EXPLODE: a Lightweight, General System for Finding Serious Storage System Errors

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Why check storage systems?

Storage system errors are among the worst

- kernel panic, data loss and corruption
- Complicated code, hard to get right
 - Simultaneously worry about speed, failures and crashes
- □ Hard to comprehensively test for failures, crashes

Goal: *comprehensively* check *many* storage systems with *little* work

EXPLODE summary

Comprehensive: uses ideas from model checking

Fast, easy

- Check new storage system: 200 lines of C++ code
- Port to new OS: 1 device driver + optional instrumentation
- General, real: check live systems.
 - Can run (on Linux, BSD), can check, even w/o source code

Effective

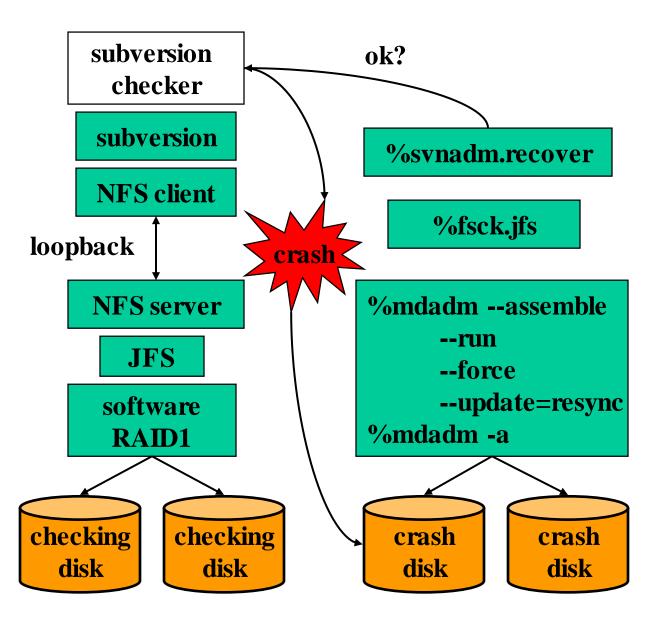
- checked 10 Linux FS, 3 version control software, Berkeley DB, Linux RAID, NFS, VMware GSX 3.2/Linux
- Bugs in all, 36 in total, mostly data loss
- Subsumes our old work FiSC [OSDI 2004]

Checking complicated stacks

Stack of storage systems

□ All real

- subversion: an open-source version control software
- User-written checker on top
- Recovery tools run after EXPLODEsimulated crashes



Outline



Checking interface

Implementation

Results

Related work, conclusion and future work

Core idea: explore all choices

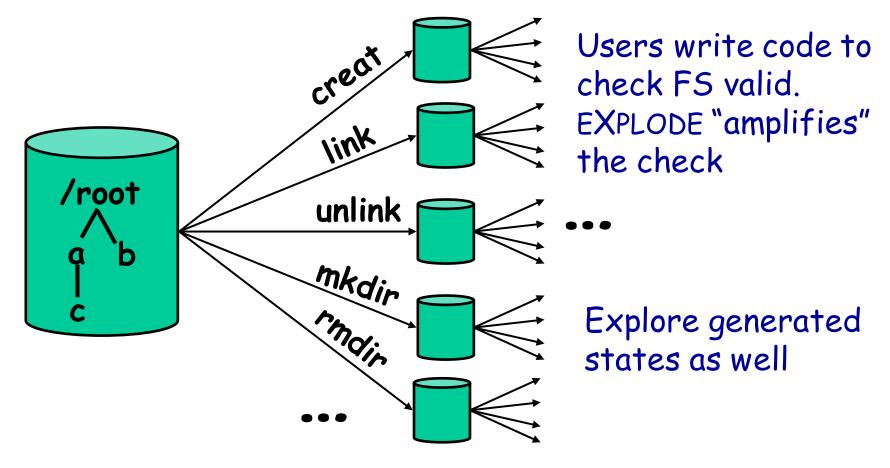
Bugs are often triggered by corner cases

How to find: drive execution down to these tricky corner cases

When execution reaches a point in program that can do one of N different actions, fork execution and in first child do first action, in second do second, etc.

