

Steiner Point Removal with Distortion $O(\log k)$

Arnold Filtser

Ben-Gurion University

April 26, 2018

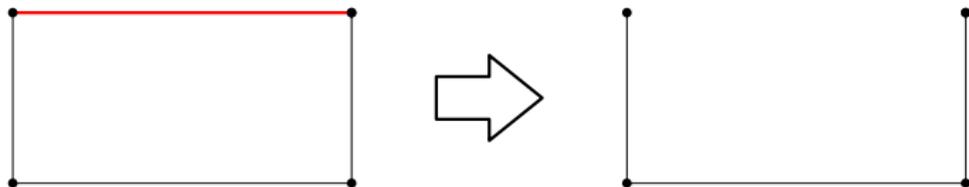
Graph Minor

H is a **minor** of $G = (V, E)$ if H can be **formed** from G by:

Graph Minor

H is a **minor** of $G = (V, E)$ if H can be **formed** from G by:

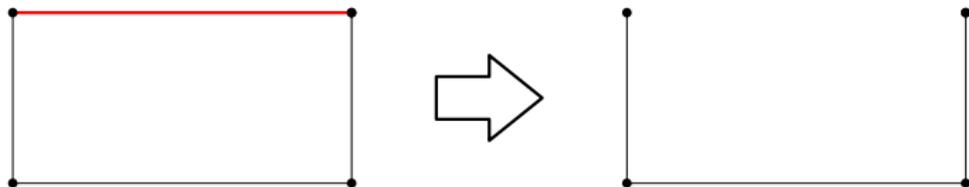
- Deleting edges.



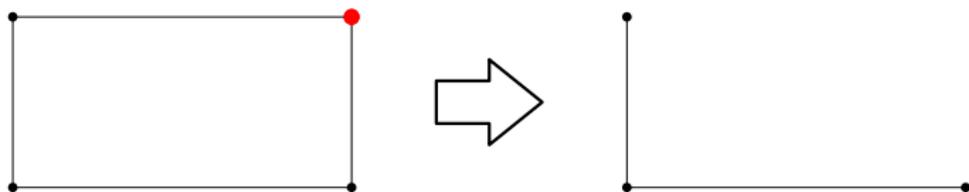
Graph Minor

H is a **minor** of $G = (V, E)$ if H can be **formed** from G by:

- Deleting edges.



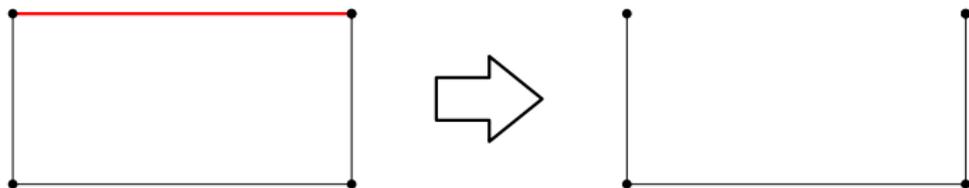
- Deleting vertices.



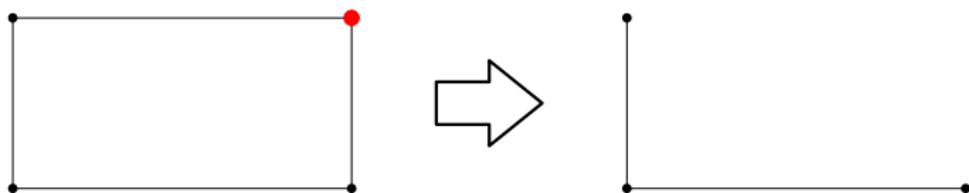
Graph Minor

H is a **minor** of $G = (V, E)$ if H can be **formed** from G by:

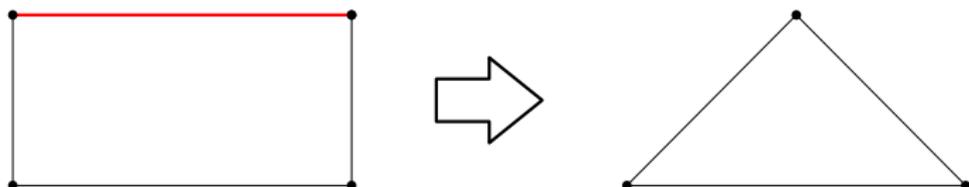
- Deleting edges.



- Deleting vertices.



- Contracting edges.



Steiner Point removal problem

$G = (V, E, w)$ - a **weighted** graph.

$K \subseteq V$ - a **terminal** set of size k .

Steiner Point removal problem

$G = (V, E, w)$ - a **weighted** graph.

$K \subseteq V$ - a **terminal** set of size k .

Construct a new graph $M = (K, E', w_M)$ such that:

Steiner Point removal problem

$G = (V, E, w)$ - a **weighted** graph.

$K \subseteq V$ - a **terminal** set of size k .

Construct a new graph $M = (K, E', w_M)$ such that:

- M has small **distortion**:

$$\forall t, t' \in K, \quad d_G(t, t') \leq d_M(t, t') \leq \alpha \cdot d_G(t, t') .$$

Steiner Point removal problem

$G = (V, E, w)$ - a **weighted** graph.

$K \subseteq V$ - a **terminal** set of size k .

Construct a new graph $M = (K, E', w_M)$ such that:

- M has small **distortion**:

$$\forall t, t' \in K, \quad d_G(t, t') \leq d_M(t, t') \leq \alpha \cdot d_G(t, t') .$$

- M is a graph **minor** of G .

Steiner Point removal problem

$G = (V, E, w)$ - a **weighted** graph.

$K \subseteq V$ - a **terminal** set of size k .

Construct a new graph $M = (K, E', w_M)$ such that:

- M has small **distortion**:

$$\forall t, t' \in K, \quad d_G(t, t') \leq d_M(t, t') \leq \alpha \cdot d_G(t, t').$$

- M is a graph **minor** of G .

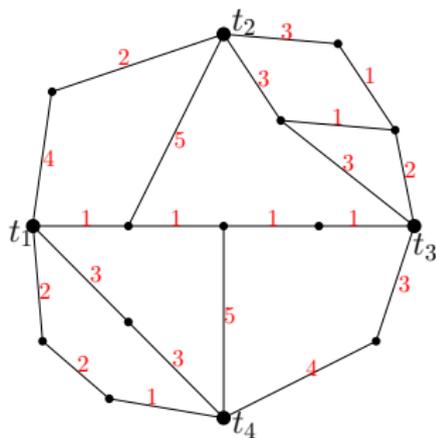


The distortion is: $\frac{d_M(t, t')}{d_G(t, t')} = \frac{4}{2} = 2$

Terminal Partitions and Induced Minor

Partition $\{V_1, \dots, V_k\}$ of V is called a **terminal partition** if for all i ,

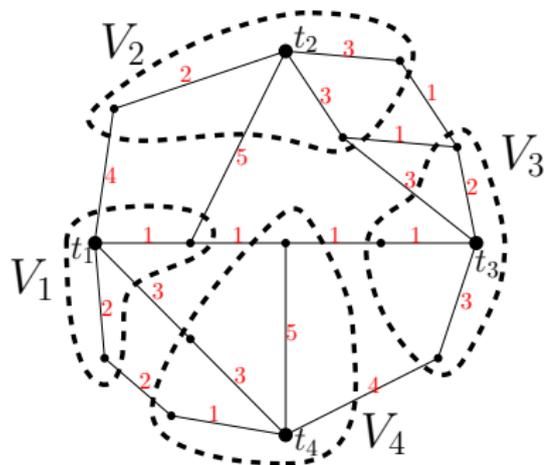
- $t_i \in V_i$.
- V_i is **connected**.



Terminal Partitions and Induced Minor

Partition $\{V_1, \dots, V_k\}$ of V is called a **terminal partition** if for all i ,

- $t_i \in V_i$.
- V_i is **connected**.

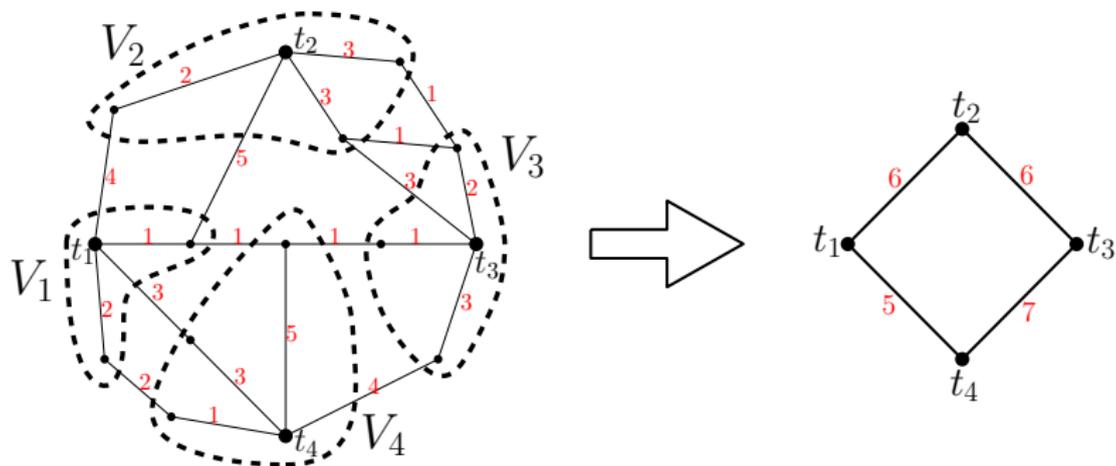


Terminal Partitions and Induced Minor

Partition $\{V_1, \dots, V_k\}$ of V is called a **terminal partition** if for all i ,

- $t_i \in V_i$.
- V_i is **connected**.

Given a terminal partition $P = \{V_1, \dots, V_k\}$, the **induced minor** M is obtained by **contracting** all the internal edges in each V_i .



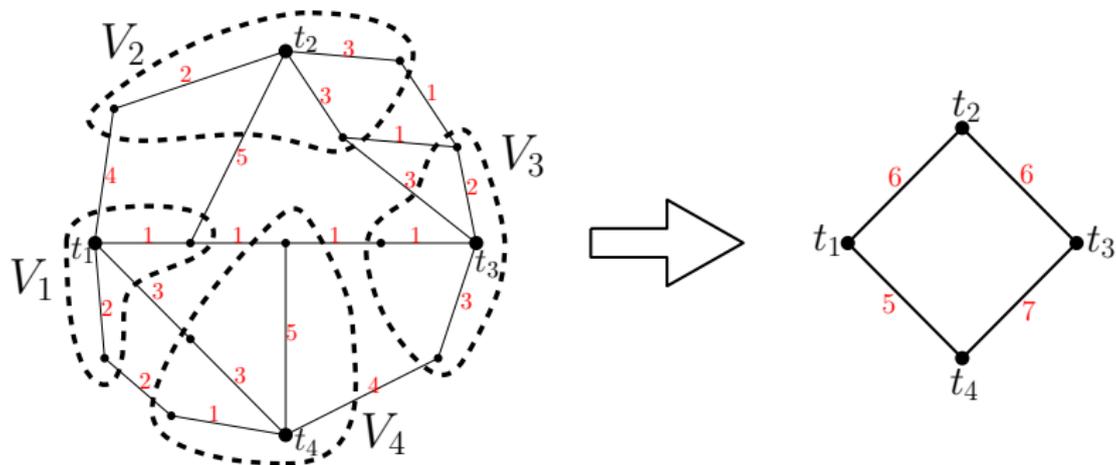
Terminal Partitions and Induced Minor

Partition $\{V_1, \dots, V_k\}$ of V is called a **terminal partition** if for all i ,

- $t_i \in V_i$.
- V_i is **connected**.

Given a terminal partition $P = \{V_1, \dots, V_k\}$, the **induced minor** M is obtained by **contracting** all the internal edges in each V_i .

The **weight** of $\{t, t'\}$ (if exist) is simply $d_G(t, t')$.



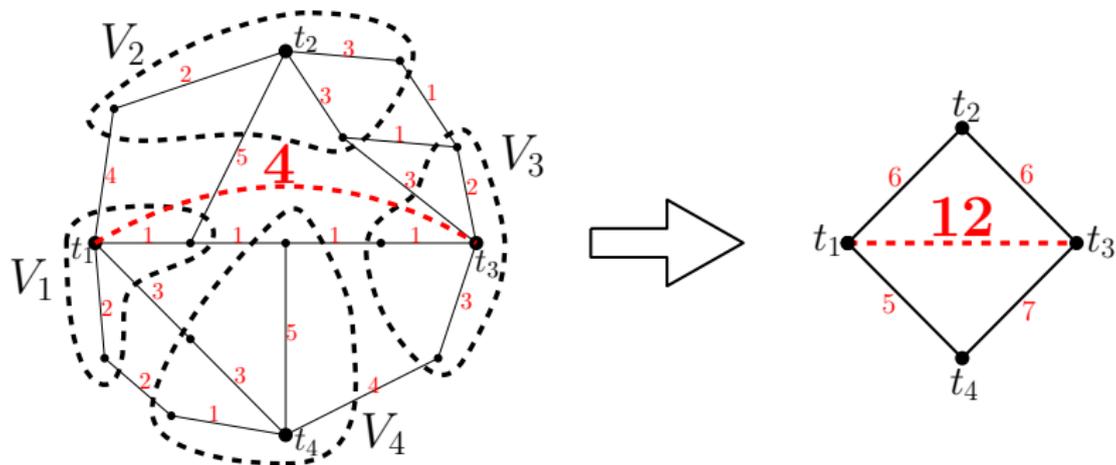
Terminal Partitions and Induced Minor

Partition $\{V_1, \dots, V_k\}$ of V is called a **terminal partition** if for all i ,

- $t_i \in V_i$.
- V_i is **connected**.

Given a terminal partition $P = \{V_1, \dots, V_k\}$, the **induced minor** M is obtained by **contracting** all the internal edges in each V_i .

The **weight** of $\{t, t'\}$ (if exist) is simply $d_G(t, t')$.



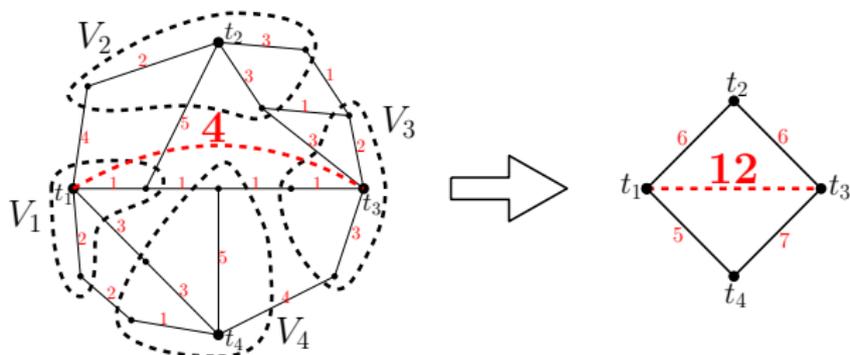
Terminal Partitions and Induced Minor

Partition $\{V_1, \dots, V_k\}$ of V is called a **terminal partition** if for all i ,

- $t_i \in V_i$.
- V_i is **connected**.

Given a terminal partition $P = \{V_1, \dots, V_k\}$, the **induced minor** M is obtained by **contracting** all the internal edges in each V_i .

The **weight** of $\{t, t'\}$ (if exist) is simply $d_G(t, t')$.



The distortion is:
$$\frac{d_M(t_1, t_3)}{d_G(t_1, t_3)} = \frac{12}{4} = 3.$$

Induced Minor by Voronoi Cells

Natural candidate:

Let V_j be the **Voronoi cell** of t_j (breaking ties arbitrarily).

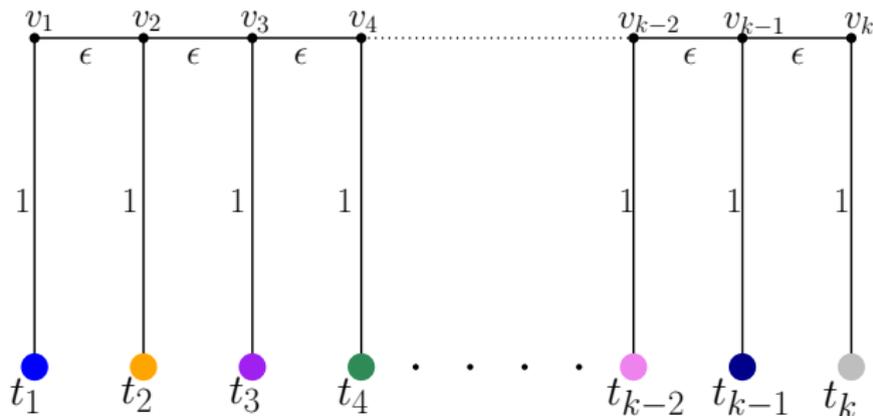
$$V_j = \{v \in V \mid \forall i \neq j \quad d_G(t_j, v) \leq d_G(t_i, v)\}$$

Induced Minor by Voronoi Cells

Natural candidate:

Let V_j be the **Voronoi cell** of t_j (breaking ties arbitrarily).

$$V_j = \{v \in V \mid \forall i \neq j \quad d_G(t_j, v) \leq d_G(t_i, v)\}$$

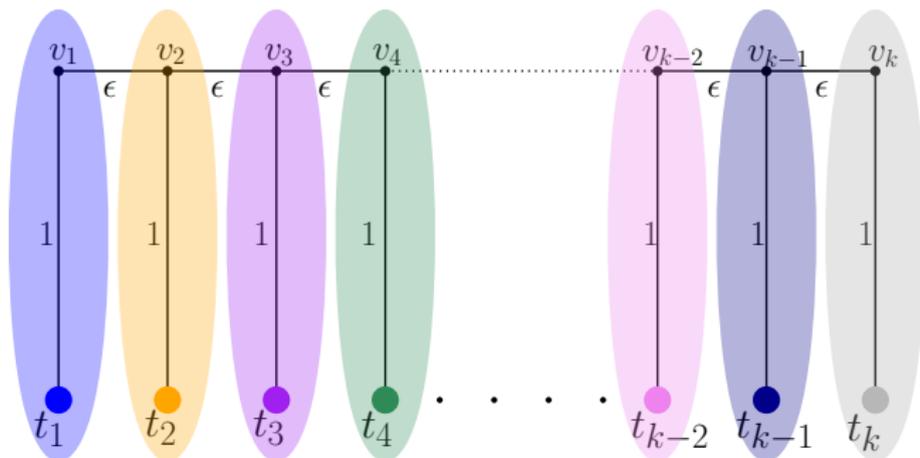


Induced Minor by Voronoi Cells

Natural candidate:

Let V_j be the **Voronoi cell** of t_j (breaking ties arbitrarily).

$$V_j = \{v \in V \mid \forall i \neq j \quad d_G(t_j, v) \leq d_G(t_i, v)\}$$

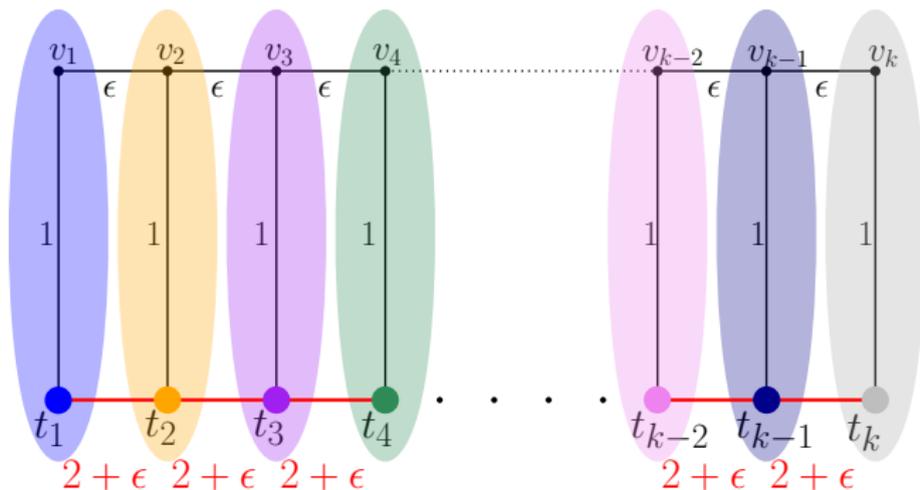


Induced Minor by Voronoi Cells

Natural candidate:

Let V_j be the **Voronoi cell** of t_j (breaking ties arbitrarily).

$$V_j = \{v \in V \mid \forall i \neq j \quad d_G(t_j, v) \leq d_G(t_i, v)\}$$

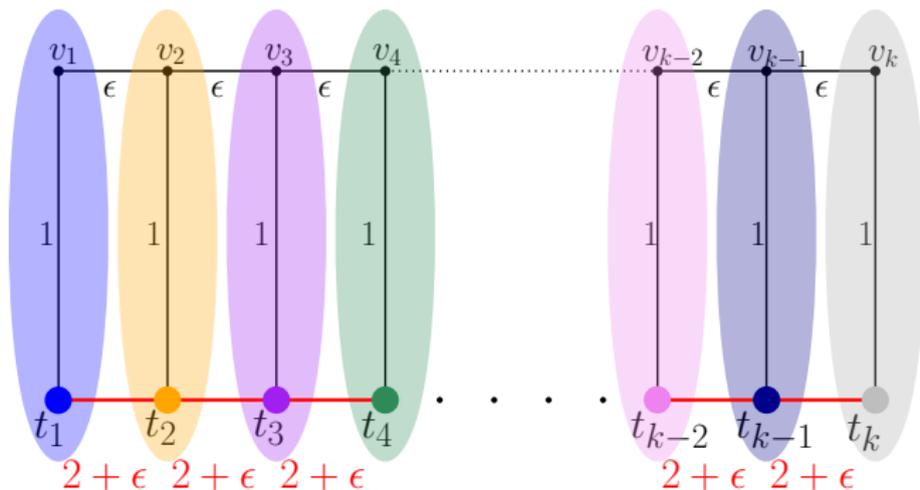


Induced Minor by Voronoi Cells

Natural candidate:

Let V_j be the **Voronoi cell** of t_j (breaking ties arbitrarily).

$$V_j = \{v \in V \mid \forall i \neq j \quad d_G(t_j, v) \leq d_G(t_i, v)\}$$



Distortion:
$$\frac{d_M(t_1, t_k)}{d_G(t_1, t_k)} = \frac{2+2(k-2)+(k-1)\epsilon}{2+(k-1)\epsilon} \xrightarrow{\epsilon \rightarrow 0} \Omega(k).$$

History

- 1 Gupta (2001) showed **upper bound** of **8** for trees.

History

- 1 Gupta (2001) showed **upper bound** of **8** for trees.
- 2 Chan, Xia, Konjevod, and Richa (2006) showed:
lower bound of **8** for trees.

History

- 1 Gupta (2001) showed **upper bound** of **8** for trees.
- 2 Chan, Xia, Konjevod, and Richa (2006) showed:
lower bound of **8** for trees.
Best known lower bound for general graphs!

History

- 1 Gupta (2001) showed **upper bound** of **8** for trees.
- 2 Chan, Xia, Konjevod, and Richa (2006) showed:
lower bound of **8** for trees.
Best known lower bound for general graphs!
- 3 Basu and Gupta (2008) showed
upper bound of $O(1)$ for **outerplanar** graphs.

History

- 1 Gupta (2001) showed **upper bound** of **8** for trees.
- 2 Chan, Xia, Konjevod, and Richa (2006) showed:
lower bound of **8** for trees.
Best known lower bound for general graphs!
- 3 Basu and Gupta (2008) showed
upper bound of $O(1)$ for **outerplanar** graphs.
- 4 Kamma, Krauthgamer and Nguyen (2014) showed
upper bound of $O(\log^6 k)$ for general graphs.

History

- 1 Gupta (2001) showed **upper bound** of **8** for trees.
- 2 Chan, Xia, Konjevod, and Richa (2006) showed:
lower bound of **8** for trees.
Best known lower bound for general graphs!
- 3 Basu and Gupta (2008) showed
upper bound of $O(1)$ for **outerplanar** graphs.
- 4 Kamma, Krauthgamer and Nguyen (2014) showed
upper bound of $O(\log^6 k)$ for general graphs.
Using the **Ball growing algorithm**.

History

- 1 Gupta (2001) showed **upper bound** of **8** for trees.
- 2 Chan, Xia, Konjevod, and Richa (2006) showed:
lower bound of **8** for trees.
Best known lower bound for general graphs!
- 3 Basu and Gupta (2008) showed
upper bound of $O(1)$ for **outerplanar** graphs.
- 4 Kamma, Krauthgamer and Nguyen (2014) showed
upper bound of $O(\log^6 k)$ for general graphs.
Using the **Ball growing algorithm**.
- 5 Kamma, Krauthgamer and Nguyen (2015)
improved analysis to $O(\log^5 k)$ (same alg).

History

- 1 Gupta (2001) showed **upper bound** of **8** for trees.
- 2 Chan, Xia, Konjevod, and Richa (2006) showed:
lower bound of **8** for trees.
Best known lower bound for general graphs!
- 3 Basu and Gupta (2008) showed
upper bound of $O(1)$ for **outerplanar** graphs.
- 4 Kamma, Krauthgamer and Nguyen (2014) showed
upper bound of $O(\log^6 k)$ for general graphs.
Using the **Ball growing algorithm**.
- 5 Kamma, Krauthgamer and Nguyen (2015)
improved analysis to $O(\log^5 k)$ (same alg).
- 6 Cheung (2018) improved analysis to $O(\log^2 k)$ (same alg).

Results

Obtain improved the analysis of the
Ball Growing algorithm to $O(\log k)$.

Results

Obtain improved the analysis of the
Ball Growing algorithm to $O(\log k)$.
(Appeared in SODA 18)

Results

Obtain improved the analysis of the
Ball Growing algorithm to $O(\log k)$.
(Appeared in SODA 18)

Introduce a new algorithm: The **Noisy Voronoi** algorithm.

- Also induce distortion of $O(\log k)$.

Results

Obtain improved the analysis of the
Ball Growing algorithm to $O(\log k)$.
(Appeared in SODA 18)

Introduce a new algorithm: The **Noisy Voronoi** algorithm.

- Also induce distortion of $O(\log k)$.
- **Simpler** analysis.

Results

Obtain improved the analysis of the
Ball Growing algorithm to $O(\log k)$.
(Appeared in SODA 18)

Introduce a new algorithm: The **Noisy Voronoi** algorithm.

- Also induce distortion of $O(\log k)$.
- **Simpler** analysis.
- Can be implemented in almost **linear time!** ($O(m \log n)$).

Results

Obtain improved the analysis of the
Ball Growing algorithm to $O(\log k)$.

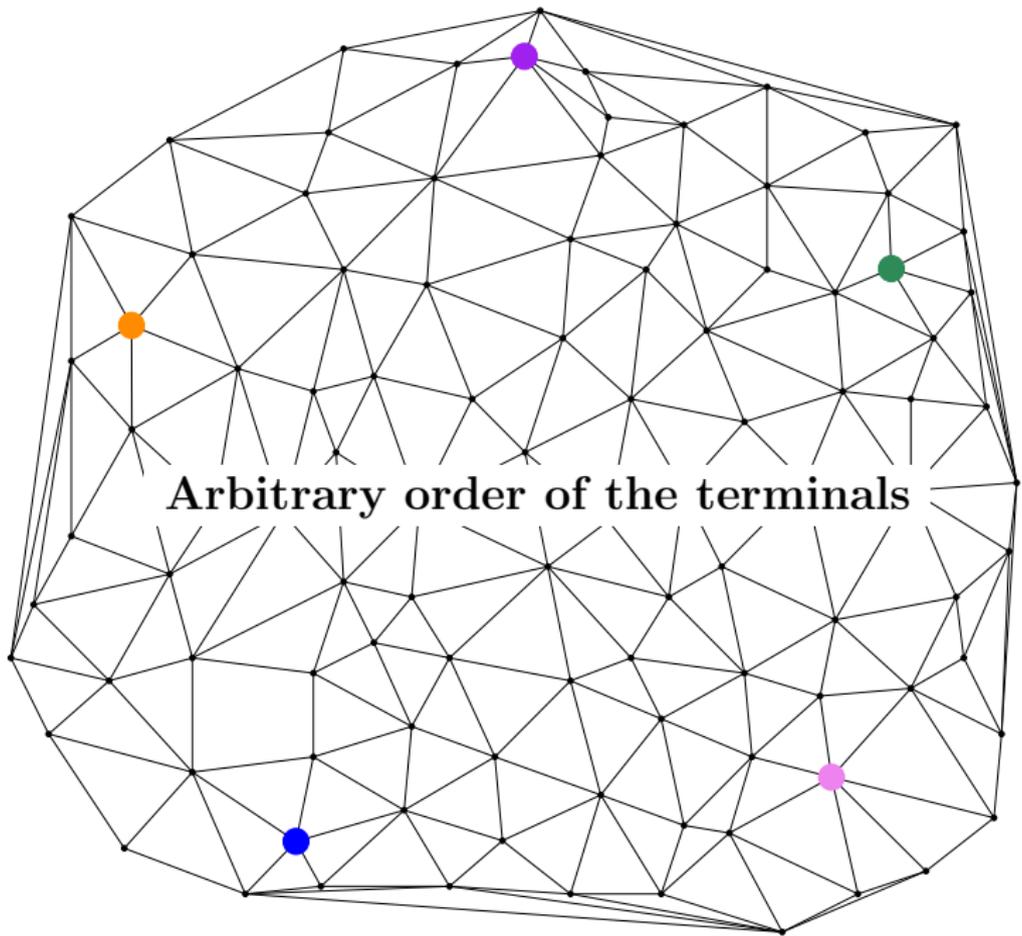
(Appeared in SODA 18)

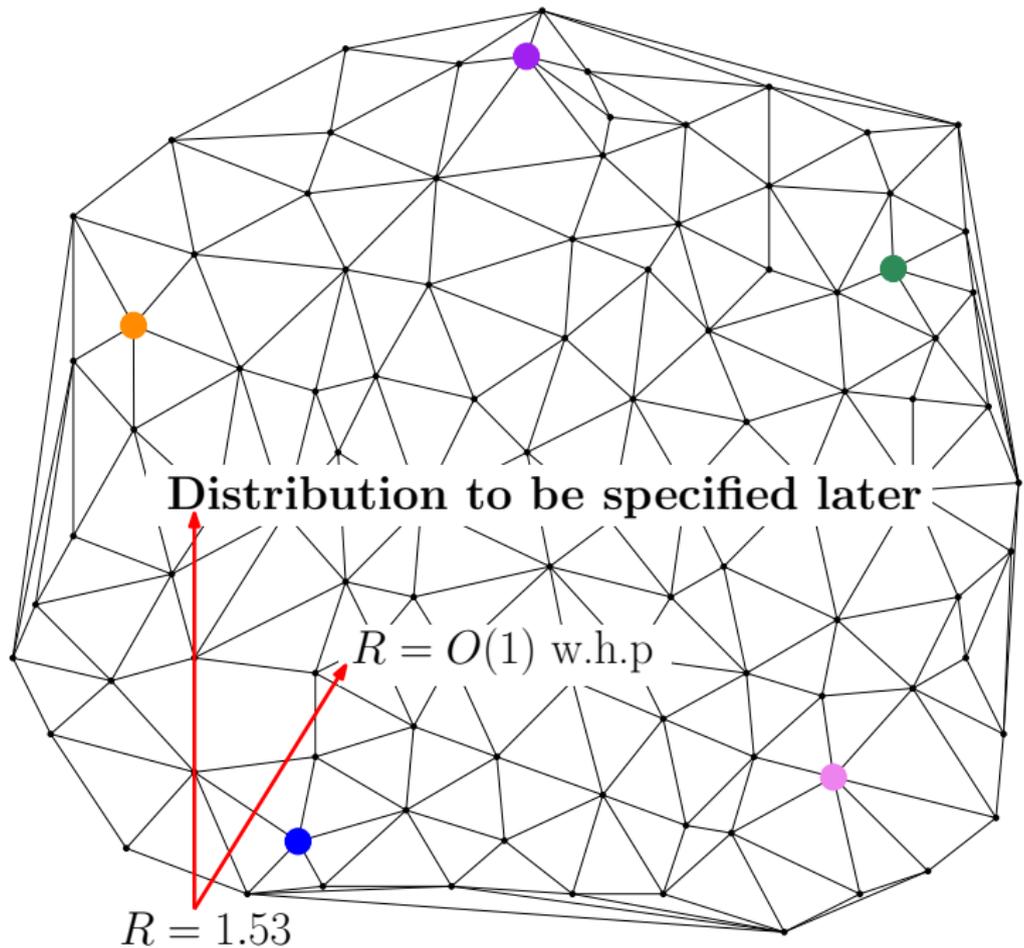
Introduce a new algorithm: The **Noisy Voronoi** algorithm.

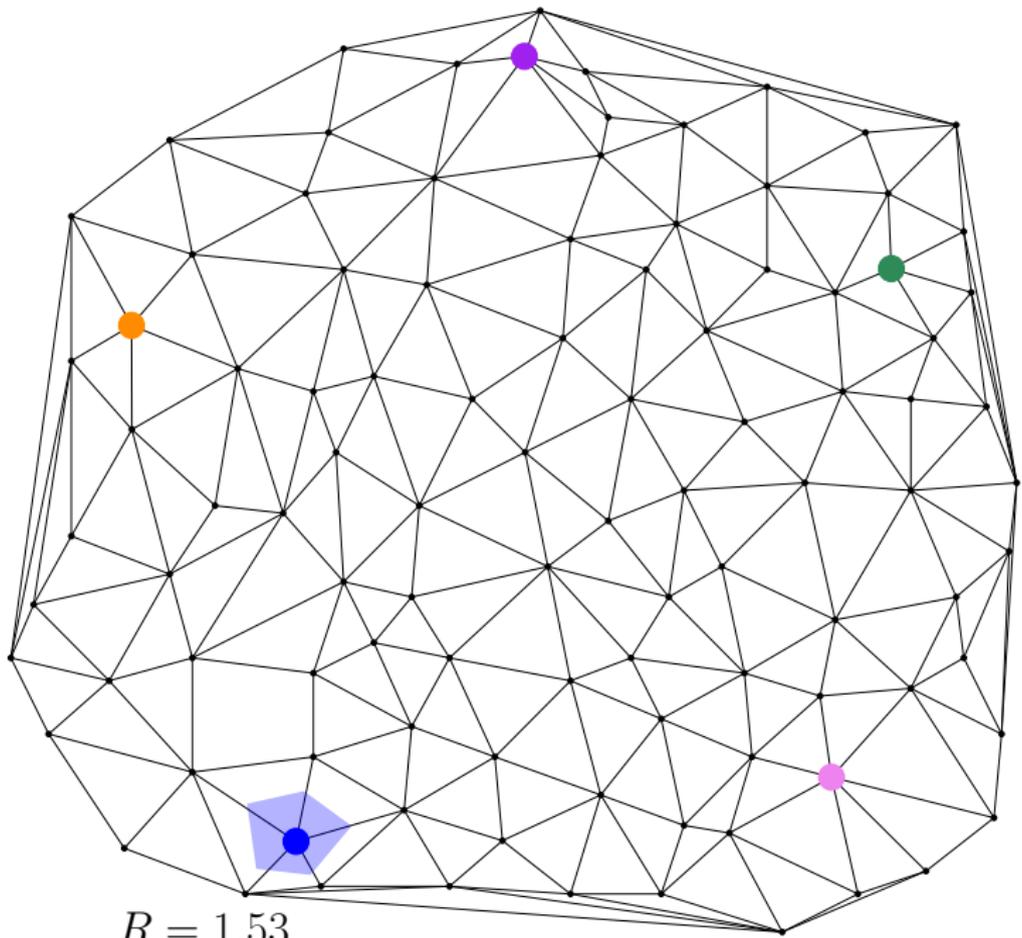
- Also induce distortion of $O(\log k)$.
- **Simpler analysis.**
- Can be implemented in almost **linear time!** ($O(m \log n)$).

