# Data Structures and Algorithms

**Session 20. April 8, 2009** 

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#### Announcements

- \* Homework 5 is out:
  - \* You can use adjacency lists if you prefer

#### Review

- \* Extensions of Dijkstra's Algorithm
  - \* Critical Path Analysis
  - \* All Pairs Shortest Path (Floyd-Warshall)
- **\*** Maximum Flow
  - \* Floyd-Fulkerson Algorithm

#### Today's Plan

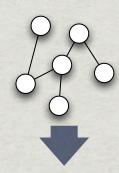
- \* Minimum Spanning Tree
  - \* Prim's Algorithm
  - \* Kruskal's Algorithm
- \* Depth first search
  - **\*** Euler Paths

# Minimum Spanning Tree Problem definition

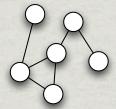
- \* Given connected graph G, find the connected, acyclic subgraph T with minimum edge weight
  - \* A tree that includes every node is called a spanning tree
- \* The method to find the MST is another example of a greedy algorithm

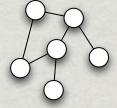
#### Motivation for Greed

\* Consider any spanning tree

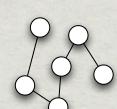


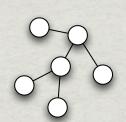
\* Adding another edge to the tree creates exactly one cycle





\* Removing an edge from that cycle restores the tree structure



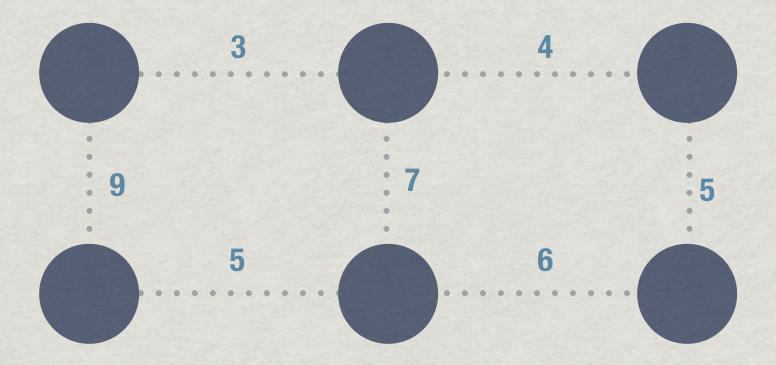


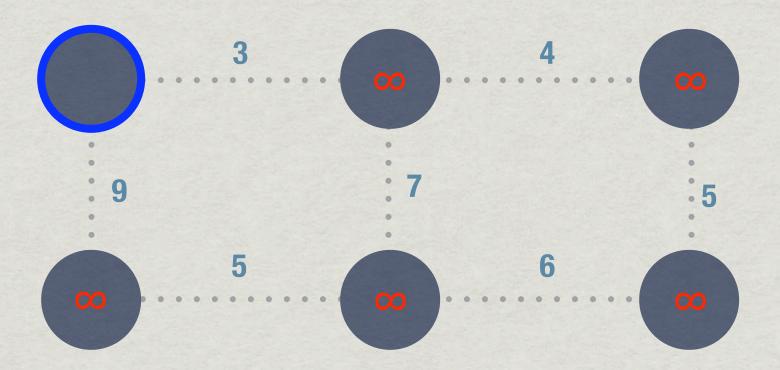
## Prim's Algorithm

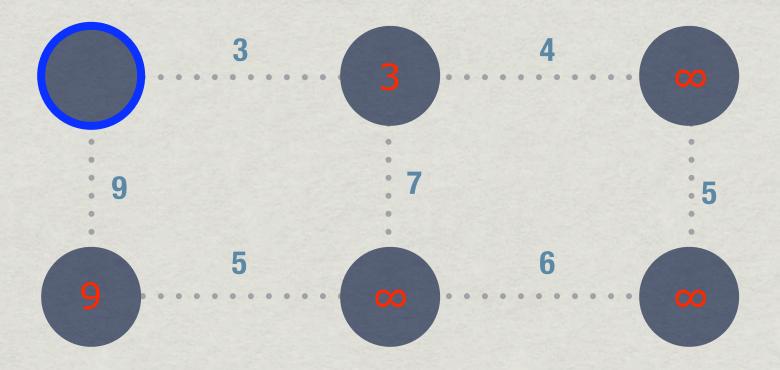
- \* Grow the tree like Dijkstra's Algorithm
- \* Dijkstra's: grow the set of vertices to which we know the shortest path
- \* Prim's: grow the set of vertices we have added to the minimum tree
- \* Store shortest edge D[] from each node to tree

