

# Data Structures in Java

Lecture 9: Binary Search Trees.

10/7/2015

Daniel Bauer

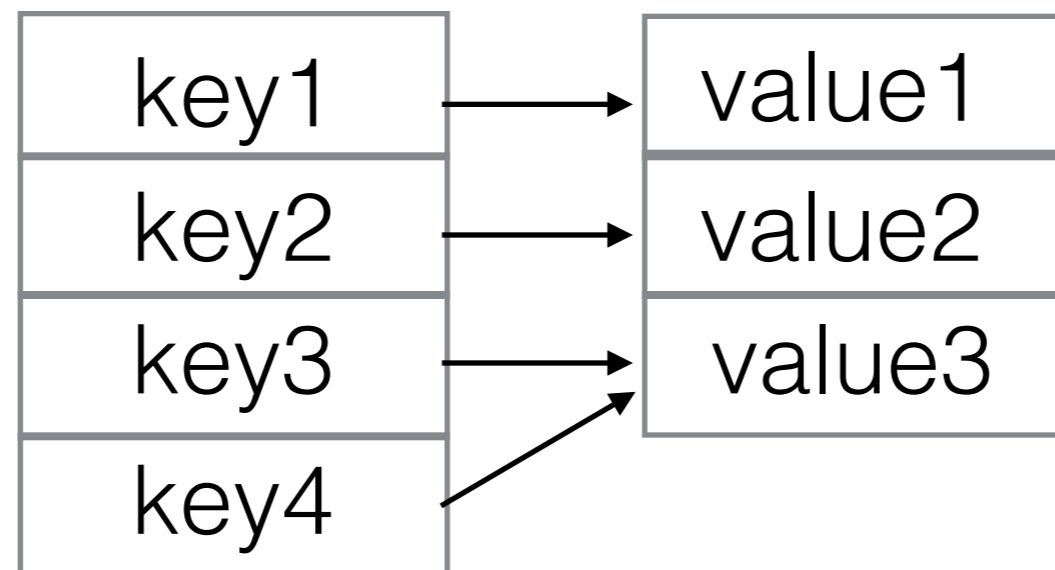
# Contents

## **1. Binary Search Trees**

## 2. Implementing Maps with BSTs

# Map ADT

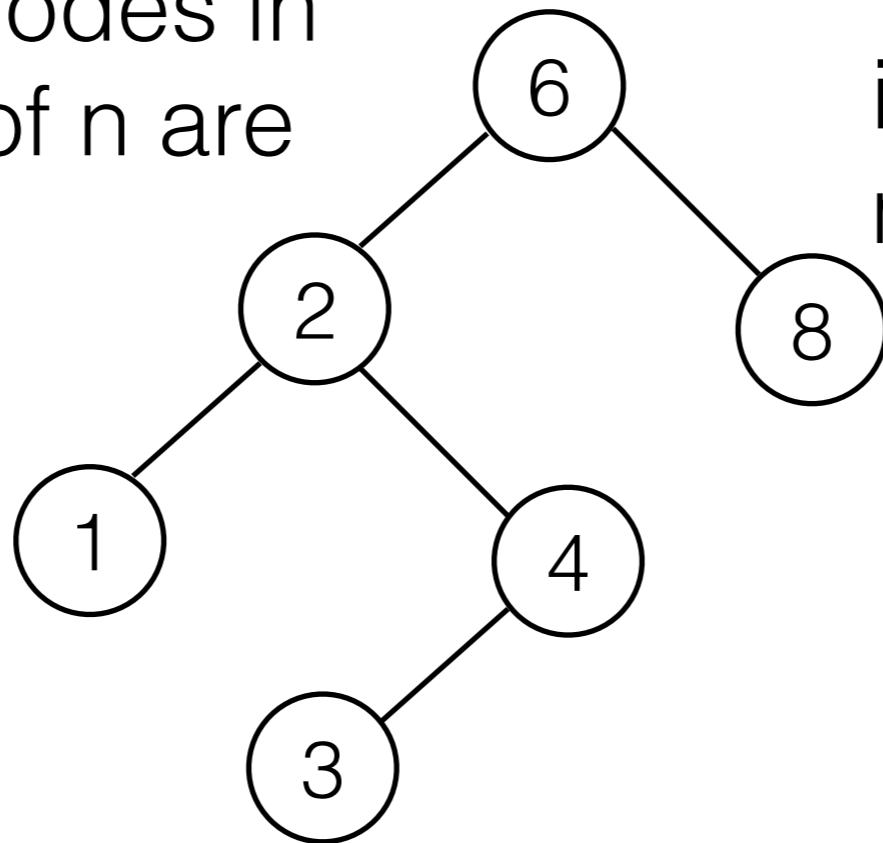
- A *map* is collection of *(key, value)* pairs.
- Keys are unique, values need not be.
- Two operations:
  - `get(key)` returns the value associated with this key
  - `put(key, value)` (overwrites existing keys)



How do we implement map operations efficiently?

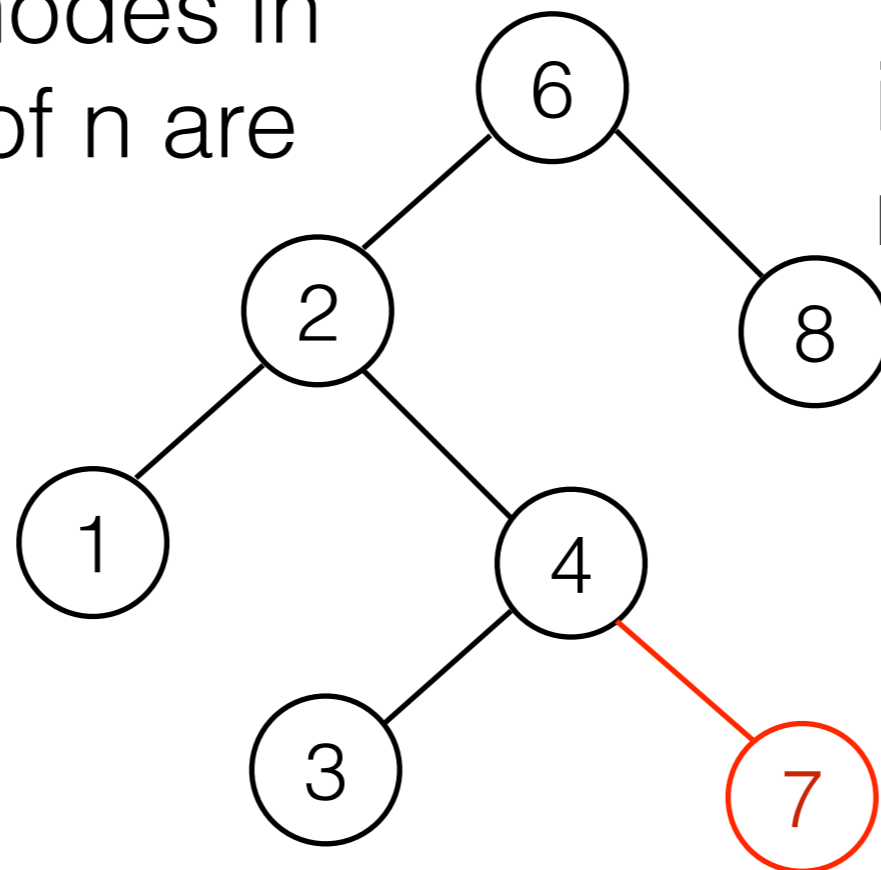
# Binary Search Tree Property

- Goal: Reduce finding an item to  $O(\log N)$
- For every node  $n$  with value  $x$ 
  - the value of all nodes in the left subtree of  $n$  are smaller than  $x$ .
  - The value of all nodes in the right subtree of  $n$  are larger than  $x$ .



# Binary Search Tree Property

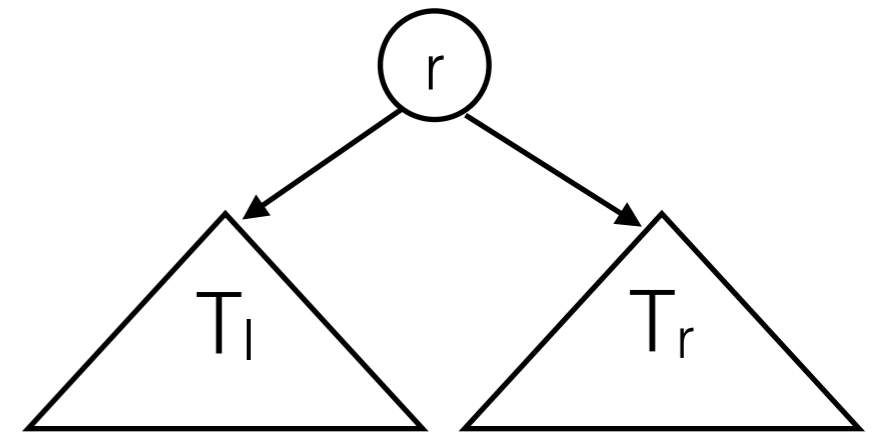
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**This is not a search tree**

# Binary Search Tree (BST) ADT

- A *Binary Search Tree*  $T$  consists of
  - A root node  $r$  with value  $r_{item}$
  - At most two non-empty subtrees  $T_l$  and  $T_r$ , connected by a directed edge from  $r$ .
- $T_l$  and  $T_r$  satisfy the BST property:
  - For all nodes  $s$  in  $T_l$ ,  $s_{item} < r_{item}$ .
  - For all nodes  $t$  in  $T_r$ ,  $t_{item} > r_{item}$ .
- No value appears more than once in the BST.

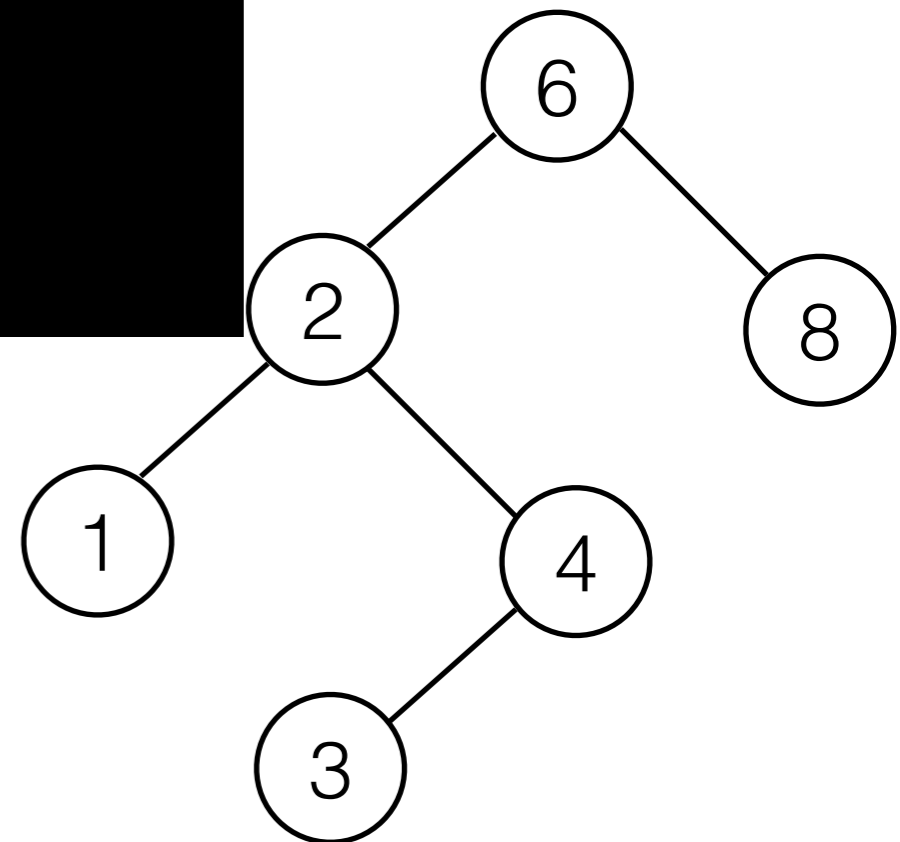


# BST operations

- `insert(x)` - add value x to T.
- `contains(x)` - check if value x is in T.
- `findMin()` - find smallest value in T.
- `findMax()` - find largest value in T.
- `remove(x)` - remove an item from T.

# BST operations: contains

```
private boolean contains( Integer x, BinaryNode t ) {  
    if( t == null )  
        return false;  
  
    if( x < t.data )  
        return contains( x, t.left );  
    else if( t.data < x )  
        return contains( x, t.right );  
    else  
        return true;    // Match  
}
```

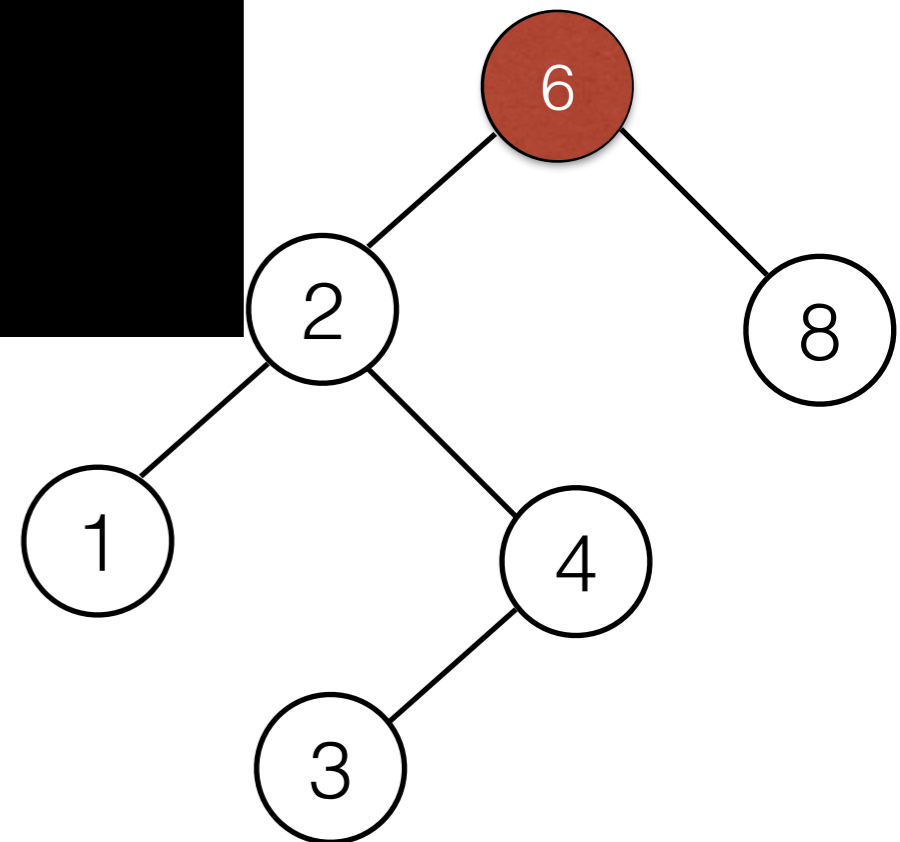




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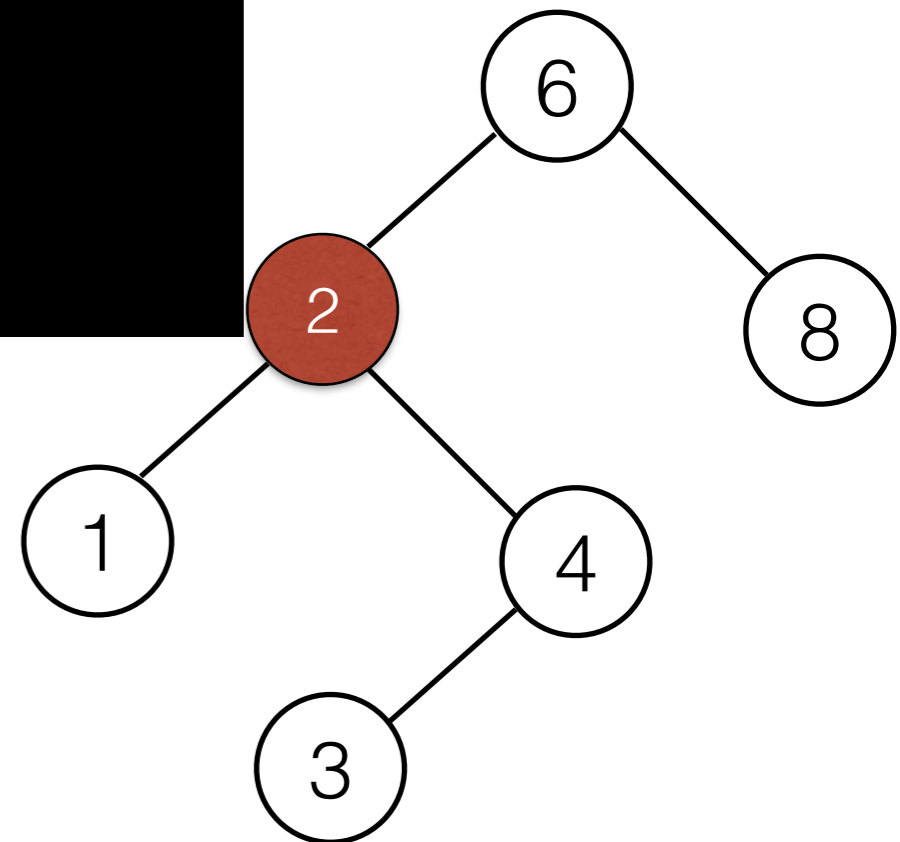
contains(3)



