

Learning Mixtures of Spherical Gaussians: Moment Methods and Spectral Decompositions

Daniel Hsu and Sham M. Kakade

Microsoft Research, New England

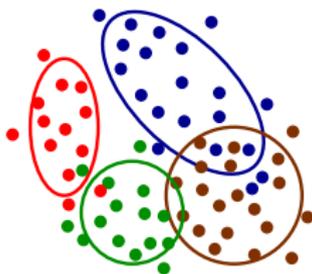
Also based on work with Anima Anandkumar (UCI),
Rong Ge (Princeton), Matus Telgarsky (UCSD).

Unsupervised machine learning

- ▶ **Many applications in machine learning and statistics:**
 - ▶ Lots of **high-dimensional** data, but **mostly unlabeled**.

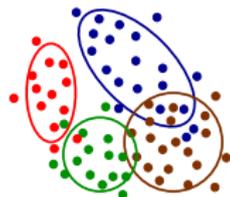
Unsupervised machine learning

- ▶ **Many applications in machine learning and statistics:**
 - ▶ Lots of **high-dimensional** data, but **mostly unlabeled**.
- ▶ **Unsupervised learning:** discover **interesting structure** of population from **unlabeled data**.
 - ▶ **This talk:** learn about **sub-populations** in data source.



Learning mixtures of Gaussians

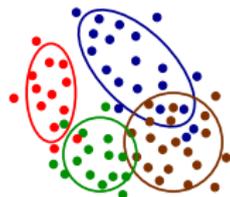
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k sub-populations;
each modeled as multivariate Gaussian $\mathcal{N}(\vec{\mu}_i, \Sigma_i)$
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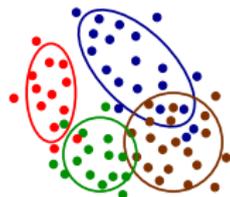


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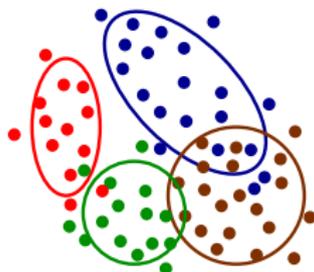
(Alternative goal: density estimation. Not in this talk.)

Learning setup

- ▶ **Input:** i.i.d. sample $S \subset \mathbb{R}^d$ from unknown mixtures of Gaussians with parameters $\theta^* := \{(\vec{\mu}_i^*, \Sigma_i^*, w_i^*) : i \in [k]\}$.

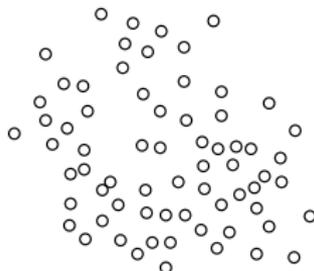
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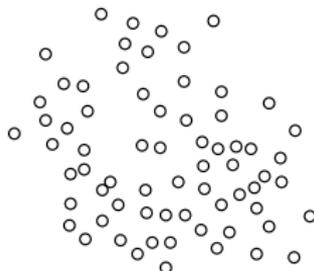
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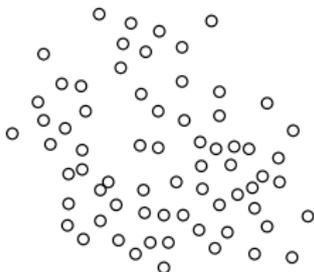
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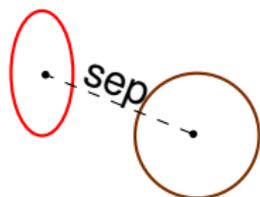
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- ▶ But **“labels” are not observed.**
- ▶ **Goal:** estimate parameters $\theta = \{(\vec{\mu}_i, \Sigma_i, w_i) : i \in [k]\}$ such that $\theta \approx \theta^*$.
- ▶ **In practice:** local search for maximum-likelihood parameters (E-M algorithm).