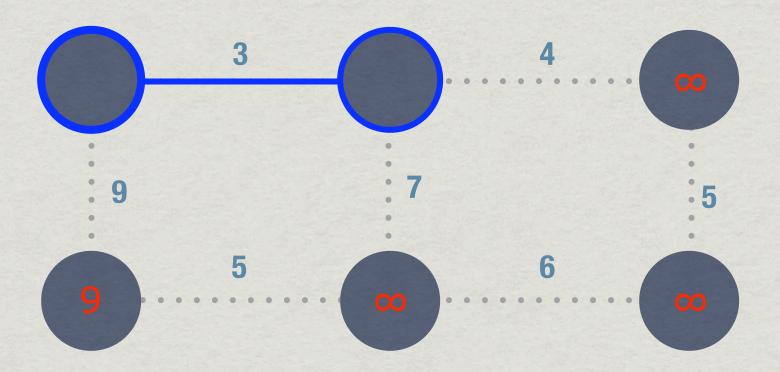
## Prim's Algorithm

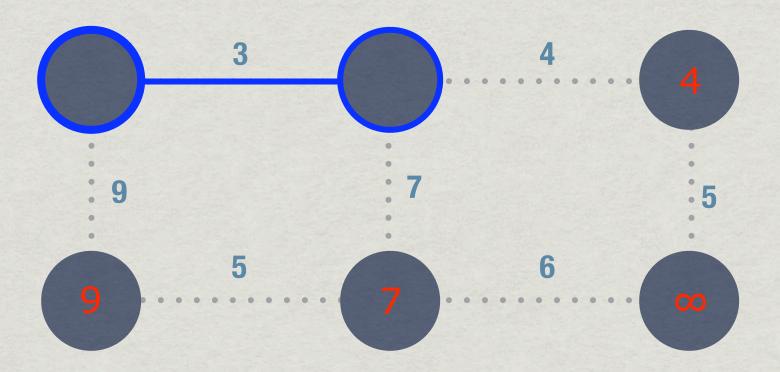
- \* Start with a single node tree, set distance of adjacent nodes to edge weights, infinite elsewhere
- \* Repeat until all nodes are in tree:
  - \* Add the node v with shortest known distance
  - # Update distances of adjacent nodes w: D[w] = min( D[w], weight(v,w))

