Loopy Belief Propagation for Bipartite Maximum Weight *b*-Matching

Bert Huang and Tony Jebara Computer Science Department Columbia University New York, NY 10027

Outline

- 1. Bipartite Weighted *b*-Matching
- 2. Edge Weights As a Distribution
- 3. Efficient Max-Product
- 4. Convergence Proof Sketch
- 5. Experiments
- 6. Discussion

Outline

- 1. Bipartite Weighted *b*-Matching
- 2. Edge Weights As a Distribution
- 3. Efficient Max-Product
- 4. Convergence Proof Sketch
- 5. Experiments
- 6. Discussion

On bipartite graph, G = (U, V, E) $\{u_1, \dots, u_n\} \in U$ $\{v_1, \dots, v_n\} \in V$ $E = (u_i, v_j), \forall i \forall j$



On bipartite graph, G = (U, V, E) $\{u_1, \dots, u_n\} \in U$ $\{v_1, \dots, v_n\} \in V$ $E = (u_i, v_j), \forall i \forall j$



A = weight matrix

s.t. weight of edge $(u_i, v_j) = A_{ij}$

Task: Find the maximum weight subset of E such that each vertex has exactly b neighbors.

Task: Find the maximum weight subset of E such that each vertex has exactly b neighbors.

Example:



Classical Application: Resource Allocation



- Team of *b* workers needed per task.
- - A_{ij} skill of worker at performing task.

Alternate uses of *b*-matching:

- Balanced *k*-nearest-neighbors

- Each node can only be picked *k* times.
- Robust to translations of test data.

- When test data is collected under different conditions (e.g. time, location, instrument calibration).

Classical algorithms solve Max-Weighted *b*-Matching in $O(bn^3)$ running time, such as:

- Blossom Algorithm (Edmonds 1965)
- Balanced Network Flow

(Fremuth-Paeger, Jungnickel 1999)

Outline

- 1. Bipartite Weighted *b*-Matching
- 2. Edge Weights As a Distribution
- 3. Efficient Max-Product
- 4. Convergence Proof Sketch
- 5. Experiments
- 6. Discussion

- Bayati, Shah, and Sharma (2005) formulated the 1-matching problem as a probability distribution.

- This work generalizes to arbitrary *b*.

Variables:

Each vertex "chooses" b neighbors.

Example: u_i



Variables:

Each vertex "chooses" b neighbors.

Variables:

Each vertex "chooses" b neighbors.

For vertex u_i , $X_i \subset V$, $|X_i| = b$ Similarly, for v_j have variable Y_j

Note: variables have $\binom{n}{b}$ possible settings.

Weights as probabilities:

Since we sum weights but multiply probabilities, exponentiate.

n

$$\phi(X_i) = \exp\left(\frac{1}{2}\sum_{v_j \in X_i} A_{ij}\right)$$
$$\phi(Y_j) = \exp\left(\frac{1}{2}\sum_{u_i \in Y_j} A_{ij}\right)$$

Enforce *b*-matching:

Neighbor "choices" must agree

Example: Invalid settings



Enforce *b*-matching:

Neighbor "choices" must agree

Enforce *b*-matching:

Neighbor "choices" must agree

Pairwise compatibility function:

$$\psi(X_i, Y_j) = \bigcap_{\substack{n \\ b \\ i \in \mathbb{N}}} = \neg (v_j \in X_i \oplus u_i \in Y_j).$$

$$P(X,Y) = \frac{1}{Z} \prod_{i,j=1}^{n} \psi(X_i, Y_j) \prod_{k=1}^{n} \phi(X_k) \phi(Y_j)$$

$$\phi(X_i) = \exp(\frac{1}{2} \sum_{v_j \in X_i} A_{ij}) \qquad \phi(Y_j) = \exp(\frac{1}{2} \sum_{u_i \in Y_j} A_{ij})$$
$$\psi(X_i, Y_j) = \neg(v_j \in X_i \oplus u_i \in Y_j).$$

$$P(X,Y) = \bigwedge_{i,j=1}^{n} \psi(X_i,Y_j) \prod_{k=1}^{n} \phi(X_k)\phi(Y_j)$$

$$\phi(X_i) = \exp(\frac{1}{2} \sum_{v_j \in X_i} A_{ij}) \qquad \phi(Y_j) = \exp(\frac{1}{2} \sum_{u_i \in Y_j} A_{ij})$$
$$\psi(X_i, Y_j) = \neg(v_j \in X_i \oplus u_i \in Y_j).$$