When are there efficient algorithms?

Well-separated mixtures: estimation is easier if there is **large minimum separation** between component means (Dasgupta, '99):

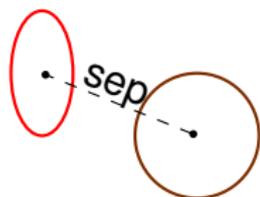


$$\text{sep} := \min_{i \neq j} \frac{\|\vec{\mu}_i - \vec{\mu}_j\|}{\max\{\sigma_i, \sigma_j\}}.$$

- ▶ $\text{sep} = \Omega(d^c)$ or $\text{sep} = \Omega(k^c)$: simple clustering methods, perhaps after dimension reduction (Dasgupta, '99; Vempala-Wang, '02; and many more.)

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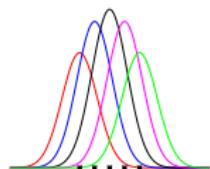
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Recent developments:

- ▶ **No minimum separation requirement**, but current methods require $\exp(\Omega(k))$ running time / sample size (Kalai-Moitra-Valiant, '10; Belkin-Sinha, '10; Moitra-Valiant, '10)

Overcoming barriers to efficient estimation

Information-theoretic barrier:

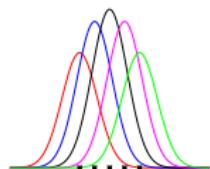


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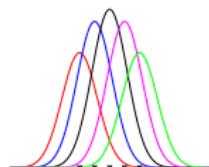
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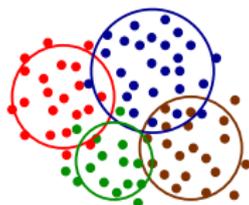


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These hard instances are degenerate in high-dimensions!

Our result: **efficient algorithms** for *non-degenerate* models in high-dimensions ($d \geq k$) with *spherical covariances*.



Main result

Theorem (H-Kakade, '13)

Assume $\{\vec{\mu}_1^*, \vec{\mu}_2^*, \dots, \vec{\mu}_k^*\}$ linearly independent, $w_i^* > 0$ for all $i \in [k]$, and $\Sigma_i^* = \sigma_i^{2*} \mathbf{I}$ for all $i \in [k]$.

There is an algorithm that, given independent draws from a mixture of k spherical Gaussians, returns ε -accurate parameters (up to permutation, under ℓ^2 metric) w.h.p.

The running time and sample complexity are

$$\text{poly}(d, k, 1/\varepsilon, 1/w_{\min}, 1/\lambda_{\min})$$

where $\lambda_{\min} = k^{\text{th}}$ -largest singular value of $[\vec{\mu}_1^ | \vec{\mu}_2^* | \dots | \vec{\mu}_k^*]$.*

(Also using new techniques from Anandkumar-Ge-H-Kakade-Telgarsky, '12.)

2. Learning algorithm

Introduction

Learning algorithm

- Method-of-moments

- Choice of moments

- Solving the moment equations

Concluding remarks

Method-of-moments

Let $S \subset \mathbb{R}^d$ be an i.i.d. sample from an unknown mixture of spherical Gaussians:

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Estimation via method-of-moments (Pearson, 1894)

Find parameters θ such that

$$\mathbb{E}_{\theta} [p(\vec{x})] \approx \hat{\mathbb{E}}_{\vec{x} \in S} [p(\vec{x})]$$

for some functions $p : \mathbb{R}^d \rightarrow \mathbb{R}$ (typically multivar. polynomials).

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Q1 Which moments to use?

Q2 How to (approx.) solve moment equations?

