



Data Structures in Java

Lecture 16: Introduction to Graphs.

11/16/2015

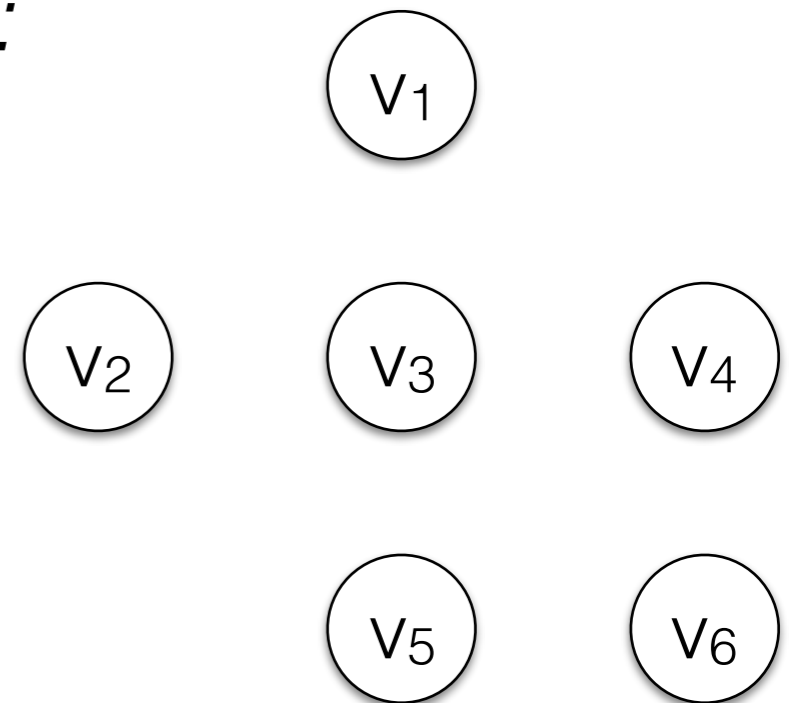
Daniel Bauer

Graphs

- A **Graph** is a pair of two sets $G=(V,E)$:
 - V : the set of **vertices** (or **nodes**)
 - E : the set of **edges**.
 - each edge is a pair (v,w) where $v,w \in V$

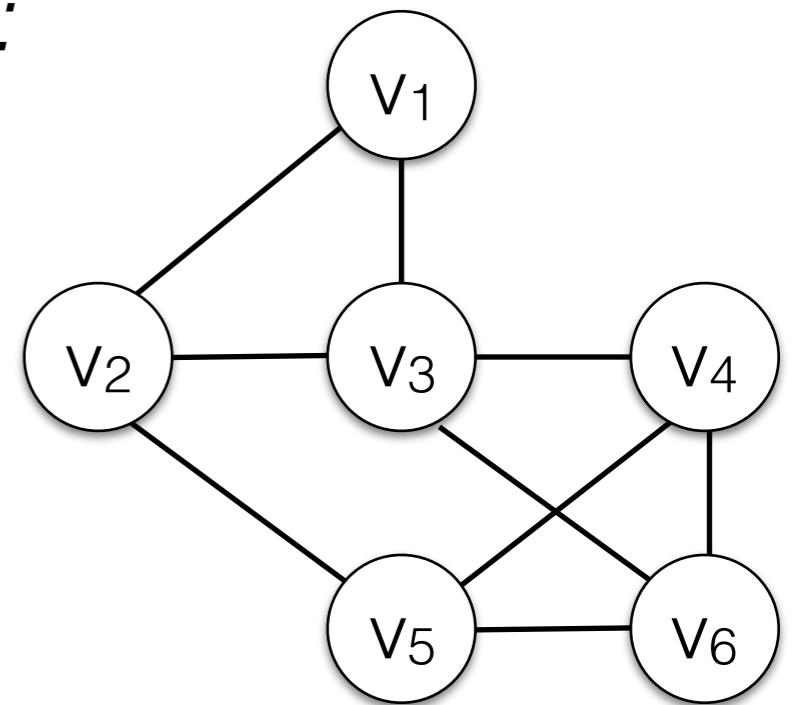
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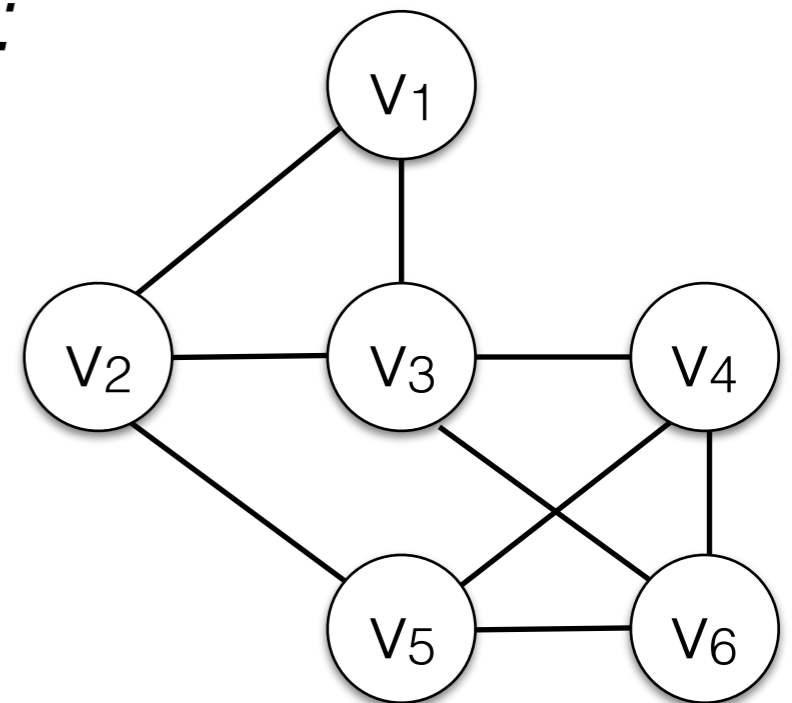
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$$V = \{V_1, V_2, V_3, V_4, V_5, V_6\}$$

$$E = \{(V_1, V_2), (V_1, V_3), (V_2, V_3), (V_2, V_5), (V_3, V_4), (V_3, V_6), (V_4, V_5), (V_4, V_6), (V_5, V_6)\}$$

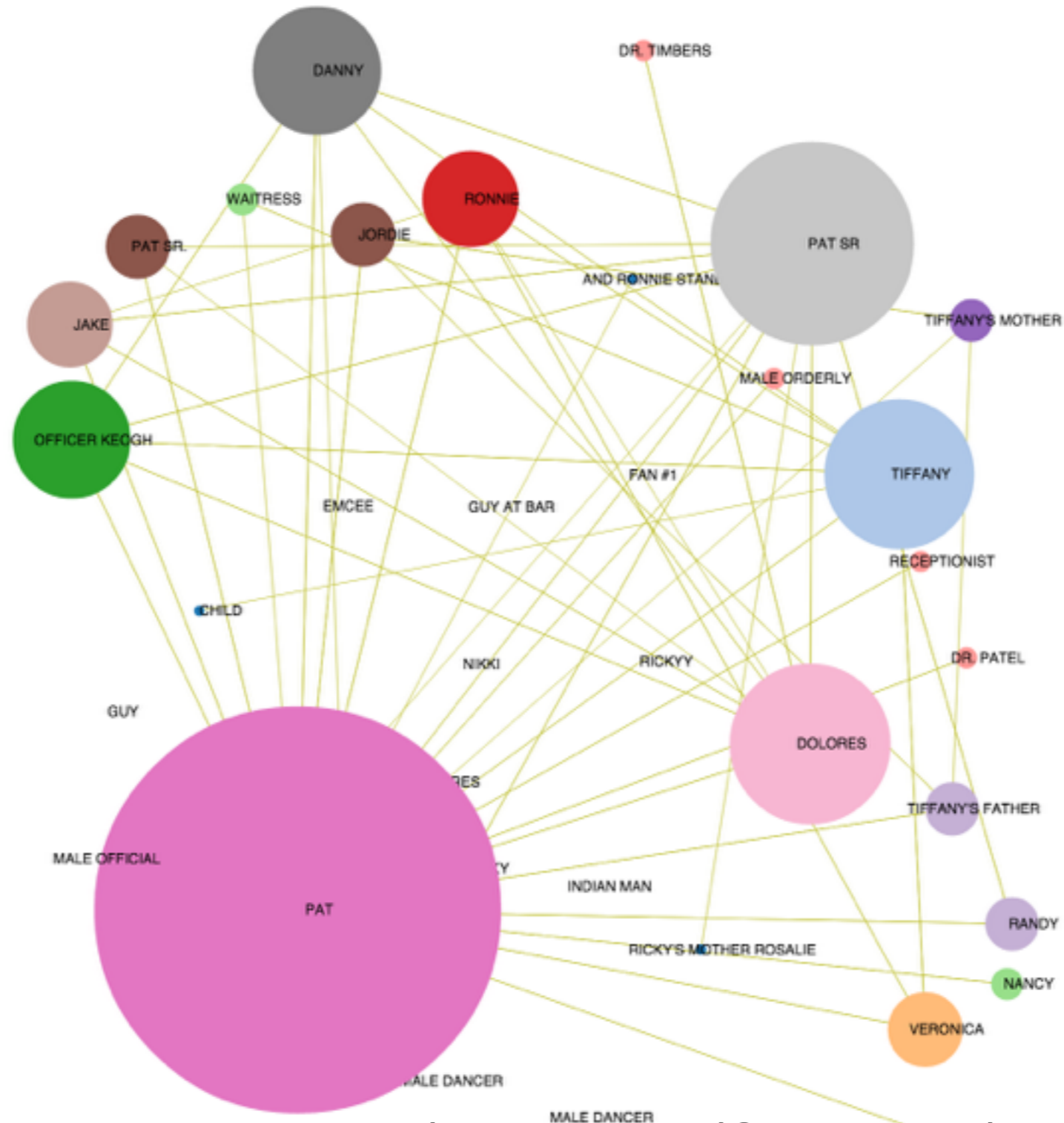
Graphs in Computer Science

- Graphs are used to model all kinds of relational data.
- General purpose algorithms make it possible to solve problems on these models.
- Shortest Paths, Spanning Tree, Finding Cliques, Strongly Connected Components, Network Flow, Graph Coloring, Minimum Edge/Vertex Cover, Graph Partitioning, ...

