\ \vdots & \vdots & \ddots & \vdots \\ W_{m-1,1} & W_{m-1,2} & \dots & W_{m-1,V} \\ W_{m,1} & W_{m,2} & \dots & W_{m,V} \end{bmatrix} \times \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} W_{1,2} \\ W_{2,2} \\ \vdots \\ W_{m-1,2} \\ W_{m,2} \\ W_{:,2} \end{bmatrix}$$

$W \cdot x_1 =$

Lookup and Concat Layer (View 1)

$$\begin{bmatrix} W_{1,1} & W_{1,2} & \dots & W_{1,V} \\ W_{2,1} & W_{2,2} & \dots & W_{2,V} \\ \vdots & \vdots & \ddots & \vdots \\ W_{m-1,1} & W_{m-1,2} & \dots & W_{m-1,V} \\ W_{m,1} & W_{m,2} & \dots & W_{m,V} \end{bmatrix} \times \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} W_{1,2} \\ W_{2,2} \\ \vdots \\ W_{m-1,2} \\ W_{m,2} \\ W_{:,2} \end{bmatrix}$$

$W \cdot x_1 =$

Lookup and Concat Layer (View 1)

Each individual embedding is then concatenated into a larger single vector.

$$h^{(1)} = \begin{bmatrix} W \cdot x_1 \\ W \cdot x_2 \\ W \cdot x_3 \end{bmatrix}$$

Lookup and Concat Layer (View 1)

Each individual embedding is then concatenated into a larger single vector.

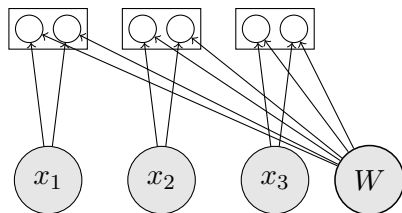
$$h^{(1)} = \begin{bmatrix} W \cdot x_1 \\ W \cdot x_2 \\ W \cdot x_3 \end{bmatrix} = \begin{bmatrix} W_{:,2} \\ W_{:,3} \\ W_{:,1} \end{bmatrix}$$

Lookup and Concat Layer (View 1)

Each individual embedding is then concatenated into a larger single vector.

$$h^{(1)} = \begin{bmatrix} W \cdot x_1 \\ W \cdot x_2 \\ W \cdot x_3 \end{bmatrix} = \begin{bmatrix} W_{:,2} \\ W_{:,3} \\ W_{:,1} \end{bmatrix} = \begin{bmatrix} W_{1,2} \\ \vdots \\ W_{m,2} \\ W_{1,3} \\ \vdots \\ W_{m,3} \\ W_{1,1} \\ \vdots \\ W_{m,1} \end{bmatrix}$$

Lookup and Concat Layer (View 2)



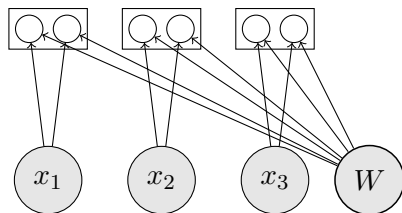
howled at the

$$x_1 = \text{index}(\text{howled}) = 2$$

$$x_2 = \text{index}(\text{at}) = 3$$

$$x_3 = \text{index}(\text{the}) = 1$$

Lookup and Concat Layer (View 2)



howled at the

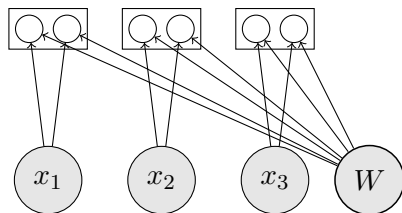
$$x_1 = \text{index}(\text{howled}) = 2$$

$$x_2 = \text{index}(\text{at}) = 3$$

$$x_3 = \text{index}(\text{the}) = 1$$

$$\text{lookup}(W, i) = W_{:,i}$$

Lookup and Concat Layer (View 2)



