



Learning Circuits with Few Negations

Boolean functions are not that monoton(ous).

Clément Canonne

LIAFA – 2015



Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

Introduction

Introduction: learning

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Goal: fixed, known class of Boolean functions $\mathcal{C} \subseteq 2^{\{0,1\}^n}$, and unknown $f \in \mathcal{C}$. How to learn f **efficiently**, i.e. output a hypothesis $\hat{f} \simeq f$?

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Many flavors:

With membership queries: Can we *approximately* learn f (in Hamming distance, with high probability) from *queries* of the form $x? \rightsquigarrow f(x)$

$$\Pr_{x \sim \{0,1\}^n} [f(x) \neq \hat{f}(x)] \leq \varepsilon \quad (\text{w.h.p.})$$

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PAC-learning: unknown underlying distribution D on $\{0,1\}^n$. Can we approximately learn f (with high probability) from random examples $\langle x, f(x) \rangle$ – where each x is a *sample* drawn independently from D ?

$$\Pr_{x \sim D} [f(x) \neq \hat{f}(x)] \leq \varepsilon \quad (\text{w.h.p.})$$

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uniform PAC learning \preceq learning with queries

Monotone functions (1)

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For circuit complexity theorists:

Definition. A Boolean function $f: \{0, 1\}^n \rightarrow \{0, 1\}$ is monotone if it is computed by a Boolean circuit with no negations (only AND and OR gates).

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For people with a twisted mind:

Definition. A Boolean function $f: \{0, 1\}^n \rightarrow \{0, 1\}$ is monotone if $f(0^n) \leq f(1^n)$, and f changes value at most once on any increasing chain from 0^n to 1^n .

(These definitions are equivalent.)

Examples.

The **majority** function (1 iff at least half the votes are positive): more votes cannot make a candidate lose.

The **s-clique** function (1 iff the input graph contains a clique of size s): more edges cannot remove a clique.

The **dictator** function (1 iff $x_1 = 1$): more voters have no influence anyway.

Monotone functions (2)

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Can we learn them?

Learning the class \mathcal{C}^n of **monotone Boolean functions** from uniform examples (to error ε) can be done in time $2^{\tilde{O}(\sqrt{n}/\varepsilon)}$. [BT96]

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Are we done here?

Outline of the talk

Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

Introduction

Generalizing monotone functions: \mathcal{C}_t^n .

Learning \mathcal{C}_t^n : Upper bound.

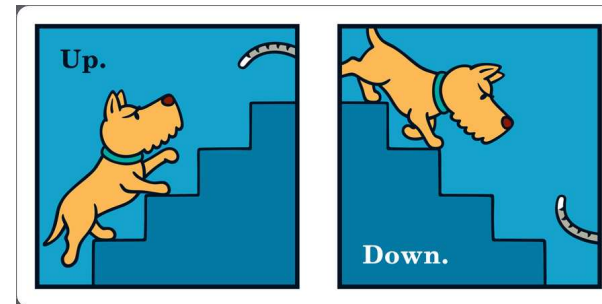
Learning \mathcal{C}_t^n : Lower bound.

Conclusion and Open Problem(s).

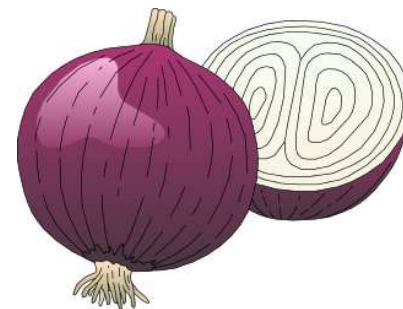
Plan in more detail

Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

- Generalizing monotone functions to “ k -alternating:” two views, reconciled by Markov’s Theorem.



- A structural theorem: characterizing these new functions as combination of simpler ones \rightsquigarrow upper bound on learning k -alternating functions, almost “for free.”