Social Networks



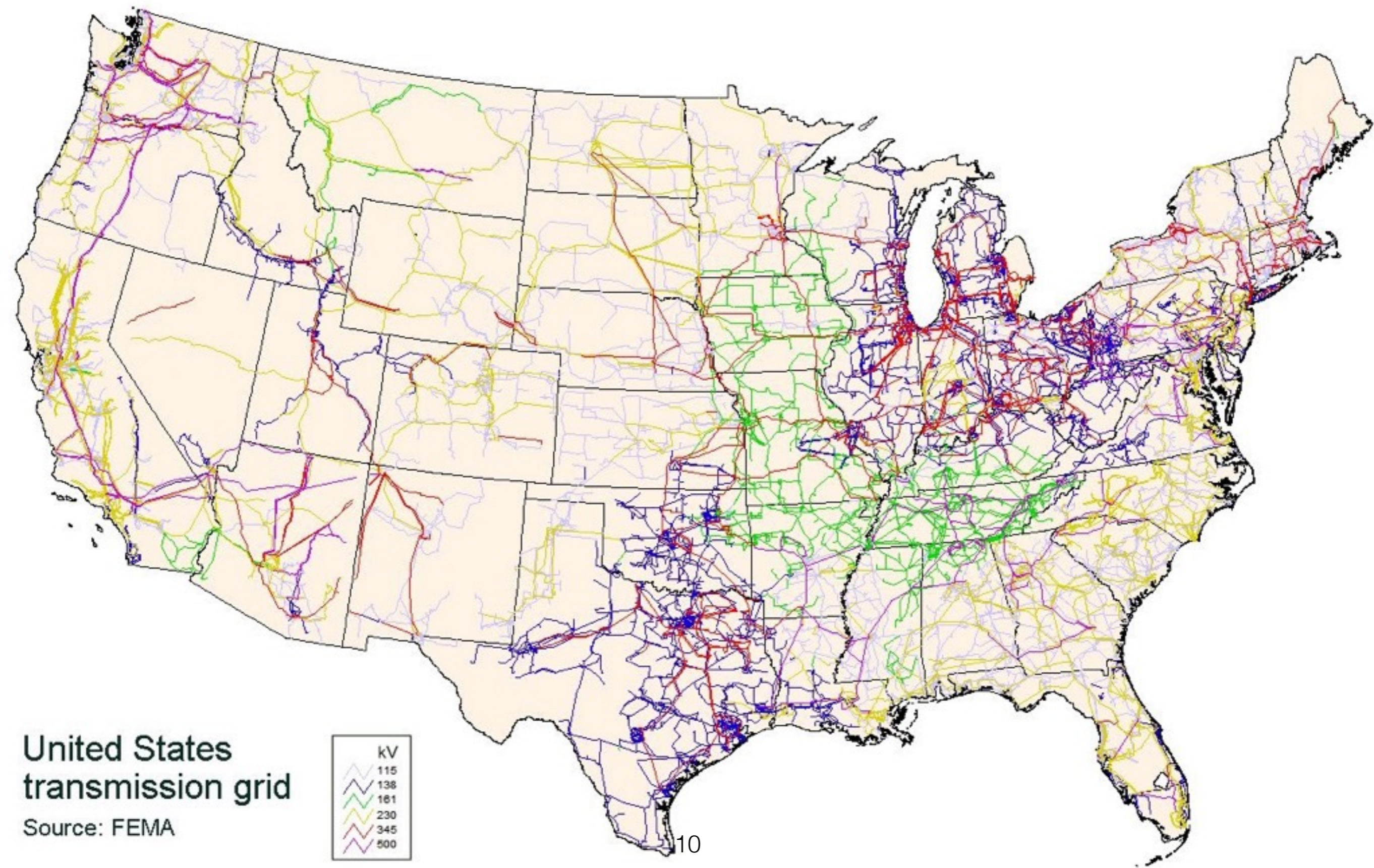
Interaction Networks Extracted from Text



Rail Network

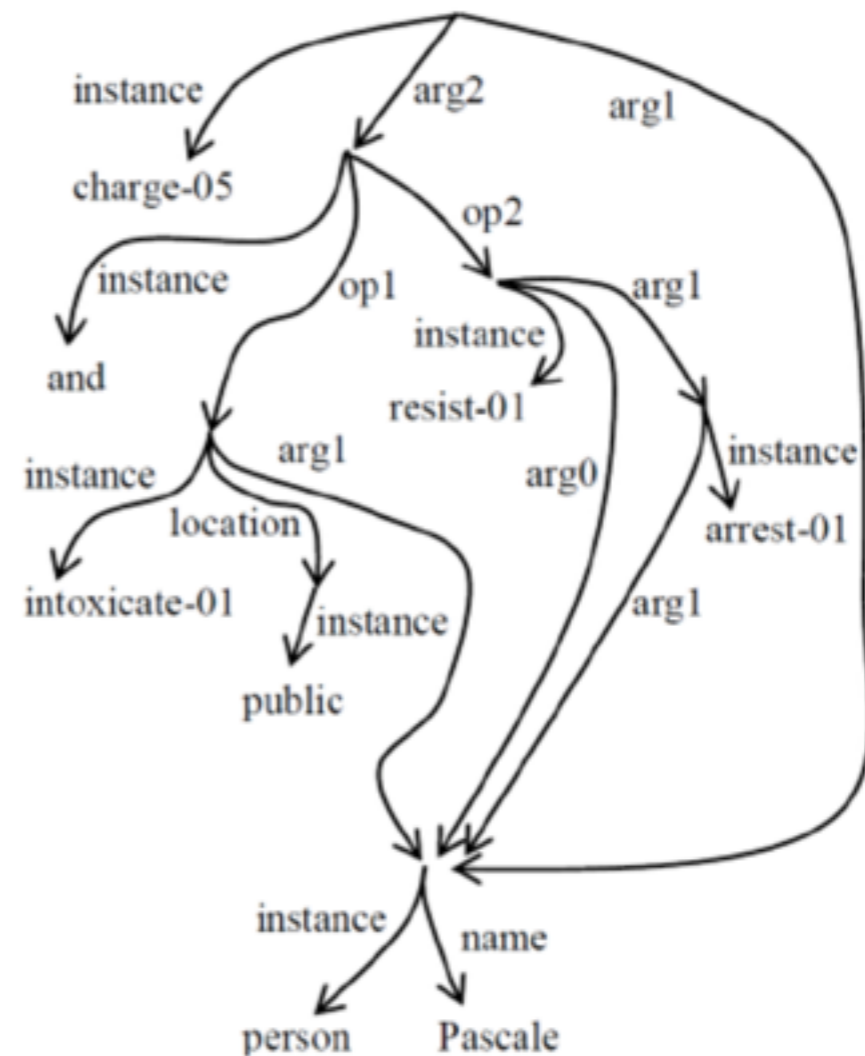


US Power Grid

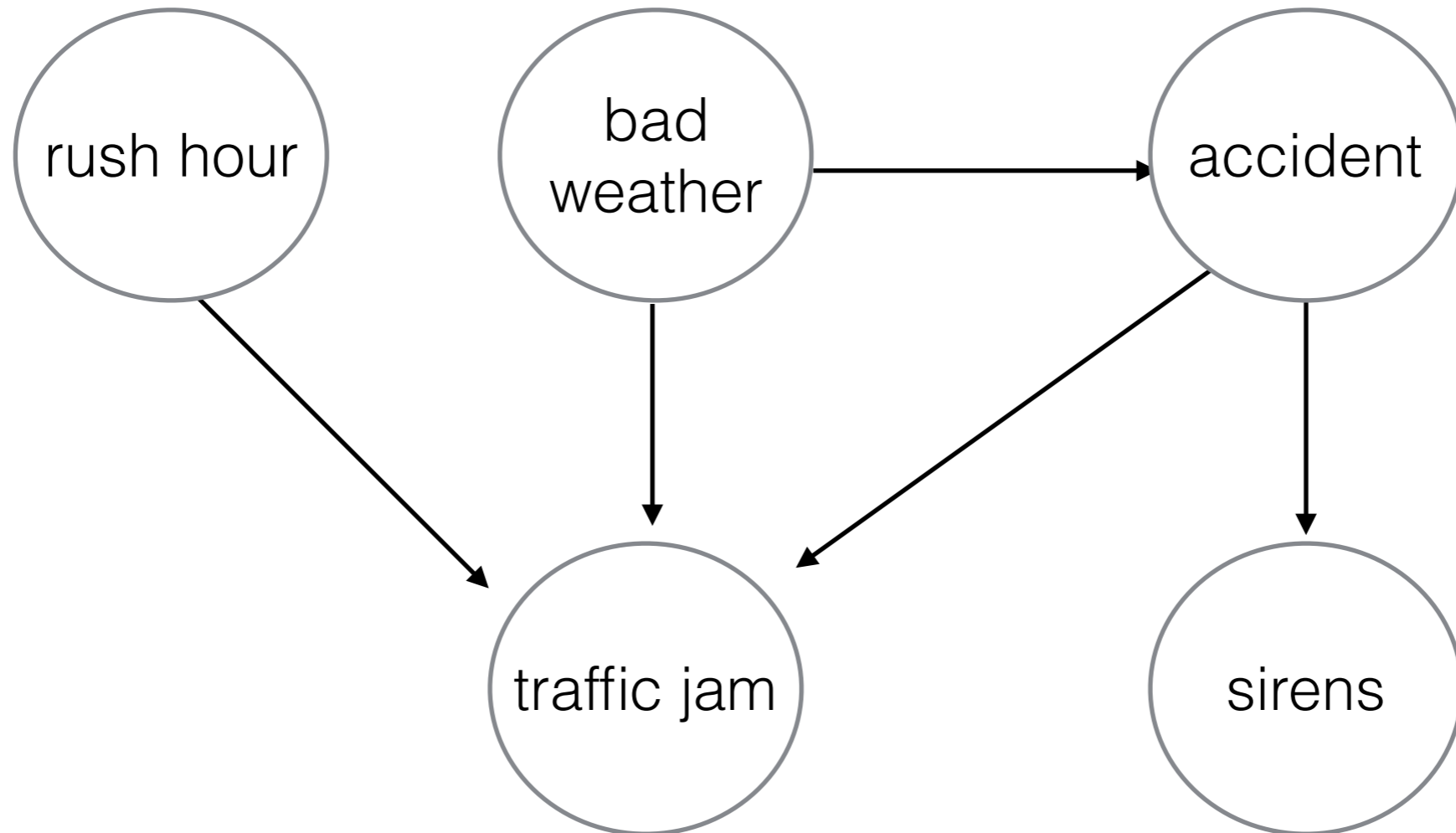


Graph-Based Representation of Sentence Meaning

“Pascale was charged with public intoxication and resisting arrest.”