howled at the

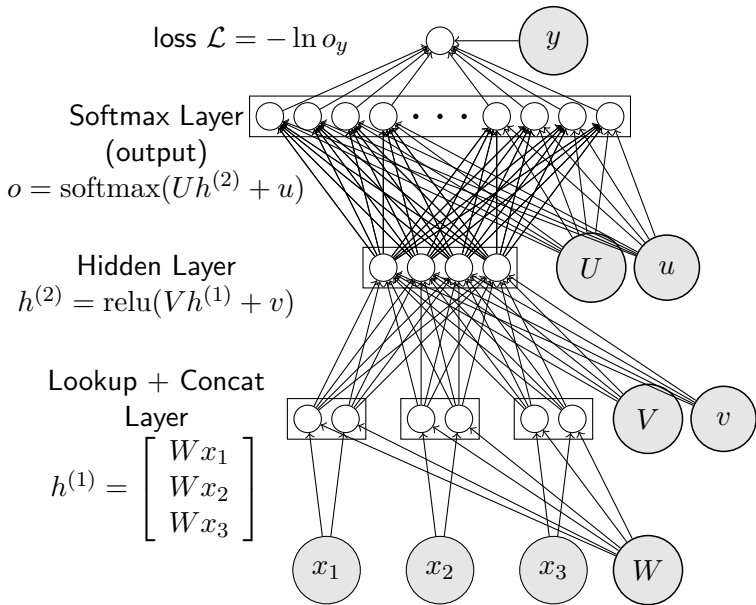
$$x_1 = \text{index}(\text{howled}) = 2$$

$$x_2 = \text{index}(\text{at}) = 3$$

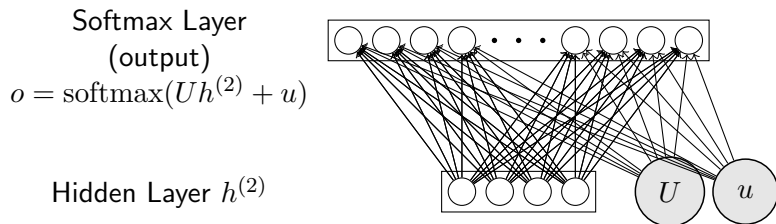
$$x_3 = \text{index}(\text{the}) = 1$$

$$\text{lookup}(W, i) = W_{:,i}$$

$$h^{(1)} = \begin{bmatrix} \text{lookup}(W, x_1) \\ \text{lookup}(W, x_2) \\ \text{lookup}(W, x_3) \end{bmatrix} = \begin{bmatrix} W_{:,2} \\ W_{:,3} \\ W_{:,1} \end{bmatrix}$$



Softmax Layer

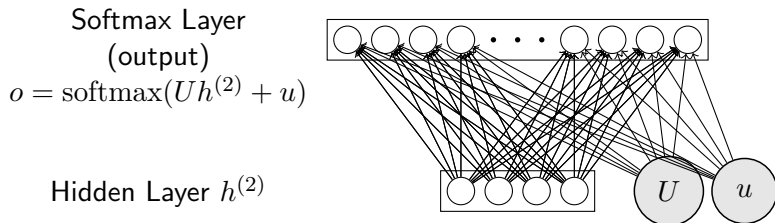


$h^{(2)} \in \mathbb{R}^d$, encoding of input word prefix into a vector space

The output layer $o \in (0, 1)^V$ contains one neuron (unit) for every word in the vocabulary.

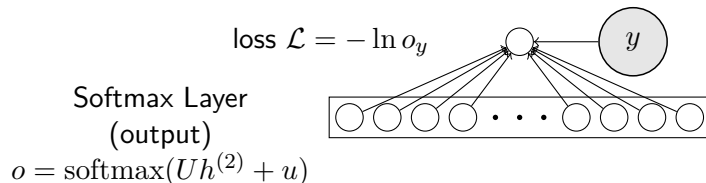
o_i represents the probability of the i -th word in the vocabulary occurring after the word prefix represented by (x_1, x_2, x_3) .

