Generalization theory

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Motivation

Support vector machines

$$\mathcal{X} = \mathbb{R}^d, \ \mathcal{Y} = \{-1, +1\}.$$

• Return solution $\hat{w} \in \mathbb{R}^d$ to following optimization problem:

$$\min_{w \in \mathbb{R}^d} \frac{\lambda}{2} \|w\|_2^2 + \frac{1}{n} \sum_{i=1}^n [1 - y_i w^{\mathsf{T}} x_i]_+.$$

Loss function is hinge loss

$$\ell(\hat{y}, y) = [1 - y\hat{y}]_{+} = \max\{1 - y\hat{y}, 0\}.$$

(Here, we are okay with a real-valued prediction.)

► The ^λ/₂ ||w||²/₂ term is called *Tikhonov regularization*, which we'll discuss later.

Basic statistical model for data

IID model of data

Training data and test example are *independent and identically* distributed (X × Y)-valued random variables:

 $(X_1, Y_1), \ldots, (X_n, Y_n), (X, Y) \sim_{\text{iid}} P.$

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SVM in the iid model

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► Therefore, ŵ is a random variable, depending on (X₁, Y₁),..., (X_n, Y_n).

Convergence of empirical risk

For \boldsymbol{w} that does not depend on training data:

Empirical risk

$$\mathcal{R}_n(w) = \frac{1}{n} \sum_{i=1}^n \ell(w^{\mathsf{T}} X_i, Y_i)$$

is a sum of iid random variables.

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Law of Large Numbers gives an asymptotic result:

$$\mathcal{R}_n(w) = \frac{1}{n} \sum_{i=1}^n \ell(w^{\mathsf{T}} X_i, Y_i) \xrightarrow{p} \mathbb{E}[\ell(w^{\mathsf{T}} X, Y)] = \mathcal{R}(w).$$

(This can be made non-asymptotic.)

Uniform convergence of empirical risk

However, \hat{w} does depend on training data.

Empirical risk of \hat{w} is *not* a sum of iid random variables:

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Idea: \hat{w} could conceivably take any value w, but if

$$\sup_{w} |\mathcal{R}_{n}(w) - \mathcal{R}(w)| \xrightarrow{p} 0, \qquad (1)$$

then $\mathcal{R}_n(\hat{w}) \xrightarrow{p} \mathcal{R}(\hat{w})$ as well. (1) is called *uniform convergence*.

Detour: Concentration inequalities

Symmetric random walk

Rademacher random variables

 $\varepsilon_1, \ldots, \varepsilon_n$ iid with $\mathbb{P}(\varepsilon_i = -1) = \mathbb{P}(\varepsilon_i = 1) = 1/2.$

Symmetric random walk: position after n steps is

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$$S_n = \sum_{i=1}^n \varepsilon_i.$$

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$$S_n = \sum_{i=1}^n \varepsilon_i.$$

How far from origin?

- By independence, $\operatorname{var}(S_n) = \sum_{i=1}^n \operatorname{var}(\varepsilon_i) = n$.
- So expected distance from origin is

$$\mathbb{E}|S_n| \le \sqrt{\operatorname{var}(S_n)} \le \sqrt{n}.$$

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How many realizations are $\gg \sqrt{n}$ from origin?

Markov's inequality

For any random variable X and any $t\geq 0,$

$$\mathbb{P}(|X| \ge t) \le \frac{\mathbb{E}|X|}{t}.$$

► Proof:

$$t\cdot \mathbb{1}\{|X|\geq t\}\leq |X|.$$

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Application to symmetric random walk:

$$\mathbb{P}(|S_n| \ge c\sqrt{n}) \le \frac{\mathbb{E}|S_n|}{c\sqrt{n}} \le \frac{1}{c}.$$

Hoeffding's inequality

If X_1, \ldots, X_n are independent random variables, with X_i taking values in $[a_i, b_i]$, then for any $t \ge 0$,

$$\mathbb{P}\left(\sum_{i=1}^{n} (X_i - \mathbb{E}(X_i)) \ge t\right) \le \exp\left(-\frac{2t^2}{\sum_{i=1}^{n} (b_i - a_i)^2}\right)$$

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E.g., Rademacher random variables have $[a_i,b_i]=[-1,+1]$, so

$$\mathbb{P}(S_n \ge t) \le \exp(-2t^2/(4n)).$$

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3. Therefore, by union bound,

$$\mathbb{P}(|S_n| \ge c\sqrt{n}) \le 2\exp(-c^2/2).$$

(Compare to bound from Markov's inequality: 1/c.)