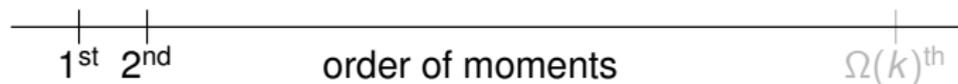
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moment order	reliable estimates?	unique solution?
1 st , 2 nd		

1st- and 2nd-order moments (*e.g.*, mean, covariance)

[Chaudhuri-Rao, '08]
[Achlioptas-McSherry, '05]
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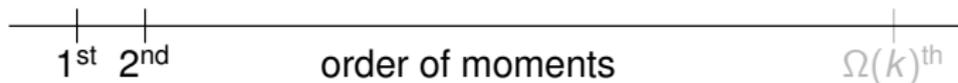
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- ▶ Fairly easy to get reliable estimates.

$$\mathbb{E}_{\vec{x} \in \mathcal{S}}[\vec{x} \otimes \vec{x}] \approx \mathbb{E}_{\theta^*}[\vec{x} \otimes \vec{x}]$$

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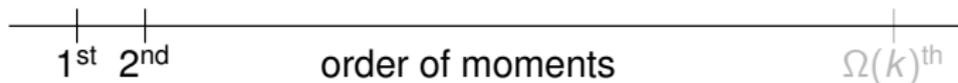
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- ▶ Can have multiple solutions to moment equations.

$$\mathbb{E}_{\theta_1}[\vec{x} \otimes \vec{x}] \approx \mathbb{E}_{\vec{x} \in S}[\vec{x} \otimes \vec{x}] \approx \mathbb{E}_{\theta_2}[\vec{x} \otimes \vec{x}], \quad \theta_1 \neq \theta_2$$

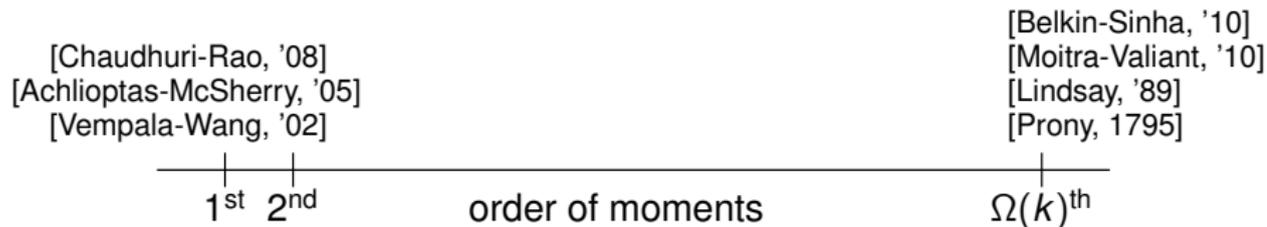
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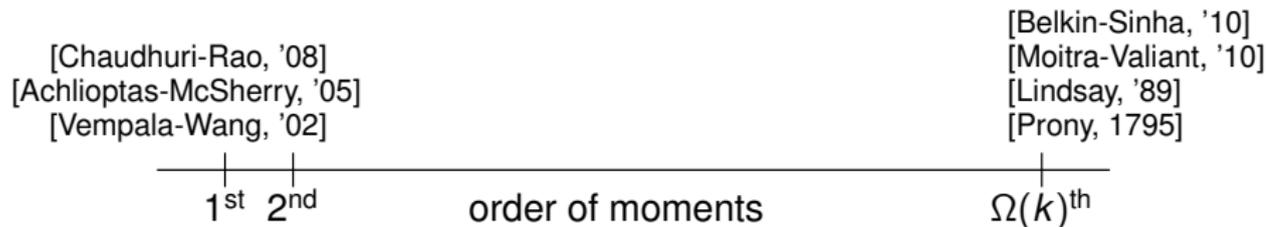


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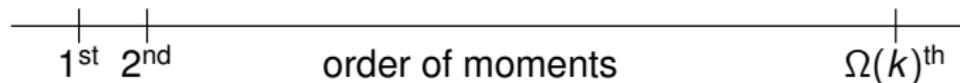
$\Omega(k)^{\text{th}}$ -order moments (e.g., $\mathbb{E}_{\theta}[\text{degree-}k\text{-poly}(\vec{x})]$)

- ▶ Uniquely pins down the solution.
- ▶ Empirical estimates very unreliable.