Softmax Layer



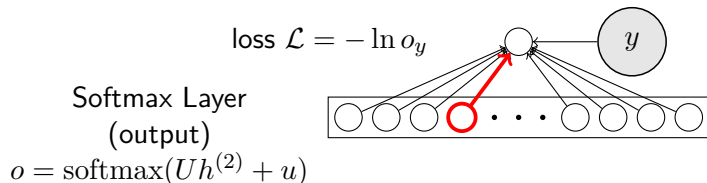
$U \in \mathbb{R}^{V \times d}$ is also a matrix of word embeddings.

Loss Layer



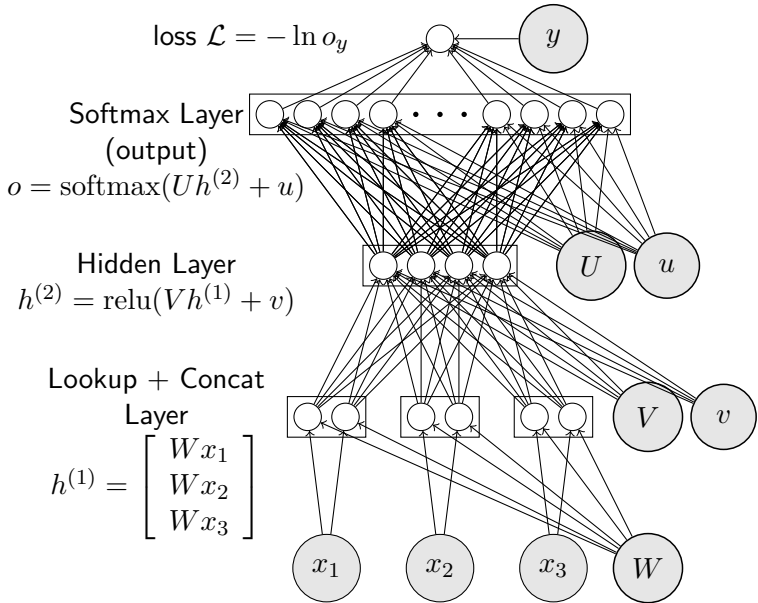
To compute the negative log likelihood (cross entropy loss), simply pick out the y -th element of o and take the negative log.

Loss Layer



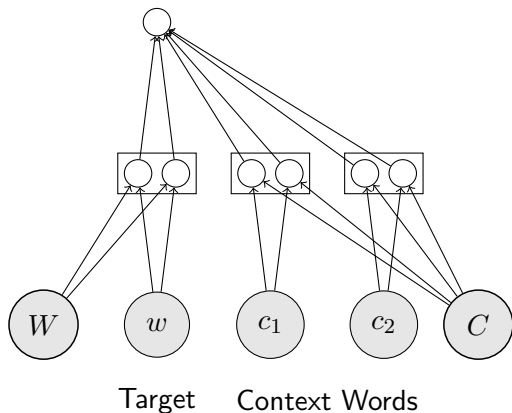
To compute the negative log likelihood (cross entropy loss), simply pick out the y -th element of o and take the negative log.

