

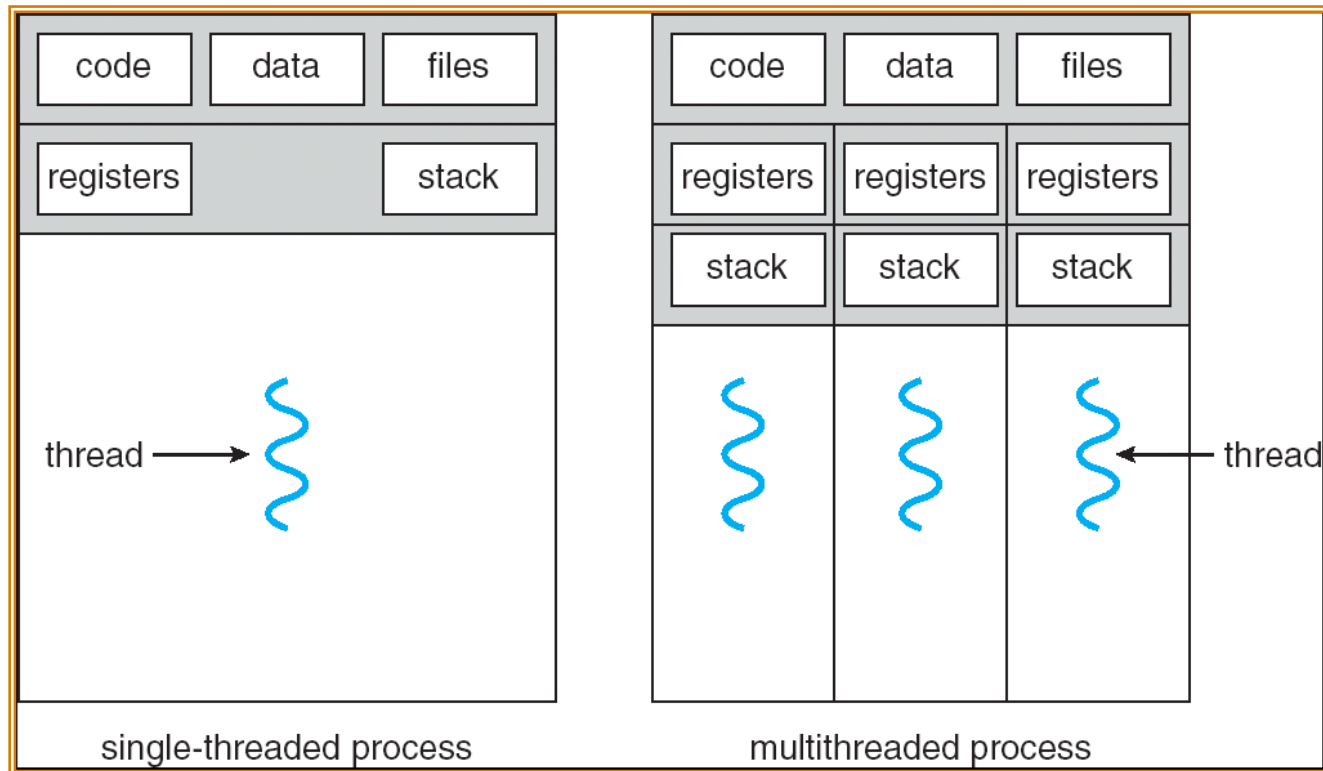
# Synchronization I

COMS W4118

**References:** Operating Systems Concepts, Linux Kernel Development, previous W4118s

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# Single and multithreaded processes



More details on implementing threads later

# Avoid race conditions

- **Critical section:** a segment of code that accesses a shared variable (or resource)
- No more than one thread in critical section at a time.

```
// ++ balance  
mov    0x8049780,%eax  
add    $0x1,%eax  
mov    %eax,0x8049780  
...
```

```
// -- balance  
mov    0x8049780,%eax  
sub    $0x1,%eax  
mov    %eax,0x8049780  
...
```