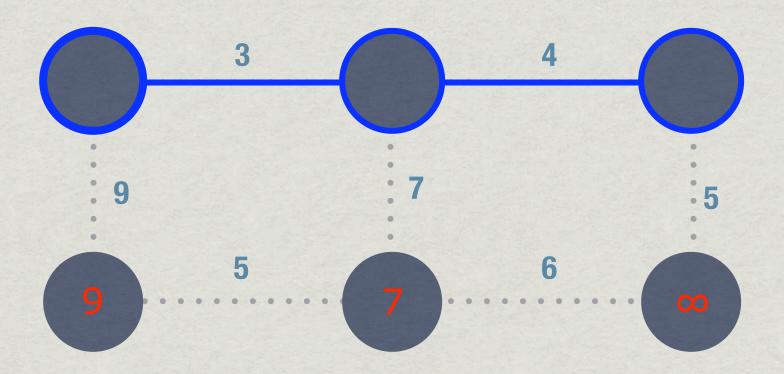


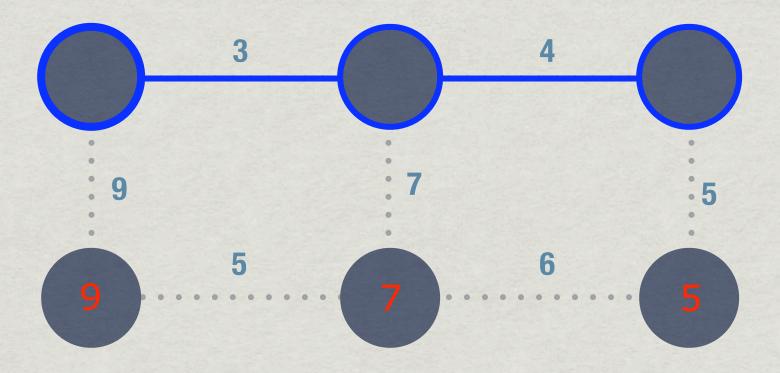


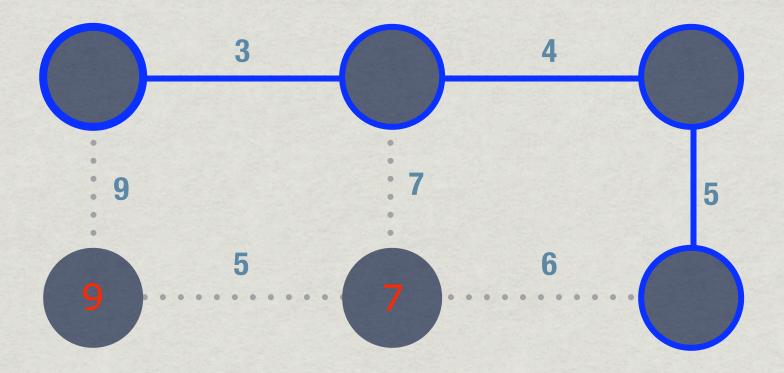


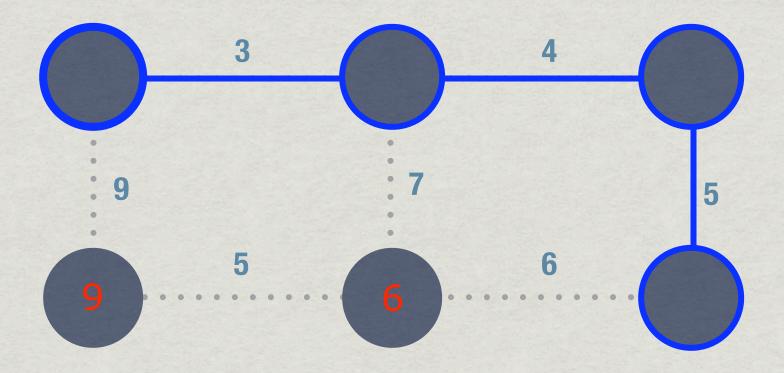


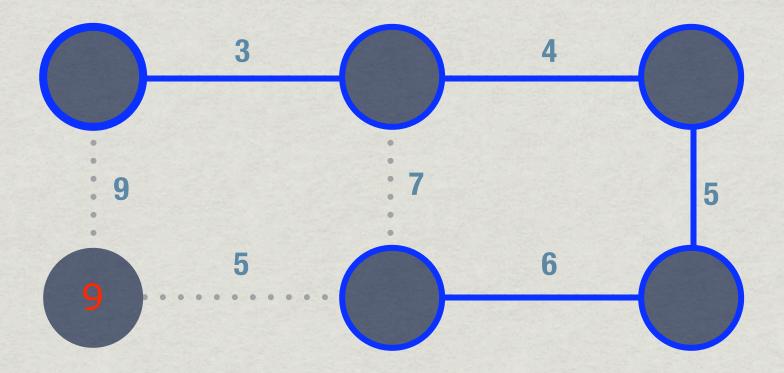


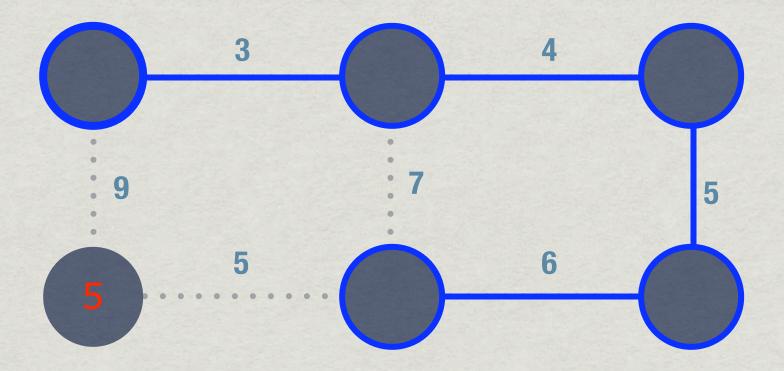


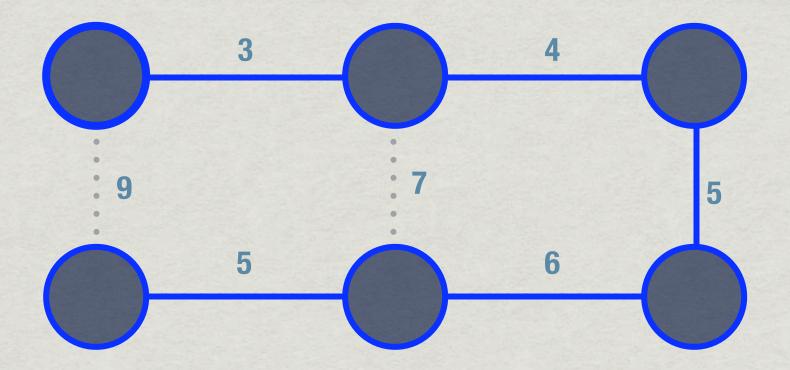












#### Implementation Details

- \* Store "previous node" like Dijkstra's Algorithm; backtrack to construct tree after completion
- \* Of course, use a priority queue to keep track of edge weights. Either
  - \* keep track of nodes inside heap & decreaseKey
  - \* or just add a new copy of the node when key decreases, and call deleteMin until you see a node not in the tree

# Prim's Algorithm Justification

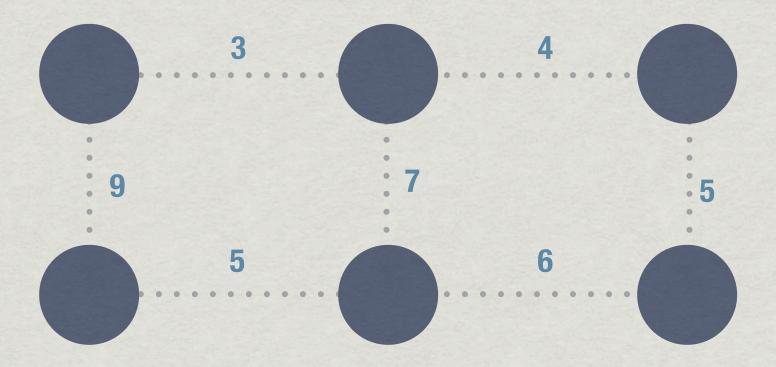
- \* At any point, we can consider the set of nodes in the tree **T** and the set outside the tree **Q**
- \* Whatever the MST structure of the nodes in **Q**, at least one edge must connect the MSTs of **T** and **Q**
- \* The greedy edge is just as good structurally as any other edge, and has minimum weight

