Review for the Midterm

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```
Structure of a Compiler
```

Scanning

Languages and Regular Expressions

NFAs

Translating REs into NFAs

Building a DFA from an NFA: Subset Construction

Parsing

Resolving Ambiguity

Rightmost and Reverse-Rightmost Derivations

Building the LR(0) Automaton

FIRST and FOLLOW

Building an SLR Parsing Table

Shift/Reduce Parsing

Name, Scope, and Bindings

Activation Records

Static Links for Nested Functions

The Midterm

75 minutes

4 problems

Closed book

One double-sided sheet of notes of your own devising

Comprehensive: Anything discussed in class is fair game

Little, if any, programming

Details of O'Caml/C/C++/Java syntax not required

Compiling a Simple Program

```
int gcd(int a, int b)
{
  while (a != b) {
    if (a > b) a -= b;
    else b -= a;
  }
  return a;
}
```

What the Compiler Sees

```
int gcd(int a, int b)
{
  while (a != b) {
    if (a > b) a -= b;
    else b -= a;
  }
  return a;
}
```

```
i n t sp g c d ( i n t sp a , sp i
n t sp b ) nl { nl sp sp w h i l e sp
( a sp ! = sp b ) sp { nl sp sp sp sp i
f sp ( a sp > sp b ) sp a sp - = sp b
; nl sp sp sp sp e l s e sp b sp - = sp
a ; nl sp sp } nl sp sp r e t u r n sp
a ; nl } nl
```

Text file is a sequence of characters

Lexical Analysis Gives Tokens

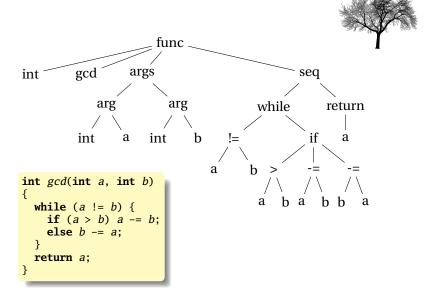
```
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{
  while (a != b) {
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```



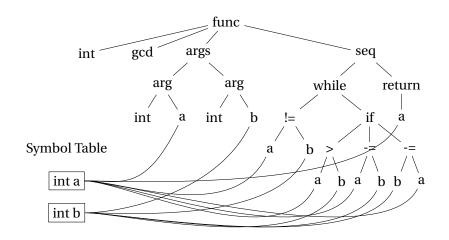
```
while
int
                               int
      gcd
                int
                                     b
                       a
                if
! =
     h
                                  b
                                                   b
                                                           else
                         a
                                          a
                    return
                               a
```

A stream of tokens. Whitespace, comments removed.

Parsing Gives an Abstract Syntax Tree



Semantic Analysis Resolves Symbols and Checks Types



Translation into 3-Address Code

```
LO: sne $1, a, b

seq $0, $1, 0

btrue $0, L1  # while (a != b)

s1 $3, b, a

seq $2, $3, 0

btrue $2, L4  # if (a < b)

sub a, a, b # a -= b

jmp L5

L4: sub b, b, a # b -= a

L5: jmp L0

L1: ret a
```

```
int gcd(int a, int b)
{
  while (a != b) {
    if (a > b) a -= b;
    else b -= a;
  }
  return a;
}
```

Idealized assembly language w/infinite registers

Generation of 80386 Assembly



```
push1 %ebp # Save BP
gcd:
     movl %esp,%ebp
     movl 8(%ebp), %eax # Load a from stack
     movl 12(%ebp),%edx # Load b from stack
.L8: cmpl %edx,%eax
     je .L3  # while (a != b)
jle .L5  # if (a < b)</pre>
     subl %edx,%eax # a -= b
     jmp .L8
.L5: subl %eax,%edx # b -= a
     jmp
           . L8
. T.3:
     1eave
                         # Restore SP, BP
     ret
```

Describing Tokens

Alphabet: A finite set of symbols

Examples: $\{0, 1\}, \{A, B, C, ..., Z\}, ASCII, Unicode$

String: A finite sequence of symbols from an alphabet

Examples: ϵ (the empty string), Stephen, $\alpha\beta\gamma$

Language: A set of strings over an alphabet

Examples: \emptyset (the empty language), {1, 11, 111, 1111}, all English words, strings that start with a letter followed by any sequence of letters and digits

Operations on Languages

```
Let L = \{ \epsilon, \text{ wo } \}, M = \{ \text{ man, men } \}
```

Concatenation: Strings from one followed by the other

 $LM = \{ \text{ man, men, woman, women } \}$

Union: All strings from each language

 $L \cup M = \{\epsilon, \text{ wo, man, men }\}$

Kleene Closure: Zero or more concatenations

 $M^* = \{\epsilon\} \cup M \cup MM \cup MMM \cdots = \{\epsilon, \text{ man, men, manman, manmen, menman, menman, manmanman, manmanman, } \dots\}$

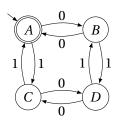
Regular Expressions over an Alphabet Σ

A standard way to express languages for tokens.

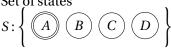
- 1. ϵ is a regular expression that denotes $\{\epsilon\}$
- 2. If $a \in \Sigma$, a is an RE that denotes $\{a\}$
- 3. If r and s denote languages L(r) and L(s),
 - $(r) \mid (s) \text{ denotes } L(r) \cup L(s)$
 - ► (r)(s) denotes $\{tu: t \in L(r), u \in L(s)\}$
 - $(r)^*$ denotes $\bigcup_{i=0}^{\infty} L^i$ $(L^0 = \{\epsilon\})$ and $L^i = LL^{i-1}$

Nondeterministic Finite Automata

"All strings containing an even number of 0's and 1's"



Set of states



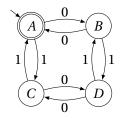
- 2. Set of input symbols Σ : {0, 1}
- 3. Transition function $\sigma: S \times \Sigma_{\epsilon} \to 2^{S}$

state	ϵ	0	1
A	Ø	$\{B\}$	{ <i>C</i> }
B	Ø	$\{A\}$	$\{D\}$
C	Ø	$\{D\}$	$\{A\}$
D	Ø	{ <i>C</i> }	$\{B\}$

