**Warranty**
Parallax warrants its products against defects in materials and workmanship for a period of 90 days. If you discover a defect, Parallax will, at its option, repair, replace, or refund the purchase price. Simply call our sales department for an RMA number, write it on the label and return the product with a description of the problem. We will return your product, or its replacement, using the same shipping method used to ship the product to Parallax (for instance, if you ship your product via overnight express, we will do the same).

This warranty does not apply if the product has been modified or damaged by accident, abuse, or misuse.

**14-Day Money-Back Guarantee**
If, within 14 days of having received your product, you find that it does not suit your needs, you may return it for a refund. Parallax will refund the purchase price of the product, excluding shipping/handling costs. This does not apply if the product has been altered or damaged.

**Copyrights and Trademarks**
Copyright © 2000 by Parallax, Inc. All rights reserved. PBASIC is a trademark and BASIC Stamp is a registered trademark or Parallax, Inc. PIC is a registered trademark of Microchip Technology, Inc. Windows is a registered trademark of Microsoft Corporation. 1-wire is a registered trademark of Dallas Semiconductor. Other brand and product names are trademarks or registered trademarks of their respective holders.

**Disclaimer of Liability**
Parallax, Inc. is not responsible for special, incidental, or consequential damages resulting from any breach of warranty, or under any legal theory, including lost profits, downtime, goodwill, damage to or replacement of equipment or property, and any costs of recovering, reprogramming, or reproducing any data stored in or used with Parallax products.

**Internet Access**
We maintain Internet systems for your convenience. These may be used to obtain software, communicate with members of Parallax, and communicate with other customers. Access information is shown below:

- **Web:** http://www.parallaxinc.com
  http://www.stampsinclass.com
- **General e-mail:** info@parallaxinc.com
- **Tech. e-mail:** stamptech@parallaxinc.com

**Internet BASIC Stamp Discussion List**
We maintain a BASIC Stamp discussion list for people interested in BASIC Stamps. Many people subscribe to the list, and all questions and answers to the list are distributed to all subscribers. It’s a fun, fast, and free way to discuss BASIC Stamp issues. To subscribe to the BASIC Stamps list, visit the Tech Support section of the Parallax, Inc website.

This manual is valid with the following software and firmware versions:

**BASIC Stamp 1:**
- STAMP.EXE software version 2.1
- Firmware version 1.4

**BASIC Stamp 2:**
- STAMP2.EXE software version 1.1
- STAMPW.EXE software version 1.096
- Firmware version 1.0

**BASIC Stamp 2e:**
- STAMP2E.EXE software version 1.0
- STAMPW.EXE software version 1.096
- Firmware version 1.0

**BASIC Stamp 2sx:**
- STAMP2SX.EXE software version 1.0
- STAMPW.EXE software version 1.096
- Firmware version 1.0

**BASIC Stamp 2p:**
- STAMP2P.EXE software version 1.6
- STAMPW.EXE software version 1.098
- Firmware version 1.1

The information herein will usually apply to newer versions but may not apply to older versions. New software can be obtained free on our ftp and web site (ftp.parallaxinc.com, www.parallaxinc.com). If you have any questions about what you need to upgrade your product, please contact Parallax.
Contents

PREFIX ........................................................................................................5

INTRODUCTION TO THE BASIC STAMP ............................................... 7

BASIC STAMP 1 HARDWARE ..................................................................... 8
BASIC STAMP 2 HARDWARE ..................................................................... 10
BASIC STAMP 2E HARDWARE ................................................................... 12
BASIC STAMP 2SX HARDWARE .................................................................. 14
BASIC STAMP 2P HARDWARE ................................................................... 16

DEVELOPMENT BOARDS ......................................................................... 18

BASIC Stamp 1 Carrier Board .................................................................... 18
BASIC Stamp 2 Carrier Board .................................................................... 19
BASIC Stamp Super Carrier Board ................................................................. 20
Board of Education ......................................................................................... 22
BASIC Stamp Activity Board ......................................................................... 23

GUIDELINES AND PRECAUTIONS ....................................................... 25

QUICK START GUIDE ............................................................................ 29

USING THE BASIC STAMP EDITOR .................................................... 33

BASIC STAMP WINDOWS EDITOR ......................................................... 34
BASIC STAMP DOS EDITOR ...................................................................... 41

BASIC STAMP ARCHITECTURE ............................................................. 45

RAM ORGANIZATION (BS1) ..................................................................... 45
RAM ORGANIZATION (BS2, BS2E, BS2sx, BS2P) ..................................... 46

DEFINING AND USING VARIABLES ...................................................... 48

The Rules of Symbol Names ........................................................................ 49
Defining Array Variables .............................................................................. 51
Aliases and Variable Modifiers .................................................................... 53

CONSTANTS AND COMPILE-TIME EXPRESSIONS .............................. 56

NUMBER REPRESENTATIONS ................................................................... 59

ORDER OF OPERATIONS ......................................................................... 60

INTEGER MATH RULES ........................................................................... 62

UNARY OPERATORS .................................................................................. 63

Absolute Value (ABS) .............................................................................. 64
Cosine (COS) ........................................................................................... 64
Decoder (DCD) ......................................................................................... 64
Contents

Inverse (~) ................................................................................................................64
Negative (-) ..............................................................................................................64
Encoder (NCD) ........................................................................................................65
Sine (SIN) .................................................................................................................65
Square Root (SQR) ...................................................................................................66

BINARY OPERATORS ..................................................................................................66
Add (+) ......................................................................................................................67
Subtract (-) ...............................................................................................................67
Multiply (*) ................................................................................................................67
Multiply High (**) .....................................................................................................68
Multiply Middle (/) ..................................................................................................68
Divide (/) ...................................................................................................................69
Modulus (//) ............................................................................................................70
Minimum (MIN) ........................................................................................................70
Maximum (MAX) ......................................................................................................71
Digit (DIG) ................................................................................................................72
Shift Left (<<) ..........................................................................................................72
Shift Right (>>) .......................................................................................................72
Reverse (REV) .........................................................................................................73
And (&) ......................................................................................................................73
Or (|) .........................................................................................................................73
Xor (^) .......................................................................................................................74
And Not (&/) .............................................................................................................75
Or Not (|/) ...............................................................................................................75
Xor Not (^/) .............................................................................................................75

BASIC STAMP COMMAND REFERENCE ..................................................................77
AUXIO ..........................................................................................................................81
BRANCH .....................................................................................................................83
BUTTON .....................................................................................................................85
COUNT .........................................................................................................................89
DATA ...........................................................................................................................91
DEBUG .........................................................................................................................97
DTMFOUT ..................................................................................................................107
EEPROM .....................................................................................................................111
END ............................................................................................................................115
FOR...NEXT ..............................................................................................................117
FREQOUT ...................................................................................................................123
GET ............................................................................................................................127
Contents

GOSUB ........................................................................................................................129
GOTO ...........................................................................................................................133
HIGH ............................................................................................................................135
I2CIN ............................................................................................................................137
I2COUT .........................................................................................................................143
IF…THEN .....................................................................................................................149
INPUT ..........................................................................................................................155
IOTERM .......................................................................................................................157
LCDCMD ......................................................................................................................159
LCDIN ..........................................................................................................................167
LCDOUt .......................................................................................................................171
LOOKDOWN ................................................................................................................177
LOOKUP ......................................................................................................................183
LOW .............................................................................................................................187
MAINIO .......................................................................................................................189
NAP .............................................................................................................................191
OUTPUT ......................................................................................................................195
OWIN ..........................................................................................................................197
OWOUT .......................................................................................................................205
PAUSE ........................................................................................................................213
POLLIN .........................................................................................................................215
POLLMODE ...................................................................................................................219
POLLOUT ....................................................................................................................225
POLLRUN ....................................................................................................................231
POLLWAIT ...................................................................................................................235
POT ..............................................................................................................................239
PULSIN .......................................................................................................................241
PULSOUT ....................................................................................................................243
PUT ..............................................................................................................................245
PWM ............................................................................................................................247
RANDOM .....................................................................................................................251
RCTIME .....................................................................................................................255
READ ..........................................................................................................................261
RETURN ......................................................................................................................265
REVERSE ...................................................................................................................267
RUN .............................................................................................................................269
SERIN ..........................................................................................................................273
SEROUT .....................................................................................................................293
SHIFTIN ......................................................................................................................309
SHIFTOUT ..................................................................................................................313
SLEEP .........................................................................................................................317
SOUND .........................................................................................................................319
# Contents

<table>
<thead>
<tr>
<th>Command</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>STOP</td>
<td>321</td>
</tr>
<tr>
<td>STOP</td>
<td>323</td>
</tr>
<tr>
<td>TOGGLE</td>
<td>327</td>
</tr>
<tr>
<td>WRITE</td>
<td>329</td>
</tr>
<tr>
<td>XOUT</td>
<td>333</td>
</tr>
</tbody>
</table>

APPENDIX A: ASCII CHART ................................................................. 337

APPENDIX B: RESERVED WORDS ............................................................. 339

APPENDIX C: CONVERSION FORMATTERS .................................................. 341
Thank you for purchasing the Parallax BASIC Stamp development system. We have done our best to produce a full-featured, yet easy to use development system for the BASIC Stamp microcontrollers. We hope you will find this system as enjoyable to use as we do.

This manual is written for the latest available BASIC Stamp modules and software as of November 2000. As the product-line evolves new information may become available. It is always recommended to visit the Parallax, Inc. web site, www.parallaxinc.com, for the latest information.

This manual is intended to be a complete reference manual to the architecture and command structure of the BASIC Stamps. This manual is not meant to teach programming or electrical design; though a person can learn a lot by paying close attention to the details in this book. If you have never programmed in the BASIC language or are unfamiliar with electronics, it would be best to locate one or more of the following books for further information:

1. Programming and Customizing the BASIC Stamp Computer
2. Microcontroller Projects with BASIC Stamps
   Al Williams, R&D Books ISBN: 0-87930-587-8
3. The Microcontroller Application Cookbook
4. What’s A Microcontroller
   Free on Parallax CD (Documentation -> Educational Curriculum section) and web site (Downloads section), or for purchase in print
5. BASIC Analog and Digital
   Free on Parallax CD (Documentation -> Educational Curriculum section) and web site (Downloads section), or for purchase in print
6. Earth Measurements
   Free on Parallax CD (Documentation -> Educational Curriculum section) and web site (Downloads section), or for purchase in print
7. Robotics
   Free on Parallax CD (Documentation -> Educational Curriculum section) and web site (Downloads section), or for purchase in print

In addition, there are hundreds of great examples available on the Parallax CD and web site (www.parallaxinc.com). Also, Nut & Volts Magazine (www.nutsvolts.com / 1-800-783-4624) is a national electronic hobbyist's
magazine that features monthly articles featuring the BASIC Stamps. This is an excellent resource for beginners and experts alike! For a sample of the BASIC Stamp articles, visit their web site.

Packing List
The BASIC Stamps are available in many different forms. You may have received them in a Starter Kit in a special limited-time package or individually. The packing list below describes the general list of items that would be included in a BASIC Stamp Starter Kit at the time of this writing:

**BASIC Stamp Starter Kit**
- (1) BASIC Stamp Module (Rev. D, BS1-IC, OEMBS1, BS2-IC, OEMBS2, BS2e-IC, BS2sx-IC or BS2p-IC)
- (1) BASIC Stamp development software (on CD in Software section)
- (1) BASIC Stamp manual (this manual)
- (1) BASIC Stamp development board (Stamp 1 Carrier Board, Stamp 2 Carrier Board, Super Carrier Board, BASIC Stamp Activity Board or Board or Education)
- (1) Set of jumper wires (only included with Board of Education)
- (1) 9-pin serial cable

If any items are missing, please let us know.
Welcome to the wonderful world of BASIC Stamp microcontrollers. BASIC Stamp microcontrollers have been in use by engineers and hobbyists since we first introduced them in 1992. As of July 2000, Parallax customers have put more than 200,000 BASIC Stamp modules into use. Over this eight-year period, the BASIC Stamp line of controllers has evolved into five models and many physical package types, explained below.

**General Operation Theory**

BASIC Stamps are microcontrollers (tiny computers) that are designed for use in a wide array of applications. Many projects that require an embedded system with some level of intelligence can use a BASIC Stamp module as the controller.

Each BASIC Stamp comes with a BASIC Interpreter chip, internal memory (RAM and EEPROM), a 5-volt regulator, a number of general-purpose I/O pins (TTL-level, 0-5 volts), and a set of built-in commands for math and I/O pin operations. BASIC Stamps are capable of running a few thousand instructions per second and are programmed with a simplified, but customized form of the BASIC programming language, called PBASIC.

**PBASIC Language**

We developed PBASIC specifically for the BASIC Stamps as a simple, easy to learn language that is also well suited for this architecture. It includes many of the instructions featured in other forms of BASIC (GOTO, FOR...NEXT, IF...THEN) as well as some specialized instructions (SERIN, PWM, BUTTON, COUNT and DTMFOUT). This manual includes an extensive section devoted to each of the available instructions.

**Hardware**

At the time of this writing, there are currently five models of the BASIC Stamp; the BASIC Stamp 1, BASIC Stamp 2, BASIC Stamp 2e, BASIC Stamp 2sx and BASIC Stamp 2p. The diagrams below detail the various package types and part numbers of these modules.
Introduction to the BASIC Stamps

BASIC Stamp 1

Figure 1.1: BASIC Stamp 1 Rev. D (27100)

Figure 1.2: BASIC Stamp 1 (Rev. B) (BS1-IC)

Figure 1.3: OEM BASIC Stamp 1 (Rev. A) (27295 or 27296)
The BASIC Stamp 1 is available in the above three physical packages. The BASIC Stamp 1 Rev. D (simply called the Rev. D), see Figure 1.1, includes prototyping area suitable for soldering electronic components. The BS1-IC (Figure 1.2) uses surface mount components to fit in a small 14-pin SIP package. The OEMBS1 (Figure 1.3) features an easier-to-trace layout meant to aid customers who wish to integrate the BASIC Stamp 1 circuit directly into their design (as a lower-cost solution). The OEMBS1 is available in either an assembled form or a kit form. All three packages are functionally equivalent with the exception that the Rev. D does not have an available reset pin.

<table>
<thead>
<tr>
<th>Pin</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>VIN</td>
<td>Unregulated power in: accepts 5.5 - 15 VDC (6-40 VDC on BS1-IC rev. b), which is then internally regulated to 5 volts. May be left unconnected if 5 volts is applied to the VDD (+5V) pin.</td>
</tr>
<tr>
<td>2</td>
<td>VSS</td>
<td>System ground: connects to PC parallel port pin 25 (GND) for programming.</td>
</tr>
<tr>
<td>3</td>
<td>PCO</td>
<td>PC Out: connects to PC parallel port pin 11 (BUSY) for programming.</td>
</tr>
<tr>
<td>4</td>
<td>PCI</td>
<td>PC In: connects to PC parallel port pin 2 (D0) for programming.</td>
</tr>
<tr>
<td>5</td>
<td>VDD</td>
<td>5-volt DC input/output: (Also called +5V) if an unregulated voltage is applied to the VIN pin, then this pin will output 5 volts. If no voltage is applied to the VIN pin, then a regulated voltage between 4.5V and 5.5V should be applied to this pin.</td>
</tr>
<tr>
<td>6</td>
<td>RES</td>
<td>Reset input/output: goes low when power supply is less than approximately 4.2 volts, causing the BASIC Stamp to reset. Can be driven low to force a reset. This pin is internally pulled high and may be left disconnected if not needed. Do not drive high.</td>
</tr>
<tr>
<td>7-14</td>
<td>P0-P7</td>
<td>General-purpose I/O pins: each can sink 25 mA and source 20 mA. However, the total of all pins should not exceed 50 mA (sink) and 40 mA (source).</td>
</tr>
</tbody>
</table>

See the "BASIC Stamp Programming Connections" section, below, for more information on the required programming connections between the PC and the BASIC Stamp.
BASIC Stamp 2

The BASIC Stamp 2 is available in the above two physical packages. The BS2-IC (Figure 1.4) uses surface mount components to fit in a small 24-pin DIP package. The OEMBS2 (Figure 1.5) features an easier-to-trace layout meant to aid customers who wish to integrate the BASIC Stamp 2 circuit directly into their design (as a lower-cost solution). The OEMBS2 is available in either an assembled form or a kit form. Both packages are functionally equivalent.
Table 1.2: BASIC Stamp 2 Pin Descriptions.

<table>
<thead>
<tr>
<th>Pin</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>SOUT</td>
<td>Serial Out: connects to PC serial port RX pin (DB9 pin 2 / DB25 pin 3) for programming.</td>
</tr>
<tr>
<td>2</td>
<td>SIN</td>
<td>Serial In: connects to PC serial port TX pin (DB9 pin 3 / DB25 pin 2) for programming.</td>
</tr>
<tr>
<td>3</td>
<td>ATN</td>
<td>Attention: connects to PC serial port DTR pin (DB9 pin 4 / DB25 pin 20) for programming.</td>
</tr>
<tr>
<td>4</td>
<td>VSS</td>
<td>System ground: (same as pin 23) connects to PC serial port GND pin (DB9 pin 5 / DB25 pin 7) for programming.</td>
</tr>
<tr>
<td>5-20</td>
<td>P0-P15</td>
<td>General-purpose I/O pins: each can sink 25 mA and source 20 mA. However, the total of all pins should not exceed 50 mA (sink) and 40 mA (source) if using the internal 5-volt regulator. The total per 8-pin groups (P0 – P7 or P8 – 15) should not exceed 50 mA (sink) and 40 mA (source) if using an external 5-volt regulator.</td>
</tr>
<tr>
<td>21</td>
<td>VDD</td>
<td>5-volt DC input/output: if an unregulated voltage is applied to the VIN pin, then this pin will output 5 volts. If no voltage is applied to the VIN pin, then a regulated voltage between 4.5V and 5.5V should be applied to this pin.</td>
</tr>
<tr>
<td>22</td>
<td>RES</td>
<td>Reset input/output: goes low when power supply is less than approximately 4.2 volts, causing the BASIC Stamp to reset. Can be driven low to force a reset. This pin is internally pulled high and may be left disconnected if not needed. Do not drive high.</td>
</tr>
<tr>
<td>23</td>
<td>VSS</td>
<td>System ground: (same as pin 4) connects to power supply's ground (GND) terminal.</td>
</tr>
<tr>
<td>24</td>
<td>VIN</td>
<td>Unregulated power in: accepts 5.5 - 15 VDC (6-40 VDC on BS2-IC rev. e), which is then internally regulated to 5 volts. May be left unconnected if 5 volts is applied to the VDD (+5V) pin.</td>
</tr>
</tbody>
</table>

See the "BASIC Stamp Programming Connections" section, below, for more information on the required programming connections between the PC and the BASIC Stamp.
The BASIC Stamp 2e is available in the above two physical packages. The BS2e-IC (Figure 1.6) uses surface mount components to fit in a small 24-pin DIP package. The OEMBS2e (Figure 1.7) features an easier-to-trace layout meant to aid customers who wish to integrate the BASIC Stamp 2e circuit directly into their design (as a lower-cost solution). The OEMBS2e is available in assembled form only.
Table 1.3: BASIC Stamp 2e Pin Descriptions.

<table>
<thead>
<tr>
<th>Pin</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>SOUT</td>
<td>Serial Out: connects to PC serial port RX pin (DB9 pin 2 / DB25 pin 3) for programming.</td>
</tr>
<tr>
<td>2</td>
<td>SIN</td>
<td>Serial In: connects to PC serial port TX pin (DB9 pin 3 / DB25 pin 2) for programming.</td>
</tr>
<tr>
<td>3</td>
<td>ATN</td>
<td>Attention: connects to PC serial port DTR pin (DB9 pin 4 / DB25 pin 20) for programming.</td>
</tr>
<tr>
<td>4</td>
<td>VSS</td>
<td>System ground: (same as pin 23) connects to PC serial port GND pin (DB9 pin 5 / DB25 pin 7) for programming.</td>
</tr>
<tr>
<td>5-20</td>
<td>P0-P15</td>
<td>General-purpose I/O pins: each can source and sink 30 mA. However, the total of all pins should not exceed 75 mA (source or sink) if using the internal 5-volt regulator. The total per 8-pin groups (P0 – P7 or P8 – 15) should not exceed 100 mA (source or sink) if using an external 5-volt regulator.</td>
</tr>
<tr>
<td>21</td>
<td>VDD</td>
<td>5-volt DC input/output: if an unregulated voltage is applied to the VIN pin, then this pin will output 5 volts. If no voltage is applied to the VIN pin, then a regulated voltage between 4.5V and 5.5V should be applied to this pin.</td>
</tr>
<tr>
<td>22</td>
<td>RES</td>
<td>Reset input/output: goes low when power supply is less than approximately 4.2 volts, causing the BASIC Stamp to reset. Can be driven low to force a reset. This pin is internally pulled high and may be left disconnected if not needed. Do not drive high.</td>
</tr>
<tr>
<td>23</td>
<td>VSS</td>
<td>System ground: (same as pin 4) connects to power supply’s ground (GND) terminal.</td>
</tr>
<tr>
<td>24</td>
<td>VIN</td>
<td>Unregulated power in: accepts 5.5 - 12 VDC (7.5 recommended), which is then internally regulated to 5 volts. May be left unconnected if 5 volts is applied to the VDD (+5V) pin.</td>
</tr>
</tbody>
</table>

See the "BASIC Stamp Programming Connections" section, below, for more information on the required programming connections between the PC and the BASIC Stamp.
BASIC Stamp 2sx

The BASIC Stamp 2sx is available in the above two physical packages. The BS2sx-IC (Figure 1.8) uses surface mount components to fit in a small 24-pin DIP package. The OEMBS2sx (Figure 1.9) features an easier-to-trace layout meant to aid customers who wish to integrate the BASIC Stamp 2sx circuit directly into their design (as a lower-cost solution). The OEMBS2sx is available in assembled form only.
Table 1.4: BASIC Stamp 2sx Pin Descriptions.

<table>
<thead>
<tr>
<th>Pin</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>SOUT</td>
<td>Serial Out: connects to PC serial port RX pin (DB9 pin 2 / DB25 pin 3) for programming.</td>
</tr>
<tr>
<td>2</td>
<td>SIN</td>
<td>Serial In: connects to PC serial port TX pin (DB9 pin 3 / DB25 pin 2) for programming.</td>
</tr>
<tr>
<td>3</td>
<td>ATN</td>
<td>Attention: connects to PC serial port DTR pin (DB9 pin 4 / DB25 pin 20) for programming.</td>
</tr>
<tr>
<td>4</td>
<td>VSS</td>
<td>System ground: (same as pin 23) connects to PC serial port GND pin (DB9 pin 5 / DB25 pin 7) for programming.</td>
</tr>
<tr>
<td>5-20</td>
<td>P0-P15</td>
<td>General-purpose I/O pins: each can source and sink 30 mA. However, the total of all pins should not exceed 75 mA (source or sink) if using the internal 5-volt regulator. The total per 8-pin groups (P0 – P7 or P8 – 15) should not exceed 100 mA (source or sink) if using an external 5-volt regulator.</td>
</tr>
<tr>
<td>21</td>
<td>VDD</td>
<td>5-volt DC input/output: if an unregulated voltage is applied to the VIN pin, then this pin will output 5 volts. If no voltage is applied to the VIN pin, then a regulated voltage between 4.5V and 5.5V should be applied to this pin.</td>
</tr>
<tr>
<td>22</td>
<td>RES</td>
<td>Reset input/output: goes low when power supply is less than approximately 4.2 volts, causing the BASIC Stamp to reset. Can be driven low to force a reset. This pin is internally pulled high and may be left disconnected if not needed. Do not drive high.</td>
</tr>
<tr>
<td>23</td>
<td>VSS</td>
<td>System ground: (same as pin 4) connects to power supply's ground (GND) terminal.</td>
</tr>
<tr>
<td>24</td>
<td>VIN</td>
<td>Unregulated power in: accepts 5.5 - 12 VDC (7.5 recommended), which is then internally regulated to 5 volts. May be left unconnected if 5 volts is applied to the VDD (+5V) pin.</td>
</tr>
</tbody>
</table>

See the "BASIC Stamp Programming Connections" section, below, for more information on the required programming connections between the PC and the BASIC Stamp.
The BASIC Stamp 2p is available in the above two physical packages. Both packages use surface mount components to fit in a small package. The BS2p24-IC (Figure 1.10) is a 24-pin DIP package. The BS2p40-IC (Figure 1.11) is a 40-pin DIP package. Both packages are functionally equivalent except that the BS2p40 has 32 I/O pins instead of 16.
Table 1.5: BASIC Stamp 2p Pin Descriptions.

<table>
<thead>
<tr>
<th>Pin</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>SOUT</td>
<td>Serial Out: connects to PC serial port RX pin (DB9 pin 2 / DB25 pin 3) for programming.</td>
</tr>
<tr>
<td>2</td>
<td>SIN</td>
<td>Serial In: connects to PC serial port TX pin (DB9 pin 3 / DB25 pin 2) for programming.</td>
</tr>
<tr>
<td>3</td>
<td>ATN</td>
<td>Attention: connects to PC serial port DTR pin (DB9 pin 4 / DB25 pin 20) for programming.</td>
</tr>
<tr>
<td>4</td>
<td>VSS</td>
<td>System ground: (same as pin 23 on BS2p24, or pin 39 on BS2p40) connects to PC serial port GND pin (DB9 pin 5 / DB25 pin 7) for programming.</td>
</tr>
<tr>
<td>5-20</td>
<td>P0-P15</td>
<td>General-purpose I/O pins: each can source and sink 30 mA. However, the total of all pins (including X0-X15, if using the BS2p40) should not exceed 75 mA (source or sink) if using the internal 5-volt regulator. The total per 8-pin groups (P0 – P7, P8 – 15, X0 – X7 or X8 – X15) should not exceed 100 mA (source or sink) if using an external 5-volt regulator.</td>
</tr>
<tr>
<td>{21-36}</td>
<td>X0-X15</td>
<td>(BS2p40 Only!) Auxiliary Bank of General-purpose I/O pins: each can source and sink 30 mA. However, the total of all pins (including P0 – P15) should not exceed 75 mA (source or sink) if using the internal 5-volt regulator. The total per 8-pin groups (P0 – P7, P8 – 15, X0 – X7 or X8 – X15) should not exceed 100 mA (source or sink) if using an external 5-volt regulator.</td>
</tr>
<tr>
<td>21</td>
<td>VDD</td>
<td>5-volt DC input/output: if an unregulated voltage is applied to the VIN pin, then this pin will output 5 volts. If no voltage is applied to the VIN pin, then a regulated voltage between 4.5V and 5.5V should be applied to this pin.</td>
</tr>
<tr>
<td>22</td>
<td>RES</td>
<td>Reset input/output: goes low when power supply is less than approximately 4.2 volts, causing the BASIC Stamp to reset. Can be driven low to force a reset. This pin is internally pulled high and may be left disconnected if not needed. Do not drive high.</td>
</tr>
<tr>
<td>23</td>
<td>VSS</td>
<td>System ground: (same as pin 4) connects to power supply’s ground (GND) terminal.</td>
</tr>
<tr>
<td>24</td>
<td>VIN</td>
<td>Unregulated power in: accepts 5.5 - 12 VDC (7.5 recommended), which is then internally regulated to 5 volts. May be left unconnected if 5 volts is applied to the VDD (+5V) pin.</td>
</tr>
</tbody>
</table>

NOTE: Pin numbers in braces () are BS2p40 pin numbers.

See the "BASIC Stamp Programming Connections" section, below, for more information on the required programming connections between the PC and the BASIC Stamp.
Development Boards
We provide a number of development boards to make using the BASIC Stamps more convenient. Below is a short description of the boards and their intended use. Please refer to the development board’s documentation (if any) for more details.

BASIC Stamp 1 Carrier Board (Rev. E)
The BASIC Stamp 1 Carrier Board (also called the BS1 Carrier Board) is designed to accommodate the BS1-IC module. The BASIC Stamp 1 Carrier Board provides nearly the same form factor and prototyping space as with the BASIC Stamp 1 Rev. D, but with the added feature of the reset button. Figure 1.12 shows the BASIC Stamp 1 Carrier Board with the BS1-IC properly inserted into the socket. This board features a 3-pin programming header and 9-volt battery clips to connect a power source. A male, 14-pin 0.1” header (to the left of the through-hole array) allows access to all the BS1’s pins. The first two columns of solder pads (closest to the header) are connected to the respective header pin. All other solder pads are isolated from each other. The entire through-hole array is provided for permanent or semi-permanent circuit design.

Figure 1.12: BASIC Stamp 1 Carrier Board (Rev. E) (shown with BS1-IC properly inserted) (27110)
BASIC Stamp 2 Carrier Board (Rev. B)
The BASIC Stamp 2 Carrier Board (also called the BS2 Carrier Board) is designed to accommodate the BS2-IC, BS2e-IC and BS2sx-IC modules. The BASIC Stamp 2 Carrier Board provides ample prototyping space for simple or moderate circuits. Figure 1.13 shows the BASIC Stamp 2 Carrier Board with the BS2-IC properly inserted into the socket. This board features a DB9 programming connector, reset button, and 9-volt battery clips. Two male, 12-pin 0.1" headers (to the left and right of the chip socket) allows access to all the module’s pins. The first two columns of solder pads (closest to the headers) are connected to the respective header pin. All other solder pads are isolated from each other. The entire through-hole array is provided for permanent or semi-permanent circuit design.

Figure 1.13: BASIC Stamp 2 Carrier Board (Rev. B) (shown with BS2-IC properly inserted) (27120)
BASIC Stamp Super Carrier (Rev. A)
The BASIC Stamp Super Carrier board is designed to accommodate the BS1-IC, BS2-IC, BS2e-IC and BS2sx-IC modules. This board provides ample prototyping space for simple or moderate circuits. Figures 1.14 and 1.15 show the board with the BS1-IC or BS2-IC properly inserted into the sockets. **NOTE: Do not power-up the board with a BS1-IC and a BS2-IC, BS2e-IC or BS2sx-IC inserted at the same time.** This board features a 3-pin programming connector (Stamp 1), DB9 programming connector (Stamp 2, 2e, 2sx), reset button, 9-volt battery clips, barrel connector, separate 5-volt regulator, and power LED. A female, 20-pin 0.1" socket allows access to all the module’s pins. Many of the solder pads (see Figure 1.16) are connected to each other in a fashion that allows breadboard-like assembly of circuits (examine the through-hole array carefully before soldering). Note: the barrel jack is designed for a center positive, 2.1 mm (pin) x 5.5 mm (barrel) plug.

![Figure 1.14: BASIC Stamp Super Carrier Board (Rev. A) (shown with BS1-IC properly inserted) (27130)](image)
In the prototype area, upper and lower rows as well as two inner columns of solder pads are connected to Vdd and Vss to provide easy access to power. IC’s measuring from 0.3” to 0.7” in width can straddle the center power rails similar to a breadboard. The right-most column of solder pads is offset to accommodate components like RJ-11 and DB9 connectors.
Board of Education (Rev. B)
The Board of Education is designed to accommodate the BS2-IC, BS2e-IC and BS2sx-IC modules. This board provides a small breadboard for quickly prototyping simple or moderate circuits. Figure 1.17 shows the board with the BS2-IC properly inserted into the socket. This board features a, DB9 programming connector, reset button, 9-volt battery clips, barrel connector, separate 5-volt regulator, power LED, 4 servo connectors and a breadboard. Three female 0.1" sockets allow for access to all the module’s pins plus Vdd, Vin and Vss. Vdd is +5 volts and Vin is 6 – 9 volts (depending on your power supply). **NOTE:** the Vdd pin on the 20-pin socket comes from the Vdd of the Stamp module (pin 21) while the 5 Vdd sockets above the breadboard come from the Board of Education’s 5-volt regulator. Use the 5 Vdd sockets for anything requiring more current than what the Stamp can provide. Also, the pins in the “red” row of the servo connectors are connected to Vin. Also note: the barrel jack is designed for a center positive, 2.1 mm (pin) x 5.5 mm (barrel) plug.
BASIC Stamp Activity Board (Rev. C)
The BASIC Stamp Activity Board (sometimes called BSAC) is designed to accommodate the BS1-IC, BS2-IC, BS2e-IC, BS2sx-IC and BS2p24-IC modules. This board provides a number of prewired components for quick prototyping of common, simple circuits. Figure 1.18 shows the board with the BS1-IC properly inserted into the socket (note that the X8 jumper must be in the "1" position). Figure 1.19 show the board with the BS2-IC properly inserted into the socket (note that the X8 jumper must be in the "2" position). This board features a DB9 programming connector, reset button, barrel connector for power, power LED, 4 push-buttons, 4 LEDs, a piezo speaker a 10K potentiometer, an RJ-11 jack (for interfacing to an X10 powerline interface), an analog output pin and two 8-pin sockets for EEPROM and ADC chips. One female 0.1" socket allows for access to all the module’s pins plus Vdd, Vin and Vss. Vdd is +5 volts and Vin is 6 – 9 volts (depending on your power supply). Also note: the barrel jack is designed for a center positive, 2.1 mm (pin) x 5.5 mm (barrel) plug.

Figure 1.18: BASIC Stamp Activity Board (shown with BS1-IC properly inserted). Note, the X8 jumper should be in the "1" position. (27905 or 27906)
find additional information on the board and source code for the BS1 and BS2 on the Parallax CD.

Figure 1.19: BASIC Stamp Activity Board (shown with BS2-IC properly inserted). Note, the X8 jumper should be in the "2" position. (27905 or 27906)

Other Boards
Other development boards for the BASIC Stamps may now be available at this time. Please refer to any documentation available for those products for specific information.
Guidelines and Precautions

When using the BASIC Stamp, or any IC chip, please follow the guidelines below.

1. **Be alert to static sensitive devices and static-prone situations.**
   a. The BASIC Stamp, like other IC’s, can be damaged by static discharge that commonly occurs touching grounded surfaces or other conductors. Environmental conditions (humidity changes, wind, static prone surfaces, etc) play a major role in the presence of random static charges. It is always recommended to use grounding straps and anti-static or static dissipative mats when handling devices like the BASIC Stamp. If the items above are not available, be sure to touch a grounded surface after you have approached the work area and before you handle static sensitive devices.

2. **Verify that all power is off before connecting/disconnecting.**
   a. If power is connected to the BASIC Stamp or any device it is connected to while inserting or removing it from a circuit, damage to the BASIC Stamp or circuit could result.

3. **Verify BASIC Stamp orientation before connection to development boards and other circuits.**
   a. Like other IC’s, the BASIC Stamp should be inserted in a specific orientation in relation to the development board or circuit. Powering the circuit with an IC connected backwards will likely damage the IC and/or other components in the circuit. Most IC’s have some form of a “pin 1 indicator” as do most IC sockets. This indicator usually takes the form of a dot, a half-circle, or the number 1 placed at or near pin 1 of the device.

The BS1-IC has a “1” and a half-circle indicator on the backside of the module. Additionally, Figure 1.2 above indicates the pin numbering and labels.

The 24-pin modules (BS2, BS2e, etc) have a half-circle indicator on the topside of the module (see Figure 1.20). This indicates (when holding the module with the half-circle facing up, or north) that pin number one is the first
pin on the upper left of the device. The socket that accepts this 24-pin module also has a half-circle or notch on one end, indicating the correct orientation. See Figure 1.21 for other examples.

![Pin 1 Indicators](BS2-IC shown in the correct orientation in relation to a 24-pin socket.)

![Additional Examples of Pin 1 Indicators](chip and socket shown in the correct orientation in relation to each other)

**BASIC Stamp Programming Connections:**
Parallax, Inc. suggests using the cables provided in the BASIC Stamp Starter Kit for programming the BASIC Stamps. When those cables are not available, you may create your own by duplicating the following diagrams in your cables and circuits.

Be very careful to follow these diagrams closely; it is quite common for programming problems with the BASIC Stamps to be a result of a poorly made custom cable or programming connections on your applications board. With the BS2, BS2e, BS2sx and BS2p programming connections, it is possible to reverse a couple of wires and still get positive results using some of the "connection" tests our Tech. Support team tries and yet you
still will not be able to communicate with the BASIC Stamp. It is vital that you check your connections with a meter and verify the pin numbering to avoid problems like this.

**Figure 1.22: BS1 Programming Connections.** Note: Though it is not shown, power must be connected to the BS1 to program it.

**Figure 1.23: BS2, BS2e, BS2sx and BS2p Programming Connections.** Note: Though it is not shown, power must be connected to the BASIC Stamp to program it. Also, the programming connections are the same for the BS2p40.
Introduction to the BASIC Stamps
Quick Start Introduction

This chapter is a quick start guide to connecting the BASIC Stamp to the PC and programming it. Without even knowing how the BASIC Stamp functions, you should be able to complete the exercise below. This exercise assumes you have a BASIC Stamp and one of the development boards shown in Chapter 1.

Connecting and Downloading

1) If the BASIC Stamp isn't already plugged into your development board, insert it into the appropriate socket as indicated in the "Development Boards" section of Chapter 1. Be careful to insert it in the correct orientation. NOTE: The BASIC Stamp 1 Rev. D is built into its own development board.

2) If using a BASIC Stamp 1, connect the 25-pin side of your programming cable to an available parallel port on your computer. Then connect the 3-pin side to the 3-pin programming header on the development board. See Figure 2.1 for an example. The 3-pin connector must be connected so that the arrows on one side of the plug line up with the arrows "<<" printed on the board.

Figure 2.1: BS1-IC and BASIC Stamp 1 Carrier Board being properly connected for programming. The BS1-IC must be powered and the 3-pin cable must be connected in the correct orientation, as shown.
3) If using a BASIC Stamp 2, 2e, 2sx or 2p, connect the 9-pin female side of a serial cable to an available serial port on your computer. Note: the serial cable should be a "straight-through" cable, not a null-modem cable. Connect the 9-pin male side of the cable to the DB9 connector on the development board. See Figure 2.2 for an example.

![Figure 2.2: BS2-IC and Board of Education being properly connected for programming. The BS2-IC must be powered and the "straight-through" serial cable must be connected, as shown.]

4) Run the BASIC Stamp editor software. Refer Table 2.1 for software versions and names. If using the DOS version of the software, try running it though DOS mode only; running it though Windows may cause it to malfunction when communicating with the BASIC Stamp.

<table>
<thead>
<tr>
<th></th>
<th>DOS Software</th>
<th>Windows Software</th>
</tr>
</thead>
<tbody>
<tr>
<td>BS1</td>
<td>Stamp.exe</td>
<td>N/A</td>
</tr>
<tr>
<td>BS2</td>
<td>Stamp2.exe</td>
<td>Stampw.exe</td>
</tr>
<tr>
<td>BS2e</td>
<td>Stamp2e.exe</td>
<td>Stampw.exe (v1.096+)</td>
</tr>
<tr>
<td>BS2sx</td>
<td>Stamp2sx.exe</td>
<td>Stampw.exe (v1.091+)</td>
</tr>
<tr>
<td>BS2p</td>
<td>Stamp2p.exe</td>
<td>Stampw.exe (v1.1+)</td>
</tr>
</tbody>
</table>

a) If using the Parallax CD, go to the Software -> BASIC Stamp -> Windows section (or the DOS section) to locate and run the software).

b) If using the Windows software, it may prompt you with a list of serial ports. Follow the prompt to configure the serial port list (if needed) for proper operation of the editor.
5) Enter the following two lines of PBASIC code in the editor window (change the "BS2" to the proper name of your module, as indicated below):

```pbasic
' {$STAMP BS2 }
DEBUG "Hello World!"
```

a) Note: The above code is written for a BASIC Stamp 2. Change the "BS2" in the first line to BS1, BS2e, BS2sx or BS2p depending on the model of the BASIC Stamp you are using. Failure to do this may cause the editor to fail to recognize your BASIC Stamp during the next step.

6) Download the program you just typed in to the BASIC Stamp. If using the DOS software, press ALT-R to download. If using the Windows software, press CTRL-R to download.

a) If the program is typed in correctly (and the BASIC Stamp is connected properly) a progress bar window should appear (perhaps very briefly) showing the download progress. Afterwards a debug window should appear and display "Hello World!"

b) If there is a syntax error in the program, the editor will highlight the text in question and display an error message. Review the error, fix the code and then try downloading again.

c) If the error reported a connection problem with the BASIC Stamp, make sure the first line of code indicates the proper module name and verify the programming cable connections, module orientation (in the socket) and that it is properly powered, then try downloading again.

7) Congratulations! You've just written and downloaded your first BASIC Stamp program! The "Hello World!" text that appeared on the screen was sent from the BASIC Stamp, back up the programming cable, to the PC.
The BASIC Stamp Editor software is available for Windows and DOS operating systems. The following system requirements are a minimum for using the BASIC Stamp Editor:

- 80486 (80286 for DOS) (or higher) IBM or compatible PC;
- Windows 95/98/NT4/2000 operating system (DOS 5.0 or higher for DOS versions);
- 16 Mb of RAM (1 Mb for DOS);
- 1 Mb of available hard drive space;
- CD-ROM drive;
- 1 available serial port (1 available parallel port for BS1).

(Note: though it is suggested that the BASIC Stamp Editor be installed on your hard drive, it is not required. The software may be run right off the Parallax CD).

To install the BASIC Stamp Editor:

1. Insert the Parallax CD into the CD-ROM drive. The CD should auto-start (unless that feature has been disabled on your computer). If using DOS, explore it with the CD (change directory) and DIR (directory list) commands.
2. Select the Software -> BASIC Stamp section.
3. Select the DOS or Windows version you wish to use and click the Install button. If exploring the CD through DOS, use the COPY command to copy it to a desired directory on your hard drive.
4. Close the CD and run the BASIC Stamp Editor program from the directory it was copied to. You may also create a shortcut to it (if using Windows).

Table 3.1 lists the available BASIC Stamp editors, their names, versions, operating system and BASIC Stamp model they support.

<table>
<thead>
<tr>
<th></th>
<th>DOS Software</th>
<th>Windows Software</th>
</tr>
</thead>
<tbody>
<tr>
<td>BS1</td>
<td>Stamp.exe</td>
<td>N/A</td>
</tr>
<tr>
<td>BS2</td>
<td>Stamp2.exe</td>
<td>Stampw.exe</td>
</tr>
<tr>
<td>BS2e</td>
<td>Stamp2e.exe</td>
<td>Stampw.exe (v1.096+)</td>
</tr>
<tr>
<td>BS2sx</td>
<td>Stamp2sx.exe</td>
<td>Stampw.exe (v1.091+)</td>
</tr>
<tr>
<td>BS2p</td>
<td>Stamp2p.exe</td>
<td>Stampw.exe (v1.1+)</td>
</tr>
</tbody>
</table>

Table 3.1: BASIC Stamp Editors for DOS and Windows.
Software Interface (Windows)

This section describes the Windows version of the BASIC Stamp Editor. See the "Software Interface (DOS)" section for information on using the DOS version. The Windows version supports multiple BASIC Stamp modules and is recommended for most tasks.

The BASIC Stamp Windows Editor, shown in Figure 3.1 was designed to be easy to use and mostly intuitive. Those that are familiar with standard Windows software should feel comfortable using the BASIC Stamp Windows Editor.

The editor consists of one main editor window that can be used to view and modify up to 16 different source code files at once. Each source code file that is loaded into the editor will have its own tab at the top of the page labeled with the name of the file (see Figure 3.2). Source code that
has never been saved to disk will default to “Untitled#”; where # is an automatically generated number. A user can switch between source code files by simply pointing and clicking on a file’s tab.

The status of the active source code page is indicated in a status bar below it and the full path to the source code (if it has been loaded from or saved to disk) will appear in the title bar of the BASIC Stamp Editor. The status bar (see Figure 3.3) contains information such as cursor position, file save status, download status and syntax error/download messages.

After entering the desired source code in the editor window, selecting Run -> Run (or pressing Ctrl-R) will tokenize and download the code to the BASIC Stamp (assuming the code is correct and the BASIC Stamp is properly connected).

Because the Windows editor supports more than one model of the BASIC Stamp, it is necessary to tell the editor which model you are trying to program.

There are three methods the editor uses to determine the model of the BASIC Stamp you are programming for. They are: 1) the STAMP directive, 2) the extension on the file name of the source code and 3) the Default Stamp Mode (as set by preferences). Whenever a file is loaded, tokenized, downloaded or viewed in the Memory Map, the BASIC Stamp looks for the STAMP directive first. If it cannot find the STAMP directive in the source code, it looks at the extension on the file name (for a .bs2, .bse, .bsx or .bsp). If it doesn’t understand the extension, then it uses the Default Stamp Mode, as defined by preferences.

The best way to force the editor to recognize the intended model of the BASIC Stamp is to use the STAMP directive, since the STAMP directive will override all other settings. If you forget to enter the STAMP directive
in your code, the editor may try to program another model of the BASIC Stamp, which may lead to some confusing error messages.

The STAMP directive is a special command that should be included (usually near the top) in a program to indicate the model of BASIC Stamp targeted. The line below is an example of the STAMP directive (in this case, it indicates that the program is intended for a BASIC Stamp 2):

'{ $STAMP BS2 }

This line should be entered into your code, usually near the top, on a line by itself. Note that the directive appears on a comment line (the apostrophe ('') indicates this) for compatibility with the DOS versions of the editor.

The 'BS2' in the example above should be changed to indicate the appropriate model of the BASIC Stamp you are using. For example, to use the BS2e, BS2sx or BS2p, enter one of the following lines into your code, respectively.

'{ $STAMP BS2e }   'This indicates to use the BASIC Stamp 2e
'{ $STAMP BS2sx }  'This indicates to use the BASIC Stamp 2sx
'{ $STAMP BS2p }   'This indicates to use the BASIC Stamp 2p

The directive itself must be enclosed in brackets, {…}. There should not be any spaces between the dollar sign, $, and the word STAMP, however, the directive may contain additional spaces in certain other areas. For example:
-- or --

'${STAMP  BS2}

-- and --

'${STAMP BS2 }

are all acceptable variations, however:

'${$ STAMP BS2)

-- and --

'${STAMPBS2}

are not acceptable and will be ignored. If one of the above two lines were entered into the source code, the editor would ignore it and, instead, rely on the extension of the filename or the Default Stamp Mode to determine the appropriate model.

The STAMP directive is read and acted upon by the BASIC Stamp Windows Editor any time a source code file is loaded, tokenized, downloaded (run) or viewed in the Memory Map.

For BS2e, BS2sx and BS2p programs, each editor page can be a separate project, or part of a single project. A project is a set of up to eight files that should all be downloaded to the BASIC Stamp for a single application. Each of the files within the project is downloaded into a separate "program slot". Only the BASIC Stamp 2e, 2sx and 2p modules support projects (multiple program slots).

For BASIC Stamp projects (consisting of multiple programs), the STAMP directive has an option to specify additional filenames. The syntax below demonstrates this form of the STAMP directive:
Use this form of the STAMP directive if a project, consisting of multiple files, is desired. This directive must be entered into the first program (to be downloaded into program slot 0) and not in any of the other files in the project. The file2, file3, etc. items should be the actual name (and optionally the path) of the other files in the project. File2 refers to the program that should be downloaded into program slot 1, file3 is the program that should be downloaded into program slot 2, etc. If no path is given, the path of program 0 (the program in which the STAMP directive is entered) is used.

Up to seven filenames can be included, bringing the total to eight files in the project all together. Upon tokenizing, running or viewing program 0 in the Memory Map, the editor will read the STAMP directive, determine if the indicated files exist, will load them if necessary and change their captions to indicate the project they belong to and their associated program number. After the directive is tokenized properly, and all associated files are labeled properly, tokenizing, running or viewing any program in the Memory Map will result in that program’s entire project being tokenized, downloaded or viewed.

When a file that is part of a BS2SX project is closed, the entire project (all the associated files) will be closed as well. When program #0 of a project is opened from diskette, the entire project will be loaded as well.

To create a project consisting of multiple files, follow these steps:

1. Create the first file in the editor and save it (we’ll call it Sample.bsx). This will be the program that is downloaded into program slot 0.
2. Create at least one other file in the editor and save it also (we’ll call it NextProgram.bsx).

Note: At this point the editor tabs will be:

0:Sample.bsx and 0:NextProgram.bsx.
indicating that there are two unrelated files open "Sample.bsx" and "NextProgram.bsx" and each will be downloaded into program slot 0.

3. Go back to the first program and enter the STAMP directive using the project format. Use "NextProgram" as the File2 argument. For example:

   ' { $STAMP BS2sx, NextProgram.bsx }

4. Then tokenize the code by pressing F7 or selecting Check Syntax from the RUN menu.

Note: At this point, the BASIC Stamp Editor will see the STAMP directive and realize that this file (Sample.bsx) is the first file in a project and that the second file should be NextProgram.bsx. It will then search for the file on the hard drive (to verify it's path is correct), will see that it is already loaded, and then will change the editor tabs to indicate the project relationship. At this point the editor tabs will be:

0:Sample.bsx and [Sample] 1:NextProgram.bsx.

indicating that there are two related files open; "Sample.bsx" and "NextProgram.bsx". NextProgram.bsx belongs to the "Sample" project and it will be downloaded into program slot 1 and Sample.bsx will be downloaded into program slot 0.

**PROJECT DOWNLOAD MODES.**

The editor has the ability to treat projects as one logical unit and can download each of the associated source code files to the BS2e, BS2sx or BS2p at once. In order to minimize download time for large projects a Project Download Mode is available in the Preferences window. The available modes are: "Modified" (the default), "All" or "Current" and are explained below. This item only affects download operations for the BS2e, BS2sx and BS2p. See Table 3.2.
Using the BASIC Stamp Editor

<table>
<thead>
<tr>
<th>Download Mode</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>Modified (default)</td>
<td>This mode will cause only the source code files that were modified since the last download to be downloaded next time. If no files have been modified since the last download, or the entire project has just been loaded into the editor, all the files will be downloaded next time. This mode decreases the delay during downloading projects and should help speed development and testing.</td>
</tr>
<tr>
<td>All</td>
<td>This mode will cause all the source code files to be downloaded each time. This will be noticeably slow with large projects.</td>
</tr>
<tr>
<td>Current</td>
<td>This mode will cause only the current source code file to be downloaded, ignoring all the others.</td>
</tr>
</tbody>
</table>

Regardless of the download mode selected, the programs will be downloaded into the program slot indicated in their tab.

The BASIC Stamp Windows Editor also features a Memory Map (not shown) that displays the layout of the current PBASIC program, DATA usage and RAM register usage. Type CTRL+M, or press F7, to activate this window.

When you activate the Memory Map, the editor will check your program for syntax errors and, if the program’s syntax is OK, will present you with a color-coded map of the RAM and EEPROM. You’ll be able to tell at a glance how much memory you have used and how much remains. Two important points to remember about this map are: 1) it only indicates how your program will be downloaded to the BASIC Stamp; it does not "read" the BASIC Stamp’s memory, and 2) fixed variables like B3 and W1 and any aliases do not show up on the memory map as memory used. The editor ignores fixed variables when it arranges automatically allocated variables in memory. Remember, fixed and allocated variables can overlap.

Another useful feature is the Identify function, CTRL+I. This will cause the editor to try to connect to the BASIC Stamp to determine its firmware version number. Use the Identify function to quickly determine if the BASIC Stamp is correctly connected to the PC for programming.

Table 3.2: Project Download Modes.
The following tables list the available keyboard shortcuts within the BASIC Stamp Windows Editor.

### Table 3.3: Shortcut Keys for File Functions (Windows editor).

<table>
<thead>
<tr>
<th>Shortcut Key</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ctrl+O</td>
<td>Open a source code file into the Editor window.</td>
</tr>
<tr>
<td>Ctrl+S</td>
<td>Save current source code file to disk.</td>
</tr>
<tr>
<td>Ctrl+P</td>
<td>Print current source code.</td>
</tr>
</tbody>
</table>

### Table 3.4: Shortcut Keys for Editing Functions (Windows editor).

<table>
<thead>
<tr>
<th>Shortcut Key</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ctrl+Z</td>
<td>Undo last action.</td>
</tr>
<tr>
<td>Ctrl+X</td>
<td>Cut selected text to the clipboard.</td>
</tr>
<tr>
<td>Ctrl+C</td>
<td>Copy selected text to the clipboard.</td>
</tr>
<tr>
<td>Ctrl+V</td>
<td>Paste text from clipboard to selected area.</td>
</tr>
<tr>
<td>Ctrl+A</td>
<td>Select all text in current source code.</td>
</tr>
<tr>
<td>Ctrl+F</td>
<td>Find or Replace text.</td>
</tr>
<tr>
<td>F3</td>
<td>Find text again.</td>
</tr>
<tr>
<td>F5</td>
<td>Open Preferences window.</td>
</tr>
</tbody>
</table>

### Table 3.5: Shortcut Keys for Coding Functions (Windows editor).

<table>
<thead>
<tr>
<th>Shortcut Key(s)</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>F6 or Ctrl+I</td>
<td>Identify BASIC Stamp firmware.</td>
</tr>
<tr>
<td>F7 or Ctrl+T</td>
<td>Perform a syntax check on the code and display any error messages.</td>
</tr>
<tr>
<td>F8 or Ctrl+M</td>
<td>Open Memory Map window.</td>
</tr>
<tr>
<td>F9 or Ctrl+R</td>
<td>Tokenize code, download to the BASIC Stamp and open Debug window if necessary.</td>
</tr>
<tr>
<td>F11 or Ctrl+D</td>
<td>Open a new Debug window.</td>
</tr>
<tr>
<td>F12</td>
<td>Switch to next window (Editor, Debug #1, Debug #2, Debug #3 or Debug #4)</td>
</tr>
<tr>
<td>Ctrl+1, Ctrl+2, Ctrl+3, Ctrl+4</td>
<td>Switch to Debug Terminal #1, Debug Terminal #2, etc. if that Terminal window is open.</td>
</tr>
<tr>
<td>Ctrl+`</td>
<td>Switch to Editor window.</td>
</tr>
<tr>
<td>ESC</td>
<td>Close current window.</td>
</tr>
</tbody>
</table>

### Software Interface (DOS)

This section describes the DOS versions of the BASIC Stamp Editor. See the "Software Interface (Windows)" section for information on using the Windows version. The DOS versions support only one BASIC Stamp module; a separate DOS editor is available for each model of the BASIC Stamp.
The BASIC Stamp DOS Editor, shown in Figure 3.4 was designed to be very simple and to provide only the necessary functionality needed for developing with a BASIC Stamp. Those that are familiar with standard DOS software should feel comfortable using the BASIC Stamp DOS Editor.

You must run the version of the DOS editor that is intended for the model of the BASIC Stamp you are using. There is a different version for each model. Refer to Table 3.1 for a list of the editors, versions and the BASIC Stamp models they support.

The BASIC Stamp DOS Editor can only load and edit one source code file at a time. Source code can be loaded into the editor by pressing ALT-L and selecting a file from the menu. NOTE: That the browse menu only shows files in the current directory; the directory that the BASIC Stamp DOS Editor is run from.

BS2e, BS2sx and BS2p models support up to eight programs to be downloaded into separate program slots. From here on, any application for these models of the BASIC Stamp will be called a project. A project is a set of up to eight files that should all be downloaded to the BASIC Stamp for a single application. Each of the files within the project must be downloaded into a separate "program slot". Only the BASIC Stamp 2e, 2sx and 2p modules support projects (multiple program slots).
For BASIC Stamp projects (consisting of multiple programs), the BASIC Stamp DOS Editor must be used to individually load and download each of the files into the appropriate slot. Keep in mind that the DOS editor can only load up one source code file at a time. NOTE: The Windows version does not have this limitation.

Pressing ALT+# (where # is a number from 0 to 7) will change the ID (shown on the title bar; see Figure 3.5) of the currently visible source code in the editor. This ID is not saved with the program and must be set and verified manually each time it is loaded from disk and before each download.

The sequence of keystrokes to load and download two programs into two separate program slots would consist of the following:

1. ALT+L loads a program into the editor.
2. ALT+0 sets the editor to program ID 0.
3. ALT+R downloads this program into program slot 0 of the BASIC Stamp's EEPROM.
4. ALT+L loads another program into the editor.
5. ALT+1 sets the editor to program ID 1.
6. ALT+R downloads this program into program slot 1 of the BASIC Stamp's EEPROM.

The shortcut key ALT+R downloads only one program at a time. Note that you must load each program separately.

The BASIC Stamp DOS Editors for the BS2, BS2e, BS2sx and BS2p, also feature a Memory Map (not shown) that displays the layout of the current PBASIC program, DATA usage and RAM register usage. Type ALT+M to activate this window.

When you activate the Memory Map, the editor will check your program for syntax errors and, if the program’s syntax is OK, will present you with a color-coded map of the RAM. You’ll be able to tell at a glance how much
memory you have used and how much remains. (You may also press the space bar to cycle through similar maps of EEPROM program memory.)

Two important points to remember about this map are, 1) it only indicates how your program will be downloaded to the BASIC Stamp; it does not "read" the BASIC Stamp's memory, and 2) fixed variables like B3 and W1 and any aliases do not show up on the memory map as memory used. The editor ignores fixed variables when it arranges automatically allocated variables in memory. Remember, fixed and allocated variables can overlap.

The following tables list the available keyboard shortcuts within the BASIC Stamp Windows Editor.

### File Functions

<table>
<thead>
<tr>
<th>Shortcut Key</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>Alt+L</td>
<td>Open a source code file into the Editor window.</td>
</tr>
<tr>
<td>Alt+S</td>
<td>Save current source code file to disk.</td>
</tr>
<tr>
<td>Alt+Q</td>
<td>Close the editor.</td>
</tr>
</tbody>
</table>

### Editing Functions

<table>
<thead>
<tr>
<th>Shortcut Key</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>Alt+X</td>
<td>Cut selected text to the clipboard.</td>
</tr>
<tr>
<td>Alt+C</td>
<td>Copy selected text to the clipboard.</td>
</tr>
<tr>
<td>Alt+V</td>
<td>Paste text from clipboard to selected area.</td>
</tr>
<tr>
<td>Alt+F</td>
<td>Find or Replace text.</td>
</tr>
<tr>
<td>Alt+N</td>
<td>Find text again.</td>
</tr>
</tbody>
</table>

### Coding Functions

<table>
<thead>
<tr>
<th>Shortcut Key(s)</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>Alt+0..7</td>
<td>Set Program Slot # to download to. (not supported on the BS1 or BS 2)</td>
</tr>
<tr>
<td>Alt+I</td>
<td>Identify BASIC Stamp firmware. (not supported on the BS1)</td>
</tr>
<tr>
<td>Alt+M</td>
<td>Open Memory Map window. (not supported on the BS1)</td>
</tr>
<tr>
<td>Alt+R</td>
<td>Tokenize code, download to the BASIC Stamp and open Debug window if necessary.</td>
</tr>
<tr>
<td>Alt+P</td>
<td>Open the potentiometer calibration window. (only supported on the BS1)</td>
</tr>
</tbody>
</table>

**Table 3.6:** Shortcut Keys for File Functions (DOS editor).

**Table 3.7:** Shortcut Keys for Editing Functions (DOS editor).

**Table 3.8:** Shortcut Keys for Coding Functions (DOS editor).
This chapter provides detail on the architecture (RAM usage) and math functions of the BS1, BS2, BS2e, BS2sx and BS2p.

The following icons will appear to indicate where there are differences between versions of the BASIC Stamp:

One or more of these icons indicates the item applies only to the BS1, BS2, BS2e, BS2sx or BS2p, respectively.

The BASIC Stamp has two kinds of memory; RAM (for variables used by your program) and EEPROM (for storing the program itself). EEPROM may also be used to store long-term data in much the same way that desktop computers use a hard drive to hold both programs and files.

An important distinction between RAM and EEPROM is this:

- RAM loses its contents when the BASIC Stamp loses power; when power returns, all RAM locations are cleared to 0s.
- EEPROM retains the contents of memory, with or without power, until it is overwritten (such as during the program-downloading process or with a WRITE instruction.)

The BS1 has 16 bytes (8 words) of RAM space arranged as shown in Table 4.1. The first word, called PORT, is used for I/O pin control. It consists of two bytes, PINS and DIRS. The bits within PINS correspond to each of the eight I/O pins on the BS1. Reading PINS effectively reads the I/O pins directly, returning an 8-bit set of 1's and 0's corresponding to the high and low state of the respective I/O pin at that moment. Writing to PINS will store a high or low value on the respective I/O pins (though only on pins that are set to outputs).

The second byte of PORT, DIRS, controls the direction of the I/O pins. Each bit within DIRS corresponds to an I/O pin's direction. A high bit (1) sets the corresponding I/O pin to an output direction and a low bit (0) sets the corresponding I/O pin to an input direction.

The remaining words (W0 – W6) are available for general-purpose use. Each word consists of separately addressable bytes and the first two bytes (B0 and B1) are bit addressable as well.
You may assign other names (symbols) to these RAM registers as shown in section "Defining and Using Variables", below.

When the BS1 is powered up, or reset, all memory locations are cleared to 0, so all pins are inputs (DIRS = %00000000). Also, if the PBASIC program sets all the I/O pins to outputs (DIRS = %11111111), then they will initially output low, since the output latch (PINS) is cleared to all zeros upon power-up or reset, as well.

<table>
<thead>
<tr>
<th>Word Name</th>
<th>Byte Names</th>
<th>Bit Names</th>
<th>Special Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>PORT</td>
<td>PINS</td>
<td>PIN0 – PIN7</td>
<td>I/O pins; bit addressable.</td>
</tr>
<tr>
<td></td>
<td>DIRS</td>
<td>DIR0 – DIR7</td>
<td>I/O pins directions; bit addressable.</td>
</tr>
<tr>
<td>W0</td>
<td>B0</td>
<td>BIT0 – BIT7</td>
<td>Bit addressable.</td>
</tr>
<tr>
<td></td>
<td>B1</td>
<td>BIT8 – BIT15</td>
<td>Bit addressable.</td>
</tr>
<tr>
<td>W1</td>
<td>B2</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>B3</td>
<td></td>
<td></td>
</tr>
<tr>
<td>W2</td>
<td>B4</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>B5</td>
<td></td>
<td></td>
</tr>
<tr>
<td>W3</td>
<td>B6</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>B7</td>
<td></td>
<td></td>
</tr>
<tr>
<td>W4</td>
<td>B8</td>
<td></td>
<td>Used by GOSUB instruction.</td>
</tr>
<tr>
<td></td>
<td>B9</td>
<td></td>
<td>Used by GOSUB instruction.</td>
</tr>
<tr>
<td>W5</td>
<td>B10</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>B11</td>
<td></td>
<td></td>
</tr>
<tr>
<td>W6</td>
<td>B12</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>B13</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

The BS2, BS2e, BS2sx and BS2p have 32 bytes of Variable RAM space arranged as shown in Table 4.2. Of these, the first six bytes are reserved for input, output, and direction control of the I/O pins. The remaining 26 bytes are available for general-purpose use as variables.

The word variable INS is unique in that it is read-only. The 16 bits of INS reflect the state of I/O pins P0 through P15. It may only be read, not written. OUTS contains the states of the 16 output latches. DIRS controls the direction (input or output) of each of the 16 I/O pins.

A 0 in a particular DIRS bit makes the corresponding pin an input and a 1 makes the corresponding pin an output. So if bit 5 of DIRS is 0 and bit 6 of DIRS is 1, then I/O pin 5 (P5) is an input and I/O pin 6 (P6) is an output. A pin that is an input is at the mercy of circuitry outside the BASIC Stamp;
the BASIC Stamp cannot change its state. A pin that is an output is set to the state indicated by the corresponding bit of the OUTS register.

When the BASIC Stamp is powered up, or reset, all memory locations are cleared to 0, so all pins are inputs (DIRS = %0000000000000000). Also, if the PBASIC program sets all the I/O pins to outputs (DIRS = %1111111111111111), then they will initially output low, since the output latch (OUTS) is cleared to all zeros upon power-up or reset, as well.

**Table 4.2:** BS2, BS2e, BS2sx and BS2p RAM Organization. Note: There are 16 words, consisting of two bytes each for a total of 32 bytes. All bits are individually addressable through modifiers and the bits within the upper three words are also individually addressable though the pre-defined names shown.

<table>
<thead>
<tr>
<th>Word Name</th>
<th>Byte Names</th>
<th>Nibble Names</th>
<th>Bit Names</th>
<th>Special Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>INS</td>
<td>INL, INH</td>
<td>INA, INB, INC, IND</td>
<td>IN0 – IN7, IN8 – IN15</td>
<td>Input pins</td>
</tr>
<tr>
<td>OUTS</td>
<td>OUTL,OUTH</td>
<td>OUTA, OUTB, OUTC, OUTD</td>
<td>OUT0 – OUT7, OUT8 – OUT15</td>
<td>Output pins</td>
</tr>
<tr>
<td>DIRS</td>
<td>DIRL,DIRH</td>
<td>DIRA,DIRB,DIRC,DIRD</td>
<td>DIR0 – DIR7, DIR8 – DIR15</td>
<td>I/O pin direction control</td>
</tr>
<tr>
<td>W0</td>
<td>B0, B1</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>W1</td>
<td>B2, B3</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>W2</td>
<td>B4, B5</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>W3</td>
<td>B6, B7</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>W4</td>
<td>B8, B9</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>W5</td>
<td>B10, B11</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>W6</td>
<td>B12, B13</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>W7</td>
<td>B14, B15</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>W8</td>
<td>B16, B17</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>W9</td>
<td>B18, B19</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>W10</td>
<td>B20, B21</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>W11</td>
<td>B22, B23</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>W12</td>
<td>B24, B25</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Note: All registers are word, byte, nibble and bit addressable.

The INS variable always shows the state of the I/O pins themselves, regardless of the direction of each I/O pin. We call this, "reading the pins". If a pin was set to an input mode (within DIRS) and an external
circuit connected the I/O pin to ground, the corresponding bit of INS would be low. If a pin was set to an output mode and the pin's state was set to a high level (within OUTS), the corresponding bit of INS would be high. If, however, that same pin was externally connected directly to ground, the corresponding bit of INS would be low; since we're reading the state of the pin itself and the BASIC Stamp cannot override a pin that is driven to ground or 5 volts externally. Note: The last example is an error, is a direct short and can cause damage to the BASIC Stamp! Do not intentionally connect output pins directly to an external power source or you risk destroying your BASIC Stamp.

To summarize: DIRS determines whether a pin’s state is set by external circuitry (input, 0) or by the state of OUTS (output, 1). INS always matches the actual states of the I/O pins, whether they are inputs or outputs. OUTS holds bits that will only appear on pins whose DIRS bits are set to output.

In programming the BASIC Stamp, it’s often more convenient to deal with individual bytes, nibbles or bits of INS, OUTS and DIRS rather than the entire 16-bit words. PBASIC has built-in names for these elements, shown in Table 4.2.

Here’s an example of what is described in Table 4.2. The INS register is 16-bits (corresponding to I/O pins 0 through 15). The INS register consists of two bytes, called INL (the Low byte) and INH (the High byte). INL corresponds to I/O pins 0 through 7 and INH corresponds to I/O pins 8 through 15. INS can also be though of as containing four nibbles, INA, INB, INC and IND. INA is I/O pins 0 through 3, INB is I/O pins 4 through 7, etc. In addition, each of the bits of INS can be accessed directly using the names IN0, IN1, IN2... IN5.

The same naming scheme holds true for the OUTS and DIRS variables as well.

As Table 4.2 shows, the BASIC Stamp’s memory is organized into 16 words of 16 bits each. The first three words are used for I/O. The remaining 13 words are available for use as general-purpose variables.

Just like the I/O variables, the general-purpose variables have predefined names: W0 through W12 and B0 through B25. B0 is the low byte of W0; B1 is the high byte of W0; and so on through W12 (B24=low byte, B25=high
byte). Unlike I/O variables, there’s no reason that your program variables have to be stuck in a specific position in the BASIC Stamp’s physical memory. A byte is a byte regardless of its location. And if a program uses a mixture of variables of different sizes, it can be a pain in the neck to logically dole them out or allocate storage.

More importantly, mixing fixed variables with automatically allocated variables (discussed in the next section) is an invitation to bugs. A fixed variable can overlap an allocated variable, causing data meant for one variable to show up in another! The fixed variable names (of the general-purpose variables) are only provided for power users who require absolute access to a specific location in RAM.

We recommend that you avoid using the fixed variables in most situations. Instead, let PBASIC allocate variables as described in the next section. The editor software will organize your storage requirements to make optimal use of the available memory.

**Defining and Using Variables.**

Before you can use a variable in a PBASIC program you must declare it. “Declare” means letting the BASIC Stamp know that you plan to use a variable, what you want to call it, and how big it is. Although PBASIC does have predefined variables that you can use without declaring them first (see previous sections), the preferred way to set up variables is to use the directive SYMBOL (for the BS1) or VAR (for all other BASIC Stamps). Here is the syntax for a variable declaration:

```
1 SYMBOL Name = RegisterName
```

-- OR --

```
2 Name VAR Size
```

where `Name` is the name by which you will refer to the variable, `RegisterName` is the "fixed" name for the register and `Size` indicates the number of bits of storage for the variable. NOTE: The top example is for the BS1 and the bottom example is for all other BASIC Stamps.

**The Rules of Symbol Names.**

There are certain rules regarding symbol names. Symbols must start with a letter, can contain a mixture of letters, numbers, and underscore (_) characters, and must not be the same as PBASIC keywords or labels used in your program. Additionally, symbols can be up to 32 characters long.
See Appendix B for a list of PBASIC keywords. PBASIC does not distinguish between upper and lower case, so the names MYVARIABLE, myVariable, and MyVaRiAbLe are all equivalent.

For the BS1, the RegisterName is one of the predefined "fixed" variable names, such as W0, W1, B0, B1, etc. Here are a few examples of variable declarations on the BS1:

```
SYMBOL Temporary = W0  ' value can be 0 to 65535
SYMBOL Counter   = B1  ' value can be 0 to 255
SYMBOL Result    = B2  ' value can be 0 to 255
```

The above example will create a variable called *Temporary* whose contents will be stored in the RAM location called W0. Also, the variable *Counter* will be located at RAM location B1 and *Result* at location B2. *Temporary* is a word-sized variable (because that's what size W0 is) while the other two are both byte-sized variables. Throughout the rest of the program, we can use the names *Temporary*, *Counter*, and *Result* instead of W0, B1 and B2, respectively. This makes the code much more readable; it's easier to determine what *Counter* is used for than it would be to figure out what the name B1 means. Please note, that *Counter* resides at location B1, and B1 happens to be the high byte of W0. This means than changing *Counter* will also change *Temporary* since they overlap. A situation like this usually is a mistake and results in strange behavior, but is also a powerful feature if used carefully.

