

Ellipsoid Algorithm

Feasibility problem: $F \triangleq \{x \in \mathbb{R}^n : Ax \leq b\}$.

find $x \in F$. (or report $F = \emptyset$).

Approx: given $\epsilon > 0$, either find $x \in F$
or report $\text{vol}(F) < \epsilon$.

For orig. problem enough $\epsilon = \exp(-\text{poly}(n, n)B)$

Solving Approx. Feasibility

Def: fix $r > 0$, ball $B_r(y) = \{x \in \mathbb{R}^n : \|x - y\| \leq r\}$

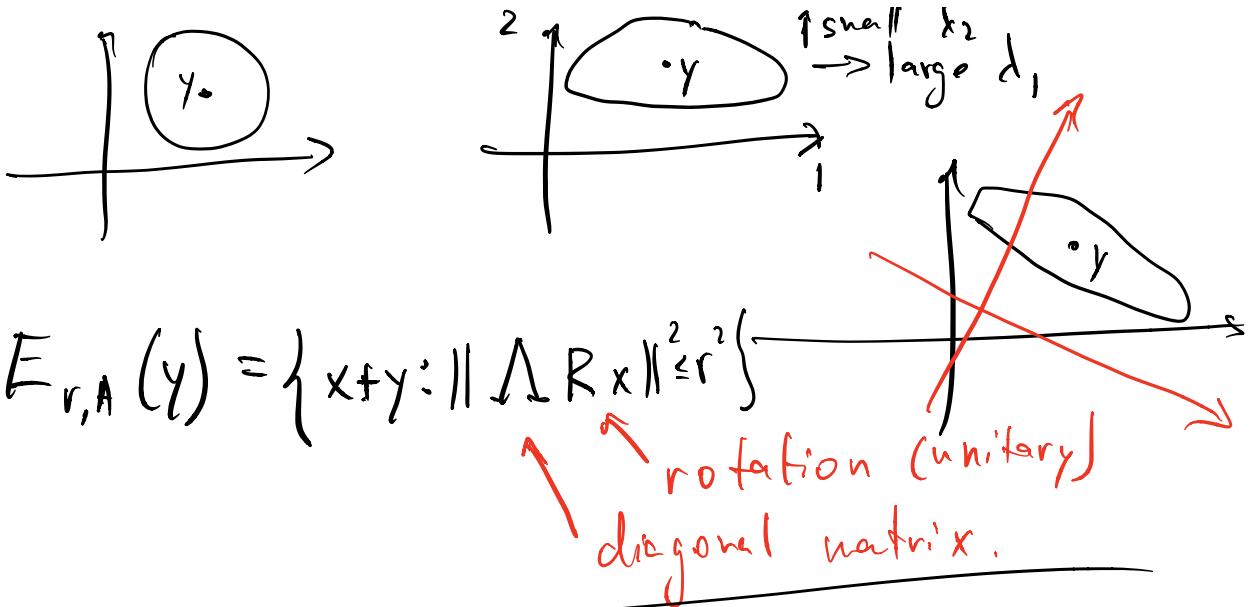
Def: axis-aligned ellipsoids

fix $\lambda_1, \dots, \lambda_n, r > 0$:

$$E_{r, \lambda}(y) = \left\{ x : \sum_{i=1}^n \left(\frac{x_i - y_i}{\lambda_i} \right)^2 \leq r^2 \right\}.$$

Def: general ellipsoids fix $r > 0$,
rank- n matrix $A \in \mathbb{R}^{n \times n}$:

$$\begin{aligned} E_{r, A}(y) &= \{x + y : x^T A^T A x \leq r^2\} \\ &= \{x + y : \|Ax\|_2^2 \leq r^2\}. \end{aligned}$$



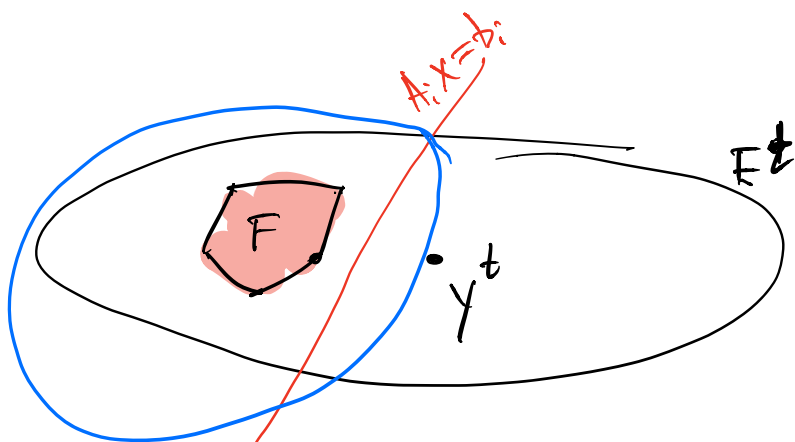
Ellipsoid Algos

Ideas - start with E^0 = some starting ellipsoid.

s.t. $F \subseteq E^0$.