- 4. Start state $s_0: (A)$
- 5. Set of accepting states $F: \left\{ \begin{pmatrix} A \end{pmatrix} \right\}$

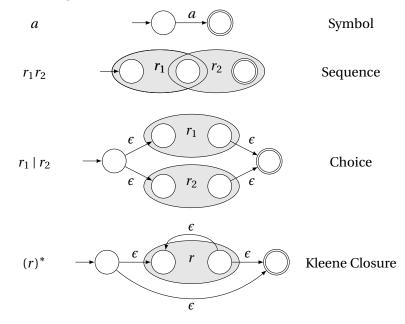
The Language induced by an NFA

An NFA accepts an input string x iff there is a path from the start state to an accepting state that "spells out" x.



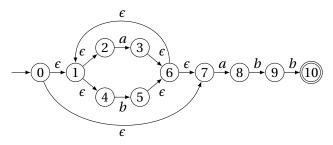
Show that the string "010010" is accepted.

Translating REs into NFAs



Translating REs into NFAs

Example: Translate $(a \mid b)^*abb$ into an NFA. Answer:



Show that the string "aabb" is accepted. Answer:

$$\longrightarrow 0 \stackrel{\epsilon}{\longrightarrow} 1 \stackrel{\epsilon}{\longrightarrow} 2 \stackrel{a}{\longrightarrow} 3 \stackrel{\epsilon}{\longrightarrow} 6 \stackrel{\epsilon}{\longrightarrow} 7 \stackrel{a}{\longrightarrow} 8 \stackrel{b}{\longrightarrow} 9 \stackrel{b}{\longrightarrow} 10$$

Simulating NFAs

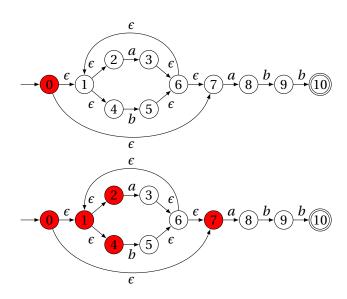
Problem: you must follow the "right" arcs to show that a string is accepted. How do you know which arc is right?

Solution: follow them all and sort it out later.

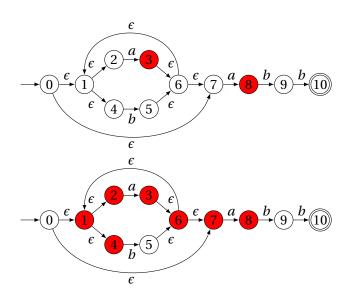
"Two-stack" NFA simulation algorithm:

- 1. Initial states: the ϵ -closure of the start state
- 2. For each character c,
 - ▶ New states: follow all transitions labeled *c*
 - Form the ϵ -closure of the current states
- 3. Accept if any final state is accepting

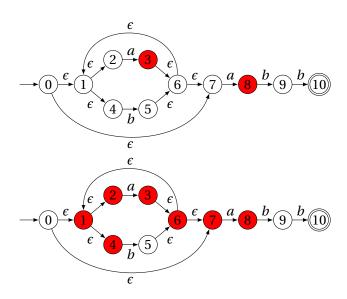
Simulating an NFA: ·*aabb*, Start



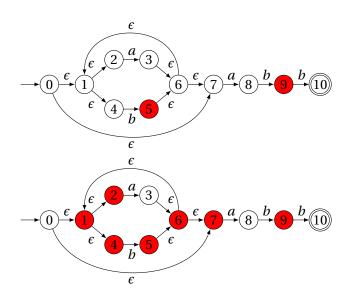
Simulating an NFA: $a \cdot abb$



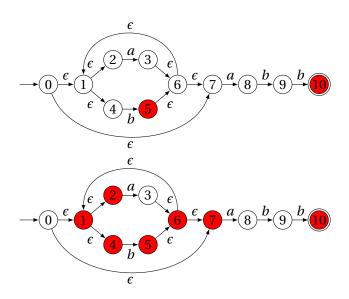
Simulating an NFA: $aa \cdot bb$



Simulating an NFA: $aab \cdot b$



Simulating an NFA: $aabb\cdot$, Done



Deterministic Finite Automata

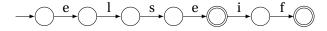
Restricted form of NFAs:

- No state has a transition on ϵ
- ► For each state *s* and symbol *a*, there is at most one edge labeled *a* leaving *s*.

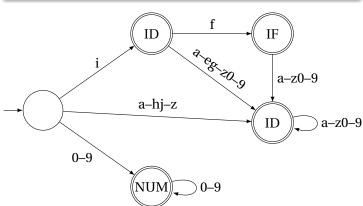
Differs subtly from the definition used in COMS W3261 (Sipser, *Introduction to the Theory of Computation*)

Very easy to check acceptance: simulate by maintaining current state. Accept if you end up on an accepting state. Reject if you end on a non-accepting state or if there is no transition from the current state for the next symbol.

Deterministic Finite Automata



Deterministic Finite Automata

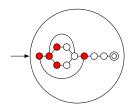


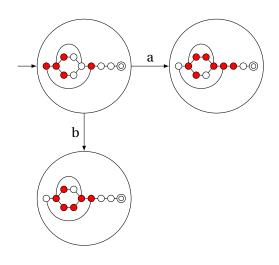
Building a DFA from an NFA

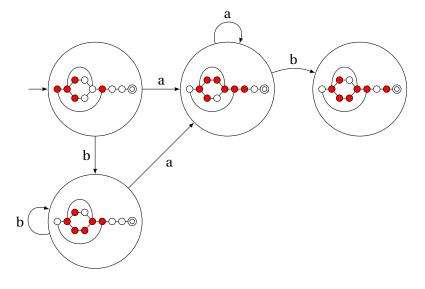
Subset construction algorithm

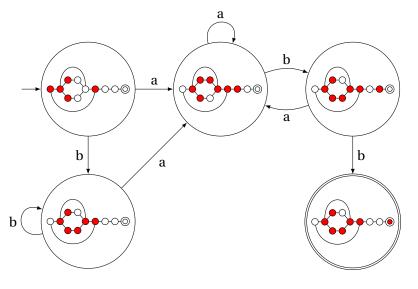
Simulate the NFA for all possible inputs and track the states that appear.