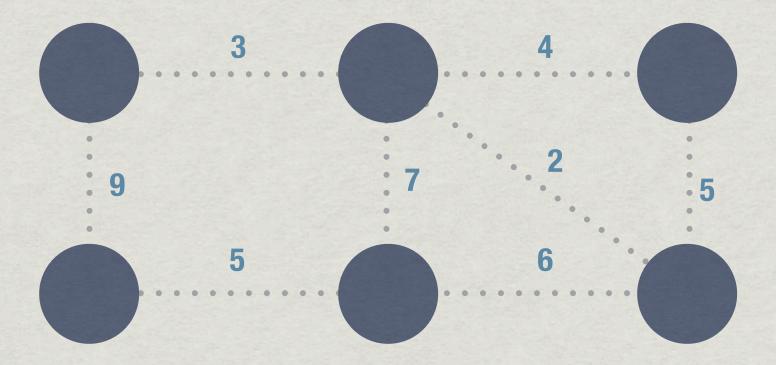
## Prim's Running Time

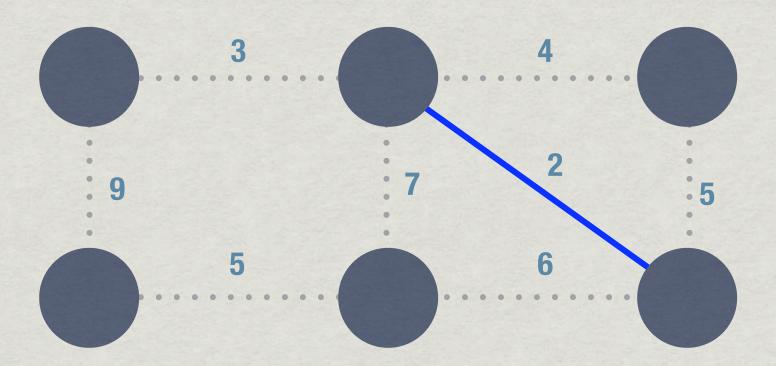
- \* Each stage requires one deleteMin O(log |V|), and there are exactly |V| stages
- \* We update keys for each edge, updating the key costs O(log |V|) (either an insert or a decreaseKey)
- \* Total time:  $O(|V| \log |V| + |E| \log |V|) = O(|E| \log |V|)$

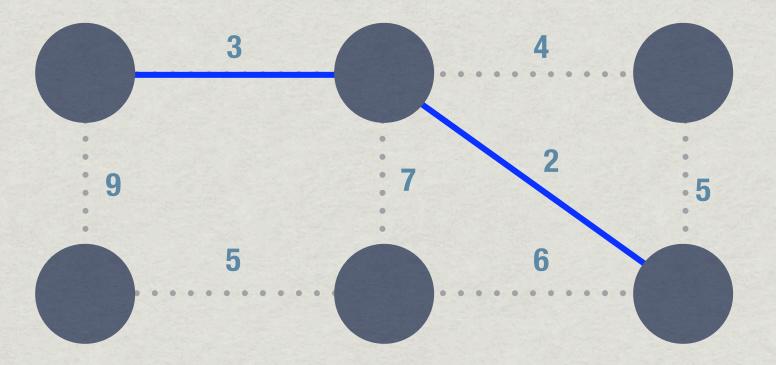
### Kruskal's Algorithm

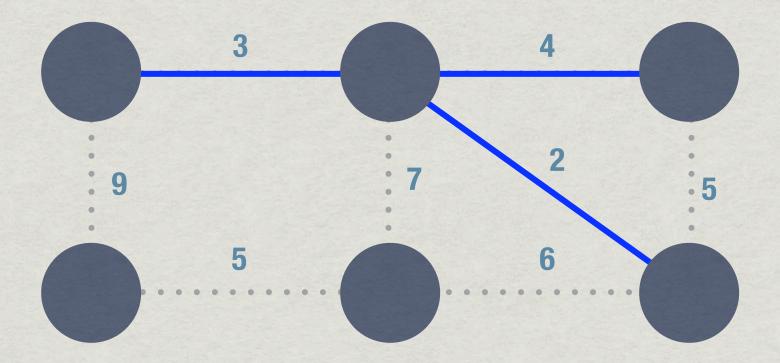
- \* Somewhat simpler conceptually, but more challenging to implement
- \* Algorithm: repeatedly add the shortest edge that does not cause a cycle until no such edges exist
- \* Each added edge performs a union on two trees; perform unions until there is only one tree
- \* Need special ADT for unions (Disjoint Set... we'll cover it later)