Equivalent form of Hoeffding's inequality

Let X_1, \ldots, X_n be independent random variables, with X_i taking values in $[a_i, b_i]$, and let $S_n = \sum_{i=1}^n X_i$. For any $\delta \in (0, 1)$,

$$\mathbb{P}\left(S_n - \mathbb{E}[S_n] < \sqrt{\frac{1}{2}\sum_{i=1}^n (b_i - a_i)^2 \ln(1/\delta)}\right) \ge 1 - \delta.$$

This is a "high probability" upper-bound on $S_n - \mathbb{E}[S_n]$.

Uniform convergence: Finite classes

Back to statistical learning

Cast of characters:

- feature and outcome spaces: \mathcal{X}, \mathcal{Y}
- function class: $\mathcal{F} \subset \mathcal{Y}^{\mathcal{X}}$
- ▶ loss function: ℓ : $\mathcal{Y} \times \mathcal{Y} \to \mathbb{R}_+$ (assume bounded by 1)
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We let $\hat{f} \in \arg\min_{f \in \mathcal{F}} \mathcal{R}_n(f)$ be minimizer of empirical risk

$$\mathcal{R}_n(f) = \frac{1}{n} \sum_{i=1}^n \ell(f(X_i), Y_i).$$

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$$\mathcal{R}_n(f) = \frac{1}{n} \sum_{i=1}^n \ell(f(X_i), Y_i).$$

Our worry: over-fitting $\mathcal{R}(\hat{f}) \gg \mathcal{R}_n(\hat{f})$.

Convergence of empirical risk for fixed function

For any fixed function $f \in \mathcal{F}$,

$$\mathbb{E}\left[\mathcal{R}_n(f)\right] = \mathbb{E}\left[\frac{1}{n}\sum_{i=1}^n \ell(f(X_i), Y_i)\right] = \frac{1}{n}\sum_{i=1}^n \mathbb{E}\left[\ell(f(X_i), Y_i)\right] = \mathcal{R}(f).$$

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Since $\mathcal{R}_n(f)$ is sum of n independent $[0, \frac{1}{n}]$ -valued random variables,

$$\mathbb{P}\left(\left|\mathcal{R}_n(f) - \mathcal{R}(f)\right| \ge t\right) \le 2\exp\left(-\frac{2t^2}{\sum_{i=1}^n (\frac{1}{n})^2}\right) = 2\exp(-2nt^2)$$

for any t > 0, by Hoeffding's inequality and union bound.

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This argument does not apply to \hat{f} , because \hat{f} depends on $(X_1, Y_1), \ldots, (X_n, Y_n)$.

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One possible solution: ensure empirical risk of every $f \in \mathcal{F}$ is close to its expected value.

This is called *uniform convergence*.

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This is called *uniform convergence*.

How much data is needed to ensure this?

Uniform convergence for all functions in a finite class

If $|\mathcal{F}| < \infty,$ then by Hoeffding's inequality and union bound,

$$\mathbb{P}\left(\exists f \in \mathcal{F} \text{ s.t. } |\mathcal{R}_n(f) - \mathcal{R}(f)| \ge t\right) = \mathbb{P}\left(\bigcup_{f \in \mathcal{F}} \left\{|\mathcal{R}_n(f) - \mathcal{R}(f)| \ge t\right\}\right)$$
$$\leq \sum_{f \in \mathcal{F}} \mathbb{P}\left(|\mathcal{R}_n(f) - \mathcal{R}(f)| \ge t\right)$$
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Choose t so that RHS is δ , and "invert".

Theorem. For any $\delta \in (0,1)$,

$$\mathbb{P}\left(\forall f \in \mathcal{F} : |\mathcal{R}_n(f) - \mathcal{R}(f)| < \sqrt{\frac{\ln(2|\mathcal{F}|/\delta)}{2n}}\right) \ge 1 - \delta.$$

What we get from uniform convergence

If $n \gg \log |\mathcal{F}|$, then with high probability, no function $f \in \mathcal{F}$ will over-fit the training data.

