# Machine Learning 4771

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## Topic 18

- •The Junction Tree Algorithm
- Collect & Distribute
- Algorithmic Complexity
- ArgMax Junction Tree Algorithm

# Review: Junction Tree Algorithm

- Send message from each clique to its separators of what it thinks the submarginal on the separator is.
- Normalize each clique by incoming message from its separators so it agrees with them

If agree: 
$$\sum_{V\setminus S} \psi_V = \phi_S = p(S) = \phi_S = \sum_{W\setminus S} \psi_W$$
 ...Done!

**Else: Send message** From V to W...

$$\begin{aligned} \varphi_S^* &= \sum_{V \setminus S} \psi_V \\ \psi_W^* &= \frac{\varphi_S^*}{\varphi_S} \psi_W \\ \psi_V^* &= \psi_V \end{aligned}$$

**Send message** From W to V...

$$\begin{vmatrix} \phi_S^{**} = \sum_{W \setminus S} \psi_W^* \\ \psi_V^{**} = \frac{\phi_S^{**}}{\phi_S^*} \psi_V^* \\ \psi_W^{**} = \psi_W^* \end{vmatrix}$$

Now they Agree...Done!

## JTA with many cliques

•Problem: what if we have more than two cliques?

1) Update AB & BC



2) Update BC & CD



•Problem: AB has not heard about CD!

After BC updates, it will be inconsistent for AB

- Need to iterate the pairwise updates many times
- •This will eventually converge to consistent marginals
- •But, inefficient... can we do better?

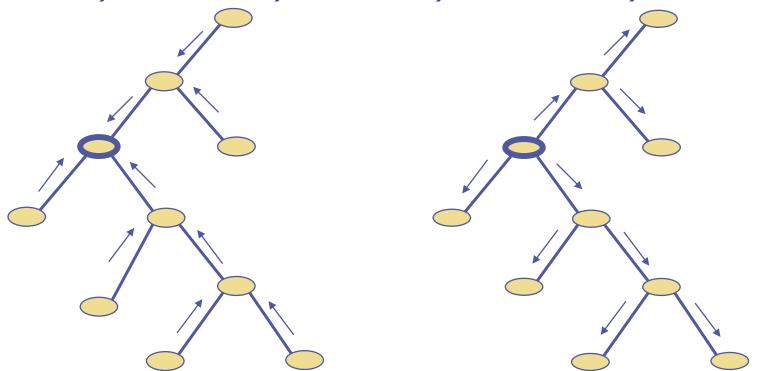
#### JTA: Collect & Distribute

Use tree recursion rather than iterate messages mindlessly!

```
initialize(DAG){ Pick root
                          Set all variables as: \psi_{C}=pig(x_{i}\mid\pi_{i}ig),\phi_{S}=1 }
collectEvidence(node) {
   for each child of node {
       update1(node,collectEvidence(child)); }
   return(node); }
distributeEvidence(node) {
   for each child of node {
       update2(child,node);
       distributeEvidence(child); } }
update1(node w,node v) { \phi_{V\cap W}^* = \sum_{V\setminus (V\cap W)} \psi_V, \ \psi_W = \frac{\phi_{V\cap W}}{\phi_{V\cap W}} \psi_W
update2(node w,node v) { \phi_{V\cap W}^{**}=\sum_{V\setminus (V\cap W)}\psi_V,\ \psi_W=\frac{\phi_{V\cap W}^{**}}{\phi_{V\cap W}^{*}}\psi_W
normalize() { p(X_C) = \frac{1}{\sum_{s} \psi_C^{**}} \psi_C^{**} \ \forall C, \ p(X_S) = \frac{1}{\sum_{s} \phi_S^{**}} \phi_S^{**} \ \forall S }
```

## Junction Tree Algorithm

•JTA: 1) *Initialize* 2) *Collect* 3) *Distribute* 4) *Normalize* 



- •Note: leaves do not change their ψ during *collect*
- •Note: the first cliques *collect* changes are parents of leaves
- •Note: root does not change its ψ during *distribute*

# **Algorithmic Complexity**

- •The 5 steps of JTA are all efficient:
- 1) Moralization

Polynomial in # of nodes

2) Introduce Evidence (fixed or constant)

Polynomial in # of nodes (convert pdf to slices)

3) Triangulate (Tarjan & Yannakakis 1984)

Suboptimal=Polynomial, Optimal=NP

4) Construct Junction Tree (Kruskal)

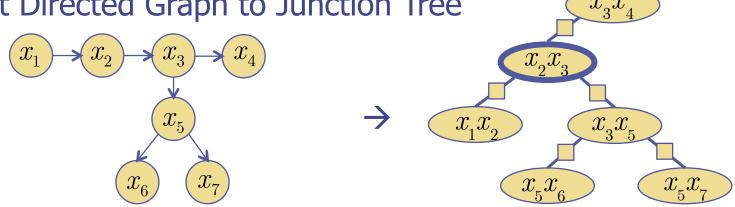
Polynomial in # of cliques

5) Junction Tree Algorithm (Init, Collect, Distribute, Normalize)