- iterate, and compute E^t at step t s.t. :

- 1) $F \subseteq E^t$.
- 2) $\text{vol}(E^t) < \text{vol}(E^{t-1})$.



- Algo: 1) start with $E^0 \supseteq F$. $E^0 = B_R$ with R large enough.
 $y^0 = \text{center of } E^0$.
- 2) for $t = 0 \dots T$:
- 3) if $y^t \in F$, done: report $x = y^t$.
- 4) if not, \exists constraint violated:
 $A_i y^t > b_i$.
 $\Rightarrow F \subseteq E^t \cap \{A_i x \leq b_i\} \subsetneq E^t$.
- 5) define E^{t+1} , $y^{t+1} = \text{smallest ellipsoid containing } E^t \cap \{A_i x \leq b_i\}$
- 6) terminate if $\text{vol}(E^{t+1}) < \epsilon$.
-

Easy check: if algo terminates it's correct.

Main question: how many iterations?
 (what is T).

Claim: $\text{vol}(E^{t+1}) \leq \text{vol}(E^t) \cdot (1 - \frac{1}{2n})$.

$$\Rightarrow \text{vol}(E^T) \leq \text{vol}(E^0) \cdot \left(1 - \frac{1}{2^n}\right)^T$$

$$\leq (2R)^n \cdot \left(1 - \frac{1}{2^n}\right)^T.$$

when $\uparrow \leq \epsilon$?

$$(2R)^n \cdot \left(1 - \frac{1}{2^n}\right)^T \leq \epsilon$$

$$-n \cdot \lg 2R + T \cdot \frac{\Theta(1)}{2^n} \geq \lg \frac{1}{\epsilon}$$

$$\Rightarrow T \geq \Theta(n) \cdot \left[\lg \frac{1}{\epsilon} + n \cdot \text{poly}(n, n) \cdot B \right].$$

$$\Rightarrow \# \text{ iterations is } \approx \Theta(n \cdot \lg \frac{1}{\epsilon} + \text{poly}(n, n) B)$$

$$\epsilon = \exp(-\text{poly}(n, m) B).$$

\Rightarrow runtime overall is $\text{poly}(n, m, B)$.

Remark: - the only "access" to input constraints $Ax \leq b$ was through "separation oracle":

$\left[\text{SO}_F: \text{ given } y \in \mathbb{R}^n \right.$
 $\left. - \text{ either report } y \in F. \right.$

- or return some constraint
Hyperplane $Ax = b$ s.t.
 F & y are on opposite
sides.

oracle calls = $\Theta(n) \cdot [\lg 1/\epsilon + n \cdot \lg R]$.

Applicable to situations where
constraints may be exponential!

Gradient Descent:

unconstrained opt: $\min_{x \in \mathbb{R}^n} f(x)$.

constrained opt: $\min_{\substack{x \in \mathbb{R}^n \\ x \in F}} f(x)$.

Reduction from const. opt. to unconstr. o.

$$g(x) \triangleq \begin{cases} f(x), & x \in F \\ +\infty, & x \notin F. \end{cases}$$

Enough to solve $\min_{x \in \mathbb{R}^n} g(x)$.

GD: - start with $x^0 \in \mathbb{R}^n$.

- at time $t = 0 \dots T$:

compute $x^{t+1} = \text{function of } x^t, f(x^t) \dots$

Main questions 1) how to define x^{t+1} from x^t .

2) #iteration T to find global min $\min_{x \in \mathbb{R}^n} f(x)$.

Assume that f is "nice" function, so that we can approx / write

Taylor expansion of f :

$$\begin{matrix} f(x+\delta) & = & f(x) & + & \nabla f(x)^T \cdot \delta & + & \delta^T \nabla^2 f(y) \cdot \delta \\ \uparrow & & \uparrow & & & & \\ \mathbb{R}^n & & \mathbb{R}^n & & & & \end{matrix} \quad y \in [x, x+\delta]$$

Def: $\nabla f(x) = \left(\frac{\partial f}{\partial x_1}(x), \frac{\partial f}{\partial x_2}(x), \dots \right) \in \mathbb{R}^n$

Hessian: $\nabla^2 f(x) = \text{matrix } n \times n \text{ with}$
 entry $ij = \frac{\partial^2 f}{\partial x_i \partial x_j}(x)$.