# Critical section requirements

- **Safety (aka mutual exclusion):** no more than one thread in critical section at a time.
- **Liveness (aka progress):**
  - If multiple threads simultaneously request to enter critical section, must allow one to proceed
  - Must not depend on threads outside critical section
- **Bounded waiting (aka starvation-free)**
  - Must eventually allow waiting thread to proceed
- Makes no assumptions about the speed and number of CPU
  - However, assumes each thread makes progress

# Critical section desirable properties

- **Efficient**: don't consume too much resource while waiting
  - Don't busy wait (spin wait) for a long time. Better to relinquish CPU and let other thread run
- **Fair**: don't make one thread wait longer than others. Hard to do efficiently
- **Simple**: should be easy to use

# Implementing critical section using locks

- `lock(l)`: acquire lock exclusively; wait if not available
- `unlock(l)`: release exclusive access to lock

`pthread_mutex_t l = PTHREAD_MUTEX_INITIALIZER`

```
void* deposit(void *arg)
{
    int i;
    for(i=0; i<1e7; ++i) {
        pthread_mutex_lock(&l);
        ++ balance;
        pthread_mutex_unlock(&l);
    }
}
```

```
void* withdraw(void *arg)
{
    int i;
    for(i=0; i<1e7; ++i) {
        pthread_mutex_lock(&l);
        -- balance;
        pthread_mutex_unlock(&l);
    }
}
```

# Outline

- Critical section requirements
- Implementing locks
- Readers-writer lock

# Version 1: Disable interrupts

- **Can cheat on uniprocessor**: implement locks by disabling and enabling interrupts

```
lock()                                unlock()
{                                       {
    disable_interrupt();              enable_interrupt();
}
```

- **Good**: simple!
- **Bad**:
  - Both operations are **privileged**, can't let user program use
  - Doesn't work on **multiprocessors**
  - Cant use for long critical sections



# Version 2: Software Locks

- **Peterson's algorithm**: software-based lock implementation (2 page paper with proof)
- **Good**: doesn't require much from hardware
- Only assumptions:
  - Loads and stores are **atomic**
  - They execute **in order**
  - **Does not require** special hardware instructions

Reference: G. L. Peterson: "Myths About the Mutual Exclusion Problem", *Information Processing Letters* 12(3) 1981, 115–116

# Software-based lock: 1<sup>st</sup> attempt

```
// 0: lock is available, 1: lock is held by a thread
int flag = 0;

lock()
{
    while (flag == 1)
        ; // spin wait

    flag = 1;
}

unlock()
{
    flag = 0;
}
```

- Idea: use one flag, test then set; if unavailable, **spin-wait**
- Problem?
  - **Not safe**: both threads can be in critical section
  - **Not efficient**: busy wait, particularly bad on uniprocessor (will solve this later)

# Unsafe software lock, 1<sup>st</sup> attempt

```
lock()
{
    1: while (flag == 1)
        ; // spin wait
    2: flag = 1;
}

flag=0;
```

Thread 0:  
call lock()  
1: while (flag ==1) // it is 0, so  
continue

2: flag = 1;

```
unlock()
{
    3: flag = 0;
}
```

Thread 1:

call lock()  
1: while(flag == 1) // it is 0, so  
continue

2: flag = 1; // ! Thread 0 is already  
in critical section

In general, adversarial scheduler model useful to think about concurrency problems

# Software-based locks: 2<sup>nd</sup> attempt

// 1: a thread wants to enter critical section, 0: it doesn't

```
int flag[2] = {0, 0};
```

```
lock()
```

```
{  
    flag[self] = 1; // I need lock  
    while (flag[1-self] == 1)  
        ; // spin wait  
}
```

```
unlock()
```

```
{  
    // not any more  
    flag[self] = 0;  
}
```

- Idea: use per thread flags, set then test, to achieve mutual exclusion
- Why doesn't work?
  - **Not live:** can deadlock

# Deadlock: 2<sup>nd</sup> attempt

// 1: a thread wants to enter critical section, 0: it doesn't

```
int flag[2] = {0, 0};
```

```
lock()
```

```
{  
    flag[self] = 1; // I need lock  
    while (flag[1-self] == 1)  
        ; // spin wait  
}
```

```
unlock()
```

```
{  
    // not any more  
    flag[self] = 0;  
}
```

Thread 0

```
call lock()  
flag[0] = 1;
```

```
while (flag[1] == 1);  
// spins forever too!
```

Thread1

```
flag[1] = 1;  
while (flag[0] == 1);  
//spins forever!
```

...