The Noisy Voronoi Algorithm

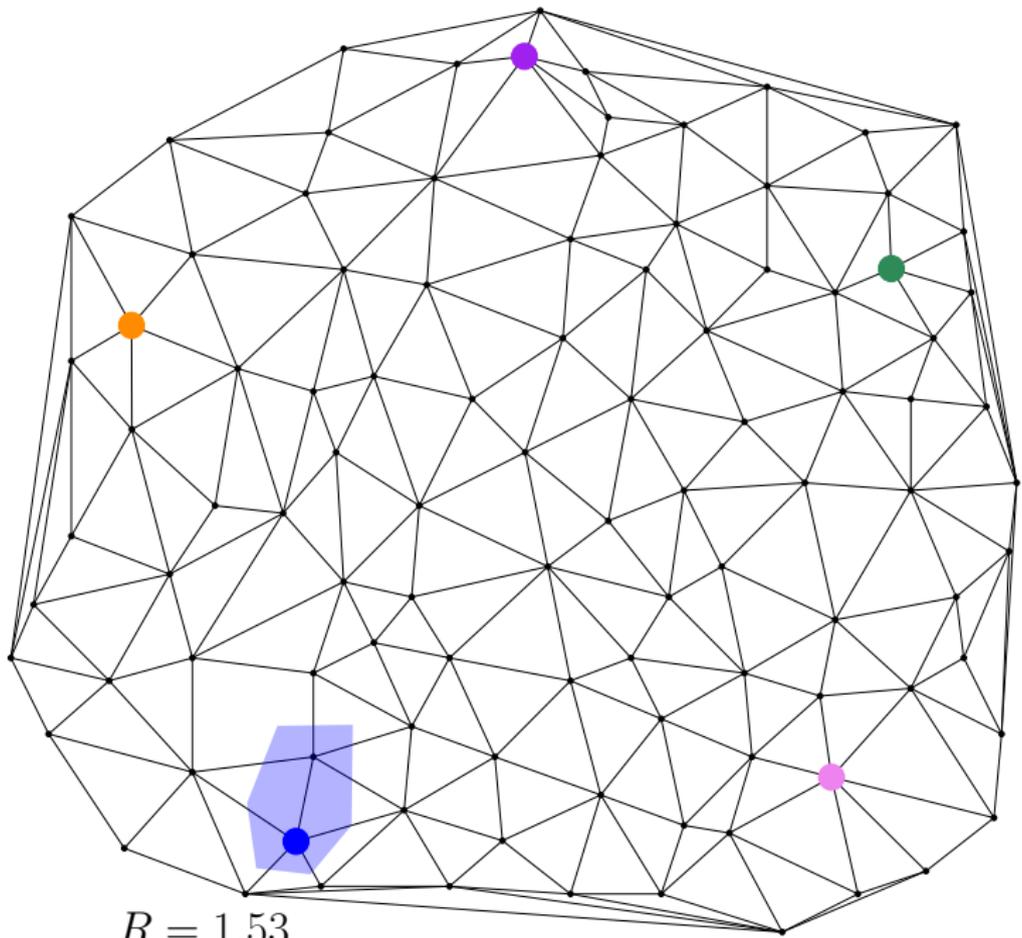




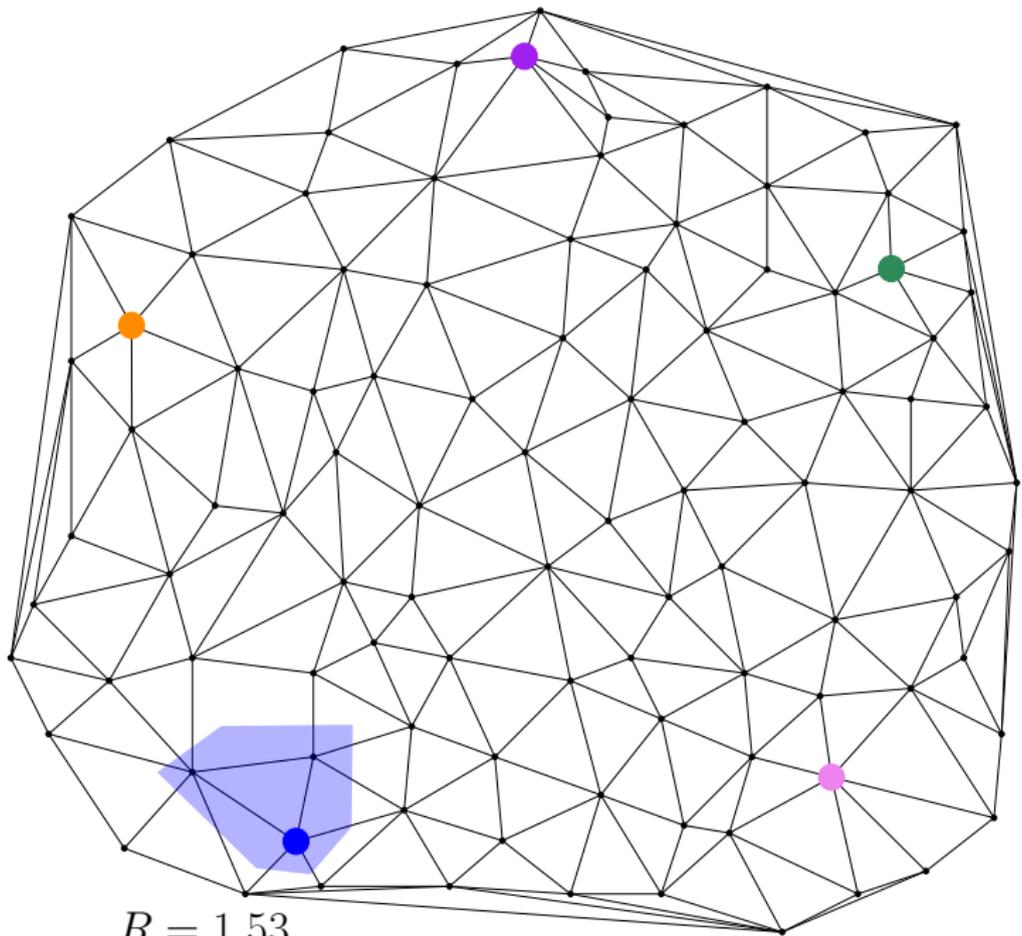




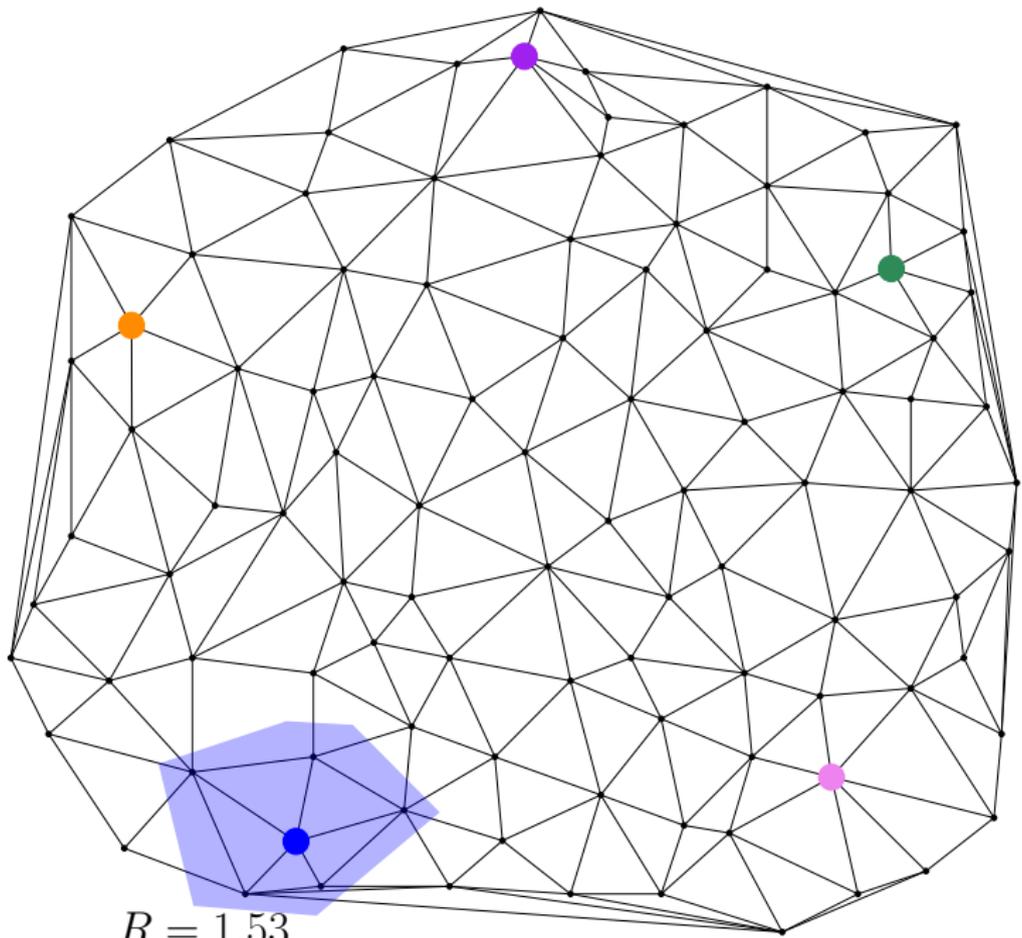
$R = 1.53$



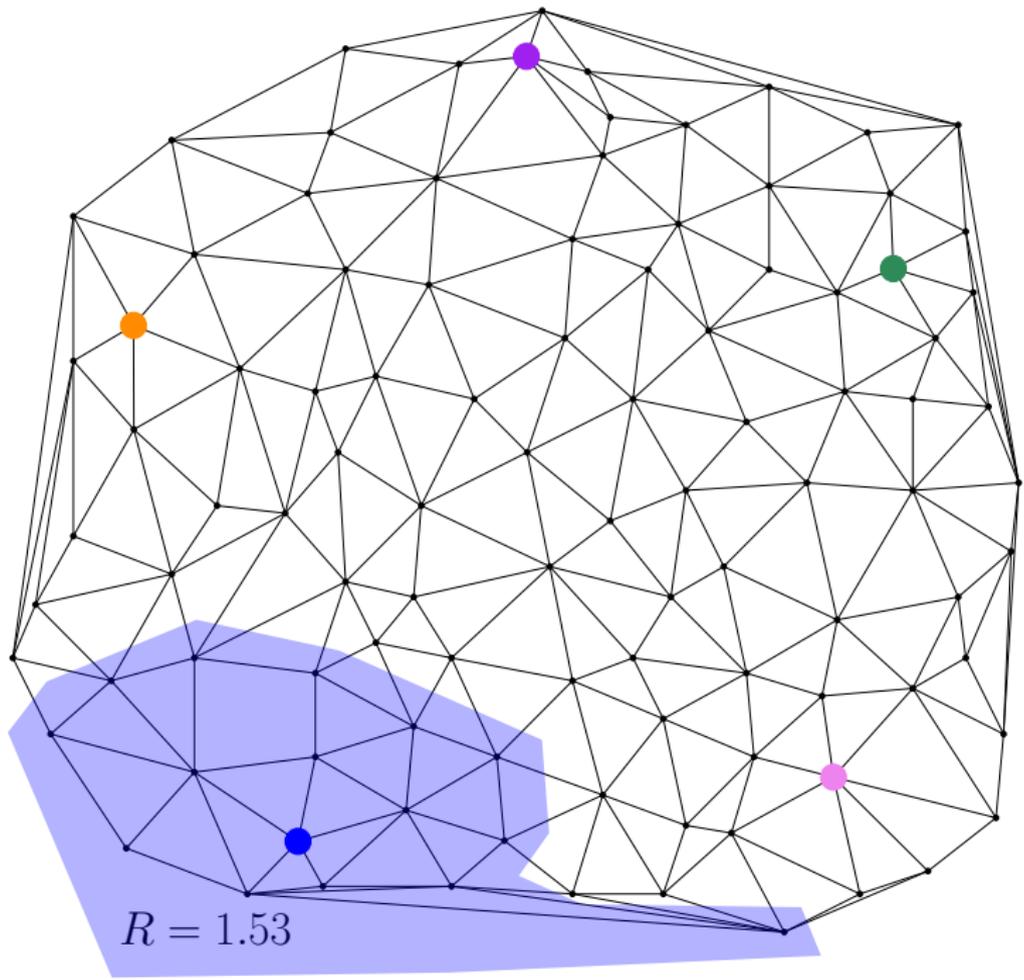
$R = 1.53$

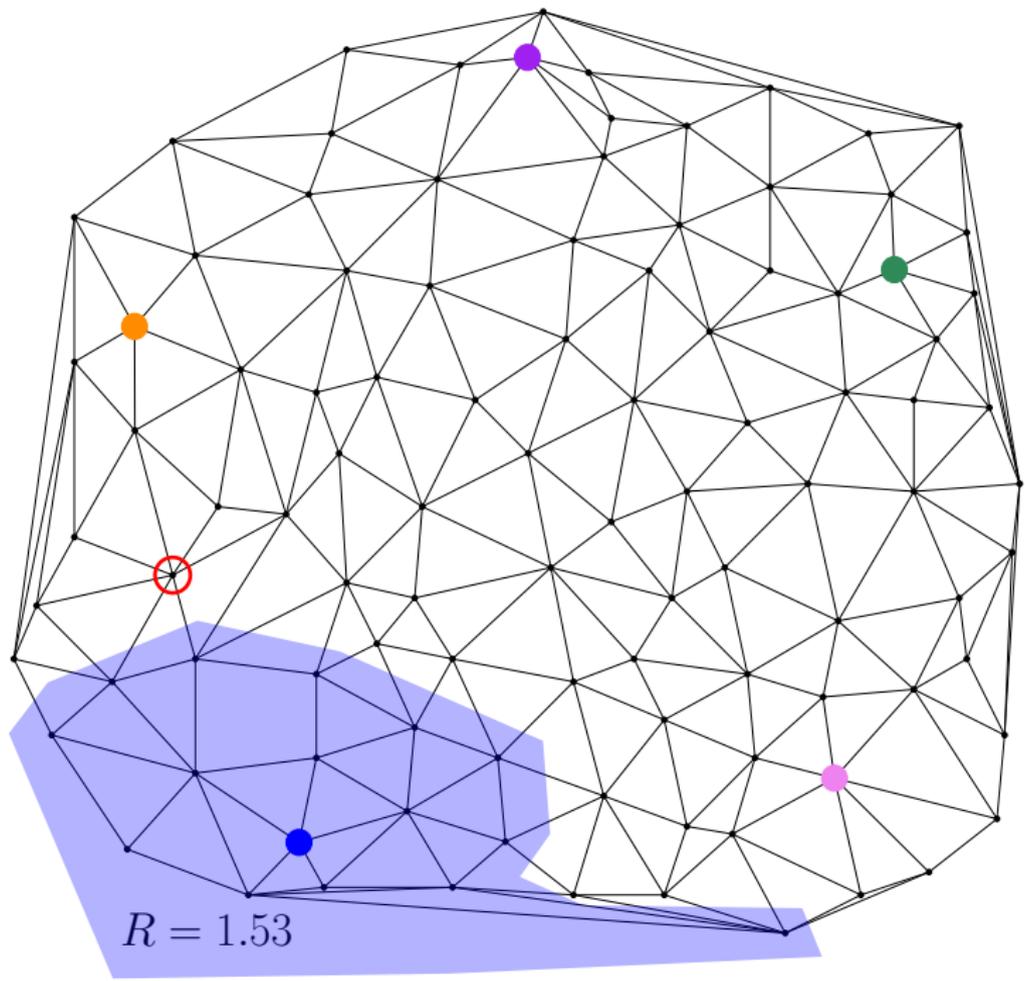


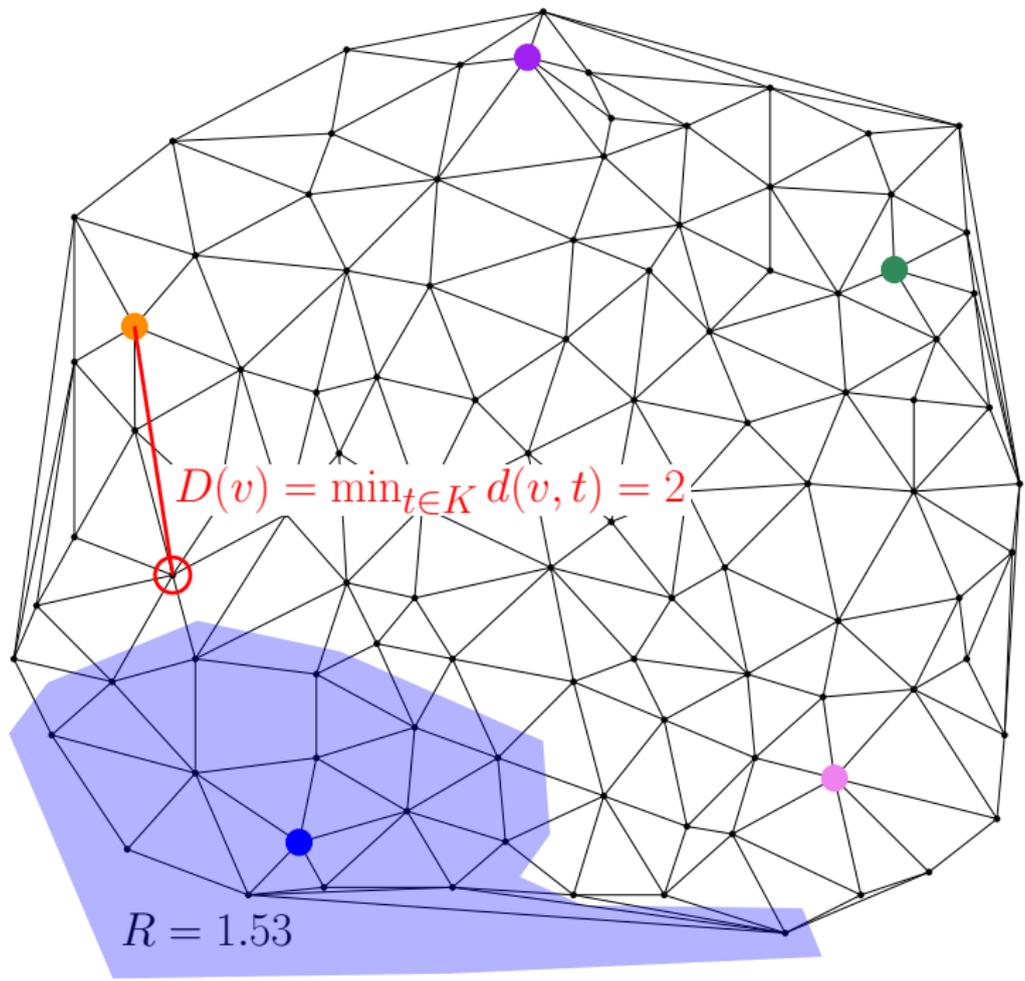
$R = 1.53$

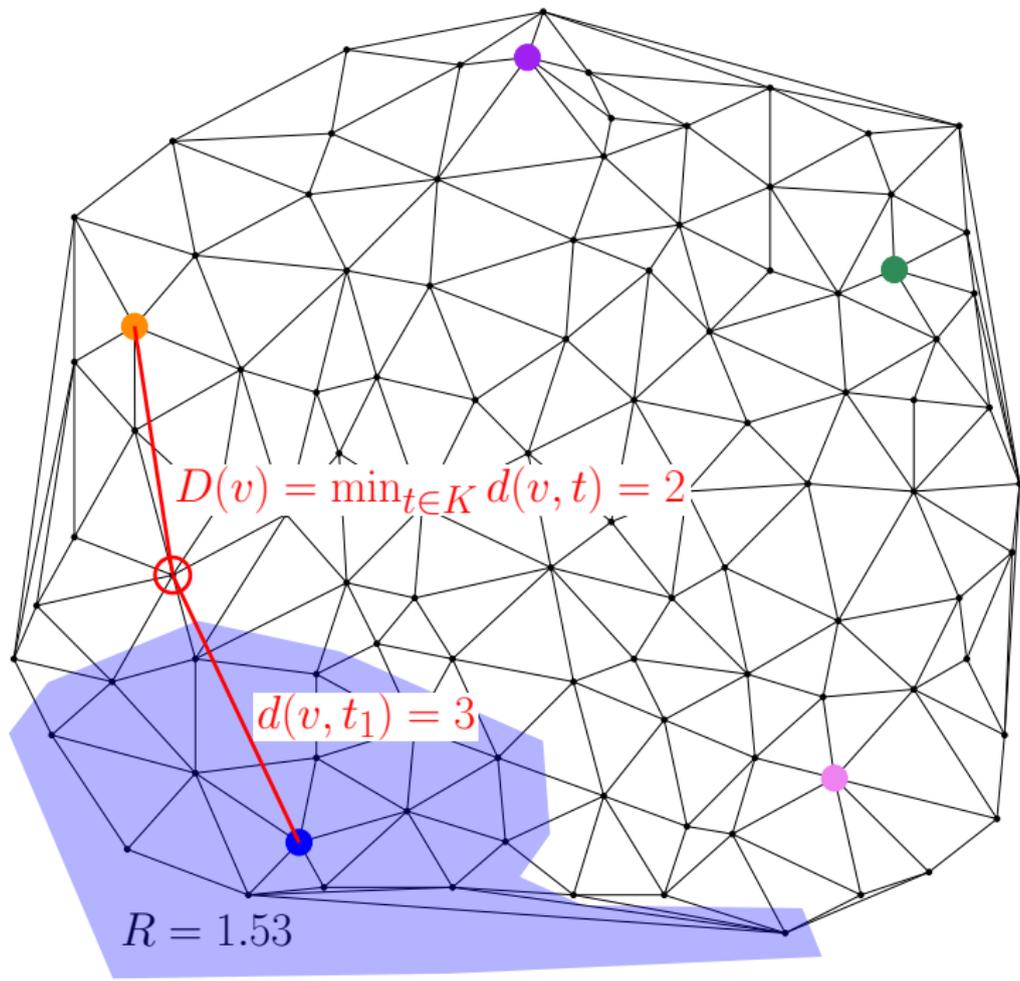


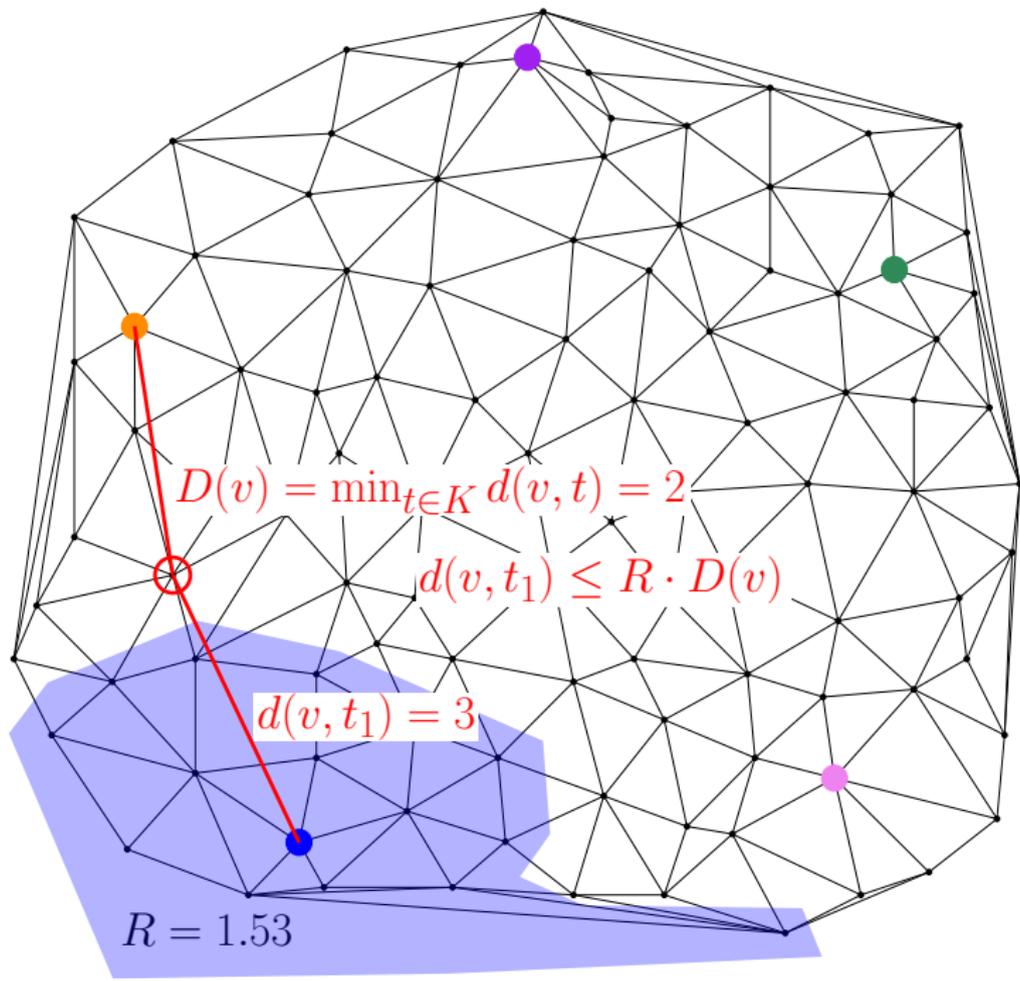
$R = 1.53$

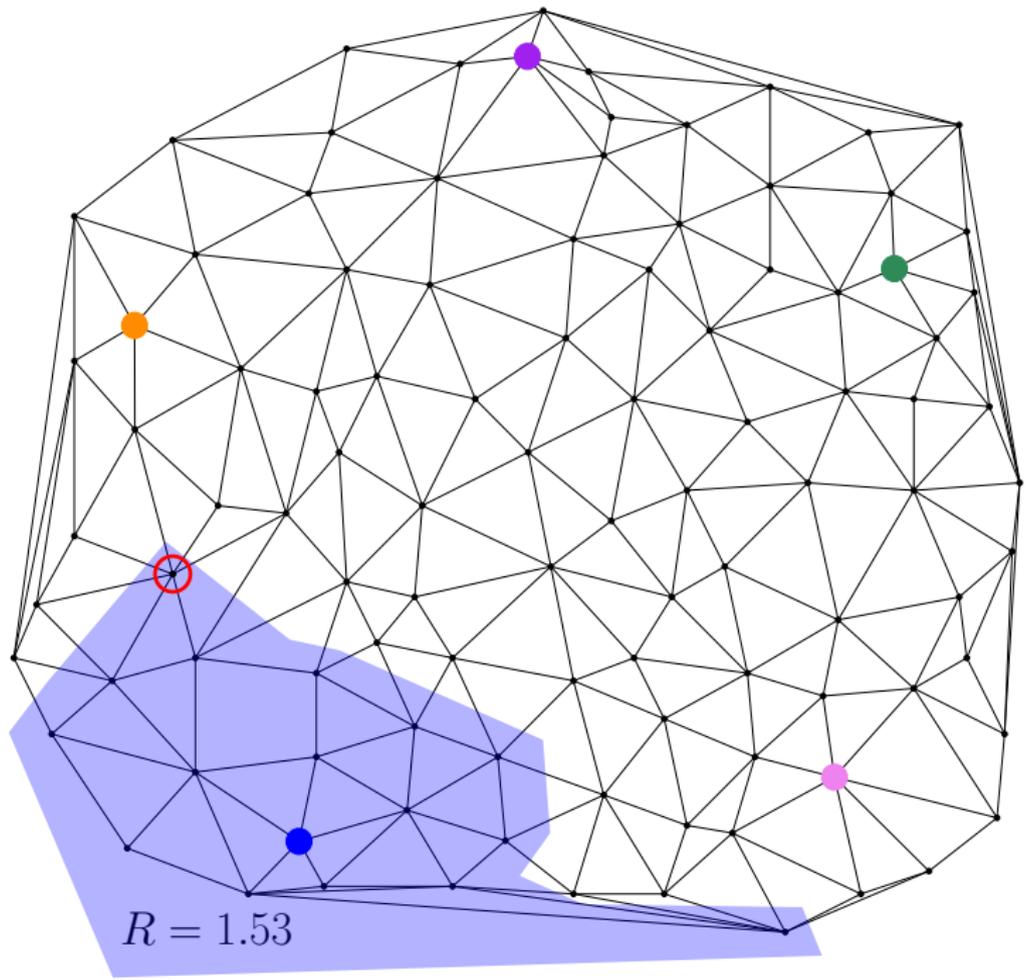




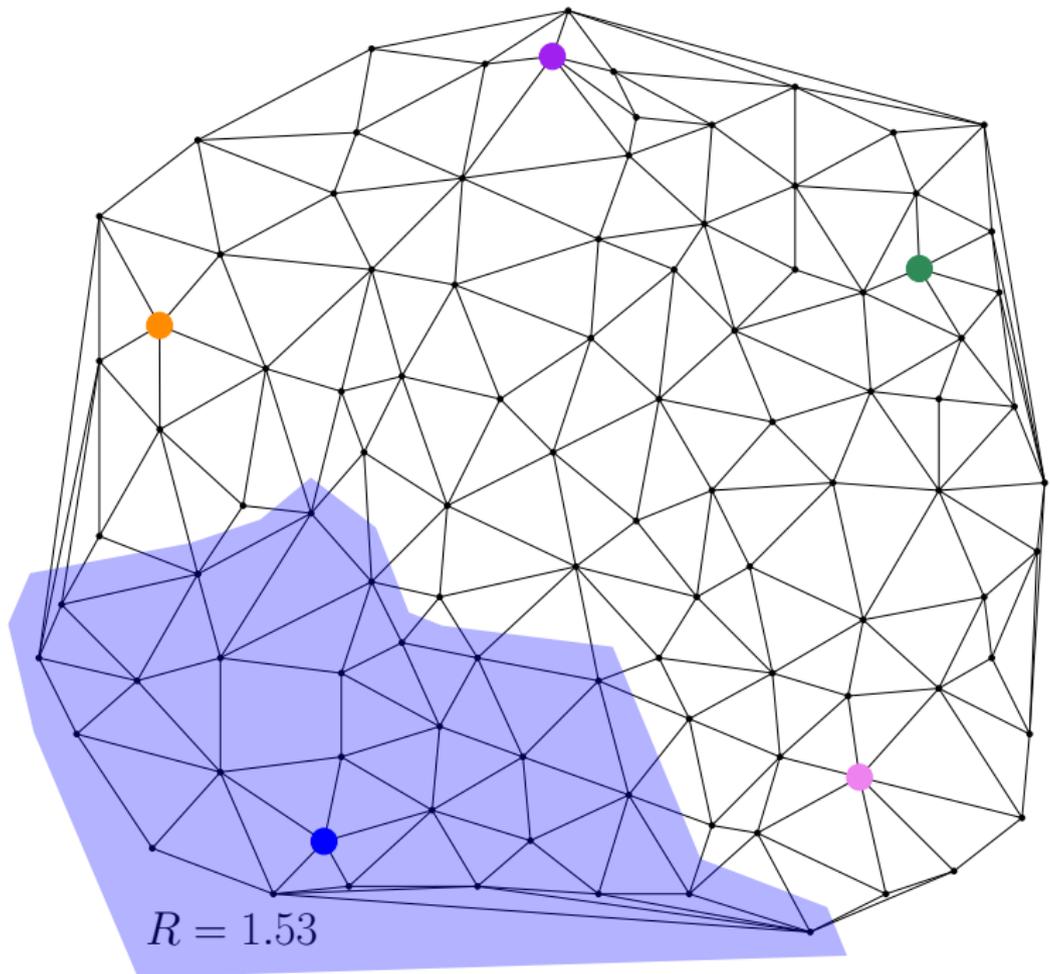




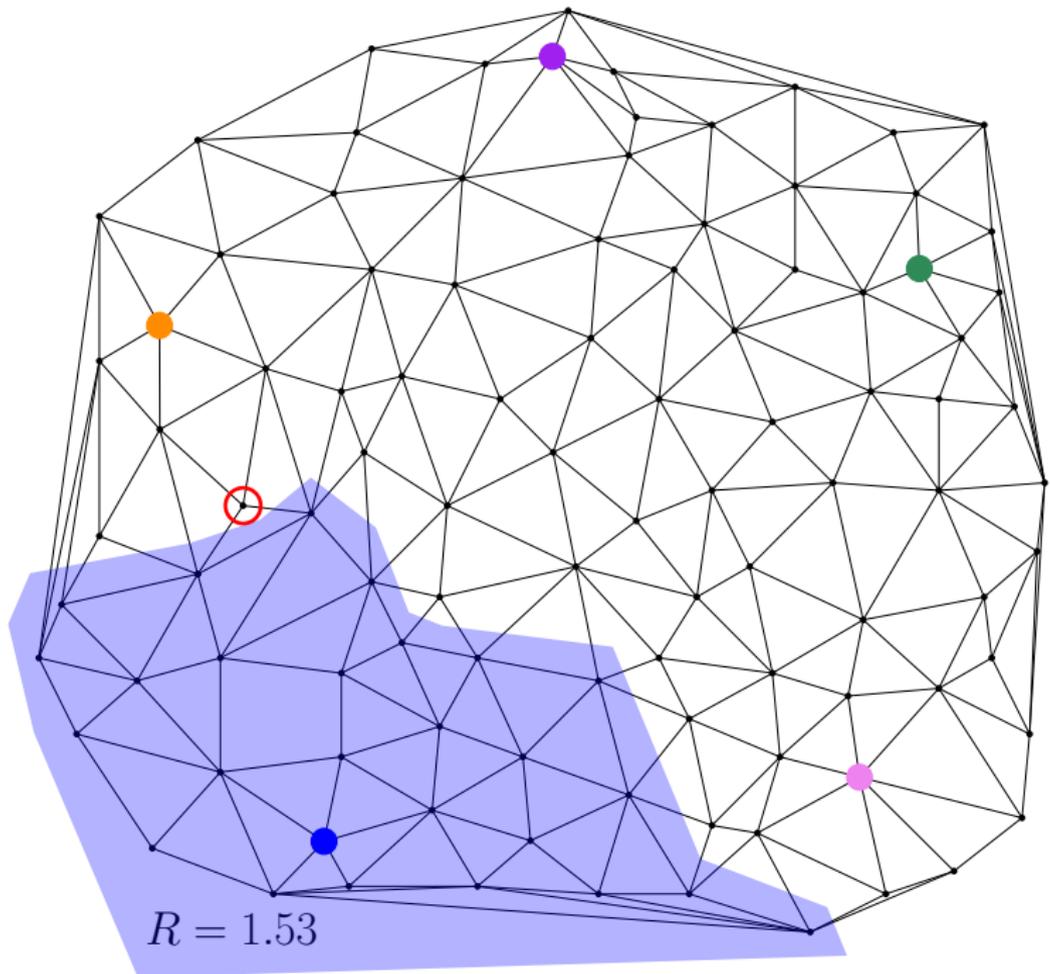




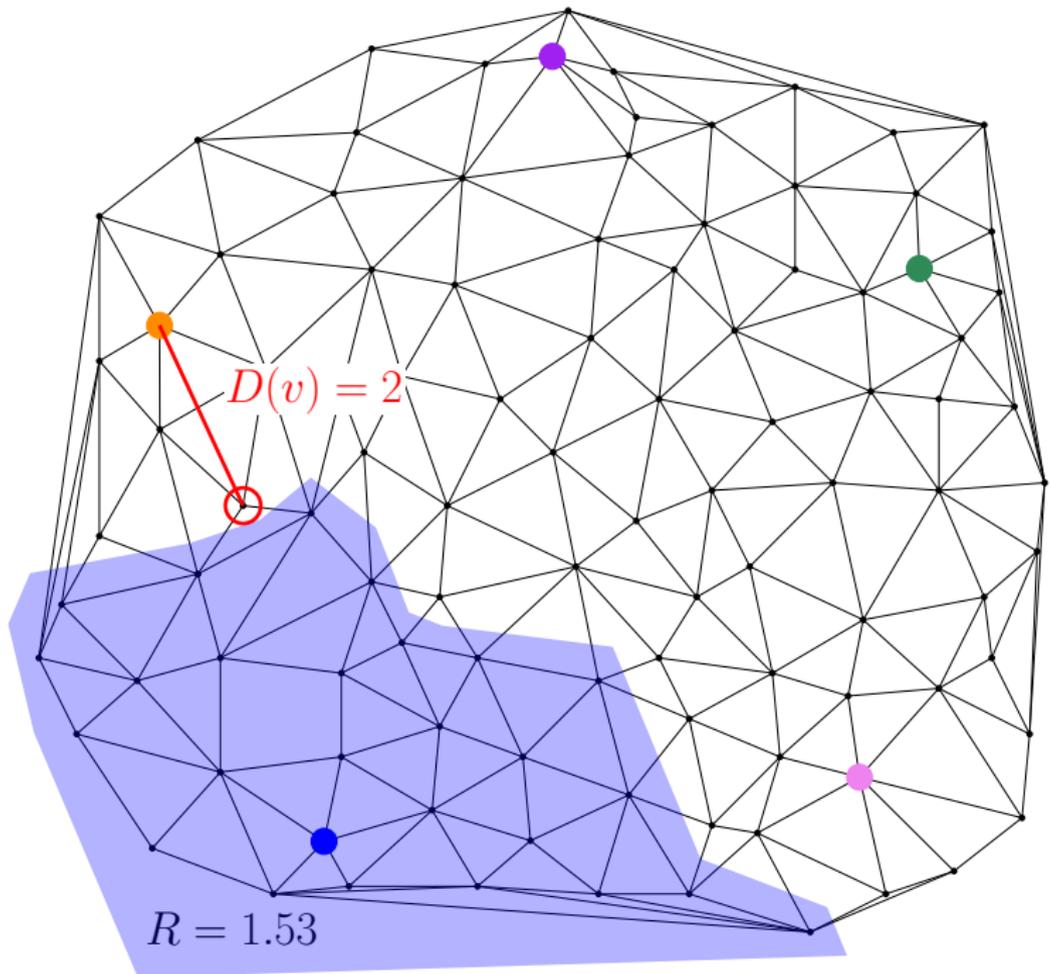
$R = 1.53$

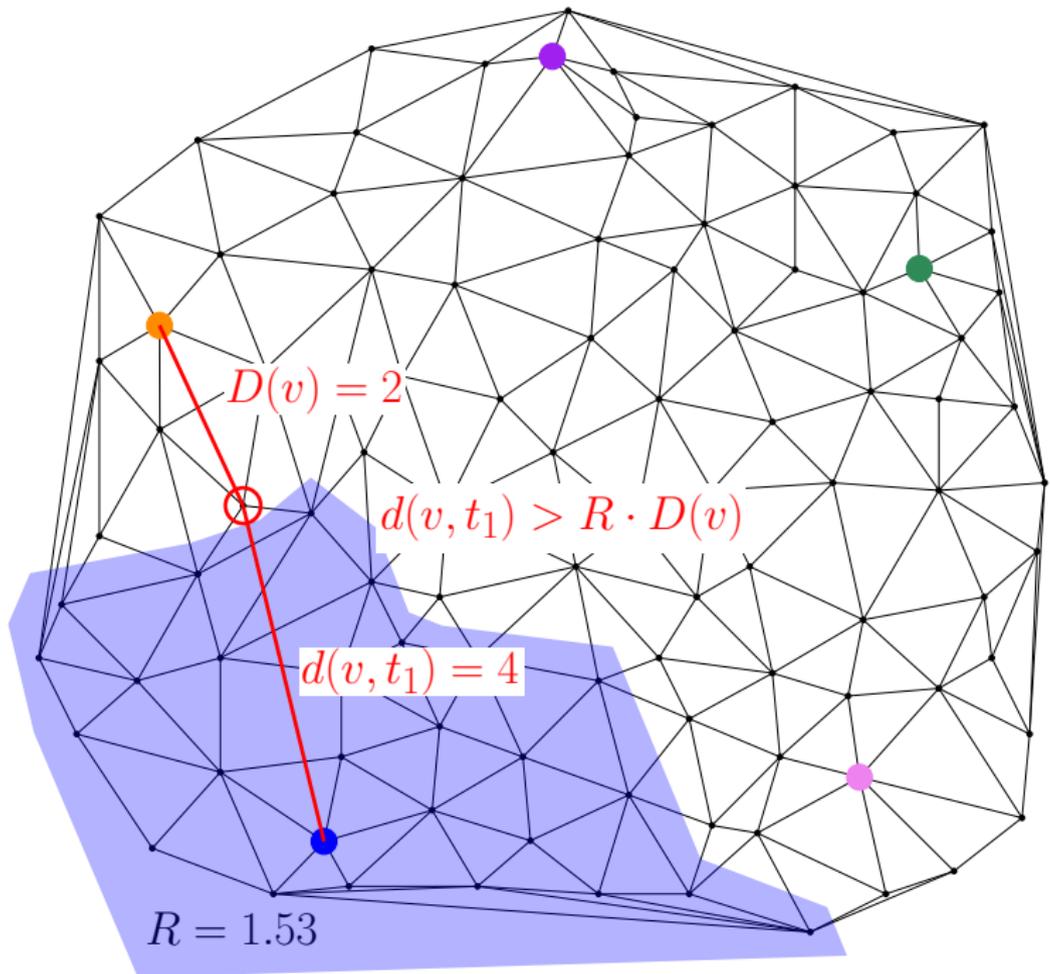


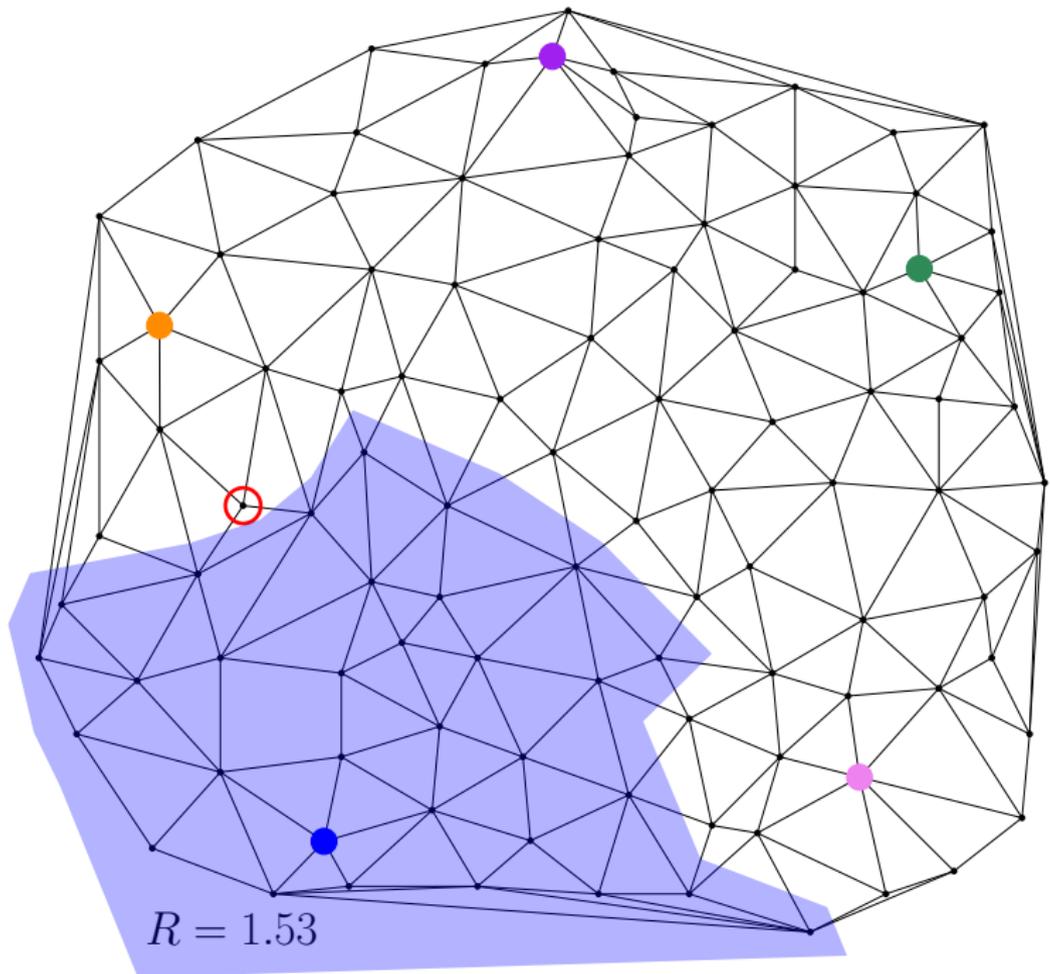
$R = 1.53$



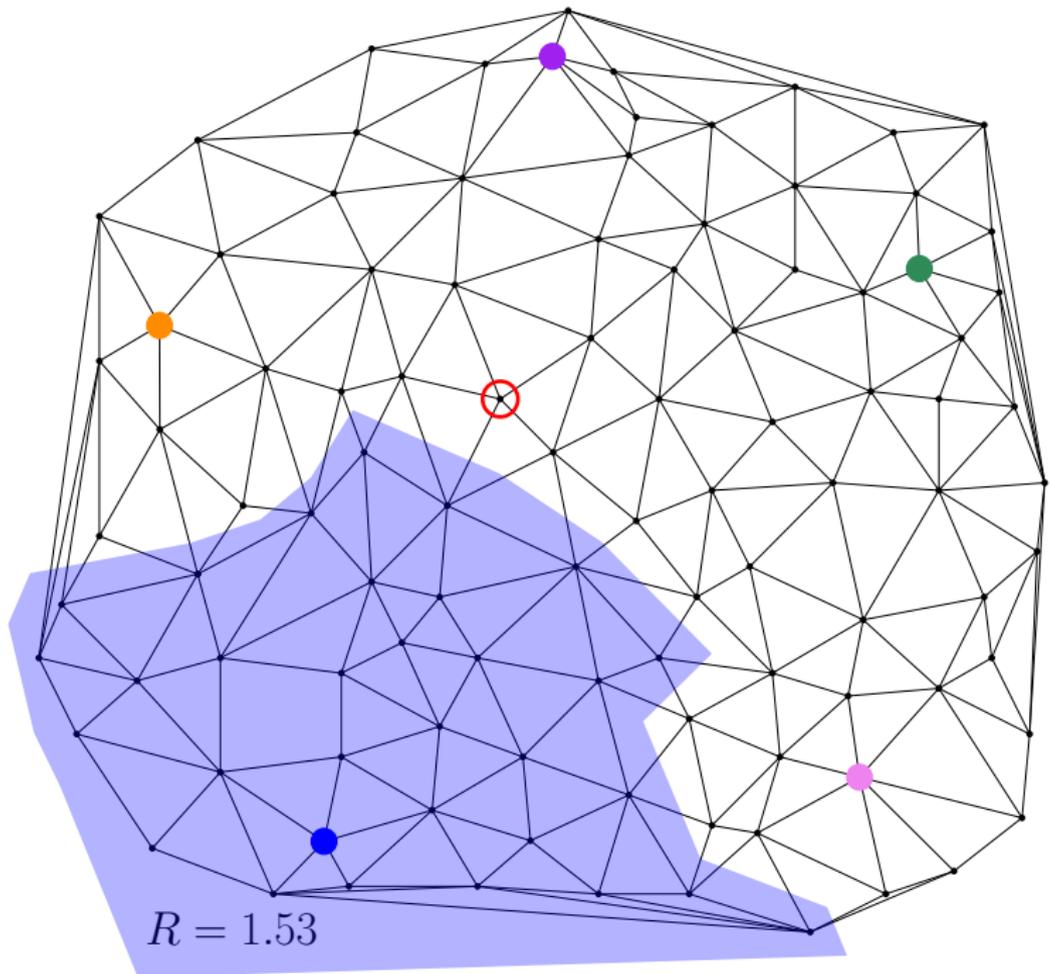
$R = 1.53$



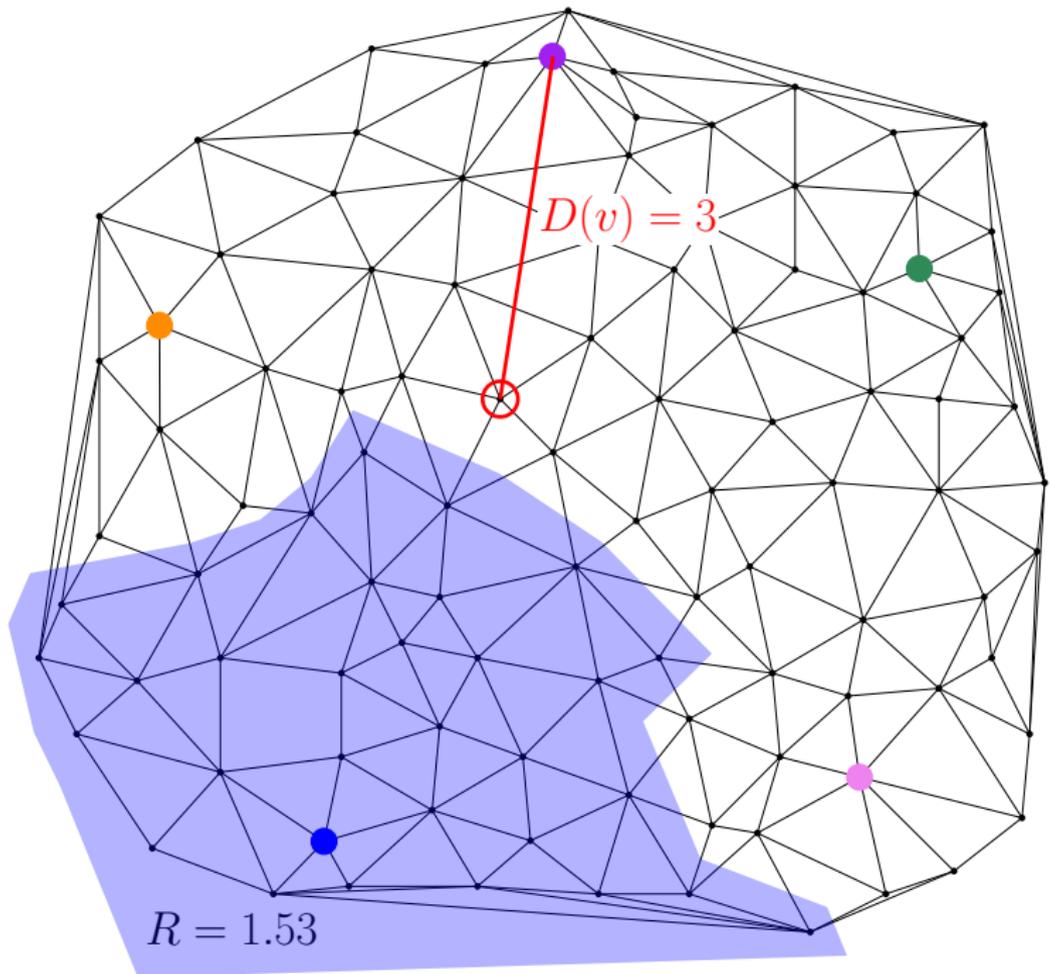




$R = 1.53$

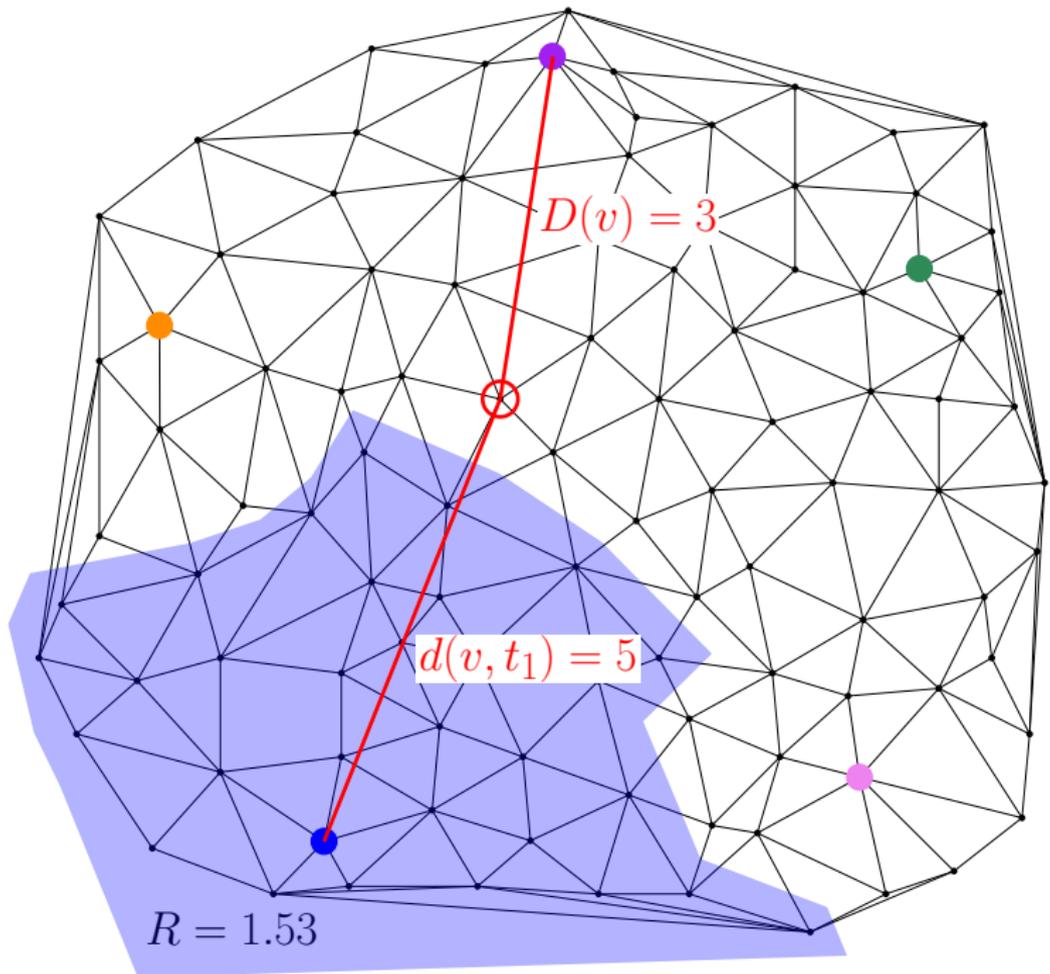


$R = 1.53$



$D(v) = 3$

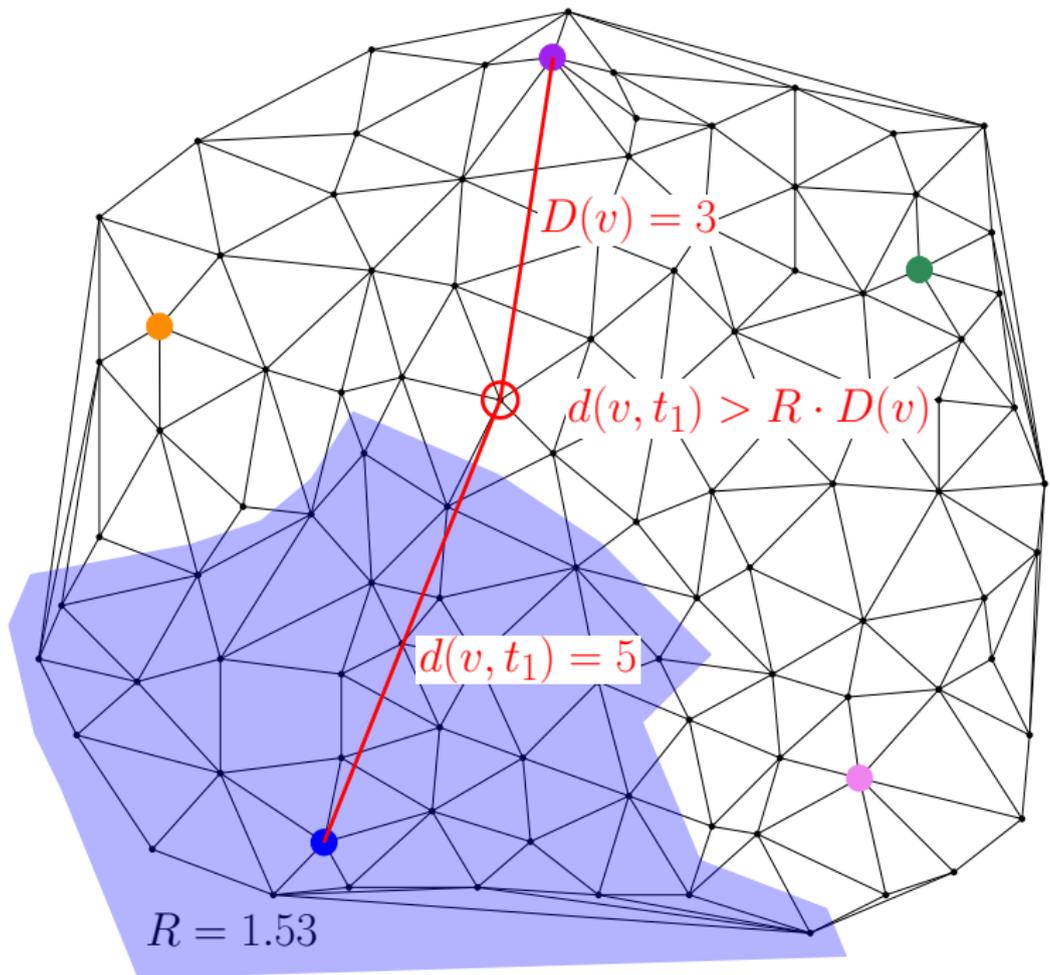
$R = 1.53$



$$D(v) = 3$$

$$d(v, t_1) = 5$$

$$R = 1.53$$

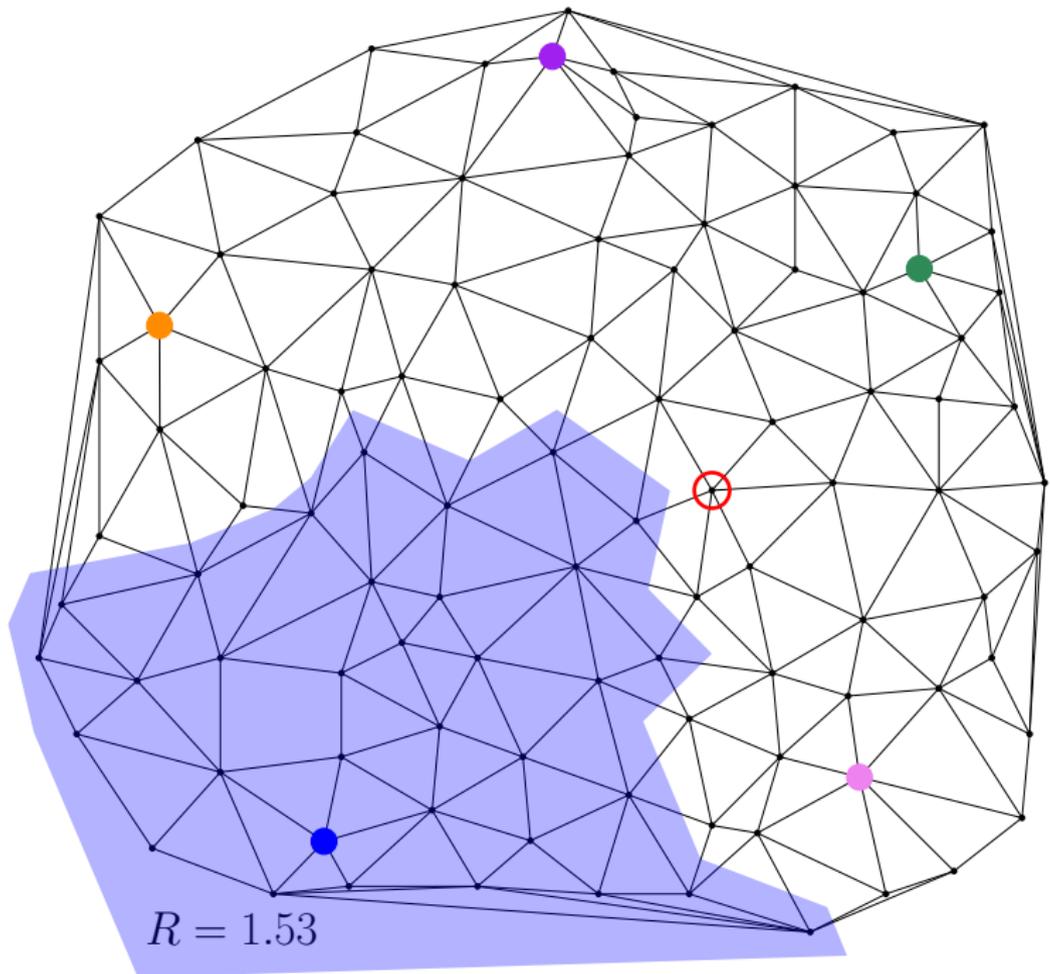


$$D(v) = 3$$

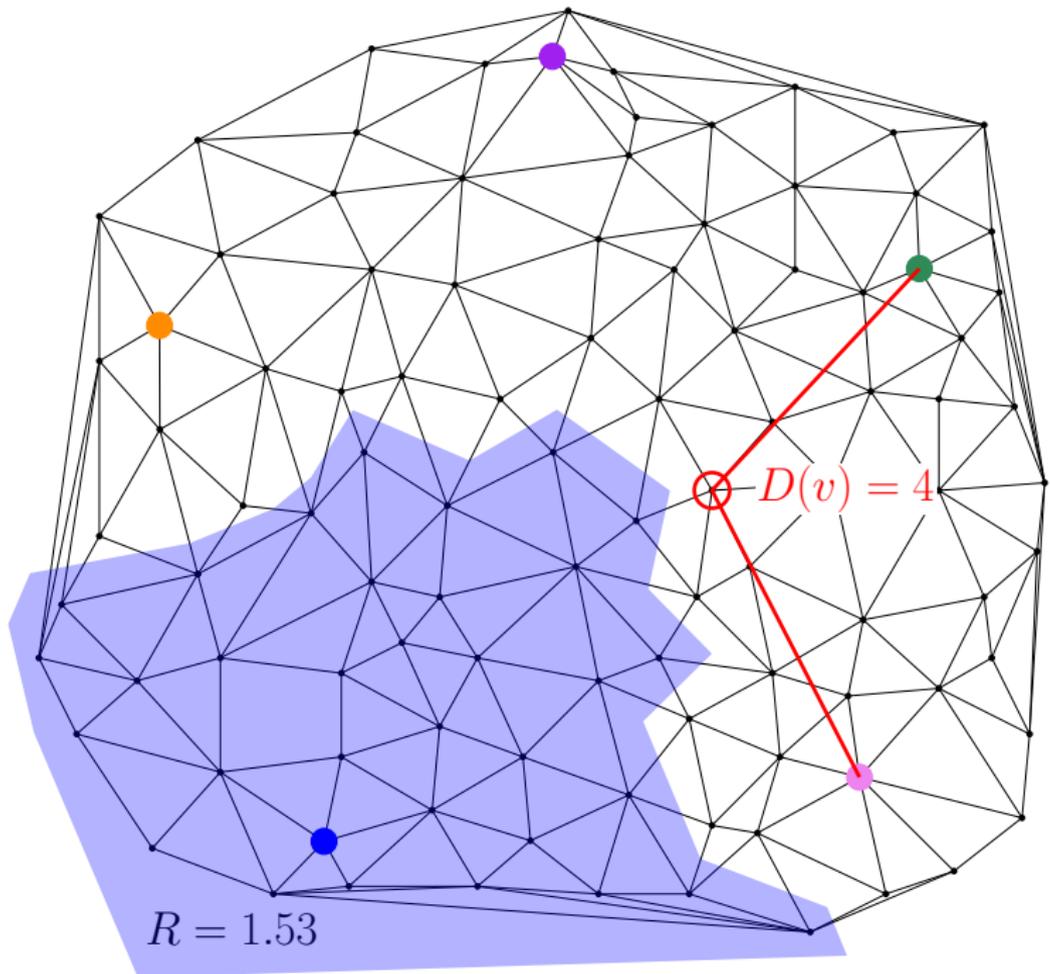
$$\text{⊗} \quad d(v, t_1) > R \cdot D(v)$$

