

AA Lecture 10 2/11/21

$c$ -approx. near neighbor search in  $\{0,1\}^d$

Def: family  $\mathcal{H}$  of  $h: \{0,1\}^d \rightarrow U$  is

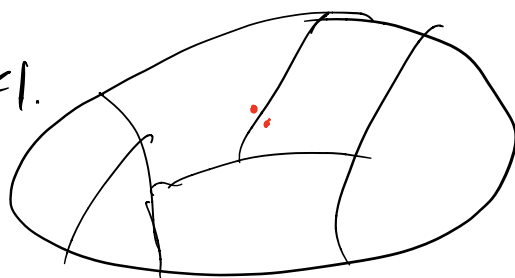
$(r, cr, P_1, P_2)$ -LSH if:  $\forall p, q \in \{0,1\}^d$

$$- \|p - q\|_1 \leq r \Rightarrow P_h[h(p) = h(q)] \geq P_1$$

$$- \|p - q\|_1 \geq cr \Rightarrow P_h[h(p) = h(q)] \leq P_2$$

Fact: if  $P_2 < 1$ , then  $P_1 < 1$ .

(related to isoperimetry questions)



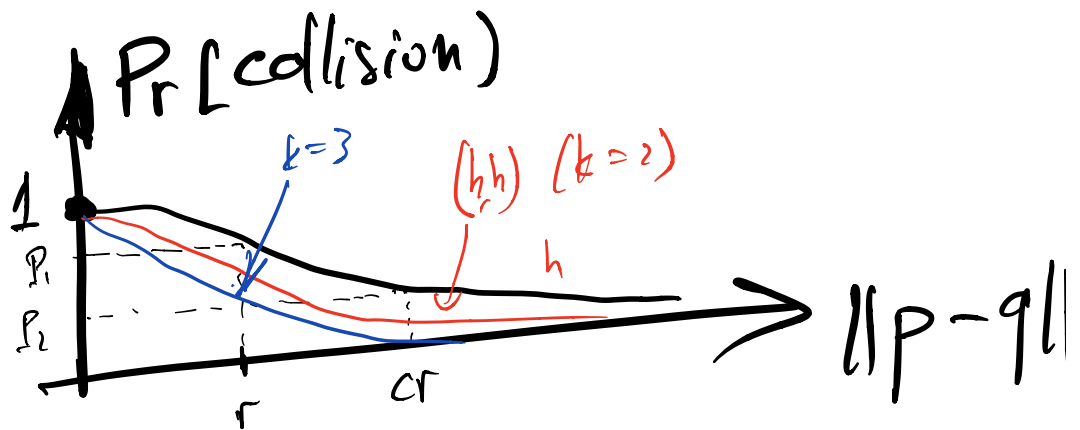
Thm of Indyk-Motwani '98: if  $\exists (r, cr, P_1, P_2)$  LSH,

then can solve  $c$ -ANN: spaces:  $O(nd + n^{1+g}/P_1)$

where  $g = \frac{\lg 1/P_1}{\lg 1/P_2} \leq 1$

q.t.:  $O(n^g/P_1)$  = do [it] time to compute  $h(q)$ .

Proof:  $h \in \mathcal{H} \rightarrow (r, cr, P_1, P_2)$ .



obs: fix  $k \geq 1$ .  $g(p) = (h_1(p), h_2(p), \dots, h_k(p))$

$h_1, \dots, h_k \in \mathcal{H}$  iid

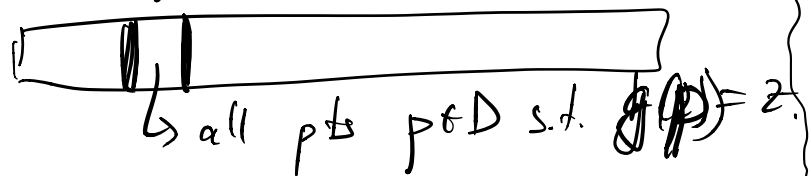
$\Rightarrow$  distrib over  $g: \{0,1\}^d \rightarrow \mathcal{U}^k$

is LSH  $(r, cr, p_1^k, p_2^k)$

$$\Pr[g(p) = g(q)] = \prod_{i=1}^k \Pr[h_i(p) = h_i(q)]$$

Let's design  $c$ -ANN data structures:

Preproc: build a dictionary data structure  
on points  $g(p), p \in D$ .



@ query  $q$ : - compute  $g(q)$

- retrieve all pts  $p \in D$  s.t.  $g(p) = g(q)$ . (using dict.)
- enumerate through them until find a point  $p$  with  $\|q-p\| \leq cr$ .