Polynomial (linear) in # of cliques, Exponential in Clique Cardinality

## Junction Tree Algorithm

Convert Directed Graph to Junction Tree



 Initialize separators to 1 (and Z=1) and set clique tables to the CPTs in the Directed Graph

$$\begin{split} p\left(\boldsymbol{X}\right) &= p\left(\boldsymbol{x}_{\!\scriptscriptstyle 1}\right) p\left(\boldsymbol{x}_{\!\scriptscriptstyle 2} \mid \boldsymbol{x}_{\!\scriptscriptstyle 1}\right) p\left(\boldsymbol{x}_{\!\scriptscriptstyle 3} \mid \boldsymbol{x}_{\!\scriptscriptstyle 2}\right) p\left(\boldsymbol{x}_{\!\scriptscriptstyle 4} \mid \boldsymbol{x}_{\!\scriptscriptstyle 3}\right) p\left(\boldsymbol{x}_{\!\scriptscriptstyle 5} \mid \boldsymbol{x}_{\!\scriptscriptstyle 3}\right) p\left(\boldsymbol{x}_{\!\scriptscriptstyle 6} \mid \boldsymbol{x}_{\!\scriptscriptstyle 5}\right) p\left(\boldsymbol{x}_{\!\scriptscriptstyle 7} \mid \boldsymbol{x}_{\!\scriptscriptstyle 5}\right) \\ p\left(\boldsymbol{X}\right) &= \frac{1}{Z} \frac{\prod_{\scriptscriptstyle C} \psi\left(\boldsymbol{X}_{\scriptscriptstyle C}\right)}{\prod_{\scriptscriptstyle S} \phi\left(\boldsymbol{X}_{\scriptscriptstyle S}\right)} = \frac{1}{1} \frac{p\left(\boldsymbol{x}_{\!\scriptscriptstyle 1}, \boldsymbol{x}_{\!\scriptscriptstyle 2}\right) p\left(\boldsymbol{x}_{\!\scriptscriptstyle 3} \mid \boldsymbol{x}_{\!\scriptscriptstyle 2}\right) p\left(\boldsymbol{x}_{\!\scriptscriptstyle 4} \mid \boldsymbol{x}_{\!\scriptscriptstyle 3}\right) p\left(\boldsymbol{x}_{\!\scriptscriptstyle 5} \mid \boldsymbol{x}_{\!\scriptscriptstyle 3}\right) p\left(\boldsymbol{x}_{\!\scriptscriptstyle 6} \mid \boldsymbol{x}_{\!\scriptscriptstyle 5}\right) p\left(\boldsymbol{x}_{\!\scriptscriptstyle 7} \mid \boldsymbol{x}_{\!\scriptscriptstyle 5}\right) \\ 1 \times 1 \times 1 \times 1 \times 1 \times 1 \end{split}$$

- •Run Collect, Distribute, Normalize
- •Get valid marginals from all  $\psi$ ,  $\phi$  tables

#### JTA with Extra Evidence

- •If extra evidence is observed, must slice tables accordingly
- •Example:  $p(A, B, C, D) = \frac{1}{Z} \psi_{AB} \psi_{BC} \psi_{CD}$

$$Z = 1 \qquad AB \qquad B \qquad BC \qquad C \qquad CD$$

$$\psi_{AB} = \begin{bmatrix} 8 & 4 \\ 3 & 1 \end{bmatrix}_{A=1}^{A=0} \qquad \psi_{BC} = \begin{bmatrix} 2 & 3 \\ 1 & 1 \end{bmatrix}_{B=1}^{B=0} \qquad \psi_{CD} = \begin{bmatrix} 1 & 4 \\ 1 & 1 \end{bmatrix}_{C=1}^{C=0}$$

•You are given evidence: A=0. Replace table with slices...

$$\psi_{AB} \rightarrow \left[ \begin{array}{ccc} 8 & 4 \end{array} \right] \qquad \qquad \psi_{BC} = \left[ \begin{array}{ccc} 2 & 3 \\ 1 & 1 \end{array} \right] \qquad \qquad \psi_{CD} = \left[ \begin{array}{ccc} 1 & 4 \\ 1 & 1 \end{array} \right]$$

•JTA now gives  $\psi$ ,  $\phi$  as marginals *conditioned* on evidence

$$p\Big(B \mid A = 0\Big) = \frac{\psi_{AB}^{**}}{\sum_{B} \psi_{AB}^{**}} \qquad p\Big(B, C \mid A = 0\Big) = \frac{\psi_{BC}^{**}}{\sum_{B, C} \psi_{BC}^{**}} \qquad p\Big(C, D \mid A = 0\Big) = \frac{\psi_{CD}^{**}}{\sum_{C, D} \psi_{CD}^{**}}$$