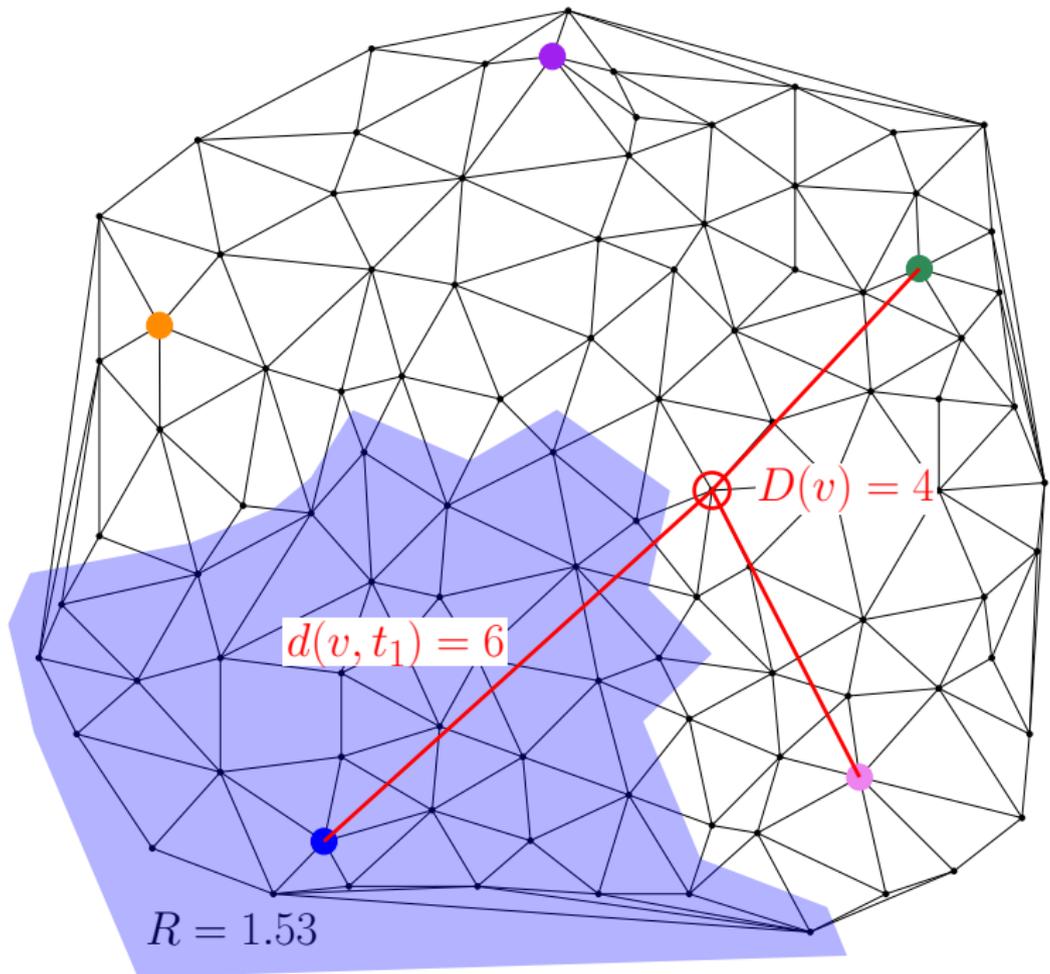
$$d(v, t_1) = 5$$

$$R = 1.53$$



$R = 1.53$

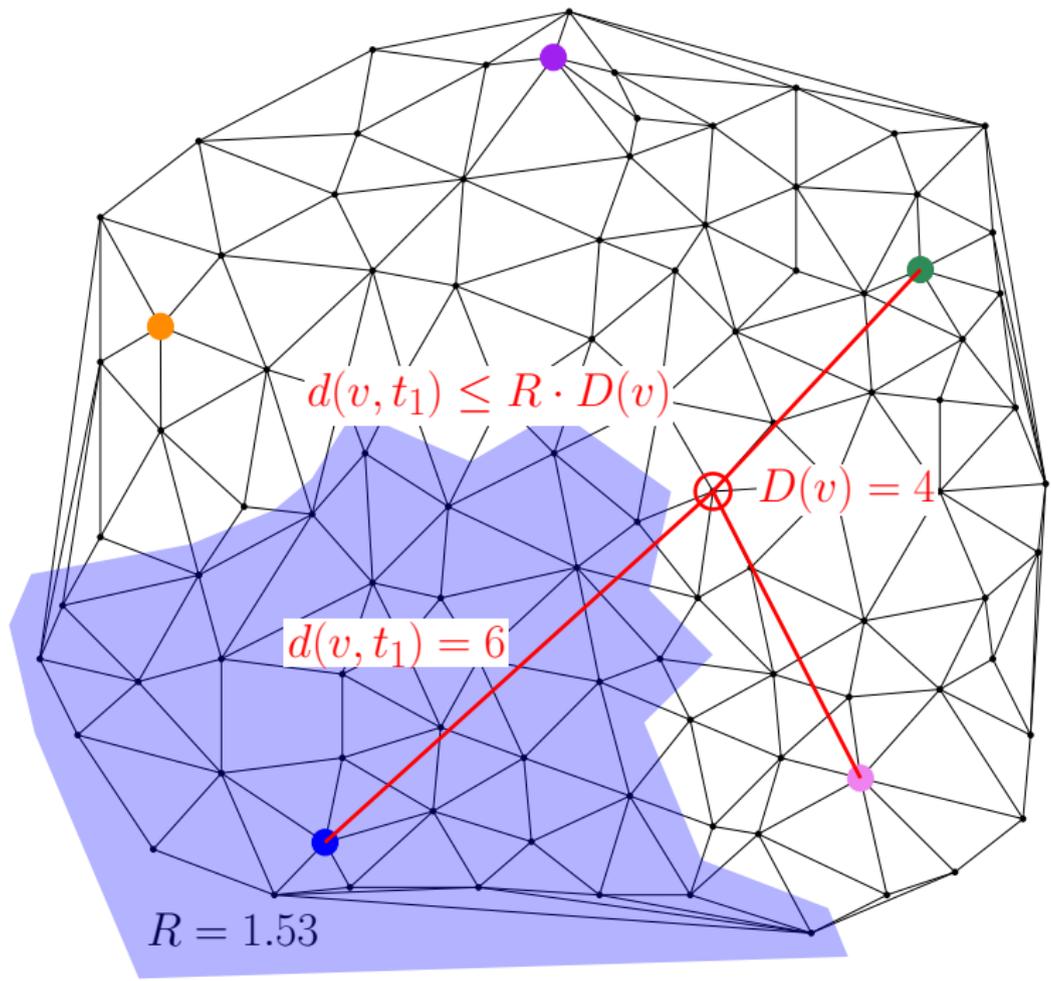


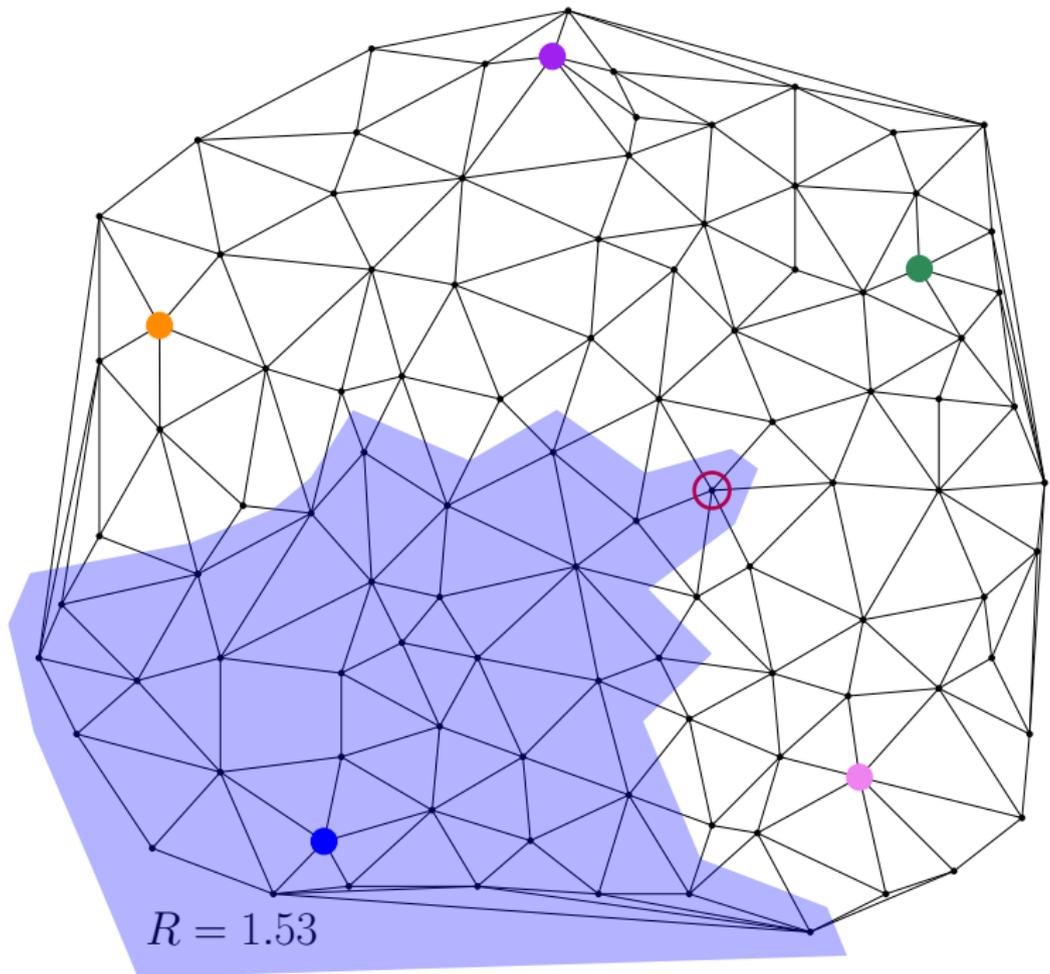


$d(v, t_1) = 6$

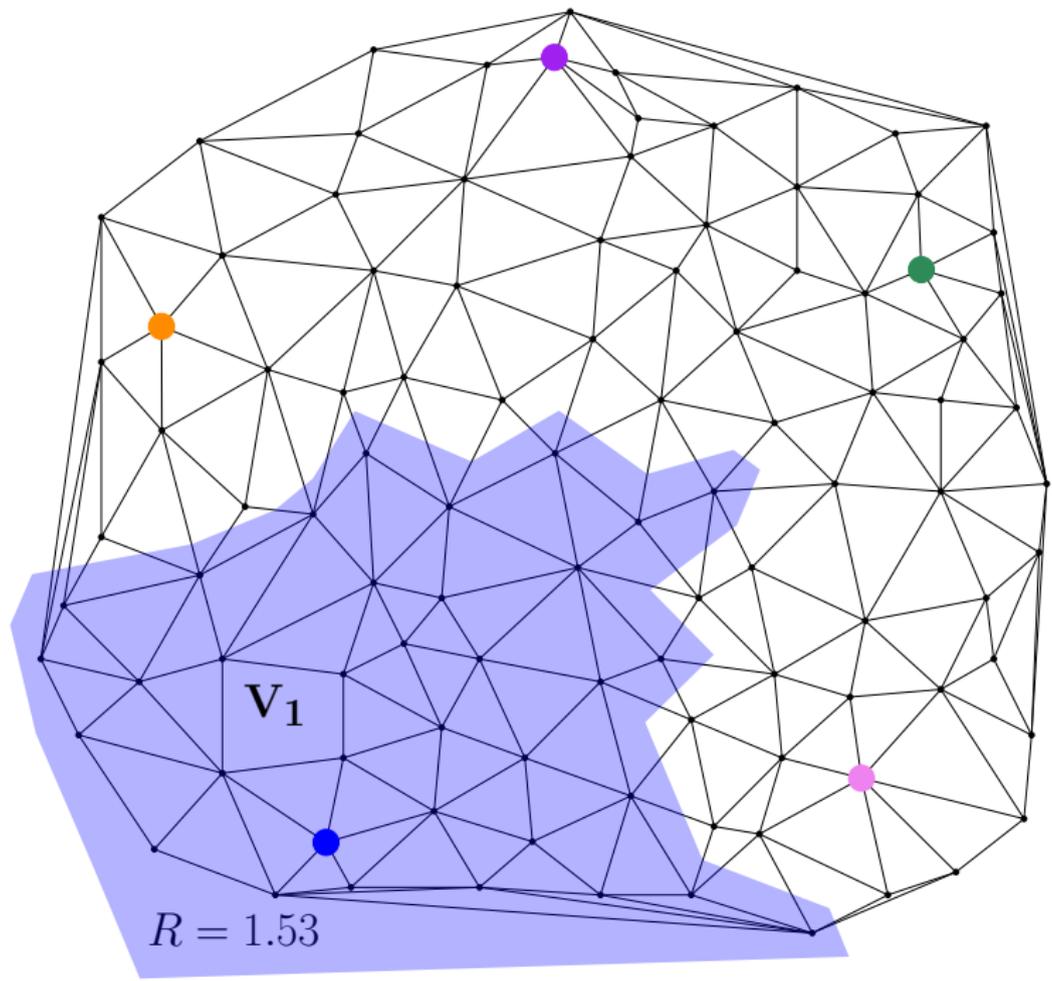
$D(v) = 4$

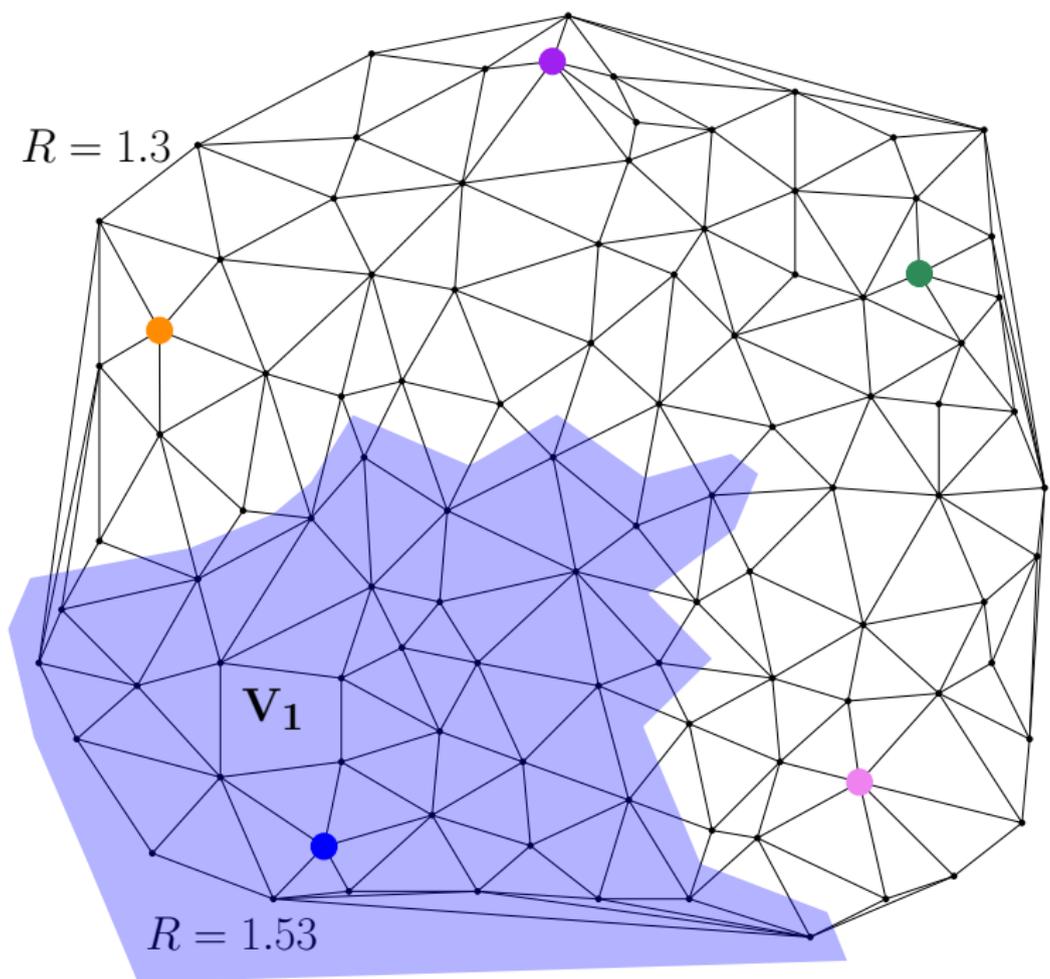
$R = 1.53$

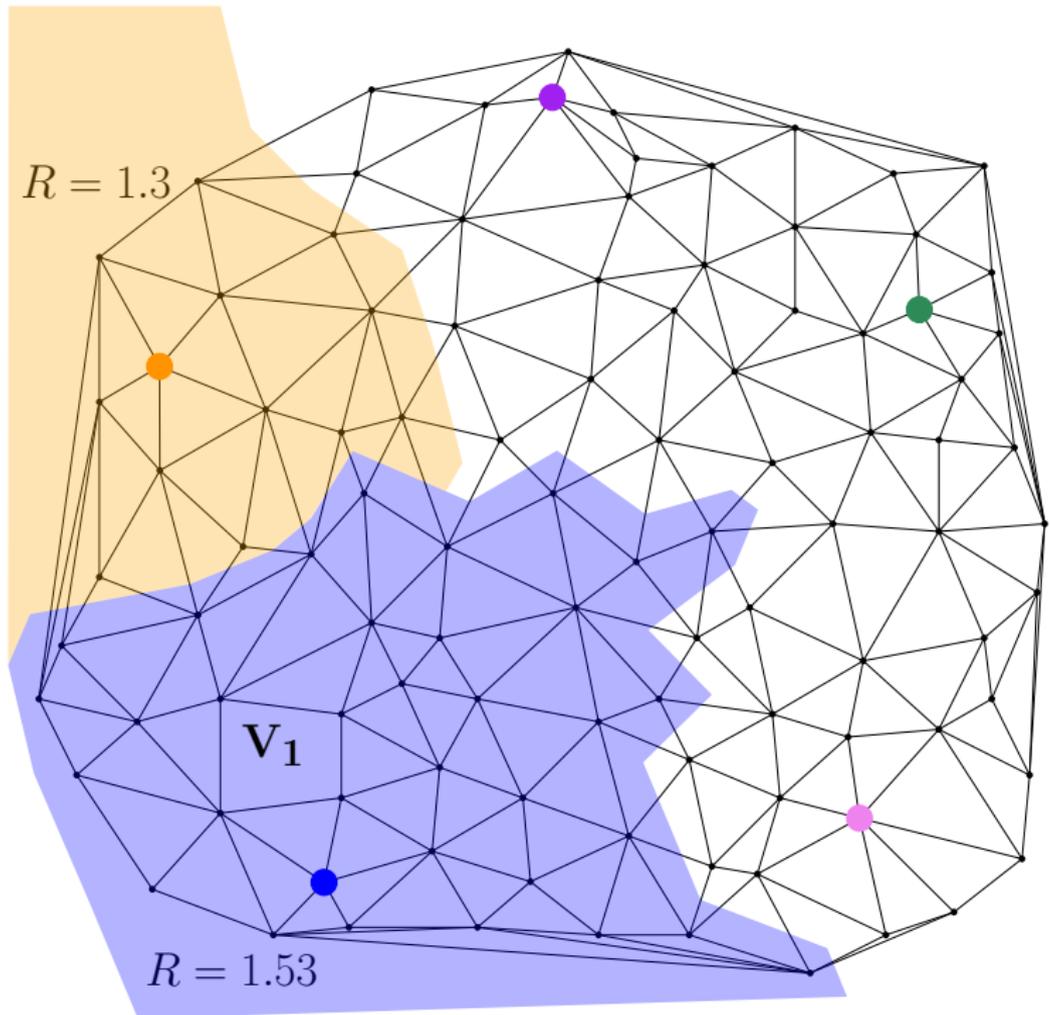


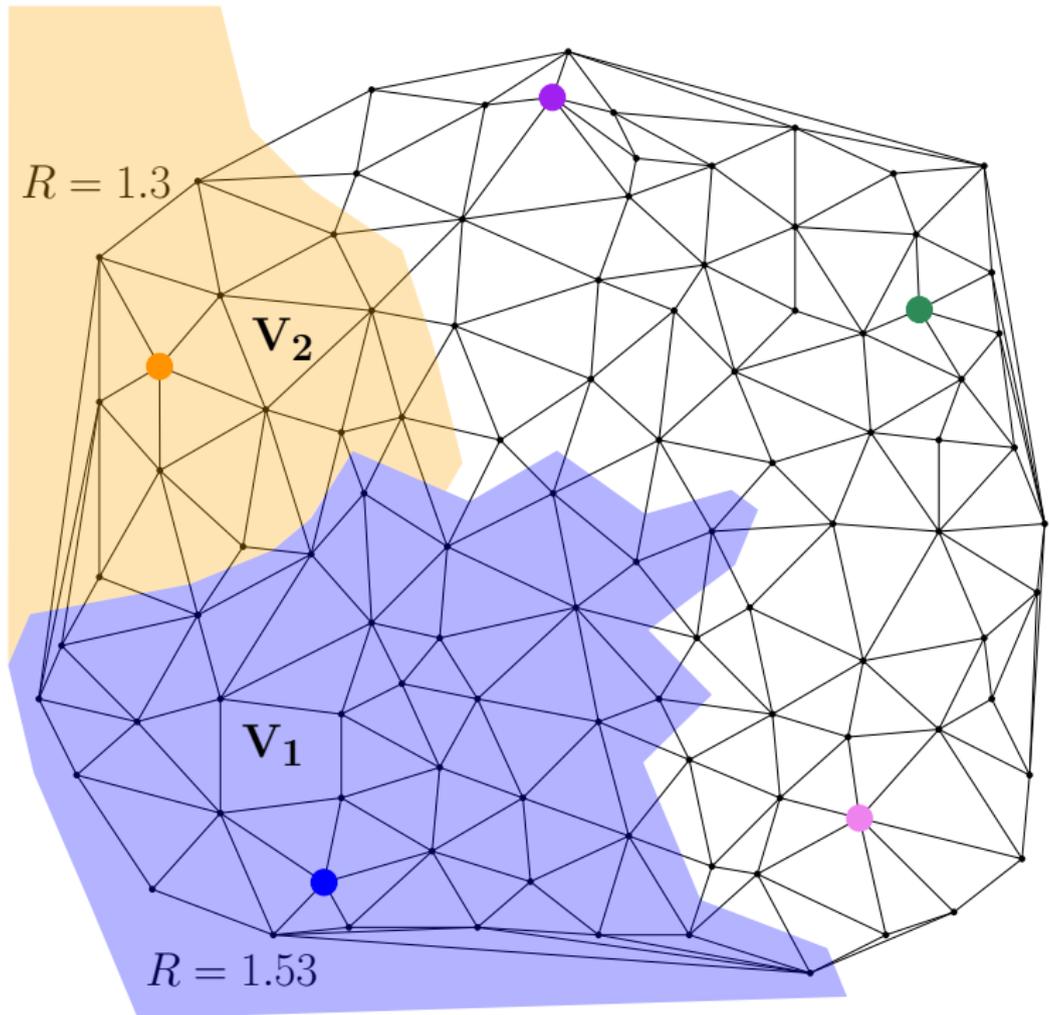


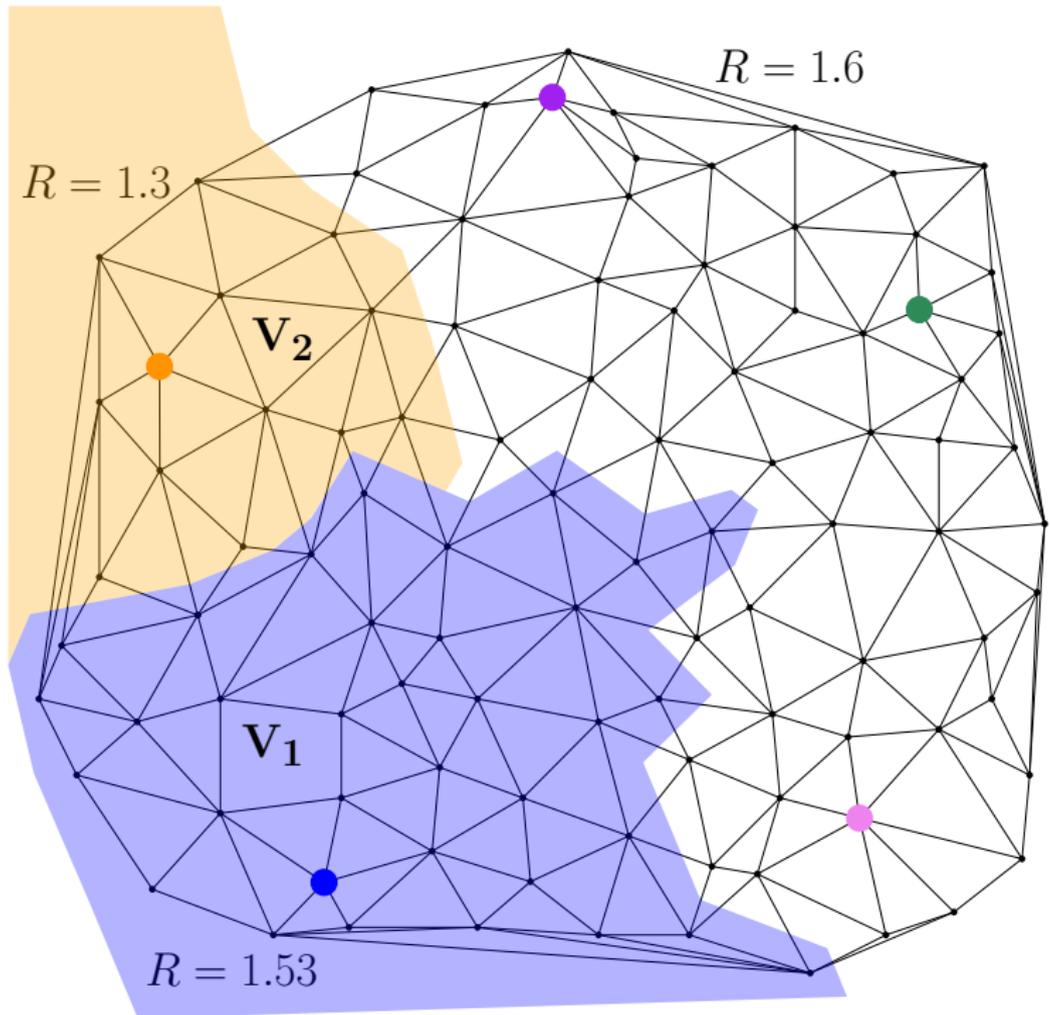
$R = 1.53$

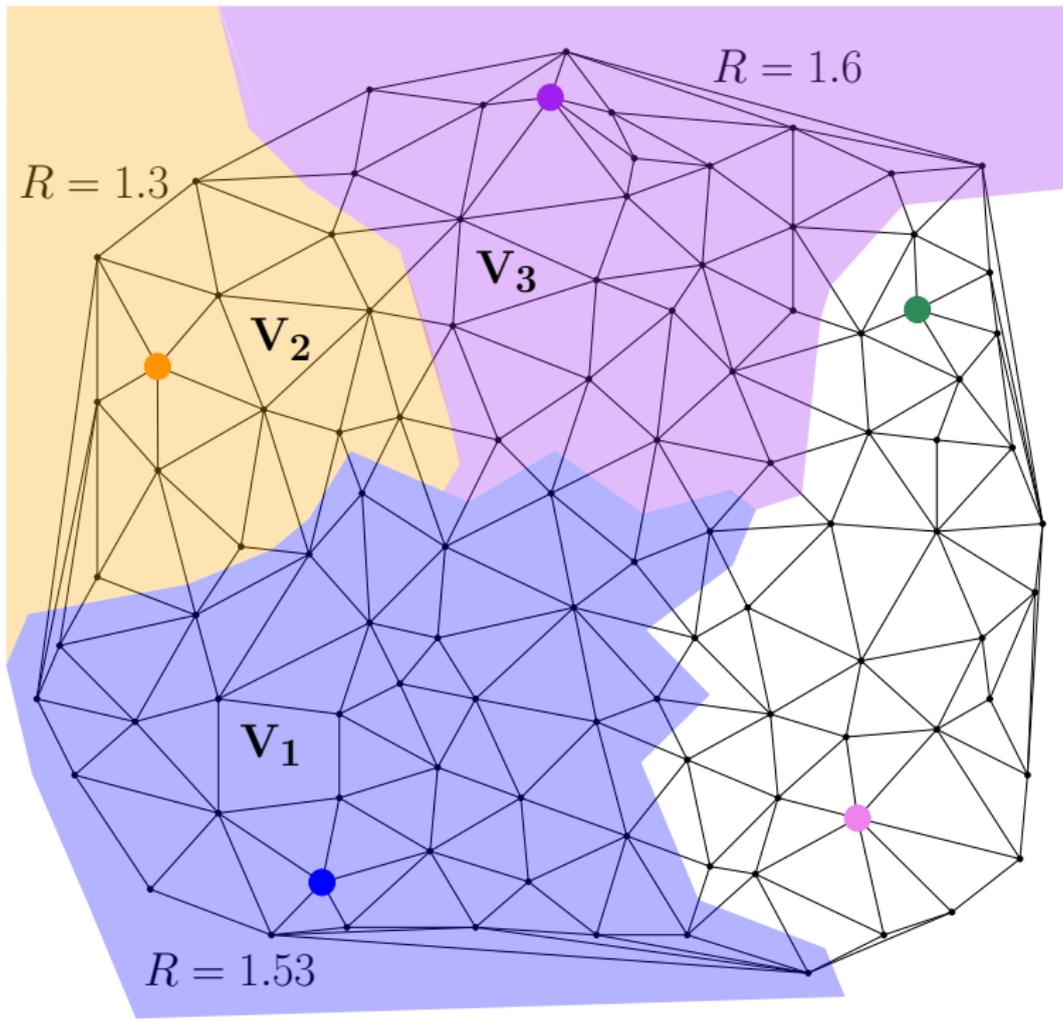


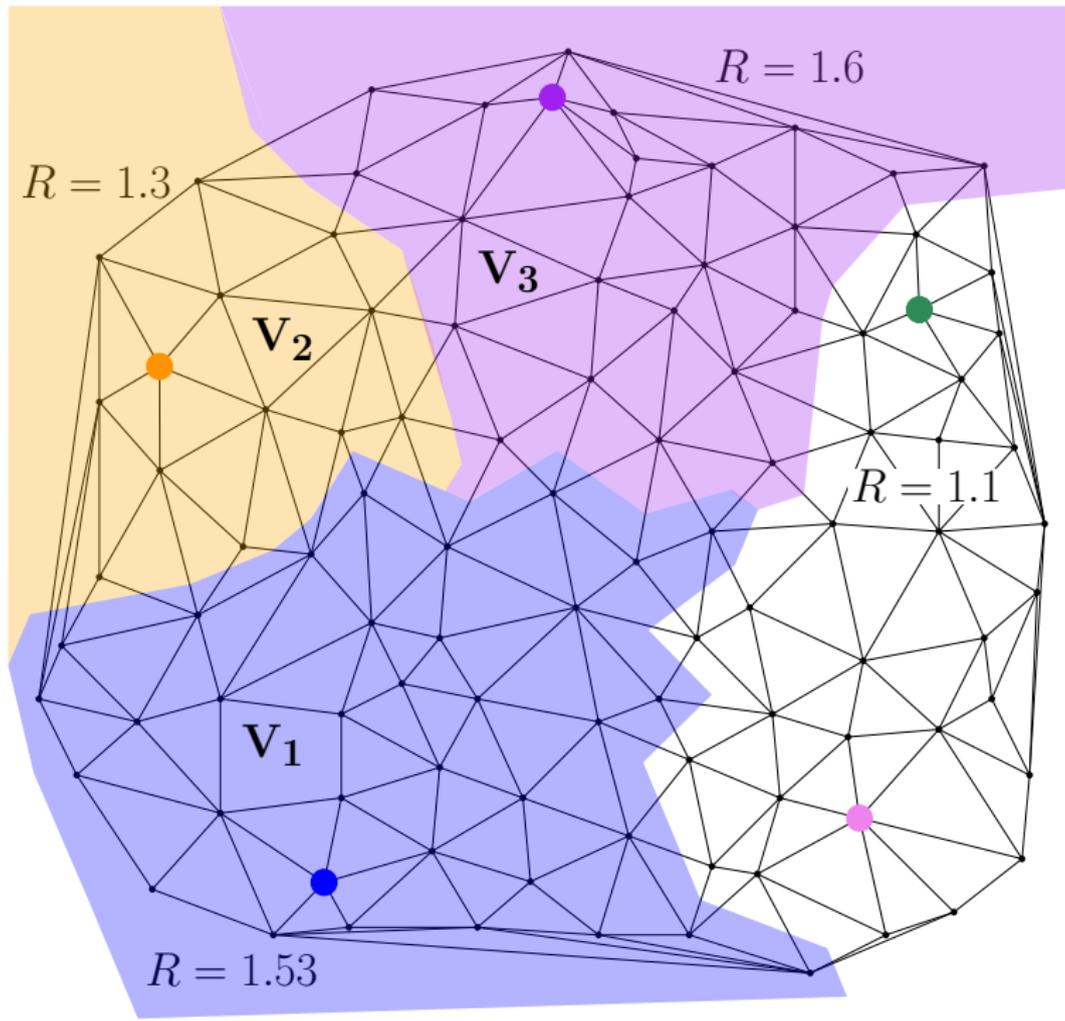


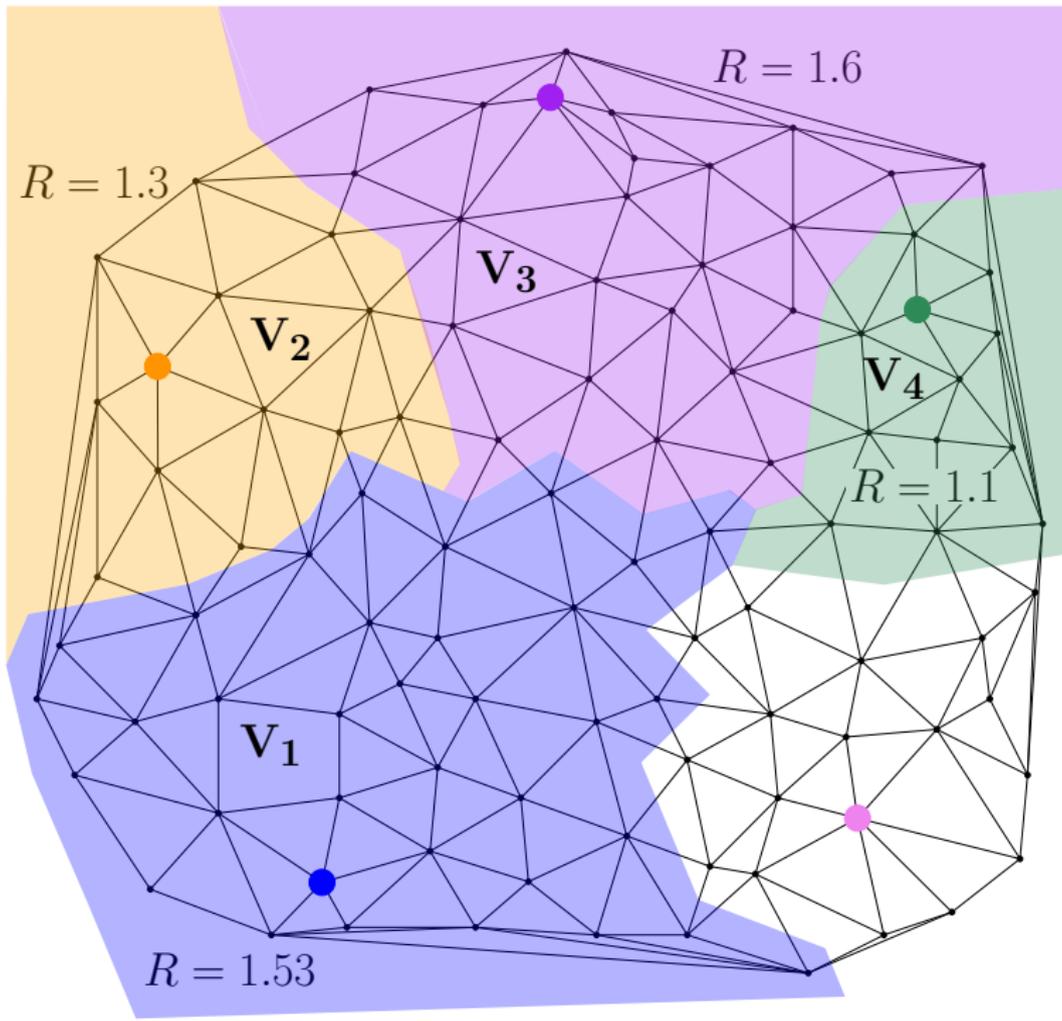


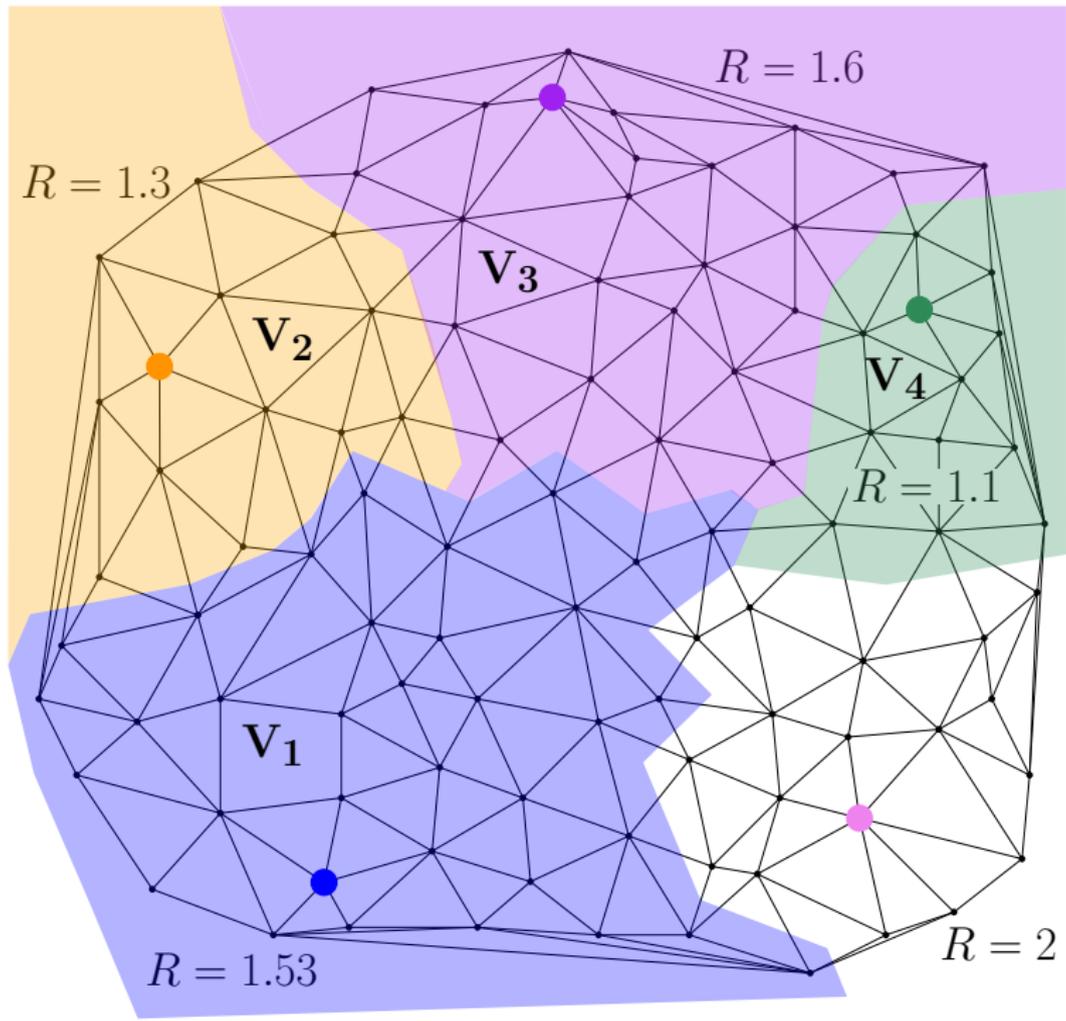


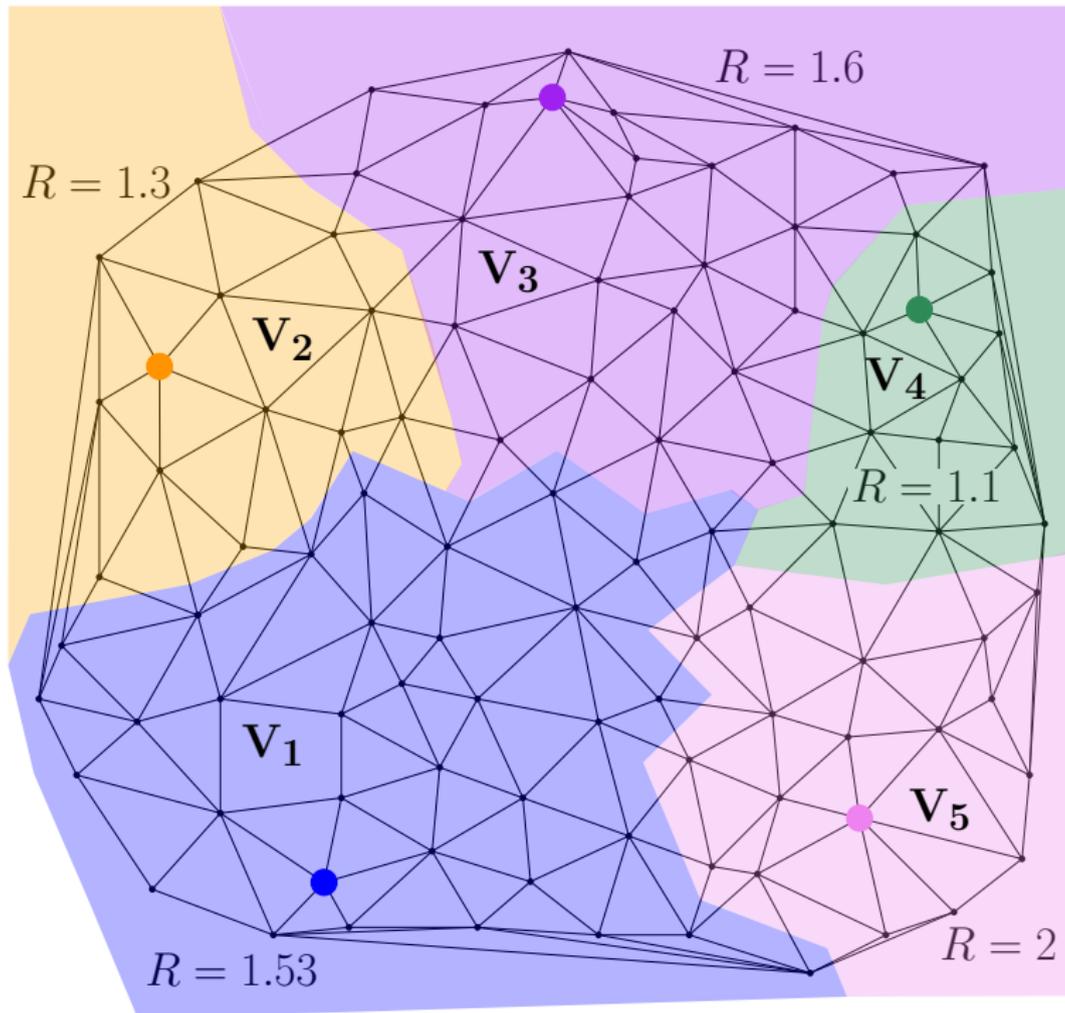


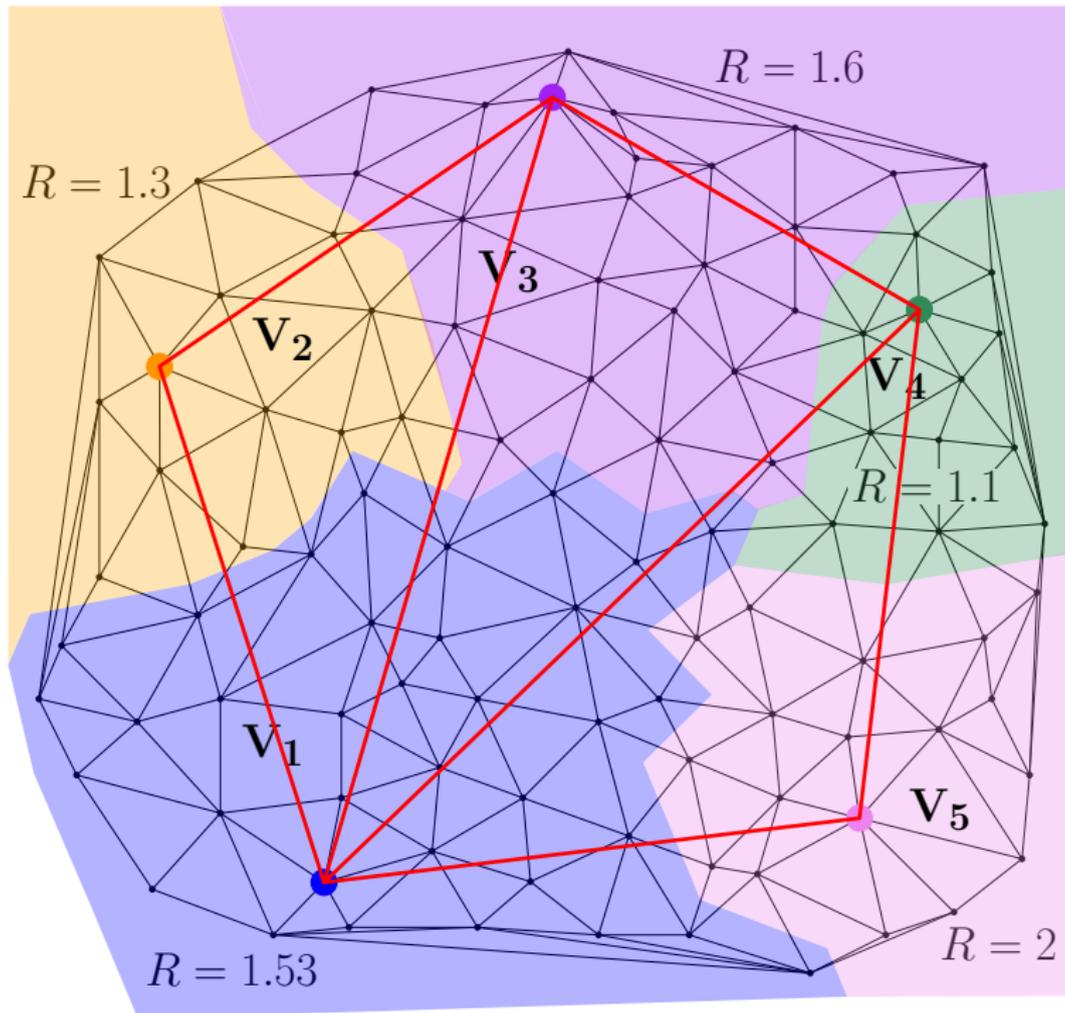












Noisy Voronoi

Set $\delta = 1/20 \ln k$ and $p = \frac{1}{5}$.

Set $R_j \leftarrow (1 + \delta)^{g_j}$,

where $g_j \sim \text{Geo}(p)$.

Noisy Voronoi

Set $\delta = 1/20 \ln k$ and $p = \frac{1}{5}$.

Set $R_j \leftarrow (1 + \delta)^{g_j}$, where $g_j \sim \text{Geo}(p)$.

Note that

$$g_j = O(\log k) \text{ (w.h.p)} \quad \Rightarrow \quad R_j = O(1).$$

Noisy Voronoi

Set $\delta = 1/20 \ln k$ and $p = \frac{1}{5}$.

Set $R_j \leftarrow (1 + \delta)^{g_j}$, where $g_j \sim \text{Geo}(p)$.

Note that

$$g_j = O(\log k) \text{ (w.h.p)} \quad \Rightarrow \quad R_j = O(1).$$

If v joins V_j , the cluster of t_j , then

$$d(v, t_j) \leq R_j \cdot D(v) = O(D(v)).$$

Noisy Voronoi

Set $\delta = 1/20 \ln k$ and $p = \frac{1}{5}$.

Set $R_j \leftarrow (1 + \delta)^{g_j}$, where $g_j \sim \text{Geo}(p)$.

Note that

$$g_j = O(\log k) \text{ (w.h.p)} \quad \Rightarrow \quad R_j = O(1).$$

If v joins V_j , the cluster of t_j , then

$$d(v, t_j) \leq R_j \cdot D(v) = O(D(v)).$$

Lemma

The Noisy Voronoi algorithm

*creates a **terminal partition**.*

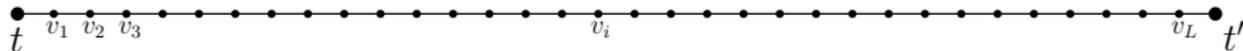
The Seed of Evil (distortion)

$t, t' \in K$, $P_{t,t'}$ is a shortest path in G .

The Seed of Evil (distortion)

$t, t' \in K$, $P_{t,t'}$ is a shortest path in G .

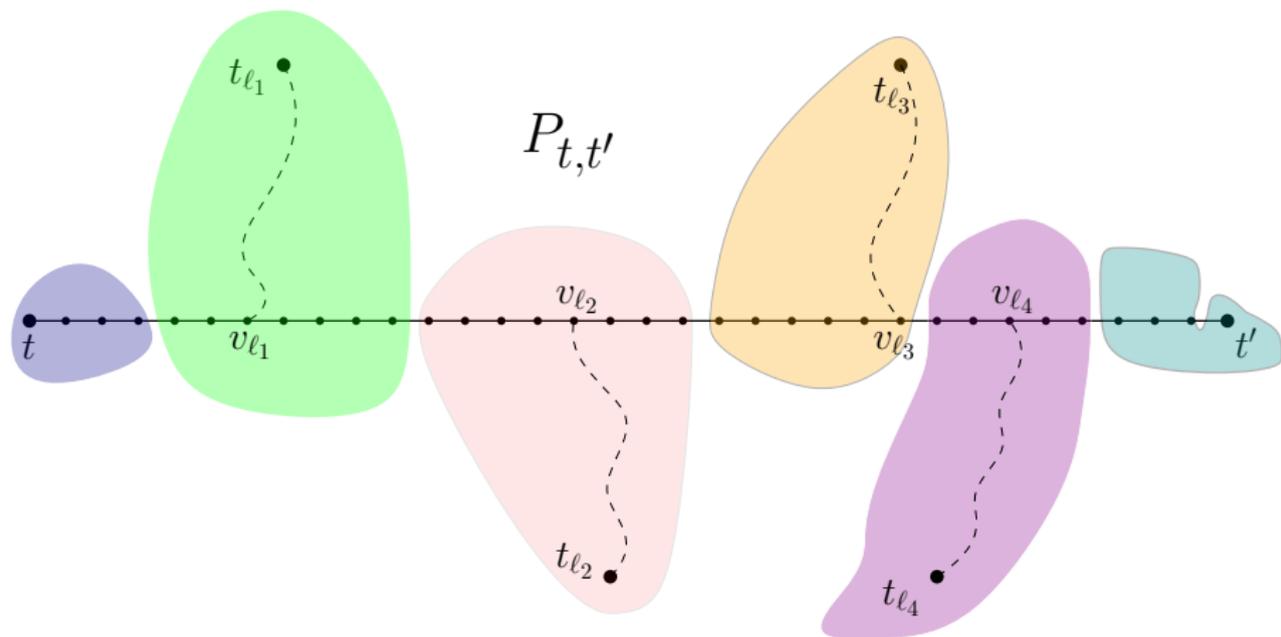
$P_{t,t'}$



The Seed of Evil (distortion)

$t, t' \in K$, $P_{t,t'}$ is a shortest path in G .

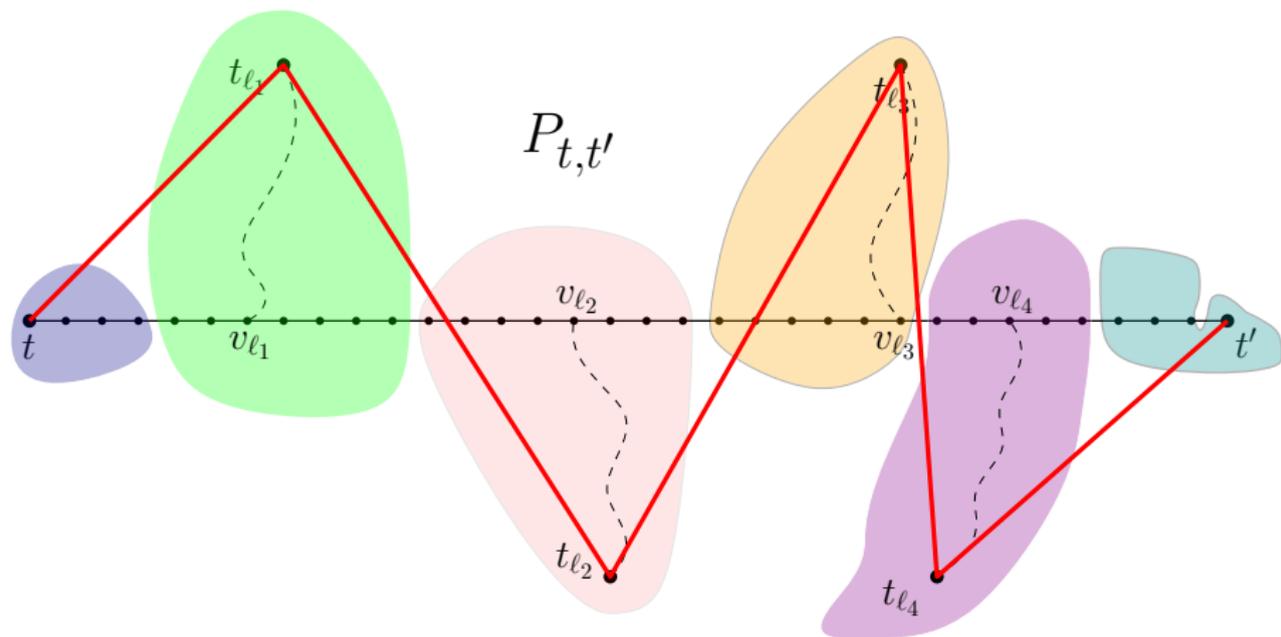
v_{l_i} is arbitrary vertex on $P_{t,t'}$ covered by t_{l_i} .



The Seed of Evil (distortion)

$t, t' \in K$, $P_{t,t'}$ is a shortest path in G .

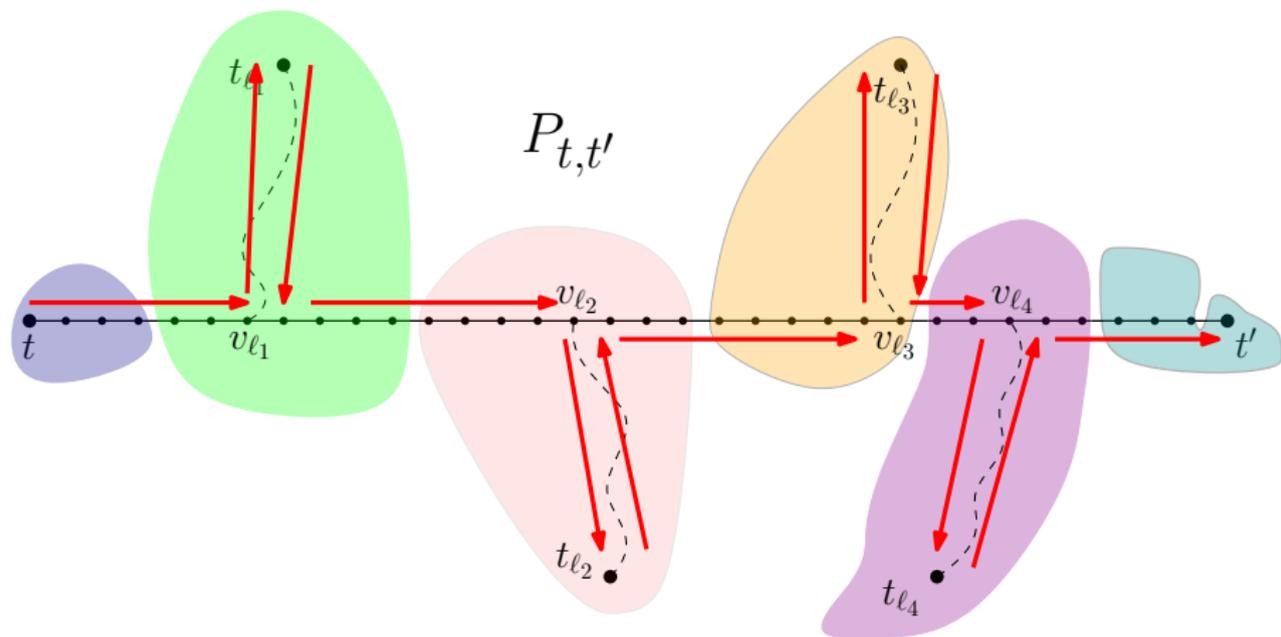
v_{l_i} is arbitrary vertex on $P_{t,t'}$ covered by t_{l_i} .



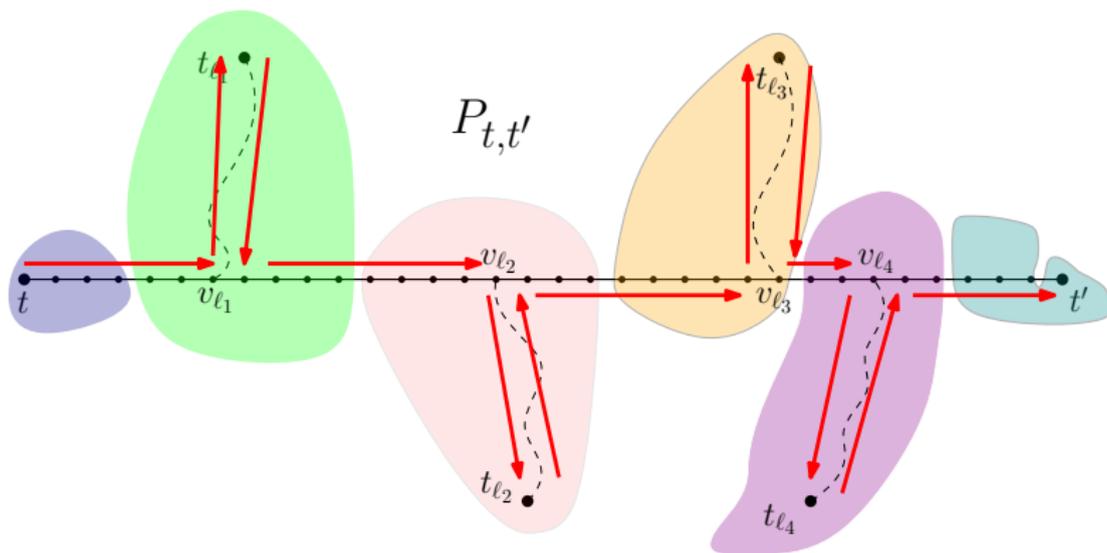