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Also: An *empirical risk minimizer* (*ERM*), like \hat{f} , is near optimal! **Theorem**. With probability at least $1 - \delta$,

$$\mathcal{R}(\hat{f}) - \mathcal{R}(f^*) = \mathcal{R}(\hat{f}) - \mathcal{R}_n(\hat{f}) \qquad (\leq \epsilon) \\ + \mathcal{R}_n(\hat{f}) - \mathcal{R}_n(f^*) \qquad (\leq 0) \\ + \mathcal{R}_n(f^*) - \mathcal{R}(f^*) \qquad (\leq \epsilon) \\ \leq 2\epsilon$$

where
$$f^* \in \arg\min_{f \in \mathcal{F}} \mathcal{R}(f)$$
 and $\epsilon = \sqrt{\frac{\ln(2|\mathcal{F}|/\delta)}{2n}}$.
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Notation:

- Let $Pf = \mathbb{E}[f(X)]$ for $X \sim P$.
- Let P_n be the empirical distribution on X₁,..., X_n ∼_{iid} P, which assigns probability mass 1/n to each X_i.

• So
$$P_n f = \frac{1}{n} \sum_{i=1}^n f(X_i)$$
.

We are interested in the maximum (or supremum) deviation:

$$\sup_{f\in\mathcal{F}}|P_nf-Pf|.$$

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The arguments from before show that for any finite class of bounded functions $\mathcal{F}\xspace$,

$$\sup_{f\in\mathcal{F}}|P_nf-Pf|\xrightarrow{p}0,$$

and also give a non-asymptotic rate of convergence.

Infinite classes

For which classes $\mathcal{F} \subset \mathbb{R}^{\mathcal{X}}$ does uniform convergence hold?

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Example:

$$\mathcal{F} = \{ f_S(x) = \mathbb{1}\{ x \in S \} : S \subset \mathbb{R}, |S| < \infty \},\$$

i.e., $\{0,1\}\text{-valued}$ functions that take value 1 on a finite set.

- If P is continuous, then Pf = 0 for all $f \in \mathcal{F}$.
- But $\sup_{f \in \mathcal{F}} P_n f = 1$ for all n.
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What is the appropriate "complexity" measure of a function class?

Rademacher complexity

Let $\varepsilon_1, \ldots, \varepsilon_n$ be independent Rademacher random variables. Uniform convergence with \mathcal{F} holds iff

$$\lim_{n \to \infty} \underbrace{\mathbb{E}\mathbb{E}_{\varepsilon} \left[\sup_{f \in \mathcal{F}} \left| \frac{1}{n} \sum_{i=1}^{n} \varepsilon_{i} f(X_{i}) \right| \right]}_{\operatorname{Rad}_{n}(\mathcal{F})} = 0$$

(where \mathbb{E}_{ε} is expectation with respect to $\varepsilon = (\varepsilon_1, \dots, \varepsilon_n)$).

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(where \mathbb{E}_{ε} is expectation with respect to $\varepsilon = (\varepsilon_1, \ldots, \varepsilon_n)$). Rad_n(\mathcal{F}) is the *Rademacher complexity* of \mathcal{F} , which measures how well vectors in (random) set

$$\mathcal{F}(X_{1:n}) = \{ (f(X_1), \dots, f(X_n)) : f \in \mathcal{F} \}$$

can correlate with uniformly random signs $\varepsilon_1, \ldots, \varepsilon_n$.

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For simplicity, assume X_1, \ldots, X_n are distinct (e.g., P continuous).

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• \mathcal{F} contains all functions $\mathcal{X} \to \{-1, +1\}$:

$$\operatorname{Rad}_{n}(\mathcal{F}) = \mathbb{E}\mathbb{E}_{\varepsilon}\left[\sup_{f\in\mathcal{F}}\left|\frac{1}{n}\sum_{i=1}^{n}\varepsilon_{i}f(X_{i})\right|\right] = 1.$$

Uniform convergence via Rademacher complexity

Theorem.