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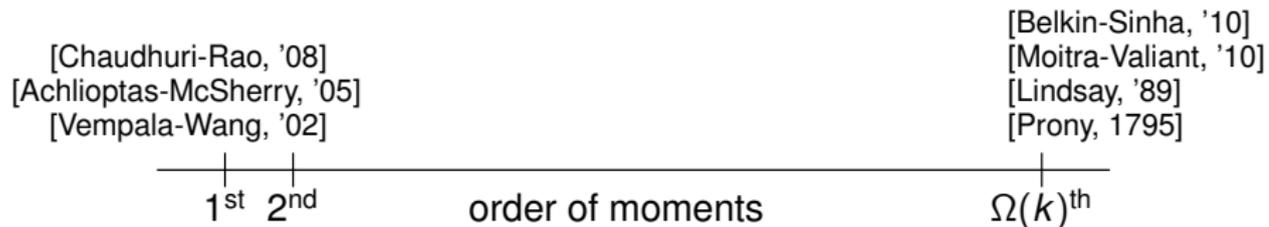
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Can we get best-of-both-worlds?



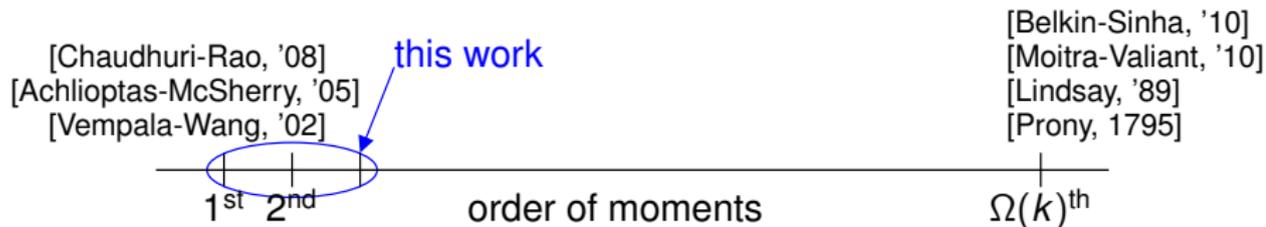
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Can we get best-of-both-worlds? **Yes!**

**In high-dimensions ($d \geq k$),
low-order multivariate moments suffice.**

(1^{st} -, 2^{nd} -, and 3^{rd} -order moments)



Structure of low-order multivariate moments

Second- and third-order multivariate moments:

$$\mathbb{E}_{\theta}[\vec{x} \otimes \vec{x}] = \sum_{i=1}^k w_i \vec{\mu}_i \otimes \vec{\mu}_i + \text{some sparse matrix};$$

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Upshot: the following can be readily estimated (with \hat{M} , \hat{T}).

$$M_{\theta^*} := \sum_{i=1}^k w_i^* \vec{\mu}_i^* \otimes \vec{\mu}_i^* \quad \text{and} \quad T_{\theta^*} := \sum_{i=1}^k w_i^* \vec{\mu}_i^* \otimes \vec{\mu}_i^* \otimes \vec{\mu}_i^*.$$

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Claim: $\{(\vec{\mu}_i, w_i)\}$ uniquely determined by M_θ and T_θ .

Variational argument for parameter uniqueness

View $M_\theta : \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$ and $T_\theta : \mathbb{R}^d \times \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$ as **bi-linear** and **tri-linear** functions.

