

The Exponential Family

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November 9, 2016

The exponential family is a class of densities (Brown, 1986). It encompasses many familiar forms of likelihoods, such as the Gaussian, Poisson, multinomial, and Bernoulli. It also encompasses their conjugate priors, such as the Gamma, Dirichlet, and beta.

1 Definition

A probability density in the exponential family has this form

$$p(x | \eta) = h(x) \exp\{\eta^\top t(x) - a(\eta)\}, \quad (1)$$

where

- η is the *natural parameter*;
- $t(x)$ are *sufficient statistics*;
- $h(x)$ is the “base measure;”
- $a(\eta)$ is the log normalizer.

Examples of exponential family distributions include Gaussian, gamma, Poisson, Bernoulli, multinomial, Markov models.

Examples of distributions that are not in this family include student-t, mixtures, and hidden Markov models. (We are considering these families as distributions of data. The latent variables are implicitly marginalized out.)

- The statistic $t(x)$ is called *sufficient* because the probability as a function of η only depends on x through $t(x)$.
- The exponential family has fundamental connections to the world of graphical models (Wainwright and Jordan, 2008). For our purposes, we’ll use exponential

families as components in directed graphical models, e.g., in the mixtures of Gaussians.

- The log normalizer ensures that the density integrates to 1,

$$a(\eta) = \log \int h(x) \exp\{\eta^\top t(x)\} d\nu(x) \quad (2)$$

This is the negative logarithm of the normalizing constant.

- The function $h(x)$ can be a source of confusion. One way to interpret $h(x)$ is the (unnormalized) distribution of x when $\eta = 0$. It might involve statistics of x that are not in $t(x)$, i.e., that do not vary with the natural parameter.

How do we take a familiar distribution with parameter μ and try to turn it into an exponential family?

1. Exponentiate the log density to find $\exp\{\log p(x | \mu)\}$.
2. Inside the exponential, find terms that can be written as $\eta_i(\mu)t_i(x)$ for sets of functions $\eta_i(\mu)$ and $t_i(x)$. These are natural parameters and sufficient statistics.
3. Find terms that are a function only of the parameters, $a(\mu)$. Try to write them in terms of the $\eta_i(\mu)$ identified in the previous step. This is the log normalizer.
4. Now look at the rest—hopefully it's a function of x and constants, i.e., not of any of the free parameters μ . This is $h(x)$.

Bernoulli. As an example, let's put the Bernoulli (in its usual form) into its exponential family form. The Bernoulli you are used to seeing is

$$p(x | \pi) = \pi^x (1 - \pi)^{1-x} \quad x \in \{0, 1\} \quad (3)$$

In exponential family form

$$p(x | \pi) = \exp \{ \log (\pi^x (1 - \pi)^{1-x}) \} \quad (4)$$

$$= \exp \{ x \log \pi + (1 - x) \log(1 - \pi) \} \quad (5)$$

$$= \exp \{ x \log \pi - x \log(1 - \pi) + \log(1 - \pi) \} \quad (6)$$

$$= \exp \{ x \log(\pi / (1 - \pi)) + \log(1 - \pi) \} \quad (7)$$

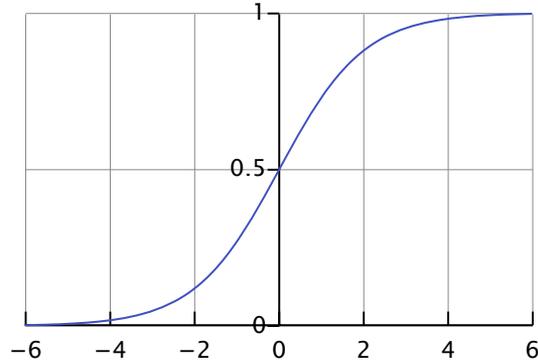


Figure 1: The logistic function (from Wikipedia).

This reveals the exponential family where

$$\eta = \log(\pi/(1 - \pi)) \quad (8)$$

$$t(x) = x \quad (9)$$

$$a(\eta) = -\log(1 - \pi) = \log(1 + e^\eta) \quad (10)$$

$$h(x) = 1 \quad (11)$$

Note the relationship between π and η is invertible

$$\pi = 1/(1 + e^{-\eta}) \quad (12)$$

This is the *logistic function*. See Figure 1.

