COMS 4995-2: Advanced Algorithms (Spring'20)

Jan 23, 2020

Lecture 2: Approximate Counting Continued, Hashing

Instructor: Alex Andoni

Scribes: Rebecca Calinsky

1 Approximate Counting Continued . . .

Recap from last lecture:

- Problem simply concerns counting up to n
- Morris Algorithm was introduced, which has one register, X, initialized to 0
- We increment as we see ticks, but much more slowly than if we just count
- The bigger X becomes, the less likely it is to increment

1.1 Morris Algorithm

- Initialize X = 0

- At tick:
$$X = \begin{cases} X, \text{ with probability } 1 - 2^{-X} \\ X + 1 \text{ with probability } 2^{-X} \end{cases}$$

- The estimator: $\hat{n} = 2^X - 1$

PART 1: What we proved last lecture . . .

Claim 1. When we define $X_n = X$, the count after n ticks, then $\mathbb{E}[\hat{n}] = \mathbb{E}[2^{X_n} - 1] = n$

Proof. (Supplied last lecture: showed expectation of the estimator equal to n using induction on n)

PART 2: We ask, "Did we gain anything?"

In Part 1, the estimator is in the right ballpark, and now we want to prove that the number of bits necessary has improved drastically ($\lg \lg n$, instead of $\lg n$, where \lg is implicitly \lg_2 from here on).

Claim 2. $\Pr[\lg X \le c \cdot \lg \lg n] \ge 0.9$ for some $c \ge 1$

Proof. Apply the **Markov Bound** on \hat{n} :

$$\Pr[\hat{n} > 10n] \le \frac{n}{10n} = 0.1$$

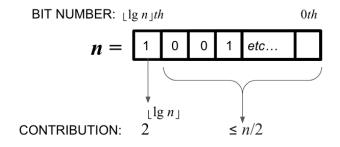
$$\implies \Pr[2^{X_n} - 1 \le 10n] \ge 0.9$$

$$2^{X_n} - 1 \le 10n \implies \log X_n \le \log \log (10n + 1)$$

$$\implies \exists c \ge 1 \text{ such that } \Pr[\log X_n \le c \cdot \lg \lg n] \ge \frac{9}{10}$$

1.2 Intuition behind the algorithm

We are counting up to n ticks, and we can think about n as being represented in binary in the following illustration:



In the above, the index of the most significant bit i_{max} (whose contribution is $2^{\lfloor \lg n \rfloor} \in [n/2, n]$) is all you need in order to have a factor 2 approximation of the number n. The number of bits necessary to communicate the number i_{max} is the lg of the number of bits needed to represent n, which results in $\lg \lg n$.

If X = the most significant bit (index) of the current n, then X should increase only when n roughly doubles. In other words, the larger of number, the less frequently its max index changes.

X is incremented with $\Pr\approx \frac{1}{n}\approx 2^{-X}$

1.3 Show $\hat{n} \approx n$ with good probability

We will use another concentration bound called the **Chebyshev Bound**, and compute $Var[\hat{n}]$.

Claim 3. $Var[\hat{n}] \leq \frac{3}{2}n(n+1) + 1$

Proof.
$$\operatorname{Var}[\hat{n}] = \operatorname{Var}[2^{X_n} - 1] = \mathbb{E}[(2^{X_n} - 1)^2] - n^2 = \mathbb{E}[2^{2X_n}] + \underbrace{1 - 2 \underbrace{\mathbb{E}[2^{X_n}]}_{n+1} - n^2}_{\leq 0} \leq \mathbb{E}[2^{2X_n}]$$

Inductive hypothesis:

$$\mathbb{E}[2^{2X_n}] \le \frac{3}{2}n(n+1) + 1$$

Base case: n = 0 : $\mathbb{E}[2^0] = 1 \le 1$

Assume the inductive hypothesis for $\mathbb{E}[2^{2X_{n-1}}]$

Now we want to compute the expectation:

$$\mathbb{E}[2^{2X_n}] = \mathbb{E}_{X_{n-1}} \left[\mathbb{E}_{X_n}[2^{2X_n}] \right]$$

$$= \sum_{i \ge 0} \Pr[X_{n-1} = i] \cdot \mathbb{E}_{X_n}[2^{2X_n} | X_{n-1} = i]$$

$$= \sum_{i \ge 0} \Pr[X_{n-1} = i] \cdot [2^{-i} \cdot 2^{2(i+1)} + (1 - 2^{-i}) \cdot 2^{2i}]$$

$$= \sum_{i \ge 0} \Pr[X_{n-1} = i] \cdot 2^i \cdot 3 + \sum_{i \ge 0} \Pr[X_{n-1} = i] \cdot 2^{2i}$$

$$= 3 \cdot \mathbb{E}[2^{X_{n-1}}] + \mathbb{E}[2^{2X_{n-1}}]$$

$$= 3 \cdot \mathbb{E}[2^{X_{n-1}}] + \mathbb{E}[2^{2X_{n-1}}]$$

$$\leq \frac{3}{2}n(n+1) + 1$$

1.4 Chebyshev

By definition of Chebyshev:

$$\Pr[|\hat{n} - \mathbb{E}(\hat{n})| > \lambda] \leq \frac{\operatorname{Var}[\hat{n}]}{\lambda^2} \leq \frac{\frac{3}{2}n(n+1) + 1}{\lambda^2} < 0.1$$

It is good enough to have $\lambda = 5n$, since this is an analysis and Chebyshev holds for any bound.