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Lemma

If $\{\vec{\mu}_i\}$ are linearly independent and all $w_i > 0$, then each of the k distinct, isolated local maximizers \vec{u}^* of

$$\max_{\vec{u} \in \mathbb{R}^d} T_\theta(\vec{u}, \vec{u}, \vec{u}) \quad \text{s.t.} \quad M_\theta(\vec{u}, \vec{u}) \leq 1$$

satisfies, for some $i \in [k]$,

$$M_\theta(\cdot, \vec{u}^*) = \sqrt{w_i} \vec{\mu}_i, \quad T_\theta(\vec{u}^*, \vec{u}^*, \vec{u}^*) = \frac{1}{\sqrt{w_i}}.$$

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$\therefore \{(\vec{\mu}_i, w_i) : i \in [k]\}$ uniquely determined by M_θ, T_θ . ■

Main idea for variational lemma

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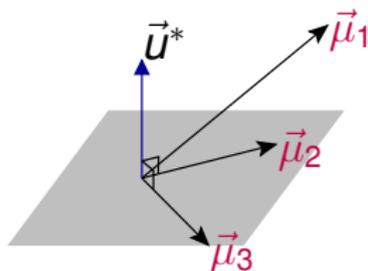
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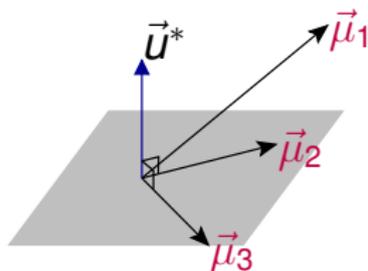
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Combine with constraints $w_j \langle \vec{\mu}_j, \vec{u}^* \rangle^2 \leq 1$ to get

$$M\vec{u}^* = \left(\sum_{i=1}^k w_i \vec{\mu}_i \otimes \vec{\mu}_i \right) \vec{u}^* = \sum_{i=1}^k w_i \vec{\mu}_i \langle \vec{\mu}_i, \vec{u}^* \rangle = \pm \sqrt{w_j} \vec{\mu}_j. \blacksquare$$

How to solve the moment equations?

Effectively want to solve

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What we do: find one component $(\vec{\mu}_i, \mathbf{w}_i)$ at a time, using **local optimization** of related (also non-convex) objective function.

$$\max_{\vec{u} \in \mathbb{R}^d} \sum_{i,j,k} \widehat{T}_{i,j,k} u_i u_j u_k \quad \text{s.t.} \quad \sum_{i,j} \widehat{M}_{i,j} u_i u_j \leq 1 \quad (\ddagger)$$

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$$\min_{\theta} \|T_{\theta} - \widehat{T}\|^2 \quad \text{s.t.} \quad M_{\theta} = \widehat{M}. \quad (\dagger)$$

Not convex in parameters $\theta = \{(\vec{\mu}_i, \mathbf{w}_i)\}$.

What we do: find one component $(\vec{\mu}_i, \mathbf{w}_i)$ at a time, using **local optimization** of related (also non-convex) objective function.

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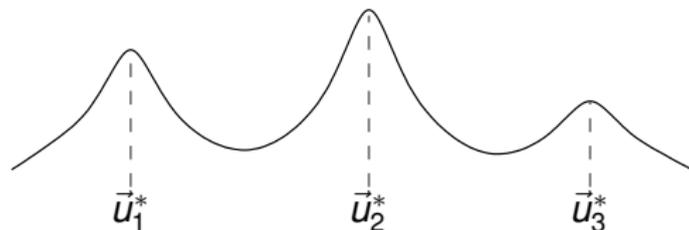
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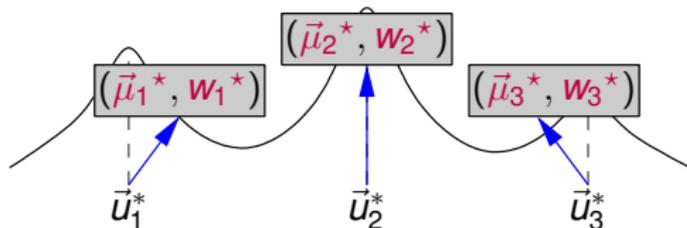
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New robust algorithm for “tensor eigen-decomposition” efficiently approximates *all local optima*, each corresponding to a component. \rightarrow Near-optimal solution to (\dagger) . ■

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Want to find *all* local maximizers of

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 - ▶ Else: abandon and restart.