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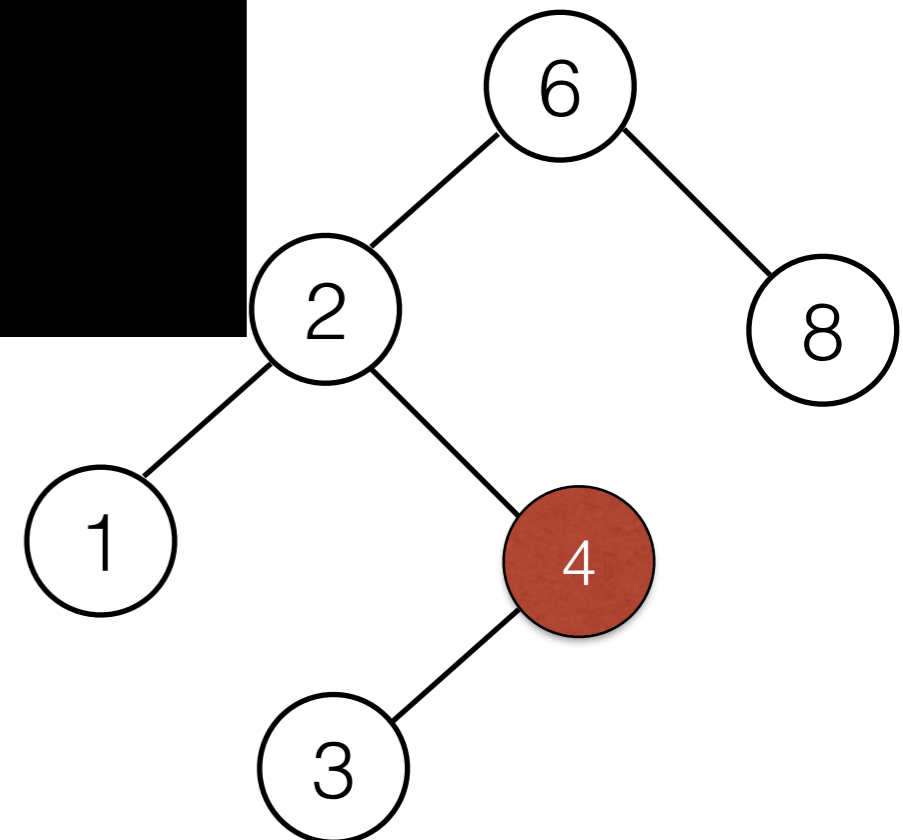
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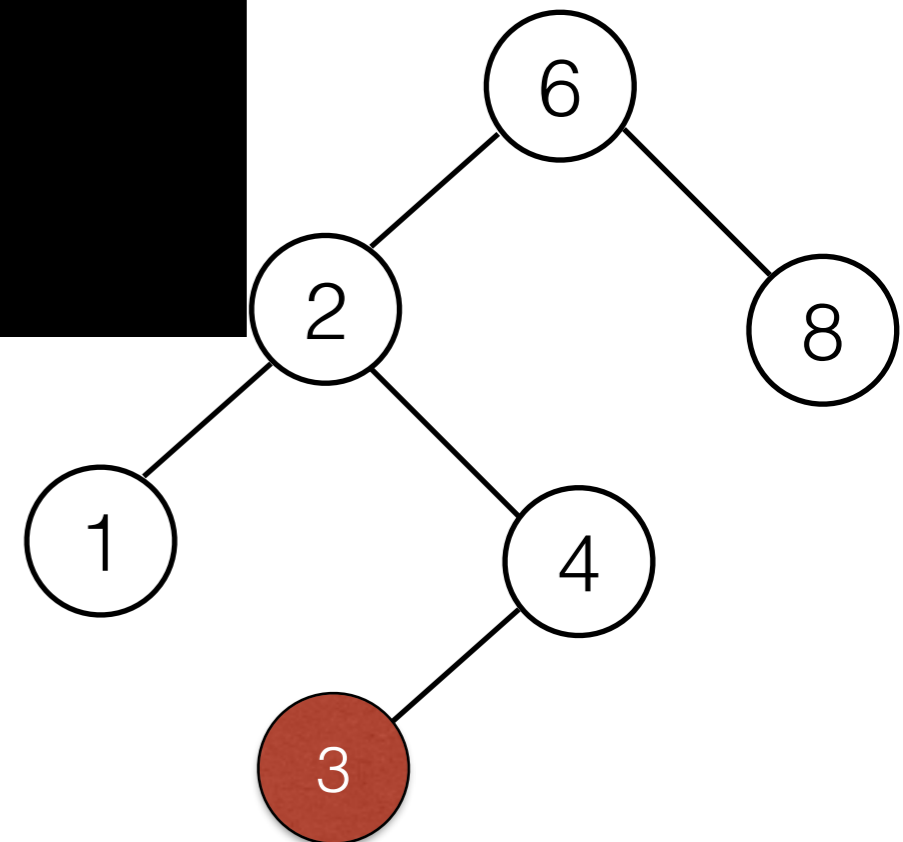
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# BST operations: contains

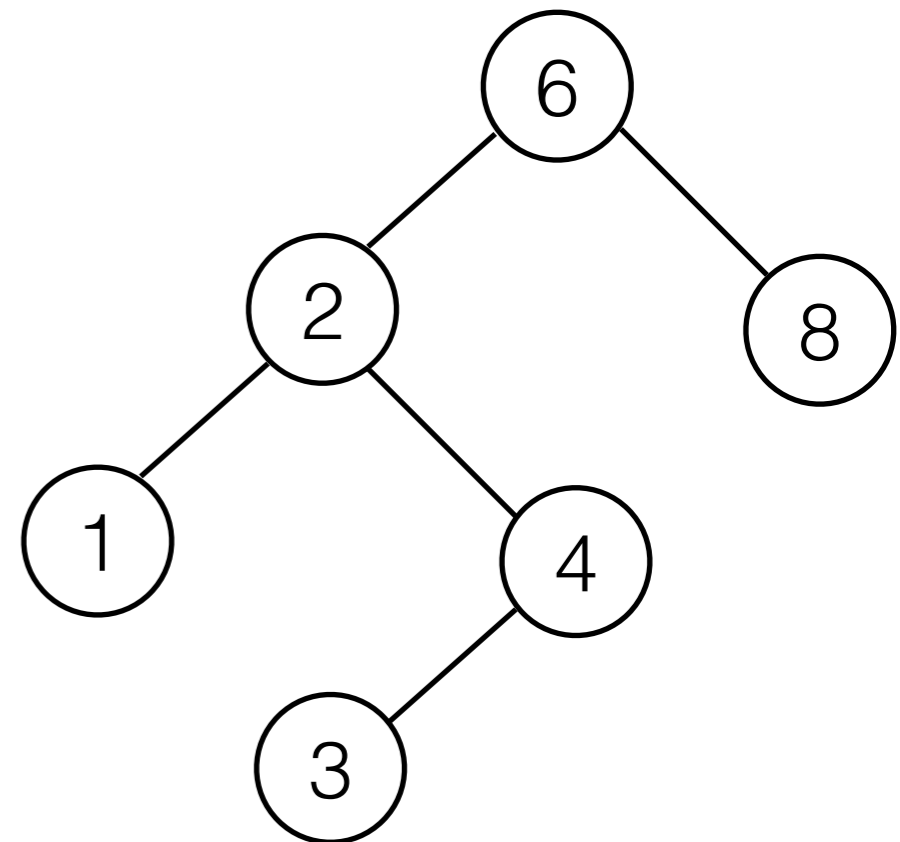
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contains(3)



# BST operations: findMin

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private BinaryNode findMin( BinaryNode t ) {  
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    else if( t.left == null )  
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    return findMin( t.left );  
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```



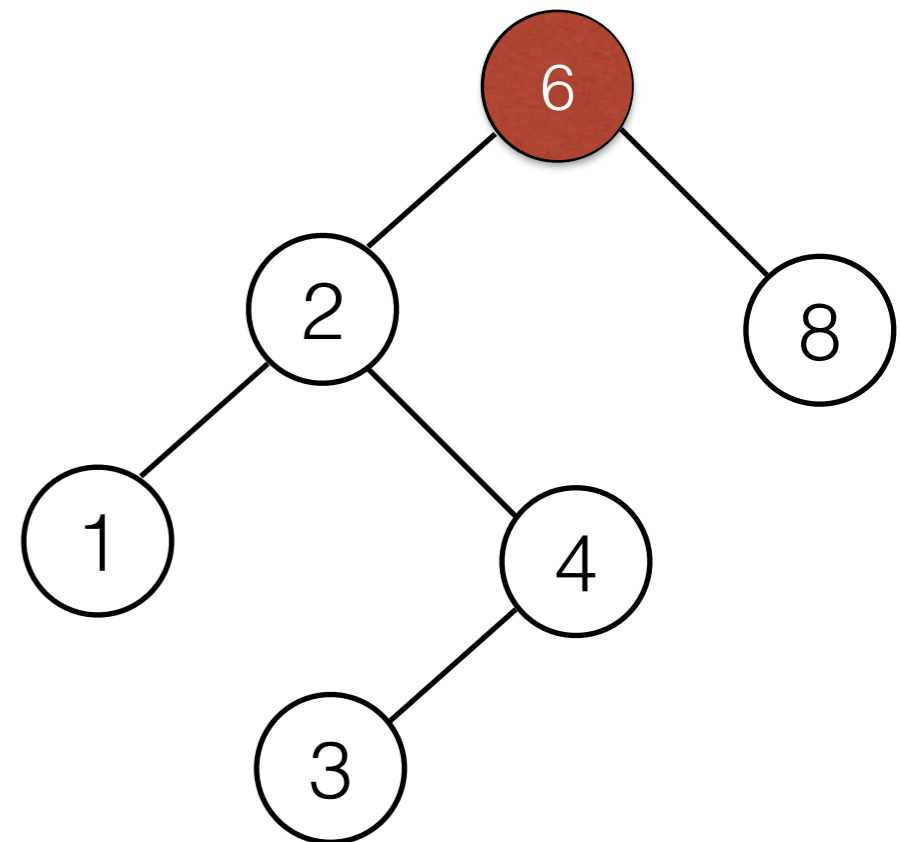
findMax is equivalent.

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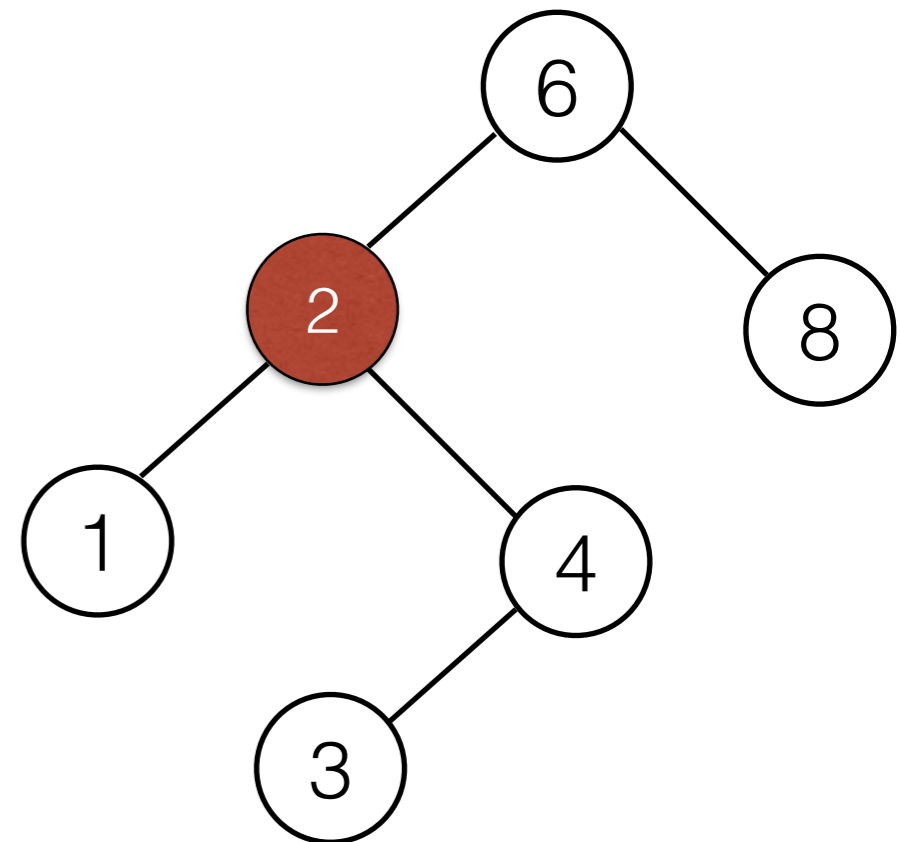