External choices

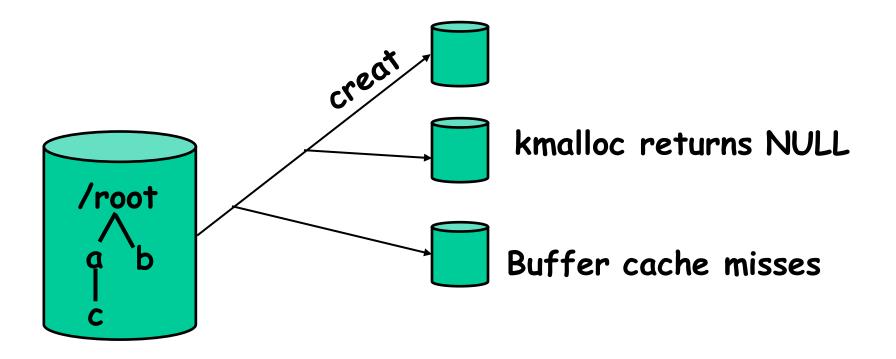
Fork and do every possible operation



Speed hack: hash states, discard if seen

Internal choices

Fork and explore all internal choices



How to expose choices

To explore N-choice point, users instrument code using choose(N)

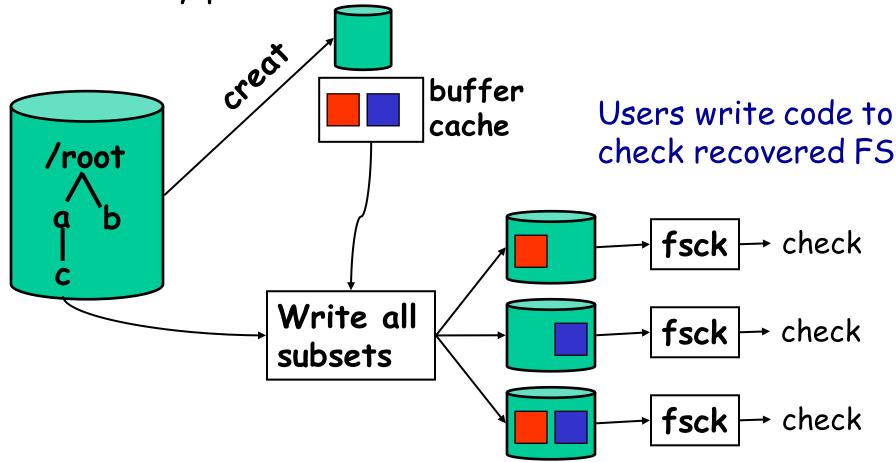
choose(N): N-way fork, return K in K'th kid

```
void* kmalloc(size s) {
    if(choose(2) == 0)
        return NULL;
    ... // normal memory allocation
}
```

We instrumented 7 kernel functions in Linux

Crashes

Dirty blocks can be written in any order, crash at any point



Outline

□ Core idea: explore all choices

- Checking interface
 - What EXPLODE provides
 - What users do to check their storage system
- Implementation
- Results

Related work, conclusion and future work

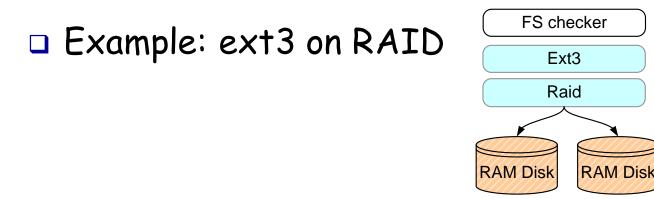
What EXPLODE provides

choose(N): conceptual N-way fork, return K in K'th child execution

- check_crash_now(): check all crashes that can happen at the current moment
 - Paper talks about more ways for checking crashes
 - Users embed non-crash checks in their code.
 EXPLODE amplifies them