Idea of bD: 1) $x^{t+1} = x^t + \delta$.

2) think of δ as being small and compute best δ s.t.

$$\min_{\delta} f(x^t + \delta)$$

Suppose $\|\delta\| \leq \epsilon$. How to choose δ ?

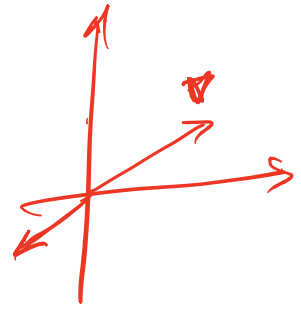
would like: $\delta = \underset{\|\delta\| \leq \epsilon}{\operatorname{argmin}} f(x) + \nabla f^T(x) \cdot \delta + \delta^T \cdot \nabla^2 f(x) \cdot \delta$

Option 1: note that:

$$f(x+\delta) \approx f(x) + \nabla f(x)^T \cdot \delta + O(\epsilon^2)$$

ignore $+ O(\epsilon^2)$ for $m, \ll \nabla f(x)^T \cdot \delta$.

$$\begin{aligned} \delta &= \underset{\|\delta\| \leq \varepsilon}{\operatorname{argmin}} f(x) + \nabla f(x)^T \delta \\ &= \underset{\|\delta\| \leq \varepsilon}{\operatorname{argmin}} \nabla f(x)^T \delta \end{aligned}$$



$$= \eta \cdot (-\nabla f(x)) \quad \text{s.t.} \quad \|\eta \cdot \nabla f(x)\| = \varepsilon.$$

$$\Leftrightarrow \eta = \frac{\varepsilon}{\|\nabla f(x)\|}.$$

Basic GD algo: $x^{t+1} = x^t - \underbrace{\eta \cdot \nabla f(x)}_{\delta}$.

Def: $\beta > 0$. Call f **β -smooth** if:

$$\forall x, y \in \mathbb{R}^n: \quad \|\nabla f(x) - \nabla f(y)\| \leq \beta \cdot \|x - y\|.$$

$$\Leftrightarrow \forall \delta \in \mathbb{R}^n: \quad \delta^T \nabla^2 f(x) \delta \leq \beta \cdot \|\delta\|^2$$

$$\Leftrightarrow \text{max eigenvalue of } \nabla^2 f(x) \leq \beta.$$

Re-derive opt. δ for GD for β -sm.
Taylor exp:

$$f(x+\delta) \approx f(x) + \nabla f(x)^T \cdot \delta + \delta^T \nabla^2 f(x) \delta / 2$$

$$\leq f(x) + \nabla f(x)^T \cdot \delta + \beta \cdot \|\delta\|^2 / 2$$

Option 2: find best step δ :

$$\delta = \operatorname{argmin}_{\delta} f(x) + \nabla f(x)^T \cdot \delta + \beta \cdot \|\delta\|^2 / 2$$

$$= \operatorname{argmin}_{\delta} \nabla f(x)^T \cdot \delta + \beta / 2 \cdot \|\delta\|^2$$

$$= \operatorname{argmin}_{\eta: \delta = \eta \cdot \nabla f(x)} -\eta \cdot \|\nabla f(x)\|^2 + \frac{\beta}{2} \cdot \eta^2 \cdot \|\nabla f(x)\|^2$$

$$= \operatorname{argmin}_{\delta = \eta \cdot \nabla f(x)} \eta \left(\frac{\beta}{2} \cdot \eta - 1 \right)$$

opt. sol. $\eta = 1/\beta$.

opt $\delta = -\frac{1}{\beta} \nabla f(x)$.

Conclusion: $f(x+\delta) \leq$

$$f(x) - \frac{1}{\beta} \|\nabla f(x)\|^2 + \frac{\beta}{2} \cdot \frac{1}{\beta^2} \|\nabla f(x)\|^2$$

$$= f(x) - \frac{1}{2\beta} \cdot \|\nabla f(x)\|^2$$

If $\nabla f(x) \neq 0 \Rightarrow$ make progress!

Will be able to bound #it. T to
get a "good" solution.