Graphical Models

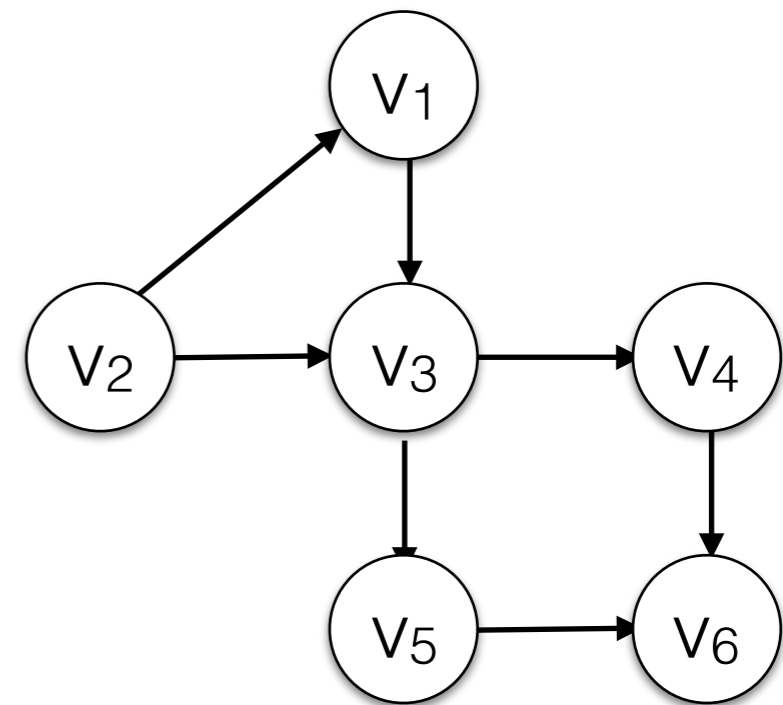


Edges

- Graphs may be **directed** or **undirected**.
 - In directed graphs, the edge pairs are ordered.
- Edges often have some weight or cost associated with them (**weighted** graphs).

$$V = \{v_1, v_2, v_3, v_4, v_5, v_6\}$$

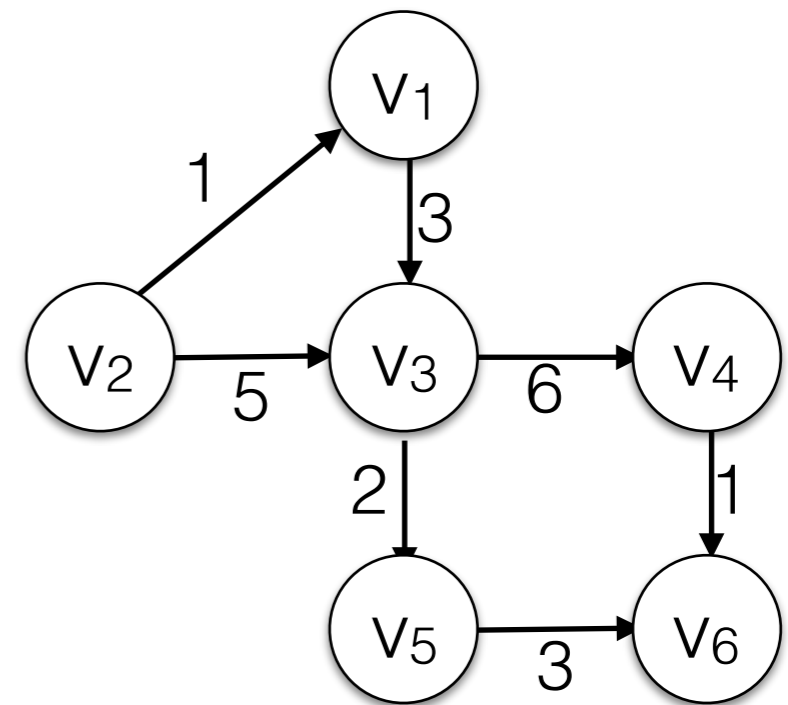
$$E = \{(v_1, v_3), (v_2, v_1), (v_2, v_3), (v_3, v_4), (v_3, v_5), (v_4, v_6), (v_5, v_6)\}$$



directed graph

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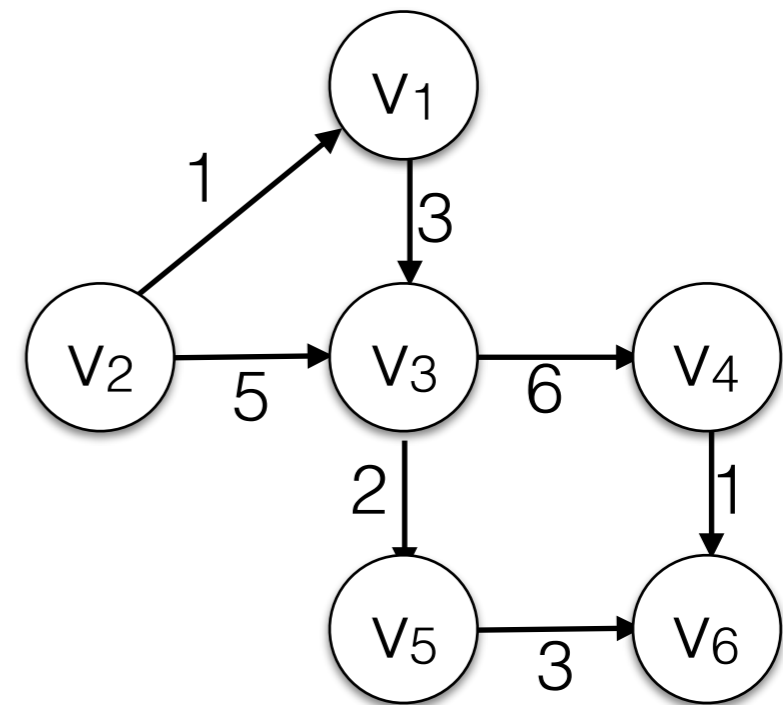


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Paths

- Vertex w is **adjacent** to vertex v iff $(w,v) \in E$.
- A **path** is a sequence of vertices w_1, w_2, \dots, w_k such that $(w_i, w_{i+1}) \in E$.

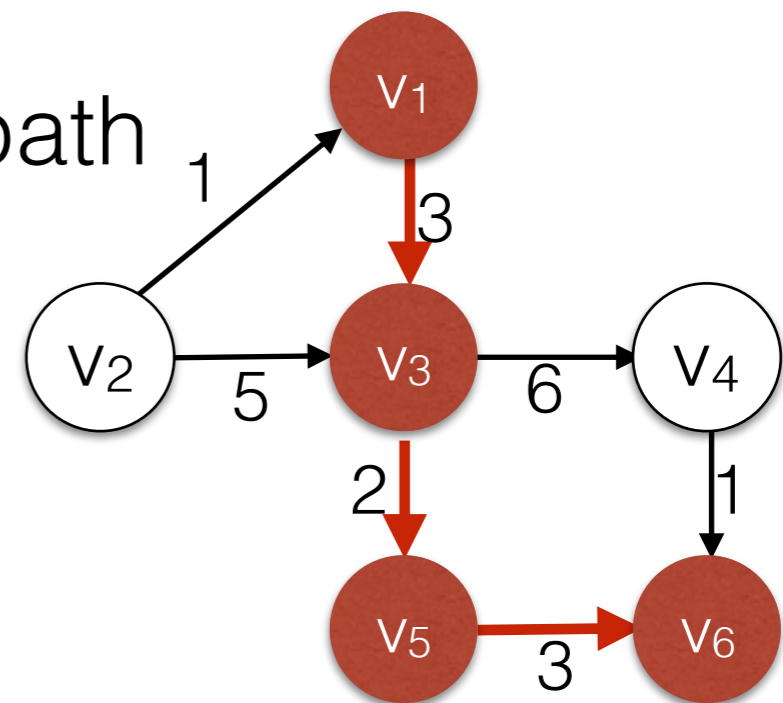


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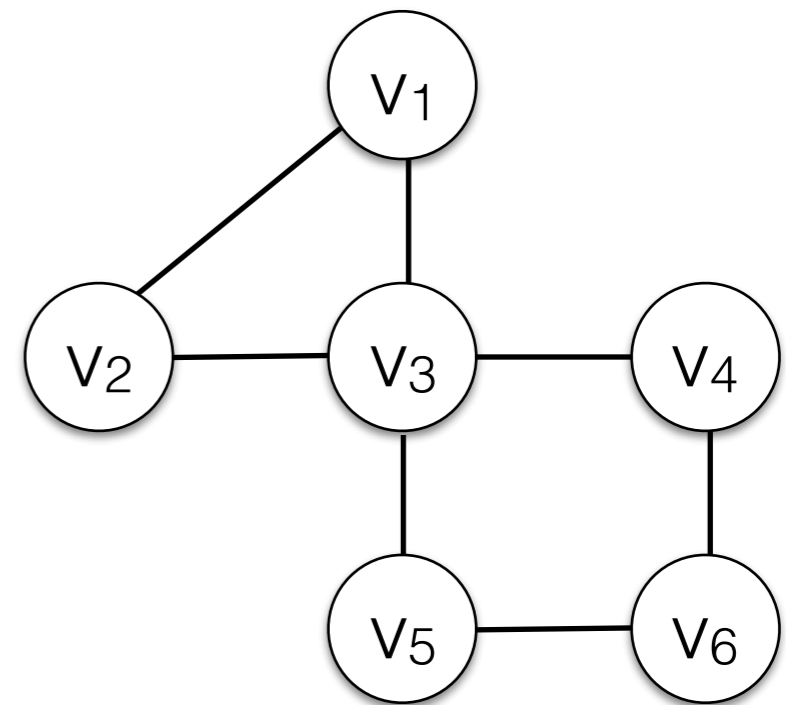
- **length** of a path:
k-1 = number of edges on path

- **cost** of a path:
Sum of all edge costs.



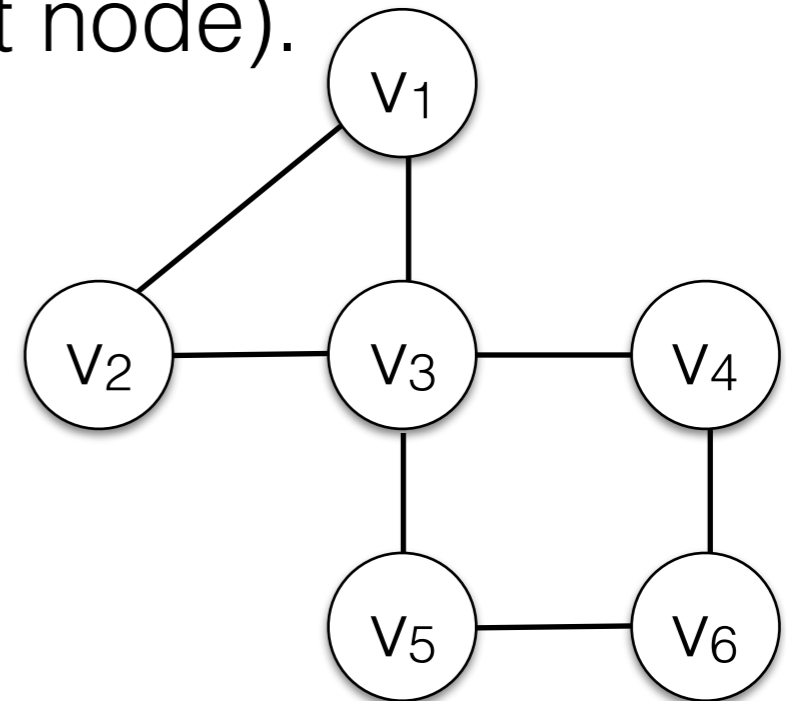
Path from v_1 to v_6 , length 3, cost 8
 $(v_1, v_3), (v_3, v_5), (v_5, v_6)$