- Lower bound: a succession and combination thereof (from monotone... to monotone to k -alternating: hardness amplification)



Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

Generalizing monotone functions: \mathcal{C}_t^n .

k -alternating functions (1)

Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

For circuit complexity theorists:

Definition. A Boolean function $f: \{0, 1\}^n \rightarrow \{0, 1\}$ has inversion complexity t if it can be computed by a Boolean circuit with t negations (besides AND and OR gates), but no less.

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For people with a twisted mind:

Definition. A Boolean function $f: \{0, 1\}^n \rightarrow \{0, 1\}$ is k -alternating if f changes value at most k times on any increasing chain from 0^n to 1^n .

(Analysis of Boolean functions enthusiasts, stay with us?)

Examples.

The “not-too-many” function (1 iff between 40% and 60% of the votes are positive): more votes can harm a candidate.

The s -clique-but-no-Hamiltonian function (1 iff the input graph contains a clique of size s , but no Hamiltonian cycle): more edges can make things worse.

The Highlander function (1 iff exactly one of the x_i 's is 1): there shall be only one.



k -alternating functions (2)



Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

But are these definitions the same? Related?

k -alternating functions (2)

Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

But are these definitions the same? Related?

Theorem 4 (Markov's Theorem [[Mar57](#)]). *Let $f: \{0, 1\}^n \rightarrow \{0, 1\}$ be a function which is not identically 0. Then f is k -alternating if and only if it has inversion complexity $O(\log k)$.*

k -alternating functions (2)

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Theorem 7 (Markov's Theorem [Mar57]). *Let $f: \{0, 1\}^n \rightarrow \{0, 1\}$ be a function which is not identically 0. Then f is k -alternating if and only if it has inversion complexity $O(\log k)$.*

A refinement of this characterization:

Theorem 8. *If f is k -alternating, then it can be written $f(x) = h(m_1(x), \dots, m_k(x))$, where each $m_i(x)$ is monotone and h is either the parity function or its negation. Conversely, any function of this form is k -alternating.*

Corollary 9. *Every $f \in \mathcal{C}_t^n$ can be expressed as $f = h(m_1, \dots, m_T)$ where h is either Parity_T or its negation, each $m_i: \{0, 1\}^n \rightarrow \{0, 1\}$ is monotone, and $T = O(2^t)$.*

k -alternating functions (2)

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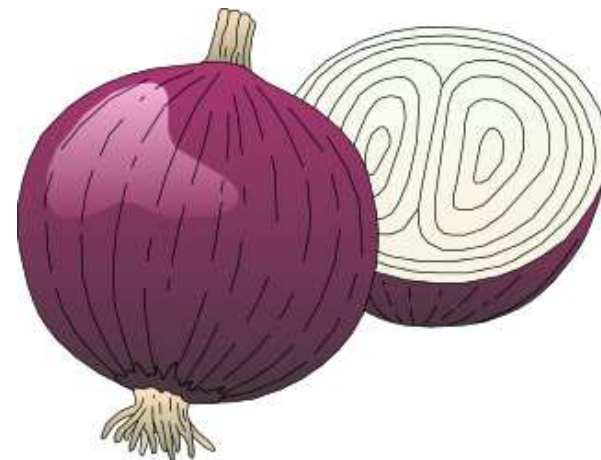
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Corollary 12. *Every $f \in \mathcal{C}_t^n$ can be expressed as $f = h(m_1, \dots, m_T)$ where h is either Parity_T or its negation, each $m_i: \{0, 1\}^n \rightarrow \{0, 1\}$ is monotone, and $T = O(2^t)$.*

Proof (and interpretation). the m_i 's are successive nested layers:



□

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Learning \mathcal{C}_t^n : Upper bound.