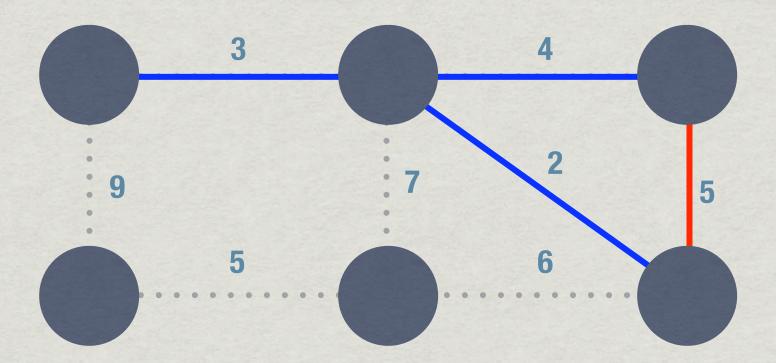


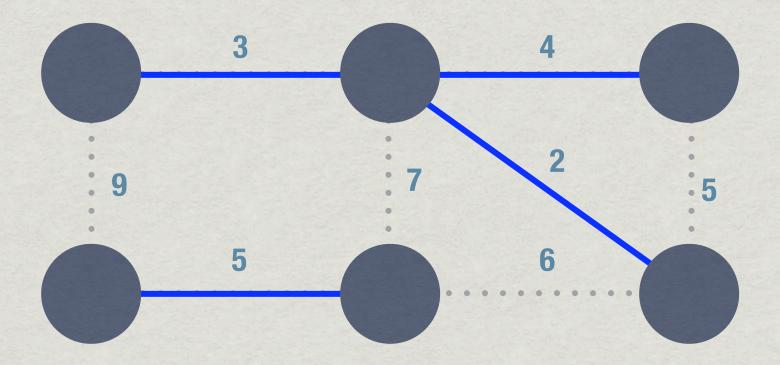


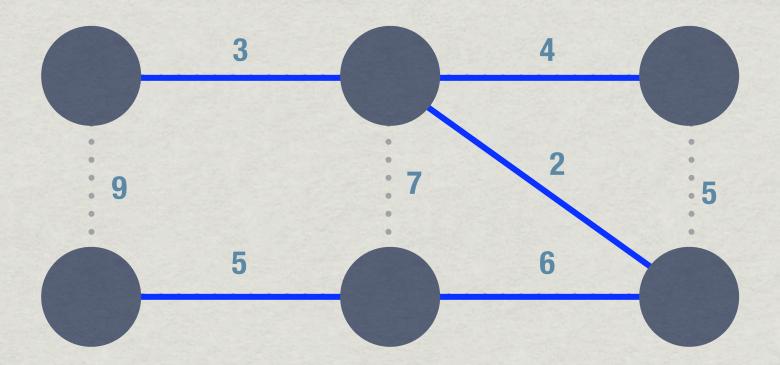












#### Kruskal's Justification

- \* At each stage, the greedy edge e connects two nodes v and w
- \* Eventually those two nodes must be connected;
  - \* we must add an edge to connect trees including v and w
- \* We can always use e to connect v and w, which must have less weight since it's the greedy choice

## Kruskal's Running Time

- \* First, buildHeap costs O(|E|)
- \* Each edge, need to check if it creates a cycle (costs O(log V))
- \* In the worst case, we have to call |E| deleteMins
- \*\* Total running time O(|E| log |E|); but  $|E| \le |V|^2$   $O(|E| \log |V|^2) = O(2|E| \log |V|) = O(|E| \log |V|)$

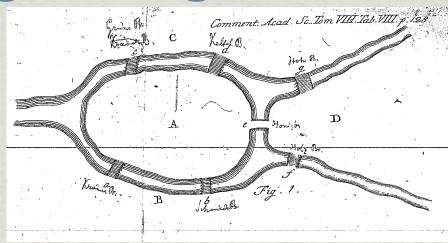
#### MST Wrapup

- \* Connect all nodes in graph using minimum weight tree
- \* Two greedy algorithms:
  - \* Prim's: similar to Dijkstra's. Easier to code
  - \* Kruskal's: easy on paper

#### Depth First Search

- \*\* Level-order <-> Breadth-first Search
  Preorder <-> Depth-first Search
- \* Visit vertex v, then recursively visit v's neighbors
- \* To avoid visiting nodes more than once in a cyclic graph, mark visited nodes,
- \* and only recurse on unmarked nodes

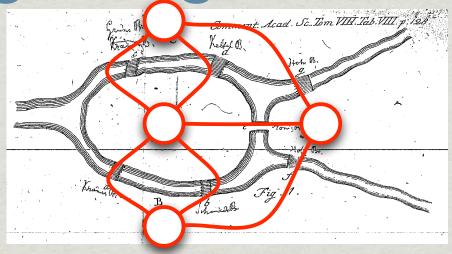
# The Seven Bridges of Königsberg



http://math.dartmouth.edu/~euler/docs/originals/E053.pdf

\* Königsburg Bridge Problem: can one walk across the seven bridges and never cross the same bridge twice?

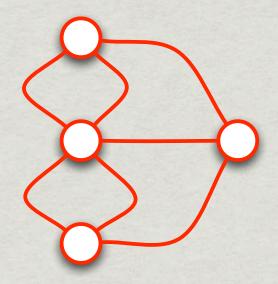
## The Seven Bridges of Königsberg



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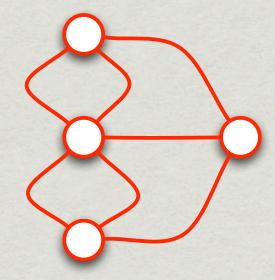
- \* Königsburg Bridge Problem: can one walk across the seven bridges and never cross the same bridge twice?
- \* Euler solved the problem by inventing graph theory

#### Euler Paths and Circuits



- \* Euler path a (possibly cyclic) path that crosses each edge exactly once
- \* Euler circuit an Euler path that starts and ends on the same node