Simple Paths



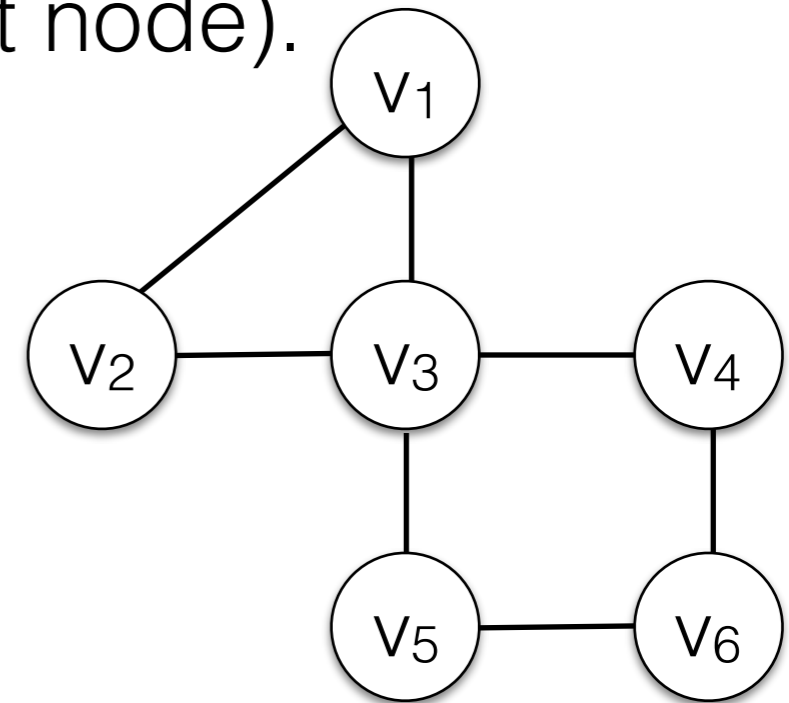
Simple Paths

- A **simple path** is a path that contains every node only once (except possibly the first and last node).



Simple Paths

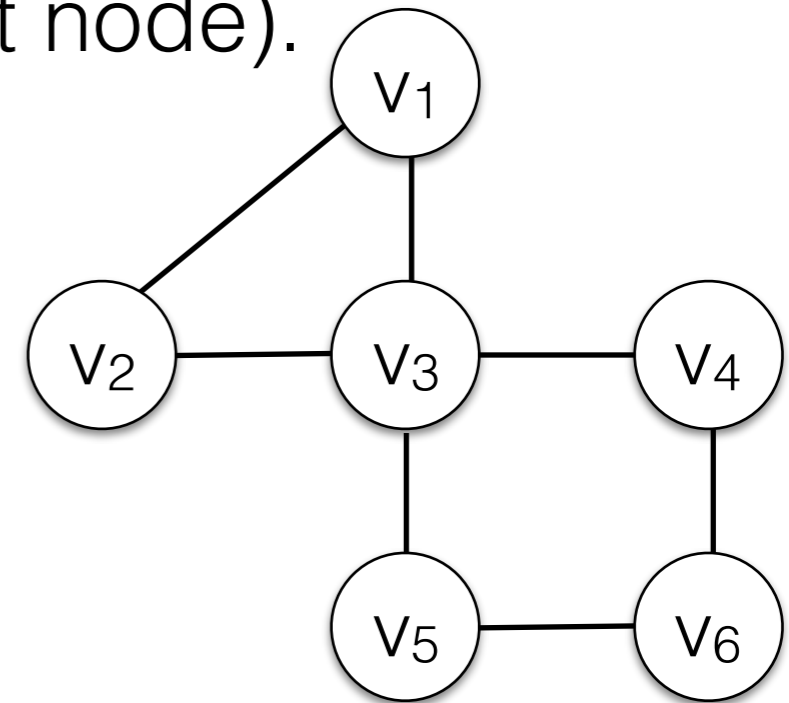
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- $(V_2, V_3, V_4, V_6, V_5, V_3, V_1)$ is a path but not a simple path.

Simple Paths

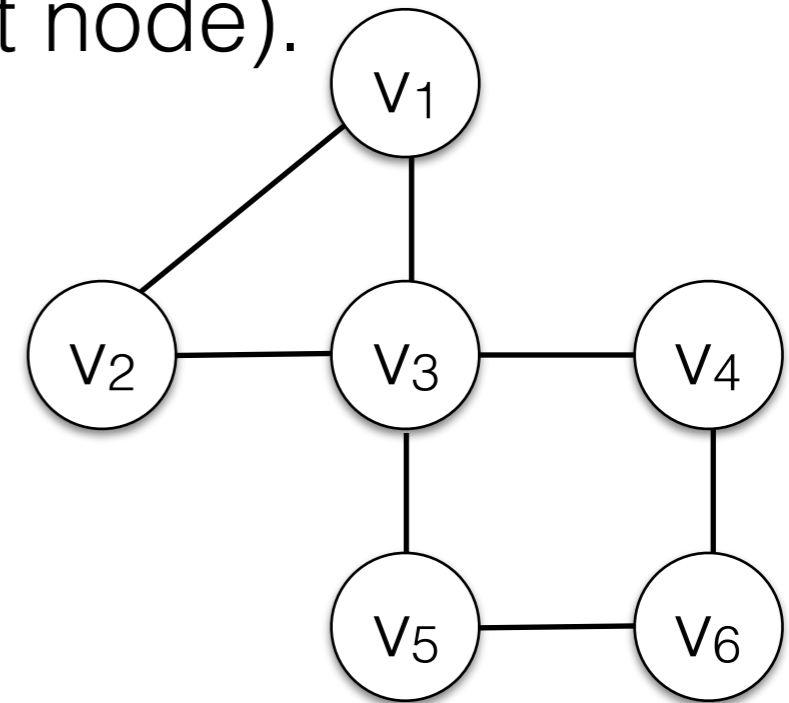
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- $(v_2, v_3, v_4, v_6, v_5, v_3, v_1)$ is a path but not a simple path.
- There are only two simple paths between v_2 and v_1 :
 (v_2, v_1) and (v_2, v_3, v_1)

Simple Paths

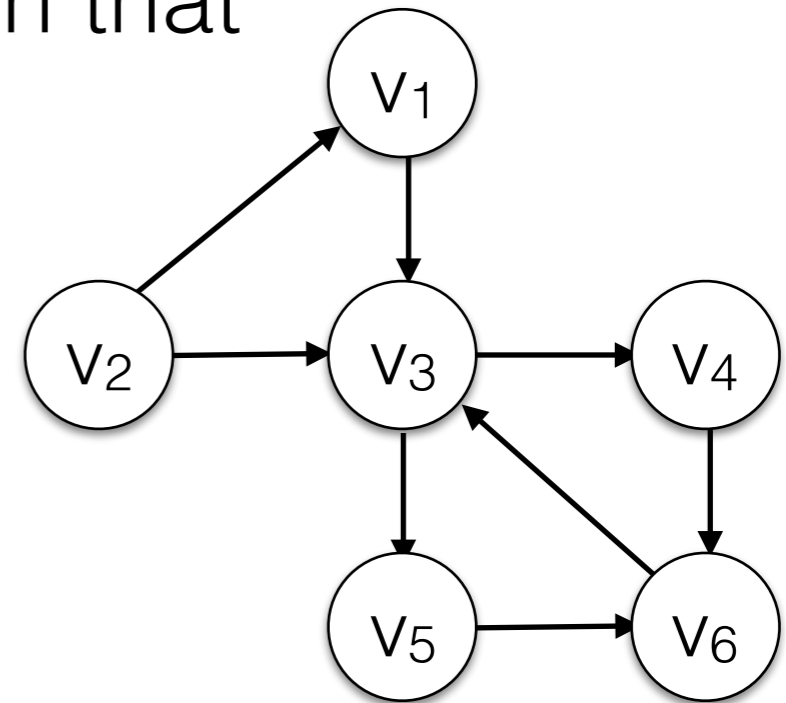
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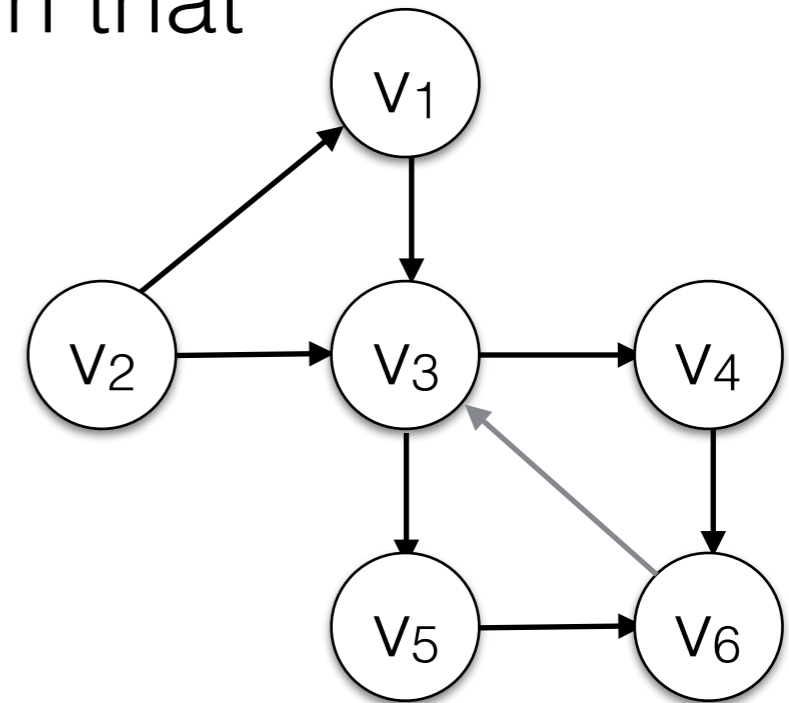
Cycles in Directed Graphs

- A **cycle** is a path (of length > 1) such that $W_1 = W_k$
- (v_3, v_4, v_6, v_3) is a cycle.



Cycles in Directed Graphs

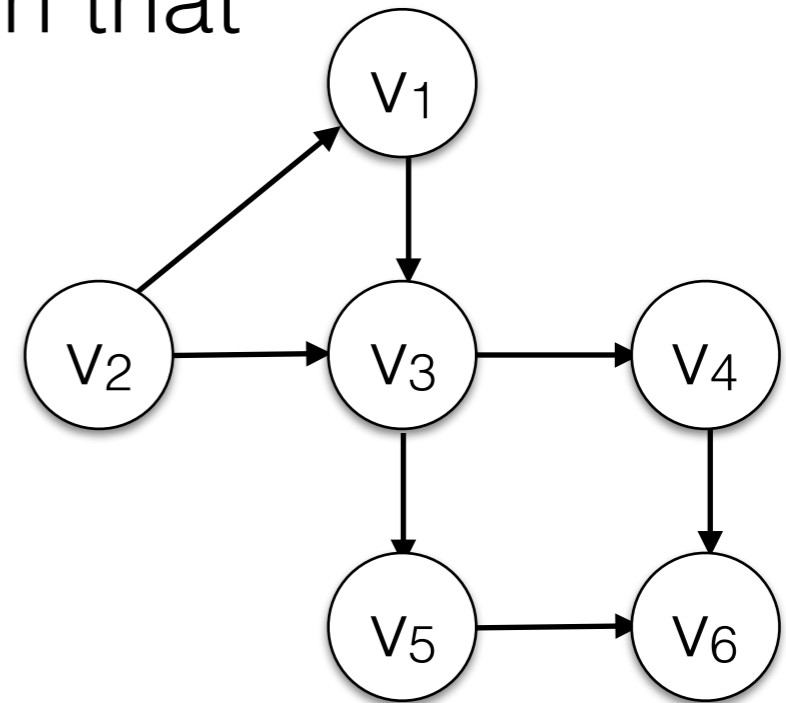
- A **cycle** is a path (of length > 1) such that $W_1 = W_k$
- (V_3, V_4, V_6, V_3) is a cycle.