Poisson. The Poisson is a distribution on integers, often used for count data. The familiar form of the Poisson is

$$p(x | \lambda) = \frac{1}{x!} \lambda^x \exp\{-\lambda\}. \quad (13)$$

Put this in exponential family form

$$p(x | \lambda) = \frac{1}{x!} \exp\{x \log \lambda - \lambda\}. \quad (14)$$

We see that

$$\eta = \log \lambda \quad (15)$$

$$t(x) = x \quad (16)$$

$$a(\eta) = \lambda = \exp\{\eta\} \quad (17)$$

$$h(x) = 1/x! \quad (18)$$

Gaussian. See Appendix A for the natural parameterization of the Gaussian.

2 Moments of an exponential family

Let's go back to the general family. We are going to take derivatives of the log normalizer. This gives us moments of the sufficient statistics,

$$\nabla_{\eta} a(\eta) = \nabla_{\eta} \{ \log \int \exp\{\eta^{\top} t(x)\} h(x) dx \} \quad (19)$$

$$= \frac{\nabla_{\eta} \int \exp\{\eta^{\top} t(x)\} h(x) dx}{\int \exp\{\eta^{\top} t(x)\} h(x) dx} \quad (20)$$

$$= \int t(x) \frac{\exp\{\eta^{\top} t(x)\} h(x)}{\int \exp\{\eta^{\top} t(x)\} h(x) dx} dx \quad (21)$$

$$= \mathbb{E}_{\eta}[t(X)] \quad (22)$$

Check: Higher order derivatives give higher order moments. For example,

$$\frac{\partial^2 a(\eta)}{\partial \eta_i \partial \eta_j} = \mathbb{E} [t_i(X) t_j(X)] - \mathbb{E} [t_i(X)] \mathbb{E} [t_j(X)] = \text{Cov}(t_i(X), t_j(X)). \quad (23)$$

There is a 1-1 relationship between the mean of the sufficient statistics $\mathbb{E} [t(X)]$ and natural parameter η . In other words, the mean is an alternative parameterization of the distribution. (Many of the forms of exponential families that you know are the mean parameterization.)

We can easily see the 1 – 1 relationship between $\mathbb{E} [t(X)]$ and η in one dimension. Let X be a scalar. Note that

- $\text{Var}(t(X)) = \nabla^2 a_{\eta}$ is positive.

- $\rightarrow a(\eta)$ is convex.
- \rightarrow 1-1 relationship between its argument and first derivative

Here is some notation for later (when we discuss generalized linear models). Denote the mean parameter as $\mu = \mathbb{E}[t(X)]$; denote the inverse map as $\psi(\mu)$, which gives the η such that $\mathbb{E}[t(X)] = \mu$.

Bernoulli. We saw the 1-1 relationship through the logistic function. Note that $\pi = \mathbb{E}[X]$ because X is an indicator.

Gaussian. The derivative with respect to η_1 is

$$\frac{da(\eta)}{d\eta_1} = -\frac{\eta_1}{2\eta_2} \quad (24)$$

$$= \mu \quad (25)$$

$$= \mathbb{E}[X] \quad (26)$$

The derivative with respect to η_2 is

$$\frac{da(\eta)}{d\eta_2} = \frac{\eta_1^2}{4\eta_2^2} - \frac{1}{2\eta_2} \quad (27)$$

$$= \sigma^2 + \mu^2 \quad (28)$$

$$= \mathbb{E}[X^2] \quad (29)$$

This means that the variance is

$$\text{Var}(X) = \mathbb{E}[X^2] - \mathbb{E}[X]^2 \quad (30)$$

$$= -\frac{1}{2\eta_2} \quad (31)$$

$$= \sigma^2 \quad (32)$$

Poisson. The expectation is the rate,

$$\mathbb{E}[X] = \frac{da(\eta)}{d\eta} = \exp\{\eta\} = \lambda. \quad (33)$$

All higher moments are the rate. This tying of mean and variance leads applied statisticians to alternatives, such as the negative Binomial, where we separately control the mean and variance.

3 Maximum likelihood estimation of an exponential family.

The data are $x_{1:n}$. We seek the value of η that maximizes the likelihood.

The log likelihood is

$$L = \sum_{n=1}^N \log p(x_n | \eta) \quad (34)$$

$$= \sum_{n=1}^N (\log h(x_n) + \eta^\top t(x_n) - a(\eta)) \quad (35)$$

$$= \sum_{n=1}^N \log h(x_n) + \eta^\top \sum_{n=1}^N t(x_n) - N \cdot a(\eta) \quad (36)$$

As a function of η , the log likelihood only depends on $\sum_{n=1}^N t(x_n)$. It has fixed dimension; there is no need to store the data. (And note that it is *sufficient* for estimating η .)