For the BS2, BS2e, BS2sx and BS2p, the *Size* argument has four choices: 1) BIT (1 bit), 2) NIB (nibble; 4 bits), 3) BYTE (8 bits), and 4) WORD (16 bits). Here are some examples of variable declarations on the BS2, BS2e, BS2sx or BS2p:

```
Mouse   VAR BIT   ' Value can be 0 or 1.
Cat     VAR NIB   ' Value can be 0 to 15.
Dog     VAR BYTE  ' Value can be 0 to 255.
Rhino   VAR WORD  ' Value can be 0 to 65535.
```
The above example will create a bit-sized variable called *Mouse*, and nibble-sized variable called *Cat*, a byte-size variable called *Dog* and a word-sized variable called *Rhino*. Unlike in the BS1, these variable declarations don’t point to a specific location in RAM. Instead, we only specified the desired size for each variable; the BASIC Stamp will arrange them in RAM as it sees fit. Throughout the rest of the program, we can use the names *Mouse*, *Cat*, *Dog* and *Rhino* to set or retrieve the contents of these variables.

A variable should be given the smallest size that will hold the largest value that will ever be stored in it. If you need a variable to hold the on/off status (1 or 0) of switch, use a bit. If you need a counter for a FOR...NEXT loop that will count from 1 to 100, use a byte. And so on.

If you assign a value to a variable that exceeds its size, the excess bits will be lost. For example, suppose you use the nibble variable *Dog*, from the example above, and write *Dog* = 260 (%100000100 binary). What will *Dog* contain? It will hold only the lowest 8 bits of 260: %00000100 (4 decimal).

On the BS2, BS2e, BS2sx and BS2p, you can also define multipart variables called arrays. An array is a group of variables of the same size, and sharing a single name, but broken up into numbered cells, called elements. You can define an array using the following syntax:

```
Name VAR Size(n)
```

where *Name* and *Size* are the same as described earlier. The new argument, (n), tells PBASIC how many elements you want the array to have. For example:

```
MyList VAR BYTE(10)  ' Create a 10-byte array.
```

Once an array is defined, you can access its elements by number. Numbering starts at 0 and ends at n–1. For example:

```
MyList(3) = 57
DEBUG ? MyList(3)
```

This code will display "MyList(3) = 57" on the PC screen. The real power of arrays is that the index value can be a variable itself. For example:
MyBytes VAR BYTE(10)  ' Define 10-byte array.
Index VAR NIB     ' Define normal nibble variable.

FOR Index = 0 TO 9
    MyBytes(Index) = Index * 13  ' Write index*13 to each cell of array.
NEXT

FOR Index = 0 TO 9
    DEBUG ? MyBytes(Index)  ' Show contents of each cell.
NEXT
STOP

If you run this program, DEBUG will display each of the 10 values stored in the elements of the array: MyBytes(0) = 0*13 = 0, MyBytes(0) = 1*13 = 13, MyBytes(2) = 2*13 = 26 ... MyBytes(9) = 9*13 = 117.

A word of caution about arrays: If you’re familiar with other BASICS and have used their arrays, you have probably run into the “subscript out of range” error. Subscript is another term for the index value. It is out-of-range when it exceeds the maximum value for the size of the array. For instance, in the example above, MyBytes is a 10-cell array. Allowable index numbers are 0 through 9. If your program exceeds this range, PBASIC will not respond with an error message. Instead, it will access the next RAM location past the end of the array. If you are not careful about this, it can cause all sorts of bugs.

If accessing an out-of-range location is bad, why does PBASIC allow it? Unlike a desktop computer, the BASIC Stamp doesn’t always have a display device connected to it for displaying error messages. So it just continues the best way it knows how. It’s up to the programmer (you!) to prevent bugs.

Another unique property of PBASIC arrays is this: You can refer to the 0th cell of the array by using just the array’s name without an index value. For example:

MyBytes VAR BYTE(10)  ' Define 10-byte array.
MyBytes(0) = 17  ' Store 17 to 0th cell.

DEBUG ? MyBytes(0)  ' Display contents of 0th cell.
DEBUG ? MyBytes  ' Also displays contents of 0th cell.
This feature is how the "string" capabilities of the DEBUG and SEROUT command expect to work. A string is simply a byte array used to store text. See the "Displaying Strings (Byte Arrays)" section in the DEBUG command description for more information.

An alias is an alternative name for an existing variable. For example:

```
SYMBOL Cat  = B0  ' Create a byte-sized variable.
SYMBOL Tabby = Cat  ' Create another name for the same variable.
```

-- OR --

```
Cat  VAR BYTE  ' Create a byte-sized variable
Tabby VAR Cat   ' Create another name for the same variable.
```

In this example, Tabby is an alias to the variable Cat. Anything stored in Cat shows up in Tabby and vice versa. Both names refer to the same physical piece of RAM. This kind of alias can be useful when you want to reuse a temporary variable in different places in your program, but also want the variable’s name to reflect its function in each place. Use caution, because it is easy to forget about the aliases; during debugging, you might end up asking ‘how did that value get here?!’ The answer is that it was stored in the variable’s alias.

On the BS2, BS2e, BS2sx and BS2p, an alias can also serve as a window into a portion of another variable. This is done using "modifiers." Here the alias is assigned with a modifier that specifies what part:

```
Rhino VAR WORD  ' A 16-bit variable.
Head VAR Rhino.HIGHBYTE  ' Highest 8 bits of Rhino.
Tail VAR Rhino.LOWBYTE  ' Lowest 8 bits of Rhino.
```

Given that example, if you write the value %1011000011111101 to Rhino, then Head would contain %10110000 and Tail would contain %11111101.

Table 4.3 lists all the variable modifiers. PBASIC2 lets you apply these modifiers to any variable name and to combine them in any fashion that makes sense. For example, it will allow:

```
Rhino VAR WORD  ' A 16-bit variable.
Eye VAR Rhino.HIGHBYTE.LOWNIB.BIT1  ' A bit.
```
BASIC Stamp Architecture – Aliases and Modifiers

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>LOWBYTE</td>
<td>low byte of a word</td>
</tr>
<tr>
<td>HIGHBYTE</td>
<td>high byte of a word</td>
</tr>
<tr>
<td>BYTE0</td>
<td>byte 0 (low byte) of a word</td>
</tr>
<tr>
<td>BYTE1</td>
<td>byte 1 (high byte) of a word</td>
</tr>
<tr>
<td>LOWNIB</td>
<td>low nibble of a word or byte</td>
</tr>
<tr>
<td>HIGHNIB</td>
<td>high nibble of a word or byte</td>
</tr>
<tr>
<td>NIB0</td>
<td>nib 0 of a word or byte</td>
</tr>
<tr>
<td>NIB1</td>
<td>nib 1 of a word or byte</td>
</tr>
<tr>
<td>NIB2</td>
<td>nib 2 of a word</td>
</tr>
<tr>
<td>NIB3</td>
<td>nib 3 of a word</td>
</tr>
<tr>
<td>LOWBIT</td>
<td>low bit of a word, byte, or nibble</td>
</tr>
<tr>
<td>HIGHBIT</td>
<td>high bit of a word, byte, or nibble</td>
</tr>
<tr>
<td>BIT0</td>
<td>bit 0 of a word, byte, or nibble</td>
</tr>
<tr>
<td>BIT1</td>
<td>bit 1 of a word, byte, or nibble</td>
</tr>
<tr>
<td>BIT2</td>
<td>bit 2 of a word, byte, or nibble</td>
</tr>
<tr>
<td>BIT3</td>
<td>bit 3 of a word, byte, or nibble</td>
</tr>
<tr>
<td>BIT4 … BIT7</td>
<td>bits 4 through 7 of a word or byte</td>
</tr>
<tr>
<td>BIT8 … Bit15</td>
<td>bits 8 through 15 of a word</td>
</tr>
</tbody>
</table>

The commonsense rule for combining modifiers is that they must get progressively smaller from left to right. It would make no sense to specify, for instance, the low byte of a nibble, because a nibble is smaller than a byte! And just because you can stack up modifiers doesn’t mean that you should unless it is the clearest way to express the location of the part you want get at. The example above might be improved:

Rhino VAR WORD ' A 16-bit variable.
Eye VAR Rhino.BIT9 ' A bit.

Although we’ve only discussed variable modifiers in terms of creating alias variables, you can also use them within program instructions:

Rhino VAR WORD ' A 16-bit variable.
Head VAR Rhino.HIGHBYTE ' Highest 8 bits of rhino.

Rhino = 13567
DEBUG ? Head ' Show the value of alias variable Head.
DEBUG ? Rhino.HIGHBYTE ' Rhino.HIGHBYTE works too.
STOP

Modifiers also work with arrays. For example:

MyBytes VAR BYTE(10) ' Define 10-byte array.
MyBytes(0) = $AB ' Hex $AB into 0th byte
DEBUG HEX ? MyBytes.LOWNIB(0) ' Show low nib ($B)
DEBUG HEX ? MyBytes.LOWNIB(1) ' Show high nib ($A)
If you looked closely at that example, you probably thought it was a misprint. Shouldn’t MyBytes.LOWNIB(1) give you the low nibble of byte 1 of the array rather than the high nibble of byte 0? Well, it doesn’t. The modifier changes the meaning of the index value to match its own size. In the example above, when MyBytes() is addressed as a byte array, it has 10 byte-sized cells numbered 0 through 9. When it is addressed as a nibble array, using MyBytes.LOWNIB(), it has 20 nibble-sized cells numbered 0 through 19. You could also address it as individual bits using MyBytes.LOWBIT(), in which case it would have 80 bit-sized cells numbered 0 through 79.

What if you use something other than a “low” modifier, say MyBytes.HIGHNIB()? That will work, but its effect will be to start the nibble array with the high nibble of MyBytes(0). The nibbles you address with this nib array will all be contiguous, one right after the other, as in the previous example.

MyBytes VAR BYTE(10) ' Define 10-byte array.
MyBytes(0) = $AB ' Hex $AB into 0th byte
MyBytes(1) = $CD ' Hex $CD into next byte
DEBUG HEX ? MyBytes.highnib(0) ' Show high nib of cell 0 ($A)
DEBUG HEX ? MyBytes.highnib(1) ' Show next nib ($D)

This property of modified arrays makes the names a little confusing. If you prefer, you can use the less-descriptive versions of the modifier names; BIT0 instead of LOWBIT, NIB0 instead of LOWNIB, and BYTE0 instead of LOWBYTE. These have exactly the same effect, but may be less likely to be misconstrued.

You may also use modifiers with the 0th cell of an array by referring to just the array name without the index value in parentheses. It’s fair game for aliases and modifiers, both in VAR directives and in instructions.

On the BS2, BS2e, BS2sx and BS2p, if you’re working on a program and wondering how much variable space you have left, you can use the memory map feature of the editor (ALT-M in the DOS editor and CTRL-M in the Windows editor). See the "Memory Map" section of the "Using the BASIC Stamp Editor" chapter for more information.
The BS2e, BS2sx and BS2p have some additional RAM called Scratch Pad
RAM. The BS2e and BS2sx have are 64 bytes of Scratch Pad RAM (0 – 63)
and the BS2p has 128 bytes of Scratch Pad RAM (0 – 127). Scratch Pad
RAM can only be accessed with the GET and PUT commands (see the GET
and PUT command descriptions for more information) and cannot have
variable names assigned to it.

The highest location in Scratch Pad RAM (location 63 on the BS2e and
BS2sx, location 127 on the BS2p) is read-only, and always contains the
number of the currently running program slot. This can be handy for
programs that need to know which program slot they exist in.

Suppose you’re working on a program called “Three Cheers” that flashes
LEDs, makes hooting sounds, and activates a motor that crashes cymbals
together, all in sets of three. A portion of your PBASIC program might
contain something like:

```
FOR Counter = 1 TO 3
  GOSUB MakeCheers
NEXT
...
FOR Counter = 1 TO 3
  GOSUB BlinkLEDs
NEXT
...
FOR Counter = 1 TO 3
  GOSUB CrashCymbals
NEXT
```

The numbers 1 and 3 in the code above are called constants. They are
constants because, while the program is running, nothing can happen to
change those numbers. This distinguishes constants from variables, which
can change while the program is running.

PBASIC allows you to use several numbering systems. By default, it
assumes that numbers are in decimal (base 10), our everyday system of
numbers. But you can also use binary and hexadecimal (hex) numbers by
identifying them with prefixes. And PBASIC will automatically convert
quoted text into the corresponding ASCII code(s). For example:

99  decimal
%1010  binary
$FE  hex
“A”  ASCII code for A (65)
You can assign names to constants in a similar fashion to how variables are declared. On a BS1, it is identical to variable declarations and on the other BASIC Stamps you use the CON directive. Here is the syntax:

1. `SYMBOLES Name = ConstantValue`

   -- OR --

2. `Name CON ConstantValue`

Once created, named constants may be used in place of the numbers they represent. For example:

1. `SYMBOLES Cheers = 3 ' Number of cheers.`

   `FOR Counter = 1 TO Cheers
   GOSUB MakeCheers
   NEXT
   ...`

   -- or --

2. ` Cheers CON 3 ' Number of cheers.`

   `FOR Counter = 1 TO Cheers
   GOSUB MakeCheers
   NEXT
   ...`

That code would work exactly the same as the previous FOR...NEXT loops. The editor software would substitute the number 3 for the constant named `Cheers` throughout your program. Like variable names, labels and instructions, constant names are not case sensitive; `CHEERS`, and `ChEErs` would all be processed as identical to `Cheers`.

Using named constants does not increase the amount of code downloaded to the BASIC Stamp, and it often improves the clarity of the program. Weeks after a program is written, you may not remember what a particular number was supposed to represent—using a name may jog your memory (or simplify the detective work needed to figure it out).

Named constants also have another benefit. Suppose the “Three Cheers” program had to be upgraded to “Five Cheers.” In the original example you would have to change all of the 3s to 5s. Search and replace would
help, but you might accidentally change some 3s that weren’t numbers of cheers, too. However, if you made smart use of a named constant, all you would have to do is change 3 to 5 in one place, the constant’s declaration:

SYMBOL Cheers = 5 ‘ Number of cheers.

-- or --

Cheers CON 5 ‘ Number of cheers.

Now, assuming that you used the constant cheers wherever your program needed ‘the number of cheers,’ your upgrade would be done.

On the BS2, BS2e, BS2sx and BS2p, you can take this idea a step further by defining constants with expressions; groups of math and/or logic operations that the editor software solves (evaluates) at compile time (the time right after you start the download and before the BASIC Stamp starts running your program). For example, suppose the “Cheers” program also controls a pump to fill glasses with champagne. Perhaps the number of glasses to fill is always twice the number of cheers, minus 1 (another constant):

Cheers CON 5 ‘ # of cheers.

Glasses CON Cheers*2-1 ‘ # of glasses.

As you can see, one constant can be defined in terms of another. That is, the number glasses depends on the number cheers.

The expressions used to define constants must be kept fairly simple. The editor software solves them from left to right, and doesn’t allow you to use parentheses to change the order of evaluation. The operators that are allowed in constant expressions are shown in Table 4.4.

<table>
<thead>
<tr>
<th>Operator Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>+</code></td>
<td>Add</td>
</tr>
<tr>
<td><code>-</code></td>
<td>Subtract</td>
</tr>
<tr>
<td><code>*</code></td>
<td>Multiply</td>
</tr>
<tr>
<td><code>/</code></td>
<td>Divide</td>
</tr>
<tr>
<td><code>&lt;&lt;</code></td>
<td>Shift Left</td>
</tr>
<tr>
<td><code>&gt;&gt;</code></td>
<td>Shift Right</td>
</tr>
<tr>
<td><code>&amp;</code></td>
<td>Logical AND</td>
</tr>
<tr>
<td>`</td>
<td>`</td>
</tr>
<tr>
<td><code>^</code></td>
<td>Logical XOR</td>
</tr>
</tbody>
</table>

Table 4.4: BS2, BS2e, BS2sx and BS2p operators allowed in constant expressions.
The BASıC Stamp, like any computer, excels at math and logic. However, being designed for control applications, the BASıC Stamp does math a little differently than a calculator or spreadsheet program. This section will help you understand BASıC Stamp numbers, math, and logic.

In your programs, you may express a number in various ways, depending on how the number will be used and what makes sense to you. By default, the BASıC Stamp recognizes numbers like 0, 99 or 62145 as being in our everyday decimal (base-10) system. However, you may also use hexadecimal (base-16; also called hex) or binary (base-2).

Since the symbols used in decimal, hex and binary numbers overlap (e.g., 1 and 0 are used by all; 0 through 9 apply to both decimal and hex) the editor software needs prefixes to tell the numbering systems apart, as shown below:

- 99       Decimal (no prefix)
- $1A6      Hex
- %1101     Binary

The BASıC Stamp also automatically converts quoted text into ASCII codes, and allows you to apply names (symbols) to constants from any of the numbering systems. For example:

```basıc
SYMBOL LetterA  =  "A"  ' ASCII code for A (65).
SYMBOL Cheers   =  3
SYMBOL Hex128  =  $80
SYMBOL FewBits =  %1101
```

-- or --

```basıc
LetterA  CON  "A"  ' ASCII code for A (65).
Cheers   CON  3
Hex128   CON  $80
FewBits  CON  %1101
```

For more information on constants, see the section "Constants and Compile-Time Expressions", above.
On the BS2, BS2e, BS2sx and BS2p, not all of the math or logic operations in a program are solved by the BASIC Stamp. The editor software solves operations that define constants before the program is downloaded to the BASIC Stamp. The preprocessing that takes place before the program is downloaded is referred to as “compile time.”

After the download is complete, the BASIC Stamp starts executing your program; this is referred to as “runtime.” At runtime the BASIC Stamp processes math and logic operations involving variables, or any combination of variables and constants.

Because compile-time and runtime expressions appear similar, it can be hard to tell them apart. A few examples will help:

Result VAR BYTE  'Compile time assignment
Cheers CON 3   ' Compile time.
Glasses CON Cheers * 2 - 1  ' Compile time.
OneNinety CON 100 + 90  ' Compile time.
NoWorkee CON 3 * Result  ' ERROR: Variables not allowed here
Result = Glasses    ' Runtime.
Result = 99 + Glasses   ' Runtime.
Result = OneNinety + 1    ' "100 + 90" solved at compile-time,
                                      ' OneNinety + 1 solved at runtime.
Result = 100 + 90    ' 100 + 90 solved at runtime.

Notice that the last example is solved at runtime, even though the math performed could have been solved at compile time since it involves two constants. If you find something like this in your own programs, you can save some EEPROM space by converting the run-time expression 100+90 into a compile-time expression like OneNinety CON 100+90.

To sum up: compile-time expressions are those that involve only constants; once a variable is involved, the expression must be solved at runtime. That’s why the line “NoWorkee CON 3 * Result” would generate an error message. The CON directive works only at compile time, ORDER OF OPERATIONS.

Let’s talk about the basic four operations of arithmetic: addition (+), subtraction (-), multiplication (*), and division (/).
You may recall that the order in which you do a series of additions and subtractions doesn’t affect the result. The expression 12+7-3+22 works out the same as 22-3+12+7. However, when multiplication or division are involved, it’s a different story; 12+3*2/4 is not the same as 2*12/4+3. In fact, you may have the urge to put parentheses around portions of those equations to clear things up.

The BASIC Stamp solves math problems in the order they are written; from left to right. The result of each operation is fed into the next operation. So to compute 12+3*2/4, the BASIC Stamp goes through a sequence like this:

\[
\begin{align*}
12 + 3 & = 15 \\
15 * 2 & = 30 \\
30 / 4 & = 7 \\
\end{align*}
\]

Note that since the BASIC Stamp performs integer math (whole numbers only) 30 / 4 results in 7, not 7.5. We’ll talk more about integers in the next section.

Some other dialects of BASIC would compute that same expression based on their precedence of operators, which requires that multiplication and division be done before addition. So the result would be:

\[
\begin{align*}
3 * 2 & = 6 \\
6 / 4 & = 1 \\
12 + 1 & = 13 \\
\end{align*}
\]

Once again, because of integer math, the fractional portion of 6 / 4 is dropped, so we get 1 instead of 1.5.

The BS1 does not allow parenthesis in expressions. Unfortunately, all expressions have to be written so that they evaluate as intended strictly from left to right.

The BS2, BS2e, BS2sx and BS2p, however, allow parenthesis to be used to change the order of evaluation. Enclosing a math operation in parentheses gives it priority over other operations. To make the BASIC Stamp compute the previous expression in the conventional way, you would write it as 12 + (3*2/4). Within the parentheses, the BASIC Stamp works from left to right.
right. If you wanted to be even more specific, you could write 12 + ((3*2)/4). When there are parentheses within parentheses, the BASIC Stamp works from the innermost parentheses outward. Parentheses placed within parentheses are called nested parentheses.

The BASIC Stamp performs all math operations by the rules of positive integer math. That is, it handles only whole numbers, and drops any fractional portions from the results of computations. The BASIC Stamp handles negative numbers using two’s complement rules.

The BS2, BS2e, BS2sx and BS2p can interpret two’s complement negative numbers correctly in DEBUG and SEROUT instructions using modifiers like SDEC (for signed decimal). In calculations, however, it assumes that all values are positive. This yields correct results with two’s complement negative numbers for addition, subtraction, and multiplication, but not for division.

The standard operators we just discussed: +, - ,* and / all work on two values; as in 1 + 3 or 26 * 144. The values that operators process are referred to as arguments. So we say that the add, subtract, multiply and divide operators take two arguments.

Operators that take one argument are called unary operators and those that take two are called binary operators. Please note that the term “binary operator” has nothing to do with binary numbers; it’s just an inconvenient coincidence that the same word, meaning ‘involving two things’ is used in both cases.

The minus sign (-) is a bit of a hybrid, it can be used as a unary operator as well: as in -4.

In classifying the BASIC Stamp's math and logic operators, we divide them into two types: unary and binary. Unary operators take precedence over binary; the unary operation is always performed first. For example, on the BS2, BS2e, BS2sx and BS2p, SQR is the unary operator for square root. In the expression 10 - SQR 16, the BASIC Stamp first takes the square root of 16, then subtracts it from 10.

Most of the descriptions that follow say something like ‘computes (some function) of a 16-bit value.’ This does not mean that the operator does not
work on smaller byte or nibble values. It just means that the computation is done in a 16-bit workspace. If the value is smaller than 16 bits, the BASIC Stamp pads it with leading 0s to make a 16-bit value. If the 16-bit result of a calculation is to be packed into a smaller variable, the higher-order bits are discarded (truncated).

Keep this in mind, especially when you are working with two’s complement negative numbers, or moving values from a larger variable to a smaller one. For example, look at what happens when you move a two’s complement negative number into a byte (rather than a word):

```
Value VAR BYTE
Value = -99
DEBUG SDEC ? Value  ' Show signed decimal result (157).
```

How did -99 become 157? Let’s look at the bits: 99 is %01100011 binary. When the BASIC Stamp negates 99, it converts the number to 16 bits %0000000001100011, and then takes the two’s complement, %1111111110011101. Since we’ve asked for the result to be placed in an 8-bit (byte) variable, the upper eight bits are truncated and the lower eight bits stored in the byte: %10011101.

Now for the second half of the story. DEBUG’s SDEC modifier (on the BS2, BS2e, BS2sx and BS2p) expects a 16-bit, two’s complement value, but we’ve only given it a byte to work with. As usual, it creates a 16-bit value by padding the leading eight bits with 0s: %0000000010011101. And what’s that in signed decimal? 157.

Table 4.5 lists the available Unary Operators. Note: the BS1 only supports negative (-).

<table>
<thead>
<tr>
<th>Operator</th>
<th>Description</th>
<th>Supported By:</th>
</tr>
</thead>
<tbody>
<tr>
<td>ABS</td>
<td>Returns absolute value</td>
<td>All except BS1</td>
</tr>
<tr>
<td>COS</td>
<td>Returns cosine in two’s compliment binary radians</td>
<td>All except BS1</td>
</tr>
<tr>
<td>DCD</td>
<td>2^2-power decoder</td>
<td>All except BS1</td>
</tr>
<tr>
<td>~</td>
<td>Inverse</td>
<td>All except BS1</td>
</tr>
<tr>
<td>-</td>
<td>Negative</td>
<td>All</td>
</tr>
<tr>
<td>NCD</td>
<td>Priority encoder of a 16-bit value</td>
<td>All except BS1</td>
</tr>
<tr>
<td>SIN</td>
<td>Returns sine in two’s compliment binary radians</td>
<td>All except BS1</td>
</tr>
<tr>
<td>SQR</td>
<td>Returns square root of value</td>
<td>All except BS1</td>
</tr>
</tbody>
</table>

Table 4.5: Unary Operators. Note: the BS1 only supports the negative (-) unary operator.
The Absolute Value operator (ABS) converts a signed (two’s complement) 16-bit number to its absolute value. The absolute value of a number is a positive number representing the difference between that number and 0. For example, the absolute value of -99 is 99. The absolute value of 99 is also 99. ABS works on two’s complement negative numbers. Examples of ABS at work:

```
Result VAR WORD
Result = -99  ' Put -99 (2's complement format) into Result.
DEBUG SDEC ? Result  ' Display it on the screen as a signed #.
DEBUG SDEC ? ABS Result  ' Display it on the screen as a signed #.
```

The Cosine operator (COS) returns the two’s complement, 16-bit cosine of an angle specified as an 8-bit (0 to 255) angle. See the explanation of the SIN operator, below. COS is the same in all respects, except that the cosine function returns the x distance instead of the y distance. To demonstrate the COS operator, use the example program from SIN, below, but substitute COS for SIN.

The Decoder operator (DCD) is a 2ⁿ-power decoder of a four-bit value. DCD accepts a value from 0 to 15, and returns a 16-bit number with the bit, described by value, set to 1. For example:

```
Result VAR WORD
Result = DCD 12  ' Set bit 12.
DEBUG BIN ? Result  ' Display result (%0001000000000000)
```

The Inverse operator (~) complements (inverts) the bits of a number. Each bit that contains a 1 is changed to 0 and each bit containing 0 is changed to 1. This process is also known as a “bitwise NOT” and one’s compliment. For example:

```
Result VAR BYTE
Result = %11110001  ' Store bits in byte Result.
DEBUG BIN ? Result  ' Display in binary (%11110001).
Result = ~ Result  ' Complement Result.
DEBUG BIN ? Result  ' Display in binary (%00001110).
```

The Negative operator (-) negates a 16-bit number (converts to its two’s complement).

```
SYMBOL Result = W1
Result = -99  ' Put -99 (2’s complement format) into Result.
Result = Result + 100  ' Add 100 to it.
DEBUG Result  ' Display Result (1)
```
ENCODER: NCD

The Encoder operator (NCD) is a "priority" encoder of a 16-bit value. NCD takes a 16-bit value, finds the highest bit containing a 1 and returns the bit position plus one (1 through 16). If no bit is set (the input value is 0) NCD returns 0. NCD is a fast way to get an answer to the question “what is the largest power of two that this value is greater than or equal to?” The answer NCD returns will be that power, plus one. Example:

```
RESULT VAR WORD
RESULT = 99
DEBUG SDEC ? RESULT
RESULT = - RESULT
DEBUG SDEC ? RESULT
```

SINE: SIN

The Sine operator (SIN) returns the two’s complement, 16-bit sine of an angle specified as an 8-bit (0 to 255) angle. To understand the SIN operator more completely, let’s look at a typical sine function. By definition: given a circle with a radius of 1 unit (known as a unit circle), the sine is the y-coordinate distance from the center of the circle to its edge at a given angle. Angles are measured relative to the 3-o’clock position on the circle, increasing as you go around the circle counterclockwise.

At the origin point (0 degrees) the sine is 0, because that point has the same y (vertical) coordinate as the circle center. At 45 degrees the sine is 0.707. At 90 degrees, sine is 1. At 180 degrees, sine is 0 again. At 270 degrees, sine is -1.

The BASIC Stamp SIN operator breaks the circle into 0 to 255 units instead of 0 to 359 degrees. Some textbooks call this unit a binary radian or brad. Each brad is equivalent to 1.406 degrees. And instead of a unit circle, which results in fractional sine values between 0 and 1, BASIC Stamp SIN is based on a 127-unit circle. Results are given in two’s complement form in order to accommodate negative values. So, at the origin, SIN is 0. At 45 degrees (32 brads), sine is 90. At 90 degrees (64 brads), sine is 127. At 180 degrees (128 brads), sine is 0. At 270 degrees (192 brads), sine is -127.
To convert brads to degrees, multiply by 180 then divide by 128. To convert degrees to brads, multiply by 128, then divide by 180. Here’s a small program that demonstrates the SIN operator:

```
Degr  VAR WORD    ' Define variables.
Sine  VAR WORD
FOR  Degr = 0  TO  359  STEP  45   ' Use degrees.
    Sine = SIN (Degr * 128 / 180)   ' Convert to brads, do SIN.
NEXT
```

The Square Root operator (SQR) computes the integer square root of an unsigned 16-bit number. (The number must be unsigned since the square root of a negative number is an ‘imaginary’ number.) Remember that most square roots have a fractional part that the BASIC Stamp discards when doing its integer-only math. So it computes the square root of 100 as 10 (correct), but the square root of 99 as 9 (the actual is close to 9.95).

Example:

```
DEBUG SQR 100   ' Display square root of 100 (10).
DEBUG SQR 99   ' Display of square root of 99 (9 due to truncation)
```

Table 4.6 lists the available Binary (two-argument) Operators.

Table 4.6: Binary Operators. Note: some binary operators are not supported by all BASIC Stamps.
The Addition operator (+) adds variables and/or constants, returning a 16-bit result. Works exactly as you would expect with unsigned integers from 0 to 65535. If the result of addition is larger than 65535, the carry bit will be lost. If the values added are signed 16-bit numbers and the destination is a 16-bit variable, the result of the addition will be correct in both sign and value. For example:

```
SYMBOL Value1 = W0  
SYMBOL Value2 = W1  
Value1 = -99  
Value2 = 100  
Value1 = Value1 + Value2  ' Add the numbers.  
DEBUG Value1  ' Show the result (1).
```

-- OR --

```
Value1 VAR WORD  
Value2 VAR WORD  
Value1 = -1575  
Value2 = 976  
Value1 = Value1 + Value2  ' Add the numbers.  
DEBUG SDEC ? Value1  ' Show the result (-599).
```

The Subtraction operator (-) subtracts variables and/or constants, returning a 16-bit result. Works exactly as you would expect with unsigned integers from 0 to 65535. If the result is negative, it will be correctly expressed as a signed 16-bit number. For example:

```
SYMBOL Value1 = W0  
SYMBOL Value2 = W1  
Value1 = 199  
Value2 = 100  
Value1 = Value1 - Value2  ' Subtract the numbers.  
DEBUG Value1  ' Show the result (99).
```

-- OR --

```
Value1 VAR WORD  
Value2 VAR WORD  
Value1 = 1000  
Value2 = 1999  
Value1 = Value1 - Value2  ' Subtract the numbers.  
DEBUG SDEC ? Value1  ' Show the result (-999).
```

The Multiply operator (*) multiplies variables and/or constants, returning the low 16 bits of the result. Works exactly as you would expect with unsigned integers from 0 to 65535. If the result of multiplication is larger...
than 65535, the excess bits will be lost. Multiplication of signed variables will be correct in both number and sign, provided that the result is in the range -32767 to +32767.

```plaintext
SYMBOL Value1 = W0 
SYMBOL Value2 = W1 
Value1= 1000 
Value2= 19 
Value1= Value1 * Value2 ' Multiply Value1 by Value2. 
DEBUG Value1 ' Show the result (19000). 
-- or -- 
Value1 VAR WORD 
Value2 VAR WORD 
Value1= 1000 
Value2= - 19 
Value1= Value1 * Value2 ' Multiply Value1 by Value2. 
DEBUG SDEC ? Value1 ' Show the result (-19000). 
```

The Multiply High operator (**) multiplies variables and/or constants, returning the high 16 bits of the result. When you multiply two 16-bit values, the result can be as large as 32 bits. Since the largest variable supported by PBASIC is 16 bits, the highest 16 bits of a 32-bit multiplication result are normally lost. The ** (double-star) instruction gives you these upper 16 bits. For example, suppose you multiply 65000 ($FDE8) by itself. The result is 4,225,000,000 or $FBD46240. The * (star, or normal multiplication) instruction would return the lower 16 bits, $6240. The ** instruction returns $FBD4.

```plaintext
SYMBOL Value1 = W0 
SYMBOL Value2 = W1 
Value1= $FDE8 
Value2= Value1 ** Value1 ' Multiply $FDE8 by itself 
DEBUG $Value2 ' Return high 16 bits. 
-- or -- 
Value1 VAR WORD 
Value2 VAR WORD 
Value1= $FDE8 
Value2= Value1 ** Value1 ' Multiply $FDE8 by itself 
DEBUG HEX ? Value2 ' Return high 16 bits. 
```

The Multiply Middle operator (*/) multiplies variables and/or constants, returning the middle 16 bits of the 32-bit result. This has the effect of multiplying a value by a whole number and a fraction. The whole number

```plaintext
-- or -- 
Value1 VAR WORD 
Value2 VAR WORD 
Value1= $FDE8 
Value2= Value1 ** Value1 ' Multiply $FDE8 by itself 
DEBUG HEX ? Value2 ' Return high 16 bits. 
```
is the upper byte of the multiplier (0 to 255 whole units) and the fraction is the lower byte of the multiplier (0 to 255 units of 1/256 each). The */ (star-slash) instruction gives you an excellent workaround for the BASIC Stamp’s integer-only math. Suppose you want to multiply a value by 1.5. The whole number, and therefore the upper byte of the multiplier, would be 1, and the lower byte (fractional part) would be 128, since 128/256 = 0.5. It may be clearer to express the */ multiplier in hex—as $0180—since hex keeps the contents of the upper and lower bytes separate. Here’s an example:

```basic
Value1 VAR WORD
Value1= 100
Value1= Value1* $0180 ' Multiply by 1.5 [1 + (128/256)]
debag ? Value1 ' Show result (150).
```

To calculate constants for use with the */ instruction, put the whole number portion in the upper byte, then use the following formula for the value of the lower byte: Hint: INT( fraction * 256). For instance, take Pi (π, 3.14159). The upper byte would be $03 (the whole number), and the lower would be INT(0.14159 * 256) = 36 ($24). So the constant Pi for use with */ would be $0324. This isn’t a perfect match for Pi, but the error is only about 0.1%.

**DIVIDE: /**

The Divide operator (/) divides variables and/or constants, returning a 16-bit result. Works exactly as you would expect with unsigned integers from 0 to 65535. Use / only with positive values; signed values do not provide correct results. Here’s an example of unsigned division:

```basic
SYMBOL Value1 = W0
SYMBOL Value2 = W1
Value1= 1000
Value2= 5
Value1= Value1 / Value2 ' Divide the numbers.
DEBUG Value1 ' Show the result (200).

-- OR --

Value1 VAR WORD
Value2 VAR WORD
Value1= 1000
Value2= 5
Value1= Value1 / Value2 ' Divide the numbers.
DEBUG DEC ? Value1 ' Show the result (200).
```
A workaround to the inability to divide signed numbers is to have your program divide absolute values, then negate the result if one (and only one) of the operands was negative. All values must lie within the range of -32767 to +32767. Here is an example:

```basic
Sign VAR BIT ' Bit to hold the sign.
Value1 VAR WORD
Value2 VAR WORD
Value1 = 100
Value2 = -3200

Sign = Value1.BIT15 ^ Value2.BIT15 ' Sign = (Value1 sign) XOR (Value1 sign).
Value2 = ABS Value2 / ABS Value1 ' Divide absolute values.
IF Sign = 0 THEN Skip0 ' Negate result if one of the
    Value2 = - Value2 ' argument was negative.
Skip0:
DEBUG SDEC ? Value2 ' Show the result (-32)
```

The Modulus operator (\//) returns the remainder left after dividing one value by another. Some division problems don’t have a whole-number result; they return a whole number and a fraction. For example, 1000/6 = 166.667. Integer math doesn’t allow the fractional portion of the result, so 1000/6 = 166. However, 166 is an approximate answer, because 166*6 = 996. The division operation left a remainder of 4. The \// (double-slash) returns the remainder of a given division operation. Naturally, numbers that divide evenly, such as 1000/5, produce a remainder of 0. Example:

```basic
SYMBOL Value1 = W0
SYMBOL Value2 = W1
Value1= 1000
Value2= 6
Value1= Value1 // Value2 ' Get remainder of Value1 / Value2.
DEBUG Value1 ' Show the result (4).
```

-- or --

```basic
Value1 VAR WORD
Value2 VAR WORD
Value1= 1000
Value2= 6
Value1= Value1 // Value2 ' Get remainder of Value1 / Value2.
DEBUG DEC ? Value1 ' Show the result (4).
```

The Minimum operator (MIN) limits a value to a specified 16-bit positive minimum. The syntax of MIN is:
4: BASIC Stamp Architecture – MAX

Value MIN Limit

Where Value is a constant or variable value to perform the MIN function upon and Limit is the minimum value that Value is allowed to be. Its logic is, ‘if Value is less than Limit, then make result = Limit; if Value is greater than or equal to Limit, make result = Value.’ MIN works in positive math only; its comparisons are not valid when used on two’s complement negative numbers, since the positive-integer representation of a number like -1 ($FFFFFF or 65535 in unsigned decimal) is larger than that of a number like 10 ($000A or 10 decimal). Use MIN only with unsigned integers. Because of the way fixed-size integers work, you should be careful when using an expression involving MIN 0. For example, 0-1 MIN 0 will result in 65535 because of the way fixed-size integers wrap around.

SYMBOL Value1 = W0
SYMBOL Value2 = W1
FOR Value1 = 100 TO 0 STEP -10 ' Walk value of Value1 from 100 to 0.
  Value2 = Value1 MIN 50
  DEBUG Value2
NEXT

-- or --

Value1 VAR WORD
FOR Value1 = 100 TO 0 STEP 10 ' Walk value of Value1 from 100 to 0.
  DEBUG ? Value1 MIN 50
NEXT

MAXIMUM: MAX

The Maximum operator (MAX) limits a value to a specified 16-bit positive maximum. The syntax of MAX is:

Value MAX Limit

Where Value is a constant or variable value to perform the MAX function upon and Limit is the maximum value that Value is allowed to be. Its logic is, ‘if Value is greater than Limit, then make result = Limit; if Value is less than or equal to Limit, make result = Value.’ MAX works in positive math only; its comparisons are not valid when used on two’s complement negative numbers, since the positive-integer representation of a number like -1 ($FFFFFF or 65535 in unsigned decimal) is larger than that of a number like 10 ($000A or 10 decimal). Use MAX only with unsigned integers. Because of the way fixed-size integers work, you should be careful when using an expression involving MAX 65535. For example,
65535+1 MAX 65535 will result in 0 because of the way fixed-size integers wrap around.

```plaintext
SYMBOL Value1 = W0
SYMBOL Value2 = W1
FOR Value1= 0 TO 100 STEP 10
  Value2 = Value1 MAX 50
  DEBUG Value2
NEXT
```

-- or --

```plaintext
Value1 VAR WORD
FOR Value1= 0 TO 100 STEP 10
  DEBUG ? Value1 MAX 50
NEXT
```

The Digit operator (DIG) returns the specified decimal digit of a 16-bit positive value. Digits are numbered from 0 (the rightmost digit) to 4 (the leftmost digit of a 16-bit number; 0 to 65535). Example:

```plaintext
Value VAR WORD
Idx VAR BYTE
Value = 9742
DEBUG ? Value DIG 2
FOR Idx = 0 TO 4
  DEBUG ? Value DIG Idx
NEXT
```

The Shift Left operator (<<) shifts the bits of a value to the left a specified number of places. Bits shifted off the left end of a number are lost; bits shifted into the right end of the number are 0s. Shifting the bits of a value left \( n \) number of times has the same effect as multiplying that number by 2 to the \( n \)th power. For instance 100 << 3 (shift the bits of the decimal number 100 left three places) is equivalent to 100 \( \times 2^3 \). Here's an example:

```plaintext
Value VAR WORD
Idx VAR BYTE
Value = %1111111111111111
FOR Idx = 1 TO 16
  DEBUG BIN ? Value << Idx
NEXT
```

The Shift Right operator (>>) shifts the bits of a variable to the right a specified number of places. Bits shifted off the right end of a number are lost; bits shifted into the left end of the number are 0s. Shifting the bits of a
value right \( n \) number of times has the same effect as dividing that number by 2 to the \( n \) power. For instance \( 100 \gg 3 \) (shift the bits of the decimal number 100 right three places) is equivalent to \( 100 / 2^3 \). Here's an example:

```plaintext
Value     VAR      WORD
Idx       VAR      BYTE
Value = %1111111111111111
FOR Idx = 1 TO 16   ' Repeat with Idx = 1 to 16.
    DEBUG BIN ? Value >> Idx  ' Shift Value right Idx places.
NEXT
```

**Reverse: REV**

The Reverse operator (REV) returns a reversed (mirrored) copy of a specified number of bits of a value, starting with the rightmost bit (lsb).

For instance, \%10101101 REV 4 would return \%1011, a mirror image of the first four bits of the value. Example:

```plaintext
DEBUG BIN ? %11001011 REV 4   ' Mirror 1st 4 bits (%1101)
```

**And: &**

The And operator (&) returns the bitwise AND of two values. Each bit of the values is subject to the following logic:

- \( 0 \) AND \( 0 \) = \( 0 \)
- \( 0 \) AND \( 1 \) = \( 0 \)
- \( 1 \) AND \( 0 \) = \( 0 \)
- \( 1 \) AND \( 1 \) = \( 1 \)

The result returned by & will contain 1s in only those bit positions in which both input values contain 1s. Example:

```plaintext
SYMBOL     Value1 = B0
SYMBOL     Value2 = B1
SYMBOL     Result  = B2
Value1 = %00001111
Value2 = %10101101
Result = Value1 & Value2
DEBUG %Result   ' Show AND result (%00001101)
```

-- or --

```plaintext
DEBUG BIN ? %00001111 & %10101101   ' Show AND result (%00001101)
```

**Or: |**

The OR operator (|) returns the bitwise OR of two values. Each bit of the values is subject to the following logic:
0 OR 0 = 0
0 OR 1 = 1
1 OR 0 = 1
1 OR 1 = 1

The result returned by | will contain 1s in any bit positions in which one or the other (or both) input values contain 1s. Example:

```
SYMBOL Value1 = B0
SYMBOL Value2 = B1
SYMBOL Result = B2
Value1 = %00001111
Value2 = %10101001
Result = Value1 | Value2
DEBUG %Result  ' Show OR result (%10101111)
```

-- or --

```
DEBUG BIN ? %00001111 | %10101001  ' Show OR result (%10101111)
```

The Xor operator (^) returns the bitwise XOR of two values. Each bit of the values is subject to the following logic:

- 0 XOR 0 = 0
- 0 XOR 1 = 1
- 1 XOR 0 = 1
- 1 XOR 1 = 0

The result returned by ^ will contain 1s in any bit positions in which one or the other (but not both) input values contain 1s. Example:

```
SYMBOL Value1 = B0
SYMBOL Value2 = B1
SYMBOL Result = B2
Value1 = %00001111
Value2 = %10101001
Result = Value1 ^ Value2
DEBUG %Result  ' Show XOR result (%10100110)
```

-- or --

```
DEBUG BIN ? %00001111 ^ %10101001  ' Show XOR result (%10100110)
```
The And Not operator (&/) returns the bitwise AND NOT of two values. Each bit of the values is subject to the following logic:

- 0 AND NOT 0 = 0
- 0 AND NOT 1 = 0
- 1 AND NOT 0 = 1
- 1 AND NOT 1 = 0

The result returned by &/ will contain 1s in any bit positions in which the first value is 1 and the second value is 0. Example:

```plaintext
SYMBOL Value1 = B0
SYMBOL Value2 = B1
SYMBOL Result = B2
Value1 = %00001111
Value2 = %10101001
Result = Value1 &/ Value2
DEBUG %Result    ' Show AND NOT result (%00000110)
```

The Or Not operator (|/) returns the bitwise OR NOT of two values. Each bit of the values is subject to the following logic:

- 0 OR NOT 0 = 1
- 0 OR NOT 1 = 0
- 1 OR NOT 0 = 1
- 1 OR NOT 1 = 1

The result returned by |/ will contain 1s in any bit positions in which the first value is 1 or the second value is 0. Example:

```plaintext
SYMBOL Value1 = B0
SYMBOL Value2 = B1
SYMBOL Result = B2
Value1 = %00001111
Value2 = %10101001
Result = Value1 |/ Value2
DEBUG %Result    ' Show OR NOT result (%01011111)
```

The Xor Not operator (^/) returns the bitwise XOR NOT of two values. Each bit of the values is subject to the following logic:
0 XOR NOT 0 = 1
0 XOR NOT 1 = 0
1 XOR NOT 0 = 0
1 XOR NOT 1 = 1

The result returned by ^/ will contain 1s in any bit positions in which the first value and second values are equal. Example:

```
SYMBOL Value1 = B0
SYMBOL Value2 = B1
SYMBOL Result = B2
Value1 = %00001111
Value2 = %10101001
Result = Value1 ^/ Value2
DEBUG %Result          ' Show OR NOT result (%01011001)
```
This chapter provides detail on all the available PBASIC instructions for the BS1, BS2, BS2e, BS2sx and BS2p. The following icons will appear to indicate where there are differences between versions of the BASIC Stamp:

One or more of these icons indicates the item applies only to the BS1, BS2, BS2e, BS2sx or BS2p, respectively.

All instructions listed below exist on all versions of the BASIC Stamp, except where noted.

**BRANCHING**
- **IF...THEN** Compare and conditionally branch.
- **BRANCH** Branch to address specified by offset.
- **GOTO** Branch to address.
- **GOSUB** Branch to subroutine at address.
- **RETURN** Return from subroutine.
- **RUN** Switch execution to another program page.
- **POLLRUN** Switch execution to another program page upon the occurrence of a polled interrupt.

**LOOPING**
- **FOR...NEXT** Establish a FOR-NEXT loop.

**EEPROM ACCESS**
- **EEPROM** Store data in EEPROM before downloading PBASIC program.
- **DATA** Store data in EEPROM before downloading PBASIC program.
- **READ** Read EEPROM byte into variable.
- **WRITE** Write byte into EEPROM.
- **STORE** Switch READ/WRITE access to different program slot.
RAM ACCESS

GET
Read Scratch Pad RAM byte into variable.

PUT
Write byte into Scratch Pad RAM.

NUMERICS

LET
Optional instruction to perform variable manipulation, such as A=5, B=A+2, etc. This instruction is not required and only exists on the BASIC Stamp 1.

LOOKUP
Lookup data specified by offset and store in variable. This instruction provides a means to make a lookup table.

LOOKDOWN
Find target’s match number (0-N) and store in variable.

RANDOM
Generate a pseudo-random number.

DIGITAL I/O

INPUT
Make pin an input.

OUTPUT
Make pin an output.

REVERSE
Reverse direction of a pin. If pin is an output, make it an input. If pin is an input, make it an output.

LOW
Make pin output low.

HIGH
Make pin output high.

TOGGLE
Make pin an output and toggle state.

PULSIN
Measure an input pulse.

PULSOUT
Output a timed pulse by inverting a pin for some time.

BUTTON
Debounce button, perform auto-repeat, and branch to address if button is in target state.

COUNT
Count cycles on a pin for a given amount of time.

XOUT
Generate X-10 power line control codes. For use with TW523 or TW513 power line interface module.

AUXIO
Activates auxiliary I/O pins in place of main I/O.

MAINIO
Activates main I/O pins in place of auxiliary I/O.
### 5: BASIC Stamp Command Reference

<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>IOTERM</td>
<td>Activates specified I/O pin group.</td>
</tr>
<tr>
<td>POLLIN</td>
<td>Specify pin and state for a polled-interrupt.</td>
</tr>
<tr>
<td>POLLOUT</td>
<td>Specify pin and state for output upon a polled-interrupt.</td>
</tr>
<tr>
<td>POLLMODE</td>
<td>Specifies the polled-interrupt mode.</td>
</tr>
</tbody>
</table>

### ASYNCHRONOUS SERIAL I/O

<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SERIN</td>
<td>Input data in an asynchronous serial stream.</td>
</tr>
<tr>
<td>SEROUT</td>
<td>Output data in an asynchronous serial stream.</td>
</tr>
<tr>
<td>OWIN</td>
<td>Input data from a 1-wire device.</td>
</tr>
<tr>
<td>OWOUT</td>
<td>Output data to a 1-wire device.</td>
</tr>
</tbody>
</table>

### SYNCHRONOUS SERIAL I/O

<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SHIFTIN</td>
<td>Shift data in from synchronous serial device.</td>
</tr>
<tr>
<td>SHIFTOUT</td>
<td>Shift data out to synchronous serial device.</td>
</tr>
<tr>
<td>I2CIN</td>
<td>Input data in from I2C serial device.</td>
</tr>
<tr>
<td>I2COUT</td>
<td>Output data out to I2C serial device.</td>
</tr>
</tbody>
</table>

### PARALLEL I/O

<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>LCDCMD</td>
<td>Writes a command to an LCD.</td>
</tr>
<tr>
<td>LCDIN</td>
<td>Reads data from an LCD.</td>
</tr>
<tr>
<td>LCDOUT</td>
<td>Writes data to an LCD.</td>
</tr>
</tbody>
</table>

### ANALOG I/O

<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>PWM</td>
<td>Output PWM, then return pin to input. This can be used to output analog voltages (0-5V) using a capacitor and resistor.</td>
</tr>
<tr>
<td>POT</td>
<td>Read a 5K - 50K ohm potentiometer and scale result.</td>
</tr>
<tr>
<td>RCTIME</td>
<td>Measure an RC charge/discharge time. Can be used to measure potentiometers.</td>
</tr>
</tbody>
</table>

### TIME

<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>PAUSE</td>
<td>Pause execution for 0–65535 milliseconds.</td>
</tr>
<tr>
<td>POLLWAIT</td>
<td>Pause until a polled-interrupt occurs.</td>
</tr>
</tbody>
</table>
SOUND

1: SOUND Generate tones or white noise.

FREQOUT Generate one or two sine waves of specified frequencies.

DTMFOUT Generate DTMF telephone tones.

POWER CONTROL

NAP Nap for a short period. Power consumption is reduced.

SLEEP Sleep for 1-65535 seconds. Power consumption is reduced.

END Sleep until the power cycles or the PC connects. Power consumption is reduced.

PROGRAM DEBUGGING

DEBUG Send information to the PC for viewing.
AUXIO

Function
Switch from control of main I/O pins to auxiliary I/O pins (on the BS2p40 only).

Quick Facts

<table>
<thead>
<tr>
<th>I/O pin IDs</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 – 15 (just like main I/O, but after AUXIO command, all references affect physical pins 21 – 36).</td>
<td></td>
</tr>
</tbody>
</table>

| Special notes | Both the BS2p24 and the BS2p40 accept this command, however, only the BS2p40 gives access to the auxiliary I/O pins. |

Explanation
The BS2p is available in two module styles, 1) a 24-pin module (called the BS2p24) that is pin compatible with the BS2, BS2e and BS2sx and 2) a 40-pin module (called the BS2p40) that has an additional 16 I/O pins (for a total of 32). The BS2p40's extra, or auxiliary, I/O pins can be accessed in the same manner as the main I/O pins (by using the IDs 0 to 15) but only after issuing an AUXIO or IOTERM command. The AUXIO command causes the BASIC Stamp to affect the auxiliary I/O pins instead of the main I/O pins in all further code until the MAINIO command is reached, or the BASIC Stamp is reset or power-cycled.

A simple AUXIO example.

The following example illustrates this:

```
HIGH 0
AUXIO
LOW 0
```

The first line of the above example will set I/O pin 0 of the main I/O pins (physical pin 5) high. Afterward, the AUXIO command tells the BASIC Stamp that all commands following it should affect the auxiliary I/O pins. The following LOW command will set I/O pin 0 of the auxiliary I/O pins (physical pin 21) low.

Note that the main I/O and auxiliary I/O pins are independent of each other; the states of the main I/O pins remain unchanged while the program affects the auxiliary I/O pins, and vice versa.

Other commands that affect I/O group access are MAINIO and IOTERM.
Demo Program (AUX_MAIN_TERM.bsp)

' This program demonstrates the use of the AUXIO, MAINIO and IOTERM commands to
'affect I/O pins in the auxiliary and main I/O groups.

'${STAMP BS2p)                      'STAMP directive (specifies a BS2p)

Port VAR BIT

Loop:
  MAINIO    'Switch to main I/O pins
  TOGGLE 0  'Toggle state of I/O pin 0 (physical pin 5)
  PWM 1, 100, 40  'Generate PWM on I/O pin 1 (physical pin 6)

  AUXIO    'Switch to auxiliary I/O pins
  TOGGLE 0  'Toggle state of I/O pin 0 (physical pin 21)
  PULSOUT 1, 1000  'Generate a pulse on I/O pin 1 (physical pin 22)
  PWM 2, 100, 40  'Generate PWM on I/O pin 2 (physical pin 23)

  IOTERM Port   'Switch to main or aux I/Os (depending on Port)
  TOGGLE 3   'Toggle state of I/O pin 3 (on main and aux, alternately)
  Port = ~Port   'Invert port (switch between 0 and 1)
  PAUSE 1000
  GOTO Loop

NOTE: This is written for the BS2p but its effects can only be seen on
the 40-pin version: the BS2p40.
BRANCH

Function
Go to the address specified by offset (if in range).

- **Offset** is a variable/constant/expression (0 – 255) that specifies the index of the address, in the list, to branch to (0 – N).

- **Addresses** are labels that specify where to go. BRANCH will ignore any list entries beyond offset 255.

Quick Facts

<table>
<thead>
<tr>
<th>Limit of Address entries</th>
<th>BS1</th>
<th>BS2, BS2e, BS2sx and BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Limited only by memory</td>
<td></td>
<td>256</td>
</tr>
</tbody>
</table>

Explanation
The BRANCH instruction is useful when you want to write something like this:

```
IF value = 0 THEN case_0  ' value =0: go to label "case_0"
IF value = 1 THEN case_1  ' value =1: go to label "case_1"
IF value = 2 THEN case_2  ' value =2: go to label "case_2"
```

You can use BRANCH to organize this into a single statement:

```
BRANCH value, [case_0, case_1, case_2]
```

This works exactly the same as the previous IF...THEN example. If the value isn’t in range (in this case if value is greater than 2), BRANCH does nothing and the program continues with the next instruction after BRANCH.

BRANCH can be teamed with the LOOKDOWN instruction to create a simplified SELECT CASE statement. See LOOKDOWN for an example.
Demo Program (BRANCH.bas)
This program shows how the value of $Idx$ controls the destination of the BRANCH instruction.

```
'{$STAMP BS1}    'STAMP directive (specifies a BS1)
SYMBOL   $Idx   = B0

Start:
FOR $Idx = 0 to 3
  DEBUG "Idx: ", #$Idx
  BRANCH $Idx, (Case0, Case1, Case2) 'If $Idx = 0..2 branch to specified label
GOTO Start  'If $Idx>2 then Start.

Case0:
  DEBUG "Branched to Case0",cr
GOTO Start

Case1:
  DEBUG "Branched to Case1",cr
GOTO Start

Case2:
  DEBUG "Branched to Case2",cr
GOTO Start
```

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, BS2sx or BS2p.

Demo Program (BRANCH.bs2)
This program shows how the value of $Idx$ controls the destination of the BRANCH instruction.

```
'{$STAMP BS2}    'STAMP directive (specifies a BS2)
$Idx   VAR   BYTE

Start:
FOR $Idx = 0 to 3
  DEBUG "Idx: ", DEC $Idx
  BRANCH $Idx, [Case0, Case1, Case2] 'If $Idx = 0..2 branch to specified label
GOTO Start  'If $Idx>2 then Start.

Case0:
  DEBUG "Branched to Case0",cr
GOTO Start

Case1:
  DEBUG "Branched to Case1",cr
GOTO Start

Case2:
  DEBUG "Branched to Case2",cr
GOTO Start
```
BUTTON

Function
Debounce button input, perform auto-repeat, and branch to address if button is in target state. Button circuits may be active-low or active-high.

- **Pin** is a variable/constant/expression (0–15) that specifies the I/O pin to use. This pin will be set to input mode.
- **DownState** is a variable/constant/expression (0 or 1) that specifies which logical state occurs when the button is pressed.
- **Delay** is a variable/constant/expression (0 – 255) that specifies how long the button must be pressed before auto-repeat starts. The delay is measured in cycles of the Button routine. Delay has two special settings: 0 and 255. If Delay is 0, Button performs no debounce or auto-repeat. If Delay is 255, Button performs debounce, but no auto-repeat.
- **Rate** is a variable/constant/expression (0 – 255) that specifies the number of cycles between auto-repeats. The rate is expressed in cycles of the BUTTON routine.
- **Workspace** is a byte variable used by BUTTON for workspace. It must be cleared to 0 before being used by BUTTON for the first time and should not be adjusted outside of the BUTTON command.
- **TargetState** is a variable/constant/expression (0 or 1) that specifies which state the button should be in for a branch to occur. (0=not pressed, 1=pressed)
- **Address** is a label that specifies where to branch if the button is in the target state.

Explanation
When you press a button or flip a switch, the contacts make or break a connection. A brief (1 to 20-ms) burst of noise occurs as the contacts scrape and bounce against each other. BUTTON’s debounce feature prevents this noise from being interpreted as more than one switch action. (For a
demonstration of switch bounce, see the demo program for the Count instruction.)

BUTTON also lets PBASIC react to a button press the way your computer keyboard does to a key press. When you press a key, a character immediately appears on the screen. If you hold the key down, there's a delay, then a rapid-fire stream of characters appears on the screen. BUTTON’s auto-repeat function can be set up to work much the same way.

BUTTON is designed for use inside a program loop. Each time through the loop, BUTTON checks the state of the specified pin. When it first matches DownState, BUTTON debounces the switch. Then, in accordance with TargetState, it either branches to address (TargetState = 1) or doesn’t (TargetState = 0).

If the switch stays in DownState, BUTTON counts the number of program loops that execute. When this count equals Delay, BUTTON once again triggers the action specified by TargetState and address. Hereafter, if the switch remains in DownState, BUTTON waits Rate number of cycles between actions. The Workspace variable is used by BUTTON to keep track of how many cycles have occurred since the pin switched to TargetState or since the last auto-repeat.

BUTTON does not stop program execution. In order for its delay and auto repeat functions to work properly, BUTTON must be executed from within a program loop.

![Figure 5.1: Sample BUTTON circuits. Active-high (left) and active-low (right).](image-url)
Demo Program (BUTTON.bas)

Connect the active-low circuit shown in Figure 5.1 to pin P0 of the BS1. When you press the button, the Debug screen will display an asterisk (*). Feel free to modify the program to see the effects of your changes on the way BUTTON responds.

```
'{$STAMP BS1}    'STAMP directive (specifies a BS1)
SYMBOL BtnWrk = B0  ' Workspace for BUTTON instruction.

Loop:
  ' Try changing the Delay value (255) in BUTTON to see the effect of
  ' its modes: 0=no debounce; 1-254=varying delays before auto-repeat;
  ' 255=no auto-repeat (one action per button press).
  BUTTON 0,0,255,250,BtnWk,0,NoPress  ' Go to NoPress unless P0 = 0.
  DEBYG "* 
NoPress:
  GOTO Loop    ' Repeat endlessly.
```

Demo Program (BUTTON.bs2)

Connect the active-low circuit shown in Figure 5.1 to pin P0 of the BS2. When you press the button, the Debug screen will display an asterisk (*). Feel free to modify the program to see the effects of your changes on the way BUTTON responds.

```
'${STAMP BS2}    'STAMP directive (specifies a BS2)
BtnWrk VAR BYTE  ' Workspace for BUTTON instruction.

Loop:
  ' Try changing the Delay value (255) in BUTTON to see the effect of
  ' its modes: 0=no debounce; 1-254=varying delays before auto-repeat;
  ' 255=no auto-repeat (one action per button press).
  BUTTON 0,0,255,250,BtnWk,0,NoPress  ' Go to NoPress unless P0 = 0.
  DEBYG "* 
NoPress:
  GOTO Loop    ' Repeat endlessly.
```

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, BS2sx or BS2p.
5: BASIC Stamp Command Reference - COUNT

COUNT

Function

Count the number of cycles (0-1-0 or 1-0-1) on the specified pin during the Period time frame and store that number in Variable.

- **Pin** is a variable/constant/expression (0 – 15) that specifies the I/O pin to use. This pin will be set to input mode.

- **Period** is a variable/constant/expression (1 – 65535) specifying the time during which to count. The unit of time for **Period** is described in Table 5.3.

- **Variable** is a variable (usually a word) in which the count will be stored.

Quick Facts

<table>
<thead>
<tr>
<th></th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Units in Period</strong></td>
<td>1 ms</td>
<td>1 ms</td>
<td>400 µs</td>
<td>287 µs</td>
</tr>
<tr>
<td><strong>Period range</strong></td>
<td>1 ms to 65.535 s</td>
<td>1 ms to 65.535 s</td>
<td>400 µs to 26.214 s</td>
<td>287 µs to 18.809 s</td>
</tr>
<tr>
<td><strong>Minimum pulse width</strong></td>
<td>4.16 µs</td>
<td>4.16 µs</td>
<td>1.66 µs</td>
<td>1.20 µs</td>
</tr>
<tr>
<td><strong>Maximum frequency (square wave)</strong></td>
<td>120,000 Hz</td>
<td>120,000 Hz</td>
<td>300,000 Hz</td>
<td>416,700 Hz</td>
</tr>
</tbody>
</table>

Explanation

The COUNT instruction makes the Pin an input, then for the specified period of time, counts cycles on that pin and stores the total in a variable. A cycle is a change in state from 1 to 0 to 1, or from 0 to 1 to 0.

According to Table 5.3, COUNT on the BS2 can respond to transitions (pulse widths) as small as 4.16 microseconds (µs). A cycle consists of two transitions (e.g., 0 to 1, then 1 to 0), so COUNT (on the BS2) can respond to square waves with periods as short as 8.32 µs; up to 120 kilohertz (kHz) in frequency. For non-square waves (those whose high time and low time are unequal), the shorter of the high and low times must be at least 4.16 µs in width (on the BS2). Refer to Table 5.3 for data on other BASIC Stamps.
If you use COUNT on slowly changing analog waveforms like sine waves, you may find that the value returned is higher than expected. This is because the waveform may pass through the BASIC Stamp’s 1.4-volt logic threshold slowly enough that noise causes false counts. You can fix this by passing the signal through a Schmitt Trigger, like one of the inverters of a 74HCT14.

Demo Program (COUNT.bs2)

Connect the active-low circuit shown in Figure 5.1 (BUTTON instruction) to pin P0 of the BS2. The Debug screen will prompt you to press the button as quickly as possible for a 1-second count. When the count is done, the screen will display your “score,” the total number of cycles registered by COUNT. Note that this score will almost always be greater than the actual number of presses because of switch bounce.

```
'${STAMP  BS2}    'STAMP directive (specifies a BS2)
Cycles var word  ' Variable to store counted cycles.

Loop:
  DEBUG cls,"How many times can you press the button in 1 second?",cr
  PAUSE 1000
  DEBUG "Ready, set... ",cr
  PAUSE 500
  DEBUG "GO!",cr
  COUNT 0,1000,Cycles
  DEBUG cr,"Your score: ", DEC Cycles,cr
  PAUSE 3000
  DEBUG "Press button to go again."

Hold:
  IF IN0 = 1 THEN Hold
GOTO Loop
```
DATA

(Symbol) DATA DatItem {, DatItem...}

Function
Write data to the EEPROM during program download.
- Symbol is an optional, unique symbol name that will be automatically defined as a constant equal to the location number of the first data item.
- DatItem is a constant/expression (0 – 65535) indicating a value or how to store a value.

Explanation
When you download a program into the BASIC Stamp, it is stored in the EEPROM starting at the highest address (2047) and working towards the lowest address. Most programs don’t use the entire EEPROM, so the lower portion is available for other uses. The DATA directive allows you to define a set of data to store in the available EEPROM locations. It is called a “directive” rather than a “command” because it performs an activity at compile-time rather than at run-time (ie: the DATA directive is not downloaded to the BASIC Stamp, but the data it contains is downloaded).

The simplest form of the DATA directive is something like the following:

DATA 100, 200, 52, 45

This example, when downloaded, will cause the values 100, 200, 52 and 45 to be written to EEPROM locations 0, 1, 2 and 3, respectively. You can then use the READ and WRITE commands in your code to access these locations and the data you’ve stored there.

DATA uses a counter, called a pointer, to keep track of available EEPROM addresses. The value of the pointer is initially 0. When a program is downloaded, the DATA directive stores the first byte value at the current pointer address, then increments (adds 1 to) the pointer. If the program contains more than one DATA directive, subsequent DATAs start with the pointer value left by the previous DATA. For example, if the program contains:

DATA 100, 200, 52, 45
DATA 100, 200, 52, 45
DATA 72, 69, 76, 76, 79

The first DATA directive will start at location 0 and increment the pointer for each data value it stores (1, 2, 3, 4 and 5). The second DATA directive will start with the pointer value of 5 and work upward from there. As a result, the first 10 bytes of EEPROM will look like the following:

<table>
<thead>
<tr>
<th>Location (address)</th>
<th>Contents</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>72</td>
</tr>
<tr>
<td>1</td>
<td>69</td>
</tr>
<tr>
<td>2</td>
<td>76</td>
</tr>
<tr>
<td>3</td>
<td>76</td>
</tr>
<tr>
<td>4</td>
<td>79</td>
</tr>
<tr>
<td>5</td>
<td>104</td>
</tr>
<tr>
<td>6</td>
<td>101</td>
</tr>
<tr>
<td>7</td>
<td>108</td>
</tr>
<tr>
<td>8</td>
<td>108</td>
</tr>
<tr>
<td>9</td>
<td>111</td>
</tr>
</tbody>
</table>

What if you don’t want to store values starting at location 0? Fortunately, the DATA directive has an option to specify the next location to use. You can specify the next location number (to set the pointer to) by inserting a DataItem in the form @x ;where x is the location number. The following code writes the same data in Table 5.4 to locations 100 through 109:

DATA @100, 72, 69, 76, 76, 79, 104, 101, 108, 108, 111

In this example, the first DataItem is @100. This tells the DATA directive to store the following DataItem(s) starting at location 100. All the DataItems to the right of the @100 are stored in their respective locations (100, 101, 102...109).

In addition, the DATA directive allows you to specify new starting locations at any time within the DataItem list. If, for example, you wanted to store 56 at location 100 and 47 at location 150 (while leaving every other location intact), you could type the following:

DATA @100, 56, @150, 47

If you have multiple DATA directives in your program, it may be difficult to remember exactly what locations contain the desired data. For this reason, the DATA directive can optionally be prefixed with a unique symbol name. This symbol becomes a constant that is set equal to the location number of the first byte of data within the directive. For example,

MyNumbers DATA @100, 72, 73

This would store the values 72 and 73 starting with location 100 and will create a constant, called MyNumbers, which is set equal to 100.
program can then use the \textit{MyNumbers} constant as a reference to the start of the data within a \texttt{READ} or \texttt{WRITE} command. Each \texttt{DATA} directive can have a unique symbol preceding it, allowing you to reference the data defined at different locations.

There may be a time when you wish to reserve a section of EEPROM for use by your BASIC code, but not necessarily store data there to begin with. To do this, simply specify a \texttt{DataItem} within parentheses, as in:

\begin{verbatim}
DATA @100, (20)
\end{verbatim}

The above \texttt{DATA} directive will reserve 20 bytes of EEPROM, starting with location 100. It doesn’t store any values there, rather it simply leaves the data as it is and increments \texttt{DATA}’s location pointer by 20. A good reason to do this is when you have a program already downloaded into the BASIC Stamp that has created or manipulated some data in EEPROM. To protect that section of EEPROM from being overwritten by your next program (perhaps a new version of the same program) you can reserve the space as shown above. The EEPROM’s contents from locations 100 to 119 will remain intact. NOTE: This only "reserves" the space for the program you are currently downloading; the BASIC Stamp does not know to "reserve" the space for future programs. In other words, make sure use this feature of the \texttt{DATA} directive in every program you download if you don’t want to risk overwriting valuable EEPROM data.

\begin{itemize}
  \item \textbf{RESERVING EEPROM LOCATIONS.}
  \item \textbf{WRITING A BLOCK OF THE SAME VALUE.}
  \item \textbf{IMPORTANT CONCEPT: HOW DATA AND PROGRAMS ARE DOWNLOADED EEPROM.}
\end{itemize}

It is important to realize that EEPROM is not overwritten during programming unless it is needed for program storage, or is filled by a \texttt{DATA} directive specifying data to be written. During downloading, EEPROM is always written in 16-byte sections if, and only if, any location within that section needs writing.

\texttt{DATA} can also store the same number in a block of consecutive locations. This is similar to reserving a block of EEPROM, above, but with a value added before the first parenthesis. For example,

\begin{verbatim}
DATA @100, 0 (20)
\end{verbatim}

This statement writes the value 0 in all the EEPROM locations from 100 to 119.
A common use for DATA is to store strings; sequences of bytes representing text. PBASIC converts quoted text like "A" into the corresponding ASCII character code (65 in this case). To make data entry easier, you can place quotes around a whole chunk of text used in a DATA directive, and PBASIC will understand it to mean a series of bytes (see the last line of code below). The following three DATA directives are equivalent:

```
DATA 72, 69, 76, 76, 79
DATA "H", "E", "L", "L", "O"
DATA "HELLO"
```

All three lines of code, above, will result in the numbers 72, 69, 76, 76, and 79 being stored into EEPROM upon downloading. These numbers are simply the ASCII character codes for "H", "E", "L", "L", and "O", respectively. See the Demo Program, below, for an example of storing and reading multiple text strings.