Ignore the *Z* normalization, P(X,Y) is exactly the exponentiated weight of the *b*-matching.

$$P(X,Y) = \bigwedge_{i,j=1}^{n} \psi(X_i,Y_j) \prod_{k=1}^{n} \phi(X_k)\phi(Y_j)$$

$$\phi(X_i) = \exp(\sum_{v_j \in X_i}^{1} A_{ij}) \qquad \phi(Y_j) = \exp(\sum_{u_i \in Y_j}^{1} A_{ij})$$
$$\psi(X_i, Y_j) = \neg(v_j \in X_i \oplus u_i \in Y_j).$$

Also, since we're maximizing, ignore the 1/2 (makes the math more readable).

Outline

- 1. Bipartite Weighted *b*-Matching
- 2. Edge Weights As a Distribution
- 3. Efficient Max-Product
- 4. Convergence Proof Sketch
- 5. Experiments
- 6. Discussion

Standard Max-Product

Send messages between variables:

$$m_{X_i}(Y_j) = \frac{1}{Z} \max_{X_i} \left[\phi(X_i) \psi(X_i, Y_j) \prod_{k \neq j} m_{Y_k}(X_i) \right]$$

Fuse messages to obtain beliefs (or estimate of max-marginals):

$$b(X_i) = \frac{1}{Z}\phi(X_i)\prod_k m_{Y_k}(X_i)$$

Standard Max-Product

Converges to true maximum on any tree structured graph (Pearl 1986).

We show that it converges to the correct maximum on our graph.

Standard Max-Product

Converges to true maximum on any tree structured graph (Pearl 1986).

We show that it converges to the correct maximum on our graph.

But what about the $\binom{n}{b}$ -length message and belief vectors?

- Use algebraic tricks to reduce $\binom{n}{b}$ -length message vectors to scalars.

- Derive new update rule for scalar messages.
- Use similar trick to maximize belief vectors efficiently.

Let's speed through the math.

Take advantage of binary $\psi(x_i, y_j)$ function: Message vectors consist of only two values

$$m_{x_i}(y_j) \propto \max_{v_j \in x_i} \phi(x_i) \prod_{k \neq j} m_{y_k}(x_i), \text{ if } u_i \in y_j$$
$$m_{x_i}(y_j) \propto \max_{v_j \notin x_i} \phi(x_i) \prod_{k \neq j} m_{y_k}(x_i), \text{ if } u_i \notin y_j$$

Take advantage of binary $\psi(x_i, y_j)$ function: Message vectors consist of only two values

$$m_{x_i}(y_j) \propto \max_{v_j \in x_i} \phi(x_i) \prod_{k \neq j} m_{y_k}(x_i), \text{ if } u_i \in y_j$$
$$m_{x_i}(y_j) \propto \max_{v_j \notin x_i} \phi(x_i) \prod_{k \neq j} m_{y_k}(x_i), \text{ if } u_i \notin y_j$$

If we rename these two values we can break up the product.

Take advantage of binary $\psi(x_i, y_j)$ function: Message vectors consist of only two values

$$\mu_{x_i y_j} \propto \max_{v_j \in x_i} \phi(x_i) \prod_{u_k \in x_i \setminus v_j} \mu_{ki} \prod_{u_k \notin x_i \setminus v_j} \nu_{ki}$$
$$\nu_{x_i y_j} \propto \max_{v_j \notin x_i} \phi(x_i) \prod_{u_k \in x_i \setminus v_j} \mu_{ki} \prod_{u_k \notin x_i \setminus v_j} \nu_{ki}.$$

If we rename these two values we can break up the product.

