Data Structures and Algorithms

Session 16. March 25, 2009

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Announcements

- # Homework 4 up on website
- # Hw3 grades coming tomorrow
- * Thanks for feedback on midterm evaluations
- I have old hw's and midterms in my office; stop by after class or let's set up a time for pickup

Review

- Midterm Solutions
- * Huffman Coding Trees
 - * Create forest of all characters weighted by frequency
 - Merge least weight trees until 1 tree left
- # (Unfinished) proof sketch of optimality

Today's Plan

- * Finish Huffman optimality proof sketch
- # Hash Tables ADT
 - * Definition and Implementation

Huffman Details

- We can manage the forest with a priority queue:
- # buildHeap first,
 - * find the least weight trees with 2 deleteMins,
 - * after merging, insert back to heap.
- In practice, also have to store coding tree, but the payoff comes when we compress larger strings

- Induction: Suppose Huffman tree is optimal for N characters. What about N+1 characters?
 - * Lemma 1: Optimal tree is full
 - * Lemma 2: the 2 least frequent characters are at the deepest level in optimal tree
 - * Lemma 3: Swapping characters at same depth doesn't affect optimality

- Induction: Suppose Huffman tree is optimal for N characters. What about N+1 characters?
 - * Lemma 1: Optimal tree is full
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 - * Lemma 3: Swapping characters at same depth doesn't affect optimality
- * Lemma 4: An optimal tree exists where the least frequent characters are siblings at deepest level.

* number of bits of an encoding is $B(T) = \sum F_i D_i$

N+1

- * F is the frequency of the character, D is the depth in the tree (the number of bits)
- Create new tree T* by removing least frequent chars and replacing with a meta-character whose frequency is the frequency of both chars,

* meta-character is one level less deep

 $B(T) = B(T*) + F_1 + F_2$

* Proof by contradiction: Assume there is a different tree T' that is better than T

B(T') < B(T) $B(T'*) + F_1 + F_2 < B(T*) + F_1 + F_2$ B(T'*) < B(T*)

* That is a contradiction because T* has N characters, which means Huffman is optimal via our inductive hypothesis

- * Assuming falseness of inductive step produced contradiction to inductive hypothesis
- * Therefore, if Huffman codes are optimal for N characters, they are also for N+1 characters
- # Huffman is obviously optimal for 2 characters
- # Huffman codes are optimal

Hash Table ADT

*** Search tree:**

findMin, findMax, insert/delete, search

***** Priority Queue:

findMin (or max), insert/delete, no search

Hash Table:

insert/delete, search

Hash Table ADT

*** Search tree:**

Stores complete order information

*** Priority Queue:**

Stores incomplete order information

Hash Table:

Stores no order information

Hash Table ADT

- Insert or delete objects by key
- * Search for objects by key
- *** No** order information whatsoever

Ideally O(1) per operation

Implementation

- Suppose we have keys between 1 and K
- * Create an array with maxKey entries
- * Insert, delete, search are just array operations

1	2	3	4	5	6	 K-3	K-2	K-1	К
* (Obvio	usly t	00 eX	pens	ive	-	-	-	

Hash Functions

- * A hash function maps any key to a valid array position
 - * Array positions range from 0 to N-1
 - * Key range possibly unlimited



Hash Functions

- * For integer keys, (key mod N) is the simplest hash function
- In general, any function that maps from the space of keys to the space of array indices is valid
- * but a good hash function spreads the data out evenly in the array;
- * A good hash function avoids **collisions**

Collisions

* A collision is when two distinct keys map to the same array index

* e.g.,
$$h(x) = x \mod 5$$

 $h(7) = 2, h(12) = 2$

- * Choose h(x) to minimize collisions, but collisions are inevitable
- * To implement a hash table, we must decide on collision resolution policy

Collision Resolution

- * Two basic strategies
 - Strategy 1: Separate Chaining
 - Strategy 2: Probing; lots of variants

Strategy 1: Separate Chaining

* Keep a list at each array entry

* Insert(x): find h(x), add to list at h(x)

- Delete(x): find h(x), search list at h(x) for x, delete
- Search(x): find h(x), search list at h(x)
- We could use a BST or other ADT, but if h(x) is a good hash function, it won't be worth the overhead

Separate Chaining Average Case

- * Load Factor $\lambda = #$ objects / TableSize
 - * Average list length is λ
 - * Time to insert = constant, or constant + λ
 - * Time to search = constant + λ or constant + $\lambda/2$

Strategy 1: Advantages and Disadvantages

- # Advantages:
 - Simple idea
 - * Removals are clean *
- Disadvantages:
 - * Need 2nd data structure, which causes extra overhead if the hash function is good

Strategy 2: Probing

- # If h(x) is occupied, try h(x)+f(i) mod N
 for i = 1 until an empty slot is found
- Many ways to choose a good f(i)
- Simplest method: Linear Probing

⋇ f(i) = i



Primary Clustering

- If there are many collisions, blocks of occupied cells form: primary clustering
- * Any hash value inside the cluster adds to the end of that cluster
- * (a) it becomes more likely that the next hash value will collide with the cluster, and (b) collisions in the cluster get more expensive

Removals

* How do we delete when probing?

- * Lazy-deletion: mark as deleted,
 - * we can overwrite it if inserting,
 - * but we know to keep looking if searching.

Quadratic Probing

- ***** f(i) = i^2
- * Avoids primary clustering
- Sometimes will never find an empty slot even if table isn't full!
- * Luckily, if load factor $\lambda \leq \frac{1}{2}~$, guaranteed to find empty slot

Quadratic Probing Example

- **₩** N = 7
- $(x) = x \mod 7$
- * insert 9
- * insert 16
- * insert 2





9 10 2

Double Hashing

* If $h_1(x)$ is occupied, probe according to $f(i) = i \times h_2(x)$

* 2nd hash function must never map to 0

* Increments differently depending on the key



Reading

Homework 4

* Weiss Ch. 5