- A **Directed Acyclic Graph (DAG)** is a directed graph that contains no cycles.

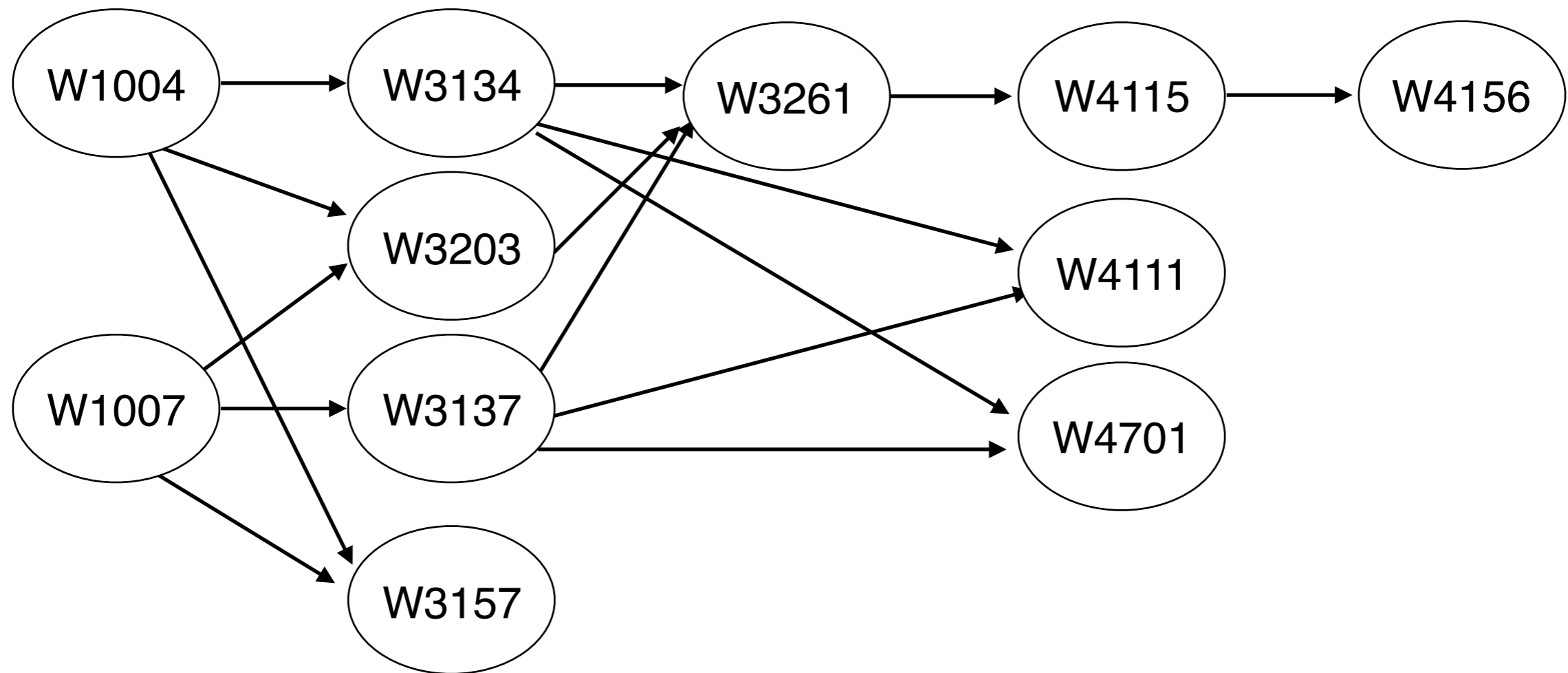
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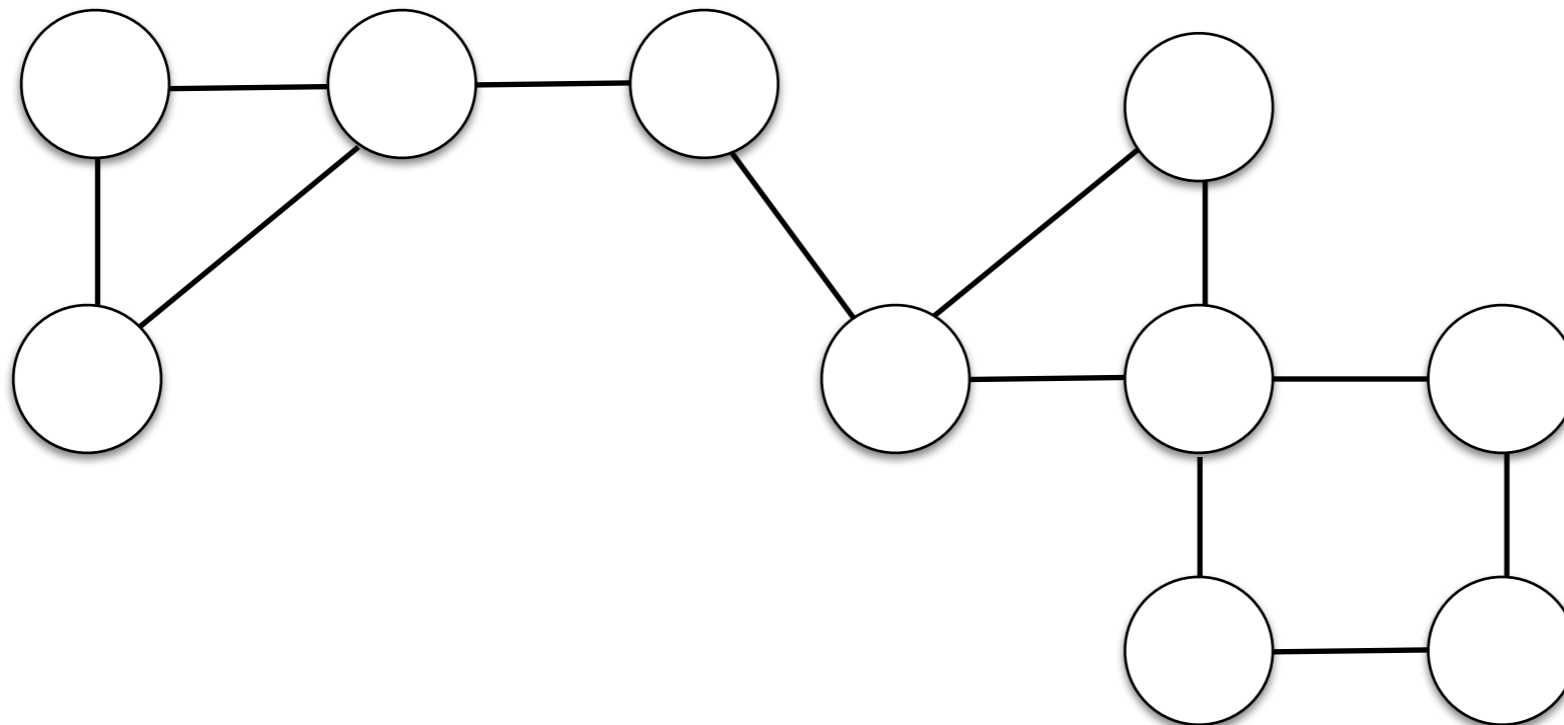
Columbia CS Course Prerequisites as a DAG



Please do not use this figure for program planning! No guarantee for accuracy.

Connectivity

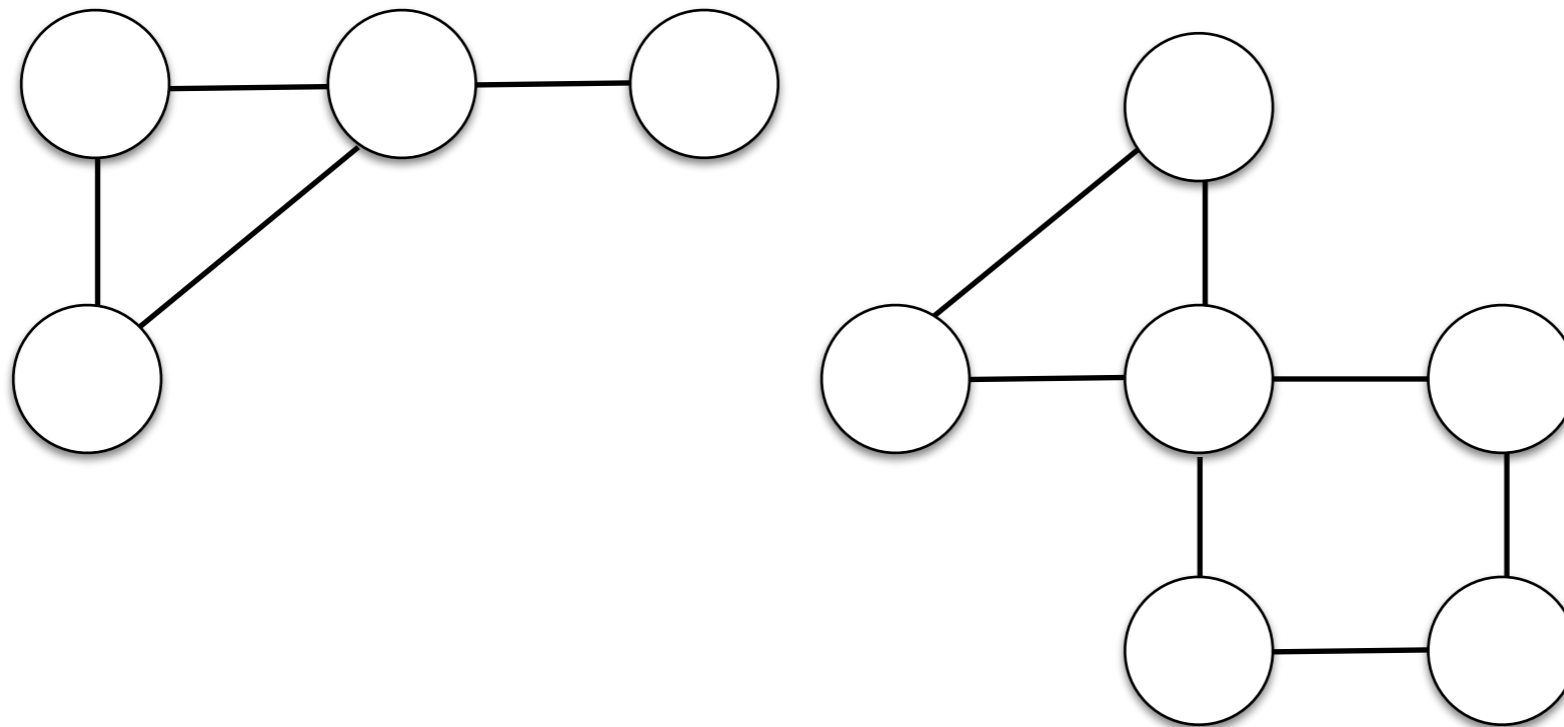
- An undirected graph is **connected** if there is a path from every vertex to every other vertex.