The Seed of Evil (distortion)

$t, t' \in K$, $P_{t,t'}$ is a shortest path in G .

v_{ℓ_i} is arbitrary vertex on $P_{t,t'}$ covered by t_{ℓ_i} .

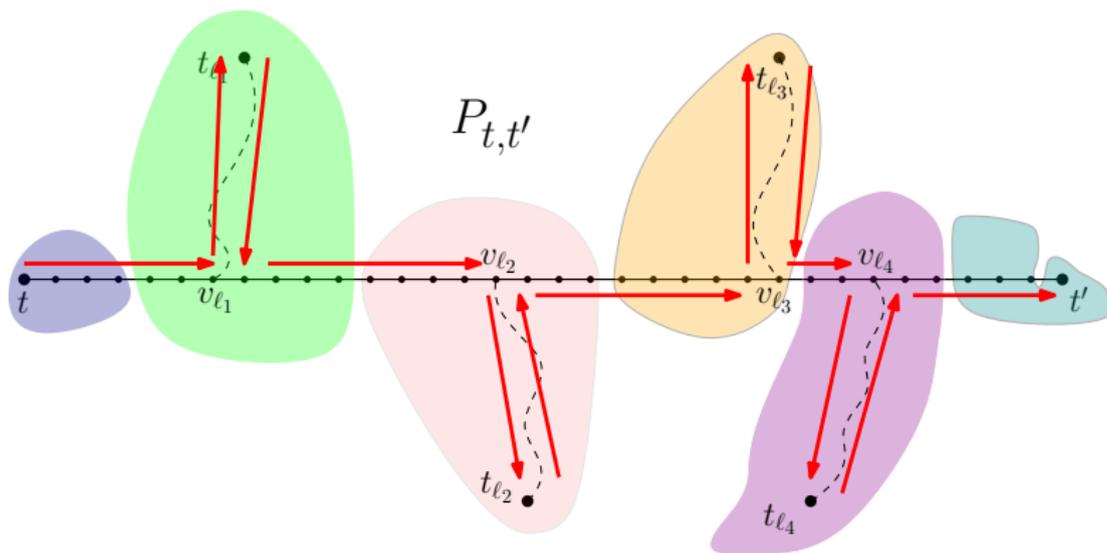


The Seed of Evil (distortion)



$$d_M(t, t') \leq d_G(t, t') + 2 \sum_i d_G(t_{l_i}, v_{l_i})$$

The Seed of Evil (distortion)



$$d_M(t, t') \leq d_G(t, t') + 2 \sum_i d_G(t_{l_i}, v_{l_i})$$

Analyze $\sum_i d_G(t_{l_i}, v_{l_i})!$

Analyzing $\sum_i d_G(t_i, v_i)$ directly will be **tricky**,
as $d_G(t_i, v_i)$ depends on V_1, \dots, V_{i-1} .

Analyzing $\sum_i d_G(t_i, v_i)$ directly will be **tricky**,
as $d_G(t_i, v_i)$ depends on V_1, \dots, V_{i-1} .

We will partition $P_{t,t'}$ into **intervals**, and **charge** the
interval starting the detour **instead** of the **terminal!**

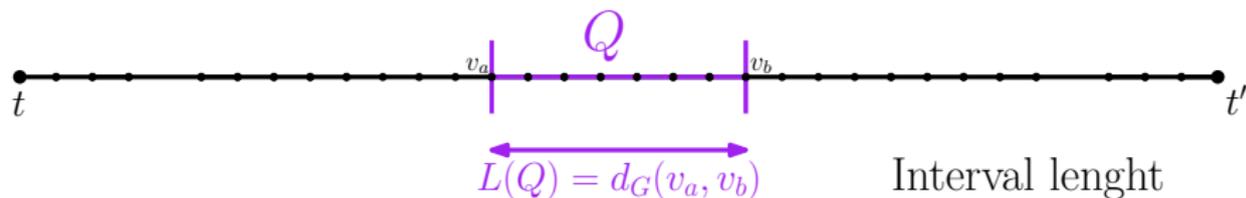
Analyzing $\sum_i d_G(t_i, v_i)$ directly will be **tricky**,
as $d_G(t_i, v_i)$ depends on V_1, \dots, V_{i-1} .

We will partition $P_{t,t'}$ into **intervals**, and **charge** the
interval starting the detour **instead** of the **terminal!**



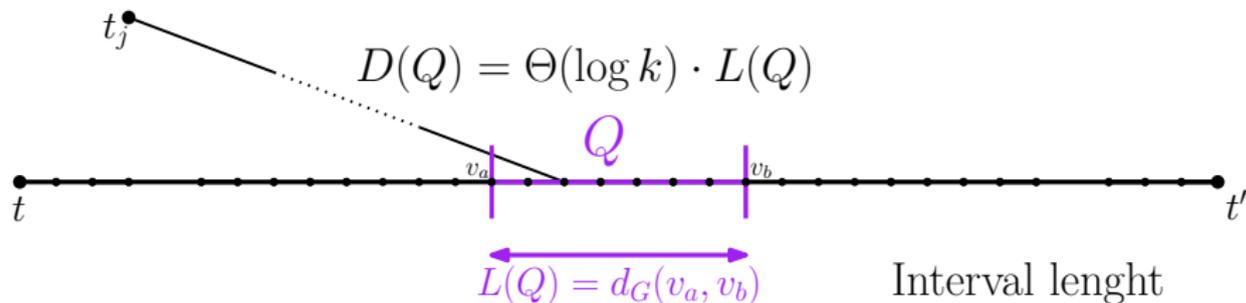
Partition of $P_{t,t'}$ to Intervals

Q is a interval of $P_{t,t'}$.



Partition of $P_{t,t'}$ to Intervals

Q is a interval of $P_{t,t'}$.

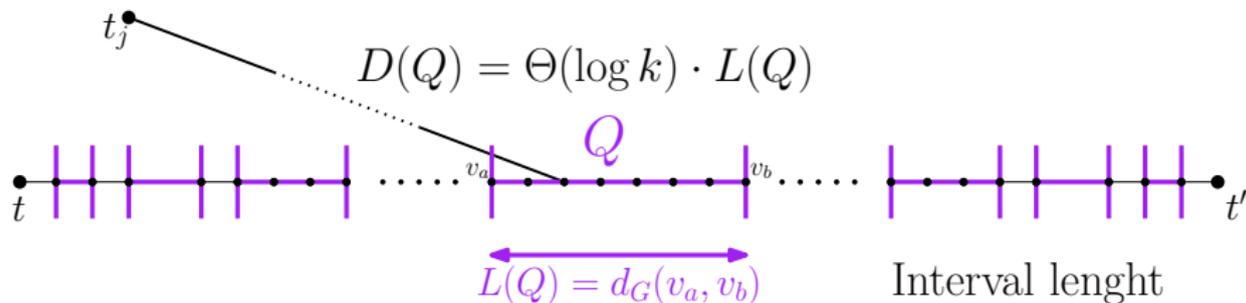


Partition $P_{t,t}$ into Q , s.t. for each $Q \in \mathcal{Q}$

$$L(Q) = \Theta\left(\frac{1}{\log k}\right) \cdot D(Q)$$

Partition of $P_{t,t'}$ to Intervals

Q is a interval of $P_{t,t'}$.

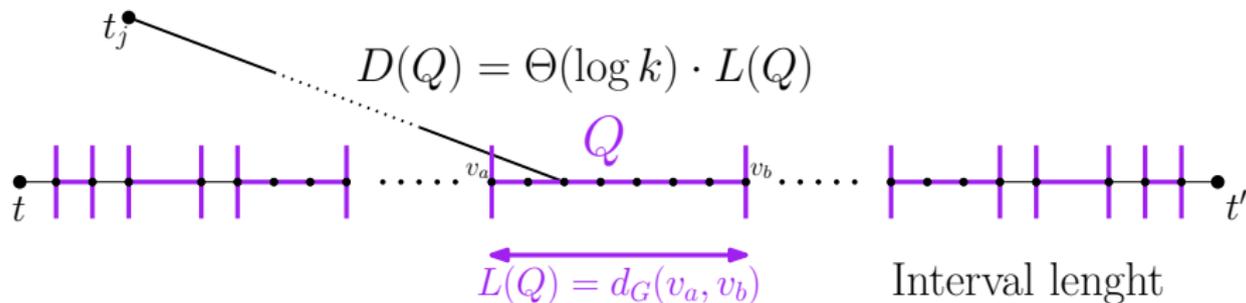


Partition $P_{t,t'}$ into Q , s.t. for each $Q \in \mathcal{Q}$

$$L(Q) = \Theta\left(\frac{1}{\log k}\right) \cdot D(Q)$$

Partition of $P_{t,t'}$ to Intervals

Q is a interval of $P_{t,t'}$.



Partition $P_{t,t}$ into Q , s.t. for each $Q \in \mathcal{Q}$

$$L(Q) = \Theta\left(\frac{1}{\log k}\right) \cdot D(Q)$$

Once t_j covered some $v_j \in Q$, w.p $1 - p$ it covers all of Q .

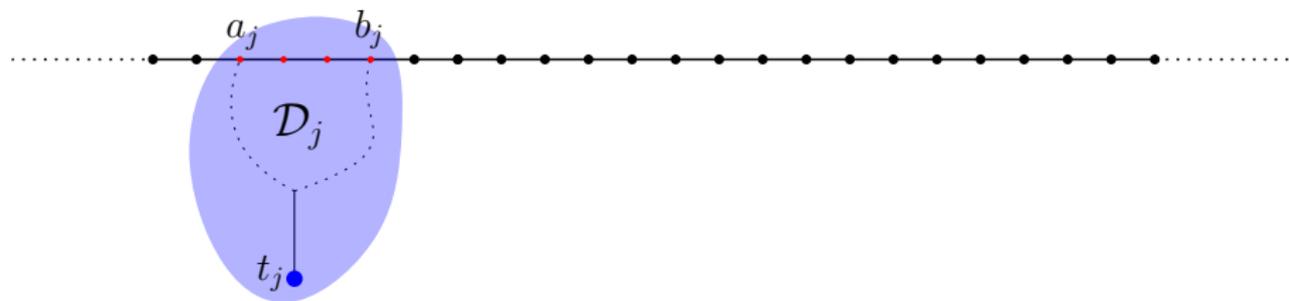
Active vertices

At the beginning all vertices are **active**.



Active vertices

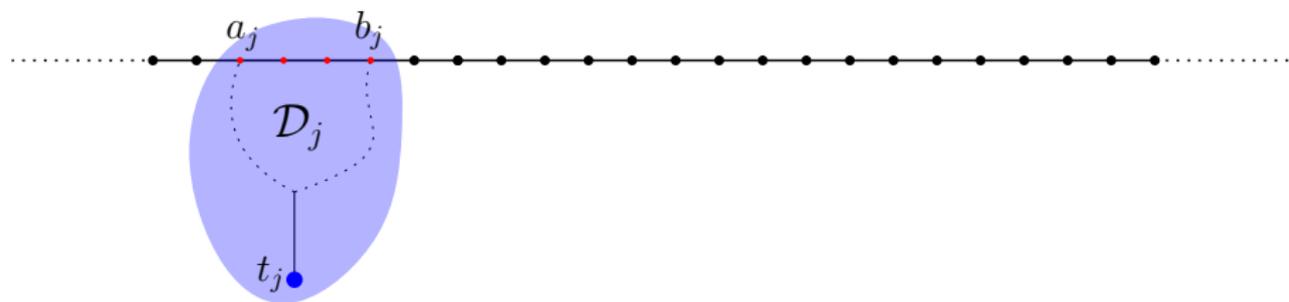
At the beginning all vertices are **active**.



Terminal t_j grows cluster V_j .

Active vertices

At the beginning all vertices are **active**.

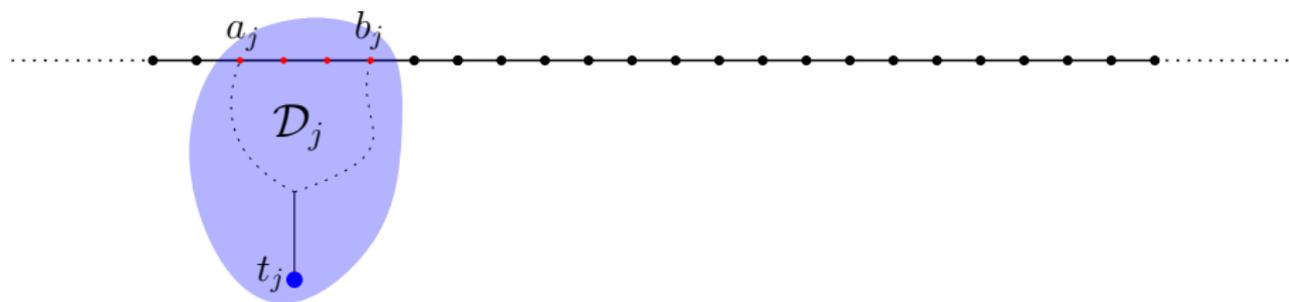


Terminal t_j grows cluster V_j .

a_j (resp. b_j) is the leftmost (resp. rightmost) **active** covered vertex.

Active vertices

At the beginning all vertices are **active**.