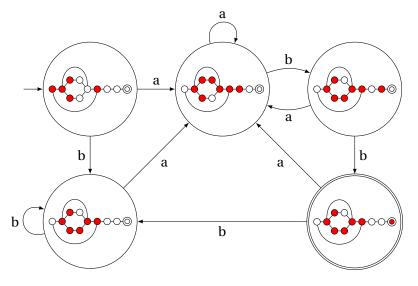
Each unique state during simulation becomes a state in the DFA.



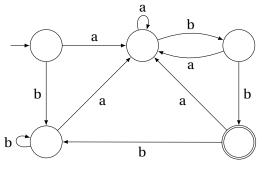








Result of subset construction for $(a \mid b)^*abb$



Is this minimal?

Ambiguous Arithmetic

Ambiguity can be a problem in expressions. Consider parsing

$$3 - 4 * 2 + 5$$

 $e \rightarrow e + e \mid e - e \mid e * e \mid e \mid e \mid N$

with the grammar

Operator Precedence

Defines how "sticky" an operator is.

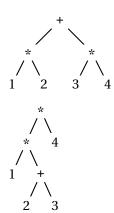
$$1 * 2 + 3 * 4$$

 \ast at higher precedence than +:

$$(1 * 2) + (3 * 4)$$

+ at higher precedence than *:

$$1 * (2 + 3) * 4$$

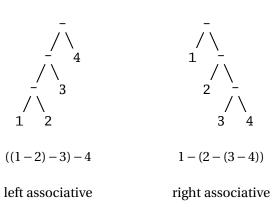


Associativity

Whether to evaluate left-to-right or right-to-left

Most operators are left-associative

$$1 - 2 - 3 - 4$$



Fixing Ambiguous Grammars

A grammar specification:

```
expr :
expr PLUS expr
expr MINUS expr
expr TIMES expr
expr DIVIDE expr
NUMBER
```

Ambiguous: no precedence or associativity.

Ocamlyacc's complaint: "16 shift/reduce conflicts."

Assigning Precedence Levels

Split into multiple rules, one per level

```
expr : expr PLUS expr
| expr MINUS expr
| term

term : term TIMES term
| term DIVIDE term
| atom

atom : NUMBER
```

Still ambiguous: associativity not defined

Ocamlyacc's complaint: "8 shift/reduce conflicts."

Assigning Associativity

Make one side the next level of precedence

```
expr : expr PLUS term
| expr MINUS term
| term

term : term TIMES atom
| term DIVIDE atom
| atom

atom : NUMBER
```

This is left-associative.

No shift/reduce conflicts.

Rightmost Derivation of Id * Id + Id

$$1: e \rightarrow t + e$$

$$2: e \rightarrow t$$

$$3: t \rightarrow \text{Id} * t$$

$$4: t \rightarrow \text{Id}$$

$$\underline{\text{Id}} * t + \underline{\text{Id}}$$

$$\underline{\text{Id}} * t + \underline{\text{Id}}$$

$$\underline{\text{Id}} * t + \underline{\text{Id}}$$

At each step, expand the *rightmost* nonterminal.

nonterminal

"handle": The right side of a production

Fun and interesting fact: there is exactly one rightmost expansion if the grammar is unambigious.

Rightmost Derivation: What to Expand

```
1: e \rightarrow t + e
2: e \rightarrow t
3: t \rightarrow \mathbf{Id} * t
4: t \rightarrow \mathbf{Id}
```

$$e$$

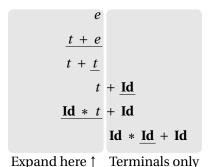
$$t + e$$

$$t + \underline{t}$$

$$t + \underline{Id}$$

$$\underline{Id} * \underline{t} + \underline{Id}$$

$$\underline{Id} * \underline{t} + \underline{Id}$$



Reverse Rightmost Derivation

```
1: e \to t + e2: e \to t
```

$$3: t \rightarrow \mathbf{Id} * t$$

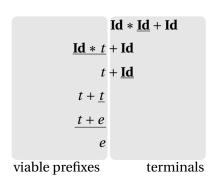
 $4: t \rightarrow \mathbf{Id}$

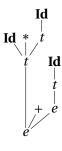
$$\frac{t+e}{t+\underline{t}}$$

$$t+\underline{\mathbf{Id}}$$

$$\underline{\mathbf{Id} * t}+\underline{\mathbf{Id}}$$

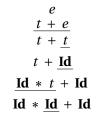
$$\underline{\mathbf{Id} * \mathbf{Id}}+\underline{\mathbf{Id}}$$

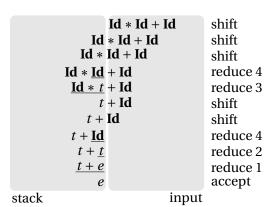




Shift/Reduce Parsing Using an Oracle

```
1: e \rightarrow t + e
2: e \rightarrow t
3: t \rightarrow \mathbf{Id} * t
4: t \rightarrow \mathbf{Id}
```





Handle Hunting

Right Sentential Form: any step in a rightmost derivation

Handle: in a sentential form, a RHS of a rule that, when rewritten, yields the previous step in a rightmost derivation.

The big question in shift/reduce parsing:

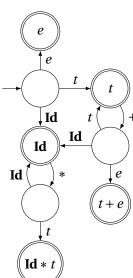
When is there a handle on the top of the stack?