1. Uniform convergence in expectation: For any $\mathcal{F} \subset \mathbb{R}^{\mathcal{X}}$,

$$\mathbb{E}\left[\sup_{f\in\mathcal{F}}|P_nf-Pf|\right] \le 2\operatorname{Rad}_n(\mathcal{F}).$$

2. Uniform convergence with high probability: For any $\mathcal{F} \subset [-1,+1]^{\mathcal{X}}$ and $\delta \in (0,1)$, with probability $\geq 1 - \delta$,

$$\sup_{f \in \mathcal{F}} |P_n f - Pf| \le 2 \operatorname{Rad}_n(\mathcal{F}) + \sqrt{\frac{2 \ln(1/\delta)}{n}}.$$

Step 1: Symmetrization by "ghost sample"

Let P'_n be empirical distribution on independent copies X'_1, \ldots, X'_n of X_1, \ldots, X_n . Write \mathbb{E}' for expectation with respect to $X'_{1:n}$.

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$$\mathbb{E}\left[\sup_{f\in\mathcal{F}}|P_nf - Pf|\right] = \mathbb{E}\left[\sup_{f\in\mathcal{F}}\left|\mathbb{E}'\left\{\frac{1}{n}\sum_{i=1}^n f(X_i) - f(X'_i)\right\}\right|\right]$$
$$\leq \mathbb{E}\left[\mathbb{E}'\left\{\sup_{f\in\mathcal{F}}\left|\frac{1}{n}\sum_{i=1}^n f(X_i) - f(X'_i)\right|\right\}\right]$$
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The random variable $P_n f - P'_n f$ is arguably nicer than $P_n f - P f$ because it is symmetric.

Step 2: Symmetrization by random signs

Consider any $\varepsilon = (\varepsilon_1, \dots, \varepsilon_n) \in \{-1, +1\}^n$. Distribution of

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Thus, this is also true for uniform average over all $\varepsilon \in \{-1, +1\}^n$ (i.e., expectation over Rademacher ε):

$$\mathbb{E}\mathbb{E}'\sup_{f\in\mathcal{F}}|P_nf - P'_nf| = \mathbb{E}\mathbb{E}'\mathbb{E}_{\varepsilon}\sup_{f\in\mathcal{F}}\left|\frac{1}{n}\sum_{i=1}^n\varepsilon_i\left(f(X_i) - f(X'_i)\right)\right|.$$

Step 3: Back to a single sample

By triangle inequality,

$$\sup_{f \in \mathcal{F}} \left| \frac{1}{n} \sum_{i=1}^{n} \varepsilon_i \left(f(X_i) - f(X'_i) \right) \right|$$

$$\leq \sup_{f \in \mathcal{F}} \left| \frac{1}{n} \sum_{i=1}^{n} \varepsilon_i f(X_i) \right| + \sup_{f \in \mathcal{F}} \left| \frac{1}{n} \sum_{i=1}^{n} \varepsilon_i f(X'_i) \right|$$

The two terms on the RHS have the same distribution.

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So

$$\left| \mathbb{E}\mathbb{E}'\mathbb{E}_{\varepsilon} \sup_{f \in \mathcal{F}} \left| \frac{1}{n} \sum_{i=1}^{n} \varepsilon_i \left(f(X_i) - f(X'_i) \right) \right| \le 2\mathbb{E}\mathbb{E}_{\varepsilon} \sup_{f \in \mathcal{F}} \left| \frac{1}{n} \sum_{i=1}^{n} \varepsilon_i f(X_i) \right|$$
$$= 2 \operatorname{Rad}_n(\mathcal{F}).$$

Recap

For any
$$\mathcal{F} \subset \mathbb{R}^{\mathcal{X}}$$
,
$$\mathbb{E}\left[\sup_{f \in \mathcal{F}} |P_n f - Pf|\right] \leq 2 \operatorname{Rad}_n(\mathcal{F}).$$

For any $\mathcal{F} \subset [-1,+1]^{\mathcal{X}}$ and $\delta \in (0,1),$ with probability $\geq 1-\delta,$

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If $\operatorname{Rad}_n(\mathcal{F}) \to 0$, then uniform convergence holds.

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Conclusion

If $\operatorname{Rad}_n(\mathcal{F}) \to 0$, then uniform convergence holds. (Can also show: If uniform convergence holds, then $\operatorname{Rad}_n(\mathcal{F}) \to 0$.)