Influence, Low-Degree Algorithm, and a Can of Soup

Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

Theorem 13. *There is a uniform-distribution learning algorithm which learns any unknown $f \in \mathcal{C}_t^n$ from random examples to error ε in time $n^{O(2^t \sqrt{n}/\varepsilon)}$.*

Influence, Low-Degree Algorithm, and a Can of Soup

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Theorem 15. *There is a uniform-distribution learning algorithm which learns any unknown $f \in \mathcal{C}_t^n$ from random examples to error ε in time $n^{O(2^t \sqrt{n}/\varepsilon)}$. (Recall the $n^{O(\sqrt{n}/\varepsilon)}$ for monotone functions, i.e. $t = 0$.)*

Influence, Low-Degree Algorithm, and a Can of Soup

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Theorem 17. *There is a uniform-distribution learning algorithm which learns any unknown $f \in \mathcal{C}_t^n$ from random examples to error ε in time $n^{O(2^t \sqrt{n}/\varepsilon)}$. (Recall the $n^{O(\sqrt{n}/\varepsilon)}$ for monotone functions, i.e. $t = 0$.)*

Proof. Recall the *influence* of a Boolean functions is defined as

$$\mathbf{Inf}[f] = \sum_{i=1}^n \mathbf{Inf}_i[f], \quad \text{where} \quad \mathbf{Inf}_i[f] = \Pr_{x \in \{0,1\}^n} [f(x) \neq f(x^{\oplus i})]$$

and that monotone functions each have total influence at most \sqrt{n} . Moreover, *we can learn functions with good Fourier concentration:*

Theorem 18 (Low-Degree Algorithm ([LMN93])). *Let \mathcal{C} be a class of Boolean functions such that for $\varepsilon > 0$ and $\tau = \tau(\varepsilon, n)$,*

$$\sum_{|S| > \tau} \hat{f}(S)^2 \leq \varepsilon$$

for any $f \in \mathcal{C}$. Then \mathcal{C} can be learned from uniform random examples in time $\text{poly}(n^\tau, 1/\varepsilon)$.

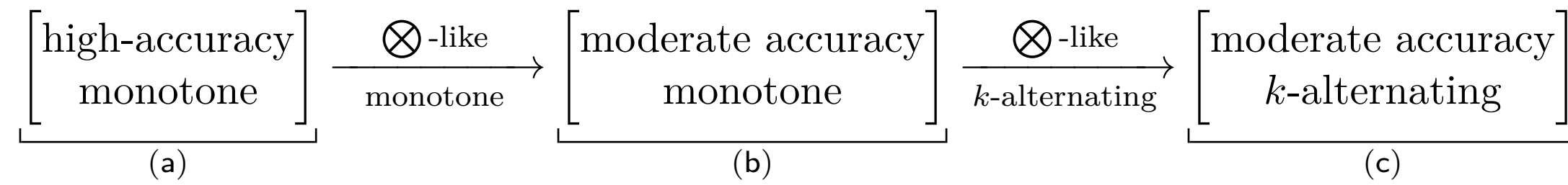
Combining the decomposition theorem, a union bound, some massaging, and the above, k -alternating functions have total influence at most $k\sqrt{n}$, and we get the theorem. □

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Learning \mathcal{C}_t^n : Lower bound.

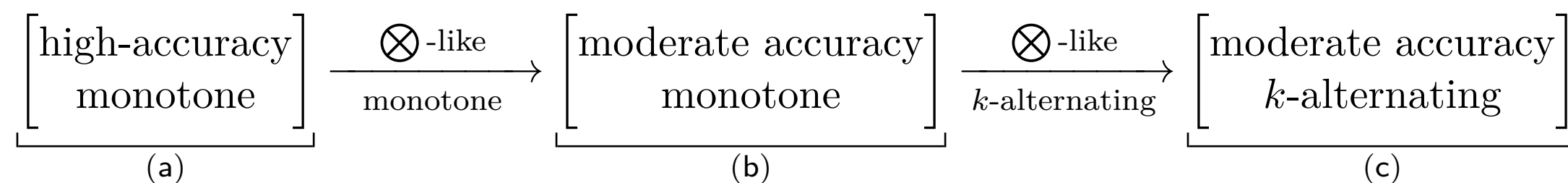
Three-step program

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(a) Monotone functions are hard to learn *well*. (A simple extension of [BT96].)