E.g. $y = 4$, $-\ln o_y = -\ln o_4$



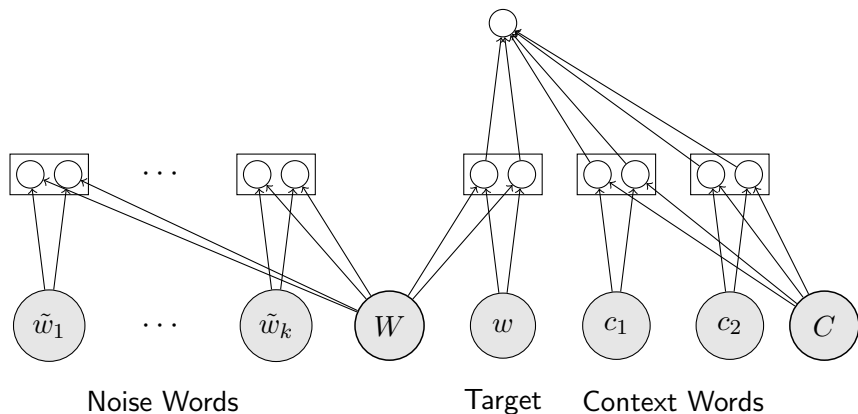
CBOW

$$\ln p(D = 1 | w, c_1, c_2)$$
$$= \ln \frac{1}{1 + \exp(-W_{:,w}^T (C_{:,c_1} + C_{:,c_2}))}$$



CBOW

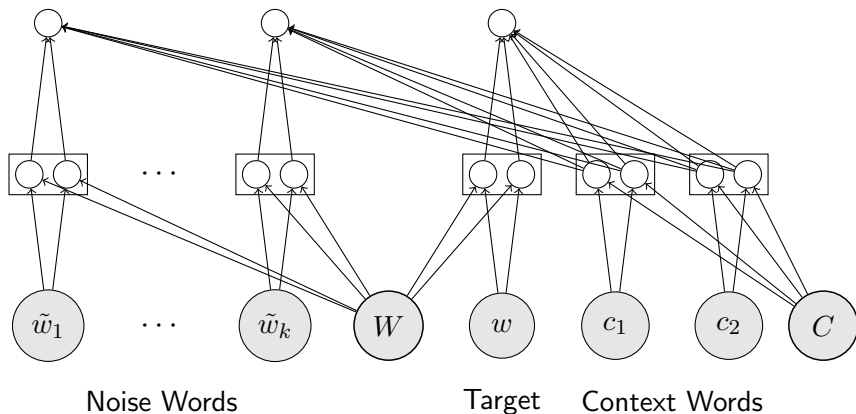
$$\ln p(D = 1 | w, c_1, c_2) \\ = \ln \frac{1}{1 + \exp(-W_{:,w}^T (C_{:,c_1} + C_{:,c_2}))}$$



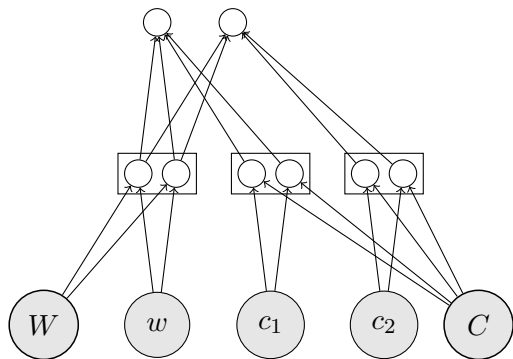
CBOW

$$\sum_{i=1}^k \ln p(D = 0 | \tilde{w}_i, c_1, c_2)$$
$$= \sum_{i=1}^k \ln \left(1 - \frac{1}{1 + \exp(-W_{:, \tilde{w}_i}^\top (C_{:, c_1} + C_{:, c_2}))} \right)$$

$$\ln p(D = 1 | w, c_1, c_2)$$
$$= \ln \frac{1}{1 + \exp(-W_{:, w}^\top (C_{:, c_1} + C_{:, c_2}))}$$