Enumerate all the right-sentential forms and pattern-match against them? *Usually infinite in number, but let's try anyway.*

The Handle-Identifying Automaton

Magical result, due to Knuth: *An automaton suffices to locate a handle in a right-sentential form.*

 $\mathbf{Id} * \mathbf{Id} * \cdots * \underline{\mathbf{Id} * t} \cdots$ $\mathbf{Id} * \mathbf{Id} * \cdots * \underline{\mathbf{Id}} \cdots$ $t + t + \cdots + \underline{t + e}$ $t + t + \cdots + t + \underline{\mathbf{Id}}$ $t + t + \cdots + t + \underline{\mathbf{Id}} * \underline{\mathbf{Id}} * \cdots * \underline{\mathbf{Id}} * \underline{t}$ $t + t + \cdots + \underline{t}$



Building the Initial State of the LR(0) Automaton

 $e' \rightarrow \cdot e$

 $1: e \rightarrow t + e$

 $2:e \rightarrow t$

 $3: t \rightarrow \mathbf{Id} * t$

 $4: t \rightarrow \mathbf{Id}$

Key idea: automata identify viable prefixes of right sentential forms. Each state is an equivalence class of possible places in productions.

At the beginning, any viable prefix must be at the beginning of a string expanded from e. We write this condition " $e' \rightarrow \cdot e$ "

Building the Initial State of the LR(0) Automaton

 $e' \rightarrow \cdot e$ $e \rightarrow \cdot t + e$ $e \rightarrow \cdot t$

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There are two choices for what an e may expand to: t + e and t. So when $e' \rightarrow \cdot e$, $e \rightarrow \cdot t + e$ and $e \rightarrow \cdot t$ are also true, i.e., it must start with a string expanded from t.

Building the Initial State of the LR(0) Automaton

 $e' \rightarrow \cdot e$ $e \rightarrow \cdot t + e$ $e \rightarrow \cdot t$ $t \rightarrow \cdot \mathbf{Id} * t$ $t \rightarrow \cdot \mathbf{Id}$

 $1: e \rightarrow t + e$ $2: e \rightarrow t$ $3: t \rightarrow \mathbf{Id} * t$ $4: t \rightarrow \mathbf{Id}$

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There are two choices for what an e may expand to: t + e and t. So when $e' \rightarrow \cdot e$, $e \rightarrow \cdot t + e$ and $e \rightarrow \cdot t$ are also true, i.e., it must start with a string expanded from t.

Similarly, *t* must be either $\mathbf{Id} * t$ or \mathbf{Id} , so $t \rightarrow \cdot \mathbf{Id} * t$ and $t \rightarrow \cdot \mathbf{Id}$.

This reasoning is a *closure* operation like ϵ -closure in subset construction.

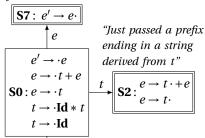
 $e' \rightarrow \cdot e$ $e \rightarrow \cdot t + e$ $\mathbf{S0} : e \rightarrow \cdot t$ $t \rightarrow \cdot \mathbf{Id} * t$

 $t \rightarrow \cdot \mathbf{Id}$

The first state suggests a viable prefix can start as any string derived from e, any string derived from t, or **Id**.

Building the LR(0) Automaton "Just passed a

string derived from e"



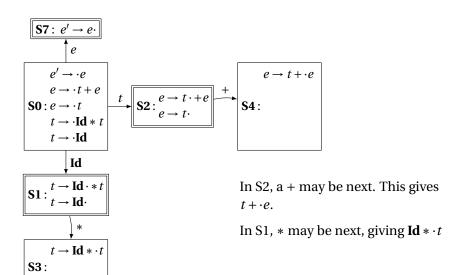
"Just passed a prefix that ended in an **Id**"

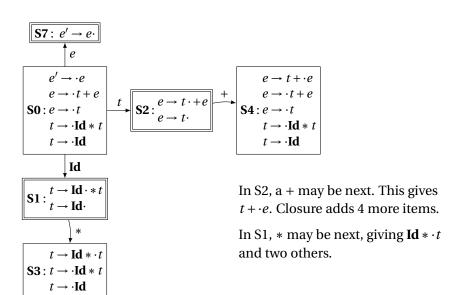
S1:

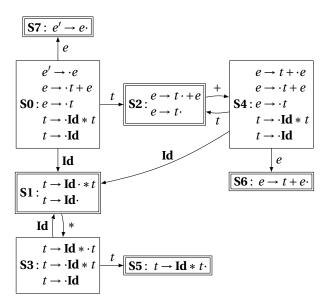
Id

The first state suggests a viable prefix can start as any string derived from e, any string derived from t, or **Id**.

The items for these three states come from advancing the \cdot across each thing, then performing the closure operation (vacuous here).







The FIRST function

If you can derive a string that starts with terminal t from some sequence of terminals and nonterminals α , then $t \in FIRST(\alpha)$.

- 1. Trivially, $FIRST(X) = \{X\}$ if X is a terminal.
- 2. If $X \to \epsilon$, then add ϵ to FIRST(X).
- 3. For each production $X \to Y \cdots$, add $FIRST(Y) \{\epsilon\}$ to FIRST(X). If X can produce something, X can start with whatever that starts with
- 4. For each production $X \to Y_1 \cdots Y_k Z \cdots$ where $\epsilon \in \text{FIRST}(Y_i)$ for i = 1, ..., k, add $\text{FIRST}(Z) \{\epsilon\}$ to FIRST(X).

 Skip all potential ϵ 's at the beginning of whatever X produces

$1: e \rightarrow t + e$	$FIRST(\mathbf{Id}) = {\mathbf{Id}}$
$2:e \rightarrow t$	$FIRST(t) = \{Id\}$ because $t \to Id * t$ and $t \to Id$
$3: t \to \mathbf{Id} * t$ $4: t \to \mathbf{Id}$	FIRST(e) = { Id } because $e \rightarrow t + e$, $e \rightarrow t$, and FIRST(t) = { Id }.

