

# Learning Mixtures of Spherical Gaussians: Moment Methods and Spectral Decompositions

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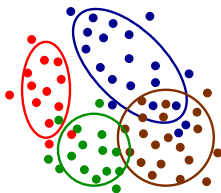
Also based on work with Anima Anandkumar (UCI),  
Rong Ge (Princeton), Matus Telgarsky (UCSD).

# Unsupervised machine learning

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  - ▶ Lots of **high-dimensional** data, but **mostly unlabeled**.

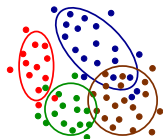
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  - ▶ Lots of **high-dimensional** data, but **mostly unlabeled**.
- ▶ **Unsupervised learning:** discover **interesting structure** of population from **unlabeled data**.
  - ▶ **This talk:** learn about **sub-populations** in data source.



# Learning mixtures of Gaussians

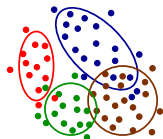
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$k$  sub-populations;  
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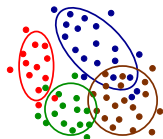


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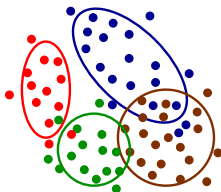
(Alternative goal: density estimation. Not in this talk.)

## Learning setup

- ▶ **Input:** i.i.d. sample  $S \subset \mathbb{R}^d$  from unknown mixtures of Gaussians with parameters  $\theta^* := \{(\vec{\mu}_i^*, \Sigma_i^*, w_i^*) : i \in [k]\}$ .

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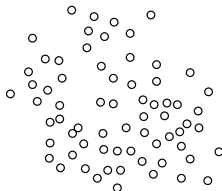
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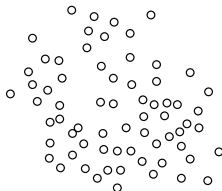
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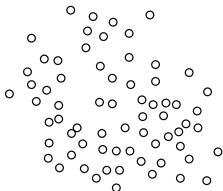
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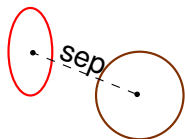
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- ▶ **In practice:** local search for maximum-likelihood parameters (E-M algorithm).

# When are there efficient algorithms?

**Well-separated mixtures:** estimation is easier if there is **large minimum separation** between component means (Dasgupta, '99):

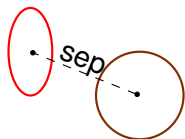


$$\text{sep} := \min_{i \neq j} \frac{\|\vec{\mu}_i - \vec{\mu}_j\|}{\max\{\sigma_i, \sigma_j\}}.$$

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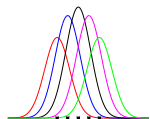
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## Recent developments:

- ▶ **No minimum separation requirement**, but current methods require  $\exp(\Omega(k))$  running time / sample size (Kalai-Moitra-Valiant, '10; Belkin-Sinha, '10; Moitra-Valiant, '10)

# Overcoming barriers to efficient estimation

## Information-theoretic barrier:

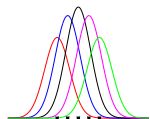


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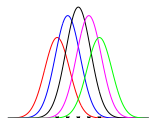
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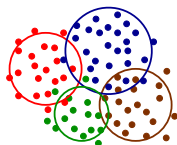


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**Our result:** **efficient algorithms** for *non-degenerate* models in high-dimensions ( $d \geq k$ ) with *spherical covariances*.





# Main result

## Theorem (H-Kakade, '13)

Assume  $\{\vec{\mu}_1^*, \vec{\mu}_2^*, \dots, \vec{\mu}_k^*\}$  linearly independent,  $w_i^* > 0$  for all  $i \in [k]$ , and  $\Sigma_i^* = \sigma_i^{2*} \mathbf{I}$  for all  $i \in [k]$ .

*There is an algorithm that, given independent draws from a mixture of  $k$  spherical Gaussians, returns  $\varepsilon$ -accurate parameters (up to permutation, under  $\ell^2$  metric) w.h.p.*

*The running time and sample complexity are*

$$\text{poly}(d, k, 1/\varepsilon, 1/w_{\min}, 1/\lambda_{\min})$$

*where  $\lambda_{\min} = k^{\text{th}}$ -largest singular value of  $[\vec{\mu}_1^* | \vec{\mu}_2^* | \dots | \vec{\mu}_k^*]$ .*

(Also using new techniques from Anandkumar-Ge-H-Kakade-Telgarsky, '12.)