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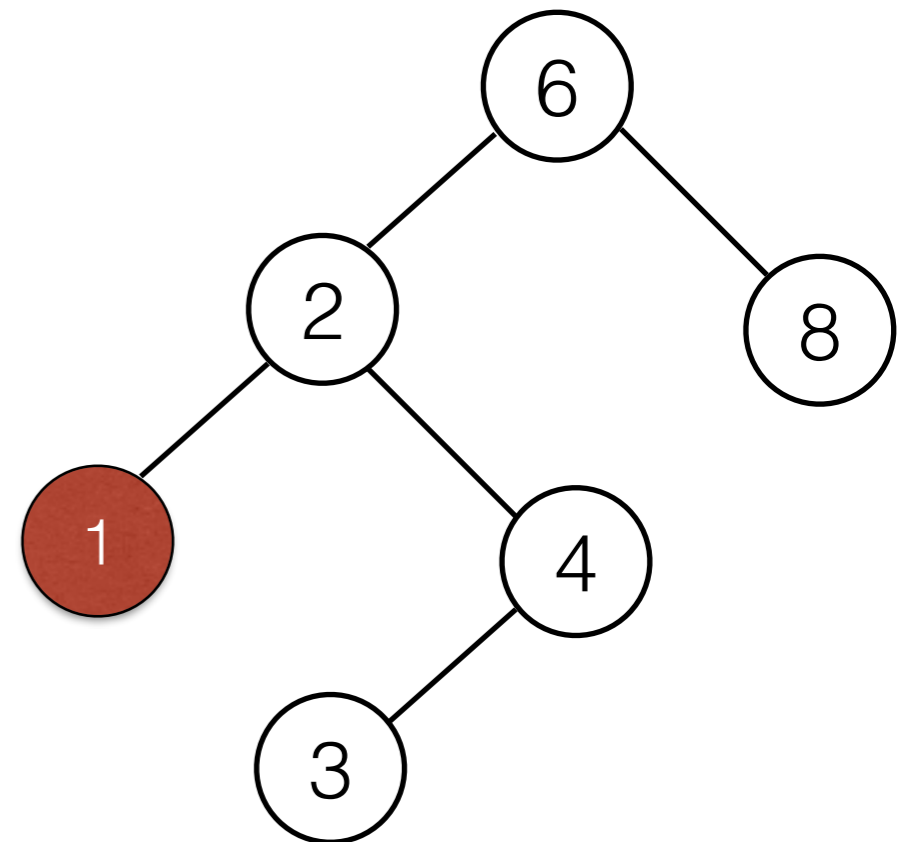


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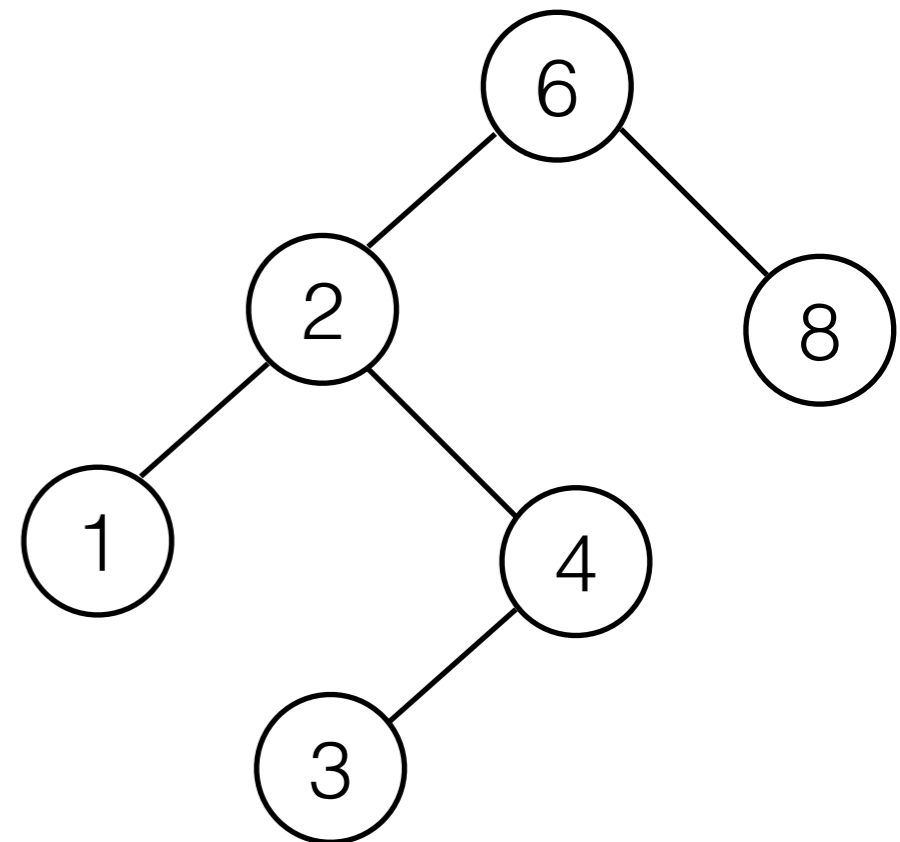




# BST operations: insert

- Follow same steps as `contains(X)`
- if `X` is found, do nothing.
- Otherwise, `contains` stopped at node `n`.  
Insert a new node for `X` as a left or right child of `n`.

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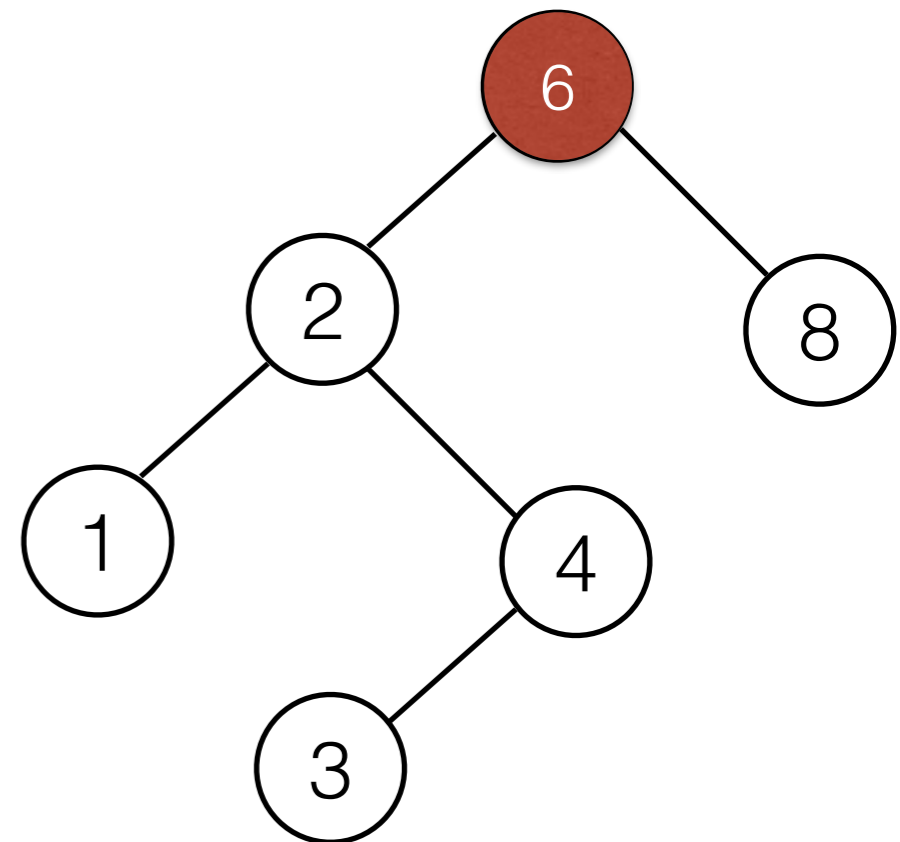
Maintains the BST property.

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`insert(5)`

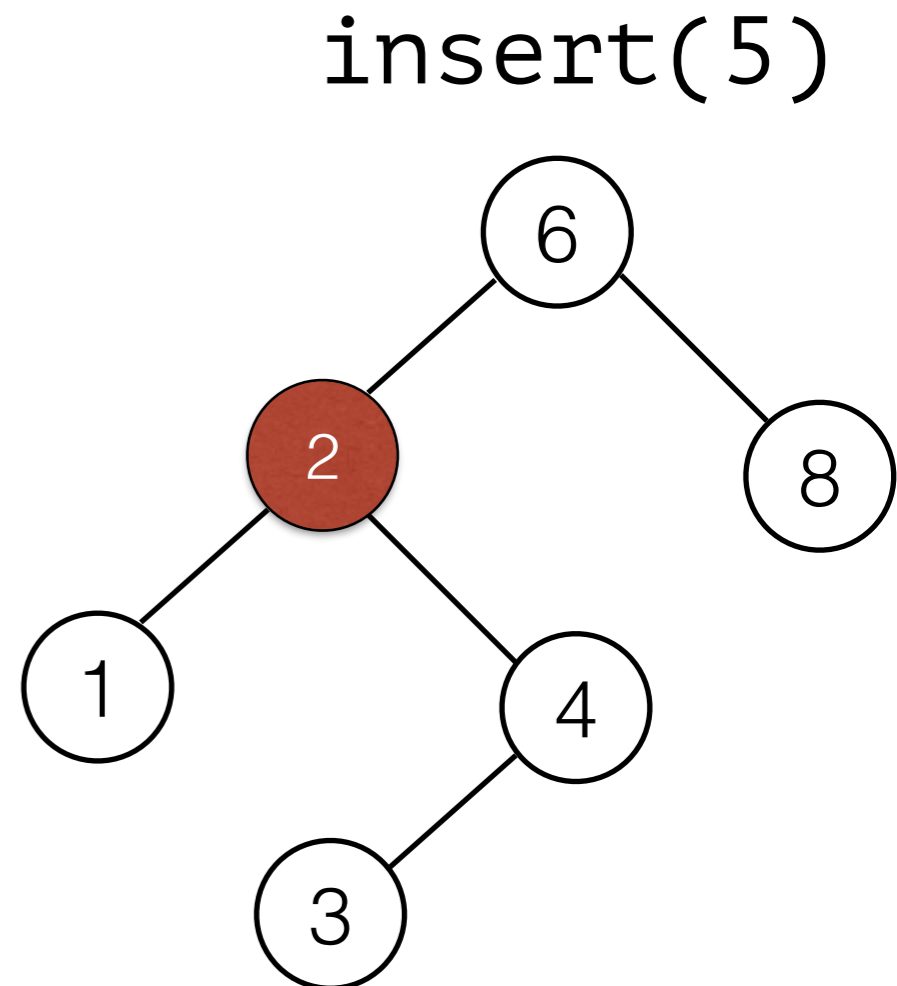


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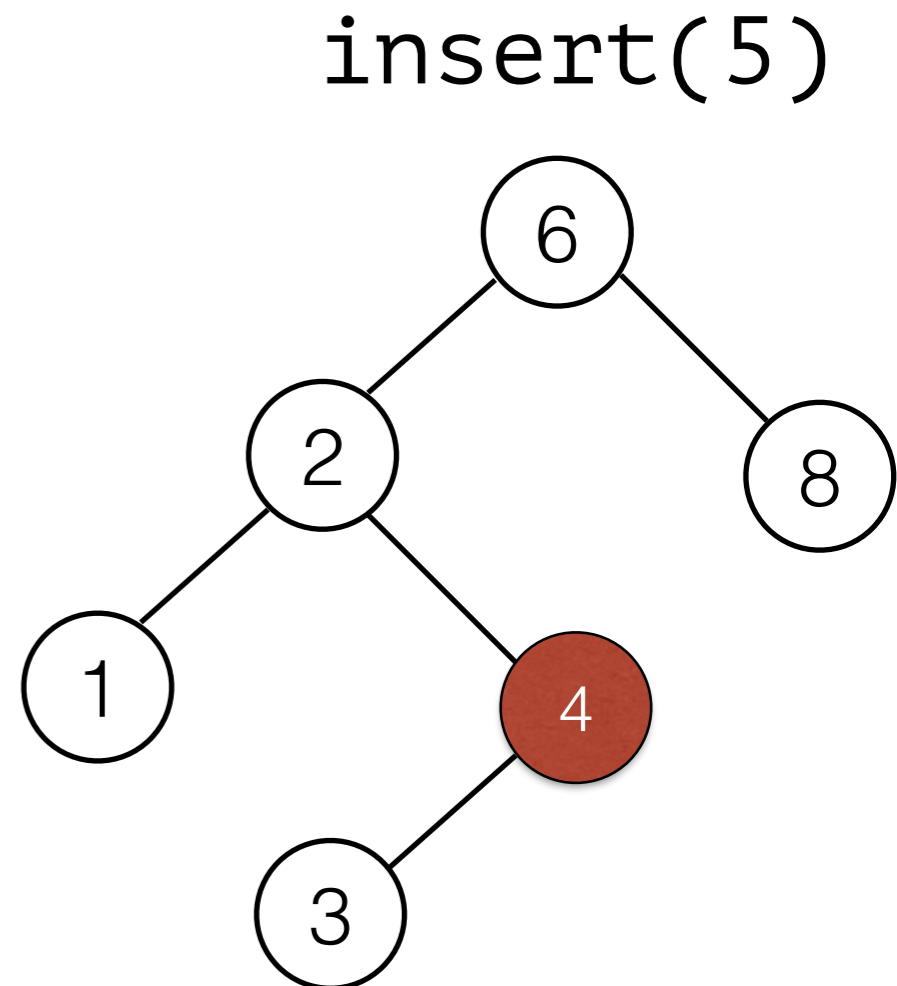