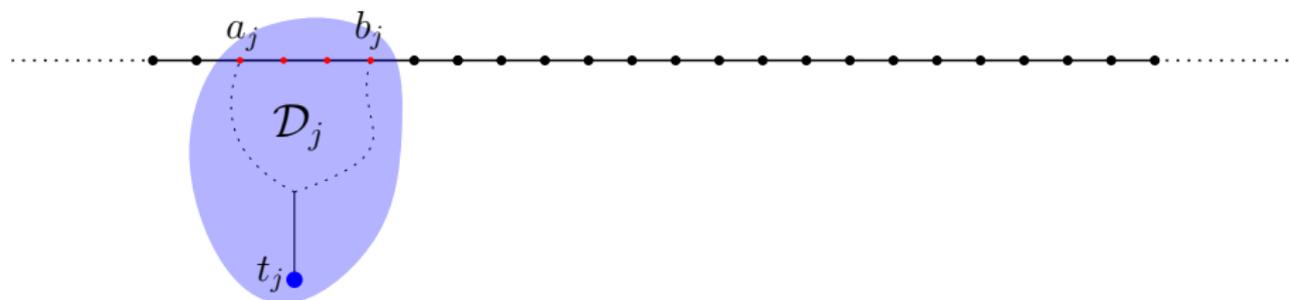
Terminal t_j grows cluster V_j .

a_j (resp. b_j) is the leftmost (resp. rightmost) **active** covered vertex.

$\mathcal{D}_j = \{a_j, \dots, b_j\} \subseteq P_{t,t'}$ is called a **detour**.

Active vertices

At the beginning all vertices are **active**.



Terminal t_j grows cluster V_j .

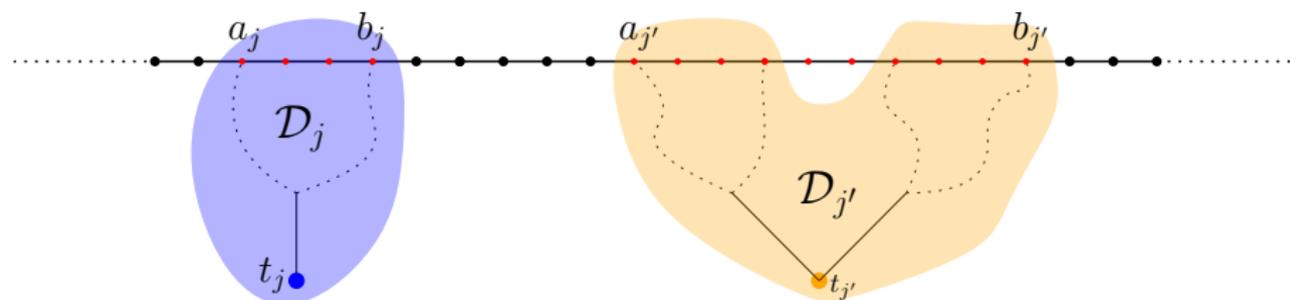
a_j (resp. b_j) is the leftmost (resp. rightmost) **active** covered vertex.

$\mathcal{D}_j = \{a_j, \dots, b_j\} \subseteq P_{t, t'}$ is called a **detour**.

All the vertices in \mathcal{D}_j become **inactive**.

Active vertices

At the beginning all vertices are **active**.



Terminal t_j grows cluster V_j .

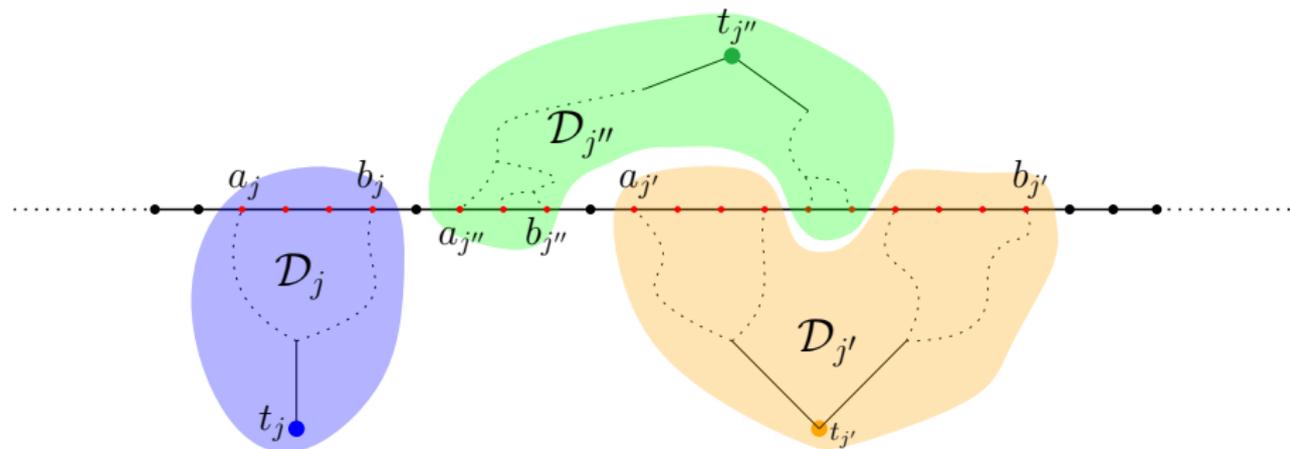
a_j (resp. b_j) is the leftmost (resp. rightmost) **active** covered vertex.

$\mathcal{D}_j = \{a_j, \dots, b_j\} \subseteq P_{t, t'}$ is called a **detour**.

All the vertices in \mathcal{D}_j become **inactive**.

Active vertices

At the beginning all vertices are **active**.



Terminal t_j grows cluster V_j .

a_j (resp. b_j) is the leftmost (resp. rightmost) **active** covered vertex.

$\mathcal{D}_j = \{a_j, \dots, b_j\} \subseteq P_{t, t'}$ is called a **detour**.

All the vertices in \mathcal{D}_j become **inactive**.

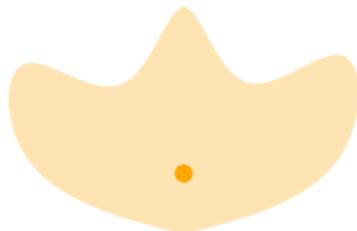
Charges



$$R_j = (1 + \delta)^{g_1}$$

Detour \mathcal{D}_j will be **charged** upon a single interval.

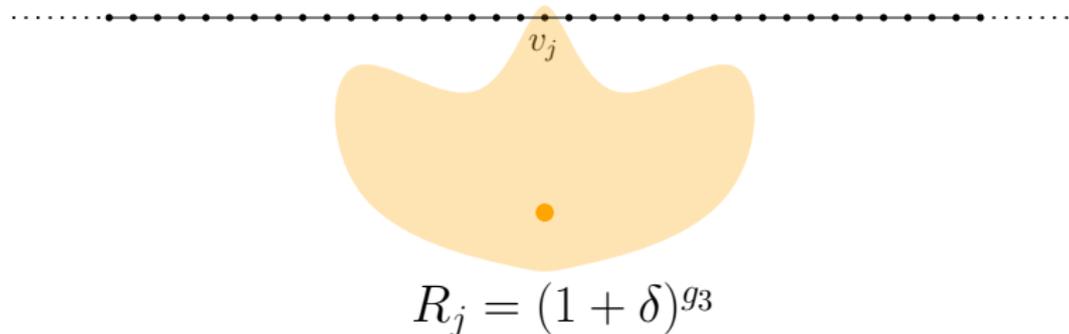
Charges



$$R_j = (1 + \delta)^{g_2}$$

Detour \mathcal{D}_j will be **charged** upon a single interval.

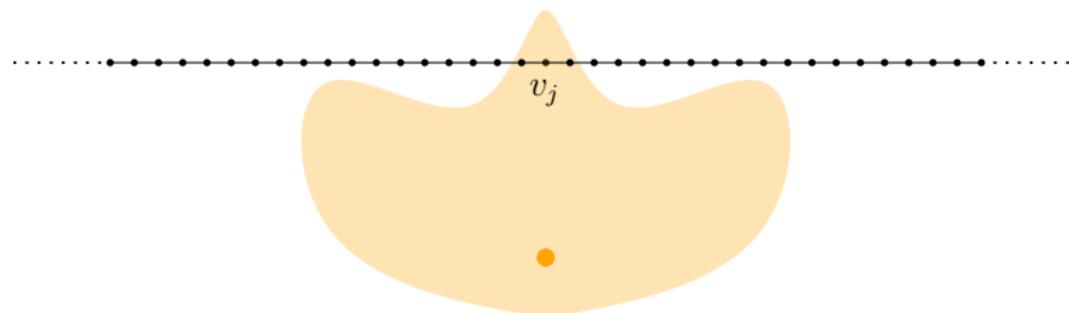
Charges



Detour \mathcal{D}_j will be **charged** upon a single interval.

v_j is the “**first active**” covered vertex by t_j in $P_{t,t'}$.

Charges

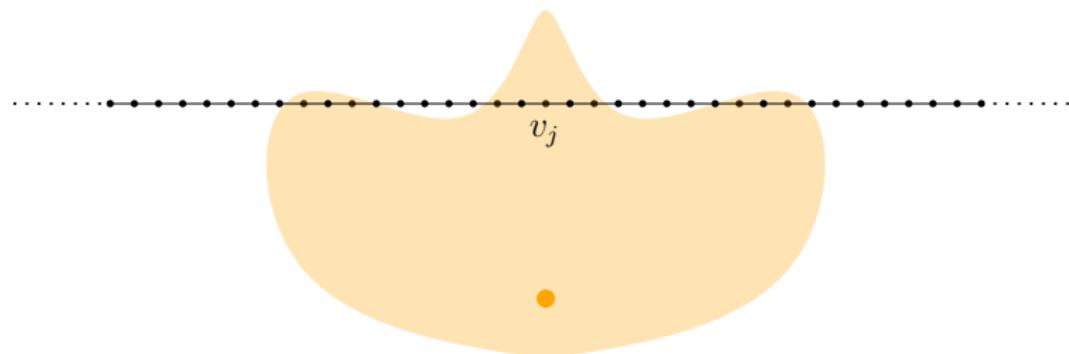


$$R_j = (1 + \delta)^{g_4}$$

Detour \mathcal{D}_j will be **charged** upon a single interval.

v_j is the “**first active**” covered vertex by t_j in $P_{t,t'}$.

Charges

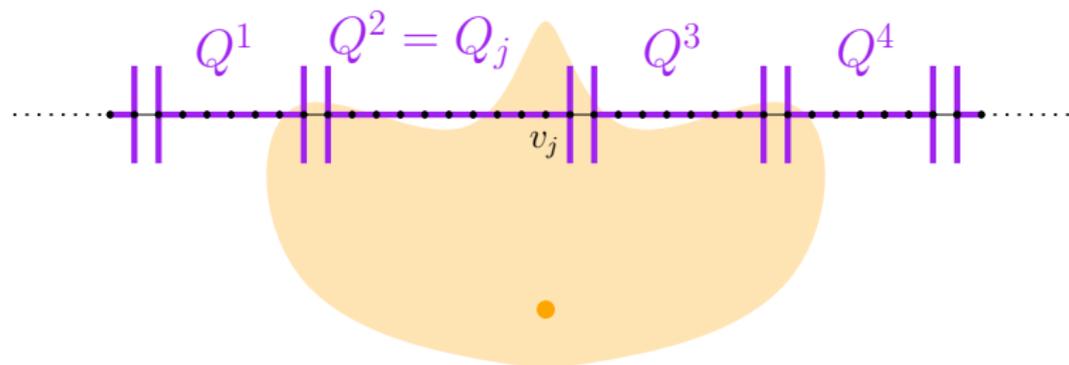


$$R_j = (1 + \delta)^{g_5}$$

Detour \mathcal{D}_j will be **charged** upon a single interval.

v_j is the “**first active**” covered vertex by t_j in $P_{t,t'}$.

Charges



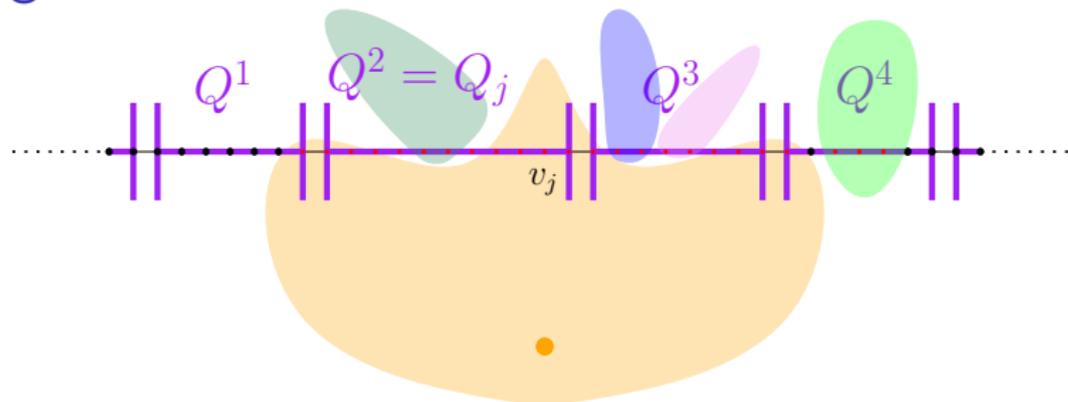
$$R_j = (1 + \delta)^{g_5}$$

Detour \mathcal{D}_j will be **charged** upon a single interval.

v_j is the “**first active**” covered vertex by t_j in $P_{t,t'}$.

$Q_j \in \mathcal{Q}$ ($v_j \in Q_j$) is charged upon \mathcal{D}_j .

Charges



$$R_j = (1 + \delta)^{g_5}$$

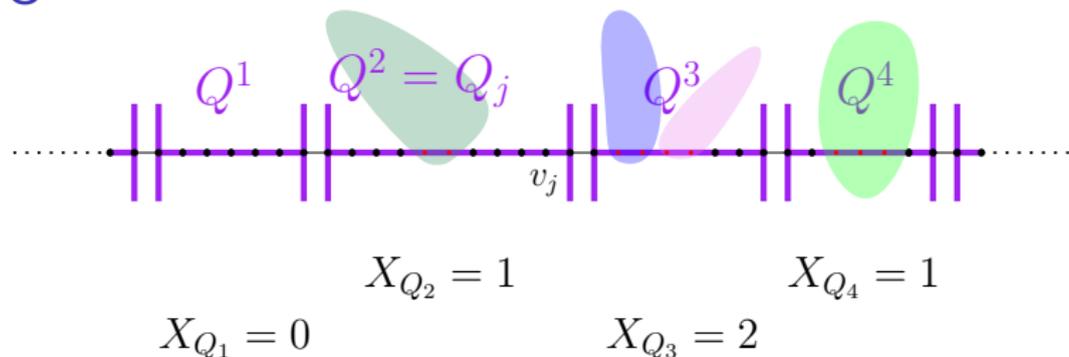
Detour \mathcal{D}_j will be **charged** upon a single interval.

v_j is the “**first active**” covered vertex by t_j in $P_{t,t'}$.

$Q_j \in \mathcal{Q}$ ($v_j \in Q_j$) is charged upon \mathcal{D}_j .

X_Q is the **current** number of detours the interval Q is **charged** for.

Charges



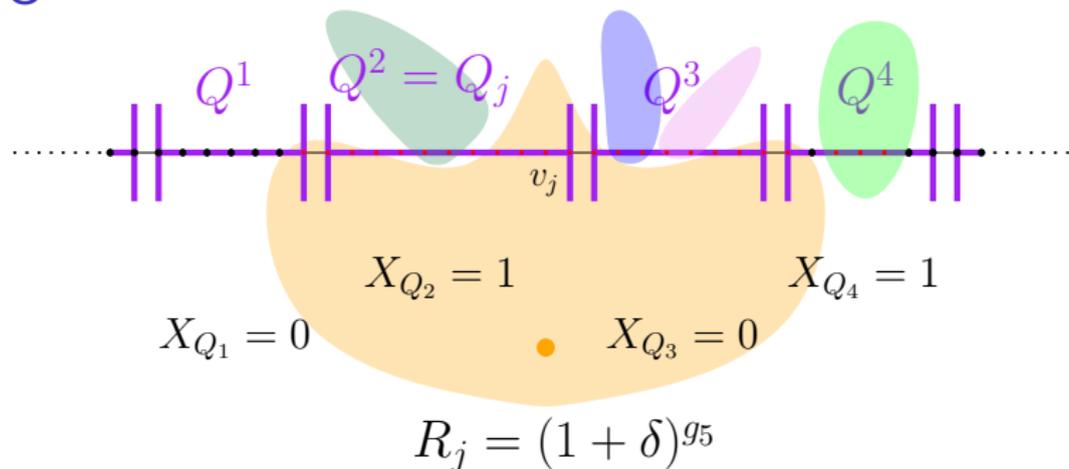
Detour \mathcal{D}_j will be **charged** upon a single interval.

v_j is the “**first active**” covered vertex by t_j in $P_{t,t'}$.

$Q_j \in \mathcal{Q}$ ($v_j \in Q_j$) is charged upon \mathcal{D}_j .

X_Q is the **current** number of detours the interval Q is **charged** for.

Charges



Detour \mathcal{D}_j will be **charged** upon a single interval.

v_j is the “**first active**” covered vertex by t_j in $P_{t,t'}$.

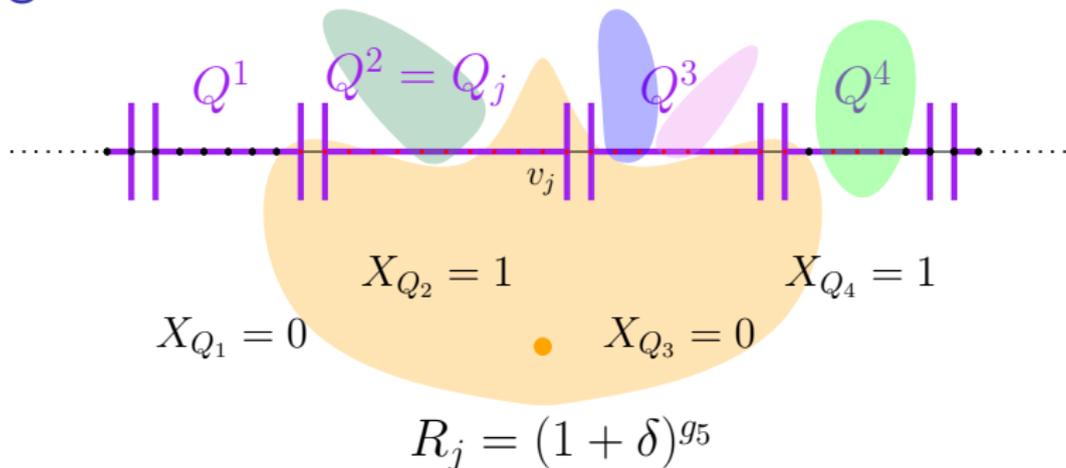
$Q_j \in \mathcal{Q}$ ($v_j \in Q_j$) is charged upon \mathcal{D}_j .

X_Q is the **current** number of detours the interval Q is **charged** for.

Every detour $\mathcal{D}_{j'}$ which is **contained** in \mathcal{D}_j **erased**,

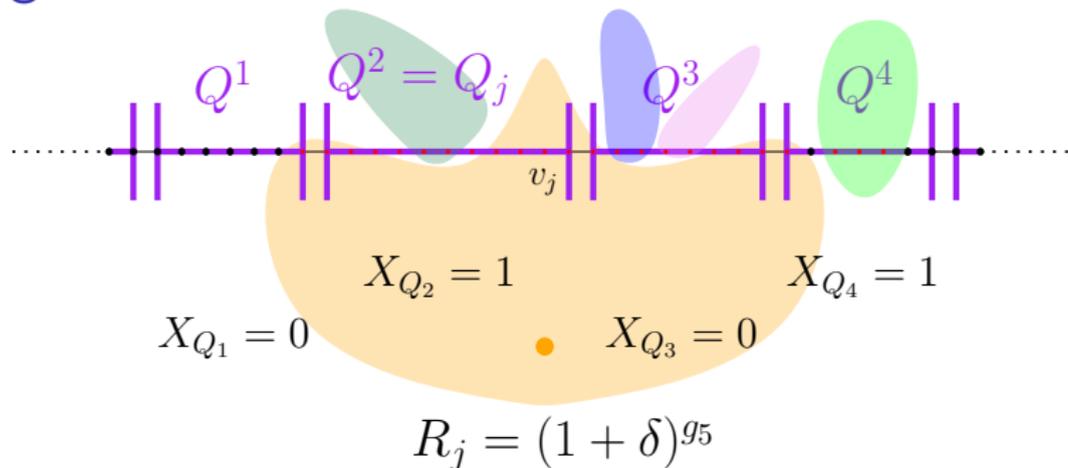
and its charge **re-funded!**

Charges



X_{Q_j} increases by **at most 1**.

Charges



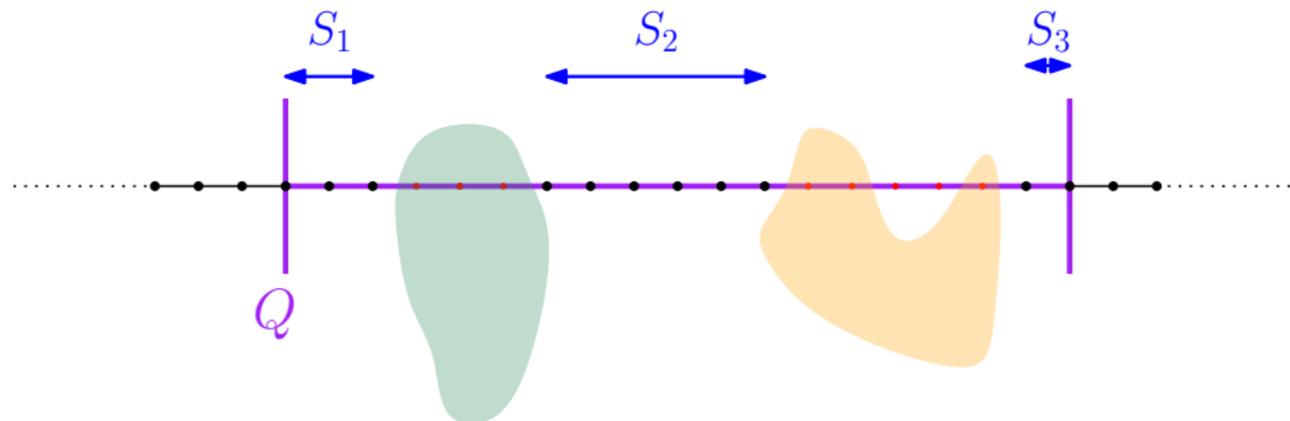
X_{Q_j} increases by **at most 1**.

For every $Q \neq Q_j$, X_Q can **only decrease**.

Slices: “The Potential to be Charged”

Within interval $Q \in \mathcal{Q}$,

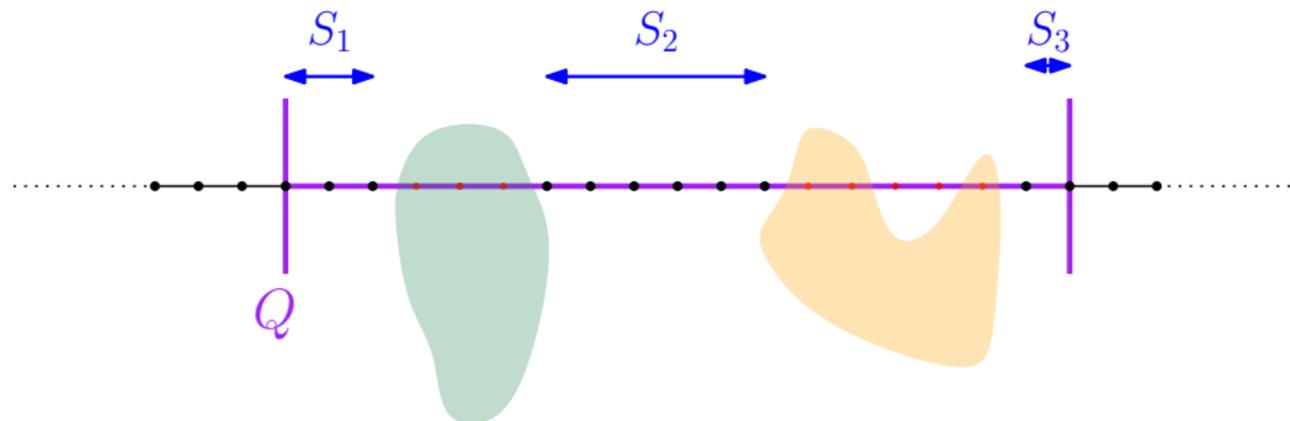
maximal sub-interval of active vertices is called a **slice**.



Slices: “The Potential to be Charged”

Within interval $Q \in \mathcal{Q}$,

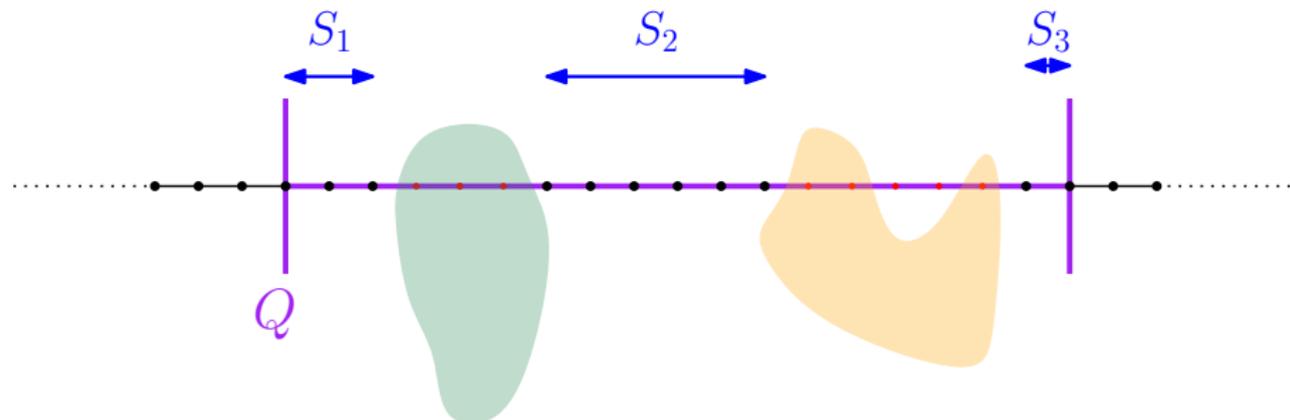
maximal sub-interval of active vertices is called a **slice**.



We denote by $\#\mathcal{S}(Q)$ the current **number of slices** in Q .

Slices: “The Potential to be Charged”

Within interval $Q \in \mathcal{Q}$,
maximal sub-interval of active vertices is called a **slice**.



We denote by $\#\mathcal{S}(Q)$ the current **number of slices** in Q .

At the start, $\#\mathcal{S}(Q) = 1$.

At the end, $\#\mathcal{S}(Q) = 0$.

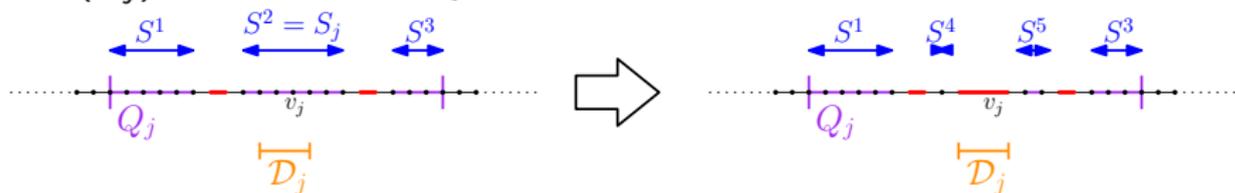
Change in Number of Slices

Let $S_j \subseteq Q_j$ be the slice containing v_j . Consider Q_j .

Change in Number of Slices

Let $S_j \subseteq Q_j$ be the slice containing v_j . Consider Q_j .

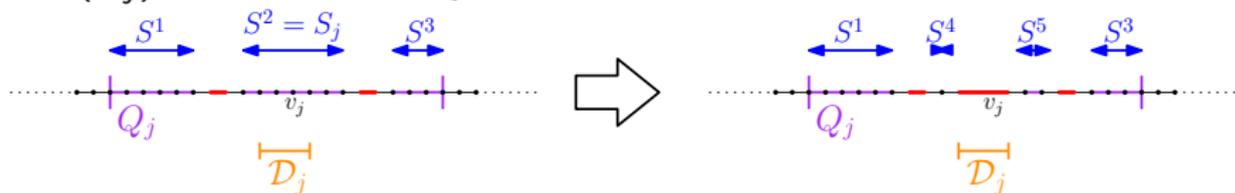
$\#S(Q_j)$ can **increase** by 1.



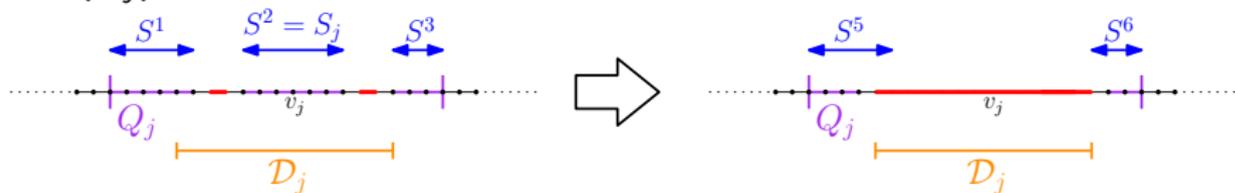
Change in Number of Slices

Let $S_j \subseteq Q_j$ be the slice containing v_j . Consider Q_j .

$\#S(Q_j)$ can **increase** by 1.



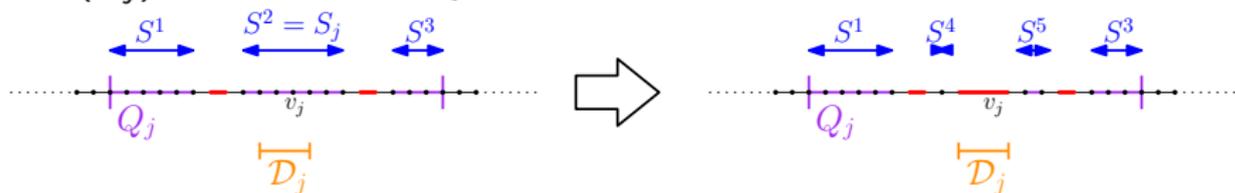
$\#S(Q_j)$ can **decrease**.



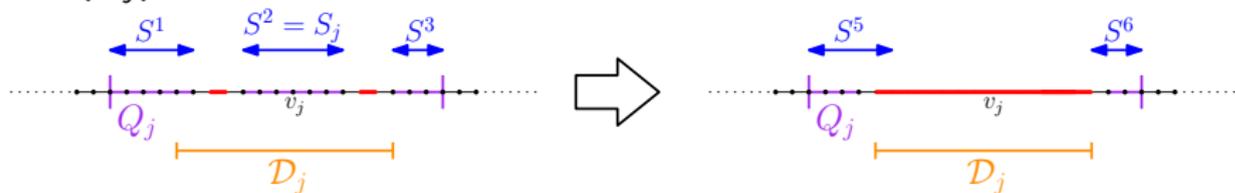
Change in Number of Slices

Let $S_j \subseteq Q_j$ be the slice containing v_j . Consider Q_j .

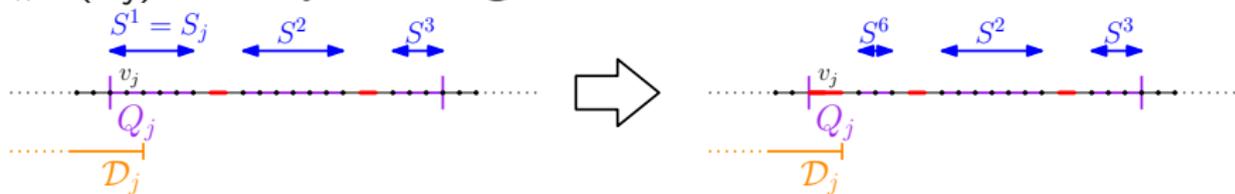
$\#S(Q_j)$ can **increase** by 1.



$\#S(Q_j)$ can **decrease**.



$\#S(Q_j)$ can stay **unchanged**.



Change in Number of Slices

Let $S_j \subseteq Q_j$ be the slice containing v_j . Consider Q_j .

In any case, $\#S(Q_j)$ can increase by **at most 1!**

Change in Number of Slices

Let $S_j \subseteq Q_j$ be the slice containing v_j . Consider Q_j .

In any case, $\#S(Q_j)$ can increase by **at most 1!**

If $\#S(Q_j)$ is decreased, we call it a **success**.

Change in Number of Slices

Let $S_j \subseteq Q_j$ be the slice containing v_j . Consider Q_j .

In any case, $\#S(Q_j)$ can increase by **at most 1!**

If $\#S(Q_j)$ is decreased, we call it a **success**.

Otherwise, we call it a **failure**.

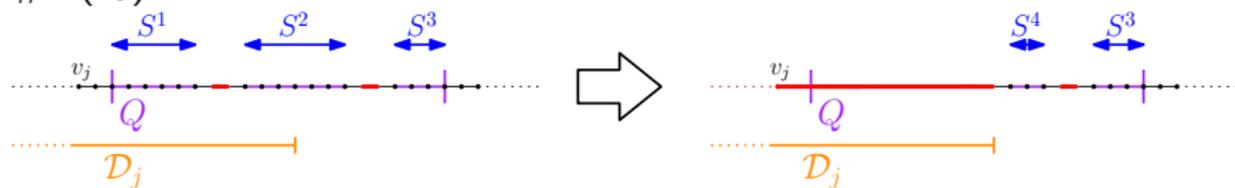
Change in Number of Slices

Let $S_j \subseteq Q_j$ be the slice containing v_j . Consider $Q \neq Q_j$.

Change in Number of Slices

Let $S_j \subseteq Q_j$ be the slice containing v_j . Consider $Q \neq Q_j$.

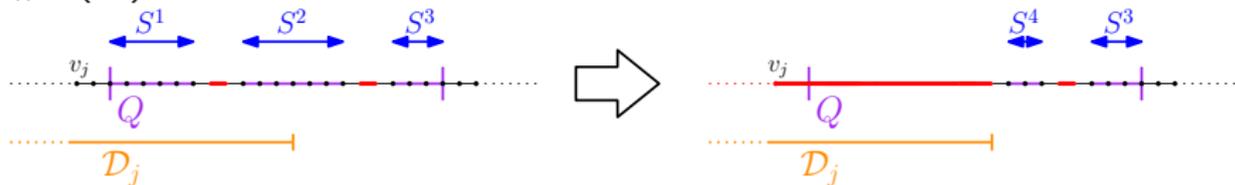
$\#S(Q)$ can **decrease**.



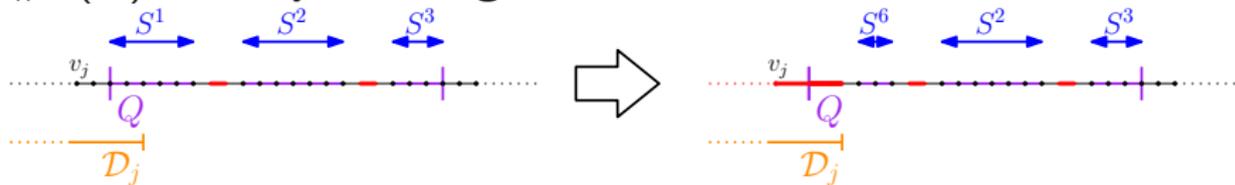
Change in Number of Slices

Let $S_j \subseteq Q_j$ be the slice containing v_j . Consider $Q \neq Q_j$.

$\#S(Q)$ can **decrease**.



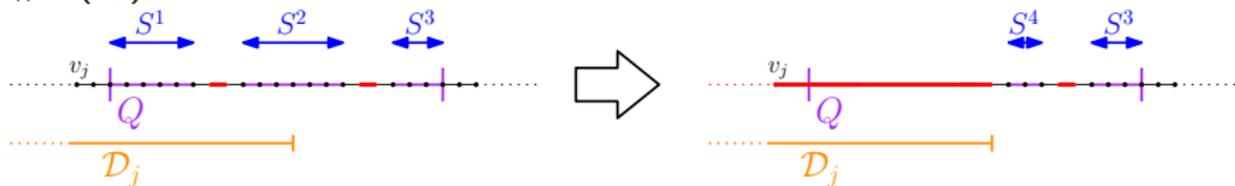
$\#S(Q)$ can stay **unchanged**.



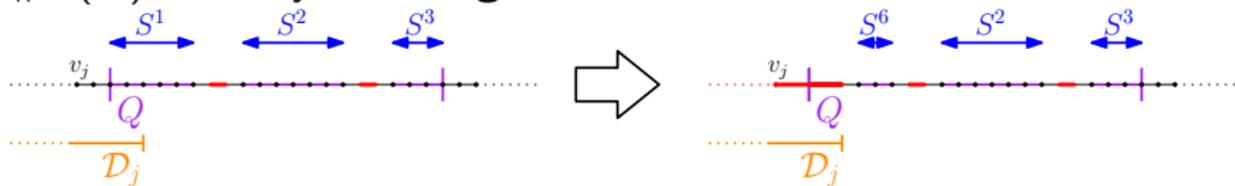
Change in Number of Slices

Let $S_j \subseteq Q_j$ be the slice containing v_j . Consider $Q \neq Q_j$.

$\#S(Q)$ can **decrease**.



$\#S(Q)$ can stay **unchanged**.



In any case, $\#S(Q)$ **cannot increase!**

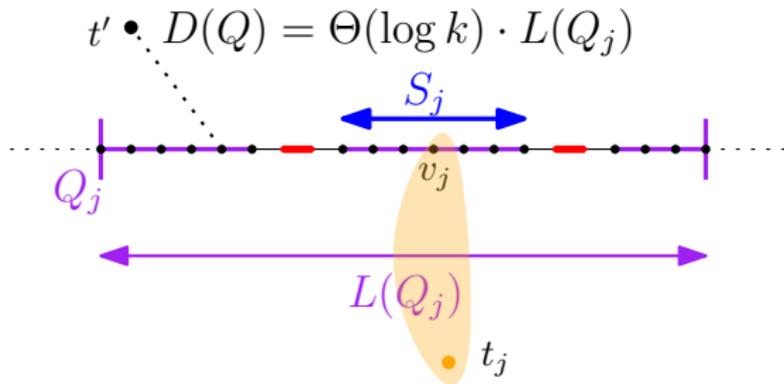
Lemma (Success probability)

Assuming at least one active vertex joins V_j ,

*the probability of **success** is at least $1 - p$.*

Lemma (Success probability)

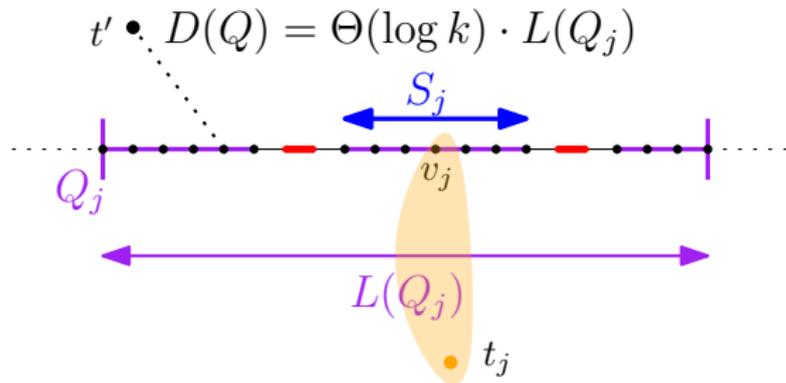
Assuming at least one active vertex joins V_j ,
the probability of **success** is at least $1 - p$.



Lemma (Success probability)

Assuming at least one active vertex joins V_j ,

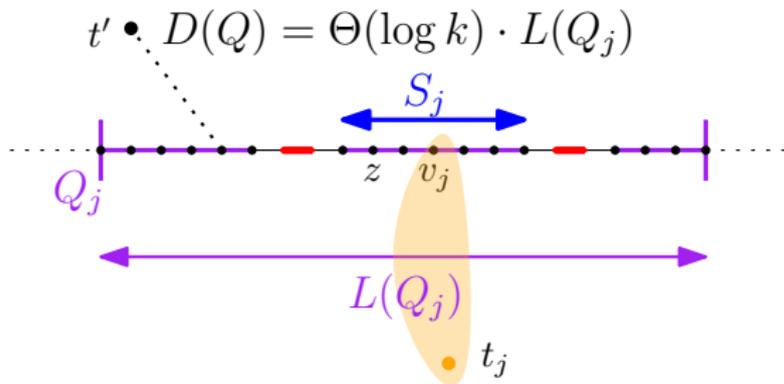
the probability of **success** is at least $1 - p$.



$$v_j \in V_j \Rightarrow R_j \geq d(v_j, t_j) / D(v_j).$$

Lemma (Success probability)

Assuming at least one active vertex joins V_j ,
the probability of **success** is at least $1 - p$.



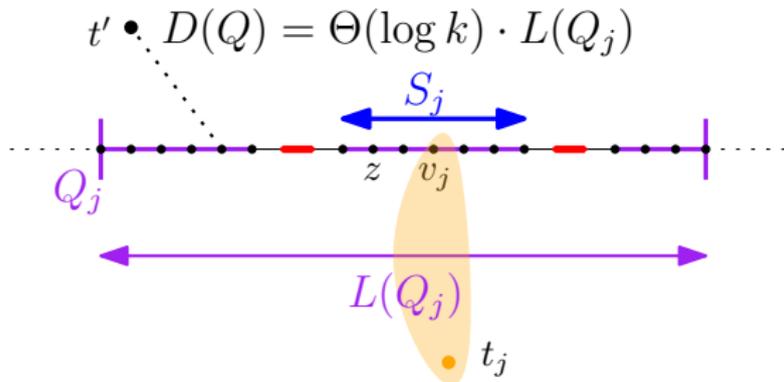
$$v_j \in V_j \Rightarrow R_j \geq d(v_j, t_j)/D(v_j).$$

For all $z \in S_j$,

Lemma (Success probability)

Assuming at least one active vertex joins V_j ,

the probability of **success** is at least $1 - p$.



$$v_j \in V_j \Rightarrow R_j \geq d(v_j, t_j) / D(v_j).$$

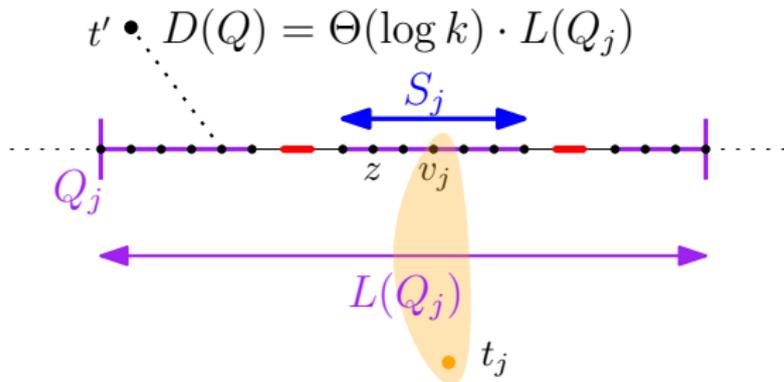
For all $z \in S_j$,

$$\frac{d(z, t_j)}{D(z)} \leq \frac{d(v_j, t_j) + L(Q_j)}{D(v_j) - L(Q_j)} \leq \frac{d(v_j, t_j)}{D(v_j)} \left(1 + \frac{O(1)}{\log k}\right)$$

Lemma (Success probability)

Assuming at least one active vertex joins V_j ,

the probability of **success** is at least $1 - p$.



$$v_j \in V_j \Rightarrow R_j \geq d(v_j, t_j) / D(v_j).$$

For all $z \in S_j$,

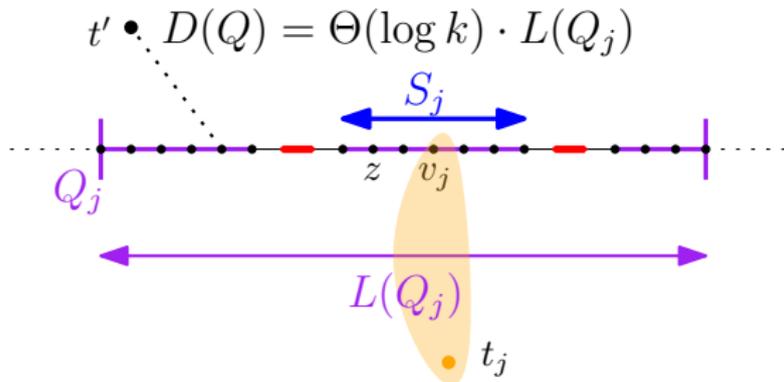
$$\frac{d(z, t_j)}{D(z)} \leq \frac{d(v_j, t_j) + L(Q_j)}{D(v_j) - L(Q_j)} \leq \frac{d(v_j, t_j)}{D(v_j)} \left(1 + \frac{O(1)}{\log k}\right)$$

Recall that $R_j = (1 + \delta)^{g_j}$, where $g_j \sim \text{Geo}(p)$.