- 1. Add \$ ("end-of-input") to FOLLOW(S) (start symbol). *End-of-input comes after the start symbol*
- 2. For each production $\rightarrow \cdots A\alpha$, add FIRST(α) $\{\epsilon\}$ to FOLLOW(A). *A is followed by the first thing after it*
- 3. For each production $A \rightarrow \cdots B$ or $a \rightarrow \cdots B\alpha$ where $\epsilon \in FIRST(\alpha)$, then add everything in FOLLOW(A) to FOLLOW(B).

 If B appears at the end of a production, it can be followed by whatever follows that production

```
1: e \rightarrow t + e FOLLOW(e) = {$}

2: e \rightarrow t FOLLOW(t) = { }

3: t \rightarrow \mathbf{Id} * t 1. Because e is the start symbol

FIRST(t) = {\mathbf{Id}}

FIRST(e) = {\mathbf{Id}}
```

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```
1: e \rightarrow t + e
2: e \rightarrow t
3: t \rightarrow \mathbf{Id} * t
4: t \rightarrow \mathbf{Id}
FIRST(t) = \{\mathbf{Id}\}
FIRST(e) = \{\mathbf{Id}\}
FOLLOW(e) = \{\$\}
2. Because e \rightarrow \underline{t} + e \text{ and } \text{FIRST}(+) = \{+\}
```

- 1. Add \$ ("end-of-input") to FOLLOW(S) (start symbol). *End-of-input comes after the start symbol*
- 2. For each production $\rightarrow \cdots A\alpha$, add FIRST(α) $\{\epsilon\}$ to FOLLOW(A). *A is followed by the first thing after it*
- 3. For each production $A \to \cdots B$ or $a \to \cdots B\alpha$ where $\epsilon \in FIRST(\alpha)$, then add everything in FOLLOW(A) to FOLLOW(B).

 If B appears at the end of a production, it can be followed by whatever follows that production

$$1: e \rightarrow t + e$$
 FOLLOW(e) = {\$}

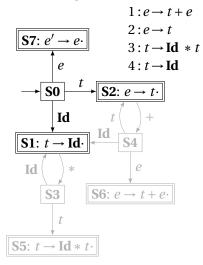
$$2: e \rightarrow t$$
 FOLLOW(t) = {+,\$}

$$3: t \rightarrow \mathbf{Id} * t$$
 3. Because $e \rightarrow \underline{t}$ and \$ \in \text{FOLLOW}(e)
FIRST(t) = {\mathbf{Id}}
FIRST(e) = {\mathbf{Id}}

- 1. Add \$ ("end-of-input") to FOLLOW(S) (start symbol). *End-of-input comes after the start symbol*
- 2. For each production $\rightarrow \cdots A\alpha$, add FIRST(α) $\{\epsilon\}$ to FOLLOW(A). *A is followed by the first thing after it*
- 3. For each production $A \to \cdots B$ or $a \to \cdots B\alpha$ where $\epsilon \in FIRST(\alpha)$, then add everything in FOLLOW(A) to FOLLOW(B).

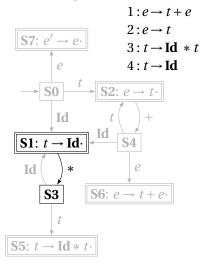
 If B appears at the end of a production, it can be followed by whatever follows that production

$1: e \rightarrow t + e$	$FOLLOW(e) = \{\$\}$
$2: e \rightarrow t$	$FOLLOW(t) = \{+,\$\}$
$3: t \rightarrow \mathbf{Id} * t$	Fixed-point reached: applying any rule does
$4:t\rightarrow \mathbf{Id}$	1 11 2 2 2
$FIRST(t) = \{ \mathbf{Id} \}$	not change any set
$FIRST(e) = \{ \mathbf{Id} \}$	



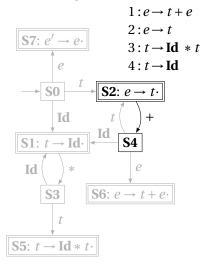
State		Act	Goto			
	Id	+	*	\$	\overline{e}	t
0	sl				7	2

From S0, shift an **Id** and go to S1; or cross a *t* and go to S2; or cross an *e* and go to S7.



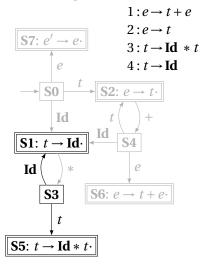
State	Action				Go	oto
	Id	+	*	\$	\overline{e}	t
0	s1				7	2
1		r4	s3	r4		

From S1, shift a * and go to S3; or, if the next input could follow a *t*, reduce by rule 4. According to rule 1, + could follow *t*; from rule 2, \$ could.



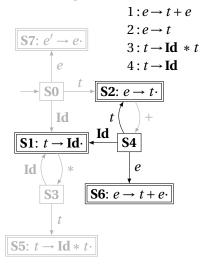
State		Goto				
	Id	+	*	\$	\overline{e}	t
0	s1				7	2
1		r4	s3	r4		
2		s4		r2		

From S2, shift a + and go to S4; or, if the next input could follow an e (only the end-of-input \$), reduce by rule 2.



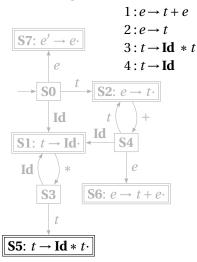
State		Goto				
	Id	+	*	\$	\overline{e}	t
0	s1				7	2
1		r4	s3	r4		
2		s4		r2		
3	s1					5

From S3, shift an **Id** and go to S1; or cross a *t* and go to S5.



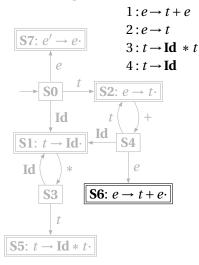
State		Goto				
	Id	+	*	\$	\overline{e}	t
0	s1				7	2
1		r4	s3	r4		
2		s4		r2		
3	s1					5
4	sl				6	2

From S4, shift an **Id** and go to S1; or cross an *e* or a *t*.



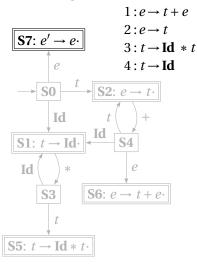
State		Goto				
	Id	+	*	\$	\overline{e}	t
0	s1				7	2
1		r4	s3	r4		
2		s4		r2		
3	s1					5
4	s1				6	2
5		r3		r3		

From S5, reduce using rule 3 if the next symbol could follow a *t* (again, + and \$).



State		Goto				
	Id	+	*	\$	\overline{e}	t
0	s1				7	2
1		r4	s3	r4		
2		s4		r2		
3	s1					5
4	s1				6	2
5		r3		r3		
6				r1		

From S6, reduce using rule 1 if the next symbol could follow an *e* (\$ only).



State		Goto				
	Id	+	*	\$	\overline{e}	t
0	s1				7	2
1		r4	s3	r4		
2		s4		r2		
3	s1					5
4	s1				6	2
5		r3		r3		
6				r1		
7				\checkmark		

If, in S7, we just crossed an *e*, accept if we are at the end of the input.