Analysis: space: just store dict. on  $n$  pts  
 $\Rightarrow O(n)$  space  
 (+  $O(nd)$  to store orig. pts)

query time: time to compute  $g(q)$ .

+ distance calculations in the bucket.

$$\mathbb{E}[\# \text{ dist. calc.}] \leq 1 + \mathbb{E}[\# \text{ dist. calc. to pts } p \in D, \text{ s.t. } \|p-q\| > cr, \text{ and } g(p) = g(q)]$$

$$\leq 1 + n \cdot \Pr\{g(p) = g(q) \mid \|p-q\| > cr\}$$

$$\leq 1 + n \cdot \frac{1}{2^k}$$

last lecture, assumed  $= \frac{1}{n}$

Correctness: assuming  $\exists p^*$  at dist  $\leq r$  from  $q$

$\Pr$  [ algo outputs a ~~cm~~-near neighbor ]

$$\Rightarrow \Pr [ g(p^*) = g(q) ] \geq P_1^k$$

To improve  $\Pr$  [ success ], we just repeat above  $L = 10/P_1^k$  times. (each with fresh hash func.  $g$ ).

Space:  $O(L \cdot n + nd)$

q.t.:  $O(L \cdot (1 + nP_2^k + \text{Time to comp } g(q)))$

$$\Pr [ \text{succ.} ] \geq 1 - (1 - P_1^k)^L \approx 1 - e^{-10/P_1^k \cdot P_1^k} \geq 0.9$$

Set  $k$  to minimize q.t.:  $k \approx \text{s.t. } P_2^k = \frac{1}{n}$

$$L = O\left(\frac{1}{P_1^k}\right) = O\left(\frac{1}{(P_2)^{k_0} \cdot \frac{19^{1/P_2}}{19^{1/P_2}}}\right) = O(n^S)$$

$\rightarrow S$

Note: factor  $1/P_1$  appears in the statement. ⊠

since  $k$  has to be integer:

$$k = \left\lceil \frac{\lg 4}{\lg 1/2} \right\rceil.$$

LSH family for  $\{0,1\}^d$  [IM'98]

$$\mathcal{H} = \{h_i \mid i=1..d\} \quad h_i(p) = p_i \in \{0,1\}.$$

$g(p)$  = concatenation of  $k$  hash func.  $h$

$g(p)$  = projection of  $p$  onto  $k$  coord. (random).

$$P_1 = \Pr_h [h(p) = h(q) \mid \|p - q\| \leq r] \approx 1 - r/d \approx e^{-r/d}$$

$$P_2 \leq 1 - \frac{cr}{d} \approx e^{-cr/d}$$

$$f = \frac{\lg 1/2}{\lg 1/4} = \frac{r/d}{cr/d} = 1/c.$$

Corollary: c-ANN for  $\{0,1\}^d$  with

space:  $O(nd + n^{1+1/c})$

q.t.:  $O(n^{1/c} \cdot d)$ .

$c=2$
$n^{1.5}$
$\sqrt{n} \cdot d$

- Thm [MNP'06, DWZ'10]: for  $\epsilon > 0$ ,  $f \geq \frac{1}{2}$ .
- for  $\epsilon_2$ : can get  $f \leq \frac{1}{2}$ , best possible.
- it is possible to beat these bounds by considering data-dep. LSH. (near perfect hashing).
- can trade-off sp vs g.t

sp:  $n^{1+\epsilon_4}$

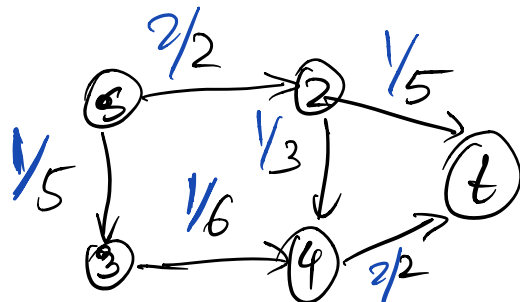
g.t:  $n^{\epsilon_9}$

$\epsilon_4, \epsilon_9$  satisf. constraints.

eg.  $\epsilon_4 \approx 0, \epsilon_9 < 1$ .

Graphs: max-flow problem.

Consider  $G = (V, E, c)$  directed.



$c_e \geq 0$ .

$n = \# \text{ nodes}$   
 $m = \# \text{ edges}$

flow:  $f \in \mathbb{R}^m$   $s = \text{start node}$   
 $t = \text{destination}$ .