The algorithm does not give a good accuracy, but there is a standard trick to boost the accuracy to get a much better estimate. In particular, we want to do the following:

GOAL: Estimate *n* up to $\pm \epsilon n$ for small $\epsilon > 0$.

- Think of epsilon as being 0.1 which is comparable to 10% error.
- "Estimate up to" means $(1 \epsilon)n \le \hat{n} \le (1 + \epsilon)n$
- To reach our goal, we will essentially do a bunch of counters and average them (Morris+ Algorithm)

1.5 Morris+ Algorithm

- Use k = TBD counters $X^1, X^2, ..., X^k$.
- Each X^i uses Morris Algorithm and is i.i.d.
- The new estimate will be $\hat{n} = \frac{1}{k} \sum_{i=1}^{k} \hat{n}^{i}$, where $\hat{n}^{i} = 2^{X^{i}} 1$

1.6 Amplification / Variance Reduction via Repetition

We will do the analysis and see what we need to set k to be such that we get the above goal. Claim 4. $\mathbb{E}[\hat{n}] = \mathbb{E}[\frac{1}{k}\sum_{i=1}^{k}\hat{n}^{i}] = n$, by linearity of expectation. Claim 5. $\operatorname{Var}[\hat{n}] = \frac{\operatorname{Var}[\hat{n}^{1}]}{k}$

Proof.

$$\operatorname{Var}[\hat{n}] = \operatorname{Var}\left[\frac{1}{k} \cdot \sum_{i=1}^{k} \hat{n}^{i}\right] = \frac{1}{k^{2}} \cdot \operatorname{Var}\left[\sum_{i=1}^{k} \hat{n}^{i}\right] = \underbrace{\frac{1}{k^{2}} \sum_{i=1}^{k} \operatorname{Var}[\hat{n}^{i}]}_{\text{Due to linearity of variance}}$$

Note that the variance of the sum of variables are independent of each other, because they each correspond to the estimate of a different run of the algorithm, where each run of the algorithm uses i.i.d. randomness. For this reason, we can use linearity of variance.

Proof of linearity of variance:

For two independent variables X and Y, their covariance is zero: Cov(X, Y) = 0

$$\operatorname{Var} X + Y = \mathbb{E}[((X + Y) - \mathbb{E}[X + Y])^{2}]$$

= $\mathbb{E}[((X - \mathbb{E}[X]) + (Y - \mathbb{E}[Y]))^{2}]$
= $\mathbb{E}[(X - \mathbb{E}[X])^{2}] + \mathbb{E}[(Y - \mathbb{E}[Y])^{2}] - 2\mathbb{E}[X - \mathbb{E}[X]]\mathbb{E}[Y - \mathbb{E}[Y]]$
= $\operatorname{Var} X + \operatorname{Var} Y - 2\underbrace{Cov(X, Y)}_{=0}$

 \therefore Var X + Y =Var X +Var Y

Set $\lambda = \epsilon n$

By the Chebyshev bound:

$$\Pr[|\hat{n} - \mathbb{E}[n]| > \lambda] \leq \frac{\operatorname{Var}[\hat{n}]}{\lambda^2}$$

 $\leq \underbrace{\frac{\frac{1}{k} \cdot \left(\frac{3}{2}n(n+1)+1\right)}{\epsilon^2 n^2}}_{\text{We want this quantity to be } < 0.1}$

$$\implies \frac{1}{k} \cdot \left(\frac{3}{2}n(n+1) + 1\right) < 0.1 \cdot \epsilon^2 n^2$$

 $\implies \mbox{ It is enough to have } k > \Omega(\frac{1}{\epsilon^2}) \ , \quad \mbox{ where } \Omega \ \mbox{is some large constant}$

With k as the above, all is satisfied and our goal is now satisfied.

 $O\left(\frac{1}{\epsilon^2} \cdot \lg \lg n\right)$ New space:

$\mathbf{2}$ Hashing

Hash function: $h: U \to [n]$ (where U is the discrete universe)

The main application we will be looking at is **Dictionary**.

Dictionary: fixed U; preprocess $S \subset U$, |S| = m, s.t. given a query $x \in U$, report if $x \in S$.

Possible solutions for this problem:

Sol 0 .	Store S	(Search time: $O(m)$; Space: $O(m \cdot \lg m)$)
Sol 0'.	Binary Search Tree	(Search time: $O(\lg m)$; Space: $O(m \cdot \lg m)$)
Sol 0".	Bit Array	(Search time: $O(1)$; Space: $ U $)

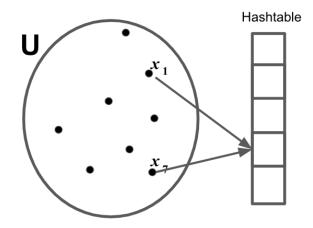
GOAL: Ideally, we would like to combine the best of both worlds and get a deterministic algorithm with both a constant runtime and a space that is linear in the size of S. We will use a hash function to get as close as possible to this goal.

2.1 Solution via a Hash Function

This solution can be thought of a variant of Solution 0''. . Our universe is very large, and this is why our space is very large, so how about we reduce the universe size?

Solution: Store an array of size n s.t. cell i stores all items $j \in S$ s.t. h(j) = i.

When this hash function is defined, it could be that a few elements from the set S map into the same cell.



In the above illustration, element x^1 and x^7 are mapped into the same cell (called a **collision**).

Possible ways we could store x^1 and x^7 :

- 1. Hashing with chaining: store them as a linked list.
- 2. Linear probing: instead of storing x^7 where it was mapped, store it in the next empty cell

3. Cuckoo hashing

The main principle is that collisions are bad!