Analysis of SVM

Loss class

Back to classes of prediction functions $\mathcal{F} \subset \mathbb{R}^{\mathcal{X}}.$

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Consider a loss function $\ell \colon \mathbb{R} \times \mathcal{Y} \to \mathbb{R}_+$ that satisfies $\ell(0, y) \leq 1$ for all $y \in \mathcal{Y}$, and is 1-Lipschitz in first argument: for all $\hat{y}, \hat{y}' \in \mathbb{R}$,

$$|\ell(\hat{y}, y) - \ell(\hat{y}', y)| \le |\hat{y} - \hat{y}'|.$$

(Example: hinge loss $\ell(\hat{y}, y) = [1 - \hat{y}y]_+$.)

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Define the associated loss class by

$$\ell_{\mathcal{F}} = \{ (x, y) \mapsto \ell(f(x), y) : f \in \mathcal{F} \}.$$

Then

$$\operatorname{Rad}_n(\ell_{\mathcal{F}}) \le 2\operatorname{Rad}_n(\mathcal{F}) + \sqrt{\frac{2\ln 2}{n}}$$

So uniform convergence holds for $\ell_{\mathcal{F}}$ if it holds for $\mathcal{F}.$

Rademacher complexity of linear predictors

Linear functions $\mathcal{F}_{\text{lin}} = \{ w \in \mathbb{R}^d \}.$

What is the Rademacher complexity of $\mathcal{F}_{\mathrm{lin}}?$

$$\operatorname{Rad}_{n}(\mathcal{F}_{\operatorname{lin}}) = \mathbb{E}\mathbb{E}_{\varepsilon}\left[\sup_{w \in \mathbb{R}^{d}} \left|\frac{1}{n} \sum_{i=1}^{n} \varepsilon_{i} w^{\mathsf{T}} X_{i}\right|\right]$$

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Inside the $\mathbb{E}\mathbb{E}_{\varepsilon}$:

$$\sup_{w \in \mathbb{R}^d} \left| w^{\mathsf{T}} \left(\frac{1}{n} \sum_{i=1}^n \varepsilon_i X_i \right) \right| = \sup_{w \in \mathbb{R}^d} \|w\|_2 \left\| \frac{1}{n} \sum_{i=1}^n \varepsilon_i X_i \right\|_2$$

As long as $\sum_{i=1}^{n} \varepsilon_i X_i \neq 0$, this is unbounded! :-(

Regularization

Recall SVM optimization problem:

$$\min_{w \in \mathbb{R}^d} \frac{\lambda}{2} \|w\|_2^2 + \frac{1}{n} \sum_{i=1}^n [1 - y_i w^{\mathsf{T}} x_i]_+.$$

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Therefore

$$\|\hat{w}\|_2^2 \le \frac{2}{\lambda}.$$

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This is d-dimensional random walk, where *i*-th step is $\pm X_i$.

Rademacher complexity of bounded linear predictors (2)

$$\mathbb{E}\mathbb{E}_{\varepsilon} \left\| \frac{1}{n} \sum_{i=1}^{n} \varepsilon_{i} X_{i} \right\|_{2}^{2} = \frac{1}{n^{2}} \mathbb{E}\mathbb{E}_{\varepsilon} \left[\sum_{i=1}^{n} \|\varepsilon_{i} X_{i}\|_{2}^{2} + \sum_{i \neq j} \varepsilon_{i} \varepsilon_{j} X_{i}^{\mathsf{T}} X_{j} \right]$$
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Conclusion

Rademacher complexity of $\mathcal{F}_{\ell_2,B} = \{ w \in \mathbb{R}^d : ||w||_2 \le B \}$:

$$\operatorname{Rad}_{n}(\mathcal{F}_{\ell_{2},B}) \leq B\sqrt{\frac{\mathbb{E}\|X\|_{2}^{2}}{n}}.$$

Risk bound for SVM

$$\mathbb{E} \left[\mathcal{R}(\hat{w}) - \mathcal{R}(w^*) \right]$$

$$= \mathbb{E} \left[\mathcal{R}(\hat{w}) - \mathcal{R}_n(\hat{w}) \right] \qquad (\leq \epsilon)$$

$$+ \mathbb{E} \left[\frac{\lambda}{2} \| \hat{w} \|_2^2 + \mathcal{R}_n(\hat{w}) - \frac{\lambda}{2} \| w^* \|_2^2 - \mathcal{R}_n(w^*) \right] \qquad (\leq 0)$$