$f$  is flow vector  $f \in \mathbb{R}_f^m$  s.t.:

- 1)  $f_e \geq 0, \forall e \in E$ .
- 2)  $f_e \leq c_e, \forall e \in E$
- 3) flow conservation  $\forall v \neq s, t$

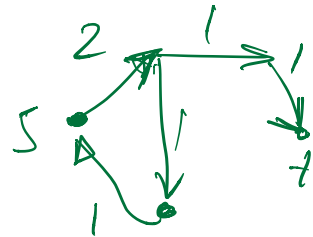
$$\sum_{(u,v) \in E} f_{u,v} - \sum_{(v,u) \in E} f_{v,u} = 0$$

Eg:  $f = \text{all } 0\text{'s}$  is valid flow.

Problem of max-flow: find  $f$  maximizing  
 flow shipped from  $s$  to  $t$ :

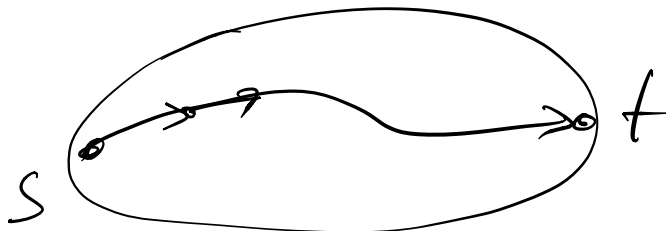
$$|f| = \sum_{(s,u) \in E} f_{s,u} - \sum_{(u,s) \in E} f_{u,s}$$

$$\stackrel{\oplus}{=} \sum_{(u,t) \in E} f_{u,t} - \sum_{(t,u) \in E} f_{t,u}$$

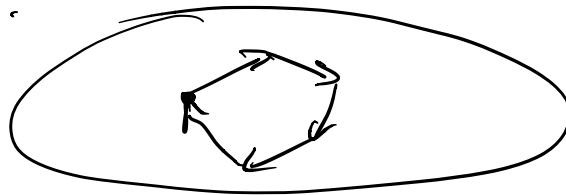


Can prove  $\textcircled{*}$  for any flow by summing  
 up all flow cons constraints for  $v \neq s, t$ .  
 $\Rightarrow$   $\forall$  edge  $(u, v)$  not incident with  $s, t$   
 will cancel out.

Def: path flow is a particular type of  
 flow:



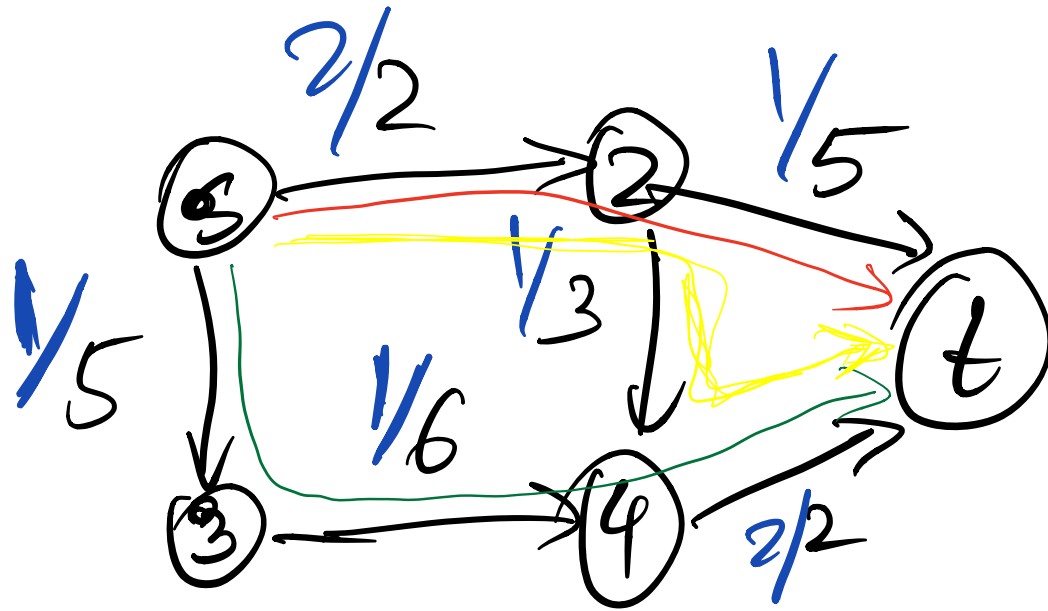
Cycle flow:



Thm: any valid flow  $f$  can be decomposed  
 into a set of path flows  $f_1, f_2, \dots, f_k$   
 and cycle flows  $f_{c_1}, f_{c_2}, \dots, f_{c_l}$  s.t.:

$$f = f_1 + \dots + f_k + f_{c_1} + \dots + f_{c_l}$$





$$k + \ell \leq m.$$