 $1: e \rightarrow t + e$

 $2:e \rightarrow t$

 $3: t \rightarrow \mathbf{Id} * t$

 $4: t \rightarrow \mathbf{Id}$

State		Action			Goto	
	Id	+	*	\$	\overline{e}	t
0	s1				7	2
1		r4	s3	r4		
2		s4		r2		
3	s1					5
4	s1				6	2
5		r3		r3		
6				r1		
7				\checkmark		

Stack	Input	Action
0	Id * Id + Id \$	Shift, goto 1

Look at the state on top of the stack and the next input token.

Find the action (shift, reduce, or error) in the table.

In this case, shift the token onto the stack and mark it with state 1.

 $1: e \rightarrow t + e$

 $2:e \rightarrow t$

 $3: t \rightarrow \mathbf{Id} * t$

 $4: t \rightarrow \mathbf{Id}$

State		Action				oto
	Id	+	*	\$	\overline{e}	t
0	s1				7	2
1		r4	s3	r4		
2		s4		r2		
3	s1					5
4	s1				6	2
5		r3		r3		
6				r1		
7				\checkmark		

Stack	Input	Action	
0	Id * Id + Id \$	Shift, goto 1	
0 Id 1	* Id + Id \$	Shift, goto 3	

Here, the state is 1, the next symbol is *, so shift and mark it with state 3.

 $1: e \rightarrow t + e$

 $2:e \rightarrow t$

 $3: t \rightarrow \mathbf{Id} * t$

 $4: t \rightarrow \mathbf{Id}$

State		Act		Go	oto	
	Id	+	*	\$	e	t
0	s1				7	2
1		r4	s3	r4		
2		s4		r2		
3	sl					5 2
4	sl				6	2
5		r3		r3		
6				r1		
7				\checkmark		

Stack	Input	Action
0	Id * Id + Id \$	Shift, goto 1
0 Id	* Id + Id \$	Shift, goto 3
0 Id * 3	Id + Id \$	Shift, goto 1
0 Id * Id 1 3 1	+ Id \$	Reduce 4

Here, the state is 1, the next symbol is +. The table says reduce using rule 4.

 $1: e \rightarrow t + e$

 $2:e \rightarrow t$

 $3: t \rightarrow \mathbf{Id} * t$

 $4: t \rightarrow \mathbf{Id}$

State		Act		Go	oto	
	Id	+	*	\$	\overline{e}	t
0	s1				7	2
1		r4	s3	r4		
2		s4		r2		
3	sl					5 2
4	sl				6	2
5		r3		r3		
6				r1		
7				\checkmark		

Stack	Input	Action
0	Id * Id + Id \$	Shift, goto 1
0 Id 1	* Id + Id \$	Shift, goto 3
0 Id * 3	Id + Id \$	Shift, goto 1
0 Id * Id 1 3 1	+ Id \$	Reduce 4
0 Id * 3	+ Id \$	

Remove the RHS of the rule (here, just **Id**), observe the state on the top of the stack, and consult the "goto" portion of the table.

 $1: e \rightarrow t + e$

 $2:e \rightarrow t$

 $3: t \rightarrow \mathbf{Id} * t$

 $4: t \rightarrow \mathbf{Id}$

State		Act		Go	oto	
	Id	+	*	\$	\overline{e}	t
0	s1				7	2
1		r4	s3	r4		
2		s4		r2		
3	s1					5 2
4	s1				6	2
5		r3		r3		
6				r1		
7				\checkmark		

Stack	Input	Action
0	Id * Id + Id \$	Shift, goto 1
$0 \frac{\mathbf{Id}}{1}$	* Id + Id \$	Shift, goto 3
0 Id * 1 3	Id + Id \$	Shift, goto 1
0 Id * Id 1 3 1	+ Id \$	Reduce 4
$0 \begin{array}{cccccccccccccccccccccccccccccccccccc$	+ Id \$	Reduce 3

Here, we push a t with state 5. This effectively "backs up" the LR(0) automaton and runs it over the newly added nonterminal.

In state 5 with an upcoming +, the action is "reduce 3."

 $1: e \rightarrow t + e$

 $2:e \rightarrow t$

 $3: t \rightarrow \mathbf{Id} * t$

 $4: t \rightarrow \mathbf{Id}$

State		Goto				
	Id	+	*	\$	\overline{e}	t
0	s1				7	2
1		r4	s3	r4		
2		s4		r2		
3	s1					5
4	s1				6	2
5		r3		r3		
6				r1		
7				\checkmark		

Stack	Input	Action
0	Id * Id + Id \$	Shift, goto
0 Id	* Id + Id \$	Shift, goto
0 Id * 3	Id + Id \$	Shift, goto
0 Id * Id 1 3 1	+ Id \$	Reduce 4
$0 \begin{array}{cccccccccccccccccccccccccccccccccccc$	+ Id \$	Reduce 3
$0 \begin{array}{c} t \\ 2 \end{array}$	+ Id \$	Shift, goto

This time, we strip off the RHS for rule 3, $\mathbf{Id} * t$, exposing state 0, so we push a t with state 2.

Shift/Reduce Parsing with an SLR Table

$1: e \rightarrow t + e$	
$2:e \rightarrow t$	
$3:t \rightarrow \mathbf{Id} * t$	
$4:t\rightarrow \mathbf{Id}$	

State	Action			Goto		
	Id	+	*	\$	\overline{e}	t
0	s1				7	2
1		r4	s3	r4		
2		s4		r2		
3	s1					5
4	s1				6	2
5		r3		r3		
6				r1		
7				1		

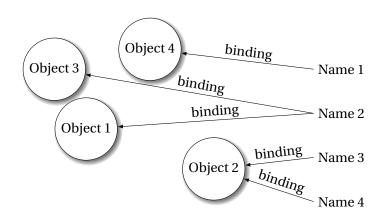
0	Id * Id + Id \$	Shift, goto 1
0 Id	* Id + Id \$	Shift, goto 3
0 Id * 3	Id + Id \$	Shift, goto 1
0 Id * Id 1 3 1	+ Id \$	Reduce 4
$0 \ \frac{1d}{1} \ \frac{*}{3} \ \frac{t}{5}$	+ Id \$	Reduce 3
$0 \begin{array}{c} t \\ 2 \end{array}$	+ Id \$	Shift, goto 4
$0 \begin{array}{ccc} t & + \\ 2 & 4 \end{array}$	Id\$	Shift, goto 1
$0 \ \ \begin{array}{ccccccccccccccccccccccccccccccccc$	\$	Reduce 4
$0\begin{array}{cccc}t&+&t\\2&4&2\end{array}$	\$	Reduce 2
$0\begin{array}{cccc} t & + & e \\ 2 & 4 & 6 \end{array}$	\$	Reduce 1
$0 \begin{array}{c} e \\ 7 \end{array}$	\$	Accept

Input

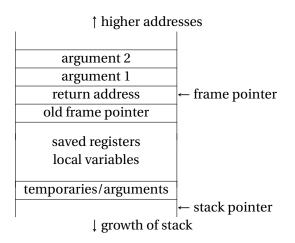
Action

Stack

Names, Objects, and Bindings



Typical Stack Layout

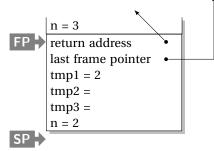


n = 3