## 2. Learning algorithm

Introduction

Learning algorithm

- Method-of-moments

- Choice of moments

- Solving the moment equations

Concluding remarks

## Method-of-moments

Let  $S \subset \mathbb{R}^d$  be an i.i.d. sample from an unknown mixture of spherical Gaussians:

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## Estimation via method-of-moments (Pearson, 1894)

Find parameters  $\theta$  such that

$$\mathbb{E}_{\theta} [ \rho(\vec{x}) ] \approx \hat{\mathbb{E}}_{\vec{x} \in S} [ \rho(\vec{x}) ]$$

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Q1 Which moments to use?

Q2 How to (approx.) solve moment equations?

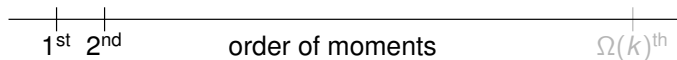
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# Which moments to use?

moment order	reliable estimates?	unique solution?
1 <sup>st</sup> , 2 <sup>nd</sup>		

**1<sup>st</sup>- and 2<sup>nd</sup>-order moments** (*e.g.*, mean, covariance)

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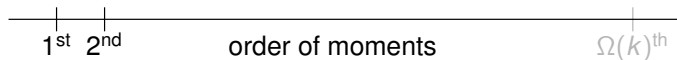
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$$\mathbb{E}_{\vec{x} \in \mathcal{S}}[\vec{x} \otimes \vec{x}] \approx \mathbb{E}_{\theta^*}[\vec{x} \otimes \vec{x}]$$

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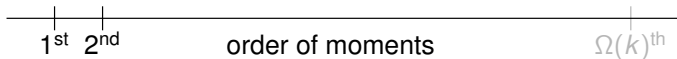
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- ▶ Can have multiple solutions to moment equations.

$$\mathbb{E}_{\theta_1}[\vec{x} \otimes \vec{x}] \approx \mathbb{E}_{\vec{x} \in S}[\vec{x} \otimes \vec{x}] \approx \mathbb{E}_{\theta_2}[\vec{x} \otimes \vec{x}], \quad \theta_1 \neq \theta_2$$

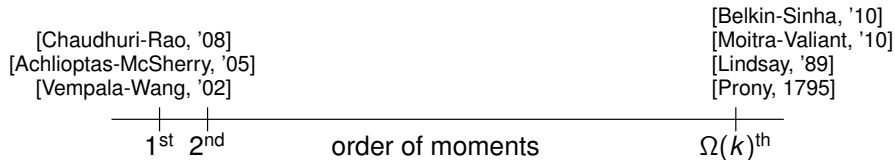
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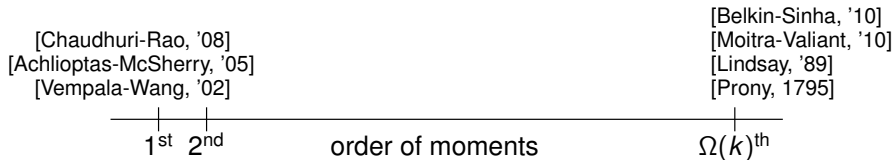


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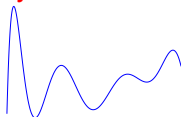


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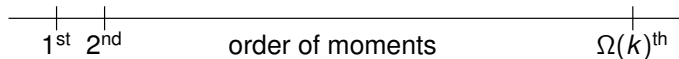
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- ▶ Uniquely pins down the solution.
- ▶ Empirical estimates very unreliable.