The EEPROM is organized as a sequential set of byte-sized memory locations. By default, the DATA directive stores bytes into EEPROM. If you try to store a word-size value (ex: DATA 1125) only the lower byte of the value will be stored. This does not mean that you can't store word-sized values, however. A word consists of two bytes, called a low-byte and a high-byte. If you wanted to store the value 1125 using the DATA directive, simply insert the prefix "word" before the number, as in:

```
DATA word 1125
```

The directive above will automatically break the word-size value into two bytes and store them into two sequential EEPROM locations (the low-byte first, followed by the high-byte). In this case, the low-byte is 101 and the high byte is 4 and they will be stored in locations 0 and 1, respectively. If you have multiple word-size values, you must prefix each value with "word", as in:

```
DATA word 1125, word 2000
```

To retrieve a word-size value, you'll need to use two READ commands and a word-size variable (along with some handy modifiers). For example,
Result   VAR   WORD
DATA     word 1125

READ 0, Result.LOWBYTE
READ 1, Result.HIGHBYTE
DEBUG DEC Result

This code would write the low-byte and high-byte of the number 1125 into locations 0 and 1 during download. When the program runs, the two READ commands will read the low-byte and high-byte out of EEPROM (reconstructing it in a word-size variable) and then display the value on the screen. See the READ and WRITE commands for more information.

Demo Program (DATA.bs2)

This program stores a number of large text strings into EEPROM with the DATA directive and then sends them, one character at a time via the DEBUG command. This is a good demonstration of how to save program space by storing large amounts of data in EEPROM directly, rather than embedding the data into DEBUG commands.

'${STAMP BS2}    'STAMP directive (specifies a BS2)

-----Define variables-----
Index     VAR   WORD   'Holds current location number
PhraseNum VAR   NIB    'Holds current phrase number
Character VAR   BYTE   'Holds current character to print

-----Define all text phrases (out of order, just for fun!)-----
Text1     DATA "Here is the first part of a large chunk of textual data", CR
DATA "that needs to be transmitted. There's a 12 second delay", CR
DATA "between text paragraphs.", CR, 255

Text3     DATA "The alternative (having multiple DEBUGs or SEROUTs, each", CR
DATA "with their own line of text) consumes MUCH more EEPROM", CR
DATA ",(program) space; up to 854 more bytes, in this case!", CR, CR, 255

Text6     DATA "The 255 is used by this program to indicate we've reached the", CR
DATA "End of Text. The Main routine pauses in between each block of", CR
DATA "text, and then uses a LOOKUP command to retrieve the location", CR
DATA ", of the next desired block of text to print.", 255

Text4     DATA CLS, "This program also demonstrates retrieving data out of order", CR
DATA "in relation to the way it is stored in EEPROM. Additionally", CR
DATA "control codes (like carriage-returns, clear-screens, etc) can", CR
DATA "be embedded right in the data, as it is here.", CR, CR, 255

Text2     DATA "This is an example of a good way to save space in your", CR
DATA "BASIC Stamp's program by storing data into EEPROM and", CR
DATA "retrieving it, one byte at a time, and transmitting it", CR
DATA "with just a single DEBUG (or SEROUT) command.", CR, CR, 255

Text5     DATA "The PrintIt routine simply takes the Index variable, retrieves", CR
DATA "the character at the EEPROM location pointed to by it, and", CR
DATA "prints it to the screen until if finds a byte with a value", CR
DATA "of 255.", CR, CR, 255

'-----Main Routine-----
Main:
FOR PhraseNum = 1 TO 6
    LOOKUP PhraseNum-1,[Text1, Text2, Text3, Text4, Text5, Text6], Index
    GOSUB PrintIt
    PAUSE 12000
NEXT
STOP

'-----PrintIt Subroutine-----
PrintIt:
READ Index, Character
IF Character = 255 THEN Done
DEBUG Character
Index = Index + 1
GOTO PrintIt

Done:
RETURN
DEBUG Function
Display information on the PC screen within the BASIC Stamp editor program. This command can be used to display text or numbers in various formats on the PC screen in order to follow program flow (called debugging) or as part of the functionality of the BASIC Stamp application.

- **OutputData** is a variable/constant/expression (0 – 65535) that specifies the information to output. Valid data can be ASCII characters (text strings and control characters), decimal numbers (0 - 65535), hexadecimal numbers ($0000 - $FFFF) or binary numbers (up to %1111111111111111). Data can be modified with special formatters as explained below.

Explanation
DEBUG provides a convenient way for your BASIC Stamp to send messages to the PC screen while running. The name “debug” suggests its most popular use; debugging programs by showing you the value of a variable or expression, or by indicating what portion of a program is currently executing. DEBUG is also a great way to rehearse programming techniques. Throughout this manual, we use DEBUG to give you immediate feedback on the effects of instructions. The following example demonstrates using the DEBUG command to send the text string message “Hello World!”.

```
DEBUG "Hello World!”                ' Test message.
```

After you download this one-line program, the BASIC Stamp Editor will open a Debug Terminal on your PC screen and wait for a response from the BASIC Stamp. A moment later, the phrase "Hello World!” will appear. Note that if you close the Debug Terminal, your program keeps executing, but you can’t see the DEBUG data anymore.

Multiple pieces of data can be sent with one DEBUG command by separating the data with commas (,). The following example produces exactly the same results as the example above.

```
DEBUG "Hello ", "World!"             'Test message
```
DEBUG can also print and format numbers (values) from both constants and variables. The formatting methods for DEBUG are very different for the BS1, than for any other BASIC Stamp. Please read the appropriate sections, below, carefully.

**BASIC Stamp 1 Formatting**
On the BS1, the DEBUG command, by default, displays numbers in the format "symbol = value" (followed by a carriage return), using the decimal number system. For example,

```plaintext
SYMBOL X = B0
X = 75
DEBUG X
```

displays "X = 75" on the screen. To display the value, in decimal, without the "X =" text, use the decimal formatter (#) before the variable name. For example, the following code displays "75" on the screen.

```plaintext
SYMBOL X = B0
X = 75
DEBUG #X
```

To display numbers in hexadecimal or binary form, use the $ or % formatter, respectively. The code below displays the same number in its hexadecimal and binary forms.

```plaintext
SYMBOL X = B0
X = 75
DEBUG $X, %X
```

After running the above code, "X = $4B" and "X = %01001011" should appear on the screen. The **hexadecimal ($)** and **binary (%) formatters always display the number using the format "symbol = value" (followed by a carriage return). There is no built-in way to display hexadecimal or binary numbers in any other form when using the BS1's DEBUG command.**

To display a number as its ASCII character equivalent, use the ASCII formatter (@). Typing `DEBUG @X` (in place of the DEBUG statement in the code above) would display "X = 'K'" on the screen.
Two pre-defined symbols, CR and CLS, can be used to send a carriage-return or clear-screen command to the Debug Terminal. The CR symbol will cause the Debug Terminal to start a new line and the CLS symbol will cause the Debug Terminal to clear itself and place the cursor at the top-left corner of the screen. The following code demonstrates this.

```
DEBUG "You can not see this.", CLS, "Here is line 1", CR, "Here is line 2"
```

When the above is run, the final result is "Here is line 1" on the first line of the screen and "Here is line 2" on the second line. You may or may not have seen "You can not see this." appear first. This is because it was immediately followed by a clear-screen symbol, CLS, which caused the display to clear the screen before displaying the rest of the information.

NOTE: The rest of this discussion does not apply to the BASIC Stamp 1.
Expressions are allowed within the DEBUG command arguments as well. In the above code, DEBUG DEC x+25 would yield "95" and DEBUG DEC x*10/2-3 would yield "322".

<table>
<thead>
<tr>
<th>Formatter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>?</td>
<td>Displays &quot;symbol = x&quot; + carriage return; where x is a number. Default format is decimal, but may be combined with number formatters below (ex: bin ? x to display &quot;x = binary_number&quot;).</td>
</tr>
<tr>
<td>ASC ?</td>
<td>Displays &quot;symbol = 'x'&quot; + carriage return; where x is an ASCII character.</td>
</tr>
<tr>
<td>DEC{1..5}</td>
<td>Decimal text, optionally fixed for 1 to 5 digits.</td>
</tr>
<tr>
<td>SDEC{1..5}</td>
<td>Signed decimal text, optionally fixed for 1 to 5 digits.</td>
</tr>
<tr>
<td>HEX{1..4}</td>
<td>Hexadecimal text, optionally fixed for 1 to 4 digits.</td>
</tr>
<tr>
<td>SHEX{1..4}</td>
<td>Signed hex text, optionally fixed for 1 to 4 digits.</td>
</tr>
<tr>
<td>IHEX{1..4}</td>
<td>Indicated hex text ($ prefix; ex.: $7A3), optionally fixed for 1 to 4 digits.</td>
</tr>
<tr>
<td>ISHEX{1..4}</td>
<td>Indicated, signed hex text, optionally fixed for 1 to 4 digits.</td>
</tr>
<tr>
<td>BIN{1..16}</td>
<td>Binary text, optionally fixed for 1 to 16 digits.</td>
</tr>
<tr>
<td>SBIN{1..16}</td>
<td>Signed binary text, optionally fixed for 1 to 16 digits.</td>
</tr>
<tr>
<td>IBIN{1..16}</td>
<td>Indicated binary text (% prefix; ex.: %1001), optionally fixed for 1 to 16 digits.</td>
</tr>
<tr>
<td>ISBIN{1..16}</td>
<td>Indicated, signed binary text, optionally fixed for 1 to 16 digits.</td>
</tr>
<tr>
<td>STR bytearray</td>
<td>ASCII string from bytearray until byte = 0.</td>
</tr>
<tr>
<td>STR bytearray\n</td>
<td>ASCII string consisting of n bytes from bytearray.</td>
</tr>
<tr>
<td>REP byte\n</td>
<td>Display ASCII character n times.</td>
</tr>
</tbody>
</table>

As seen in Table 6.3, special versions of the DEC, HEX and BIN formatters allow for the display of indicated, signed and fixed-width numbers. The term "indicated" simply means that a special symbol is displayed, before the number, indicating what number system it belongs to. For example,

```plaintext
x  VAR  BYTE
x  =  65
DEBUG  HEX  x  ' Show hexadecimal value of x.
```

displays "41" (65, in decimal, is 41, in hexadecimal). You might see a problem here... unless you knew the number was supposed to be hexadecimal, you might think it was 41, in decimal... a totally different number. To help avoid this, use the IHEX formatter (the 'I' stands for indicated). Changing the DEBUG line to read: DEBUG IHEX x would print "$41" on the screen. A similar formatter for binary also exists, IBIN, which prints a "%" before the number.
Signed numbers are preceded with a space ( ) or a minus sign (-) to indicate a positive or negative number, respectively. Normally, any number displayed by the BASIC Stamp is shown in its unsigned (positive) form without any indicator. The signed formatters allow you to display the number as a signed (rather than unsigned) value. **NOTE:** **Only Word-sized variables can be used for signed number display.** The code below demonstrates the difference in all three numbering schemes.

```basic
x VAR WORD
x = -65
DEBUG "Signed: ", SDEC x, " ", ISHEX x, " ", ISBIN x, CR
DEBUG "Unsigned: ", DEC x, " ", IHEX x, " ", IBIN x
```

This code will generate the display shown below:

Signed: -65  -$41  -%1000001
Unsigned: 65471  $FFBF  %1111111110111111

The signed form of the number –65 is shown in decimal, hexadecimal and then in binary on the top line. The unsigned form, in all three number systems, is shown on the bottom line. If the unsigned form looks strange to you, it’s because negative numbers are stored in twos-compliment format within the BASIC Stamp.

Suppose that your program contained several DEBUG instructions showing the contents of different variables. You would want some way to tell them apart. One possible way is to do the following:

```basic
x VAR BYTE
y VAR BYTE
x = 100
y = 250
DEBUG "X = ", DEC x, CR  ' Show decimal value of x
DEBUG "Y = ", DEC y, CR  ' Show decimal value of y
```

but typing the name of the variables in quotes (for the display) can get a little tedious. A special formatter, the question mark (?), can save you a lot of time. The code below does exactly the same thing (with less typing):
The display would look something like this:

x = 100  
y = 250  

The ? formatter always displays data in the form "symbol = value" (followed by a carriage return). In addition, it defaults to displaying in decimal, so we really only needed to type: DEBUG ? x for the above code. You can, of course, use any of the three number systems. For example: DEBUG HEX ? x or DEBUG BIN ? y.

It's important to note that the "symbol" it displays is taken directly from what appears to the right of the ?. If you were to use an expression, for example: DEBUG ? x*10/2+3 in the above code, the display would show: "x*10/2+3 = 503".

A special formatter, ASC, is also available for use only with the ? formatter to display ASCII characters, as in: DEBUG ASC ? x.

What if you need to display a table of data; multiple rows and columns? The Signed/Unsigned code (above) approaches this but, if you notice, the columns don't line up. The number formatters (DEC, HEX and BIN) have some useful variations to make the display fixed-width (see Table 6.3). Up to 5 digits can be displayed for decimal numbers. To fix the value to a specific number of decimal digits, you can use DEC1, DEC2, DEC3, DEC4 or DEC5. For example:

x = 165  
DEBUG DEC5 x  

displays "00165". Notice that leading zeros? The display is "fixed" to 5 digits, no more and no less. Any unused digits will be filled with zeros.
Using DEC4 in the same code would display "0165". DEC3 would display "165". What would happen if we used DEC2? Regardless of the number, the BASIC Stamp will ensure that it is always the exact number of digits you specified. In this case, it would truncate the "1" and only display "65".

Using the fixed-width version of the formatters in the Signed/Unsigned code above, may result in the following code:

```basic
x VAR WORD
x = -65
DEBUG "Signed: ", SDEC5 x, ", ", ISHEX4 x, ", ", ISBIN16 x, CR
DEBUG "Unsigned: ", DEC5 x, ", ", IHEX4 x, ", ", IBIN16 x
```

and displays:

Signed: -00065 -$0041 -%0000000001000001
Unsigned: 65471 $FFBF %1111111110111111

Note: The columns don't line up exactly (due to the extra "sign" characters in the first row), but it certainly looks better than the alternative.

**DISPLAYING STRINGS (BYTE ARRAYS).**

If you have a string of characters to display (a byte array), you can use the STR formatter to do so. The STR formatter has two forms (as shown in Table 6.3) for variable-width and fixed-width data. The example below is the variable-width form.

```basic
x VAR BYTE(5)
x(0) = "A"
x(1) = "B"
x(2) = "C"
x(3) = "D"
x(4) = 0
DEBUG STR x
```

This code displays "ABCD" on the screen. In this form, the STR formatter displays each character contained in the byte array until it finds a character that is equal to 0 (value 0, not "0"). This is convenient for use with the SERIN command's STR formatter, which appends 0's to the end of variable-width character string inputs. **NOTE:** If your byte array doesn't end with 0, the BASIC Stamp will read and output all RAM register contents until it finds a 0 or until it cycles through all RAM locations.
To specify a fixed-width format for the STR formatter, use the form \texttt{STR x\textbackslash n}; where \texttt{x} is the byte array and \texttt{n} is the number of characters to print. Changing the DEBUG line in the example above to: \texttt{DEBUG STR x\textbackslash 2} would display "AB" on the screen.

If you need to display the same ASCII character multiple times, the REP (repeat) formatter can help. REP takes the form: \texttt{REP x\textbackslash n}; where \texttt{x} is the character and \texttt{n} is the number of times to repeat it. For example:

\begin{verbatim}
DEBUG REP "-"\textbackslash 10
\end{verbatim}

would display 10 hyphens on the screen, "----------".

Since individual DEBUG instructions can grow to be fairly complicated, and since a program can contain many DEBUGS, you’ll probably want to control the character positioning of the Debug Terminal screen. DEBUG supports a number of different control characters, some with pre-defined symbols (see Table 6.4). The Debug Terminal in the Windows version of the editor supports all the control characters in Table 6.4, while the DOS version only supports a few of them.

Some of the control characters have pre-defined symbols associated with them. In your DEBUG commands, you can use those symbols, for example: \texttt{DEBUG "Hello", CR} displays "Hello" followed by a carriage return. You can always use the ASCII value for any of the control characters, however. For example: \texttt{DEBUG "Hello", 13} is exactly the same as the code above.

The Move To control character is perhaps the most unique of the set. If the Debug Terminal receives this character, it expects to see an \texttt{x} and \texttt{y} position value to follow (in the next two characters received). The following line moves the cursor to column number 4 in row number 5 and displays "Hello":

\begin{verbatim}
DEBUG 2, 4, 5, "Hello"
\end{verbatim}

The upper-left cursor position is 0,0 (that is column 0, row 0). The right-most cursor positions depend on the size of the Debug Terminal window (which is user adjustable). If a character position that is out of range is
received, the Debug Terminal wraps back around to the opposite side of
the screen.

The Clear Right control character clears the characters that appear to the
right of, and on, the cursor's current position. The cursor is not moved by
this action.

The Clear Down control character clears the characters that appear below,
and on, the cursor's current line. The cursor is not moved by this action.

Table 5.6: Special Control
Characters.

<table>
<thead>
<tr>
<th>Name</th>
<th>Symbol</th>
<th>ASCII Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Clear Screen</td>
<td>CLS</td>
<td>0</td>
<td>Clear the screen and place cursor at home position.</td>
</tr>
<tr>
<td>Home</td>
<td>HOME</td>
<td>1</td>
<td>Place cursor at home in upper-left corner of the screen.</td>
</tr>
<tr>
<td>Move To (x,y)*</td>
<td></td>
<td>2</td>
<td>Move cursor to specified location. Must be followed by two values (x and then y)</td>
</tr>
<tr>
<td>Cursor Left*</td>
<td></td>
<td>3</td>
<td>Move cursor one character to left.</td>
</tr>
<tr>
<td>Cursor Right*</td>
<td></td>
<td>4</td>
<td>Move cursor one character to right.</td>
</tr>
<tr>
<td>Cursor Up*</td>
<td></td>
<td>5</td>
<td>Move cursor one character up.</td>
</tr>
<tr>
<td>Cursor Down*</td>
<td></td>
<td>6</td>
<td>Move cursor one character down.</td>
</tr>
<tr>
<td>Bell</td>
<td>BELL</td>
<td>7</td>
<td>Beep the PC speaker.</td>
</tr>
<tr>
<td>Backspace</td>
<td>BKSP</td>
<td>8</td>
<td>Back up cursor to left one space.</td>
</tr>
<tr>
<td>Tab</td>
<td>TAB</td>
<td>9</td>
<td>Tab to the next column.</td>
</tr>
<tr>
<td>Line Feed*</td>
<td></td>
<td>10</td>
<td>Move cursor down one line.</td>
</tr>
<tr>
<td>Clear Right*</td>
<td></td>
<td>11</td>
<td>Clear line contents to the right of cursor.</td>
</tr>
<tr>
<td>Clear Down*</td>
<td></td>
<td>12</td>
<td>Clear screen contents below cursor.</td>
</tr>
<tr>
<td>Carriage Return</td>
<td>CR</td>
<td>13</td>
<td>Move cursor to the first column of the next line (shift any data on the right down to that line as well)</td>
</tr>
</tbody>
</table>

* This control character only works with the Windows version of the editor software.

DEBUG is actually a special case of the SEROUT instruction. It is set for
inverted (RS-232-compatible) serial output through the programming
connector (the SOUT pin) at 9600 baud, no parity, 8 data bits, and 1 stop
bit. For example,

DEBUG "Hello"

is exactly like:

SEROUT 16, $4054, ["Hello"]
in terms of function (on a BS2). The DEBUG line actually takes less program space, and is obviously easier to type.

You may view DEBUG’s output using a terminal program set to the above parameters, but you may have to modify either your carrier board or the serial cable to temporarily disconnect pin 3 of the BASIC Stamp (pin 4 of the DB-9 connector). See the SEROUT command for more detail.
Function
Generate dual-tone, multifrequency tones (DTMF, i.e., telephone “touch” tones).

- **Pin** is a variable/constant/expression (0 – 15) that specifies the I/O pin to use. This pin will be set to output mode during generation of tones and set to input mode afterwards.

- **OnTime** is an optional variable/constant/expression (0 – 65535) specifying a duration of the tone. The unit of time and the default time for **OnTime** is described in Table 5.7.

- **OffTime** is an optional variable/constant/expression (0 – 65535) specifying the length of silent pause after a tone (or between tones, if multiple tones are specified). The unit of time and the default time for **OffTime** is described in Table 5.7.

- **Tone** is a variable/constant/expression (0 – 15) specifying the DTMF tone to generate. Tones 0 through 11 correspond to the standard layout of the telephone keypad, while 12 through 15 are the fourth-column tones used by phone test equipment and in ham-radio applications.

### Quick Facts

<table>
<thead>
<tr>
<th>BS2, BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Default <strong>OnTime</strong></td>
<td>200 ms</td>
<td>80 ms</td>
</tr>
<tr>
<td>Default <strong>OffTime</strong></td>
<td>50 ms</td>
<td>50 ms</td>
</tr>
<tr>
<td>Units in <strong>OnTime</strong> and <strong>OffTime</strong></td>
<td>1 ms</td>
<td>0.4 ms</td>
</tr>
</tbody>
</table>

### Explanation
DTMF tones are used to dial the phone or remotely control certain radio equipment. The BASIC Stamp can generate these tones digitally using the DTMFOUT instruction. Figure 5.2 shows how to connect a speaker or audio amplifier to hear these tones and Figure 5.3 shows how to connect the BASIC Stamp to the phone line.
The following DTMFOUT instruction will generate DTMF tones on I/O pin 0:

```
DTMFOUT 0, [ 6, 2, 4, 8, 3, 3, 3] ' Call Parallax.
```

If the BASIC Stamp is connected to the phone line properly, the above command would be equivalent to dialing 624-8333 from a phone keypad. If you wanted to slow the pace of the dialing to accommodate a noisy phone line or radio link, you could use the optional OnTime and OffTime values:

```
DTMFOUT 0, 500, 100, [ 6, 2, 4, 8, 3, 3, 3] ' Call Parallax, slowly.
```

In this example, on a BS2 the OnTime is set to 500 ms (1/2 second) and OffTime to 100 ms (1/10th second).

<table>
<thead>
<tr>
<th>Tone Value</th>
<th>Corresponding Telephone Key</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 – 9</td>
<td>Digits 0 through 9</td>
</tr>
<tr>
<td>10</td>
<td>Star (*)</td>
</tr>
<tr>
<td>11</td>
<td>Pound (#)</td>
</tr>
<tr>
<td>12 – 15</td>
<td>Fourth column tones A through D</td>
</tr>
</tbody>
</table>

Table 5.8: DTMF Tones and Corresponding Telephone Keys.

![Diagram of RC Filter Circuits for Driving an Audio Amplifier or a Speaker.](image)

Figure 5.2: Example RC Filter Circuits for Driving an Audio Amplifier or a Speaker.

![Diagram of Driving a Speaker Circuit.](image)

Driving a Speaker

Notes:
C1 may be omitted for piezo speakers
C2 is optional, but reduces high-frequency noise
The BASIC Stamp controller is a purely digital device. DTMF tones are analog waveforms, consisting of a mixture of two sine waves at different audio frequencies. So how does a digital device generate analog output? The BASIC Stamp creates and mixes the sine waves mathematically, then uses the resulting stream of numbers to control the duty cycle of a very fast pulse-width modulation (PWM) routine. So what's actually coming out of the I/O pin is a rapid stream of pulses. The purpose of the filtering arrangements shown in Figures 5.2 and 5.3 is to smooth out the high-frequency PWM, leaving only the lower frequency audio behind.

Keep this in mind if you want to interface BASIC Stamp's DTMF output to radios and other equipment that could be adversely affected by the presence of high-frequency noise on the input. Make sure to filter the DTMF output thoroughly. The circuits in Figure 5.2 are only a starting point; you may want to use an active low-pass filter with a roll-off point around 2 kHz.

**Figure 5.3:** Example DAA Circuit to Interface to a Standard Telephone Line.

**Interfacing to the Telephone Line**

connect switch (or relay contacts)  
600-600Ω transformer (JC: 117760)  
1 kΩ 0.1µF  
from I/O pin  
phone line (red and green)  
10Ω (both)  
270V “Sidactor” (DK: P3000AA61-ND P3000AA61-ND)  
3.9V zeners (both)  
DK: 1N5228BCT-ND  
V5s

### Parts Sources

- **Digi-Key (DK), 1-800-344-4539 or 218-681-6674**
- **Jameco (JC), 1-800-831-4242 or 415-592-8097**

**Demo Program (DTMFOUT.bs2)**

This demo program is a rudimentary memory dialer. Since DTMF digits fit within a nibble (four bits), the program below packs two DTMF digits into each byte of three EEPROM data tables. The end of a phone number is marked by the nibble $F, since this is not a valid phone-dialing digit.

```
'[$STAMP  BS2]  
'-----Define variables-----  
EElc  VAR  BYTE  
EEByte  VAR  BYTE  
'STAMP directive (specifies a BS2)  
' EEPROM address of stored number.  
' Byte containing two DTMF digits.  

'BASIC Stamp Programming  Manual 2.0c • www.parallaxinc.com • Page 109
```
DTMFOUT - BASIC Stamp Command Reference

DTdigit   VAR   EEBYTE.highNIB   ' Digit to dial.
Phone     VAR   NIB            ' Pick a phone #.
HiLo      VAR   BIT            ' Bit to select upper and lower nibble.

'-----Define data-----
Parallax   DATA $19,$16,$62,$48,$33,$3F ' Phone: 1-916-624-8333
ParallaxFax DATA $19,$16,$62,$48,$00,$3F ' Phone: 1-916-624-8003
Information DATA $15,$20,$55,$51,$21,$2F  ' Phone: 1-520-555-1212

'-----Main Routine-----
FOR Phone = 0 TO 2   ' For each phone #, get location of # in EEPROM.
  LOOKUP Phone,[Parallax,ParallaxFax,Information],EEloc
Dial:
  READ EEloc,EEByte   ' Retrieve byte from EEPROM.
  FOR HiLo = 0 to 1
    IF DTdigit = $F THEN Done ' Hex $F is end-of-number flag
    DTMFout 11,[DTdigit] ' Dial digit.
    EEBYTE = EEBYTE << 4 ' Shift in next digit.
  NEXT
EEloc = EEloc + 1    ' next pair of digits.
GOTO dial ' Keep dialing until done ($F in DTdigit).

done:     ' This number is done.
  PAUSE 2000    ' Wait a couple of seconds.
  NEXT

STOP
EEPROM {Location,} (DataItem {, DataItem,...})

Function
Write data to the EEPROM during program download.

- **Location** is an optional variable/constant (0 – 255) that specifies the starting location in the EEPROM at which data should be stored. If no location is given, data is written starting at the next available location.

- **DataItem** is a constant (0 – 255) to be stored in EEPROM.

Explanation
When you download a program into the BASIC Stamp 1, it is stored in the EEPROM starting at the highest address (255) and working towards the lowest address. Most programs don’t use the entire EEPROM, so the lower portion is available for other uses. The EEPROM directive allows you to define a set of data to store in the available EEPROM locations. It is called a “directive” rather than a “command” because it performs an activity at compile-time rather than at run-time (ie: the EEPROM directive is not downloaded to the BASIC Stamp 1, but the data it contains is downloaded).

**Writing simple, sequential data.** The simplest form of the EEPROM directive is something like the following:

```
EEPROM (100, 200, 52, 45)
```

This example, when downloaded, will cause the values 100, 200, 52 and 45 to be written to EEPROM locations 0, 1, 2 and 3, respectively. You can then use the READ and WRITE commands in your code to access these locations and the data you’ve stored there.

**The EEPROM pointer (counter).** The EEPROM directive uses a counter, called a pointer, to keep track of available EEPROM addresses. The value of the pointer is initially 0. When a program is downloaded, the EEPROM directive stores the first byte value at the current pointer address, then increments (adds 1 to) the pointer. If the program contains more than one EEPROM directive,
subsequent EEPROM directives start with the pointer value left by the previous EEPROM directive. For example, if the program contains:

EEPROM  (72, 69, 76, 76, 79)

The first EEPROM directive will start at location 0 and increment the pointer for each data value it stores (1, 2, 3, 4 and 5). The second EEPROM directive will start with the pointer value of 5 and work upward from there. As a result, the first 10 bytes of EEPROM will look like the following:

<table>
<thead>
<tr>
<th>EEPROM Location (address)</th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Contents</td>
<td>0</td>
<td>1</td>
<td>2</td>
<td>3</td>
<td>4</td>
<td>5</td>
<td>6</td>
<td>7</td>
<td>8</td>
</tr>
<tr>
<td></td>
<td>72</td>
<td>69</td>
<td>76</td>
<td>76</td>
<td>79</td>
<td>104</td>
<td>101</td>
<td>108</td>
<td>108</td>
</tr>
</tbody>
</table>

Table 5.9: Example EEPROM storage.

What if you don’t want to store values starting at location 0? Fortunately, the EEPROM directive has an option to specify the next location to use. You can specify the next location number (to set the pointer to) by using the optional Location argument before the list of Dataitems. The following code writes the same data in Table 5.9 to locations 50 through 59:


In this example, the Location argument is given and tells the EEPROM directive to store the following DataItem(s) starting at location 50. The DataItems in the list are stored in their respective locations (50, 51, 52... 59).

It is important to realize that the entire BASIC Stamp 1 EEPROM is overwritten during programming. Any EEPROM location not containing a PBASIC program or Dataitems from an EEPROM directive is written with a 0.

A common use for EEPROM is to store strings; sequences of bytes representing text. PBASIC converts quoted text like "A" into the corresponding ASCII character code (65 in this case). To make data entry easier, you can place quotes around a whole chunk of text used in a EEPROM directive, and PBASIC will understand it to mean a series of bytes (see the last line of code below). The following three EEPROM directives are equivalent:

| W| S| T| I| N| G| D| A| T| A| S| T| O| O| T| H| L| O| C| A| T| I| O| N| S|
| W| T| R| I| N| G| D| A| T| A| S| T| O| O| T| H| L| O| C| A| T| I| O| N| S|
| I| M| P| O| R| A| N| T| C| O| N| C| E| P| S| T| A| N| T| I| O| N| S|
| H| O| W| D| A| T| A| S| T| R| Y| A| S| P| R| O| A| M| S| A| D| R| A| T| E| D| S|

Writing data to other locations.

Writing text strings.

Important concept: How data and programs are downloaded EEPROM.

Important concept: How data and programs are downloaded EEPROM.
All three lines of code, above, will result in the numbers 72, 69, 76, 76, and 79 being stored into EEPROM upon downloading. These numbers are simply the ASCII character codes for "H", "E", "L", "L", and "O", respectively. See the Demo Program, below, for an example of storing and reading multiple text strings.

The EEPROM is organized as a sequential set of byte-sized memory locations. The EEPROM directive only stores bytes into EEPROM. If you try to store a word-size value, for example: EEPROM (1125), only the lower byte of the value will be stored (in this case, 101). This does not mean that you can't store word-sized values, however. A word consists of two bytes, called a low-byte and a high-byte. If you wanted to store the value 1125 using the EEPROM directive you'll have to calculate the low-byte and the high-byte and insert them in the list in the proper order, as in:

EEPROM (101, 4)

The directive above will store the two bytes into two sequential EEPROM locations (the low-byte first, followed by the high-byte). We calculated this in the following manner: 1) high-byte is INT(value / 256) and 2) low-byte is value – (high-byte * 256).

To retrieve a word-size value, you'll need to use two READ commands and a word-size variable. For example,

```
SYMBOL Result   =  W0 'The full word-sized variable
SYMBOL Result_Low =  B0 'B0 happens to be the low-byte of W0
SYMBOL Result_High =  B1 'B1 happens to be the high-byte of W0
EEPROM (101, 4)
READ 0, Result_Low
READ 1, Result_High
DEBUG #Result
```

This code would write the low-byte and high-byte of the number 1125 into locations 0 and 1 during download. When the program runs, the two READ commands will read the low-byte and high-byte out of EEPROM (reconstructing it in a word-size variable) and then display the value on the screen. See the READ and WRITE commands for more information.
Demo Program (EEPROM.bas)
This program stores a couple of text strings into EEPROM with the EEPROM directive and then sends them, one character at a time via the SEROUT command. This is a good demonstration of how to save program space by storing large amounts of data in EEPROM directly, rather than embedding the data into SEROUT commands.

'${STAMP BS1}'  'STAMP directive (specifies a BS1)
'Define variables-----
SYMBOL Index = B0  'Holds current location number
SYMBOL Phrase = B1
SYMBOL Character = B2  'Holds current character to print

'Define all text phrases -----
EEPROM ("Here is a long message that needs to be transmitted.", 255)
EEPROM ("Here is some more text to be transmitted.", 255)

'Main Routine-----
Main:
    Index = 0
    FOR Phrase = 1 TO 2
        GOSUB PrintIt
        PAUSE 12000    'Pause for 12 seconds in between text blocks
    NEXT
END

'PrintIt Subroutine-----
PrintIt:
    READ Index, Character  'Get next character
    IF Character = 255 THEN Done  'If it is 255, we're done with this block
    SEROUT 0,N2400,(Character)  'Otherwise, transmit it
    Index = Index + 1  'Increment Index to the next EEPROM location
    GOTO PrintIt  'Loop again

Done:
    RETURN  'Return to the main routine
Function
End the program, placing the BASIC Stamp into low-power mode indefinitely. This is equivalent to having a program that does not loop continuously; once the BASIC Stamp reaches the end of the PBASIC program, it enters low-power mode indefinitely. The END command is optional and is rarely used.

Quick Facts

<table>
<thead>
<tr>
<th></th>
<th>BS1</th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Apx. current draw @ 5 vdc during run*</td>
<td>2 mA</td>
<td>8 mA</td>
<td>25 mA</td>
<td>60 mA</td>
<td>40 mA</td>
</tr>
<tr>
<td>Apx. current draw @ 5 vdc during end*</td>
<td>20 µA</td>
<td>40 µA</td>
<td>60 µA</td>
<td>60 µA</td>
<td>60 µA</td>
</tr>
</tbody>
</table>

* This is an approximate value, not including loads on the I/O pins.

Explanation
END puts the BASIC Stamp into its inactive, low-power mode. In this mode the Stamp’s current draw (excluding loads driven by the I/O pins) is reduced to the amount shown in Table 5.10. END keeps the BASIC Stamp inactive until the reset line is activated, the power is cycled off and back on or the PC downloads another program.

Just as with the SLEEP command, pins will retain their input or output settings after the BASIC Stamp is deactivated by END. For example, if the BASIC Stamp is powering an LED when END executes, the LED will stay lit after END, but every 2.3 seconds, there will be a visible wink of the LED as the output pin switches to the input direction for 18 ms. (See the SLEEP command for more information).
FOR...NEXT

FUNCTION

Create a repeating loop that executes the program lines between FOR and NEXT, incrementing or decrementing Counter according to StepValue until the value of the Counter variable passes the EndValue.

- **Counter** is a variable (usually a byte or a word) used as a counter.
- **StartValue** is a variable/constant/expression (0 – 65535) that specifies the initial value of the variable (Counter).
- **EndValue** is a variable/constant/expression (0 – 65535) that specifies the end value of the variable (Counter). When the value of Counter is outside of the range StartValue to EndValue, the FOR...NEXT loop stops executing and the program goes on to the instruction after NEXT.
- **StepValue** is an optional variable/constant/expression (0 – 65535) by which the Counter increases or decreases with each iteration through the FOR...NEXT loop. On the BS1, use a minus sign (-) in front of the StepValue to indicate a negative step. On all other BASIC Stamps, if StartValue is larger than EndValue, PBASIC understands StepValue to be negative, even though no minus sign is used.

Quick Facts

<table>
<thead>
<tr>
<th></th>
<th>BS1</th>
<th>BS2, BS2e, BS2sx and BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Max. nested commands</strong></td>
<td>8</td>
<td>16</td>
</tr>
<tr>
<td><strong>To decrement counter variable</strong></td>
<td>Set StartValue &gt; EndValue and enter negative StepValue*</td>
<td>Set StartValue &gt; EndValue</td>
</tr>
<tr>
<td><strong>Counter comparison</strong></td>
<td>Exit loop if Counter exceeds EndValue</td>
<td>Exit loop if Counter outside of range set by StartValue to EndValue</td>
</tr>
</tbody>
</table>

* Direction (ie: increment/decrement) cannot be changed at runtime.
FOR...NEXT loops let your program execute a series of instructions for a specified number of repetitions (called iterations). By default, each time through the loop, the counter variable is incremented by 1. It will continue to loop until the result of the counter is outside of the range set by StartValue and EndValue. Also, FOR...NEXT loops always execute at least once. The simplest form is shown here:

```
Reps VAR NIB
FOR Reps = 1 TO 3
  DEBUG "*"
NEXT
```

In the above code, the FOR command sets Reps = 1. Then the DEBUG line (within the FOR...NEXT loop) is executed; printing an asterisk (*) on the screen. When the BASIC Stamp sees the NEXT command, it goes back to the previous FOR command, adds 1 to Reps and compares the result to the range set by StartValue and EndValue. If Reps is still within range, it executes the code in the loop again. Each time the FOR...NEXT loop executes, the value of Reps is updated (incremented by 1) and the code within the loop (the DEBUG line) is executed; printing another asterisk on the screen. This code will run through the loop three times; setting Reps to 1, 2 and 3, and printing three asterisks on the screen. After the third loop, again the BASIC Stamp goes back up to the FOR command, adds 1 to Reps and compares the result (4 in this case) to the range. Since the range is 1 to 3 and the value is 4 (outside the range) the FOR...NEXT loop is done and the BASIC Stamp will jump down to the first line of code following the NEXT command.

You can view the changing values of Reps by including the Reps variable in a DEBUG command within the loop:

```
Reps VAR NIB
FOR Reps = 1 TO 3
  DEBUG DEC Reps, CR
NEXT
```

Running this example should display "1", "2", and "3" on the screen.

FOR...NEXT can also be made to decrement (rather than increment) the counter variable. The BS1 does this when you specify a negative StepValue (as well as a StartValue that is greater than the EndValue). All other BASIC

```
NOTE: Change the first line as noted above and replace line 3 with
DEBUG #Reps, CR
on the BS1.
```

```
NOTE: On the BS1, the loop will continue until Counter has gone past EndValue.
```

```
NOTE: Replace the first line with SYMBOL Reps = B0 on the BS1.
```

```
SIMPLEST FORM OF FOR...NEXT.
```

```
SIMPLEST FORM OF FOR...NEXT.
```

```
DÉCREMENTING THE COUNTER INSTEAD OF INCREMENTING IT.
```

Page 118 • BASIC Stamp Programming Manual 2.0b • www.parallaxinc.com
Stamps do this automatically when the StartValue is greater than the EndValue. Examples of both are shown below:

```plaintext
SYMBOL Reps = B0  ' Counter for the FOR/NEXT loop.
FOR Reps = 3 TO 1 STEP -1  ' Repeat with Reps = 3, 2, 1.
  DEBUG #Reps, CR  ' Each repetition, put the number of the repetition on the screen.
NEXT

-- or --
Reps VAR NIB  ' Counter for the FOR/NEXT loop.
FOR Reps = 3 TO 1  ' Repeat with Reps = 3, 2, 1.
  DEBUG DEC Reps, CR  ' Each repetition, put the number of the repetition on the screen.
NEXT
```

Note that the code for the BS2, BS2e, BS2sx and BS2p did not use the optional STEP argument. This is because we wanted to decrement by positive 1 anyway (the default unit) and the BASIC Stamp realizes it needs to decrement because the StartValue is greater than the EndValue. A negative StepValue on the BS2, BS2e, BS2sx and BS2p would be treated as its positive, two’s compliment counterpart. For example, –1 in two’s complement is 65535. So the following code executes only once:

```plaintext
Reps VAR NIB  ' Counter for the FOR/NEXT loop.
FOR Reps = 3 TO 1 STEP -1  ' This will try to decrement 3 by 65535.
  DEBUG DEC Reps, CR  ' Each repetition, put the number of the repetition on the screen.
NEXT
```

The above code would run through the loop once with Reps set to 3. The second time around, it would decrement Reps by 65535 (-1 is 65535 in two’s compliment) effectively making the number –65532 (4 in two’s compliment) which is outside the range of the loop.

Using variables as arguments.

All the arguments in the FOR...NEXT command can be constants, variables or expressions (on the BS2, BS2e, BS2sx and BS2p). This leads to some interesting uses. For example, if you make the StartValue and EndValue a variable, and change their values within the loop, you'll change the behavior of the loop itself. Try the following:
Reps VAR WORD   ' Counter for the loop.
StartVal VAR BYTE
EndVal VAR BYTE

StartVal = 1
EndVal = 3
FOR Reps = StartVal TO EndVal
  DEBUG DEC Reps,CR
  IF Reps <> 3 THEN Done
    StartVal = 3
    EndVal = 1
Done:
NEXT

Here the loop starts with a range of 1 to 3. First, the DEBUG line prints the value of Reps. Then the IF...THEN line makes a decision; if Reps is not equal to 3, jump to the label "Done." If, however, Reps is equal to 3, the two lines following IF...THEN swap the order of StartVal and EndVal, making the range 3 to 1. The next time through the loop, Reps will be decremented instead of incremented because StartVal is greater than EndVal. The result is a display on the screen of the numbers 1, 2, 3, 2, 1.

The following example uses the value of Reps as the StepValue. This creates a display of power's of 2 (1, 2, 4, 8, 16, 32, 64, etc):

Reps VAR WORD   ' Counter for the loop.
FOR Reps = 1 TO 256 STEP Reps   ' Each loop add current value of Reps
  DEBUG DEC ? Reps   ' Show reps in debug window.
NEXT

There is a potential bug that you should be careful to avoid. The BASIC Stamp uses unsigned 16-bit integer math for any math operation it performs, regardless of the size of values or variables. The maximum value the BASIC Stamp can internally calculate is 65535 (the largest 16-bit number). If you add 1 to 65535, you get 0 as the 16-bit register rolls over (like a car’s odometer does when you exceed the maximum mileage it can display). Similarly, if you subtract 1 from 0, you’ll get 65535 as the 16-bit register rolls under (a rollover in the opposite direction).

If you write a FOR...NEXT loop who’s StepValue would cause the counter variable to go past 65535, this rollover may cause the loop to execute more times than you expect. Try the following example:
Reps VAR WORD  ' Counter for the loop.
FOR  Reps = 0  TO  65535  STEP 3000  ' Each loop add 3000.
    DEBUG  DEC ? Reps   ' Show reps in debug window.
NEXT

The value of reps increases by 3000 each trip through the loop. As it approaches the EndValue, an interesting thing happens; Reps is: 57000, 60000, 63000, 464, 3464... It passes the EndValue, rolls over and keeps going. That’s because the result of the calculation 63000 + 3000 exceeds the maximum capacity of a 16-bit number and then rolls over to 464. When the result of 464 is tested against the range (“Is Reps > 0 and is Reps < 65500?”) it passes the test and the loop continues.

A similar symptom can be seen in a program who’s EndValue is mistakenly set higher than what the counter variable can hold. The example below uses a byte-sized variable, but the EndValue is set to a number greater than what will fit in a byte:

SYMBOL  Reps = B0  ' Counter for the loop.
FOR  Reps = 0  TO  300  ' Each loop add 1.
    DEBUG  Reps    ' Show reps in debug window.
NEXT

-- or --

SYMBOL  Reps = B0  ' Counter for the loop.
FOR  Reps = 0  TO  300  ' Each loop add 1.
    DEBUG  DEC ? Reps   ' Show reps in debug window.
NEXT

Here, Reps is a byte variable; which can only hold the number range 0 to 255. The EndValue is set to 300, however; greater than 255. This code will loop endlessly because when Reps is 255 and the FOR...NEXT loop adds 1, Reps becomes 0 (bytes will rollover after 255 just like words will rollover after 65535). The result, 0, is compared against the range (0 – 255) and it is found to be within the range, so the FOR...NEXT loop continues.

It's important to realize that on the BS2, BS2e, BS2sx and BS2p, the test is against the entire range, not just the EndValue. The code below is a slight modification of the previous example (the StartValue is 10 instead of 0) and will not loop endlessly.
Reps VAR BYTE ' Counter for the loop.
FOR Reps = 10 to 300 ' Each loop add 1.
  DEBUG DEC ? Reps ' Show reps in debug window.
NEXT

Reps still rolls over to 0, as before, however, this time it is outside the range of 10 to 255. The loop stops, leaving Reps at 0. Note that this code is still in error since Reps will never reach 300 until it is declared as a WORD.

Demo Program (FORNEXT.bas)
' This example uses a FOR...NEXT loop to churn out a series of sequential squares (numbers 1, 2, 3, 4... raised to the second power) by using a variable to set the FOR...NEXT StepValue, and incrementing StepValue within the loop. Sir Isaac Newton is generally credited with the discovery of this technique.

'STAMP directive (specifies a BS1)
SYMBOL Square = B0 ' FOR/NEXT counter and series of squares.
SYMBOL StepSize = B1 ' Step size, which will increase by 2 each loop.

StepSize = 1
Square = 1
FOR Square = 1 TO 250 STEP StepSize ' Show squares up to 250.
  DEBUG Square ' Display on screen.
  StepSize = StepSize + 2 ' Add 2 to StepSize
NEXT ' Loop til square > 250.

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, BS2sx or BS2p.
**FREQOUT**

(See SOUND)

FREQOUT  Pin,  Period,  Freq1 {, Freq2}

**Function**

Generate one or two sine-wave tones for a specified period.

- **Pin** is a variable/constant/expression (0 – 15) that specifies the I/O pin to use. This pin will be set to output mode.

- **Period** is a variable/constant/expression (0 - 65535) specifying the amount of time to generate the tone(s). The unit of time for **Period** is described in Table 5.12.

- **Freq1** is a variable/constant/expression (0 – 32767) specifying frequency of the first tone. The unit of **Freq1** is described in Table 5.12.

- **Freq2** is an optional argument exactly like **Freq1**. When specified, two frequencies will be mixed together on the specified I/O pin.

**Quick Facts**

<table>
<thead>
<tr>
<th>BS2, BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Units in <strong>Period</strong></td>
<td>1 ms</td>
<td>0.4 ms</td>
</tr>
<tr>
<td>Units in <strong>Freq1</strong> and <strong>Freq2</strong></td>
<td>1 Hz</td>
<td>2.5 Hz</td>
</tr>
<tr>
<td>Range of frequency</td>
<td>0 to 32767 Hz</td>
<td>0 to 81.917 kHz</td>
</tr>
</tbody>
</table>

**Explanation**

FREQOUT generates one or two sine waves using a pulse-width modulation algorithm. The circuits shown in Figure 5.4 will filter the signal in order to play the tones through a speaker or audio amplifier. Here’s a simple FREQOUT command:

**SIMPLEST FORM OF FREQOUT.**

FREQOUT  2, 1000, 2500

On the BS2, this command generates a 2500 Hz tone for 1 second (1000 ms) on I/O pin 2. See Table 5.12 for timing data on other BASIC Stamps.

**GENERATING TWO TONES AT ONCE.**

To play two tones on the same I/O pin at once:
FREQOUT 2, 1000, 2500, 3000

This will generate a 2500 Hz and 3000 Hz tone (on the BS2) for 1 second. The frequencies will mix together for a chord- or bell-like sound. To generate a silent pause, specify frequency value(s) of 0.

The circuits in Figure 5.4 work by filtering out the high-frequency PWM used to generate the sine waves. FREQOUT works over a very wide range of frequencies (as shown in Table 5.12) so at the upper end of its range, those PWM filters will also filter out most of the desired frequency. You may find it necessary to reduce values of the parallel capacitors shown in the circuit, or to devise a custom active filter for your application.

The circuits in Figure 5.4 work by filtering out the high-frequency PWM used to generate the sine waves. FREQOUT works over a very wide range of frequencies (as shown in Table 5.12) so at the upper end of its range, those PWM filters will also filter out most of the desired frequency. You may find it necessary to reduce values of the parallel capacitors shown in the circuit, or to devise a custom active filter for your application.

Demo Program (FREQOUT.bs2)

` This program plays "Mary Had a Little Lamb" by reading the notes from a LOOKUP table.   ' It was designed to sound good on the piezo speaker that comes with the BASIC Stamp   ' Activity Board. To demonstrate the effect of mixing sine waves, the first frequency   ' is the musical note itself, while the second is 8 Hz lower. The difference creates a   ' quiver (vibrato) on each note. Subtracting 8 from the note frequency poses a problem   ' when the frequency is 0, because the BASIC Stamp's positive-integer math wraps around   ' to 65528. FREQOUT would ignore the highest bit of this value and generate a frequency   ' of 32760 Hz rather than a truly silent pause. Although humans can't hear 32762 Hz,   ' slight imperfections in filtering will cause an audible noise in the speaker. To clean   ' this up, we use the expression "(f-8) max 32768," which changes 65528 to 32768. FREQOUT   ' discards the highest bit of 32768, which results in 0, the desired silent pause.

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, BS2sx or BS2p.
'${STAMP BS2}    'STAMP directive (specifies a BS2)

i VAR BYTE  ' Counter for position in tune.
f VAR WORD  ' Frequency of note for FREQOUT.
C CON 2092  ' C note
D CON 2348  ' D note
E CON 2636  ' E note
G CON 3136  ' G note
R CON 8     ' Silent pause (rest).

FOR i = 0 TO 28  ' Play the 29 notes of the LOOKUP table.
    LOOKUP i,[E,D,C,D,E,E,R,D,D,R,E,G,G,R,E,D,C,D,E,E,E,D,D,E,D,C],f
    FREQOUT 11,225,f,(f-8) MAX 32768
NEXT
STOP
GET Location, Variable

Function
Read value from Scratch Pad RAM Location and store in Variable.

- **Location** is a variable/constant-expression (0 – 63 for BS2e and BS2sx and 0 – 127 for BS2p) that specifies the Scratch Pad RAM location to read from.

- **Variable** is a variable (usually a byte) to store the value into.

### Quick Facts

<table>
<thead>
<tr>
<th>Scratch Pad RAM size and organization</th>
<th>BS2e, BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Size</td>
<td>64 bytes (0 – 63). Organized as bytes only.</td>
<td>128 bytes (0 – 127). Organized as bytes only.</td>
</tr>
<tr>
<td>General purpose locations</td>
<td>0 – 62</td>
<td>0 – 126</td>
</tr>
<tr>
<td>Special use location</td>
<td>Current program slot number in read-only location 63.</td>
<td>Current program slot number in lowest nibble of read-only location 127. Current read/write slot number in highest nibble of location 127.</td>
</tr>
</tbody>
</table>

### Explanation

The GET command reads a byte-sized value from the specified Scratch Pad RAM location and stores it into Variable. All values in all locations can be retrieved from within any of the 8 program slots.

Scratch Pad RAM is useful for passing data to programs in other program slots and for additional workspace. It is different than regular RAM in that symbol names cannot be assigned directly to locations and each location is always configured as a byte only. The following code will read the value at location 25, store it in a variable called Temp and display it:

```
Temp VAR BYTE
GET 25, Temp
DEBUG DEC Temp
```
contains the current program slot that will be used for the READ and WRITE commands. See the demo program below for an example of use.

Demo Program (GETPUT1.bsx)

' This example demonstrates the use of the GET and PUT commands. First, location 63
' is read using GET to display the currently running program number. Then a set of
' values are written (PUT) into locations 0 to 9. Afterwards, program number 1 is run.
' This program is a BS2sx project consisting of GETPUT1.bsx and GETPUT2.bsx. See the
' BASIC Stamp Project section in the manual for more information.

'{$STAMP  BS2sx, GETPUT2.BSX} 'STAMP directive (specifies a BS2sx and
' a second program, GETPUT2.BSX)

Value   VAR   BYTE
Index   VAR   BYTE

GET 63, Value
DEBUG "Program ",DEC Value, CR

FOR Index = 0 TO 9
    Value = (Index + 3) * 8
    PUT Index, Value
    DEBUG " Writing ", DEC2 Value, " to location: ", DEC2 Index, CR
NEXT

RUN 1

Demo Program (GETPUT2.bsx)

' This example demonstrates the use of the GET and PUT commands. First, location 63
' is read using GET to display the currently running program number. Then a set of
' values are read (GET) from locations 0 to 9 and displayed on the screen for verification.
' This program is a BS2sx project consisting of GETPUT1.bsx and GETPUT2.bsx. See the
' BASIC Stamp Project section in the manual for more information.

'{$STAMP  BS2sx} 'STAMP directive (specifies a BS2sx)

Value   VAR   BYTE
Index   VAR   BYTE

GET 63, Value
DEBUG CR, "Program ",DEC Value, CR

FOR Index = 0 TO 9
    GET Index, Value
    DEBUG " Reading ", DEC2 Value, " from location: ", DEC2 Index, CR
NEXT

STOP

NOTE: This is written for the BS2sx but can be used for the BS2e, and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, or BS2p.
GOSUB

Function

Store the address of the next instruction after GOSUB, then go to the point in the program specified by Address; with the intention of returning to the stored address.

- Address is a label that specifies where to go.

Quick Facts

<table>
<thead>
<tr>
<th>Max. GOSUBs per program</th>
<th>BS1</th>
<th>BS2, BS2e, BS2sx and BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Max. nested GOSUBs</td>
<td>16</td>
<td>255</td>
</tr>
</tbody>
</table>

Explanation

GOSUB is a close relative of GOTO, in fact, its name means, "GO to a SUBroutine". When a PBASIC program reaches a GOSUB, the program executes the code beginning at the specified address label. Unlike GOTO, GOSUB also stores the address of the instruction immediately following itself. When the program encounters a RETURN command, it interprets it to mean, “go to the instruction that follows the most recent GOSUB.” In other words, a GOSUB makes the BASIC Stamp do a similar operation as you do when you see a table or figure reference in this manual; 1) you remember where you are, 2) you go to the table or figure and read the information there, and 3) when you’ve reached the end of it, you "return" to the place you were reading originally.

GOSUB is mainly used to execute the same piece of code from multiple locations. If you have, for example, a block of three lines of code that need to be run from 10 different locations in your entire program you could simply copy and paste those three lines to each of those 10 locations. This would amount to a total of 30 lines of repetitive code (and extra space wasted in the program memory). A better solution is to place those three lines in a separate routine, complete with its own label and followed by a RETURN command, then just use a GOSUB command at each of the 10 locations to access it. This technique can save a lot of program space.
Try the example below:

GOSUB  Hello
DEBUG "How are you?"
END

Hello:
   DEBUG "Hello my friend.", CR
RETURN

The above code will start out by GOSUB'ing to the section of code beginning with the label Hello. It will print "Hello my friend." on the screen then RETURN to the line after the GOSUB... which prints "How are you?" and ENDS.

There's another interesting lesson here; what would happen if we removed the END command from this example? Since the BASIC Stamp reads the code from left to right / top to bottom (like the English language) once it had returned to and run the "How are you?" line, it would naturally "fall into" the Hello routine again. Additionally, at the end of the Hello routine, it would see the RETURN again (although it didn't GOSUB to that routine this time) and because there wasn't a previous place to return to, the BASIC Stamp will start the entire program over again. This would cause an endless loop. The important thing to remember here is to always make sure your program doesn't allow itself to "fall into" a subroutine.

Only a limited number of GOSUBs are allowed per program (as shown in Table 5.14), but they may be nested only four levels deep. In other words, the subroutine that's the destination of a GOSUB can contain a GOSUB to another subroutine, and so on, to a maximum depth (total number of GOSUBS before the first RETURN) of four. Any deeper, and the program will "forget" its way back to the starting point (the instruction following the very first GOSUB).

When GOSUBS are nested, each RETURN takes the program back to the instruction after the most-recent GOSUB. As is mentioned above, if the BASIC Stamp encounters a RETURN without a previous GOSUB, the entire program starts over from the beginning. Take care to avoid these phenomena.
Demo Program (GOSUB.bas)

This program is a guessing game that generates a random number in a subroutine called PickANumber. It is written to stop after three guesses. To see a common bug associated with GOSUB, delete or comment out the line beginning with STOP after the FOR/NEXT loop. This means that after the loop is finished, the program will wander into the PickANumber subroutine. When the RETURN at the end executes, the program will go back to the beginning of the program. This will cause the program to execute endlessly. Make sure that your programs can't accidentally execute subroutines!

```basic
'STAMP directive (specifies a BS1)
SYMBOL Rounds = B2  ' Number of reps.
SYMBOL NumGen = W0  ' Random number holder (must be 16 bits).
SYMBOL MyNum = B3  ' Random number, 1-10.

NumGen = 11500  ' Initialize random "seed"
FOR Rounds = 1 TO 3  ' Go three rounds.
  DEBUG CLS,"Pick a number from 1 to 10", CR
  GOSUB PickANumber  ' Get a random number, 1-10.
  PAUSE 2000  ' Dramatic pause.
  DEBUG "My number was: ", #MyNum  ' Show the number.
  PAUSE 2000  ' Another pause.
NEXT
END  ' When done, stop execution here.

' Random-number subroutine. A subroutine is just a piece of code with the RETURN instruction at the end. Always make sure your program enters subroutines with a GOSUB. If you don't, the RETURN won't have the correct address, and your program will have a bug!
PickANumber:
  RANDOM NumGen  ' Stir up the bits of NumGen.
  DEBUG NumGen
  MyNum = NumGen / 6550 MIN 1  ' Scale to fit 1-10 range.
  RETURN  ' Go back to the 1st instruction after the GOSUB that got us here.
```

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, BS2sx or BS2p.

Demo Program (GOSUB.bas2)

This program is a guessing game that generates a random number in a subroutine called PickANumber. It is written to stop after three guesses. To see a common bug associated with GOSUB, delete or comment out the line beginning with STOP after the FOR/NEXT loop. This means that after the loop is finished, the program will wander into the PickANumber subroutine. When the RETURN at the end executes, the program will go back to the beginning of the program. This will cause the program to execute endlessly. Make sure that your programs can't accidentally execute subroutines!

```basic
'STAMP directive (specifies a BS2)
VAR Rounds = NIB  ' Number of reps.
VAR NumGen = WORD  ' Random-number holder (must be 16 bits).
VAR MyNum = NIB  ' Random number, 1-10.
```

BASIC Stamp Programming Manual 2.0c • www.parallaxinc.com • Page 131
FOR Rounds = 1 TO 3
   DEBUG CLS,"Pick a number from 1 to 10", CR
   GOSUB PickANumber   ' Get a random number, 1-10.
   PAUSE 2000          ' Dramatic pause.
   DEBUG "My number was: ", DEC MyNum   ' Show the number.
   PAUSE 2000          ' Another pause.
NEXT
STOP   ' When done, stop execution here.

' Random-number subroutine. A subroutine is just a piece of code with the RETURN
' instruction at the end. Always make sure your program enters subroutines with a GOSUB.
' If you don't, the RETURN won't have the correct address, and your program will have a bug!
PickANumber:
   RANDOM NumGen       ' Stir up the bits of NumGen.
   MyNum = NumGen / 6550 MIN 1   ' Scale to fit 1-10 range.
   RETURN               ' Go back to the 1st instruction
                        ' after the GOSUB that got us here.
GOTO

Function
Go to the point in the program specified by Address.

- Address is a label that specifies where to go.

Quick Facts

<table>
<thead>
<tr>
<th>BS1, BS2, BS2e, BS2sx and BS2p</th>
<th>Max. GOTOs per program</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Unlimited, but good programming practices suggest using the least amount possible.</td>
</tr>
</tbody>
</table>

Explanation
The GOTO command makes the BASIC Stamp execute the code that starts at the specified Address location. The BASIC Stamp reads PBASIC code from left to right / top to bottom, just like in the English language. The GOTO command forces the BASIC Stamp to jump to another section of code.

A common use for GOTO is to create endless loops; programs that repeat a group of instructions over and over. For example:

Loop:
DEBUG "Hi", CR
GOTO Loop

The above code will print "Hi" on the screen, over and over again. The GOTO Loop line simply tells it to go back to the code that begins with the label Loop.

Demo Program (GOTO.bs2)

' This program is not very practical, but demonstrates the use of GOTO to jump around the code. This code jumps between three different routines, each of which print something different on the screen. The routines are out of order for this example.

'{$STAMP BS2}    'STAMP directive (specifies a BS2)
GOTO Routine1

Routine2:
DEBUG "We're in routine #2",CR
PAUSE 1000

NOTE: This is written for the BS2 but can be used for the BS1, BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS1, BS2e, BS2sx or BS2p.
GOTO Routine3

Routine1:
   DEBUG "We're in routine #1",CR
   PAUSE 1000
   GOTO Routine2

Routine3:
   DEBUG "We're in routine #3",CR
   PAUSE 1000
   GOTO Routine1
**5: BASIC Stamp Command Reference – HIGH**

[Table]

<table>
<thead>
<tr>
<th>Pin</th>
<th>BS1</th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Function**

Make the specified pin output high.

- *Pin* is a variable/constant/expression (0 – 15) that specifies which I/O pin to set high. This pin will be placed into output mode.

**Explanation**

The HIGH command sets the specified pin to 1 (a +5 volt level) and then sets its mode to output. For example,

```
HIGH 6
```

does exactly the same thing as:

```
OUT6 = 1
DIR6 = 1
```

Using the HIGH command is faster, in this case.

Connect an LED and a resister as shown in Figure 5.5 for the demo program below.

**Figure 5.5:** Example LED Circuit.

![LED Circuit Diagram]

NOTE: Expressions are not allowed as arguments on the BS1. The range of the *Pin* argument on the BS1 is 0 – 7.
### Demo Program (HIGH.bs2)

This simple program sets I/O pin 0 high for 1/2 second and low for 1/2 second in an endless loop.

```basic
' This simple program sets I/O pin 0 high for 1/2 second and low for 1/2 second
' in an endless loop.
'{$STAMP BS2}  'STAMP directive (specifies a BS2)

Loop:
  HIGH 0
  PAUSE 500
  LOW 0
  PAUSE 500
  GOTO Loop
```

**NOTE:** This is written for the BS2 but can be used for the BS1, BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS1, BS2e, BS2sx or BS2p.
I2CIN

**Function**
Receive data from a device using the I²C protocol.

- **Pin** is a variable/constant/expression (0 or 8) that specifies which I/O pins to use. I²C devices require two I/O pins to communicate. The Pin argument serves a double purpose; specifying the first pin (for connection to the chip’s SDA pin) and, indirectly, the other required pin (for connection to the chip’s SCL pin). See explanation below. Both I/O pins will be toggled between output and input mode during the I2CIN command and both will be set to input mode by the end of the I2CIN command.
- **SlaveID** is a variable/constant/expression (0 – 255) indicating the unique ID of the I²C chip.
- **Address** is a variable/constant/expression (0 – 255) indicating the desired address within the I²C chip to receive data from. The Address argument may be used with the optional LowAddress argument to indicate a word-sized address value.
- **LowAddress** is a variable/constant/expression (0 – 255) indicating the low-byte of the word-sized address within the I²C chip to receive data from. This argument must be used along with the Address argument.
- **InputData** is a list of variables and modifiers that tells I2CIN what to do with incoming data. I2CIN can store data in a variable or array, interpret numeric text (decimal, binary, or hex) and store the corresponding value in a variable, wait for a fixed or variable sequence of bytes, or ignore a specified number of bytes. These actions can be combined in any order in the InputData list.

**Quick Facts**

<table>
<thead>
<tr>
<th>BS2p</th>
</tr>
</thead>
</table>

<table>
<thead>
<tr>
<th>Values for Pin</th>
<th>0 or 8</th>
</tr>
</thead>
</table>

<table>
<thead>
<tr>
<th>I/O pin arrangement</th>
<th>When Pin is 0:</th>
<th>When Pin is 8:</th>
</tr>
</thead>
<tbody>
<tr>
<td>0: Serial Data (SDA) pin</td>
<td>8: Serial Data (SDA) pin</td>
<td></td>
</tr>
<tr>
<td>1: Serial Clock (SCL) pin</td>
<td>9: Serial Clock (SCL) pin</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Transmission Rate</th>
<th>Approximately 81 kbits/sec (not including overhead).</th>
</tr>
</thead>
</table>

| Special notes | Both the SDA and SCL pins must have 4.7 KΩ pull-up resistors. The I2CIN command does not allow for multiple masters. The BASIC Stamp cannot operate as an I²C slave device. |
The I2C protocol is a form of synchronous serial communication developed by Phillips Semiconductors. It only requires two I/O pins and both pins can be shared between multiple I2C devices. The I2CIN command allows the BASIC Stamp to receive data from an I2C device.

The following is an example of the I2CIN command:

```basic
Result VAR BYTE
I2CIN 0, $A1, 0, [Result]
```

This code will transmit a "read" command to an I2C device (connected to I/O pins 0 and 1) and then will receive one byte and store it in the variable Result. Though it may seem strange, the I2CIN command first transmits some data and then receives data. It must first transmit information (ID, read/write and address) in order to tell the I2C device what information it would like to receive. The exact information transmitted ($A1, 0) depends on the I2C device that is being used.

The above example will read a byte of data from location 0 of a 24LC16B EEPROM from Microchip. Figure 5.6 shows the proper wiring for this example to work. The SlaveID argument ($A1) is both the ID of the chip and the command to read from the chip; the 1 means read. The Address argument (0) is the EEPROM location to read from.

The I2CIN command’s InputData argument is similar to the SERIN command’s InputData argument. This means data can be received as ASCII character values, decimal, hexadecimal and binary translations and string data as in the examples below. (Assume the 24LC16B EEPROM is used and it has the string, "Value: 3A:101" stored, starting at location 0).
Tables 5.17 and 5.18 list all the available conversion formatters and special formatters available to the I2CIN command. See the SERIN command for additional information and examples of their use.

### Table 5.17: I2CIN Conversion Formatters

<table>
<thead>
<tr>
<th>Conversion Formatter</th>
<th>Type of Number</th>
<th>Numeric Characters Accepted</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>DEC{1..5}</td>
<td>Decimal, optionally limited to 1 – 5 digits</td>
<td>0 through 9</td>
<td>1</td>
</tr>
<tr>
<td>SDEC{1..5}</td>
<td>Signed decimal, optionally limited to 1 – 5 digits</td>
<td>-, 0 through 9</td>
<td>1,2</td>
</tr>
<tr>
<td>HEX{1..4}</td>
<td>Hexadecimal, optionally limited to 1 – 4 digits</td>
<td>0 through 9, A through F</td>
<td>1,3</td>
</tr>
<tr>
<td>SHEX{1..4}</td>
<td>Signed hexadecimal, optionally limited to 1 – 4 digits</td>
<td>-, 0 through 9, A through F</td>
<td>1,2,3</td>
</tr>
<tr>
<td>IHEX{1..4}</td>
<td>Indicated hexadecimal, optionally limited to 1 – 4 digits</td>
<td>$, 0 through 9, A through F</td>
<td>1,3,4</td>
</tr>
<tr>
<td>ISHEX{1..4}</td>
<td>Signed, indicated hexadecimal, optionally limited to 1 – 4 digits</td>
<td>-, $, 0 through 9, A through F</td>
<td>1,2,3,4</td>
</tr>
<tr>
<td>BIN{1..16}</td>
<td>Binary, optionally limited to 1 – 16 digits</td>
<td>0, 1</td>
<td>1</td>
</tr>
<tr>
<td>SBIN{1..16}</td>
<td>Signed binary, optionally limited to 1 – 16 digits</td>
<td>-, 0, 1</td>
<td>1,2</td>
</tr>
<tr>
<td>IBIN{1..16}</td>
<td>Indicated binary, optionally limited to 1 – 16 digits</td>
<td>%, 0, 1</td>
<td>1,4</td>
</tr>
<tr>
<td>ISBIN{1..16}</td>
<td>Signed, indicated binary, optionally limited to 1 – 16 digits</td>
<td>-, %, 0, 1</td>
<td>1,2,4</td>
</tr>
</tbody>
</table>

1. All numeric conversions will continue to accept new data until receiving either the specified number of digits (ex: three digits for DEC3) or a non-numeric character.
2. To be recognized as part of a number, the minus sign (-) must immediately precede a numeric character. The minus sign character occurring in non-numeric text is ignored and any character (including a space) between a minus and a number causes the minus to be ignored.
3. The hexadecimal formatters are not case-sensitive; “a” through “f” means the same as “A” through “F”.
4. Indicated hexadecimal and binary formatters ignore all characters, even valid numerics, until they receive the appropriate prefix ($ for hexadecimal, % for binary). The indicated formatters can differentiate between text and hexadecimal (ex: ABC would be interpreted by HEX as a number but IHEX would ignore it unless expressed as $ABC). Likewise, the binary version can distinguish the decimal number 10 from the binary number %10. A prefix occurring in non-numeric text is ignored, and any character (including a space) between a prefix and a number causes the prefix to be ignored. Indicated, signed formatters require that the minus sign come before the prefix, as in -$1B45.
The I2C protocol has a well-defined standard for the information passed at the start of each transmission. First of all, any information sent must be transmitted in units of 1 byte (8-bits). The first byte, we call the SlaveID, is an 8-bit pattern whose upper 7-bits contain the unique ID of the device you wish to communicate with. The lowest bit indicates whether this is a write operation (0) or a read operation (1). Figure 5.7 shows this format.

![Figure 5.7: SlaveID Format.](image)

The second byte, immediately following the SlaveID, is the Address. It indicates the 8-bit address (within the device) containing the data you would like to receive.

Some devices require more than 8 bits of address. For this case, the optional LowAddress argument can be used for the low-byte of the required address. When using the LowAddress argument, the Address argument is effectively the high-byte of the address value. For example, if the entire address value is 2050, use 8 for the Address argument and 2 for the LowAddress argument (8 * 256 + 2 = 2050).

Following the last address byte is the first byte of data. This data byte may be transmitted or received by the BASIC Stamp. In the case of the I2CIN command, this data byte is transmitted by the device and received by the BASIC Stamp. Additionally, multiple data bytes can follow the address, depending on the I2C device. Note that every device has different limitations regarding how many contiguous bytes they can receive or transmit in one session. Be aware of these device limitations and program accordingly.
Every I\(^2\)C transmission session begins with a Start Condition and ends with a Stop Condition. Additionally, immediately after every byte is transmitted, an extra clock cycle is used to send or receive an acknowledgment signal (ACK). All of these operations are automatically taken care of by the I2CIN command so that you need not be concerned with them. The general I\(^2\)C transmission format is shown in Figure 5.8.