# Software-based locks: 3<sup>rd</sup> attempt

```
// whose turn is it?  
int turn = 0;
```

```
lock()  
{  
    // wait for my turn  
    while (turn == 1 - self)  
        ; // spin wait  
}
```

```
unlock()  
{  
    // I'm done. your turn  
    turn = 1 - self;  
}
```

- Idea: strict alternation to achieve mutual exclusion
- Why doesn't work?
  - **Not live**: depends on threads outside critical section
  - Can't handle repeated calls to lock by same thread

# Software-based locks: final attempt (Peterson's algorithm)

```
// whose turn is it?
int turn = 0;
// 1: a thread wants to enter critical section, 0: it doesn't
int flag[2] = {0, 0};

lock()
{
    flag[self] = 1; // I need lock
    turn = 1 - self;
    // wait for my turn
    while (flag[1-self] == 1
        && turn == 1 - self)
        ; // spin wait while the
        // other thread has intent
        // AND it is the other
        // thread's turn
}

unlock()
{
    // not any more
    flag[self] = 0;
}

• Why works?
    – Safe?
    – Live?
    – Bounded wait?
```

# Software-based lock

- Problem
  - It's hard!
  - $N > 2$  threads? (Lamport's Bakery algorithm)
  - Modern out of order processors?



# Multiprocessor Challenges

- Modern processors are out-of-order/speculative
  - Reorder instructions to keep execution units full
  - Try very hard to avoid inconsistency
  - Guarantees valid only within single execution stream
- Memory access guarantees on x86
  - x86 is relatively conservative with reordering
  - Loads not reordered with other loads
  - Stores not reordered with other stores
  - Stores not reordered with older loads
  - All loads and stores to same location are not reordered
  - Load can reorder with older store to different addr
- Breaks Peterson's algorithm!

Reference: <http://www.linuxjournal.com/article/8211>

<http://www.intel.com/content/dam/www/public/us/en/documents/manuals/64-ia-32-architectures-software-developer-manual-325462.pdf>

# Instruction Reordering affects Locking

Thread 0

```
Lock: flag[0] = 1; // I need lock
turn = 1;
while (flag[1]==1 && turn==1);
}
```

Thread 1

```
Lock: flag[1] = 1; // I need lock
turn = 0;
while (flag[0]==1 && turn==0);
}
```

- Possible for mutual exclusion to be violated?

— Yes!

Reorder

```
Lock: r1 = Load(flag[1])

turn = 1;
flag[0] = 1; // I need lock
while (r1==1 && turn==1);
// flag[1]==0
}
```

```
Lock: flag[1] = 1; // I need lock
turn = 0;
while (flag[0]==1 && turn==0);
// flag[0]==0
}
```

# Memory Barriers

- A memory barrier or fence
  - Ensures that all memory operations up to the barrier are executed before proceeding
- x86 provides several memory fence instructions
  - Relatively expensive (100s of cycles)
  - mfence: all prior memory accesses completed
  - lfence: all prior loads completed
  - sfence: all prior stores flushed

```
lock() {  
    flag[self] = 1; // I need lock  
    turn = 1 - self;  
    sfence; // Store barrier  
    while (flag[1-self] == 1 && turn == 1 - self);  
}
```

# Lamport's Bakery Algorithm

- Support more than 2 processes
  - Integer tokens (increasing numbers)
  - Each customer gets next largest token
  - Same token? Smaller thread\_id gets priority
  - Smallest token enters critical region

```
bool flag[1..NUM_THREADS] = {0}; // Want to enter
int token[1..NUM_THREADS] = {0}; // My token
lock(i) { // Lock by thread i
    flag[i] = 1;
    token[i] = 1 + max(token[0..NUM_THREADS-1]);
    flag[i] = 0;
    for (j = 1; j <= NUM_THREADS; j++) {
        while (flag[j]); // Is j getting token?
        while ((token[j] && ((token[j], j) < (token[i], i))); // j has smaller token?
    }
}
unlock(integer i) {
    token[i] = 0;
}
```