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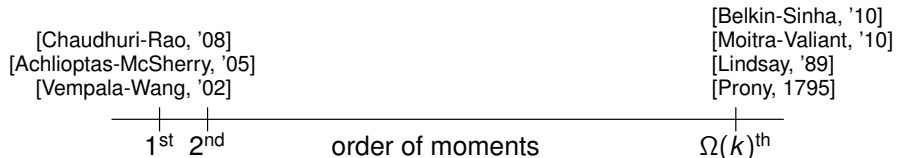
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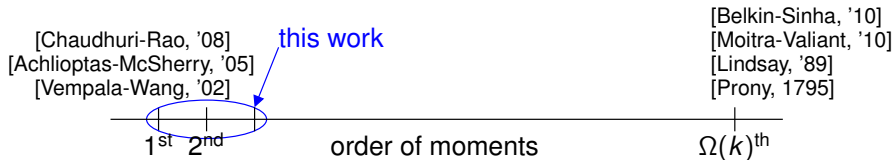
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Can we get best-of-both-worlds? **Yes!**

**In high-dimensions ( $d \geq k$ ),  
low-order multivariate moments suffice.**

( $1^{\text{st}}$ -,  $2^{\text{nd}}$ -, and  $3^{\text{rd}}$ -order moments)



# Structure of low-order multivariate moments

## Second- and third-order multivariate moments:

$$\mathbb{E}_{\theta}[\vec{x} \otimes \vec{x}] = \sum_{i=1}^k w_i \vec{\mu}_i \otimes \vec{\mu}_i + \text{some sparse matrix};$$

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**Upshot:** the following can be readily estimated (with  $\hat{M}$ ,  $\hat{T}$ ).

$$M_{\theta^*} := \sum_{i=1}^k w_i^* \vec{\mu}_i^* \otimes \vec{\mu}_i^* \quad \text{and} \quad T_{\theta^*} := \sum_{i=1}^k w_i^* \vec{\mu}_i^* \otimes \vec{\mu}_i^* \otimes \vec{\mu}_i^*.$$

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**Claim:**  $\{(\vec{\mu}_i, w_i)\}$  uniquely determined by  $M_\theta$  and  $T_\theta$ .

## Variational argument for parameter uniqueness

View  $M_\theta : \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$  and  $T_\theta : \mathbb{R}^d \times \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$  as **bi-linear** and **tri-linear** functions.

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## Lemma

If  $\{\vec{\mu}_i\}$  are linearly independent and all  $w_i > 0$ , then each of the  $k$  distinct, isolated local maximizers  $\vec{u}^*$  of

$$\max_{\vec{u} \in \mathbb{R}^d} T_\theta(\vec{u}, \vec{u}, \vec{u}) \quad \text{s.t.} \quad M_\theta(\vec{u}, \vec{u}) \leq 1$$

satisfies, for some  $i \in [k]$ ,

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$\therefore \{(\vec{\mu}_i, w_i) : i \in [k]\}$  uniquely determined by  $M_\theta, T_\theta$ . ■

## Main idea for variational lemma

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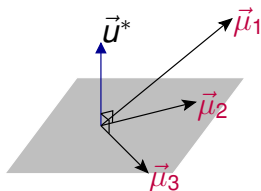
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Maximizers are directions  $\vec{u}^*$  orthogonal to all but one  $\vec{\mu}_j$ .

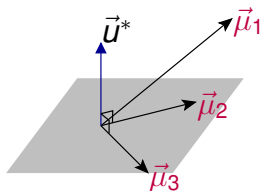




## Main idea for variational lemma

$$\max_{\vec{u} \in \mathbb{R}^d} \sum_{i=1}^k w_i \langle \vec{\mu}_i, \vec{u} \rangle^3 \quad \text{s.t.} \quad \sum_{i=1}^k w_i \langle \vec{\mu}_i, \vec{u} \rangle^2 \leq 1$$

Maximizers are directions  $\vec{u}^*$  orthogonal to all but one  $\vec{\mu}_j$ .



Combine with constraints  $w_j \langle \vec{\mu}_j, \vec{u}^* \rangle^2 \leq 1$  to get

$$M\vec{u}^* = \left( \sum_{i=1}^k w_i \vec{\mu}_i \otimes \vec{\mu}_i \right) \vec{u}^* = \sum_{i=1}^k w_i \vec{\mu}_i \langle \vec{\mu}_i, \vec{u}^* \rangle = \pm \sqrt{w_j} \vec{\mu}_j. \quad \blacksquare$$

## How to solve the moment equations?

Effectively want to solve

$$\min_{\theta} \|T_{\theta} - \widehat{T}\|^2 \quad \text{s.t.} \quad M_{\theta} = \widehat{M}. \quad (\dagger)$$