Learning *monotone* functions to (very small) error $\frac{1}{\sqrt{n}}$ requires 2^{Cn} queries, for some absolute $C > 0$.

(b) Monotone functions are hard to learn, *period*. (Hardness amplification and the previous result.)

Learning *monotone* functions to (almost any) error ε requires $2^{\Omega(\sqrt{n}/\varepsilon)}$ queries.

(c) k -alternating functions are hard to learn, *too!* (Hardness amplification again – and a truncated parity.)

Learning k -alternating functions to (almost any) error ε requires $2^{\Omega(k\sqrt{n}/\varepsilon)}$ queries.

In more detail: tools for (b) and (c) – bear with me

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Definition (Composition). For $f: \{0, 1\}^m \rightarrow \{0, 1\}$ and $g: \{0, 1\}^r \rightarrow \{0, 1\}$, $g \otimes f$ is the function on $n = mr$ variables defined by

$$(g \otimes f)(x) \stackrel{\text{def}}{=} g(f(x_1, \dots, x_m), \dots, f(x_{(r-1)m+1}, \dots, x_{rm}))$$

For any $g: \{0, 1\}^r \rightarrow \{0, 1\}$ and $\mathcal{F}_m \subseteq 2^{\{0,1\}^m}$, $g \otimes \mathcal{F}_m = \{g \otimes f : f \in \mathcal{F}_m\}$ and $g \otimes \mathcal{F} = \{g \otimes \mathcal{F}_m\}_{m \geq 1}$.

Definition (Noise stability). For $f: \{0, 1\}^n \rightarrow \{0, 1\}$, the noise stability of f at $\eta \in [-1, 1]$ is

$$\text{Stab}_\eta(f) \stackrel{\text{def}}{=} 1 - 2 \Pr[f(x) \neq f(y)]$$

where $x \sim \{0, 1\}^n$, and x and y are η -correlated.

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where $x \sim \{0, 1\}^n$, and x and y are η -correlated.

Definition (Bias and expected bias). The bias of a Boolean function $h: \{0, 1\}^n \rightarrow \{0, 1\}$ is $\text{bias}(h) \stackrel{\text{def}}{=} \max(\Pr[h = 1], \Pr[h = 0])$ while the expected bias of h at δ is defined as

$$\text{ExpBias}_\delta(h) \stackrel{\text{def}}{=} \mathbb{E}_\rho[\text{bias}(h_\rho)]$$

where ρ is a random δ -restriction on n coordinates.

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where ρ is a random δ -restriction on n coordinates.

Theorem 21 (Theorem 12 of [FLS11]). Fix $g: \{0, 1\}^r \rightarrow \{0, 1\}$, and let \mathcal{F} be a class of m -variable functions with “very small bias.” Let A be a membership query algorithm that learns $g \otimes \mathcal{F}$ to accuracy $\text{ExpBias}_\gamma(g) + \epsilon$ using $T(m, r, 1/\epsilon, 1/\gamma)$ queries. Then there is a membership query algorithm to learn \mathcal{F} to accuracy $1 - \gamma$, using $O(T \cdot \text{poly}(m, r, 1/\epsilon, 1/\gamma))$ membership queries.

In more detail: step (b)

Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

Theorem 22. *There exists a class \mathcal{H}_n of balanced n -variable monotone Boolean functions such that for any $\varepsilon \in [1/n^{1/6}, .49]$, learning \mathcal{H}_n to error ε requires $2^{\Omega(\sqrt{n}/\varepsilon)}$ membership queries.*

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Sketch.

- Choose suitable $m, r = \omega(1)$ such that $mr = n$.