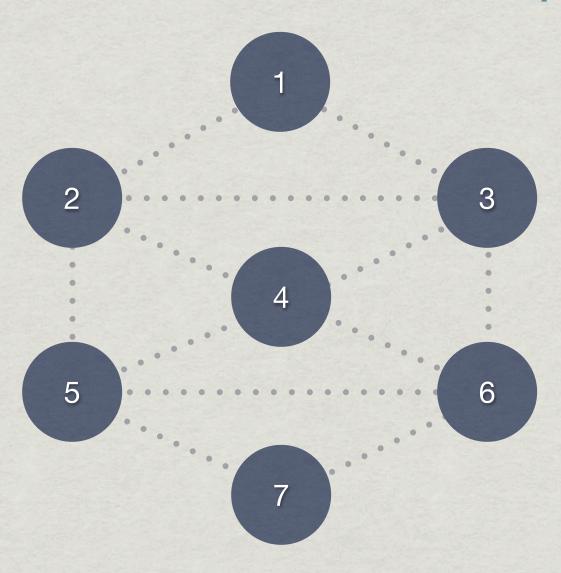
#### Euler's Proof

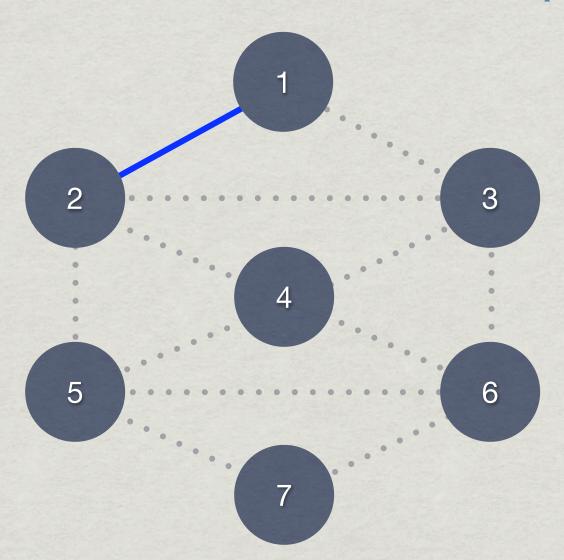


- \* Does an Euler path exist? No
- \* Nodes with an odd degree must either be the start or end of the path
- \* Only one node in the Königsberg graph has odd degree; the path cannot exist
- \* What about an Euler circuit?

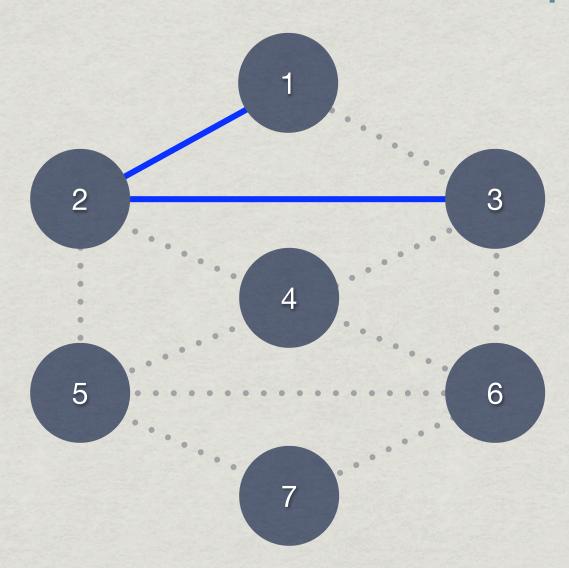
### Finding an Euler Circuit

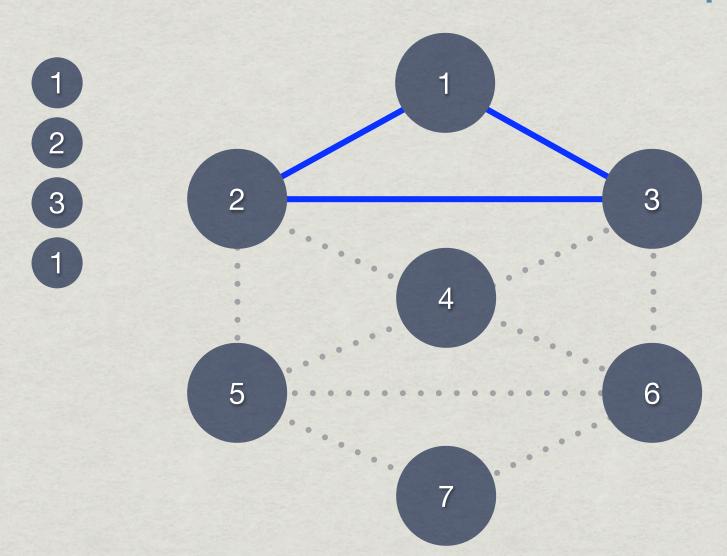
- \* Run a partial DFS; search down a path until you need to backtrack (mark edges instead of nodes)
- \* At this point, you will have found a circuit
- \* Find first node along the circuit that has unvisited edges; run a DFS starting with that edge
- \* Splice the new circuit into the main circuit, repeat until all edges are visited