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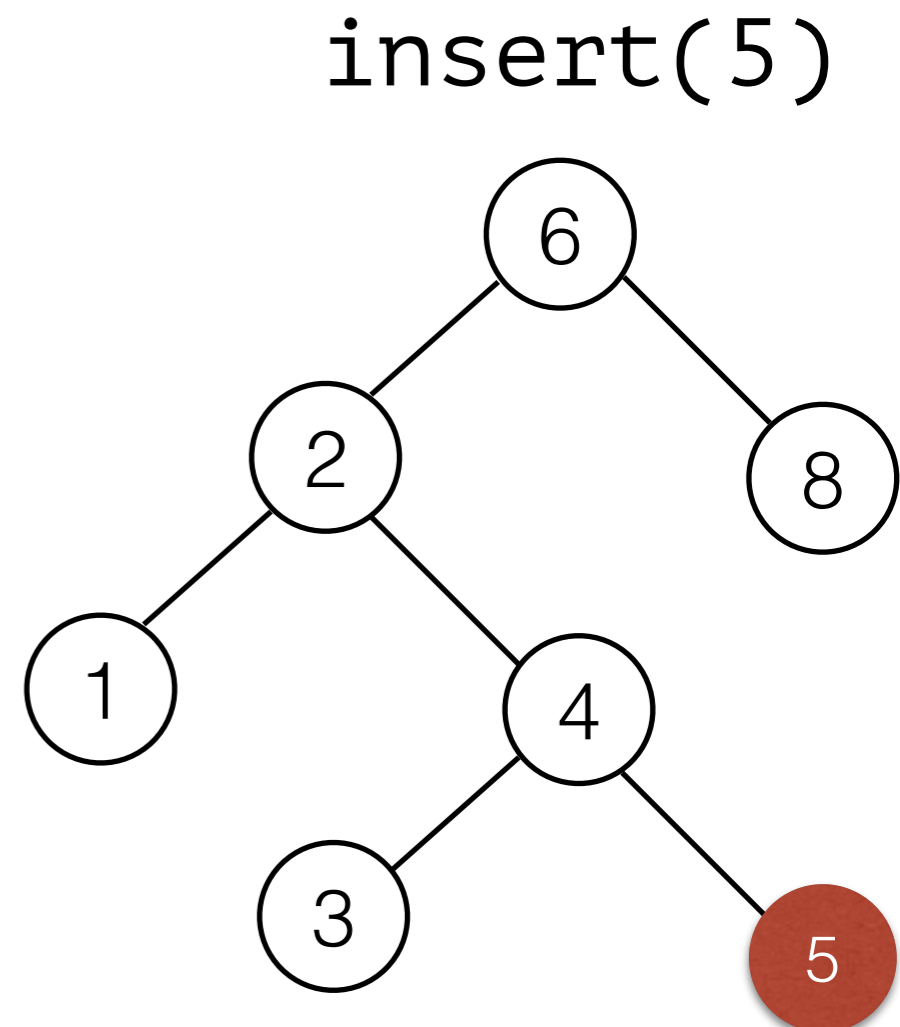
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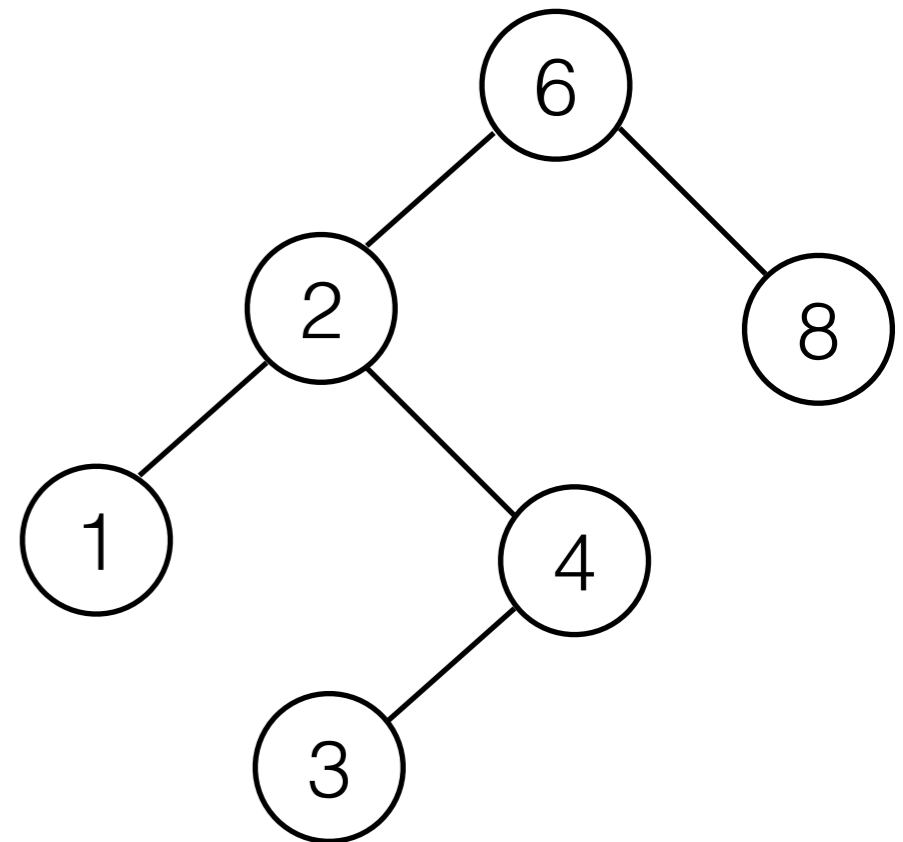
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# BST operations: remove

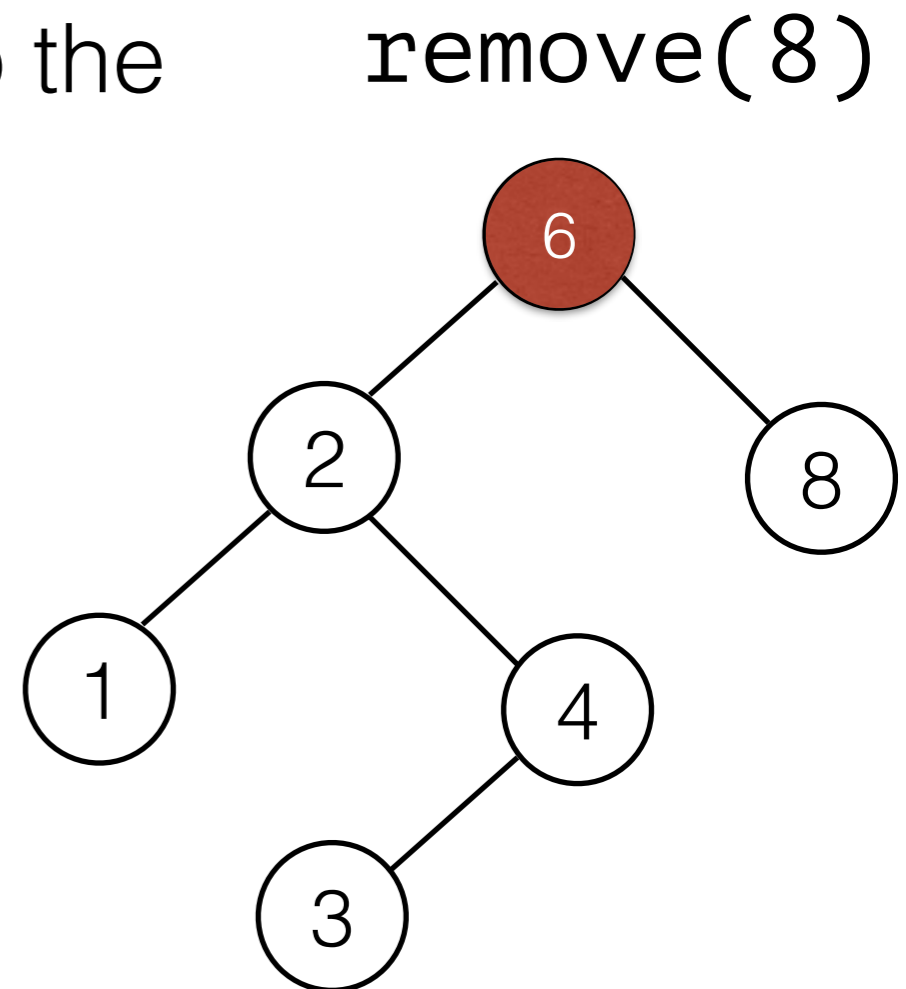
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Maintains the BST property.

# BST operations: `remove`

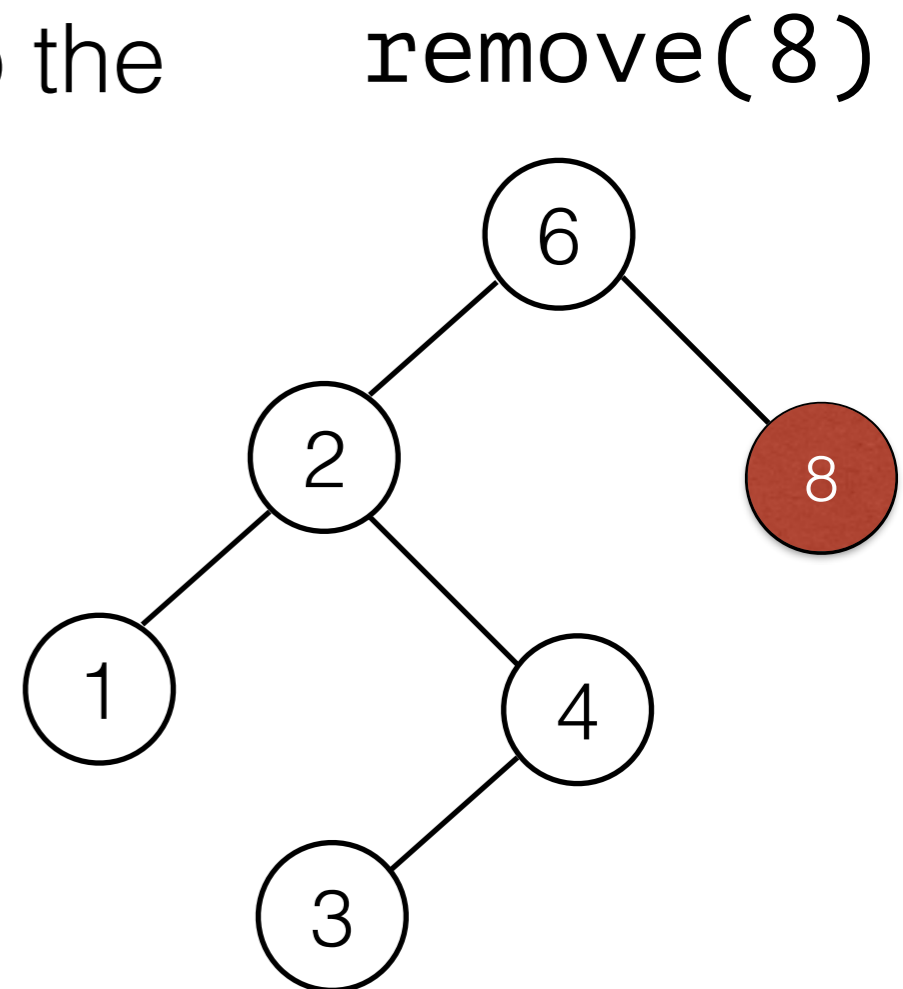
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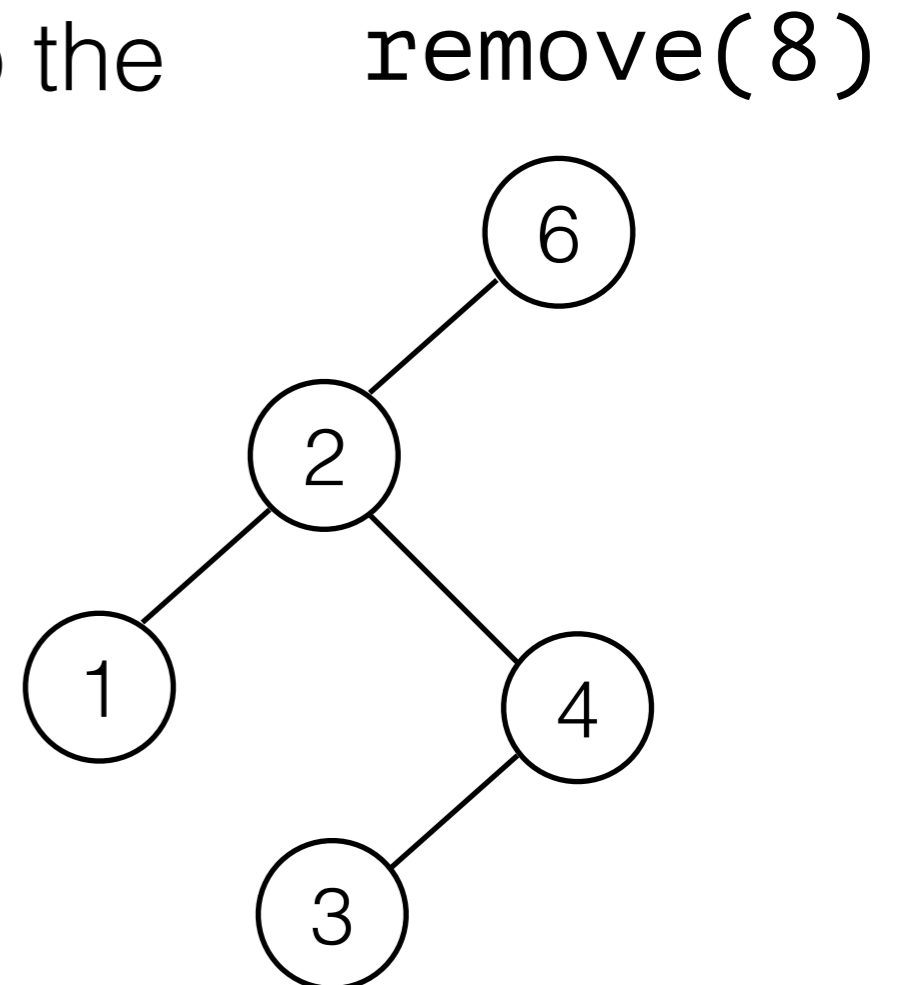