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Theorem 24. *There exists a class \mathcal{H}_n of balanced n -variable monotone Boolean functions such that for any $\varepsilon \in [1/n^{1/6}, .49]$, learning \mathcal{H}_n to error ε requires $2^{\Omega(\sqrt{n}/\varepsilon)}$ membership queries.*

Sketch.

- Choose suitable $m, r = \omega(1)$ such that $mr = n$.
- Take the “Mossel–O’Donnell function” g_r [MO03] (a balanced monotone function **minimally stable** under very small noise)
(*Why? We want $\text{ExpBias}_\gamma(g_r) + \epsilon' \leq 1 - \varepsilon$, and less stable means smaller expected bias*)

In more detail: step (b)

Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

Theorem 25. *There exists a class \mathcal{H}_n of balanced n -variable monotone Boolean functions such that for any $\varepsilon \in [1/n^{1/6}, .49]$, learning \mathcal{H}_n to error ε requires $2^{\Omega(\sqrt{n}/\varepsilon)}$ membership queries.*

Sketch.

- Choose suitable $m, r = \omega(1)$ such that $mr = n$.
- Take the “Mossel–O’Donnell function” g_r [MO03] (a balanced monotone function **minimally stable** under very small noise)
(*Why? We want $\text{ExpBias}_\gamma(g_r) + \epsilon' \leq 1 - \varepsilon$, and less stable means smaller expected bias*)
- Apply the hardness amplification theorem on $g_r \otimes \mathcal{G}_m$, \mathcal{G}_m being the “hard class of monotone functions” from Step (a).

In more detail: step (b)

Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

Theorem 26. *There exists a class \mathcal{H}_n of balanced n -variable monotone Boolean functions such that for any $\varepsilon \in [1/n^{1/6}, .49]$, learning \mathcal{H}_n to error ε requires $2^{\Omega(\sqrt{n}/\varepsilon)}$ membership queries.*

Sketch.

- Choose suitable $m, r = \omega(1)$ such that $mr = n$.
- Take the “Mossel–O’Donnell function” g_r [MO03] (a balanced monotone function **minimally stable** under very small noise)
(*Why? We want $\text{ExpBias}_\gamma(g_r) + \epsilon' \leq 1 - \varepsilon$, and less stable means smaller expected bias*)
- Apply the hardness amplification theorem on $g_r \otimes \mathcal{G}_m$, \mathcal{G}_m being the “hard class of monotone functions” from Step (a).
- Hope all the constants and parameters work out.

In more detail: step (b)

Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

Theorem 27. *There exists a class \mathcal{H}_n of balanced n -variable monotone Boolean functions such that for any $\varepsilon \in [1/n^{1/6}, .49]$, learning \mathcal{H}_n to error ε requires $2^{\Omega(\sqrt{n}/\varepsilon)}$ membership queries.*

Sketch.

- Choose suitable $m, r = \omega(1)$ such that $mr = n$.
- Take the “Mossel–O’Donnell function” g_r [MO03] (a balanced monotone function **minimally stable** under very small noise)
(*Why? We want $\text{ExpBias}_\gamma(g_r) + \epsilon' \leq 1 - \varepsilon$, and less stable means smaller expected bias*)
- Apply the hardness amplification theorem on $g_r \otimes \mathcal{G}_m$, \mathcal{G}_m being the “hard class of monotone functions” from Step (a).
- Hope all the constants and parameters work out.