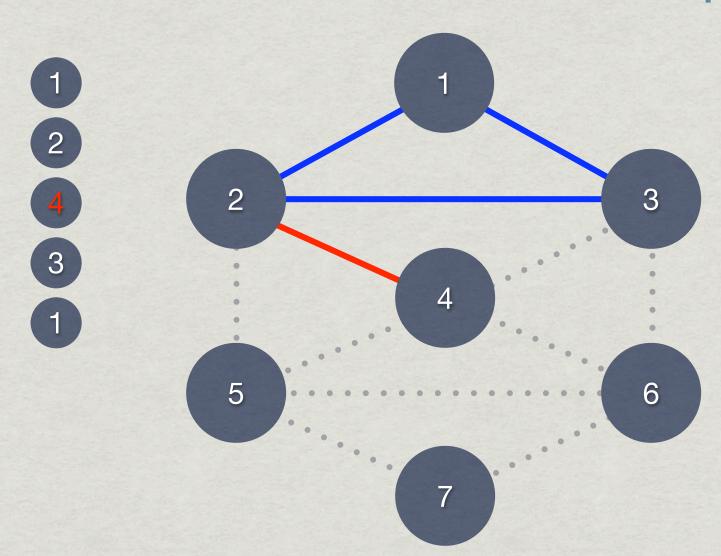


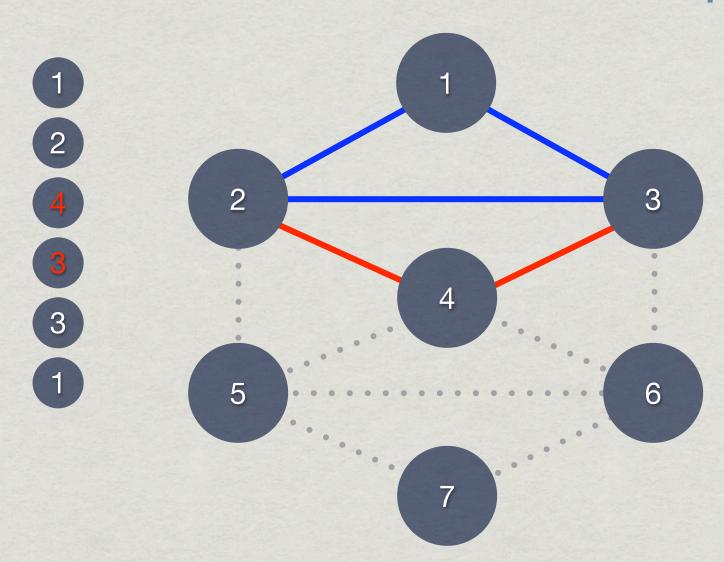




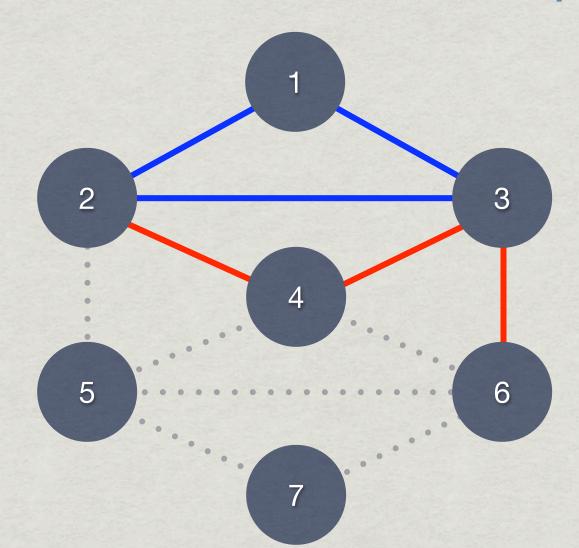




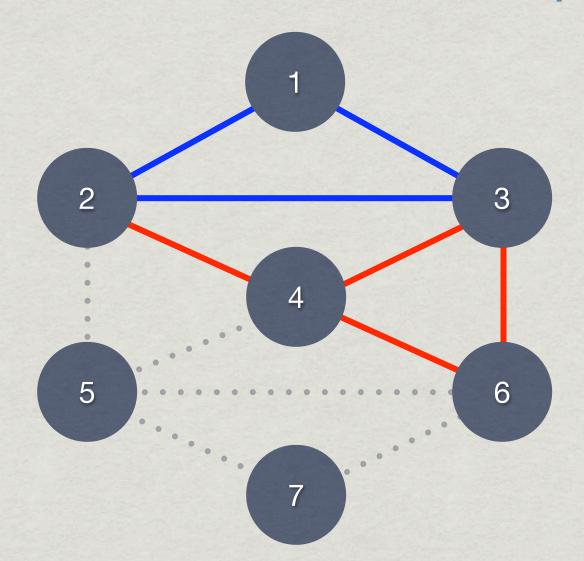




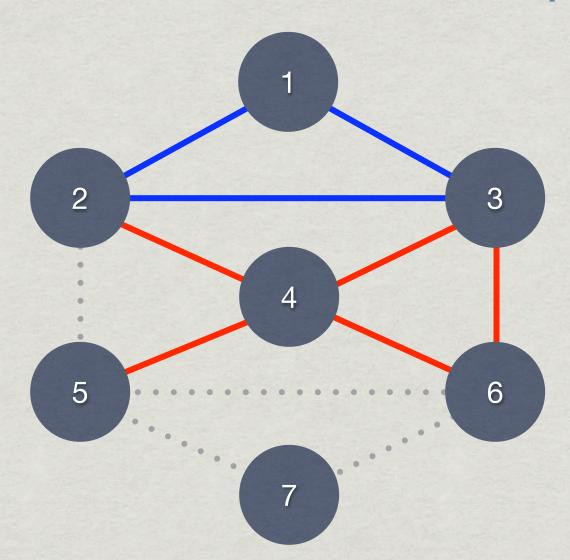


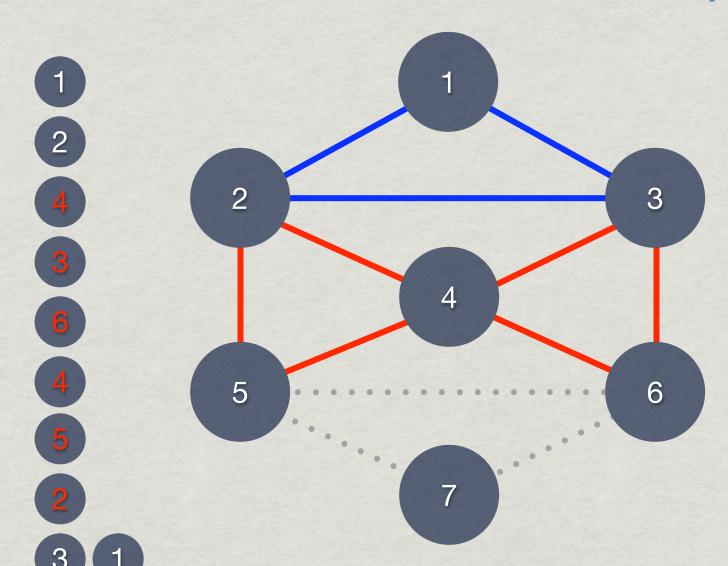


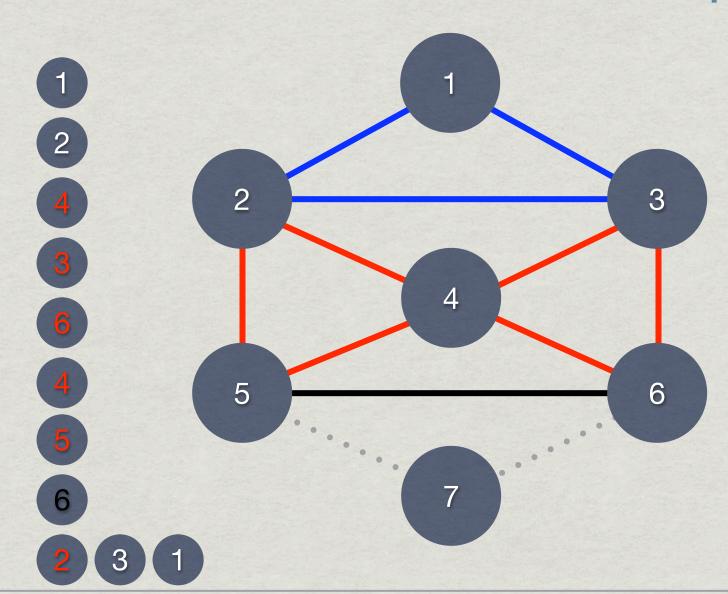


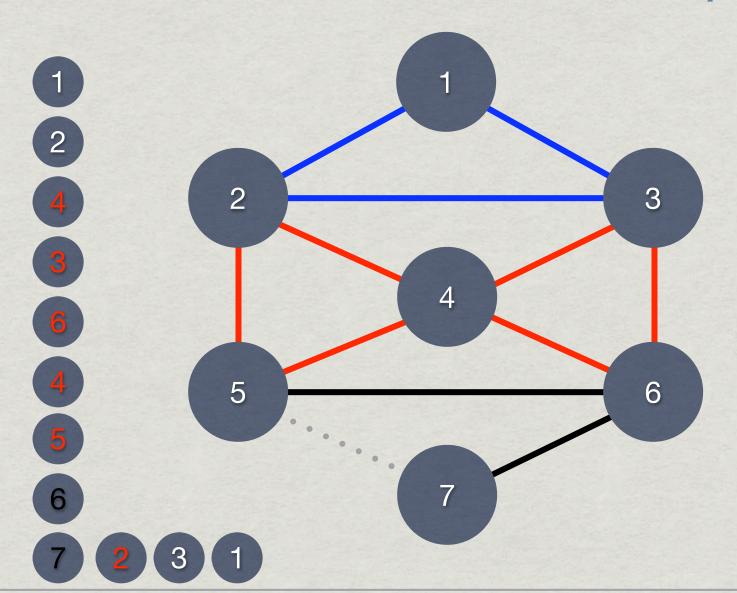


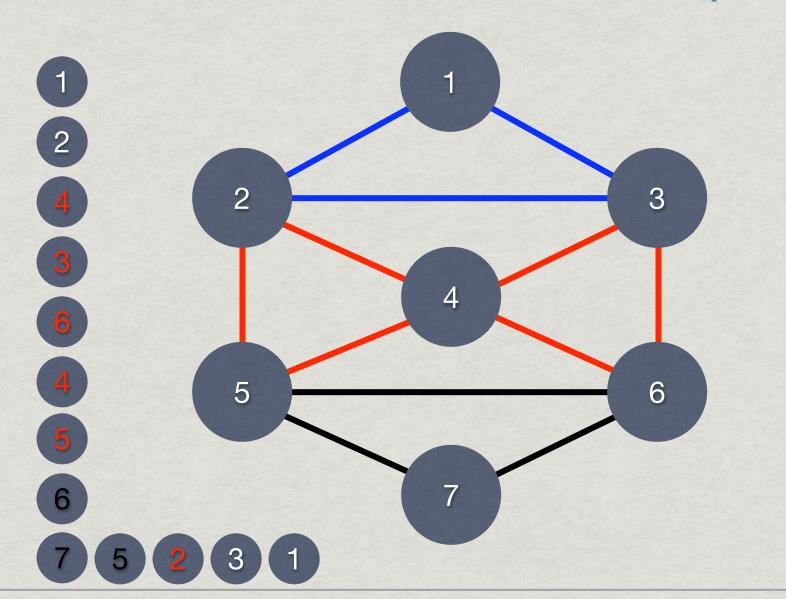












#### Euler Circuit Running Time

- \* All our DFS's will visit each edge once, so at least O(|E|)
- \* Must use a linked list for efficient splicing of path, so searching for a vertex with unused edge can be expensive
- \* but cleverly saving the last scanned edge in each adjacency list can prevent having to check edges more than once, so also O(|E|)

#### Hamiltonian Cycle

- \* Now that we know how to find Euler circuits efficiently, can we find Hamiltonian Cycles?
- \* Hamiltonian cycle path that visits each *node* once, starts and ends on same node

## Reading

- \* Weiss 9.5 (MST today's material)
- \* Weiss 9.6 (DFS today's material)
- \* Weiss 9.7 (P vs. NP Monday)