Take the gradient of the likelihood and set it to zero,

$$\nabla_{\eta} L = \sum_{n=1}^N t(x_n) - N \nabla_{\eta} a(\eta). \quad (37)$$

It's now easy to solve for the mean parameter:

$$\mu_{\text{ML}} = \frac{\sum_{n=1}^N t(x_n)}{N}. \quad (38)$$

This is, as you might guess, the empirical mean of the sufficient statistics. The inverse map gives us the natural parameter,

$$\eta_{\text{ML}} = \psi(\mu_{\text{ML}}). \quad (39)$$

Bernoulli. The MLE of the mean parameter μ_{ML} is the sample mean; the MLE of the natural parameter is the corresponding log odds.

Gaussian. The MLE of the mean parameters are the sample mean and the sample variance.

Poisson. The MLE of the mean parameters is the sample mean; the MLE of the natural parameter is its log.

4 Conjugacy

Consider the following set up:

$$\eta \sim F(\cdot | \lambda) \tag{40}$$

$$x_i \sim G(\cdot | \eta) \quad \text{for } i \in \{1, \dots, n\}. \tag{41}$$

This is a classical Bayesian data analysis setting. And, this is used as a component in more complicated models, e.g., in hierarchical models.

The posterior distribution of η given the data $x_{1:n}$ is

$$p(\eta | x_{1:n}, \lambda) \propto F(\eta | \lambda) \prod_{i=1}^n G(x_i | \eta). \tag{42}$$

Suppose this distribution is in the same family as F , i.e., its parameters are in the space indexed by λ . Then F and G are a **conjugate pair**.

For example,

- Gaussian likelihood with fixed variance; Gaussian prior on the mean
- Multinomial likelihood; Dirichlet prior on the probabilities
- Bernoulli likelihood; beta prior on the bias
- Poisson likelihood; gamma prior on the rate

In all these settings, the conditional distribution of the parameter given the data is in the same family as the prior.

4.1 A generic conjugate prior

Suppose the data come from an exponential family. Every exponential family has a conjugate prior ([Diaconis and Ylvisaker, 1979](#); [Bernardo and Smith, 1994](#)),

$$p(x_i | \eta) = h_\ell(x) \exp\{\eta^\top t(x_i) - a_\ell(\eta)\} \tag{43}$$

$$p(\eta | \lambda) = h_c(\eta) \exp\{\lambda_1^\top \eta + \lambda_2(-a_\ell(\eta)) - a_c(\lambda)\}. \tag{44}$$

The natural parameter $\lambda = [\lambda_1, \lambda_2]$ has dimension $\dim(\eta) + 1$. The sufficient statistics are $[\eta, -a(\eta)]$.

The other terms $h_c(\cdot)$ and $a_c(\cdot)$ depend on the form of the exponential family. For example, when η are multinomial parameters, these terms define a Dirichlet.

4.2 The posterior

We compute the posterior in the general case,

$$p(\eta | x_{1:n}, \lambda) \propto p(\eta | \lambda) \prod_{i=1}^n p(x_i | \eta) \quad (45)$$

$$= h(\eta) \exp\{\lambda_1^\top \eta + \lambda_2(-a(\eta)) - a_c(\lambda)\} \quad (46)$$

$$\cdot \left(\prod_{i=1}^n h(x_i)\right) \exp\{\eta^\top \sum_{i=1}^n t(x_i) - n a_c(\eta)\} \\ \propto h(\eta) \exp\{(\lambda_1 + \sum_{i=1}^n t(x_i))^\top \eta + (\lambda_2 + n)(-a(\eta))\}. \quad (47)$$

This is the same exponential family as the prior, with parameters

$$\hat{\lambda}_1 = \lambda_1 + \sum_{i=1}^n t(x_i) \quad (48)$$

$$\hat{\lambda}_2 = \lambda_2 + n. \quad (49)$$

4.3 The posterior predictive

We compute the posterior predictive distribution. This comes up frequently in applications of models (i.e., when doing prediction) and in inference (i.e., when doing collapsed Gibbs sampling).

Consider a new data point x_{new} . Its posterior predictive is

$$p(x_{\text{new}} | x_{1:n}) = \int p(x_{\text{new}} | \eta) p(\eta | \mathbf{x}) d\eta \quad (50)$$

$$= \int \exp\{\eta^\top x_{\text{new}} - a(\eta)\} \exp\{\hat{\lambda}_1^\top \eta + \hat{\lambda}_2(-a(\eta)) - a(\hat{\lambda})\} d\eta \quad (51)$$

$$= \frac{\int \exp\{(\hat{\lambda}_1 + x_{\text{new}})^\top \eta + (\hat{\lambda}_2 + 1)(-a(\eta))\} d\eta}{\exp\{a(\hat{\lambda}_1, \hat{\lambda}_2)\}} \quad (52)$$

$$= \exp\{a(\hat{\lambda}_1 + x_{\text{new}}, \hat{\lambda}_2 + 1) - a(\hat{\lambda}_1, \hat{\lambda}_2)\} \quad (53)$$

In other words, the posterior predictive density is a ratio of normalizing constants.