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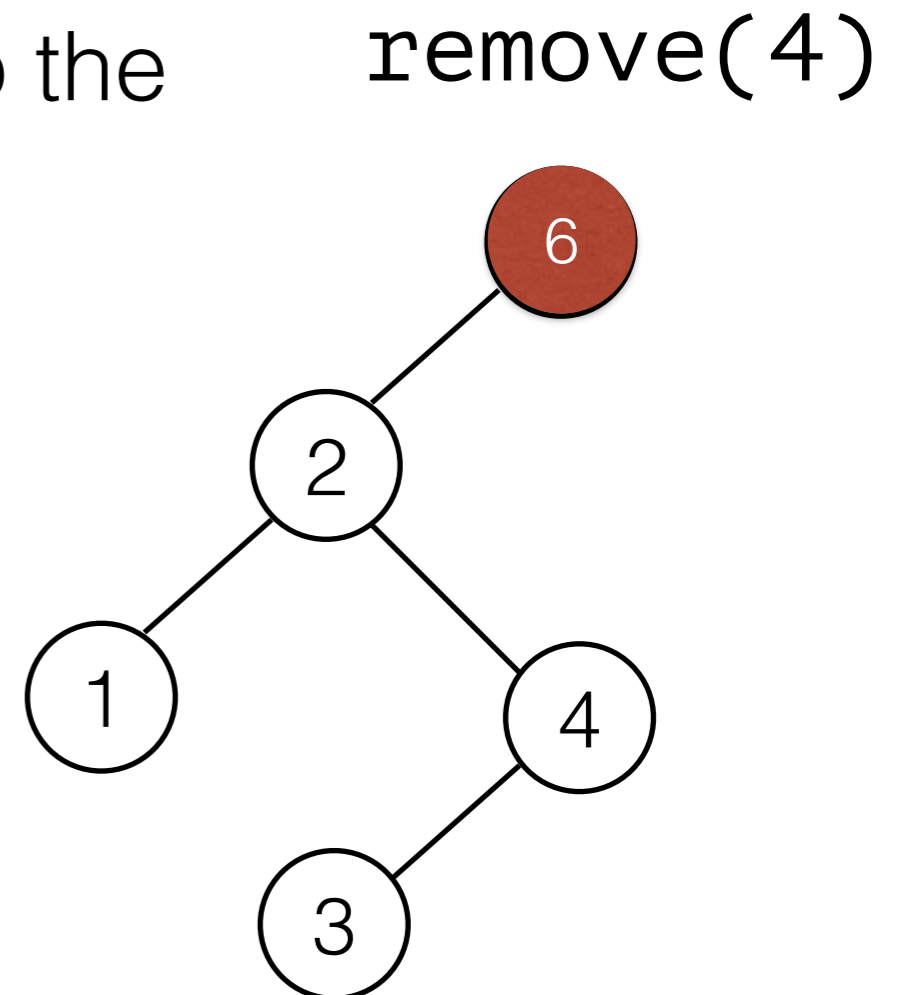
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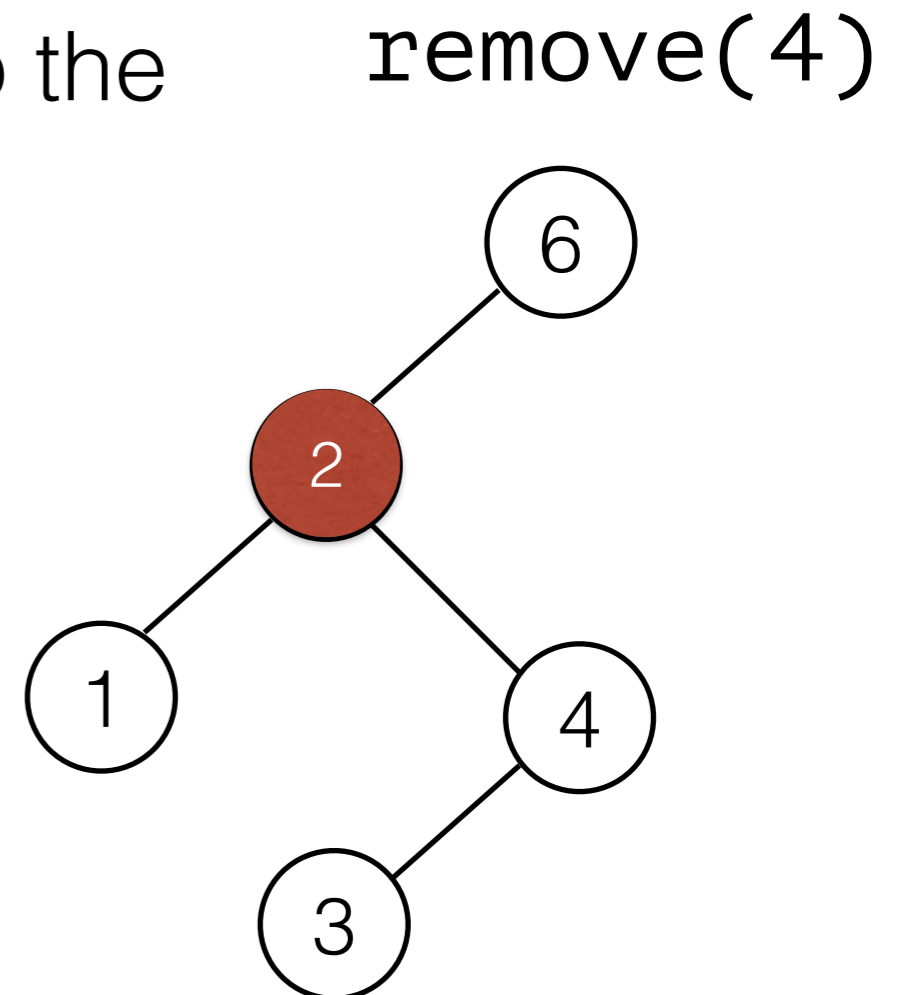
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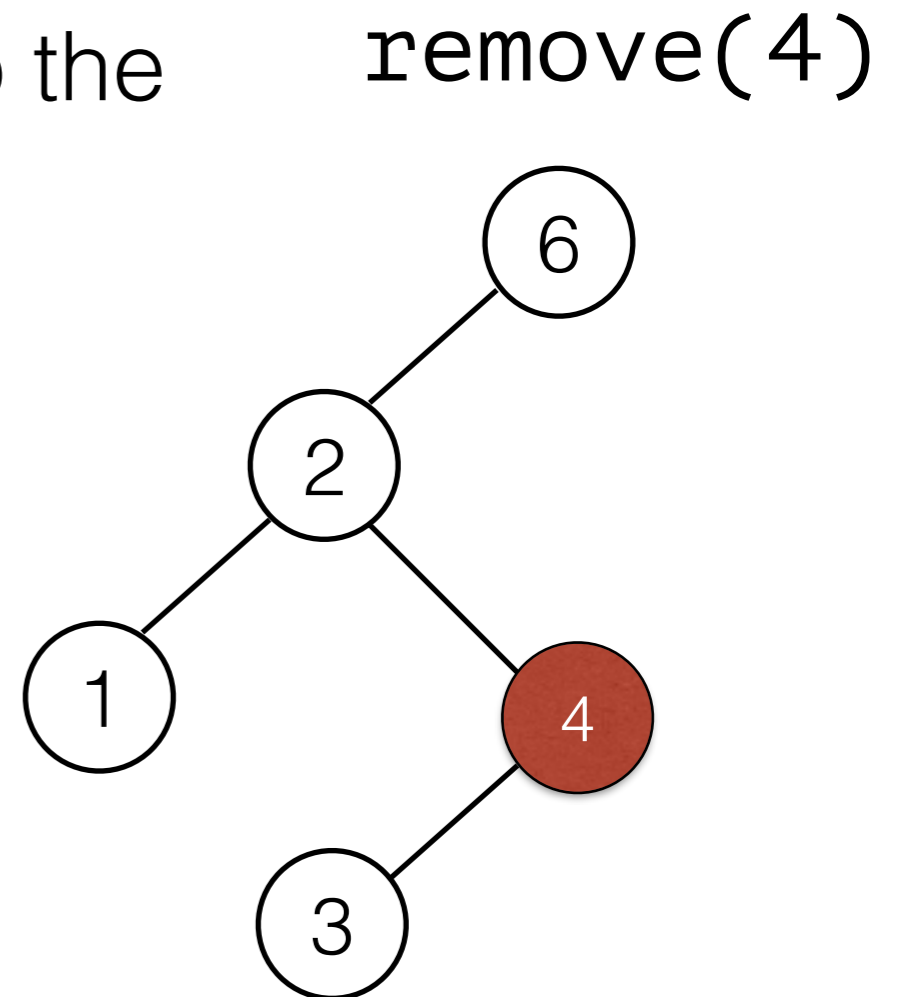
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# BST operations: `remove`

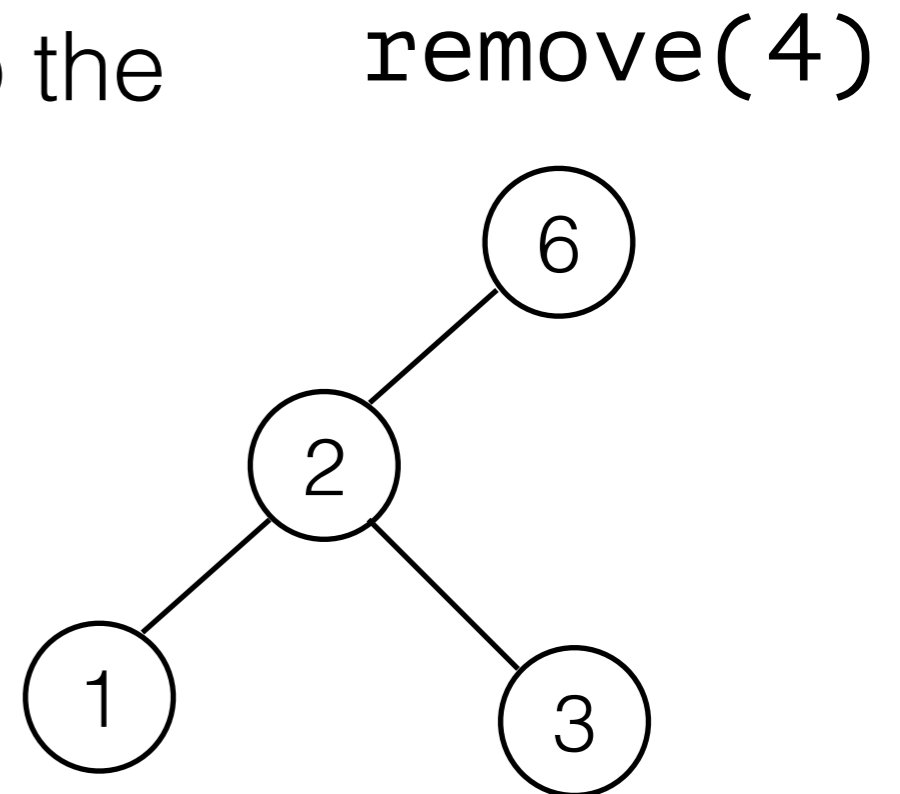
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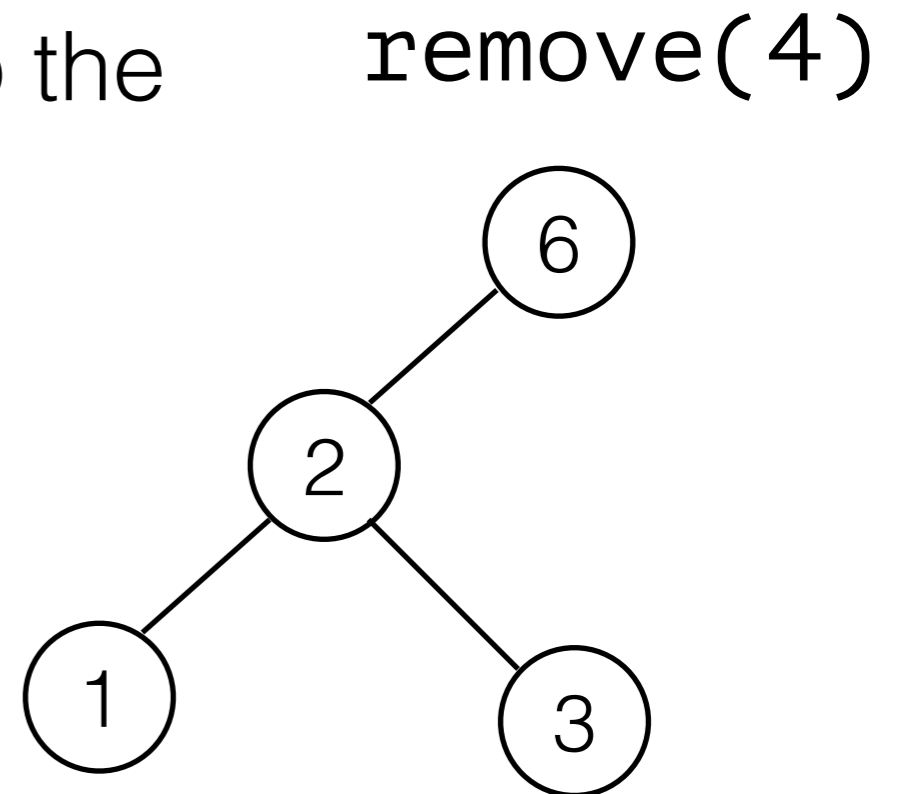
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# BST operations: `remove`

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  - if  $s$  has a single child  $t$ , attach  $t$  to the parent of  $s$ , in place of  $s$ .
  - what if  $s$  has two children?



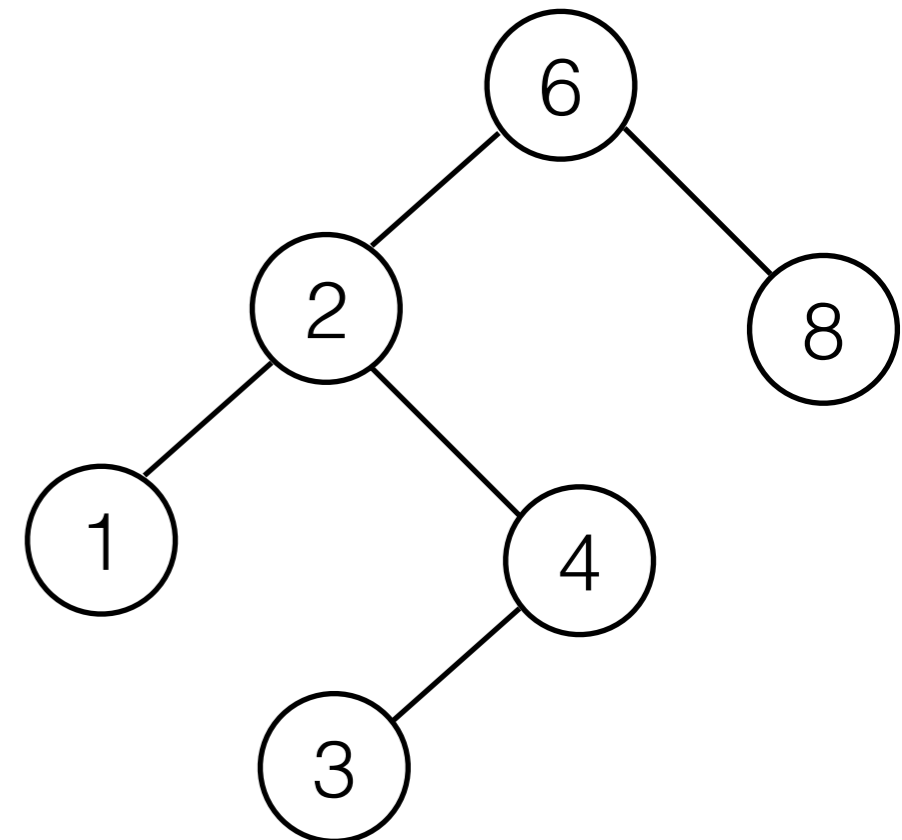
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# BST operations: remove

- If  $x$  is found in a node  $s$  that has two children  $t_{\text{left}}$  and  $t_{\text{right}}$ :
  - Find the smallest node  $u$  in the subtree rooted in  $t_{\text{right}}$ .
  - replace value of  $s$  with value of  $u$ .
  - recursively remove  $u$ .

To maintain the BST property, the node to replace  $s$  needs to be

- larger than any node in the left subtree
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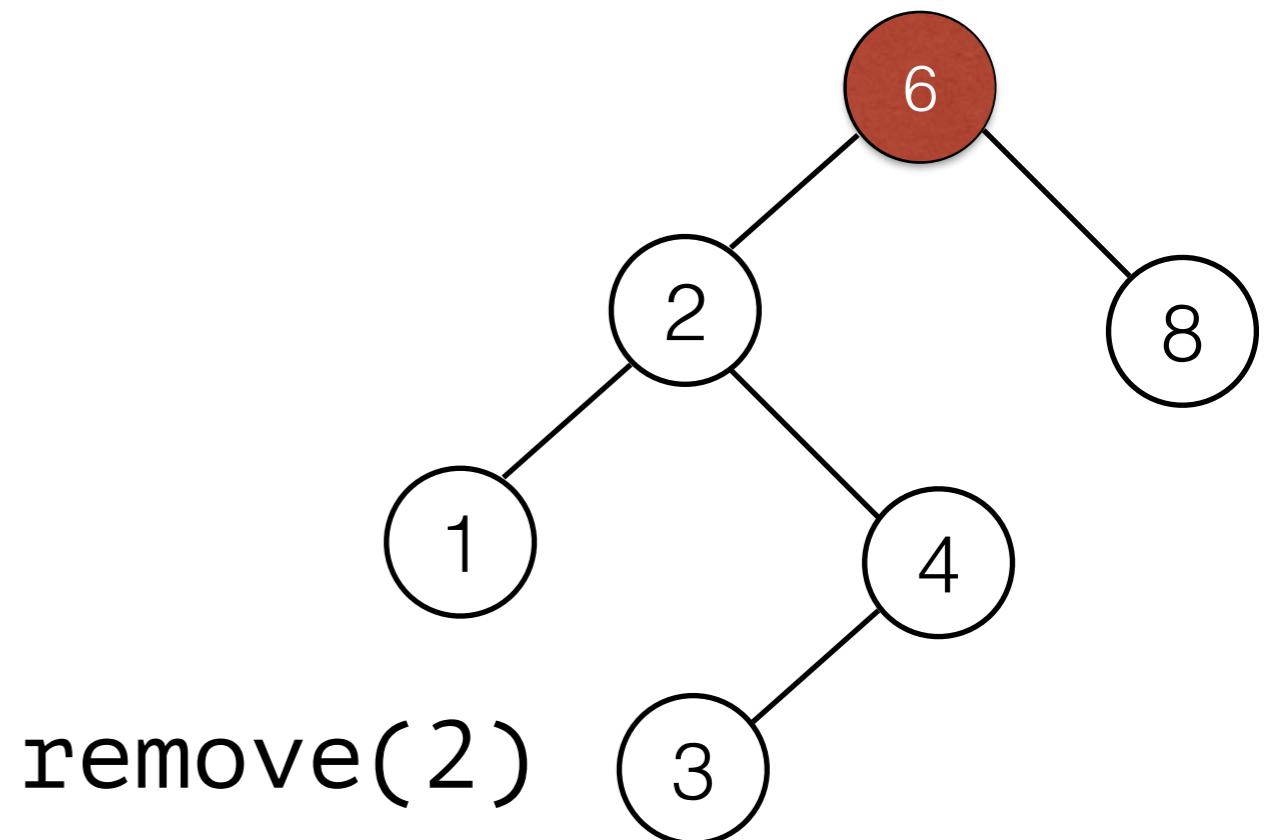