"Normalize" messages by dividing whole vector by $\nu_{x_i y_j}$

$$\hat{\mu}_{x_i y_j} = \frac{\mu_{x_i y_j}}{\nu_{x_i y_j}}$$
 and $\hat{\nu}_{x_i y_j} = 1$

"Normalize" messages by dividing whole vector by $\nu_{x_i y_j}$

$$\hat{\mu}_{x_i y_j} = \frac{\mu_{x_i y_j}}{\nu_{x_i y_j}}$$
 and $\hat{\nu}_{x_i y_j} = 1$



$$\hat{\mu}_{x_i y_j} = \frac{\max_{j \in x_i} \phi(x_i) \prod_{k \in x_i \setminus j} \hat{\mu}_{ki}}{\max_{j \notin x_i} \phi(x_i) \prod_{k \in x_i \setminus j} \hat{\mu}_{ki}}$$



$$\hat{\mu}_{x_i y_j} = \frac{\max_{j \in x_i} \phi(x_i) \prod_{k \in x_i \setminus j} \hat{\mu}_{ki}}{\max_{j \notin x_i} \phi(x_i) \prod_{k \in x_i \setminus j} \hat{\mu}_{ki}} \\ = \frac{\max_{j \in x_i} \prod_{k \in x_i} \exp(A_{ik}) \prod_{k \in x_i \setminus j} \hat{\mu}_{ki}}{\max_{j \notin x_i} \prod_{k \in x_i} \exp(A_{ik}) \prod_{k \in x_i \setminus j} \hat{\mu}_{ki}}}$$

$$\hat{\mu}_{x_i y_j} = \frac{\max_{j \in x_i} \phi(x_i) \prod_{k \in x_i \setminus j} \hat{\mu}_{ki}}{\max_{j \notin x_i} \phi(x_i) \prod_{k \in x_i \setminus j} \hat{\mu}_{ki}}$$

$$= \frac{\max_{j \in x_i} \prod_{k \in x_i} \exp(A_{ik}) \prod_{k \in x_i \setminus j} \hat{\mu}_{ki}}{\max_{j \notin x_i} \prod_{k \in x_i} \exp(A_{ik}) \prod_{k \in x_i \setminus j} \hat{\mu}_{ki}}$$

$$= \frac{\exp(A_{ij}) \max_{j \in x_i} \prod_{k \in x_i} \exp(A_{ij}) \hat{\mu}_{ki}}{\max_{j \notin x_i} \prod_{k \in x_i} \exp(A_{ij}) \hat{\mu}_{ki}}$$

After canceling terms message update simplifies to

$$\hat{\mu}_{x_i y_j} = \frac{\exp(A_{ij})}{\exp(A_{i\ell})\hat{\mu}_{y_\ell x_i}}. \quad \ell = \begin{cases} \text{of } k \text{ for the term} \\ \exp(A_{ik})m_{y_k}(x_i), \text{ s. t. } k \neq j \end{cases}$$

and we maximize beliefs with

$$\max_{x_i} b(x_i) \propto \max_{x_i} \phi(x_i) \prod_{k \in x_i} \hat{\mu}_{y_k x_i}$$
$$\propto \max_{x_i} \prod_{k \in x_i} \exp(A_{ik}) \hat{\mu}_{y_k x_i}$$

Both these updates take O(bn) time per vertex.

Outline

- 1. Bipartite Weighted *b*-Matching
- 2. Edge Weights As a Distribution
- 3. Efficient Max-Product
- 4. Convergence Proof Sketch
- 5. Experiments
- 6. Discussion

Assumptions:

- Optimal *b*-matching is unique.
- ϵ = difference between weight of best and 2nd best *b*-matching is constant.
- Weights treated as constants.