In the numerator is the posterior with the new data point added; in the denominator is the posterior without the new data point.

Note: this is how we can derive collapsed Gibbs samplers.

4.4 Canonical prior

There is a variation on the form of the simple conjugate prior that is useful for understanding its properties. Set $\lambda_1 = x_0 n_0$ and $\lambda_2 = n_0$. (And, for convenience, drop the sufficient statistic so that $t(x) = x$.)

In this form the conjugate prior is

$$p(\eta | x_0, n_0) \propto \exp\{n_0 x_0^\top \eta - n_0 a(\eta)\}. \quad (54)$$

We can interpret x_0 as our prior idea of the expectation of x , and n_0 as the number of “prior data points.”

Consider the predictive expectation of X , $\mathbb{E}_\eta [\mathbb{E}_X [X | \eta]]$. The first expectation is with respect to the prior; the second is respect to the data distribution. Fact:

$$\mathbb{E} [\mathbb{E} [X | \eta]] = x_0. \quad (55)$$

Assume data $x_{1:n}$. The mean is

$$\bar{x} = (1/n) \sum_{i=1}^n x_i \quad (56)$$

Given the data and a prior, the posterior parameters are

$$\hat{x}_0 = \frac{n_0 x_0 + n \bar{x}}{n + n_0} \quad (57)$$

$$\hat{n} = n_0 + n \quad (58)$$

This follows from $\hat{\lambda}_1, \hat{\lambda}_2$ in Equation 48 and Equation 49. Notice the posterior expectation of X , \hat{x}_0 , is a convex combination of x_0 (our prior idea) and \bar{x} (the data mean). This is a property of conjugate priors ([Diaconis and Ylvisaker, 1979](#)).

As an example, we now derive the canonical prior for a Bernoulli likelihood. (Appendix B derives the canonical prior for a unit-variance Gaussian.)

4.5 Example: Data from a Bernoulli

The Bernoulli likelihood is

$$p(x | \pi) = \pi^x (1 - \pi)^{1-x}. \quad (59)$$

Above we have seen its form as a minimal exponential family. Let's rewrite that, but keeping the mean parameter in the picture,

$$p(x | \pi) = \exp\{x \log(\pi/(1 - \pi)) + \log(1 - \pi)\} \quad (60)$$

The canonical conjugate prior therefore looks like this,

$$p(\pi | x_0, n_0) = \exp\{n_0 x_0 \log(\pi/(1 - \pi)) + n_0 \log(1 - \pi) - a(n_0, x_0)\} \quad (61)$$

This simplifies to

$$p(\pi | x_0, n_0) = \exp\{n_0 x_0 \log(\pi) + n_0 (1 - x_0) \log(1 - \pi) - a(n_0, x_0)\} \quad (62)$$

Putting this in non-exponential family form,

$$p(\pi | x_0, n_0) \propto \pi^{n_0 x_0} (1 - \pi)^{n_0 (1 - x_0)} \quad (63)$$

which *nearly* looks like the familiar Beta distribution.

To get the beta, we set $\alpha \triangleq n_0 x_0 + 1$ and $\beta \triangleq n_0 (1 - x_0) + 1$. Bringing in the resulting normalizer, we have

$$p(\pi | \alpha, \beta) = \frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha)\Gamma(\beta)} \pi^{\alpha-1} (1 - \pi)^{\beta-1}. \quad (64)$$

The posterior distribution follows the usual recipe, from which we can derive that

the corresponding updates are

$$\hat{\alpha} = \alpha + \sum_{i=1}^n x_i \quad (65)$$

$$\hat{\beta} = \beta + \sum_{i=1}^n (1 - x_i) \quad (66)$$

To see this, update \hat{x}_0 and \hat{n}_0 as above and compute $\hat{\alpha}$ and $\hat{\beta}$ from the definitions.

4.6 The big picture

Exponential families and conjugate priors can be used in many graphical models. Gibbs sampling is straightforward when each complete conditional involves a conjugate “prior” and likelihood pair.

For example, we can now define an exponential family mixture model. The mixture components are drawn from a conjugate prior; the data are drawn from the corresponding exponential family.