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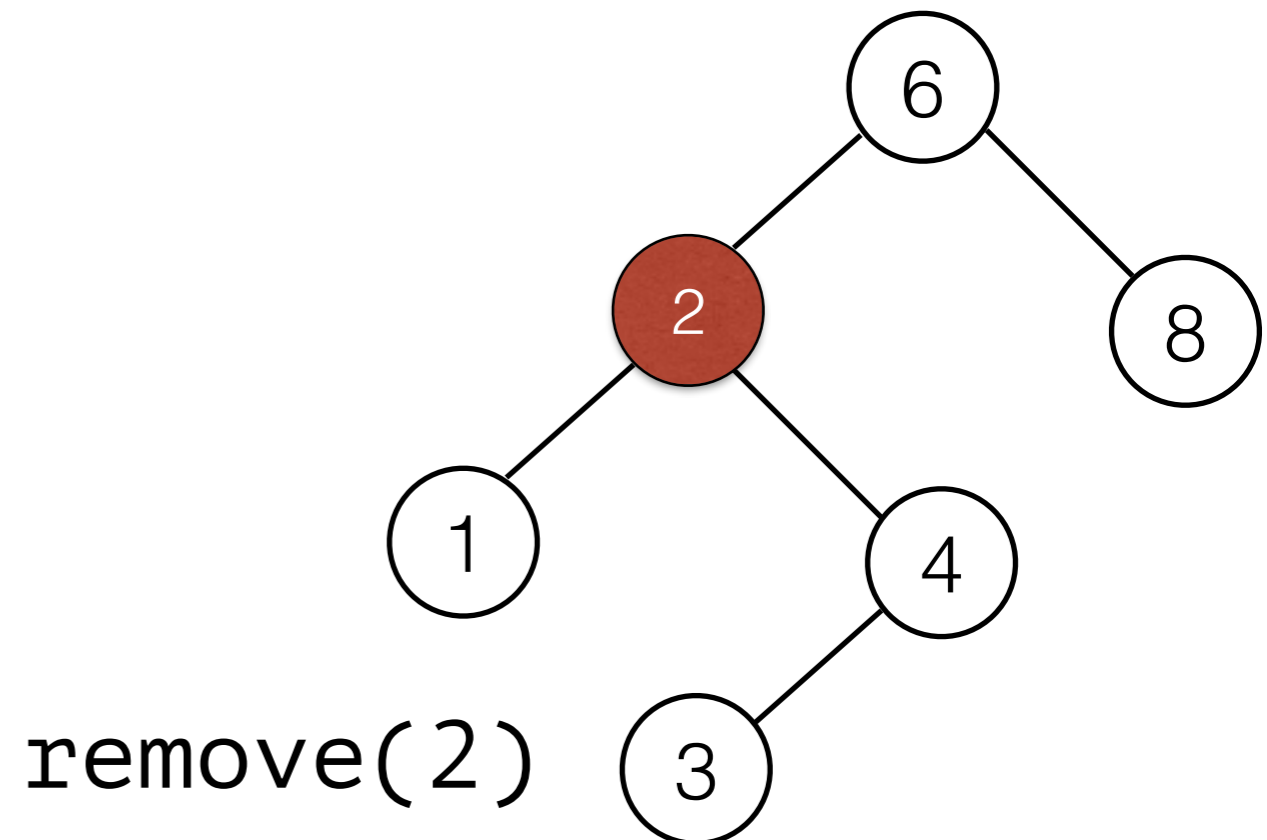


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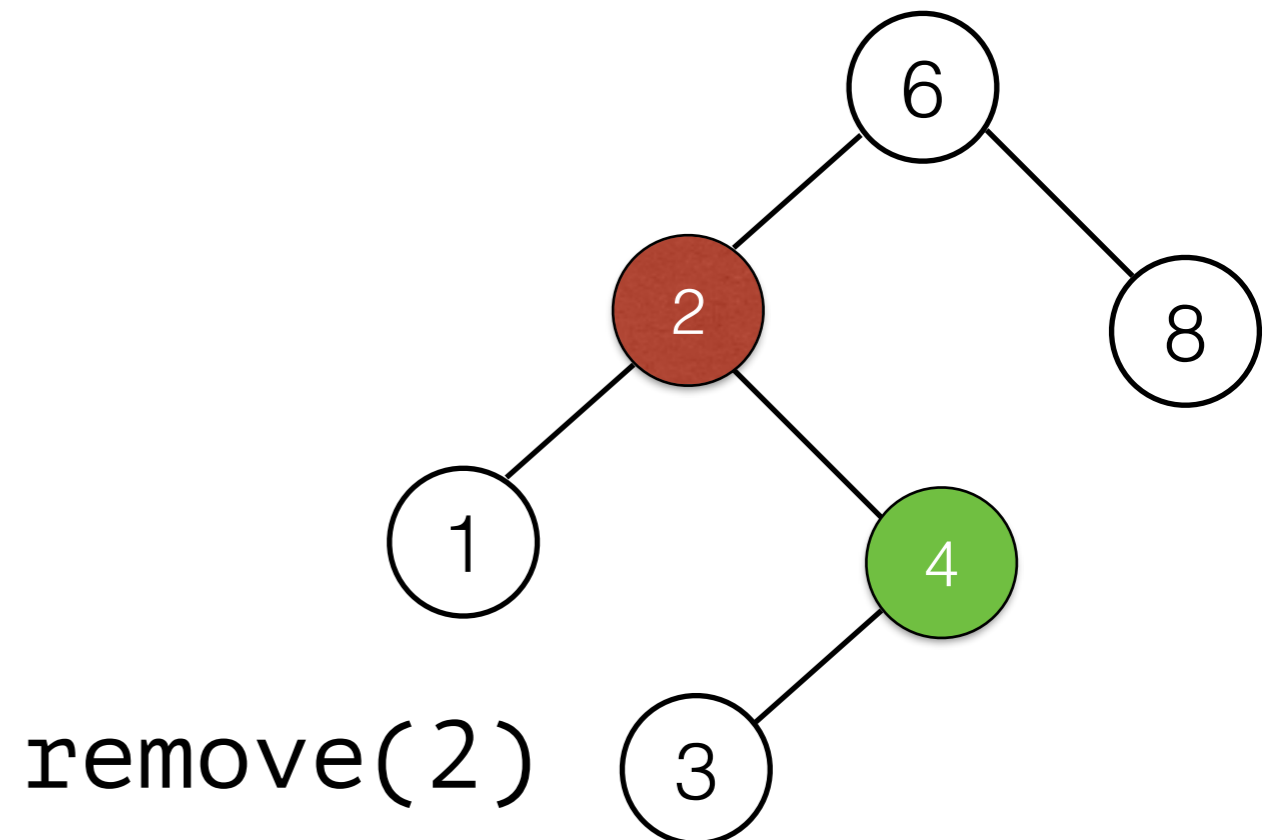


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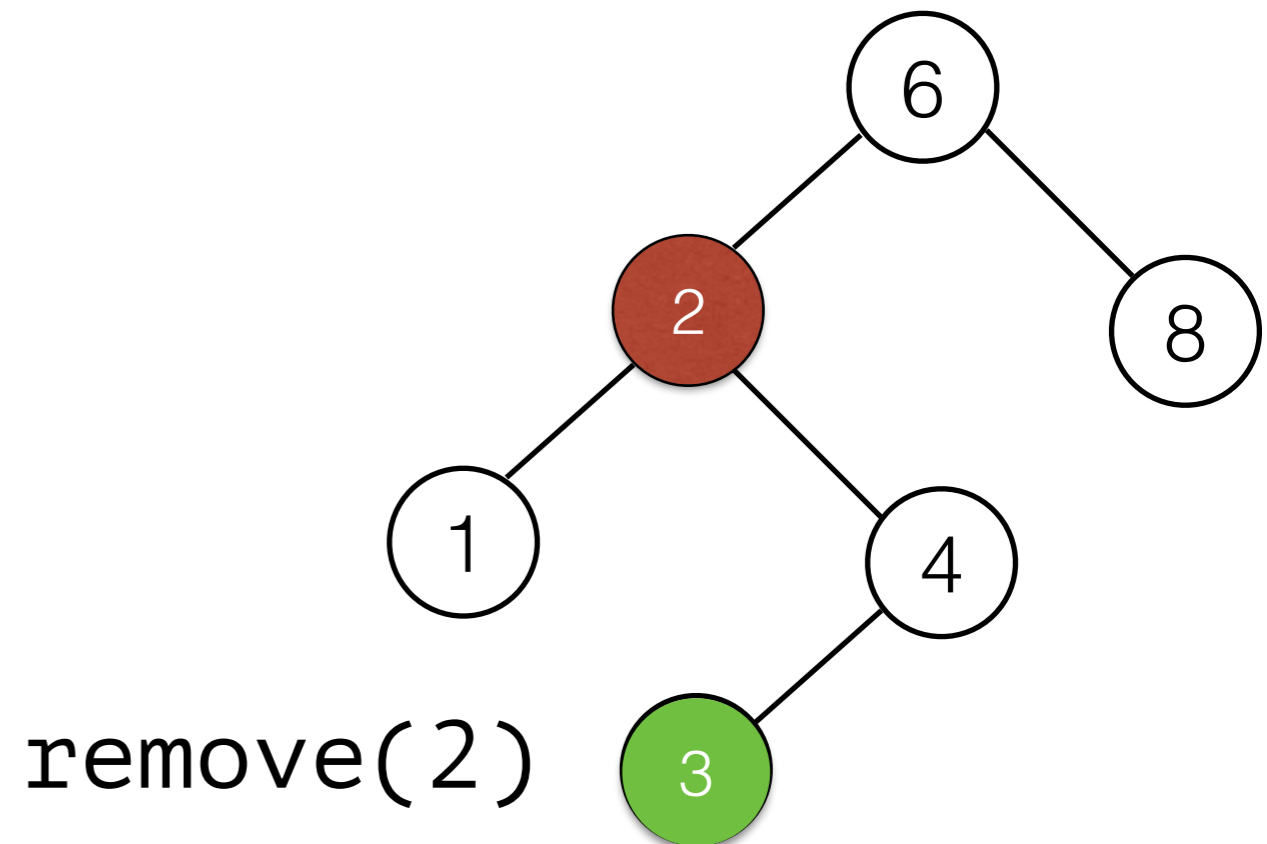


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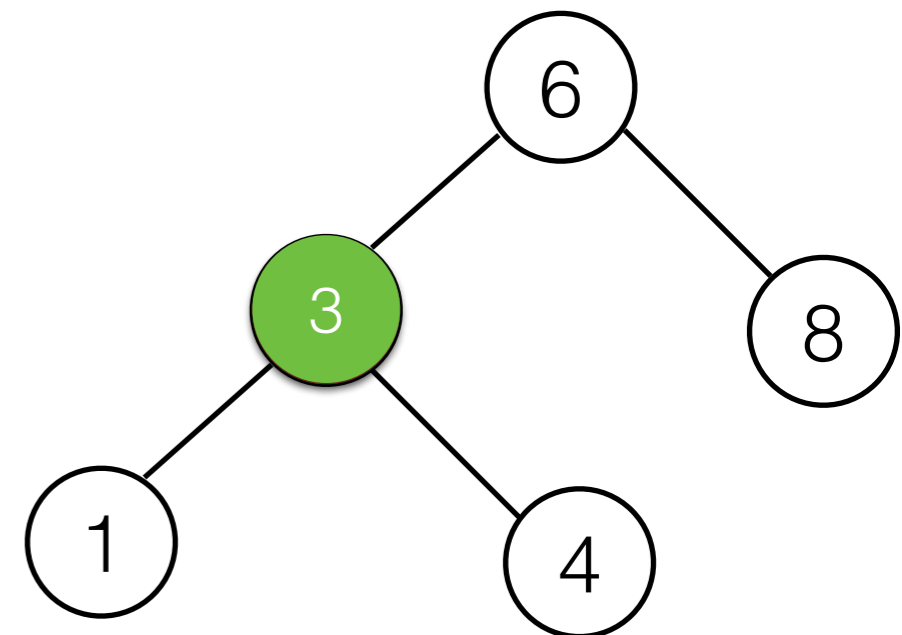


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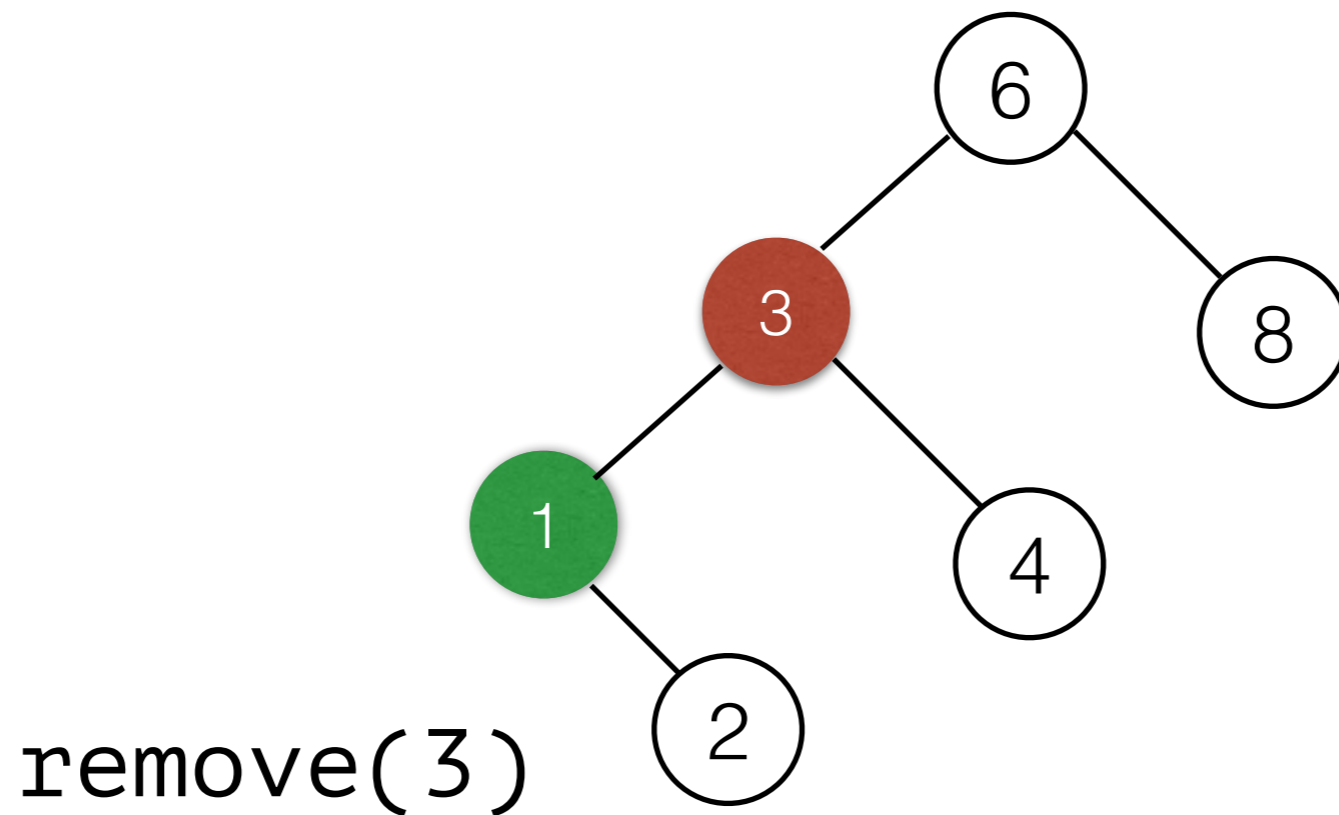
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`remove(2)`

