W4118: scheduling

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References: Modern Operating Systems (3rd edition), Operating Systems Concepts (8th edition), previous W4118, and OS at MIT, Stanford, and UWisc

Outline

Introduction to scheduling

Scheduling algorithms

Direction within course

- Until now: interrupts, processes, threads, synchronization
 - Mostly mechanisms
- □ From now on: resources
 - Resources: things processes operate upon
 - E.g., CPU time, memory, disk space
 - Mostly policies

Types of resource

□ Preemptible

- OS can take resource away, use it for something else, and give it back later
 - E.g., CPU
- □ Non-preemptible
 - OS cannot easily take resource away; have to wait after the resource is voluntarily relinquished
 - E.g., disk space

Type of resource determines how to manage

Decisions about resource

Allocation: which process gets which resources

- Which resources should each process receive?
- Space sharing: Controlled access to resource
- Implication: resources are not easily preemptible

□ Scheduling: how long process keeps resource

- In which order should requests be serviced?
- Time sharing: more resources requested than can be granted
- Implication: Resource is preemptible

Role of Dispatcher vs. Scheduler

Dispatcher

- Low-level mechanism
- Responsibility: context switch
- Scheduler
 - High-level policy
 - Responsibility: deciding which process to run
- Could have an allocator for CPU as well
 - Parallel and distributed systems

When to schedule?

- When does scheduler make decisions?
 When a process
 - 1. switches from running to waiting state
 - 2. switches from running to ready state
 - 3. switches from waiting to ready
 - 4. terminates
- Minimal: nonpreemptive

• ?

Additional circumstances: preemptive
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Outline

Introduction to scheduling

Scheduling algorithms

Overview of scheduling algorithms

Criteria: workload and environment

Workload

- Process behavior: alternating sequence of CPU and I/O bursts
- CPU bound v.s. I/O bound

Environment

- Batch v.s. interactive?
- Specialized v.s. general?

Scheduling performance metrics

- Min waiting time: don't have process wait long in ready queue
- □ Max CPU utilization: keep CPU busy
- Max throughput: complete as many processes as possible per unit time
- □ Min response time: respond immediately
- Fairness: give each process (or user) same percentage of CPU

First-Come, First-Served (FCFS)

Simplest CPU scheduling algorithm

- First job that requests the CPU gets the CPU
- Nonpreemptive

□ Implementation: FIFO queue

Example of FCFS



□ Average waiting time: (0 + 7 + 11 + 12)/4 = 7.5

Example of FCFS: different arrival order

Arrival order: P_3 P_2 P_4 P_1

□ Gantt chart



□ Average waiting time: (9 + 1 + 0 + 5)/4 = 3.75

FCFS advantages and disadvantages

Advantages

- Simple
- Fair
- Disadvantages
 - waiting time depends on arrival order
 - Convoy effect: short process stuck waiting for long process
 - Also called head of the line blocking

Shortest Job First (SJF)

□ Schedule the process with the shortest time

□ FCFS if same time

Example of SJF (w/o preemption)

| <u>Process</u> | <u>Arrival Time</u> | <u>Burst Time</u> |
|----------------|---------------------|-------------------|
| P ₁ | 0 | 7 |
| P ₂ | 2 | 4 |
| P ₃ | 4 | 1 |
| P ₄ | 5 | 4 |

Gantt chart



□ Average waiting time: (0 + 6 + 3 + 7)/4 = 4

Shortest Job First (SJF)

- Schedule the process with the shortest time
 - FCFS if same time
- Advantages
 - Minimizes average wait time. Provably optimal if no preemption allowed
- Disadvantages
 - Not practical: difficult to predict burst time
 - Possible: past predicts future
 - May starve long jobs

Shortest Remaining Time First (SRTF)

- If new process arrives w/ shorter CPU burst than the remaining for current process, schedule new process
 - SJF with preemption

Advantage: reduces average waiting time

Example of SRTF

□ Gantt chart



□ Average waiting time: (9 + 1 + 0 + 2)/4 = 3

Round-Robin (RR)

Practical approach to support time-sharing

Run process for a time slice, then move to back of FIFO queue

Preempted if still running at end of time-slice

□ How to determine time slice?

Example of RR: time slice = 3

□ Gantt chart with time slice = 3



Average waiting time: (8 + 8 + 5 + 7)/4 = 7
 Average response time: (0 + 1 + 5 + 5)/4 = 2.75
 # of context switches: 7

Example of RR: smaller time slice

□ Gantt chart with time slice = 1



Average waiting time: (8 + 6 + 1 + 7)/4 = 5.5
 Average response time: (0 + 0 + 1 + 2)/4 = 0.75
 # of context switches: 14

Example of RR: larger time slice

□ Gantt chart with time slice = 10



- □ Average waiting time: (0 + 5 + 7 + 7)/4 = 4.75
- □ Average response time: same
- □ # of context switches: 3 (minimum)

RR advantages and disadvantages

- Advantages
 - Low response time, good interactivity
 - Fair allocation of CPU across processes
 - Low average waiting time when job lengths vary widely
- Disadvantages
 - Poor average waiting time when jobs have similar lengths
 - Average waiting time is even worse than FCFS!
 - Performance depends on length of time slice
 - Too high → degenerate to FCFS
 - Too low → too many context switches, costly

Priorities

□ A priority is associated with each process

- Run highest priority ready job (some may be blocked)
- Round-robin among processes of equal priority
- Can be preemptive or nonpreemptive
- Representing priorities
 - Typically an integer
 - The larger the higher or the lower?

Setting priorities

Priority can be statically assigned

- Some always have higher priority than others
- Problem: starvation

Priority can be dynamically changed by OS

 Aging: increase the priority of processes that wait in the ready queue for a long time

Priority inversion

- High priority process depends on low priority process (e.g. to release a lock)
 - Another process with in-between priority arrives?
- □ Solution: priority inheritance
 - Inherit highest priority of waiting process
 - Must be able to chain multiple inheritances
 - Must ensure that priority reverts to original value