connected graph

Connectivity

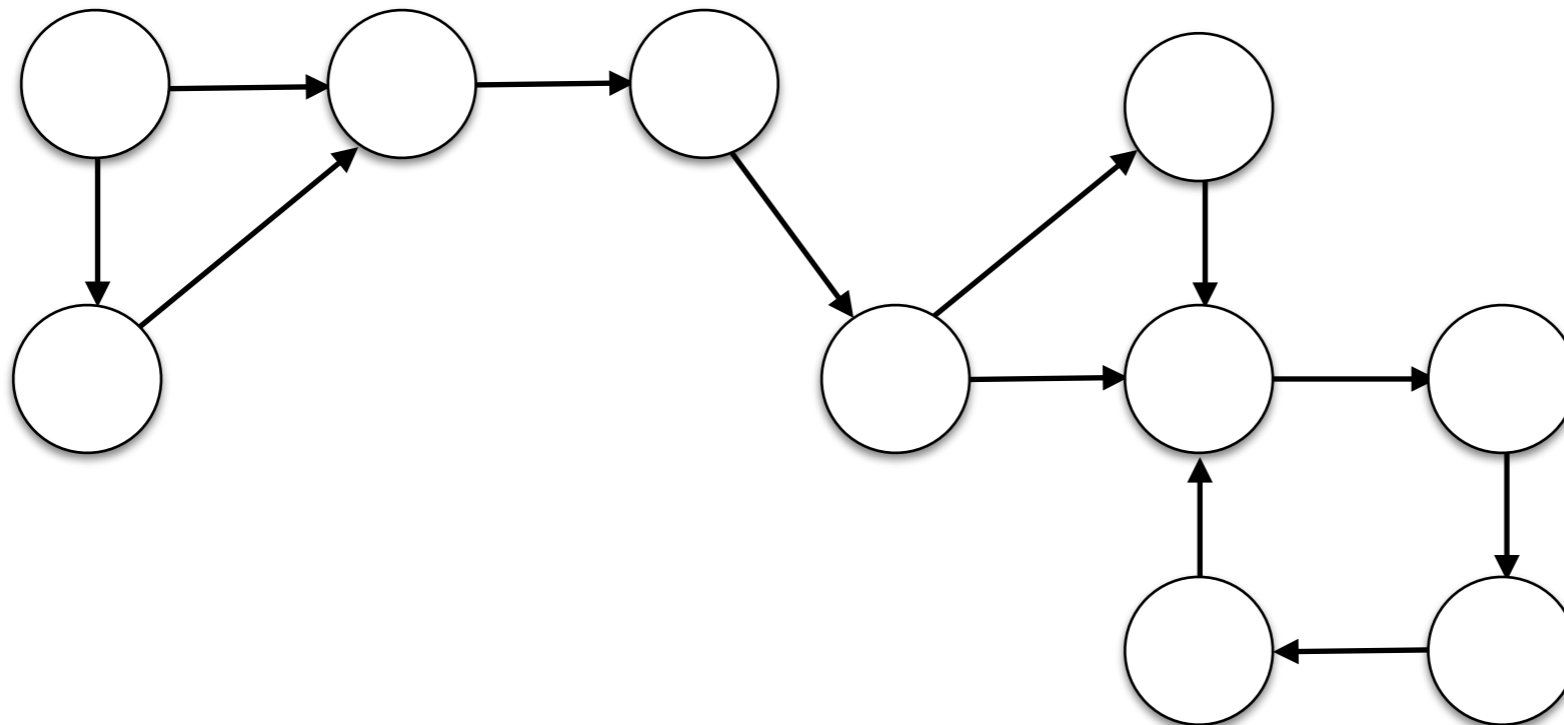
- An undirected graph is **connected** if there is a path from every vertex to every other vertex.



unconnected graph

Connectivity in Directed Graphs

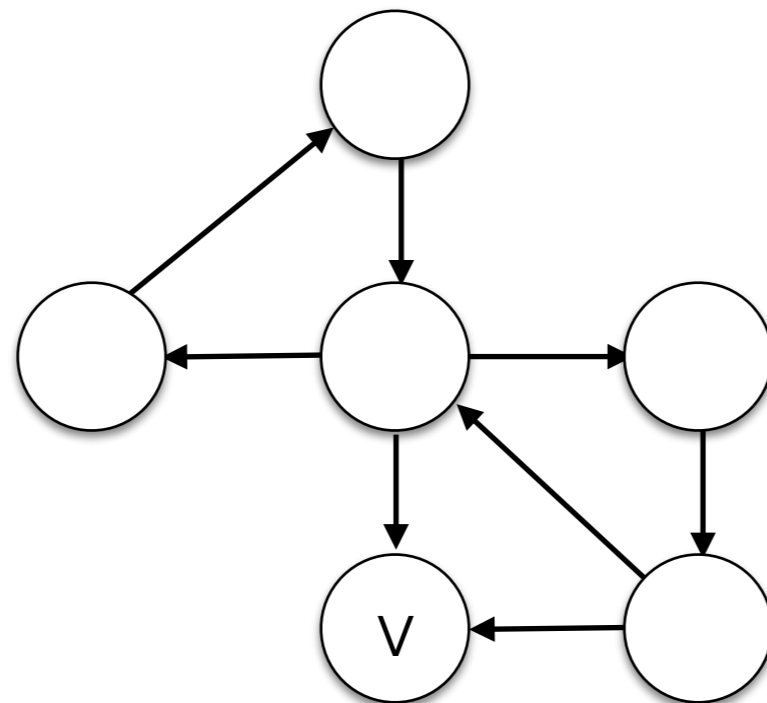
- A directed graph is **weakly connected** if there is an *undirected* path from every vertex to every other vertex.



weakly connected graph

Strongly Connected Graphs

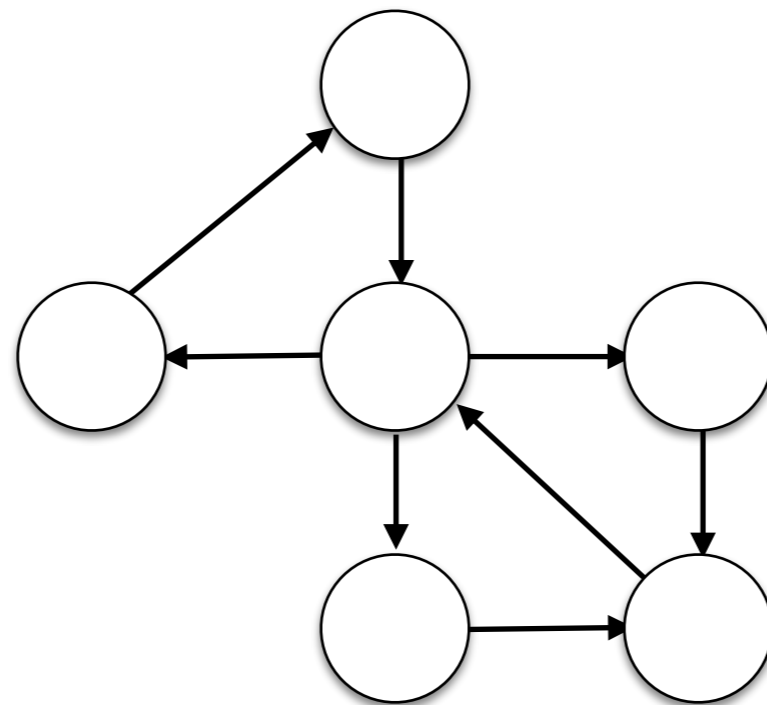
- A directed graph is **strongly connected** if there is a path from every vertex to every other vertex.



Weakly connected, but not strongly connected (no other vertex can be reached from v).

Strongly Connected Graphs

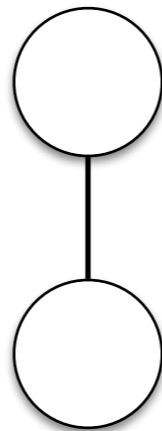
- A directed graph is **strongly connected** if there is a path from every vertex to every other vertex.



strongly connected

Complete Graphs

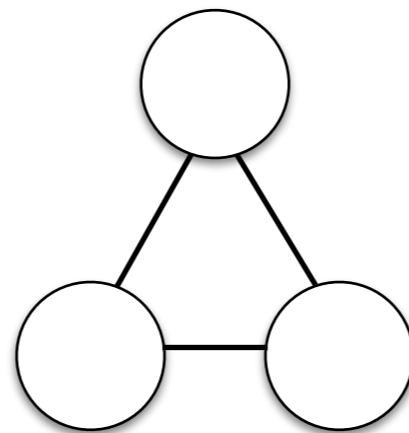
- A **complete graph** has edges between every pair of vertices.



$N=2$

Complete Graphs

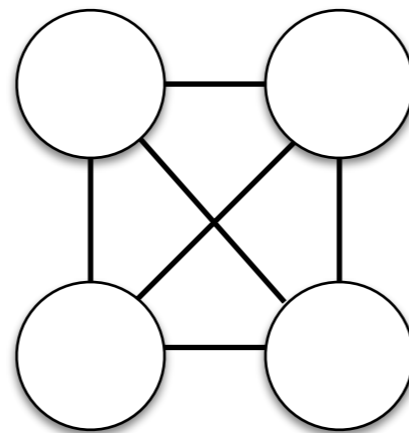
- A **complete graph** has edges between every pair of vertices.