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$$\leq \epsilon + \frac{\lambda}{2} \| w^* \|_2^2$$

where

$$w^* \in \underset{w \in \mathbb{R}^d}{\operatorname{arg\,min}} \frac{\lambda}{2} \|w\|_2^2 + \mathcal{R}(w), \quad \epsilon = O\left(\sqrt{\frac{\mathbb{E}\|X\|_2^2}{\lambda n}} + \frac{1}{\sqrt{n}}\right).$$

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This suggests we should use $\lambda \to 0$ such that $\lambda n \to \infty$ as $n \to \infty$.

Kernels

Excess risk bound has no *explicit* dependence on the dimension d. In particular, it holds in infinite dimensional inner product spaces.

- SVM can be applied in such spaces as long as there is an algorithm for computing inner products.
- This is the kernel trick, and these corresponding spaces are called Reproducing Kernel Hilbert Spaces (RKHS).

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- This is the kernel trick, and these corresponding spaces are called Reproducing Kernel Hilbert Spaces (RKHS).

Universal approximation

With some RKHS, can approximate any function arbitrarily well:

$$\lim_{\lambda \to 0} \left\{ \inf_{w \in \mathcal{F}} \frac{\lambda}{2} \|w\|^2 + \mathcal{R}(w) \right\} = \inf_{g \colon \mathcal{X} \to \mathbb{R}} \mathcal{R}(g).$$

Other regularizers

Instead of SVM, suppose \hat{w} is solution to

 $\min_{w \in \mathbb{R}^d} \lambda \|w\|_1 + \mathcal{R}_n(w).$

So $\hat{w} \in \mathcal{F}_{\ell_1,B} = \{w \in \mathbb{R}^d : \|w\|_1 \le B\}$ for $B = 1/\lambda$.

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So $\hat{w} \in \mathcal{F}_{\ell_1,B} = \{w \in \mathbb{R}^d : ||w||_1 \leq B\}$ for $B = 1/\lambda$. What is Rademacher complexity of $\mathcal{F}_{\ell_1,B}$?

$$\operatorname{Rad}_{n}(\mathcal{F}_{\ell_{1},B}) = \mathbb{E}\mathbb{E}_{\varepsilon} \left[\sup_{\|w\|_{1} \leq B} \left| \frac{1}{n} \sum_{i=1}^{n} \varepsilon_{i} w^{\mathsf{T}} X_{i} \right| \right]$$
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Can show, using martingale argument,

$$\mathbb{E}\mathbb{E}_{\varepsilon} \left\| \frac{1}{n} \sum_{i=1}^{n} \varepsilon_{i} X_{i} \right\|_{\infty} \leq \sqrt{\frac{O(\log d) \cdot \mathbb{E} \|X\|_{\infty}^{2}}{n}}$$

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Let $\mathcal{X} = \{-1, +1\}^d$. Then $\|x\|_2^2 = d$ but $\|x\|_{\infty}^2 = 1$ for all $x \in \mathcal{X}$.

Dependence on d much better than using bound for ℓ_2 -bounded linear predictors, which would have looked like $B\sqrt{d/n}$.

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This kind of bound is used to study generalization of AdaBoost.

Other examples of Rademacher complexity

• \mathcal{F} = any class of $\{0, 1\}$ -valued functions with VC dimension V:

$$\operatorname{Rad}_n(\mathcal{F}) = O\left(\sqrt{\frac{V}{n}}\right)$$

F = ReLU networks of depth D with parameter matrices of Frobenius norm ≤ 1:

$$\operatorname{Rad}_{n}(\mathcal{F}) = O\left(\sqrt{\frac{D \cdot \mathbb{E} \|X\|_{2}^{2}}{n}}\right)$$

- ► \mathcal{F} = Lipschitz functions from $[0,1]^d$ to \mathbb{R} : Rad_n(\mathcal{F}) = $O\left(n^{-1/(2+d)}\right)$.
- ► $\mathcal{F} =$ functions from $[0, 1]^d$ to \mathbb{R} with Lipschitz k-th derivatives: $\operatorname{Rad}_n(\mathcal{F}) = O\left(n^{-(k+1)/(2(k+1)+d)}\right).$

Are these the "right" notions of complexity?