•All denominators equal the new normalizer Z'

$$Z' = p(EVIDENCE) = \sum_{B} \psi_{AB}^{**} = \sum_{B,C} \psi_{BC}^{**} = \sum_{C,D} \psi_{CD}^{**}$$

# ArgMax Junction Tree Algorithm

- We can also use JTA for finding the max not the sum over the joint to get argmax of marginals & conditionals
- •Say have some evidence:  $p(X_F, \overline{X}_E) = p(x_1, ..., x_n, \overline{x}_{n+1}, ..., \overline{x}_N)$
- •Most likely (highest p)  $X_F$ ?  $X_F^* = \arg \max_{X_F} p(X_F, \bar{X}_E)$
- •What is most likely state of patient with fever & headache?

$$\begin{split} p_F^* &= \max_{x_2, x_3, x_4, x_5} \, p \Big( x_1 = 1, x_2, x_3, x_4, x_5, x_6 = 1 \Big) \\ &= \max_{x_2} \, p \Big( x_2 \mid x_1 = 1 \Big) \, p \Big( x_1 = 1 \Big) \max_{x_3} \, p \Big( x_3 \mid x_1 = 1 \Big) \\ &\max_{x_4} \, p \Big( x_4 \mid x_2 \Big) \max_{x_5} \, p \Big( x_5 \mid x_3 \Big) \, p \Big( x_6 = 1 \mid x_2, x_5 \Big) \end{split}$$

Solution: replace sum with max inside JTA update code

$$\phi_{V\cap W}^* = \max_{V\setminus \left(V\cap W\right)} \psi_V, \ \psi_W = \frac{\phi_{V\cap W}^*}{\phi_{V\cap W}} \psi_W \qquad \phi_{V\cap W}^{**} = \max_{V\setminus \left(V\cap W\right)} \psi_V, \ \psi_W = \frac{\phi_{V\cap W}^{**}}{\phi_{V\cap W}^*} \psi_W$$

- •Final potentials are max marginals:  $\psi^{**}ig(X_Cig) = \max_{U\setminus C} pig(Xig)$
- •Highest value in potential is most likely:  $X_C^* = \arg\max_C \psi^{**}(X_C)$

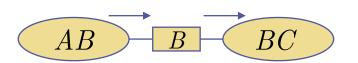
# ArgMax Junction Tree Algorithm

- •Why do I need the ArgMax junction tree algorithm?
- •Can't I just compute marginals using the Sum algorithm and then find the highest value in each marginal???
- •No!! Here's a counter-example:  $x_1 x_1 x_1$

- •Most likely is  $x_1^*=C$  and  $x_2^*=0$
- •But the sub-marginals  $p(x_1)$  and  $p(x_2)$  do not reveal this...

•The marginals would falsely imply that is  $x_1^*=A$  and  $x_2^*=1$ 

## Example



- Note that products are element-wise
- Let us send a regular JTA message from AB to BC

$$\psi_{AB} = \begin{bmatrix} 8 & 4 \\ 3 & 1 \\ B = 0 \end{bmatrix}_{A=1}^{A=0} \qquad \phi_{B} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}_{B=0}^{B=0} \qquad \psi_{BC} = \begin{bmatrix} 2 & 3 \\ 1 & 1 \\ S = 0 \end{bmatrix}_{B=1}^{B=0}$$

$$\phi_{B}^{*} = \sum_{A} \psi_{AB} = \sum_{A} \begin{bmatrix} 8 & 4 \\ 3 & 1 \end{bmatrix} = \begin{bmatrix} 11 & 5 \\ B = 0 & B = 1 \end{bmatrix} = \begin{bmatrix} 11 \\ 5 \end{bmatrix}_{B=0}^{B=0}$$

$$\psi_{BC}^{*} = \frac{\phi_{B}^{*}}{\phi_{B}} \psi_{BC} = \frac{\begin{bmatrix} 11 \\ 5 \end{bmatrix}}{\begin{bmatrix} 1 \\ 1 \end{bmatrix}} \begin{bmatrix} 2 & 3 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 22 & 33 \\ 5 & 5 \\ C = 0 & C = 1 \end{bmatrix}_{B=1}^{B=0}$$
The argument ITA instruction and the constraint and the following states the constraint and the properties are small as a sum of the constraint and the properties are small as a sum of the constraint and the properties are small as a sum of the constraint and the properties are small as a sum of the constraint and the properties are small as a sum of the constraint and the properties are small as a sum of the constraint and the properties are small as a sum of the constraint and the properties are small as a sum of the

•If argmax JTA, just change the separator update to:

$$\phi_B^* = \max_A \psi_{AB} = \max_A \begin{bmatrix} 8 & 4 \\ 3 & 1 \end{bmatrix} = \begin{bmatrix} 8 & 4 \\ B=0 & B=1 \end{bmatrix} = \begin{bmatrix} 8 \\ 4 \end{bmatrix}_{B=1}^{B=0}$$