□ error(): record trace for deterministic replay

What users do



checker: drive ext3 to do something: mutate(), then verify what ext3 did was correct: check()

storage component: set up, repair and tear down ext3, RAID. Write once per system

□ assemble a checking stack

FS Checker

- mutate

ext3
 Component

Stack

const char *dir = "/mnt/sbd0/"; **const char** *file = "/mnt/sbd0/test-file"; **void** FsChecker::mutate(**void**) { **switch**(choose(4)) ase 0 systemf("echo $\$ test $\ >$ %s", file); if(choose(2)) == 0sy**ic();** else { do_fsync(file); // fsync parent to commit the new directory entry do_fsync("/mnt/sbd0"); heck_crash_now(); // invokes check() for each crash break; case 1: systemf("rm %s", file); break; case 2: systemf("mkdir %s%d, dir, choose(5)); break; case 3: systemf("rmdir %s%a", dir, choose(5)); break; choose(4) rm file creat file mkdir rmdir fsync sync

FS Checker

check

ext3
 Component

Stack

Found JFS fsync bug, caused by reusing directory inode as file inode

Checkers can be simple (50 lines) or very complex(5,000 lines)

Whatever you can express in C++, you can check

□ FS Checker

ext3
 Component

Stack

storage component: initialize, repair, set up, and tear down your system

- Mostly wrappers to existing utilities. "mkfs", "fsck", "mount", "umount"
- threads(): returns list of kernel thread IDs for deterministic error replay
- Write once per system, reuse to form stacks

Real code on next slide

□ FS Checker

ext3
 Component

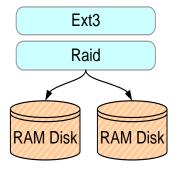
Stack

```
void Ext3::init(void) {
  // create an empty ext3 FS with
  // user-specified block size
  systemf("mkfs.ext3 -F -j -b %d %s",
    get_option(blk_size), children[0]->path());
}
void Ext3::recover() {
 systemf("fsck.ext3 -y %s", children[0]->path())
void Ext3::mount(void) {
  int ret = systemf("sudo mount -t ext3 %s %s",
     children[0]—>path(), path());
  if(ret < 0) error("Corrupt FS: Can't mount!");</pre>
}
void Ext3::umount(void) {
 systemf("sudo umount %s", path());
}
void Ext3::threads(threads_t & thids) {
  int thid:
  if((thid=get_pid("kjournald")) != -1)
     thids.push_back(thid);
  else
     explode_panic("can't get kjournald pid!");
```

FS Checker

ext3 Component

Stack



assemble a checking stack

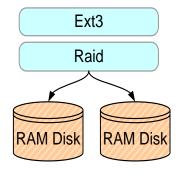
Let EXPLODE know how subsystems are connected together, so it can initialize, set up, tear down, and repair the entire stack

Real code on next slide

□ FS Checker

ext3
 Component

Stack



}

// Assemble FS + RAID storage stack step by step.
void assemble(Component *&top, TestDriver *&driver) {
 // 1. load two RAM disks with size specified by user
 ekm_load_rdd(2, get_option(rdd, sectors));
 Disk *d1 = new Disk("/dev/rdd0");
 Disk *d2 = new Disk("/dev/rdd1");

// 2. plug a mirrored RAID array onto the two RAM disks. Raid *raid = new Raid("/dev/md0", "raid1"); raid->plug_child(d1); raid->plug_child(d2);

// 3. plug an ext3 system onto RAID
Ext3 *ext3 = new Ext3("/mnt/sbd0");
ext3->plug_child(raid);
top = ext3; // let eXplode know the top of storage stack

// 4. attach a file system test driver onto ext3 layer
driver = new FsChecker(ext3);