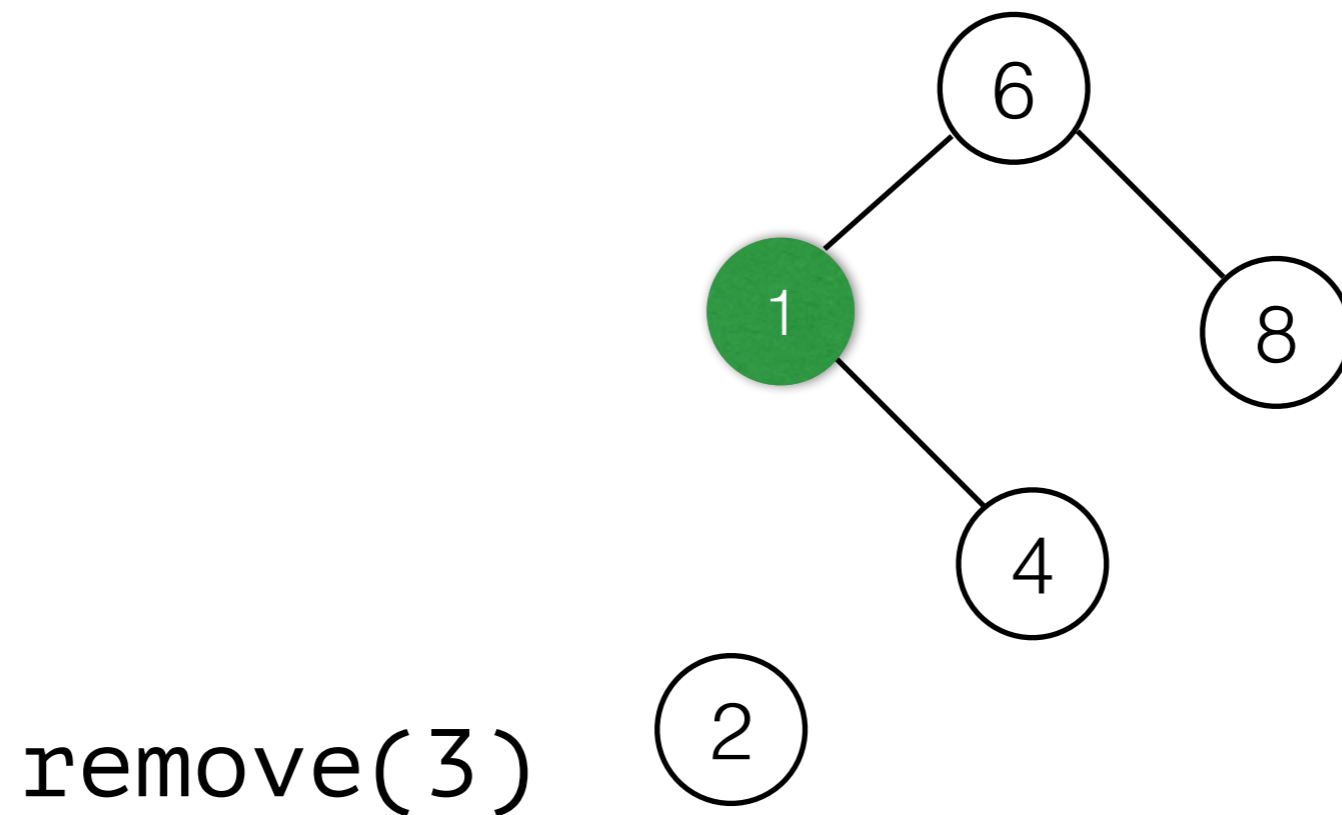
# BST operations: `remove`

- Why not just replace `s` with the root of `tleft`?



# BST operations: `remove`

- Why not just replace `s` with the root of `tleft`?



# Implementing remove

```
private BinaryNode remove( Integer x, BinaryNode t ){
    if( t == null )
        return t; // Item not found; do nothing

    if (x < t.data )
        t.left = remove( x, t.left );
    else if(t.data < x )
        t.right = remove( x, t.right );

    else //found x
        if( t.left != null && t.right != null ) { // 2 children
            t.element = findMin( t.right ).element;
            t.right = remove( t.element, t.right );
        } else
            if (t.left != null) // 1 or 0 children.
                return t.left;
            else
                return t.right;
}
```

# Running Time Analysis

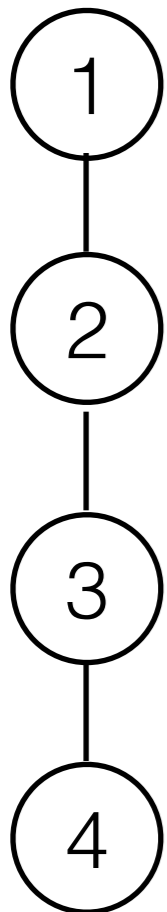
- How long do the BST operations take?
- Given a BST  $T$ , we need a single pass down the tree to access some node  $s$  in  $depth(s)$  steps.
- What is the best/expected/worst-case depth of a node in any BST?



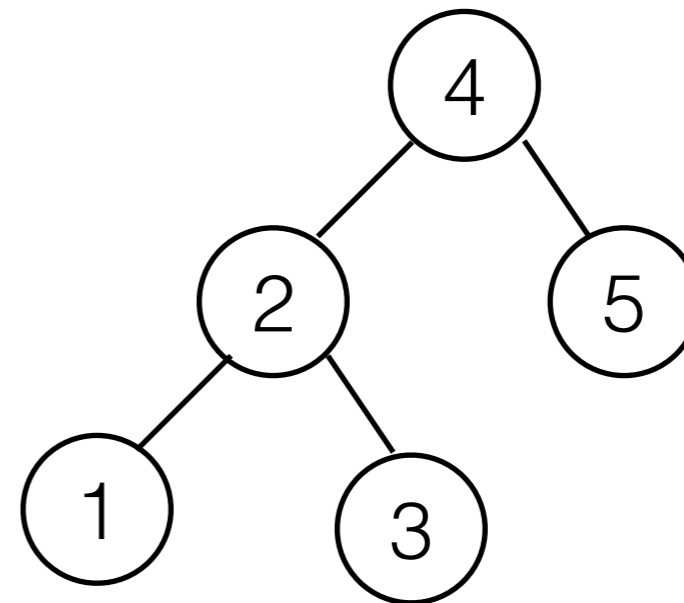
# Worst and Best Case Height of a BST

- Assume we have a BST with  $N$  nodes.

- Worst case:  $T$  does not branch  $height(T)=N$



- Best case:  $height(T)=\log N$

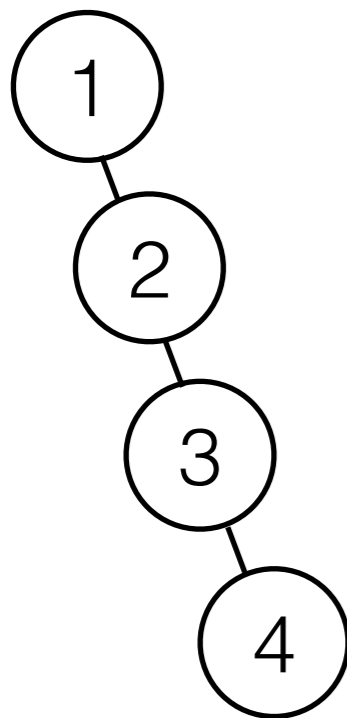


**complete binary tree.**

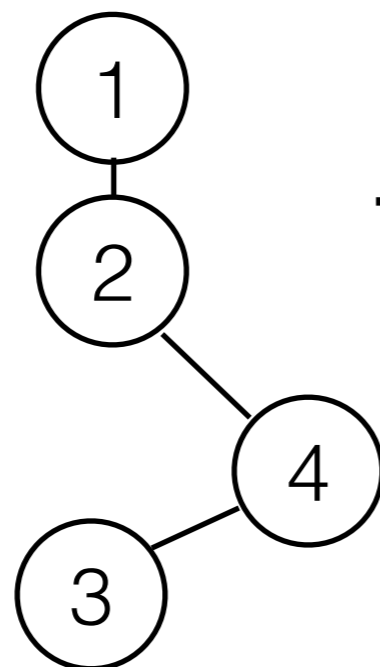
# Random BSTs

- Assume we have  $N$  elements. All  $N!$  permutations of these elements are equally likely.
- We insert items in the order of any permutation into an initially empty BST. What is the average depth of a node?

[1 2 3 4]

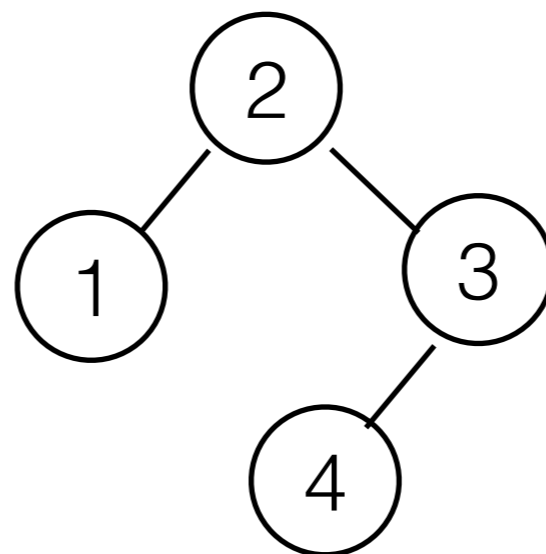


[1 2 4 3]

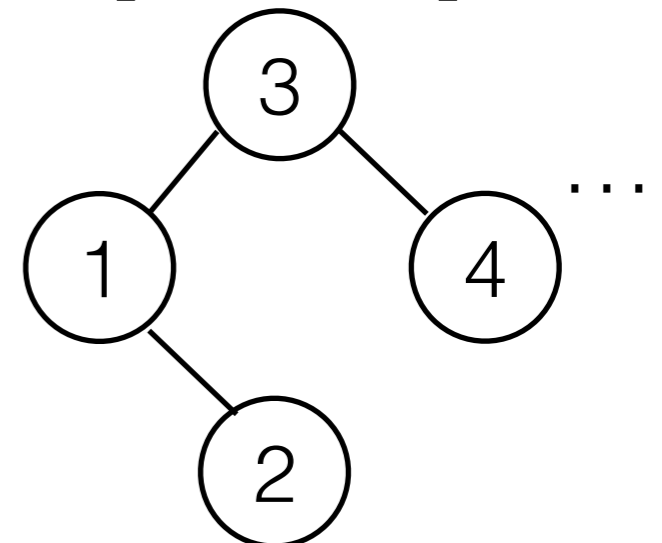


...

[2 3 4 1]

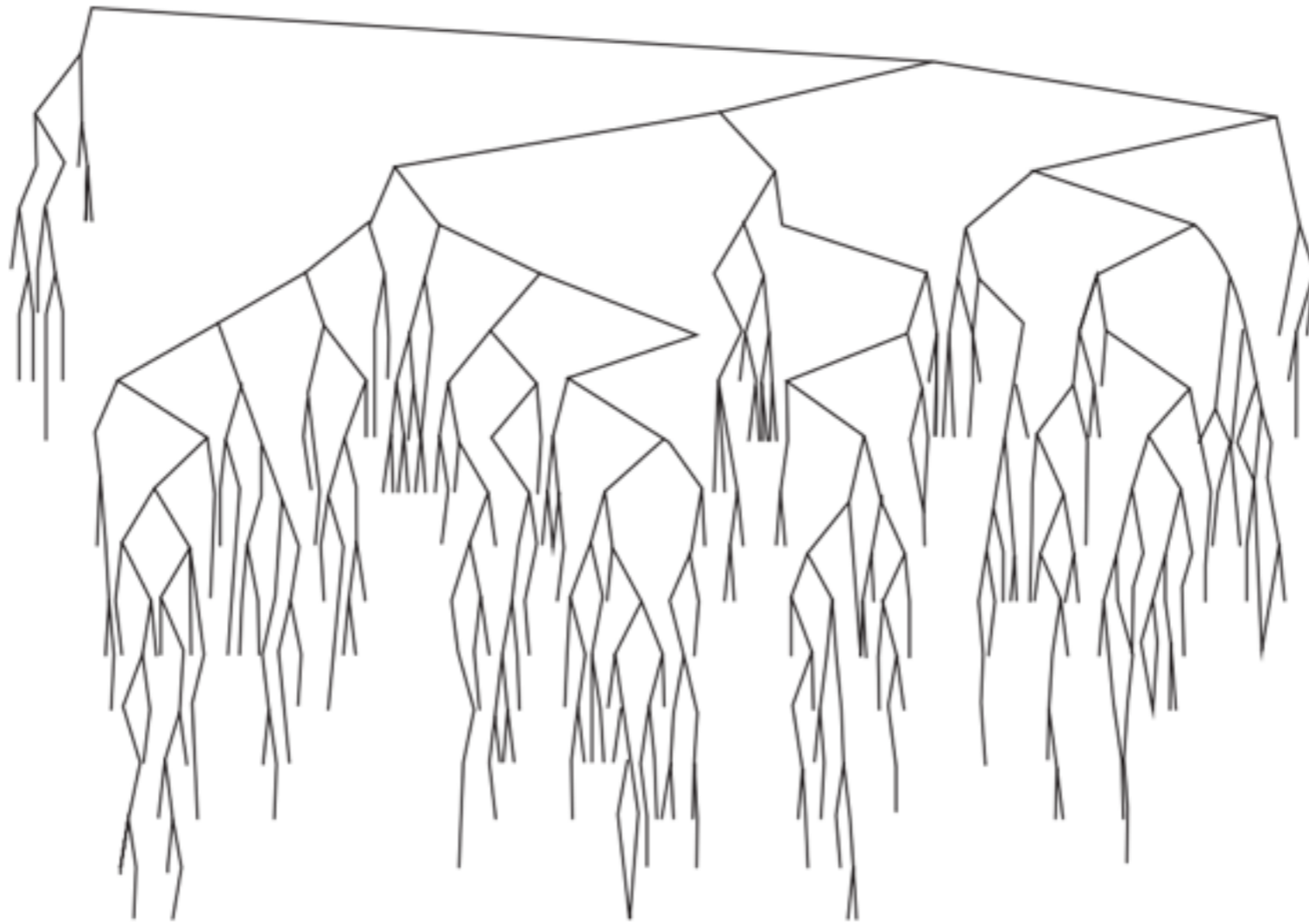


[3 1 2 4]