Since the I2CIN command is intended for input only, it actually overrides the "R/W" bit (bit 0) in the SlaveID argument. This is done so that it can use the I\(^2\)C protocol's "Combined Format" for receiving data. Put simply, this means a command such as: I2CIN 0, $A1, 10, [Result] actually transmits $A0, then 10, then $A1 and then it reads the data back from the device. The $A0 means "write", the 10 is the address to write to and, finally, the $A1 indicates a change of direction; to "read" the location, instead. Even though the I2CIN command really doesn't care what the value of the SlaveID's LSB is, it is suggested that you still set it appropriately for clarity.

Also note that the I2CIN command does not support multiple I\(^2\)C masters and the BASIC Stamp cannot operate as an I\(^2\)C slave device.

**Demo Program (I2C.bsp)**

```
' This program demonstrates writing and reading every location in the 24LC16B EEPROM
' using the BS2p's I2C commands. Connect the BS2p to the 24LC16B DIP EEPROM as
' shown in the diagram in the I2CIN or I2COUT command description.

'{STAMP BS2p}   'STAMP directive (specifies a BS2p)
```
Idx VAR WORD  'Index variable for address
Check VAR NIB   'Index for checking returned values
Result VAR BYTE(16) '16-byte array for returned value

WriteToEEPROM:
DEBUG "Writing...", CR
PAUSE 2000
FOR Idx = 0 TO 2047 STEP 16    'For all 2K locations,
   I2COUT 0, $A0+((Idx>>8)*2), Idx, [REP Idx>>4\16\]  'Write 16 bytes at once
   PAUSE 5
NEXT
PAUSE 2000

ReadFromEEPROM:
DEBUG CR, "Reading...", CR
PAUSE 2000
FOR Idx = 0 TO 2047 STEP 16    'For all 2K locations,
   I2CIN 0, $A1+((Idx>>8)*2), Idx, [STR Result\16\]  'Read 16 bytes at once
   FOR Check = 0 TO 15          'Check all 16 for
      IF Result(Check) <> Idx>>4 & $FF THEN Error      'accuracy, stop if error
   NEXT
NEXT
PAUSE 1000
DEBUG CR, " All Locations PASSED!"
STOP

Error:
DEBUG "Error at location: ", DEC4 Idx+Check, CR
DEBUG "Found: ", DEC3 Result(Check), " Expected: ", DEC3 Idx>>4 & $FF
STOP
I2COUT

I2COUT  Pin, SlaveID, Address {LowAddress}, [OutputData]

Function
Send data to a device using the I2C protocol.

- **Pin** is a variable/constant/expression (0 or 8) that specifies which I/O pins to use. I2C devices require two I/O pins to communicate. The Pin argument serves a double purpose; specifying the first pin (for connection to the chip's SDA pin) and, indirectly, the other required pin (for connection to the chip’s SCL pin). See explanation below. Both I/O pins will be toggled between output and input mode during the I2COUT command and both will be set to input mode by the end of the I2COUT command.

- **SlaveID** is a variable/constant/expression (0 – 255) indicating the unique ID of the I2C chip.

- **Address** is a variable/constant/expression (0 – 255) indicating the desired address within the I2C chip to send data to. The Address argument may be used with the optional LowAddress argument to indicate a word-sized address value.

- **LowAddress** is a variable/constant/expression (0 – 255) indicating the low-byte of the word-sized address within the I2C chip to receive data from. This argument must be used along with the Address argument.

- **OutputData** is a list of variables, constants, expressions and formatters that tells I2COUT how to format outgoing data. I2COUT can transmit individual or repeating bytes, convert values into decimal, hexadecimal or binary text representations, or transmit strings of bytes from variable arrays. These actions can be combined in any order in the OutputData list.

Quick Facts

<table>
<thead>
<tr>
<th>Table 5.19: I2COUT Quick Facts.</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Values for Pin</strong></td>
<td></td>
</tr>
<tr>
<td>0 or 8</td>
<td></td>
</tr>
<tr>
<td><strong>I/O pin arrangement</strong></td>
<td></td>
</tr>
<tr>
<td>When Pin is 0:</td>
<td></td>
</tr>
<tr>
<td>0: Serial Data (SDA) pin</td>
<td></td>
</tr>
<tr>
<td>1: Serial Clock (SCL) pin</td>
<td></td>
</tr>
<tr>
<td>When Pin is 8:</td>
<td></td>
</tr>
<tr>
<td>8: Serial Data (SDA) pin</td>
<td></td>
</tr>
<tr>
<td>9: Serial Clock (SCL) pin</td>
<td></td>
</tr>
<tr>
<td><strong>Transmission Rate</strong></td>
<td></td>
</tr>
<tr>
<td>Approximately 81 kbits/sec (not including overhead).</td>
<td></td>
</tr>
<tr>
<td><strong>Special notes</strong></td>
<td></td>
</tr>
<tr>
<td>Both the SDA and SCL pins must have 4.7 KΩ pull-up resistors.</td>
<td></td>
</tr>
<tr>
<td>The I2COUT command does not allow for multiple masters.</td>
<td></td>
</tr>
<tr>
<td>The BASIC Stamp cannot operate as an I2C slave device.</td>
<td></td>
</tr>
</tbody>
</table>
Explanation
The I2C protocol is a form of synchronous serial communication developed by Phillips Semiconductors. It only requires two I/O pins and both pins can be shared between multiple I2C devices. The I2COUT command allows the BASIC Stamp to send data to an I2C device.

The following is an example of the I2COUT command:

I2COUT 0, $A0, 5, [100]

This code will transmit a "write" command to an I2C device (connected to I/O pins 0 and 1), followed by an address of 5 and finally will transmit the number 100.

The above example will write a byte of data to location 5 of a 24LC16B EEPROM from Microchip. Figure 5.9 shows the proper wiring for this example to work. The SlaveID argument ($A0) is both the ID of the chip and the command to write to the chip; the 0 means write. The Address argument (5) is the EEPROM location to write to.

The I2COUT command's OutputData argument is similar to the DEBUG and SEROUT command's OutputData argument. This means data can be sent as literal text, ASCII character values, repetitive values, decimal, hexadecimal and binary translations and string data as in the examples below. (Assume the 24LC16B EEPROM is being used).
5: BASIC Stamp Command Reference – I2COUT

Value VAR BYTE
Value = 65
I2COUT 0, $A0, 0, [Value]  'send the ASCII value for "A"
I2COUT 0, $A0, 0, [REP Value\5]  'send the ASCII value for "A" five times, ie: "AAAAA"
I2COUT 0, $A0, 0, [DEC Value]  'send two characters, "6" and "5"
I2COUT 0, $A0, 0, [HEX Value]  'send two characters, "4" and "1"
I2COUT 0, $A0, 0, [BIN Value]  'send seven characters, "1000001"

Tables 5.20 and 5.21 list all the available conversion formatters and special formatters available to the I2COUT command. See the DEBUG and SEROUT commands for additional information and examples of their use.

**Table 5.20: I2COUT Conversion Formatters.**

<table>
<thead>
<tr>
<th>Conversion Formatter</th>
<th>Type of Number</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>DEC{1..5}</td>
<td>Decimal, optionally fixed to 1 – 5 digits</td>
<td>1</td>
</tr>
<tr>
<td>SDEC{1..5}</td>
<td>Signed decimal, optionally fixed to 1 – 5 digits</td>
<td>1,2</td>
</tr>
<tr>
<td>HEX{1..4}</td>
<td>Hexadecimal, optionally fixed to 1 – 4 digits</td>
<td>1</td>
</tr>
<tr>
<td>SHEX{1..4}</td>
<td>Signed hexadecimal, optionally fixed to 1 – 4 digits</td>
<td>1,2</td>
</tr>
<tr>
<td>IHEX{1..4}</td>
<td>Indicated hexadecimal, optionally fixed to 1 – 4 digits ($ prefix)</td>
<td>1</td>
</tr>
<tr>
<td>ISHEX{1..4}</td>
<td>Signed, indicated hexadecimal, optionally fixed to 1 – 4 digits ($ prefix)</td>
<td>1,2</td>
</tr>
<tr>
<td>BIN{1..16}</td>
<td>Binary, optionally fixed to 1 – 16 digits</td>
<td>1</td>
</tr>
<tr>
<td>SBIN{1..16}</td>
<td>Signed binary, optionally fixed to 1 – 16 digits</td>
<td>1,2</td>
</tr>
<tr>
<td>IBIN{1..16}</td>
<td>Indicated binary, optionally fixed to 1 – 16 digits (% prefix)</td>
<td>1</td>
</tr>
<tr>
<td>ISBIN{1..16}</td>
<td>Signed, indicated binary, optionally fixed to 1 – 16 digits (% prefix)</td>
<td>1,2</td>
</tr>
</tbody>
</table>

1 Fixed-digit formatters like DEC4 will pad the number with leading 0s if necessary; ex: DEC4 65 sends 0065. If a number is larger than the specified number of digits, the leading digits will be dropped; ex: DEC4 56422 sends 6422.
2 Signed modifiers work under two's complement rules.

**Table 5.21: I2COUT Special Formatters.**

<table>
<thead>
<tr>
<th>Special Formatter</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>?</td>
<td>Displays &quot;symbol = x' + carriage return; where x is a number. Default format is decimal, but may be combined with conversion formatters (ex: BIN ? x to display &quot;x = binary_number&quot;).</td>
</tr>
<tr>
<td>ASC ?</td>
<td>Displays &quot;symbol = 'x'&quot; + carriage return; where x is an ASCII character.</td>
</tr>
<tr>
<td>STR ByteArray \L</td>
<td>Send character string from an array. The optional \L argument can be used to limit the output to L characters, otherwise, characters will be sent up to the first byte equal to 0 or the end of RAM space is reached.</td>
</tr>
<tr>
<td>REP Byte \L</td>
<td>Send a string consisting of Byte repeated L times (ex: REP &quot;X&quot;\10 sends &quot;XXXXXXXXX&quot;).</td>
</tr>
</tbody>
</table>

The I2C protocol has a well-defined standard for the information passed at the start of each transmission. First of all, any information sent must be transmitted in units of 1 byte (8-bits). The first byte, we call the SlaveID, is an 8-bit pattern whose upper 7-bits contain the unique ID of the device.
you wish to communicate with. The lowest bit indicates whether this is a write operation (0) or a read operation (1). Figure 5.10 shows this format.

![Figure 5.10: SlaveID Format.](image)

The second byte, immediately following the SlaveID, is the Address. It indicates the 8-bit address (within the device) you would like to send data to.

Some devices require more than 8 bits of address. For this case, the optional LowAddress argument can be used for the low-byte of the required address. When using the LowAddress argument, the Address argument is effectively the high-byte of the address value. For example, if the entire address value is 2050, use 8 for the Address argument and 2 for the LowAddress argument (8 * 256 + 2 = 2050).

Following the last address byte is the first byte of data. This data byte may be transmitted or received by the BASIC Stamp. In the case of the I2COUT command, this data byte is transmitted by the BASIC Stamp and received by the device. Additionally, multiple data bytes can follow the address, depending on the I²C device. Note that every device has different limitations regarding how many contiguous bytes they can receive or transmit in one session. Be aware of these device limitations and program accordingly.
Every I²C transmission session begins with a Start Condition and ends with a Stop Condition. Additionally, immediately after every byte is transmitted, an extra clock cycle is used to send or receive an acknowledgment signal (ACK). All of these operations are automatically taken care of by the I2CIN command so that you need not be concerned with them. The general I²C transmission format is shown in Figure 5.11.

Since the I2COUT command is intended for output only, it actually overrides the "R/W" bit (bit 0) in the SlaveID argument. This is done to avoid device conflicts should the value be mistyped. Put simply, this means commands such as: I2COUT 0, $A0, 10, [0] and I2COUT 0, $A1, 10, [0] both transmit the same thing ($A0, then 10, then the data). Even though the I2COUT command really doesn’t care what the value of the SlaveID’s LSB is, it is suggested that you still set it appropriately for clarity.

Also note that the I2COUT command does not support multiple I²C masters and the BASIC Stamp cannot operate as an I²C slave device.
DEBUG "Writing...", CR
PAUSE 2000
FOR Idx = 0 TO 2047 STEP 16  'For all 2K locations,
   I2COUT 0, $A0+((Idx>>8)*2), Idx, [REP Idx>>4\16\]  'Write 16 bytes at once
   PAUSE 5
NEXT
PAUSE 2000

ReadFromEEPROM:
DEBUG CR, "Reading...", CR
PAUSE 2000
FOR Idx = 0 TO 2047 STEP 16  'For all 2K locations,
   I2CIN 0, $A1+((Idx>>8)*2), Idx, [STR Result\16\]       'Read 16 bytes at once
   FOR Check = 0 TO 15          'Check all 16 for
      IF Result(Check) <> Idx>>4 & $FF THEN Error     'accuracy, stop if error
   NEXT
NEXT
PAUSE 1000
DEBUG CR, " All Locations PASSED!"
STOP

Error:
   DEBUG "Error at location: ", DEC4 Idx+Check, CR
   DEBUG "Found: ", DEC3 Result(Check), " Expected: ", DEC3 Idx>>4 & $FF
STOP
5: BASIC Stamp Command Reference – IF...THEN

IF...THEN

IF Condition THEN Address

Function
Evaluate Condition and, if it is true, go to the point in the program marked by Address.

• Condition is a statement, such as “x = 7” that can be evaluated as true or false. The Condition can be a very simple or very complex relationship, as described below.

• Address is a label that specifies where to go in the event that Condition is true.

Quick Facts

<table>
<thead>
<tr>
<th>BS1</th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
</table>

<table>
<thead>
<tr>
<th>Comparison operators</th>
<th>(=), (&lt;), (&gt;), (&lt;=), (&gt;=)</th>
<th>(=), (&lt;), (&gt;), (&lt;=), (&gt;=)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Conditional logic operators</td>
<td>AND, OR</td>
<td>NOT, AND, OR, XOR</td>
</tr>
<tr>
<td>Format of condition</td>
<td>Variable Comparison Value; where Value is a variable or constant</td>
<td>Value1 Comparison Value2; where Value1 and Value2 can be any of variable, constant or expression</td>
</tr>
<tr>
<td>Parentheses</td>
<td>Not Allowed</td>
<td>Allowed</td>
</tr>
</tbody>
</table>

Explanation
IF...THEN is PBASIC’s decision maker. It tests a condition and, if that condition is true, goes to a point in the program specified by an address label. The condition that IF...THEN tests is written as a mixture of comparison and logic operators. The available comparison operators are:

<table>
<thead>
<tr>
<th>Comparison Operator Symbol</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>(=)</td>
<td>Equal</td>
</tr>
<tr>
<td>(&lt;)</td>
<td>Not Equal</td>
</tr>
<tr>
<td>(&gt;)</td>
<td>Greater Than</td>
</tr>
<tr>
<td>(&lt;)</td>
<td>Less Than</td>
</tr>
<tr>
<td>(&gt;=)</td>
<td>Greater Than or Equal To</td>
</tr>
<tr>
<td>(&lt;=)</td>
<td>Less Than or Equal To</td>
</tr>
</tbody>
</table>

Table 5.23: IF...THEN Comparison Operators.

NOTE: Expressions are not allowed as arguments on the BS1. The range of the Pin argument on the
IF...THEN - BASIC Stamp Command Reference

constants, or expressions. The following example is an IF...THEN
command with a simple condition:

IF 10 < 200 THEN Loop

This code will compare the number 10 to the number 200. If 10 is less than
200, the condition is true. In this case, 10 is less than 200 (and always will
be), so the program will jump (or GOTO) the label called Loop. Of course,
this is a silly example (10 is always less than 200 so this line will always
cause a jump to Loop). Most of the time, you'll use at least one variable in
your condition:

Value VAR WORD

Loop:
PULSIN 0, Value
DEBUG DEC Value, CR
IF Value < 4000 THEN Loop
DEBUG "Value was greater than 4000!"

Here, the BASIC Stamp will look for and measure a pulse on I/O pin 0,
then compare the result, Value, against 4000. If Value is less than (<) 4000,
it will jump back to Loop. Each time through the loop, it displays the
measured value and once it is greater than or equal to 4000, it displays,
"Value was greater than 4000!"

On the BS2, BS2e, BS2sx and BS2p, the values can be expressions as well.
This leads to very flexible and sophisticated comparisons. The IF...THEN
statement below is functionally the same as the one in the program above:

IF Value < 45 * 100 – ( 25 * 20 ) THEN Loop

Here the BASIC Stamp evaluates the expression: 45 * 100 = 4500, 25 * 20 =
500, and 4500 – 500 = 4000. Then the BAISC Stamp performs the
comparison: is Value < 4000? Another example that is functionally the
same:

IF Value / 100 < 40 THEN Loop

It's important to realize that all comparisons are performed using
unsigned, 16-bit math. This can lead to strange results if you mix signed
and unsigned numbers in IF...THEN conditions. Watch what happens
here when we include a signed number (−99):

NOTE: For BS1’s, change line 1 to
SYMBOL Value = W0
and line 4 to
DEBUG #Value, CR

WATCH OUT FOR UNSIGNED MATH
COMPARISON ERRORS
IF -99 < 100 THEN IsLess
DEBUG "Greater than or equal to 100"
END

IsLess:
DEBUG "Less than 100"
END

Although -99 is obviously less than 100, the program will say it is greater. The problem is that -99 is internally represented as the two’s complement value 65437, which (using unsigned math) is greater than 100. This phenomena will occur whether or not the negative value is a constant, variable or expression.

IF...THEN supports the conditional logic operators NOT, AND, OR, and XOR. See Table 5.24 for a list of the operators and their effects.

The NOT operator inverts the outcome of a condition, changing false to true, and true to false. The following IF...THENs are equivalent:

IF x <> 100 THEN NotEqual ' Goto NotEqual if x is not 100.
IF NOT x = 100 THEN NotEqual ' Goto NotEqual if x is not 100.

The operators AND, OR, and XOR can be used to join the results of two conditions to produce a single true/false result. AND and OR work the same as they do in everyday speech. Run the example below once with AND (as shown) and again, substituting OR for AND:

Value1 VAR BYTE
Value2 VAR BYTE
Value1 = 5
Value2 = 9
IF Value1 = 5 AND Value2 = 10 THEN True ' Change AND to OR and see
DEBUG "Statement was false." ' what happens.
END

True:
DEBUG "Statement was true."

The condition “Value1 = 5 AND Value2 = 10” is not true. Although Value1 is 5, Value2 is not 10. The AND operator works just as it does in English; both conditions must be true for the statement to be true. The OR operator also works in a familiar way; if one or the other or both conditions are true, then the statement is true. The XOR operator (short for exclusive-OR) may not be familiar, but it does have an English
counterpart: If one condition or the other (but not both) is true, then the statement is true.

Table 5.24 below summarizes the effects of the conditional logic operators. As with math, you can alter the order in which comparisons and logical operations are performed by using parentheses. Operations are normally evaluated left-to-right. Putting parentheses around an operation forces PBASIC2 to evaluate it before operations not in parentheses.

<table>
<thead>
<tr>
<th>Condition A</th>
<th>NOT A</th>
</tr>
</thead>
<tbody>
<tr>
<td>False</td>
<td>True</td>
</tr>
<tr>
<td>True</td>
<td>False</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Condition A</th>
<th>Condition B</th>
<th>A AND B</th>
</tr>
</thead>
<tbody>
<tr>
<td>False</td>
<td>False</td>
<td>False</td>
</tr>
<tr>
<td>False</td>
<td>True</td>
<td>False</td>
</tr>
<tr>
<td>True</td>
<td>False</td>
<td>False</td>
</tr>
<tr>
<td>True</td>
<td>True</td>
<td>True</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Condition A</th>
<th>Condition B</th>
<th>A OR B</th>
</tr>
</thead>
<tbody>
<tr>
<td>False</td>
<td>False</td>
<td>True</td>
</tr>
<tr>
<td>False</td>
<td>True</td>
<td>True</td>
</tr>
<tr>
<td>True</td>
<td>False</td>
<td>True</td>
</tr>
<tr>
<td>True</td>
<td>True</td>
<td>False</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Condition A</th>
<th>Condition B</th>
<th>A XOR B</th>
</tr>
</thead>
<tbody>
<tr>
<td>False</td>
<td>False</td>
<td>False</td>
</tr>
<tr>
<td>False</td>
<td>True</td>
<td>True</td>
</tr>
<tr>
<td>True</td>
<td>False</td>
<td>True</td>
</tr>
<tr>
<td>True</td>
<td>True</td>
<td>False</td>
</tr>
</tbody>
</table>

Unlike the IF...THEN commands in other BASIC's, PBASIC’s IF...THEN can only go to a label as the result of a decision. It cannot conditionally perform some instruction, as in “IF x < 20 THEN y = y + 1.” To achieve this in PBASIC, you have to invert the logic using NOT and skip over the conditional instruction unless the condition is met:

```plaintext
IF NOT x < 20 THEN NoInc
    y = y + 1
NoInc:
```

' Don't increment y unless x < 20.
' Increment y if x < 20.
' Program continues.

You can also code a conditional GOSUB, as in “IF x = 100 THEN GOSUB Centennial.” In PBASIC:

NOTE: On the BS1, parentheses are not allowed within arguments.

NOTE: The NOT operator is not available on the BS1.

NOTE: The XOR operator is not available on the BS1.

IF...THEN CAN ONLY JUMP TO A LABEL IF THE CONDITION IS TRUE.
Internally, the BASIC Stamp defines “false” as 0 and “true” as any value other than 0. Consider the following instructions:

```plaintext
Flag = 1
IF Flag THEN IsTrue
DEBUG "false"
END

IsTrue:
DEBUG "true"
END
```

Since `Flag` is 1, IF...THEN would evaluate it as true and print the message “true” on the screen. Suppose you changed the IF...THEN command to read “IF NOT Flag THEN IsTrue.” That would also evaluate as true. Whoa! Isn’t NOT 1 the same thing as 0? No, at least not in the 16-bit world of the BASIC Stamp.

Internally, the BASIC Stamp sees a bit variable containing 1 as the 16-bit number %0000000000000001. So it sees the NOT of that as %1111111111111110. Since any non-zero number is regarded as true, NOT 1 is true. Strange but true.

The easiest way to avoid the kinds of problems this might cause is to always use a conditional operator with IF...THEN. Change the example above to read IF Flag = 1 THEN IsTrue. The result of the comparison will follow IF...THEN rules. Also, the logical operators will work as they should; IF NOT Flag = 1 THEN IsTrue will correctly evaluate to false when `Flag` contains 1.

This also means that you should only use the "named" conditional logic operators NOT, AND, OR, and XOR with IF...THEN. The conditional logic operators format their results correctly for IF...THEN instructions. The other logical operators, represented by symbols ~ & | and ^ do not; they are binary logic operators.
Demo Program (IFTHEN.bas)

' The program below generates a series of 16-bit random numbers and tests each to
determine whether they're evenly divisible by 3. If a number is evenly divisible
by 3, then it is printed, otherwise, the program generates another random number.
The program counts how many numbers it prints, and quits when this number reaches 10.

'${STAMP BS1}    'STAMP directive (specifies a BS1)
SYMBOL Sample = W0 ' Random number to be tested.
SYMBOL Samps = B2 ' Number of samples taken.
SYMBOL Temp = B3 ' Temporary workspace
Sample = 11500
Mul3:
    RANDOM Sample
    Temp = Sample // 3
    IF Temp <> 0 THEN Mul3
    DEBUG #Sample," is divisible by 3.", CR
    Samps = Samps + 1
    IF Samps = 10 THEN DONE
    GOTO Mul3

Done:
DEBUG CR, "All done."
END

Demo Program (IFTHEN.bs2)

' The program below generates a series of 16-bit random numbers and tests each to
determine whether they're evenly divisible by 3. If a number is evenly divisible
by 3, then it is printed, otherwise, the program generates another random number.
The program counts how many numbers it prints, and quits when this number reaches 10.

'${STAMP BS2}    'STAMP directive (specifies a BS2)
Sample VAR WORD  ' Random number to be tested.
Samps VAR NIB   ' Number of samples taken.
Mul3:
    RANDOM Sample
    IF NOT Sample // 3 = 0 THEN Mul3
    DEBUG DEC Sample," is divisible by 3.",CR
    Samps = Samps + 1
    IF Samps = 10 THEN DONE
    GOTO Mul3

Done:
DEBUG CR, "All done."
STOP

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, BS2sx or BS2p.
**INPUT**

**Function**
Make the specified pin an input.

- **Pin** is a variable/constant/expression (0 – 15) that specifies which I/O pin to set to input mode.

**Explanation**
There are several ways to make a pin an input. When a program begins, all of the BASIC Stamp’s pins are inputs. Commands that rely on input pins, like PULSIN and SERIN, automatically change the specified pin to input. Writing 0s to particular bits of the variable DIRS makes the corresponding pins inputs. And then there’s the INPUT command.

When a pin is an input, your program can check its state by reading the corresponding INS variable (PINS on the BS1). For example:

```basic
INPUT 4
Hold:
  IF IN4 = 0 THEN Hold  ' Stay here until P4 is 1.
```

The code above will read the state of P4 as set by external circuitry. If nothing is connected to P4, it will alternate between states (1 or 0) apparently at random.

What happens if your program writes to the OUTS bit (PINS bit on the BS1) of a pin that is set up as an input? The value is stored in OUTS (PINS on the BS1), but has no effect on the outside world. If the pin is changed to output, the last value written to the corresponding OUTS bit (or PINS bit on the BS1) will appear on the pin. The demo program shows how this works.

**Demo Program (INPUT.bas)**

```
' This program demonstrates how the input/output direction of a pin is determined by
' the corresponding bit of DIRS. It also shows that the state of the pin itself (as
' reflected by the corresponding bit of PINS) is determined by the outside world when
' the pin is an input, and by the corresponding bit of PINS when it's an output. To
' set up the demo, connect a 10k resistor from +5V to P7 on the BASIC Stamp. The
' resistor to +5V puts a high (1) on the pin when it's an input. The BASIC Stamp can
' override this state by writing a low (0) to bit 7 of OUTS and changing the pin to output.
```

**NOTE:** Expressions are not allowed as arguments on the BS1. The range of the Pin argument on the BS1 is 0 – 7.
Demo Program (INPUT.bs2)

This program demonstrates how the input/output direction of a pin is determined by the corresponding bit of DIRS. It also shows that the state of the pin itself (as reflected by the corresponding bit of INS) is determined by the outside world when the pin is an input, and by the corresponding bit of OUTS when it's an output. To set up the demo, connect a 10k resistor from +5V to P7 on the BASIC Stamp. The resistor to +5V puts a high (1) on the pin when it's an input. The BASIC Stamp can override this state by writing a low (0) to bit 7 of OUTS and changing the pin to output.

`{'$STAMP BS2}'  'STAMP directive (specifies a BS2)

INPUT 7       ' Make I/O pin 7 an input.
DEBUG "State of pin 7: ", BIN IN7, CR

OUT7 = 0      ' Write 0 to output latch.
DEBUG "After 0 written to OUT7: ", BIN IN7, CR

OUTPUT 7      ' Make I/O pin 7 an output.
DEBUG "After pin 7 changed to output: ", BIN IN7

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, BS2sx or BS2p.
IOTERM

**BS2p**

Table 5.25: IOTERM Quick Facts.

<table>
<thead>
<tr>
<th>BS2p</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>switch to main I/O group, 1 = switch to auxiliary I/O group.</td>
</tr>
<tr>
<td>I/O pin IDs</td>
<td>0 – 15 (after IOTERM command, all references affect physical pins 5 – 20 or 21 – 36 depending on state of Port).</td>
</tr>
<tr>
<td>Special notes</td>
<td>Both the BS2p24 and the BS2p40 accept this command, however, only the BS2p40 gives access to the auxiliary I/O pins.</td>
</tr>
</tbody>
</table>

**Explanation**

The BS2p is available in two module styles, 1) a 24-pin module (called the BS2p24) that is pin compatible with the BS2, BS2e and BS2sx and 2) a 40-pin module (called the BS2p40) that has an additional 16 I/O pins (for a total of 32). The BS2p40's I/O pins are organized into two groups, called main and auxiliary. The I/O pins in each group can be accessed in the same manner (by referencing I/O pins 0 – 15) but access is only possible within one group at a time. The IOTERM command causes the BASIC Stamp to affect either the main or auxiliary I/O pins in all further code until the MAINIO, AUXIO or another IOTERM command is reached, or the BASIC Stamp is reset or power-cycled. The value of Port determines which group of I/O pins will be referenced. Using 0 for Port will switch to the main I/O group and using 1 for Port will switch to the auxiliary group.

The following example illustrates this:

```
HIGH 0
IOTERM 1
LOW 0
```

The first line of the above example will set I/O pin 0 of the main I/O pins (physical pin 5) high. Afterward, the IOTERM command tells the BASIC Stamp that all commands following it should affect the auxiliary I/O pins (Port = 1). The following LOW command will set I/O pin 0 of the auxiliary I/O pins (physical pin 21) low.
Note that the main I/O and auxiliary I/O pins are independent of each other; the states of the main I/O pins remain unchanged while the program affects the auxiliary I/O pins, and vice versa.

Other commands that affect I/O group access are AUXIO and MAINIO.

### Demo Program (AUX_MAIN_TERM.bsp)

This program demonstrates the use of the AUXIO, MAINIO and IOTERM commands to affect I/O pins in the auxiliary and main I/O groups.

```basic
'{$STAMP  BS2p}    'STAMP directive (specifies a BS2p)
Port VAR BIT
Loop:
  MAINIO    'Switch to main I/O pins
  TOGGLE  0   'Toggle state of I/O pin 0 (physical pin 5)
  PWM  1, 100, 40   'Generate PWM on I/O pin 1 (physical pin 6)
  AUXIO    'Switch to auxiliary I/O pins
  TOGGLE  0   'Toggle state of I/O pin 0 (physical pin 21)
  PULSOUT  1, 1000  'Generate a pulse on I/O pin 1 (physical pin 22)
  PWM  2, 100, 40   'Generate PWM on I/O pin 2 (physical pin 23)
  IOTERM Port   'Switch to main or aux I/Os (depending on Port)
  TOGGLE  3   'Toggle state of I/O pin 3 (on main and aux, alternately)
  Port = ~Port   'Invert port (switch between 0 and 1)
  PAUSE  1000
GOTO  Loop
```

**NOTE:** This is written for the BS2p but its effects can only be seen on the 40-pin version: the BS2p40.
LCDCMD

Pin, Command

Function
Send a command to an LCD display.

- **Pin** is a variable/constant/expression (0 – 1 or 8 – 9) that specifies which I/O pins to use. The LCD requires, at most, seven I/O pins to operate. The **Pin** argument serves a double purpose; specifying the first pin and, indirectly, the group of other required pins. See explanation below. All I/O pins will be set to output mode.

- **Command** is a variable/constant/expression (0 – 255) indicating the LCD command to send.

<table>
<thead>
<tr>
<th>Table 5.26: LCDCMD Quick Facts.</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Values for Pin</strong></td>
</tr>
<tr>
<td>0 or 1 (depending on pin): LCD Enable (E) pin</td>
</tr>
<tr>
<td>2: LCD Read/Write (R/W) pin</td>
</tr>
<tr>
<td>3: LCD Register Select (RS) pin</td>
</tr>
<tr>
<td>4 – 7: LCD Data Buss (DB4 – DB7, respectively) pins</td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td><strong>I/O pin arrangement when Pin is</strong></td>
</tr>
<tr>
<td>0 or 1</td>
</tr>
<tr>
<td>8 or 9 (depending on pin): LCD Enable (E) pin</td>
</tr>
<tr>
<td>10: LCD Read/Write (R/W) pin</td>
</tr>
<tr>
<td>11: LCD Register Select (RS) pin</td>
</tr>
<tr>
<td>12 – 15: LCD Data Buss (DB4 – DB7, respectively) pins</td>
</tr>
</tbody>
</table>

Quick Facts

<table>
<thead>
<tr>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>0, 1, 8 or 9</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Special notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>LCDCMD is designed to use the LCD’s 4-bit mode only.</td>
</tr>
</tbody>
</table>

Explanation
The three LCD commands (LCDCMD, LCDIN and LCDOUT) allow the BS2p to interface directly to standard LCD displays that feature a Hitachi 44780 controller (part #HD44780A). This includes many 1 x 16, 2 x 16 and 4 x 20 character LCD displays.

The Hitachi 44780 LCD controller supports a number of special instructions for initializing the display, moving the cursor, changing the default layout, etc. The LCDCMD command is used to send one of these instructions to the LCD. It is most commonly used to initialize the display upon a power-up or reset condition.

A SIMPLE LCDCMD EXAMPLE.

The following is an example of the LCDCMD command:

LCDCMD 1, 24
The above code will send the Scroll Left command (represented by the number 24) to the LCD whose enable pin is connected to I/O pin 1. This will cause the LCD display to scroll, or shift, the entire display one character to the left.

You may have noticed that the Pin argument in the example above was 1. The LCDCMD command actually uses more than just this I/O pin, however. The LCDCMD command requires seven I/O pins. This is because the standard LCD displays have a parallel interface, rather than a serial one. The Pin argument can be the numbers 0, 1, 8 or 9 and will result in the use of the I/O pins shown in Table 5.26. Figure 5.12 shows the required wiring for the above command to work.

Note that we could have used 0 for the Pin argument and moved the LCD’s Enable pin (pin 6) to I/O pin 0. Similarly, using 9 for the Pin argument would have required us to wire the LCD’s pins to I/O pins 9 through 15, rather than I/O pins 1 through 7.

When the LCD is first powered-up, it will be in an unknown state and must be properly configured before sending commands like the one
shown above. This process is known as initializing the LCD and is the first thing your program should do upon starting up. The following code is a good example of LCD initialization.

```basic
InitLCD:
  'LCD's usually take more than 500 µs to power-up. This pause is
  PAUSE 1000  'to keep the BASIC Stamp from talking to the LCD too early.
  LCDCMD 1, 48  'Send wakeup sequence to LCD (three Wake-Up (48) commands)
  PAUSE 10  'This pause is necessary to meet the LCD specs
  LCDCMD 1, 48
  PAUSE 1  'This pause is necessary to meet the LCD specs
  LCDCMD 1, 48
  PAUSE 1  'This pause is necessary to meet the LCD specs
  LCDCMD 1, 32  'Set data bus to 4-bit mode
  LCDCMD 1, 40  'Set to 2-line mode with 5x8 font
  LCDCMD 1, 8  'Turn display off
  LCDCMD 1, 12  'Turn display on without cursor
  LCDCMD 1, 6  'Set to auto-increment cursor (no display shift)
  LCDCMD 1, 1  'Clear the display
```

This initialization code is the most commonly used sequence for a 2 x 16 and 4 x 20 LCD display (the 2-line mode instruction sets the 4 x 20 to 4-line mode). The PAUSE 1000 command is optional, but only if your program takes more than approximately 700 ms before it executes the InitLCD code above. Without it, upon powering your circuit, the BASIC Stamp may talk to the LCD too early, the LCD will then miss some of the commands and the display will operate strangely, or not at all.

Do not change the "wake-up" and "4-bit mode" sequence commands. However, the commands below the line that says, "Set data bus to 4-bit mode" may be modified to set other desired modes.

Table 5.27 shows the most commonly used LCD commands. Here's an example:

```basic
LCDCMD 1, 16
```

This will make the LCD's cursor move left by one character (16 is the Cursor Left command), even if the cursor is not visible. The next character printed on the display (with the LCDOUT command) will appear at the current cursor's location. Here's another example:

```basic
LCDCMD 1, 128 + 64
```

The above command will move the cursor to the first character position on the second line (on a 2 x 16 display). 128 is the Move To Display Address
command and 64 is the location number. See the "Character Positioning" section, below, for more information.

<table>
<thead>
<tr>
<th>Command</th>
<th>Command (in decimal)</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Do Nothing</td>
<td>0</td>
<td>Don't perform any special operation.</td>
</tr>
<tr>
<td>Clear Display</td>
<td>1</td>
<td>Clear the display and move cursor to home position.</td>
</tr>
<tr>
<td>Home Display</td>
<td>2</td>
<td>Move cursor and display to home position.</td>
</tr>
<tr>
<td>Inc Cursor</td>
<td>6</td>
<td>Set cursor direction to right, without a display shift.</td>
</tr>
<tr>
<td>Display Off</td>
<td>8</td>
<td>Turn off display (display data is retained).</td>
</tr>
<tr>
<td>Display On</td>
<td>12</td>
<td>Turn on display without cursor (display is restored).</td>
</tr>
<tr>
<td>Blinking Cursor</td>
<td>13</td>
<td>Turn on display with blinking cursor.</td>
</tr>
<tr>
<td>Underline Cursor</td>
<td>14</td>
<td>Turn on display with underline cursor.</td>
</tr>
<tr>
<td>Cursor Left</td>
<td>16</td>
<td>Move cursor left one character.</td>
</tr>
<tr>
<td>Cursor Right</td>
<td>20</td>
<td>Move cursor right one character.</td>
</tr>
<tr>
<td>Scroll Left</td>
<td>24</td>
<td>Scroll display left one character.</td>
</tr>
<tr>
<td>Scroll Right</td>
<td>28</td>
<td>Scroll display right one character.</td>
</tr>
<tr>
<td>Move To CRAM Address</td>
<td>64 + address</td>
<td>Move pointer to character RAM location</td>
</tr>
<tr>
<td>Move To DRAM Address</td>
<td>128 + address</td>
<td>Move cursor to display RAM location</td>
</tr>
</tbody>
</table>

While most users will only need the commands shown in Table 5.27, above, Table 5.28, below, details all of the instructions supported by the LCD (for advanced users). Many instructions are multipurpose, depending on the state of special bits. Cleaver manipulation of the instruction bits will allow for powerful control of the LCD.

The last command shown above (Move To DRAM Address) is used to move the cursor to a specific position on the LCD. The LCD's DRAM (Display RAM) is a fixed size with unique position number for each character cell. The viewable portion of the DRAM depends on the LCD's logical view position (which can be altered with the Scroll Display command). The default view position is called the Home position; it means that the display's upper left character corresponds to DRAM location 0. Figure 5.13 indicates the position numbers for characters on the LCD screen.

Note that Figure 5.13 shows the most common DRAM mapping, though some LCD's may have organized the DRAM differently. A little experimentation with your LCD may reveal this.
Table 5.28: All LCD Commands (for advanced users). These are supported by LCDs with the Hitachi 44780 controller.

<table>
<thead>
<tr>
<th>Command Code (in binary)</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0 0 0 0 1</td>
<td>Clear entire display and move cursor home (address 0).</td>
</tr>
<tr>
<td>0 0 0 0 0 0 1 0</td>
<td>Move cursor home and return display to home position.</td>
</tr>
<tr>
<td>0 0 0 0 0 1 M S</td>
<td>Sets cursor direction (M: 0=left, 1=right) and display scrolling (S: 0=no scroll, 1=scroll)</td>
</tr>
<tr>
<td>0 0 0 0 1 D U B</td>
<td>Sets display on/off (D), underline cursor (U) and blinking block cursor (B). (0=off, 1=on)</td>
</tr>
<tr>
<td>0 0 0 1 C M 0 0</td>
<td>Shifts display or cursor (C: 0=cursor, 1=display) left or right (M: 0=left, 1=right).</td>
</tr>
<tr>
<td>0 0 1 B L F 0 0</td>
<td>Sets bus size (B: 0=4-bits, 1=8-bits), number of lines (L: 0=1-line, 1=2-lines) and font size (F: 0=5x8, 1=5x10)</td>
</tr>
<tr>
<td>0 1 A A A A A A</td>
<td>Move pointer to character RAM location specified by address (A)</td>
</tr>
<tr>
<td>1 A A A A A A A A</td>
<td>Move cursor to display RAM location specified by address (A)</td>
</tr>
</tbody>
</table>

On a standard 2 x 16 character display, the following command would move the cursor to the third column of the second line:

LCDCMD  1, 128 + 66

Figure 5.13: LCD Character Positions. NOTE: Many 1 x 16 displays conform to the position numbers shown on Line 1 of the 2 x 16 display.
The number 128 tells the LCD we wish to move the cursor and 66 is the location number of the desired position. Similarly, sending just 128 (128 + 0) would move the cursor to the first character of the first line (the upper left character if the display is at the home position).

You may have noticed that the 2 x 16 display has many locations that are not visible; they are to the right of the edge of the screen. These locations (16 – 39 and 80 to 103) become important for scrolling operations. For example, it is possible to move the cursor to location 16, print some text there and then issue a number of Scroll Left instructions (LCDCMD 1, 24) to slowly scroll the text onto the display from right to left. If you did so, the DRAM positions that were on the left of the screen would now be past the left edge of the screen. For example,

\[
\text{LCDCMD 1, 24}
\]
\[
\text{LCDCMD 1, 24}
\]

would cause the screen to scroll to the left by two characters. At this point, the upper-left character in the display would actually be DRAM location 2 and the lower-left character would be DRAM location 66. Locations 0, 1, 64 and 65 would be off the left edge of the LCD and would no longer be visible. Some interesting effects can be achieved by taking advantage of this feature.

The 4 x 20 LCD has a strange DRAM map. The upper-right character is location 19 and the next location, 20, appears as the first character of the third line. This strange mapping is due to constraints in the LCD controller and the manufacturer’s design, and unfortunately makes the scrolling features virtually useless on the 4 x 20 displays.

Even though the LCD requires many pins to talk to it, only the Enable pin needs to remain dedicated to the LCD and all the other pins can be multiplexed (shared) with certain other devices (if wired carefully). In addition, the I/O pin connected to the LCD’s R/W pin is only necessary if the LCDIN command will be used in the application. If the LCDIN command will not be used, LCD pin 5 (R/W pin) can be connected to ground and I/O pin 2 (shown above) may be left disconnected. I/O pin 2 will still be set to output mode for each LCDCMD and LCDOUT command executed, however.
Demo Program (LCDINIT.bsp)

'This program demonstrates initialization and printing on a 2 x 16 character LCD display. The set of "LCD constants", below, are provided as pre-defined and useful LCD commands, though only a few are actually used in this program.

'{$STAMP  BS2p}   'STAMP directive (specifies a BS2p)

'-----Define LCD constants-----
WakeUp  CON  %00110000   'Wake-up
FourBitMode CON  %00100000 'Set to 4-bit mode
OneLine5x8Font CON  %00100000 'Set to 1 display line, 5x8 font
OneLine5x10Font CON  %00100100 'Set to 1 display line, 5x10 font
TwoLine5x8Font CON  %00101000   'Set to 2 display lines, 5x8 font
TwoLine5x10Font CON  %00101100 'Set to 2 display lines, 5x10 font
DisplayOff CON  %00001000   'Turn off display, data is retained
DisplayOn CON  %00001100   'Turn on display, no cursor
DisplayOnULCrsr CON  %00001110 'Turn on display, with underline cursor
DisplayOnBLCrsr CON  %00001101 'Turn on display, with blinking cursor
IncCrsr CON  %00000110   'Auto-increment cursor, no display shift
IncCrsrShift CON  %00000111 'Auto-increment cursor, shift display left
DecCrsr CON  %00000100 'Auto-decrement cursor, no display shift
DecCrsrShift CON  %00000101 'Auto-decrement cursor, shift display right
ClearDisplay CON  %00000001 'Clear the display
HomeController CON  %00000100 'Move cursor and display to home position
ScrollLeft CON  %00001000 'Scroll display to the left
ScrollRight CON  %00001100 'Scroll display to the right
CrsrLeft CON  %00001000 'Move cursor left
CrsrRight CON  %00001100 'Move cursor right
MoveCrsr CON  %001100000 'Move cursor to position (must add address)
MoveToCGRAM CON  %00000000 'Move to CGRAM position (must add address)

'-----Main Routines-----
Init:
   PAUSE  1000
   GOSUB  InitLCD

Start:
   LCDOUT  1, ClearDisplay, ["Hello World!"]
   LCDOUT  1, MoveCrsr+64, ["How are you?"]
STOP

'-----Subroutines-----
InitLCD:
   LCDCMD  1, WakeUp   'Send wakeup sequence to LCD
   PAUSE  10
   LCDCMD  1, WakeUp   'These pauses are necessary to meet the LCD specs
   PAUSE  1
   LCDCMD  1, WakeUp
   PAUSE  1

BASIC Stamp Programming  Manual 2.0c  www.parallaxinc.com  Page 165
<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>LCDCMD 1, FourBitMode</td>
<td>'Set bus to 4-bit mode</td>
</tr>
<tr>
<td>LCDCMD 1, TwoLine5x8Font</td>
<td>'Set to 2-line mode with 5x8 font</td>
</tr>
<tr>
<td>LCDCMD 1, DisplayOff</td>
<td>'Turn display off</td>
</tr>
<tr>
<td>LCDCMD 1, DisplayOn</td>
<td>'Turn display on with blinking cursor</td>
</tr>
<tr>
<td>LCDCMD 1, IncCrsr</td>
<td>'Set to auto-increment cursor (no display shift)</td>
</tr>
<tr>
<td>LCDCMD 1, ClearDisplay</td>
<td>'Clear the display</td>
</tr>
<tr>
<td>RETURN</td>
<td></td>
</tr>
</tbody>
</table>
5: BASIC Stamp Command Reference – LCDIN

**LCDIN**

BS1 | BS2 | BS2e | BS2sx | BS2p
---|---|---|---|---

**Function**

Receive data from an LCD display.

- **Pin** is a variable/constant/expression (0 – 1 or 8 – 9) that specifies which I/O pins to use. The LCD requires, at most, seven I/O pins to operate. The Pin argument serves a double purpose; specifying the first pin and, indirectly, the group of other required pins. See explanation below. All I/O pins will be set to output mode initially and the upper I/O pins (4 – 7 or 12 – 15) will be set to input mode by the end of the LCDIN command.

- **Command** is a variable/constant/expression (0 – 255) indicating the LCD command to send.

- **InputData** is a list of variables and formatters that tells LCDIN what to do with incoming data. LCDIN can store data in a variable or array, interpret numeric text (decimal, binary, or hex) and store the corresponding value in a variable, wait for a fixed or variable sequence of bytes, or ignore a specified number of bytes. These actions can be combined in any order in the InputData list.

**Quick Facts**

<table>
<thead>
<tr>
<th>BS2p</th>
<th>Values for Pin</th>
<th>I/O pin arrangement when Pin is</th>
<th>I/O pin arrangement when Pin is</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>0, 1, 8 or 9</td>
<td>0 or 1 (depending on pin): LCD Enable (E) pin</td>
<td>8 or 9 (depending on pin): LCD Enable (E) pin</td>
</tr>
<tr>
<td></td>
<td></td>
<td>2: LCD Read/Write (R/W) pin</td>
<td>10: LCD Read/Write (R/W) pin</td>
</tr>
<tr>
<td></td>
<td></td>
<td>3: LCD Register Select (RS) pin</td>
<td>11: LCD Register Select (RS) pin</td>
</tr>
<tr>
<td></td>
<td></td>
<td>4 – 7: LCD Data Buss (DB4 – DB7, respectively) pins</td>
<td>12 – 15: LCD Data Buss (DB4 – DB7, respectively) pins</td>
</tr>
</tbody>
</table>

**Explanation**

The three LCD commands (LCDCMD, LCDIN and LCDOUT) allow the BS2p to interface directly to standard LCD displays that feature a Hitachi 44780 controller (part #HD44780A). This includes many 1 x 16, 2 x 16 and 4 x 20 character LCD displays.
The LCDIN command is used to send one instruction and then receive at least one data byte from the LCD's Character RAM or Display RAM. The following is an example of the LCDIN command:

Char  VAR  BYTE 
LCDIN  1, 128, [Char] 

The above code will read the character value at location 0 of the DRAM. See the "Character Positioning" section, below, for more information.

The LCDIN command actually uses more than just the I/O pin specified by the Pin argument. The LCDIN command requires seven I/O pins. This is because the standard LCD displays have a parallel interface, rather than a serial one. The Pin argument can be the numbers 0, 1, 8 or 9 and will result in the use of the I/O pins shown in Table 5.29. Please refer to the LCDCMD command description for information on properly wiring the LCD display.

When the LCD is first powered-up, it will be in an unknown state and must be properly configured before sending commands like the one shown above. This process is known as initializing the LCD and is the first thing your program should do upon starting up. Please refer to the LCDCMD command description for information on properly initializing the LCD display.

The LCDIN command's InputData argument is similar to the SERIN command's InputData argument. This means data can be received as ASCII character values, decimal, hexadecimal and binary translations and string data as in the examples below (assume the LCD display has "Value: 3A:101" starting at the first character of the first line on the screen).

Value  VAR  BYTE(13) 
LCDIN  1, 128, [Value]  'receive the ASCII value for "V"
LCDIN  1, 128, [DEC Value]  'receive the number 3.
LCDIN  1, 128, [HEX Value]  'receive the number $3A.
LCDIN  1, 128, [BIN Value]  'receive the number %101.
LCDIN  1, 128, [STR Value\13]  'receive the string "Value: 3A:101"

Tables 5.30 and 5.31 list all the available conversion formatters and special formatters available to the LCDIN command. See the SERIN command for additional information and examples of their use.
Some possible uses of the LCDIN command are 1) in combination with the LCDOUT command to store and read data from the unused DRAM or CRAM locations (as extra variable space), 2) to verify that the data from a previous LCDOUT command was received and processed properly by the LCD, and 3) to read character data from CRAM for the purposes of modifying it and storing it as a custom character.

<table>
<thead>
<tr>
<th>Conversion Formatter</th>
<th>Type of Number</th>
<th>Numeric Characters Accepted</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>DEC{1..5}</td>
<td>Decimal, optionally limited to 1 – 5 digits</td>
<td>0 through 9</td>
<td>1</td>
</tr>
<tr>
<td>SDEC{1..5}</td>
<td>Signed decimal, optionally limited to 1 – 5 digits</td>
<td>-, 0 through 9</td>
<td>1,2</td>
</tr>
<tr>
<td>HEX{1..4}</td>
<td>Hexadecimal, optionally limited to 1 – 4 digits</td>
<td>0 through 9, A through F</td>
<td>1,3</td>
</tr>
<tr>
<td>SHEX{1..4}</td>
<td>Signed hexadecimal, optionally limited to 1 – 4 digits</td>
<td>-, 0 through 9, A through F</td>
<td>1,2,3</td>
</tr>
<tr>
<td>IHEX{1..4}</td>
<td>Indicated hexadecimal, optionally limited to 1 – 4 digits</td>
<td>$, 0 through 9, A through F</td>
<td>1,3,4</td>
</tr>
<tr>
<td>ISHEX{1..4}</td>
<td>Signed, indicated hexadecimal, optionally limited to 1 – 4 digits</td>
<td>-, $, 0 through 9, A through F</td>
<td>1,2,3,4</td>
</tr>
<tr>
<td>BIN{1..16}</td>
<td>Binary, optionally limited to 1 – 16 digits</td>
<td>0, 1</td>
<td>1</td>
</tr>
<tr>
<td>SBIN{1..16}</td>
<td>Signed binary, optionally limited to 1 – 16 digits</td>
<td>-, 0, 1</td>
<td>1,2</td>
</tr>
<tr>
<td>IBIN{1..16}</td>
<td>Indicated binary, optionally limited to 1 – 16 digits</td>
<td>%, 0, 1</td>
<td>1,4</td>
</tr>
<tr>
<td>ISBIN{1..16}</td>
<td>Signed, indicated binary, optionally limited to 1 – 16 digits</td>
<td>-, %, 0, 1</td>
<td>1,2,4</td>
</tr>
</tbody>
</table>

1 All numeric conversions will continue to accept new data until receiving either the specified number of digits (ex: three digits for DEC3) or a non-numeric character.
2 To be recognized as part of a number, the minus sign (⁻) must immediately precede a numeric character. The minus sign character occurring in non-numeric text is ignored and any character (including a space) between a minus and a number causes the minus to be ignored.
3 The hexadecimal formatters are not case-sensitive; “a” through “f” means the same as “A” through “F”.
4 Indicated hexadecimal and binary formatters ignore all characters, even valid numerics, until they receive the appropriate prefix ($ for hexadecimal, % for binary). The indicated formatters can differentiate between text and hexadecimal (ex: ABC would be interpreted by HEX as a number but IHEX would ignore it unless expressed as $ABC). Likewise, the binary version can distinguish the decimal number 10 from the binary number %10. A prefix occurring in non-numeric text is ignored, and any character (including a space) between a prefix and a number causes the prefix to be ignored. Indicated, signed formatters require that the minus sign come before the prefix, as in -$1B45.
**Special Formatter** | **Action**
---|---
STR ByteArray \L {E} | Input a character string of length L into an array. If specified, an end character E causes the string input to end before reaching length L. Remaining bytes are filled with 0s (zeros).
WAITSTR ByteArray \L | Wait for a sequence of bytes matching a string stored in an array variable, optionally limited to L characters. If the optional L argument is left off, the end of the array-string must be marked by a byte containing a zero (0).
SKIP Length | Ignore Length bytes of characters.

### Demo Program (LCDIN.bsp)
```
' This program demonstrates initialization, printing and reading from a 2 x 16 character LCD display.
' STAMP directive (specifies a BS2p)
Char VAR BYTE(16) 'Variable for holding text read from LCD

Init:
  LCDCMD 1,48 'Send wakeup sequence to LCD
  PAUSE 10 'These pauses are necessary to meet the LCD specs
  LCDCMD 1,48
  PAUSE 1
  LCDCMD 1,48
  PAUSE 1
  LCDCMD 1,32 'Set buss to 4-bit mode
  LCDCMD 1,40 'Set to 2-line mode with 5x8 font
  LCDCMD 1,8 'Turn display off
  LCDCMD 1,12 'Turn display on with blinking cursor
  LCDCMD 1,6 'Set to auto-increment cursor (no display shift)

Start:
  LCDOUT 1,1,["Hello!"]
  GOSUB ReadLCDScreen
  PAUSE 3000
  LCDOUT 1,1,["I'm a 2x16 LCD!"]
  GOSUB ReadLCDScreen
  PAUSE 3000
  GOTO Start

ReadLCDScreen:
  DEBUG "LCD Now Says: 
  LCDIN 1,128,[STR Char\16]
  DEBUG STR Char\16,CR,CR
  RETURN
```
5: BASIC Stamp Command Reference – LCDOUT

**LCDOUT**

Pin, Command, [OutputData]

Function
Send data to an LCD display.

- **Pin** is a variable/constant/expression (0 – 1 or 8 – 9) that specifies which I/O pins to use. The LCD requires, at most, seven I/O pins to operate. The Pin argument serves a double purpose; specifying the first pin and, indirectly, the group of other required pins. See explanation below. All I/O pins will be set to output mode initially and the upper I/O pins (4 – 7 or 12 – 15) will be set to input mode by the end of the LCDIN command.

- **Command** is a variable/constant/expression (0 – 255) indicating an LCD command to send.

- **OutputData** is a list of variables, constants, expressions and formatters that tells LCDOUT how to format outgoing data. LCDOUT can transmit individual or repeating bytes, convert values into decimal, hex or binary text representations, or transmit strings of bytes from variable arrays. These actions can be combined in any order in the OutputData list.

**Quick Facts**

<table>
<thead>
<tr>
<th>BS2p</th>
<th>BS1</th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
</tr>
</thead>
<tbody>
<tr>
<td>LCDOUT values for Pin</td>
<td>0, 1, 8 or 9</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>I/O pin arrangement when Pin is 0 or 1</td>
<td>0 or 1 (depending on pin): LCD Enable (E) pin</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>2: LCD Read/Write (R/W) pin</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>3: LCD Register Select (RS) pin</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>4 – 7: LCD Data Buss (DB4 – DB7, respectively) pins</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>I/O pin arrangement when Pin is 8 or 9</td>
<td>8 or 9 (depending on pin): LCD Enable (E) pin</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>10: LCD Read/Write (R/W) pin</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>11: LCD Register Select (RS) pin</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>12 – 15: LCD Data Buss (DB4 – DB7, respectively) pins</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Special notes</td>
<td>LCDOUT is designed to use the LCD's 4-bit mode only.</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Explanation**

The three LCD commands (LCDCMD, LCDIN and LCDOUT) allow the BS2p to interface directly to standard LCD displays that feature a Hitachi 44780 controller (part #HD44780A). This includes many 1 x 16, 2 x 16 and 4 x 20 character LCD displays.

The LCDOUT command is used to send one instruction followed by at least one data byte to the LCD. The data that is output is written to the

---

**A simple LCDOUT example.**

The LCDOUT command is used to send one instruction followed by at least one data byte to the LCD. The data that is output is written to the
LCDOUT is a command used to send data to LCD displays. It requires specifying the LCD's Character RAM or Display RAM. An example usage is:

```
LCDOUT 1, 1, ["Hello World!"]
```

This code will clear the LCD screen and then send "Hello World!" to the screen. The first argument (1) is the starting I/O pin number and the second argument (also 1) is the LCD's instruction for Clear Screen.

The LCDOUT command actually uses more than just the I/O pin specified by the Pin argument. The LCDOUT command requires seven I/O pins. This is because the standard LCD displays have a parallel interface, rather than a serial one. The Pin argument can be the numbers 0, 1, 8 or 9 and will result in the use of the I/O pins shown in Table 5.32. Please refer to the LCDCMD command description for information on properly wiring the LCD display.

When the LCD is first powered-up, it will be in an unknown state and must be properly configured before sending commands like the one shown above. This process is known as initializing the LCD and is the first thing your program should do upon starting up. Please refer to the LCDCMD command description for information on properly initializing the LCD display.

The LCDOUT command's OutputData argument is exactly like that of the DEBUG and SEROUT command's OutputData argument. This means data can be sent as literal text, ASCII character values, repetitive values, decimal, hexadecimal and binary translations and string data as in the examples below.

```
Value   VAR    BYTE
Value  =  65
LCDOUT 1, 0, [Value]  'send the ASCII value for "A"
LCDOUT 1, 0, [REP Value5] 'send the ASCII value for "A" five time, ie: "AAAAA"
LCDOUT 1, 0, [DEC Value] 'send two characters, "6" and "5"
LCDOUT 1, 0, [HEX Value] 'send two characters, "4" and "1"
LCDOUT 1, 0, [BIN Value] 'send seven characters, "1000001"
```

Tables 5.33 and 5.34 list all the available conversion formatters and special formatters available to the LCDOUT command. See the DEBUG and SEROUT commands for additional information and examples of their use.

Two very important steps:
1) Wiring the BS2P to an LCD.
2) Initializing the LCD.
## Table 5.33: LCDOUT Conversion Formatters.

<table>
<thead>
<tr>
<th>Conversion Formatter</th>
<th>Type of Number</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>DEC{1..5}</td>
<td>Decimal, optionally fixed to 1 – 5 digits</td>
<td>1</td>
</tr>
<tr>
<td>SDEC{1..5}</td>
<td>Signed decimal, optionally fixed to 1 – 5 digits</td>
<td>1,2</td>
</tr>
<tr>
<td>HEX{1..4}</td>
<td>Hexadecimal, optionally fixed to 1 – 4 digits</td>
<td>1</td>
</tr>
<tr>
<td>SHEX{1..4}</td>
<td>Signed hexadecimal, optionally fixed to 1 – 4 digits</td>
<td>1,2</td>
</tr>
<tr>
<td>IHEX{1..4}</td>
<td>Indicated hexadecimal, optionally fixed to 1 – 4</td>
<td>1</td>
</tr>
<tr>
<td>ISHEX{1..4}</td>
<td>Signed, indicated hexadecimal, optionally fixed to 1 – 4 digits</td>
<td>1,2</td>
</tr>
<tr>
<td>BIN{1..16}</td>
<td>Binary, optionally fixed to 1 – 16 digits</td>
<td>1</td>
</tr>
<tr>
<td>SBIN{1..16}</td>
<td>Signed binary, optionally fixed to 1 – 16 digits</td>
<td>1,2</td>
</tr>
<tr>
<td>IBIN{1..16}</td>
<td>Indicated binary, optionally fixed to 1 – 16 digits</td>
<td>1</td>
</tr>
<tr>
<td>ISBIN{1..16}</td>
<td>Signed, indicated binary, optionally fixed to 1 – 16 digits</td>
<td>1,2</td>
</tr>
</tbody>
</table>

1 Fixed-digit formatters like DEC4 will pad the number with leading 0s if necessary; ex: DEC4 65 sends 0065. If a number is larger than the specified number of digits, the leading digits will be dropped; ex: DEC4 56422 sends 6422.
2 Signed modifiers work under two's complement rules.

## Table 5.34: LCDOUT Special Formatters.

<table>
<thead>
<tr>
<th>Special Formatter</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>?</td>
<td>Displays &quot;symbol = x' + carriage return; where x is a number. Default format is decimal, but may be combined with conversion formatters (ex: BIN ? x to display &quot;x = binary_number&quot;).</td>
</tr>
<tr>
<td>ASC ?</td>
<td>Displays &quot;symbol = 'x'&quot; + carriage return; where x is an ASCII character.</td>
</tr>
<tr>
<td>STR ByteArray {L}</td>
<td>Send character string from an array. The optional \L argument can be used to limit the output to L characters, otherwise, characters will be sent up to the first byte equal to 0 or the end of RAM space is reached.</td>
</tr>
<tr>
<td>REP Byte \L</td>
<td>Send a string consisting of Byte repeated L times (ex: REP &quot;X&quot;\10 sends &quot;XXXXXXXXXX&quot;).</td>
</tr>
</tbody>
</table>

### Using the Command Argument.

The **Command** argument is useful for proceeding a set of data with a special LCD instruction. For example, the code below will move the cursor to location 64 (the first character on the second line) and print "Hi":

```
LCDOUT 1, 128 + 64, ["Hi"]
```

The next example, below, will turn on the blinking block cursor and print "Yo!":

```
LCDOUT 1, 13, ["Yo!"]
```

Occasionally, you will want to send data without preceding it with a command. To do this, simply use 0 for the **Command** argument, as in:

```
LCDOUT 1, 0, ["Hello there!"]
```
Another use for the LCDOUT command is to access and create custom characters. The Hitachi 44780 controller has a built-in character set that is similar to the ASCII character set (at least for the first 128 characters). Most of these characters are stored in ROM and are not changeable, however, the first eight characters (ASCII 0 through 7) are programmable.

Each of the programmable characters is five pixels wide and eight pixels tall. It takes eight bytes to describe each character; one byte per row (the left-most three bits are ignored). For example, the character at ASCII location 0 is defined by the bit patterns stored in bytes 0 through 7 of Character RAM (CRAM). The character at ASCII location 1 is defined by the bit patterns stored in bytes 8 through 15 of CRAM, and so on.

To create a custom character, use some graph paper to plot out the bit pattern (on and off pixels) in a 5 x 8 pattern, as shown in Figure 5.14. Then calculate the corresponding binary value of the bit pattern for each of the eight rows of character data.

<table>
<thead>
<tr>
<th>Character Cell Structure and Data</th>
</tr>
</thead>
<tbody>
<tr>
<td>Byte 0:</td>
</tr>
<tr>
<td>---</td>
</tr>
<tr>
<td>[ ]</td>
</tr>
<tr>
<td>[ ]</td>
</tr>
<tr>
<td>[ ]</td>
</tr>
<tr>
<td>[ ]</td>
</tr>
<tr>
<td>[ ]</td>
</tr>
<tr>
<td>[ ]</td>
</tr>
<tr>
<td>[ ]</td>
</tr>
<tr>
<td>[ ]</td>
</tr>
</tbody>
</table>

After the data is calculated for each character (8 byte values per character), use the LCDOUT command with the "Move To CRAM Address" instruction to insert the data into the character's CRAM locations. For example, the code below will store the character shown in Figure 5.14 into character 0's CRAM data locations. Then it will place the cursor back on the display (DRAM) and print the character on the screen.

```
LCDOUT 1, 64+0, [00, 10, 00, 04, 17, 14, 00, 00]
LCDOUT 1, 128+0, ["Custom Char: ", 0]
```

The number 64 in the Command argument is the LCD's "Move to CRAM Address" instruction and the 0 that is added to it is the location of the first
row of data for the character 0. The LCDOUT command will write the first OutputData value (00) to this location, the second OutputData value (10) to location 1, etc. If we wanted this custom character to affect character 1, instead of 0, we’d have to adjust value of the "Move To..." command, ie: 64+8. To affect character 2, we’d use 64+16.

To try the example above, don’t forget to execute the LCD initialization code (shown in the LCDCMD description) first and never forget to move the cursor back to the screen (as with the last command, above) when you’re done writing the character data to CRAM.

---

**Demo Program (LCDOUT.bsp)**

' This program demonstrates initialization and printing on a 2 x 16 character LCD display.
' This is a modified version of the LCDINIT.bsp program.
'{$STAMP BS2p}   'STAMP directive (specifies a BS2p)

'-----Define LCD constants-----
WakeUp        CON %00110000  'Wake-up
FourBitMode   CON %00100000  'Set to 4-bit mode
TwoLine5x8Font CON %00101000  'Set to 2 display lines, 5x8 font
DisplayOff    CON %00001000  'Turn off display, data is retained
DisplayOn     CON %00001100  'Turn on display, no cursor
IncCrsr       CON %00000110  'Auto-increment cursor, no display shift
ClearDisplay  CON %00000001  'Clear the display
MoveCrsr      CON %10000000  'Move cursor to position (must add address)

'-----Main Routines-----
Init:
    PAUSE  1000
    GOSUB  InitLCD

Start:
    LCDOUT  1, ClearDisplay, ["Hello my friend."]
    PAUSE  1000
    LCDOUT  1, MoveCrsr+64, ["How are you?"]
    PAUSE  3000
    LCDCMD  1, ClearDisplay
    LCDOUT  1, MoveCrsr+1, ["I'm doing just"]
    LCDOUT  1, MoveCrsr+70, ["fine!"]
    PAUSE  3000
    GOTO  Start

'-----Subroutines-----
InitLCD:
    LCDCMD  1, WakeUp        'Send wakeup sequence to LCD
    PAUSE  10
    LCDCMD  1, WakeUp        'These pauses are necessary to meet the LCD specs
    PAUSE  1
<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>LCDCMD 1, WakeUp</td>
<td>'Set buss to 4-bit mode</td>
</tr>
<tr>
<td>PAUSE 1</td>
<td></td>
</tr>
<tr>
<td>LCDCMD 1, FourBitMode</td>
<td>'Set to 2-line mode with 5x8 font</td>
</tr>
<tr>
<td>LCDCMD 1, TwoLine5x8Font</td>
<td>'Turn display off</td>
</tr>
<tr>
<td>LCDCMD 1, DisplayOff</td>
<td>'Turn display on with blinking cursor</td>
</tr>
<tr>
<td>LCDCMD 1, DisplayOn</td>
<td>'Set to auto-increment cursor (no display shift)</td>
</tr>
<tr>
<td>LCDCMD 1, IncCrsr</td>
<td>'Clear the display</td>
</tr>
<tr>
<td>LCDCMD 1, ClearDisplay</td>
<td></td>
</tr>
</tbody>
</table>

RETURN
### LOOKDOWN

**BS1** | **BS2** | **BS2e** | **BS2sx** | **BS2p**
---|---|---|---|---

**LOOKDOWN**

**Function**

Compare **Target** value to a list of values and store the index number of the first value that matches into **Variable**. If no value in the list matches, **Variable** is left unaffected. On the BS2, BS2e, BS2sx and BS2p, the optional **ComparisonOp** is used as criteria for the match; the default criteria is "equal to."

- **Target** is a variable/constant/expression (0 – 65535) to be compared to the values in the list.
- **ComparisonOp** is an optional comparison operator (as described in Table 5.36) to be used as the criteria when comparing values. When no **ComparisonOp** is specified, equal to (=) is assumed. This argument is not available on the BS1.
- **Values** are variables/constants/expressions (0 – 65535) to be compared to **Target**.
- **Variable** is a variable (usually a byte) that will be set to the index (0 – 255) of the matching value in the **Values** list. If no matching value is found, **Variable** is left unaffected.

#### Quick Facts

<table>
<thead>
<tr>
<th>Limit of value entries</th>
<th>BS1, BS2, BS2e, BS2sx and BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>256</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Starting index number</th>
<th>BS1, BS2, BS2e, BS2sx and BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>If value list contains no match...</th>
<th>BS1, BS2, BS2e, BS2sx and BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Variable is left unaffected</td>
<td></td>
</tr>
</tbody>
</table>

#### Explanation

LOOKDOWN works like the index in a book. In an index, you search for a topic and get the page number. LOOKDOWN searches for a target value in a list, and stores the index number of the first match in a variable. For example:

---

**NOTE:** Expressions are not allowed as arguments on the BS1.

---

**Table 5.35:** LOOKDOWN Quick Facts.
LOOKDOWN - BASIC Stamp Command Reference

SYMBOL  Value  =  B0
SYMBOL  Result  =  B1
Value  =  17
Result  =  15

LOOKDOWN  Value, (26, 177, 13, 1, 0, 17, 99), Result
DEBUG  "Value matches item ", #Result, " in list"

-- or --

Value  VAR  BYTE
Result  VAR  NIB
Value  =  17
Result  =  15

LOOKDOWN  Value, [26, 177, 13, 1, 0, 17, 99], Result
DEBUG  "Value matches item ", DEC  Result, " in list"

DEBUG prints, "Value matches item 5 in list" because the value (17) matches item 5 of [26, 177, 13, 1, 0, 17, 99]. Note that index numbers count up from 0, not 1; that is, in this list, 26 is item 0.

What happens if the value doesn’t match any of the items in the list? Try changing “Value = 17” to “Value = 2.” Since 2 is not on the list, LOOKDOWN leaves Result unaffected. Since Result contained 15 before LOOKDOWN executed, DEBUG prints “Value matches item 15 in list.” By strategically setting the initial value of Result, as we have here, your program can be written to detect when an item was not found in the list.