3. Concluding remarks

Introduction

Learning algorithm

Concluding remarks

Open problems and summary

Some open problems

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- ▶ **Question #1:** What about mixtures of Gaussians with arbitrary covariances?
- ▶ **Question #2:** How to handle degenerate cases / $k \gg d$?
(Practical relevance: automatic speech recognition)

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 - ▶ **Similar story for many other statistical models** (e.g., HMMs (Mossel-Roch, '06; H-Kakade-Zhang, '09), topic models (Arora-Ge-Moitra, '12; Anandkumar *et al*, '12), ICA (Arora *et al*, '12)).

Summary

- ▶ **Learning mixtures of spherical Gaussians:** **worst-case (information-theoretically) hard**, but **non-degenerate cases are easy**.
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- ▶ **Open problem:** efficient estimators for highly over-complete and general mixture models ($k \gg d$).

Thanks!

Related survey/overview-ish paper:

- ▶ Tensor decompositions for latent variable models (with Anandkumar, Ge, Kakade, and Telgarsky): <http://arxiv.org/abs/1210.7559>

Structure of low-order moments

- ▶ **First-order moments:**

$$\mathbb{E}[\vec{x}] = \sum_{i=1}^k w_i \vec{\mu}_i.$$

- ▶ **Second-order moments:**

$$\mathbb{E}[\vec{x} \otimes \vec{x}] = \sum_{i=1}^k w_i \vec{\mu}_i \otimes \vec{\mu}_i + \bar{\sigma}^2 \mathbf{I}$$

where $\bar{\sigma}^2 := \sum_{i=1}^k w_i \sigma_i^2$.

Fact: $\bar{\sigma}^2$ is the smallest eigenvalue of $\text{Cov}(\vec{x}) = \mathbb{E}[\vec{x} \otimes \vec{x}] - \mathbb{E}[\vec{x}] \otimes \mathbb{E}[\vec{x}]$.

Structure of low-order moments

► **Third-order moments:**

$$\begin{aligned}\mathbb{E}[\vec{x} \otimes \vec{x} \otimes \vec{x}] &= \sum_{i=1}^k w_i \vec{\mu}_i \otimes \vec{\mu}_i \otimes \vec{\mu}_i \\ &+ \sum_{i=1}^d \vec{m} \otimes \mathbf{e}_i \otimes \mathbf{e}_i + \mathbf{e}_i \otimes \vec{m} \otimes \mathbf{e}_i + \mathbf{e}_i \otimes \mathbf{e}_i \otimes \vec{m}\end{aligned}$$

where $\vec{m} := \sum_{i=1}^k w_i \sigma_i^2 \vec{\mu}_i$.

Fact: $\vec{m} = \mathbb{E}[(\vec{u}^\top (\vec{x} - \mathbb{E}[\vec{x}]))^2 \vec{x}]$ for any unit-norm eigenvector \vec{u} of $\text{Cov}(\vec{x})$ corresponding to eigenvalue $\bar{\sigma}^2$.

Proof idea for optimization lemma

$$\max_{\vec{u} \in \mathbb{R}^d} T(\vec{u}, \vec{u}, \vec{u}) \text{ s.t. } M(\vec{u}, \vec{u}) \leq 1$$

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$$\max_{\vec{u} \in \mathbb{R}^d} \sum_{i=1}^k w_i \langle \vec{\mu}_i, \vec{u} \rangle^3 \quad \text{s.t.} \quad \sum_{i=1}^k w_i \langle \vec{\mu}_i, \vec{u} \rangle^2 \leq 1$$

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$$\max_{\vec{\theta} \in \mathbb{R}^k} \sum_{i=1}^k \frac{1}{\sqrt{w_i}} \theta_i^3 \quad \text{s.t.} \quad \sum_{i=1}^k \theta_i^2 \leq 1$$

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Isolated local maxima are $\frac{1}{\sqrt{w_1}}, \frac{1}{\sqrt{w_2}}, \dots$, achieved at

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Translates to directions \vec{u}^* orthogonal to all but one $\vec{\mu}_j$.