Lemma (Success probability)

Assuming at least one active vertex joins V_j ,

the probability of **success** is at least $1 - p$.



$$v_j \in V_j \Rightarrow R_j \geq d(v_j, t_j) / D(v_j).$$

For all $z \in S_j$,

$$\frac{d(z, t_j)}{D(z)} \leq \frac{d(v_j, t_j) + L(Q_j)}{D(v_j) - L(Q_j)} \leq \frac{d(v_j, t_j)}{D(v_j)} \left(1 + \frac{O(1)}{\log k}\right)$$

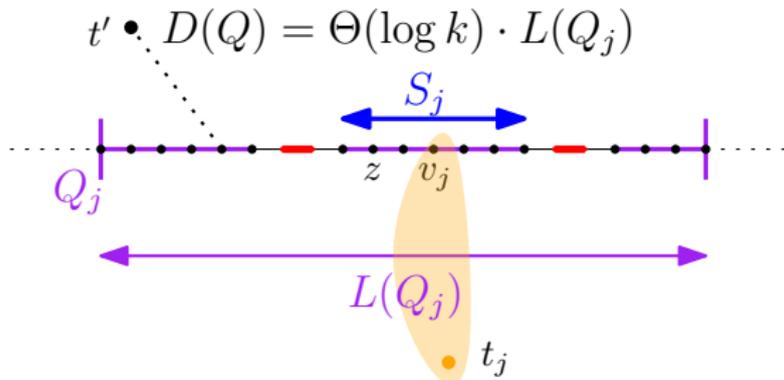
Recall that $R_j = (1 + \delta)^{g_j}$, where $g_j \sim \text{Geo}(p)$.

W.P. $1 - p$.

Lemma (Success probability)

Assuming at least one active vertex joins V_j ,

the probability of **success** is at least $1 - p$.



$$v_j \in V_j \Rightarrow R_j \geq d(v_j, t_j) / D(v_j).$$

For all $z \in S_j$,

$$\frac{d(z, t_j)}{D(z)} \leq \frac{d(v_j, t_j) + L(Q_j)}{D(v_j) - L(Q_j)} \leq \frac{d(v_j, t_j)}{D(v_j)} \left(1 + \frac{O(1)}{\log k}\right)$$

Recall that $R_j = (1 + \delta)^{g_j}$, where $g_j \sim \text{Geo}(p)$.

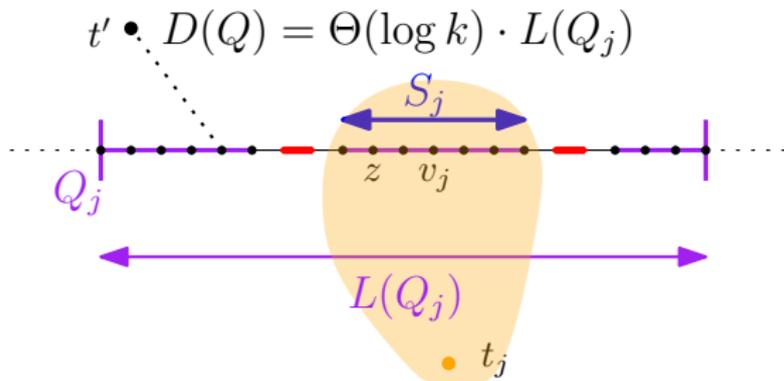
W.P. $1 - p$.

$$R_j \geq (1 + \delta) \frac{d(v_j, t_j)}{D(v_j)} \geq \frac{d(z, t_j)}{D(z)}$$

Lemma (Success probability)

Assuming at least one active vertex joins V_j ,

the probability of **success** is at least $1 - p$.



$$v_j \in V_j \Rightarrow R_j \geq d(v_j, t_j) / D(v_j).$$

For all $z \in S_j$,

$$\frac{d(z, t_j)}{D(z)} \leq \frac{d(v_j, t_j) + L(Q_j)}{D(v_j) - L(Q_j)} \leq \frac{d(v_j, t_j)}{D(v_j)} \left(1 + \frac{O(1)}{\log k}\right)$$

Recall that $R_j = (1 + \delta)^{g_j}$, where $g_j \sim \text{Geo}(p)$.

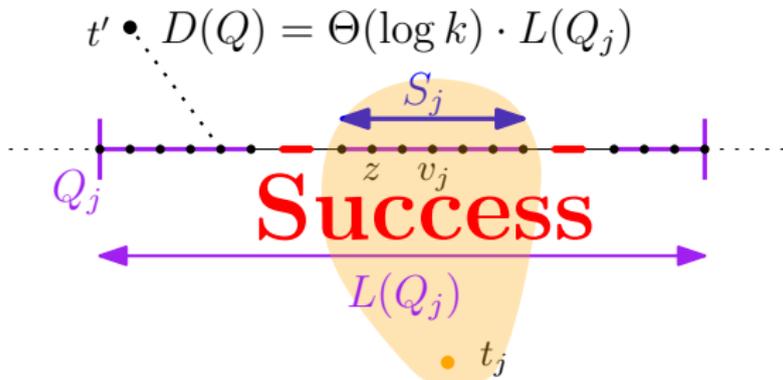
W.P. $1 - p$.

$$R_j \geq (1 + \delta) \frac{d(v_j, t_j)}{D(v_j)} \geq \frac{d(z, t_j)}{D(z)}$$

Lemma (Success probability)

Assuming at least one active vertex joins V_j ,

the probability of **success** is at least $1 - p$.



$$v_j \in V_j \Rightarrow R_j \geq d(v_j, t_j) / D(v_j).$$

For all $z \in S_j$,

$$\frac{d(z, t_j)}{D(z)} \leq \frac{d(v_j, t_j) + L(Q_j)}{D(v_j) - L(Q_j)} \leq \frac{d(v_j, t_j)}{D(v_j)} \left(1 + \frac{O(1)}{\log k}\right)$$

Recall that $R_j = (1 + \delta)^{g_j}$, where $g_j \sim \text{Geo}(p)$.

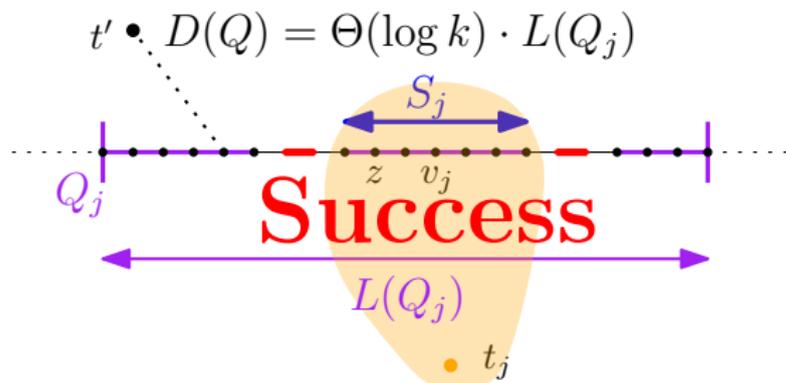
W.P. $1 - p$.

$$R_j \geq (1 + \delta) \frac{d(v_j, t_j)}{D(v_j)} \geq \frac{d(z, t_j)}{D(z)}$$

Lemma (Success probability)

Assuming at least one active vertex joins V_j ,

the probability of **success** is at least $1 - p$.



$$v_j \in V_j \Rightarrow R_j \geq d(v_j, t_j)/D(v_j).$$

Recall that $R_j = (1 + \delta)^{g_j}$, where $g_j \sim \text{Geo}(p)$.

For all $z \in S_j$,

W.P. $1 - p$.

$$R_j \geq (1 + \delta) \frac{d(v_j, t_j)}{D(v_j)} \geq \frac{d(z, t_j)}{D(z)}$$

In fact, the success probability is **either** 1 or $1 - p$.

Corollary (Expected Charge)

For all $Q \in \mathcal{Q}$, $\mathbb{E}[X_Q] = O(\mathbf{1})$.

Corollary (Expected Charge)

For all $Q \in \mathcal{Q}$, $\mathbb{E}[X_Q] = O(1)$.

Proof.

$$\mathbb{E}[X_Q] \leq 1 + p \cdot 2\mathbb{E}[X_Q] \quad \Rightarrow \quad \mathbb{E}[X_Q] \leq \frac{1}{1-2p} = O(1). \quad \square$$

Corollary (Expected Charge)

For all $Q \in \mathcal{Q}$, $\mathbb{E}[X_Q] = O(1)$.

Proof.

$$\mathbb{E}[X_Q] \leq 1 + p \cdot 2\mathbb{E}[X_Q] \quad \Rightarrow \quad \mathbb{E}[X_Q] \leq \frac{1}{1-2p} = O(1). \quad \square$$

Corollary (High Probability Charge Bound)

With **high probability**, for all $Q \in \mathcal{Q}$, $X_Q = O(\log k)$.

Corollary (Expected Charge)

For all $Q \in \mathcal{Q}$, $\mathbb{E}[X_Q] = O(1)$.

Proof.

$$\mathbb{E}[X_Q] \leq 1 + p \cdot 2\mathbb{E}[X_Q] \quad \Rightarrow \quad \mathbb{E}[X_Q] \leq \frac{1}{1-2p} = O(1). \quad \square$$

Corollary (High Probability Charge Bound)

With **high probability**, for all $Q \in \mathcal{Q}$, $X_Q = O(\log k)$.

Proof.

Chernoff. □

Definition (Charge Function)

$$f(x_1, x_2, \dots, x_\varphi) = \sum_i x_i \cdot L(Q^i) \quad ,$$

here $\varphi = |Q|$.

Definition (Charge Function)

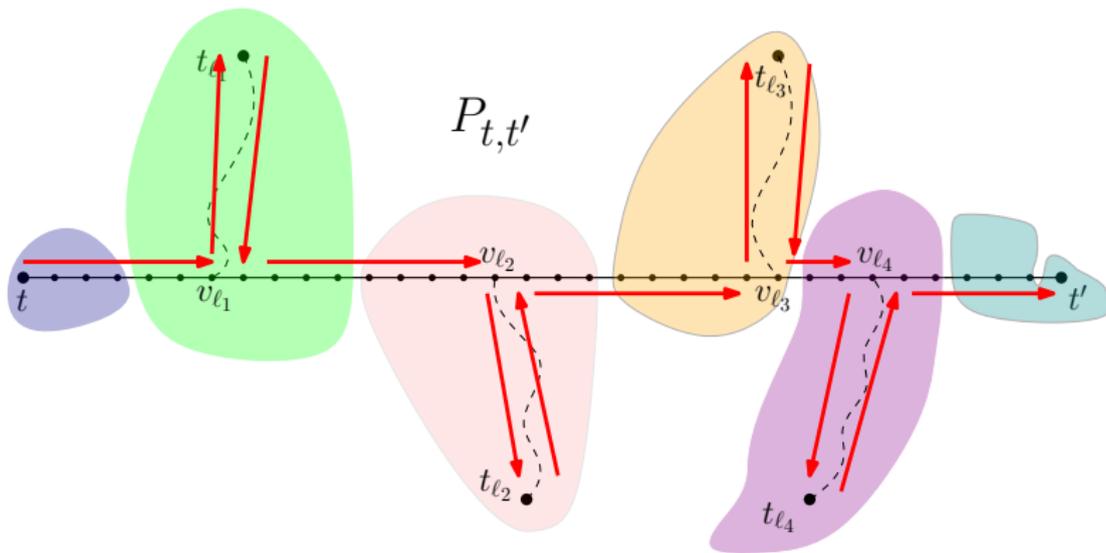
$$f(x_1, x_2, \dots, x_\varphi) = \sum_i x_i \cdot L(Q^i) \quad , \quad \text{here } \varphi = |Q|.$$

f is linear and monotonically increasing.

Definition (Charge Function)

$$f(x_1, x_2, \dots, x_\varphi) = \sum_i x_i \cdot L(Q^i) ,$$

here $\varphi = |Q|$.



$$d_M(t, t') \leq d_G(t, t') + 2 \sum_j d_G(t_j, v_j)$$

Definition (Charge Function)

$$f(x_1, x_2, \dots, x_\varphi) = \sum_i x_i \cdot L(Q^i) \quad ,$$

here $\varphi = |Q|$.

$$\begin{aligned} d_M(t, t') &\leq d_G(t, t') + 2 \sum_j d_G(t_j, v_j) \\ &= d_G(t, t') + O(1) \cdot \sum_j D(v_j) \end{aligned}$$

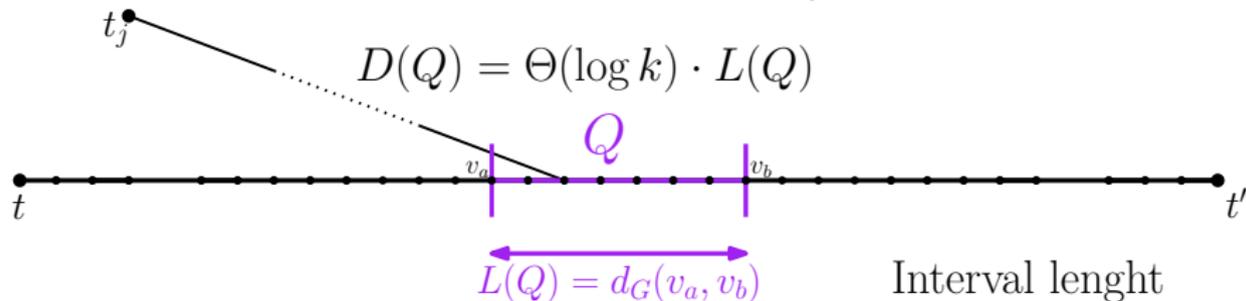
Recall $R_j = O(1)$, thus $d_G(t_j, v_j) \leq R_j \cdot D(v_j) = O(D(v_j))$.

Definition (Charge Function)

$$f(x_1, x_2, \dots, x_\varphi) = \sum_i x_i \cdot L(Q^i) \quad ,$$

here $\varphi = |Q|$.

$$\begin{aligned} d_M(t, t') &\leq d_G(t, t') + 2 \sum_j d_G(t_j, v_j) \\ &= d_G(t, t') + O(1) \cdot \sum_j D(v_j) \\ &= d_G(t, t') + O(\log k) \cdot \sum_j L(Q_j) \end{aligned}$$



Definition (Charge Function)

$$f(x_1, x_2, \dots, x_\varphi) = \sum_i x_i \cdot L(Q^i) \quad ,$$

here $\varphi = |Q|$.

$$\begin{aligned} d_M(t, t') &\leq d_G(t, t') + 2 \sum_j d_G(t_j, v_j) \\ &= d_G(t, t') + O(1) \cdot \sum_j D(v_j) \\ &= d_G(t, t') + O(\log k) \cdot \sum_j L(Q_j) \\ &= d_G(t, t') + O(\log k) \cdot \sum_{Q \in \mathcal{Q}} X_Q \cdot L(Q) \end{aligned}$$

Definition (Charge Function)

$$f(x_1, x_2, \dots, x_\varphi) = \sum_i x_i \cdot L(Q^i) \quad ,$$

here $\varphi = |Q|$.

$$\begin{aligned} d_M(t, t') &\leq d_G(t, t') + 2 \sum_j d_G(t_j, v_j) \\ &= d_G(t, t') + O(1) \cdot \sum_j D(v_j) \\ &= d_G(t, t') + O(\log k) \cdot \sum_j L(Q_j) \\ &= d_G(t, t') + O(\log k) \cdot \sum_{Q \in Q} X_Q \cdot L(Q) \\ &= d_G(t, t') + O(\log k) \cdot f(X_{Q^1}, \dots, X_{Q^\varphi}) \end{aligned}$$

Definition (Charge Function)

$$f(x_1, x_2, \dots, x_\varphi) = \sum_i x_i \cdot L(Q^i) \quad ,$$

here $\varphi = |Q|$.

$$d_M(t, t') = d_G(t, t') + O(\log k) \cdot f(X_{Q^1}, \dots, X_{Q^\varphi})$$

Definition (Charge Function)

$$f(x_1, x_2, \dots, x_\varphi) = \sum_i x_i \cdot L(Q^i) \quad , \quad \text{here } \varphi = |\mathcal{Q}|.$$

$$d_M(t, t') = d_G(t, t') + O(\log k) \cdot f(X_{Q^1}, \dots, X_{Q^\varphi})$$

$$\mathbb{E}[f(X_{Q^1}, \dots, X_{Q^\varphi})] = \sum_{Q \in \mathcal{Q}} \mathbb{E}[X_Q] \cdot L(Q)$$

Definition (Charge Function)

$$f(x_1, x_2, \dots, x_\varphi) = \sum_i x_i \cdot L(Q^i) \quad , \quad \text{here } \varphi = |Q|.$$

$$d_M(t, t') = d_G(t, t') + O(\log k) \cdot f(X_{Q^1}, \dots, X_{Q^\varphi})$$

$$\begin{aligned} \mathbb{E}[f(X_{Q^1}, \dots, X_{Q^\varphi})] &= \sum_{Q \in \mathcal{Q}} \mathbb{E}[X_Q] \cdot L(Q) \\ &= O(1) \cdot \sum_{Q \in \mathcal{Q}} L(Q) = O(1) \cdot d_G(t, t') \end{aligned}$$

Definition (Charge Function)

$$f(x_1, x_2, \dots, x_\varphi) = \sum_i x_i \cdot L(Q^i) \quad , \quad \text{here } \varphi = |Q|.$$

$$d_M(t, t') = d_G(t, t') + O(\log k) \cdot f(X_{Q^1}, \dots, X_{Q^\varphi})$$

$$\begin{aligned} \mathbb{E}[f(X_{Q^1}, \dots, X_{Q^\varphi})] &= \sum_{Q \in \mathcal{Q}} \mathbb{E}[X_Q] \cdot L(Q) \\ &= O(1) \cdot \sum_{Q \in \mathcal{Q}} L(Q) = O(1) \cdot d_G(t, t') \end{aligned}$$

Theorem

*The **expected distortion** of the minor M returned by the *Noisy Voronoi* algorithm is $O(\log k)$.*

Definition (Charge Function)

$$f(x_1, x_2, \dots, x_\varphi) = \sum_i x_i \cdot L(Q^i) \quad , \quad \text{here } \varphi = |Q|.$$

$$d_M(t, t') = d_G(t, t') + O(\log k) \cdot f(X_{Q^1}, \dots, X_{Q^\varphi})$$

Moreover, with high probability

Definition (Charge Function)

$$f(x_1, x_2, \dots, x_\varphi) = \sum_i x_i \cdot L(Q^i) \quad , \quad \text{here } \varphi = |Q|.$$

$$d_M(t, t') = d_G(t, t') + O(\log k) \cdot f(X_{Q_1}, \dots, X_{Q_\varphi})$$

Moreover, with high probability

$$f(X_{Q_1}, \dots, X_{Q_\varphi}) = \sum_{Q \in Q} X_Q \cdot L(Q)$$

Definition (Charge Function)

$$f(x_1, x_2, \dots, x_\varphi) = \sum_i x_i \cdot L(Q^i) \quad , \quad \text{here } \varphi = |Q|.$$

$$d_M(t, t') = d_G(t, t') + O(\log k) \cdot f(X_{Q_1}, \dots, X_{Q_\varphi})$$

Moreover, with high probability

$$\begin{aligned} f(X_{Q_1}, \dots, X_{Q_\varphi}) &= \sum_{Q \in Q} X_Q \cdot L(Q) \\ &= O(\log k) \cdot \sum_{Q \in Q} L(Q) = O(\log k) \cdot d_G(t, t') \end{aligned}$$

Definition (Charge Function)

$$f(x_1, x_2, \dots, x_\varphi) = \sum_i x_i \cdot L(Q^i) \quad , \quad \text{here } \varphi = |Q|.$$

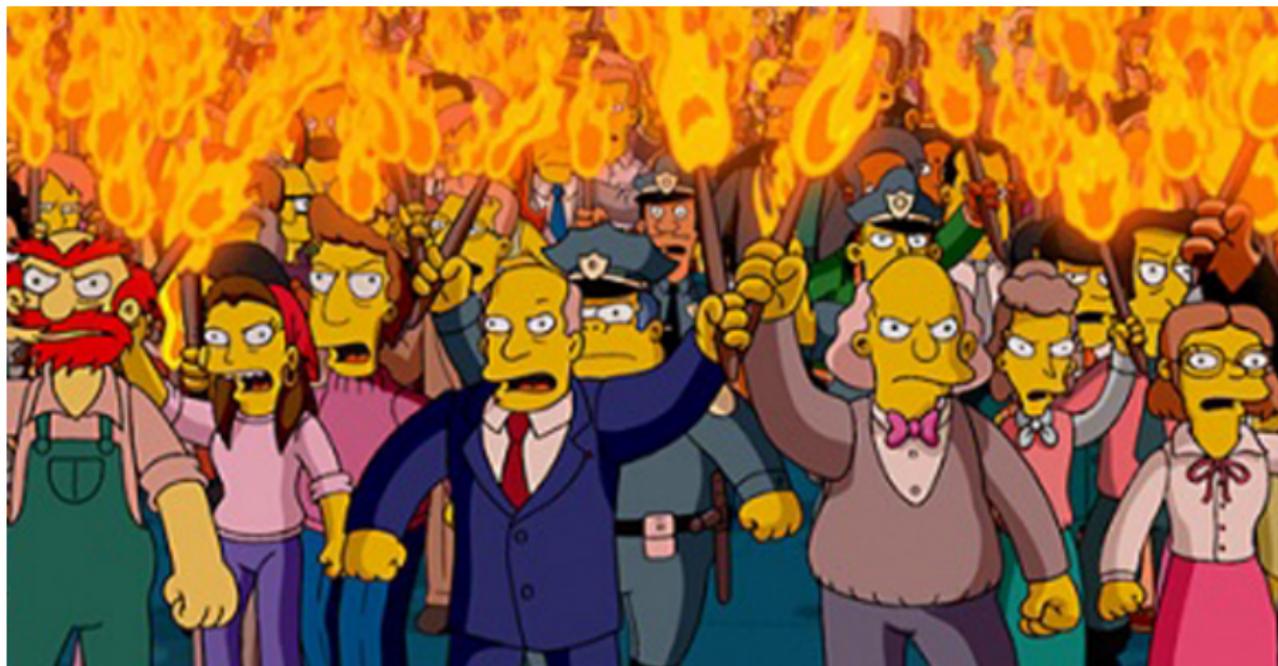
$$d_M(t, t') = d_G(t, t') + O(\log k) \cdot f(X_{Q_1}, \dots, X_{Q_\varphi})$$

Moreover, with high probability

$$\begin{aligned} f(X_{Q_1}, \dots, X_{Q_\varphi}) &= \sum_{Q \in Q} X_Q \cdot L(Q) \\ &= O(\log k) \cdot \sum_{Q \in Q} L(Q) = O(\log k) \cdot d_G(t, t') \end{aligned}$$

Theorem

*With **high probability**, the Noisy Voronoi algorithm returns a minor M with distortion $O(\log^2 k)$.*



But you promised distortion $O(\log k)$!

Analyze $f(X_{Q^1}, \dots, X_{Q^\varphi}) = \sum_{Q \in \mathcal{Q}} X_Q \cdot L(Q)$ **better**.

Analyze $f(X_{Q^1}, \dots, X_{Q^\varphi}) = \sum_{Q \in \mathcal{Q}} X_Q \cdot L(Q)$ **better**.

But $X_{Q^1}, \dots, X_{Q^\varphi}$ are **dependent**.

Analyze $f(X_{Q^1}, \dots, X_{Q^\varphi}) = \sum_{Q \in \mathcal{Q}} X_Q \cdot L(Q)$ **better**.

But $X_{Q^1}, \dots, X_{Q^\varphi}$ are **dependent**.

What can we do?



Analyze $f(X_{Q^1}, \dots, X_{Q^\varphi}) = \sum_{Q \in \mathcal{Q}} X_Q \cdot L(Q)$ **better**.

But $X_{Q^1}, \dots, X_{Q^\varphi}$ are **dependent**.

What can we do?



They maybe dependent, but in a “**positive**” way!

Idea

We will introduce new **series** of **independent random variables** and show that they **dominate** $X_{Q^1}, \dots, X_{Q^\varphi}$.

Idea

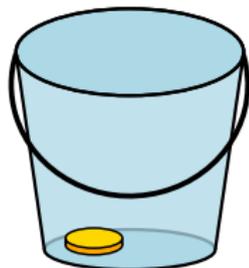
We will introduce new **series** of **independent random variables** and show that they **dominate** $X_{Q^1}, \dots, X_{Q^\varphi}$.



Active



Inactive



Idea

We will introduce new **series** of **independent random variables** and show that they **dominate** $X_{Q^1}, \dots, X_{Q^\varphi}$.



Active



Inactive



Idea

We will introduce new **series** of **independent random variables** and show that they **dominate** $X_{Q^1}, \dots, X_{Q^\varphi}$.



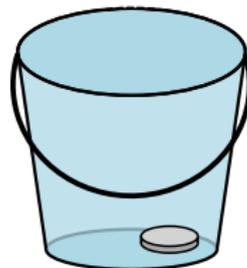
Active



Inactive



W.P. $1 - p$



W.P. p

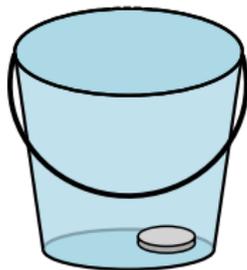


 Active

 Inactive



W.P. $1 - p$



W.P. p



Denote by $A(B)$ the number of **active** Coins in the bucket B .
Denote by $IN(B)$ the number of **inactive** Coins in the bucket B .

Coupling

$$\begin{aligned} \#S(Q^1) &= 1 \\ X_{Q^1} &= 0 \end{aligned}$$

Q^1

.....

$$\begin{aligned} \#S(Q^{i-1}) &= 1 \\ X_{Q^{i-1}} &= 0 \end{aligned}$$

Q^{i-1}

$$\begin{aligned} \#S(Q^i) &= 1 \\ X_{Q^i} &= 0 \end{aligned}$$

Q^i

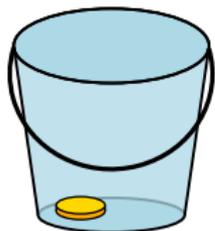
$$\begin{aligned} \#S(Q^{i+1}) &= 1 \\ X_{Q^{i+1}} &= 0 \end{aligned}$$

Q^{i+1}

.....

$$\begin{aligned} \#S(Q^\varphi) &= 1 \\ X_{Q^\varphi} &= 0 \end{aligned}$$

Q^φ



B_1

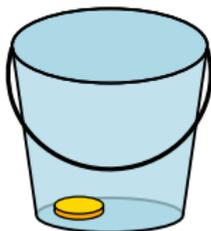
.....



B_{i-1}



B_i



B_{i+1}

.....



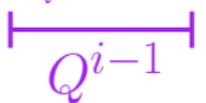
B_φ

Coupling

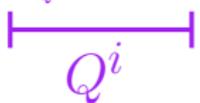
$$\begin{array}{l} \#S(Q^1) = 1 \\ X_{Q^1} = 0 \end{array}$$



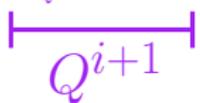
$$\begin{array}{l} \#S(Q^{i-1}) = 1 \\ X_{Q^{i-1}} = 0 \end{array}$$



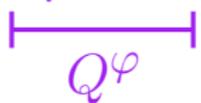
$$\begin{array}{l} \#S(Q^i) = 1 \\ X_{Q^i} = 0 \end{array}$$



$$\begin{array}{l} \#S(Q^{i+1}) = 1 \\ X_{Q^{i+1}} = 0 \end{array}$$



$$\begin{array}{l} \#S(Q^\varphi) = 1 \\ X_{Q^\varphi} = 0 \end{array}$$



B_1



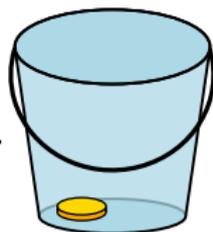
B_{i-1}



B_i



B_{i+1}

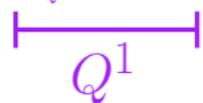


B_φ

B_1, \dots, B_φ are independent buckets.

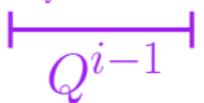
Coupling

$$\begin{array}{l} \#S(Q^1) = 1 \\ X_{Q^1} = 0 \end{array}$$



.....

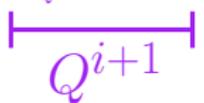
$$\begin{array}{l} \#S(Q^{i-1}) = 1 \\ X_{Q^{i-1}} = 0 \end{array}$$



$$\begin{array}{l} \#S(Q^i) = 1 \\ X_{Q^i} = 0 \end{array}$$

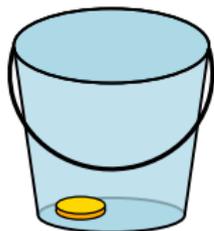
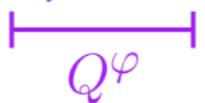


$$\begin{array}{l} \#S(Q^{i+1}) = 1 \\ X_{Q^{i+1}} = 0 \end{array}$$



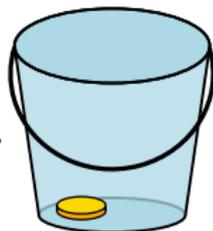
.....

$$\begin{array}{l} \#S(Q^\varphi) = 1 \\ X_{Q^\varphi} = 0 \end{array}$$

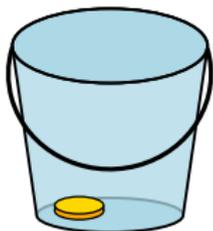


B_1

.....



B_{i-1}

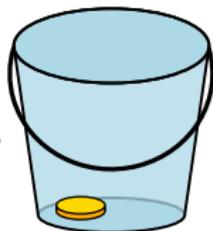


B_i



B_{i+1}

.....



B_φ

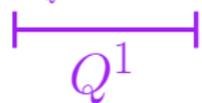
B_1, \dots, B_φ are independent buckets.

We execute Noisy Voronoi algorithm

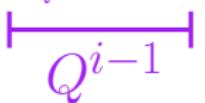
and use it in order to determine $IN(B_1), \dots, IN(B_\varphi)$.

Coupling

$$\begin{array}{l} \#S(Q^1) = 1 \\ X_{Q^1} = 0 \end{array}$$



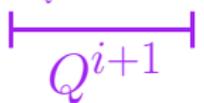
$$\begin{array}{l} \#S(Q^{i-1}) = 1 \\ X_{Q^{i-1}} = 0 \end{array}$$



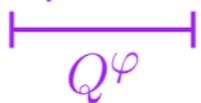
$$\begin{array}{l} \#S(Q^i) = 1 \\ X_{Q^i} = 0 \end{array}$$



$$\begin{array}{l} \#S(Q^{i+1}) = 1 \\ X_{Q^{i+1}} = 0 \end{array}$$



$$\begin{array}{l} \#S(Q^\varphi) = 1 \\ X_{Q^\varphi} = 0 \end{array}$$



B_1



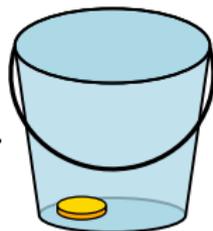
B_{i-1}



B_i



B_{i+1}



B_φ

Maintain, for all i ,

$$X_{Q^i} \leq IN(B_i) \quad \& \quad \#S(Q^i) \leq A(B_i)$$

Coupling

Maintain, for all i , $X_{Q^i} \leq IN(\mathcal{B}_i)$ & $\#S(Q^i) \leq A(\mathcal{B}_i)$

Coupling

Maintain, for all i , $X_{Q^i} \leq IN(\mathcal{B}_i)$ & $\#S(Q^i) \leq A(\mathcal{B}_i)$

Suppose t_j grows cluster V_j .

Coupling

Maintain, for all i , $X_{Q^i} \leq IN(\mathcal{B}_i)$ & $\#S(Q^i) \leq A(\mathcal{B}_i)$

Suppose t_j grows cluster V_j .

- If **no** active vertex **joins** V_j . **Nothing change.**

Coupling

Maintain, for all i , $X_{Q^i} \leq IN(\mathcal{B}_i)$ & $\#S(Q^i) \leq A(\mathcal{B}_i)$

Suppose t_j grows cluster V_j .

- If **no** active vertex **joins** V_j . **Nothing change.**

Else, $v_j \in S_j \subseteq Q_j$ is the first vertex to **join** V_j .

$\mathcal{B}_{(j)}$ is the corresponding bucket to Q_j .

Coupling

Maintain, for all i , $X_{Q^i} \leq IN(\mathcal{B}_i)$ & $\#S(Q^i) \leq A(\mathcal{B}_i)$

Suppose t_j grows cluster V_j .

- If **no** active vertex **joins** V_j . **Nothing change**.

Else, $v_j \in S_j \subseteq Q_j$ is the first vertex to **join** V_j .

$\mathcal{B}_{(j)}$ is the corresponding bucket to Q_j .

Let p' be the **probability** that **not all** of S_j **joins** V_j . Recall $p' \leq p$.

Coupling

Maintain, for all i , $X_{Q^i} \leq IN(\mathcal{B}_i)$ & $\#S(Q^i) \leq A(\mathcal{B}_i)$

Suppose t_j grows cluster V_j .

- If **no** active vertex **joins** V_j . **Nothing change**.

Else, $v_j \in S_j \subseteq Q_j$ is the first vertex to **join** V_j .

$\mathcal{B}_{(j)}$ is the corresponding bucket to Q_j .

Let p' be the **probability** that **not all** of S_j **joins** V_j . Recall $p' \leq p$.

- If not all of S_j joins V_j : **Fail in both processes**.
Add two active coins.

Coupling

Maintain, for all i , $X_{Q^i} \leq IN(\mathcal{B}_i)$ & $\#S(Q^i) \leq A(\mathcal{B}_i)$

Suppose t_j grows cluster V_j .

- If **no** active vertex **joins** V_j . **Nothing change**.

Else, $v_j \in S_j \subseteq Q_j$ is the first vertex to **join** V_j .

$\mathcal{B}_{(j)}$ is the corresponding bucket to Q_j .

Let p' be the **probability** that **not all** of S_j **joins** V_j . Recall $p' \leq p$.

- If not all of S_j joins V_j : **Fail in both processes**.

Add two active coins.

- ▶ $A(\mathcal{B}_{(j)}) \leftarrow A(\mathcal{B}_{(j)}) + 1$, $IN(\mathcal{B}_{(j)}) \leftarrow IN(\mathcal{B}_{(j)}) + 1$.
For $i \neq (j)$, $A(\mathcal{B}_i)$, $IN(\mathcal{B}_i)$ **unchanged**.

Coupling

Maintain, for all i , $X_{Q_i} \leq IN(\mathcal{B}_i)$ & $\#S(Q_i) \leq A(\mathcal{B}_i)$

Suppose t_j grows cluster V_j .

- If **no** active vertex **joins** V_j . **Nothing change**.

Else, $v_j \in S_j \subseteq Q_j$ is the first vertex to **join** V_j .

$\mathcal{B}_{(j)}$ is the corresponding bucket to Q_j .

Let p' be the **probability** that **not all** of S_j **joins** V_j . Recall $p' \leq p$.

- If not all of S_j joins V_j : **Fail in both processes**.

Add two active coins.

- ▶ $A(\mathcal{B}_{(j)}) \leftarrow A(\mathcal{B}_{(j)}) + 1$, $IN(\mathcal{B}_{(j)}) \leftarrow IN(\mathcal{B}_{(j)}) + 1$.
For $i \neq (j)$, $A(\mathcal{B}_i)$, $IN(\mathcal{B}_i)$ **unchanged**.
- ▶ $\#S(Q_j) \leq \#S(Q_j) + 1$, $X_{Q_j} \leq X_{Q_j} + 1$.
For $i \neq j$, $\#S(Q_i)$, X_{Q_i} might **only decrease**.

Coupling

Maintain, for all i , $X_{Q_i} \leq IN(\mathcal{B}_i)$ & $\#S(Q_i) \leq A(\mathcal{B}_i)$

Suppose t_j grows cluster V_j .

- If **no** active vertex **joins** V_j . **Nothing change**.

Else, $v_j \in S_j \subseteq Q_j$ is the first vertex to **join** V_j .

$\mathcal{B}_{(j)}$ is the corresponding bucket to Q_j .

Let p' be the **probability** that **not all** of S_j **joins** V_j . Recall $p' \leq p$.

Coupling

Maintain, for all i , $X_{Q_i} \leq IN(\mathcal{B}_i)$ & $\#S(Q_i) \leq A(\mathcal{B}_i)$

Suppose t_j grows cluster V_j .

- If **no** active vertex **joins** V_j . **Nothing change**.

Else, $v_j \in S_j \subseteq Q_j$ is the first vertex to **join** V_j .

$\mathcal{B}_{(j)}$ is the corresponding bucket to Q_j .

Let p' be the **probability** that **not all** of S_j **joins** V_j . Recall $p' \leq p$.

- If all of S_j joins V_j : **Success in alg.**

With probability $\frac{p-p'}{1-p'}$, add two active coins (**fail in buckets**).

Coupling

Maintain, for all i , $X_{Q_i} \leq IN(\mathcal{B}_i)$ & $\#S(Q_i) \leq A(\mathcal{B}_i)$

Suppose t_j grows cluster V_j .

- If **no** active vertex **joins** V_j . **Nothing change**.

Else, $v_j \in S_j \subseteq Q_j$ is the first vertex to **join** V_j .

$\mathcal{B}_{(j)}$ is the corresponding bucket to Q_j .

Let p' be the **probability** that **not all** of S_j **joins** V_j . Recall $p' \leq p$.

- If all of S_j joins V_j : **Success in alg.**

With probability $\frac{p-p'}{1-p'}$, add two active coins (**fail in buckets**).

- ▶ $A(\mathcal{B}_{(j)}) \geq A(\mathcal{B}_{(j)}) - 1$, $IN(\mathcal{B}_{(j)}) \leftarrow IN(\mathcal{B}_{(j)}) + 1$.
For $i \neq (j)$, $A(\mathcal{B}_i)$, $IN(\mathcal{B}_i)$ **unchanged**.

Coupling

Maintain, for all i , $X_{Q_i} \leq IN(\mathcal{B}_i)$ & $\#S(Q_i) \leq A(\mathcal{B}_i)$

Suppose t_j grows cluster V_j .

- If **no** active vertex **joins** V_j . **Nothing change**.

Else, $v_j \in S_j \subseteq Q_j$ is the first vertex to **join** V_j .

$\mathcal{B}_{(j)}$ is the corresponding bucket to Q_j .

Let p' be the **probability** that **not all** of S_j **joins** V_j . Recall $p' \leq p$.

- If all of S_j joins V_j : **Success in alg.**

With probability $\frac{p-p'}{1-p'}$, add two active coins (**fail in buckets**).

- ▶ $A(\mathcal{B}_{(j)}) \geq A(\mathcal{B}_{(j)}) - 1$, $IN(\mathcal{B}_{(j)}) \leftarrow IN(\mathcal{B}_{(j)}) + 1$.

For $i \neq (j)$, $A(\mathcal{B}_i)$, $IN(\mathcal{B}_i)$ **unchanged**.

- ▶ $\#S(Q_j) \leq \#S(Q_j) - 1$, $X_{Q_j} \leq X_{Q_j} + 1$.

For $i \neq j$, $\#S(Q_i)$, X_{Q_i} might **only decrease**.

Coupling

Maintain, for all i , $X_{Q_i} \leq IN(\mathcal{B}_i)$ & $\#S(Q_i) \leq A(\mathcal{B}_i)$

Suppose t_j grows cluster V_j .

- If **no** active vertex **joins** V_j . **Nothing change**.

Else, $v_j \in S_j \subseteq Q_j$ is the first vertex to **join** V_j .

$\mathcal{B}_{(j)}$ is the corresponding bucket to Q_j .

Let p' be the **probability** that **not all** of S_j **joins** V_j . Recall $p' \leq p$.

- If all of S_j joins V_j : **Success in alg.**

With probability $\frac{p-p'}{1-p'}$, add two active coins (**fail in buckets**).

- ▶ $A(\mathcal{B}_{(j)}) \geq A(\mathcal{B}_{(j)}) - 1$, $IN(\mathcal{B}_{(j)}) \leftarrow IN(\mathcal{B}_{(j)}) + 1$.

For $i \neq (j)$, $A(\mathcal{B}_i)$, $IN(\mathcal{B}_i)$ **unchanged**.

- ▶ $\#S(Q_j) \leq \#S(Q_j) - 1$, $X_{Q_j} \leq X_{Q_j} + 1$.

For $i \neq j$, $\#S(Q_i)$, X_{Q_i} might **only decrease**.

The probability of failure in the bucket is: $p' + (1 - p') \cdot \frac{p-p'}{1-p'} = p$

Coupling

Maintain, for all i , $X_{Q_i} \leq IN(\mathcal{B}_i)$ & $\#S(Q_i) \leq A(\mathcal{B}_i)$

Suppose t_j grows cluster V_j .

- If **no** active vertex **joins** V_j . **Nothing change**.

Else, $v_j \in S_j \subseteq Q_j$ is the first vertex to **join** V_j .

$\mathcal{B}_{(j)}$ is the corresponding bucket to Q_j .

Let p' be the **probability** that **not all** of S_j **joins** V_j . Recall $p' \leq p$.

- If all of S_j joins V_j : **Success in alg.**

With probability $\frac{p-p'}{1-p'}$, add two active coins (**fail in buckets**).

- ▶ $A(\mathcal{B}_{(j)}) \geq A(\mathcal{B}_{(j)}) - 1$, $IN(\mathcal{B}_{(j)}) \leftarrow IN(\mathcal{B}_{(j)}) + 1$.

For $i \neq (j)$, $A(\mathcal{B}_i)$, $IN(\mathcal{B}_i)$ **unchanged**.