□

In more detail: step (c)

Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

Theorem 28. *For any function $k: \mathbb{N} \rightarrow \mathbb{N}$, there exists a class $\mathcal{H}^{(k)}$ of balanced $k(n)$ -alternating Boolean functions (on n variables) such that, for any n sufficiently large and $\varepsilon > 0$ such that (i) $2 \leq k < n^{1/14}$, and (ii) $k^{7/3}/n^{1/6} \leq \varepsilon \leq .49$, learning $\mathcal{H}^{(k)}$ to accuracy $1 - \varepsilon$ requires $2^{\Omega(k\sqrt{n}/\varepsilon)}$ membership queries.*

In more detail: step (c)

Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

Theorem 29. *For any function $k: \mathbb{N} \rightarrow \mathbb{N}$, there exists a class $\mathcal{H}^{(k)}$ of balanced $k(n)$ -alternating Boolean functions (on n variables) such that, for any n sufficiently large and $\varepsilon > 0$ such that (i) $2 \leq k < n^{1/14}$, and (ii) $k^{7/3}/n^{1/6} \leq \varepsilon \leq .49$, learning $\mathcal{H}^{(k)}$ to accuracy $1 - \varepsilon$ requires $2^{\Omega(k\sqrt{n}/\varepsilon)}$ membership queries.*

Sketch.

- Choose suitable $m, r = \omega(1)$ such that $mr = n$ and $r \approx k^2$.

In more detail: step (c)

Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

Theorem 30. *For any function $k: \mathbb{N} \rightarrow \mathbb{N}$, there exists a class $\mathcal{H}^{(k)}$ of balanced $k(n)$ -alternating Boolean functions (on n variables) such that, for any n sufficiently large and $\varepsilon > 0$ such that (i) $2 \leq k < n^{1/14}$, and (ii) $k^{7/3}/n^{1/6} \leq \varepsilon \leq .49$, learning $\mathcal{H}^{(k)}$ to accuracy $1 - \varepsilon$ requires $2^{\Omega(k\sqrt{n}/\varepsilon)}$ membership queries.*

Sketch.

- Choose suitable $m, r = \omega(1)$ such that $mr = n$ and $r \approx k^2$.
- Take $\text{Parity}_{k,r}$, the “ k -Truncated Parity function on r variables” as combining function, *in lieu* of the previous g_r .
(Why? We want our function to be k -alternating, very little stable, and $r \approx k^2$ instead of k is a technicality)

In more detail: step (c)

Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

Theorem 31. *For any function $k: \mathbb{N} \rightarrow \mathbb{N}$, there exists a class $\mathcal{H}^{(k)}$ of balanced $k(n)$ -alternating Boolean functions (on n variables) such that, for any n sufficiently large and $\varepsilon > 0$ such that (i) $2 \leq k < n^{1/14}$, and (ii) $k^{7/3}/n^{1/6} \leq \varepsilon \leq .49$, learning $\mathcal{H}^{(k)}$ to accuracy $1 - \varepsilon$ requires $2^{\Omega(k\sqrt{n}/\varepsilon)}$ membership queries.*

Sketch.

- Choose suitable $m, r = \omega(1)$ such that $mr = n$ and $r \approx k^2$.
- Take $\text{Parity}_{k,r}$, the “ k -Truncated Parity function on r variables” as combining function, *in lieu* of the previous g_r .
(*Why? We want our function to be k -alternating, very little stable, and $r \approx k^2$ instead of k is a technicality*)
- Apply the hardness amplification theorem on $\text{Parity}_{k,r} \otimes \mathcal{H}_m$, \mathcal{H}_m being the “hard class of monotone functions” from Step (b).

In more detail: step (c)

Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

Theorem 32. For any function $k: \mathbb{N} \rightarrow \mathbb{N}$, there exists a class $\mathcal{H}^{(k)}$ of balanced $k(n)$ -alternating Boolean functions (on n variables) such that, for any n sufficiently large and $\varepsilon > 0$ such that (i) $2 \leq k < n^{1/14}$, and (ii) $k^{7/3}/n^{1/6} \leq \varepsilon \leq .49$, learning $\mathcal{H}^{(k)}$ to accuracy $1 - \varepsilon$ requires $2^{\Omega(k\sqrt{n}/\varepsilon)}$ membership queries.

Sketch.