Don’t forget that text phrases are just lists of byte values, so they too are eligible for LOOKDOWN searches, as in this example:

SYMBOL  Value  =  B0
SYMBOL  Result  =  B1
Value  =  "f"
Result  =  255

LOOKDOWN  Value, ("The quick brown fox"), Result
DEBUG  "Value matches item ", #Result, " in list"

-- or --

Value  VAR  BYTE
Result  VAR  NIB
Value  =  "f"
Result  =  255
LOOKDOWN Value, ["The quick brown fox"], Result  
DEBUG "Value matches item ", DEC Result, " in list"

DEBUG prints, “Value matches item 16 in list” because the character at  
index item 16 is "f" in the phrase, “The quick brown fox”.

The examples above show LOOKDOWN working with lists of constants,  
but it also works with variables and expressions also. Note, however, that  
expressions are not allowed as argument on the BS1.

On the BS2, BS2e, BS2sx and BS2p, the LOOKDOWN command can also  
use another criteria (other than "equal to") for its list. All of the examples  
above use LOOKDOWN’s default comparison operator, =, that searches  
for an exact match. The entire list of ComparisonOps is shown in Table 5.36.  
The "greater than" comparison operator (>) is used in the following  
example:

```
Value VAR BYTE
Result VAR NIB
Value = 17
Result = 15

LOOKDOWN Value, >[26, 177, 13, 1, 0, 17, 99], Result  
DEBUG "Value greater than item ", DEC Result, " in list"
```

DEBUG prints, “Value greater than item 2 in list” because the first item the  
value 17 is greater than is 13 (which is item 2 in the list). Value is also  
greater than items 3 and 4, but these are ignored, because LOOKDOWN  
only cares about the first item that matches the criteria. This can require a  
certain amount of planning in devising the order of the list. See the demo  
program below.

LOOKDOWN comparison operators use unsigned 16-bit math. They will  
not work correctly with signed numbers, which are represented internally  
as two’s complement (large 16-bit integers). For example, the two’s  
complement representation of -99 is 65437. So although -99 is certainly  
less than 0, it would appear to be larger than zero to the LOOKDOWN  
comparison operators. The bottom line is: Don’t used signed numbers  
with LOOKDOWN comparisons.
A common application for LOOKDOWN is to use it in conjunction with the BRANCH command to create selective jumps based on a simple variable input:

```
Cmd    VAR   BYTE
Cmd = "M"
LOOKDOWN Cmd, ["SLMH"], Cmd
BRANCH Cmd, [_Stop, _Low, _Medium, _High]
DEBUG "Command not in list"
END

_Stop: DEBUG "stop"
END

_Low: DEBUG "low"
END

_Medium: DEBUG "medium"
END

_High: DEBUG "high"
END
```

In this example, `Cmd` contains "M" (ASCII 77). LOOKDOWN finds that this is item 2 of a list of one-character commands and stores 2 into `Cmd`. BRANCH then goes to item 2 of its list, which is the program label "_Medium" at which point DEBUG prints "medium" on the PC screen. This is a powerful method for interpreting user input, and a lot neater than the alternative IF...THEN instructions.

Another great use of LOOKDOWN is in combination with LOOKUP to "map" non-contiguous sets of numbers together. For example, you may have an application where certain numbers are received by the BASIC Stamp and, in response, the BASIC Stamp needs to send a specific set of numbers. This may be easy to code if the numbers are contiguous, or follow some know algebraic equations… but what if they don’t? The table

<table>
<thead>
<tr>
<th>ComparisonOp Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>=</td>
<td>Find the first value Target is equal to</td>
</tr>
<tr>
<td>&lt;&gt;</td>
<td>Find the first value Target is not equal to</td>
</tr>
<tr>
<td>&gt;</td>
<td>Find the first value Target is greater than</td>
</tr>
<tr>
<td>&lt;</td>
<td>Find the first value Target is less than</td>
</tr>
<tr>
<td>&gt;=</td>
<td>Find the first value Target is greater than or equal to</td>
</tr>
<tr>
<td>&lt;=</td>
<td>Find the first value Target is less than or equal to</td>
</tr>
</tbody>
</table>

Table 5.36: LOOKDOWN Comparison Operators.
below shows some sample, non-contiguous inputs and the corresponding outputs the BASIC Stamp needs to respond with:

<table>
<thead>
<tr>
<th>Each of these values received (inputs):</th>
<th>Needs to result in each of these values sent (outputs):</th>
</tr>
</thead>
<tbody>
<tr>
<td>5</td>
<td>16</td>
</tr>
<tr>
<td>14</td>
<td>17</td>
</tr>
<tr>
<td>1</td>
<td>18</td>
</tr>
<tr>
<td>43</td>
<td>24</td>
</tr>
<tr>
<td>26</td>
<td>10</td>
</tr>
<tr>
<td>22</td>
<td>12</td>
</tr>
<tr>
<td>30</td>
<td>11</td>
</tr>
</tbody>
</table>

So, if we receive the number 5, we need to output 16. If we received 43, we need to output 24, and so on. These numbers are not contiguous and they don't appear to be derived from any simple algorithm. We can solve this problem with two lines of code, as follows:

LOOKDOWN Value, [5, 14, 1, 43, 26, 22, 30], Value
LOOKUP Value, [16, 17, 18, 24, 10, 12, 11], Value

Assuming our received number is in Value, the first line (LOOKDOWN) will find the value in the list and store the index of the location that matches back into Value. (This step "maps" the non-contiguous numbers: 5, 14, 1, etc, to a contiguous set of numbers: 0, 1, 2, etc). The second line (LOOKUP) takes our new Value, finds the number at that location and stores it back into Value. If the received value was 14, LOOKDOWN stores 1 into Value and LOOKUP looks at the value at location 1 and stores 17 in Value. The number 43 gets mapped to 3, 3 gets mapped to 24, and so on. This is a quick and easy fix for a potentially messy problem!
Demo Program (LOOKDOWN.bas)
' This program uses LOOKDOWN followed by LOOKUP to map the numbers:
' 0, 10, 50, 64, 71 and 98 to 35, 40, 58, 62, 79, and 83, respectively. All other
' numbers are mapped to 255.

'{$STAMP BS1}    'STAMP directive (specifies a BS1)

SYMBOL I = W0  ' Holds current number.
SYMBOL Result = W1  ' Holds mapped result.

FOR I = 0 TO 100
Result = 255    ' If no match in list, must be 0.
LOOKDOWN I, (0, 10, 50, 64, 71, 98), Result
LOOKUP Result, (35, 40, 58, 62, 79, 83), Result
DEBUG "I=", #I, "Result=", #Result, CR
PAUSE 100
NEXT

Demo Program (LOOKDOWN.bs2)
' This program uses LOOKDOWN to determine the number of decimal digits in a number.
' The reasoning is that numbers less than 10 have one digit; greater than or equal
' to 10 but less than 100 have two; greater than or equal to 100 but less than 1000
' have three; greater than or equal to 1000 but less than 10000 have four; and greater
' than or equal to 10000 but less than 65535 (the largest number we can represent in
' 16-bit math) have five. There are two loopholes that we have to plug: (1) The number
' 0 does not have zero digits, and (2) The number 65535 has five digits. To ensure that
' 0 is accorded one-digit status, we just put 0 at the beginning of the LOOKDOWN list.
' Since 0 is not less than 0, an input of 0 results in 1 as it should. At the other end
' of the scale, 65535 is not less than 65535, so LOOKDOWN will end without writing to the
' result variable, NumDig. To ensure that an input of 65535 returns 5 in NumDig, we just
' put 5 into numDig beforehand.

'{$STAMP BS2}    'STAMP directive (specifies a BS2)

I  VAR WORD  ' Variable (0-65535).
NumDig  VAR NIB  ' Variable (0-15) to hold # of digits.

FOR I = 0 TO 1000 STEP 8
NumDig = 5    ' If no ‘true’ in list, must be 65535.
LOOKDOWN I, <[0, 10, 100, 1000, 10000, 65535], NumDig
DEBUG "I=", REP " ", (5 – NumDig ), DEC I, TAB, "digits=", DEC NumDig, CR
PAUSE 100
NEXT

NOTE: This is written for the BS2
but can be used for the BS2e,
BS2sx and BS2p also. Locate the
proper source code file or modify
the STAMP directive before
downloading to the BS2e, BS2sx or
BS2p.
### LOOKUP

<table>
<thead>
<tr>
<th>BS1</th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
</table>

**Function**

Find the value at location `Index` and store it in `Variable`. If `Index` exceeds the highest index value of the items in the list, `Variable` is left unaffected.

- `Index` is a variable/constant/expression (0 – 255) indicating the list item to retrieve.
- `Values` are variables/constants/expressions (0 – 65535).
- `Variable` is a variable that will be set to the value at the `Index` location. If `Index` exceeds the highest location number, `Variable` is left unaffected.

**Quick Facts**

<table>
<thead>
<tr>
<th></th>
<th>BS1, BS2, BS2e, BS2sx and BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Limit of value entries</td>
<td>256</td>
</tr>
<tr>
<td>Starting index number</td>
<td>0</td>
</tr>
<tr>
<td>If index exceeds the highest location...</td>
<td>Variable is left unaffected</td>
</tr>
</tbody>
</table>

**Explanation**

LOOKUP retrieves an item from a list based on the item’s position, `Index`, in the list. For example:

```basic
SYMBOL Index = B0
SYMBOL Result = B1
Index = 3
Result = 255

LOOKUP Index, (26, 177, 13, 1, 0, 17, 99), Result
DEBUG "Item ", #Index, ": ", #Result
```

-- or --
LOOKUP - BASIC Stamp Command Reference

Index VAR NIB
Result VAR BYTE

Index = 3
Result = 255

LOOKUP Index, [26, 177, 13, 1, 0, 17, 99], Result
DEBUG "Item ", DEC Index, " is: ", DEC Result

In this example, DEBUG prints “Item 3 is: 1.” Note that the first location number is 0. In the list above, item 0 is 26, item 1 is 177, etc.

If Index is beyond the end of the list, the result variable is unchanged. In the example above, if index were greater than 6, the message would have reported the result to be 255, because that’s what Result contained before LOOKUP executed.

Don’t forget that text phrases are just lists of byte values, so they too are eligible for LOOKUP searches, as in this example:

SYMBOL Value = B0
SYMBOL Result = B1
Index = 16
Result = " "

LOOKUP Index, ("The quick brown fox"), Result
DEBUG @Result

-- or --

Index VAR BYTE
Result VAR NIB
Index = 16
Result = " "

LOOKUP Index, ["The quick brown fox"], Result
DEBUG ASC? Result

DEBUG prints, “Result = ‘f’” because the character at index item 16 is "f" in the phrase, “The quick brown fox”.

The examples above show LOOKUP working with lists of constants, but it also works with variables and expressions also. Note, however, that expressions are not allowed as argument on the BS1.
A great use of LOOKUP is in combination with LOOKDOWN to "map" non-contiguous sets of numbers together. For example, you may have an application where certain numbers are received by the BASIC Stamp and, in response, the BASIC Stamp needs to send a specific set of numbers. This may be easy to code if the numbers are contiguous, or follow some known algebraic equations... but what if they don't? The table below shows some sample, non-contiguous inputs and the corresponding outputs the BASIC Stamp needs to respond with:

<table>
<thead>
<tr>
<th>Each of these values received (inputs):</th>
<th>Needs to result in each of these values sent (outputs):</th>
</tr>
</thead>
<tbody>
<tr>
<td>5</td>
<td>16</td>
</tr>
<tr>
<td>14</td>
<td>17</td>
</tr>
<tr>
<td>1</td>
<td>18</td>
</tr>
<tr>
<td>43</td>
<td>24</td>
</tr>
<tr>
<td>26</td>
<td>10</td>
</tr>
<tr>
<td>22</td>
<td>12</td>
</tr>
<tr>
<td>30</td>
<td>11</td>
</tr>
</tbody>
</table>

So, if we receive the number 5, we need to output 16. If we received 43, we need to output 24, and so on. These numbers are not contiguous and they don't appear to be derived from any simple algorithm. We can solve this problem with two lines of code, as follows:

```basic
LOOKDOWN Value, [5, 14, 1, 43, 26, 22, 30], Value
LOOKUP Value, [16, 17, 18, 24, 10, 12, 11], Value
```

Assuming our received number is in `Value`, the first line (LOOKDOWN) will find the value in the list and store the index of the location that matches back into `Value`. (This step "maps" the non-contiguous numbers: 5, 14, 1, etc, to a contiguous set of numbers: 0, 1, 2, etc). The second line (LOOKUP) takes our new `Value`, finds the number at that location and stores it back into `Value`. If the received value was 14, LOOKDOWN stores 1 into `Value` and LOOKUP looks at the value at location 1 and stores 17 in `Value`. The number 43 gets mapped to 3, 3 gets mapped to 24, and so on. This is a quick and easy fix for a potentially messy problem!
Demo Program (LOOKDOWN.bas)

' This program uses Lookup to create a debug-window animation of a spinning propeller.
' The animation consists of the four ASCII characters | / - \ which, when printed rapidly
' in order at a fixed location, appear to spin. (A little imagination helps a lot here.)

'${STAMP BS1}    'STAMP directive (specifies a BS1)
SYMBOL    I = B0
SYMBOL    Frame = B1

Rotate:
FOR I = 0 TO 3
  LOOKUP I,("|/-\"),Frame
  DEBUG CLS, @Frame
  PAUSE 50
NEXT
GOTO Rotate

Demo Program (LOOKUP.bs2)

' This program uses Lookup to create a debug-window animation of a spinning propeller.
' The animation consists of the four ASCII characters | / - \ which, when printed rapidly
' in order at a fixed location, appear to spin. (A little imagination helps a lot here.)

'${STAMP BS2}    'STAMP directive (specifies a BS2)
I   VAR   NIB
Frame   VAR   BYTE

Rotate:
FOR I = 0 TO 3
  LOOKUP I,("|/-\"),Frame
  DEBUG HOME, Frame
  PAUSE 50
NEXT
GOTO Rotate

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, BS2sx or BS2p.
LOW

Function
Make the specified pin output low.

- Pin is a variable/constant/expression (0 – 15) that specifies which I/O pin to set low. This pin will be placed into output mode.

Explanation
The LOW command sets the specified pin to 0 (a 0 volt level) and then sets its mode to output. For example,

LOW 6

does exactly the same thing as:

OUT6 = 0
DIR6 = 1

Using the LOW command is faster, in this case.

Connect an LED and a resistor as shown in Figure 5.15 for the demo program below.

Figure 5.15: Example LED Circuit.
Demo Program (LOW.bs2)
' This simple program sets I/O pin 0 high for 1/2 second and low for 1/2 second
' in an endless loop.
'[$STAMP BS2]    'STAMP directive (specifies a BS2)
Loop:
  HIGH 0
  PAUSE 500
  LOW 0
  PAUSE 500
  GOTO Loop

NOTE: This is written for the BS2 but can be used for the BS1, BS2e, BS2sx and BS2p also. Locate the
proper source code file or modify the STAMP directive before downloading to the BS1, BS2e, BS2sx or BS2p.
5: BASIC Stamp Command Reference – MAINIO

**MAINIO**

Function

Switch from control of auxiliary I/O pins to main I/O pins (on the BS2p40 only).

**Quick Facts**

<table>
<thead>
<tr>
<th></th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>I/O pin IDs</td>
<td>0 – 15 (just like auxiliary I/O, but after MAINIO command, all references affect physical pins 5 – 20).</td>
</tr>
<tr>
<td>Special notes</td>
<td>Both the BS2p24 and the BS2p40 accept this command, however, only the BS2p40 gives access to the auxiliary I/O pins.</td>
</tr>
</tbody>
</table>

**Explanation**

The BS2p is available in two module styles, 1) a 24-pin module (called the BS2p24) that is pin compatible with the BS2, BS2e and BS2sx and 2) a 40-pin module (called the BS2p40) that has an additional 16 I/O pins (for a total of 32). The BS2p40's extra, or auxiliary, I/O pins can be accessed in the same manner as the main I/O pins (by using the IDs 0 to 15) but only after issuing a command called AUXIO or IOTERM. The MAINIO command causes the BASIC Stamp to affect the main I/O pins (the default) instead of the auxiliary I/O pins in all further code until the AUXIO or IOTERM command is reached, or the BASIC Stamp is reset or power-cycled.

**A SIMPLE MAINIO EXAMPLE.**

The following example illustrates this:

```
AUXIO
HIGH 0
MAINIO
LOW 0
```

The first line of the above example will tell the BASIC Stamp to affect the auxiliary I/O pins in the commands following it. Line 2, sets I/O pin 0 of the auxiliary I/O pins (physical pin 21) high. Afterward, the MAINIO command tells the BASIC Stamp that all commands following it should affect the main I/O pins. The last command, LOW, will set I/O pin 0 of the main I/O pins (physical pin 5) low.
Note that the main I/O and auxiliary I/O pins are independent of each other; the states of the main I/O pins remain unchanged while the program affects the auxiliary I/O pins, and vice versa.

Other commands that affect I/O group access are AUXIO and IOTERM.

**Demo Program (AUX_MAIN_TERM.bsp)**

' This program demonstrates the use of the AUXIO, MAINIO and IOTERM commands to ' affect I/O pins in the auxiliary and main I/O groups.

'${STAMP BS2p}   'STAMP directive (specifies a BS2p)

Port VAR BIT

Loop:
MAINIO   'Switch to main I/O pins
TOGGLE 0   'Toggle state of I/O pin 0 (physical pin 5)
PWM 1, 100, 40   'Generate PWM on I/O pin 1 (physical pin 6)

AUXIO   'Switch to auxiliary I/O pins
TOGGLE 0   'Toggle state of I/O pin 0 (physical pin 21)
PULSOUT 1, 1000   'Generate a pulse on I/O pin 1 (physical pin 22)
PWM 2, 100, 40   'Generate PWM on I/O pin 2 (physical pin 23)

IOTERM Port   'Switch to main or aux I/Os (depending on Port)
TOGGLE 3   'Toggle state of I/O pin 3 (on main and aux, alternately)
Port = ~Port   'Invert port (switch between 0 and 1)
PAUSE 1000
GOTO Loop
Function

Enter sleep mode for a short period. Power consumption is reduced as indicated in Table 5.41 assuming no loads are being driven.

- **Period** is a variable/constant/expression (0 – 7) that specifies the duration of the reduced-power nap. The duration is \(2^{\text{Period}} \times 18\) ms. Table 5.42 indicates the nap length for any given **Period**.

Quick Facts

<table>
<thead>
<tr>
<th>BS1</th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Current draw during run</td>
<td>2 mA</td>
<td>8 mA</td>
<td>25 mA</td>
<td>60 mA</td>
</tr>
<tr>
<td>Current draw during NAP</td>
<td>20 µA</td>
<td>40 µA</td>
<td>60 µA</td>
<td>60 µA</td>
</tr>
<tr>
<td>Accuracy of NAP</td>
<td>–50 to 100% (±10% @ 75°F with stable power supply)</td>
<td>–50 to 100% (±10% @ 75°F with stable power supply)</td>
<td>–50 to 100% (±10% @ 75°F with stable power supply)</td>
<td>–50 to 100% (±10% @ 75°F with stable power supply)</td>
</tr>
</tbody>
</table>

Explanation

NAP uses the same shutdown/startup mechanism as SLEEP, with one big difference. During SLEEP, the BASIC Stamp automatically compensates for variations in the speed of the watchdog timer oscillator that serves as its alarm clock. As a result, longer SLEEP intervals are accurate to approximately ±1 percent.

<table>
<thead>
<tr>
<th>Period</th>
<th>Length of Nap</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>18 ms</td>
</tr>
<tr>
<td>1</td>
<td>36 ms</td>
</tr>
<tr>
<td>2</td>
<td>72 ms</td>
</tr>
<tr>
<td>3</td>
<td>144 ms</td>
</tr>
<tr>
<td>4</td>
<td>288 ms</td>
</tr>
<tr>
<td>5</td>
<td>576 ms</td>
</tr>
<tr>
<td>6</td>
<td>1152 ms (1.152 seconds)</td>
</tr>
<tr>
<td>7</td>
<td>2304 ms (2.304 seconds)</td>
</tr>
</tbody>
</table>

NAP intervals are directly controlled by the watchdog timer without compensation. Variations in temperature, supply voltage, and manufacturing tolerance of the BASIC Stamp’s interpreter chip can cause...
the actual timing to vary by as much as –50, +100 percent (i.e., a Period of 0, NAP can range from 9 to 36 ms). At room temperature with a fresh battery or other stable power supply, variations in the length of a NAP will be less than ±10 percent.

One great use for NAP is in a battery-powered application where at least some small amount of time is spent doing nothing. For example, you may have a program that loops endlessly, performing some task, and pausing for approximately 100 ms each time through the loop. You could replace your PAUSE 100 with NAP 3, as long as the timing of the 100 ms pause was not critical. The NAP 3 would effectively pause your program for about 144 ms and, at the same time, would place the BASIC Stamp in low-power mode, which would extend your battery life.

If your application is driving loads (sourcing or sinking current through output-high or output-low pins) during a NAP, current will be interrupted for about 18 ms when the BASIC Stamp wakes up. The reason is that the watchdog-timer reset that awakens the BASIC Stamp also causes all of the pins to switch to input mode for approximately 18 ms. When the interpreter firmware regains control of the processor, it restores the I/O direction dictated by your program.

If you plan to use END, NAP, or SLEEP in your programs, make sure that your loads can tolerate these power outages. The simplest solution is often to connect resistors high or low (to +5V or ground) as appropriate to ensure a continuing supply of current during the reset glitch.

The demo program can be used to demonstrate the effects of the NAP glitch with an LED and resistor as shown in Figure 5.16.
The program below lights an LED by placing a low on pin 0. This completes the circuit from +5V, through the LED and resistor, to ground. During the NAP interval, the LED stays lit, but blinks off for a fraction of a second. This blink is caused by the NAP wakeup mechanism. During wakeup, all pins briefly slip into input mode, effectively disconnecting them from loads.

```
{STAMP BS2}    'STAMP directive (specifies a BS2)
LOW 0       ' Turn LED on.
Snooze:
    NAP 4   ' Nap for 288 ms.
GOTO Snooze
```

**Demo Program (NAP.bs2)**

Figure 5.16: Example LED Circuit.

**NOTE:** This is written for the BS2 but can be used for the BS1, BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS1, BS2e, BS2sx or BS2p.
## OUTPUT

<table>
<thead>
<tr>
<th>BS1</th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
</table>

### OUTPUT Pin

**Function**
Make the specified pin an output.

- **Pin** is a variable/constant/expression (0 – 15) that specifies which I/O pin to set to output mode.

### Explanation
There are several ways to make a pin an output. Commands that rely on output pins, like PULSOUT and SEROUT, automatically change the specified pin to output. Writing 1s to particular bits of the variable DIRS makes the corresponding pins outputs. And then there’s the OUTPUT command.

When a pin is an output, your program can change its state by writing to the corresponding bit in the OUTS variable (PINS on the BS1). For example:

```
OUTPUT 4
OUT4 = 1
```

When your program changes a pin from input to output, whatever state happens to be in the corresponding bit of OUTS (PINS on the BS1) sets the initial state of the pin. To simultaneously make a pin an output and set its state use the HIGH and LOW commands.

### Demo Program (INOUT.bas)

`' This program demonstrates how the input/output direction of a pin is determined by
' the corresponding bit of DIRS. It also shows that the state of the pin itself (as
' reflected by the corresponding bit of PINS) is determined by the outside world when
' the pin is an input, and by the corresponding bit of PINS when it's an output. To
' set up the demo, connect a 10k resistor from +5V to P7 on the BASIC Stamp. The
' resistor to +5V puts a high (1) on the pin when it's an input. The BASIC Stamp can
' override this state by writing a low (0) to bit 7 of OUTS and changing the pin to output.

'{$STAMP  BS1}    'STAMP directive (specifies a BS1)
INPUT 7      ' Make I/O pin 7 an input.
DEBUG "State of pin 7: ", #PIN7, CR
PIN7 = 0     ' Write 0 to output latch.
DEBUG "After 0 written to OUT7: ", #PIN7, CR
`
Demo Program (INPUT_OUTPUT.bs2)

' This program demonstrates how the input/output direction of a pin is determined by
' the corresponding bit of DIRS. It also shows that the state of the pin itself (as
' reflected by the corresponding bit of INS) is determined by the outside world when
' the pin is an input, and by the corresponding bit of OUTS when it's an output. To
' set up the demo, connect a 10k resistor from +5V to P7 on the BASIC Stamp. The
' resistor to +5V puts a high (1) on the pin when it's an input. The BASIC Stamp can
' override this state by writing a low (0) to bit 7 of OUTS and changing the pin to output.

'{$STAMP BS2}

INPUT 7      ' Make I/O pin 7 an input.
DEBUG "State of pin 7: ", BIN IN7, CR

OUT7 = 0     ' Write 0 to output latch.
DEBUG "After 0 written to OUT7: ", BIN IN7, CR

OUTPUT 7     ' Make I/O pin 7 an output.
DEBUG "After pin 7 changed to output: ", BIN IN7

NOTE: This is written for the BS2 but can be used for the BS2e,
BS2sx and BS2p also. Locate the proper source code file or modify
the STAMP directive before downloading to the BS2e, BS2sx or
BS2p.
5: BASIC Stamp Command Reference – OWIN

OWIN

Function
Receive data from a device using the 1-wire protocol.

- **Pin** is a variable/constant/expression (0 – 15) that specifies which I/O pin to use. 1-wire devices require only one I/O pin (called DQ) to communicate. This I/O pin will be toggled between output and input mode during the OWIN command and will be set to input mode by the end of the OWIN command.

- **Mode** is a variable/constant/expression (0 – 15) indicating the mode of data transfer. The *Mode* argument controls placement of reset pulses (and detection of presence pulses) as well as byte vs. bit input and normal vs. high speed. See explanation below.

- **InputData** is a list of variables and modifiers that tells OWIN what to do with incoming data. OWIN can store data in a variable or array, interpret numeric text (decimal, binary, or hex) and store the corresponding value in a variable, wait for a fixed or variable sequence of bytes, or ignore a specified number of bytes. These actions can be combined in any order in the *InputData* list.

Quick Facts

| BS2p | BS2sx BS2e BS2 | BS2 | BS1 |
|------|----------------|
| **Receive Rate** | Approximately 20 kbits/sec (low speed, not including reset pulse) |
| **Special notes** | The DQ pin (specified by *Pin*) must have a 4.7 KΩ pull-up resistor. |

**Table 5.43: OWIN Quick Facts.**

Explanation
The 1-wire protocol is a form of asynchronous serial communication developed by Dallas Semiconductor. It only requires one I/O pin and that pin can be shared between multiple 1-wire devices. The OWIN command allows the BASIC Stamp to receive data from a 1-wire device.

A SIMPLE OWIN EXAMPLE.

The following is an example of the OWIN command:

```
Result VAR BYTE
OWIN 0, 1, [Result]
```

This code will transmit a "reset" pulse to a 1-wire device (connected to I/O pin 0) and then will detect the device's "presence" pulse and then receive one byte and store it in the variable *Result.*
The \textit{Mode} argument is used to control placement of reset pulses (and detection of presence pulses) and to designate byte vs. bit input and normal vs. high speed. Figure 5.17 shows the meaning of each of the 4 bits of \textit{Mode}. Table 5.44 shows just some of the 16 possible values and their effect.

![Figure 5.17: Mode Format.](image)

<table>
<thead>
<tr>
<th>Mode</th>
<th>Effect</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>No Reset, Byte mode, Low speed</td>
</tr>
<tr>
<td>1</td>
<td>Reset before data, Byte mode, Low speed</td>
</tr>
<tr>
<td>2</td>
<td>Reset after data, Byte mode, Low speed</td>
</tr>
<tr>
<td>3</td>
<td>Reset before and after data, Byte mode, Low speed</td>
</tr>
<tr>
<td>4</td>
<td>No Reset, Bit mode, Low speed</td>
</tr>
<tr>
<td>5</td>
<td>Reset before data, Bit mode, Low speed</td>
</tr>
<tr>
<td>8</td>
<td>No Reset, Byte mode, High speed</td>
</tr>
<tr>
<td>9</td>
<td>Reset before data, Byte mode, High speed</td>
</tr>
</tbody>
</table>

The proper value for \textit{Mode} depends on the 1-wire device and the portion of the communication you're working on. Please consult the data sheet for the device in question to determine the correct value for \textit{Mode}. In many cases, however, when using the OWIN command, \textit{Mode} should be set for either No Reset (to receive data from a transaction already started by a OWOUT command) or a Back-End Reset (to terminate the session after data is received). This may vary due to device and application requirements, however.

When using the Bit (rather than Byte) mode of data transfer, all variables in the \textit{InputData} argument will only receive one bit. For example, the following code could be used to receive two bits using this mode:
FirstBit VAR BIT
SecondBit VAR BIT
OWIN 0, 6, [FirstBit, SecondBit]

In the code above, we chose the value "6" for Mode. This sets Bit transfer and Back-End Reset modes. Also, we could have chosen to make the FirstBit and SecondBit variables each a byte in size, but they still would only have received one bit each in the OWIN command (due to the Mode we chose).

The OWIN command's InputData argument is similar to the SERIN command's InputData argument. This means data can be received as ASCII character values, decimal, hexadecimal and binary translations and string data as in the examples below. (Assume a 1-wire device is used and that it transmits the string, "Value: 3A:101" every time it receives a Front-End Reset pulse).

Value VAR BYTE(13)
OWIN 0, 1, [Value]   'receive the ASCII value for "V"
OWIN 0, 1, [DEC Value]   'receive the number 3.
OWIN 0, 1, [HEX Value] 'receive the number $3A.
OWIN 0, 1, [BIN Value] 'receive the number %101.
OWIN 0, 1, [STR Value13] 'receive the string "Value: 3A:101"

Tables 5.45 and 5.46 list all the available special formatters and conversion formatters available to the OWIN command. See the SERIN command for additional information and examples of their use.

<table>
<thead>
<tr>
<th>Special Formatter</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>STR ByteArray \L {E}</td>
<td>Input a character string of length L into an array. If specified, an end character E causes the string input to end before reaching length L. Remaining bytes are filled with 0s (zeros).</td>
</tr>
<tr>
<td>WAITSTR ByteArray {L}</td>
<td>Wait for a sequence of bytes matching a string stored in an array variable, optionally limited to L characters. If the optional L argument is left off, the end of the array-string must be marked by a byte containing a zero (0).</td>
</tr>
<tr>
<td>SKIP Length</td>
<td>Ignore Length bytes of characters.</td>
</tr>
</tbody>
</table>
### Table 5.46: OWIN Conversion Formatters.

<table>
<thead>
<tr>
<th>Conversion Formatter</th>
<th>Type of Number</th>
<th>Numeric Characters Accepted</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>DEC{1..5}</td>
<td>Decimal, optionally limited to 1 – 5 digits</td>
<td>0 through 9</td>
<td>1</td>
</tr>
<tr>
<td>SDEC{1..5}</td>
<td>Signed decimal, optionally limited to 1 – 5 digits</td>
<td>-, 0 through 9</td>
<td>1,2</td>
</tr>
<tr>
<td>HEX{1..4}</td>
<td>Hexadecimal, optionally limited to 1 – 4 digits</td>
<td>0 through 9, A through F</td>
<td>1,3</td>
</tr>
<tr>
<td>SHEX{1..4}</td>
<td>Signed hexadecimal, optionally limited to 1 – 4 digits</td>
<td>-, 0 through 9, A through F</td>
<td>1,2,3</td>
</tr>
<tr>
<td>IHEX{1..4}</td>
<td>Indicated hexadecimal, optionally limited to 1 – 4 digits</td>
<td>$, 0 through 9, A through F</td>
<td>1,3,4</td>
</tr>
<tr>
<td>ISHEX{1..4}</td>
<td>Signed, indicated hexadecimal, optionally limited to 1 – 4 digits</td>
<td>-, $, 0 through 9, A through F</td>
<td>1,2,3,4</td>
</tr>
<tr>
<td>BIN{1..16}</td>
<td>Binary, optionally limited to 1 – 16 digits</td>
<td>0, 1</td>
<td>1</td>
</tr>
<tr>
<td>SBIN{1..16}</td>
<td>Signed binary, optionally limited to 1 – 16 digits</td>
<td>-, 0, 1</td>
<td>1,2</td>
</tr>
<tr>
<td>IBIN{1..16}</td>
<td>Indicated binary, optionally limited to 1 – 16 digits</td>
<td>%, 0, 1</td>
<td>1,4</td>
</tr>
<tr>
<td>ISBIN{1..16}</td>
<td>Signed, indicated binary, optionally limited to 1 – 16 digits</td>
<td>-, %, 0, 1</td>
<td>1,2,4</td>
</tr>
</tbody>
</table>

1. All numeric conversions will continue to accept new data until receiving either the specified number of digits (ex: three digits for DEC3) or a non-numeric character.
2. To be recognized as part of a number, the minus sign (−) must immediately precede a numeric character. The minus sign character occurring in non-numeric text is ignored and any character (including a space) between a minus and a number causes the minus to be ignored.
3. The hexadecimal formatters are not case-sensitive; “a” through “f” means the same as “A” through “F”.
4. Indicated hexadecimal and binary formatters ignore all characters, even valid numerics, until they receive the appropriate prefix ($ for hexadecimal, % for binary). The indicated formatters can differentiate between text and hexadecimal (ex: ABC would be interpreted by HEX as a number but IHEX would ignore it unless expressed as $ABC). Likewise, the binary version can distinguish the decimal number 10 from the binary number %10. A prefix occurring in non-numeric text is ignored, and any character (including a space) between a prefix and a number causes the prefix to be ignored. Indicated, signed formatters require that the minus sign come before the prefix, as in -$1B45.
The 1-wire protocol has a well-defined standard for transaction sequences. Every transaction sequence consists of four parts: 1) Initialization, 2) ROM Function Command, 3) Memory Function Command, and 4) Transaction/Data. Additionally, the ROM Function Command and Memory Function Command are always 8 bits wide (1 byte in size) and is sent least-significant-bit (LSB) first.

The Initialization part consists of a reset pulse (generated by the master) and will be followed by a presence pulse (generated by all slave devices). Figure 5.18 details the reset pulse generated by the BASIC Stamp and a typical presence pulse generated by a 1-wire slave, in response.

This reset pulse is controlled by the lowest two bits of the Mode argument in the OWIN command. It can be made to appear before the ROM Function Command (ex: Mode = 1), after the Transaction/Data portion (ex: Mode = 2), before and after the entire transaction (ex: Mode = 3) or not at all (ex: Mode = 0). See the section on Mode, above, for more information.

Following the Initialization part is the ROM Function Command. The ROM Function Command is used to address the desired 1-wire device. Table 5.47 shows common ROM Function Commands. If only a single 1-wire device is connected, the Match ROM command can be used to address it. If more than one 1-wire device is attached, the BASIC Stamp will ultimately have to address them individually using the Match ROM command.
The third part, the Memory Function Command, allows the BASIC Stamp to address specific memory locations, or features, of the 1-wire device. Refer to the 1-wire device's data sheet for a list of the available Memory Function Commands.

Finally, the Transaction/Data section is used to read or write data to the 1-wire device. The OWIN command will read data at this point in the transaction. A read is accomplished by generating a brief low-pulse and sampling the line within 15 µs of the falling edge of the pulse. This is called a "Read Slot." Figure 5.19 shows typical Read Slots performed by the BASIC Stamp. See the OWOUT command for information on Write Slots.

### Table 5.47: 1-wire ROM Function Commands.

<table>
<thead>
<tr>
<th>Command</th>
<th>Value (in Hex)</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>Read ROM</td>
<td>$33</td>
<td>Reads the 64-bit ID of the 1-wire device. This command can only be used if there is a single 1-wire device on the line.</td>
</tr>
<tr>
<td>Match ROM</td>
<td>$55</td>
<td>This command, followed by a 64-bit ID, allows the BASIC Stamp to address a specific 1-wire device.</td>
</tr>
<tr>
<td>Skip ROM</td>
<td>$CC</td>
<td>Address a 1-wire device without its 64-bit ID. This command can only be used if there is a single 1-wire device on the line.</td>
</tr>
<tr>
<td>Search ROM</td>
<td>$F0</td>
<td>Reads the 64-bit IDs of all the 1-wire devices on the line. A process of elimination is used to distinguish each unique device.</td>
</tr>
</tbody>
</table>

Figure 5.19: Example Read Slot.
The Demo Program uses a Dallas Semiconductor DS1820 Digital Thermometer device connected as follows. Note that the 4.7 kΩ pull-up resistor is required for proper operation.

**Figure 5.20:** DS1820 Circuit. NOTE: The 4.7 kΩ resistor is required for proper operation.

---

**Demo Program (I2C.bsp)**

This program demonstrates interfacing to a Dallas Semiconductor DS1820 1-wire Digital Thermometer chip using the BS2p’s 1-wire commands. Connect the BS2p to the DS1820 as shown in the diagram in the OWIN or OWOOUT command description.

This code reads the Counts Remaining and Counts per Degree C registers in the DS1820 chip in order to provide a more accurate temperature reading (down to 1/100th of a degree). It also calculates degrees Fahrenheit. NOTE: The algebraic equations used will not work properly with negative temperatures.

```plaintext
STAMP BS2p 'STAMP directive (specifies a BS2p)

Temp VAR WORD 'Holds the temperature value
CRem VAR BYTE 'Holds the counts remaining value
CPerC VAR BYTE 'Holds the Counts per degree C value

Start:
  OWOUT 0, 1, [$CC, $44] 'Send Calculate Temperature command

CheckForDone: 'Wait until conversion is done
  PAUSE 25
  OWIN 0, 4, [Temp]
  IF Temp = 0 THEN CheckForDone 'Here we just keep reading low pulses until the DS1820 is done, then it returns high.

  OWOUT 0, 1, [$CC, $BE] 'Send Read ScratchPad command

'Calculate temperature in degrees C
  Temp = Temp>>1*100-25+((CPerC*100-(CRem*100))/CPerC)
  DEBUG HOME, DEC3 Temp/100, ".", DEC2 Temp-(Temp/100*100), " C", CR

'Calculate temperature in degrees F
  Temp = Temp*/461+3200
  DEBUG DEC3 Temp/100, ".", DEC2 Temp-(Temp/100*100), " F"
  GOTO Start
```
**OWOUT**  
BS1 | BS2 | BS2e | BS2sx | BS2p
---|---|---|---|---

**Function**

Send data to a device using the 1-wire protocol.

- **Pin** is a variable/constant/expression (0 – 15) that specifies which I/O pin to use. 1-wire devices require only one I/O pin (called DQ) to communicate. This I/O pin will be toggled between output and input mode during the OWOUT command and will be set to input mode by the end of the OWOUT command.

- **Mode** is a variable/constant/expression (0 – 15) indicating the mode of data transfer. The Mode argument controls placement of reset pulses (and detection of presence pulses) as well as byte vs. bit input and normal vs. high speed. See explanation below.

- **OutputData** is a list of variables and modifiers that tells OWOUT how to format outgoing data. OWOUT can transmit individual or repeating bytes, convert values into decimal, hexadecimal or binary text representations, or transmit strings of bytes from variable arrays. These actions can be combined in any order in the OutputData list.

<table>
<thead>
<tr>
<th><strong>Quick Facts</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>BS2p</strong></td>
</tr>
<tr>
<td><strong>Transmission Rate</strong></td>
</tr>
<tr>
<td><strong>Special notes</strong></td>
</tr>
</tbody>
</table>

**Explanation**

The 1-wire protocol is a form of asynchronous serial communication developed by Dallas Semiconductor. It only requires one I/O pin and that pin can be shared between multiple 1-wire devices. The OWOUT command allows the BASIC Stamp to send data to a 1-wire device.

**A simple OWOUT example.**

The following is an example of the OWOUT command:

```
OWOUT 0, 1, [$4E]
```

This code will transmit a "reset" pulse to a 1-wire device (connected to I/O pin 0) and then will detect the device’s "presence" pulse and then transmit one byte (the value $4E).
The *Mode* argument is used to control placement of reset pulses (and detection of presence pulses) and to designate byte vs. bit input and normal vs. high speed. Figure 5.21 shows the meaning of each of the 4 bits of *Mode*. Table 5.49 shows just some of the 16 possible values and their effect.

The proper value for *Mode* depends on the 1-wire device and the portion of the communication you're working on. Please consult the data sheet for the device in question to determine the correct value for *Mode*. In many cases, however, when using the OWOUT command, *Mode* should be set for a Front-End Reset (to initialize the transaction). This may vary due to device and application requirements, however.

When using the Bit (rather than Byte) mode of data transfer, all variables in the *OutputData* argument will only transmit one bit. For example, the following code could be used to send two bits using this mode:
FirstBit VAR BIT
SecondBit VAR BIT
FirstBit = 0
SecondBit = 1
OWOUT 0, 5, [FirstBit, SecondBit]

In the code above, we chose the value "6" for \textit{Mode}. This sets Bit transfer and Front-End Reset modes. Also, we could have chosen to make the \textit{FirstBit} and \textit{SecondBit} variables each a byte in size, but the BASIC Stamp would still only use their lowest bit (BIT0) as the value to transmit in the OWOUT command (due to the \textit{Mode} we chose).

The OWOUT command's \textit{OutputData} argument is similar to the DEBUG and SEROUT command's \textit{OutputData} argument. This means data can be sent as literal text, ASCII character values, repetitive values, decimal, hexadecimal and binary translations and string data as in the examples below. (Assume a 1-wire device is used and that it transmits the string, "Value: 3A:101" every time it receives a Front-End Reset pulse).

\begin{verbatim}
Value VAR BYTE
Value = 65
OWOUT 0, 1, [Value] 'send the ASCII value for "A"
OWOUT 0, 1, [REP Value\5] 'send the ASCII value for "A" five times, ie: "AAAAA"
OWOUT 0, 1, [DEC Value] 'send two characters, "6" and "5"
OWOUT 0, 1, [HEX Value] 'send two characters, "4" and "1"
OWOUT 0, 1, [BIN Value] 'send seven characters, "1000001"
\end{verbatim}

Tables 5.50 and 5.51 list all the available special formatters and conversion formatters available to the OWOUT command. See the DEBUG and SEROUT commands for additional information and examples of their use.

\begin{table}
\centering
\caption{OWOUT Special Formatters.}
\begin{tabular}{|c|l|}
\hline
\textbf{Special Formatter} & \textbf{Action} \\
\hline
? & Displays "symbol = x' + carriage return; where x is a number. Default format is decimal, but may be combined with conversion formatters (ex: BIN ? x to display "x = binary_number"). \\
\hline
ASC ? & Displays "symbol = 'x'" + carriage return; where x is an ASCII character. \\
\hline
STR \textit{ByteArray} \{\texttt{L}\} & Send character string from an array. The optional \texttt{L} argument can be used to limit the output to \texttt{L} characters, otherwise, characters will be sent up to the first byte equal to 0 or the end of RAM space is reached. \\
\hline
REP \textit{Byte} \texttt{L} & Send a string consisting of \textit{Byte} repeated \texttt{L} times (ex: REP "X",10 sends "XXXXXXXXXXX"). \\
\hline
\end{tabular}
\end{table}
### Table 5.51: OWOUT Conversion Formatters.

<table>
<thead>
<tr>
<th>Conversion Formatter</th>
<th>Type of Number</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>DEC(1..5)</td>
<td>Decimal, optionally fixed to 1 – 5 digits</td>
<td>1</td>
</tr>
<tr>
<td>SDEC(1..5)</td>
<td>Signed decimal, optionally fixed to 1 – 5 digits</td>
<td>1,2</td>
</tr>
<tr>
<td>HEX(1..4)</td>
<td>Hexadecimal, optionally fixed to 1 – 4 digits</td>
<td>1</td>
</tr>
<tr>
<td>SHEX(1..4)</td>
<td>Signed hexadecimal, optionally fixed to 1 – 4 digits</td>
<td>1,2</td>
</tr>
<tr>
<td>IHEX(1..4)</td>
<td>Indicated hexadecimal, optionally fixed to 1 – 4 digits ($ prefix)</td>
<td>1</td>
</tr>
<tr>
<td>ISHEX(1..4)</td>
<td>Signed, indicated hexadecimal, optionally fixed to 1 – 4 digits ($ prefix)</td>
<td>1,2</td>
</tr>
<tr>
<td>BIN(1..16)</td>
<td>Binary, optionally fixed to 1 – 16 digits</td>
<td>1</td>
</tr>
<tr>
<td>SBIN(1..16)</td>
<td>Signed binary, optionally fixed to 1 – 16 digits</td>
<td>1,2</td>
</tr>
<tr>
<td>IBIN(1..16)</td>
<td>Indicated binary, optionally fixed to 1 – 16 digits (% prefix)</td>
<td>1</td>
</tr>
<tr>
<td>ISBIN(1..16)</td>
<td>Signed, indicated binary, optionally fixed to 1 – 16 digits (% prefix)</td>
<td>1,2</td>
</tr>
</tbody>
</table>

1 Fixed-digit formatters like DEC4 will pad the number with leading 0s if necessary; ex: DEC4 65 sends 0065. If a number is larger than the specified number of digits, the leading digits will be dropped; ex: DEC4 56422 sends 6422.

2 Signed modifiers work under two's complement rules.

The 1-wire protocol has a well-defined standard for transaction sequences. Every transaction sequence consists of four parts: 1) Initialization, 2) ROM Function Command, 3) Memory Function Command, and 4) Transaction/Data. Additionally, the ROM Function Command and Memory Function Command are always 8 bits wide (1 byte in size) and is sent least-significant-bit (LSB) first.

The Initialization part consists of a reset pulse (generated by the master) and will be followed by a presence pulse (generated by all slave devices). Figure 5.22 details the reset pulse generated by the BASIC Stamp and a typical presence pulse generated by a 1-wire slave, in response.
This reset pulse is controlled by the lowest two bits of the \textit{Mode} argument in the OWOUT command. It can be made to appear before the ROM Function Command (ex: \textit{Mode} = 1), after the Transaction/Data portion (ex: \textit{Mode} = 2), before and after the entire transaction (ex: \textit{Mode} = 3) or not at all (ex: \textit{Mode} = 0). See the section on \textit{Mode}, above, for more information.

Following the Initialization part is the ROM Function Command. The ROM Function Command is used to address the desired 1-wire device. Table 5.52 shows common ROM Function Commands. If only a single 1-wire device is connected, the Match ROM command can be used to address it. If more than one 1-wire device is attached, the BASIC Stamp will ultimately have to address them individually using the Match ROM command.

<table>
<thead>
<tr>
<th>Command</th>
<th>Value (in Hex)</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>Read ROM</td>
<td>$33</td>
<td>Reads the 64-bit ID of the 1-wire device. This command can only be used if there is a single 1-wire device on the line.</td>
</tr>
<tr>
<td>Match ROM</td>
<td>$55</td>
<td>This command, followed by a 64-bit ID, allows the BASIC Stamp to address a specific 1-wire device.</td>
</tr>
<tr>
<td>Skip ROM</td>
<td>$CC</td>
<td>Address a 1-wire device without its 64-bit ID. This command can only be used if there is a single 1-wire device on the line.</td>
</tr>
<tr>
<td>Search ROM</td>
<td>$F0</td>
<td>Reads the 64-bit IDs of all the 1-wire devices on the line. A process of elimination is used to distinguish each unique device.</td>
</tr>
</tbody>
</table>
The third part, the Memory Function Command, allows the BASIC Stamp to address specific memory locations, or features, of the 1-wire device. Refer to the 1-wire device’s data sheet for a list of the available Memory Function Commands.

Finally, the Transaction/Data section is used to read or write data to the 1-wire device. The OW OUT command will write data at this point in the transaction. A write is accomplished by generating a low-pulse of a varying width to indicate a 0 or a 1. This is called a "Write Slot" and must be at least 60 µs wide. Figure 5.23 shows typical Write Slots performed by the BASIC Stamp. See the OWIN command for information on Read Slots.

The Demo Program uses a Dallas Semiconductor DS1820 Digital Thermometer device connected as follows. Note that the 4.7 kΩ pull-up resister is required for proper operation.
Demo Program (I2C.bsp)

This program demonstrates interfacing to a Dallas Semiconductor DS1820 1-wire Digital Thermometer chip using the BS2p's 1-wire commands. Connect the BS2p to the DS1820 as shown in the diagram in the OWIN or OWOUT command description.

This code reads the Counts Remaining and Counts per Degree C registers in the DS1820 chip in order to provide a more accurate temperature reading (down to 1/100th of a degree). It also calculates degrees Fahrenheit. NOTE: The algebraic equations used will not work properly with negative temperatures.

`{$STAMP BS2p}`

'TSTAMP directive (specifies a BS2p)

Temp  VAR  WORD  'Holds the temperature value
CRem  VAR  BYTE  'Holds the counts remaining value
CPerC VAR  BYTE  'Holds the Counts per degree C value

Start:

OWOUT 0, 1, [$CC, $44]  'Send Calculate Temperature command

CheckForDone:

PAUSE 25

OWIN 0, 4, [Temp]  'Here we just keep reading low pulses until the DS1820 is done, then it returns high.

IF  Temp = 0  THEN  CheckForDone

OWOUT 0, 1, [$CC, $BE]  'Send Read ScratchPad command

OWIN 0, 2, [Temp.LOWBYTE,Temp.HIGHBYTE,CRem,CRem,CRem,CRem,CRem,CPerC]

'Calculate temperature in degrees C
Temp = Temp>>1*100-25+((CPerC*100-(CRem*100))/CPerC)
DEBUG  HOME, DEC3  Temp/100, ".", DEC2  Temp-(Temp/100*100), " C", CR

'Calculate temperature in degrees F
Temp = Temp*/461+3200
DEBUG  DEC3  Temp/100, ".", DEC2  Temp-(Temp/100*100), " F"
GOTO  Start
PAUSE

Function
Pause the program (do nothing) for the specified \textit{Period}.

- \textit{Period} is a variable/constant/expression (0 – 65535) that specifies the duration of the pause. The unit of time for \textit{Period} is 1 millisecond.

Explanation
PAUSE delays the execution of the next program instruction for the specified number of milliseconds. For example:

Flash:
- LOW 0
- PAUSE 100
- HIGH 0
- PAUSE 100
- GOTO Flash

This code causes pin 0 to go low for 100 ms, then high for 100 ms. The delays produced by PAUSE are as accurate as the ceramic-resonator time base (on the BASIC Stamp modules), ±1 percent. When you use PAUSE in timing-critical applications, keep in mind the relatively low speed of the PBASIC interpreter. This is the time required for the BASIC Stamp to read and interpret an instruction stored in the EEPROM.

Demo Program (PAUSE.bs2)
This program demonstrates the PAUSE command's time delays. Once a second, the program will put the message, "paused" on the screen.

\begin{verbatim}
'STAMP directive (specifies a BS2)

Again:
DEBUG "paused", cr
PAUSE 1000
GOTO Again
\end{verbatim}
POLLIN

Function
Specify a polled-input pin and active state.

- **Pin** is a variable/constant/expression (0 – 15) that specifies the I/O pin to use. This I/O pin will be set to input mode.
- **State** is a variable/constant/expression (0 – 1) that specifies whether to poll the I/O pin for a low (0) or a high (1) level.

Quick Facts

<table>
<thead>
<tr>
<th>BS2p</th>
<th>BS1</th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
</tr>
</thead>
</table>

**Table 5.53: POLLIN Quick Facts.**

<table>
<thead>
<tr>
<th>Available actions in response to reaching the desired State</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>1) Nothing, 2) Set polled-output pins to a specified state,</td>
<td></td>
</tr>
<tr>
<td>3) Run another program (in a specified program-slot), 4)</td>
<td></td>
</tr>
<tr>
<td>Wait (pause program execution) until desired <strong>State</strong> is</td>
<td></td>
</tr>
<tr>
<td>reached, 5) Any combination of 2, 3 and 4, above.</td>
<td></td>
</tr>
</tbody>
</table>

**Special notes**
- The polled-input pins are monitored (polled) in-between each command within the PBASIC code.
- On the BS2p40, polled-input pins can be defined on both Main I/O and Aux I/O pins. These are all active regardless of which group the program happens to be using at the time of a polling event.

**Explanation**

The POLLIN command is one of a family of unique "polling" commands on the BS2p module. The other commands in this family include POLLMODE, POLLOUT, POLLRUN and POLLWAIT. The POLLIN command is used to specify an input pin to monitor, or "poll", in-between instructions during the rest of the PBASIC program. The BASIC Stamp will then perform some activity (in-between instructions) when the specified **State** is detected. The activity performed depends on the POLLMODE, POLLOUT and POLLRUN commands.

The "polling" commands allow the BASIC Stamp to respond to certain I/O pin events at a faster rate than what is normally possible through manual PBASIC programming. The term "poll" comes from the fact that the BASIC Stamp's interpreter periodically checks the state of the designated polled-input pins. It "polls" these pins after the end of each PBASIC command and before it reads the next PBASIC command from the user program; giving the appearance that it is polling "in the background".
This feature should not be confused with the concept of interrupts, as the BASIC Stamp does not support true interrupts.

The following is an example of the POLLIN command:

```
POLLIN 0, 1
POLLMODE 2
```

The POLLIN command in the above code will cause the BASIC Stamp to set I/O pin 0 to an input mode and get ready to poll it for a high (1) state. The BASIC Stamp will not actually start polling until it is set to the appropriate mode, however. The second line, POLLMODE, initiates the polling process (see the POLLMODE description for more information). From then on, as the BASIC Stamp executes the rest of the program, it will check for a high level (logic 1) on I/O pin 0, in-between instructions.

In the code above, no obvious action will be noticed since we didn’t tell the BASIC Stamp what to do when it detects a change on the I/O pin. One possible action the BASIC Stamp can be instructed to take is to change the state of an output, called a polled-output. Take a look at the next example:

```
POLLIN 0, 1
POLLOUT 1, 0
POLLMODE 2
Loop:
  DEBUG "Looping…", CR
  GOTO Loop
```

In this example, in addition to an endless loop, we’ve added another polling command called POLLOUT (see the POLLOUT description for more information). Our POLLOUT command tells the BASIC Stamp to set I/O pin 1 to an output mode and set it low (0) when it detects the desired poll state. The poll state is the high (1) level on I/O pin 0 that POLLIN told it to look for. If the polled-input pin is not high, it will set polled-output pin 1 to high (1), instead.

Once the program reaches the endless loop, called Loop, it will continuously print "Looping..." on the PC screen. In between reading the DEBUG command and the GOTO command (and vice versa) it will check polled-input pin 0 and set polled-output pin 1 accordingly. In this case, when I/O pin 0 is set high, the BASIC Stamp will set I/O pin 1 low. When I/O pin 0 is set low, the BASIC Stamp will set I/O pin 1 high. It will
continue to perform this operation, in-between each command in the loop, endlessly.

It's important to note that, in this example, only the DEBUG and GOTO commands are being executed over and over again. The first three lines of code are only run once, yet their effects are "remembered" by the BASIC Stamp throughout the rest of the program.

If the polling commands were not used, the program would have to look like the one below in order to achieve the same effect.

```
INPUT 0
OUTPUT 1
Loop:
  OUT1 = ~IN0
  DEBUG "Looping…", CR
  OUT1 = ~IN0
  GOTO Loop
```

In this example, we create the inverse relationship of input pin 0 and output pin 1 manually, in-between the DEBUG and GOTO lines. Though the effects are the same as when using the polling commands, this program actually takes a little longer to run and consumes 7 additional bytes of program (EEPROM) space. Clearly, using the polling commands is more efficient.

You can have as many polled-input and polled-output pins as you have available. If multiple polled-input pins are defined, any one of them can trigger changes on the polled-output pins that are also defined. For example:

```
POLLIN 0, 1
POLLIN 1, 1
POLLOUT 2, 0
POLLOUT 3, 0
POLLMODE 2
Loop:
  DEBUG "Looping…", CR
  GOTO Loop
```

This code sets I/O pins 0 and 1 to polled-input pins (looking for a high (1) state) and sets I/O pins 2 and 3 to polled-output pins (with a low-active state). If either I/O pin 0 or 1 goes high, the BASIC Stamp will set I/O
pins 2 and 3 low. This works similar to a logical OR operation. The truth table below shows all the possible states of these two polled-input pins and the corresponding states the BASIC Stamp will set the polled-output pins to.

<table>
<thead>
<tr>
<th>Polled-Inputs</th>
<th>Polled-Outputs</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
</tr>
</tbody>
</table>

Table 5.54: Polled-Inputs / Polled-Outputs Truth Table.

Normally, any polled-output pins reflect the state changes continuously, as described above. The POLLMODE command supports another feature, however, where the polled-output pins will latch the active state; they will change only once (when the poll state is reached) and stay in the new state until the PBASIC program tells it to change again. See the POLLMODE description for more information.

Other possible actions in response to polled-input states are: 1) Running another program (in a specified program slot), 2) Waiting (pausing program execution with or without low-power mode) until the poll state is reached, or 3) Any combination of the above-mentioned actions.

Demo Program (POLINOUT.bsp)

' This program demonstrates the POLLIN, POLLOUT and POLLMODE commands. It will watch for a high signal on I/O pin 0 and then will output the opposite signal on I/O pin 1 all while printing a message on the PC screen.

'${STAMP  BS2p}   'STAMP directive (specifies a BS2p)

Init:
POLLIN 0, 1
POLLOUT 1, 0
POLLMODE 2

Main:
DEBUG "Working...", BIN1 OUT2, CR   'Waste time writing to PC screen
PAUSE 100
GOTO Main
POLLMODE

Function
Specify a polled command mode.
• Mode is a variable/constant/expression (0 – 15) that indicates the mode in which to process the polled command configuration.

Quick Facts

<table>
<thead>
<tr>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>• Polled-output pins will either change states continuously, just once or not at all, depending on the POLLMODE command.</td>
</tr>
<tr>
<td>• A poll-mode of 2 or 4 is required for a POLLWAIT command to work.</td>
</tr>
<tr>
<td>• If both polled-outputs and polled-run are active, the polled-output event will occur before the polled-run event.</td>
</tr>
</tbody>
</table>

Explanation
The POLLMODE command is one of a family of unique "polling" commands on the BS2p module. The other commands in this family include POLLIN, POLLOUT, POLLRUN and POLLWAIT. The POLLMODE command is used to specify the mode in which polling events and activities are processed. This activity will occur in-between instructions during the rest of the PBASIC program.

The "polling" commands allow the BASIC Stamp to respond to certain I/O pin events at a faster rate than what is normally possible through manual PBASIC programming. The term "poll" comes from the fact that the BASIC Stamp’s interpreter periodically checks the state of the designated polled-input pins. It "polls" these pins after the end of each PBASIC command and before it reads the next PBASIC command from the user program; giving the appearance that it is polling "in the background". This feature should not be confused with the concept of interrupts, as the BASIC Stamp does not support true interrupts.

The POLLMODE command sets one of 15 possible modes for the polling commands. It is used mainly before and/or after any POLLIN, POLLOUT and POLLRUN commands to disable and enable the polling features as desired. Table 5.56 shows the mode values and their effect.
After the polled-run action occurs, the mode switches to 1 (deactivated, saved) or 2 (activated, outputs), respectively. This is so that the BASIC Stamp doesn’t continuously go to the start of the designated program slot while the polled-inputs are in the desired poll state. Without this "one shot" feature, your program would appear to lock-up as long as the polled-inputs are in the designated state.

The clear configuration modes, 5, 6 and 7, are also unique. These modes do not override the previous mode. For example, if polled-inputs, polled-outputs and a polled-run configuration was set and the mode was set to 4 (activated, outputs and run) and later the program issued a POLLMODE 6 command, the polled-output configuration would be cleared but the mode would switch back to 4... still allowing the run action. This also means if, later still, the program issues a POLLOUT command, this polled-output would take effect immediately (since the mode is still 4). Also note that these modes do not change the output state of previously defined polled-output pins.

The POLLMODE command determines what action, if any, will occur in response to a polled-input event. This command works in conjunction with the POLLIN, POLLOUT and POLLRUN commands. The following is an example of the POLLMODE command:

A SIMPLE POLLMODE EXAMPLE.
POLLIN 0, 1
POLLOUT 1, 0
POLLMODE 2

Loop:
   DEBUG "Looping…", CR
GOTO Loop

In this example, the first two lines configure I/O pin 0 as a polled-input (looking for a high state) and I/O pin 1 as a polled-output (going low if I/O pin 0 goes high, and vice versa). The third line, POLLMODE, initiates the polling process and configures polled-outputs to be active. From then on, as the BASIC Stamp executes the rest of the program, it will check for a high level (logic 1) on I/O pin 0, in-between instructions and will set I/O pin 1 accordingly.

If, in the above example, the poll mode was set to 1 (which means deactivate polling but save configuration) I/O pins 0 and 1 would still be defined the same way, and I/O pin 1 would still be set to output mode, but no polling would take place during the rest of the program.

Here's another example that demonstrates mode 1 (deactivate but save configuration).

POLLIN 0, 1
POLLOUT 1, 0
POLLMODE 2

DEBUG "Polling configured", CR

Main:
   POLLMODE 1
   DEBUG "No polling allowed here…", CR
   PAUSE 1000
   POLLMODE 2

Loop:
   DEBUG "Polling now…", CR
GOTO Loop

In this case, polling is configured and activated before "Polling configured" is printed on the screen. Once we reach the Main routine, however, polling is disabled (via the POLLMODE 1 command) and no polling occurs during the printing of "No polling allowed here…" or during the 1 second pause afterward. Finally, polling is activated again, and since the configuration was saved (because of mode 1, before) the polling activity...
acts just like it did initially for the remainder of the program. The ability to temporarily disable polling, without changing the configuration, can be a powerful feature for certain "critical" parts of a program.

The following example contains two programs. The first should be downloaded into program slot 0 and the second into program slot 1. We’ll assume they are called POLL0.bsp and POLL1.bsp, respectively (as defined in the STAMP directive lines).

```
' ----- program #1 (slot 0) -----
' {$STAMP  BS2p, POLL1.bsp}

POLLIN 0, 1
POLLOUT 1, 1
POLLRUN 1
POLLMODE 4

Loop:
  DEBUG "Program 1", CR
GOTO Loop

' ----- program #2 (slot 1) -----
' {$STAMP  BS2p}

DEBUG "Switching…", CR

Loop:
  DEBUG "Program 2", CR
GOTO Loop
```

In this example (containing two programs; one is slot 0 and the other in slot 1) program 1 (slot 0) will configure polled-input pin 0 to detect a high state and polled-output 1 to go high in response. Program 1 also configures a polled-run activity (see the POLLRUN description for more information) to run the program in slot 1. The POLLMODE setting activates the polled-output and the polled-run. Then, program 1 continuously prints "Program 1" on the PC screen.

Once I/O pin 0 goes high, however, the BASIC Stamp will set I/O pin 1 high, then execution will be switched to the program in slot 1 (program 2). Program 2 will first print "Switching…" on the PC screen and then will continuously print "Program 2". From this point forward, I/O pin 1 will continue to be set low and high in response to changes occurring on I/O
pin 0, but the polled-run activity is disabled and the BASIC Stamp endlessly runs the code in program 2's Loop routine.

---

**Demo Program (POLINOUT.bsp)**

`This program demonstrates the POLLIN, POLLOUT and POLLMODE commands. It will watch for a high signal on I/O pin 0 and then will output the opposite signal on I/O pin 1 all while printing a message on the PC screen.

`{STAMP BS2p}`

'STAMP directive (specifies a BS2p)

Init:

<table>
<thead>
<tr>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>POLLIN 0, 1</td>
<td>Set I/O pin 0 to polled-input looking for a high</td>
</tr>
<tr>
<td>POLLOUT 1, 0</td>
<td>Set I/O pin 1 to polled-output; opposite level a 0</td>
</tr>
<tr>
<td>POLLMODE 2</td>
<td>Set mode to enable polled-outputs</td>
</tr>
</tbody>
</table>

Main:

```plaintext
DEBUG "Working...", BIN1 OUT2, CR  'Waste time writing to PC screen
PAUSE 100
GOTO Main
```

---


POLLOUT  BS1 BS2 BS2e BS2sx BS2p

Function
Specify a polled-output pin and active state.
• *Pin* is a variable/constant/expressions (0 – 15) that specifies the I/O pin to use. This I/O pin will be set to output mode.
• *State* is a variable/constant/expressions (0 – 1) that specifies whether to set the I/O pin low (0) or high (1) when a polled-input pin changes to its poll state.

**Quick Facts**

<table>
<thead>
<tr>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>• The POLLOUT command will immediately change the I/O pin to an output mode and set its level opposite to that of &quot;State,&quot; regardless of the polled-input states or the polled mode.</td>
</tr>
<tr>
<td>• Polled-output pins will either change states continuously, just once or not at all, depending on the POLLMODE command.</td>
</tr>
<tr>
<td>• On the BS2p40, polled-output pins can be defined on both Main I/O and Aux I/O pins. These are all active regardless of which group the program happens to be using at the time of a polling event.</td>
</tr>
<tr>
<td>• If both polled-outputs and polled-run are active, the polled-output event will occur before the polled-run event.</td>
</tr>
</tbody>
</table>

**Explanation**

The POLLOUT command is one of a family of unique "polling" commands on the BS2p module. The other commands in this family include POLLIN, POLLMODE, POLLRUN and POLLWAIT. The POLLOUT command is used to specify an output pin that changes states in response to changes on any of the defined polled-input pins. This activity will occur in-between instructions during the rest of the PBASIC program.

The "polling" commands allow the BASIC Stamp to respond to certain I/O pin events at a faster rate than what is normally possible through manual PBASIC programming. The term "poll" comes from the fact that the BASIC Stamp’s interpreter periodically checks the state of the designated polled-input pins. It "polls" these pins after the end of each PBASIC command and before it reads the next PBASIC command from the user program; giving the appearance that it is polling "in the background". This feature should not be confused with the concept of interrupts, as the BASIC Stamp does not support true interrupts.
The POLLOUT command achieves one of three possible actions in response to a polled-input event. This command works in conjunction with the POLLIN and POLLMODE commands. The following is an example of the POLLOUT command:

```plaintext
POLLIN 0, 1
POLLOUT 1, 0
POLLMODE 2

Loop:
  DEBUG "Looping...", CR
  GOTO Loop
```

In this example, the POLLOUT command tells the BASIC Stamp to set I/O pin 1 to an output mode and set it low (0) when it detects the desired poll state. The poll state is the high (1) level on I/O pin 0 that POLLIN told it to look for. If the polled-input pin is not high, the BASIC Stamp will set polled-output pin 1 to high (1), instead. The BASIC Stamp will not actually start polling until it is set to the appropriate mode, however. The third line, POLLMODE, initiates the polling process (see the POLLMODE description for more information). From then on, as the BASIC Stamp executes the rest of the program, it will check for a high level (logic 1) on I/O pin 0, in-between instructions.

Once the program reaches the endless loop, called `Loop`, it will continuously print "Looping..." on the PC screen. In between reading the DEBUG command and the GOTO command (and vice versa) it will check polled-input pin 0 and set polled-output pin 1 accordingly. In this case, when I/O pin 0 is set high, the BASIC Stamp will set I/O pin 1 low. When I/O pin 0 is set low, the BASIC Stamp will set I/O pin 1 high. It will continue to perform this operation, in-between each command in the loop, endlessly.

It's important to note that in this example only the DEBUG and GOTO commands are being executed over and over again. The first three lines of code are only run once, yet their effects are "remembered" by the BASIC Stamp throughout the rest of the program.

If the polling commands were not used, the program would have to look like the one below in order to achieve the same effect.
5: BASIC Stamp Command Reference – POLLOUT

INPUT 0
OUTPUT 1

Loop:
  OUT1 = ~IN0
  DEBUG "Looping…", CR
  OUT1 = ~IN0
  GOTO Loop

In this example, we create the inverse relationship of input pin 0 and output pin 1 manually, in-between the DEBUG and GOTO lines. Though the effects are the same as when using the polling commands, this program actually takes a little longer to run and consumes 7 additional bytes of program (EEPROM) space. Clearly, using the polling commands is more efficient.

You can have as many polled-input and polled-output pins as you have available. If multiple polled-output pins are defined, all of them change in response to changes on the polled-input pins. For example:

POLLIN 0, 1
POLLOUT 1, 0
POLLOUT 2, 1
POLLOUT 3, 1
POLLMODE 2

Loop:
  DEBUG "Looping…", CR
  GOTO Loop

This code sets up I/O pin 0 as a polled-input pin (looking for a high (1) state) and sets I/O pins 1, 2 and 3 to polled-output pins. Polled-output pin 1 is set to a low-active state and pins 2 and 3 are set to a high-active state. If I/O pin 0 goes high, the BASIC Stamp will set I/O pin 1 low and I/O pins 2 and 3 high. The table below shows the two possible states of the polled-input pin and the corresponding states the BASIC Stamp will set the polled-output pins to.

<table>
<thead>
<tr>
<th>Polled-Input</th>
<th>Polled-Outputs</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>1 2 3</td>
</tr>
<tr>
<td>0</td>
<td>1 0 0</td>
</tr>
<tr>
<td>1</td>
<td>0 1 1</td>
</tr>
</tbody>
</table>

Table 5.58: POLLOUT Truth Table.

Normally, any polled-output pins reflect the state changes continuously, as described above. The POLLMODE command supports another feature,
however, where the polled-output pins will latch the active state; they will change only once (when the poll state is reached) and stay in the new state until the PBASIC program tells it to change again. See the POLLMODE description for more information.

A clever use of the "latched" feature is to set a polled-output to be the same as the polled-input. For example, suppose an application needed to respond in some way if a polled-input pin goes high, but it doesn't need to respond immediately, and the other tasks should not be interrupted. In essence, we need a way to know if the pin has gone high since the last time we checked it. Look at this example:

```
POLLOUT 0, 1  'Set I/O 0 to polled-output, high
POLLIN 0, 1   'Set I/O 0 back to polled-input, high
POLLMODE 10   'Set mode to latch the polled-output

Idx VAR BYTE

Work:     'Do nonsense work, but check once in a while to see if the polled event ever occurred
  FOR Idx = 1 TO 20
    DEBUG "Working…", CR
  NEXT
  IF OUT0 = 0 THEN Work

Respond:     'Send a different message if it did occur
  DEBUG CR, "Hey! You set my pin high!", CR
  POLLMODE 10   'Reset polled-output's latch function
  GOTO Work
```

Here, we set I/O pin 0 to a polled-output, then immediately set it to a polled-input. Then we set the polled-mode to latch the polled-outputs. Since the POLLIN command occurred after the POLLOUT, I/O pin 0 will be an input, but the polling feature will still affect the OUT0 bit (output latch for I/O pin 0). Then, the program performs some work, and once in a while, checks the state of OUT0. If OUT0 is 0, I/O pin 0 was never seen to go high. If, however, OUT0 is 1, I/O pin 0 must have gone high while the program was doing other work, and now it can respond in the proper manner. This even works if the pin had gone high and then low again before we check it (as long as it was high at some point in between the instructions in our Work routine.