```
int fib(int n) {
    int tmp1, tmp2, tmp3;
    tmp1 = n < 2;
    if (!tmp1) goto L1;
    return 1:
L1: tmp1 = n - 1;
    tmp2 = fib(tmp1);
L2: tmp1 = n - 2;
    tmp3 = fib(tmp1);
L3: tmp1 = tmp2 + tmp3;
    return tmp1;
}
```

Executing fib(3)

```
int fib(int n) {
    int tmp1, tmp2, tmp3;
    tmp1 = n < 2;
    if (!tmp1) goto L1;
    return 1:
L1: tmp1 = n - 1;
    tmp2 = fib(tmp1);
L2: tmp1 = n - 2;
    tmp3 = fib(tmp1);
L3: tmp1 = tmp2 + tmp3;
    return tmp1;
}
```



```
Executing fib(3)
                                          n = 3
                                          return address
                                          last frame pointer
                                          tmp1 = 2
                                          tmp2 =
  int fib(int n) {
                                          tmp3 =
      int tmp1, tmp2, tmp3;
                                          n = 2
      tmp1 = n < 2;
                                          return address
      if (!tmp1) goto L1;
                                          last frame pointer
                                          tmp1 = 1
      return 1:
                                          tmp2 =
 L1: tmp1 = n - 1;
                                          tmp3 =
      tmp2 = fib(tmp1);
                                          n = 1
 L2: tmp1 = n - 2;
      tmp3 = fib(tmp1);
 L3: tmp1 = tmp2 + tmp3;
      return tmp1;
  }
```

```
Executing fib(3)
                                            n = 3
                                            return address
                                            last frame pointer
                                            tmp1 = 2
                                            tmp2 =
  int fib(int n) {
                                            tmp3 =
       int tmp1, tmp2, tmp3;
                                            n = 2
      tmp1 = n < 2;
                                            return address
                                            last frame pointer
      if (!tmp1) goto L1;
                                            tmp1 = 1
      return 1:
                                            tmp2 =
  L1: tmp1 = n - 1;
                                            tmp3 =
      tmp2 = fib(tmp1); \Leftarrow
                                            n = 1
  L2: tmp1 = n - 2;
                                            return address
      tmp3 = fib(tmp1);
                                            last frame pointer
  L3: tmp1 = tmp2 + tmp3;
                                            tmp1 = 1
      return tmp1;
                                            tmp2 =
  }
                                            tmp3 =
```

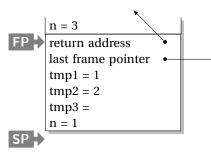
```
Executing fib(3)
                                          n = 3
                                          return address
                                          last frame pointer
                                          tmp1 = 2
                                          tmp2 =
  int fib(int n) {
                                          tmp3 =
      int tmp1, tmp2, tmp3;
                                          n = 2
      tmp1 = n < 2;
                                          return address
                                          last frame pointer
      if (!tmp1) goto L1;
                                          tmp1 = 0
      return 1:
                                          tmp2 = 1
 L1: tmp1 = n - 1;
                                          tmp3 =
      tmp2 = fib(tmp1);
                                          n = 0
 L2: tmp1 = n - 2;
      tmp3 = fib(tmp1);
 L3: tmp1 = tmp2 + tmp3;
      return tmp1;
  }
```

```
Executing fib(3)
                                           n = 3
                                           return address
                                           last frame pointer
                                           tmp1 = 2
                                           tmp2 =
  int fib(int n) {
                                           tmp3 =
      int tmp1, tmp2, tmp3;
                                           n = 2
      tmp1 = n < 2;
                                           return address
                                           last frame pointer
      if (!tmp1) goto L1;
                                           tmp1 = 0
      return 1:
                                           tmp2 = 1
 L1: tmp1 = n - 1;
                                           tmp3 =
      tmp2 = fib(tmp1);
                                           n = 0
 L2: tmp1 = n - 2;
                                           return address
      tmp3 = fib(tmp1);
                                           last frame pointer
 L3: tmp1 = tmp2 + tmp3;
                                           tmp1 = 1
      return tmp1;
                                           tmp2 =
                                           tmp3 =
```