- Choose suitable $m, r = \omega(1)$ such that $mr = n$ and $r \approx k^2$.
- Take $\text{Parity}_{k,r}$, the “ k -Truncated Parity function on r variables” as combining function, *in lieu* of the previous g_r .
(Why? We want our function to be k -alternating, very little stable, and $r \approx k^2$ instead of k is a technicality)
- Apply the hardness amplification theorem on $\text{Parity}_{k,r} \otimes \mathcal{H}_m$, \mathcal{H}_m being the “hard class of monotone functions” from Step (b).
- *Really* hope all the constants and parameters work out.

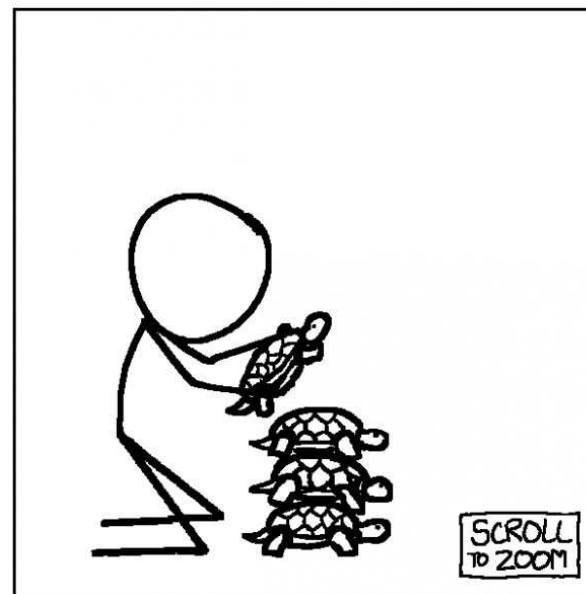
In more detail: step (c)

Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

Theorem 33. For any function $k: \mathbb{N} \rightarrow \mathbb{N}$, there exists a class $\mathcal{H}^{(k)}$ of balanced $k(n)$ -alternating Boolean functions (on n variables) such that, for any n sufficiently large and $\varepsilon > 0$ such that (i) $2 \leq k < n^{1/14}$, and (ii) $k^{7/3}/n^{1/6} \leq \varepsilon \leq .49$, learning $\mathcal{H}^{(k)}$ to accuracy $1 - \varepsilon$ requires $2^{\Omega(k\sqrt{n}/\varepsilon)}$ membership queries.

Sketch.

- Choose suitable $m, r = \omega(1)$ such that $mr = n$ and $r \approx k^2$.
- Take $\text{Parity}_{k,r}$, the “ k -Truncated Parity function on r variables” as combining function, *in lieu* of the previous g_r .
(Why? We want our function to be k -alternating, very little stable, and $r \approx k^2$ instead of k is a technicality)
- Apply the hardness amplification theorem on $\text{Parity}_{k,r} \otimes \mathcal{H}_m$, \mathcal{H}_m being the “hard class of monotone functions” from Step (b).
- *Really* hope all the constants and parameters work out.



□



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Conclusion and Open Problem(s).



Open problems

Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

Weak Learning: can one learn \mathcal{C}_t^n to error $\frac{1}{2} - \frac{1}{\text{poly}(n)}$ (“barely better than random”) in polynomial time?

(Related) Fourier spectrum: Can we get any further understanding of the Fourier spectrum of k -alternating functions?

Concrete example:

Let f, g be monotone Boolean functions, and $h = \text{Parity}(f, g)$. Can we prove

$$\sum_{|S| \leq 2} \hat{h}(S)^2 \geq \frac{1}{\text{poly}(n)}?$$

Or even $\sum_{|S| \leq 2} \hat{h}(S)^2 > 0$?



Thank you.

Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

Any question?

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Introduction Generalizing monotone functions: \mathcal{C}_t^n . Learning \mathcal{C}_t^n : Upper bound. Learning \mathcal{C}_t^n : Lower bound. Conclusion and Open Problem(s).

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