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► For SVM, the complexity of ℓ₂-bounded linear predictors is relevant because ℓ₂-regularization explicitly ensures the solution to SVM problem is ℓ₂-bounded.

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Are these the "right" notions of complexity?

- ► For SVM, the complexity of ℓ₂-bounded linear predictors is relevant because ℓ₂-regularization explicitly ensures the solution to SVM problem is ℓ₂-bounded.
- Do training algorithms for neural nets lead to Frobenius norm-bounded parameter matrices?

Do complexity bounds suggest different algorithms?

Beyond uniform convergence

Deficiencies of uniform convergence analysis

- ► For certain loss functions, if R(f) is small, then variance of R_n(f) is also small, and bound should reflect this.
 - Instead of Hoeffding's inequality, use concentration inequality that involves variance information (e.g., *Bernstein's inequality*).
- Overkill to require *all* functions in \mathcal{F} to not over-fit.
 - > Just need to worry about the f, e.g., with small empirical risk.
 - Solution: *Local* Rademacher complexity.

Example: Occam's razor bound

Suppose \mathcal{F} is countable and we fix (*a priori*) a probability distribution $\pi = (\pi_f : f \in \mathcal{F})$ on \mathcal{F} .

Think of π as placing bets on which functions are likely to be the one to be picked by your learning algorithm.

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For any fixed $f \in \mathcal{F}$,

$$\mathbb{P}\left(\left|\mathcal{R}_n(f) - \mathcal{R}(f)\right| \ge t_f\right) \le 2\exp(-2nt_f^2)$$

for any $t_f > 0$, by Hoeffding's inequality and union bound. **Note**: We can choose the t_f 's non-uniformly. Occam's razor bound (continued) Let $t_f = \sqrt{\frac{\ln(1/\pi_f) + \ln(2/\delta)}{2n}}$.

By union bound,

$$\mathbb{P}\left(\exists f \in \mathcal{F} \text{ s.t. } |\mathcal{R}_n(f) - \mathcal{R}(f)| \ge t_f\right)$$

$$\leq \sum_{f \in \mathcal{F}} \mathbb{P}\left(|\mathcal{R}_n(f) - \mathcal{R}(f)| \ge t_f\right)$$

$$\leq \sum_{f \in \mathcal{F}} 2\exp(-2nt_f^2) = \sum_{f \in \mathcal{F}} \pi_f \delta = \delta.$$

Occam's razor bound (continued) Let $t_f = \sqrt{\frac{\ln(1/\pi_f) + \ln(2/\delta)}{2n}}$.

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Theorem. For any $\delta \in (0,1)$,

$$\mathbb{P}\left(\forall f \in \mathcal{F} : |\mathcal{R}_n(f) - \mathcal{R}(f)| < \sqrt{\frac{\ln(1/\pi_f) + \ln(2/\delta)}{2n}}\right) \ge 1 - \delta.$$

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Better bound for functions f with higher "prior probability" π_f !

Other forms of generalization analysis

- Stability
 - If a learning algorithm's output does not change much if a single data point is changed, then its output will generalize.
 - Connections to differential privacy and regularization.
- Compression bounds
 - If a learning algorithm's output is invariant to all but a small number k ≪ n of training data (e.g., # support vectors in SVM), then get bound of the form √k/(n - k).
- Direct analyses
 - Some well-known learning algorithms do not fit the mold of typical (regularized) ERM algorithm, and seem to require a direct analysis.
 - E.g., nearest neighbor rule.
- Many others

Many active areas of research in learning theory

- Implicit bias of optimization algorithms
 - E.g., gradient descent for least squares linear regression converges to solution of smallest norm.
 - What about for other problems?
- Efficient algorithms for non-linear models
 - E.g., polynomials, neural networks, kernel machines.
 - Understand if/why existing algorithms work!
- Learning algorithms with robustness guarantees
 - Noisy labels, missing / malformed data, heavy-tail distributions, adversarial corruptions, etc.
- Interactive learning
 - Learning algorithms that interact with external environment (e.g., bandits, active learning, reinforcement learning).
- ► More: see proceedings of Conference on Learning Theory!