Reference: A New Solution of Dijkstra's Concurrent Programming Problem. L. Lamport. Communications of the ACM, 1974. <http://research.microsoft.com/en-us/um/people/lamport/pubs/bakery.pdf>

# Version 3: Hardware Instructions

```
// 0: lock is available, 1: lock is held by a thread
```

```
int flag = 0;
```

```
lock()
```

```
{
```

```
    while(test_and_set(&flag))
```

```
        ;
```

```
}
```

```
unlock()
```

```
{
```

```
    flag = 0;
```

```
}
```

- Problem with the test-then-set approach: **test and set are not atomic**
- Fix: **special atomic operation**
  - `int test_and_set (int *lock) {`
    - `int old = *lock;`
    - `*lock = 1;`
    - `return old;`
  - `}`
  - Atomically returns `*lock` and sets `*lock` to 1

# Implementing test\_and\_set on x86

```
long test_and_set(volatile long* lock)
{
    int old;
    asm("xchgl %0, %1"
        : "=r"(old), "+m"(*lock) // output
        : "0"(1) // input
        : "memory" // can clobber anything in memory
    );
    return old;
}
```

- `xchg reg, addr`: atomically swaps `*addr` and `reg`
- Spin locks on x86 are implemented using this instruction
- x86 also provides a `lock` prefix that allows bus to be locked for inst
- In Linux:
  - Arch independent: [kernel/spinlock.c](#)
  - Arch dependent: [arch/x86/include/asm/spinlock.h](#)

# Spin-wait or block?

- **Problem of spin-wait: waste CPU cycles**
  - Worst case: thread holding a busy-wait lock gets preempted, other threads try to acquire the same lock
- On uniprocessor: should **not** use spin-lock
  - Yield CPU when lock not available (need OS support)
- On multi-processor
  - Thread holding lock gets preempted → ???
  - Correct action depends on how long before lock release
    - Lock released “quickly” → ?
    - Lock released “slowly” → ?

# Problem with simple yield

```
lock()
{
    while(test_and_set(&flag))
        yield();
}
```

- Problem:
  - Still a lot of context switches: **thundering herd**
  - Starvation possible
- Why? **No control** over who gets the lock next
- **Need explicit control over who gets the lock**



# Version 4: Sleep Locks

```
lock() {  
  while  
  (test_and_set(&flag))  
    add myself to wait queue  
    yield  
  ...  
}
```

```
unlock() {  
  flag = 0  
  if(any thread in wait queue)  
    wake up one wait thread  
  ...  
}
```

← Lock from another thread?

- The idea: **add thread to queue when lock unavailable**; in **unlock()**, wake up one thread in queue
- Problem I: **lost wakeup**
- Problem II: **wrong thread gets lock**

# Lost wakeup

```
lock() {  
  1: while (test_and_set(&flag))  
  2: add myself to wait queue  
  3: yield  
  ...  
}
```

```
Thread 0:  
call lock()  
while (test_and_set(&flag)) {  
  
  add myself to wait queue  
  yield  
} // wait forever (or until next unlock)!
```

```
unlock() {  
  4: flag = 0  
  5: if(any thread in wait queue)  
  6: wake up one wait thread  
  ...  
}
```

```
Thread 1  
  
call unlock()  
flag = 0  
if (any thread in wait queue) // No!  
  wake_up_one_wait_thread
```

# Wrong thread gets lock

```
lock() {  
  1: while (test_and_set(&flag))  
  2: add myself to wait queue  
  3: yield  
  ...  
}
```

```
unlock() {  
  4: flag = 0  
  5: if (any thread in wait queue)  
  6: wake up one wait thread  
  ...  
}
```

Thread 0:

```
call lock()  
while (test_set(&flag))  
  add myself to wait queue  
  yield
```

Thread 1

```
call unlock()  
flag = 0  
if (thread in wait queue)  
  wake_up_thread
```