It is important to note that during the time between the POLLOUT and POLLIN commands, I/O pin 0 will be set to an output direction. This can cause a temporary short with the circuitry connected to I/O pin 0, so it is
vital that a large enough series resister (perhaps 100 ohms or greater) be inserted on that pin to protect the external device and the BASIC Stamp.

Demo Program (POLINOUT.bsp)

' This program demonstrates the POLLIN, POLLOUT and POLLMODE commands. It will watch for a high signal on I/O pin 0 and then will output the opposite signal on I/O pin 1 all while printing a message on the PC screen.

'{'$STAMP BS2p'}  'STAMP directive (specifies a BS2p)

Init:

    POLLIN 0, 1  'Set I/O pin 0 to polled-input looking for a high
    POLLOUT 1, 0 'Set I/O pin 1 to polled-output; opposite level a 0
    POLLMODE 2  'Set mode to enable polled-outputs

Main:

    DEBUG "Working...", BIN1 OUT2, CR  'Waste time writing to PC screen
    PAUSE 100
    GOTO Main
POLLRUN

Function
Specify a program to run upon a polled-input event.

- **Slot** is a variable/constant/expression \((0 \text{ - } 7)\) that specifies the program slot to run when a polled-input event occurs.

### Quick Facts

<table>
<thead>
<tr>
<th>BS2p</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Default Slot</strong></td>
<td>The default polled-run slot is 0. If no POLLRUN command is given and a poll mode of 3 or 4 is set, the program in slot 0 will run in response to a polled-input event.</td>
</tr>
<tr>
<td><strong>Special notes</strong></td>
<td>If both polled-outputs and polled-run are active, the polled-output event will occur before the polled-run event.</td>
</tr>
</tbody>
</table>

**Explanation**

The POLLRUN command is one of a family of unique "polling" commands on the BS2p module. The other commands in this family include POLLIN, POLLMODE, POLLOUT and POLLWAIT. The POLLRUN command is used to specify a program slot to run in response to a polled event. This activity can occur in-between any two instructions within the rest of the PBASIC program.

The "polling" commands allow the BASIC Stamp to respond to certain I/O pin events at a faster rate than what is normally possible through manual PBASIC programming. The term "poll" comes from the fact that the BASIC Stamp’s interpreter periodically checks the state of the designated polled-input pins. It "polls" these pins after the end of each PBASIC command and before it reads the next PBASIC command from the user program; giving the appearance that it is polling "in the background". This feature should not be confused with the concept of interrupts, as the BASIC Stamp does not support true interrupts.

**A simple POLLRUN example**

The following is a simple example of the POLLRUN command.
POLLIN 0, 1
POLLRUN 1
POLLMODE 3

Loop:
    DEBUG "Waiting in Program Slot 0…", CR
    GOTO Loop

The first line of the above code will set up I/O pin 0 as a polled-input pin looking for a high (1) state. The second line, POLLRUN, tells the BASIC Stamp that when I/O pin 0 goes high, it should switch execution over to the program residing in program slot 1. The third line, POLLMODE, activates the polled-run configuration.

Once the BASIC Stamp reaches the Loop routine, it will continuously print "Waiting in Program Slot 0…" on the PC screen. In between reading the DEBUG and GOTO commands, however, the BASIC Stamp will poll I/O pin 0 and check for a high or low state. If the state of pin 0 is low, it will do nothing and continue as normal. If the state of pin 1 is high, it will switch execution over to the program in slot 1 (the second program is not shown in this example). The switch to another program slot works exactly like with the RUN command; the designated program is run and the BASIC Stamp does not "return" to the previous program (similar to a GOTO command).

Note that in order for the polled-run activity to occur, the poll mode must be set to either 3 or 4 (the two modes that activate polled-run). Also note, that the polled-run modes, 3 and 4, are unique. As soon as the polled-run action occurs, the mode switches to 1 (deactivated, saved) or 2 (activated, outputs), respectively. This is so that the BASIC Stamp doesn’t continuously go to the start of the designated program slot while the polled-inputs are in the desired poll state. Without this "one shot" feature, your program would appear to lock-up as long as the polled-inputs are in the designated state.

After the program switch takes place, the Slot value is maintained. Any future change to poll mode 3 or 4, without another POLLRUN command, will result in the previously defined program slot being used.
Demo Program (POLLRUN0.bsp)

This program demonstrates the POLLRUN command. It is intended to be downloaded to program slot 0, and the program called PROGRUN1.BSP should be downloaded to program slot 1. I/O pin 0 is set to watch for a high signal. Once the Loop routine starts running, the program constant prints its program slot number to the screen. If I/O pin 0 goes high, the program in program slot 1 (which should be POLLRUN1.BSP) is run.

'($STAMP BS2p, PollRun1.bsp)

ProgSlot VAR BYTE

Init:

POLLIN 0, 1  'Set I/O 0 to polled-input looking for a high
POLLRUN 1    'Set polled-run to program slot 1
POLLMODE 3   'Set mode to enable polled-outputs and polled wait

Loop:

GET 127, ProgSlot
DEBUG "Running Program ", DEC ProgSlot.LOWNIB, CR
GOTO Loop

Demo Program (POLLRUN1.bsp)

This program demonstrates the POLLRUN command. It is intended to be downloaded to program slot 1, and the program called PROGRUN0.BSP should be downloaded to program slot 0. This program is run when program 0 detects a high on I/O pin 0 via the polled commands.

ProgSlot VAR BYTE

Loop:

GET 127, ProgSlot
DEBUG "Running Program ", DEC ProgSlot.LOWNIB, CR
GOTO Loop
POLLWAIT

Function
Pause program execution, in a low-power mode, in units of Period until any polled-input pin reaches the desired poll state.

- Period is a variable/constant/expression (0 – 8) that specifies the duration of the low-power state. The duration is \((2^\text{Period}) \times 18 \text{ ms}\). Table 5.61 indicates the low-power length for any give Period. Using 8 as the Period is a special case; the BS2p will not go into low-power mode and will respond quicker to polled-inputs.

Quick Facts

<table>
<thead>
<tr>
<th>BS2p</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Current draw during POLLWAIT</td>
<td>60 µA</td>
</tr>
<tr>
<td>Response time with Period set to 8</td>
<td>Less than 160 µS</td>
</tr>
</tbody>
</table>

Special notes
- Poll mode must be 2 or 4 and at least one polled-input must be set to activate POLLWAIT (POLLWAIT will be ignored otherwise).
- If both polled-wait and polled-run are active, the polled-run event will occur immediately after the polled-wait detects an event.

Explanation
The POLLWAIT command is one of a family of unique "polling" commands on the BS2p module. The other commands in this family include POLLIN, POLLMODE, POLLOUT and POLLRUN. The POLLWAIT command is used to pause program execution and go into a low-power state until any polled-input pin reaches the desired poll state.

The "polling" commands allow the BASIC Stamp to respond to certain I/O pin events at a faster rate than what is normally possible through manual PBASIC programming. The term "poll" comes from the fact that the BASIC Stamp's interpreter periodically checks the state of the designated polled-input pins. It "polls" these pins after the end of each PBASIC command and before it reads the next PBASIC command from the user program; giving the appearance that it is polling "in the background".

This feature should not be confused with the concept of interrupts, as the BASIC Stamp does not support true interrupts.
The POLLWAIT command is unique among the polling commands in that it actually causes execution to halt, until a polled-input pin event occurs. The *Period* argument is similar to that of the NAP command; using the values 0 to 7 specifies the duration of the low-power period. After the low-power period is over, the BASIC Stamp polls the polled-input pins and determines if any meet the desired poll state. If no polled-input is in the desired state (as set by POLLIN command) the BASIC Stamp goes back into low-power mode, again, for the same duration as before. If any polled-input is in the desired state, however, the BASIC Stamp will continue execution with the next line of code.

A *Period* of 8, makes the BASIC Stamp pause execution in normal running mode (not low-power mode) until a polled-input event occurs. The response time is indicated in Table 5.60. Since the response time is so fast, this feature can be used to synchronize a portion of PBASIC code to an incoming pulse.

<table>
<thead>
<tr>
<th>Period</th>
<th>Length of Low-Power Mode</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>18 ms</td>
</tr>
<tr>
<td>1</td>
<td>36 ms</td>
</tr>
<tr>
<td>2</td>
<td>72 ms</td>
</tr>
<tr>
<td>3</td>
<td>144 ms</td>
</tr>
<tr>
<td>4</td>
<td>288 ms</td>
</tr>
<tr>
<td>5</td>
<td>576 ms</td>
</tr>
<tr>
<td>6</td>
<td>1152 ms (1.152 seconds)</td>
</tr>
<tr>
<td>7</td>
<td>2304 ms (2.304 seconds)</td>
</tr>
<tr>
<td>8</td>
<td>No power-down</td>
</tr>
</tbody>
</table>

The following is a simple example of the POLLWAIT command.

```
POLLIN  0, 1
Loop:
    POLLWAIT  0
    TOGGLE  1
    GOTO  Loop
```

In this example, the POLLIN command sets I/O pin 0 to be a polled-input pin looking for a high (1) state. The *Loop* routine immediately runs a POLLWAIT command and specifies a *Period* of 0 (with results in a low-power state of 18 ms). This means that every 18 ms, the BASIC Stamp wakes-up and checks I/O pin 0 for a high. If I/O pin 0 is low, it goes back...
to sleep for another 18 ms. If I/O pin 0 is high, it runs the next line of code, which toggles the state of I/O pin 1. Then the loop starts all over again. Note: Due to the nature of low-power mode, I/O pin 1 may toggle between high and low (at 18 ms intervals in this case) even if I/O pin 0 stays low. This is an artifact of the "reset" condition in the interpreter chip that occurs when the chip wakes up from a low-power state. Upon this "reset" condition, all the I/O pins are switched to inputs for apx. 18 ms. It is the switching to inputs that will cause I/O pin 1 to appear to toggle. See the NAP or SLEEP commands for more information.

If low-power mode is not required, change the POLLWAIT command in the example above to "POLLWAIT 8" instead. This will have the effect of keeping the BASIC Stamp in normal running mode (ie: no low-power glitches) and will also cause the TOGGLE command to execute in a much shorter amount of time after a polled-input event occurs.

```
Demo Program (POLLWAIT.bsp)
' This program demonstrates the POLLWAIT command. I/O pin 0 is set to watch for a
' high signal. Once the Loop routine starts running, the POLLWAIT command causes the
' program to halt until the polled event happens (I/O pin is high) then it prints
' a message on the PC screen. It will do nothing until I/O pin is high.

'${STAMP BS2p}          'STAMP directive (specifies a BS2p)

POLLIN 0, 1          'Set I/O 0 to polled-input looking for a high
POLLMODE 2            'Set mode to enable polled-outputs and polled wait

Loop:
POLLWAIT 8            'Wait for polled event (in normal power mode)
DEBUG "I/O 0 is HIGH!", CR      'Print to the screen when polled event occurs
GOTO Loop
```
POT

Function
Read a 5 kΩ to 50 kΩ potentiometer, thermistor, photocell, or other variable resistance.

- **Pin** is a variable/constant (0 – 7) that specifies the I/O pin to use. This pin will be set to output mode initially, then to input mode.

- **Scale** is a variable/constant (0 – 255) used to scale the command’s internal 16-bit result. See Explanation below for steps to finding the scale value to use for your circuit.

- **Variable** is a variable (usually a byte) where the final result of the reading will be stored. Internally, the POT command calculates a 16-bit value, which is scaled down to an 8-bit value.

Explanation
POT reads a variable resistance and returns a value (0 – 255) representing the amount of time it took to discharge the capacitor through the resistance. **Pin** must be connected to one side of the variable resistance, whose other side is connected through a capacitor to ground, as shown in Figure 5.25.

Figure 5.25: Example Variable Resistance Circuit.

POT works by first setting the specified I/O pin to an output and setting its state high. This step places +5 volts on one side of the capacitor (see Figure 5.25) and ground (0 volts) on the other side, which charges the capacitor. POT waits for 10 ms and then sets the I/O pin to an input mode and starts its timer. Initially the I/O pin will see a high (1) that will eventually drop to a low (0) when the capacitor discharges past the 1.4-volt threshold. The timer stops once the low is seen. The value of the
variable resistor affects the time it takes to discharge the capacitor from 5 volts to approximately 1.4 volts.

The 16-bit reading is multiplied by \((\text{Scale}/256)\), so a scale value of 128 would reduce the range by approximately 50%, a scale of 64 would reduce to 25%, and so on. The amount by which the internal value must be scaled varies with the size of the resistor being used.

Finding the best \textit{Scale} value:
1. Build the circuit shown in Figure 5.25 and plug the BS1 into the PC.
2. In the DOS editor (stamp.exe) press ALT-P. A special calibration window appears, allowing you to find the best value.
3. The window asks for the number of the I/O pin to which the variable resistor is connected. Select the appropriate pin (0-7).
4. The editor downloads a short program to the BS1 (this overwrites any program already stored in the BS1).
5. Another window appears, showing two numbers: scale and value. Adjust the resistor until the smallest number is shown for scale (assuming you can adjust the resistor, as with a potentiometer).
6. Once you’ve found the smallest number for scale, you’re done. This number should be used for the \textit{Scale} in the POT command.
7. Optionally, you can verify the scale number found above by pressing the spacebar. This locks the scale and causes the BS1 to read the resistor continuously. The window displays the value. If the scale is good, you should be able to adjust the resistor, achieving a 0–255 reading for the value (or as close as possible). To change the scale value and repeat this step, just press the spacebar. Continue this process until you find the best scale.

\textbf{Demo Program (POT.bas)}

\begin{verbatim}
' This program demonstrates the PAUSE command's time delays. Once a second, the
' program will put the message, "paused" on the screen.

'{$STAMP BS1}    'STAMP directive (specifies a BS1)

Loop:
   POT 0, 100, B2    ' Read potentiometer on pin 0.
   SEROUT 1, N300, (B2) ' Send potentiometer reading
   GOTO Loop
\end{verbatim}
PULSIN

**Function**

Measure the width of a pulse on *Pin* described by *State* and store the result in *Variable*.

- **Pin** is a variable/constant/expression (0 – 15) that specifies the I/O pin to use. This pin will be set to input mode.

- **State** is a variable/constant/expression (0 – 1) that specifies whether the pulse to be measured is low (0) or high (1). A low pulse begins with a 1-to-0 transition and a high pulse begins with a 0-to-1 transition.

- **Variable** is a variable (usually a word) in which the measured pulse duration will be stored. The unit of time for *Variable* is described in Table 5.62.

---

**Quick Facts**

<table>
<thead>
<tr>
<th></th>
<th>BS1</th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Units in <em>Variable</em></td>
<td>10 µs</td>
<td>2 µs</td>
<td>2 µs</td>
<td>0.8 µs</td>
<td>0.75 µs</td>
</tr>
<tr>
<td>Maximum pulse width</td>
<td>655.35 ms</td>
<td>131.07 ms</td>
<td>131.07 ms</td>
<td>52.428 ms</td>
<td>49.125 ms</td>
</tr>
</tbody>
</table>

---

**Explanation**

PULSIN is like a fast stopwatch that is triggered by a change in state (0 or 1) on the specified pin. The entire width of the specified pulse (high or low) is measured, in units shown in Table 5.62, and stored in *Variable*.

Many analog properties (voltage, resistance, capacitance, frequency, duty cycle) can be measured in terms of pulse durations. This makes PULSIN a valuable form of analog-to-digital conversion.

---

**Specifics of PULSIN's operation.**

PULSIN will wait, for the desired pulse, for up to the maximum pulse width it can measure, shown in Table 5.62. If it sees the desired pulse, it measures the time until the end of the pulse and stores the result in *Variable*. If it never sees the start of the pulse, or the pulse is too long (greater than the Maximum Pulse Width shown in Table 5.62) PULSIN...
"times out" and store 0 in Variable. This operation keeps your program from locking-up should the desired pulse never occur.

Regardless of the size of Variable, PULSIN internally uses a 16-bit timer. Unless the pulse widths are known to be short enough to fit in an 8-bit result, it is recommended using a word-sized variable. Not doing so may result in strange and misleading results as the BASIC Stamp will only store the lower 8-bits into a byte variable.

Demo Program (PULSIN.bas)

' This program uses PULSIN to measure a pulse generated by discharging a 0.1 uF capacitor through a 1k resistor (see the figure in the description of PULSIN in the manual).
' Pressing the switch generates the pulse, which should ideally be approximately 120 µs (12 PULSIN units of 10 us) long. Variations in component values may produce results that are up to 10 units off from this value. For more information on calculating resistor-capacitor timing, see the RCTIME command.

'{STAMP BS1}    'STAMP directive (specifies a BS1)

SYMBOL Time = W0

Again:
PULSIN 7, 1, Time  ' Measure positive pulse.
IF Time = 0 THEN Again  ' If 0, try again.
DEBUG CLS, Time  ' Otherwise, display result.
GOTO Again

Demo Program (PULSIN.bs2)

' This program uses PULSIN to measure a pulse generated by discharging a 0.1 µF capacitor through a 1k resistor (see the figure in the description of PULSIN in the manual).
' Pressing the switch generates the pulse, which should ideally be approximately 120 µs (60 PULSIN units of 2 µs) long. Variations in component values may produce results that are up to 10 units off from this value. For more information on calculating resistor-capacitor timing, see the RCTIME command.

'{STAMP BS2}    'STAMP directive (specifies a BS2)

Time VAR WORD

Again:
PULSIN 7, 1, Time  ' Measure positive pulse.
IF Time = 0 THEN Again  ' If 0, try again.
DEBUG CLS, DEC ? Time  ' Otherwise, display result.
GOTO Again

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, BS2sx or BS2p. Keep in mind that the unit of time may be different than what appears in the comments here.
5: BASIC Stamp Command Reference – PULSOUT

PULSOUT Pin, Period

Function
Generate a pulse on Pin with a width of Period.

- **Pin** is a variable/constant/expression (0 – 15) that specifies the I/O pin to use. This pin will be set to output mode.
- **Period** is a variable/constant/expression (0 – 65535) that specifies the duration of the pulse. The unit of time for Period is described in Table 5.63.

Quick Facts

<table>
<thead>
<tr>
<th>Pin</th>
<th>BS1</th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Period Units</td>
<td>10 µs</td>
<td>2 µs</td>
<td>2 µs</td>
<td>0.8 µs</td>
<td>1.18 µs</td>
</tr>
<tr>
<td>Maximum pulse width</td>
<td>655.35 ms</td>
<td>131.07 ms</td>
<td>131.07 ms</td>
<td>52.428 ms</td>
<td>55.479 ms</td>
</tr>
</tbody>
</table>

Explanation
PULSOUT sets Pin to output mode, inverts the state of that pin; waits for the specified Period; then inverts the state of the pin again; returning the bit to its original state. The unit of Period is described in Table 5.63. The following example will generate a 100 us pulse on I/O pin 5 (of the BS2):

```plaintext
PULSOUT 5, 50 ' Generate a pulse on pin 5.
```

The polarity of the pulse depends on the state of the pin before the command executes. In the example above, if pin 5 was low, PULSOUT would produce a positive pulse. If the pin was high, PULSOUT would produce a negative pulse.

If the pin is an input, the output state bit, OUT5 (PIN5 on the BS1) won’t necessarily match the state of the pin. What happens then? For example: pin 7 is an input (DIR7 = 0) and pulled high by a resistor as shown in Figure 5.26a. Suppose that pin 7 is low when we execute the instruction:

```plaintext
PULSOUT 7, 5 ' Generate a pulse on pin 7.
```

Figure 5.26b shows the sequence of events on that pin. Initially, pin 7 is high. Its output driver is turned off (because it is in input mode), so the

NOTE: Expressions are not allowed as arguments on the BS1. The range of the Pin argument on the BS1 is 0 – 7.
10k resistor sets the state on the pin. When PULSOUT executes, it turns on the output driver, allowing OUT7 (PIN7 on the BS1) to control the pin.

Since OUT7 (PIN7 on the BS1) is low, the pin goes low. After a few microseconds of preparation, PULSOUT inverts the state of the pin; from low to high. It leaves the pin in that state for the specified time (10µs if using a BS2) and then inverts it again, leaving the pin in its original state.

Demo Program (PULSOUT.bas)

```
' This program blinks an LED on for 10ms at 1-second intervals. Connect the LED to I/O ' pin 0 as shown in the figure within the NAP command description of the manual.

'{STAMP  BS1}                      'STAMP directive (specifies a BS1)
HIGH  0
Again:
PULSOUT  0, 1000        ' Flash the LED for 10 ms.
PAUSE  1000            ' Wait one second.
GOTO  Again           ' Repeat endlessly.
```

Demo Program (PULSOUT.bs2)

```
' This program blinks an LED on for 10ms at 1-second intervals. Connect the LED to I/O ' pin 0 as shown in the figure within the NAP command description of the manual.

'{STAMP  BS2}                      'STAMP directive (specifies a BS2)
HIGH  0
Again:
PULSOUT  0, 5000        ' Flash the LED for 10 ms.
PAUSE  1000            ' Wait one second.
GOTO  Again           ' Repeat endlessly.
```

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, BS2sx or BS2p. Keep in mind that the unit of time may be different than what appears in the comments here.
**5: BASIC Stamp Command Reference – PUT**

**PUT**

<table>
<thead>
<tr>
<th>BS1</th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
</table>

**Location, Value**

**Function**

Put Value into Scratch Pad RAM Location.

- Location is a variable/constant/expression (0 – 63: BS2e/BS2sx, 0 - 127: BS2p) that specifies the Scratch Pad RAM location to write to.

- Value is a variable/constant/expression (0 - 255) to store in RAM.

**Quick Facts**

<table>
<thead>
<tr>
<th>BS2e, BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Scratch Pad RAM size and organization</td>
<td>64 bytes (0 – 63). Organized as bytes only.</td>
</tr>
<tr>
<td>General-purpose locations</td>
<td>0 – 62</td>
</tr>
<tr>
<td>Special use location</td>
<td>Current program slot number in read-only location 63.</td>
</tr>
</tbody>
</table>

**Explanation**

The PUT command writes a byte-sized value into the specified Scratch Pad RAM location. All values in the general-purpose locations can be written to from within any of the 8 program slots.

**Uses for Scratch Pad RAM.**

Scratch Pad RAM is useful for passing data to programs in other program slots and for additional workspace. It is different than regular RAM in that symbol names cannot be assigned directly to locations and each location is always configured as a byte only. The following code will write the value 100 to location 25, read it back out with GET, and display it:

```
Temp VAR BYTE
PUT 25, 100
GET 25, Temp
DEBUG DEC Temp
```

**Scratch Pad RAM locations and their purpose.**

Most Scratch Pad RAM locations are available for general use. The highest location (63 for BS2e/BS2sx and 127 for BS2p) is a special, read-only, location that always contains the number of the currently running program slot. On the BS2p, the upper nibble of location 127 also contains
the current program slot that will be used for the READ and WRITE commands. Any values written to this location will be ignored.

**Demo Program (GETPUT1.bsx)**

This example demonstrates the use of the GET and PUT commands. First, location 63 is read using GET to display the currently running program number. Then a set of values are written (PUT) into locations 0 to 9. Afterwards, program number 1 is run.

This program is a BS2sx project consisting of GETPUT1.bsx and GETPUT2.bsx. See the BASIC Stamp Project section in the manual for more information.

```
'stamp BS2sx, GETPUT2.BSX' 'STAMP directive (specifies a BS2sx and a second program, GETPUT2.BSX)

Value VAR BYTE
Index VAR BYTE

GET 63, Value
DEBUG "Program ", DEC Value, CR

FOR Index = 0 TO 9
    Value = (Index + 3) * 8
    PUT Index, Value
    DEBUG " Writing: ", DEC2 Value, " to location: ", DEC2 Index, CR
NEXT

RUN 1
```

**Demo Program (GETPUT2.bsx)**

This example demonstrates the use of the GET and PUT commands. First, location 63 is read using GET to display the currently running program number. Then a set of values are read (GET) from locations 0 to 9 and displayed on the screen for verification.

This program is a BS2sx project consisting of GETPUT1.bsx and GETPUT2.bsx. See the BASIC Stamp Project section in the manual for more information.

```
'stamp BS2sx' 'STAMP directive (specifies a BS2sx)

Value VAR BYTE
Index VAR BYTE

GET 63, Value
DEBUG CR, "Program ", DEC Value, CR

FOR Index = 0 TO 9
    GET Index, Value
    DEBUG " Reading: ", DEC2 Value, " from location: ", DEC2 Index, CR
NEXT

STOP
```
5: BASIC Stamp Command Reference – PWM

PWM

<table>
<thead>
<tr>
<th>BS1</th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
</table>

Pulse-width modulation (PWM) allows the BASIC Stamp (a purely digital device) to generate an analog voltage. The basic idea is this: If you make a pin output high, the voltage at that pin will be close to 5V. Output low is close to 0V. What if you switched the pin rapidly between high and low so that it was high half the time and low half the time? The average voltage over time would be halfway between 0 and 5V (2.5V). PWM emits a burst of 1s and 0s whose ratio is proportional to the duty value you specify.

The proportion of 1s to 0s in PWM is called the duty cycle. The duty cycle controls the analog voltage in a very direct way; the higher the duty cycle the higher the voltage. In the case of the BASIC Stamp, the duty cycle can range from 0 to 255. Duty is literally the proportion of 1s to 0s output by the PWM command. To determine the proportional PWM output voltage,

**Function**

Convert a digital value to analog output via pulse-width modulation.

- **Pin** is a variable/constant/expression (0 – 15) that specifies the I/O pin to use. This pin will be set to output mode initially then set to input mode when the command finishes.

- **Duty** is a variable/constant/expression (0 - 255) that specifies the analog output level (0 to 5V).

- **Cycles** is a variable/constant/expression (0 - 255) that specifies the duration of the PWM signal.

**Quick Facts**

### Table 5.65: PWM Quick Facts.

<table>
<thead>
<tr>
<th>Units in Cycles</th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Average voltage equation</td>
<td>1 ms</td>
<td>1 ms</td>
<td>400 µs</td>
<td>652 µs</td>
</tr>
<tr>
<td>Require charge time (Cycles) equation</td>
<td>Average Voltage = (Duty / 255) * 5 volts</td>
<td>Charge time = 4 * R * C</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Special notes</td>
<td>Pin is set to output initially, and set to input at end</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Explanation**

NOTE: Expressions are not allowed as arguments on the BS1. The range of the Pin argument on the BS1 is 0 – 7.
use this formula: \( \frac{\text{Duty}}{255} \times 5V \). For example, if \( \text{Duty} \) is 100, \( \frac{100}{255} \times 5V = 1.96V \); PWM outputs a train of pulses whose average voltage is 1.96V.

In order to convert PWM into an analog voltage we have to filter out the pulses and store the average voltage. The resistor/capacitor combination in Figure 5.27 will do the job. The capacitor will hold the voltage set by PWM even after the instruction has finished. How long it will hold the voltage depends on how much current is drawn from it by external circuitry, and the internal leakage of the capacitor. In order to hold the voltage relatively steady, a program must periodically repeat the PWM instruction to give the capacitor a fresh charge.

![Figure 5.27: Example PWM Filter Circuit.](image)

Just as it takes time to discharge a capacitor, it also takes time to charge it in the first place. The PWM command lets you specify the charging time in terms of PWM cycles. The period of each cycle is shown in Table 5.65. So, on the BS2, to charge a capacitor for 5ms, you would specify 5 cycles in the PWM instruction.

How do you determine how long to charge a capacitor? Use this rule-of-thumb formula: Charge time = \( 4 \times R \times C \). For instance, Figure 5.27 uses a 10k (\( 10 \times 10^3 \) ohm) resistor and a 1 \( \mu \text{F} \) (\( 1 \times 10^{-6} \) F) capacitor:

\[
\text{Charge time} = 4 \times 10 \times 10^3 \times 1 \times 10^{-6} = 40 \times 10^{-3} \text{ seconds, or 40 ms.}
\]

Since, on the BS2, each cycle is approximately a millisecond, it would take at least 40 cycles to charge the capacitor. Assuming the circuit is connected to pin 0, here’s the complete PWM instruction:

```
PWM 0, 100, 40 ' Put a 1.96V charge on capacitor.
```

After outputting the PWM pulses, the BASIC Stamp leaves the pin in input mode (0 in the corresponding bit of DIRS). In input mode, the pin’s output driver is effectively disconnected. If it were not, the steady output state of the pin would change the voltage on the capacitor and undo the
voltage setting established by PWM. Keep in mind that leakage currents of up to 1 µA can flow into or out of this “disconnected” pin. Over time, these small currents will cause the voltage on the capacitor to drift. The same applies for leakage current from an op-amp’s input, as well as the capacitor’s own internal leakage. Executing PWM occasionally will reset the capacitor voltage to the intended value.

PWM charges the capacitor; the load presented by your circuit discharges it. How long the charge lasts (and therefore how often your program should repeat the PWM command to refresh the charge) depends on how much current the circuit draws, and how stable the voltage must be. You may need to buffer PWM output with a simple op-amp follower if your load or stability requirements are more than the passive circuit of Figure 5.27 can handle.

The term “PWM” applies only loosely to the action of the BASIC Stamp's PWM command. Most systems that output PWM do so by splitting a fixed period of time into an on time (1) and an off time (0). Suppose the interval is 1 ms and the duty cycle is 100 / 255. Conventional PWM would turn the output on for 0.39 ms and off for 0.61 ms, repeating this process each millisecond. The main advantage of this kind of PWM is its predictability; you know the exact frequency of the pulses (in this case, 1 kHz), and their widths are controlled by the duty cycle.

BASIC Stamp's PWM does not work this way. It outputs a rapid sequence of on/off pulses, as short as 1.6 µs in duration, whose overall proportion over the course of a full PWM cycle of approximately a millisecond is equal to the duty cycle. This has the advantage of very quickly zeroing in on the desired output voltage, but it does not produce the neat, orderly pulses that you might expect. The BS2, BS2e, BS2sx and BS2p also uses this high-speed PWM to generate pseudo-sine wave tones with the DTMFOUT and FREQOUT instructions.
Demo Program (PWM.bs2)

' Connect a voltmeter (such as a digital multimeter set to its voltage range) to the output of
' the circuit shown in the figure for the PWM command (in the manual). Run the program
' and observe the readings on the meter. They should come very close to 1.96V, then
' decrease slightly as the capacitor discharges. Try varying the interval between PWM
' bursts (by changing the PAUSE value) and the number of PWM cycles to see their effect.

'[$STAMP BS2]    'STAMP directive (specifies a BS2)

Again:
PWM 0, 100, 40    ' 40 cycles of PWM at 100/255 duty
PAUSE 1000    ' Wait a second.
GOTO Again    ' Repeat

NOTE: This is written for the BS2
but can be used for the BS1, BS2e,
BS2sx and BS2p also. Locate the
proper source code file or modify
the STAMP directive and the Cycles
value of PWM before downloading
to the BS1, BS2e, BS2sx or BS2p.
5: BASIC Stamp Command Reference – RANDOM

RANDOM

Function
Generate a pseudo-random number.

- Variable is a variable (usually a word) whose bits will be scrambled to produce a random number. Variable acts as RANDOM's input and its result output. Each pass through RANDOM stores the next number, in the pseudorandom sequence, in Variable.

Explanation
RANDOM generates pseudo-random numbers ranging from 0 to 65535. They're called "pseudo-random" because they appear random, but are generated by a logic operation that uses the initial value in Variable to "tap" into a sequence of 65535 essentially random numbers. If the same initial value, called the "seed", is always used, then the same sequence of numbers is generated. The following example demonstrates this:

1 SYMBOL Result = W0
Loop:
  Result = 11000
  RANDOM Result
  DEBUG Result
  GOTO Loop

-- or --

Result VAR WORD
Loop:
  Result = 11000
  RANDOM Result
  DEBUG DEC ? Result
  GOTO Loop

In this example, the same number would appear on the screen over and over again. This is because the same seed value was used each time; specifically, the first line of the loop sets Result to 11,000. The RANDOM command really needs a different seed value each time. Moving the "Result =" line out of the loop will solve this problem, as in:
SYMBOL Result = W0
Result = 11000 ' Set initial "seed" value
Loop:
  RANDOM Result
  DEBUG Result
  GOTO Loop

-- or --

Result VAR WORD
Result = 11000 ' Set initial "seed" value
Loop:
  RANDOM Result
  DEBUG DEC ? Result
  GOTO Loop

Here, Result is only initialized once, before the loop. Each time through the loop, the previous value of Result, generated by RANDOM, is used as the next seed value. This generates a more desirable set of pseudorandom numbers.

In applications requiring more apparent randomness, it's necessary to "seed" RANDOM with a more random value every time. For instance, in the demo program below, RANDOM is executed continuously (using the previous resulting number as the next seed value) while the program waits for the user to press a button. Since the user can't control the timing of button presses very accurately, the results approach true randomness. Another possibility is to take advantage of the "floating" effect of unused input pins. Because any I/O pin that is an input, and is not electrically connected to anything, tends to "float" randomly between 0 and 1, this is a good source of a potential seed value. For example, if the upper 8 pins on a BS2 are not being used, leave them as inputs and don't electrically connect them (leave them "floating"). Then, use something like the following code to initialize the seed value:

Result = INH * 256 + INH ' Fill high and low byte with current, floating, value of I/O pins 8 - 15

NOTE: BS1's only have 8 I/O pins. There may not be enough unused pins to do something similar, but if so, use the PINS variable, rather than INH.
Demo Program (RANDOM.bas)

' Connect a button to I/O pin 7 as shown in the figure in the RANDOM command description
' (in the manual) and run this program. This program uses RANDOM to simulate a coin toss.
' After 100 trials, it reports the total number of heads and tails thrown.

'${STAMP BS1}

SYMBOL Flip = W0 ' The random number.
SYMBOL Coin = BIT0 ' A single bit of the random number.
SYMBOL Trials = B2 ' Number of flips.
SYMBOL Heads = B3 ' Number of throws that came up heads.
SYMBOL Tails = B4 ' Number of throws that came up tails.
SYMBOL Btn = B5 ' Workspace for Button instruction.

Start:
DEBUG CLS, "Press button to start"

FOR Trials = 1 TO 100   ' 100 tosses of the coin.
Hold:
    RANDOM Flip
    BUTTON 7, 0, 250, 100, Btn, 0, Hold
    BRANCH Coin,(Head,Tail)
Head:
    DEBUG CR, "HEADS"
    Heads = Heads + 1
    GOTO TheNext
Tail:
    DEBUG CR, "TAILS"
    Tails = Tails + 1
TheNext:
    NEXT

' When done, show the total number of heads and tails.
Demo Program (RANDOM.bs2)
' Connect a button to I/O pin 7 as shown in the figure in the RANDOM command description
' (in the manual) and run this program. This program uses RANDOM to simulate a coin toss.
' After 100 trials, it reports the total number of heads and tails thrown.

'${STAMP BS2}    'STAMP directive (specifies a BS2)
Flip    VAR WORD  ' The random number.
Coin    VAR Flip.BIT0  ' A single bit of the random number.
Trials  VAR BYTE   ' Number of flips.
Heads   VAR BYTE   ' Number of throws that came up heads.
Tails   VAR BYTE   ' Number of throws that came up tails.
Btn     VAR BYTE   ' Workspace for Button instruction.

Start:
  DEBUG CLS, "Press button to start"

FOR Trials = 1 TO 100   ' 100 tosses of the coin.
  Hold:
    RANDOM Flip
    BUTTON 7, 0, 250, 100, Btn, 0, Hold
    branch coin,[head,tail]
  Head:
    DEBUG CR, "HEADS"
    Heads = Heads + 1
    GOTO TheNext
  Tail:
    DEBUG CR, "TAILS"
    Tails = Tails + 1
    TheNext:
    NEXT
  branch coin,[head,tail]

END:

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, BS2sx or BS2p.
RCTIME

(See POT)

Function
Measure time while Pin remains in State; usually to measure the charge/discharge time of resistor/capacitor (RC) circuit.

- Pin is a variable/constant/expression (0 – 15) that specifies the I/O pin to use. This pin will be placed into input mode.
- State is a variable/constant/expression (0 - 1) that specifies the desired state to measure. Once Pin is not in State, the command ends and stores the result in Variable.
- Variable is a variable (usually a word) in which the time measurement will be stored. The unit of time for Variable is described in Table 5.66.

Quick Facts

<table>
<thead>
<tr>
<th>Units in Variable</th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>131.07 ms</td>
<td>2 µs</td>
<td>2 µs</td>
<td>0.8 µs</td>
<td>0.9 µs</td>
</tr>
</tbody>
</table>

Explanation
RCTIME can be used to measure the charge or discharge time of a resistor/capacitor circuit. This allows you to measure resistance or capacitance; use R or C sensors such as thermistors or capacitive humidity sensors or respond to user input through a potentiometer. In a broader sense, RCTIME can also serve as a fast, precise stopwatch for events of very short duration.

When RCTIME executes, it starts a counter (who's unit of time is shown in Table 5.66). It stops this counter as soon as the specified pin is no longer in State (0 or 1). If pin is not in State when the instruction executes, RCTIME will return 1 in Variable, since the instruction requires one timing cycle to discover this fact. If pin remains in State longer than 65535 timing cycles RCTIME returns 0.
Figure 5.29 shows suitable RC circuits for use with RCTIME. The circuit in 5.29a is preferred, because the BASIC Stamp's logic threshold is approximately 1.5 volts. This means that the voltage seen by the pin will start at 5V then fall to 1.5V (a span of 3.5V) before RCTIME stops. With the circuit of 5.29b, the voltage will start at 0V and rise to 1.5V (spanning only 1.5V) before RCTIME stops. For the same combination of R and C, the circuit shown in 5.29a will yield a higher count, and therefore more resolution than 5.29b.

Before RCTIME executes, the capacitor must be put into the state specified in the RCTIME instruction. For example, with figure 5.29a, the capacitor must be discharged until both plates (sides of the capacitor) are at 5V. It may seem counterintuitive that discharging the capacitor makes the input high, but remember that a capacitor is charged when there is a voltage difference between its plates. When both sides are at +5V, the cap is considered discharged.

Here’s a typical sequence of instructions for 5.29a (assuming I/O pin 7 is used):

```
Result VAR WORD ' Word variable to hold result.
HIGH 7 ' Discharge the cap
PAUSE 1 ' for 1 ms.
RCTIME 7,1,Result ' Measure RC charge time.
DEBUG ? Result ' Show value on screen.
```

Using RCTIME is very straightforward, except for one detail: For a given R and C, what value will RCTIME return? It’s easy to figure, based on a

---

**Figure 5.29: Example RC Circuits.**
Use A (left) with *State = 1*. Use B (right) with *State = 0*. (Note: Diagrams not included in text)
value called the RC time constant, or tau (τ) for short. Tau represents the
time required for a given RC combination to charge or discharge by 63
percent of the total change in voltage that they will undergo. More
importantly, the value τ is used in the generalized RC timing calculation.
Tau’s formula is just R multiplied by C:

\[ \tau = R \times C \]

The general RC timing formula uses τ to tell us the time required for an
RC circuit to change from one voltage to another:

\[ \text{time} = -\tau \times \left( \ln \left( \frac{V_{\text{final}}}{V_{\text{initial}}} \right) \right) \]

In this formula ln is the natural logarithm; it’s a key on most scientific
calculators. Let’s do some math. Assume we’re interested in a 10 k
resistor and 0.1 µF cap. Calculate τ:

\[ \tau = (10 \times 10^3) \times (0.1 \times 10^{-6}) = 1 \times 10^{-3} \]

The RC time constant is 1 x 10^-3 or 1 millisecond. Now calculate the time
required for this RC circuit to go from 5V to 1.5V (as in Figure 5.29a):

\[ \text{Time} = -1 \times 10^{-3} \times \left( \ln(5.0v / 1.5v) \right) = 1.204 \times 10^{-3} \]

On the BS2, the unit of time is 2µs (See Table 5.66), that time (1.204 x 10^-3)
works out to 602 units. With a 10 k resistor and 0.1 µF cap, RCTIME would
return a value of approximately 600. Since \( V_{\text{initial}} \) and \( V_{\text{final}} \) doesn’t change,
we can use a simplified rule of thumb to estimate RCTIME results for
circuits like 5.29a:

\[ \text{RCTIME units} = 600 \times R \text{ (in kΩ)} \times C \text{ (in µF)} \]

Another handy rule of thumb can help you calculate how long to
charge/discharge the capacitor before RCTIME. In the example above
that’s the purpose of the HIGH and PAUSE commands. A given RC
charges or discharges 98 percent of the way in 4 time constants (4 x R x C).
In Figure 5.29, the charge/discharge current passes through the 220 Ω
series resistor and the capacitor. So if the capacitor were 0.1 µF, the
minimum charge/discharge time should be:
Charge time = 4 x 220 x (0.1 x 10^{-6}) = 88 x 10^{-6}

So it takes only 88 µs for the cap to charge/discharge, meaning that the 1 ms charge/discharge time of the example is plenty.

A final note about Figure 5.29: You may be wondering why the 220 Ω resistor is necessary at all. Consider what would happen if resistor R in Figure 5.29a were a pot, and were adjusted to 0 Ω. When the I/O pin went high to discharge the cap, it would see a short direct to ground. The 220 Ω series resistor would limit the short circuit current to 5V/220 Ω = 23 mA and protect the BASIC Stamp from damage. (Actual current would be quite a bit less due to internal resistance of the pin’s output driver, but you get the idea.)

Demo Program (RCTIME1.bs2)
‘ This program shows the standard use of the RCTIME instruction measuring an RC
‘ charge/discharge time. Use the circuit in the RCTIME description (in the manual)
‘ with R = 10 k pot and C = 0.1 µf. Connect the circuit to pin 7 and run the program.
‘ Adjust the pot and watch the value shown on the Debug screen change.

‘{$STAMP BS2} ‘STAMP directive (specifies a BS2)
Result VAR WORD ‘Word variable to hold result.
Again:
    HIGH 7 ‘Discharge the cap
    PAUSE 1 ‘for 1 ms.
    RCTIME 7, 1, Result ‘Measure RC charge time.
    DEBUG CLS, DEC Result ‘Show value on screen.
GOTO Again

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, BS2sx or BS2p.
Figure 5.30: Relay circuit for Demo Program 2.

Demo Program (RCTIME2.bs2)

'This program illustrates the use of RCTIME as a fast stopwatch. The program energizes a relay coil, then measures how long it takes for the relay contacts to close. Figure 5.30 shows the circuit. Note that RCTIME doesn't start timing instantly.

'($STAMP BS2)
'STAMP directive (specifies a BS2)

Result VAR WORD

Again:
Low 6
RCTIME 7, 1, Result
DEBUG "Time to close: ", DEC Result, CR
HIGH 6
PAUSE 1000
GOTO Again

'Energize relay coil.
'Measure time to contact closure.
'Release the relay.
'Wait a second.
'Do it again.
5: BASIC Stamp Command Reference – READ

READ

Function
Read value at Location in EEPROM and store the result in result in Variable.

- **Location** is a variable/constant/expression (0 – 255 on BS1, 0 – 2047 on all other BASIC Stamps) that specifies the EEPROM address to read from.

- **Variable** is a variable (usually a byte) where the value is stored.

Quick Facts

<table>
<thead>
<tr>
<th>BS1</th>
<th>BS2, BS2e, BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 to 255</td>
<td>0 to 2047</td>
<td>0 to 2047 (see notes below)</td>
</tr>
<tr>
<td>n/a</td>
<td>READ only works with current program slot on BS2e and BS2sx.</td>
<td>READ works with any program slot as set by the STORE command.</td>
</tr>
</tbody>
</table>

Explanation
The EEPROM is used for both program storage (which builds downward from address 255 on BS1, 2047 on all other BASIC Stamps) and data storage (which builds upward from address 0). The READ instruction retrieves a byte of data from any EEPROM address and stores that byte in Variable. Any location within the EEPROM can be read (including your PBASIC program's tokens) at run-time. This feature is mainly used to retrieve long-term data from EEPROM; data stored in EEPROM is not lost when the power is removed.

A simple READ command.

The following READ command retrieves the value at location 100 and stores it into the variable called Result:

```
SYMBOL Result = B0
READ 100, Result
```

---or---

```
Result VAR BYTE
READ 100, Result
```
The EEPROM is organized as a sequential set of byte-sized memory locations. The READ command only retrieves byte-sized values from EEPROM. This does not mean that you can’t read word-sized values, however. A word consists of two bytes, called a low-byte and a high-byte. If you wanted to read a word-sized value, you’ll need to use two READ commands and a word-size variable (along with some handy modifiers). For example,

```basic
SYMBOL Result   = W0 'The full word-sized variable
SYMBOL Result_Low = B0 'B0 happens to be the low-byte of W0
SYMBOL Result_High = B1 'B1 happens to be the high-byte of W0
EEPROM (101, 4) 'Store word-sized value in locations 0 and 1
READ 0, Result_Low
READ 1, Result_High
DEBUG #Result
```

--or--

```basic
Result VAR WORD
DATA word 1125 'Store word-sized value in locations 0 and 1
READ 0, Result.LOWBYTE
READ 1, Result.HIGHBYTE
DEBUG DEC Result
```

This code uses the EEPROM or DATA directive to write the low-byte and high-byte of the number 1125 into locations 0 and 1 during download. When the program runs, the two READ commands will read the low-byte and high-byte out of EEPROM (reconstructing it in a word-size variable) and then display the value on the screen.

Note that the EEPROM and DATA directives store data in the EEPROM before the program runs, however, the WRITE command can be used to store data while the program is running. Additionally, the EEPROM locations can be read an unlimited number of times, but EEPROM locations can be worn out by excessive writes. See the WRITE command for more information.

When using the READ and WRITE commands, take care to ensure that your program doesn’t overwrite itself. On the BS1, location 255 holds the address of the last instruction in your program. Therefore, your program can use any space below the address given in location 255. For example, if
location 255 holds the value 100, then your program can use locations 0–99 for data.

On other BASIC Stamps, you'll need to view the Memory Map of the program before you download it, to determine the last EEPROM location used. See the "Memory Map Function" section in Chapter 3.

On the BS2p, the READ and WRITE commands can affect locations in any program slot as set by the STORE command. See the STORE command for more information.

Demo Program (READ.bas)

' This program reads a string of data stored in EEPROM. The EEPROM data is downloaded to the BS1 at compile-time and remains there (even with the power off) until overwritten. Put ASCII characters into EEPROM, followed by 0, which will serve as the end-of-message marker.

'({$STAMP  BS1})  'STAMP directive (specifies a BS1)
EEPROM ("BS1 EEPROM Storage!",0)

SYMBOL StrAddr = W0
SYMBOL Char = B2

StrAddr = 0    'Set address to start of Message.

StringOut:
  READ StrAddr,Char   'Get a byte from EEPROM.
  IF Char <> 0 THEN Cont  'Not end? Continue.
END      'Stop here when done.

Cont:
  DEBUG @Char    'Show character on screen.
  StrAddr = StrAddr + 1   'Point to next character.
  GOTO StringOut    'Get next character.

Demo Program (READ.bs2)

' This program reads a string of data stored in EEPROM. The EEPROM data is downloaded to the BS2 at compile-time and remains there (even with the power off) until overwritten. Put ASCII characters into EEPROM, followed by 0, which will serve as the end-of-message marker.

'({$STAMP  BS2})  'STAMP directive (specifies a BS2)

Message DATA "BS2 EEPROM Storage!",0

StrAddr VAR WORD
Char VAR BYTE

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, BS2sx or BS2p.
StrAddr = Message

StringOut:
  READ StrAddr, Char
  IF Char <> 0 THEN Cont
Stop
Cont:
  DEBUG Char
  StrAddr = StrAddr + 1
GOTO StringOut

'Set address to start of Message.

'Get a byte from EEPROM.

'Not end? Continue.

'Stop here when done.

'Show character on screen.

'Point to next character.

'Get next character.
# 5: BASIC Stamp Command Reference – RETURN

## RETURN

### Function
Return from a subroutine, assuming there was a previous GOSUB executed.

### Quick Facts

**Table 5.68: RETURN Quick Facts.**

<table>
<thead>
<tr>
<th>Maximum number of RETURNS per program</th>
<th>BS1, BS2, BS2e, BS2sx and BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Unlimited. However, the number of GOSUBs are limited. See GOSUB for more information.</td>
<td></td>
</tr>
</tbody>
</table>

### Explanation
RETURN sends the program back to the address (instruction) immediately following the most recent GOSUB. If RETURN is executed without a prior GOSUB, the BASIC Stamp will return to the first executable line of the program; usually resulting in a logical bug in the code. See the GOSUB command for more information.

The example below will start out by GOSUB'ing to the section of code beginning with the label `Hello`. It will print "Hello my friend." on the screen then RETURN to the line after the GOSUB... which prints "How are you?" and ENDS.

```plaintext
GOSUB Hello
DEBUG "How are you?"
END

Hello:
  DEBUG "Hello my friend.", CR
RETURN
```

There's another interesting lesson here; what would happen if we removed the END command from this example? Since the BASIC Stamp reads the code from left to right / top to bottom (like the English language) once it had returned to and run the "How are you?" line, it would naturally "fall into" the `Hello` routine again. Additionally, at the end of the `Hello` routine, it would see the RETURN again (although it didn't GOSUB to that routine...

---

**NOTE:** On the BS1, a RETURN without a GOSUB will return the program to the last GOSUB (or will end the program if no GOSUB was executed).
this time) and because there wasn't a previous place to return to, the BASIC Stamp will start the entire program over again. This would cause an endless loop. The important thing to remember here is to always make sure your program doesn't allow itself to "fall into" a subroutine.

**Demo Program (RETURN.bs2)**

```
'{STAMP  BS2}    'STAMP directive (specifies a BS2)
DEBUG "Starting Program",CR 'Indicate the start of the program
Main:
  PAUSE 1000
  GOSUB DemoSub 'Call the subroutine
  PAUSE 1000
  DEBUG "Returned from Subroutine", CR 'Indicate the return from the subroutine
  PAUSE 1000
DemoSub:
  DEBUG " Executing Subroutine", CR 'Indicate the execution of the subroutine
  RETURN
```

**NOTE:** This is written for the BS2 but can be used for the BS1, BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS1, BS2e, BS2sx or BS2p.
**Reverse**

Function

Reverse the data direction of the specified pin.

- *Pin* is a variable/constant/expression (0 – 15) that specifies the I/O pin to use. This pin will be placed into the mode opposite of its current input/output mode.

Explanation

REVERSE is convenient way to switch the I/O direction of a pin. If the pin is an input, REVERSE makes it an output; if it’s an output, REVERSE makes it an input.

Remember that “input” really has two meanings: (1) Setting a pin to input makes it possible to check the state (1 or 0) of external circuitry connected to that pin. The current state is in the corresponding bit of the INS register (PINS on the BS1). (2) Setting a pin to input also disconnects the output driver, the corresponding bit of OUTS (PINS on the BS1).

The demo program below illustrates this second fact with a two-tone LED blinks.

**Figure 5.31:** LED circuit for Demo Programs.
Demo Program (REVERSE.bas)

' Connect the circuit shown in the REVERSE command description to I/O pin 0 and run this ' program. The LED will alternate between two states, dim and bright. The BASIC Stamp is ' using the REVERSE command to toggling I/O pin 0 between input and output states. When ' pin 0 is an input, current flows through R1, through the LED, through R2 to ground. Pin 0 is ' effectively disconnected and doesn't play a part in the circuit. The total resistance ' encountered by current flowing through the LED is R1 + R2 = 440 Ohms. When pin 0 is ' reversed to an output, current flows through R1, through the LED, and into pin 0 to ground ' (because of the 0 written to PIN0). The total resistance encountered by current flowing ' through the LED is R1, 220 Ohms. With only half the resistance, the LED glows brighter.

'{$STAMP BS1}    'STAMP directive (specifies a BS1)

PIN0 = 0  ' Put a low in the pin 0 output driver.

Again:
PAUSE 200  ' Brief (1/5th second) pause.
REVERSE 0  ' Invert pin 0 I/O direction.
GOTO Again  ' Repeat forever.

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, BS2sx or BS2p.

Demo Program (REVERSE.bs2)

' Connect the circuit shown in the REVERSE command description to I/O pin 0 and run this ' program. The LED will alternate between two states, dim and bright. The BASIC Stamp is ' using the REVERSE command to toggling I/O pin 0 between input and output states. When ' pin 0 is an input, current flows through R1, through the LED, through R2 to ground. Pin 0 is ' effectively disconnected and doesn't play a part in the circuit. The total resistance ' encountered by current flowing through the LED is R1 + R2 = 440 Ohms. When pin 0 is ' reversed to an output, current flows through R1, through the LED, and into pin 0 to ground ' (because of the 0 written to OUT0). The total resistance encountered by current flowing ' through the LED is R1, 220 Ohms. With only half the resistance, the LED glows brighter.

'{$STAMP BS2}    'STAMP directive (specifies a BS2)

OUT0 = 0   ' Put a low in the pin 0 output driver.

Again:
PAUSE 200  ' Brief (1/5th second) pause.
REVERSE 0  ' Invert pin 0 I/O direction.
GOTO Again  ' Repeat forever.
Function
Switches execution to another BASIC Stamp program (in a different program slot).
- *Program* is a variable/constant/expression (0 – 7) that specifies the program slot to run.

### Quick Facts

<table>
<thead>
<tr>
<th></th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Number of program slots</strong></td>
<td>8 (numbered 0 to 7)</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Time delay to switch between program slots</strong></td>
<td>770 µs</td>
<td>300 µs</td>
<td>250 µs</td>
</tr>
<tr>
<td><strong>Special notes</strong></td>
<td>RUN is similar to a GOTO… you can not &quot;return&quot; from a RUN</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Explanation
The BS2e, BS2sx and BS2p have a total of 16k bytes of code space. This code space is organized into eight slots of 2 kbytes each. Up to eight different programs can be downloaded to the BASIC Stamp (one program per slot). When the BASIC Stamp powers up, or is reset, the program in slot 0 is executed.

The RUN command allows you to activate another program and causes the BASIC Stamp to stay in the newly activated program until it receives another RUN command, or until a power-down or reset condition occurs. The RUN command is similar to a GOTO command in that it allows you to "goto" another program. Normally a master-type program will be used in program slot 0 (since slot 0 runs first) and will control initial execution of the other programs.

Look at the following example (there are two programs here, make sure to download them into program slots 0 and 1, respectively):
' Download the following two lines into program slot 0
DEBUG "Hello"
RUN 1

'Download the following three lines into program slot 1
DEBUG "World!", CR
PAUSE 0
RUN 0

The above two programs (assuming they have been downloaded into program slots 0 and 1, respectively) will display "Hello World!" on the screen. Program 0 is the first to run and it displays "Hello", then issues a RUN 1 command. The BASIC Stamp then starts execution of program 1, from its first line of code, which causes "World!" to be displayed. Program 1 then pauses for 1 second and the runs program 0 again.

The I/O pins retain their current state (directions and output latches) and all Variable and Scratch Pad RAM locations retain their current data during a transition between programs with the RUN command. If sharing data between programs within Variable RAM, make sure to keep similar variable declarations (defined in the same order) in all programs so that the variables align themselves on the proper word, byte, nibble and bit boundaries across programs.

Any program number specified above 7 will wrap around and result in running one of the 8 programs (RUN 8 will run program 0, RUN 9 will run program 1, etc).

Review the BASIC Stamp Project section for more information on downloading multiple programs to a BS2e, BS2sx or BS2p.

Demo Program (RUN1.bsx)

' This example demonstrates the use of the RUN command. First, location 63 is read ' using the GET command to display the currently running program number. Then a set ' of values (based on the program number) are displayed on the screen. Afterwards, ' program number 1 is run. This program is a BS2sx project consisting of RUN1.bsx and ' RUN2.bsx. See the BASIC Stamp Project section in the manual for more information.

'${STAMP BS2sx, RUN2.BSX}' 'STAMP directive (specifies a BS2sx and 'a second program, RUN2.BSX)

DATA 100, 40, 80, 35, 91

NOTE: This is written for the BS2sx but can be used for the BS2e, and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, or BS2p.
Demo Program (RUN2.bsx)

This example demonstrates the use of the RUN command. First, location 63 is read using the GET command to display the currently running program number. Then a set of values (based on the program number) are displayed on the screen. Afterwards, program number 0 is run. This program is a BS2sx project consisting of RUN1.bsx and RUN2.bsx. See the BASIC Stamp Project section in the manual for more information.

```
{:STAMP  BS2sx}    'STAMP directive (specifies a BS2sx and a second program, RUN2.BSX)
```

```
DATA 100, 40, 80, 35, 91
DATA 200, 65, 23, 70, 90

ProgNum VAR BYTE
Value VAR BYTE
Index VAR BYTE

GET  63, ProgNum
DEBUG "Program ", DEC ProgNum, CR

FOR Index = 0 TO 4
    READ ProgNum*5+Index, Value
    DEBUG DEC3 Value, " "
NEXT
DEBUG CR
PAUSE 1000
RUN 0
```
SERIN

Function
Receive asynchronous serial data (e.g., RS-232 data).

- **Rpin** is a variable/constant/expression (0 – 16) that specifies the I/O pin through which the serial data will be received. This pin will be set to input mode. On the BS2, BS2e, BS2sx and BS2p, if Rpin is set to 16, the BASIC Stamp uses the dedicated serial-input pin (SIN, physical pin 2), which is normally used by the Stamp Editor during the download process.

- **Fpin** is an optional variable/constant/expression (0 – 15) that specifies the I/O pin to indicate flow control status on. This pin will be set to output mode.

- **Baudmode** is variable/constant/expression (0 – 7 on the BS1, 0 – 65535 on all other BASIC Stamps) that specifies serial timing and configuration.

- **Qualifier** is an optional variable/constant (0 – 255) indicating data that must be received before execution can continue. Multiple qualifiers can be indicated with commas separating them.

- **Plabel** is an optional label indicating where the program should go in the event of a parity error. This argument should only be provided if **Baudmode** indicates 7 bits, and even parity.

- **Timeout** is an optional variable/constant/expression (0 – 65535) that tells SERIN how long to wait for incoming data. If data does not arrive in time, the program will jump to the address specified by **Tlabel**.

- **Tlabel** is an optional label that must be provided along with **Timeout**, indicating where the program should go in the event that data does not arrive within the period specified by **Timeout**.

- **InputData** is list of variables and formatters that tells SERIN what to do with incoming data. SERIN can store data in a variable or array, interpret numeric text (decimal, binary, or hex) and store the

NOTE: Expressions are not allowed as arguments on the BS1. The range of the Rpin argument on the BS1 is 0 – 7.

NOTE: The BS1’s **InputData** argument can only be a list of variables and the optional decimal modifier (#).
corresponding value in a variable, wait for a fixed or variable sequence of bytes, or ignore a specified number of bytes. These actions can be combined in any order in the InputData list.

Quick Facts

<table>
<thead>
<tr>
<th>BS1</th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Units in Timeout</td>
<td>n/a</td>
<td>1 ms</td>
<td>1 ms</td>
<td>400 µs</td>
</tr>
<tr>
<td>Baud Range</td>
<td>300, 600, 1200, and 2400 only</td>
<td>243 to 50K</td>
<td>243 to 50K</td>
<td>608 to 115K</td>
</tr>
<tr>
<td>Baud Limit with Flow Control</td>
<td>n/a</td>
<td>19.2K</td>
<td>19.2K</td>
<td>19.2K</td>
</tr>
<tr>
<td>Limit to Qualifiers</td>
<td>Unlimited</td>
<td>6 (in WAIT formatter)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>I/O Pins Available</td>
<td>0 - 7</td>
<td>0 - 15</td>
<td>0 - 15</td>
<td>0 - 15</td>
</tr>
<tr>
<td>Other Serial Port Pins</td>
<td>n/a</td>
<td>SIN pin (physical pin 2) when Rpin = 16</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Table 5.70: SERIN Quick Facts.

Explanation

One of the most popular forms of communication between electronic devices is serial communication. There are two major types of serial communication; asynchronous and synchronous. The SERIN and SEROUT commands are used to receive and send asynchronous serial data. See the SHIFTIN and SHIFTOUT command for information on the synchronous method.

SERIN can wait for, filter and convert incoming data in powerful ways. SERIN deserves some lengthy discussion, below, since all this power brings some complexity.

The term asynchronous means “no clock.” More specifically, "asynchronous serial communication" means data is transmitted and received without the use of a separate "clock" wire. Data can be sent using as little as two wires; one for data and one for ground. The PC’s serial ports (also called COM ports or RS-232 ports) use asynchronous serial communication. Note: the other kind of serial communication, synchronous, uses at least three wires; one for clock, one for data and one for ground.
RS-232 is the electrical specification for the signals that PC serial ports use. Unlike normal logic, where a 5 volts is a logic 1 and 0 volts is logic 0, RS-232 uses -12 volts for logic 1 and +12 volts for logic 0. This specification allows communication over longer wire lengths without amplification.

Most circuits that work with RS-232 use a line driver/receiver. This component does two things: (1) it converts the ±12 volts of RS-232 to TTL-compatible 0 to 5-volt levels and (2) it inverts the relationship of the voltage levels, so that 5 volts = logic 1 and 0 volts = logic 0.

All BASIC Stamps (except the BS1) have a line receiver on its SIN pin (Rpin = 16). See the "Hardware" section of the "Introduction to the BASIC Stamps" chapter. The SIN pin goes to a PC’s serial data-out pin on the DB9 connector built into BASIC Stamp development boards. The connector is wired to allow both programming and run-time serial communication (unless you are using the Stamp 2 Carrier Board which is only designed for programming). For the built-in serial port set the Rpin argument to 16 in the SERIN command.

All BASIC Stamps (including the BS1) can also receive RS-232 data through any of their I/O pins (Rpin = 0 – 7 for BS1, Rpin = 0 – 15 on all other BASIC Stamps). The I/O pins don’t need a line receiver, just a 22 kΩ resistor. The resistor limits current into the I/O pins’ built-in clamping diodes, which keep input voltages within a safe range. See Figure 5.32

---

**Figure 5.32:** Serial Port Diagram Showing Correct Connections to a BASIC Stamp’s I/O pin. NOTE: The 22 kΩ resister is not required if connecting to the SIN pin.

<table>
<thead>
<tr>
<th>Function</th>
<th>DB9</th>
<th>DB25</th>
</tr>
</thead>
<tbody>
<tr>
<td>Data Carrier Detect (DCD)</td>
<td>1</td>
<td>8</td>
</tr>
<tr>
<td>Receive Data (RD)</td>
<td>2</td>
<td>3</td>
</tr>
<tr>
<td>Transmit Data (TD)</td>
<td>3</td>
<td>2</td>
</tr>
<tr>
<td>Data Terminal Ready (DTR)</td>
<td>4</td>
<td>20</td>
</tr>
<tr>
<td>Signal Ground (SG)</td>
<td>5</td>
<td>7</td>
</tr>
<tr>
<td>Data Set Ready (DSR)</td>
<td>6</td>
<td>6</td>
</tr>
<tr>
<td>Request to Send (RTS)</td>
<td>7</td>
<td>4</td>
</tr>
<tr>
<td>Clear to Send (CTS)</td>
<td>8</td>
<td>5</td>
</tr>
</tbody>
</table>

NOTE: The connections shown with double-lines are normally not necessary. They indicate optional connections to disable hardware handshaking (DTR-DSR-DCD and RTS-CTS). This is only necessary if you are using software or hardware that expects hardware handshaking.
Figure 5.32 shows the pinouts of the two styles of PC serial ports and how to connect them to the BASIC Stamp’s I/O pin (the 22K resistor is not needed if connecting to the SIN pin). Though not normally needed, the figure also shows loop back connections that defeat hardware handshaking used by some PC software. Note that PC serial ports are always male connectors. The 25-pin style of serial port (called a DB25) looks similar to a printer (parallel) port except that it is male, whereas a parallel port is female.

Asynchronous serial communication relies on precise timing. Both the sender and receiver must be set for identical timing, usually expressed in bits per second (bps) called baud.

On all BASIC Stamps, SERIN requires a value called *Baudmode* that tells it the important characteristics of the incoming serial data; the bit period, number of data and parity bits, and polarity.

On the BS1, serial communication is limited to: no-parity, 8-data bits and 1-stop bit at one of four different speeds: 300, 600, 1200 or 2400 baud. Table 5.71 indicates the *Baudmode* value or symbols to use when selecting the desired mode.

<table>
<thead>
<tr>
<th>Baudmode Value</th>
<th>Symbol</th>
<th>Baud Rate</th>
<th>Polarity</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>T2400</td>
<td>2400</td>
<td>TRUE</td>
</tr>
<tr>
<td>1</td>
<td>T1200</td>
<td>1200</td>
<td>TRUE</td>
</tr>
<tr>
<td>2</td>
<td>T600</td>
<td>600</td>
<td>TRUE</td>
</tr>
<tr>
<td>3</td>
<td>T300</td>
<td>300</td>
<td>TRUE</td>
</tr>
<tr>
<td>4</td>
<td>N2400</td>
<td>2400</td>
<td>INVERTED</td>
</tr>
<tr>
<td>5</td>
<td>N1200</td>
<td>1200</td>
<td>INVERTED</td>
</tr>
<tr>
<td>6</td>
<td>N600</td>
<td>600</td>
<td>INVERTED</td>
</tr>
<tr>
<td>7</td>
<td>N300</td>
<td>300</td>
<td>INVERTED</td>
</tr>
</tbody>
</table>

Table 5.71: BS1 Baudmode values.

On the BS2, BS2e, BS2sx and BS2p, serial communication is very flexible. The *Baudmode* argument for SERIN accepts a 16-bit value that determines its characteristics: 1-stop bit, 8-data bits/no-parity or 7-data bits/even-parity and virtually any speed from as low as 300 baud to greater than 100K baud (depending on the BASIC Stamp). Table 5.72
shows how Baudmode is calculated and Tables 5.73, 5.74 and 5.75 show common baud modes for standard serial baud rates.

<table>
<thead>
<tr>
<th>Baud Rate</th>
<th>8-bit no-parity</th>
<th>8-bit no-parity</th>
<th>7-bit even-parity</th>
<th>7-bit even-parity</th>
</tr>
</thead>
<tbody>
<tr>
<td>300</td>
<td>19697</td>
<td>3313</td>
<td>27889</td>
<td>11505</td>
</tr>
<tr>
<td>600</td>
<td>18030</td>
<td>1646</td>
<td>26222</td>
<td>9838</td>
</tr>
<tr>
<td>1200</td>
<td>17197</td>
<td>813</td>
<td>25389</td>
<td>9005</td>
</tr>
<tr>
<td>2400</td>
<td>16780</td>
<td>396</td>
<td>24972</td>
<td>8588</td>
</tr>
<tr>
<td>4800*</td>
<td>16572</td>
<td>188</td>
<td>24764</td>
<td>8380</td>
</tr>
<tr>
<td>9600*</td>
<td>16468</td>
<td>84</td>
<td>24660</td>
<td>8276</td>
</tr>
</tbody>
</table>

*The BASIC Stamp 2 and BASIC Stamp 2e may have trouble synchronizing with the incoming serial stream at this rate and higher due to the lack of a hardware input buffer. Use only simple variables and no formatters to try to solve this problem.

<table>
<thead>
<tr>
<th>Baud Rate</th>
<th>8-bit no-parity</th>
<th>8-bit no-parity</th>
<th>7-bit even-parity</th>
<th>7-bit even-parity</th>
</tr>
</thead>
<tbody>
<tr>
<td>1200</td>
<td>18447</td>
<td>2063</td>
<td>26639</td>
<td>10255</td>
</tr>
<tr>
<td>2400</td>
<td>17405</td>
<td>1021</td>
<td>25597</td>
<td>9213</td>
</tr>
<tr>
<td>4800</td>
<td>16884</td>
<td>500</td>
<td>25076</td>
<td>8692</td>
</tr>
<tr>
<td>9600*</td>
<td>16624</td>
<td>240</td>
<td>24816</td>
<td>8432</td>
</tr>
</tbody>
</table>

*The BASIC Stamp 2sx may have trouble synchronizing with the incoming serial stream at this rate and higher due to the lack of a hardware input buffer. Use only simple variables and no formatters to try to solve this problem.

<table>
<thead>
<tr>
<th>Baud Rate</th>
<th>8-bit no-parity</th>
<th>8-bit no-parity</th>
<th>7-bit even-parity</th>
<th>7-bit even-parity</th>
</tr>
</thead>
<tbody>
<tr>
<td>1200</td>
<td>18447</td>
<td>2063</td>
<td>26639</td>
<td>10255</td>
</tr>
<tr>
<td>2400</td>
<td>17405</td>
<td>1021</td>
<td>25597</td>
<td>9213</td>
</tr>
<tr>
<td>4800</td>
<td>16884</td>
<td>500</td>
<td>25076</td>
<td>8692</td>
</tr>
<tr>
<td>9600*</td>
<td>16624</td>
<td>240</td>
<td>24816</td>
<td>8432</td>
</tr>
</tbody>
</table>

*The BASIC Stamp 2p may have trouble synchronizing with the incoming serial stream at this rate and higher due to the lack of a hardware input buffer. Use only simple variables and no formatters to try to solve this problem.
If you’re communicating with existing software or hardware, its speed(s) and mode(s) will determine your choice of baud rate and mode. In general, 7-bit/even-parity (7E) mode is used for text, and 8-bit/no-parity (8N) for byte-oriented data. Note: the most common mode is 8-bit/no-parity, even when the data transmitted is just text. Most devices that use a 7-bit data mode do so in order to take advantage of the parity feature. Parity can detect some communication errors, but to use it you lose one data bit. This means that incoming data bytes transferred in 7E (even-parity) mode can only represent values from 0 to 127, rather than the 0 to 255 of 8N (no-parity) mode.