Outline

□ Core idea: explore all choices

□ Checking interface: 200 lines of C++ to check a system

Implementation

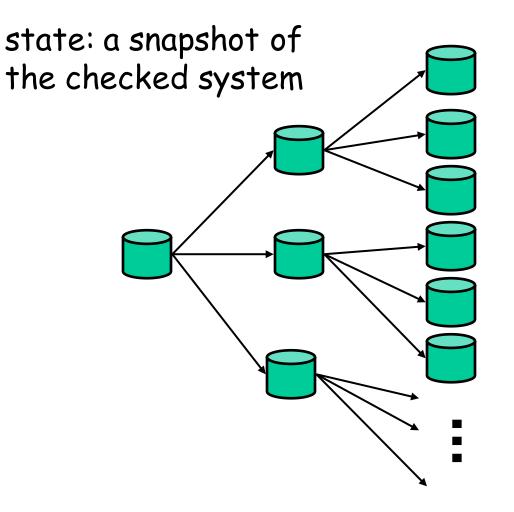
- Checkpoint and restore states
- Deterministic replay
- Checking process
- Checking crashes
- Checking "soft" application crashes

Results

Related work, conclusion and future work

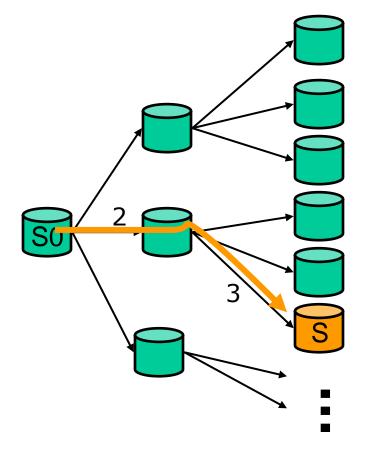
Recall: core idea

• "Fork" at decision point to explore all choices



How to checkpoint live system?

- Hard to checkpoint live kernel memory
 - VM checkpoint heavy-weight
- checkpoint: record all choose() returns from SO
- restore: umount, restore S0, re-run code, make K'th choose() return K'th recorded values
- □ Key to EXPLODE approach



S = S0 + redo choices(2, 3)

Deterministic replay

Need it to recreate states, diagnose bugs

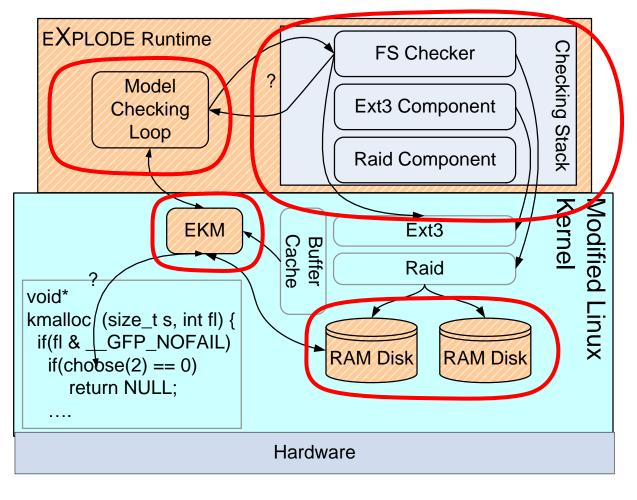
Sources of non-determinism

□ Kernel choose() can be called by other code

- Fix: filter by thread IDs. No choose() in interrupt
- Kernel scheduler can schedule any thread
 - Opportunistic hack: setting priorities. Worked well
 - Can't use lock: deadlock. A holds lock, then yield to B
- Other requirements in paper

Worst case: non-repeatable error. Automatic detect and ignore

EXPLODE: put it all together



User code

💹 EXPLODE 🗌

EKM = EXPLODE device driver

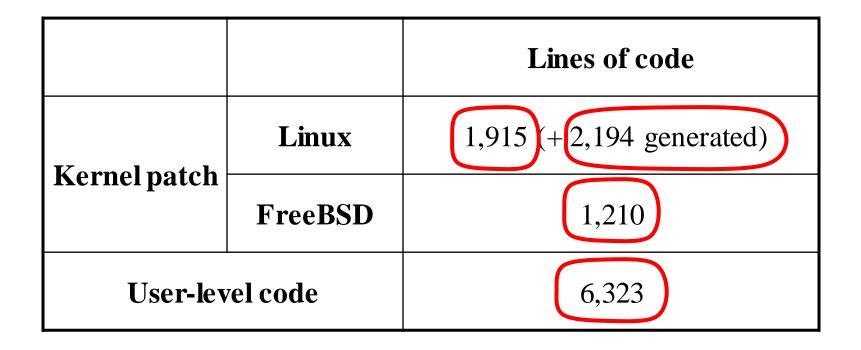
Outline

□ Core idea: explore all choices

- Checking interface: 200 lines of C++ to check a system
- Implementation
- Results
 - Lines of code
 - Errors found