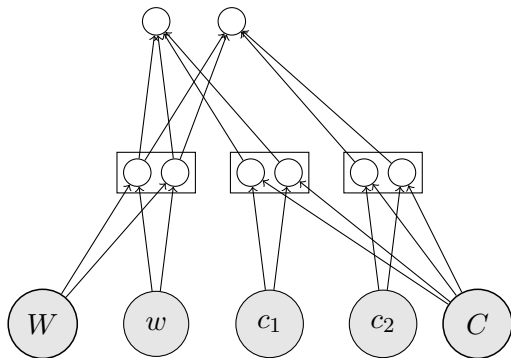
Skip-Gram



Target Context Words

Skip-Gram

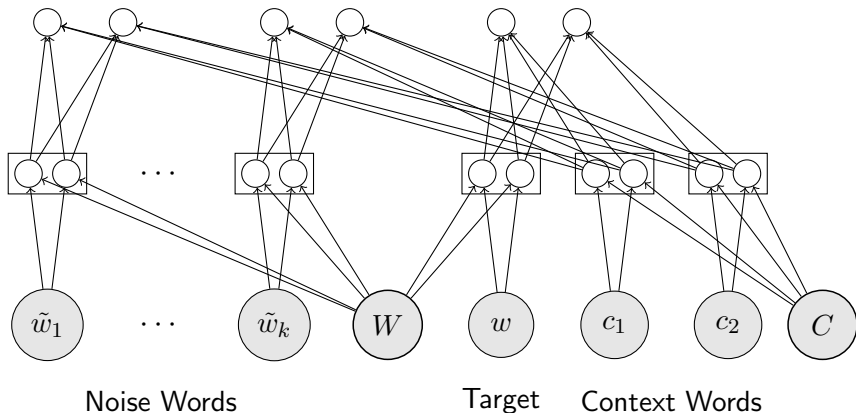
$$\begin{aligned} & \ln p(D = 1 | w, c_1, c_2) \\ &= \ln p(D = 1 | w, c_1) + \ln p(D = 1 | w, c_2) \\ &= \sum_{i=1}^2 \ln \frac{1}{1 + \exp(-W_{:,w}^T C_{:,c_i})} \end{aligned}$$



Target Context Words

Skip-Gram

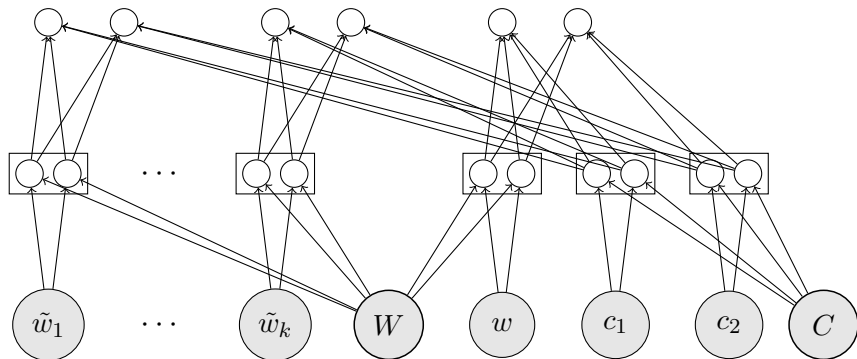
$$\begin{aligned} & \ln p(D = 1 | w, c_1, c_2) \\ &= \ln p(D = 1 | w, c_1) + \ln p(D = 1 | w, c_2) \\ &= \sum_{i=1}^2 \ln \frac{1}{1 + \exp(-W_{:,w}^T C_{:,c_i})} \end{aligned}$$



Skip-Gram

$$\begin{aligned} & \sum_{i=1}^k \ln p(D = 0 | \tilde{w}_i, c_1, c_2) \\ &= \sum_{i=1}^k \ln p(D = 0 | \tilde{w}_i, c_1) + \ln p(D = 0 | \tilde{w}_i, c_2) \\ &= \sum_{i=1}^k \sum_{j=1}^2 \ln \left(1 - \frac{1}{1 + \exp(-W_{:, \tilde{w}_i}^T C_{:, c_j})} \right) \end{aligned}$$

$$\begin{aligned} & \ln p(D = 1 | w, c_1, c_2) \\ &= \ln p(D = 1 | w, c_1) + \ln p(D = 1 | w, c_2) \\ &= \sum_{i=1}^2 \ln \frac{1}{1 + \exp(-W_{:, w}^T C_{:, c_i})} \end{aligned}$$



Noise Words

Target

Context Words