- 1. Pick root node
- 2. Copy all neighbors
- 3. Continue but don't backtrack
- 4. Continue to depth d



 u_1

- 1. Pick root node
- 2. Copy all neighbors
- 3. Continue but don't backtrack
- 4. Continue to depth d



- 1. Pick root node
- 2. Copy all neighbors
- 3. Continue but don't backtrack
- 4. Continue to depth d





- 1. Pick root node
- 2. Copy all neighbors
- 3. Continue but don't backtrack
- 4. Continue to depth d





 u_1

 $v_2 v_3 v_4 v_2 v_3 v_4 v_2 v_3 v_4 v_1 v_3 v_4 v_1 v_3 v_4 v_1 v_3 v_4 v_1 v_2 v_4 v_1 v_2 v_4 v_1 v_2 v_4 v_1 v_2 v_3 v_1$

 u_2

 u_4

 v_3

 u_3

 v_2

 u_3

Basic mechanism: Unwrapped Graph, T

1. Pick root node

 v_1

 u_3

 u_2

- 2. Copy all neighbors
- 3. Continue but don't backtrack

 u_2

4. Continue to depth d

 u_4



 u_4

 u_2

 v_4

 u_3

 u_4

Basic mechanism: Unwrapped Graph, T

- Construction follows loopy BP messages in reverse.

- True max-marginals of root node are exactly belief at iteration *d*.

- Max of unwrapped graph distribution is the maximum weight *b*-matching on tree.

Proof by contradiction:

What happens if optimal *b*-matching on *T* differs from optimal *b*-matching on *G* at root?



There exists at least one path on *T* that alternates between edges that are *b*-matched in each *b*-matching.



There exists at least one path on *T* that alternates between edges that are *b*-matched in each *b*-matching.



Claim: If depth *d* is great enough, if we replace the blue edges of this path with the red edges in the optimal *b*-matching on *T*, we get a new *b*-matching with greater weight.



Claim: If depth *d* is great enough, if we replace the blue edges of this path with the red edges in the optimal *b*-matching on *T*, we get a new *b*-matching with greater weight.



Claim: If depth *d* is great enough, if we replace the blue edges of this path with the red edges in the optimal *b*-matching on *T*, we get a new *b*-matching with greater weight.





We can analyze the change in weight by looking only at edges on path.

 v_4 v_1 v_3 v_2 u_3 ` u_3 ` u_4 u_3 u_4 u_4 u_4 u_3 u_2 u_2 u_2 u_2 $v_3 v_4 v_2 v_3 v_4 \overline{v_2} v_3 v_4 v_1 v_3 v_4 v_1 v_3 v_4 v_1 v_3 v_4 v_1 v_2 \overline{v_4} v_1 v_2 v_4 v_1 v_2 v_4 v_1 v_2 v_3 v_$

 u_1

Loopy BP converges to true maximum weight *b*-matching in *d* iterations

$$d \ge \frac{n}{\epsilon} \max_{i,j} A_{ij} = O(n)$$

 $\epsilon =$ difference between weight of best and 2nd best *b*-matching.

Loopy BP converges to true maximum weight *b*-matching in *d* iterations

$$d \ge \frac{n}{\epsilon} \max_{i,j} A_{ij} = O(n)$$

 $\epsilon =$ difference between weight of best and 2nd best *b*-matching.

Running time of full algorithm: $O(bn^3)$

Outline

- 1. Bipartite Weighted *b*-Matching
- 2. Edge Weights As a Distribution
- 3. Efficient Max-Product
- 4. Convergence Proof Sketch
- 5. Experiments
- 6. Discussion

Experiments

Running time comparison against GOBLIN graph optimization library.

- Random weights.
- Varied graph size *n* from 3 to 100
- Varied *b* from 1 to $\lfloor n/2 \rfloor$

Experiments



Experiments: Translated Test Data

On toy data, translation cripples KNN but *b*-matching makes no classification errors.



Experiments

MNIST Digits with pseudo-translation

- Image data with background changes is like translation.

- Train on MNIST digits 3, 5, and 8.



- Test on new examples with various "bluescreen" textures.



Outline

- 1. Bipartite Weighted *b*-Matching
- 2. Edge Weights As a Distribution
- 3. Efficient Max-Product
- 4. Convergence Proof Sketch
- 5. Experiments
- 6. Discussion

Discussion

Provably convergent belief propagation for a new type of graph (*b*-matchings).

- + Empirically faster than previous algorithms.
- + Parallelizeable
- Only bipartite case.
- Requires unique maximum.

Interesting theoretical results coming out of sum-product for approximating marginals.