Related work, conclusion and future work

EXPLODE core lines of code



3 kernels: Linux 2.6.11, 2.6.15, FreeBSD 6.0. FreeBSD patch doesn't have all functionality yet

Checkers lines of code, errors found

Storage System Checked		Component		nt	Checker	Bugs
10 file systems		744/10			5,477	18
Storage applications	CVS		27		68	1
	Subversion		31		69	1
	"EXPENSIVE"		30		124	3
	Berkeley DB		82		202	6
Transparent subsystems	RAID		144		FS + 137	2
	NFS		34		FS	4
	VMware GSX/Linux		54		FS	1
Total			1,115		6,008	36

Outline

□ Core idea: explore all choices

- Checking interface: 200 lines of C++ to check new storage system
- Implementation
- Results
 Lines of code
 Errors found

Related work, conclusion and future work

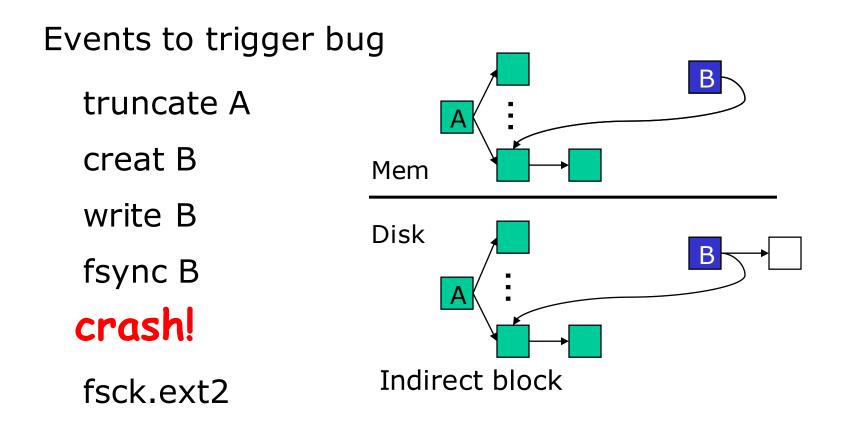
FS Sync checking results

FS	sync	mount sync	fsync	O_SYNC
ext2		×	×	×
ext3				×
ReiserFS		×		×
Reiser4				×
JFS		×	×	×
XFS		×		×
MSDOS	×	×		×
VFAT	×	×		×
HFS	×	×	×	×
HFS+	×	×	×	×

★ indicates a failed check

App rely on sync operations, yet they are broken

ext2 fsync bug



Bug is fundamental due to ext2 asynchrony

Classic app mistake: "atomic" rename

□ All three version control app. made this mistake

Atomically update file A to avoid corruption

fd = creat(A_tmp, ...);
write(fd, ...);
fsync(fd); // missing!
close(fd);
rename(A_tmp, A);

Problem: rename guarantees nothing abt. Data

Outline

□ Core idea: explore all choices

- Checking interface: 200 lines of C++ to check a system
- Implementation
- Results: checked many systems, found many bugs

Related work, conclusion and future work

Related work

□ FS testing

- IRON
- Static analysis
 - Traditional software model checking
 - Theorem proving
 - Other techniques

Conclusion and future work

EXPLODE

- Easy: need 1 device driver. simple user interface
- General: can run, can check, without source
- Effective: checked many systems, 36 bugs

□ Future work:

- Work closely with storage system implementers to check more systems and more properties
- Smart search
- Automatic diagnosis
- Automatically inferring "choice points"
- Approach is general, applicable to distributed systems, secure systems, ...