```
Executing fib(3)
                                          n = 3
                                          return address
                                          last frame pointer
                                          tmp1 = 2
                                          tmp2 =
  int fib(int n) {
                                          tmp3 =
      int tmp1, tmp2, tmp3;
                                          n = 2
      tmp1 = n < 2;
                                          return address
                                          last frame pointer
      if (!tmp1) goto L1;
                                          tmp1 = 2
      return 1:
                                          tmp2 = 1
 L1: tmp1 = n - 1;
                                          tmp3 = 1
      tmp2 = fib(tmp1);
 L2: tmp1 = n - 2;
      tmp3 = fib(tmp1);
 L3: tmp1 = tmp2 + tmp3;
      return tmp1;
```

Executing fib(3)

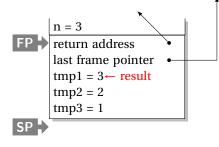
```
int fib(int n) {
    int tmp1, tmp2, tmp3;
    tmp1 = n < 2;
    if (!tmp1) goto L1;
    return 1:
L1: tmp1 = n - 1;
    tmp2 = fib(tmp1);
L2: tmp1 = n - 2;
    tmp3 = fib(tmp1);
L3: tmp1 = tmp2 + tmp3;
    return tmp1;
}
```



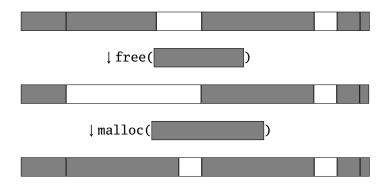
```
Executing fib(3)
                                          n = 3
                                          return address
                                          last frame pointer
                                          tmp1 = 1
                                          tmp2 = 2
  int fib(int n) {
                                          tmp3 =
      int tmp1, tmp2, tmp3;
                                          n = 1
      tmp1 = n < 2;
                                          return address
      if (!tmp1) goto L1;
                                          last frame pointer
                                          tmp1 = 1
      return 1:
                                          tmp2
 L1: tmp1 = n - 1;
                                          tmp3 =
      tmp2 = fib(tmp1);
 L2: tmp1 = n - 2;
      tmp3 = fib(tmp1);
 L3: tmp1 = tmp2 + tmp3;
      return tmp1;
  }
```

Executing fib(3)

```
int fib(int n) {
    int tmp1, tmp2, tmp3;
    tmp1 = n < 2;
    if (!tmp1) goto L1;
    return 1:
L1: tmp1 = n - 1;
    tmp2 = fib(tmp1);
L2: tmp1 = n - 2;
    tmp3 = fib(tmp1);
L3: tmp1 = tmp2 + tmp3;
    return tmp1;
}
```



Dynamic Storage Allocation



Dynamic Storage Allocation

```
Rules:
```

Each allocated block contiguous (no holes)

Blocks stay fixed once allocated

malloc()

Find an area large enough for requested block

Mark memory as allocated

free()

Mark the block as unallocated



Simple Dynamic Storage Allocation

Maintaining information about free memory

Simplest: Linked list

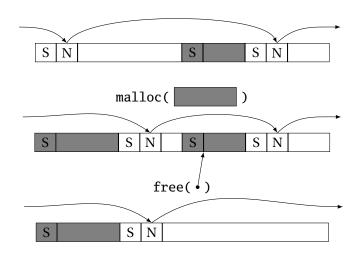
The algorithm for locating a suitable block

Simplest: First-fit

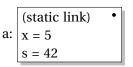
The algorithm for freeing an allocated block

Simplest: Coalesce adjacent free blocks

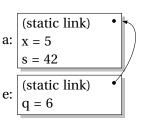
Simple Dynamic Storage Allocation



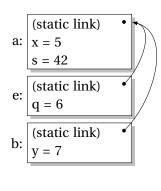
```
let a x s =
  let b y =
    \mathbf{let} \ c \ z = z + s \ \mathbf{in}
    let d w = c (w+1) in
    d(y+1) in (* b *)
  let e \ q = b \ (q+1) in
e (x+1) (* a *)
```



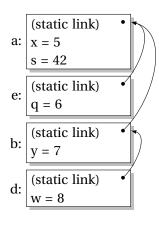
```
let a x s =
  let b y =
     \mathbf{let} \ c \ z = z + s \ \mathbf{in}
    let d w = c (w+1) in
    d(y+1) in (* b *)
  let e \ q = b \ (q+1) in
e (x+1) (* a *)
```



```
let a x s =
  let b y =
    \mathbf{let} \ c \ z = z + s \ \mathbf{in}
    let d w = c (w+1) in
    d(y+1) in (* b *)
  let e \ q = b \ (q+1) in
e(x+1)(*a*)
```

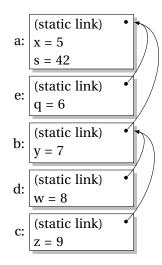


```
let a x s =
 let b y =
   let c z = z + s in
   let d w = c (w+1) in
   d(y+1) in (* b *)
 let e \ q = b \ (q+1) in
e(x+1)(*a*)
```



```
let a x s =
 let b y =
    let c z = z + s in
   let d w = c (w+1) in
   d(y+1) in (* b *)
 let e \ q = b \ (q+1) in
e(x+1)(*a*)
```

What does "a 5 42" evaluate to?



Static vs. Dynamic Scope

```
program example;
var a : integer; (* Outer a *)
  procedure seta;
  begin
    a := 1 (* Which a does this change? *)
  end
  procedure locala;
  var a : integer; (* Inner a *)
  begin
   seta
  end
begin
  a := 2;
  if (readln() = 'b')
   locala
  else
    seta;
 writeln(a)
end
```