Usually a device requires only 1 stop bit per byte. Occasionally, however, you may find a device that requires 2 or more stop bits. Since a stop bit is really just a delay between transmitted bytes (leaving the line in a resting state) the BASIC Stamp can receive transmissions with multiple stop bits per byte without any trouble. In fact, sometimes it is desirable to have multiple stop bits (see the “SERIN Troubleshooting” section, below, for more information).

The example below will receive a single byte through I/O pin 1 at 2400 baud, 8N1, inverted:

Symbol SerData = B0
SERIN 1, N2400, SerData

--or--

SerData VAR BYTE
SERIN 1, 16780, [SerData]

Here, SERIN will wait for and receive a single byte of data through pin 1 and store it in the variable SerData. If the BASIC Stamp were connected to a PC running a terminal program (set to the same baud rate) and the user pressed the "A" key on the keyboard, after the SERIN command executed, the variable SerData would contain 65, the ASCII code for the letter "A" (see the ASCII character chart in the appendix).

What would happen if, using the example above, the user pressed the "1" key? The result would be that SerData would contain the value 49 (the ASCII code for the character "1"). This is a critical point to remember: every time you press a character on the keyboard, the computer receives the ASCII value of that character. It is up to the receiving side (in serial
communication) to interpret the values as necessary. In this case, perhaps we actually wanted SerData to end up with the value 1, rather than the ASCII code 49.

The SERIN command provides a formatter, called the decimal formatter, which will interpret this for us. Look at the following code:

```
Symbol SerData = B0
SERIN 1, N2400, #SerData
```

---or---

```
SerData VAR BYTE
SERIN 1, 16780, [DEC SerData]
```

Notice the decimal formatter in the SERIN command. It is the “#” (for the BS1) or “DEC” (for the other BASIC Stamps) that appears just to the left of the SerData variable. This tells SERIN to convert incoming text representing decimal numbers into true-decimal form and store the result in SerData. If the user running the terminal software pressed the "1", "2" and then "3" keys followed by a space or other non-numeric text, the value 123 will be stored in SerData. Afterwards, the program can perform any numeric operation on the number just like with any other number. Without the decimal formatter, however, you would have been forced to receive each character ("1", "2" and "3") separately, and then would still have to do some manual conversion to arrive at the number 123 (one hundred twenty three) before you can do the desired calculations on it.

The decimal formatter is designed to seek out text that represents decimal numbers. The characters that represent decimal numbers are the characters “0” through “9”. Once the SERIN command is asked to use the decimal formatter for a particular variable, it monitors the incoming serial data, looking for the first decimal character. Once it finds the first decimal character, it will continue looking for more (accumulating the entire multi-digit number) until it finds a non-decimal numeric character. Keep in mind that it will not finish until it finds at least one decimal character followed by at least one non-decimal character.
To further illustrate this, consider the following examples (assuming we’re using the same code example as above):

1) **Serial input:** ABC  
   **Result:** The BASIC Stamp halts at the SERIN command, continuously waiting for decimal text.

2) **Serial input:** 123 (with no characters following it)  
   **Result:** The BASIC Stamp halts at the SERIN command. It recognizes the characters “1”, “2” and “3” as the number one hundred twenty three, but since no characters follow the “3”, it waits continuously, since there’s no way to tell whether 123 is the entire number or not.

3) **Serial input:** 123 (followed by a space character)  
   **Result:** Similar to example 2, above, except once the space character is received, the BASIC Stamp knows the entire number is 123, and stores this value in **SerData**. The SERIN command then ends, allowing the next line of code, if any, to run.

4) **Serial input:** 123A  
   **Result:** Same as example 3, above. The “A” character, just like the space character, is the first non-decimal text after the number 123, indicating to the BASIC Stamp that it has received the entire number.

5) **Serial input:** ABCD123EFGH  
   **Result:** Similar to examples 3 and 4 above. The characters “ABCD” are ignored (since they’re not decimal text), the characters “123” are evaluated to be the number 123 and the following character, “E”, indicates to the BASIC Stamp that it has received the entire number.

Of course, as with all numbers in the BASIC Stamp, the final result is limited to 16 bits (up to the number 65535). If a number larger than this is received by the decimal formatter, the end result will look strange because the result rolled-over the maximum 16-bit value.

The BS1 is limited to the decimal formatter shown above, however the BS2, BS2e, BS2sx and BS2p have many more conversion formatters.

**WATCH OUT FOR ROLLOVER ERRORS.**
available for the SERIN command. If not using a BS1, see the “Additional Conversion Formatters” section below for more information.

The SERIN command can also be configured to wait for specified data before it retrieves any additional input. For example, suppose a device that is attached to the BASIC Stamp is known to send many different sequences of data, but the only data you desire happens to appear right after the unique characters, “XYZ”. The BS1 has optional *Qualifier* arguments for this purpose. On the BS2, BS2e, BS2sx and BS2p a special formatter called WAIT can be used for this.

```plaintext
Symbol SerData = B0
SERIN 1, N2400, ("XYZ"), #SerData
```

---or---

```plaintext
SerData VAR BYTE
SERIN 1, 16780, [WAIT("XYZ"), DEC SerData]
```

The above code waits for the characters “X”, “Y” and “Z” to be received, in that order, and then it looks for a decimal number to follow. If the device in this example were to send the characters “XYZ100” followed by a carriage return or some other non-decimal numeric character, the SerData variable would end up with the number 100 after the SERIN line finishes. If the device sent some data other than “XYZ” followed by a number, the BASIC Stamp would continue to wait at the SERIN command.

The BS1 will accept an unlimited number of *Qualifiers*. The BS2, BS2e, BS2sx and BS2p will only accept up to six bytes (characters) in the WAIT formatter.

Keep in mind that when we type “XYZ” into the SERIN command, the BASIC Stamp actually uses the ASCII codes for each of those characters for its tasks. We could also have typed: 88, 89, 90 in place of “XYZ” and the code would run the same way since 88 is the ASCII code for the “X” character, 89 is the ASCII code for the “Y” character, and so on. Also note, serial communication with the BASIC Stamp is case sensitive. If the device mentioned above sent, “xYZ” or “xyZ”, or some other combination of lower and upper-case characters, the BASIC Stamp would have ignored it because we told it to look for “XYZ” (all capital letters).
The BS1’s SERIN command is limited to above-mentioned features. If you are not using a BS1, please continue reading about the additional features below.

The decimal formatter is only one of a whole family of conversion formatters available with SERIN on the BS2, BS2e, BS2sx and BS2p. See Table 5.76 for a list of available conversion formatters. All of the conversion formatters work similar to the decimal formatter (as described in the “Decimal Formatter Specifics” section, above). The formatters receive bytes of data, waiting for the first byte that falls within the range of characters they accept (e.g., “0” or “1” for binary, “0” to “9” for decimal, “0” to “9” and “A” to “F” for hex, and “+” or “-” for signed variations of any type). Once they receive a numeric character, they keep accepting input until a non-numeric character arrives or (in the case of the fixed length formatters) the maximum specified number of digits arrives.

While very effective at filtering and converting input text, the formatters aren’t completely foolproof. As mentioned before, many conversion formatters will keep accepting text until the first non-numeric text arrives, even if the resulting value exceeds the size of the variable. After SERIN, a byte variable will contain the lowest 8 bits of the value entered and a word would contain the lowest 16 bits. You can control this to some degree by using a formatter that specifies the number of digits, such as DEC2, which would accept values only in the range of 0 to 99.

The BS2, BS2e, BS2sx and BS2p also have special formatters for handling a string of characters, a sequence of characters and undesirable characters. See Table 5.77 for a list of these special formatters. Also, see Appendix C for example serial inputs and the result of using these formatters.
### Table 5.76: BS2, BS2e, BS2sx and BS2p Conversion Formatters.

<table>
<thead>
<tr>
<th>Conversion Formatter</th>
<th>Type of Number</th>
<th>Numeric Characters Accepted</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>DEC{1..5}</td>
<td>Decimal, optionally limited to 1 – 5 digits</td>
<td>0 through 9</td>
<td>1</td>
</tr>
<tr>
<td>SDEC{1..5}</td>
<td>Signed decimal, optionally limited to 1 – 5 digits</td>
<td>-, 0 through 9</td>
<td>1,2</td>
</tr>
<tr>
<td>HEX{1..4}</td>
<td>Hexadecimal, optionally limited to 1 – 4 digits</td>
<td>0 through 9, A through F</td>
<td>1,3</td>
</tr>
<tr>
<td>SHEX{1..4}</td>
<td>Signed hexadecimal, optionally limited to 1 – 4 digits</td>
<td>-, 0 through 9, A through F</td>
<td>1,2,3</td>
</tr>
<tr>
<td>IHEX{1..4}</td>
<td>Indicated hexadecimal, optionally limited to 1 – 4 digits</td>
<td>$, 0 through 9, A through F</td>
<td>1,3,4</td>
</tr>
<tr>
<td>ISHEX{1..4}</td>
<td>Signed, indicated hexadecimal, optionally limited to 1 – 4 digits</td>
<td>-, $, 0 through 9, A through F</td>
<td>1,2,3,4</td>
</tr>
<tr>
<td>BIN{1..16}</td>
<td>Binary, optionally limited to 1 – 16 digits</td>
<td>0, 1</td>
<td>1</td>
</tr>
<tr>
<td>SBIN{1..16}</td>
<td>Signed binary, optionally limited to 1 – 16 digits</td>
<td>-, 0, 1</td>
<td>1,2</td>
</tr>
<tr>
<td>IBIN{1..16}</td>
<td>Indicated binary, optionally limited to 1 – 16 digits</td>
<td>%, 0, 1</td>
<td>1,4</td>
</tr>
<tr>
<td>ISBIN{1..16}</td>
<td>Signed, indicated binary, optionally limited to 1 – 16 digits</td>
<td>-, %, 0, 1</td>
<td>1,2,4</td>
</tr>
</tbody>
</table>

1. All numeric conversions will continue to accept new data until receiving either the specified number of digits (ex: three digits for DEC3) or a non-numeric character.
2. To be recognized as part of a number, the minus sign (\( - \)) must immediately precede a numeric character. The minus sign character occurring in non-numeric text is ignored and any character (including a space) between a minus and a number causes the minus to be ignored.
3. The hexadecimal formatters are not case-sensitive; “a” through “f” means the same as “A” through “F”.
4. Indicated hexadecimal and binary formatters ignore all characters, even valid numerics, until they receive the appropriate prefix ($ for hexadecimal, % for binary). The indicated formatters can differentiate between text and hexadecimal (ex: ABC would be interpreted by HEX as a number but IHEX would ignore it unless expressed as $ABC). Likewise, the binary version can distinguish the decimal number 10 from the binary number %10. A prefix occurring in non-numeric text is ignored, and any character (including a space) between a prefix and a number causes the prefix to be ignored. Indicated, signed formatters require that the minus sign come before the prefix, as in -$1B45.
The string formatter is useful for receiving a string of characters into a byte array variable. A string of characters is a set of characters that are arranged or accessed in a certain order. The characters "ABC" could be stored in a string with the "A" first, followed by the "B" and then followed by the "C." A byte array is a similar concept to a string; it contains data that is arranged in a certain order. Each of the elements in an array is the same size. The string "ABC" could be stored in a byte array containing three bytes (elements). See the "Defining Arrays" section in Chapter 4 for more information on arrays.

Here is an example that receives nine bytes through I/O pin 1 at 9600 bps, N81/inverted and stores them in a 10-byte array:

```
  SerString VAR BYTE(10)   ' Make a 10-byte array.
  SerString(9) = 0     ' Put 0 in last byte.
  SERIN 1, 16468, [STR SerString] ' Get 9-byte string.
  DEBUG STR SerString ' Display the string.
```

Why store only 9 bytes in a 10-byte array? We want to reserve space for the 0 byte that many BASIC Stamp string-handling routines regard as an end-of-string marker. This becomes important when dealing with variable-length arrays. For example, the STR formatter (see Table 5.77) can accept an additional parameter telling it to end the string when a particular byte is received, or when the specified length is reached, whichever comes first. An example:

```
  SerString VAR BYTE(10)   ' Make a 10-byte array.
  SerString(9) = 0     ' Put 0 in last byte.
  SERIN 1, 16468, [STR SerString] ' Stop at "**" or 9 bytes.
  DEBUG STR SerString ' Display the string.
```
If the serial input were "hello*" DEBUG would display "hello" since it collects bytes up to (but not including) the end character. It fills the unused bytes up to the specified length with 0s. DEBUG’s normal STR formatter understands a 0 to mean end-of-string. However, if you use DEBUG’s fixed-length string modifier, STR ByteArray\L, you will inadvertently clear the DEBUG screen. The fixed-length specification forces DEBUG to read and process the 0s at the end of the string, and 0 is equivalent to DEBUG’s CLS (clear-screen) instruction! Be alert for the consequences of mixing fixed- and variable-length string operations.

As shown before, SERIN can compare incoming data with a predefined sequence of bytes using the WAIT formatter. The simplest form waits for a sequence of up to six bytes specified as part of the InputData list, like so:

```
SERIN 1, 16468, [WAIT ("SESAME")]
DEBUG "Password accepted"
```

SERIN will wait for that word, and the program will not continue until it is received. Since WAIT is looking for an exact match for a sequence of bytes, it is case-sensitive—“sesame” or “SESAmE” or any other variation from “SESAME” would be ignored.

SERIN can also wait for a sequence that matches a string stored in an array variable with the WAITSTR formatter. In the example below, we’ll capture a string with STR then have WAITSTR look for an exact match:

```
SerString VAR BYTE(10)    ' Make a 10-byte array.
SerString(9) = 0           ' Put 0 in last byte.
SERIN 1, 16468, [STR SerString\9"!"]
DEBUG "Waiting for: ", STR SerString, CR
SERIN 1, 16468, [WAITSTR SerString]
DEBUG "Password accepted!", CR
```

You can also use WAITSTR with fixed-length strings as in the following example:
**SERIN - BASIC Stamp Command Reference**

SerString  VAR BYTE(4)    ' Make a 4-byte array.
DEBUG  "Enter a 4 character password", CR
SERIN  1, 16468, [STR  SerString\4]  ' Get the string
DEBUG  "Waiting for: ", STR  SerString\4, CR
SERIN  1, 16468, [WAITSTR  SerString\4]  'Wait for a match
DEBUG  "Password accepted!", CR

SERIN’s *InputData* can be structured as a sophisticated list of actions to perform on the incoming data. This allows you to process incoming data in powerful ways. For example, suppose you have a serial stream that contains “pos: xxxx yyyy” (where xxxx and yyyy are 4-digit numbers) and you want to capture just the decimal y value. The following code would do the trick:

YOffset VAR WORD
SERIN  1, 16468, [WAIT ("pos: "), SKIP  4, DEC  yOffset]
DEBUG  ? yOffset

The items of the *InputData* list work together to locate the label “pos: “, skip over the four-byte x data, then convert and capture the decimal y data. This sequence assumes that the x data is always four digits long; if its length varies, the following code would be more appropriate:

YOffset VAR WORD
SERIN  1, 16468, [WAIT ("pos: "), DEC  yOffset, DEC  yOffset]
DEBUG  ? yOffset

The unwanted x data is stored in yOffset then replaced by the desired y data. This is a sneaky way to filter out a number of any size without using an extra variable. With a little creativity, you can combine the *InputData* modifiers to filter and extract almost any data.

Parity is a simple error-checking feature. When a serial sender is set for even parity (the mode the BASIC Stamps support) it counts the number of 1s in an outgoing byte and uses the parity bit to make that number even. For instance, if it is sending the 7-bit value: %0011010, it sets the parity bit to 1 in order to make an even number of 1s (four).

The receiver also counts the data bits to calculate what the parity bit should be. If it matches the parity bit received, the serial receiver assumes that the data was received correctly. Of course, this is not necessarily true, since two incorrectly received bits could make parity seem correct when
the data was wrong, or the parity bit itself could be bad when the rest of the data was OK.

Many systems that work exclusively with text use (or can be set for) 7-bit/even-parity mode. Tables 5.73, 5.74 and 5.75 show appropriate BaudMode settings for different BASIC Stamps. For example, with the BS2, to receive one data byte through pin 1 at 9600 baud, 7E, inverted:

```plaintext
SerData VAR BYTE
SERIN 1, 24660, [SerData]
```

That instruction will work, but it doesn’t tell the BS2 what to do in the event of a parity error. Here’s an improved version that uses the optional Plabel argument:

```plaintext
SerData VAR BYTE
SERIN 1, 24660, BadData, [SerData]
DEBUG ? SerData
STOP

BadData:
DEBUG "parity error"
```

If the parity matches, the program continues at the DEBUG instruction after SERIN. If the parity doesn’t match, the program goes to the label BadData. Note that a parity error takes precedence over other InputData specifications (as soon as an error is detected, SERIN aborts and goes to the Plabel routine).

In all the examples above, the only way to end the SERIN instruction (other than RESET or power-off) is to give SERIN the serial data it wants. If no serial data arrives, the program is stuck. However, you can tell the BASIC Stamp to abort SERIN if it doesn’t receive data within a specified number of milliseconds. For instance, to receive a decimal number through pin 1 at 9600 baud, 8N, inverted and abort SERIN after 2 seconds (2000 ms) if no data arrives:

```plaintext
Result VAR BYTE
SERIN 1, 16468, 2000, NoData, DEC Result
Debug CLS, ? Result
STOP

NoData:
DEBUG CLS, "timed out"
```

**USING THE SERIAL TIME-OUT FEATURE.**
If no data arrives within 2 seconds, the program aborts SERIN and continues at the label NoData.

Here's a very important concept: this timeout feature is not picky about the kind of data SERIN receives; if any serial data is received, it prevents the timeout. In the example above, SERIN wants a decimal number. But even if SERIN received letters “ABCD...” at intervals of less than two seconds, it would never abort.

You can combine parity and serial timeouts. Here is an example for the BS2 designed to receive a decimal number through pin 1 at 2400 baud, 7E, inverted with a 10-second timeout:

Result \text{VAR BYTE}

Again:

SERIN 1, 24660, BadData, 10000, NoData, [DEC Result]
DEBUG CLS, ? Result
GOTO Again

NoData:
DEBUG CLS, "timed out"
GOTO Again

BadData:
DEBUG CLS, "parity error"
GOTO Again

When you design an application that requires serial communication between BASIC Stamps, you have to work within these limitations:

- When the BASIC Stamp is sending or receiving data, it can’t execute other instructions.
- When the BASIC Stamp is executing other instructions, it can’t send or receive data. The BASIC Stamp does not have a serial buffer as there is in PCs. At most serial rates, the BASIC Stamp cannot receive data via SERIN, process it, and execute another SERIN in time to catch the next chunk of data, unless there are significant pauses between data transmissions.

These limitations can sometimes be addressed by using flow control; the \textit{Fpin} option for SERIN and SEROUT (at baud rates of up to the limitation shown in Table 5.70). Through \textit{Fpin}, SERIN can tell a BASIC Stamp sender when it is ready to receive data. (For that matter, \textit{Fpin} flow control follows
the rules of other serial handshaking schemes, but most computers other than the BASIC Stamp cannot start and stop serial transmission on a byte-by-byte basis. That’s why this discussion is limited to communication between BASIC Stamps.)

Here’s an example using flow control on the BS2 (data through I/O pin 1, flow control through I/O pin 0, 9600 baud, N8, noninverted):

```
SerData VAR BYTE
SERIN 1\0, 84, [SerData]
```

When SERIN executes, I/O pin 1 (Rpin) is made an input in preparation for incoming data, and I/O pin 0 (Fpin) is made output low, to signal “go” to the sender. After SERIN finishes receiving, I/O pin 0 goes high to tell the sender to stop. If an inverted BaudMode had been specified, the Fpin’s responses would have been reversed. Here’s the relationship of serial polarity to Fpin states.

<table>
<thead>
<tr>
<th></th>
<th>Ready to Receive (“Go”)</th>
<th>Not Ready to Receive (“Stop”)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Inverted</td>
<td>Fpin is High (1)</td>
<td>Fpin is Low (0)</td>
</tr>
<tr>
<td>Non-inverted</td>
<td>Fpin is Low (0)</td>
<td>Fpin is High (1)</td>
</tr>
</tbody>
</table>

See the Demo Program, below, for a flow control example using two BS2s. In the demo program example, without flow control, the sender would transmit the whole word “HELLO!” in about 6 ms. The receiver would catch the first byte at most; by the time it got back from the first 1-second PAUSE, the rest of the data would be long gone. With flow control, communication is flawless since the sender waits for the receiver to catch up.

In Figure 5.33, I/O pin 0, Fpin, is pulled to ground through a 10k resistor. This is to ensure that the sender sees a stop signal (0 for inverted communications) when the receiver is being programmed.
Serial communication, because of its complexity, can be very difficult to work with at times. Please follow these guidelines when developing a project using the SERIN and SEROUT commands:

1. Always build your project in steps.
   a. Start with small, manageable pieces of code, that deals with serial communication) and test them, one at a time.
   b. Add more and more small pieces, testing them each time, as you go.
   c. Never write a large portion of code that works with serial communication without testing its smallest workable pieces first.

2. Pay attention to timing.
   a. Be very careful to calculate and overestimate the amount of time operations should take within the BASIC Stamp. Misunderstanding the timing constraints is the source of most problems with code that communicate serially.
   b. If the serial communication in your project is bi-directional, the above statement is even more critical.

3. Pay attention to wiring.
   a. Take extra time to study and verify serial communication wiring diagrams. A mistake in wiring can cause strange problems in communication, or no communication at all. Make sure to connect the ground pins (Vss) between the devices that are communicating serially.

4. Verify port setting on the PC and in the SERIN/SEROUT commands.
   a. Unmatched settings on the sender and receiver side will cause garbled data transfers or no data transfers. If the
data you receive is unreadable, it is most likely a baud rate setting error.

5. If receiving data from another device that is not a BASIC Stamp, try to use baud rates of 4800 and below.
   a. Because of additional overhead in the BASIC Stamp, and the fact that the BASIC Stamp has no hardware receive buffer for serial communication, received data may sometimes be missed or garbled. If this occurs, try lowering the baud rate (if possible), adding extra stop bits, and not using formatters in the SERIN command. Using simple variables (not arrays) and no formatters will increase the chance that the BASIC Stamp can receive the data properly.

6. Be sure to study the effects of SERIN formatters.
   a. Some formatters have specific requirements that may cause problems in received data. For example, the DEC formatter requires a non-decimal-numeric character to follow the received number before it will allow the BASIC Stamp to continue. See Appendix C for example input data and the effects on formatters.

---

Demo Program (SERIN.bas)

' This program waits for the characters "A", "B", "C" and "D" to arrive serially
' (Inverted 2400 baud, N81) on I/O pin 0, followed by a number and a carriage return
' (or some other non-number). It then displays the received number on the DEBUG screen.

'{$STAMP  BS1}' STAMP directive (specifies a BS1)

SYMBOL Result = W0

Loop:
  SERIN 0, N2400, ("ABCD"), #Result
  DEBUG #Result, CR
  GOTO Loop
Demo Program (SERIN-OUT_SENDER.bs2 & SERIN-OUT_RECEIVER.bs2)

' Using two BS2-IC’s, connect the circuit shown in the SERIN command description and run
' this program on the BASIC Stamp designated as the Sender. This program demonstrates
' the use of Flow Control (FPin). Without flow control, the sender would transmit the
' whole word "HELLO!" in about 6 ms. The receiver would catch the first byte at most; by
' the time it got back from the first 1-second PAUSE, the rest of the data would be long
' gone. With flow control, communication is flawless since the sender waits for the
' receiver to catch up.

'STAMP BS2}

Loop:
SEROUT 1\0, 16468, ["HELLO!"]
PAUSE 2500
GOTO Loop

' Using two BS2-IC’s, connect the circuit shown in the SERIN command description and run
' this program on the BASIC Stamp designated as the Receiver. This program demonstrates
' the use of Flow Control (FPin). Without flow control, the sender would transmit the
' whole word "HELLO!" in about 6 ms. The receiver would catch the first byte at most; by
' the time it got back from the first 1-second PAUSE, the rest of the data would be long
' gone. With flow control, communication is flawless since the sender waits for the
' receiver to catch up.

Letter VAR BYTE

Again:
SERIN 1\0, 16468, [Letter]
DEBUG Letter
PAUSE 1000
GOTO Again

Case2:
DEBUG "Branched to Case2",cr
GOTO Start

NOTE: This is written for the BS2
but can be used for the BS2e,
BS2sx and BS2p also (with
modifications). Locate the proper
source code file or modify the
STAMP directive and the
Baudmode before downloading to
the BS2e, BS2sx or BS2p.
5: BASIC Stamp Command Reference – SEROUT

**SEROUT**

BS1 | BS2 | BS2e | BS2sx | BS2p
---|---|---|---|---

SEROUT Tpin, Baudmode, ( {#} OutputData )

SEROUT Tpin {Fpin}, Baudmode, {Pace,} {Timeout, Tlabel,} [ InputData ]

**Function**

Transmit asynchronous serial data (e.g., RS-232 data).

- **Fpin** is an optional variable/constant/expression (0 – 15) that specifies the I/O pin to monitor for flow control status. This pin will be set to input mode. NOTE: Fpin must be specified to use the optional **Timeout** and **Tlabel** arguments in the SEROUT command.

- **Baudmode** is variable/constant/expression (0 – 7 on the BS1, 0 – 65535 on all other BASIC Stamps) that specifies serial timing and configuration.

- **Pace** is an optional variable/constant/expression (0 – 65535) that determines the length of the pause between transmitted bytes. NOTE: Pace cannot be used simultaneously with **Timeout**.

- **Timeout** is an optional variable/constant/expression (0 – 65535) that tells SEROUT how long to wait for Fpin permission to send. If permission does not arrive in time, the program will jump to the address specified by **Tlabel**. NOTE: Fpin must be specified to use the optional **Timeout** and **Tlabel** arguments in the SEROUT command.

- **Tlabel** is an optional label that must be provided along with **Timeout**. Tlabel indicates where the program should go in the event that permission to send data is not granted within the period specified by **Timeout**.

- **OutputData** is list of variables, constants, expressions and formatters that tells SEROUT how to format outgoing data. SEROUT can transmit individual or repeating bytes, convert values into decimal,
hex or binary text representations, or transmit strings of bytes from variable arrays. These actions can be combined in any order in the OutputData list.

Quick Facts

<table>
<thead>
<tr>
<th>Units in Pace and Timeout</th>
<th>BS1</th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>n/a</td>
<td>1 ms</td>
<td>1 ms</td>
<td>400 µs</td>
<td>400 µs</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Baud range</th>
<th>300, 600, 1200, and 2400 only</th>
<th>243 to 50K</th>
<th>243 to 50K</th>
<th>608 to 115.2K</th>
<th>608 to 115.2K</th>
</tr>
</thead>
<tbody>
<tr>
<td>Baud limit with flow control</td>
<td>n/a</td>
<td>19.2K</td>
<td>19.2K</td>
<td>19.2K</td>
<td>19.2K</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>I/O pins available</th>
<th>0 - 7</th>
<th>0 - 15</th>
<th>0 - 15</th>
<th>0 - 15 (in current I/O block)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Other serial port pins</td>
<td>n/a</td>
<td>SOUT pin (physical pin 1) when Rp in = 16</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Special cases</td>
<td>n/a</td>
<td>Fpin must be specified to use Timeout and Tlabel. Pace cannot be specified at the same time as Timeout.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Table 5.79: SEROUT Quick Facts.

Explanation

One of the most popular forms of communication between electronic devices is serial communication. There are two major types of serial communication; asynchronous and synchronous. The SERIN and SEROUT commands are used to receive and send asynchronous serial data. See the SHIFTIN and SHIFTOUT command for information on the synchronous method.

The following information is supplemental to what is discussed in the SERIN command section. Please read through the SERIN command section for additional information.

All BASIC Stamps (except the BS1) have a line driver on its SOUT pin (Tpin = 16). See the "Hardware" section of the "Introduction to the BASIC Stamps" chapter. The SOUT pin goes to a PC’s serial data-in pin on the DB9 connector built into BASIC Stamp development boards. The connector is wired to allow both programming and run-time serial communication (unless you are using the Stamp 2 Carrier Board which is only designed for programming). For the built-in serial port set the Tpin argument to 16 in the SEROUT command.
All BASIC Stamps (including the BS1) can also transmit RS-232 data through any of their I/O pins ($T_{pin} = 0 – 7$ for BS1, $T_{pin} = 0 – 15$ on all other BASIC Stamps). The I/O pins only provide a 0 to +5 volt swing (outside of RS-232 specs) and may need to be connected through a line driver for proper operation with all serial ports. Most serial ports are able to recognize a 0 to +5 volt swing, however. See Figure 5.34 for sample wiring.

Asynchronous serial communication relies on precise timing. Both the sender and receiver must be set for identical timing, usually expressed in bits per second (bps) called baud.

On all BASIC Stamps, SEROUT requires a value called Baudmode that tells it the important characteristics of the outgoing serial data; the bit period, number of data and parity bits, and polarity.
On the BS1, serial communication is limited to: no-parity, 8-data bits and 1-stop bit at one of four different speeds: 300, 600, 1200 or 2400 baud. Table 5.80 indicates the Baudmode value or symbols to use when selecting the desired mode.

<table>
<thead>
<tr>
<th>Baudmode Value</th>
<th>Symbol</th>
<th>Baud Rate</th>
<th>Polarity and Output Mode</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>T2400</td>
<td>2400</td>
<td>TRUE (always driven)</td>
</tr>
<tr>
<td>1</td>
<td>T1200</td>
<td>1200</td>
<td>TRUE (always driven)</td>
</tr>
<tr>
<td>2</td>
<td>T600</td>
<td>600</td>
<td>TRUE (always driven)</td>
</tr>
<tr>
<td>3</td>
<td>T300</td>
<td>300</td>
<td>TRUE (always driven)</td>
</tr>
<tr>
<td>4</td>
<td>N2400</td>
<td>2400</td>
<td>INVERTED (always driven)</td>
</tr>
<tr>
<td>5</td>
<td>N1200</td>
<td>1200</td>
<td>INVERTED (always driven)</td>
</tr>
<tr>
<td>6</td>
<td>N600</td>
<td>600</td>
<td>INVERTED (always driven)</td>
</tr>
<tr>
<td>7</td>
<td>N300</td>
<td>300</td>
<td>INVERTED (always driven)</td>
</tr>
<tr>
<td>8</td>
<td>OT2400</td>
<td>2400</td>
<td>TRUE (open drain, driven high)</td>
</tr>
<tr>
<td>9</td>
<td>OT1200</td>
<td>1200</td>
<td>TRUE (open drain, driven high)</td>
</tr>
<tr>
<td>10</td>
<td>OT600</td>
<td>600</td>
<td>TRUE (open drain, driven high)</td>
</tr>
<tr>
<td>11</td>
<td>OT300</td>
<td>300</td>
<td>TRUE (open drain, driven high)</td>
</tr>
<tr>
<td>12</td>
<td>ON2400</td>
<td>2400</td>
<td>INVERTED (open source, driven low)</td>
</tr>
<tr>
<td>13</td>
<td>ON1200</td>
<td>1200</td>
<td>INVERTED (open source, driven low)</td>
</tr>
<tr>
<td>14</td>
<td>ON600</td>
<td>600</td>
<td>INVERTED (open source, driven low)</td>
</tr>
<tr>
<td>15</td>
<td>ON300</td>
<td>300</td>
<td>INVERTED (open source, driven low)</td>
</tr>
</tbody>
</table>

On the BS2, BS2e, BS2sx and BS2p, serial communication is very flexible. The Baudmode argument for SEROUT accepts a 16-bit value that determines its characteristics: 1-stop bit, 8-data bits/no-parity or 7-data bits/even-parity and virtually any speed from as low as 300 baud to greater than 100K baud (depending on the BASIC Stamp). Table 5.81 shows how Baudmode is calculated and Tables 5.82, 5.83 and 5.84 show common baud modes for standard serial baud rates.

<table>
<thead>
<tr>
<th>Step 1: Determine the bit period (bits 0 – 11)</th>
</tr>
</thead>
<tbody>
<tr>
<td>BS2 and BS2e:   = INT(1,000,000 / baud rate) – 20</td>
</tr>
<tr>
<td>BS2sx:         = INT(2,500,000 / baud rate) – 20</td>
</tr>
<tr>
<td>BS2p:          = INT(2,500,000 / baud rate) – 20</td>
</tr>
<tr>
<td>Note: INT means 'convert to integer;' drop the numbers to the right of the decimal point.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Step 2: Set data bits and parity (bit 13)</th>
</tr>
</thead>
<tbody>
<tr>
<td>8-bit/no-parity = 0</td>
</tr>
<tr>
<td>7-bit/even-parity = 8192</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Step 3: Select polarity (bit 14)</th>
</tr>
</thead>
<tbody>
<tr>
<td>True (noninverted) = 0</td>
</tr>
<tr>
<td>Inverted = 16384</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Step 4: Select driven or open output (bit 15)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Driven = 0</td>
</tr>
<tr>
<td>Open = 32768</td>
</tr>
</tbody>
</table>

Table 5.81: BS2, BS2e, BS2sx and BS2p Baudmode calculation. Add the results of steps 1, 2, 3 and 4 to determine the proper value for the Baudmode argument.
Table 5.82: BS2 and BS2e common baud rates and corresponding Baudmodes.

<table>
<thead>
<tr>
<th>Baud Rate</th>
<th>8-bit no-parity inverted</th>
<th>8-bit no-parity true</th>
<th>7-bit even-parity inverted</th>
<th>7-bit even-parity true</th>
</tr>
</thead>
<tbody>
<tr>
<td>300</td>
<td>19697</td>
<td>3313</td>
<td>27889</td>
<td>11505</td>
</tr>
<tr>
<td>600</td>
<td>18030</td>
<td>1646</td>
<td>26222</td>
<td>9838</td>
</tr>
<tr>
<td>1200</td>
<td>17197</td>
<td>813</td>
<td>25389</td>
<td>9005</td>
</tr>
<tr>
<td>2400</td>
<td>16780</td>
<td>396</td>
<td>24972</td>
<td>8588</td>
</tr>
<tr>
<td>4800</td>
<td>16572</td>
<td>188</td>
<td>24764</td>
<td>8380</td>
</tr>
<tr>
<td>9600</td>
<td>16468</td>
<td>84</td>
<td>24660</td>
<td>8276</td>
</tr>
</tbody>
</table>

NOTE: For “open” baudmodes used in networking, add 32768 to the values from the table above. If the dedicated serial port (Tpin=16) is used, the data is inverted and driven regardless of the baudmode setting.

Table 5.83: BS2sx common baud rates and corresponding Baudmodes.

<table>
<thead>
<tr>
<th>Baud Rate</th>
<th>8-bit no-parity inverted</th>
<th>8-bit no-parity true</th>
<th>7-bit even-parity inverted</th>
<th>7-bit even-parity true</th>
</tr>
</thead>
<tbody>
<tr>
<td>1200</td>
<td>18447</td>
<td>2063</td>
<td>26639</td>
<td>10255</td>
</tr>
<tr>
<td>2400</td>
<td>17405</td>
<td>1021</td>
<td>25597</td>
<td>9213</td>
</tr>
<tr>
<td>4800</td>
<td>16884</td>
<td>500</td>
<td>25076</td>
<td>8692</td>
</tr>
<tr>
<td>9600</td>
<td>16624</td>
<td>240</td>
<td>24816</td>
<td>8432</td>
</tr>
</tbody>
</table>

NOTE: For “open” baudmodes used in networking, add 32768 to the values from the table above. If the dedicated serial port (Tpin=16) is used, the data is inverted and driven regardless of the baudmode setting.

Table 5.84: BS2p common baud rates and corresponding Baudmodes.

<table>
<thead>
<tr>
<th>Baud Rate</th>
<th>8-bit no-parity inverted</th>
<th>8-bit no-parity true</th>
<th>7-bit even-parity inverted</th>
<th>7-bit even-parity true</th>
</tr>
</thead>
<tbody>
<tr>
<td>1200</td>
<td>18447</td>
<td>2063</td>
<td>26639</td>
<td>10255</td>
</tr>
<tr>
<td>2400</td>
<td>17405</td>
<td>1021</td>
<td>25597</td>
<td>9213</td>
</tr>
<tr>
<td>4800</td>
<td>16884</td>
<td>500</td>
<td>25076</td>
<td>8692</td>
</tr>
<tr>
<td>9600</td>
<td>16624</td>
<td>240</td>
<td>24816</td>
<td>8432</td>
</tr>
</tbody>
</table>

NOTE: For “open” baudmodes used in networking, add 32768 to the values from the table above. If the dedicated serial port (Tpin=16) is used, the data is inverted and driven regardless of the baudmode setting.

Choosing the proper baud mode.

If you’re communicating with existing software or hardware, its speed(s) and mode(s) will determine your choice of baud rate and mode. See the SERIN command description for more information.

A simple form of SEROUT.

The example below will transmit a single byte through I/O pin 1 at 2400 baud, 8N1, inverted:
SEROUT 1, N2400, (65)

--or--

SEROUT 1, 16780, [65]

Here, SEROUT will transmit a byte equal to 65 (the ASCII value of the character "A") through pin 1. If the BASIC Stamp were connected to a PC running a terminal program (set to the same baud rate) the character "A" would appear on the screen (see the ASCII character chart in the appendix).

What if you really wanted the value 65 to appear on the screen? If you remember from the discussion in the SERIN command, "It is up to the receiving side (in serial communication) to interpret the values..." In this case, the PC is interpreting the byte-sized value to be the ASCII code for the character "A". Unless you're also writing the software for the PC, you can't change how the PC interprets the incoming serial data, so to solve this problem, the data needs to be translated before it is sent.

The SEROUT command provides a formatter, called the decimal formatter, which will translate the value 65 to two ASCII codes for the characters "6" and "5" and then transmit them. Look at the following code:

SEROUT 1, N2400, (#65)

--or--

SEROUT 1, 16780, [DEC 65]

Notice the decimal formatter in the SEROUT command. It is the "#" (for the BS1) or "DEC" (for the other BASIC Stamps) that appears just to the left of the number 65. This tells SEROUT to convert the number into separate ASCII characters which represent the value in decimal form. If the value 65 in the code were changed to 123, the SEROUT command would send three bytes (49, 50 and 51) corresponding to the characters "1", "2" and "3".

The BS2, BS2e, BS2sx and BS2p have many more conversion formatters available for the SEROUT command. See the “Additional Conversion Formatters” section below for more information.
The SEROUT command sends quoted text exactly as it appears in the \textit{OutputData} list:

```
SEROUT 1, N2400, ( "HELLO", CR )
SEROUT 1, N2400, ( "Num = ", #100 )
```

--or--

```
SEROUT 1, 16780, [ "HELLO", CR ]
SEROUT 1, 16780, [ "Num = ", DEC 100 ]
```

The above code will display "HELLO" on one line and "Num = 100" on the next line. Notice that you can combine data to output in one SEROUT command, separated by commas. In the example above, we could have written it as one line of code, with "HELLO", CR, "Num = ", DEC 100 in the \textit{OutputData} list.

The BS1's SEROUT command is limited to above-mentioned features. If you are not using a BS1, please continue reading about the additional features below.

The SEROUT command can also be configured to pause between transmitted bytes. This is the purpose of the optional \textit{Pace} argument. For example (9600 baud N8, inverted):

```
SEROUT 1, 16468, 1000, [ "Slowly" ]
```

Here, the BASIC Stamp transmits the word "Slowly" with a 1 second delay between each character. See Table 5.79 for units of the \textit{Pace} argument. One good reason to use the \textit{Pace} feature is to support devices that require more than one stop bit. Normally, the BASIC Stamp sends data as fast as it can (with a minimum of 1 stop bit between bytes). Since a stop bit is really just a resting state in the line (no data transmitted), using the \textit{Pace} option will effectively add multiple stop bits. Since the requirement for 2 or more stop bits (on some devices) is really just a "minimum" requirement, the receiving side should receive this data correctly.

Keep in mind that when we type something like “XYZ” into the SEROUT command, the BASIC Stamp actually uses the ASCII codes for each of those characters for its tasks. We could also typed: 88, 89, 90 in place of “XYZ” and the program would run the same way since 88 is the ASCII
code for the “X” character, 89 is the ASCII code for the “Y” character, and so on.

The decimal formatter is only one of a whole family of conversion formatters available with SERIN on the BS2, BS2e, BS2sx and BS2p. See Table 5.85 for a list of available conversion formatters. All of the conversion formatters work similar to the decimal formatter. The formatters translate the value into separate bytes of data until the entire number is translated or until the indicated number of digits (in the case of the fixed length formatters) is translated.

The BS2, BS2e, BS2sx and BS2p also have special formatters for outputting a string of characters, repeated characters and undesirable characters. See Table 5.86 for a list of these special formatters.

<table>
<thead>
<tr>
<th>Conversion Formatter</th>
<th>Type of Number</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>DEC{1..5}</td>
<td>Decimal, optionally fixed to 1 – 5 digits</td>
<td>1</td>
</tr>
<tr>
<td>SDEC{1..5}</td>
<td>Signed decimal, optionally fixed to 1 – 5 digits</td>
<td>1,2</td>
</tr>
<tr>
<td>HEX{1..4}</td>
<td>Hexadecimal, optionally fixed to 1 – 4 digits</td>
<td>1</td>
</tr>
<tr>
<td>SHEX{1..4}</td>
<td>Signed hexadecimal, optionally fixed to 1 – 4 digits</td>
<td>1,2</td>
</tr>
<tr>
<td>IHEX{1..4}</td>
<td>Indicated hexadecimal, optionally fixed to 1 – 4 digits ($ prefix)</td>
<td>1</td>
</tr>
<tr>
<td>ISHEX{1..4}</td>
<td>Signed, indicated hexadecimal, optionally fixed to 1 – 4 digits ($ prefix)</td>
<td>1,2</td>
</tr>
<tr>
<td>BIN{1..16}</td>
<td>Binary, optionally fixed to 1 – 16 digits</td>
<td>1</td>
</tr>
<tr>
<td>SBIN{1..16}</td>
<td>Signed binary, optionally fixed to 1 – 16 digits</td>
<td>1,2</td>
</tr>
<tr>
<td>IBIN{1..16}</td>
<td>Indicated binary, optionally fixed to 1 – 16 digits (% prefix)</td>
<td>1</td>
</tr>
<tr>
<td>ISBIN{1..16}</td>
<td>Signed, indicated binary, optionally fixed to 1 – 16 digits (% prefix)</td>
<td>1,2</td>
</tr>
</tbody>
</table>

1 Fixed-digit formatters like DEC4 will pad the number with leading 0s if necessary; ex: DEC4 65 sends 0065. If a number is larger than the specified number of digits, the leading digits will be dropped; ex: DEC4 56422 sends 6422.
2 Signed modifiers work under two’s complement rules.
5: BASIC Stamp Command Reference – SEROUT

Table 5.86: BS2, BS2e, BS2sx and BS2p Special Formatters.

<table>
<thead>
<tr>
<th>Special Formatter</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>?</td>
<td>Displays &quot;symbol = x' + carriage return; where x is a number. Default format is decimal, but may be combined with conversion formatters (ex: BIN ? x to display &quot;x = binary_number&quot;).</td>
</tr>
<tr>
<td>ASC ?</td>
<td>Displays &quot;symbol = 'x'' + carriage return; where x is an ASCII character.</td>
</tr>
<tr>
<td>STR ByteArray {\L}</td>
<td>Send character string from an array. The optional \L argument can be used to limit the output to L characters, otherwise, characters will be sent up to the first byte equal to 0 or the end of RAM space is reached.</td>
</tr>
<tr>
<td>REP Byte \L</td>
<td>Send a string consisting of Byte repeated L times (ex: REP &quot;X&quot;\10 sends &quot;XXXXXXXXX&quot;).</td>
</tr>
</tbody>
</table>

The STR (STRING) FORMATTER.

The string formatter is useful for transmitting a string of characters from a byte array variable. A string of characters is a set of characters that are arranged or accessed in a certain order. The characters "ABC" could be stored in a string with the "A" first, followed by the "B" and then followed by the "C." A byte array is a similar concept to a string; it contains data that is arranged in a certain order. Each of the elements in an array is the same size. The string "ABC" could be stored in a byte array containing three bytes (elements). See the “Defining Arrays” section in Chapter 4 for more information on arrays.

Here is an example that transmits five bytes (from a byte array) through I/O pin 1 at 9600 bps, N81/inverted:

```
SerString VAR BYTE(5) ' Make a 5-byte array.
SerString(0) = "H"
SerString(1) = "E"
SerString(2) = "L"
SerString(3) = "L"
SerString(4) = "O"
SEROUT 1, 16468, [ STR SerString\5 ] ' Send 5-byte string.
```

Note that we use the optional \L argument of STR. If we didn't specify this, the BASIC Stamp would try to keep sending characters until it found a byte equal to 0. Since we didn't specify a last byte of 0 in the array, we chose to tell it explicitly to only send 5 characters.

USING PARITY AND HANDLING PARITY ERRORS.

Parity is a simple error-checking feature. When the SEROUT command's Baudmode is set for even parity it counts the number of 1s in the outgoing byte and uses the parity bit to make that number even. For instance, if it is
sending the 7-bit value: %0011010, it sets the parity bit to 1 in order to make an even number of 1s (four).

The receiver also counts the data bits to calculate what the parity bit should be. If it matches the parity bit received, the serial receiver assumes that the data was received correctly. Of course, this is not necessarily true, since two incorrectly received bits could make parity seem correct when the data was wrong, or the parity bit itself could be bad when the rest of the data was OK. Parity errors are only detected on the receiver side. Generally, the receiver determines how to handle the error. In a more robust application, the receiver and transmitter might be set up such that the receiver can request a re-send of data that was received with a parity error.

When you design an application that requires serial communication between BASIC Stamps, you have to work within these limitations:

- When the BASIC Stamp is sending or receiving data, it can’t execute other instructions.
- When the BASIC Stamp is executing other instructions, it can’t send or receive data. The BASIC Stamp does not have a serial buffer as there is in PCs. At most serial rates, the BASIC Stamp cannot receive data via SERIN, process it, and execute another SERIN in time to catch the next chunk of data, unless there are significant pauses between data transmissions.

These limitations can sometimes be addressed by using flow control; the $Fpin$ option for SERIN and SEROUT (at baud rates of up to the limitation shown in Table 5.79). Through $Fpin$, SERIN can tell a BASIC Stamp sender when it is ready to receive data and SEROUT (on the sender) will wait for permission to send. (For that matter, $Fpin$ flow control follows the rules of other serial handshaking schemes, but most computers other than the BASIC Stamp cannot start and stop serial transmission on a byte-by-byte basis. That’s why this discussion is limited to communication between BASIC Stamps.)

Here’s an example using flow control on the BS2 (data through I/O pin 1, flow control through I/O pin 0, 9600 baud, N8, noninverted):
SerData VAR BYTE
SEROUT 1\0, 84, [SerData]

When SEROUT executes, I/O pin 1 (Tpin) is made an output, and I/O pin 0 (Fpin) is made an input, to wait for the "go" signal from the receiver. Here's the relationship of serial polarity to Fpin states.

<table>
<thead>
<tr>
<th></th>
<th>Ready to Receive</th>
<th>Not Ready to Receive</th>
</tr>
</thead>
<tbody>
<tr>
<td>Inverted</td>
<td>Fpin is High (1)</td>
<td>Fpin is Low (0)</td>
</tr>
<tr>
<td>Non-inverted</td>
<td>Fpin is Low (0)</td>
<td>Fpin is High (1)</td>
</tr>
</tbody>
</table>

See the Demo Program, below, for a flow control example using two BS2s. In the demo program example, without flow control, the sender would transmit the whole word “HELLO!” in about 6 ms. The receiver would catch the first byte at most; by the time it got back from the first 1-second PAUSE, the rest of the data would be long gone. With flow control, communication is flawless since the sender waits for the receiver to catch up.

In Figure 5.35, I/O pin 0, Fpin, is pulled to ground through a 10k resistor. This is to ensure that the sender sees a stop signal (0 for inverted communications) when the receiver is being programmed.

In the flow control examples above, the only way the SEROUT instruction will end (other than RESET or power-off) is if the receiver allows it to send the entire OutputData list. If Fpin permission never occurs, the program is stuck. However, you can tell the BASIC Stamp to abort SEROUT if it doesn’t receive Fpin permission within a specified time period. For instance, to transmit a decimal number through pin 1 at 9600 baud, 8N, inverted and abort SEROUT after 2 seconds (2000 ms) if no Fpin permission arrives on I/O pin 0:

SEROUT 1\0, 16468, 2000, NoPermission, [DEC 150]

NoPermission:
DEBUG CLS, "timed out"

If no Fpin permission arrives within 2 seconds, the program aborts SEROUT and continues at the label NoPermission.
The SEROUT command supports open-drain and open-source output, which makes it possible to network multiple BASIC Stamps on a single pair of wires. These "open baudmodes" only actively drive the Tpin in one state (for the other state, they simply disconnect the pin; setting it to an input mode). If two BASIC Stamps in a network had their SEROUT lines connected together (while a third device listened on that line) and the BASIC Stamps were using always-driven baudmodes, they could simultaneously output two opposite states (ie: +5 volts and ground). This would create a short circuit. The heavy current flow would likely damage the I/O pins or the BASIC Stamps themselves. Since the open baudmodes only drive in one state and float in the other, there's no chance of this kind of short.

The polarity selected for SEROUT determines which state is driven and which is open as in Table 5.88.

<table>
<thead>
<tr>
<th></th>
<th>State (0)</th>
<th>State (1)</th>
<th>Resister Pulled to</th>
</tr>
</thead>
<tbody>
<tr>
<td>Inverted</td>
<td>Open</td>
<td>Driven</td>
<td>Gnd (Vss)</td>
</tr>
<tr>
<td>Non-inverted</td>
<td>Driven</td>
<td>Open</td>
<td>+5V (Vdd)</td>
</tr>
</tbody>
</table>

Since open baudmodes only drive to one state, they need a resistor to pull the networked line into the other state, as shown in Table 5.88 and in Figures 5.36 and 5.37.

Open baudmodes allow the BASIC Stamp to share a line, but it is up to your program to resolve other networking issues such as who talks when and how to detect, prevent and fix data errors.
Serial communication, because of its complexity, can be very difficult to work with at times. Please follow these guidelines (and those in the "SERIN Troubleshooting" section of the SERIN command description) when developing a project using the SERIN and SEROUT commands:

1. Always build your project in steps.
   a. Start with small, manageable pieces of code, that deals with serial communication) and test them, one at a time.
   b. Add more and more small pieces, testing them each time, as you go.
   c. Never write a large portion of code that works with serial communication without testing its smallest workable pieces first.
2. Pay attention to timing.
   a. Be very careful to calculate and overestimate the amount of
time operations should take within the BASIC Stamp.
   Misunderstanding the timing constraints is the source of most
problems with code that communicate serially.
   b. If the serial communication in your project is bi-directional,
the above statement is even more critical.
3. Pay attention to wiring.
   a. Take extra time to study and verify serial communication
wiring diagrams. A mistake in wiring can cause strange
problems in communication, or no communication at all.
   Make sure to connect the ground pins (Vss) between the
devices that are communicating serially.
4. Verify port setting on the PC and in the SERIN/SEROUT
   commands.
   a. Unmatched settings on the sender and receiver side will cause
garbled data transfers or no data transfers. If the data you
receive is unreadable, it is most likely a baud rate setting
error.
5. If data transmitted to the Stamp Editor's Debug Terminal is
garbled, verify the output format.
   a. A common mistake is to send data with SEROUT in ASCII
format. For example, SEROUT 16, 84, [ 0 ] instead of
SEROUT 16, 84, [ DEC 0 ]. The first example will send a byte
equal to 0 to the PC, resulting in the Debug Terminal clearing
the screen (since 0 is the control character for a clear-screen
action).

Demo Program (SEROUT.bas)
' This program transmits the characters "A", "B", "C" and "D" (Inverted 2400 baud, N81) on
' I/O pin 0, followed by a number and a carriage return.

'${STAMP BS1}    'STAMP directive (specifies a BS1)
SYMBOL  Result = W0
Result = 1500
Loop:
   SERIN  0, N2400, ("ABCD"), #Result
   PAUSE 1000
   GOTO  Loop
Demo Program (SERIN-OUT_SENDER.bs2 & SERIN-OUT_RECEIVER.bs2)

Using two BS2-IC's, connect the circuit shown in the SEROUT command description and run this program on the BASIC Stamp designated as the Sender. This program demonstrates the use of Flow Control (FPin). Without flow control, the sender would transmit the whole word "HELLO!" in about 6 ms. The receiver would catch the first byte at most; by the time it got back from the first 1-second PAUSE, the rest of the data would be long gone. With flow control, communication is flawless since the sender waits for the receiver to catch up.

`{$STAMP BS2}`  'STAMP directive (specifies a BS2)

Loop:
    SEROUT 1\0, 16468, ["HELLO!"]  ' Send the greeting.
    PAUSE 2500
    GOTO Loop

Using two BS2-IC's, connect the circuit shown in the SEROUT command description and run this program on the BASIC Stamp designated as the Receiver. This program demonstrates the use of Flow Control (FPin). Without flow control, the sender would transmit the whole word "HELLO!" in about 6 ms. The receiver would catch the first byte at most; by the time it got back from the first 1-second PAUSE, the rest of the data would be long gone. With flow control, communication is flawless since the sender waits for the receiver to catch up.

Letter VAR BYTE

Again:
    SERIN 1\0, 16468, [Letter]  ' Get 1 byte.
    DEBUG Letter  ' Display on screen.
    PAUSE 1000  ' Wait a second.
    GOTO Again

Case2:
    DEBUG "Branch to Case2",cr
GOTO Start

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also (with modifications). Locate the proper source code file or modify the STAMP directive and the Baudmode before downloading to the BS2e, BS2sx or BS2p.
5: BASIC Stamp Command Reference – SHIFTIN

SHIFTIN (BS1 BS2 BS2e BS2sx BS2p)

SHIFTIN Dpin, Cpin, Mode, [ Variable {Bits} , Variable {Bits}… ]

Function
Shift data in from a synchronous serial device.

- **Dpin** is a variable/constant/expression (0 – 15) that specifies the I/O pin that will be connected to the synchronous serial device’s data output. This pin will be set to input mode.

- **Cpin** is a variable/constant/expression (0 – 15) that specifies the I/O pin that will be connected to the synchronous serial device’s clock input. This pin will be set to output mode.

- **Mode** is a variable/constant/expression (0 – 3), or one of four predefined symbols, that tells SHIFTIN the order in which data bits are to be arranged and the relationship of clock pulses to valid data. See Table 5.90 for value and symbol definitions.

- **Variable** is a variable in which incoming data bits will be stored.

- **Bits** is an optional variable/constant/expression (1 – 16) specifying how many bits are to be input by SHIFTIN. If no Bits entry is given, SHIFTIN defaults to 8 bits.

Quick Facts

<table>
<thead>
<tr>
<th></th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Timing of ( T_1 ) and ( t )</strong></td>
<td>14 ( \mu )s / 46 ( \mu )s</td>
<td>14 ( \mu )s / 46 ( \mu )s</td>
<td>5.6 ( \mu )s / 18 ( \mu )s</td>
<td>5.6 ( \mu )s / 18.8 ( \mu )s</td>
</tr>
<tr>
<td><strong>Transmission Rate</strong></td>
<td>~16 kbits/sec</td>
<td>~16 kbits/sec</td>
<td>~42 kbits/sec</td>
<td>~42 kbits/sec</td>
</tr>
</tbody>
</table>

Explanation
SHIFTIN and SHIFTOUT provide an easy method of acquiring data from synchronous serial devices. Synchronous serial differs from asynchronous serial (like SERIN and SEROUT) in that the timing of data bits (on a data line) is specified in relationship to clock pulses (on a clock line). Data bits may be valid after the rising or falling edge of the clock line. This kind of serial protocol is commonly used by controller peripherals like ADCs, DACs, clocks, memory devices, etc.

At their heart, synchronous-serial devices are essentially shift-registers; trains of flip-flops that pass data bits along in a bucket brigade fashion to a
single data output pin. Another bit is output each time the appropriate edge (rising or falling, depending on the device) appears on the clock line.

The SHIFTIN instruction first causes the clock pin to output low and the data pin to switch to input mode. Then, SHIFTIN either reads the data pin and generates a clock pulse (PRE mode) or generates a clock pulse then reads the data pin (POST mode). SHIFTIN continues to generate clock pulses and read the data pin for as many data bits as are required.

Making SHIFTIN work with a particular device is a matter of matching the mode and number of bits to that device’s protocol. Most manufacturers use a timing diagram to illustrate the relationship of clock and data. Items to look for include: 1) which bit of the data arrives first; most significant bit (MSB) or least significant bit (LSB) and 2) is the first data bit ready before the first clock pulse (PRE) or after the first clock pulse (POST). Table 5.90 shows the values and symbols available for the Mode argument and Figure 5.38 shows SHIFTIN’s timing.

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Value</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>MSBPRE</td>
<td>0</td>
<td>Data is msb-first; sample bits before clock pulse</td>
</tr>
<tr>
<td>LSBPRE</td>
<td>1</td>
<td>Data is lsb-first; sample bits before clock pulse</td>
</tr>
<tr>
<td>MSBPOST</td>
<td>2</td>
<td>Data is msb-first; sample bits after clock pulse</td>
</tr>
<tr>
<td>LSBPOST</td>
<td>3</td>
<td>Data is lsb-first; sample bits after clock pulse</td>
</tr>
</tbody>
</table>

(Msb is most-significant bit; the highest or leftmost bit of a nibble, byte, or word. Lsb is the least-significant bit; the lowest or rightmost bit of a nibble, byte, or word.)

Figure 5.38: SHIFTIN Timing Diagram. Refer to the SHIFTIN Quick Answers table for timing information on tₘ and tᵣ.
Here is a simple example:

```basic
Result VAR BYTE
SHIFTIN 0, 1, MSBPRE, [ Result ]
```

Here, the SHIFTIN command will read I/O pin 0 (the \( D_{pin} \)) and will generate a clock signal on I/O 1 (the \( C_{pin} \)). The data that arrives on the \( D_{pin} \) depends on the device connected to it. Let's say, for example, that a shift register is connected and has a value of $AF (10101111) waiting to be sent. Additionally, let's assume that the shift register sends out the most significant bit first, and the first bit is on the \( D_{pin} \) before the first clock pulse (MSBPRE). The SHIFTIN command above will generate eight clock pulses and sample the data pin (\( D_{pin} \)) eight times. Afterward, the \( Result \) variable will contain the value $AF.

By default, SHIFTIN acquires eight bits, but you can set it to shift any number of bits from 1 to 16 with the \( Bits \) argument. For example:

```basic
Result VAR BYTE
SHIFTIN 0, 1, MSBPRE, [ Result 4 ]
```

Will only input the first 4 bits. In the example discussed above, the \( Result \) variable will be left with %1010.

Some devices return more than 16 bits. For example, most 8-bit shift registers can be daisy-chained together to form any multiple of 8 bits; 16, 24, 32, 40... To solve this, you can use a single SHIFTIN instruction with multiple variables. Each variable can be assigned a particular number of bits with the \( Bits \) argument. As in:

```basic
ResultLow VAR WORD
ResultHigh VAR NIB
SHIFTIN 0, 1, MSBPRE, [ ResultHigh\4 , ResultLow\16 ]
```

The above code will first shift in four bits into \( ResultHigh \) and then 16 bits into \( ResultLow \). The two variables together make up a 20 bit value.
Demo Program (SHIFTIN.bs2)

' This program uses the SHIFTIN instruction to interface with the ADC0831 8-bit
' analog-to-digital converter from National Semiconductor.

'[$STAMP  BS2]    'STAMP directive (specifies a BS2)
ADres   VAR   BYTE    'A-to-D result: one byte.
CS     CON   0       'Chip select is pin 0.
AData  CON   1       'ADC data output is pin 1.
CLK    CON   2       'Clock is pin 2.

HIGH  CS     'Deselect ADC to start.

' In the loop below, just three lines of code are required to read the ADC0831. The
' SHIFTIN command does most of the work. The mode argument in the SHIFTIN command
' specifies msb or lsb-first and whether to sample data before or after the clock.
' In this case, we chose msb-first, post-clock. The ADC0831 precedes its data output
' with a dummy bit, which we take care of by specifying 9 bits of data instead of 8.

Again:
  LOW  CS          'Activate the ADC0831.
  SHIFTIN  AData, CLK, MSBPOST, [ADres\9]    'Shift in the data.
  HIGH  CS        'Deactivate ADC0831.
  DEBUG  ? ADres   'Show us the conversion result.
  PAUSE  1000     'Wait a second.
  GOTO  Again     'Do it again.

NOTE: This is written for the BS2 but can be used for the BS2e,
BS2sx and BS2p also. Locate the proper source code file or modify
the STAMP directive before downloading to the BS2e, BS2sx or
BS2p.
SHIFTOUT  

SHIFTOUT  

Function
Shift data out to a synchronous serial device.

- **Dpin** is a variable/constant/expression (0 – 15) that specifies the I/O pin that will be connected to the synchronous serial device’s data input. This pin will be set to output mode.

- **Cpin** is a variable/constant/expression (0 – 15) that specifies the I/O pin that will be connected to the synchronous serial device’s clock input. This pin will be set to output mode.

- **Mode** is a variable/constant/expression (0 – 1), or one of two predefined symbols, that tells SHIFTOUT the order in which data bits are to be arranged. See Table 5.92 for value and symbol definitions.

- **OutputData** is a variable/constant/expression containing the data to be sent.

- **Bits** is an optional variable/constant/expression (1 – 16) specifying how many bits are to be output by SHIFTOUT. If no Bits entry is given, SHIFTOUT defaults to 8 bits.

Quick Facts

<table>
<thead>
<tr>
<th></th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Timing of (t_h), (t_r), (t_a), and (t_b)</td>
<td>14 µs / 46 µs</td>
<td>14 µs / 46 µs</td>
<td>5.6 µs / 18 µs</td>
<td>5.6 µs / 18.8 µs</td>
</tr>
<tr>
<td>Transmission Rate</td>
<td>~16 kbits/sec</td>
<td>~16 kbits/sec</td>
<td>~42 kbits/sec</td>
<td>~42 kbits/sec</td>
</tr>
</tbody>
</table>

Explanation
SHIFTIN and SHIFTOUT provide an easy method of acquiring data from synchronous serial devices. Synchronous serial differs from asynchronous serial (like SERIN and SEROUT) in that the timing of data bits (on a data line) is specified in relationship to clock pulses (on a clock line). Data bits may be valid after the rising or falling edge of the clock line. This kind of serial protocol is commonly used by controller peripherals like ADCs, DACs, clocks, memory devices, etc.
At their heart, synchronous-serial devices are essentially shift-registers; trains of flip-flops that receive data bits in a bucket brigade fashion from a single data input pin. Another bit is input each time the appropriate edge (rising or falling, depending on the device) appears on the clock line.

The SHIFTOUT instruction first causes the clock pin to output low and the data pin to switch to output mode. Then, SHIFTOUT sets the data pin to the next bit state to be output and generates a clock pulse. SHIFTOUT continues to generate clock pulses and places the next data bit on the data pin for as many data bits as are required for transmission.

Making SHIFTOUT work with a particular device is a matter of matching the mode and number of bits to that device’s protocol. Most manufacturers use a timing diagram to illustrate the relationship of clock and data. One of the most important items to look for is which bit of the data should be transmitted first; most significant bit (MSB) or least significant bit (LSB). Table 5.92 shows the values and symbols available for the Mode argument and Figure 5.39 shows SHIFTOUT’s timing.

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Value</th>
<th>Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>LSBFIRST</td>
<td>0</td>
<td>Data is shifted out lsb-first</td>
</tr>
<tr>
<td>MSBFIRST</td>
<td>1</td>
<td>Data is shifted out msb-first</td>
</tr>
</tbody>
</table>

(Msb is most-significant bit; the highest or leftmost bit of a nibble, byte, or word. Lsb is the least-significant bit; the lowest or rightmost bit of a nibble, byte, or word.)

![SHIFTOUT Timing Diagram](image-url)

 shiftedout basic stamp command reference
Here is a simple example:

```
SHIFTOUT 0, 1, MSBFIRST, [ 250 ]
```

Here, the SHIFTOUT command will write to I/O pin 0 (the Dpin) and will generate a clock signal on I/O 1 (the Cpin). The SHIFTOUT command will generate eight clock pulses while writing each bit (of the 8-bit value 250) onto the data pin (Dpin). In this case, it will start with the most significant bit first as indicated by the Mode value of MSBFIRST.

By default, SHIFTOUT transmits eight bits, but you can set it to shift any number of bits from 1 to 16 with the Bits argument. For example:

```
SHIFTOUT 0, 1, MSBFIRST, [ 250\4 ]
```

Will only output the lowest 4 bits (%0000 in this case).

Some devices require more than 16 bits. To solve this, you can use a single SHIFTOUT command with multiple values. Each value can be assigned a particular number of bits with the Bits argument. As in:

```
SHIFTOUT 0, 1, MSBFIRST, [ 250\4 , 1045\16 ]
```

The above code will first shift out four bits of the number 250 (%1111) and then 16 bits of the number 1045 (%0000010000010101). The two values together make up a 20 bit value.

In the examples above, specific numbers were entered as the data to transmit, but, of course, the SHIFTOUT command will accept variables and expressions for the OutputData and even for the Bits argument.
Demo Program (SHIFTOUT.bs2)

' This program uses the SHIFTOUT command to interface to the 74HC595 shift register as an
' 8-bit output port. The '595 requires a minimum of three inputs: data, clock, and latch. See
' the figure in the SHIFTOUT command description in the manual for wiring information.
' SHIFTOUT automatically handles the data and clock, pulsing the clock to shift data bits into
' the '595. An extra step (pulsing the latch input) is required to move the shifted bits in parallel
' onto the '595's output pins. Note: this code does not control the output-enable or reset lines
' of the '595. This means that before the BASIC Stamp first sends, the '595's output latches
' are turned on and may contain random data. In critical applications, you should hold
' output-enable high (disabled) until the BASIC Stamp can take control.

'{$STAMP BS2}

DataP CON 0
Clock CON 1
Latch CON 2
Counter VAR BYTE

' This loop moves the 8-bit value 'counter' onto the output lines of the '595, pauses, then
' increments counter and repeats. The data is shifted msb first so that the msb appears on
' pin QH and the lsb on QA. Changing 'msbfirst' to 'lsbfirst' causes the data to
' appear backwards on the outputs.

Again:
SHIFTOUT DataP,Clock,MSBFIRST,[Counter]
PULSOUT Latch,1
PAUSE 50
Counter = Counter + 1
GOTO Again

NOTE: This is written for the BS2
but can be used for the BS2e,
BS2sx and BS2p also. Locate the
proper source code file or modify
the STAMP directive before
downloading to the BS2e, BS2sx or
BS2p.
SLEEP

Function
Put the BASIC Stamp into low-power mode for a specified time.

- **Period** is a variable/constant/expression (1 – 65535) that specifies the duration of sleep. The unit of time for **Period** is 1 second, though the BASIC Stamp rounds up to the nearest multiple of 2.3 seconds.

Quick Facts

<table>
<thead>
<tr>
<th>BS1</th>
<th>BS2</th>
<th>BS2e</th>
<th>BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>Current draw during run</td>
<td>2 mA</td>
<td>8 mA</td>
<td>25 mA</td>
<td>60 mA</td>
</tr>
<tr>
<td>Current draw during SLEEP</td>
<td>20 µA</td>
<td>40 µA</td>
<td>60 µA</td>
<td>60 µA</td>
</tr>
<tr>
<td>Accuracy of SLEEP</td>
<td>±1% @ 75°F with stable power supply</td>
<td>±1% @ 75°F with stable power supply</td>
<td>±1% @ 75°F with stable power supply</td>
<td>±1% @ 75°F with stable power supply</td>
</tr>
</tbody>
</table>

Explanation
SLEEP allows the BASIC Stamp to turn itself off, then turn back on after a programmed period of time. The length of SLEEP can range from 2.3 seconds to slightly over 18 hours. Power consumption is reduced to the amount described in Table 5.93, assuming no loads are being driven. The resolution of the SLEEP instruction is 2.304 seconds. SLEEP rounds the specified number of seconds up to the nearest multiple of 2.304. For example, SLEEP 1 causes 2.3 seconds of sleep, while SLEEP 10 causes 11.52 seconds (5 x 2.304) of sleep.

Pins retain their previous I/O directions during SLEEP. However, outputs are interrupted every 2.3 seconds during SLEEP due to the way the chip keeps time. The alarm clock that wakes the BASIC Stamp up is called the watchdog timer. The watchdog is a resistor/capacitor oscillator built into the interpreter chip. During SLEEP, the chip periodically wakes up and adjusts a counter to determine how long it has been asleep. If it isn’t time to wake up, the chip “hits the snooze bar” and goes back to sleep.

To ensure accuracy of SLEEP intervals, the BASIC Stamp periodically compares the watchdog timer to the more-accurate resonator time base. It
calculates a correction factor that it uses during SLEEP. As a result, longer SLEEP intervals are accurate to approximately ±1 percent.

If your application is driving loads (sourcing or sinking current through output-high or output-low pins) during SLEEP, current will be interrupted for about 18 ms when the BASIC Stamp wakes up every 2.3 seconds. The reason is that the watchdog-timer reset that awakens the BASIC Stamp also causes all of the pins to switch to input mode for approximately 18 ms. When the interpreter firmware regains control of the processor, it restores the I/O directions dictated by your program.

If you plan to use END, NAP, or SLEEP in your programs, make sure that your loads can tolerate these periodic power outages. The simplest solution is often to connect resistors high or low (to +5V or ground) as appropriate to ensure a continuing supply of current during the reset glitch.

The demo program can be used to demonstrate the effects of the SLEEP glitch with an LED and resistor as shown in Figure 5.41.