# Randomly generated BST

$N=500$ , average depth = 9.89



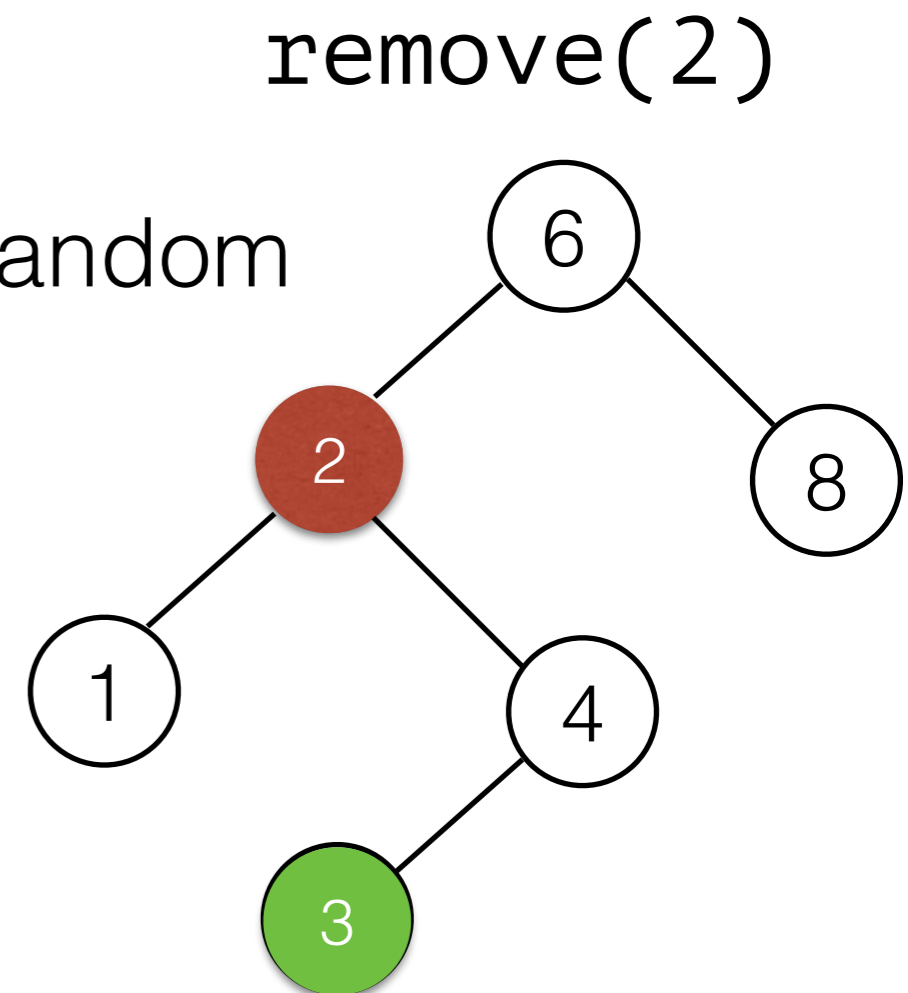
Theoretical analysis of random BSTs: Average depth of a node  
in a random BST of  $N$  nodes is about

$$2 \log N = O(\log N)$$

# What about Different Sequences of Operations?

- The expected depth of a random BST (insertions of a random permutation of elements) is  $O(\log N)$ .

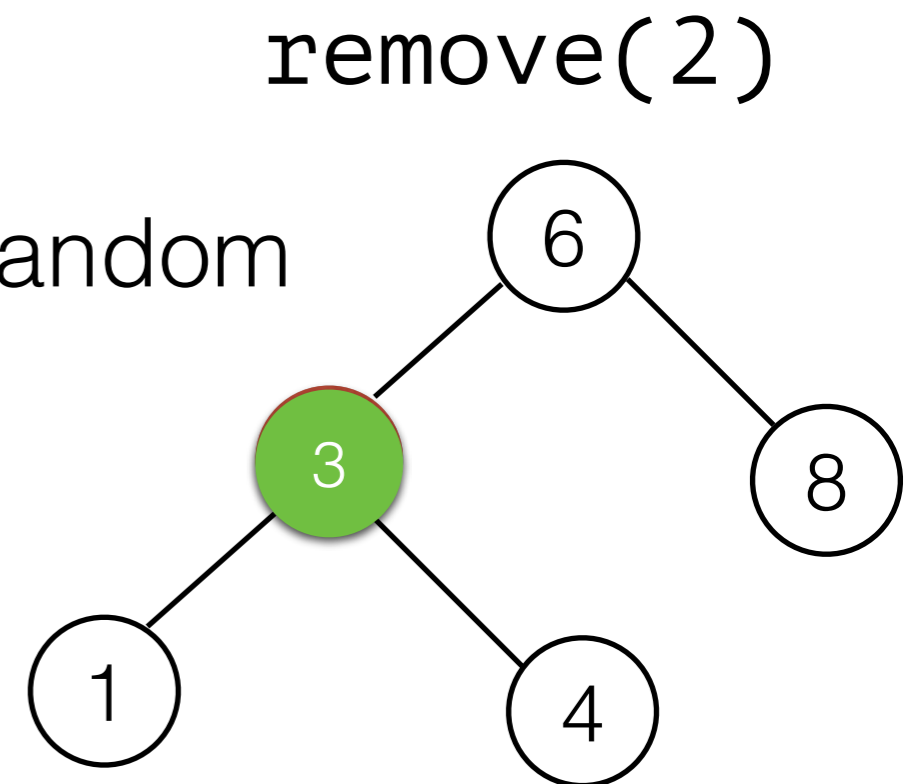
- But what happens if there are also random deletions?
- Deletion produces shorter right subtrees.



# What about Different Sequences of Operations?

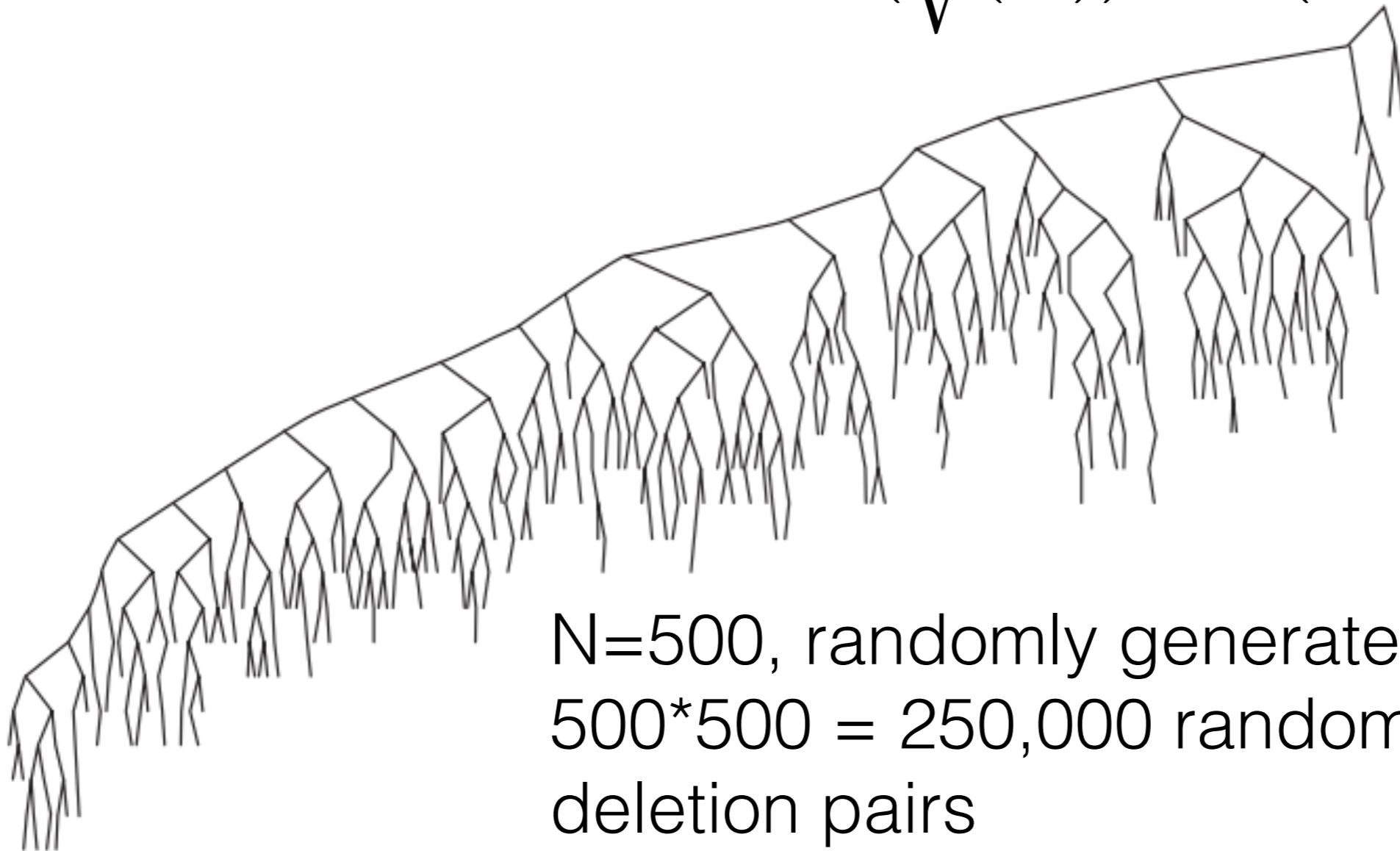
- The expected depth of a random BST (insertions of a random permutation of elements) is  $O(\log N)$ .

- But what happens if there are also random deletions?
- Deletion produces shorter right subtrees.



# Random Insertions and Deletions

- After  $\Theta(N^2)$  alternating insertion/deletion pairs, the expected depth is  $\Theta(\sqrt{N}) = \Theta(N^{1/2})$



$N=500$ , randomly generated as before.  
 $500 \cdot 500 = 250,000$  random insertion/  
deletion pairs

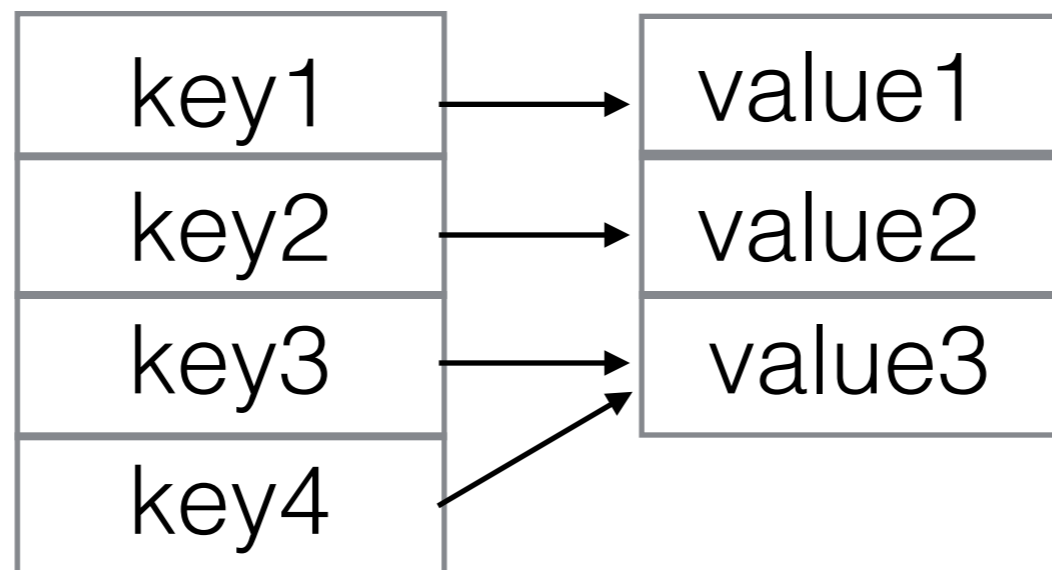
# Contents

1. Binary Search Trees

**2. Implementing Maps with BSTs**

# Map ADT

- A *map* is collection of *(key, value)* pairs.
- Keys are unique, values need not be.
- Two operations:
  - `get(key)` returns the value associated with this key
  - `put(key, value)` (overwrites existing keys)

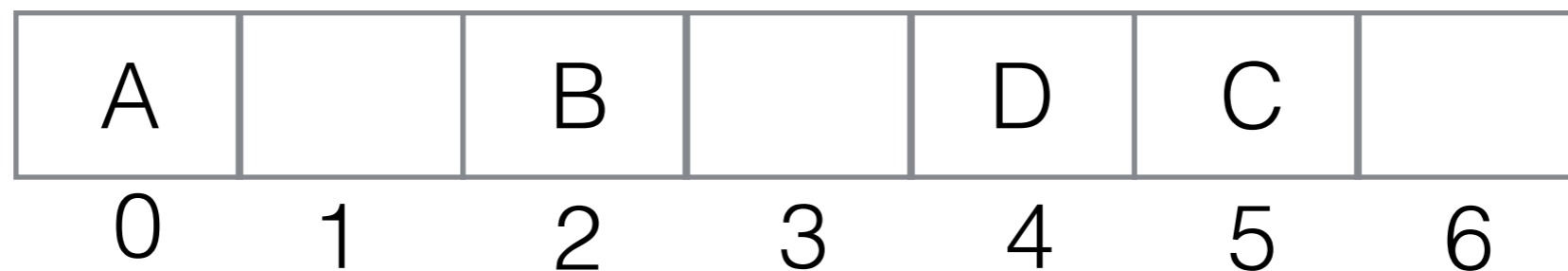


How do we implement map operations efficiently?



# Arrays as Maps

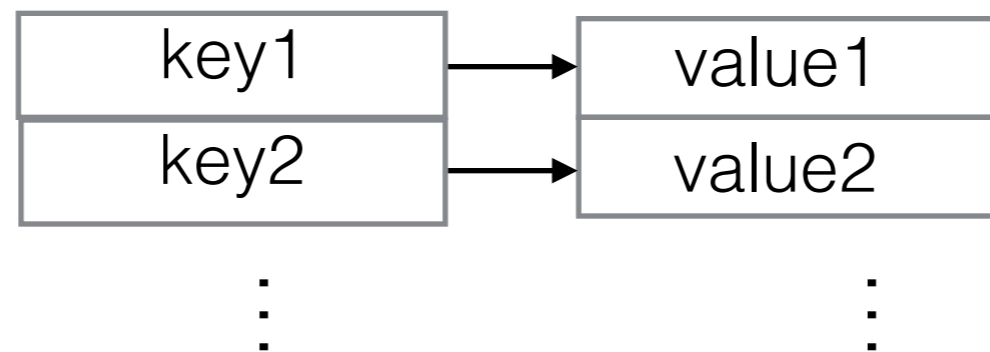
- When keys are integers, arrays provide a convenient way of implementing maps.
- Time for `get` and `put` is  $O(1)$ .



- What if we don't have integer keys?

# Comparing Complex Items

- So far, our BSTs contained `Integers`.
- One Goal of BSTs: Implement efficient lookup for Map keys and sorted Sets.



- We can implement generic BSTs that can contain any kind of element, including (key,value) pairs.
- But we must be able to *sort* the elements, i.e. compare them using `<`, `>`, and `=`. The (key, value) pair class should implement `Comparable`.

# Example (key/value) Pair Implementation

```
private class Pair<K extends Comparable<K>, V>  
    implements Comparable<Pair<K, ?>> {  
    public K key;  
    public V value;  
  
    public Pair(K theKey, V theValue) {  
        key = theKey; value = theValue;  
    }  
  
    @Override  
    public int compareTo(Pair<K, ?> other) {  
        return key.compareTo(other.key);  
    }  
}
```

# Implementing Maps with BSTs

(see example code)