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**What we do:** find one component  $(\vec{\mu}_i, \mathbf{w}_i)$  at a time, using **local optimization** of related (also non-convex) objective function.

$$\max_{\vec{u} \in \mathbb{R}^d} \sum_{i,j,k} \widehat{T}_{i,j,k} u_i u_j u_k \quad \text{s.t.} \quad \sum_{i,j} \widehat{M}_{i,j} u_i u_j \leq 1 \quad (\ddagger)$$

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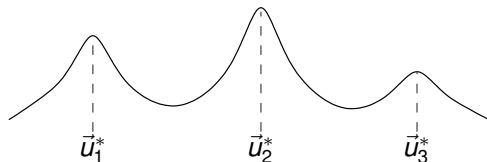
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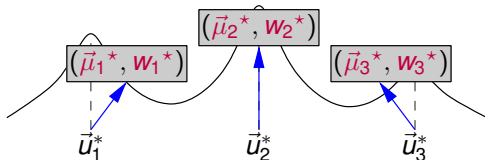
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**New robust algorithm for “tensor eigen-decomposition”** efficiently approximates *all local optima*, each corresponding to a component.  $\rightarrow$  Near-optimal solution to  $(\dagger)$ . ■

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Want to find *all* local maximizers of

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  - ▶ Else: abandon and restart.

## 3. Concluding remarks

Introduction

Learning algorithm

Concluding remarks

Open problems and summary

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- ▶ Can also handle mixtures of Gaussians with **somewhat more general covariances**, under incoherence conditions

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- ▶ **Question #1:** What about mixtures of Gaussians with arbitrary covariances?
- ▶ **Question #2:** How to handle degenerate cases /  $k \gg d$ ?  
(Practical relevance: automatic speech recognition)

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- ▶ **Open problem:** efficient estimators for highly over-complete and general mixture models ( $k \gg d$ ).

# Thanks!

Related survey/overview-ish paper:

- ▶ Tensor decompositions for latent variable models (with Anandkumar, Ge, Kakade, and Telgarsky): <http://arxiv.org/abs/1210.7559>

# Structure of low-order moments

- ▶ **First-order moments:**

$$\mathbb{E}[\vec{x}] = \sum_{i=1}^k w_i \vec{\mu}_i.$$

- ▶ **Second-order moments:**

$$\mathbb{E}[\vec{x} \otimes \vec{x}] = \sum_{i=1}^k w_i \vec{\mu}_i \otimes \vec{\mu}_i + \bar{\sigma}^2 \mathbf{I}$$

where  $\bar{\sigma}^2 := \sum_{i=1}^k w_i \sigma_i^2$ .

**Fact:**  $\bar{\sigma}^2$  is the smallest eigenvalue of  $\text{Cov}(\vec{x}) = \mathbb{E}[\vec{x} \otimes \vec{x}] - \mathbb{E}[\vec{x}] \otimes \mathbb{E}[\vec{x}]$ .



# Structure of low-order moments

► **Third-order moments:**

$$\begin{aligned}\mathbb{E}[\vec{x} \otimes \vec{x} \otimes \vec{x}] &= \sum_{i=1}^k w_i \vec{\mu}_i \otimes \vec{\mu}_i \otimes \vec{\mu}_i \\ &+ \sum_{i=1}^d \vec{m} \otimes \mathbf{e}_i \otimes \mathbf{e}_i + \mathbf{e}_i \otimes \vec{m} \otimes \mathbf{e}_i + \mathbf{e}_i \otimes \mathbf{e}_i \otimes \vec{m}\end{aligned}$$

where  $\vec{m} := \sum_{i=1}^k w_i \sigma_i^2 \vec{\mu}_i$ .

**Fact:**  $\vec{m} = \mathbb{E}[(\vec{u}^\top (\vec{x} - \mathbb{E}[\vec{x}]))^2 \vec{x}]$  for any unit-norm eigenvector  $\vec{u}$  of  $\text{Cov}(\vec{x})$  corresponding to eigenvalue  $\bar{\sigma}^2$ .

## Proof idea for optimization lemma

$$\max_{\vec{u} \in \mathbb{R}^d} T(\vec{u}, \vec{u}, \vec{u}) \text{ s.t. } M(\vec{u}, \vec{u}) \leq 1$$

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