[graphical model]

In the mixture of Gaussians, the conditional distribution of the mixture locations was Gaussian. This was thanks to conjugacy. In general, we can imagine a mixture of multinomials (with Dirichlet priors), a mixture of Poissons (with Gamma priors), and so on.

Imagine a generic model $p(\mathbf{z}, \mathbf{x} | \alpha)$. Suppose each complete conditional is in the exponential family,

$$p(z_i | \mathbf{z}_{-i}, \mathbf{x}, \alpha) = h(z_i) \exp\{\eta_i(\mathbf{z}_{-i}, \mathbf{x})^\top z_i - a(\eta_i(\mathbf{z}_{-i}, \mathbf{x}))\}. \quad (67)$$

Notice the natural parameter is a function of the variables we condition on. This is called a *conditionally conjugate model*. Provided we can compute the natural parameter, Gibbs sampling is immediate.

Many models from the machine learning research literature are conditionally conjugate. Examples include hidden Markov models, Kalman filters, mixture models, hierarchical linear regression, probit regression, factorial models, and others.

Consider the HMM, for example, but with its parameters unknown,

[graphical model]

Notice that this is like a mixture model, but where the mixture components are embedded in a Markov chain.

Each row of the transition matrix is a point on the $(K - 1)$ -simplex; each set of emission probabilities is a point on the $(V - 1)$ -simplex. Place Dirichlet priors on these components. (We discuss the Dirichlet later. It is a multivariate generalization of the beta distribution, and is the conjugate prior to the categorical/multinomial distribution.)

We easily obtain the complete conditional of z_i . The complete conditionals of the transitions & emissions follow from our discussion of conjugacy.

References

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A The natural parameterization of the Gaussian

The familiar form of the univariate Gaussian is

$$p(x | \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left\{-\frac{(x - \mu)^2}{2\sigma^2}\right\} \quad (68)$$

We put it in exponential family form by expanding the square

$$p(x | \mu, \sigma^2) = \frac{1}{\sqrt{2\pi}} \exp\left\{\frac{\mu}{\sigma^2}x - \frac{1}{2\sigma^2}x^2 - \frac{1}{2\sigma^2}\mu^2 - \log \sigma\right\} \quad (69)$$

We see that

$$\eta = [\mu/\sigma^2, -1/2\sigma^2] \quad (70)$$

$$t(x) = [x, x^2] \quad (71)$$

$$a(\eta) = \mu^2/2\sigma^2 + \log \sigma \quad (72)$$

$$= -\eta_1^2/4\eta_2 - (1/2) \log(-2\eta_2) \quad (73)$$

$$h(x) = 1/\sqrt{2\pi} \quad (74)$$

B The unit-variance Gaussian and its canonical prior

Suppose the data x_i come from a unit variance Gaussian

$$p(x | \mu) = \frac{1}{\sqrt{2\pi}} \exp\{-(x - \mu)^2/2\}. \quad (75)$$

This is a simpler exponential family than the previous Gaussian

$$p(x | \mu) = \frac{\exp\{-x^2/2\}}{\sqrt{2\pi}} \exp\{\mu x - \mu^2/2\}. \quad (76)$$

In this case

$$\eta = \mu \quad (77)$$

$$t(x) = x \quad (78)$$

$$h(x) = \frac{\exp\{-x^2/2\}}{\sqrt{2\pi}} \quad (79)$$

$$a(\eta) = \mu^2/2 = \eta^2/2. \quad (80)$$

What is the conjugate prior? It is

$$p(\eta | \lambda) = h(\eta) \exp\{\lambda_1 \eta + \lambda_2(-\eta^2/2) - a_c(\lambda)\} \quad (81)$$

This has sufficient statistics $[\eta, -\eta^2/2]$, which means it's a *Gaussian distribution*.

Put it in canonical form,

$$p(\eta | n_0, x_0) = h(\eta) \exp\{n_0 x_0 \eta - n_0(\eta^2/2) - a_c(n_0, x_0)\}. \quad (82)$$

The posterior parameters are

$$\hat{x}_0 = \frac{n_0 x_0 + n \bar{x}}{n_0 + n} \quad (83)$$

$$\hat{n}_0 = n + n_0. \quad (84)$$

We now use the mapping from mean to natural parameters (Equation 70) to derive the posterior mean and variance. They are

$$\hat{\mu} = \hat{x}_0 \quad (85)$$

$$\hat{\sigma}^2 = 1/(n_0 + n). \quad (86)$$

These are results that we asserted earlier.

When we haven't seen any data then our estimate of the mean is the *prior mean*. As we see more data, our estimate of the mean moves towards the *sample mean*.

Before seeing data, our "confidence" about the estimate is the prior variance. As we see more data, the confidence decreases.