$N=3$

Complete Graphs

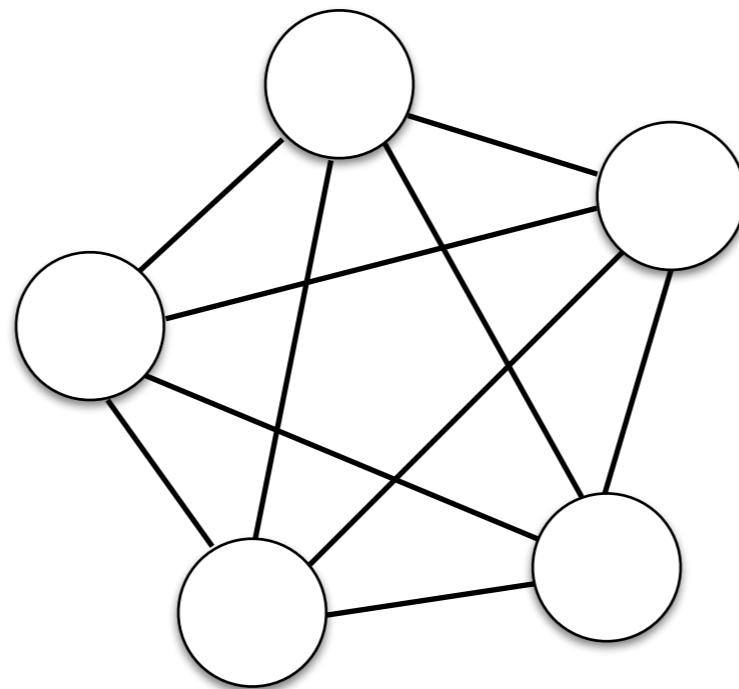
- A **complete graph** has edges between every pair of vertices.



$N=4$

Complete Graphs

- A **complete graph** has edges between every pair of vertices.

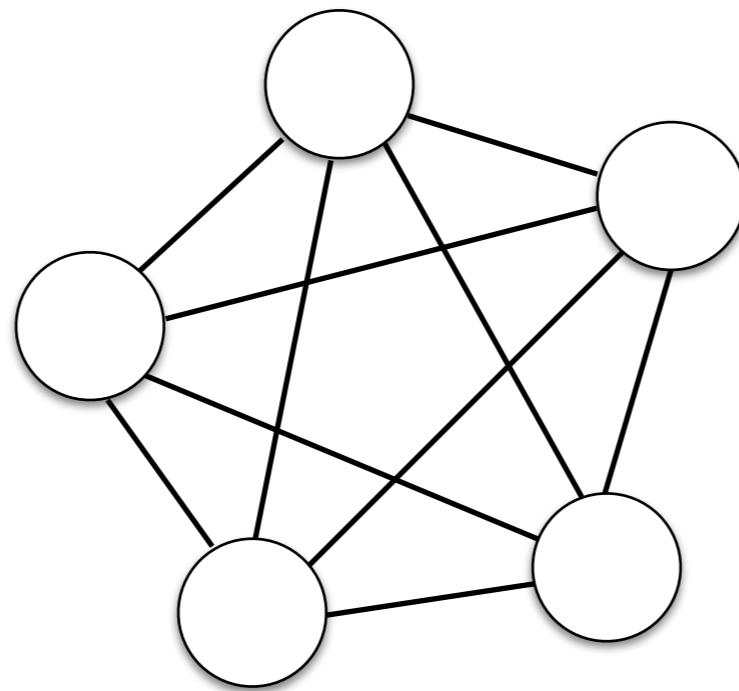


$N=5$

How many edges are there in a complete graph of size N ?

Complete Graphs

- A **complete graph** has edges between every pair of vertices.



N=5

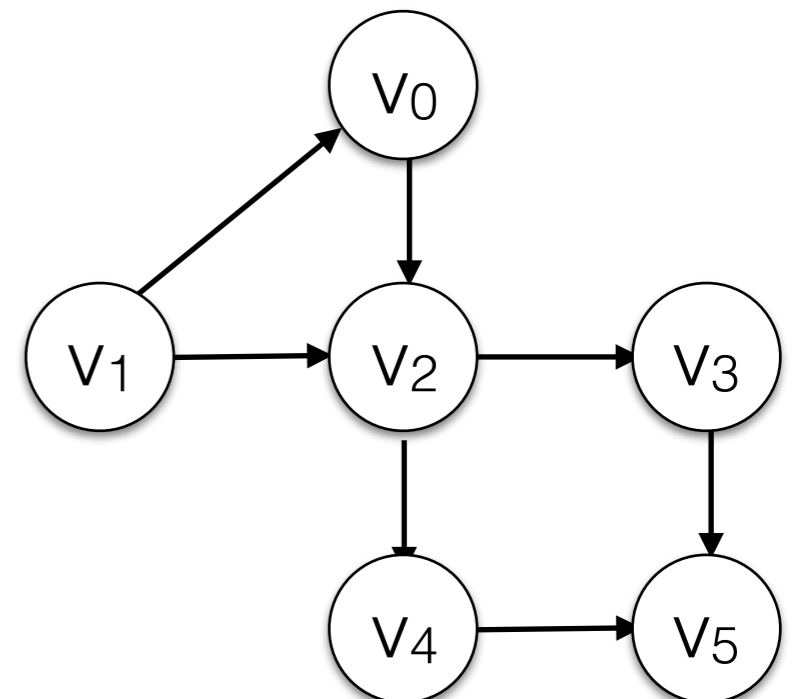
How many edges are there in a complete graph of size N?

$$\sum_{i=1}^{N-1} i = \frac{N \cdot (N - 1)}{2}$$

Representing Graphs

- Represent graph $G = (E, V)$, option 1:
 - $N \times N$ **Adjacency Matrix** represented as 2-dimensional `Boolean[][]`.
 - $A[u][v] = \text{true}$ if $(u, v) \in E$, else false

	0	1	2	3	4	5
0	f	f	t	f	f	f
1	t	f	t	f	f	f
2	f	f	f	t	t	f
3	f	f	f	f	f	t
4	f	f	f	f	f	t
5	f	f	f	f	f	f

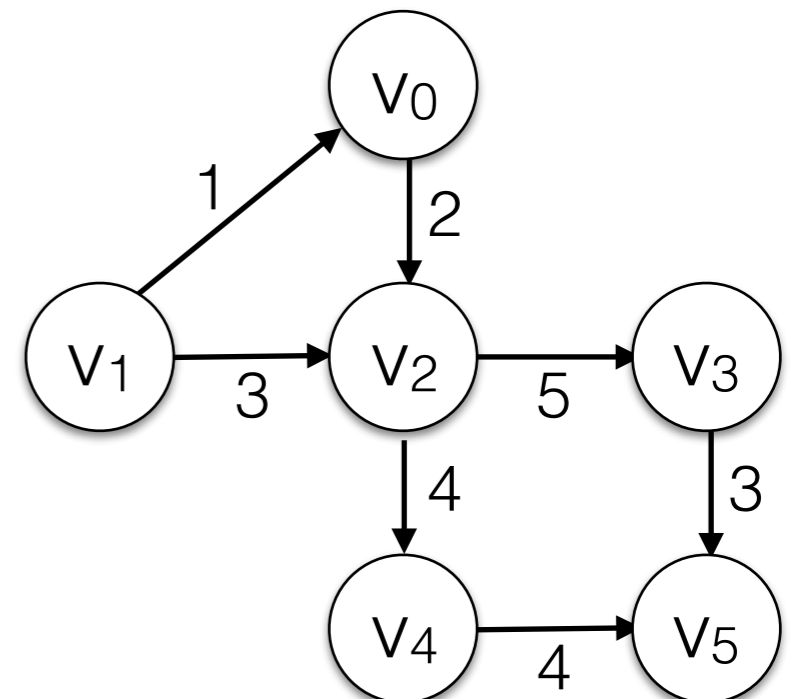


Representing Graphs

- Represent graph $G = (E, V)$, option 1:
 - $N \times N$ **Adjacency Matrix** represented as 2-dimensional `Integer[][]`.
 - $A[u][v] = \text{cost}(u, v)$ if $(u, v) \in E$, else ∞

	0	1	2	3	4	5
0	∞	∞	2	∞	∞	∞
1	1	∞	3	∞	∞	∞
2	∞	∞	∞	5	4	∞
3	∞	∞	∞	∞	∞	3
4	∞	∞	∞	∞	∞	4
5	∞	∞	∞	∞	∞	∞

32

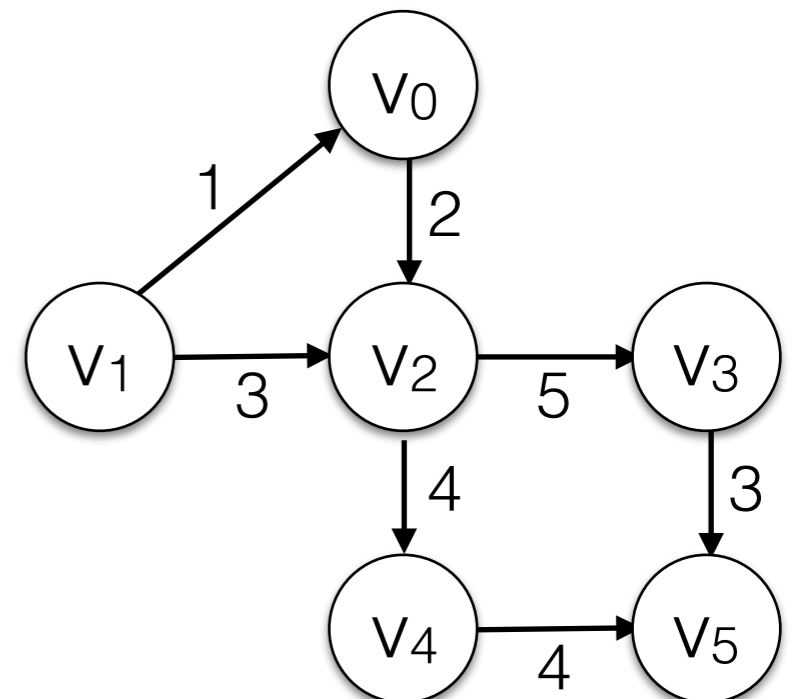


Representing Graphs

- Problem of Adjacency Matrix representation:
 - For **sparse** graphs (that contain much less than $|V|^2$ edges), a lot of array space is wasted.