**Demo Program (SLEEP.bs2)**

```plaintext
' This program lights an LED and then goes to sleep. Connect an LED to pin 0 as shown in ' the description of SLEEP in the manual and run the program. The LED will turn on, then ' the BASIC Stamp will go to sleep. During sleep, the LED will remain on, but will blink ' at intervals of approximately 2.3 seconds due to the watchdog timeout and reset.

'{STAMP BS2}   'STAMP directive (specifies a BS2)
LOW 0   ' Turn LED on
Snooze:
   SLEEP 10    ' Sleep for 10 seconds.
GOTO Snooze
```

**Figure 5.41**: SLEEP Example LED Circuit.

NOTE: This is written for the BS2 but can be used for the BS1, BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS1, BS2e, BS2sx or BS2p.
FUNCTION

Generate square-wave tones for a specified period.

- **Pin** is a variable/constant (0 – 7) that specifies the I/O pin to use. This pin will be set to output mode.
- **Note** is a variable/constant (0 – 255) specifying the type and frequency of the tone. 1 – 127 are ascending tones and 128 – 255 are ascending white noises ranging from buzzing (128) to hissing (255).
- **Period** is a variable/constant (1 - 255) specifying the amount of time to generate the tone(s). The unit of time for **Period** is 12 ms.

EXPLANATION

SOUND generates one of 255 square-wave frequencies on an I/O pin. The output pin should be connected as shown in Figure 5.42.

The tones produced by SOUND can vary in frequency from 94.8 Hz (1) to 10,550 Hz (127). If you need to determine the frequency corresponding to a given note value, or need to find the note value that will give you best approximation for a given frequency, use the equations below.

\[
\text{Note} = 127 - \left( \frac{(1/\text{Frequency})-0.000095}{0.000083} \right)
\]

--and--

\[
\text{Frequency} = \left( \frac{1}{0.000095 + (127-\text{Note}) \times 0.000083} \right)
\]

Note, in the above equations, Frequency is in Hertz (Hz).
Demo Program (SOUND.bas)
' This program generates a constant tone 25 followed by an ascending tones. Both the tones
' have the same period (duration).

'${STAMP BS1}                  'STAMP directive (specifies a BS1)
SYMBOL   Tone = B0
FOR   Tone = 0 TO 255
    SOUND   1, (25, 10, Tone, 10)
NEXT

Figure 5.42: Example RC filter circuits for driving an audio amplifier or a speaker.

Driving a Speaker

from I/O pin

1k
0.1µF
Vss
C1
Vss

1k
0.01µF
Vss
C2
Vss

≥40Ω Speaker
(or 8Ω in series
with 33Ω resistor)

Notes:
C1 may be omitted for piezo speakers
C2 is optional, but reduces high-frequency noise

Driving an Audio Amplifier

from I/O pin

1k
0.1µF
Vss

1k
0.01µF
Vss

Amplifier
(e.g., Radio Shack
277-1008C)
STOP

Function
Stop program execution.

Explanation
STOP prevents the BASIC Stamp from executing any further instructions until it is reset. The following actions will reset the BASIC Stamp:

1. Pressing and releasing the RESET button on the development board.
2. Driving the RES pin low then letting it float (high).
3. Downloading a new program
4. Disconnecting then reconnecting the power.

STOP differs from END in two respects:
1. Stop does not put the BASIC Stamp into low-power mode. The BASIC Stamp draws just as much current as if it were actively running program instructions.
2. The output glitch that occurs after a program has "ended" does not occur after a program has "stopped."

Demo Program (STOP.bs2)

' This program is similar to SLEEP.bs2 except that the LED will not blink since the BASIC Stamp does not go into low power mode. Use the circuit shown in the description of the SLEEP command for this example.

'{$STAMP BS2}' 'STAMP directive (specifies a BS2)
LOW 0 ' Turn LED on
STOP ' Stop the program forever

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, BS2sx or BS2p.
Function
Designate a program slot for the READ/WRITE instructions to operate upon.

- **ProgramSlot** is a variable/constant/expression (0 – 7) that specifies the program slot to use for READ and WRITE instructions.

Explanation
STORE tells the BS2p which program slot to use when a READ or WRITE instruction is executed. The STORE command only affects the READ and WRITE instructions.

The STORE command allows a program to access all EEPROM locations that exist on the BS2p, regardless of which program is running or which program slot is active. The READ and WRITE commands can only access locations 0 to 2047 within a single program slot. The STORE command switches the program slot that the READ and WRITE commands operate on.

The default program slot that the READ and WRITE instructions operate on is the currently running program. The STORE command can be used to temporarily change this, to any program slot. The change will remain in effect until another STORE command is issued, or until another program slot is executed.

Demo Program (STORE0.bsp)

This program demonstrates the STORE command and how it affects the READ and WRITE commands. This program "STORE0.BSP" is intended to be downloaded into program slot 0. It is meant to work with STORE1.BSP and STORE2.BSP. Each program is very similar (they display the current Program Slot and Read/Write Slot numbers and the values contained in the first five EEPROM locations. Each program slot will have different data due to different DATA commands in each of the programs downloaded.

```plaintext
'$STAMP BS2p, Store1.bsp, Store2.bsp'  'STAMP directive (specifies a BS2p)

DATA @0, 1, 2, 3, 4, 5

Idx    VAR    WORD
Value  VAR    BYTE
```

```plaintext
Demo Program (STORE0.bsp)

This program demonstrates the STORE command and how it affects the READ and WRITE commands. This program "STORE0.BSP" is intended to be downloaded into program slot 0. It is meant to work with STORE1.BSP and STORE2.BSP. Each program is very similar (they display the current Program Slot and Read/Write Slot numbers and the values contained in the first five EEPROM locations. Each program slot will have different data due to different DATA commands in each of the programs downloaded.

`'$STAMP BS2p, Store1.bsp, Store2.bsp'  'STAMP directive (specifies a BS2p)

DATA @0, 1, 2, 3, 4, 5

Idx    VAR    WORD
Value  VAR    BYTE
```
' -------------------------- Main Routines --------------------------

Main:
GOSUB DisplaySlotsAndReadData
PAUSE 2000
STORE 1               'Switch to READ/WRITE slot 1
GOSUB DisplaySlotsAndReadData
PAUSE 2000
RUN 1                  'Switch to program 1

' --------------------------- Subroutines ---------------------------
DisplaySlotsAndReadData:
GET 127, Value
DEBUG CR, "Prog Slot: ", DEC1 Value.LOWNIB
DEBUG "   R/W Slot: ", DEC1 Value.HIGNIB, CR, CR

FOR Idx = 0 TO 4
   READ Idx, Value
   DEBUG "Location: ", DEC Idx, " Value: ", DEC3 Value, CR
NEXT
RETURN

Demo Program (STORE1.bsp)
DATA @0, 6, 7, 8, 9, 10

Idx       VAR    WORD
Value     VAR    BYTE

' -------------------------- Main Routines --------------------------

Main:
GOSUB DisplaySlotsAndReadData
PAUSE 2000
STORE 0               'Switch to READ/WRITE slot 0
GOSUB DisplaySlotsAndReadData
PAUSE 2000
RUN 2                  'Switch to program 2

' --------------------------- Subroutines ---------------------------
DisplaySlotsAndReadData:
GET 127, Value
DEBUG CR, "Prog Slot: ", DEC1 Value.LOWNIB
DEBUG "   R/W Slot: ", DEC1 Value.HIGNIB, CR, CR

FOR Idx = 0 TO 4
   READ Idx, Value
   DEBUG "Location: ", DEC Idx, " Value: ", DEC3 Value, CR
NEXT
RETURN
Demo Program (STORE2.bsp)

DATA @0, 11, 12, 13, 14, 15

Idx  VAR  WORD
Value  VAR  BYTE

' -------------------------- Main Routines --------------------------
Main:
  GOSUB  DisplaySlotsAndReadData
  PAUSE  2000
  STORE  0  'Switch to READ/WRITE slot 0
  GOSUB  DisplaySlotsAndReadData
  STOP  'Stop execution

' --------------------------- Subroutines ---------------------------
DisplaySlotsAndReadData:
  GET  127,  Value
  DEBUG  CR, "Prog Slot: ", DEC1  Value.LOWNIB
  DEBUG  "   R/W Slot: ", DEC1  Value.HIGNIB, CR, CR
  FOR  Idx = 0  TO  4
    READ  Idx, Value
    DEBUG  "Location: ", DEC  Idx, "  Value: ", DEC3  Value, CR
  NEXT
  RETURN

The next Demo Program, StoreAll.bsp, is not related to the previous three programs. StoreAll.bsp demonstrates the use of the STORE command to treat contiguous program slots as one block of memory (14 kbytes). This illustrates one of the most powerful uses of the STORE command.

Demo Program (STOREALL.bsp)

' This program demonstrates the STORE command and how it can be used to "flatten" the EEPROM space for applications requiring a lot of storage. This program writes to EEPROM locations within program slots 1 through 7 and, thus, has access to 14 kbytes of space.

'{$STAMP  BS2p}  'STAMP directive (specifies a BS2p)

Idx  VAR  WORD
Value  VAR  WORD

' -------------------------- Main Routines --------------------------
Main:
  DEBUG  "Writing...", CR
  PAUSE  2000
  FOR  Idx = 2048  TO  16383  STEP  32  'Write values to EEPROM
}
Value = Idx – 2048 * 2
'Use different numbers in each location
GOSUB WriteWordToEEPROM
DEBUG "Location: ", DEC5 Idx, " Value: ", DEC5 Value, CR
NEXT

DEBUG "Reading...", CR
PAUSE 2000
FOR Idx = 2048 TO 16383 STEP 32 'Read values from EEPROM
  GOSUB ReadWordFromEEPROM
  DEBUG "Location: ", DEC5 Idx, " Value: ", DEC5 Value, CR
NEXT
STOP

' --------------------------- Subroutines ---------------------------
WriteWordToEEPROM:
'NOTE: This routine is written to work only when Idx is an even-byte boundary
STORE Idx >> 11 'Set to proper READ/WRITE slot (upper 3-bits of address)
WRITE Idx, Value.LOWBYTE
WRITE Idx+1, Value.HIGHBYTE
RETURN

ReadWordFromEEPROM:
'NOTE: This routine is written to work only when Idx is an even-byte boundary
STORE Idx >> 11 'Set to proper READ/WRITE slot (upper 3-bits of address)
READ Idx, Value.LOWBYTE
READ Idx+1, Value.HIGHBYTE
RETURN
TOGGLE

Function
Invert the state of an output pin.

- Pin is a variable/constant/expression (0 – 15) that specifies which I/O pin to set high. This pin will be placed into output mode.

Explanation
TOGGLE sets a pin to output mode and inverts the output state of the pin, changing 0 to 1 and 1 to 0.

In some situations TOGGLE may appear to have no effect on a pin’s state. For example, suppose pin 2 is in input mode and pulled to +5V by a 10k resistor. Then the following code executes:

```plaintext
DIR2 = 0  ' Pin 2 in input mode.
PIN2 = 0  ' Pin 2 output driver low.
DEBUG ? PIN2  ' Show state of pin 2 (1 due to pullup).
TOGGLE 2  ' Toggle pin 2 (invert PIN2, put 1 in DIR2).
DEBUG ? PIN2  ' Show state of pin 2 (1 again).
```

--or--

```plaintext
DIR2 = 0  ' Pin 2 in input mode.
OUT2 = 0  ' Pin 2 output driver low.
DEBUG ? IN2  ' Show state of pin 2 (1 due to pullup).
TOGGLE 2  ' Toggle pin 2 (invert OUT2, put 1 in DIR2).
DEBUG ? IN2  ' Show state of pin 2 (1 again).
```

The state of pin 2 doesn’t change; it’s high (due to the resistor) before TOGGLE, and it’s high (due to the pin being output high) afterward. The point is that TOGGLE works on the OUTS register, which may not match the pin’s state when the pin is initially an input. To guarantee that the state actually changes, regardless of the initial input or output mode, do this:

```plaintext
PIN2 = PIN2' Make output driver match pin state.
TOGGLE 2  ' Then toggle.
```

--or--

```plaintext
OUT2 = IN2 ' Make output driver match pin state.
TOGGLE 2  ' Then toggle.
```
Demo Program (TOGGLE.bas)
' Connect LEDs to pins 0 through 3 as shown in the TOGGLE command description in the manual and run this program. The TOGGLE command will treat you to a light show. You may also run the demo without LEDs. The debug window will show you the states of pins 0 through 3.

'{STAMP BS1}
SYMBOL ThePin = B0 ' Variable to count 0-3.
Again:
FOR ThePin = 0 TO 3 ' Pins 0 to 3 driving LEDs.
   TOGGLE ThePin ' Toggle each pin.
   DEBUG CLS, #PINS ' No LEDs? Watch debug screen.
   PAUSE 200 ' Brief delay.
NEXT ' Next pin
GOTO Again ' Repeat endlessly.

Demo Program (TOGGLE.bs2)
' Connect LEDs to pins 0 through 3 as shown in the TOGGLE command description in the manual and run this program. The TOGGLE command will treat you to a light show. You may also run the demo without LEDs. The debug window will show you the states of pins 0 through 3.

'{STAMP BS2}
ThePin VAR NIB ' Variable to count 0-3.
Again:
FOR ThePin = 0 TO 3 ' Pins 0 to 3 driving LEDs.
   TOGGLE ThePin ' Toggle each pin.
   DEBUG CLS, BIN4 INA ' No LEDs? Watch debug screen.
   PAUSE 200 ' Brief delay.
NEXT ' Next pin
GOTO Again ' Repeat endlessly.

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, BS2sx or BS2p.
WRITE

Function
Write *DataItem* into *Location* in EEPROM.

- *Location* is a variable/constant/expression (0 – 255 on BS1, 0 – 2047 on all other BASIC Stamps) that specifies the EEPROM address to write to.

- *DataItem* is a variable/constant/expression specifying the value to be stored.

Quick Facts

<table>
<thead>
<tr>
<th>BS1</th>
<th>BS2</th>
<th>BS2e, BS2sx</th>
<th>BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 to 255</td>
<td>0 to 2047</td>
<td>0 to 2047</td>
<td>0 to 2047 (see notes below)</td>
</tr>
<tr>
<td>10 million</td>
<td>10 million</td>
<td>100,000</td>
<td>100,000</td>
</tr>
</tbody>
</table>

Special notes
WRITE only works with current program slot on BS2e and BS2sx. WRITE works with any program slot as set by the STORE command.

Explanation
The EEPROM is used for both program storage (which builds downward from address 255 on BS1, 2047 on all other BASIC Stamps) and data storage (which builds upward from address 0). The WRITE instruction stores a byte of data to any EEPROM address. Any location within the EEPROM can be written to (including your PBASIC program’s locations) at run-time. This feature is mainly used to store long-term data from EEPROM; data stored in EEPROM is not lost when the power is removed.

A SIMPLE WRITE COMMAND.

The following WRITE command stores the value 245 at location 100:

```
WRITE 100, 245
```
WRITE 100, 245

--or--

WRITE 100, 245

The EEPROM is organized as a sequential set of byte-sized memory locations. The WRITE command only stores byte-sized values into EEPROM. This does not mean that you can’t write word-sized values, however. A word consists of two bytes, called a low-byte and a high-byte. If you wanted to write a word-sized value, you’ll need to use two WRITE commands and a word-size value or variable (along with some handy modifiers). For example,

```
SYMBOL Value   = W0 'The full word-sized variable
SYMBOL Value_Low  = B0 'B0 happens to be the low-byte of W0
SYMBOL Value_High = B1 'B1 happens to be the high-byte of W0
```

Value = 1125

```
WRITE 0, Value_Low
WRITE 1, Value_High
```

--or--

```
Value VAR WORD
WRITE 0, Value.LOWBYTE
WRITE 1, Value.HIGHBYTE
```

When this program runs, the two WRITE commands will store the low-byte and high-byte of the number 1125 into EEPROM.

EEPROM differs from RAM, the memory in which variables are stored, in several respects:

1. Writing to EEPROM takes more time than storing a value in a variable. Depending on many factors, it may take several milliseconds for the EEPROM to complete a write. RAM storage is nearly instantaneous.
2. The EEPROM can only accept a finite number of write cycles per location before it wears out. Table 5.94 indicates the guaranteed number of writes before failure. If a program frequently writes to the same EEPROM location, it makes sense to estimate how long it...
might take to exceed the guaranteed maximum. For example, on the BS2, at one write per second (86,400 writes/day) it would take nearly 116 days of continuous operation to exceed 10 million.

3. The primary function of the EEPROM is to store programs (data is stored in leftover space). If data overwrites a portion of your program, the program will most likely crash.

Check the program’s memory map to determine what portion of memory your program occupies and make sure that EEPROM writes cannot stray into this area. You may also use the DATA directive on the BS2, BS2e, BS2sx and BS2p to set aside EEPROM space.

On the BS1, location 255 holds the address of the last instruction in your program. Therefore, your program can use any space below the address given in location 255. For example, if location 255 holds the value 100, then your program can use locations 0–99 for data.

On other BASIC Stamps, you'll need to view the Memory Map of the program before you download it, to determine the last EEPROM location used. See the "Memory Map Function" section in Chapter 3.

On the BS2p, the READ and WRITE commands can affect locations in any program slot as set by the STORE command. See the STORE command for more information.

Demo Program (WRITE.bas)

` This program writes a few bytes to EEPROM and then reads them back out and displays them on the screen.

`{STAMP BS1}    'STAMP directive (specifies a BS1)

SYMBOL ValAddr = B0
SYMBOL Value = B1

WriteItOut:
WRITE 0, 100    'Write some data to location 0 through 3
WRITE 1, 200
WRITE 2, 45
WRITE 3, 28

ReadItOut:
FOR ValAddr = 0 TO 3
READ ValAddr, Value
DEBUG ? Value

' Read all four locations and display the value on the screen
Demo Program (WRITE.bs2)

' This program writes a few bytes to EEPROM and then reads them back out and displays
' them on the screen.

'{$STAMP BS2} 'STAMP directive (specifies a BS2)
ValAddr VAR BYTE
Value VAR BYTE

WriteItOut:
WRITE 0, 100
WRITE 1, 200
WRITE 2, 45
WRITE 3, 28

ReadItOut:
FOR ValAddr = 0 TO 3
  READ ValAddr, Value
  DEBUG ? Value
NEXT

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the
proper source code file or modify the STAMP directive before
downloading to the BS2e, BS2sx or BS2p.
XOUT Mpin, Zpin, [ House\Command {\Cycles} {, House\Command {\Cycles}…} ]

Function
Send an X-10 power-line control command (through the appropriate power-line interface).

- \textit{Mpin} is a variable/constant/expression (0 – 15) that specifies the I/O pin to output X-10 signals (modulation) to the power-line interface device. This pin will be set to output mode.

- \textit{Zpin} is a variable/constant/expression (0 – 15) that specifies the I/O pin that inputs the zero-crossing signal from the power-line interface device. This pin will be set to input mode.

- \textit{House} is a variable/constant/expression (0 – 15) that specifies the X-10 house code (values 0 - 15 representing letters A through P).

- \textit{Command} is a variable/constant/expression (0 – 30) that specifies the command to send. Values 0 – 15 correspond to unit codes 1 – 16. Other commands are shown in Table 5.96.

- \textit{Cycles} is an optional variable/constant/expression (1 – 255) specifying the number of times to transmit a given key or command. If no \textit{Cycles} entry is used, XOUT defaults to two. The \textit{Cycles} entry should be used only with the DIM and BRIGHT command codes.

Quick Facts

<table>
<thead>
<tr>
<th>Compatible power-line interfaces</th>
<th>BS2, BS2e, BS2sx and BS2p</th>
</tr>
</thead>
<tbody>
<tr>
<td>PL-513 and TW-523</td>
<td></td>
</tr>
</tbody>
</table>

| Special notes | The XOUT command will stop the BASIC Stamp program until it is able to send the transmission. If there is no AC power to the power-line interface, the BASIC Stamp program will halt forever. |

Explanation
XOUT lets you control appliances via signals sent through household AC wiring to X-10 modules. The appliances plugged into these modules can be switched on or off; lights may also be dimmed. Each module is assigned a house code and unit code by setting dials or switches on the
module. To talk to a particular module, XOUT sends the appropriate house code and unit code. The module with the corresponding code listens for its house code again followed by a command (on, off, dim, or bright).

X-10 signals are digital codes imposed on a 120 kHz carrier that is transmitted during zero crossings of the AC line. To send X-10 commands, a controller must synchronize to the AC line frequency with 50 µs precision, and transmit an 11-bit code sequence representing the command.

XOUT interfaces to the AC power-line through an approved interface device such as a PL-513 or TW-523, available from Parallax or X-10 dealers. The hookup requires a length of four-conductor phone cable and a standard modular phone-base connector (6P4C type). Connections are shown in Figure 5.44.

Figure 5.44: XOUT Power-Line Interface Circuit.
Table 5.96 lists the XOUT command codes and their functions:

<table>
<thead>
<tr>
<th>Command</th>
<th>Value</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>UnitOn</td>
<td>%10010</td>
<td>Turn on the currently selected unit.</td>
</tr>
<tr>
<td>UnitOff</td>
<td>%11010</td>
<td>Turn off the currently selected unit.</td>
</tr>
<tr>
<td>UnitsOff</td>
<td>%11100</td>
<td>Turn off all modules in this house code.</td>
</tr>
<tr>
<td>LightsOn</td>
<td>%10100</td>
<td>Turn on all lamp modules in this house code.</td>
</tr>
<tr>
<td>Dim</td>
<td>%11110</td>
<td>Reduce brightness of currently selected lamp.</td>
</tr>
<tr>
<td>Bright</td>
<td>%10110</td>
<td>Increase brightness of currently selected lamp.</td>
</tr>
</tbody>
</table>

Note: In most applications, it’s not necessary to know the code for a given X-10 instruction. Just use the command constant (UnitOn, Dim, etc.) instead. But knowing the codes leads to some interesting possibilities. For example, XORing a UnitOn command with the value %1000 turns it into a UnitOff command, and vice-versa. This makes it possible to write the equivalent of an X-10 “toggle” instruction.

Here is an example of the XOUT instruction:

```
Zpin   CON 0  ' Zpin is P0.
Mpin   CON 1  ' Mpin is P1.
HouseA CON 0  ' House code A = 0.
Unit1  CON 0  ' Unit code 1 = 0.

XOUT  Mpin, Zpin, [HouseA\Unit1]  ' Get unit 1’s attention..
XOUT  Mpin, Zpin, [HouseA\UnitOn] ' ..and tell it to turn on.
```

Combining multiple commands.

You can combine those two XOUT instructions into one like so:

```
XOUT  Mpin, Zpin, [HouseA\Unit1\2, HouseA\UnitOn]  ' Unit 1 on.
```

Note that to complete the attention-getting code HouseA\Unit1 we tacked on the normally optional cycles entry \2 to complete the command before beginning the next one. Always specify two cycles in multiple commands unless you’re adjusting the brightness of a lamp module.

Dimming lights.

Here is an example of a lamp-dimming instruction:

```
Zpin   CON 0  ' Zpin is P0.
Mpin   CON 1  ' Mpin is P1.
HouseA CON 0  ' House code A = 0.
Unit1  CON 0  ' Unit code 1 = 0.

XOUT  Mpin, Zpin, [HouseA\Unit1]       'Get unit 1’s attention..
XOUT  Mpin, Zpin, [HouseA\UnitOff\10, HouseA\Dim\10] 'Dim halfway.
```

The dim/bright commands support 19 brightness levels. Lamp modules may also be turned on and off using the standard UnitOn and UnitOff commands. In the example instruction above, we dimmed the lamp by
first turning it completely off, then sending 10 cycles of the Dim command. This may seem odd, but it follows the peculiar logic of the X-10 system.

### Demo Program (X10.bs2)

This program--really two program fragments--demonstrates the syntax and use of the XOUT command. XOUT works like pressing the buttons on an X-10 control box; first you press one of 16 keys to identify the unit you want to control, then you press the key for the action you want that unit to take (turn ON, OFF, Bright, or Dim). There are also two group-action keys, Lights ON and All OFF. Lights ON turns all lamp modules on without affecting appliance modules. All OFF turns off all modules, both lamp and appliance types. Connect the BASIC Stamp to a power-line interface as shown in the XOUT command description in the manual.

```plaintext
' STAMP directive (specifies a BS2)

Zpin  CON 0 ' Zero-crossing-detect pin from TW523 or PL513.
Mpin  CON 1 ' Modulation-control pin to TW523 or PL513.
HouseA CON 0 ' House code: 0=A, 1=B... 15=P
Unit1 CON 0 ' Unit code: 0=1, 1=2... 15=16
Unit2 CON 1 ' Unit code 1=2.

' This first example turns a standard (appliance or non-dimmer lamp) module ON, then OFF. Note that once the Unit code is sent, it need not be repeated--subsequent instructions are understood to be addressed to that unit.
XOUT  Mpin, Zpin, [HouseA[Unit1\2, HouseA[UnitOn\]
PAUSE 1000 ' Wait a second.
XOUT  Mpin, Zpin, [HouseA[UnitOff\]

' The next example talks to a lamp module using the dimmer feature. Dimmers go from full ON to dimmed OFF in 19 steps. Because dimming is relative to the current state of the lamp, the only guaranteed way to set a predefined brightness level is to turn the dimmer fully OFF, then ON, then dim to the desired level.

XOUT  Mpin, Zpin, [HouseA[Unit2]

' This example shows the use of the optional Cycles argument. Here we Dim for 10 cycles.
XOUT  Mpin, Zpin, [HouseA[UnitOff\2, HouseA[Dim\10]

STOP
```

NOTE: This is written for the BS2 but can be used for the BS2e, BS2sx and BS2p also. Locate the proper source code file or modify the STAMP directive before downloading to the BS2e, BS2sx or BS2p.
### ASCII Chart (first 128 characters)

<table>
<thead>
<tr>
<th>Dec</th>
<th>Hex</th>
<th>Char</th>
<th>Name / Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>00</td>
<td>NUL</td>
<td>Null</td>
</tr>
<tr>
<td>1</td>
<td>01</td>
<td>SOH</td>
<td>Start Of Heading</td>
</tr>
<tr>
<td>2</td>
<td>02</td>
<td>STX</td>
<td>Start Of Text</td>
</tr>
<tr>
<td>3</td>
<td>03</td>
<td>ETX</td>
<td>End Of Text</td>
</tr>
<tr>
<td>4</td>
<td>04</td>
<td>EOT</td>
<td>End Of Transmit</td>
</tr>
<tr>
<td>5</td>
<td>05</td>
<td>ENQ</td>
<td>Enquiry</td>
</tr>
<tr>
<td>6</td>
<td>06</td>
<td>ACK</td>
<td>Acknowledge</td>
</tr>
<tr>
<td>7</td>
<td>07</td>
<td>BEL</td>
<td>Bell</td>
</tr>
<tr>
<td>8</td>
<td>08</td>
<td>BS</td>
<td>Backspace</td>
</tr>
<tr>
<td>9</td>
<td>09</td>
<td>HT</td>
<td>Horizontal Tab</td>
</tr>
<tr>
<td>10</td>
<td>0A</td>
<td>LF</td>
<td>Line Feed</td>
</tr>
<tr>
<td>11</td>
<td>0B</td>
<td>VT</td>
<td>Vertical Tab</td>
</tr>
<tr>
<td>12</td>
<td>0C</td>
<td>FF</td>
<td>Form Feed</td>
</tr>
<tr>
<td>13</td>
<td>0D</td>
<td>CR</td>
<td>Carriage Return</td>
</tr>
<tr>
<td>14</td>
<td>0E</td>
<td>SO</td>
<td>Shift Out</td>
</tr>
<tr>
<td>15</td>
<td>0F</td>
<td>SI</td>
<td>Shift In</td>
</tr>
<tr>
<td>16</td>
<td>10</td>
<td>DLE</td>
<td>Data Line Escape</td>
</tr>
<tr>
<td>17</td>
<td>11</td>
<td>DC1</td>
<td>Device Control 1</td>
</tr>
<tr>
<td>18</td>
<td>12</td>
<td>DC2</td>
<td>Device Control 2</td>
</tr>
<tr>
<td>19</td>
<td>13</td>
<td>DC3</td>
<td>Device Control 3</td>
</tr>
<tr>
<td>20</td>
<td>14</td>
<td>DC4</td>
<td>Device Control 4</td>
</tr>
<tr>
<td>21</td>
<td>15</td>
<td>NAK</td>
<td>Non Acknowledge</td>
</tr>
<tr>
<td>22</td>
<td>16</td>
<td>SYN</td>
<td>Synchronous Idle</td>
</tr>
<tr>
<td>23</td>
<td>17</td>
<td>ETB</td>
<td>End Transmit Block</td>
</tr>
<tr>
<td>24</td>
<td>18</td>
<td>CAN</td>
<td>Cancel</td>
</tr>
<tr>
<td>25</td>
<td>19</td>
<td>EM</td>
<td>End Of Medium</td>
</tr>
<tr>
<td>26</td>
<td>1A</td>
<td>SUB</td>
<td>Substitute</td>
</tr>
<tr>
<td>27</td>
<td>1B</td>
<td>ESC</td>
<td>Escape</td>
</tr>
<tr>
<td>28</td>
<td>1C</td>
<td>FS</td>
<td>File Separator</td>
</tr>
<tr>
<td>29</td>
<td>1D</td>
<td>GS</td>
<td>Group Separator</td>
</tr>
<tr>
<td>30</td>
<td>1E</td>
<td>RS</td>
<td>Record Separator</td>
</tr>
<tr>
<td>31</td>
<td>1F</td>
<td>US</td>
<td>Unit Separator</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Dec</th>
<th>Hex</th>
<th>Char</th>
<th>Name / Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>32</td>
<td>20</td>
<td>space</td>
<td></td>
</tr>
<tr>
<td>33</td>
<td>21</td>
<td>!</td>
<td></td>
</tr>
<tr>
<td>34</td>
<td>22</td>
<td>&quot;</td>
<td></td>
</tr>
<tr>
<td>35</td>
<td>23</td>
<td>#</td>
<td></td>
</tr>
<tr>
<td>36</td>
<td>24</td>
<td>$</td>
<td></td>
</tr>
<tr>
<td>37</td>
<td>25</td>
<td>%</td>
<td></td>
</tr>
<tr>
<td>38</td>
<td>26</td>
<td>&amp;</td>
<td></td>
</tr>
<tr>
<td>39</td>
<td>27</td>
<td>'</td>
<td></td>
</tr>
<tr>
<td>40</td>
<td>28</td>
<td>(</td>
<td></td>
</tr>
<tr>
<td>41</td>
<td>29</td>
<td>)</td>
<td></td>
</tr>
<tr>
<td>42</td>
<td>2A</td>
<td>*</td>
<td></td>
</tr>
<tr>
<td>43</td>
<td>2B</td>
<td>+</td>
<td></td>
</tr>
<tr>
<td>44</td>
<td>2C</td>
<td>,</td>
<td></td>
</tr>
<tr>
<td>45</td>
<td>2D</td>
<td>-</td>
<td></td>
</tr>
<tr>
<td>46</td>
<td>2E</td>
<td>.</td>
<td></td>
</tr>
<tr>
<td>47</td>
<td>2F</td>
<td>/</td>
<td></td>
</tr>
<tr>
<td>48</td>
<td>30</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>49</td>
<td>31</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>50</td>
<td>32</td>
<td>2</td>
<td></td>
</tr>
<tr>
<td>51</td>
<td>33</td>
<td>3</td>
<td></td>
</tr>
<tr>
<td>52</td>
<td>34</td>
<td>4</td>
<td></td>
</tr>
<tr>
<td>53</td>
<td>35</td>
<td>5</td>
<td></td>
</tr>
<tr>
<td>54</td>
<td>36</td>
<td>6</td>
<td></td>
</tr>
<tr>
<td>55</td>
<td>37</td>
<td>7</td>
<td></td>
</tr>
<tr>
<td>56</td>
<td>38</td>
<td>8</td>
<td></td>
</tr>
<tr>
<td>57</td>
<td>39</td>
<td>9</td>
<td></td>
</tr>
<tr>
<td>58</td>
<td>3A</td>
<td>:</td>
<td></td>
</tr>
<tr>
<td>59</td>
<td>3B</td>
<td>;</td>
<td></td>
</tr>
<tr>
<td>60</td>
<td>3C</td>
<td>&lt;</td>
<td></td>
</tr>
<tr>
<td>61</td>
<td>3D</td>
<td>=</td>
<td></td>
</tr>
<tr>
<td>62</td>
<td>3E</td>
<td>&gt;</td>
<td></td>
</tr>
<tr>
<td>63</td>
<td>3F</td>
<td>?</td>
<td></td>
</tr>
<tr>
<td>64</td>
<td>40</td>
<td>@</td>
<td></td>
</tr>
<tr>
<td>65</td>
<td>41</td>
<td>A</td>
<td></td>
</tr>
<tr>
<td>66</td>
<td>42</td>
<td>B</td>
<td></td>
</tr>
<tr>
<td>67</td>
<td>43</td>
<td>C</td>
<td></td>
</tr>
<tr>
<td>68</td>
<td>44</td>
<td>D</td>
<td></td>
</tr>
<tr>
<td>69</td>
<td>45</td>
<td>E</td>
<td></td>
</tr>
<tr>
<td>70</td>
<td>46</td>
<td>F</td>
<td></td>
</tr>
<tr>
<td>71</td>
<td>47</td>
<td>G</td>
<td></td>
</tr>
<tr>
<td>72</td>
<td>48</td>
<td>H</td>
<td></td>
</tr>
<tr>
<td>73</td>
<td>49</td>
<td>I</td>
<td></td>
</tr>
<tr>
<td>74</td>
<td>4A</td>
<td>J</td>
<td></td>
</tr>
<tr>
<td>75</td>
<td>4B</td>
<td>K</td>
<td></td>
</tr>
<tr>
<td>76</td>
<td>4C</td>
<td>L</td>
<td></td>
</tr>
<tr>
<td>77</td>
<td>4D</td>
<td>M</td>
<td></td>
</tr>
<tr>
<td>78</td>
<td>4E</td>
<td>N</td>
<td></td>
</tr>
<tr>
<td>79</td>
<td>4F</td>
<td>O</td>
<td></td>
</tr>
<tr>
<td>80</td>
<td>50</td>
<td>P</td>
<td></td>
</tr>
<tr>
<td>81</td>
<td>51</td>
<td>Q</td>
<td></td>
</tr>
<tr>
<td>82</td>
<td>52</td>
<td>R</td>
<td></td>
</tr>
<tr>
<td>83</td>
<td>53</td>
<td>S</td>
<td></td>
</tr>
<tr>
<td>84</td>
<td>54</td>
<td>T</td>
<td></td>
</tr>
<tr>
<td>85</td>
<td>55</td>
<td>U</td>
<td></td>
</tr>
<tr>
<td>86</td>
<td>56</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>87</td>
<td>57</td>
<td>W</td>
<td></td>
</tr>
<tr>
<td>88</td>
<td>58</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>89</td>
<td>59</td>
<td>Y</td>
<td></td>
</tr>
<tr>
<td>90</td>
<td>5A</td>
<td>Z</td>
<td></td>
</tr>
<tr>
<td>91</td>
<td>5B</td>
<td>[</td>
<td></td>
</tr>
<tr>
<td>92</td>
<td>5C</td>
<td>\</td>
<td></td>
</tr>
<tr>
<td>93</td>
<td>5D</td>
<td>]</td>
<td></td>
</tr>
<tr>
<td>94</td>
<td>5E</td>
<td>^</td>
<td></td>
</tr>
<tr>
<td>95</td>
<td>5F</td>
<td>_</td>
<td></td>
</tr>
</tbody>
</table>

Note that the control codes (lowest 32 ASCII characters) have no standardized screen symbols. The characters listed for them are just names used in referring to these codes. For example, to move the cursor to the beginning of the next line of a printer or terminal often requires sending line feed and carriage return codes. This common pair is referred to as "LF/CR."
## Appendix B: Reserved Words

### Reserved Words

<table>
<thead>
<tr>
<th>BS1</th>
<th>BS2</th>
<th>BS2e/sx (same as BS2 plus below)</th>
<th>BS2p (same as BS2 plus below)</th>
</tr>
</thead>
<tbody>
<tr>
<td>AND</td>
<td>ABS</td>
<td>GET</td>
<td>AUXIO</td>
</tr>
<tr>
<td>B0..B13</td>
<td>AND</td>
<td>PUT</td>
<td>GET</td>
</tr>
<tr>
<td>BIT0..BIT15</td>
<td>ASC</td>
<td>PUT</td>
<td>I2CIN</td>
</tr>
<tr>
<td>BRANCH</td>
<td>B0..B25</td>
<td>IF</td>
<td>I2COUT</td>
</tr>
<tr>
<td>BSAVE</td>
<td>BELL</td>
<td>IHEX1..IHEX4</td>
<td>IOTERM</td>
</tr>
<tr>
<td>BUTTON</td>
<td>BKSP</td>
<td>OUTPUT</td>
<td>LCDCMD</td>
</tr>
<tr>
<td>DEBUG</td>
<td>BIN</td>
<td>PAUSE</td>
<td>LCDIN</td>
</tr>
<tr>
<td>DIR0..DIR7</td>
<td>BIN1..BIN4</td>
<td>INB</td>
<td>LCDOUT</td>
</tr>
<tr>
<td>DIRS</td>
<td>BIT</td>
<td>INC</td>
<td>MAINIO</td>
</tr>
<tr>
<td>EEPROM</td>
<td>BIT0..BIT15</td>
<td>IND</td>
<td>OWIN</td>
</tr>
<tr>
<td>END</td>
<td>BRANCH</td>
<td>INL</td>
<td>OWOUT</td>
</tr>
<tr>
<td>FOR</td>
<td>BRIGHT</td>
<td>INPUT</td>
<td>POLLIN</td>
</tr>
<tr>
<td>GOSUB</td>
<td>BUTTON</td>
<td>INS</td>
<td>POLLOUT</td>
</tr>
<tr>
<td>GOTO</td>
<td>BYTE</td>
<td>REVERSE</td>
<td>POLLWAIT</td>
</tr>
<tr>
<td>HIGH</td>
<td>CLS</td>
<td>SBIN1..SBIN16</td>
<td>POLLMODE</td>
</tr>
<tr>
<td>IF</td>
<td>CON</td>
<td>SBIN</td>
<td>POLLRUN</td>
</tr>
<tr>
<td>INPUT</td>
<td>COS</td>
<td>SDEC1..SDEC5</td>
<td>POLLWAIT</td>
</tr>
<tr>
<td>LET</td>
<td>COUNT</td>
<td>LIGHTSON</td>
<td>PUT</td>
</tr>
<tr>
<td>LOOKDOWN</td>
<td>CR</td>
<td>LOCKDOWN</td>
<td>RUN</td>
</tr>
<tr>
<td>LOOKUP</td>
<td>DATA</td>
<td>SERIN</td>
<td>STORE</td>
</tr>
<tr>
<td>LOW</td>
<td>DEBUG</td>
<td>LOWBIT</td>
<td></td>
</tr>
<tr>
<td>MAX</td>
<td>DEC</td>
<td>SHIFTIN</td>
<td></td>
</tr>
<tr>
<td>MIN</td>
<td>DEC1..DEC5</td>
<td>LSBFIRST</td>
<td></td>
</tr>
<tr>
<td>N300</td>
<td>DIG</td>
<td>SHIFTOUT</td>
<td></td>
</tr>
<tr>
<td>N600</td>
<td>DIM</td>
<td>SIN</td>
<td></td>
</tr>
<tr>
<td>N1200</td>
<td>DIR0..DIR15</td>
<td>LSBPOST</td>
<td></td>
</tr>
<tr>
<td>N2400</td>
<td>DIRA</td>
<td>STEP</td>
<td></td>
</tr>
<tr>
<td>NAP</td>
<td>DIRB</td>
<td>SLEEP</td>
<td></td>
</tr>
<tr>
<td>NEXT</td>
<td>DIRC</td>
<td>STEP</td>
<td></td>
</tr>
<tr>
<td>ON300</td>
<td>DIRD</td>
<td>STOP</td>
<td></td>
</tr>
<tr>
<td>ON600</td>
<td>DIRH</td>
<td>STR</td>
<td></td>
</tr>
<tr>
<td>ON1200</td>
<td>DIRL</td>
<td>SQR</td>
<td></td>
</tr>
<tr>
<td></td>
<td>DIRS</td>
<td>TAB</td>
<td></td>
</tr>
<tr>
<td></td>
<td>DTMFOUT</td>
<td>NIB</td>
<td></td>
</tr>
<tr>
<td></td>
<td>END</td>
<td>NIB0..NIB3</td>
<td></td>
</tr>
<tr>
<td></td>
<td>FOR</td>
<td>NOT</td>
<td></td>
</tr>
<tr>
<td></td>
<td>FREQOUT</td>
<td>NUM</td>
<td></td>
</tr>
<tr>
<td></td>
<td>GOSUB</td>
<td>OR</td>
<td></td>
</tr>
<tr>
<td></td>
<td>GOTO</td>
<td>W0..W6</td>
<td></td>
</tr>
<tr>
<td></td>
<td>HEX</td>
<td>WRITE</td>
<td></td>
</tr>
<tr>
<td></td>
<td>HEX1..HEX4</td>
<td>OUTA</td>
<td></td>
</tr>
<tr>
<td></td>
<td>HIGH</td>
<td>OUTC</td>
<td></td>
</tr>
<tr>
<td></td>
<td>HIGHBIT</td>
<td>OUTD</td>
<td></td>
</tr>
<tr>
<td></td>
<td>HIGHNIB</td>
<td>OUTH</td>
<td></td>
</tr>
<tr>
<td></td>
<td>OUT</td>
<td>WORD</td>
<td></td>
</tr>
<tr>
<td></td>
<td>OUTA</td>
<td>WAIT</td>
<td></td>
</tr>
<tr>
<td></td>
<td>OUTB</td>
<td>WAITSTR</td>
<td></td>
</tr>
<tr>
<td></td>
<td>OUTC</td>
<td>WRITE</td>
<td></td>
</tr>
<tr>
<td></td>
<td>OUTD</td>
<td>XOUT</td>
<td></td>
</tr>
<tr>
<td></td>
<td>OUTH</td>
<td>XOUT</td>
<td></td>
</tr>
</tbody>
</table>
Appendix C: Conversion Formatters

Conversion Formatters

This appendix lists the Conversion Formatters available for the commands SERIN, I2CIN, LCDIN, and OWIN and demonstrates, though various input/output data examples, exactly what will be received when using these formatters.

### Decimal Formatters

<table>
<thead>
<tr>
<th>Decimals</th>
<th>Characters Received</th>
<th>DEC</th>
<th>DEC1</th>
<th>DEC2</th>
<th>DEC3</th>
<th>DEC4</th>
<th>DEC5</th>
<th>SDEC</th>
<th>SDEC1</th>
<th>SDEC2</th>
<th>SDEC3</th>
<th>SDEC4</th>
<th>SDEC5</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>123</strong></td>
<td>©</td>
<td>123</td>
<td>123</td>
<td>123</td>
<td>12345</td>
<td>0</td>
<td>58647</td>
<td>6</td>
<td>2</td>
<td>65</td>
<td>25</td>
<td>655</td>
<td>2552</td>
</tr>
<tr>
<td><strong>-123</strong></td>
<td>©</td>
<td>-123</td>
<td>-123</td>
<td>-123</td>
<td>-123</td>
<td>-123</td>
<td>-123</td>
<td>-123</td>
<td>-123</td>
<td>-123</td>
<td>-123</td>
<td>-123</td>
<td>-123</td>
</tr>
<tr>
<td><strong>12345</strong></td>
<td>©</td>
<td>12345</td>
<td>12345</td>
<td>12345</td>
<td>12345</td>
<td>12345</td>
<td>12345</td>
<td>12345</td>
<td>12345</td>
<td>12345</td>
<td>12345</td>
<td>12345</td>
<td>12345</td>
</tr>
<tr>
<td><strong>65536</strong></td>
<td>©</td>
<td>65536</td>
<td>65536</td>
<td>65536</td>
<td>65536</td>
<td>65536</td>
<td>65536</td>
<td>65536</td>
<td>65536</td>
<td>65536</td>
<td>65536</td>
<td>65536</td>
<td>65536</td>
</tr>
<tr>
<td><strong>255255</strong></td>
<td>©</td>
<td>255255</td>
<td>255255</td>
<td>255255</td>
<td>255255</td>
<td>255255</td>
<td>255255</td>
<td>255255</td>
<td>255255</td>
<td>255255</td>
<td>255255</td>
<td>255255</td>
<td>255255</td>
</tr>
</tbody>
</table>

© Means any non-decimal-numeric characters such as letters, spaces, minus signs, carriage returns, control characters, etc. (Decimal numerics are: 0,1,2,3,4,5,6,7,8 and 9).

-- Means no valid data (or not enough valid data) was received so the SERIN command will halt forever (unless the *Timeout* argument is used).

### Hexadecimal Formatters

<table>
<thead>
<tr>
<th>Hexadecimals</th>
<th>Characters Received</th>
<th>HEX</th>
<th>HEX1</th>
<th>HEX2</th>
<th>HEX3</th>
<th>HEX4</th>
<th>SHEX</th>
<th>SHEX1</th>
<th>SHEX2</th>
<th>SHEX3</th>
<th>SHEX4</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>1F</strong></td>
<td>©</td>
<td>1F</td>
<td>1F</td>
<td>1F</td>
<td>1F</td>
<td>1F</td>
<td>1F</td>
<td>1F</td>
<td>1F</td>
<td>1F</td>
<td>1F</td>
</tr>
<tr>
<td><strong>-1F</strong></td>
<td>©</td>
<td>-1F</td>
<td>-1F</td>
<td>-1F</td>
<td>-1F</td>
<td>-1F</td>
<td>-1F</td>
<td>-1F</td>
<td>-1F</td>
<td>-1F</td>
<td>-1F</td>
</tr>
<tr>
<td><strong>15AF</strong></td>
<td>©</td>
<td>15AF</td>
<td>15AF</td>
<td>15AF</td>
<td>15AF</td>
<td>15AF</td>
<td>15AF</td>
<td>15AF</td>
<td>15AF</td>
<td>15AF</td>
<td>15AF</td>
</tr>
<tr>
<td><strong>10000</strong></td>
<td>©</td>
<td>10000</td>
<td>10000</td>
<td>10000</td>
<td>10000</td>
<td>10000</td>
<td>10000</td>
<td>10000</td>
<td>10000</td>
<td>10000</td>
<td>10000</td>
</tr>
<tr>
<td><strong>3E517</strong></td>
<td>©</td>
<td>3E517</td>
<td>3E517</td>
<td>3E517</td>
<td>3E517</td>
<td>3E517</td>
<td>3E517</td>
<td>3E517</td>
<td>3E517</td>
<td>3E517</td>
<td>3E517</td>
</tr>
</tbody>
</table>

© Means any non-hexadecimal-numeric characters such as letters (greater than F), spaces, minus signs, carriage returns, control characters, etc. (Hexadecimal numerics are: 0,1,2,3,4,5,6,7,8,9,A,B,C,D,E,F).

-- Means no valid data (or not enough valid data) was received so the SERIN command will halt forever (unless the *Timeout* argument is used).

NOTE: The HEX formatters are not case sensitive. For example, 1F is the same as 1f.

NOTE: The HEX formatters are not case sensitive. For example, 1F is the same as 1f.

© Means any non-hexadecimal-numeric characters such as letters (greater than F), spaces, minus signs, carriage returns, control characters, etc. (Hexadecimal numerics are: 0,1,2,3,4,5,6,7,8,9,A,B,C,D,E,F).

-- Means no valid data (or not enough valid data) was received so the SERIN command will halt forever (unless the *Timeout* argument is used).
# Conversion Formatters

<table>
<thead>
<tr>
<th>Additional Hexadecimal Formatters</th>
<th>Characters Received</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>⊗ 1F 1F₉ $1F $1F₉ -$1F₉ ⊗$1F₉ $15AF₉</td>
</tr>
<tr>
<td>IHEX</td>
<td>-- -- -- -- 1F 1F 1F 1F 15AF</td>
</tr>
<tr>
<td>IHEX1</td>
<td>-- -- -- 1 1 1 1 1</td>
</tr>
<tr>
<td>IHEX2</td>
<td>-- -- -- 1F 1F 1F 1F 15</td>
</tr>
<tr>
<td>IHEX3</td>
<td>-- -- -- -- 1F 1F 1F 1F 15A</td>
</tr>
<tr>
<td>IHEX4</td>
<td>-- -- -- -- 1F 1F 1F 1F 15AF</td>
</tr>
<tr>
<td>ISHEX</td>
<td>-- -- -- -- 1F -1F 1F 15AF</td>
</tr>
<tr>
<td>ISHEX1</td>
<td>-- -- -- 1 1 -1 1 1</td>
</tr>
<tr>
<td>ISHEX2</td>
<td>-- -- -- 1F 1F -1F 1F 15</td>
</tr>
<tr>
<td>ISHEX3</td>
<td>-- -- -- -- 1F -1F 1F 15A</td>
</tr>
<tr>
<td>ISHEX4</td>
<td>-- -- -- -- 1F -1F 1F 15AF</td>
</tr>
</tbody>
</table>

- NOTE: The HEX formatters are not case sensitive. For example, 1F is the same as 1f.
- ⊗ Means any non-hexadecimal-numeric characters such as letters (greater than F), spaces, minus signs, carriage returns, control characters, etc. (Hexadecimal numerics are: 0,1,2,3,4,5,6,7,8,9,A,B,C,D,E,F).
- -- Means no valid data (or not enough valid data) was received so the SERIN command will halt forever (unless the `Timeout` argument is used).

<table>
<thead>
<tr>
<th>Binary Formatters</th>
<th>Characters Received</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>⊗ 11 11₁₀ -1₁₀ ⊗₁₁₀ 10₁₀ 3E5₁₇₁₀</td>
</tr>
<tr>
<td>BIN</td>
<td>-- -- 11 11 11 101 1</td>
</tr>
<tr>
<td>BIN1</td>
<td>-- 1 1 1 1 1 1</td>
</tr>
<tr>
<td>BIN2</td>
<td>-- 11 11 11 11 10 1</td>
</tr>
<tr>
<td>BIN3 – BIN16</td>
<td>-- -- 11 11 11 101 1</td>
</tr>
<tr>
<td>SBIN</td>
<td>-- -- 11 -11 11 101 1</td>
</tr>
<tr>
<td>SBIN1</td>
<td>-- 1 1 -1 1 1 1</td>
</tr>
<tr>
<td>SBIN2</td>
<td>-- 11 11 -11 11 10 1</td>
</tr>
<tr>
<td>SBIN3 – SBIN16</td>
<td>-- -- 11 -11 11 101 1</td>
</tr>
</tbody>
</table>

- ⊗ Means any non-binary-numeric characters such as letters, spaces, minus signs, carriage returns, control characters, etc. (Binary numerics are: 0 and 1).
- -- Means no valid data (or not enough valid data) was received so the SERIN command will halt forever (unless the `Timeout` argument is used).
### Appendix C: Conversion Formatters

<table>
<thead>
<tr>
<th>Additional Binary Formatters</th>
<th>Characters Received</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>⊗</td>
</tr>
<tr>
<td>IBIN</td>
<td>--</td>
</tr>
<tr>
<td>IBIN1</td>
<td>--</td>
</tr>
<tr>
<td>IBIN2</td>
<td>--</td>
</tr>
<tr>
<td>IBIN3 – IBIN16</td>
<td>--</td>
</tr>
<tr>
<td>ISBIN</td>
<td>--</td>
</tr>
<tr>
<td>ISBIN1</td>
<td>--</td>
</tr>
<tr>
<td>ISBIN2</td>
<td>--</td>
</tr>
<tr>
<td>ISBIN3 – ISBIN16</td>
<td>--</td>
</tr>
</tbody>
</table>

⊗ Means any non-binary-numeric characters such as letters, spaces, minus signs, carriage returns, control characters, etc. (Binary numerics are: 0 and 1).

-- Means no valid data (or not enough valid data) was received so the SERIN command will halt forever (unless the Timeout argument is used).
Conversion Formatters
— Symbols —

- 63, 64, 66, 67
& 66, 73
&/ 66, 75
* 66, 67
** 66, 68
*/ 66, 68
/ 66, 69
// 66, 70
?, 100, 102, 145, 207, 301
^ 66, 74
^/ 66, 75
| 66, 73
|/ 66, 75
~ 63, 64
+ 66, 67
<< 66, 72
>> 66, 72

— 1 —

1-Wire Protocol 197–203, 205–11

— 2 —

24LC16B EEPROM, 138, 144

— A —

ABS, 63, 64
Absolute Value (ABS), 63, 64
Accessing I/O Pins, 45, 46, 47
Add (+), 66, 67
Aliases, 53–55
Aliases and Variable Modifiers, 53–55
Analog I/O, 107, 123, 239, 247, 255, 319
AND (&), 66, 73
AND NOT (&/), 66, 75

Architectures, 45
Arrays, 51–53
ASC ?, 100, 102, 145, 207, 301
ASCII Chart, 337
ASCII Notation, 59
Asynchronous Serial, 274, 294
ATN, 11, 13, 15, 17
Auxiliary I/O Pins, 81, 157
AUXIO, 81–82, 189

B0-B13, 45
BASIC Stamp
Architecture, 45
Hardware, 7
Memory, 45
Networking, 304
Pinouts, 8–17
Projects (DOS), 42–43
Projects (Windows), 37–40
Reserved Words, 339
BASIC Stamp 1 Carrier Board, 18
BASIC Stamp 1 Rev. D, 9
BASIC Stamp 2 Carrier Board, 19
BASIC Stamp Activity Board, 23
BASIC Stamp DOS Editor, 41
BASIC Stamp Windows Editor, 34
Baud Mode (table), 276, 296
Baud Mode, Choosing, 278, 297
BELL, 105
BIN, 99, 100, 139, 145, 169, 173, 200, 208, 283, 300
Binary Notation, 59
Binary Operators, 62, 66–75
Add (+), 66, 67
AND (&), 66, 73
AND NOT (&/), 66, 75
Digit (DIG), 66, 72
Divide (/), 66, 69
Maximum (MAX), 66, 71
Minimum (MIN), 66, 70
### Index

- **Connection** (diagram), 29
- **Constants**, 56–58
- **Control Characters**, 104
- **Conversion Formatters**, 341
- **Conversion Formatters** (SERIN), 283
- **Conversion Formatters** (SEROUT), 300
- **COS**, 63, 64
- **Cosine** (COS), 63, 64
- **COUNT**, 89–90
- **Counting Pulses**, 89–90
- **CR**, 105
- **Current Limit**, 9, 11, 13, 15, 17
- **Cycle Counting**, 89

---

### C

- **Cable** (Programming), 26
- **Carrier Board**
  - **BS1**, 18
  - **BS2**, 19
  - **Super**, 20
- **CLS**, 105
- **Comparison Operators**, 149
- **Compile-time Expressions**, 56–58, 60
- **Conditional GOSUB**, 152
- **Conditional Logic Operators**, 151
- **Conditions**, 149–54
- **Connecting & Downloading**, 29
- **Connecting/Disconnecting**, 25, 26

---

### D

- **DATA**, 91–96
  - Reading Word Values, 95
  - Writing Block, 93
  - Writing Text Strings, 94, 112
  - Writing Word Values, 94, 113
- **Data and Program Downloading**, 93, 112
- **DCD**, 63, 64
- **Debounce Buttons**, 85
- **DEBUG**, 97–106
- **DEBUG Formatters**, 99
- **DEBUG Formatting** (BS1), 98
- **DEBUG Formatting** (Non-BS1), 99
- **DEC**, 99, 100, 102, 139, 145, 169, 173, 200, 208, 278, 283, 298, 300
- **Decimal Notation**, 59
- **Decoder** (DCD), 63, 64
- **Default State, I/O Pins**, 47
- **Default State, I/O Pins** (BS1), 46
- **Defining Constants**, 56–58
- **Defining Symbols**, 49–56
- **Delaying Execution**, 213
- **Development Boards**, 18
- **DIG**, 66, 72
- **Digit** (DIG), 66, 72
- **Digital I/O**, 81, 85, 89, 135, 137, 143, 155, 157, 159, 167, 171, 187, 189, 195, 197,
Index

205, 215, 225, 267, 273, 293, 309, 313, 327, 333
Dim, 335
Direction (setting of I/O pins), 45, 46, 155, 195, 267
DIRS, 46
DIRS (BS1), 45
Discussion List, 2
Displaying Information, 97
Displaying Unsigned Numbers, 101
Divide (/), 66, 69
DS1820 Temperature Sensor, 203, 210
DTMFOUT, 107–10

— E —
Editor
Described (DOS), 42
Described (Windows), 34
DOS, 41
Editor Screen (DOS) (diagram), 42
Editor Screen (Windows) (diagram), 34
Editor Tabs (Windows), 34
Identify (Window), 40
Installing, 33
Memory Map (DOS), 43
Memory Map (Windows), 40
Shortcut Keys (DOS), 44
Shortcut Keys (Windows), 41
STAMP Directive, 35
Status (Windows), 35
System Requirements, 33
Using, 33
Using Multiple Modules (Windows), 35
Windows, 34
Editor Software (table), 30, 33
EEPROM, 111–14
EEPROM Usage, 91, 261–64, 321
EEPROM Usage (BS1), 111
Encoder (NCD), 63, 65
END, 115
Expressions, 56–58
Expressions in Constants, 58

— F —
Flow Control, 288, 302
FOR... NEXT, 117–22
FPin, 288, 302
FREQOUT, 123–25

— G —
Generating Pulses, 243–44
Generating Random Numbers, 251–54
Generating Sound (BS1), 319–20
Generating Sound (Non-BS1), 123–25
GET, 127–28
GOSUB, 129–32
GOTO, 133–34
Guidelines, 25

— H —
Hardware
BASIC Stamp 1 Carrier Board, 18
BASIC Stamp 2 Carrier Board, 19
BASIC Stamp Activity Board, 23
BASIC Stamps, 7
Board of Education, 22
BS1, 8
BS2, 10
BS2e, 12
BS2p, 16
BS2sx, 14
Development Boards, 18
Super Carrier Board, 20
HEX, 99, 100, 139, 145, 169, 173, 200, 208, 283, 300
Hexadecimal Notation, 59
HIGH, 135–36
Hitachi 44780 Controller, 159, 167, 171
HOME, 105
Index

— I —

I/O Pins
Accessing, 45, 46, 47
Auxiliary, 81, 157
Directions, 45, 46, 155, 195, 267
Main, 157, 189
Pinouts
   BS1, 9
   BS2, 11
   BS2e, 13
   BS2p, 17
   BS2sx, 15
Reading, 47
Reading (BS1), 45
Source/Sink
   BS1, 9
   BS2, 11
   BS2e, 13
   BS2p, 17
   BS2sx, 15
Writing (BS1), 45
I^C Protocol, 137–42, 143–48
I2CIN, 137–42
I2COUT, 143–48
IBIN, 100, 139, 145, 169, 173, 200, 208, 283, 300
IF...THEN, 83, 149–54
IHEX, 100, 139, 145, 169, 173, 200, 208, 283, 300
INPUT, 155–56
INS, 46
Integer Math Rules, 62
Interface to Telephone Line, 109
Inverse (~), 63, 64
IOTERM, 81, 157–58, 189
ISBIN, 100, 139, 145, 169, 173, 200, 208, 283, 300
ISHEX, 100, 139, 145, 169, 173, 200, 208, 283, 300

— L —

Language
   PBASIC, 7
LCD Commands, 161
LCD Customer Characters, 174
LCD Displays, 159, 167, 171
LCD Initialization, 161, 168, 172
LCDCMD, 159–66
LCDIN, 167–70
LCDOUT, 171–76
LightsOn, 335
LOOKDOWN, 83, 177–82
LOOKUP, 183–86
Loops, 117–22
LOW, 187–88
Low-Power Mode, 115, 191, 317–18
LSBFIRST, 314
LSBPOST, 310
LSBPRE, 310

— M —

Main I/O Pins, 157, 189
MAINIO, 81, 189–90
Mapping Non-Contiguous Numbers, 180, 185
MAX, 66, 71
Maximum (MAX), 66, 71
Measuring Pulses, 241–42
Memory, 45
Memory Map, 55
   (DOS), 43
   (Windows), 40
MIN, 66, 70
Minimum (MIN), 66, 70
Modifiers, 53–55
Modulus (/\), 66, 70
MSBFIRST, 314
MSBPOST, 310
<table>
<thead>
<tr>
<th>Page Numbers</th>
<th>Index Terms</th>
</tr>
</thead>
<tbody>
<tr>
<td>310</td>
<td>MSBPRE</td>
</tr>
<tr>
<td>66, 67</td>
<td>Multiply (*)</td>
</tr>
<tr>
<td>66, 68</td>
<td>Multiply High (**)</td>
</tr>
<tr>
<td>66, 68</td>
<td>Multiply Middle (*/ )</td>
</tr>
<tr>
<td>191–93</td>
<td>NAP</td>
</tr>
<tr>
<td>63, 65</td>
<td>NCD</td>
</tr>
<tr>
<td>63, 64</td>
<td>Negative (-)</td>
</tr>
<tr>
<td>304</td>
<td>Networking BASIC Stamps</td>
</tr>
<tr>
<td>91</td>
<td>Non-volatile Storage</td>
</tr>
<tr>
<td>56, 59</td>
<td>Numbering Systems</td>
</tr>
<tr>
<td>56, 59</td>
<td>Numbers</td>
</tr>
<tr>
<td>8</td>
<td>OEMBS1</td>
</tr>
<tr>
<td>10</td>
<td>OEMBS2</td>
</tr>
<tr>
<td>12</td>
<td>OEMBS2e</td>
</tr>
<tr>
<td>14</td>
<td>OEMBS2sx</td>
</tr>
<tr>
<td>304</td>
<td>Open Baud Modes</td>
</tr>
<tr>
<td>7</td>
<td>Operation, General Theory</td>
</tr>
<tr>
<td>62, 66–75</td>
<td>Operators</td>
</tr>
<tr>
<td>149</td>
<td>Comparison</td>
</tr>
<tr>
<td>179</td>
<td>Comparison (LOOKDOWN)</td>
</tr>
<tr>
<td>151</td>
<td>Conditional Logic</td>
</tr>
<tr>
<td>62, 63–66</td>
<td>Unary</td>
</tr>
<tr>
<td>66, 73</td>
<td>OR (</td>
</tr>
<tr>
<td>66, 75</td>
<td>OR NOT (</td>
</tr>
<tr>
<td>60–62</td>
<td>Order of Operations</td>
</tr>
<tr>
<td>25</td>
<td>Orientation</td>
</tr>
<tr>
<td>195–96</td>
<td>OUTPUT</td>
</tr>
<tr>
<td>46</td>
<td>OUTS</td>
</tr>
<tr>
<td>197–203</td>
<td>OWIN</td>
</tr>
<tr>
<td>205–11</td>
<td>OWOUT</td>
</tr>
<tr>
<td>299</td>
<td>Pace</td>
</tr>
<tr>
<td>293</td>
<td>Pacing</td>
</tr>
<tr>
<td>7</td>
<td>PBASIC Language</td>
</tr>
<tr>
<td>9</td>
<td>PCI</td>
</tr>
<tr>
<td>9</td>
<td>PCO</td>
</tr>
<tr>
<td>25</td>
<td>Pin-1 Indicators</td>
</tr>
<tr>
<td>8</td>
<td>OEMBS1</td>
</tr>
<tr>
<td>10</td>
<td>OEMBS2</td>
</tr>
<tr>
<td>12</td>
<td>OEMBS2e</td>
</tr>
<tr>
<td>14</td>
<td>OEMBS2sx</td>
</tr>
<tr>
<td>304</td>
<td>Open Baud Modes</td>
</tr>
<tr>
<td>7</td>
<td>Operation, General Theory</td>
</tr>
<tr>
<td>62, 66–75</td>
<td>Operators</td>
</tr>
<tr>
<td>149</td>
<td>Comparison</td>
</tr>
<tr>
<td>179</td>
<td>Comparison (LOOKDOWN)</td>
</tr>
<tr>
<td>151</td>
<td>Conditional Logic</td>
</tr>
<tr>
<td>62, 63–66</td>
<td>Unary</td>
</tr>
<tr>
<td>66, 73</td>
<td>OR (</td>
</tr>
<tr>
<td>66, 75</td>
<td>OR NOT (</td>
</tr>
<tr>
<td>60–62</td>
<td>Order of Operations</td>
</tr>
<tr>
<td>25</td>
<td>Orientation</td>
</tr>
<tr>
<td>195–96</td>
<td>OUTPUT</td>
</tr>
<tr>
<td>46</td>
<td>OUTS</td>
</tr>
<tr>
<td>197–203</td>
<td>OWIN</td>
</tr>
<tr>
<td>205–11</td>
<td>OWOUT</td>
</tr>
<tr>
<td>299</td>
<td>Pace</td>
</tr>
<tr>
<td>293</td>
<td>Pacing</td>
</tr>
<tr>
<td>8</td>
<td>OEMBS1</td>
</tr>
<tr>
<td>10</td>
<td>OEMBS2</td>
</tr>
<tr>
<td>12</td>
<td>OEMBS2e</td>
</tr>
<tr>
<td>14</td>
<td>OEMBS2sx</td>
</tr>
<tr>
<td>254</td>
<td>Power Control</td>
</tr>
<tr>
<td>255–59</td>
<td>Potentiometer</td>
</tr>
<tr>
<td>22, 23</td>
<td>Power Supply</td>
</tr>
<tr>
<td>334</td>
<td>Powerline Interface</td>
</tr>
<tr>
<td>26</td>
<td>Programming Connections</td>
</tr>
<tr>
<td>26</td>
<td>Projects</td>
</tr>
</tbody>
</table>
Download Modes, 39
Introduction (DOS), 42
Introduction (Windows), 37
Steps To Create (DOS), 43
Steps To Create (Windows), 38

Protocol
1-Wire, Dallas, 197–203, 205–11
Asynchronous RS-232, 273–92, 293–307
I²C, 137–42, 143–48
Synchronous (SPI), 309–12, 313–16
X10, 333–36
Pulse Width Modulation, 247–50
Pulses, Generating, 243–44
Pulses, Measuring, 241–42
PULSIN, 241–42
PULSOUT, 243–44
PUT, 245–46
PWM, 247–50

— Q —
Quick Start Guide, 29

— R —
Radian, Binary, 65
RAM Organization
   BS1, 45
   BS2, 46
   BS2e, 46
   BS2p, 46
   BS2sx, 46
RANDOM, 251–54
Random Numbers, 251–54
RCTIME, 255–59
RCTime Equation, 257
READ, 261–64
Reading Potentiometers, 239–40, 255–59
Reading Pulses, 89–90, 241–42
Reading Word Values, 262
REP, 100, 104, 145, 207, 301
RES, 9, 11, 13, 15, 17

— S —
Reserved Words, 339
Reserving EEPROM Locations, 93
Reset, 9, 11, 13, 15, 17
RETURN, 265–66
REV, 66, 73
REVERSE, 267–68
Reverse (REV), 66, 73
Rules of Integer Math, 62
Rules of Symbols, 49
RUN, 269–71
Runtime, 60

SBIN, 100, 139, 145, 169, 173, 200, 208, 283, 300
Scratch Pad RAM, 56, 127, 245–46
SDEC, 100, 139, 145, 169, 173, 200, 208, 283, 300
Serial Timeout, 287, 303
Serial Troubleshooting, 290, 305
SERIN, 273–92
SEROUT, 293–307
SHEX, 100, 139, 145, 169, 173, 200, 208, 283, 300
Shift Left (<<), 66, 72
Shift Right (>>, 66, 72
SHIFTIN, 309–12
SHIFTOUT, 313–16
Shortcut Keys
   Editor (DOS), 44
   Editor (Windows), 41
SIN, 63, 65
SIN (pin), 11, 13, 15, 17
Sine (SIN), 63, 65
SKIP, 140, 170, 199, 284
SLEEP, 115, 317–18
SOUND, 319–20
Sound, Generation (BS1), 319–20
Sound, Generation (Non-BS1), 123–25
SOUT, 11, 13, 15, 17
Special Formatters (SERIN), 284
Special Formatters (SEROUT), 301
SQR, 63, 66
Square Root (SQR), 63, 66
STAMP Directive, 35–39
Stamp List, 2
Starter Kit, 6
Static Sensitive Devices, 25
STOP, 321
STORE, 323–24
STR, 100, 103, 140, 145, 170, 199, 207, 284, 301
Subroutines, 129, 265
Subtract (-), 66, 67
Super Carrier Board, 20
Switching Program Slots, 269–71
Symbol Name Rules, 49
Synchronous Serial, 309–12, 313–16

— T —

TAB, 105
Tables, 91–96, 111–14, 177–82, 183–86
Telephone Touch Tones, 107
Theory of Operation, 7
Timeout, 273, 287, 293, 303
TOGGLE, 327–28
Tone Generation, 107–10, 123–25, 319–20
Troubleshooting Serial, 290, 305
Two’s Compliment, 62

— U —

Unary Operators, 62, 63–66
Absolute Value (ABS), 63, 64
Cosine (COS), 63, 64
Decoder (DCD), 63, 64
Encoder (NCD), 63, 65
Inverse (~), 63, 64
Negative (-), 63, 64
Sine (SIN), 63, 65
Square Root (SQR), 63, 66
UnitOff, 335
UnitOn, 335
UnitsOff, 335

— V —

Variable Resistance, Measuring, 239–40, 255–59
Variables
Aliases, 53–55
Arrays, 51–53
Defining, 49–56
Fixed, 48
Modifiers, 53–55
Sizes, 50
VDD, 9, 11, 13, 15, 17, 22, 23
Versions, 2
VIN, 9, 11, 13, 15, 17
VSS, 9, 11, 13, 15, 17

— W —

W0-W6, 45
WAIT, 281, 284
WAITSTR, 140, 170, 199, 284, 285
Warranty, 2
WRITE, 329–32
Writing Word Values, 330

— X —

X0-X15, 17
X10 Control, 333–36
XOR (^), 66, 74
XOR NOT (^/), 66, 75
XOUT, 333–36