Thread 2

```
call lock()  
while (test_set(&flag))
```

- Fix: `unlock()` directly transfers lock to waiting thread

# Implementing locks: version 4, the code

```
typedef struct __mutex_t {  
    int flag;    // 0: mutex is available, 1: mutex is not available  
    int guard;  // guard lock to avoid losing wakeups  
    queue_t *q; // queue of waiting threads  
} mutex_t;
```

```
void lock(mutex_t *m) {  
    while (test_and_set(m->guard))  
        ; //acquire guard lock by spinning  
    if (m->flag == 0) {  
        m->flag = 1; // acquire mutex  
        m->guard = 0;  
    } else {  
        enqueue(m->q, self);  
        m->guard = 0;  
        yield();  
    }  
}
```

```
void unlock(mutex_t *m) {  
    while (test_and_set(m->guard))  
        ;  
    if (queue_empty(m->q))  
        // release mutex; no one wants mutex  
        m->flag = 0;  
    else  
        // direct transfer mutex to next thread  
        wakeup(dequeue(m->q));  
    m->guard = 0;  
}
```

# Adaptive Mutexes

- Cons of Spinlocks
  - Inefficient if lock is held for long duration
- Cons of Sleeplocks
  - Higher overhead, state maintenance
- Solaris, OS X, FreeBSD
  - Idea: use spinlock if holder is currently running, sleeplock otherwise
  - Best of both worlds

# Outline

- Critical section requirements
- Implementing locks
- **Readers-writer lock**

# Readers-Writers problem

- A **reader** is a thread that needs to look at the shared data but won't change it
- A **writer** is a thread that modifies the shared data
- Example: making an airline reservation
- Courtois et al 1971

# Readers-writer lock

```
rwlock_t lock;
```

## Writer

```
write_lock (&lock);  
...  
// write shared data  
...  
write_unlock (&lock);
```

## Reader

```
read_lock (&lock);  
...  
// read shared data  
...  
read_unlock (&lock);
```

- **read\_lock**: acquires lock in read (shared) mode
  - Lock is not acquired or is acquired in read mode → success
  - Otherwise (lock is in write mode) → wait
- **write\_lock**: acquires lock in write (exclusive) mode
  - Lock is not acquired → success
  - Otherwise → wait



# Implementing readers-writer lock

```
struct rwlock_t {  
    int nreader;    // init to 0  
    lock_t guard;  // init to unlocked  
    lock_t lock;   // init to unlocked  
};
```

```
write_lock(rwlock_t *l)  
{  
    lock(&l->lock);  
}
```

```
write_unlock(rwlock_t *l)  
{  
    unlock(&l->lock);  
}
```

```
read_lock(rwlock_t *l)  
{  
    lock(&l->guard);  
    ++ nreader;  
    if(nreader == 1) // first reader  
        lock(&l->lock);  
    unlock(&l->guard);  
}
```

```
read_unlock(rwlock_t *l)  
{  
    lock(&l->guard);  
    -- nreader;  
    if(nreader == 0) // last reader  
        unlock(&l->lock);  
    unlock(&l->guard);  
}
```

**Problem: may starve writer!**

# Driving out readers in a RW-Lock

```
struct rwlock_t {
    int nreader;    // init to 0
    lock_t guard;  // init to unlocked
    lock_t lock;   // init to unlocked
    lock_t writer; // init to unlocked
};

write_lock(rwlock_t *l)
{
    lock(&l->writer);
    lock(&l->lock);
    unlock(&l->writer);
}

write_unlock(rwlock_t *l)
{
    unlock(&l->lock);
}

read_lock(rwlock_t *l)
{
    lock(&l->writer);
    lock(&l->guard);
    ++ nreader;
    if(nreader == 1) // first reader
        lock(&l->lock);
    unlock(&l->guard);
    unlock(&l->writer);
}

read_unlock(rwlock_t *l)
{
    lock(&l->guard);
    -- nreader;
    if(nreader == 0) // last reader
        unlock(&l->lock);
    unlock(&l->guard);
}
```

Q: In write\_lock, can we just use guard instead of writer lock?