	0	1	2	3	4	5
0	∞	∞	2	∞	∞	∞
1	1	∞	3	∞	∞	∞
2	∞	∞	∞	5	4	∞
3	∞	∞	∞	∞	∞	3
4	∞	∞	∞	∞	∞	4
5	∞	∞	∞	∞	∞	∞

33



Representing Graphs

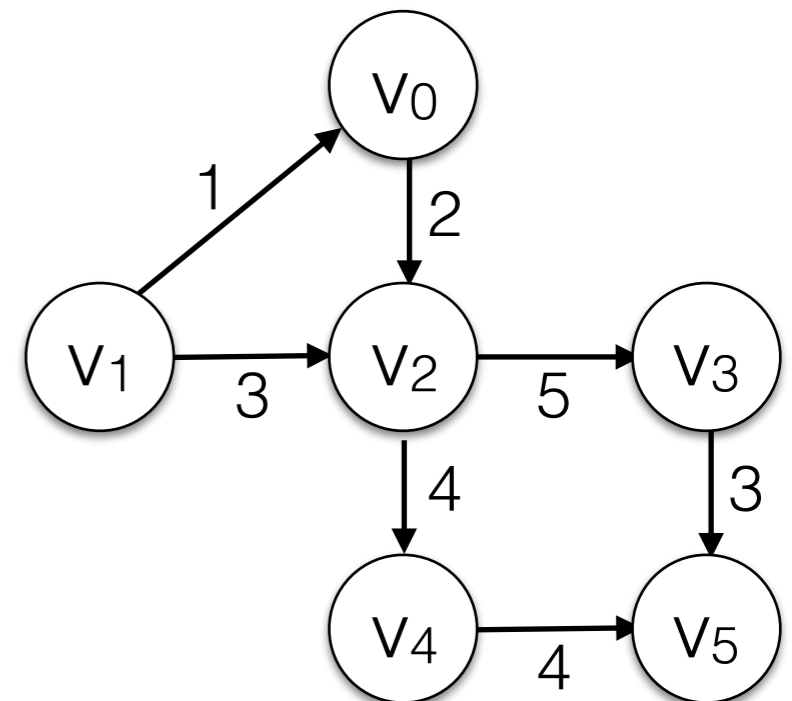
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Space requirement: $\Theta(|V|^2)$

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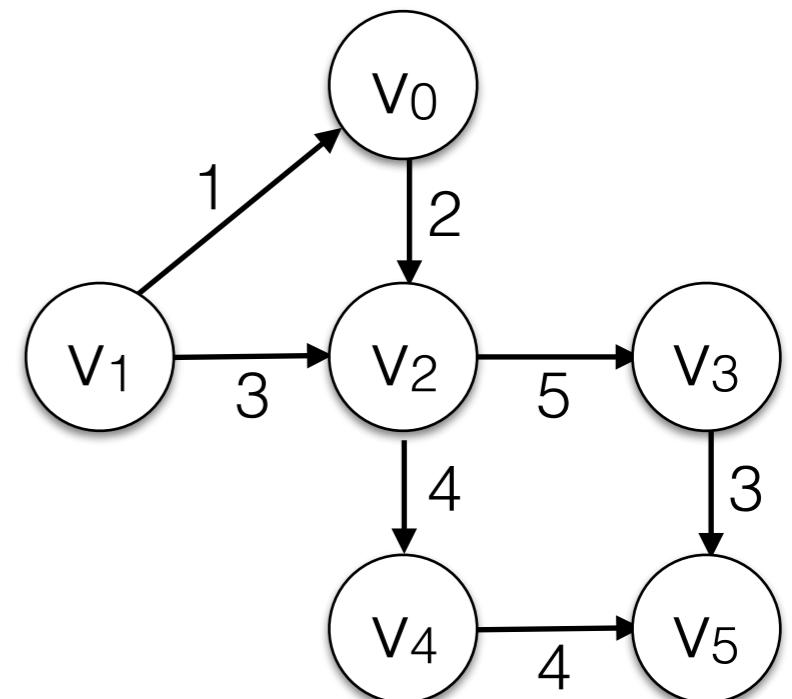
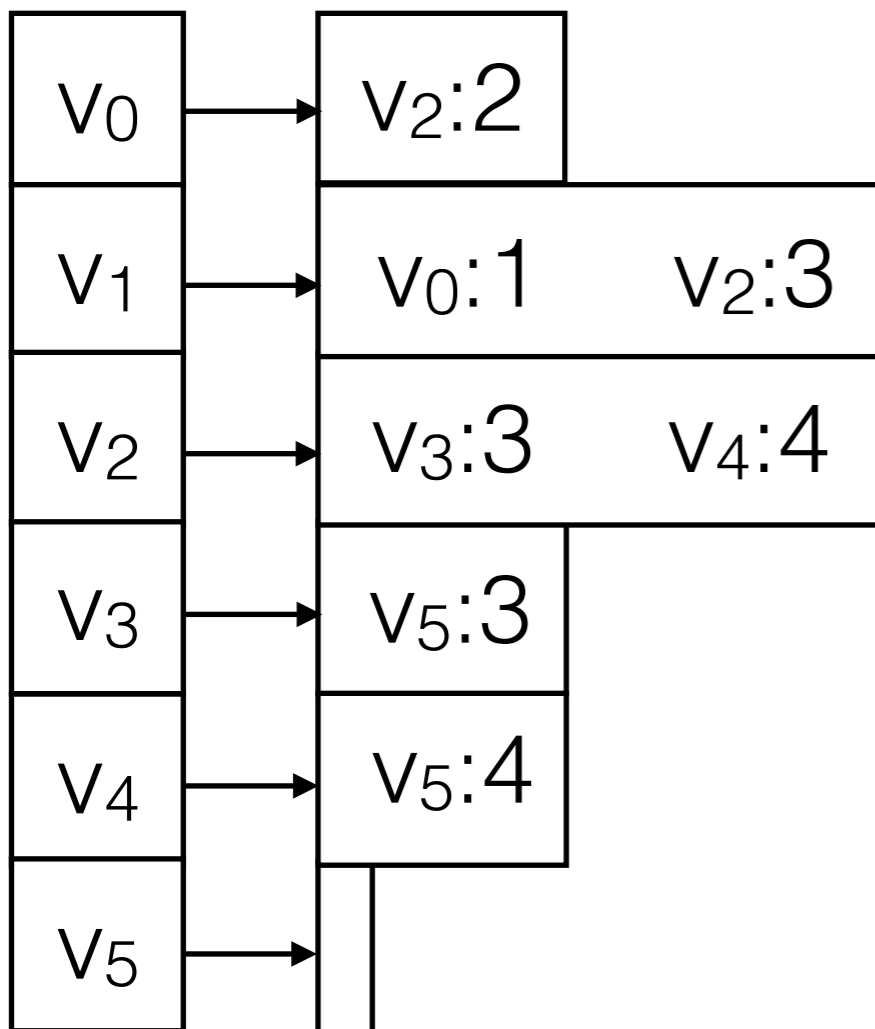
	0	1	2	3	4	5
0	∞	∞	2	∞	∞	∞
1	1	∞	3	∞	∞	∞
2	∞	∞	∞	5	4	∞
3	∞	∞	∞	∞	∞	3
4	∞	∞	∞	∞	∞	4
5	∞	∞	∞	∞	∞	∞

33



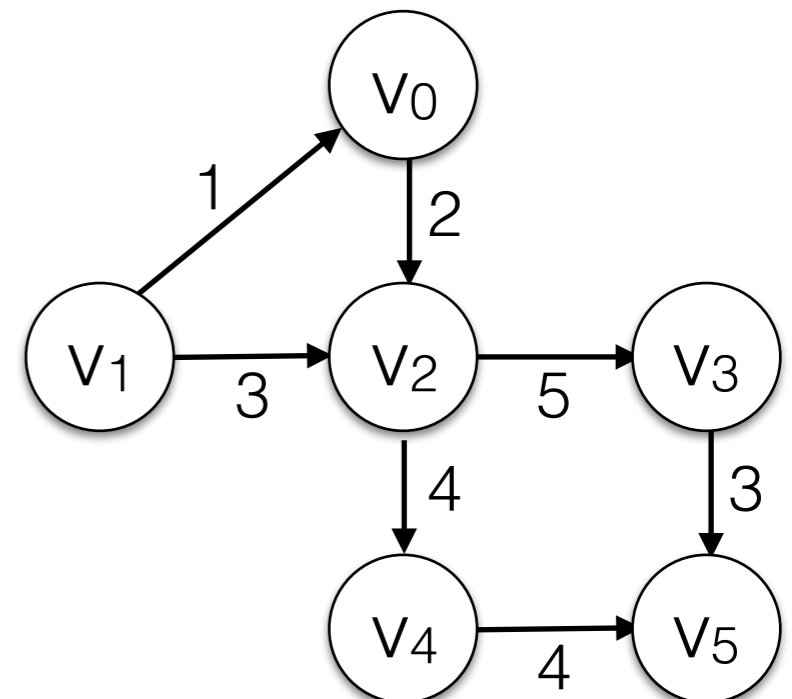
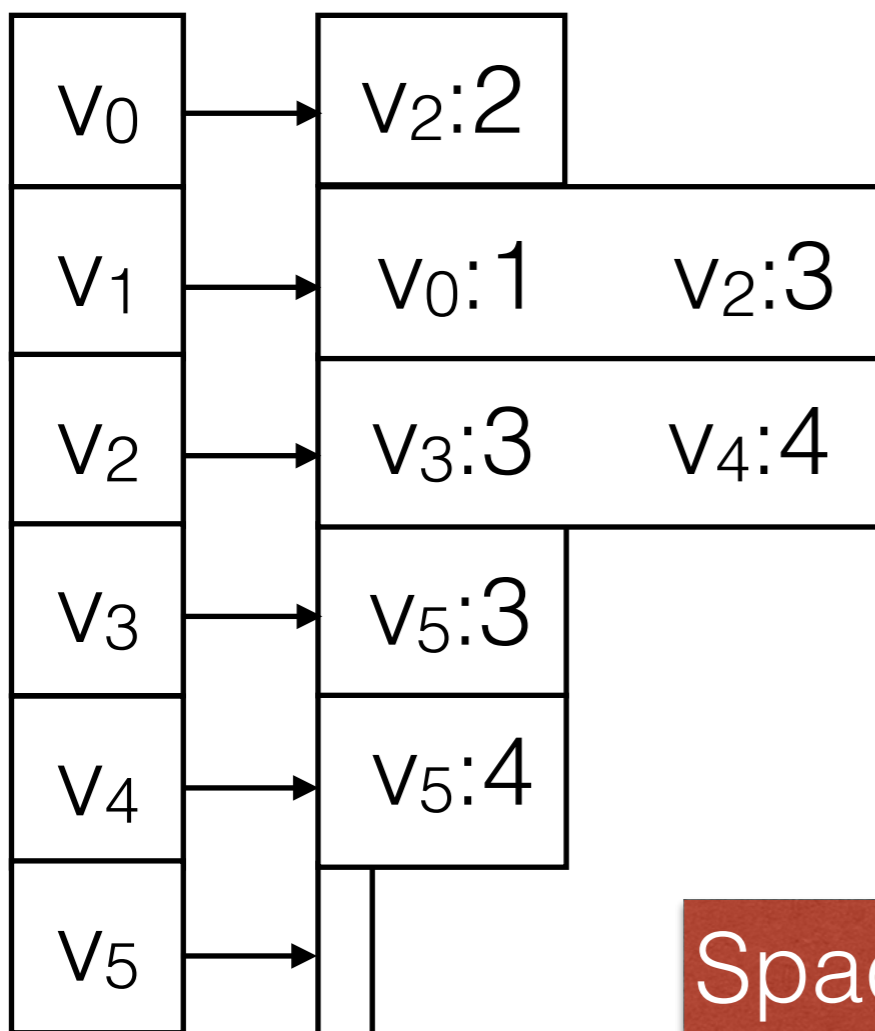
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- Represent graph $G = (E, V)$, option 2: **Adjacency Lists**
 - For each vertex, keep a list of all adjacent vertices.



Representing Graphs

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 - For each vertex, keep a list of all adjacent vertices.



Space requirement: $\Theta(|V| + |E|)$

Storing Adjacency Lists

- If we construct a graph (or read it in from some specification), a LinkedList is better than an ArrayList because we don't know how many adjacent vertices there are for each vertex.
- Create an instance of a Vertex class for each vertex and keep adjacency list in this object.
- Can also keep an index to quickly access vertices by name.