- ▶ $\#S(Q_j) \leq \#S(Q_j) - 1$, $X_{Q_j} \leq X_{Q_j} + 1$.

For $i \neq j$, $\#S(Q_i)$, X_{Q_i} might **only decrease**.

The probability of failure in the bucket is: $p' + (1 - p') \cdot \frac{p-p'}{1-p'} = p$

The **marginal distribution** on the buckets is correct!

While the processes remain coupled, we **maintained** for all i ,

$$X_{Q^i} \leq IN(\mathcal{B}_i) \quad \& \quad \#S(Q^i) \leq A(\mathcal{B}_i)$$

While the processes remain coupled, we **maintained** for all i ,

$$X_{Q^i} \leq IN(\mathcal{B}_i) \quad \& \quad \#S(Q^i) \leq A(\mathcal{B}_i)$$

At end, if active coins remain, just **flip** them **regularly**.

While the processes remain coupled, we **maintained** for all i ,

$$X_{Q^i} \leq IN(\mathcal{B}_i) \quad \& \quad \#S(Q^i) \leq A(\mathcal{B}_i)$$

At end, if active coins remain, just **flip** them **regularly**.

$IN(\mathcal{B})$ can **only grow!**

While the processes remain coupled, we **maintained** for all i ,

$$X_{Q^i} \leq IN(\mathcal{B}_i) \quad \& \quad \#S(Q^i) \leq A(\mathcal{B}_i)$$

At end, if active coins remain, just **flip** them **regularly**.

$IN(\mathcal{B})$ can **only grow!**

Thus, $(X_{Q^1}, \dots, X_{Q^\varphi}) \leq (IN(\mathcal{B}_1), \dots, IN(\mathcal{B}_\varphi))$ **coordinatewise**

While the processes remain coupled, we **maintained** for all i ,

$$X_{Q^i} \leq IN(\mathcal{B}_i) \quad \& \quad \#S(Q^i) \leq A(\mathcal{B}_i)$$

At end, if active coins remain, just **flip** them **regularly**.

$IN(\mathcal{B})$ can **only grow!**

Thus, $(X_{Q^1}, \dots, X_{Q^\varphi}) \leq (IN(\mathcal{B}_1), \dots, IN(\mathcal{B}_\varphi))$ **coordinatewise**

Corollary (The buckets **dominate** the detour charges)

For all $\alpha \geq 0$,

$$\Pr [f(X_{Q^1}, \dots, X_{Q^\varphi}) \geq \alpha] \leq \Pr [f(IN(\mathcal{B}_1), \dots, IN(\mathcal{B}_\varphi)) \geq \alpha]$$

Lemma (**Exponential Distribution** Dominates Bucket)

For all $\alpha \geq 0$,

$$\Pr [IN(\mathcal{B}) \geq \alpha] \leq \Pr [Exp(10) + 1 \geq \alpha]$$

Lemma (**Exponential Distribution** Dominates Bucket)

For all $\alpha \geq 0$,

$$\Pr [IN(\mathcal{B}) \geq \alpha] \leq \Pr [Exp(10) + 1 \geq \alpha]$$

Proof.

Meh. Too Technical. □

Lemma (**Exponential Distribution** Dominates Bucket)

For all $\alpha \geq 0$,

$$\Pr [IN(\mathcal{B}) \geq \alpha] \leq \Pr [Exp(10) + 1 \geq \alpha]$$

Corollary (**Series** of Exponential Dominates the Buckets)

For all $\alpha \geq 0$,

$$\begin{aligned} \Pr [f (IN(\mathcal{B}_1), \dots, IN(\mathcal{B}_\varphi)) \geq \alpha] \\ \leq \Pr [f (Exp(10) + 1, \dots, Exp(10) + 1) \geq \alpha] \end{aligned}$$

Lemma (**Exponential Distribution** Dominates Bucket)

For all $\alpha \geq 0$,

$$\Pr [IN(\mathcal{B}) \geq \alpha] \leq \Pr [Exp(10) + 1 \geq \alpha]$$

Corollary (**Series** of Exponential Dominates the Buckets)

$$\begin{aligned} \text{For all } \alpha \geq 0, \quad \Pr [f (IN(\mathcal{B}_1), \dots, IN(\mathcal{B}_\varphi)) \geq \alpha] \\ \leq \Pr [f (Exp(10) + 1, \dots, Exp(10) + 1) \geq \alpha] \end{aligned}$$

Proof.

You know the drill... (f is linear and monotone coordinatewise.) \square

Lemma (**Exponential Distribution** Dominates Bucket)

For all $\alpha \geq 0$,

$$\Pr [IN(\mathcal{B}) \geq \alpha] \leq \Pr [Exp(10) + 1 \geq \alpha]$$

Corollary (**Series** of Exponential Dominates the Buckets)

$$\begin{aligned} \text{For all } \alpha \geq 0, \quad \Pr [f (IN(\mathcal{B}_1), \dots, IN(\mathcal{B}_\varphi)) \geq \alpha] \\ \leq \Pr [f (Exp(10) + 1, \dots, Exp(10) + 1) \geq \alpha] \end{aligned}$$

Note that

$$\begin{aligned} f (Exp(10) + 1, \dots, Exp(10) + 1) = f (Exp(10), \dots, Exp(10)) \\ + f(1, \dots, 1) \end{aligned}$$

Lemma (**Exponential Distribution** Dominates Bucket)

For all $\alpha \geq 0$,

$$\Pr [IN(\mathcal{B}) \geq \alpha] \leq \Pr [Exp(10) + 1 \geq \alpha]$$

Corollary (**Series** of Exponential Dominates the Buckets)

For all $\alpha \geq 0$,

$$\begin{aligned} \Pr [f (IN(\mathcal{B}_1), \dots, IN(\mathcal{B}_\varphi)) \geq \alpha] \\ \leq \Pr [f (Exp(10) + 1, \dots, Exp(10) + 1) \geq \alpha] \end{aligned}$$

Thus, in order to bound $f (X_{Q_1}, \dots, X_{Q_\varphi})$ it will be enough to bound

$$\begin{aligned} f (Exp(10), \dots, Exp(10)) &= \sum_{i=1}^{\varphi} Exp(10) \cdot L(Q_i) \\ &= \sum_{i=1}^{\varphi} Exp(10 \cdot L(Q_i)) \end{aligned}$$

Goal:

bound

$$\sum_{i=1}^{\varphi} \text{Exp}(10 \cdot L(Q_i)).$$

Goal: bound $\sum_{i=1}^{\varphi} \text{Exp}(10 \cdot L(Q_i))$.

Lemma (**Concentration Bound** for Exp)

X_1, \dots, X_n are i.r.v., where $X_i \sim \text{Exp}(\lambda_i)$.

Set: $X = \sum_i X_i$, $\lambda_M = \max_i \lambda_i$, $\mu = \mathbb{E}[X] = \sum_i \lambda_i$.

Goal: bound $\sum_{i=1}^{\varphi} \text{Exp}(10 \cdot L(Q_i))$.

Lemma (**Concentration Bound** for Exp)

X_1, \dots, X_n are i.r.v, where $X_i \sim \text{Exp}(\lambda_i)$.

Set: $X = \sum_i X_i$, $\lambda_M = \max_i \lambda_i$, $\mu = \mathbb{E}[X] = \sum_i \lambda_i$.

For $a \geq 2\mu$ $\Pr[X \geq a] \leq \exp\left(-\frac{1}{2\lambda_M}(a - 2\mu)\right)$

Goal: bound $\sum_{i=1}^{\varphi} \text{Exp}(10 \cdot L(Q_i))$.

Lemma (**Concentration Bound** for Exp)

X_1, \dots, X_n are i.r.v, where $X_i \sim \text{Exp}(\lambda_i)$.

Set: $X = \sum_i X_i$, $\lambda_M = \max_i \lambda_i$, $\mu = \mathbb{E}[X] = \sum_i \lambda_i$.

$$\text{For } a \geq 2\mu \quad \Pr[X \geq a] \leq \exp\left(-\frac{1}{2\lambda_M}(a - 2\mu)\right)$$

In our case, $X_i \sim \text{Exp}(10 \cdot L(Q_i))$. $X = \sum_i X_i$.

Goal: bound $\sum_{i=1}^{\varphi} \text{Exp}(10 \cdot L(Q_i))$.

Lemma (**Concentration Bound** for Exp)

X_1, \dots, X_n are i.r.v, where $X_i \sim \text{Exp}(\lambda_i)$.

Set: $X = \sum_i X_i$, $\lambda_M = \max_i \lambda_i$, $\mu = \mathbb{E}[X] = \sum_i \lambda_i$.

$$\text{For } a \geq 2\mu \quad \Pr[X \geq a] \leq \exp\left(-\frac{1}{2\lambda_M}(a - 2\mu)\right)$$

In our case, $X_i \sim \text{Exp}(10 \cdot L(Q_i))$. $X = \sum_i X_i$.

$$\mu = \mathbb{E}[X] = \mathbb{E}\left[\sum_i X_i\right] = \sum_i \mathbb{E}[X_i] = \sum_i 10 \cdot L(Q_i) \leq 10 \cdot d_G(t, t')$$

Goal: bound $\sum_{i=1}^{\varphi} \text{Exp}(10 \cdot L(Q_i))$.

Lemma (**Concentration Bound** for Exp)

X_1, \dots, X_n are i.r.v, where $X_i \sim \text{Exp}(\lambda_i)$.

Set: $X = \sum_i X_i$, $\lambda_M = \max_i \lambda_i$, $\mu = \mathbb{E}[X] = \sum_i \lambda_i$.

$$\text{For } a \geq 2\mu \quad \Pr[X \geq a] \leq \exp\left(-\frac{1}{2\lambda_M}(a - 2\mu)\right)$$

In our case, $X_i \sim \text{Exp}(10 \cdot L(Q_i))$. $X = \sum_i X_i$.

$$\mu = \mathbb{E}[X] = \mathbb{E}\left[\sum_i X_i\right] = \sum_i \mathbb{E}[X_i] = \sum_i 10 \cdot L(Q_i) \leq 10 \cdot d_G(t, t')$$

$$\lambda_M = \max_i \{10 \cdot L(Q_i)\} = \max_i \left\{ O\left(\frac{D(Q_i)}{\log k}\right) \right\} = O\left(\frac{d_G(t, t')}{\log k}\right)$$

$$\mu \leq 10 \cdot d_G(t, t')$$

Thus for $a = 30 \cdot d_G(t, t')$

$$\lambda_M = O\left(\frac{d_G(t, t')}{\log k}\right)$$

$$\Pr[X \geq a] \leq \exp\left(-\frac{1}{2\lambda_M}(a - 2\mu)\right) =$$

$$\mu \leq 10 \cdot d_G(t, t')$$

$$\lambda_M = O\left(\frac{d_G(t, t')}{\log k}\right)$$

Thus for $a = 30 \cdot d_G(t, t')$

$$\Pr[X \geq a] \leq \exp\left(-\frac{1}{2\lambda_M}(a - 2\mu)\right) = \exp(-\Omega(\log k)) = \frac{1}{k^3}$$

$$\mu \leq 10 \cdot d_G(t, t')$$

$$\lambda_M = O\left(\frac{d_G(t, t')}{\log k}\right)$$

Thus for $a = 30 \cdot d_G(t, t')$

$$\Pr[X \geq a] \leq \exp\left(-\frac{1}{2\lambda_M}(a - 2\mu)\right) = \exp(-\Omega(\log k)) = \frac{1}{k^3}$$

We conclude

$$\Pr[f(X_{Q_1}, \dots, X_{Q_\varphi}) \geq O(d_G(t, t'))]$$

$$\mu \leq 10 \cdot d_G(t, t')$$

$$\lambda_M = O\left(\frac{d_G(t, t')}{\log k}\right)$$

Thus for $a = 30 \cdot d_G(t, t')$

$$\Pr[X \geq a] \leq \exp\left(-\frac{1}{2\lambda_M}(a - 2\mu)\right) = \exp(-\Omega(\log k)) = \frac{1}{k^3}$$

We conclude

$$\begin{aligned} & \Pr[f(X_{Q_1}, \dots, X_{Q_\varphi}) \geq O(d_G(t, t'))] \\ & \leq \Pr[f(IN(\mathcal{B}_1), \dots, IN(\mathcal{B}_\varphi)) \geq O(d_G(t, t'))] \end{aligned}$$

$$\mu \leq 10 \cdot d_G(t, t')$$

$$\lambda_M = O\left(\frac{d_G(t, t')}{\log k}\right)$$

Thus for $a = 30 \cdot d_G(t, t')$

$$\Pr[X \geq a] \leq \exp\left(-\frac{1}{2\lambda_M}(a - 2\mu)\right) = \exp(\Omega(\log k)) = \frac{1}{k^3}$$

We conclude

$$\begin{aligned} & \Pr[f(X_{Q_1}, \dots, X_{Q_\varphi}) \geq O(d_G(t, t'))] \\ & \leq \Pr[f(IN(\mathcal{B}_1), \dots, IN(\mathcal{B}_\varphi)) \geq O(d_G(t, t'))] \\ & \leq \Pr[f(\text{Exp}(10), \dots, \text{Exp}(10)) \geq O(d_G(t, t'))] \end{aligned}$$

$$\mu \leq 10 \cdot d_G(t, t')$$

$$\lambda_M = O\left(\frac{d_G(t, t')}{\log k}\right)$$

Thus for $a = 30 \cdot d_G(t, t')$

$$\Pr[X \geq a] \leq \exp\left(-\frac{1}{2\lambda_M}(a - 2\mu)\right) = \exp(\Omega(\log k)) = \frac{1}{k^3}$$

We conclude

$$\begin{aligned} & \Pr[f(X_{Q_1}, \dots, X_{Q_\varphi}) \geq O(d_G(t, t'))] \\ & \leq \Pr[f(IN(\mathcal{B}_1), \dots, IN(\mathcal{B}_\varphi)) \geq O(d_G(t, t'))] \\ & \leq \Pr[f(\text{Exp}(10), \dots, \text{Exp}(10)) \geq O(d_G(t, t'))] \\ & = \Pr[X \geq a] \leq \frac{1}{k^3} \end{aligned}$$

$$\mu \leq 10 \cdot d_G(t, t')$$

$$\lambda_M = O\left(\frac{d_G(t, t')}{\log k}\right)$$

Thus for $a = 30 \cdot d_G(t, t')$

$$\Pr[X \geq a] \leq \exp\left(-\frac{1}{2\lambda_M}(a - 2\mu)\right) = \exp(\Omega(\log k)) = \frac{1}{k^3}$$

We conclude

$$\begin{aligned} & \Pr[f(X_{Q_1}, \dots, X_{Q_\varphi}) \geq O(d_G(t, t'))] \\ & \leq \Pr[f(IN(\mathcal{B}_1), \dots, IN(\mathcal{B}_\varphi)) \geq O(d_G(t, t'))] \\ & \leq \Pr[f(\text{Exp}(10), \dots, \text{Exp}(10)) \geq O(d_G(t, t'))] \\ & = \Pr[X \geq a] \leq \frac{1}{k^3} \end{aligned}$$

If this event indeed occurs

$$\mu \leq 10 \cdot d_G(t, t')$$

$$\lambda_M = O\left(\frac{d_G(t, t')}{\log k}\right)$$

Thus for $a = 30 \cdot d_G(t, t')$

$$\Pr[X \geq a] \leq \exp\left(-\frac{1}{2\lambda_M}(a - 2\mu)\right) = \exp(\Omega(\log k)) = \frac{1}{k^3}$$

We conclude

$$\begin{aligned} & \Pr[f(X_{Q_1}, \dots, X_{Q_\varphi}) \geq O(d_G(t, t'))] \\ & \leq \Pr[f(IN(\mathcal{B}_1), \dots, IN(\mathcal{B}_\varphi)) \geq O(d_G(t, t'))] \\ & \leq \Pr[f(\text{Exp}(10), \dots, \text{Exp}(10)) \geq O(d_G(t, t'))] \\ & = \Pr[X \geq a] \leq \frac{1}{k^3} \end{aligned}$$

If this event indeed occurs

$$d_M(t, t') \leq d_G(t, t') + O(\log k) \cdot f(X_{Q_1}, \dots, X_{Q_\varphi})$$

$$\mu \leq 10 \cdot d_G(t, t')$$

$$\lambda_M = O\left(\frac{d_G(t, t')}{\log k}\right)$$

Thus for $a = 30 \cdot d_G(t, t')$

$$\Pr[X \geq a] \leq \exp\left(-\frac{1}{2\lambda_M}(a - 2\mu)\right) = \exp(\Omega(\log k)) = \frac{1}{k^3}$$

We conclude

$$\begin{aligned} & \Pr[f(X_{Q_1}, \dots, X_{Q_\varphi}) \geq O(d_G(t, t'))] \\ & \leq \Pr[f(IN(\mathcal{B}_1), \dots, IN(\mathcal{B}_\varphi)) \geq O(d_G(t, t'))] \\ & \leq \Pr[f(\text{Exp}(10), \dots, \text{Exp}(10)) \geq O(d_G(t, t'))] \\ & = \Pr[X \geq a] \leq \frac{1}{k^3} \end{aligned}$$

If this event indeed occurs

$$\begin{aligned} d_M(t, t') & \leq d_G(t, t') + O(\log k) \cdot f(X_{Q_1}, \dots, X_{Q_\varphi}) \\ & = O(\log k) \cdot d_G(t, t') \end{aligned}$$

By **union bound**, w.h.p for all t, t' , $d_M(t, t') = O(\log k) \cdot d_G(t, t')$.

By union bound, w.h.p for all t, t' , $d_M(t, t') = O(\log k) \cdot d_G(t, t')$.



Open Question

Close the gap between 8 to $\log k!$

Open Question

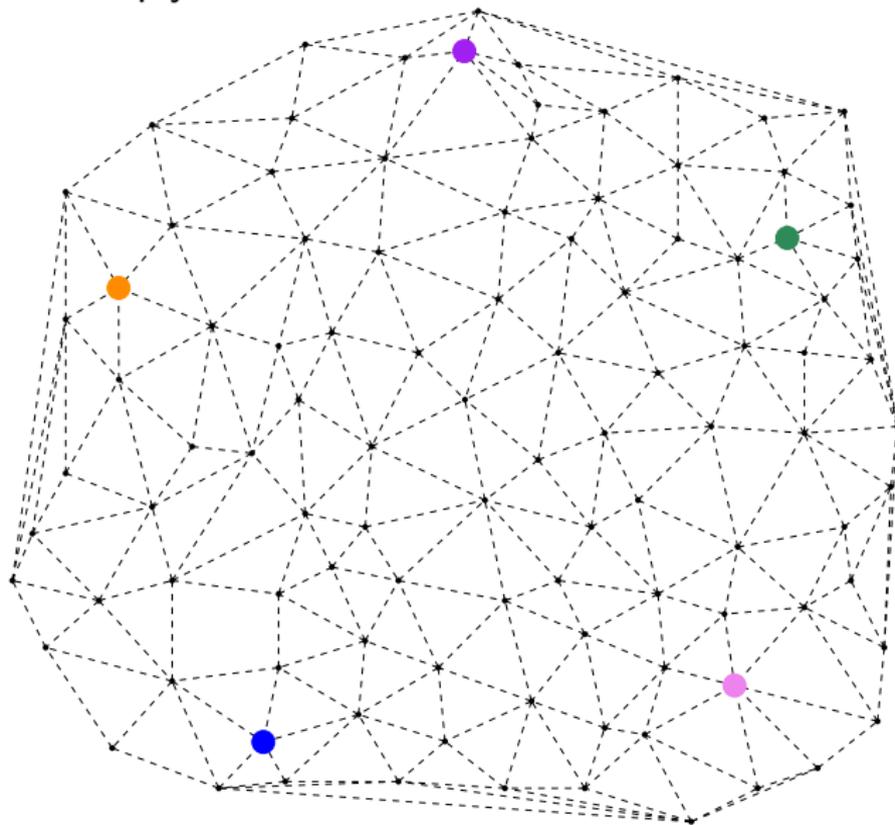
Close the gap between 8 to $\log k!$



Thank You!

We can assume that edges has infinitesimally small weights.
Otherwise we simply subdivide.

34



The set of minors and the geometry of the terminals remain the same!

Ball Growing Algorithm [KKN14]

Algorithm 1 $M = \text{Ball-Growing}(G = (V, E), w, K = \{t_1, \dots, t_k\})$

- 1: Set $r \leftarrow 1 + \delta / \ln k$, where $\delta = 1/80$.
 - 2: Set $D \leftarrow \frac{\delta}{\ln k}$.
 - 3: For each $j \in [k]$, set $V_j \leftarrow \{t_j\}$, and set $R_j \leftarrow 0$.
 - 4: Set $V_\perp \leftarrow V \setminus \left(\cup_{j=1}^k V_j\right)$.
 - 5: Set $\ell \leftarrow 0$.
 - 6: **while** $\left(\cup_{j=1}^k V_j\right) \neq V$ **do**
 - 7: **for** j from 1 to k **do**
 - 8: Choose independently at random q_j^ℓ distributed according to $\text{Exp}(D \cdot r^\ell)$.
 - 9: Set $R_j \leftarrow R_j + q_j^\ell$.
 - 10: Set $V_j \leftarrow B_{G[V_\perp \cup V_j]}(t_j, R_j)$.
 - 11: Set $V_\perp \leftarrow V \setminus \left(\cup_{j=1}^k V_j\right)$.
 - 12: **end for**
 - 13: $\ell \leftarrow \ell + 1$.
 - 14: **end while**
 - 15: **return** the terminal-centered minor M of G induced by V_1, \dots, V_k .
-

Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

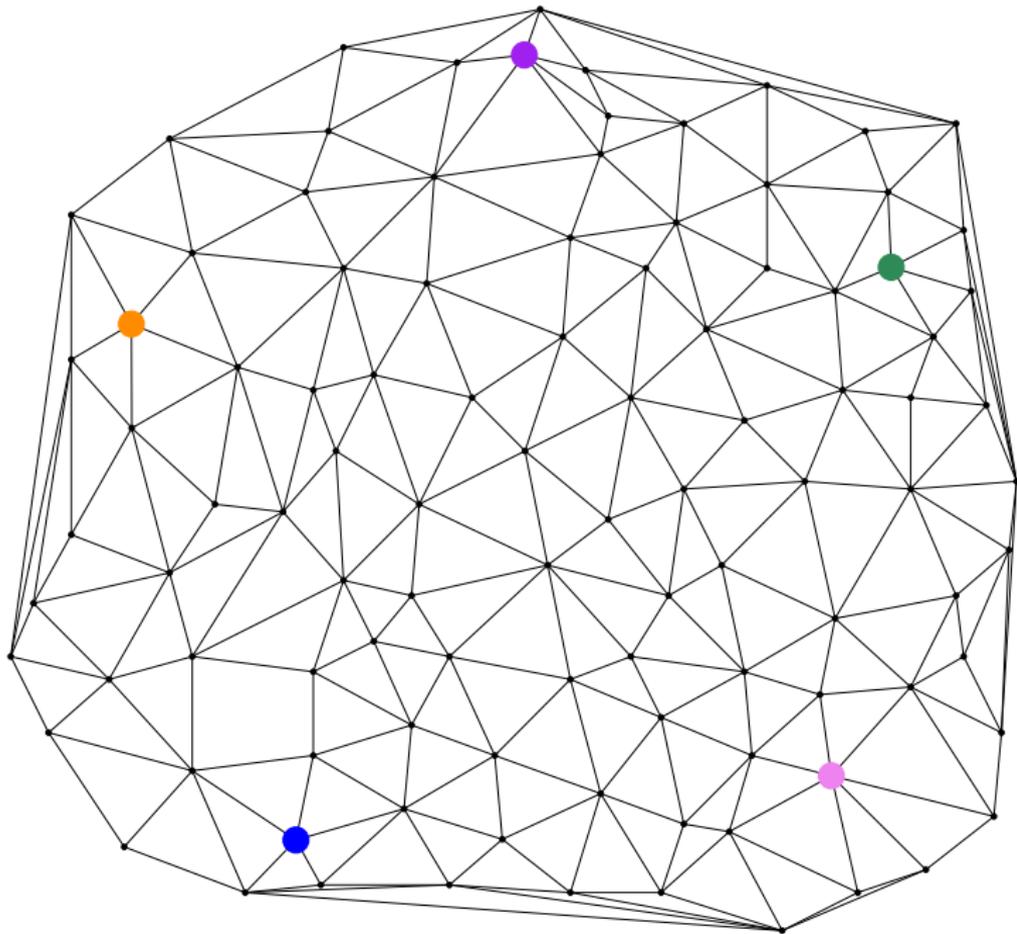
$$R_1 = 0$$

$$R_2 = 0$$

$$R_3 = 0$$

$$R_4 = 0$$

$$R_5 = 0$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

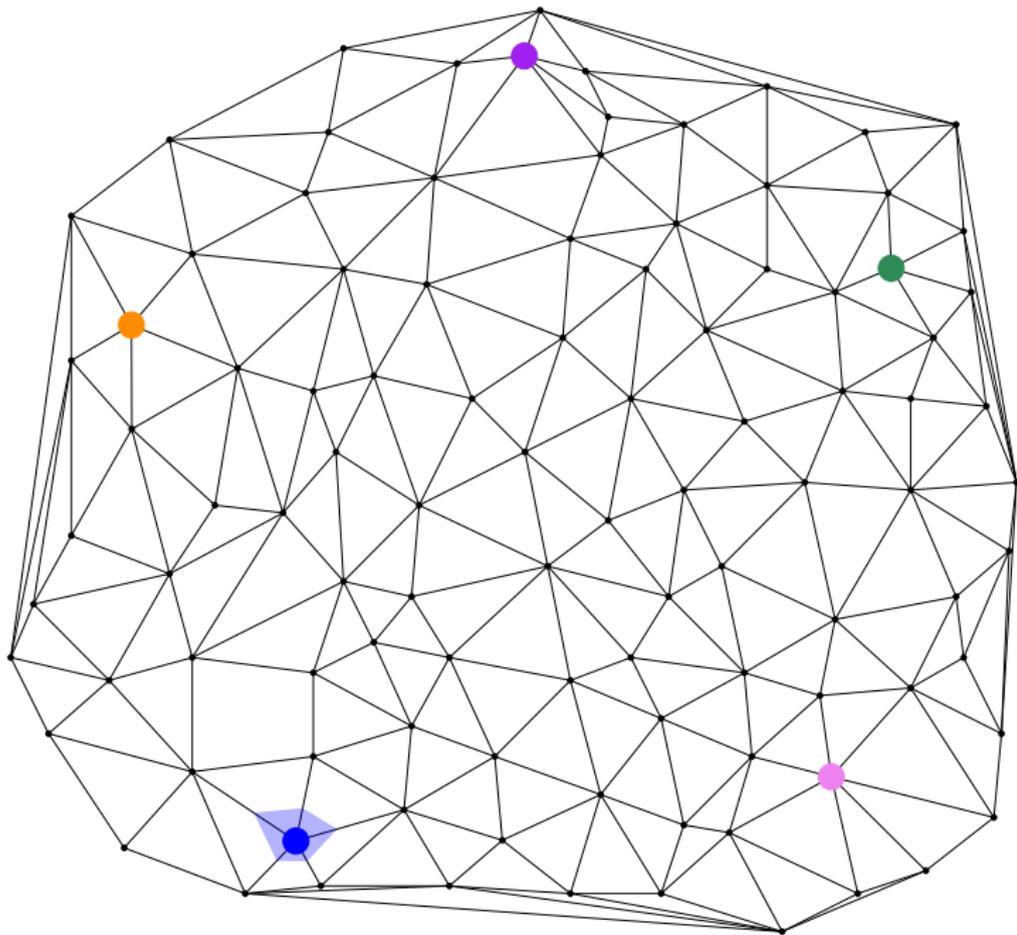
$$R_1 = 0.2$$

$$R_2 = 0$$

$$R_3 = 0$$

$$R_4 = 0$$

$$R_5 = 0$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

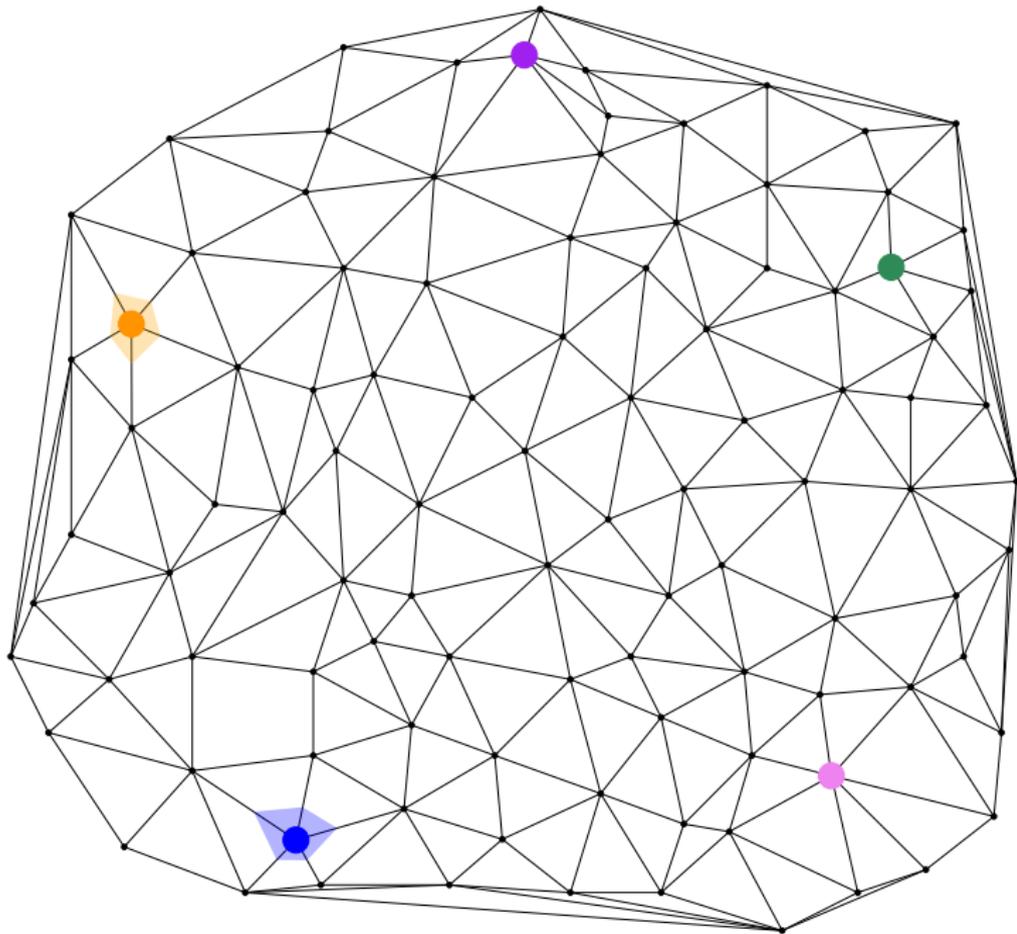
$$R_1 = 0.2$$

$$R_2 = 0.1$$

$$R_3 = 0$$

$$R_4 = 0$$

$$R_5 = 0$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

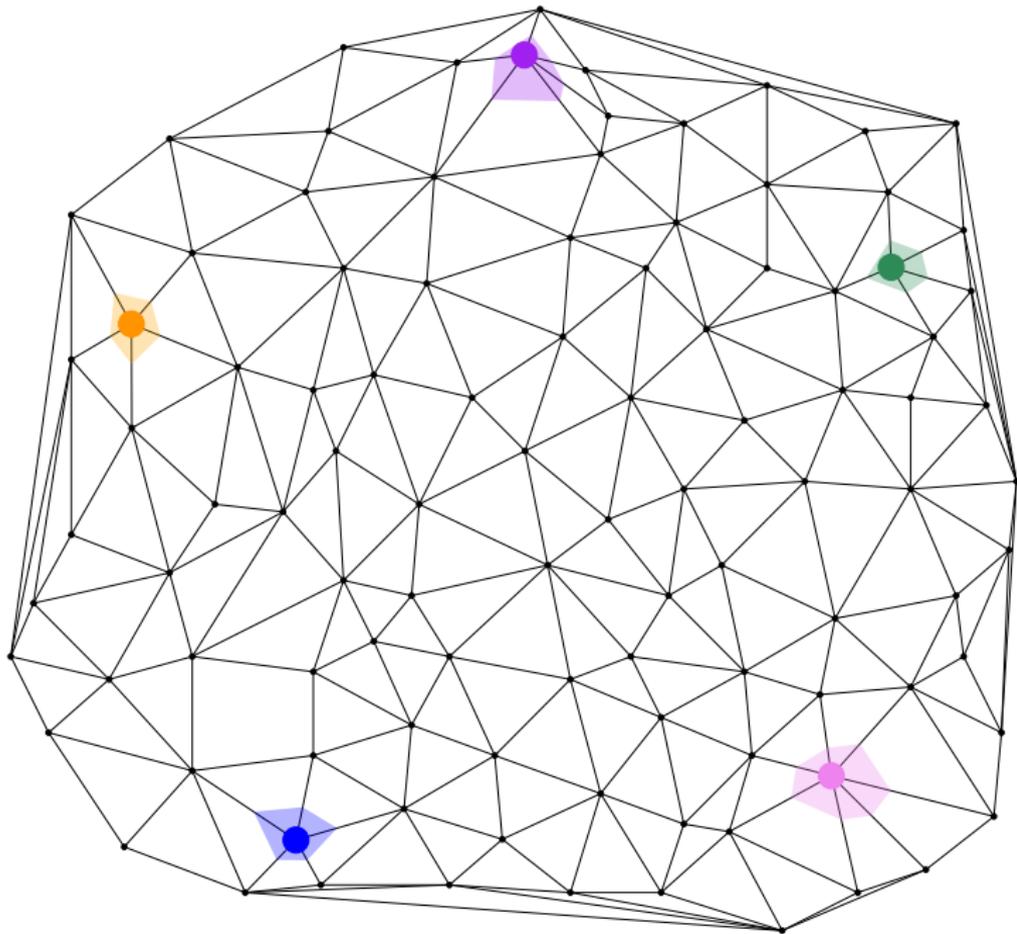
$$R_1 = 0.2$$

$$R_2 = 0.1$$

$$R_3 = 0.3$$

$$R_4 = 0.1$$

$$R_5 = 0.25$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

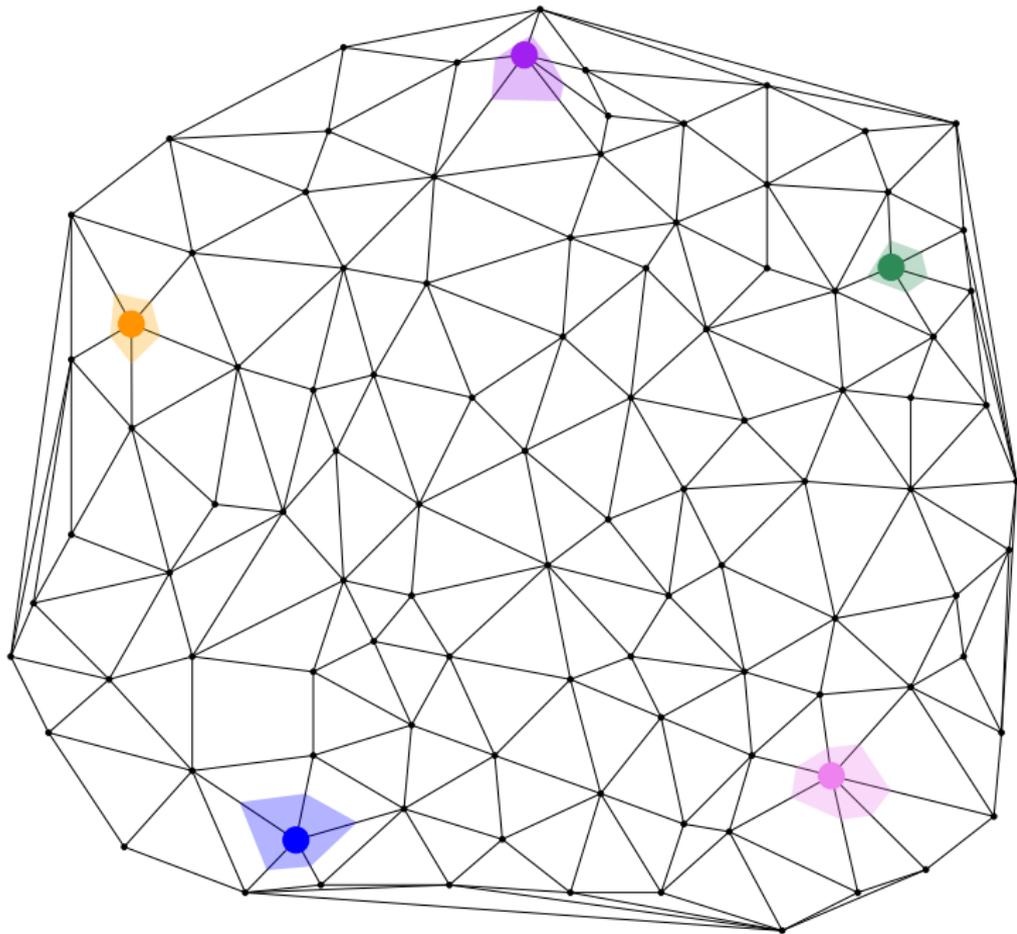
$$R_1 = 0.5$$

$$R_2 = 0.1$$

$$R_3 = 0.3$$

$$R_4 = 0.1$$

$$R_5 = 0.25$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

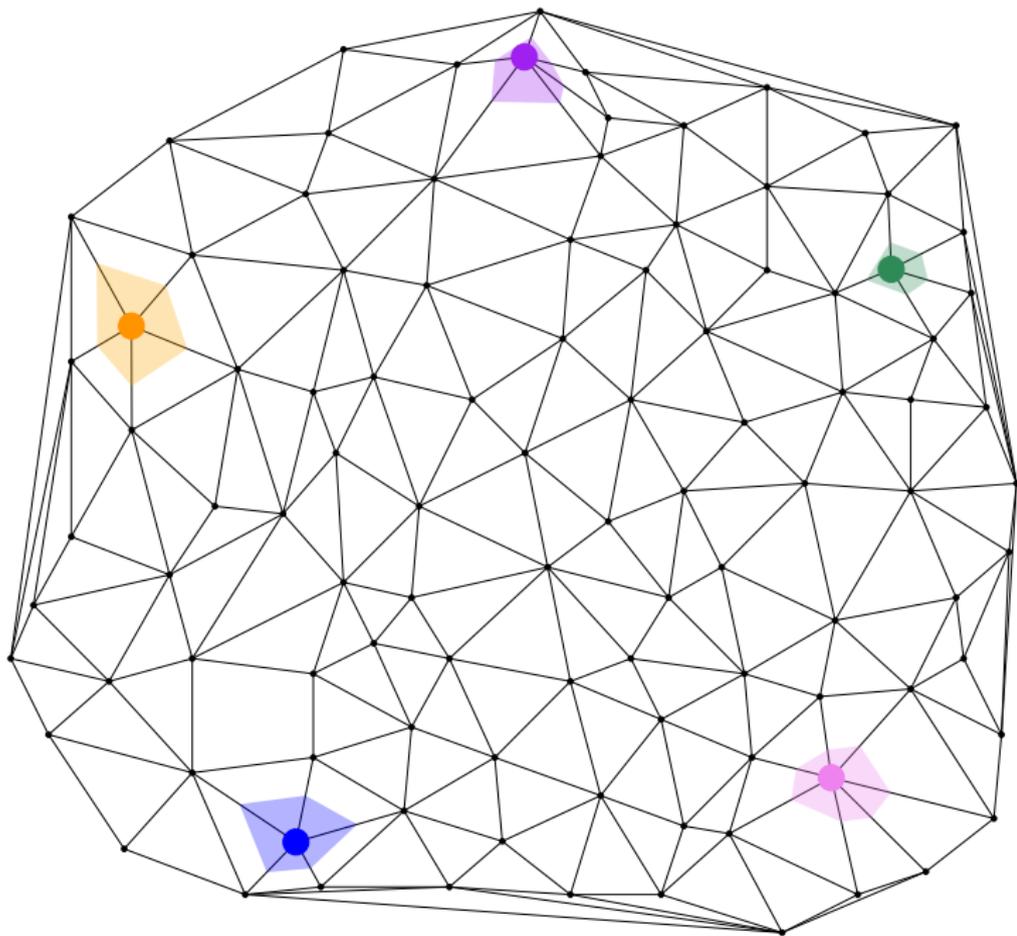
$$R_1 = 0.5$$

$$R_2 = 0.55$$

$$R_3 = 0.3$$

$$R_4 = 0.1$$

$$R_5 = 0.25$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

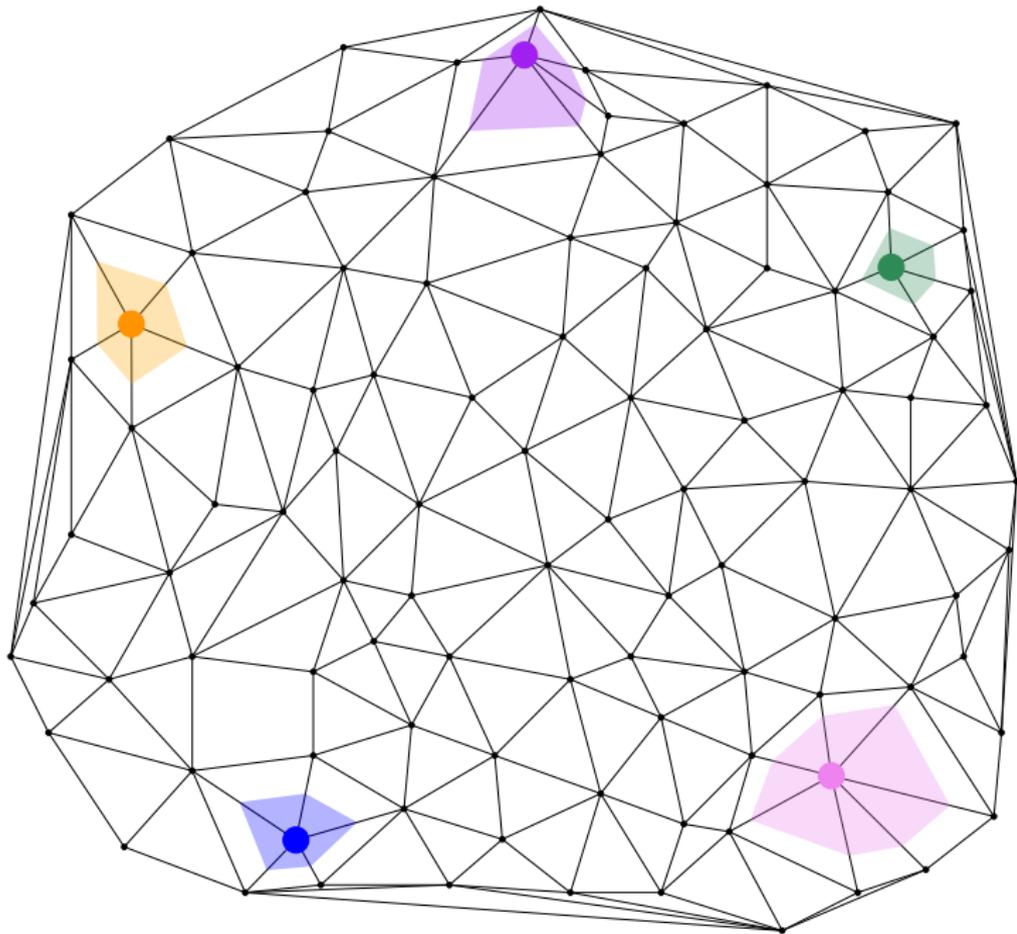
$$R_1 = 0.5$$

$$R_2 = 0.55$$

$$R_3 = 0.6$$

$$R_4 = 0.2$$

$$R_5 = 0.8$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

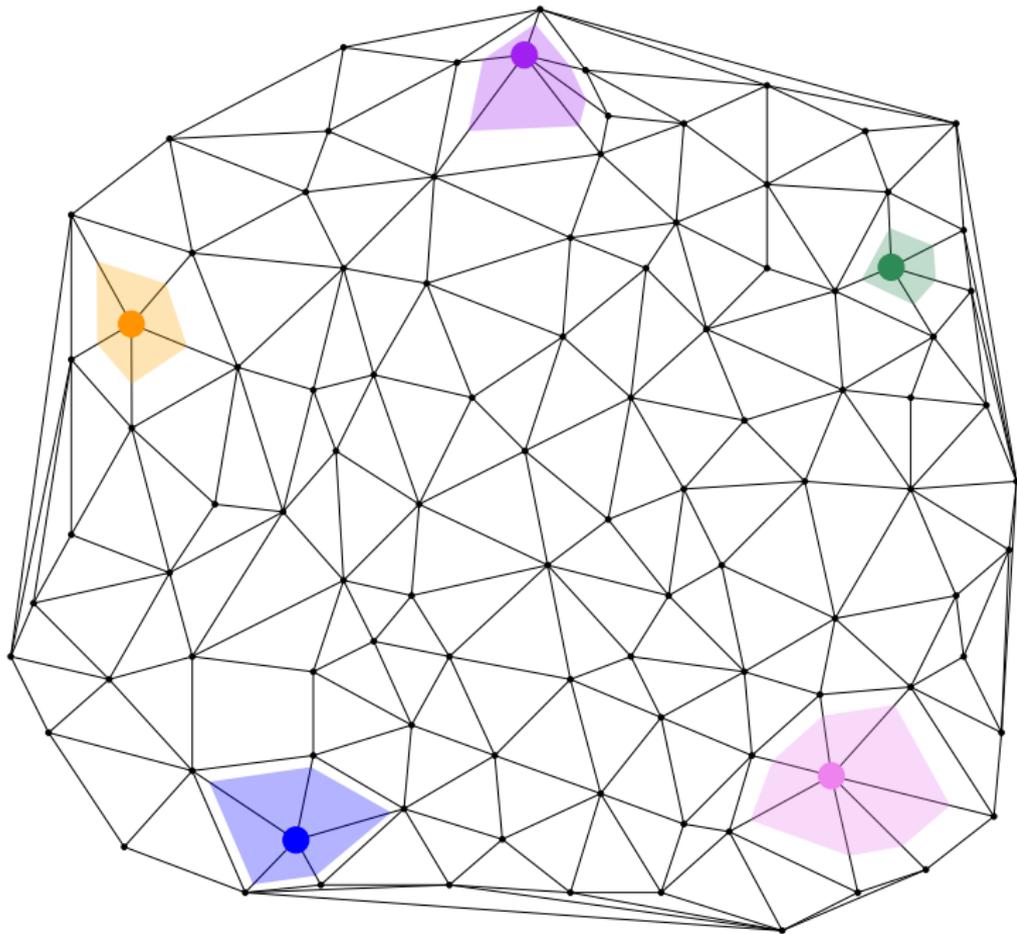
$$R_1 = 0.9$$

$$R_2 = 0.55$$

$$R_3 = 0.6$$

$$R_4 = 0.2$$

$$R_5 = 0.8$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

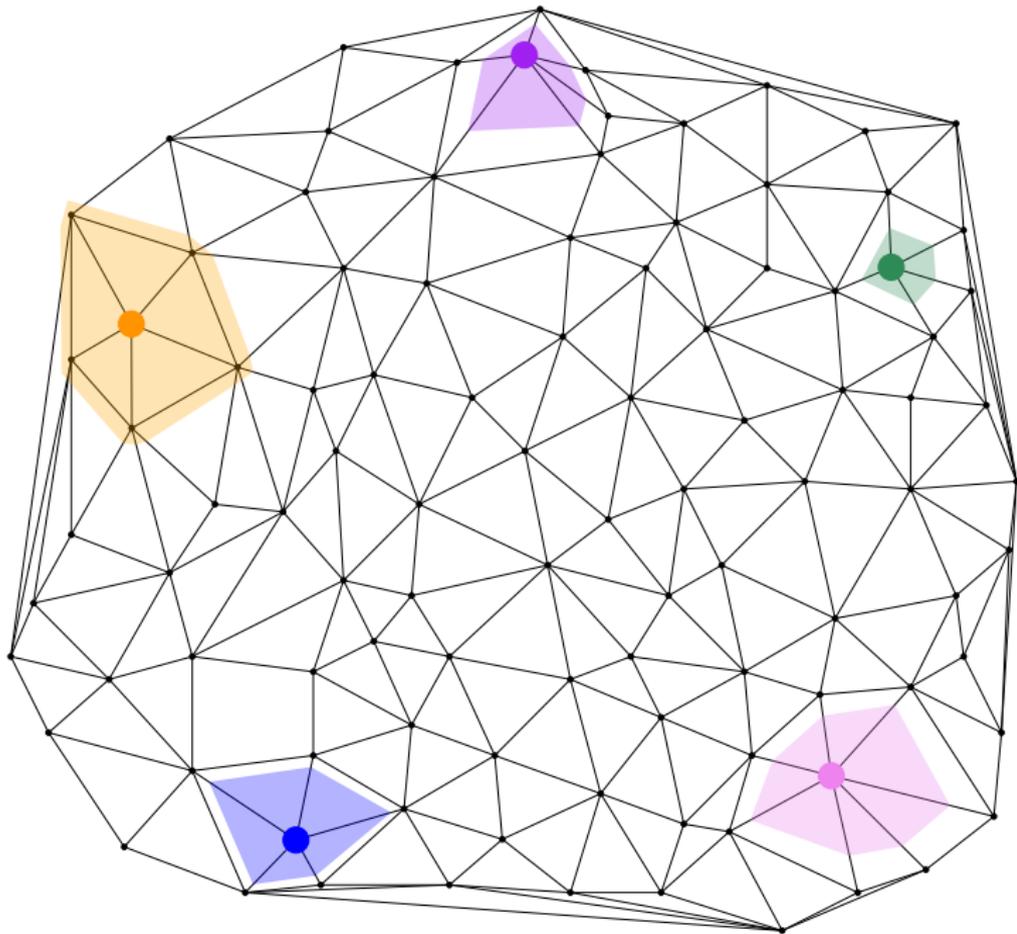
$$R_1 = 0.9$$

$$R_2 = 1.05$$

$$R_3 = 0.6$$

$$R_4 = 0.2$$

$$R_5 = 0.8$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

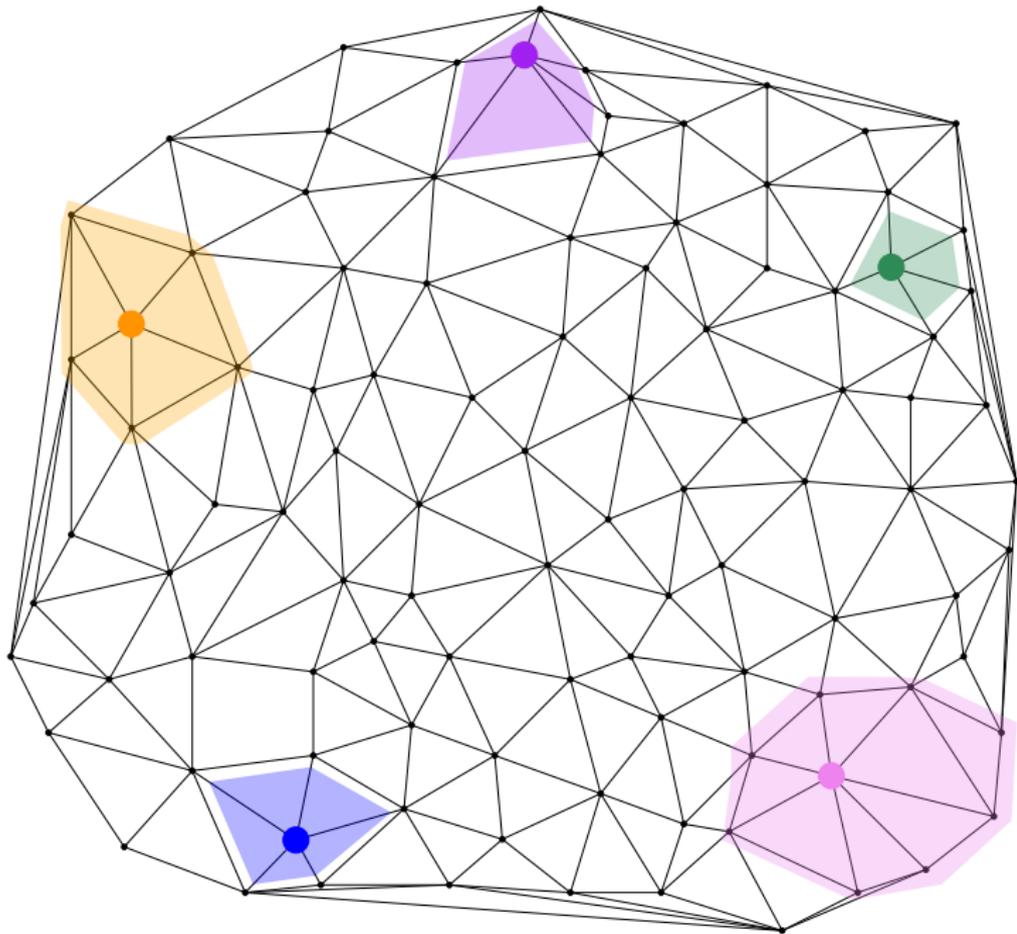
$$R_1 = 0.9$$

$$R_2 = 1.05$$

$$R_3 = 0.85$$

$$R_4 = 0.7$$

$$R_5 = 1.1$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

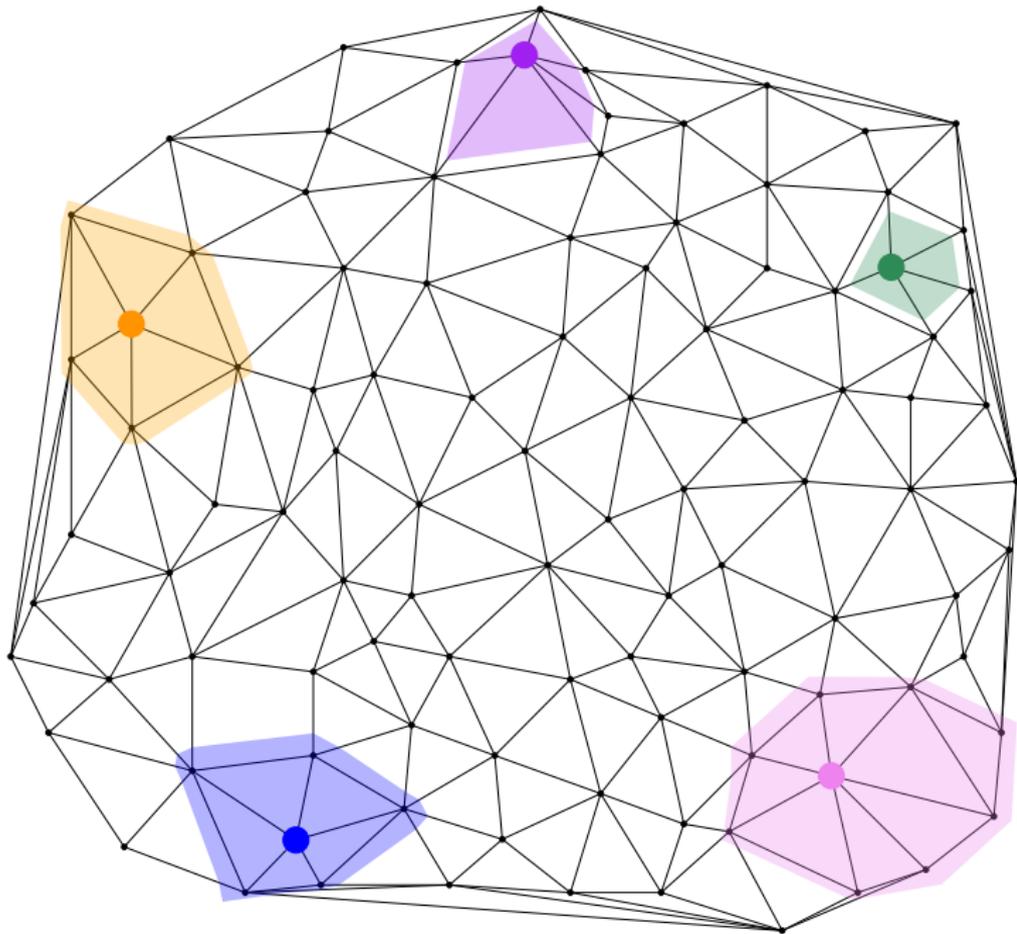
$$R_1 = 1.1$$

$$R_2 = 1.05$$

$$R_3 = 0.85$$

$$R_4 = 0.7$$

$$R_5 = 1.1$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

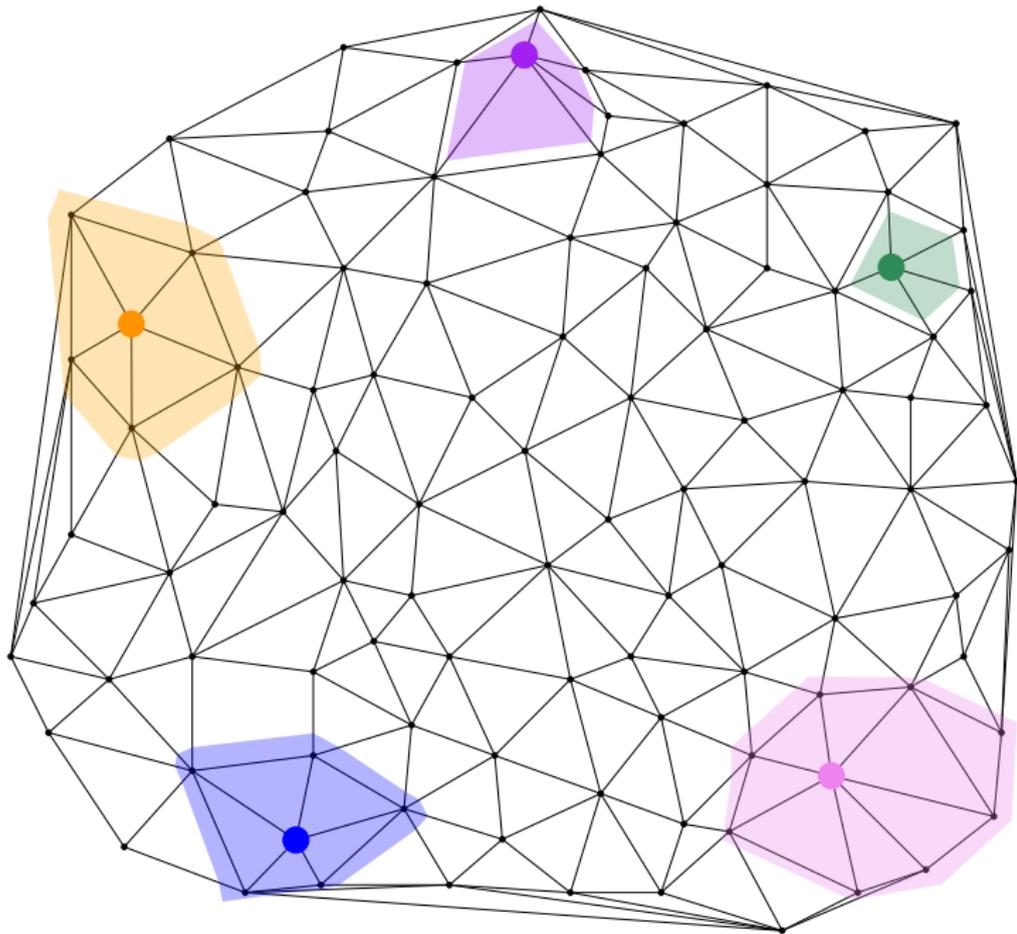
$$R_1 = 1.1$$

$$R_2 = 1.2$$

$$R_3 = 0.85$$

$$R_4 = 0.7$$

$$R_5 = 1.1$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

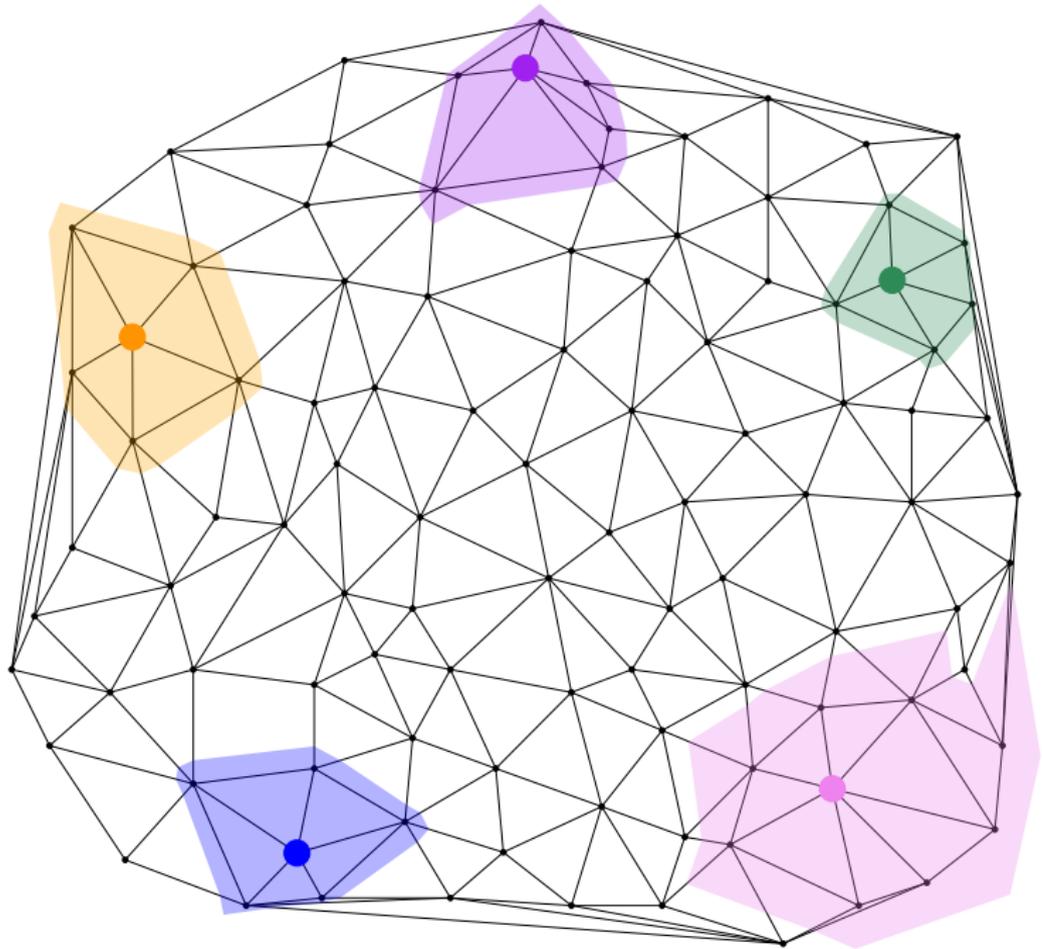
$$R_1 = 1.1$$

$$R_2 = 1.2$$

$$R_3 = 1.1$$

$$R_4 = 1.05$$

$$R_5 = 1.9$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

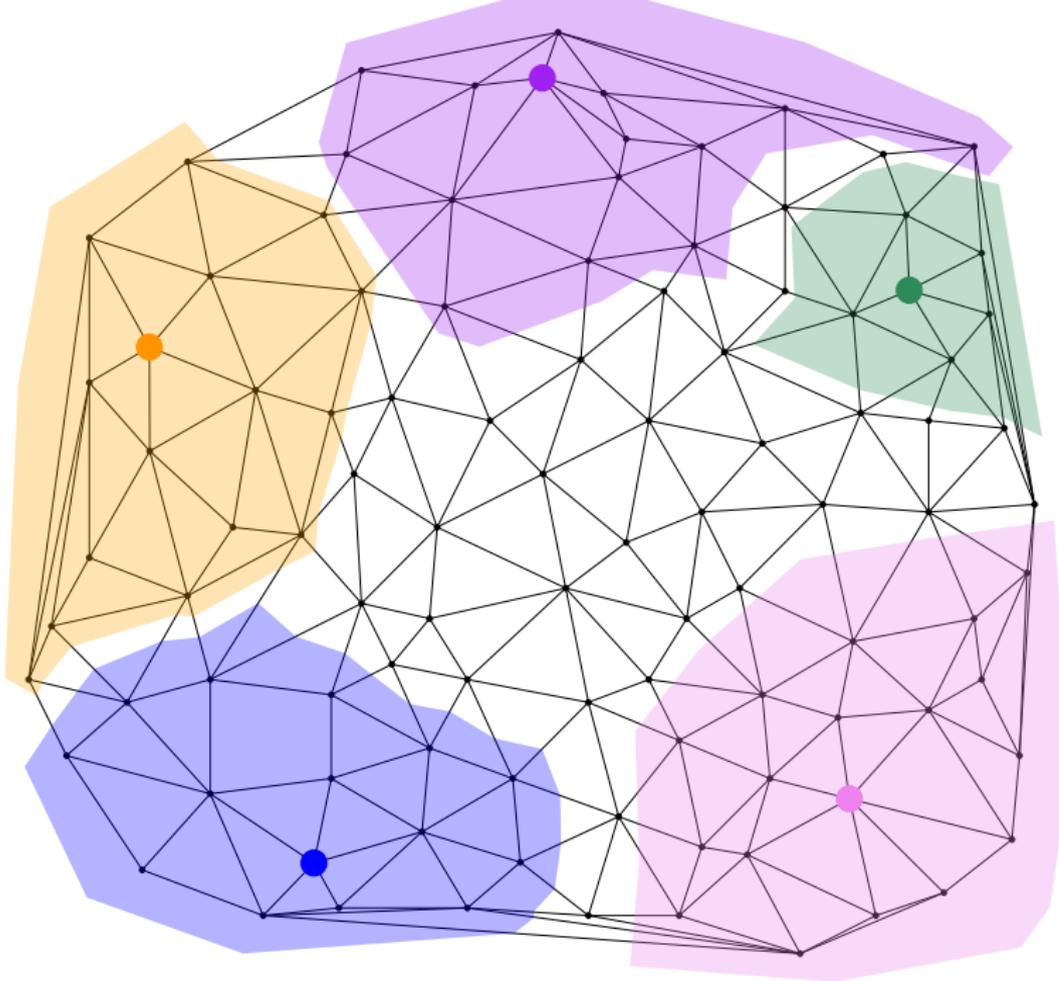
$$R_1 = 2.5$$

$$R_2 = 2.2$$

$$R_3 = 2.3$$

$$R_4 = 1.8$$

$$R_5 = 2.8$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

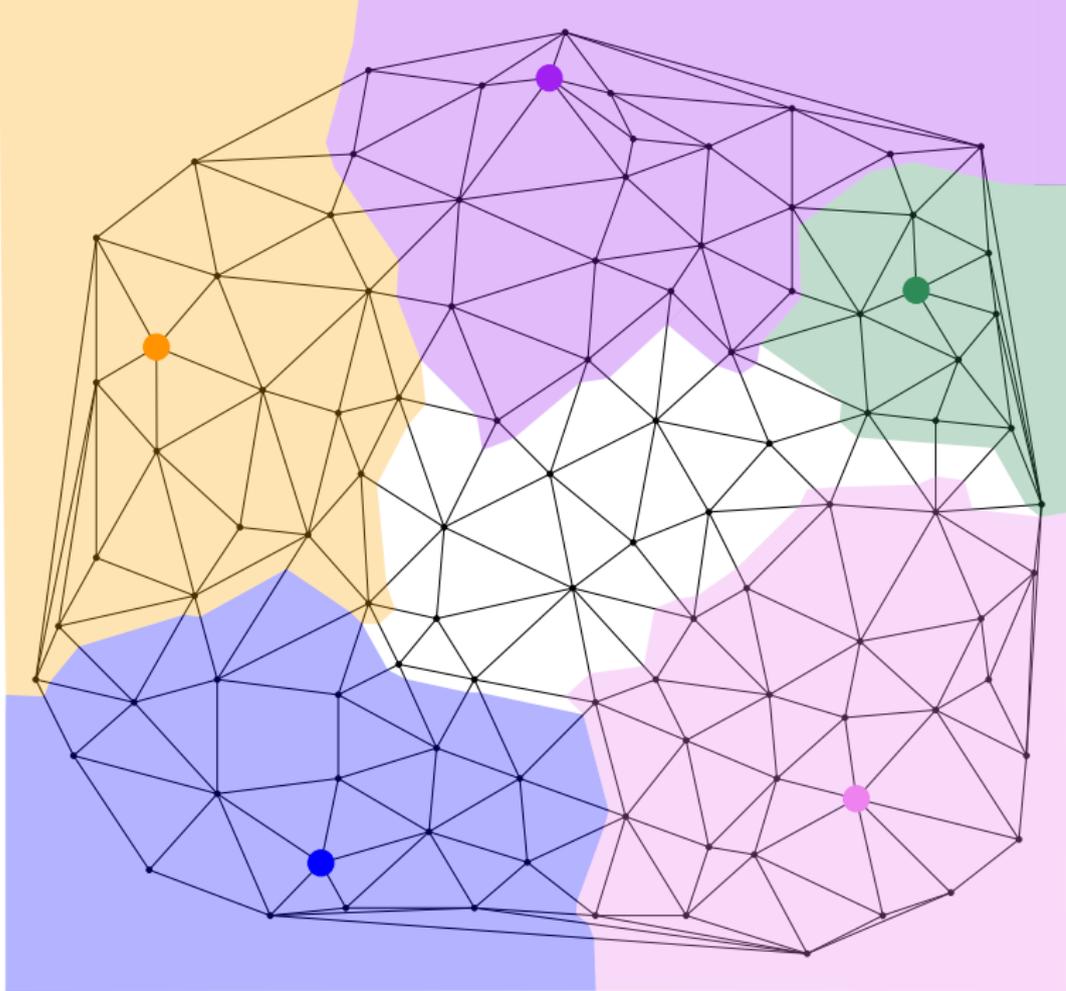
$$R_1 = 2.9$$

$$R_2 = 3.2$$

$$R_3 = 3.15$$

$$R_4 = 2.2$$

$$R_5 = 3.2$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

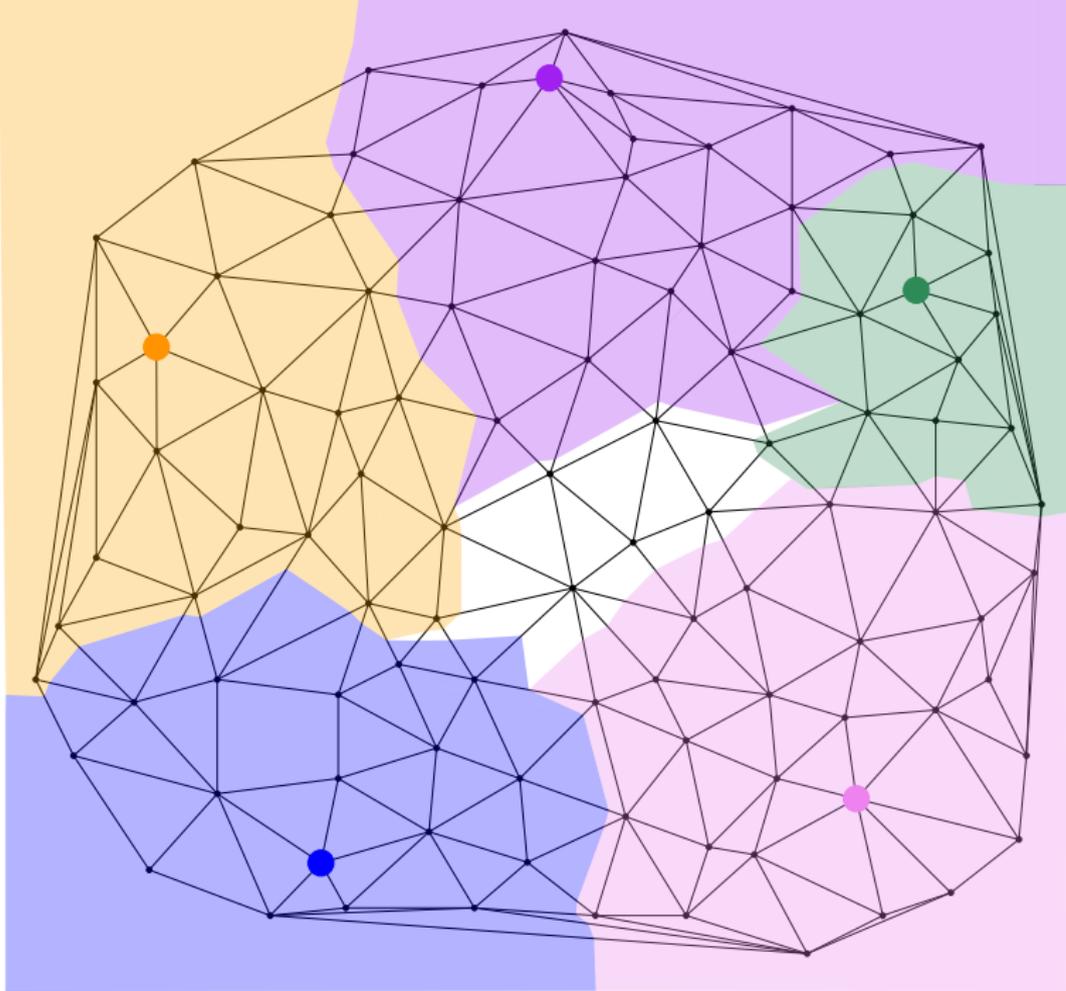
$$R_1 = 3.4$$

$$R_2 = 4.1$$

$$R_3 = 3.8$$

$$R_4 = 3.1$$

$$R_5 = 3.6$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

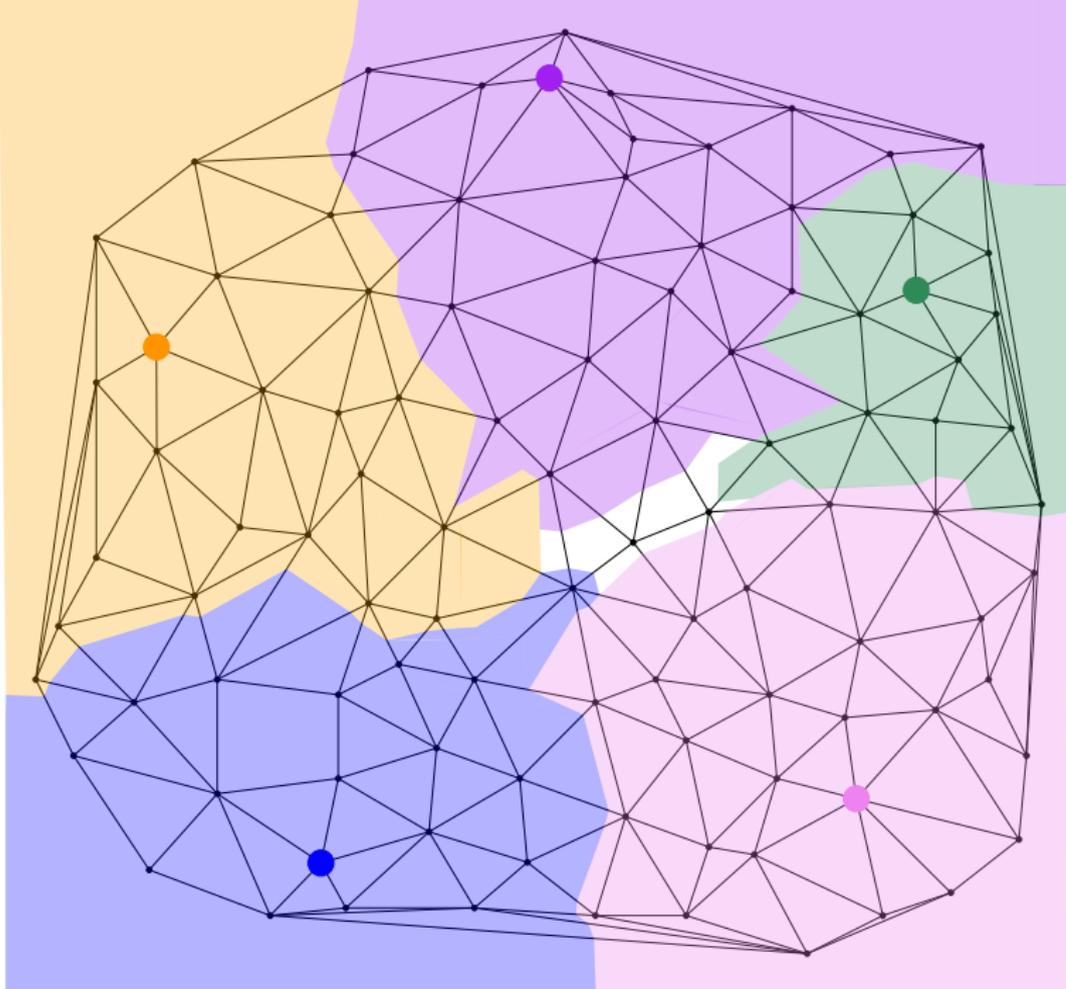
$$R_1 = 4.2$$

$$R_2 = 4.8$$

$$R_3 = 4.5$$

$$R_4 = 3.7$$

$$R_5 = 3.8$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

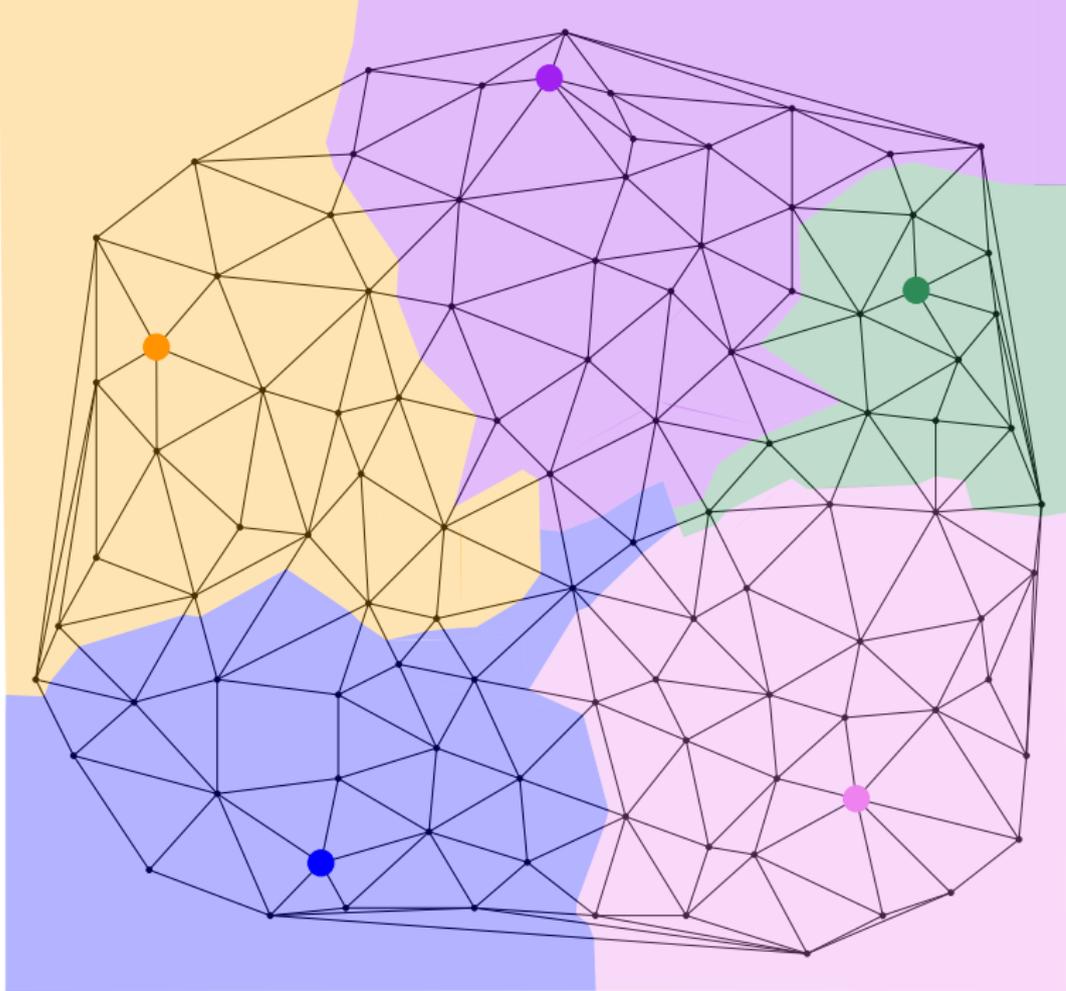
$$R_1 = 5.5$$

$$R_2 = 6$$

$$R_3 = 4.9$$

$$R_4 = 4.5$$

$$R_5 = 5.1$$



Ball Growing Algorithm

Arbitrary order.

Expand cluster in every round.

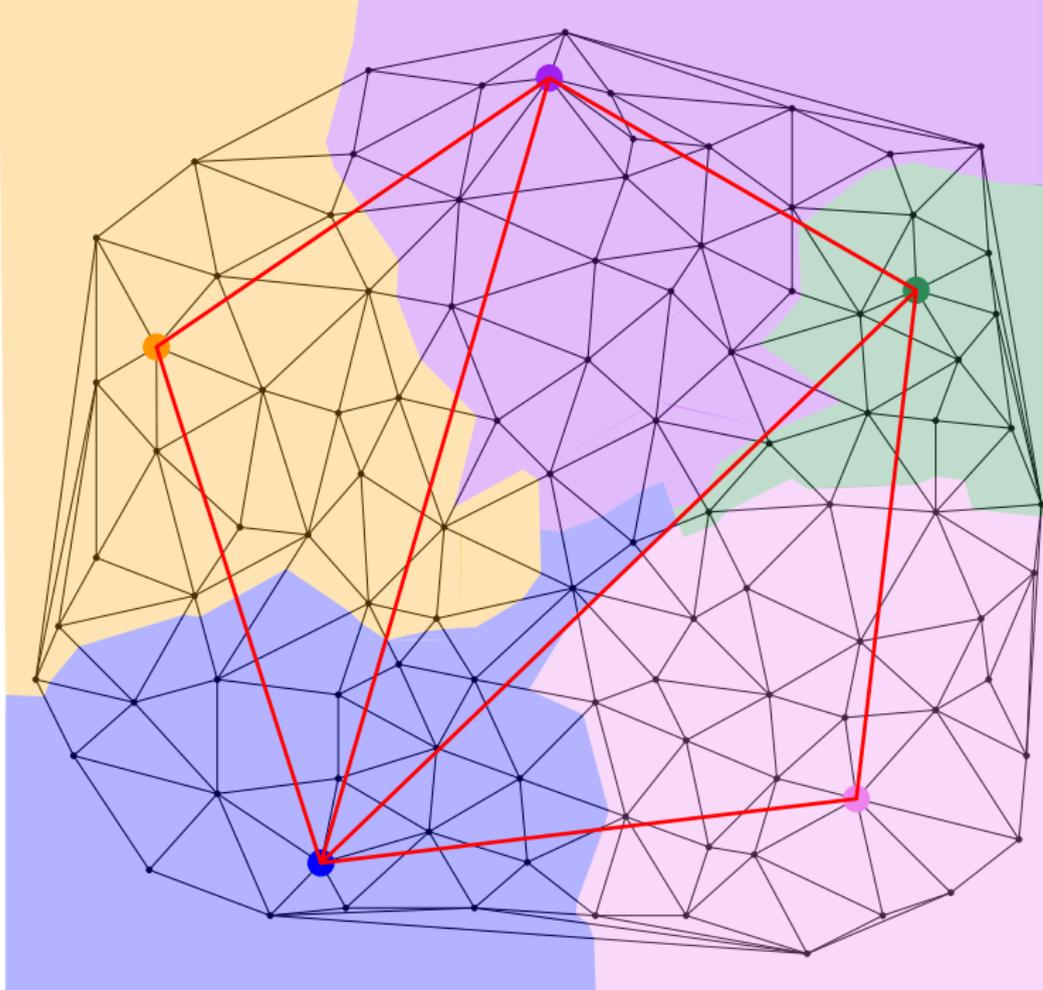
$$R_1 = 5.5$$

$$R_2 = 6$$

$$R_3 = 4.9$$

$$R_4 = 4.5$$

$$R_5 = 5.1$$



Ball Growing Algorithm

7

Arbitrary order.

Expand cluster in every round.

$$R_1 = 5.5$$

$$R_2 = 6$$

$$R_3 = 4.9$$

$$R_4 = 4.5$$

$$R_5 = 5.1$$

Noisy Voronoi

Algorithm 2 $M = \text{Noisy-Voronoi}(G = (V, E, w), K = \{t_1, \dots, t_k\})$

- 1: Set $\delta = 1/20 \ln k$ and $p = \frac{1}{5}$.
 - 2: Set $V_{\perp} \leftarrow V \setminus K$.
 - 3: **for** j from 1 to k **do**
 - 4: Choose independently at random g_j distributed according to $\text{Geo}(p)$.
 - 5: Set $R_j \leftarrow (1 + \delta)^{g_j}$.
 - 6: Set $V_j \leftarrow \text{Create-Cluster}(G, V_{\perp}, t_j, R_j)$.
 - 7: Remove all the vertices in V_j from V_{\perp} .
 - 8: **end for**
 - 9: **return** the terminal-centered minor M of G induced by V_1, \dots, V_k .
-

Noisy Voronoi

Algorithm 2 $M = \text{Noisy-Voronoi}(G = (V, E, w), K = \{t_1, \dots, t_k\})$

- 1: Set $\delta = 1/20 \ln k$ and $p = \frac{1}{5}$.
 - 2: Set $V_{\perp} \leftarrow V \setminus K$.
 - 3: **for** j from 1 to k **do**
 - 4: Choose independently at random g_j distributed according to $\text{Geo}(p)$
 - 5: Set $R_j \leftarrow (1 + \delta)^{g_j}$.
 - 6: Set $V_j \leftarrow \text{Create-Cluster}(G, V_{\perp}, t_j, R_j)$.
 - 7: Remove all the vertices in V_j from V_{\perp} .
 - 8: **end for**
 - 9: **return** the terminal-centered minor M of G induced by V_1, \dots, V_k .
-